Curriculum Vitae

Personal Information

Dan Calderone, PhD Postdoctoral Researcher University of Washington 1305 E Mercer, Apt 502, Seattle, WA, 98102

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EDUCATION

08/2010-05/2017 Ph.D., Electrical & Computer Engineering

University of California, Berkeley (UCB)

Thesis: Models of Competition for Intelligent Transportation Infrastructure: Park-

ing, Ridesharing, and External Factors in Routing Decisions

Advisor: S. Shankar Sastry

08/2006–05/2010 B.Sc., Mechanical Engineering

University of Maryland, College Park (UMD)

PROFESSIONAL EXPERIENCE

01/2018-12/2020 University of Washington

06/2022-current

Position: Postdoctoral Scholar

Departments: Aerospace/electrical engineering Supervisor: Lillian J. Ratliff, Behcet Ackimese

Projects: (see below)

Markov decision process congestion games, multi-dimensional continuous-type pop-

ulation games, stability of learning dynamics in games

04/2019–06/2022 University of Washington

Position: Lecturer

Departments: Aerospace/electrical engineering

Courses: (see below)

Linear algebra/linear systems, SISO/MIMO/Robust control, estimation, convex

optimization, network dynamics, statics

Markov Decision Process Congestion Games **Overview:** Developed a version of routing games where individual agents solve a Markov decision process as opposed to a shortest path problem.

Applications: ride-sharing, urban parking, aircraft control management. **Papers:**

1. Calderone, D., and Sastry, S. S. Markov decision process routing games. In 2017 ACM/IEEE 8th International Conference on Cyber-Physical Systems (ICCPS) (2017), IEEE, pp. 273–280

doi: https://doi.org/10.1145/3055004.3055026

pdf: https://danjcalderone.github.io/papers/mdproutingfin.pdf

- 2. Calderone, D., and Shankar, S. Infinite-horizon average-cost markov decision process routing games. In 2017 IEEE 20th International Conference on Intelligent Transportation Systems (ITSC) (2017), IEEE, pp. 1–6 doi: https://doi.org/10.1109/ITSC.2017.8317849 pdf: https://danjcalderone.github.io/papers/mdproutinginf.pdf
- 3. Li, S. H., Yu, Y., Calderone, D., Ratliff, L., and Açrkmeşe, B. Tolling for constraint satisfaction in markov decision process congestion games. In 2019 American Control Conference (ACC) (2019), IEEE, pp. 1238–1243 doi: https://doi.org/0.23919/ACC.2019.8814925 pdf: https://danjcalderone.github.io/papers/mdptolling.pdf
- 4. Li, S. H., Yu, Y., Miguel, N., Calderone, D., Ratliff, L. J., and Acikmese, B. Adaptive constraint satisfaction for markov decision process congestion games: Application to transportation networks. arXiv preprint arXiv:1907.08912 (2019)

pdf: https://danjcalderone.github.io/papers/mdpconstraints.pdf

5. Li, S. H., Calderone, D., and Acikmese, B. Congestion-aware motion planning game with markov decision process dynamics. arXiv preprint arXiv:2203.12133 (2022)

doi: https://doi.org/10.48550/arXiv.2203.12133

pdf: https://danjcalderone.github.io/papers/mdpcoordination.pdf

6. Yu, Y., Calderone, D., Li, S. H., Ratliff, L. J., and Açıkmeşe, B. Variable demand and multi-commodity flow in markovian network equilibrium. *Automatica* 140 (2022), 110224

doi: https://doi.org/

pdf: https://danjcalderone.github.io/papers/mdpalgorithms.pdf

Continuous-Type Population Games **Overview:** Developed equilibrium concept and potential function for population games with preferences modeled as multi-dimensional mass distribution.

Applications: general non-homogeneous population preferences, transportation choice problems.

Papers:

1. Calderone, D., and Ratliff, L. J. Multi-dimensional continuous type population potential games. In 2019 IEEE 58th Conference on Decision and Control (CDC) (2019), IEEE, pp. 5138–5143

doi: https://doi.org/10.1109/CDC40024.2019.9029519

pdf: https://danjcalderone.github.io/papers/continoustypemd.pdf

2. Calderone, D., Dong, R., and Sastry, S. S. External-cost continuous-type wardrop equilibria in routing games. In 2017 IEEE 20th International Conference on Intelligent Transportation Systems (ITSC) (2017), IEEE, pp. 1–6

doi: https://doi.org/10.1109/ITSC.2017.8317866

pdf: https://danjcalderone.github.io/papers/continoustype2d.pdf

Braess Paradox: Algebraic Description

Overview: Obtained algebraic characterization of Braess paradox in routing games and MDP congestion games.

Papers:

1. Li, S. H., Calderone, D., Ratliff, L., and Açıkmeşe, B. Sensitivity analysis for markov decision process congestion games. In 2019 IEEE 58th Conference on Decision and Control (CDC) (2019), IEEE, pp. 1301–1306 doi: https://doi.org/10.1109/CDC40024.2019.9028933

pdf: https://danjcalderone.github.io/papers/mdpsensitivity.pdf

Stability of Game Learning Dynamics

Overview: Stability of gradient play in continuous-action two-player games. Applications: learning in neural networks, generative-adversarial networks, multiagent optimization

Papers:

1. Chasnov, B. J., Calderone, D., Açıkmeşe, B., Burden, S. A., and Ratliff, L. J. Stability of gradient learning dynamics in continuous games: Scalar action spaces. In 2020 59th IEEE Conference on Decision and Control (CDC) (2020), IEEE, pp. 3543–3548

doi: https://doi.org/10.1109/CDC42340.2020.9304165

pdf: https://danjcalderone.github.io/papers/stablescalar.pdf

Parking Routing Games

Overview: Formulated a version of routing games where agents consider street

parking choice as well as travel time. **Applications:** urban street parking

Papers:

1. Calderone, D., Mazumdar, E., Ratliff, L. J., and Sastry, S. S. Understanding the impact of parking on urban mobility via routing games on queue-flow networks. In 2016 IEEE 55th Conference on Decision and Control (CDC) (2016), IEEE, pp. 7605–7610

doi: https://doi.org/10.1109/CDC.2016.7799444

pdf: https://danjcalderone.github.io/papers/parkingrouting.pdf

Other Projects

Papers:

- CALDERONE, D. J., RATLIFF, L. J., AND SASTRY, S. S. Lane pricing via decision-theoretic lane changing model of driver behavior. In 2015 54th IEEE Conference on Decision and Control (CDC) (2015), IEEE, pp. 3457–3462 doi: https://doi.org/10.1109/CDC.2015.7402754
- 2. Calderone, D., Ratliff, L. J., and Sastry, S. S. Pricing for coordination in open-loop differential games. *IFAC Proceedings Volumes* 47, 3 (2014), 9001–9006

doi: https://doi.org/10.3182/20140824-6-ZA-1003.02655

3. Calderone, D., Ratliff, L. J., and Sastry, S. S. Pricing for coordination in open-loop differential games. *IFAC Proceedings Volumes* 47, 3 (2014), 9001–9006

doi: https://doi.org/10.3182/20140824-6-ZA-1003.02655

- 4. Calderone, D., Ratliff, L., and Sastry, S. Pricing design for robustness in linear-quadratic dynamic games. In *In the Proceedings of the 52rd Annual IEEE Conference on Decision and Control* (2013) doi: https://doi.org/10.1109/CDC.2013.6760558
- 5. Coogan, S., Ratliff, L. J., Calderone, D., Tomlin, C., and Sastry, S. S. Energy management via pricing in lq dynamic games. In 2013 American Control Conference (2013), IEEE, pp. 443–448 doi: https://doi.org/10.1109/ACC.2013.6579877
- 6. Ratliff, L. J., Coogan, S., Calderone, D., and Sastry, S. S. Pricing in linear-quadratic dynamic games. In 2012 50th Annual Allerton Conference on Communication, Control, and Computing (Allerton) (2012), IEEE, pp. 1798–1805

doi: https://doi.org/10.1109/Allerton.2012.6483440

Teaching

Online Content

Summary: I am developing a collection of interactive visualizations for an online textbook teaching linear algebra, optimization, and other subjects.

WEBSITE: (under construction) https://danjcalderone.github.io/dcmath/

Select Examples—

Hypershapes https://danjcalderone.github.io/dcmath/linalg/hypershapes
Matrices https://danjcalderone.github.io/dcmath/linalg/matrices
Inner Products https://danjcalderone.github.io/dcmath/linalg/innerproducts
Matrix Products https://danjcalderone.github.io/dcmath/linalg/matrixmultiply

Inverses https://danjcalderone.github.io/dcmath/linalg/inverses

COURSES

Materials: https://danjcalderone.github.io/teaching.html

Linear Algebra/

Courses: AA510, AE510

Linear Systems

Offerings: Winter 2020, Fall 2020, Winter 2021, Winter 2020

Level: Masters/PhD Role: Instructor Select Topics:

Vectors, inner products, linear transforms/ matrices, range/nullspace, rank, Gaussian elimination, matrix inverses, systems of equations, coordinates, similarity, eigen-problem/ diagonalization, spectral mapping, Cayley Hamilton, state-space, LTI/LTV systems, transfer functions, controllability/ observability, canonical forms, pole-placement, observer design, separation principle, Grammians, SVD/ polar

SISO Control

Courses: AA447

Offerings: Spring 2021 Level: Undergraduate Role: Instructor

Topics:

Time/ frequency domains, Laplace transforms, transfer functions, impulse response, block diagrams, PI/PID control, disturbance rejection, internal model principle, Bode/Nyquist-plots, Nyquist stability, gain/phase/stability margins, loop

shaping.

MIMO Control

Courses: AE513

Offerings: Fall 2019, Fall 2021

Level: Masters Role: Instructor

Topics:

Dynamical systems, linearization, open-loop and feedback control, PD matrices, Lyapunov theory/equations, Grammians, dynamic programming/ Bellman equation, LQR (DT / CT, fin / inf horizon), Riccati ODE/ ARE Hamiltonian systems, adjoint method for optimal control, intro to Kalman filter, LQG control.

Robust Control

Courses: AA594

Offerings: Winter 2022

Level: PhD

Role: Instructor

Topics:

Estimation Courses: AA549,AE514

Offerings: Spring 2019, Fall 2020, Spring 2021

Level: Masters/PhD Role: Instructor

Topics:

Positive definite matrices, basic probability, multivariate Gaussians, covariance matrices, basis functions, weighted least squares, nonlinear least squares, maximum likelihood estimation (MLE), maximum a-posteriori estimation (MAP), Kalman filter (CT / DT), extended Kalman filter, unscented Kalman filter, particle filters

Convex Optimization Courses: AA578

Offerings: Winter 2021

Level: Masters/PhD Role: Instructor

Topics:

Linear transformations of sets, affine sets - range and null space representations, inequality constraints, polytopes, slack variables, linear programs (LP), quadratic programs (QP) Lagrange multipliers, vector space duality, Lagrangian duality - game interpretation LP / QP duality, primal and dual visual interpretations, KKT conditions, complementary slackness, simplex algorithm, gradient descent, Newton's method, barrier methods, interior point methods.

Network Dynamics Courses: AA597

Offerings: Spring 2022

Level: Masters/PhD Role: Instructor

Topics:

Undirected/ directed graphs, matrices (incidence/ adjacency/ Laplacian), matrix decompositions, Laplacian spectra, agreement protocol (undirected/ directed, CT/DT), distributed estimation, distributed optimization, formation control, input/output controllability/ observability.

Statics

Courses: AA210

Offerings: Spring 2022 Level: Undergraduate

Role: Instructor

Topics:

Free body diagrams, forces/moments/couples, distributed loads, rigid body equilibrium, static determinancy, truss methods (joints/sections), zero-force members, space-trusses, frames/machines, cables/arches,retaining walls, friction, centers of mass/ centroids, moments of inertia, Mohr's circle, shear/ bending moment diagrams.

Robotic Courses: EE125 (UCB)
Manipulators Offerings: Fall 2013

Level: Undergraduate Role: Teaching Assistant

Responsibilities: Lectured in discussion section, designed homeworks, designed &

implemented labs

Topics:

Coordinate transformations, rotations, skew-symmetric matrix exponential, homogeneous transformations, inverting coordinate transforms, Lie groups and lie algebras, SO(3)/so(3), SE(3)/se(3), joint transformations, product of exponentials, forward kinematics, inverse kinematics via Paden-Kahn subproblems, Lagrangian

dynamics formulation Courses: EE16A (UCB)

EE Intro Survey Course

Offerings: Fall 2015 Level: Undergraduate Role: Teaching Assistant

Responsibilities: Lead content team (of 15 TAs) designing homeworks

Industry/Work Experience

eBay Advertising Role: Internship

Dates: May-Dec 2014

Description: Developed regression models for predicting the impact of advertising

on eBay sales

Army Role: Internship
Research Dates: May-Aug 2009

Lab Description: Investigated biological systems for low power communications in small

robotic platforms.

Johns Hopkins Role: Internship Applied Dates: May-Aug 2008

Physics Lab Description: Finite element modeling of human torso for studying blast trauma.

Alfred Gessow Role: Internship Rotorcraft Dates: May-Aug 2007

Center (UMD) Description: Assisted with fabrication of experimental helicopter rotors for hover-

stand test.

OUTREACH EXPERIENCE

EE-Graduate Dates: May 2013-Fall 2016

Outreach Description: Develop and presented engineering interest talks at elementary, mid-

Program (UCB) dle, and high schools.

Dates: Sept 2013-Spring 2014 EEGSA (UCB)

Description: Organized social and outreach events for UCB graduate student or-Co-President

ganization.

EEGSA (UCB) Dates: March 2013

Visit-Day Description: Lead team of ten students in assigning mentors, organizing accommo-Coordinator

dations, and planning social events for new students during recruitment weekend.

Resident Dates: Aug 2008–Spring 2010

Assistant (UMD) Description: Developed community, planned educational events, maintained secu-

> rity, enforced policies, and provided personal support for 70 freshman on a residence hall floor. Voted RA of the Year for 2009-2010 by the fifteen other RA's in

the residence hall.

Student Honor Dates: Aug 2007–Spring 2008

Council (UMD) Description: Promoted the academic integrity of the university by educating stu-

dents and adjudicating cases of academic dishonesty.

January 13, 2023