Algorithms and Data Structures for Biology

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1 The Problem

Suppose you are a biologist who will soon move to the franco-italian Antartic Station1. The Station is not covered by broadband Internet, and so most of the needed data must be brought with you. You can bring with you only one hard disk with a capacity of n gigabytes. Inside the hard disk you need to fit as many of your databases as possible. You are currently working with m different databases, call them 1....m, with database j having a size equal to S_j megabytes. Please notice that S_j is much bigger than n gigabtyes How should you decide which ones of the databases you should bring with you? You first attribute to each database a measure U_j of the utility the database has for you. Then, you realise you want to bring with you a set of databases with maximal total quality among those which fits into your hard disk.

2 Description of the combinatorial problem

Given a set of objects 1....m and an integer number n. To each object j of 1....m, we assign two integer numbers S_j and U_j . Consider that: $\sum_{j \in 1, ..., m} S_j > n$. Find the subset D of 1....m such that:

$$\sum_{i \in D} U_i$$
 is maximal and $\sum_{i \in D} S_i \leq n$ where $D \subseteq 1, ..., m$.

3 The Algorithm-Exhaustive Search

REQUIRE: An integer number m an other integer number n and two arrays S and U containing integer numbers such that both S and U have size equal to m.

ENSURE: Return the subset D of integer numbers of 1....m such that: $\sum_{i \in D} U_i$ is maximal and $\sum_{i \in D} S_i \leq n$ where $D \subseteq 1....m$.

The pseudo code that has been constructed for the development of the algorithm, is composed of two functions:

• the first function setOfPossibleCombinations($\{1,\ldots,m\}$) is fundamental since it defines the search space, so the environment where the algorithm has to search the subset D of $1,\ldots,m$ that maximise the $\sum_{i\in D}U_i$ and has $\sum_{i\in D}S_i\leq n$. So this function is responsible of building all possible subsets of $1,\ldots,m$ having size from 0 up to m, which represents all possible combinations through which the elements in $1,\ldots,m$ can be combined. The function starts from all possible subsets of size 1 and from these, it builds all possible combinations of subsets of size increased by one. The results are collected in two arrays: one called result that at the end of the execution will contain the entire search space; another one called volPermu which temporary becomes the starting point for computing the subsets of higher

size. The function keep on computing the different combinations until the last created one has a size equal to the set $1, \dots, m$, meaning that it has generated all possible subsets of all sizes. The function avoids to compute redundant subsets meaning that, if we consider the subset 1, 2, 3 has the same meaning of the subset 2, 1, 3;

• the second function ExhaustiveSearchAlgorithm(n,m,S,U) analyzes each element of the search space. As it analyzes the current subset, it evaluates the $\sum_{i \in subset} S_i$ and the $\sum_{i \in subset} U_i$ keeping on track of just those subsets where $\sum_{i \in subset} S_i \leq n$ and $\sum_{i \in subset} U_i$ being maximal. So at the end, the function will return the best possible solution.

```
SETSOFPOSSIBLECOMBINATIONS({1....M})
  result \leftarrow array of all possible subsets of length 1 and 0
  permu \leftarrow array of all possible subsets of length 1
  while |lastelementinresult| \neq |1....m| do
     volPermu \leftarrow empty array
     for all elements e in permu do
       start \leftarrow position of the last character of e in 1....m
       i \leftarrow \text{start} + 1
       while i \neq |1....m| do
          vol \leftarrow e + m_i
          volPermu \leftarrow volPermu + vol
          i \leftarrow i + 1
       end while
       result \leftarrow result + volPermu
       permu \leftarrow volPermu
     end for
  end while
  return result
```

How does this function generates the search space? Basically, it starts considering all possible subsets of 1.....m having size equal to one. Then, per each subset under analysis, the function uses a for loop and a nested while loop to generate all possible subsets of size being increased by one. The for loop selects the starting subset and then the while loop creates all different new subsets of size increased by one by adding one element of 1.....m that is not already present in the subset under analysis. In this way, the function avoids to create redundant combinations. Once the for loop has evaluated all subsets of the current size, it starts again considering those that has been just generated, so those having a size being increased by one. The process continues until all subsets of all different sizes has been generated. In fact, the overall iteration process is controlled by a while loop that, once new subsets has been generated, checks their size. If the size of the last element added in the power set is equal to the one of 1.....m,its guard fails meaning that all possible subsets of all possible sizes has been created and collected in the search space.

```
\begin{split} & \text{ExhaustiveSearchAlgorithm(n,m,S,U)} \\ & \textit{databases} \leftarrow \{1.....m\} \\ & \textit{sets} \leftarrow \text{setsOfPossibleCombinations(databases)} \\ & \textit{databases} \leftarrow \text{empty array} \\ & \textit{maxU} \leftarrow 0 \\ & \text{for all elements } e \text{ in sets do} \\ & \textit{volS} \leftarrow 0 \\ & \textit{volU} \leftarrow 0 \\ & \text{for all elements } i \text{ in e do} \\ & \textit{volS} \leftarrow \sum_{i \in e} S_i \\ & \textit{volU} \leftarrow \sum_{i \in e} U_i \end{split}
```

```
end for if volS \le n and volU > maxU then maxU \leftarrow volU databases \leftarrow e end if end for return databases
```

This function is responsible to evaluate each element in the search space. The latter is generated by calling the function $setsOfPossibleCombinations(\{1,\ldots,m\})$. Once the search space is available, the search for the subset D of 1....m that has $\sum_{i\in D} S_i \leq n$ and $\sum_{i\in D} U_i$ maximal is performed by two for loops, nested one inside the other. The first considers the subsets in the power set, each by each. The second, calculates the $\sum_{i\in subset} S_i$ and the $\sum_{i\in subset} U_i$ of each element considered in the first for loop. Then, these summations are validated by an if statement that keeps on track of best subset from 1....m having $\sum_{i\in D} S_i \leq n$ and $\sum_{i\in D} U_i$ maximal. In the final output, the best combination is reported.

4 The Implementation-Exhaustive Search

The algorithm has been developed in python language (version(3.7)). The program is structured of two python functions, each performing a specific role.

The following Python function setsPos(m) implements the above algorithm for the creation of all possible subsets of 1....m of different sizes representing all possible combinations through which one can organize elements of the set 1....m. So this python function is responsible of constructing the search space.

```
def setsPos(m):
      result = [[],] + [[y,] for y in m]
      permu = [[x,] for x in m]
      while len(result[-1]) != len(m):
            volPermu = []
            for e in permu:
                   end = m.index(e[-1])
                   i = end+1
                   while i < len(m):
                         vol = []
                         vol = e + [m[i],]
                         volPermu += [vol,]
                         i += 1
            result += volPermu
            permu = volPermu
      return result
```

The following python function ExhaustiveSearch(n,m,S,U) implements the above algorithm for searching among all possible subsets of 1....m, the one D having $\sum_{i \in D} U_i$ is maximal and $\sum_{i \in D} S_i \leq n$

```
def ExhaustiveSearch(n,m,S,U):
   databases = [z for z in range(m)]
   sets = setsPos(databases)
   maxU = 0
   database = []
```

```
for e in sets:
   volS = 0
   volU = 0
   for i in e:
       search = databases.index(i)
       volS += S[search]
       volU += U[search]
   if volS <= n and volU > maxU:
       maxU = volU
       database = e
```

return database

5 Proof Time Complexity-Exhaustive Search

We want to calculate the time complexity of the algorithm for any value m. As the value of m increases, the time needed by the algorithm to execute all the instructions increases exponentially. Considering the function $\mathtt{setsOfPossibleCombinations(m)}$, we observe that the output of this function has a size equal to 2^m . So it produces an array carrying such number of elements which basically represents our search space. We can say that the output of this function is an array counting 2^m elements simply because it calculates the power \mathtt{set} , that considers all kinds of possible subsets, avoiding to compute redundant elements. Therefore, we can conclude that the total number of elements obtained by this function increases exponentially as the value of m becomes higher. Considering the pseudo-code that has been constructed, the structures that rise the number of instructions are two while loops and one for loop that are nested in a hierarchical and precise way.

Since we want to count the number of instructions performed by each of them, we proceed analysing the first while loop found in the pseudo-code. Basically, the guard is evaluated m times. This is due to the fact that, every time the array result is extended with all subsets having the same size, the value of the size under the analysis of the guard of the while loop, increases. Therefore, considering that the power set is made by a number of elements having length that can take values from 1 up to m and that the while loop is evaluated only once all subsets of the same size are created, the guard will be checked for a number of times equal to the number of possible value of size available in the power set, so m times.

Now we can move to the nested for loop and we can notice that at the end of the execution, the variable e present in the guard, is gradually assigned to all values in the search space along the execution. Basically, the guard of the for loop under analysis considers an array called permu a total number of m times since its execution is ruled by a while loop whose guard, as we said before, is evaluated m times. So the for loop evaluates a total number of m guards. At each run, the variable e in the current guard of the for loop is assigned to all subsets having same size present in the array permu. At the end of the loop, the array on which the for loop iterates is updated with all subsets having size increased by one. So, since this process continue up the failure of the guard of the first while loop, marking that all subsets of all size from 1 up to m have been constructed, the variable e in the for loop, will be assigned to 2^m values, so the entire power set. Then, considering the last while loop, nested in the previously analyzed for loop, we can see that, in the worst case, the guard is evaluated m times since the variable e is has to consider all elements of the set e1....em to built all subsets of size increased by one, each being different from the others. So, to conclude, the total number of instructions performed by the function setsOfPossibleCombinations(m) is equal to:

```
number of basic instructions = m * 2^m * m = m^2 2^m
number of basic instructions = m^2 2^m
```

Now, we can consider the second function of the algorithm ExhaustiveSearchAlgorithm(n,m,S,U). Basically, in this case, the number of instructions is dictated by two for loops.

Considering the first one, the variable e is assigned 2^m times since it has to analyze all possible elements of the search space, that, as we have already discussed, counts a total of 2^m subsets in it.

The second for loop, in the worst case, evaluates the variable i a total number of m times since it has to calculate the $\sum_{i \in subset} S_i$ and the $\sum_{i \in subset} U_i$ per each subset in the power set. Therefore, considering that the search space is formed of elements of size from 1 up to m, when the variable e of the first for loop considers a set of size m the variable i of the second for loop (nested in the first one) is evaluated m times since it considers all values of the set under analysis. So the total number of instructions performed by the functionExhaustiveSearchAlgorithm(n,m,S,U) is equal to:

```
number of basic instructions = m * 2^m
number of basic instructions = m 2^m
```

To conclude, the time complexity of the algorithm under analysis can be evaluated summing the number of basic instructions performed by the two functions that we have just explained.

```
sum of basic instructions = m^2 \ 2^m + m \ 2^m
sum of basic instructions = m^2 \ 2^m
```

So the complexity of the algorithm is approximately $O(m^2 \ 2^m)$. Therefore we can observe that the number of basic instructions grows exponentially as the value of m increases.

6 The algorithm-Branch And Bound

In this section, we analyze the possible improvement of the Exhaustive Search algorithm. Basically, one way that can be used to make the algorithm faster, even if the complexity remains exponential, is to consider only subsets where $\sum_{i \in subset} S_i$ does not exceed the threshold n. In the moment in which the program meets a subset that is not favorable to be taken into consideration, there is no need to calculate its relative, so the algorithm skips them and proceed into evaluating other subsets. Otherwise, when a subset is in a favorable condition, meaning that $\sum_{i \in subset} S_i < n$, the program explores its relatives which are subsets of higher length. The algorithm has been developed following the Branch And Bound methodology in which each internal node represents a possible subset of size lower then m.

The pseudo-code that has been constructed is formed of four functions, each performing a specific functionality:

- the function OverPass(node,m) is responsible of bypassing a node, which represents one possible combination, in the moment in which the $\sum_{i \in node} S_i > n$;
- the function NextNode(node,m) is responsible of building a node of size increased by one, so a possible subset of 1....m, originated from the current node under analysis. So it allows the exploration of novel nodes of higher size;
- the function ComputeSums(node,S,U) is responsible to calculate the $\sum_{i \in node} S_i$ and the $\sum_{i \in node} U_i$ of the current node so of the current subset of 1....m;
- the function BranchAndBound(n,m,S,U) is responsible of evaluating the validity of the subset of 1.....m under study. The control is performed analysing the $\sum_{i \in node} S_i$ and the $\sum_{i \in node} U_i$, where node is the current subset of 1.....m.

```
OVERPASS(NODE,M)
  if a subset from which no further combinations are available then
     node \leftarrow remove the last element of the current node {go back to the vertex}
     node \leftarrow \text{increase the last value of } node \text{ by } 1 \text{ go to the node on the right}
     return node
  else
     node \leftarrow \text{add } 1 \text{ to the last element of the current node } \{\text{bypass the current node}\}
     return node
  end if
NEXTNODE(NODE,M)
  if a subset from which no further combinations are available then
     node \leftarrow \text{remove the last element of the current node } \{\text{go back to the vertex}\}
     node \leftarrow \text{increase the last value of } node \text{ by 1 } \{ \text{go to right node} \}
     return node
  else
     node \leftarrow build node of size increased by 1 {explore lower level in the tree}
     return node
  end if
COMPUTESUMS (NODE, S, U)
  capacity \leftarrow 0
  utility \leftarrow 0
  for all elements e in node do
     capacity \leftarrow \sum_{e \in node} S_e
     utility \leftarrow \sum_{e \in node}^{e \in node} U_e
  end for
  return capacity, utility
BranchAndBound(n,m,S,U)
  finalQual \leftarrow 0
  output \leftarrow \text{empty array}
  for i \leftarrow 1 to m do
     node \leftarrow array containing i
     capacity \leftarrow array containing the corresponding element at position i in S
     utility \leftarrow array containing the corresponding element at position i in U
     while forever do
        if The current node is the last leaf of this section of the tree then
          stop while
        end if
        if capacity > n then
          node \leftarrow OverPass(node, m)
          newSums \leftarrow ComputeSums(node,S,U)
          capacity \leftarrow first element of newSums
          utility \leftarrow second element of newSums
        else
          if utility > finalQual then
             finalQual \leftarrow utility
             output \leftarrow the current node to output
          end if
          node \leftarrow NextNode(node,m)
          newSums \leftarrow ComputeSums(node,S,U)
```

```
\begin{array}{c} capacity \leftarrow \text{first element of newSums} \\ utility \leftarrow \text{second element of newSums} \\ \textbf{end if} \\ \textbf{end while} \\ \textbf{end for} \\ \textbf{if number of subsets} = 1 \textbf{ then} \\ \textbf{if } S_{node} < n \textbf{ then} \\ \textbf{return } m \\ \textbf{else} \\ \textbf{return } \text{no subsets, respecting the condition, available} \\ \textbf{end if} \\ \textbf{return last element collected in } output \end{array}
```

7 The implementation-Branch And Bound

The following python function OverPass(node,m) is the implementation of the first function represented in the pseudo-code. It is entitled to bypass a node of the tree in the moment in which the value of the $\sum_{i \in node} S_i$ exceed the threshold n in this way, the algorithm avoids to perform useful computations.

```
def OverPass(node,m):
    if node[-1] == m-1:
        back = node[:-1]
        back[-1] += 1
        return back
    else:
        node[-1] += 1
        return node
```

The following python function NextNode(node,m) is the implementation of the second function provided in the pseudo-code. It is responsible to explore the internal nodes of the tree in the moment in which the $\sum_{i \in node} S_i$ is lower or equal then the threshold n.

```
def NextNode(node,m):
    if node[-1] == m-1:
        back = node[:-1]
        back[-1] += 1
        return back
else:
        node = node + [node[-1] +1]
        return node
```

The following python function ComputeSums (node,S,U) id the implementation of the third function provided by the pseudo-code. It is responsible of calculating the $\sum_{i \in node} S_i$ and the $\sum_{i \in node} U_i$ of the current node under analysis.

```
def ComputeSums(node, S, U):
    capacity = 0
    utility = 0
    for e in node:
        capacity += S[e]
        utility += U[e]
    return capacity, utility
```

The following python function BrancAndBound(n,m,S,U) is the implementation of the fourth function provided by the pseudo-code. It is responsible of evaluating each node provided by the other functions of the algorithm, starting from the root node. As a node has a $\sum_{i \in node} S_i$ greater then the threshold n, it induce the algorithm to bypass it and its relatives. Otherwise, it explores them keeping on track of the max $\sum_{i \in node} U_i$.

```
def BranchAndBound(n,m,S,U):
      finalQual = 0
      output = []
      for x in range(m-1):
            node = [x]
            capacity = S[x]
            utility = U[x]
            while True:
                   if node == [x,m-1] or node == [m-1]:
                         break
                   if capacity > n:
                         node = OverPass(node,m)
                         newSums = ComputeSums(node,S,U)
                         capacity = newSums[0]
                         utility = newSums[1]
                   else:
                         if utility > finalQual:
                               finalQual = utility
                               output += [node[:],]
                         node = NextNode(node,m)
                         newSums = ComputeSums(node,S,U)
                         capacity = newSums[0]
                         utility = newSums[1]
      if len(output) == 0:
                             #special case when m=1
            if S[0] < n:
                   return [m-1,]
            else:
                   return None
      return output[-1]
```

8 Testing Routine

This section is dedicated to present a possible function that can be used to test the two algorithms Exhaustive Search and Branch And Bound. This function does not take any argument. As the function is executed, it takes one random value of m among 5,10,15,20,25. It builds two arrays S and U having both size being equal to m and the values inside are selected randomly from 1 to 10. Then the function tests both algorithms for the given value of m, S, U and n where the latter is evaluated for two values: m*7 and m*3.

The following function is the implementation of such test:

```
import random
def test():
    testNumber = [5,10,15,20,25]
    m = random.choice(testNumber)
```

```
S = [random.randint(1,10) for x in range(1,m+1)]
U = [random.randint(1,10) for y in range(1,m+1)]
print('the_number_of_databases_is:',m)
print("The_array_S_contains_the_following_sizes:",S)
print("The_array_U_contains_the_following_utilities:",U)
for e in (3*m,7*m):
    n = e
    print('The_total_amount_of_mamory_available_is:',n)
    print('EXHAUSTIVE_SEARCH')
    ES = ExhaustiveSearch(n,m,S,U)
    print(ES)
    print('BRANCH_AND_BOUND')
    BB = BranchAndBound(n,m,S,U)
    print(BB)
    print('Are_they_equal?', ES==BB)
```

return ''

The values inside S and U are provided randomly importing the dedicated python module import random, that must be inserted before the function definition.

As we can noticed, the algorithms are evaluated for different values of n each: the first time with n=m*7 and the second with n=m*3. The test for the second value of n is performed because considering that the values of S are taken randomly in a range between 1 and 10, the total $\sum_i S_i$ will mostly result to be lower then n when n=m*7. So the final solution of the algorithm will be the overall set 1....m

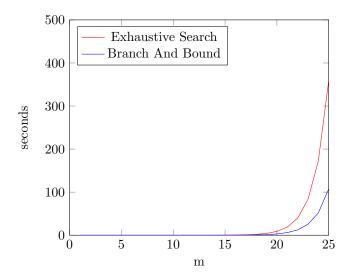
In the last part of the test, the function evaluates if the result of the two algorithms is the same. If such happens, the function will return the Boolean value TRUE. Otherwise, the output will be FALSE.

Performing 10 tests for values of n equal to m*7 and m*3 for each value of m among (5, 10, 15, 20, 25), a total number of 100 test has been done. Among these, 10 provided FALSE as result. This is due to the fact that, values inside S and U are randomly taken from 1 to 10. So it can happen that there are different elements of 1....m having same S or U. Therefore, at the end, we could find subsets of 1....m being different but still having same $\sum_{i \in subset} S_i$ and same $\sum_{i \in subset} U_i$. The ratio of FALSE as result in the test routine increases as the value of m becomes bigger since the number of possible elements of 1....m having different S or U associated to them increases.

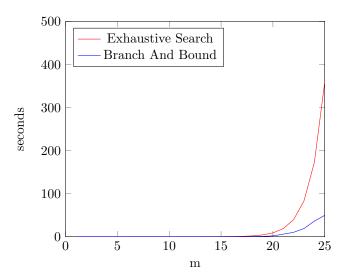
9 Performance ExhaustiveSearch and BranchAndBound algorithms

The following graphs represent the comparison of the performance. The latter has been evaluated considering how the time needed by the algorithms to be executed changes as the value of m increases. Time has been measured in seconds. So two different graphs have been created. The first one considers a value of n being equal to m*7. While in the second, the value of n is equal to m*3. In both graph we find the values of m from 1 up to 25 on the x-axis; while seconds are reported in the y-axis where the value considered go from 1 up to 500. The data cornering time, has been extrapolated by testing the algorithms with different values of m using the python package cProfile.

The following graph shows how the performance, expressed as number of seconds, changes as the value of m increases when the value of n is equal to m * 7. From the graph we can observe that as m becomes bigger and bigger, the time grows exponentially.



The following shows how the performance, expressed as number of seconds, changes as the value of m increases when the value of n is equal to m*3. From the graph we can observe that as m becomes bigger and bigger, the time grows exponentially but in the case of the Branch And Bound algorithm, the amount of seconds needed to provide a result is lower for high values of m. This is mainly due to the fact the Branch And Bound algorithm has been developed to avoid not useful computations in the moment in which a the value of the $\sum_{i \in node} S_i$ exceed the threshold n. Therefore, when n is equal to m*3, it lowers the value of the threshold and considering that there are more probable sets where the $\sum_{i \in set} S_i > n$, the algorithm will skip them, reducing the number of computations and so the amount of seconds of the overall execution.



We can notice from both graphs that, for both values of n, the Exhaustive Search algorithm has the same behaviour. This is mainly due to the fact that the algorithm follows a Brute Force structure, so, independently from the value of n, it has to evaluate all possible solutions rising the number of computations each time.