

Graph Structures & Matrices

Algebraic Graph Theory

Acknowledgements: Mehran Mesbahi
Mathias Colbert Russelson,
Sarah Li
Shahriar Talebi

Spring 2022 - Dan Calderone

Graphs

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

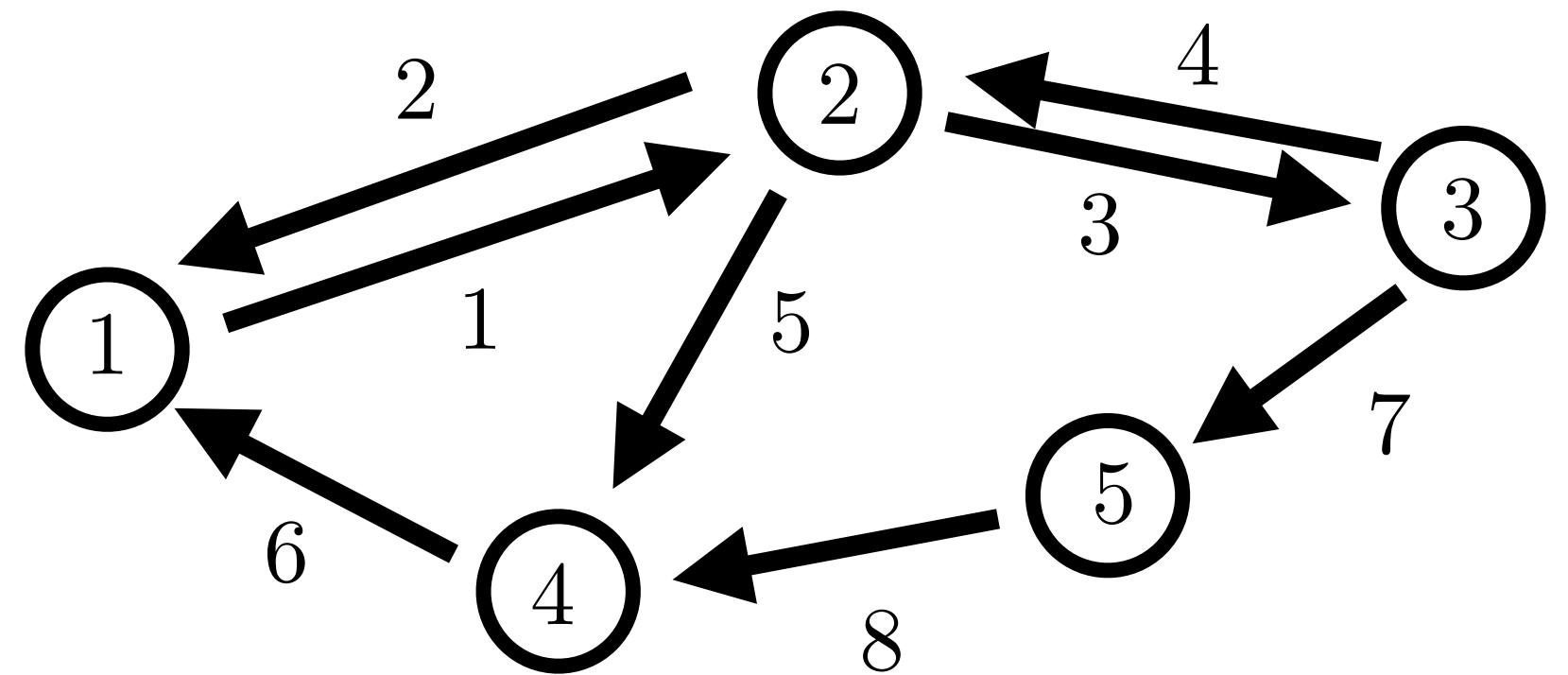
Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$



Graphs

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

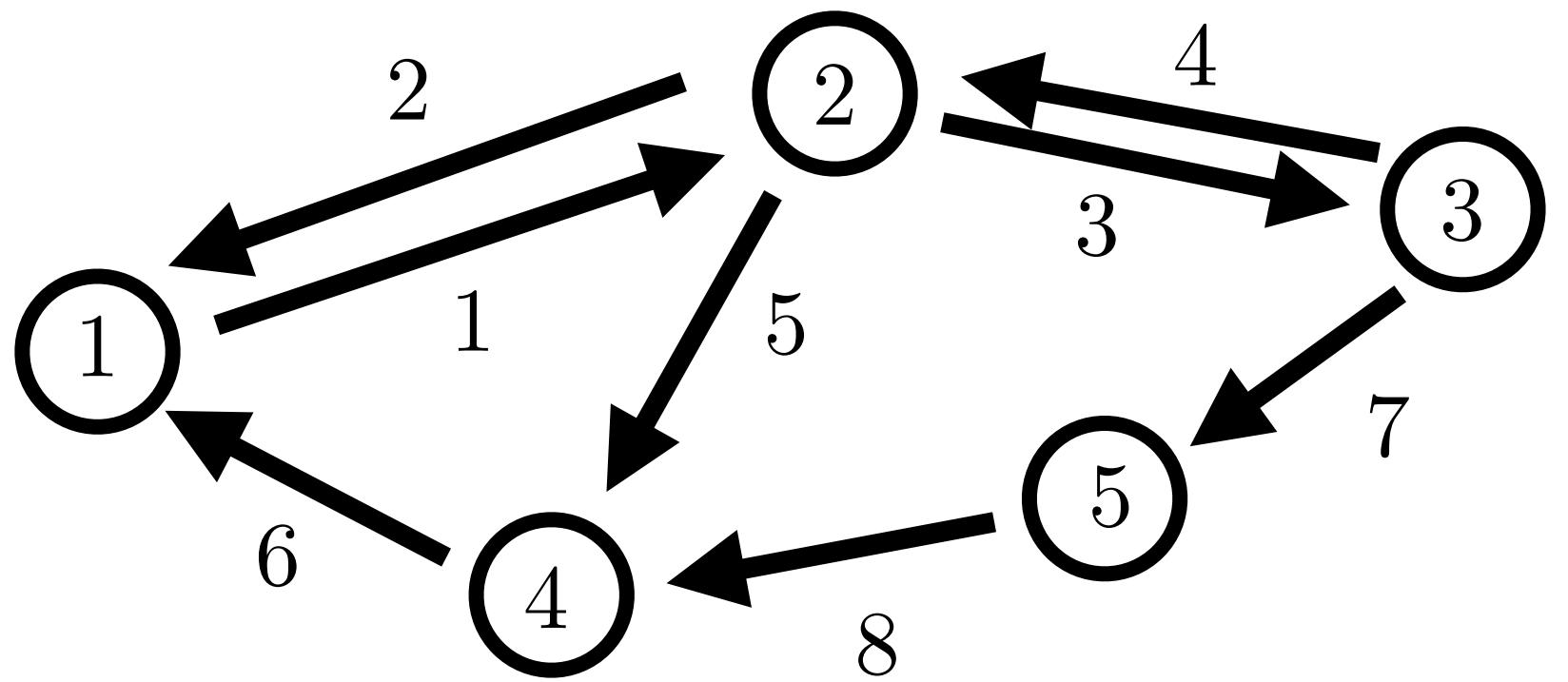
Directed or Undirected Edges

$$e = (v, v') \quad \text{edge } e \text{ is "incident" to } v \text{ and } v'$$

Neighborhoods: set of "adjacent" nodes

$$\mathcal{N}_v = \{v' \in \mathcal{V} \mid e = (v, v') \in \mathcal{E}\}$$

(degree of vertex) $d_v = |\mathcal{N}_v|$



Incidence Matrix

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

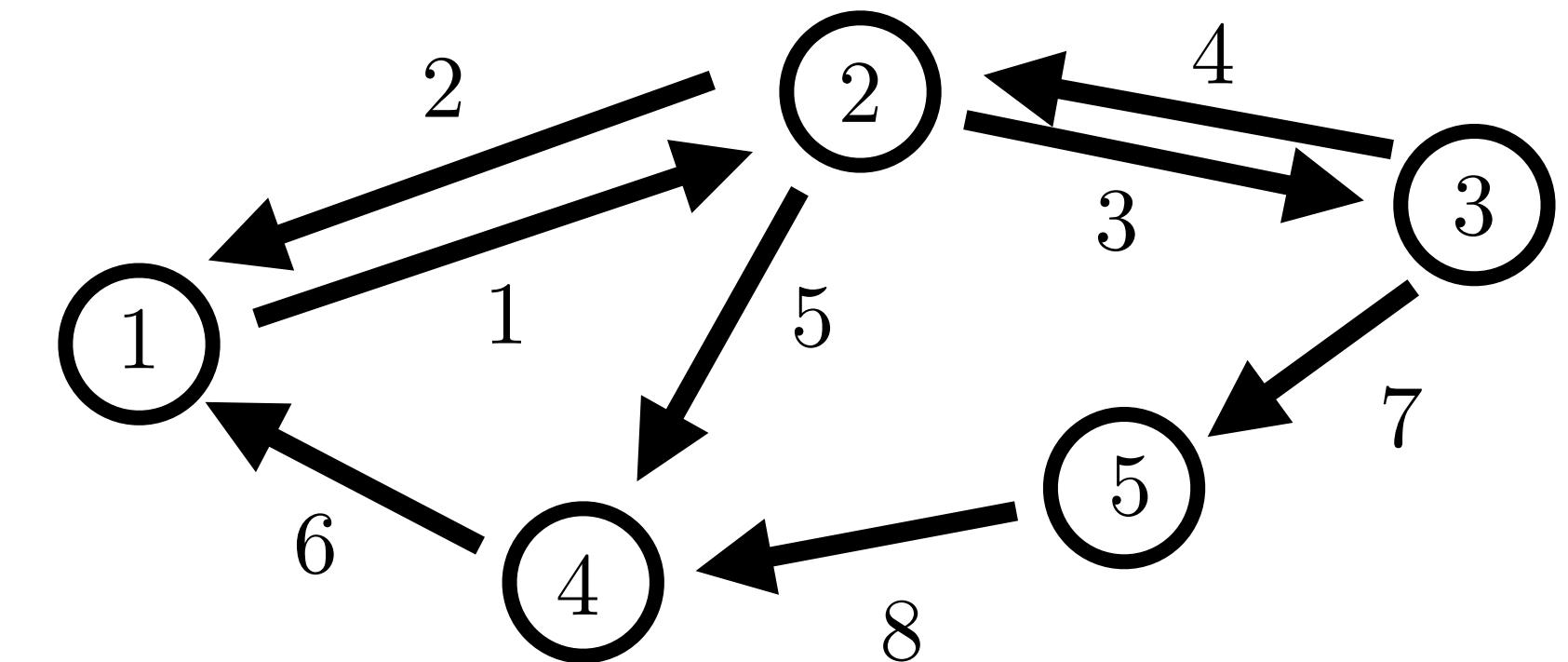
$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$D = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix}$$

edges \longleftrightarrow

vertices ↑ ↓



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Incidence Matrix

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E}) \quad \begin{array}{l} \text{Vertices} \\ v \in \mathcal{V} \end{array} \quad \begin{array}{l} \text{Edges} \\ e \in \mathcal{E} \end{array} \quad \begin{array}{l} e = (v, v') \end{array}$$

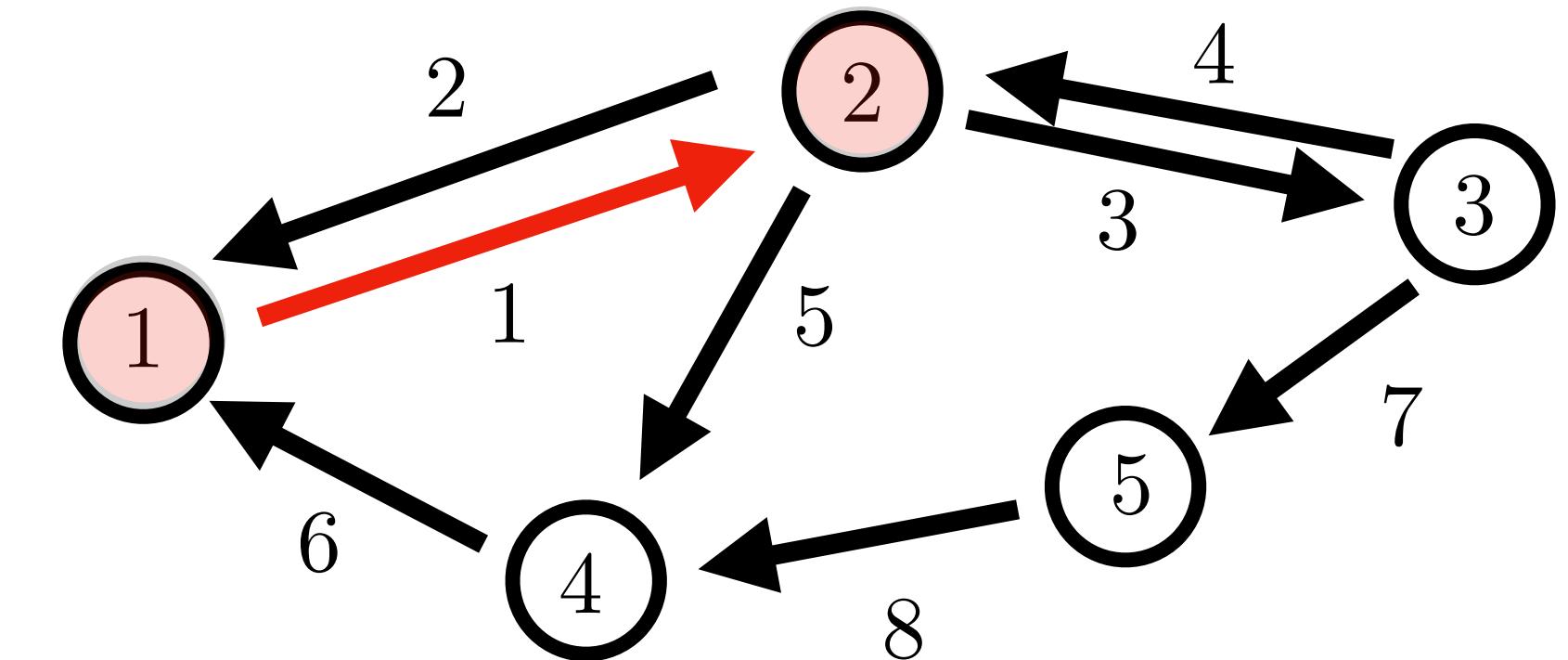
Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$D = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \quad \begin{array}{c} \xleftarrow{\hspace{1cm}} \text{edges} \xrightarrow{\hspace{1cm}} \\ \uparrow \quad \downarrow \\ \text{vertices} \end{array}$$



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Incidence Matrix

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E}) \quad \begin{array}{l} \text{Vertices} \\ v \in \mathcal{V} \end{array} \quad \begin{array}{l} \text{Edges} \\ e \in \mathcal{E} \end{array} \quad \begin{array}{l} e = (v, v') \end{array}$$

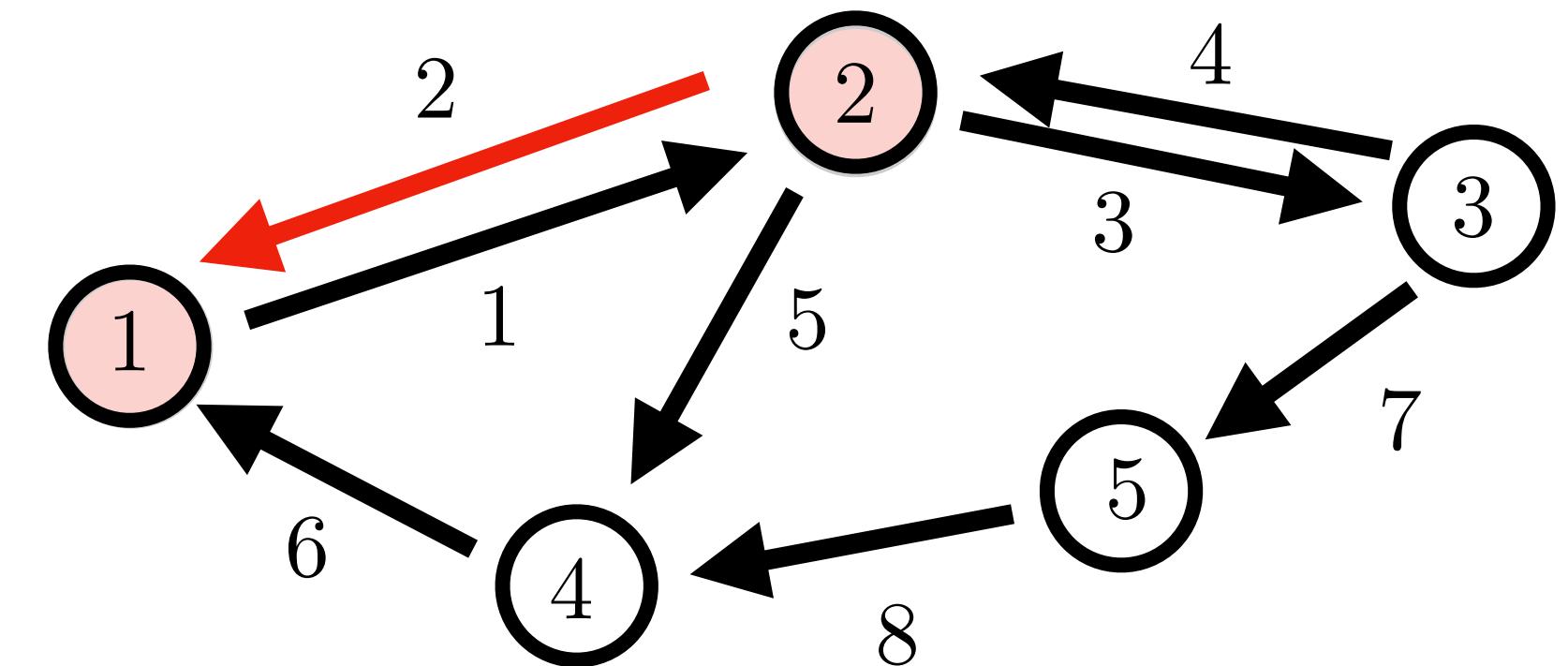
Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$D = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & -1 & 0 \end{bmatrix} \quad \begin{array}{c} \xleftarrow{\hspace{1cm}} \text{edges} \xrightarrow{\hspace{1cm}} \\ \uparrow \quad \downarrow \\ \text{vertices} \end{array}$$



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Incidence Matrix

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E}) \quad \begin{array}{l} \text{Vertices} \\ v \in \mathcal{V} \end{array} \quad \begin{array}{l} \text{Edges} \\ e \in \mathcal{E} \end{array} \quad \begin{array}{l} e = (v, v') \end{array}$$

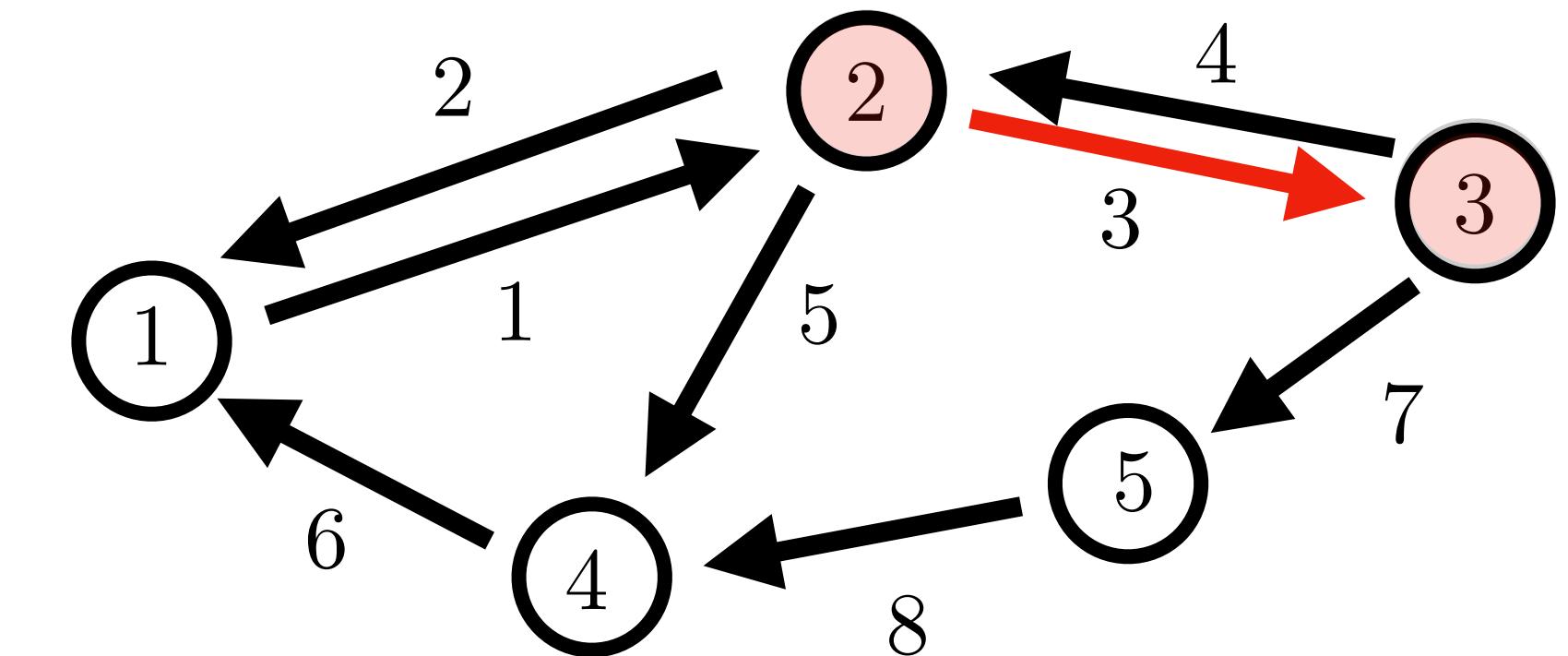
Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$D = \begin{bmatrix} -1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \quad \begin{array}{c} \xleftarrow{\hspace{1cm}} \text{edges} \xrightarrow{\hspace{1cm}} \\ \uparrow \quad \downarrow \\ \text{vertices} \end{array}$$



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Incidence Matrix

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E}) \quad \begin{array}{l} \text{Vertices} \\ v \in \mathcal{V} \end{array} \quad \begin{array}{l} \text{Edges} \\ e \in \mathcal{E} \end{array} \quad \begin{array}{l} e = (v, v') \end{array}$$

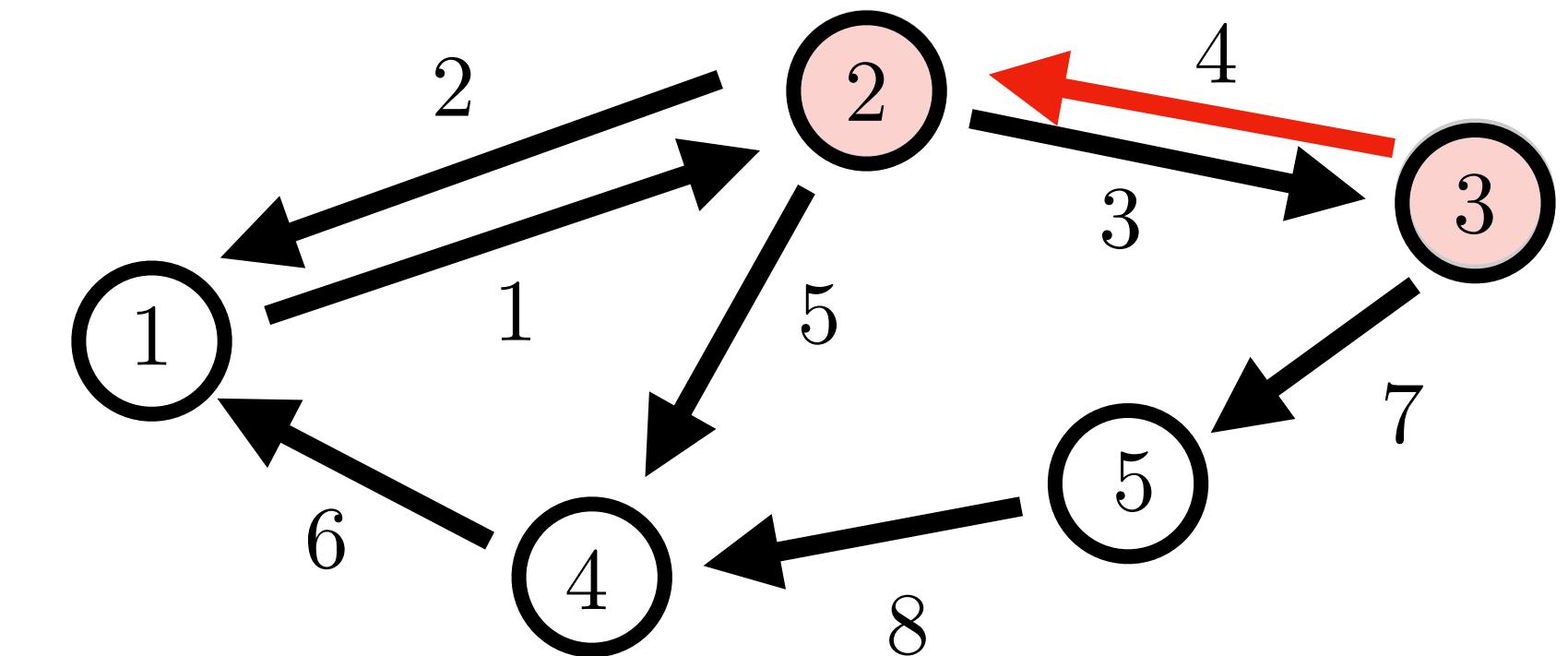
Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$D = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \quad \begin{array}{c} \xleftarrow{\text{edges}} \\ \uparrow \\ \text{vertices} \\ \downarrow \end{array}$$



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \end{bmatrix}$$

Incidence Matrix

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

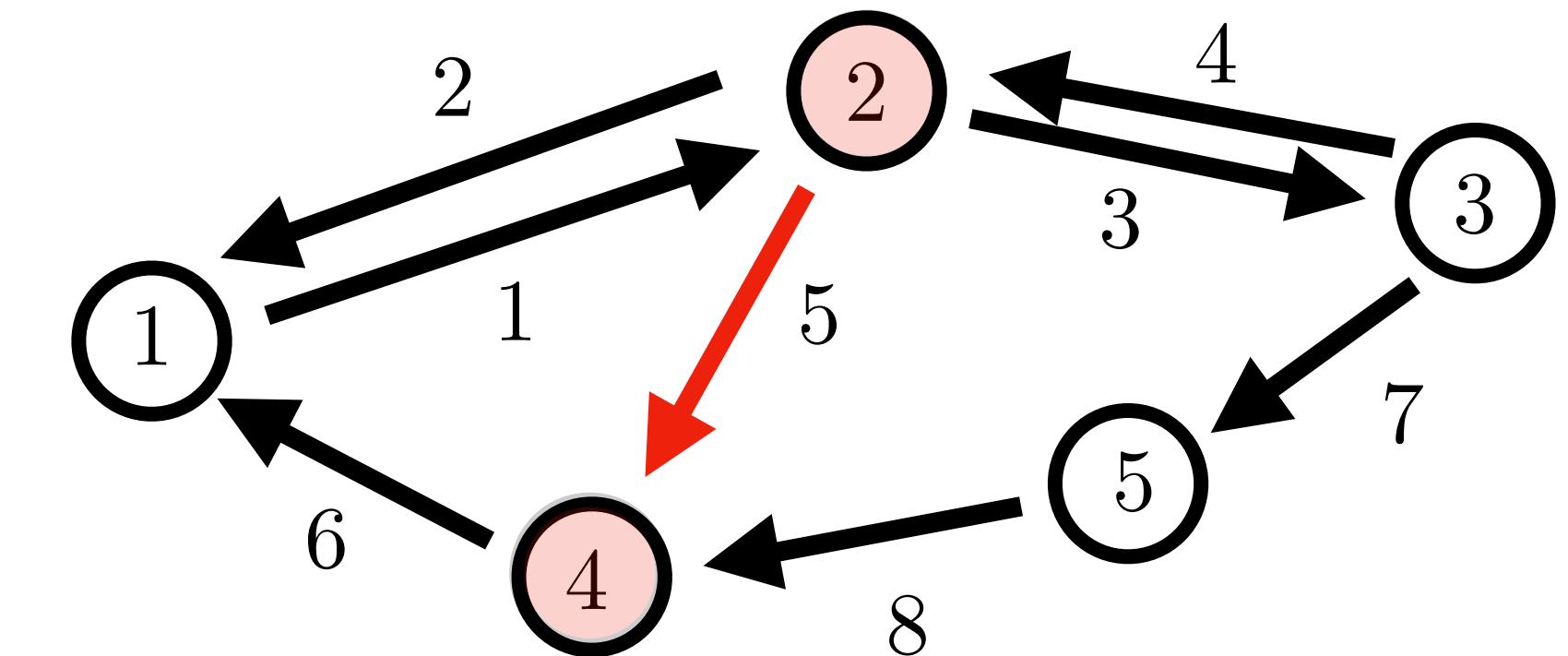
$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$D = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix}$$

edges \longleftrightarrow vertices



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Incidence Matrix

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

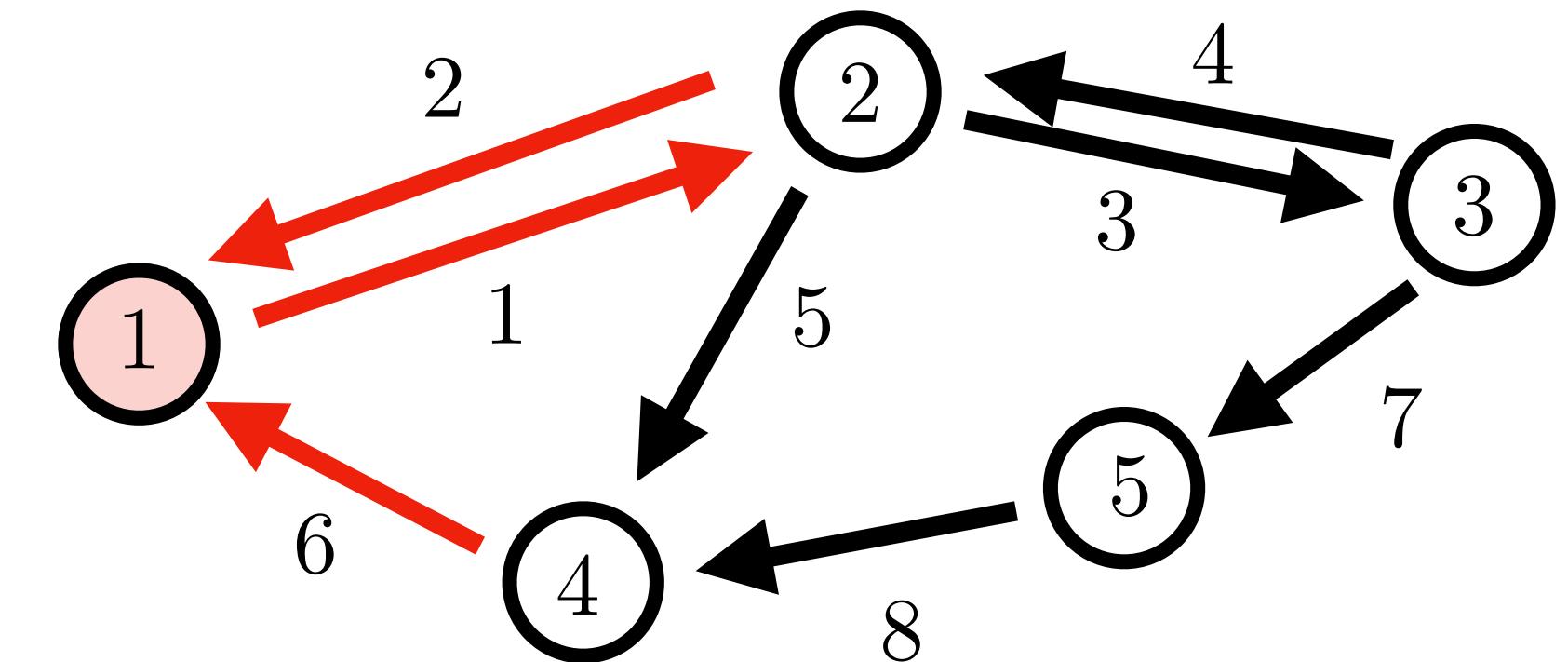
$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$D = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix}$$

edges \longleftrightarrow

vertices \uparrow



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Incidence Matrix

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E}) \quad \begin{array}{l} \text{Vertices} \\ v \in \mathcal{V} \end{array} \quad \begin{array}{l} \text{Edges} \\ e \in \mathcal{E} \end{array} \quad \begin{array}{l} e = (v, v') \end{array}$$

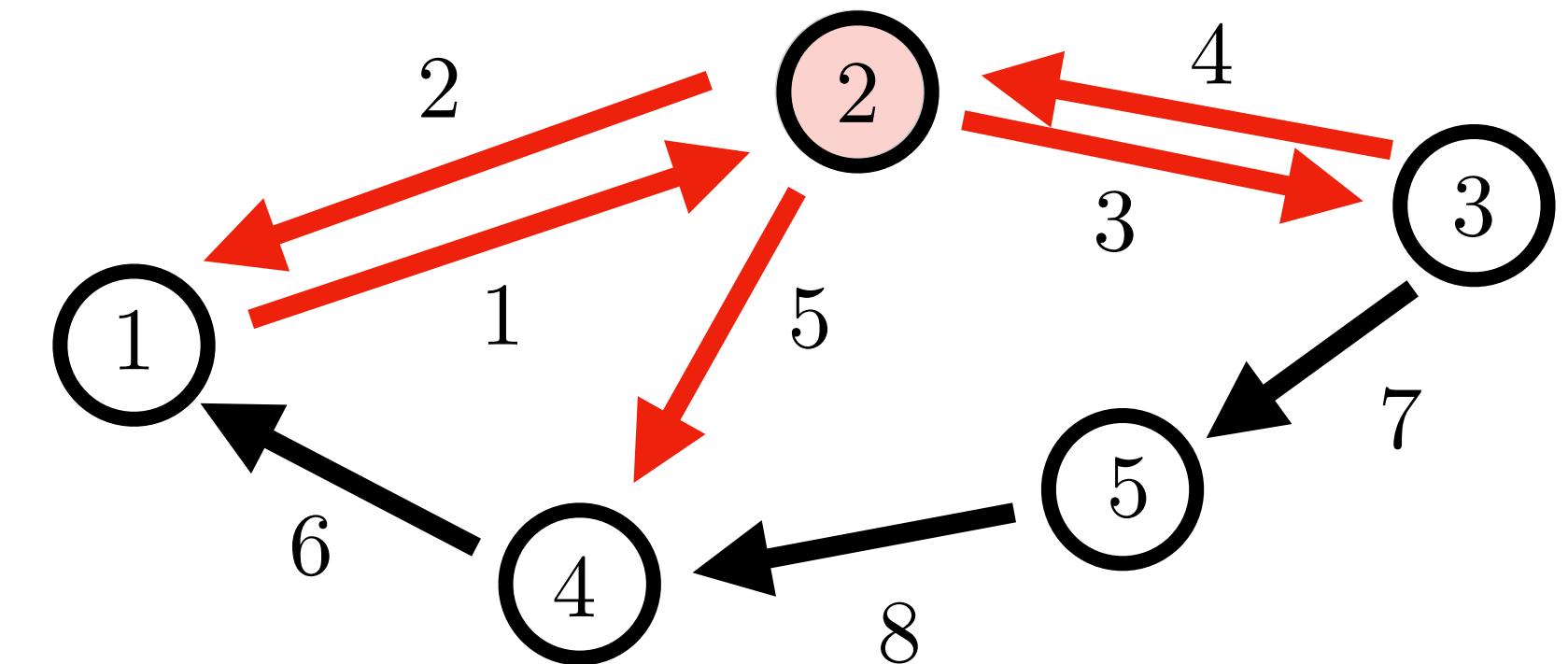
Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$D = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \quad \begin{array}{c} \xleftarrow{\hspace{1cm}} \text{edges} \xrightarrow{\hspace{1cm}} \\ \uparrow \qquad \downarrow \\ \text{vertices} \end{array}$$



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Incidence Matrix

Graph:

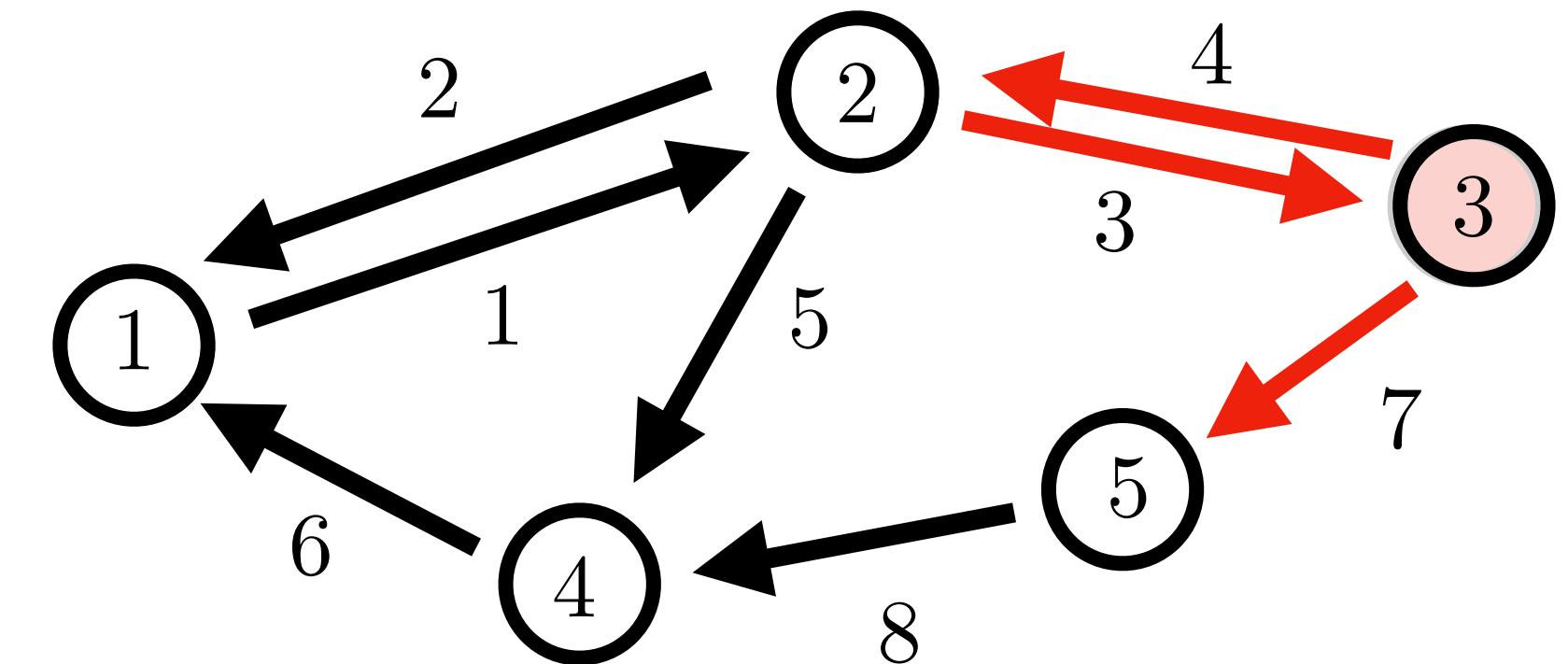
$$\mathcal{G} = (\mathcal{V}, \mathcal{E}) \quad \begin{array}{l} \text{Vertices} \\ v \in \mathcal{V} \end{array} \quad \begin{array}{l} \text{Edges} \\ e \in \mathcal{E} \end{array} \quad e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases} \quad [D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$D = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \quad \begin{array}{c} \xleftarrow{\hspace{1cm}} \text{edges} \xrightarrow{\hspace{1cm}} \\ \uparrow \quad \downarrow \\ \text{vertices} \end{array}$$



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Incidence Matrix

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E}) \quad \begin{array}{l} \text{Vertices} \\ v \in \mathcal{V} \end{array} \quad \begin{array}{l} \text{Edges} \\ e \in \mathcal{E} \end{array} \quad \begin{array}{l} e = (v, v') \end{array}$$

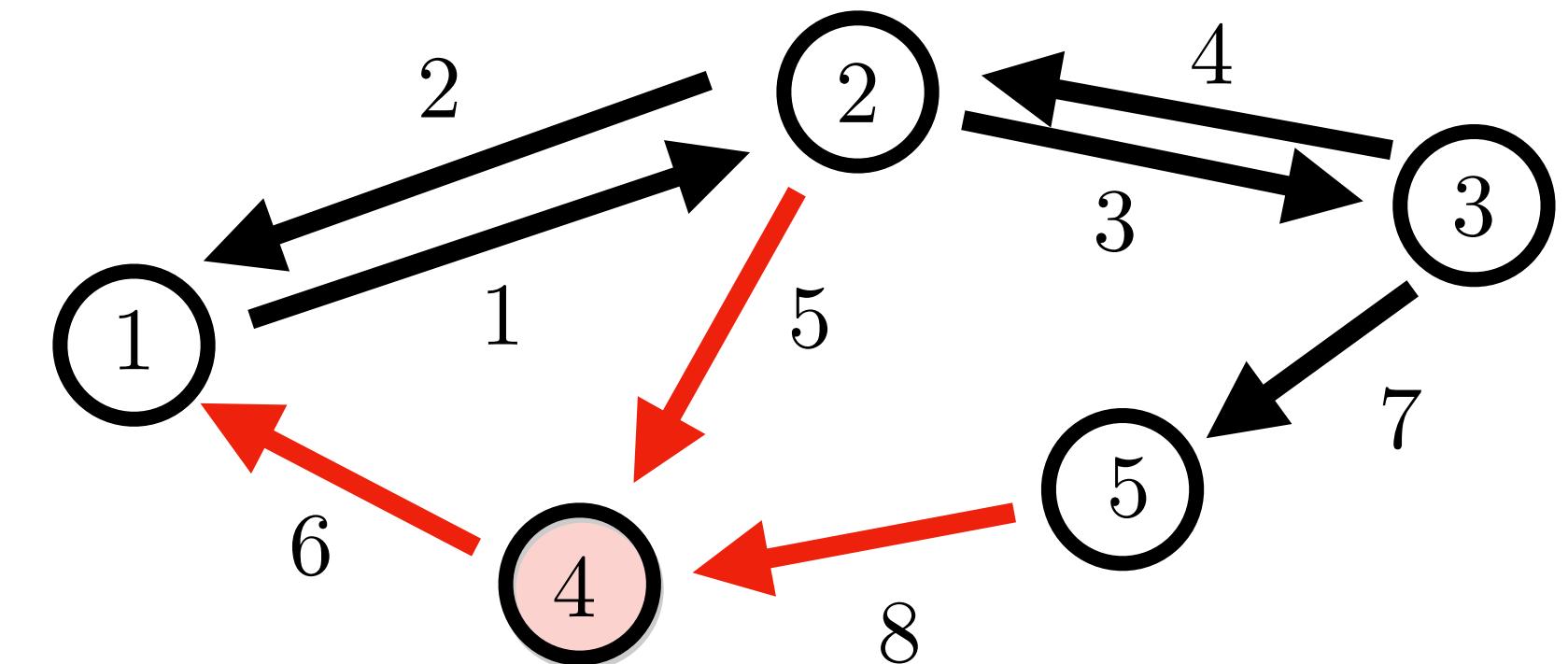
Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$D = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \quad \begin{array}{c} \xleftarrow{\hspace{1cm}} \text{edges} \xrightarrow{\hspace{1cm}} \\ \uparrow \quad \downarrow \\ \text{vertices} \end{array}$$



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Incidence Matrix - Left Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

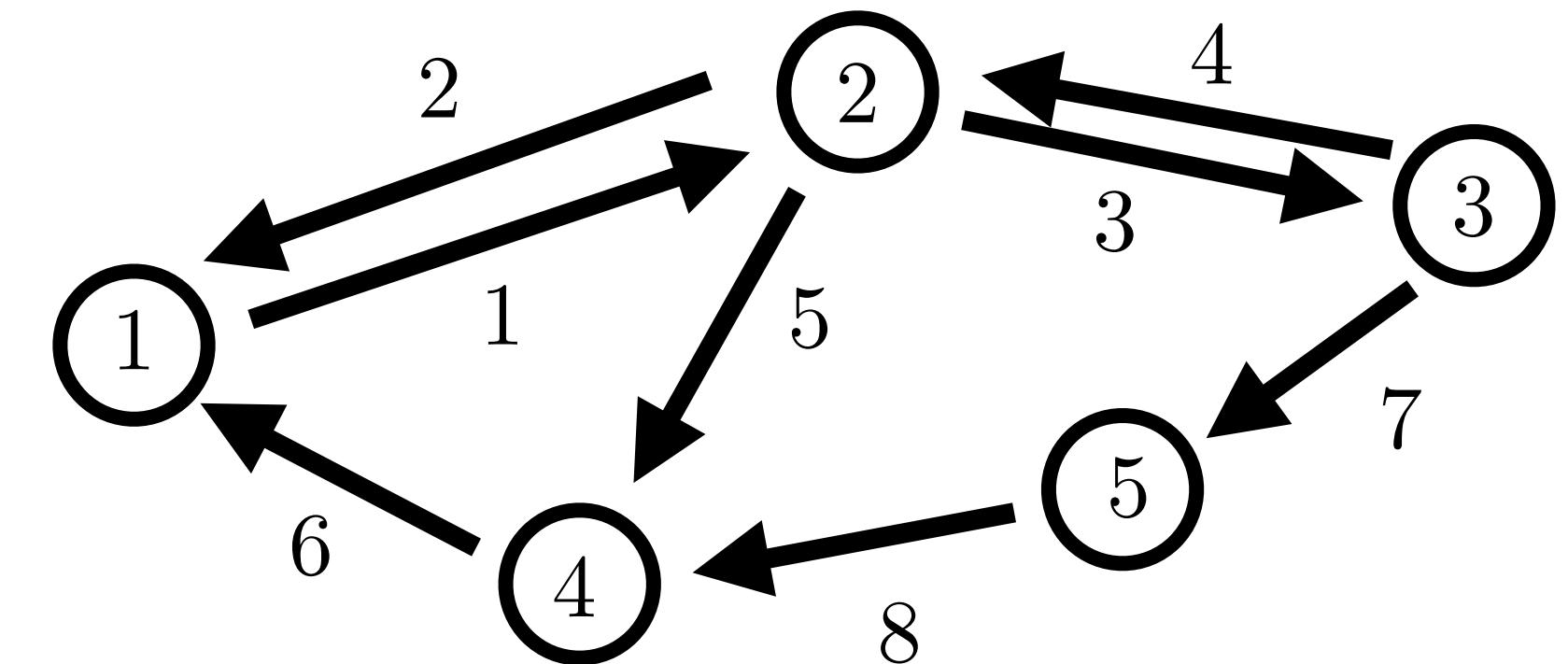
$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[1 \ 1 \ 1 \ 1 \ 1] \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} = \mathbf{0}$$

Left
Nullspace

$$1^T D = 0$$



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Incidence Matrix - Left Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E} \quad e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

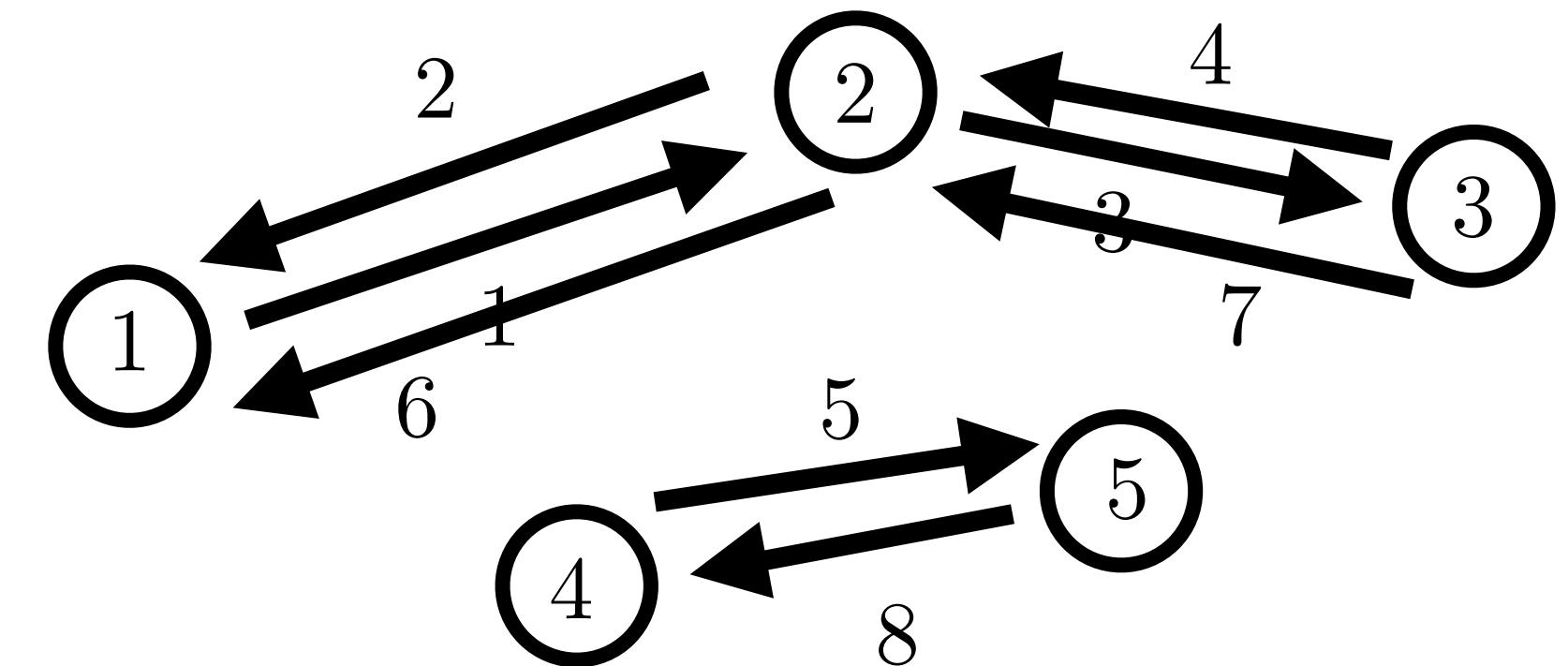
$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases} \quad [D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} -1 & 1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ \hline 0 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} = \mathbf{0}$$

Left
Nullspace

$$1^T D = 0$$



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Incidence Matrix - Left Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ out of } v \\ 0 & ; \text{ otherwise} \end{cases}$$

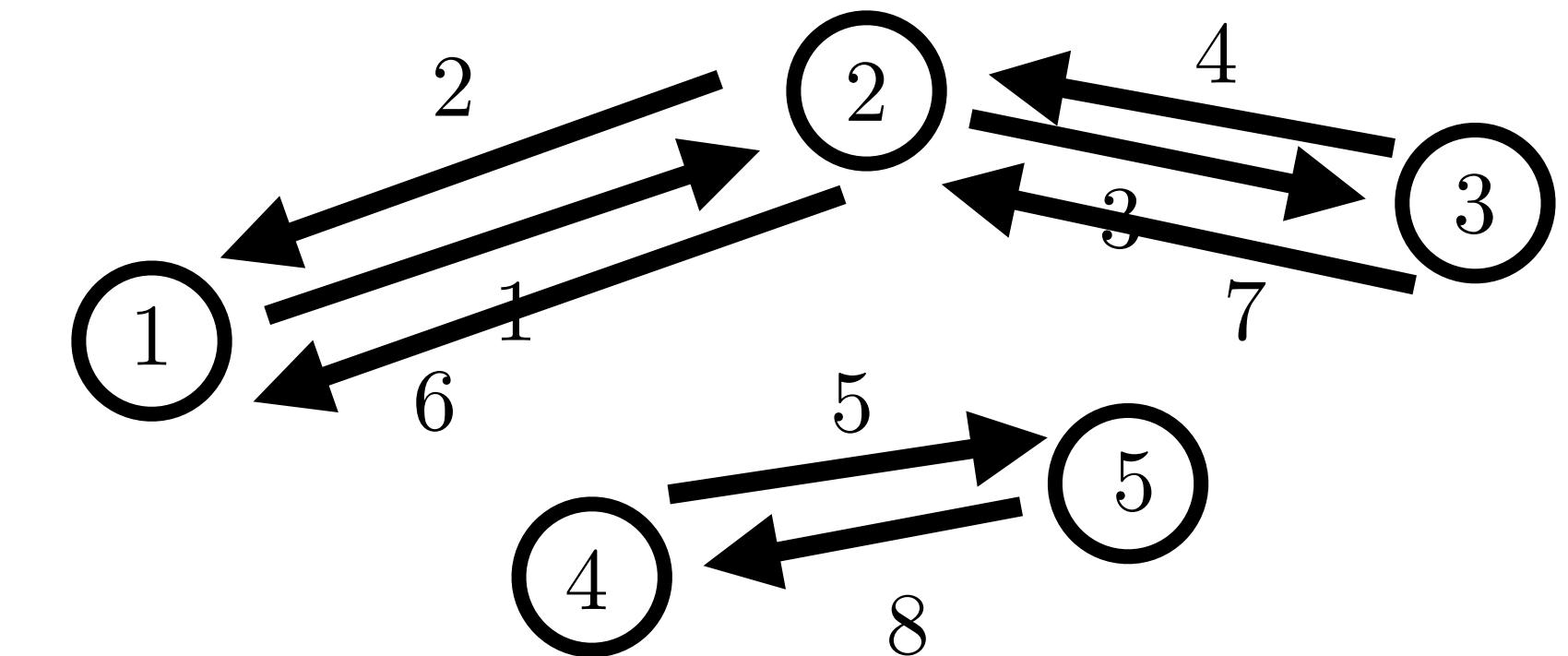
$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} -1 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & -1 \end{bmatrix} = \mathbf{0}$$

Left
Nullspace
(General)

$$\begin{bmatrix} \mathbf{1}^T & 0 & \dots & 0 \\ 0 & \mathbf{1}^T & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \mathbf{1}^T \end{bmatrix} \begin{bmatrix} D \end{bmatrix} = \mathbf{0}$$

dim left
nullspace
= num
connected
components



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix:

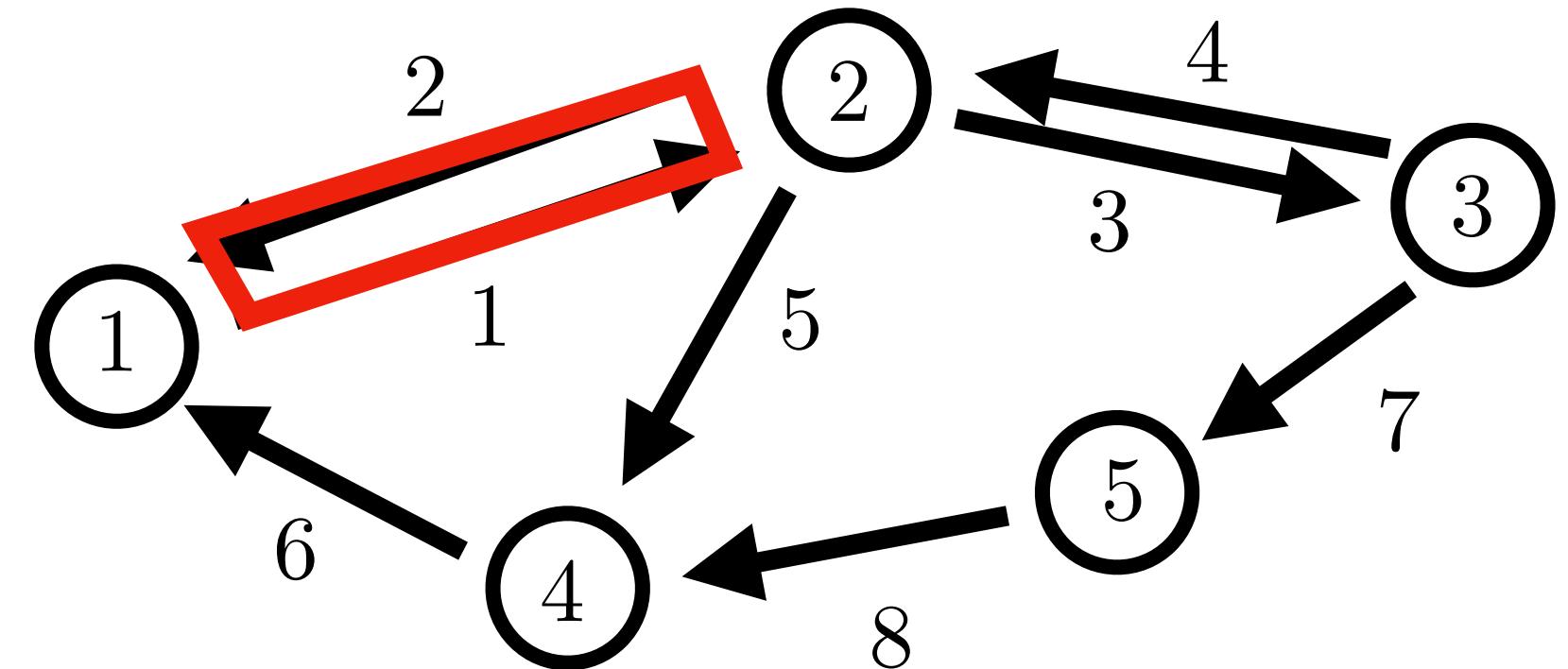
$$D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

edge mass flows →

ea. equation:
Conservation
of flow
at ea. node



Cycle indicator (basis) matrix:

$$[C]_{ec} = \begin{cases} 1 & ; \text{ if } e \text{ flows with cycle } c \\ -1 & ; \text{ if } e \text{ flows against cycle } c \\ 0 & ; e \text{ not in cycle } c \end{cases}$$

Right
Nullspace

$$DC = 0$$

Cycle space \mathcal{C}

$$\dim \mathcal{C} = |\mathcal{E}| - |\mathcal{V}| + 1$$

$$\text{Ex: } 8 - 5 + 1 = 4$$

$$C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Sign indicates
if cycle goes
with or against
edge direction

Columns =
basis for \mathcal{C}

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix:

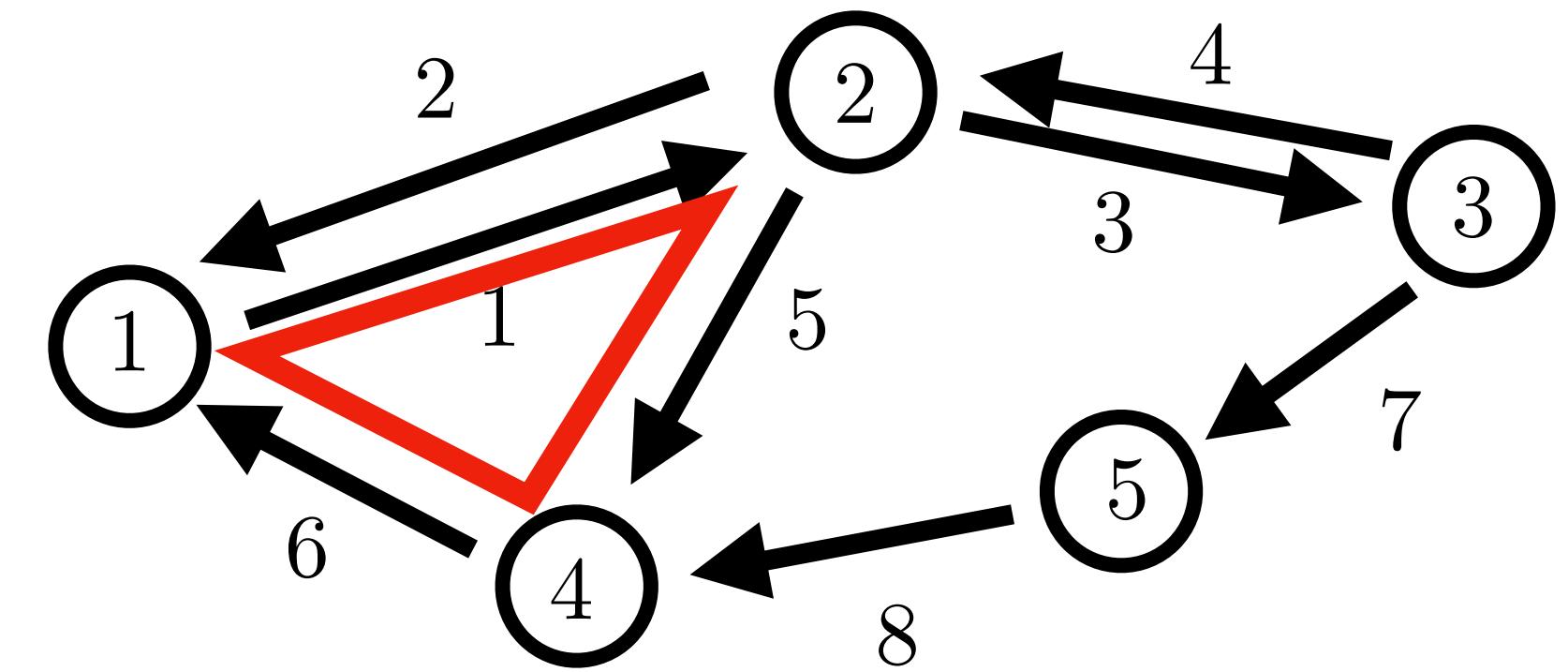
$$D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

edge mass flows →

ea. equation:
Conservation
of flow
at ea. node



Cycle indicator (basis) matrix:

$$[C]_{ec} = \begin{cases} 1 & ; \text{ if } e \text{ flows with cycle } c \\ -1 & ; \text{ if } e \text{ flows against cycle } c \\ 0 & ; e \text{ not in cycle } c \end{cases}$$

Right
Nullspace

$$DC = 0$$

Cycle space \mathcal{C}

$$\dim \mathcal{C} = |\mathcal{E}| - |\mathcal{V}| + 1$$

$$\text{Ex: } 8 - 5 + 1 = 4$$

$$C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

← Sign indicates
if cycle goes
with or against
edge direction

Columns =
basis for \mathcal{C}

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix:

$$D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

edge mass flows →

ea. equation:
Conservation
of flow
at ea. node

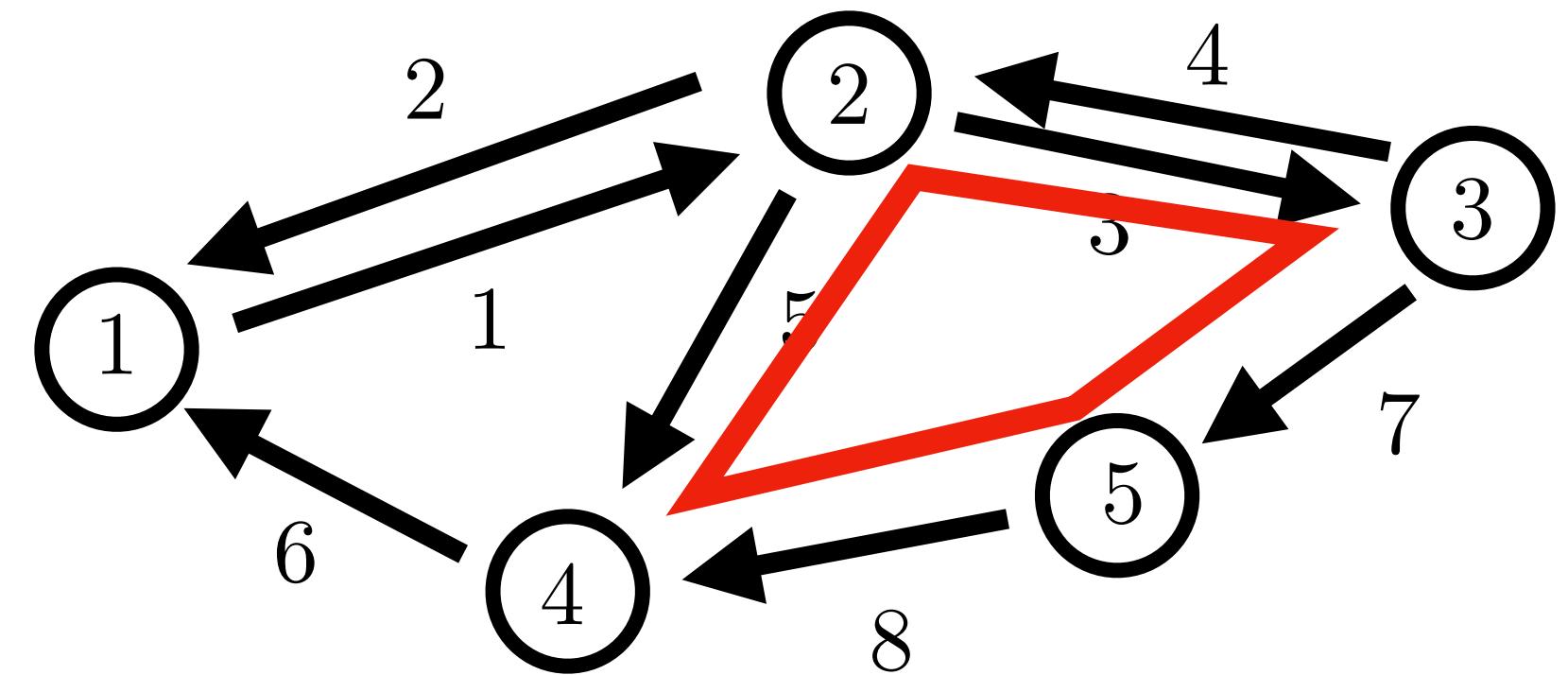
Right
Nullspace

$$DC = 0$$

Cycle space \mathcal{C}

$$\dim \mathcal{C} = |\mathcal{E}| - |\mathcal{V}| + 1$$

$$\text{Ex: } 8 - 5 + 1 = 4$$



Cycle indicator (basis) matrix:

$$[C]_{ec} = \begin{cases} 1 & ; \text{ if } e \text{ flows with cycle } c \\ -1 & ; \text{ if } e \text{ flows against cycle } c \\ 0 & ; e \text{ not in cycle } c \end{cases}$$

$$C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Sign indicates
if cycle goes
with or against
edge direction

Columns =
basis for \mathcal{C}

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix:

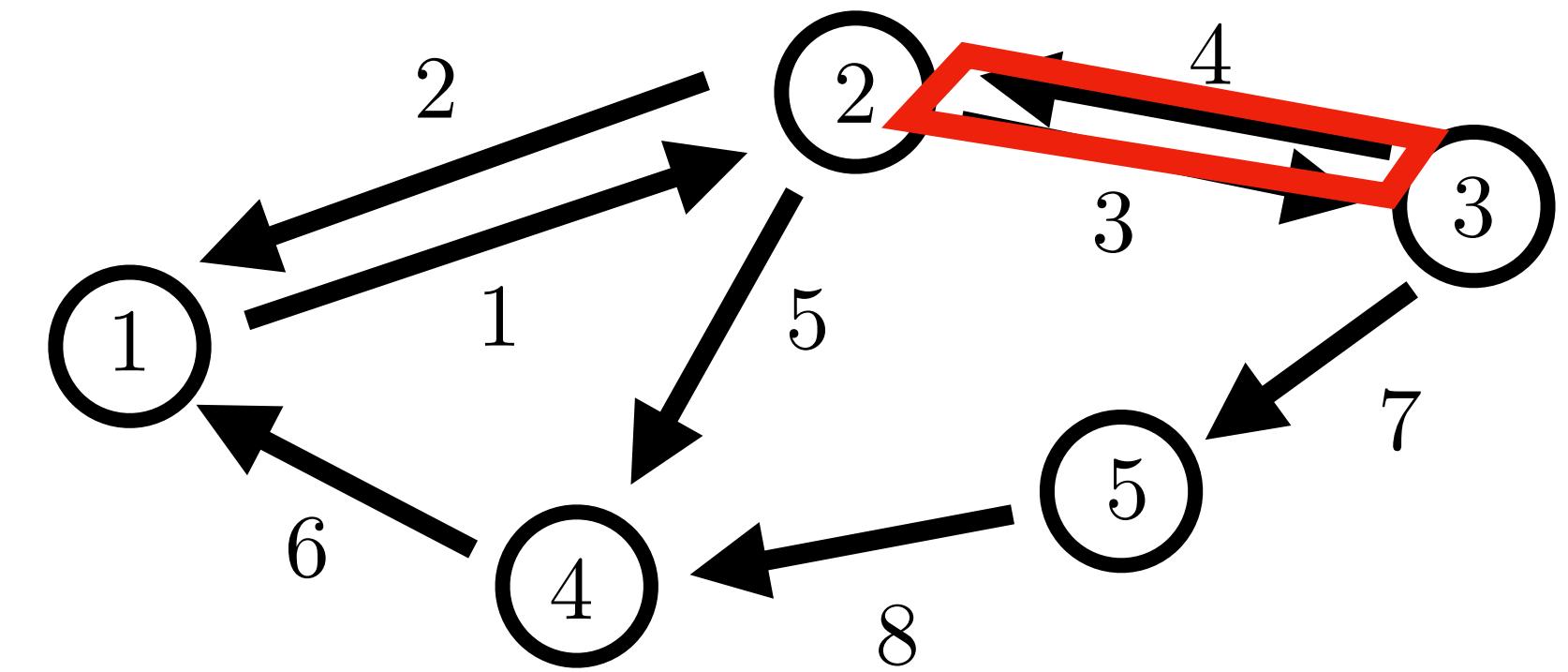
$$D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

edge mass flows →

ea. equation:
Conservation
of flow
at ea. node



Cycle indicator (basis) matrix:

$$[C]_{ec} = \begin{cases} 1 & ; \text{ if } e \text{ flows with cycle } c \\ -1 & ; \text{ if } e \text{ flows against cycle } c \\ 0 & ; e \text{ not in cycle } c \end{cases}$$

Right
Nullspace

$$DC = 0$$

Cycle space \mathcal{C}

$$\dim \mathcal{C} = |\mathcal{E}| - |\mathcal{V}| + 1$$

$$\text{Ex: } 8 - 5 + 1 = 4$$

$$C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Sign indicates
if cycle goes
with or against
edge direction

Columns =
basis for \mathcal{C}

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

edge mass flows →

ea. equation:
Conservation
of flow
at ea. node

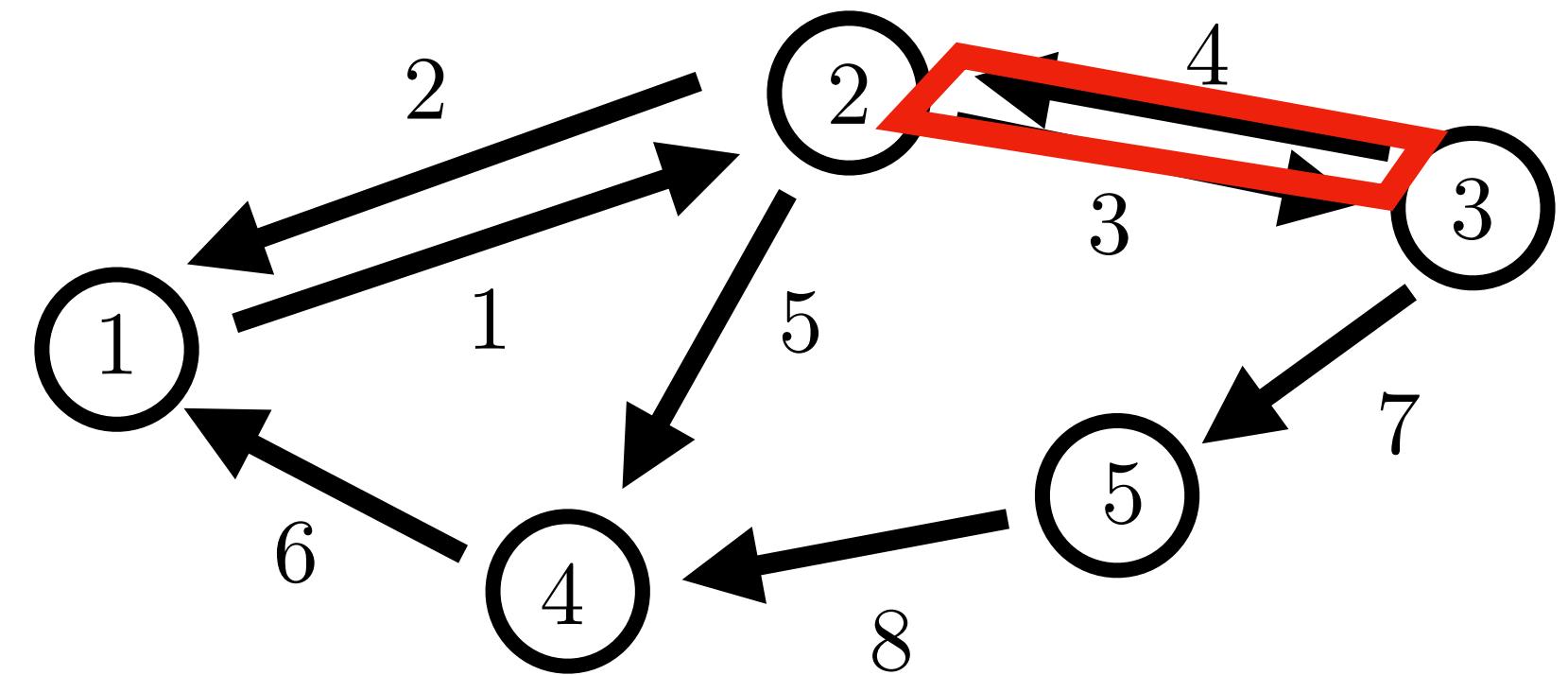
**Subspace
Constraint**

$$Dx = 0 \Rightarrow x = Cz$$

Cycle space \mathcal{C}

$$\dim \mathcal{C} = |\mathcal{E}| - |\mathcal{V}| + 1$$

$$\text{Ex: } 8 - 5 + 1 = 4$$



Cycle indicator (basis) matrix:

$$[C]_{ec} = \begin{cases} 1 & ; \text{ if } e \text{ flows with cycle } c \\ -1 & ; \text{ if } e \text{ flows against cycle } c \\ 0 & ; e \text{ not in cycle } c \end{cases}$$

$$C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Sign indicates
if cycle goes
with or against
edge direction

Columns =
basis for \mathcal{C}

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

flow source at ea. node

edge mass flows \rightarrow

Affine
Constraint

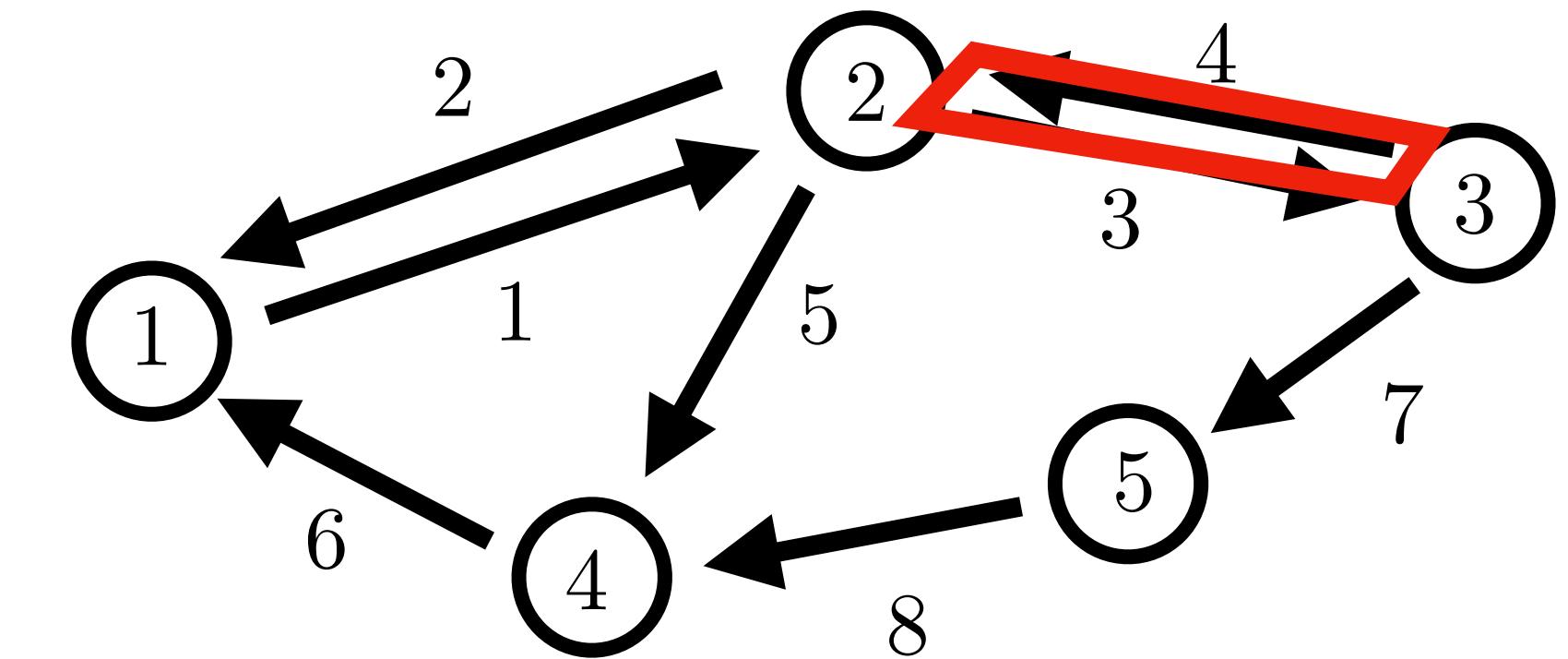
$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution

Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$



Cycle indicator (basis) matrix:

$$[C]_{ec} = \begin{cases} 1 & ; \text{ if } e \text{ flows with cycle } c \\ -1 & ; \text{ if } e \text{ flows against cycle } c \\ 0 & ; e \text{ not in cycle } c \end{cases}$$

$$C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Sign indicates if cycle goes with or against edge direction

Columns = basis for \mathcal{C}

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$ $[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix} \quad \text{flow source at ea. node}$$

edge mass flows →

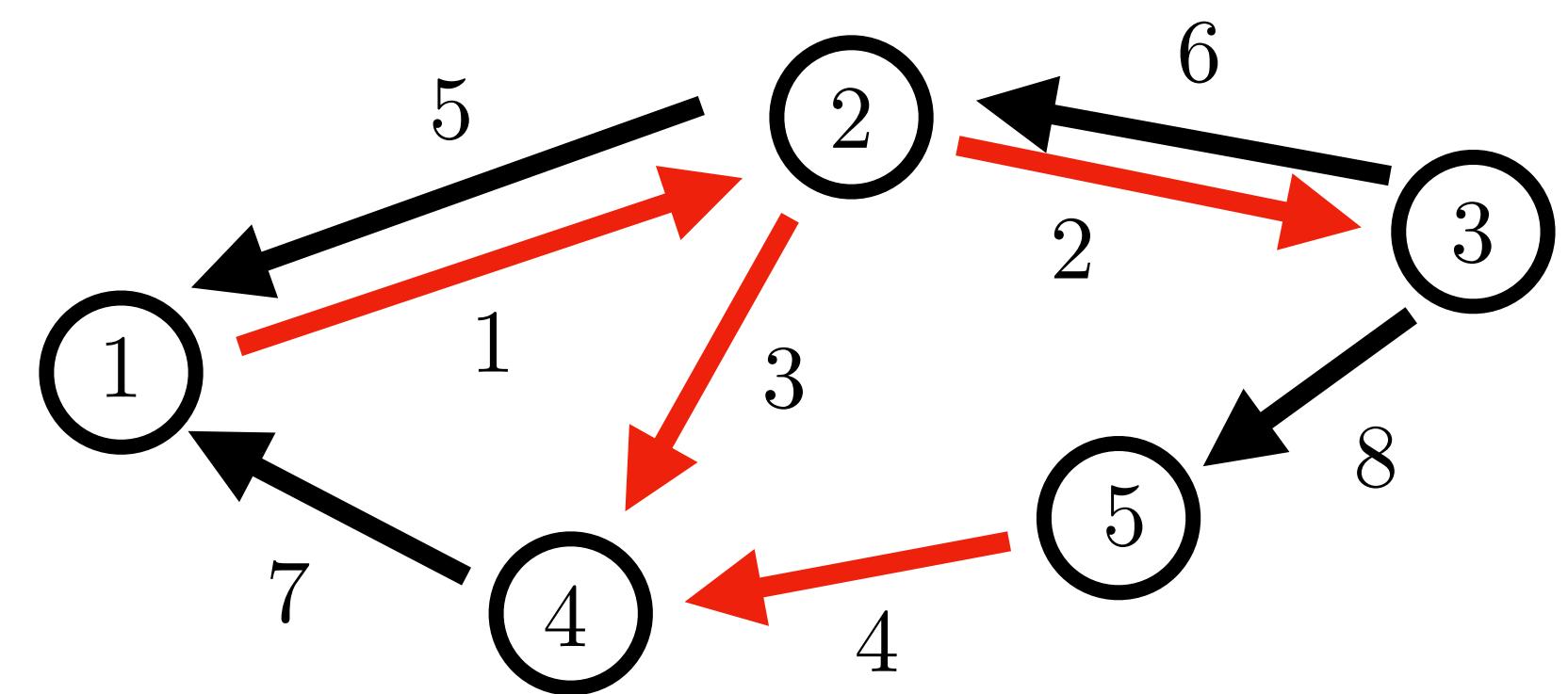
Affine
Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$



Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$|V| \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} |V| - 1$$

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$ $[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix} \quad \text{flow source at ea. node}$$

edge mass flows →

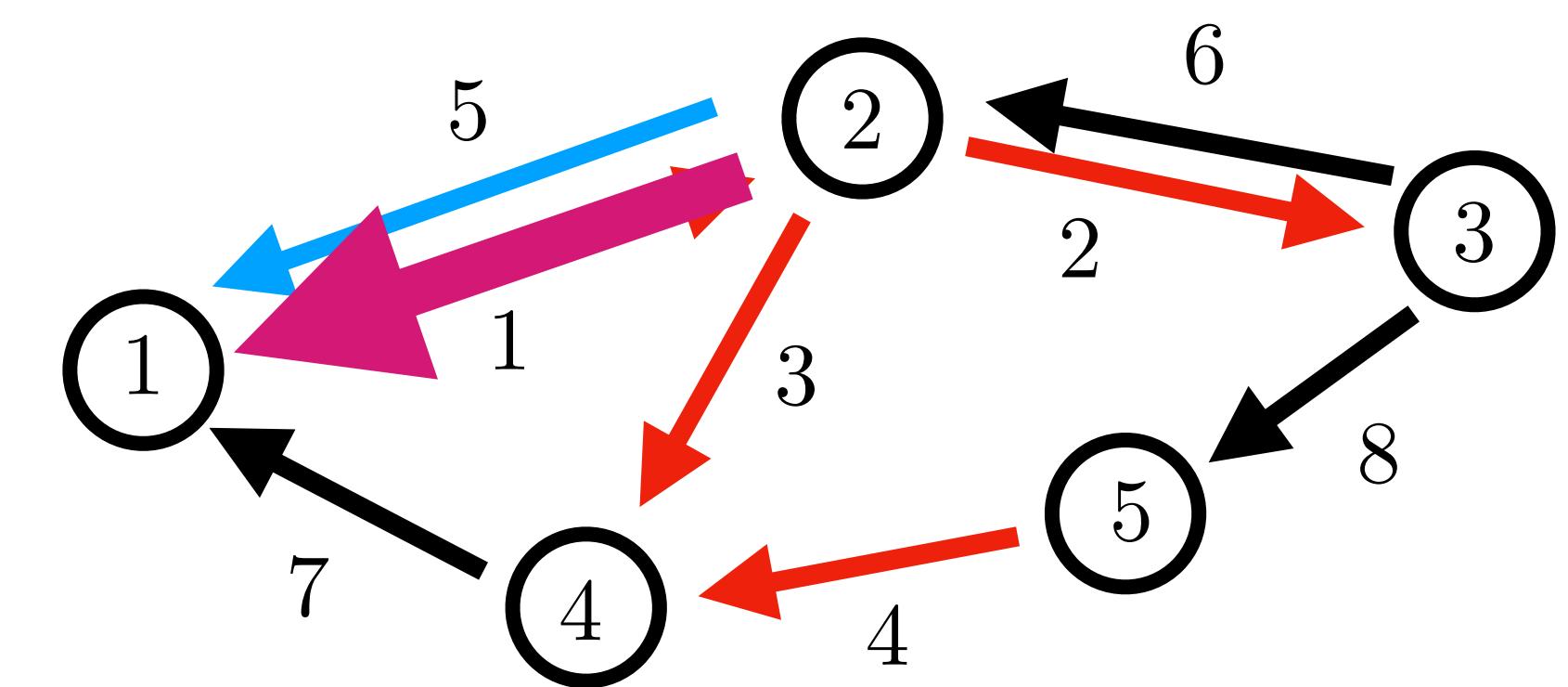
Affine
Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$



Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$|\mathcal{V}| \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \quad |\mathcal{V}| - 1$$

$$D'M = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$ $[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix} \quad \text{flow source at ea. node}$$

edge mass flows \rightarrow

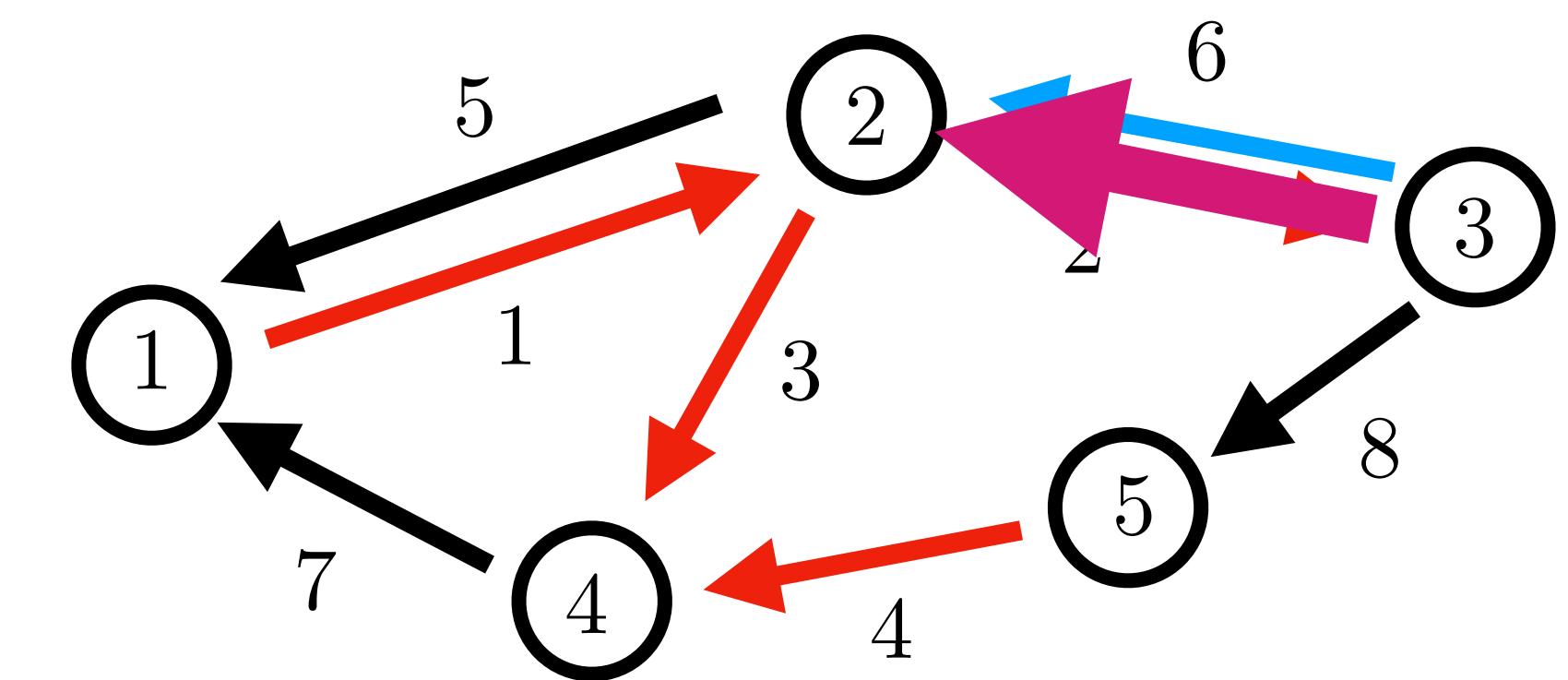
Affine
Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$



Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$|\mathcal{V}| \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \quad |\mathcal{V}| - 1$$

$$D'M = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$ $[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix} \quad \text{flow source at ea. node}$$

edge mass flows →

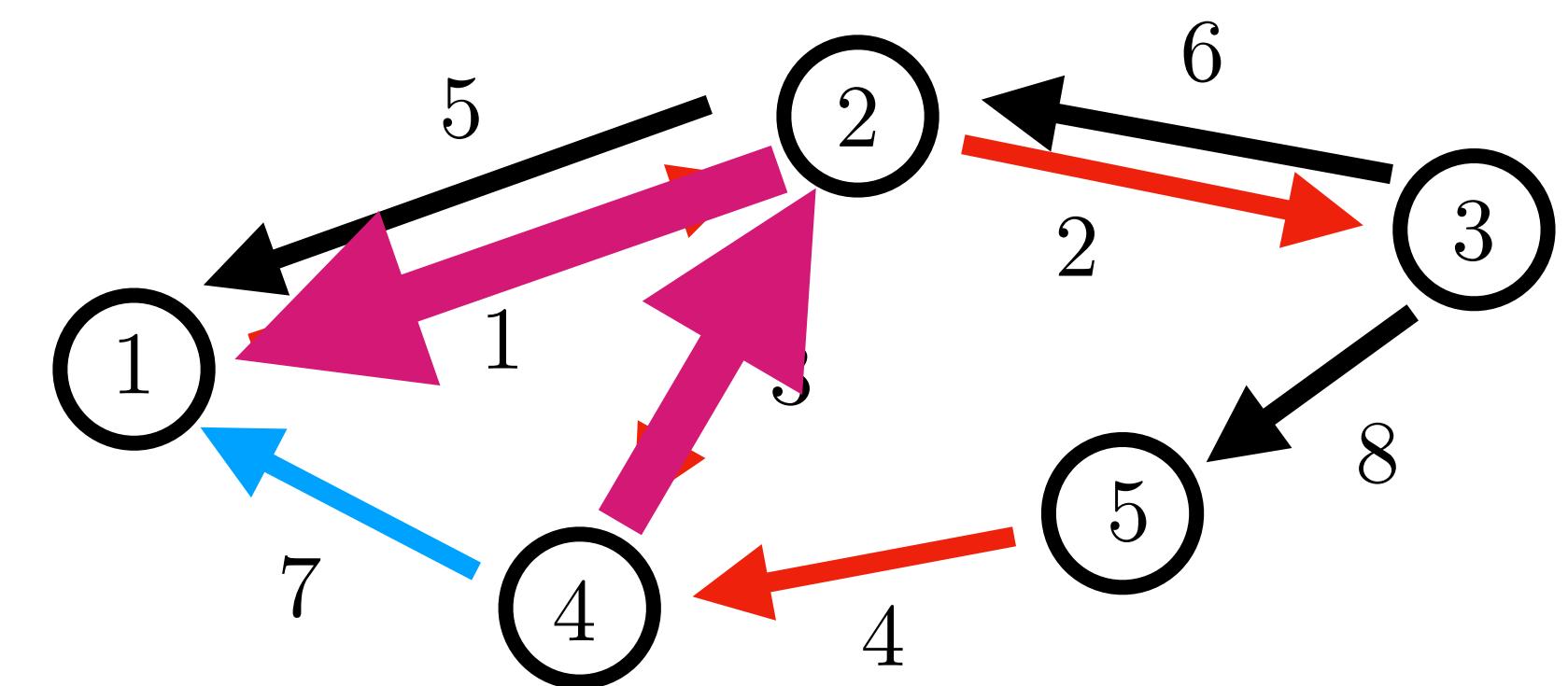
Affine
Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$



Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$|V| \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} |V| - 1$$

$$D'M = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix} \quad \text{flow source at ea. node}$$

edge mass flows \rightarrow

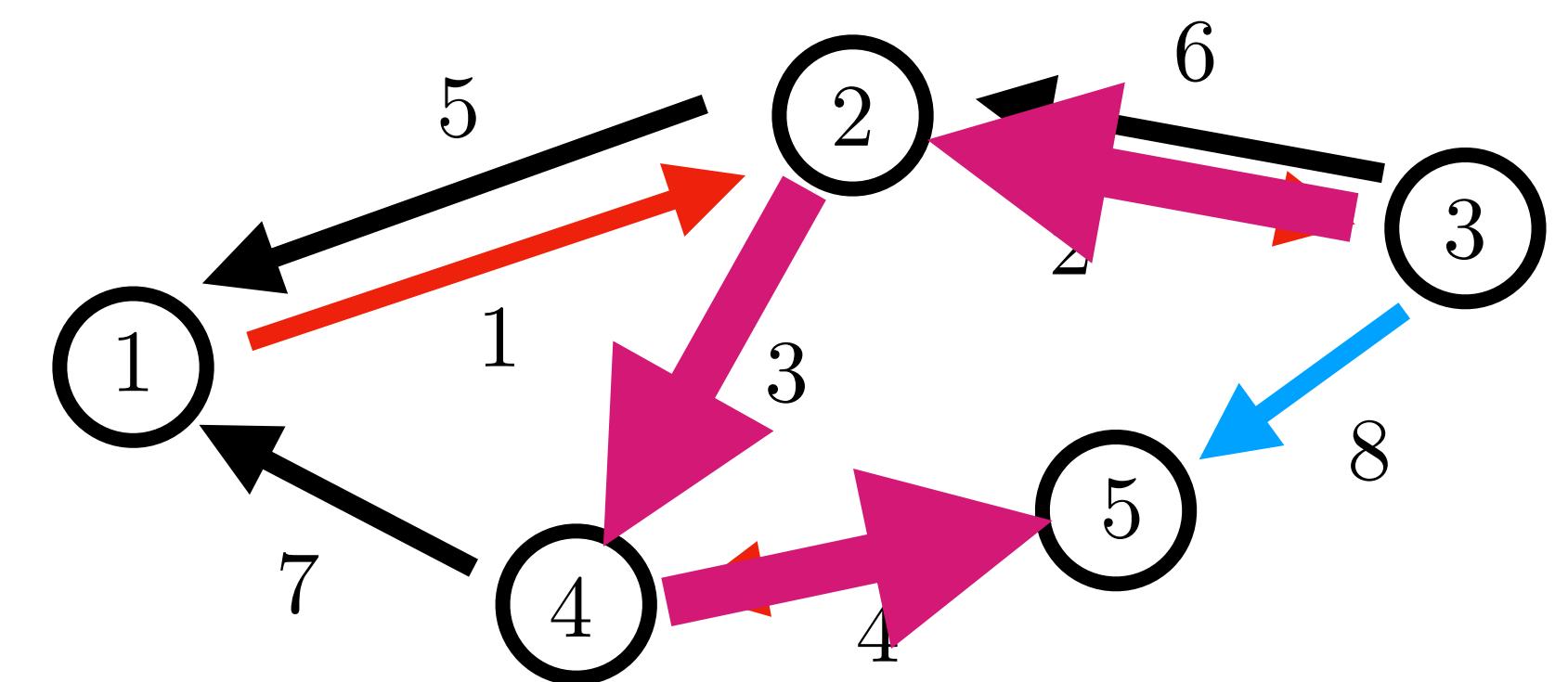
Affine
Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$



Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$|V| \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} |V|-1$$

$$D'M = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

flow source
at ea. node

edge mass flows →

Affine
Constraint

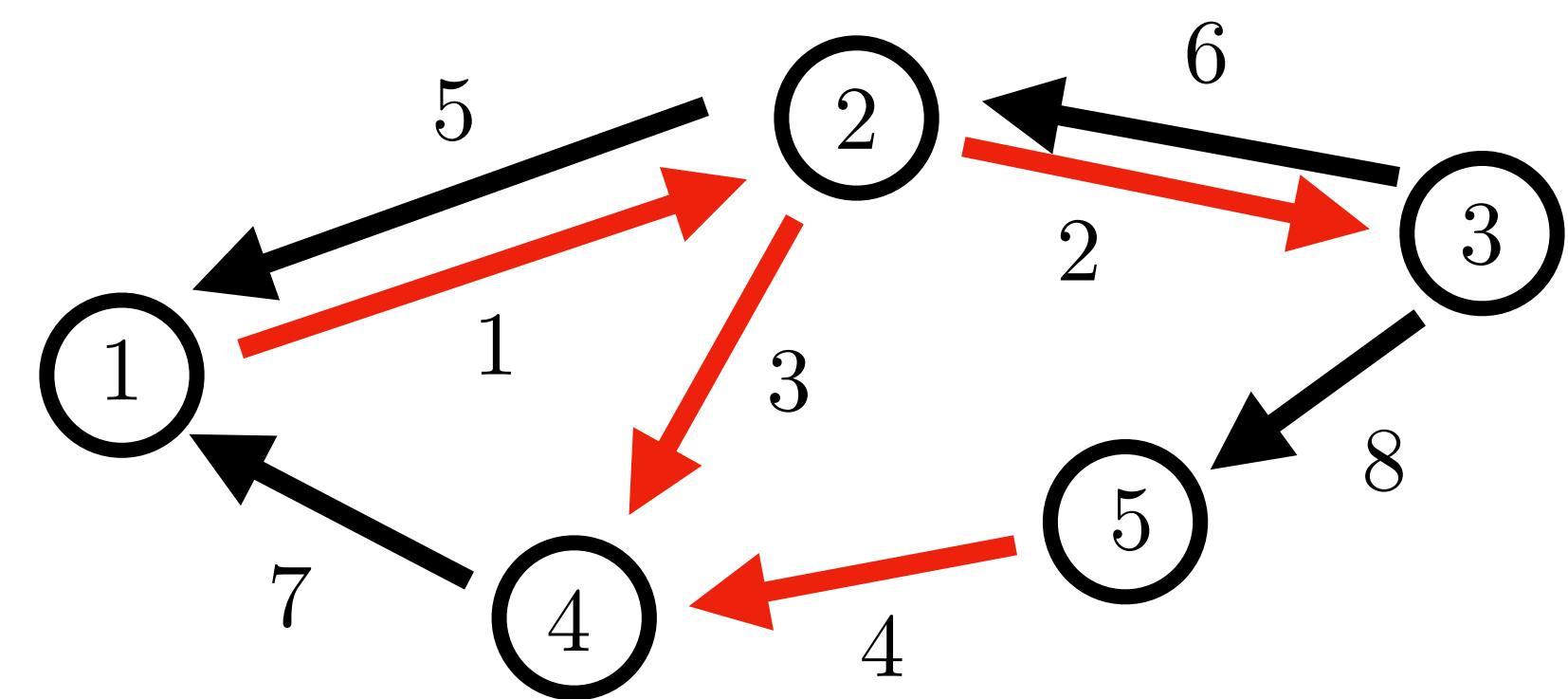
$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution

Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$



Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$D = \left[\begin{array}{cccc} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{array} \right] \left[\begin{array}{cccc} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{array} \right] \left[\begin{array}{cccc} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \end{array} \right]$$

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

flow source
at ea. node

edge mass flows →

Affine
Constraint

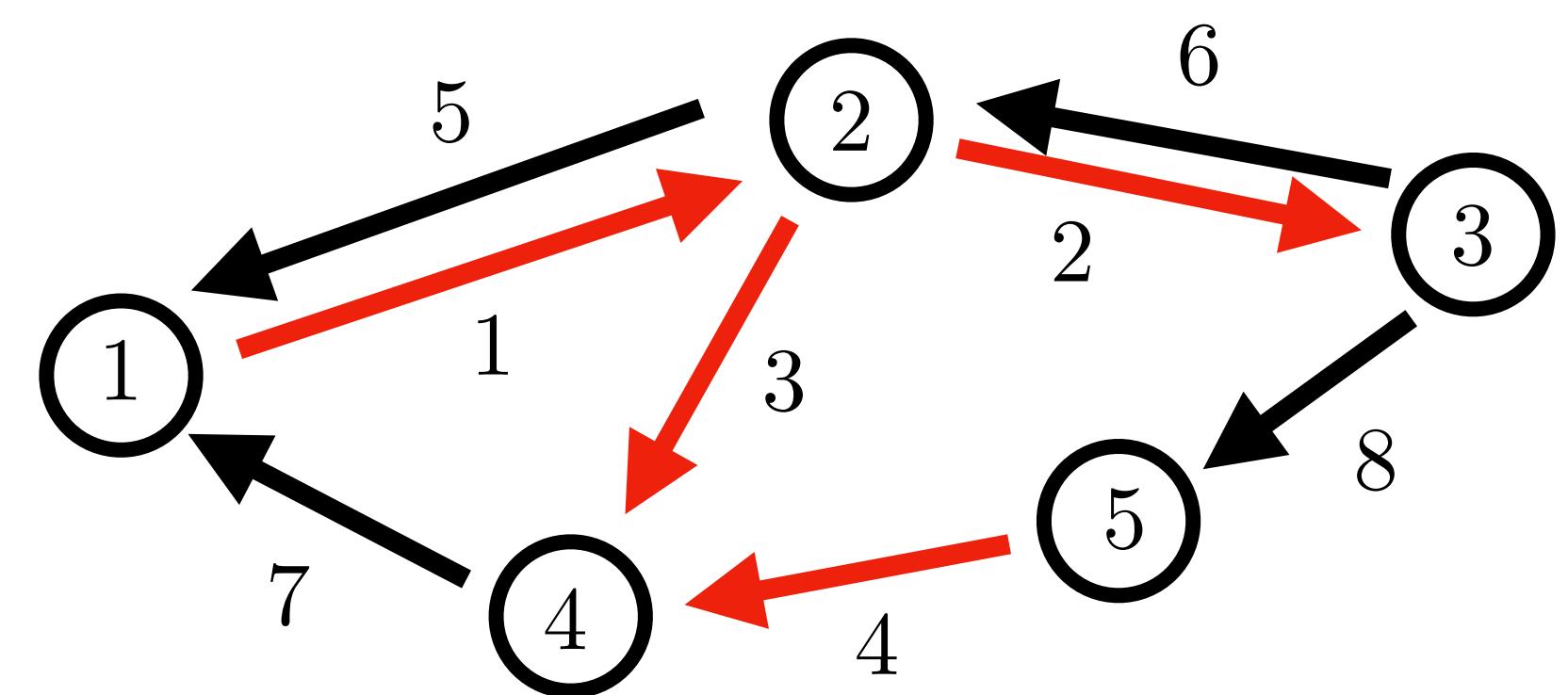
$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution

Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$



Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 0 & 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & -1 \end{bmatrix}$$

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

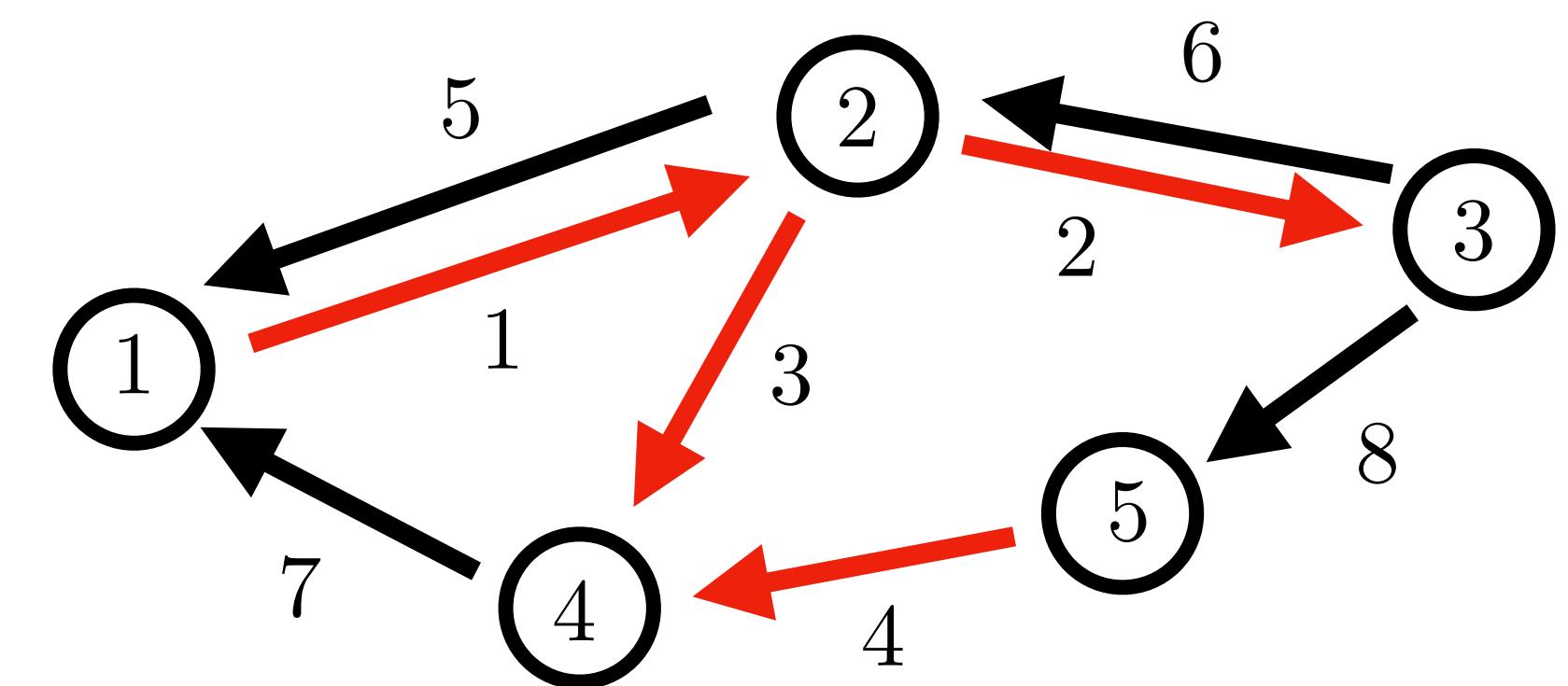
$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$ $[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

flow source at ea. node

edge mass flows \rightarrow



Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 0 & 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & -1 \end{bmatrix}$$

Affine
Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$

$$C = \begin{bmatrix} M \\ -I \end{bmatrix} = \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

$$DC = [D' \ D''] \begin{bmatrix} M \\ -I \end{bmatrix} = D'M - D'' = 0$$

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

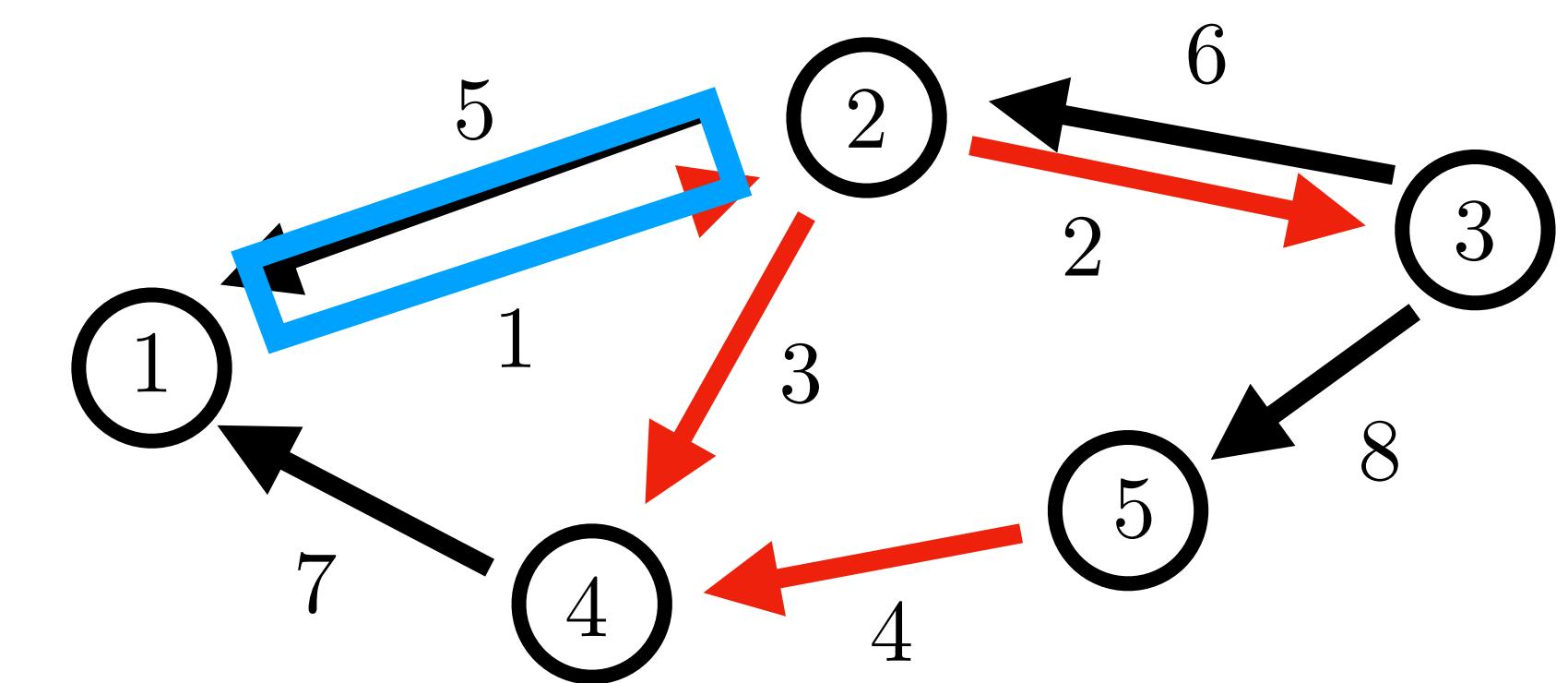
Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

flow source at ea. node

edge mass flows \rightarrow



Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 0 & 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & -1 \end{bmatrix}$$

Affine
Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$

$$C = \begin{bmatrix} M \\ -I \end{bmatrix} = \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

$$DC = [D' \ D''] \begin{bmatrix} M \\ -I \end{bmatrix} = D'M - D'' = 0$$

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

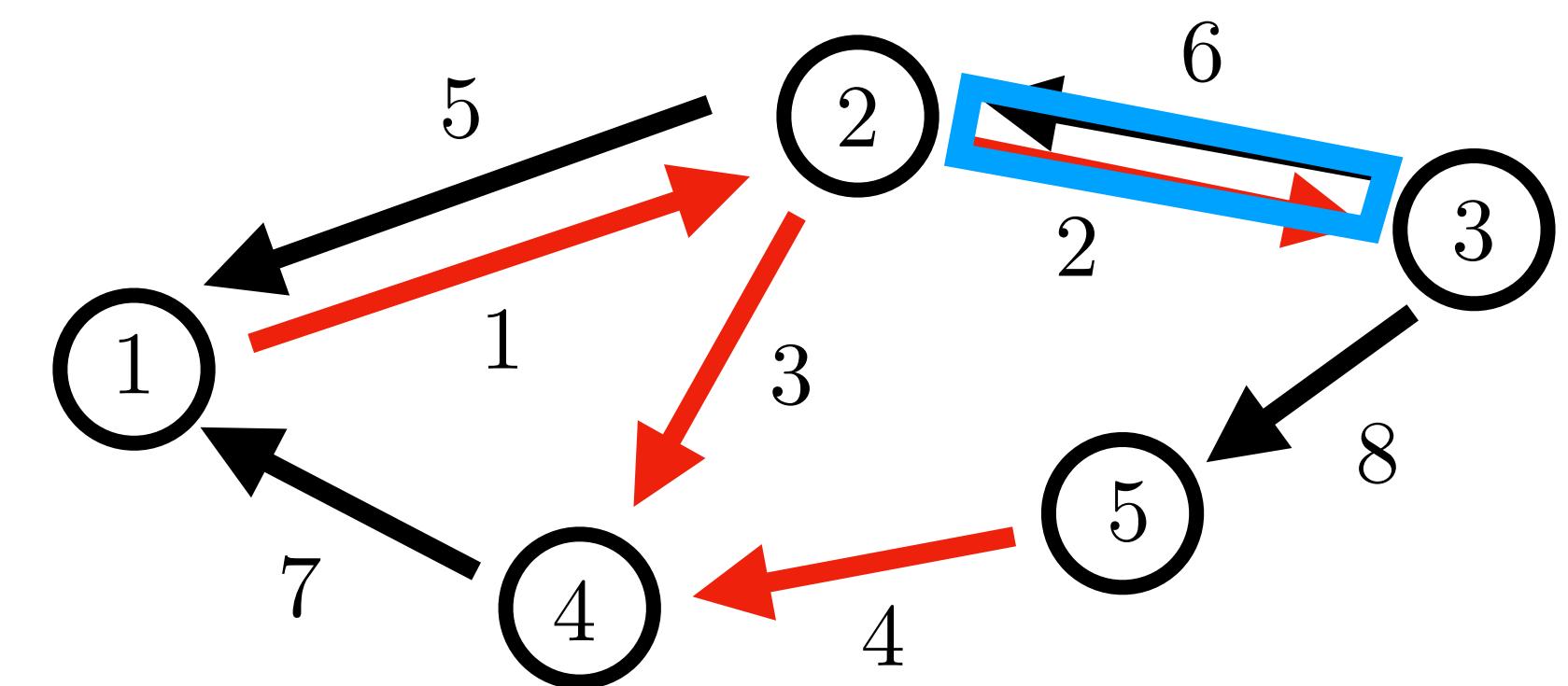
$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$ $[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

flow source at ea. node

edge mass flows \rightarrow



Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 0 & 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & -1 \end{bmatrix}$$

Affine
Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$

$$C = \begin{bmatrix} M \\ -I \end{bmatrix} = \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

$$DC = [D' \ D''] \begin{bmatrix} M \\ -I \end{bmatrix} = D'M - D'' = 0$$

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

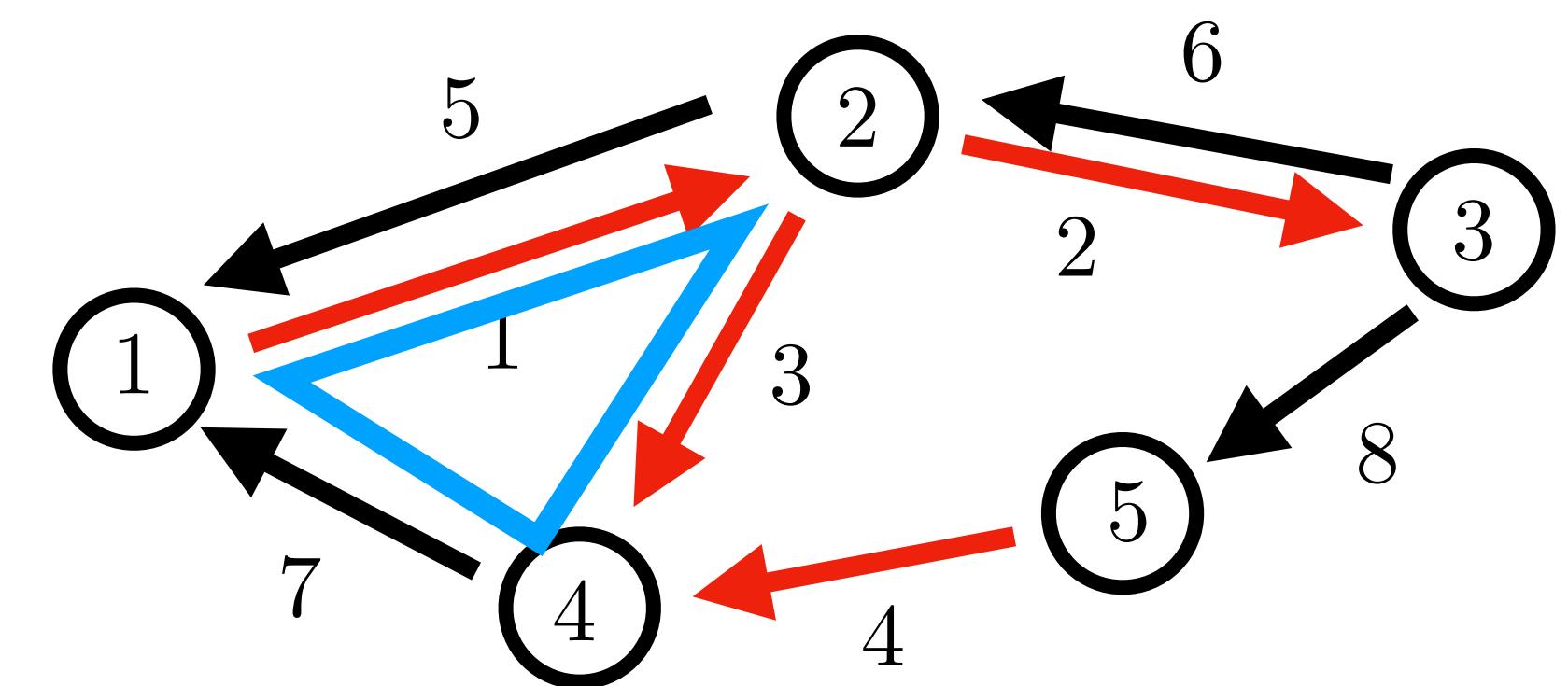
$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$ $[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

flow source at ea. node

edge mass flows \rightarrow



Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 0 & 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 \end{bmatrix}$$

Affine
Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$

$$C = \begin{bmatrix} M \\ -I \end{bmatrix} = \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

$$DC = [D' \ D''] \begin{bmatrix} M \\ -I \end{bmatrix} = D'M - D'' = 0$$

Incidence Matrix - Right Nullspace

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

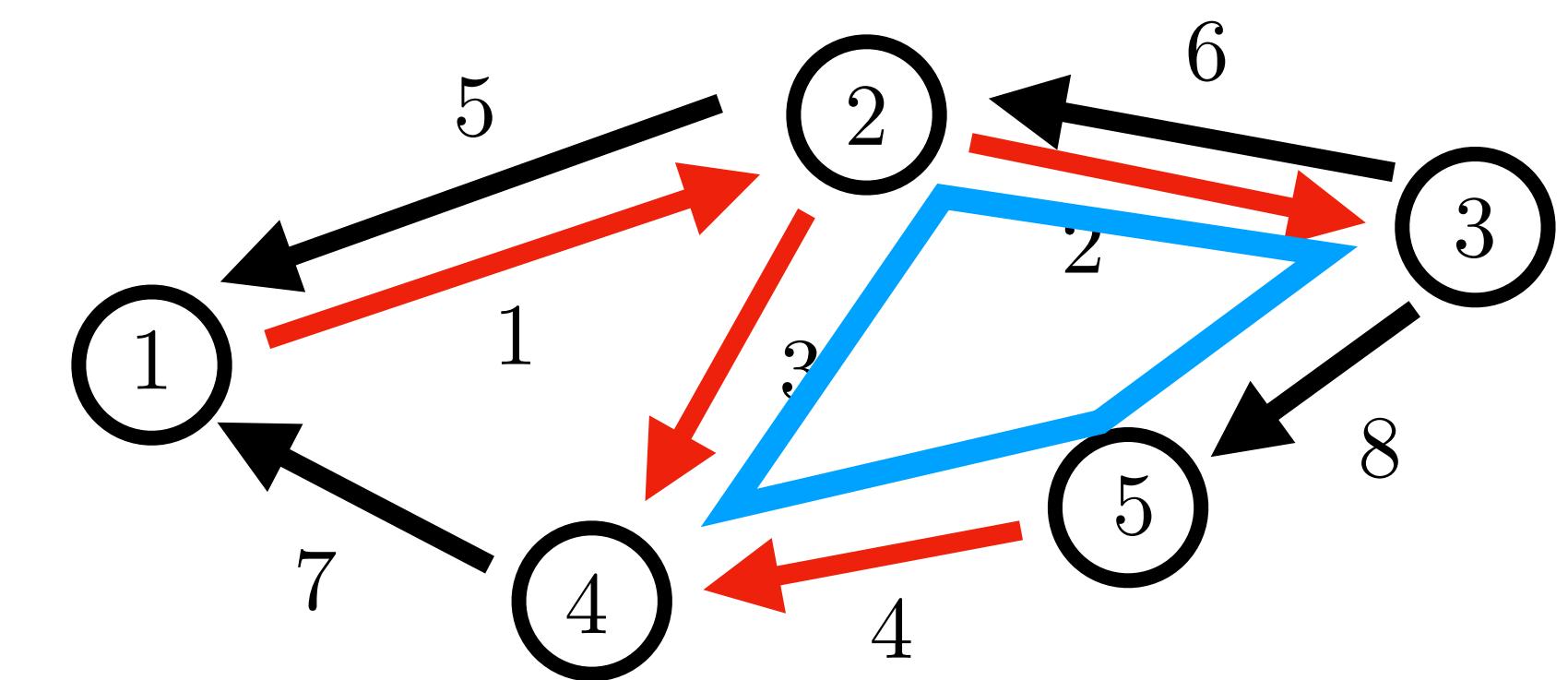
Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{ if } e \text{ out of } v \\ 1 & ; \text{ if } e \text{ into } v \\ 0 & ; \text{ otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

flow source
at ea. node

edge mass flows →



Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 0 & 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & -1 \end{bmatrix}$$

Affine
Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific
Solution Cyclic
Flow

Min Norm
Solution

$$\bar{x} = D^T(DD^T)^\dagger S$$

$$C = \begin{bmatrix} M \\ -I \end{bmatrix} = \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

$$DC = [D' \ D''] \begin{bmatrix} M \\ -I \end{bmatrix} = D'M - D'' = 0$$

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

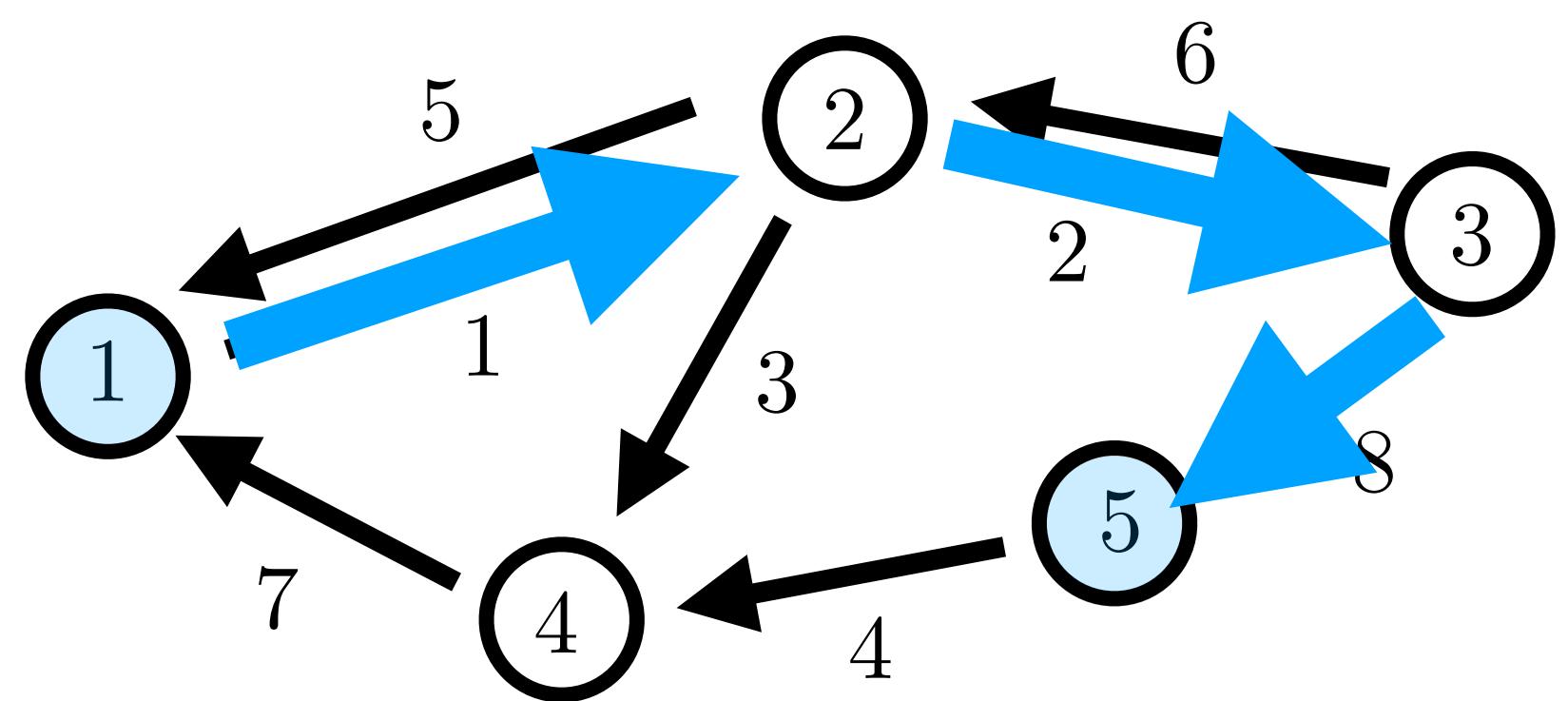
Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$



Domain & Co-Domain Interpretation

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

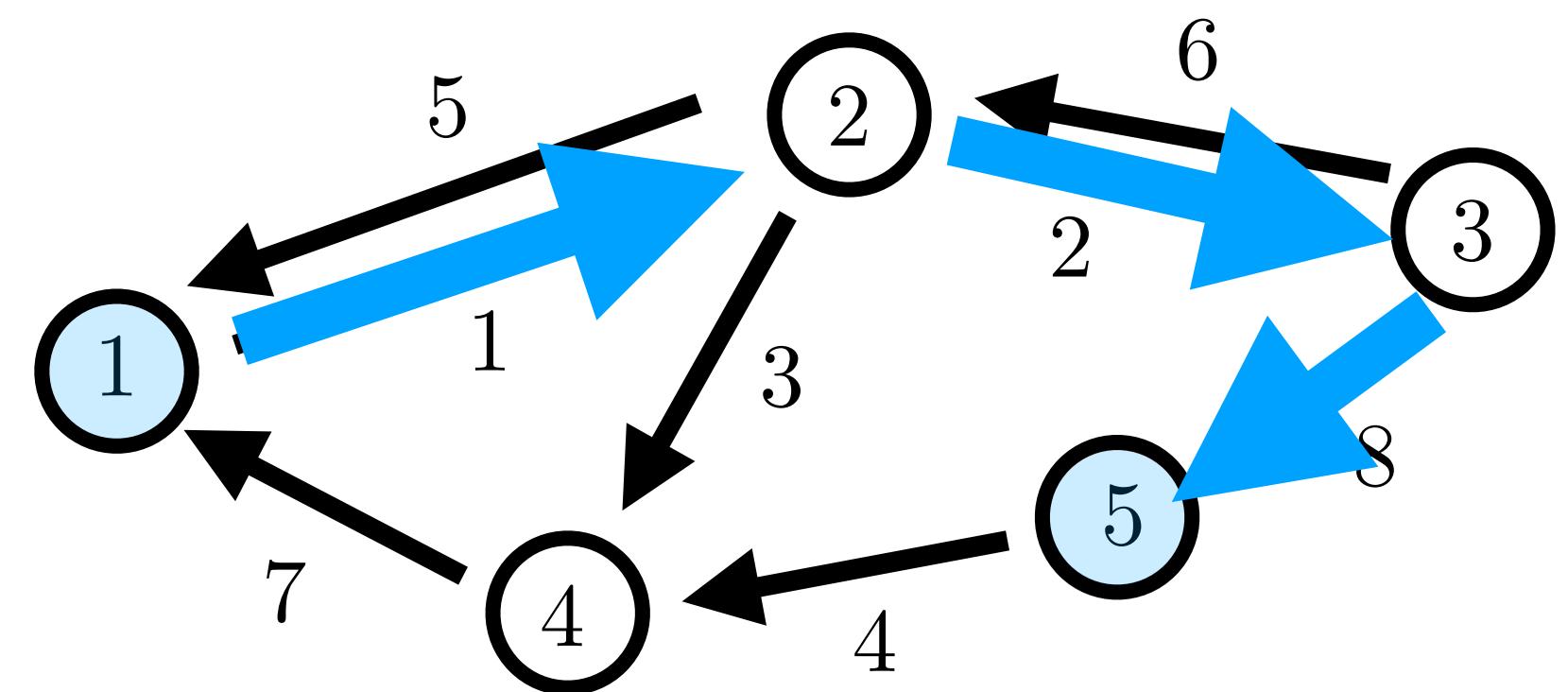
Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$



Domain & Co-Domain Interpretation

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

$$S = \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

Cyclic Flow

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

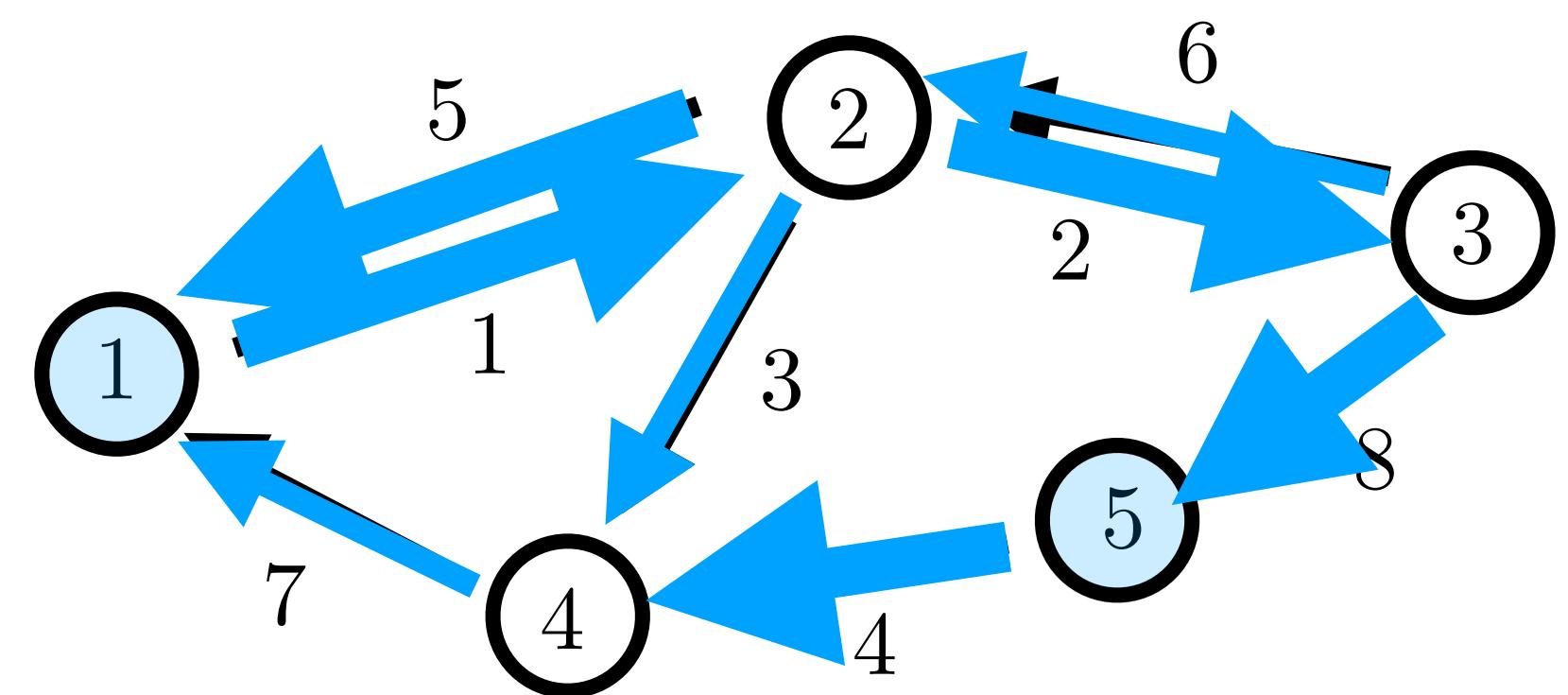
Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$



Domain & Co-Domain Interpretation

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

$$S = \begin{bmatrix} -1 \\ 0.5 \\ 2 \\ 0.2 \\ 1 \end{bmatrix}$$

Cyclic Flow

Incidence Matrix - Column Geometry

Graph: Vertices

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Edges

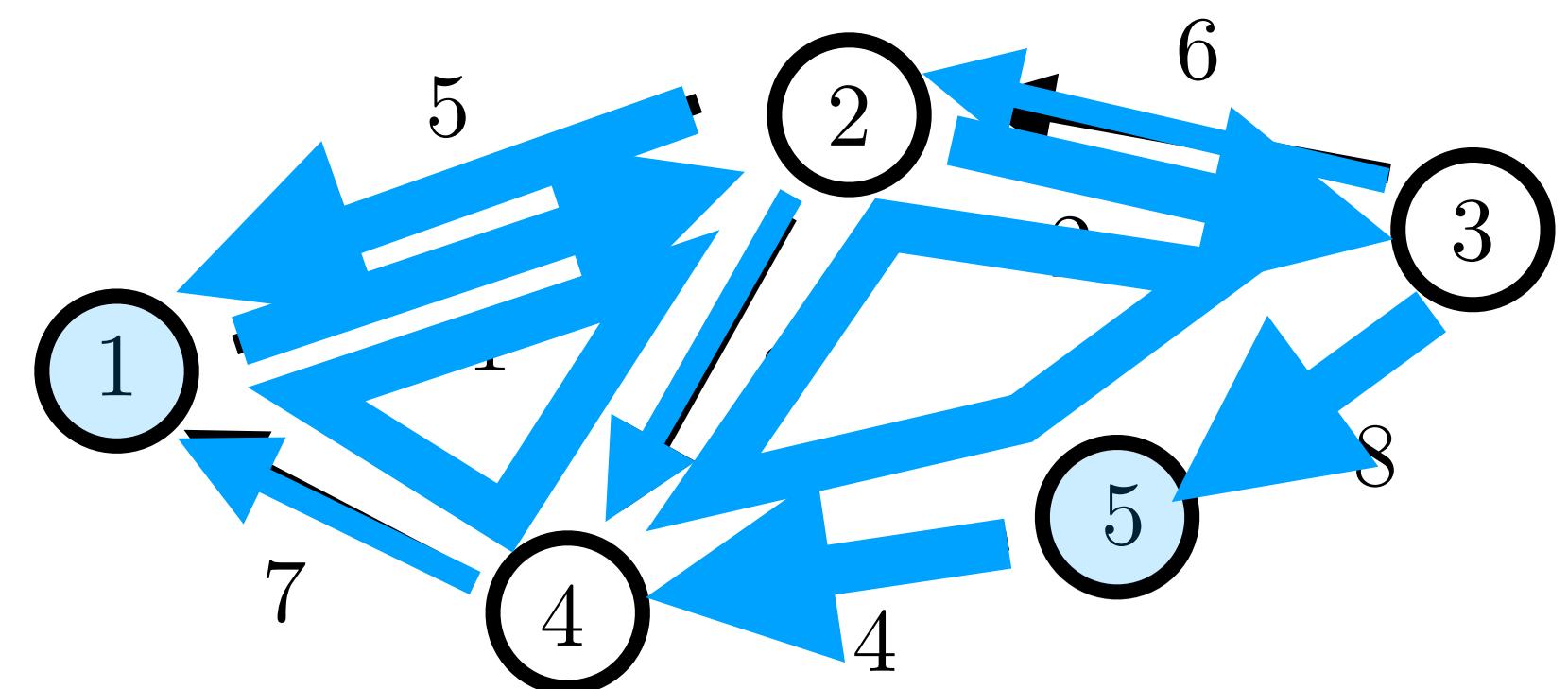
$$v \in \mathcal{V}$$

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$



Domain & Co-Domain Interpretation

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

$$S = \begin{bmatrix} -1 \\ 0.5 \\ 2 \\ 0.2 \\ 1 \end{bmatrix}$$

Cyclic Flow

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

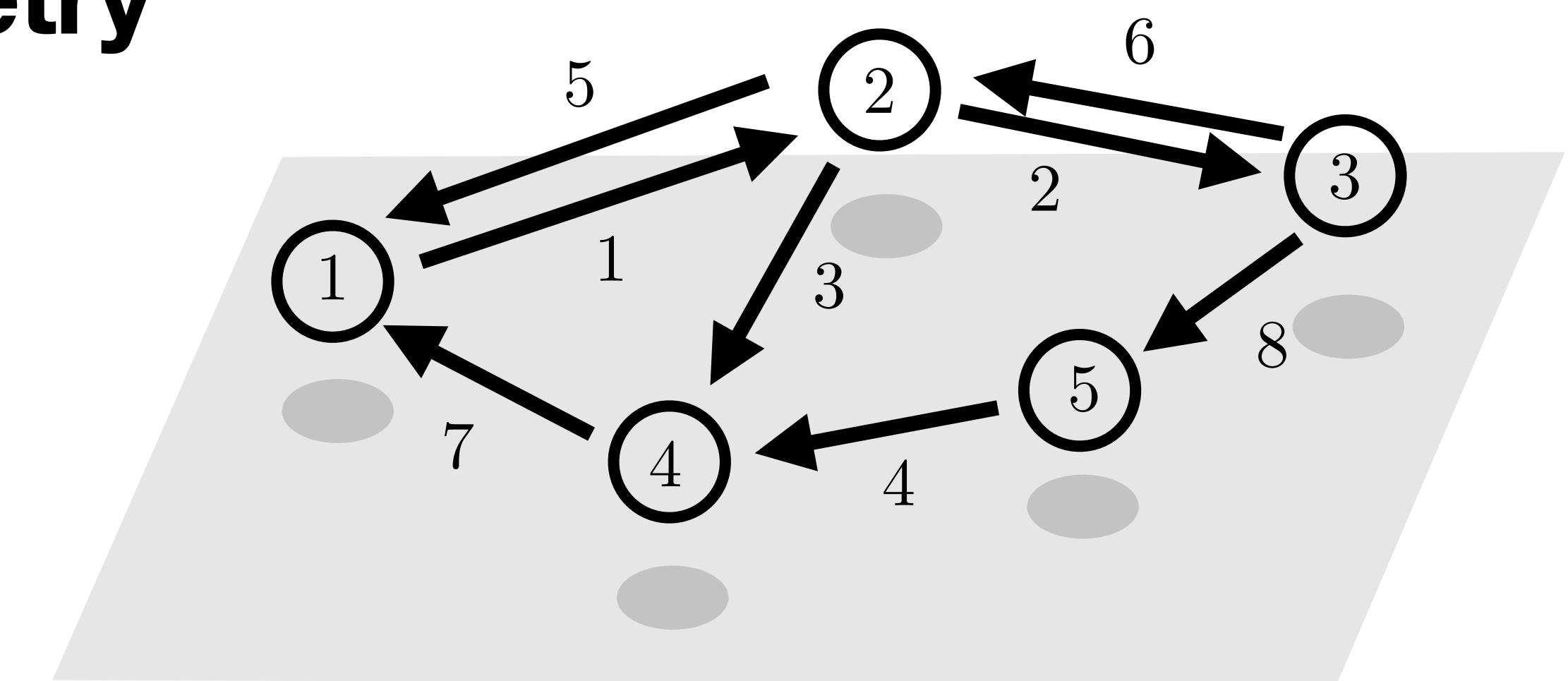
Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

Cyclic Flow



Domain & Co-Domain Interpretation

Co-domain: $w \in \mathbb{R}^{|\mathcal{V}|}$...source-sink on nodes

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

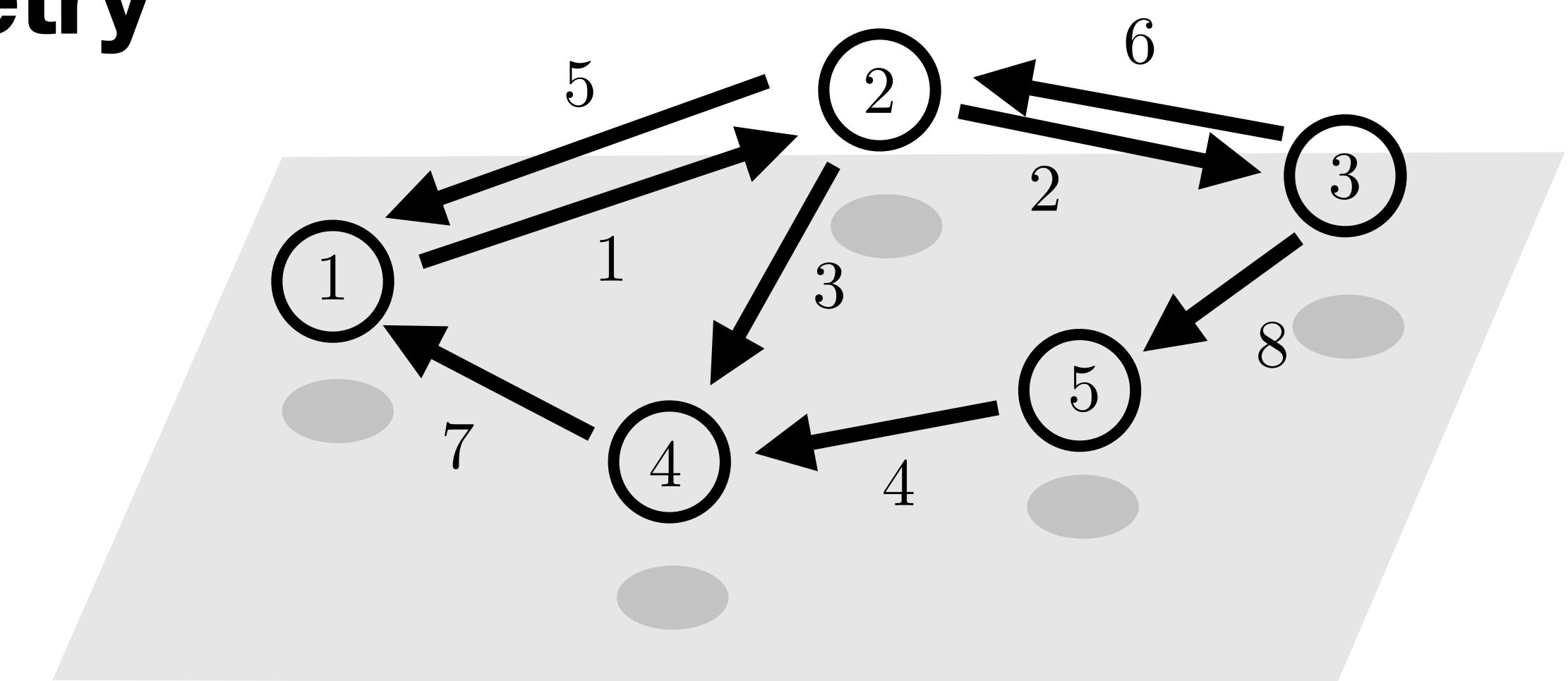
Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

Cyclic Flow



Domain & Co-Domain Interpretation

Co-domain: $w \in \mathbb{R}^{|\mathcal{V}|}$...source-sink on nodes
...value function on nodes

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

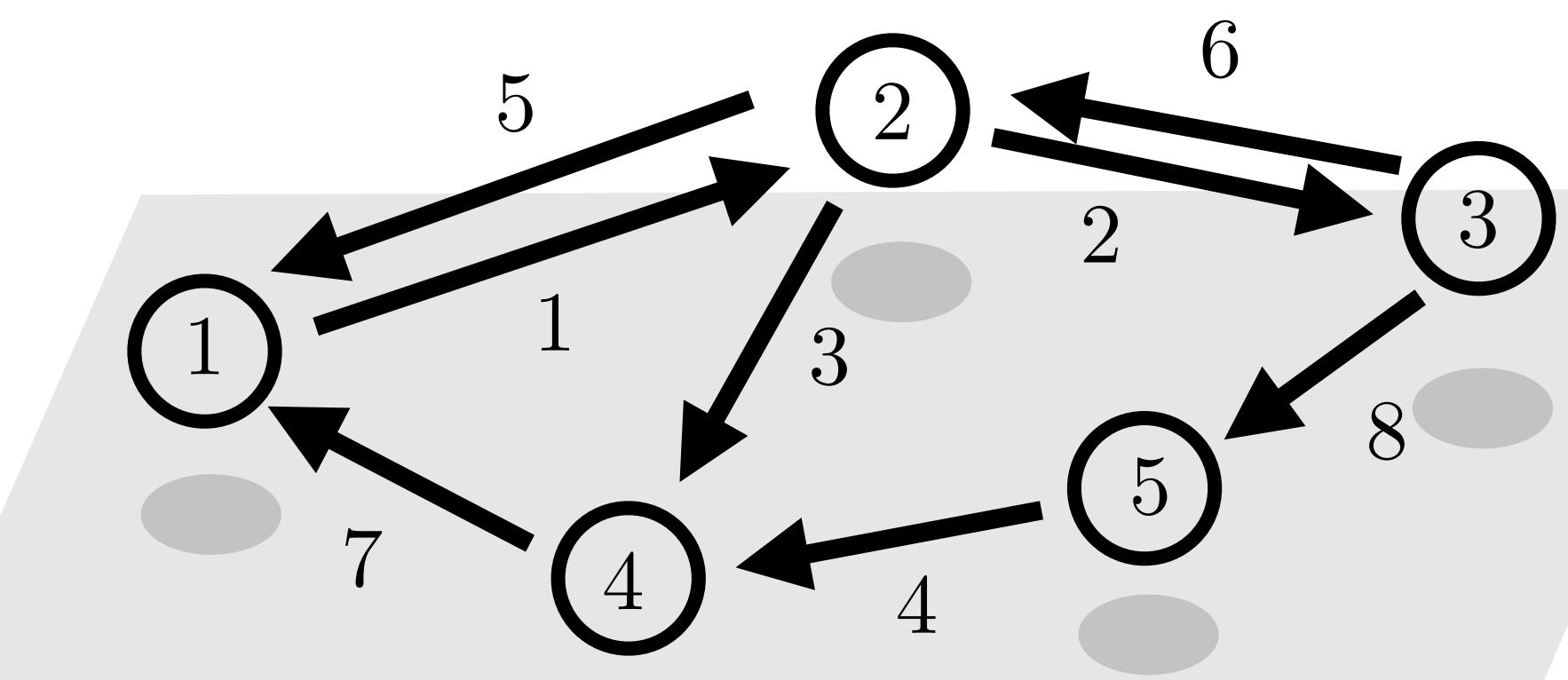
Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

Cyclic Flow



Domain & Co-Domain Interpretation

Co-domain: $w \in \mathbb{R}^{|\mathcal{V}|}$...source-sink on nodes
...value function on nodes

$$w^T D = \tau^T$$

Value function Edge tension

Value Function

Cost-to-go
Potential value
“Height” - gravitational potential

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

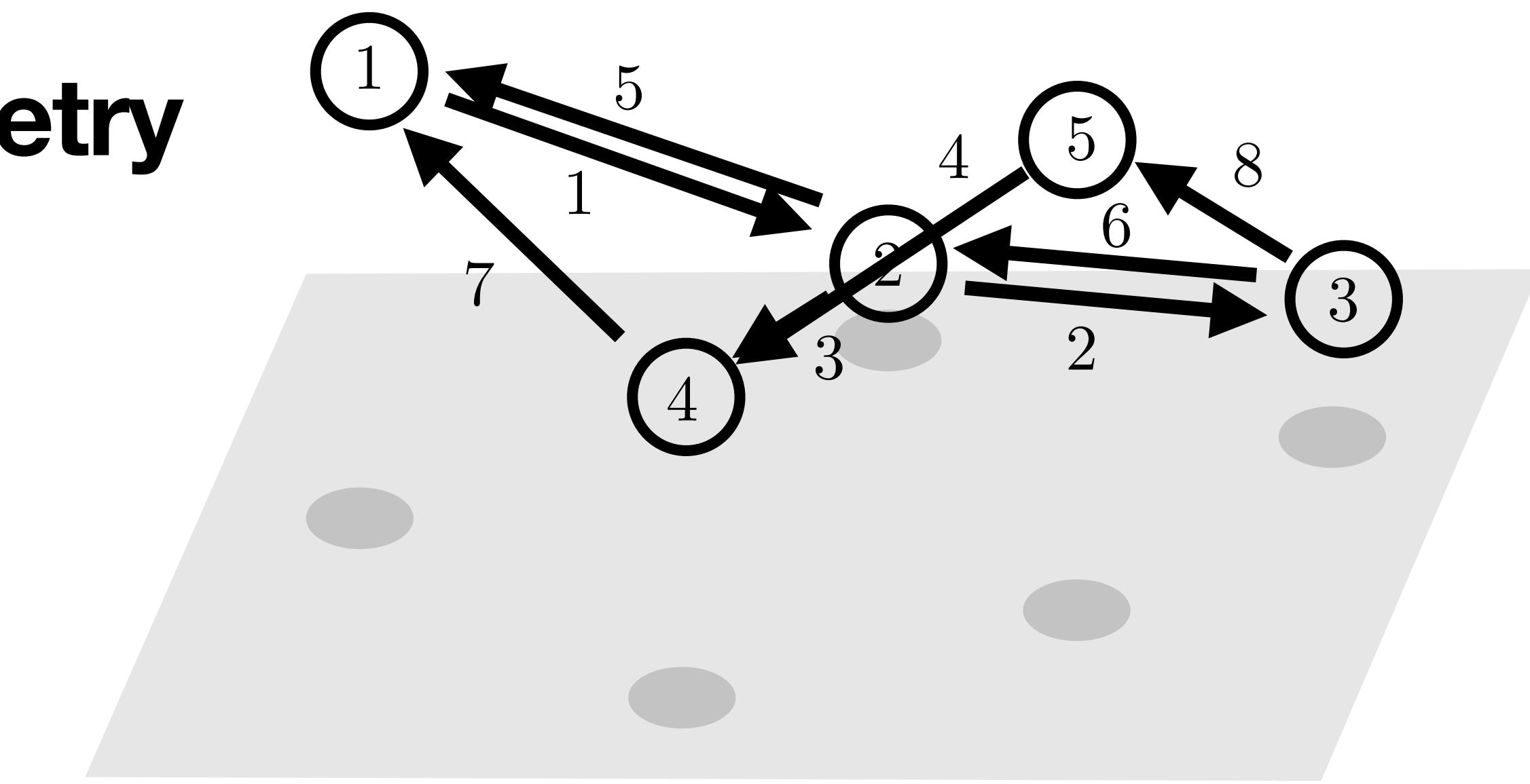
Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

Cyclic Flow



Domain & Co-Domain Interpretation

Co-domain: $w \in \mathbb{R}^{|\mathcal{V}|}$...source-sink on nodes
...value function on nodes

$$w^T D = \tau^T$$

Value function Edge tension

Value Function

Cost-to-go
Potential value
“Height” - gravitational potential

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

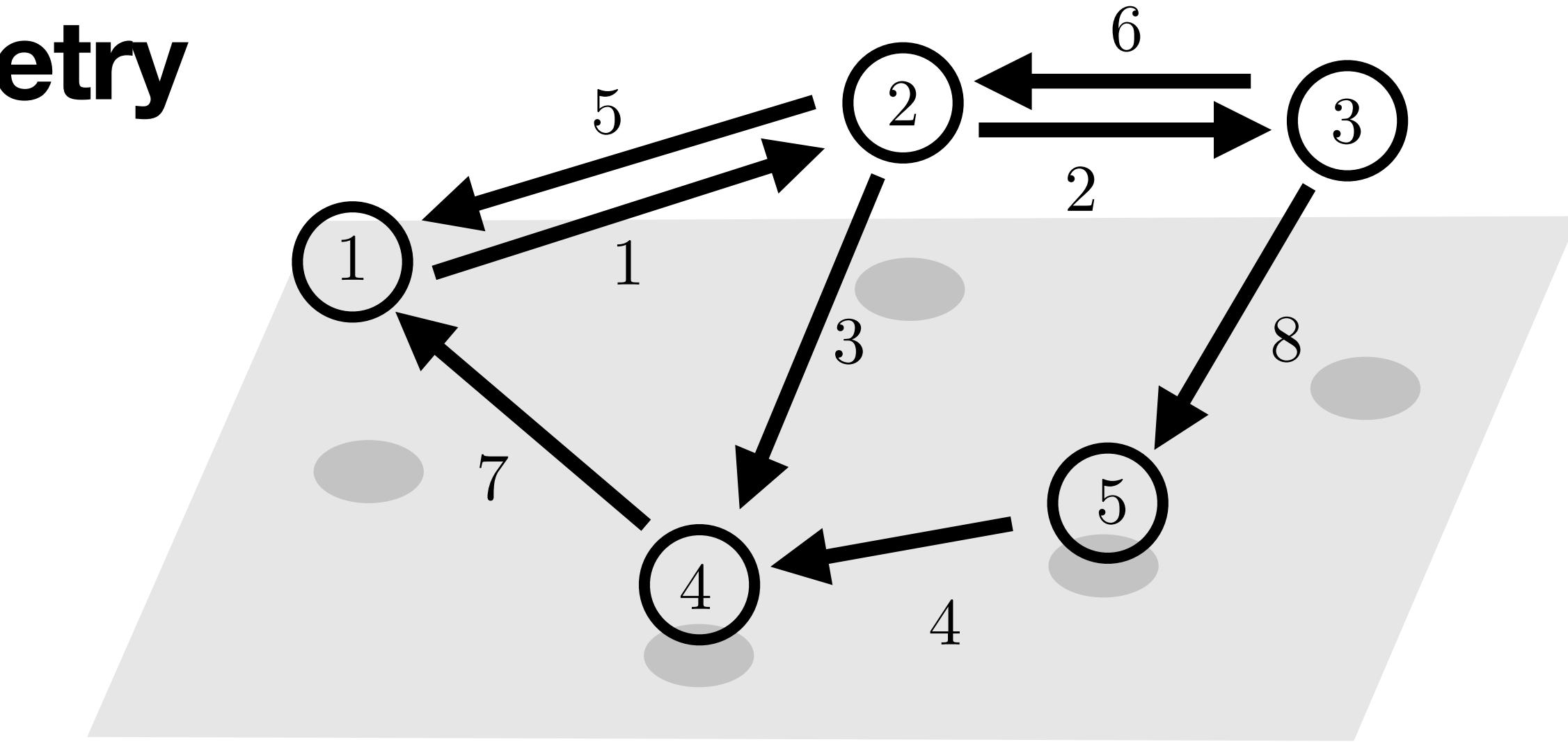
Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

Cyclic Flow



Domain & Co-Domain Interpretation

Co-domain: $w \in \mathbb{R}^{|\mathcal{V}|}$...source-sink on nodes
...value function on nodes

$$w^T D = \tau^T$$

Value function Edge tension

Value Function

Cost-to-go
Potential value
“Height” - gravitational potential

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

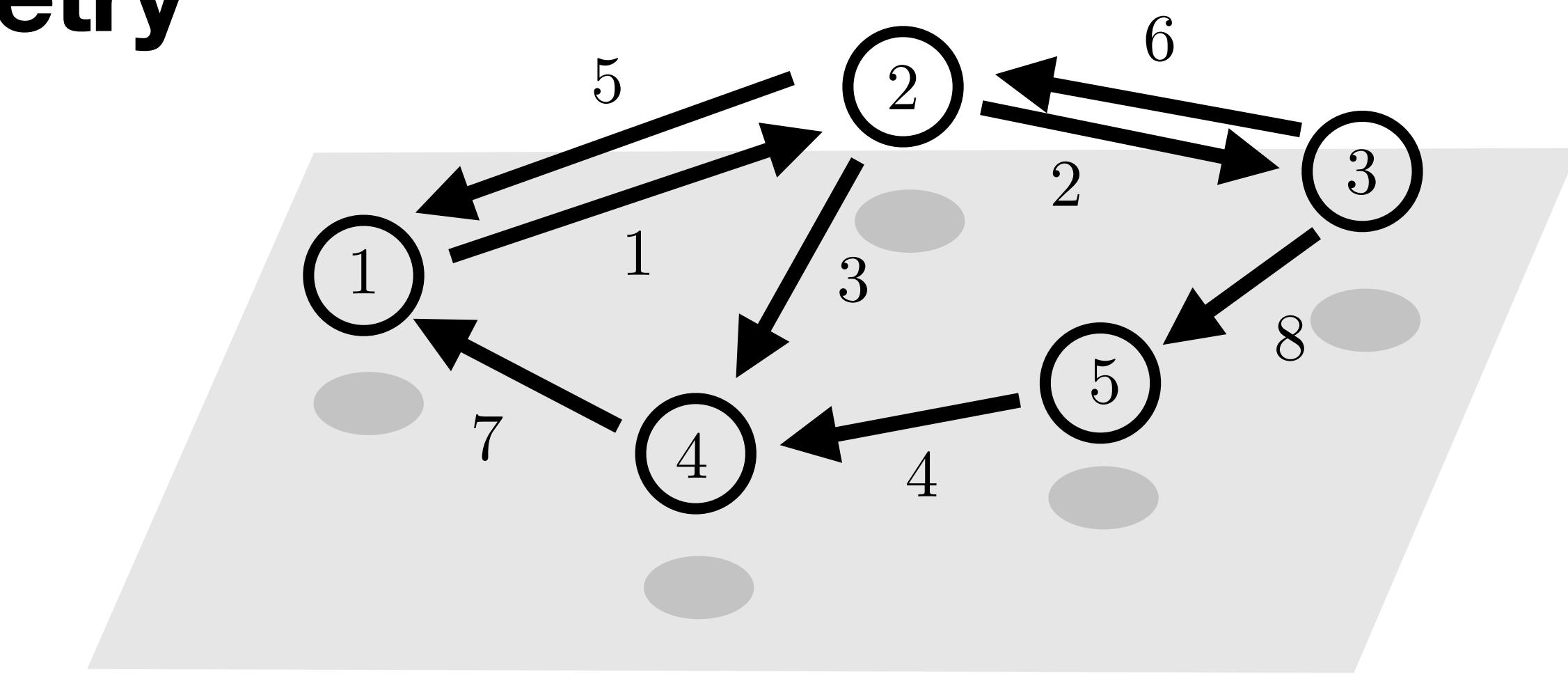
Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

Cyclic Flow



Domain & Co-Domain Interpretation

Co-domain: $w \in \mathbb{R}^{|\mathcal{V}|}$...source-sink on nodes
...value function on nodes

$$w^T D = \tau^T$$

Value function Edge tension

$$[w^T D]_e = w_i - w_{i'} = \tau_e$$

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

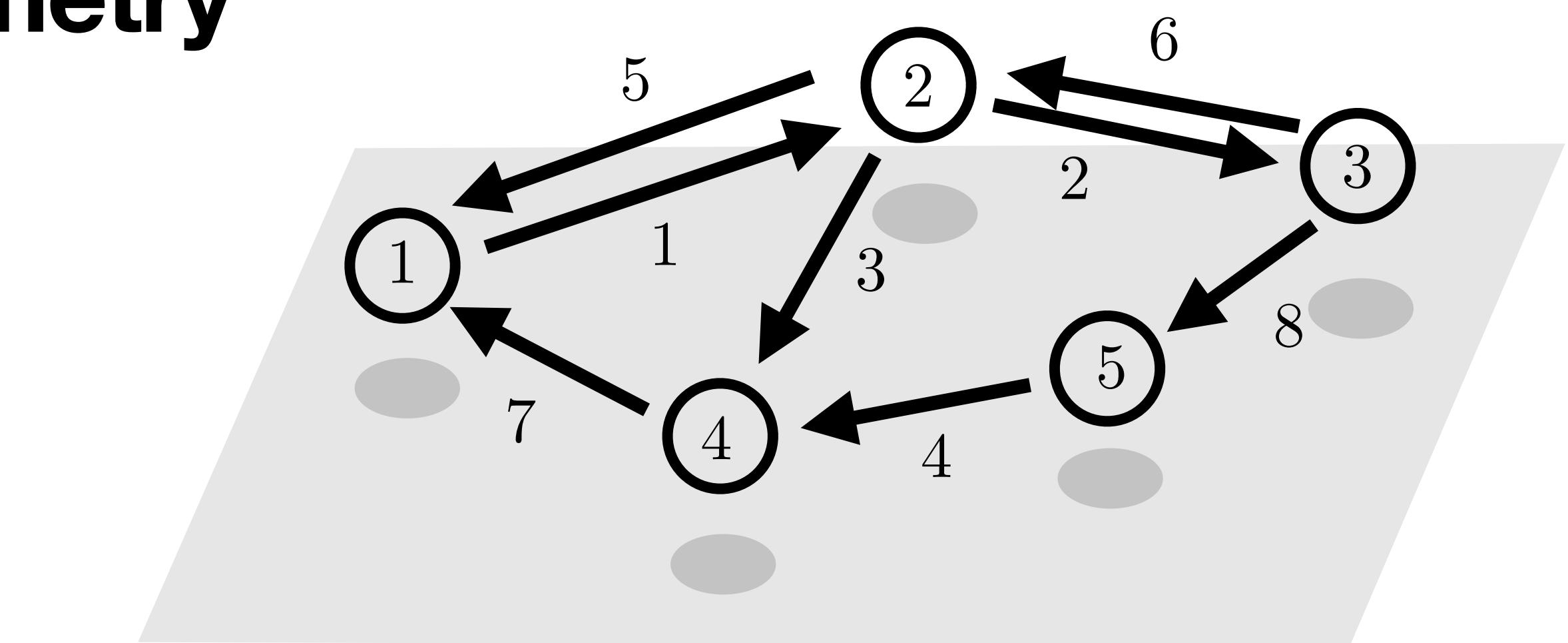
Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

Cyclic Flow



Domain & Co-Domain Interpretation

Co-domain: $w \in \mathbb{R}^{|\mathcal{V}|}$...source-sink on nodes
...value function on nodes

$$w^T D = \tau^T$$

Value function Edge tension

$$(w^T + 1^T)D = \tau^T$$

Constant shift
(doesn't change tension)

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

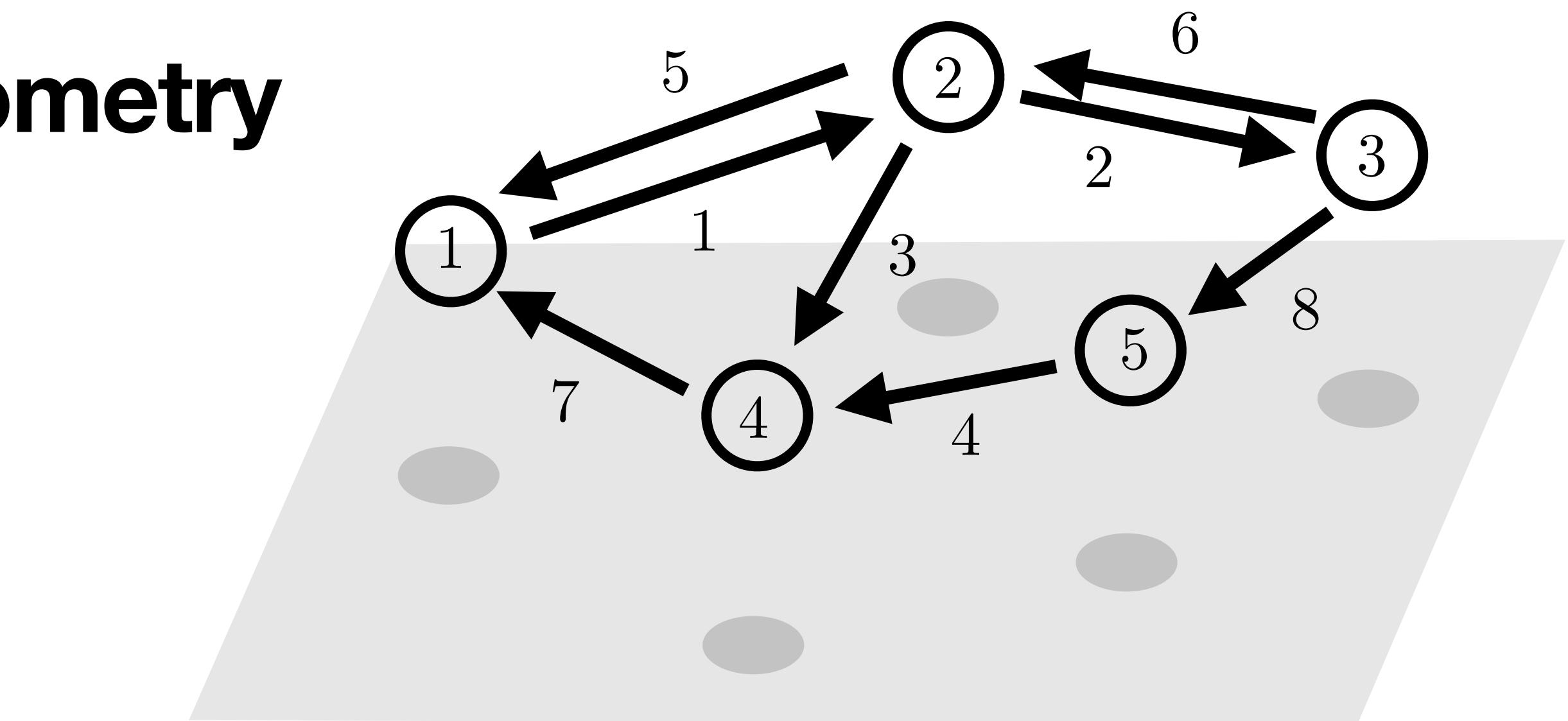
Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

Cyclic Flow



Domain & Co-Domain Interpretation

Co-domain: $w \in \mathbb{R}^{|\mathcal{V}|}$...source-sink on nodes
...value function on nodes

$$w^T D = \tau^T$$

Value function Edge tension

$$(w^T + 1^T)D = \tau^T$$

Constant shift
(doesn't change tension)

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

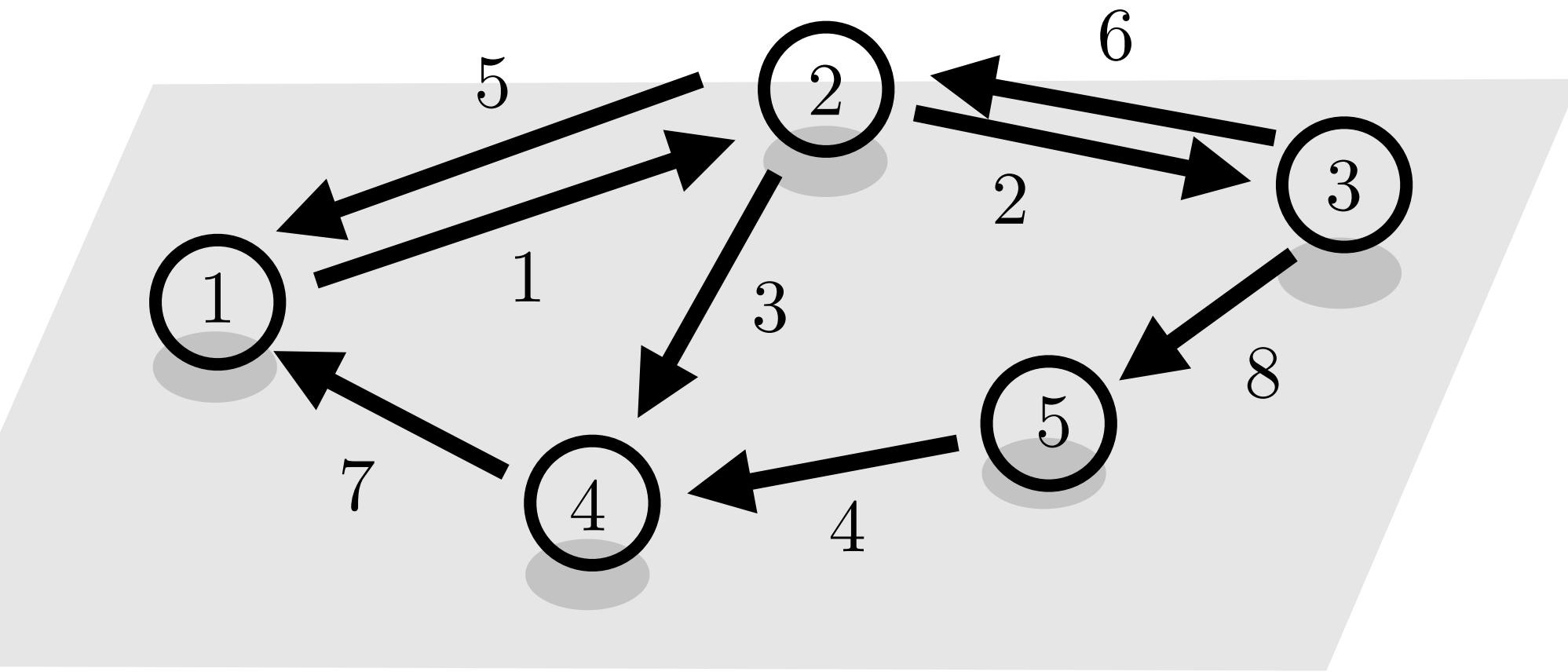
$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix:

$$D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$



Domain & Co-Domain Interpretation

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

Co-domain: $w \in \mathbb{R}^{|\mathcal{V}|}$...source-sink on nodes
...value function on nodes

Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$w^T D = \tau^T$$

$$x = \bar{x} + Cz$$

Value function Edge tension

Specific Solution

Cyclic Flow

$$(w^T + 1^T)D = \tau^T$$

Constant shift
(doesn't change tension)

Incidence Matrix - Column Geometry

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Domain: $x \in \mathbb{R}^{|\mathcal{E}|}$...mass flow on edges

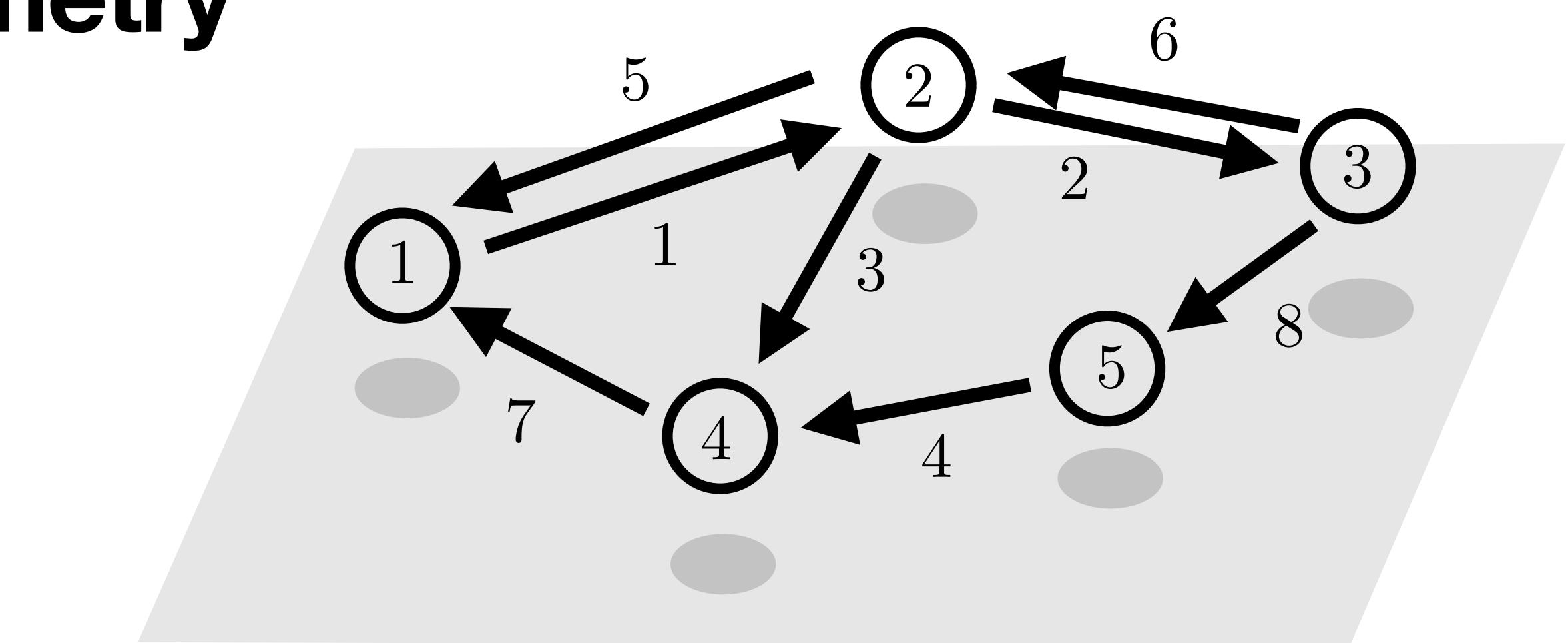
Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

Cyclic Flow



Domain & Co-Domain Interpretation

Co-domain: $w \in \mathbb{R}^{|\mathcal{V}|}$...source-sink on nodes
...value function on nodes

$$w^T D = \tau^T$$

Value function Edge tension

$$(w^T + 1^T) D = \tau^T$$

Constant shift
(doesn't change tension)

Graph Laplacians

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E}) \quad \begin{array}{l} \text{Vertices} \\ v \in \mathcal{V} \end{array} \quad \begin{array}{l} \text{Edges} \\ e \in \mathcal{E} \end{array} \quad e = (v, v')$$

Incidence Matrix:

$$D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$$

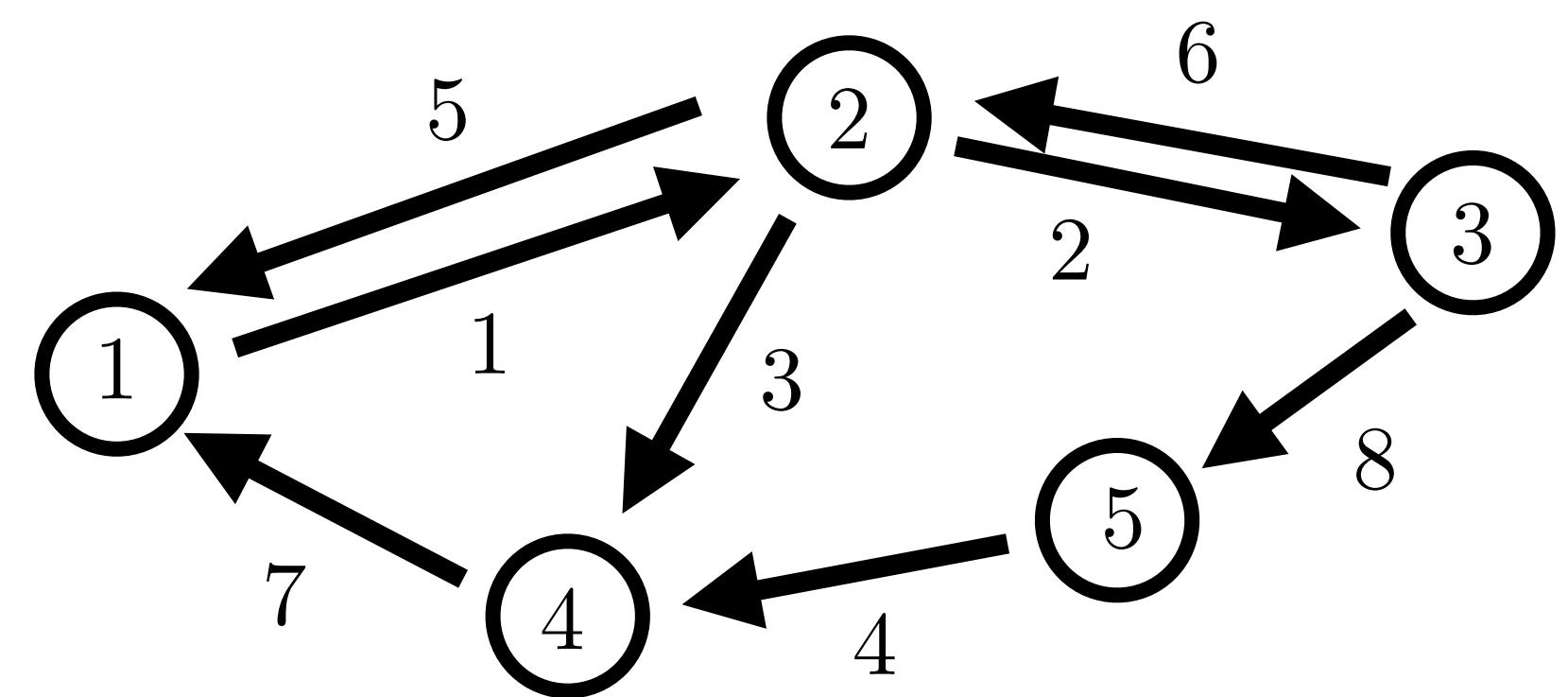
$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

General Matrix

$$A \in \mathbb{R}^{m \times n}$$

$$A = \begin{bmatrix} | & & | \\ A_1 & \dots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$



Review: Shape Matrices

Graph Laplacians

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

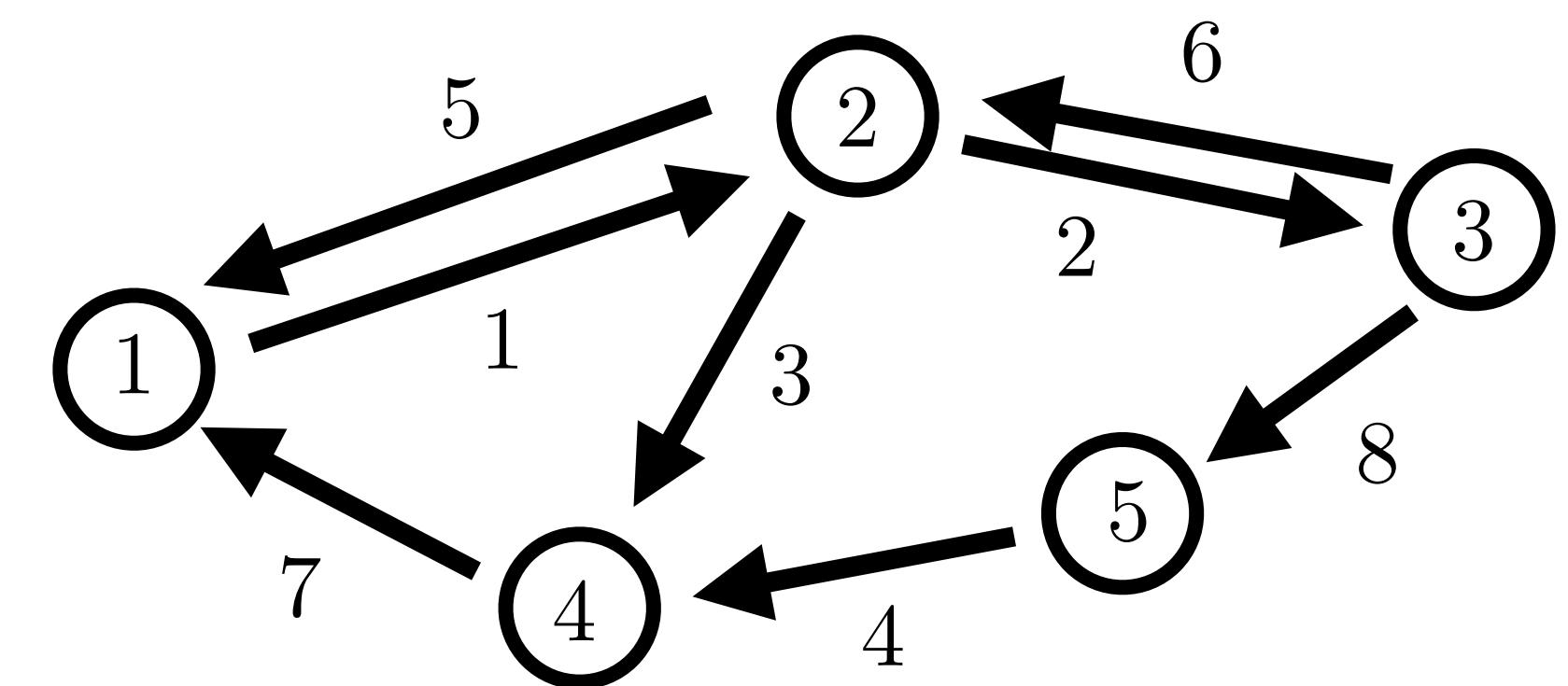
General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \cdots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ \vdots & & \vdots \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

$$A^T A = \begin{bmatrix} A_1^T A_1 & \cdots & A_1^T A_n \\ \vdots & & \vdots \\ A_n^T A_1 & \cdots & A_n^T A_n \end{bmatrix}$$

$$A A^T = \begin{bmatrix} a_1^T a_1 & \cdots & a_1^T a_m \\ \vdots & & \vdots \\ a_m^T a_1 & \cdots & a_m^T a_m \end{bmatrix}$$



Review: Shape Matrices

Inner products
of columns

“Relative geometry
of columns”

Inner products
of rows

“Relative geometry
of rows”

Graph Laplacians

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

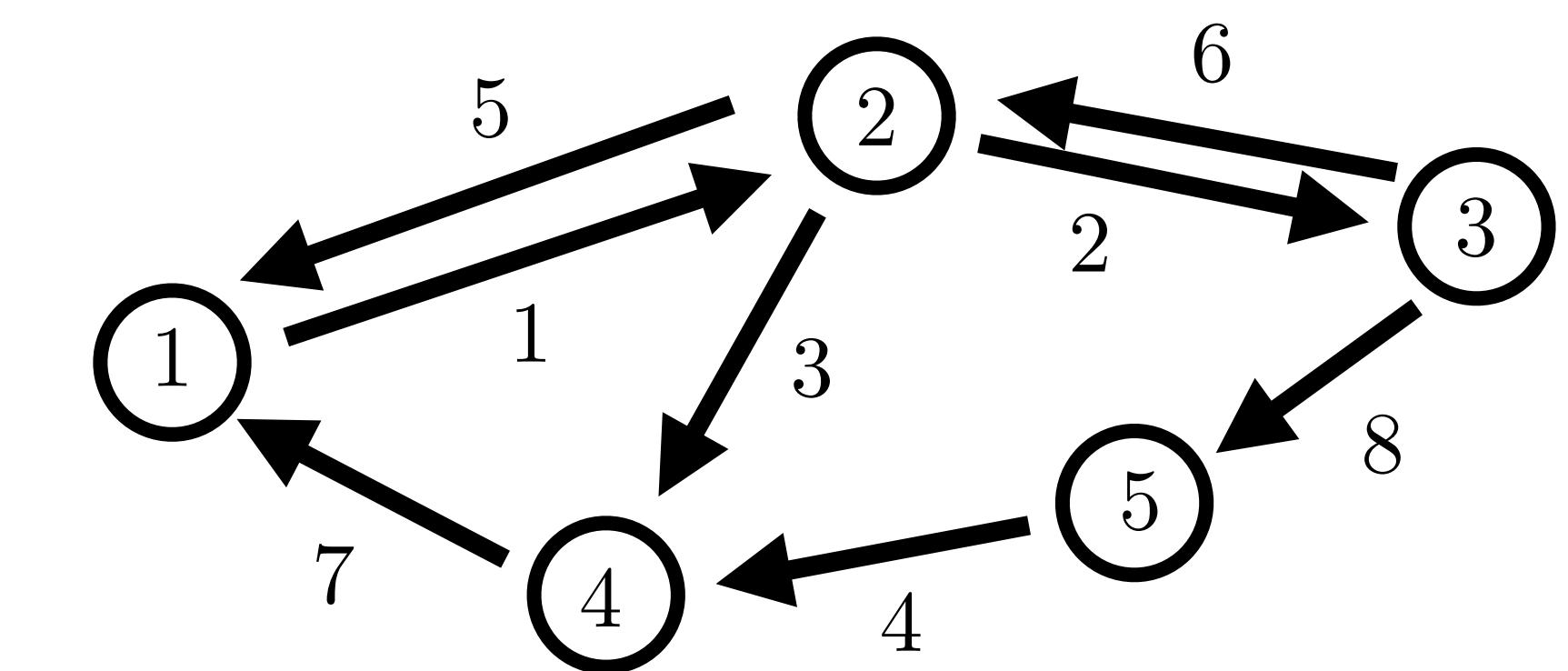
General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \cdots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ \vdots & & \vdots \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

$$A^T A = \begin{bmatrix} A_1^T A_1 & \cdots & A_1^T A_n \\ \vdots & & \vdots \\ A_n^T A_1 & \cdots & A_n^T A_n \end{bmatrix}$$

$$AA^T = \begin{bmatrix} a_1^T a_1 & \cdots & a_1^T a_m \\ \vdots & & \vdots \\ a_m^T a_1 & \cdots & a_m^T a_m \end{bmatrix}$$



Review: Shape Matrices

RA rotate columns of A ...
....relative geometry stays the same.

$$(RA)^T (RA) = A^T R^T RA = A^T A$$

AR rotate rows of A ...
....relative geometry stays the same.

$$(AR)(AR)^T = ARR^T A^T = AA^T$$

Graph Laplacians

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E}) \quad \begin{array}{l} \text{Vertices} \\ v \in \mathcal{V} \end{array} \quad \begin{array}{l} \text{Edges} \\ e \in \mathcal{E} \end{array} \quad \begin{array}{l} e = (v, v') \end{array}$$

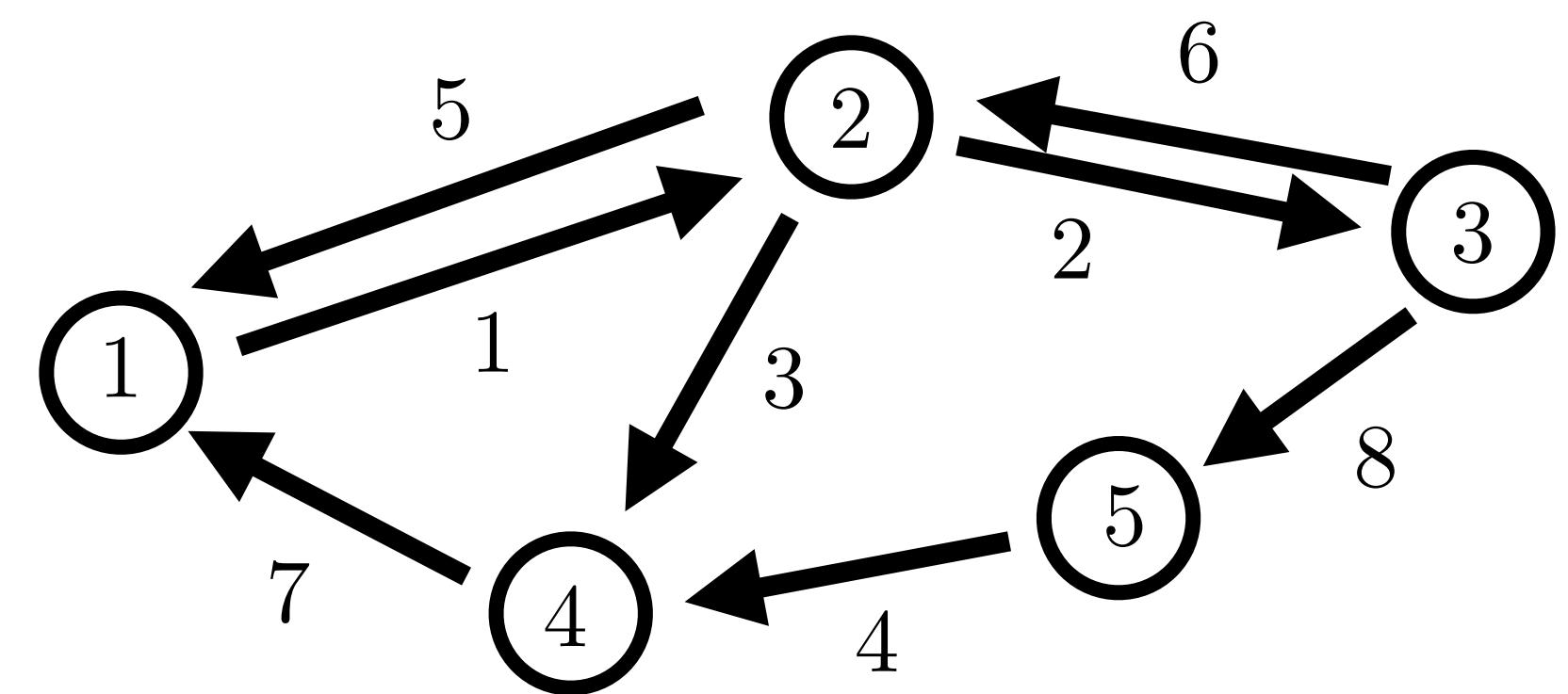
Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \dots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$



Review: Shape Matrices

“Shape” of the columns of A

$$A^T A$$

Graph Laplacians

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

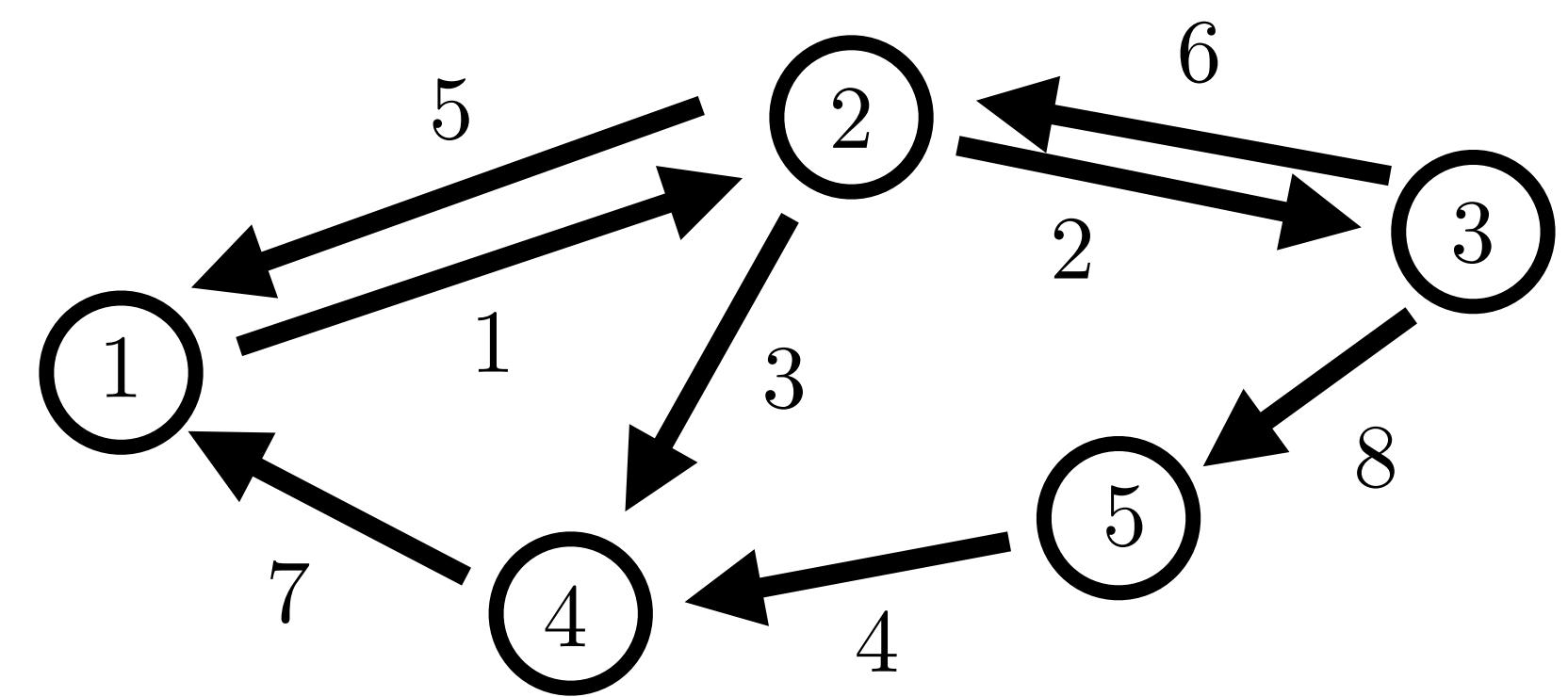
Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \dots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$



Review: Shape Matrices

~~“Shape” of the columns of A~~

Graph Laplacians

Graph:
 $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

Vertices $v \in \mathcal{V}$
Edges $e \in \mathcal{E}$

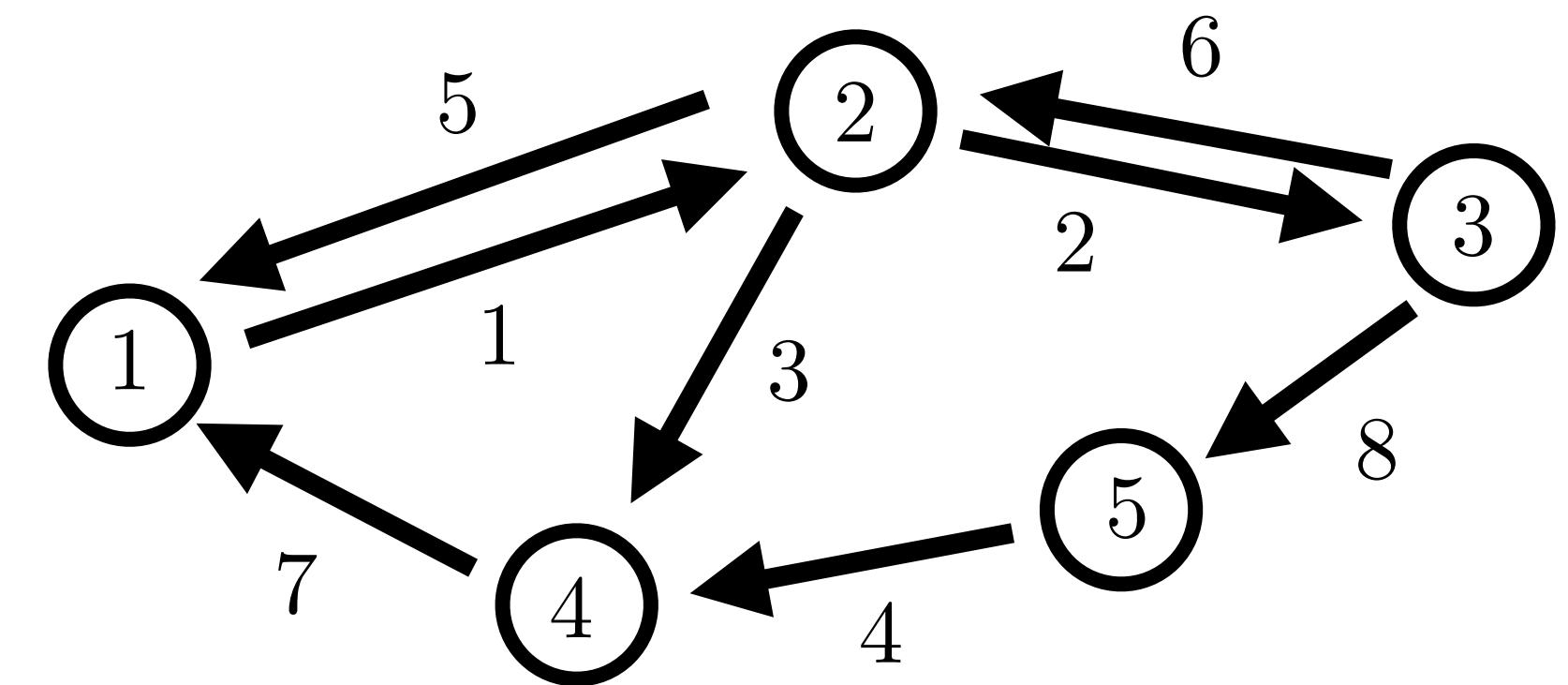
Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \dots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$



Review: Shape Matrices

$(A^T A)^{1/2}$ “Shape” of the columns of A

More
Accurate

Graph Laplacians

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E}) \quad \begin{array}{l} \text{Vertices} \\ v \in \mathcal{V} \end{array} \quad \begin{array}{l} \text{Edges} \\ e \in \mathcal{E} \end{array} \quad e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

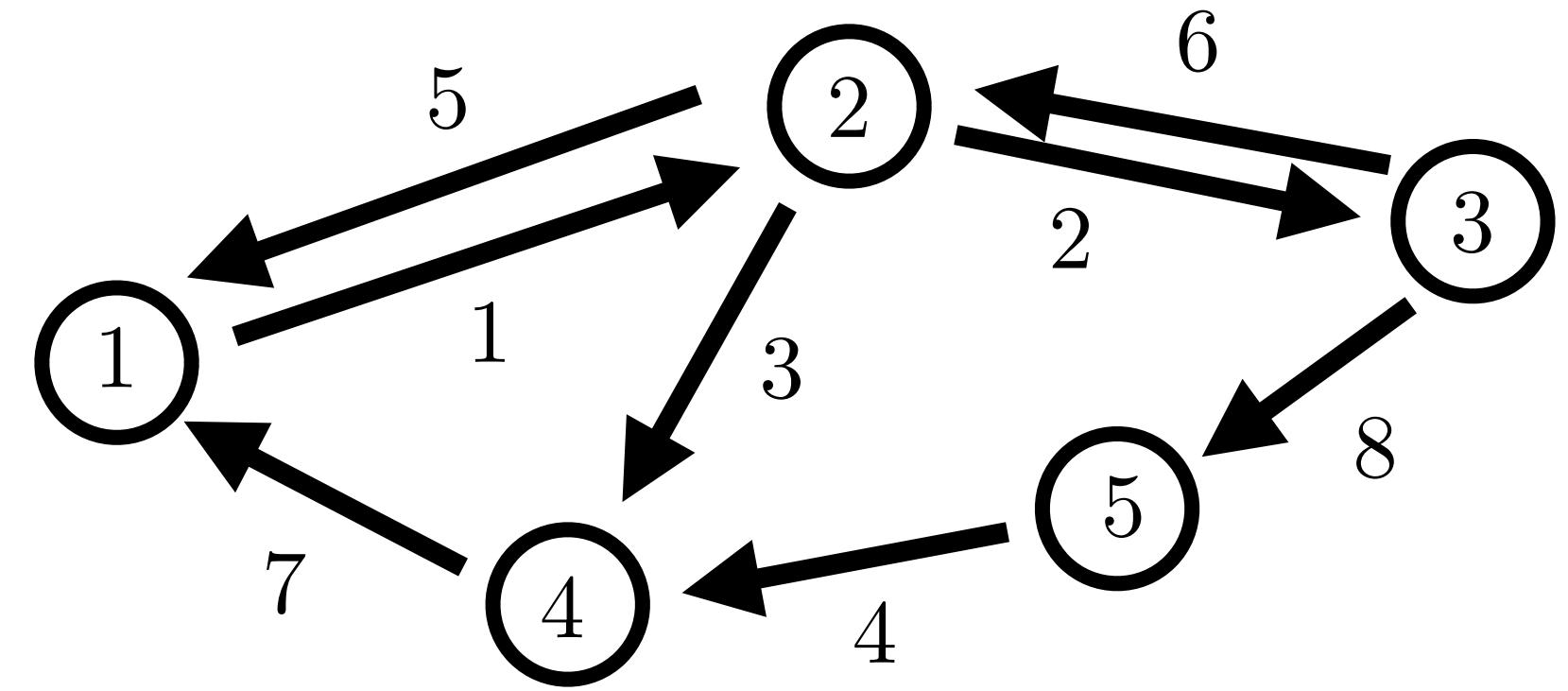
$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$(A^T A)^{1/2}$$

General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \dots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$



Review: Shape Matrices

“Shape” of columns

$(AA^T)^{1/2}$ “Shape” of rows

Graph Laplacians

Graph: **Vertices** $v \in \mathcal{V}$
 $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ **Edges** $e \in \mathcal{E}$ $e = (v, v')$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

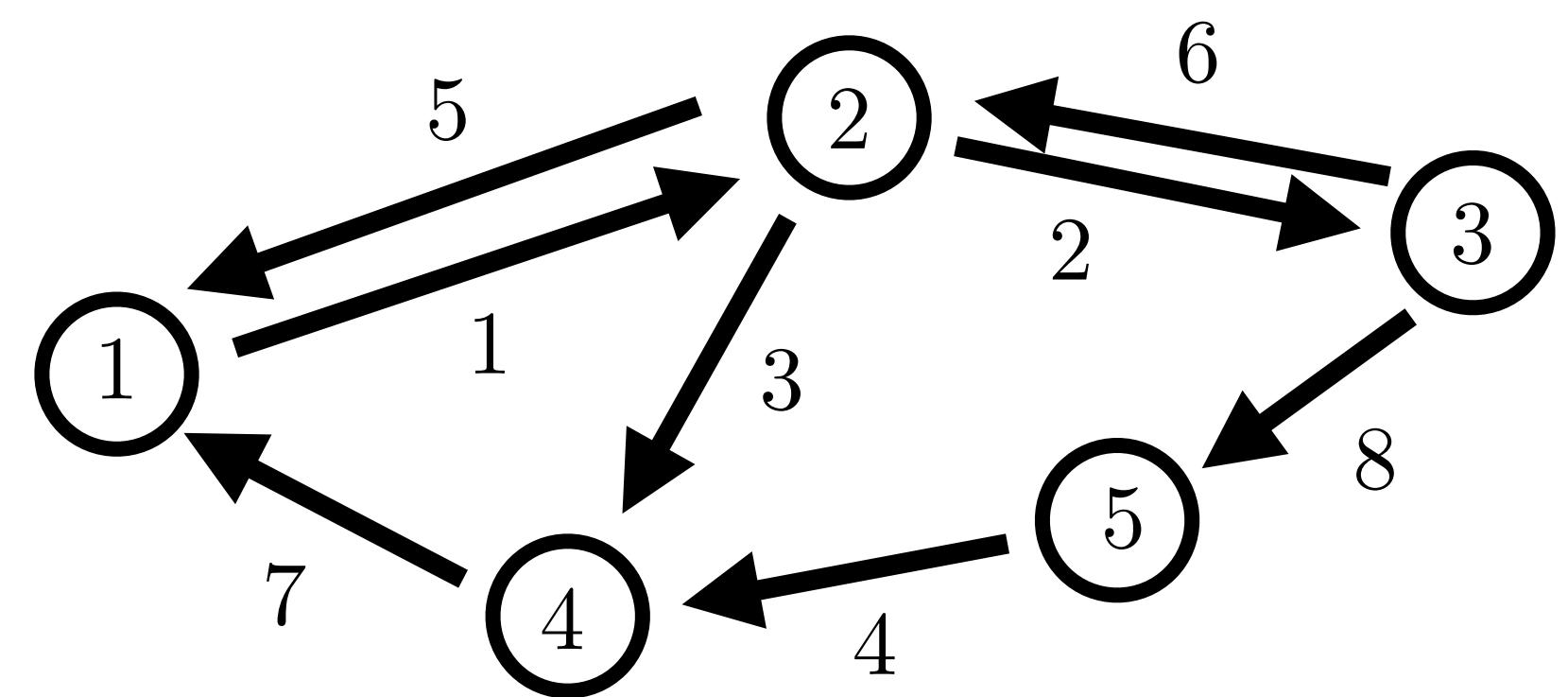
$$(A^T A)^{1/2} \quad \text{"Shape" of columns} \quad (AA^T)^{1/2} \quad \text{"Shape" of rows}$$

General Matrix $A \in \mathbb{R}^{m \times n}$

$$\text{Analogy: } z \in \mathbb{C} \quad |z| = \sqrt{z^* z} \quad z = |z|e^{i\phi}$$

$$A = \begin{bmatrix} | & & | \\ A_1 & \dots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$



Review: Shape Matrices

Graph Laplacians

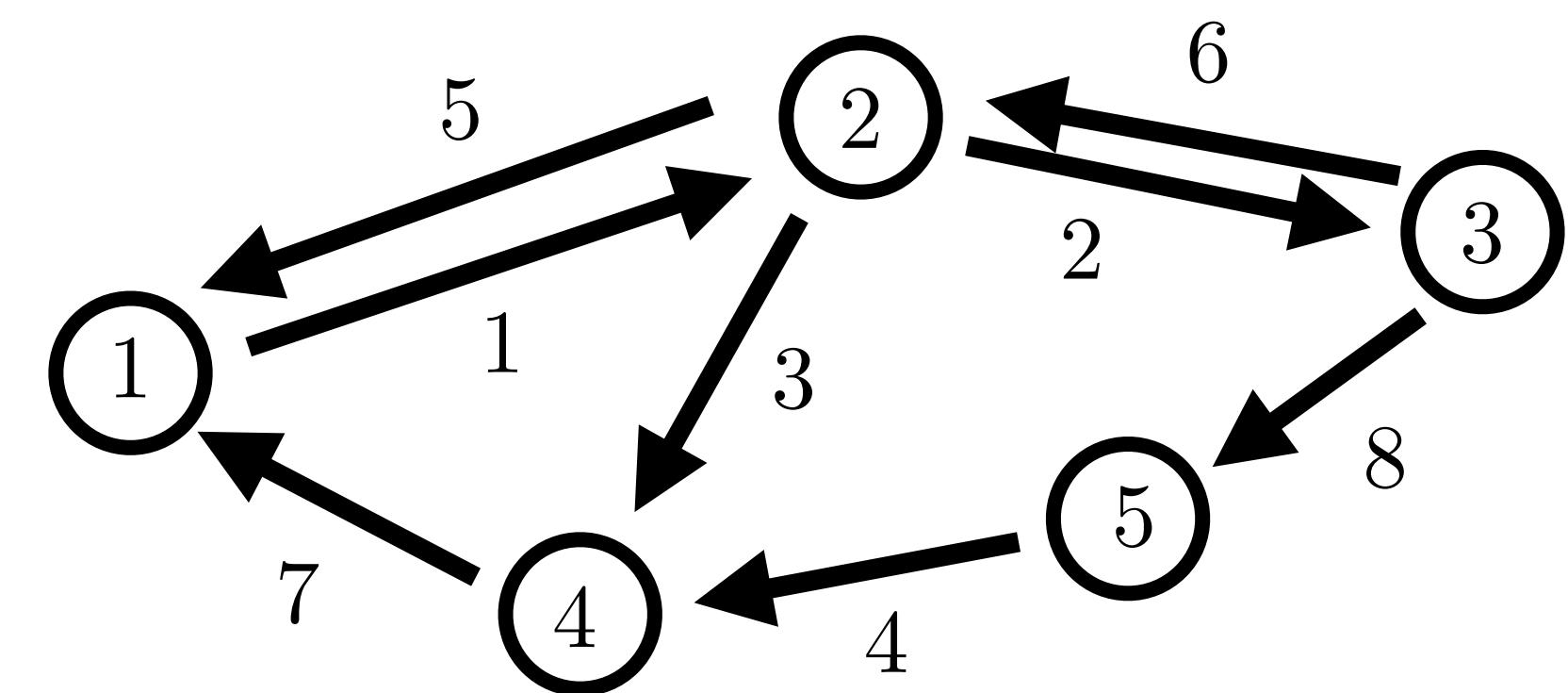
Graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

Vertices	$v \in \mathcal{V}$
Edges	$e \in \mathcal{E}$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$e = (v, v')$$



General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \cdots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

Polar Decomposition

Analogy:

$$z \in \mathbb{C} \quad |z| = \sqrt{z^* z}$$

$$z = |z|e^{i\phi}$$

$$A = A(A^T A)^{-1/2} \cdot (A^T A)^{1/2}$$

Rotation

PSD “shape”

“Column version”

Graph Laplacians

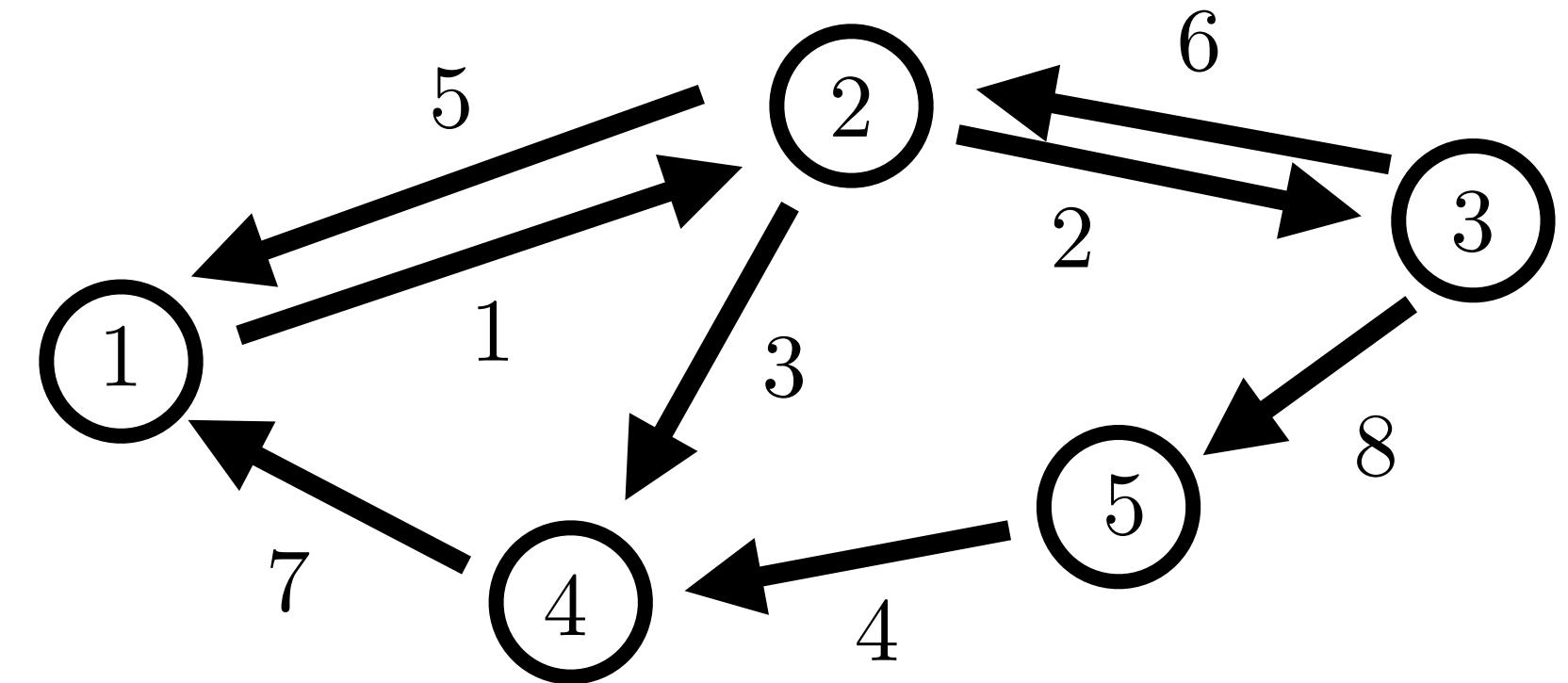
Graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

Vertices	$v \in \mathcal{V}$
Edges	$e \in \mathcal{E}$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$e = (v, v')$$



General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \cdots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

Polar Decomposition

$$(A^T A)^{1/2} \quad \text{“Shape” of columns} \quad (AA^T)^{1/2} \quad \text{“Shape” of rows}$$

$$\text{Analogy: } z \in \mathbb{C} \quad |z| = \sqrt{z^* z} \quad z = |z|e^{i\phi}$$

$$A = A(A^T A)^{-1/2} \cdot (A^T A)^{1/2}$$

Rotation PSD “shape”

$$A = (AA^T)^{1/2} \cdot (AA^T)^{-1/2} A$$

PSD “shape” Rotation

“Column version”

“Row version”

Graph Laplacians

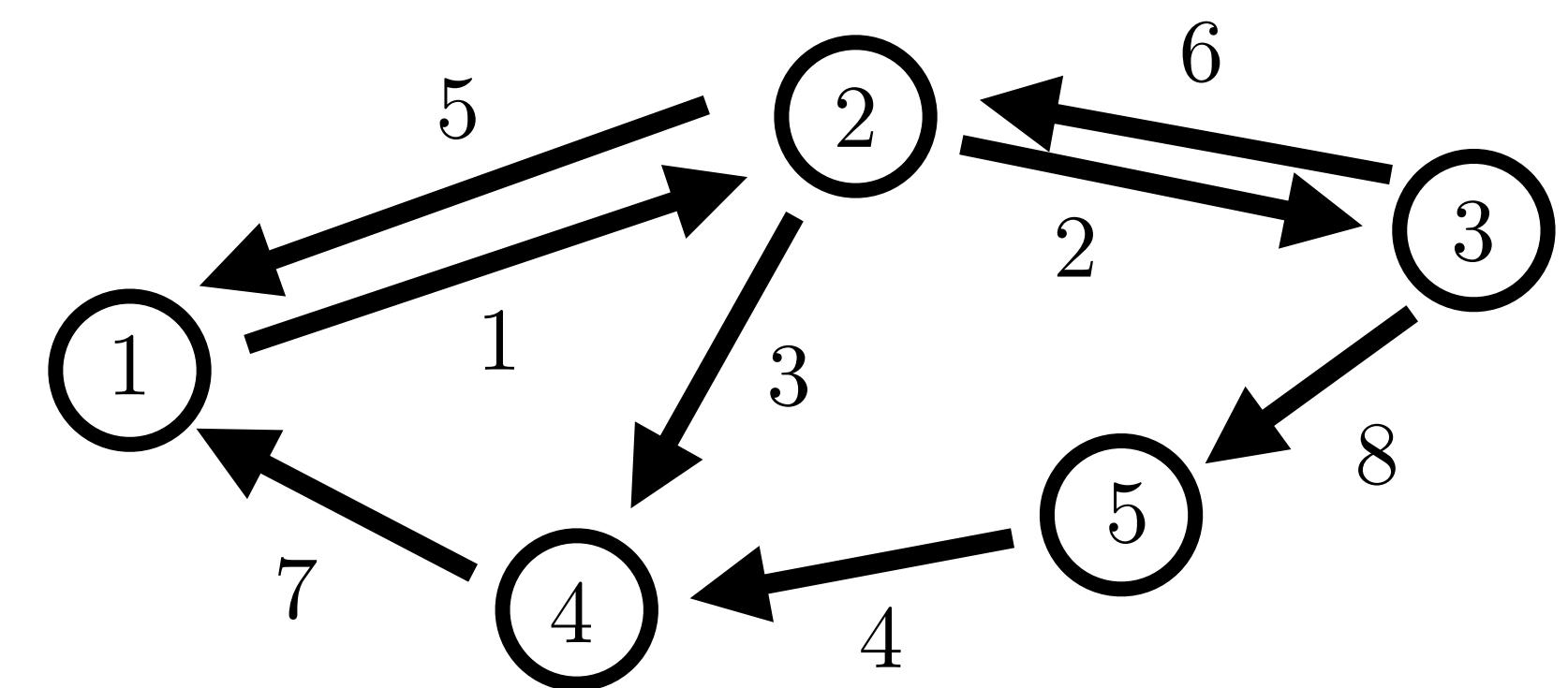
Graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

Vertices	$v \in \mathcal{V}$
Edges	$e \in \mathcal{E}$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$e = (v, v')$$



General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \cdots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

Polar Decomposition

Checking rotation...

$$(A^T A)^{1/2} \quad \text{"Shape" of columns} \quad (AA^T)^{1/2} \quad \text{"Shape" of rows}$$

$$\text{Analogy: } z \in \mathbb{C} \quad |z| = \sqrt{z^* z} \quad z = |z|e^{i\phi}$$

$$A = A(A^T A)^{-1/2} \cdot (A^T A)^{1/2}$$

Rotation PSD "shape"

$$A = (AA^T)^{1/2} \cdot (AA^T)^{-1/2} A$$

PSD "shape" Rotation

"Column version"

"Row version"

$$(A^T A)^{-1/2} A^T A (A^T A)^{-1/2} = I$$

Graph Laplacians

Graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

Vertices	$v \in \mathcal{V}$
Edges	$e \in \mathcal{E}$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

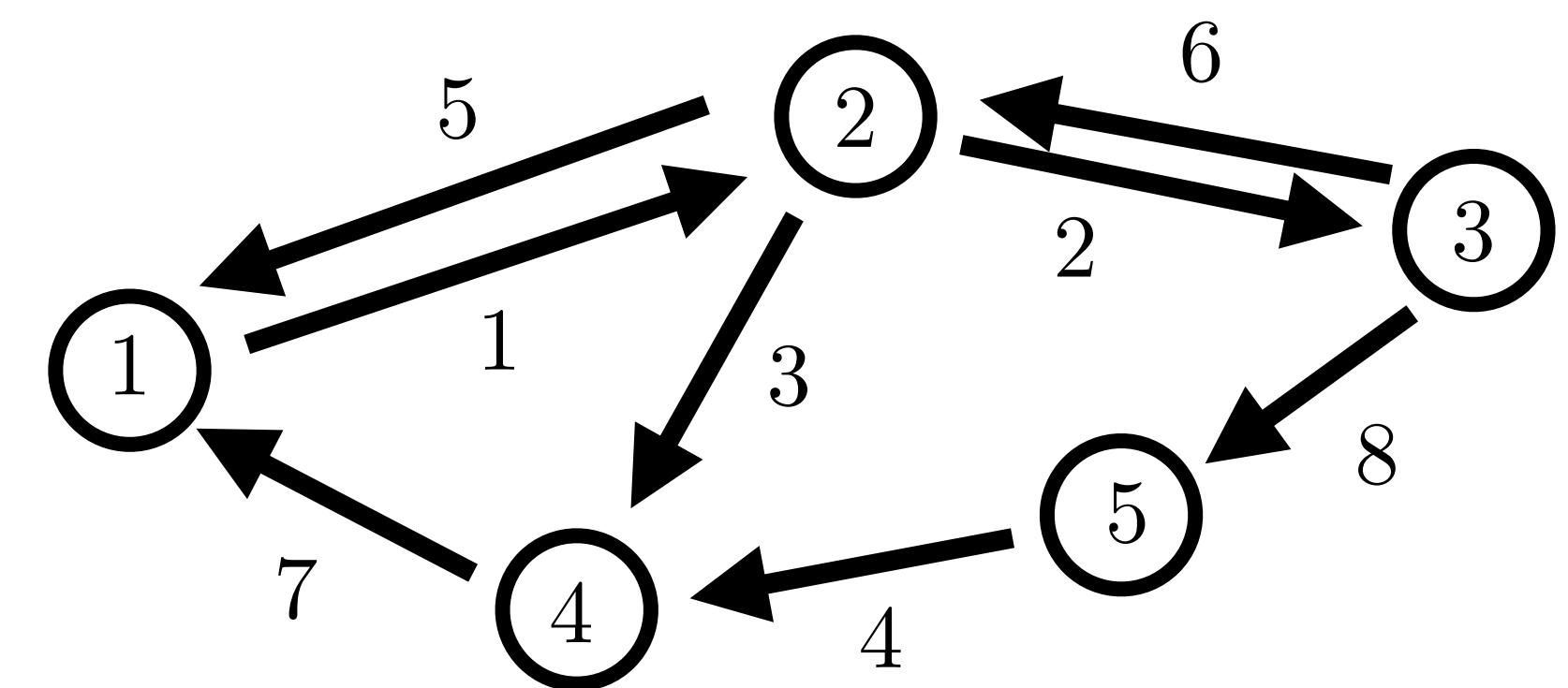
$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \cdots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

$$e = (v, v')$$



Review: Shape Matrices

$$(A^T A)^{1/2} \quad \text{"Shape" of columns} \quad (AA^T)^{1/2} \quad \text{"Shape" of rows}$$

EVD of Shapes

$$(A^T A)^{1/2} = V \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T \quad (AA^T)^{1/2} = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Polar Decomposition

$$A = A(A^T A)^{-1/2} \cdot (A^T A)^{1/2}$$

Rotation PSD "shape"

$$A = (AA^T)^{1/2} \cdot (AA^T)^{-1/2} A$$

PSD "shape" Rotation

"Column version"

"Row version"

Graph Laplacians

Graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

Vertices	$v \in \mathcal{V}$
Edges	$e \in \mathcal{E}$

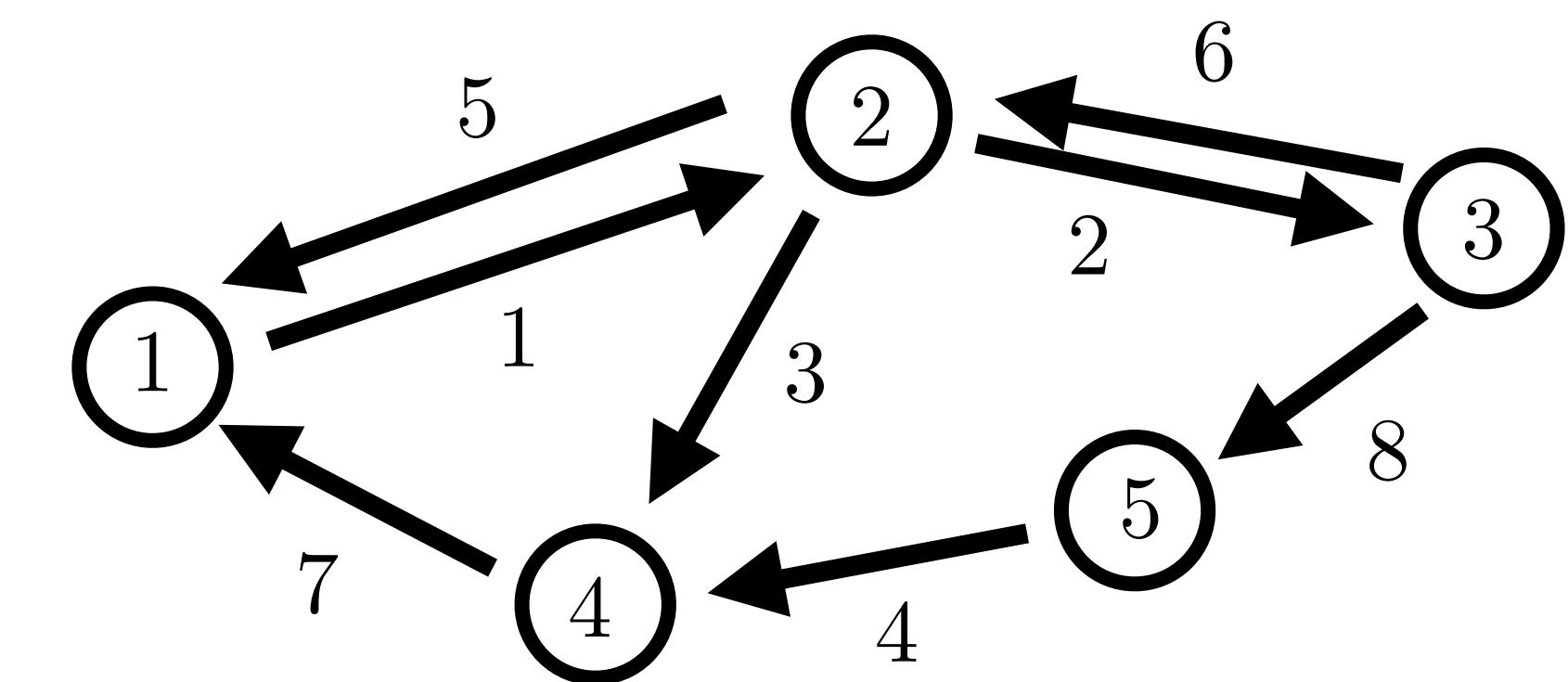
Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \cdots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$



Review: Shape Matrices

$$(A^T A)^{1/2} \quad \text{"Shape" of columns} \quad (AA^T)^{1/2} \quad \text{"Shape" of rows}$$

$$\text{EVD of Shapes} \quad (A^T A)^{1/2} = V \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T \quad (AA^T)^{1/2} = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} U^T$$

$$\text{Polar Decomposition} \quad A = UV^T \cdot V \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T \quad \text{"Column version"}$$

$$\begin{array}{ccc} \text{Rotation} & \text{PSD "shape"} & \\ A = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} U^T \cdot UV^T & & \text{"Row version"} \\ \text{PSD "shape"} & & \text{Rotation} \end{array}$$

Graph Laplacians

Graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

Vertices	$v \in \mathcal{V}$
Edges	$e \in \mathcal{E}$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

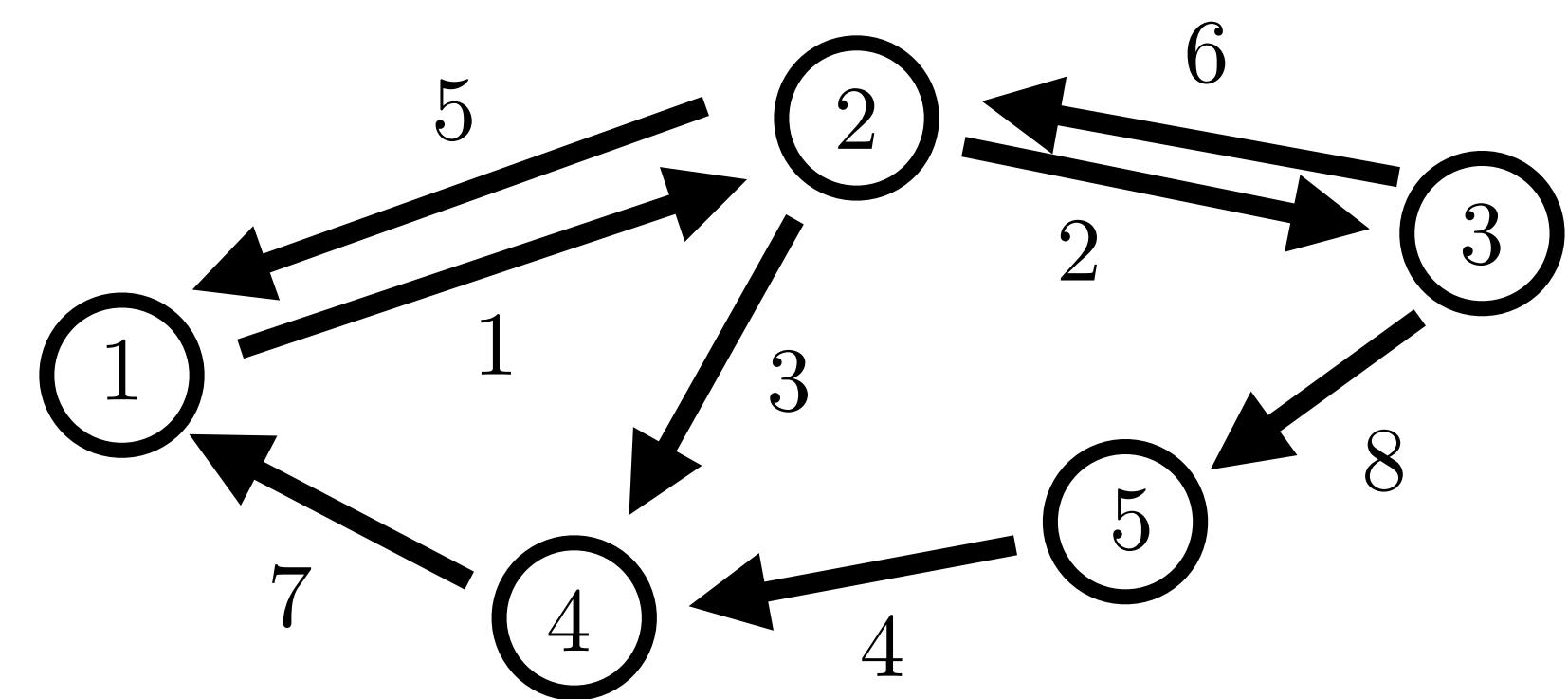
$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \dots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ \vdots & & \vdots \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

$$e = (v, v')$$



Review: Shape Matrices

$$(A^T A)^{1/2} \quad \text{"Shape" of columns} \quad (A A^T)^{1/2} \quad \text{"Shape" of rows}$$

EVD of Shapes

$$(A^T A)^{1/2} = V \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T \quad (A A^T)^{1/2} = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Singular Value Decomposition

$$A = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$$

Graph Laplacians

Graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

Vertices	$v \in \mathcal{V}$
Edges	$e \in \mathcal{E}$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

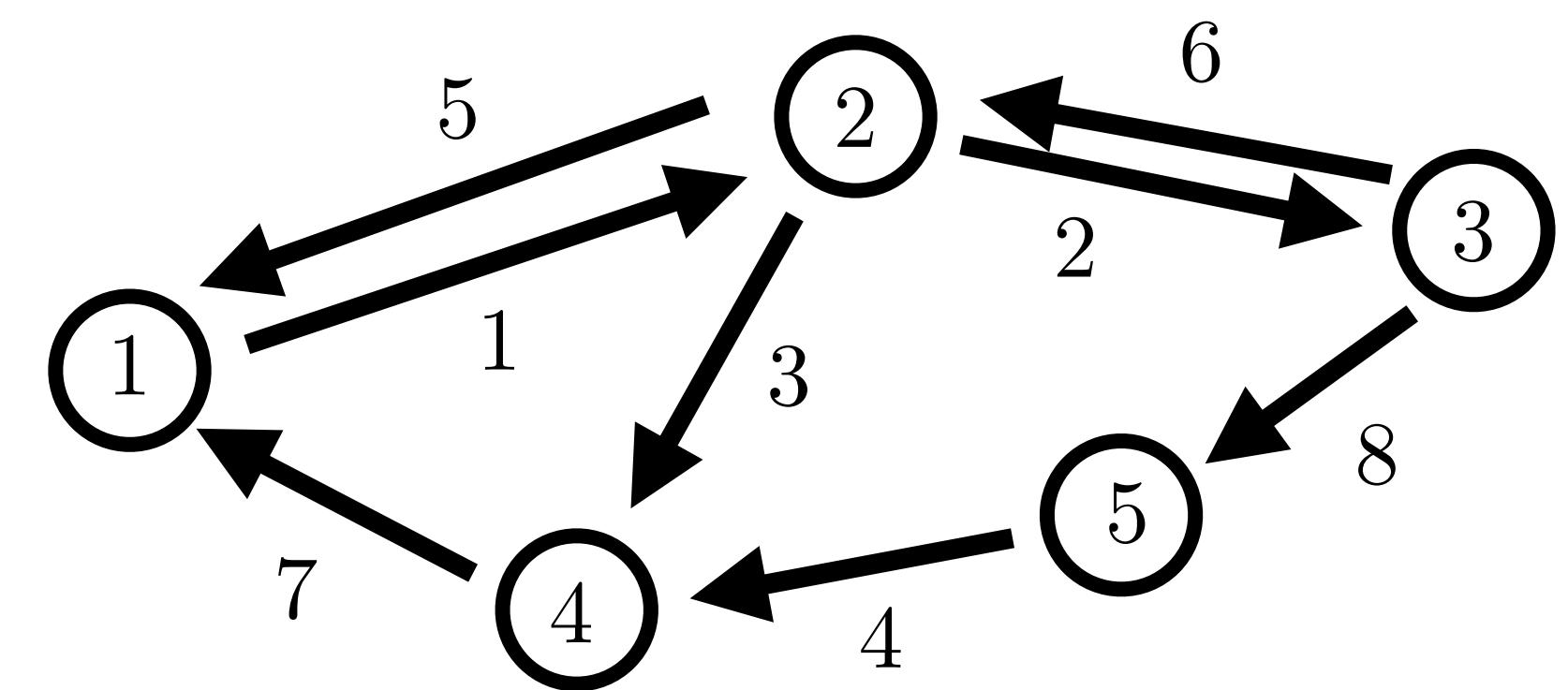
$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

General Matrix $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \dots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

$$= \begin{bmatrix} - & a_1^T & - \\ \vdots & & \vdots \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

$$e = (v, v')$$



Review: Shape Matrices

$$(A^T A)^{1/2} \quad \text{"Shape" of columns} \quad (AA^T)^{1/2} \quad \text{"Shape" of rows}$$

EVD of Shapes

$$(A^T A)^{1/2} = V \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T \quad (AA^T)^{1/2} = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Singular Value Decomposition

$$A = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$$

$$U' = AV'\Sigma^{-1} \quad V'^T = \Sigma^{-1}U'^T A$$

for singular vectors w/ non-zero values

Graph Laplacians

Graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ **Vertices** $v \in \mathcal{V}$ **Edges** $e \in \mathcal{E}$ $e = (v, v')$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

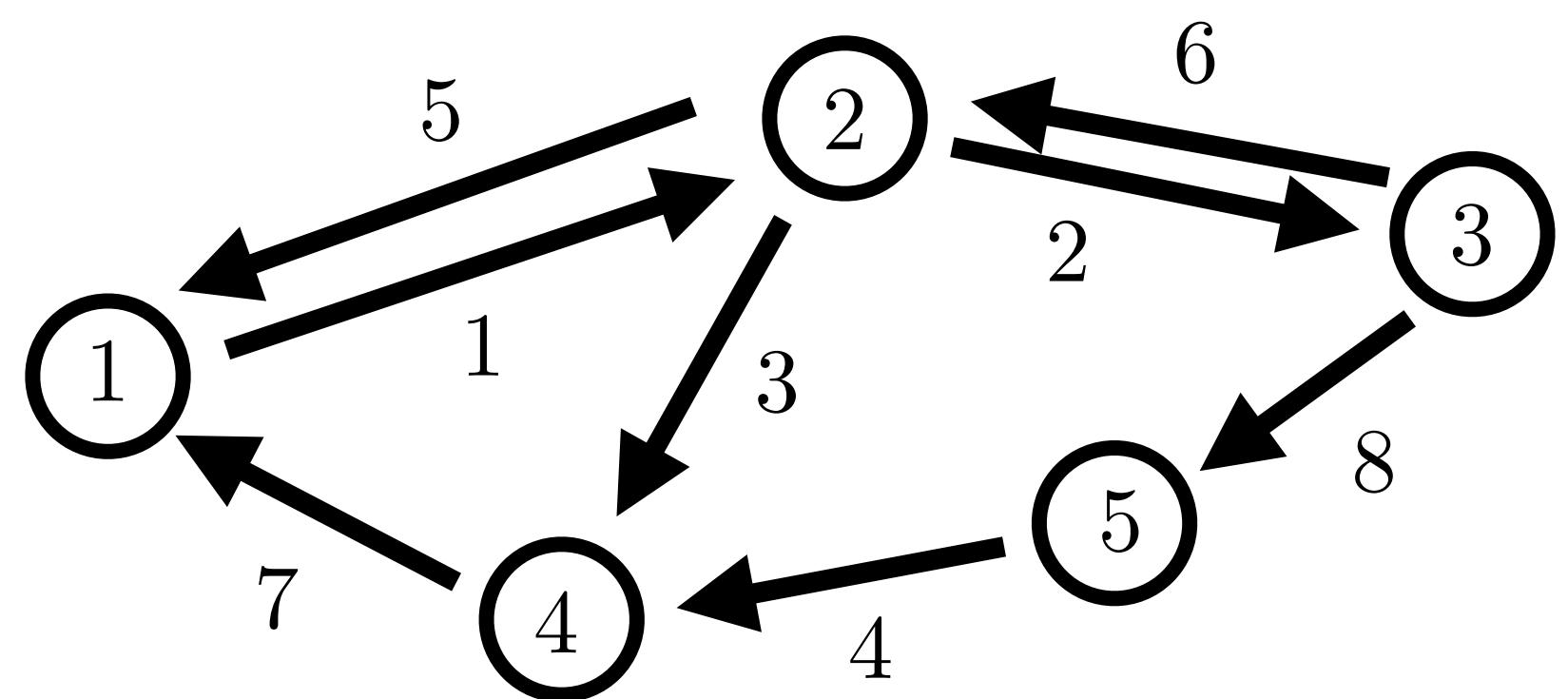
Incidence SVD $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

Laplacian row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Edge-Laplacian col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



Graph Laplacians

Graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

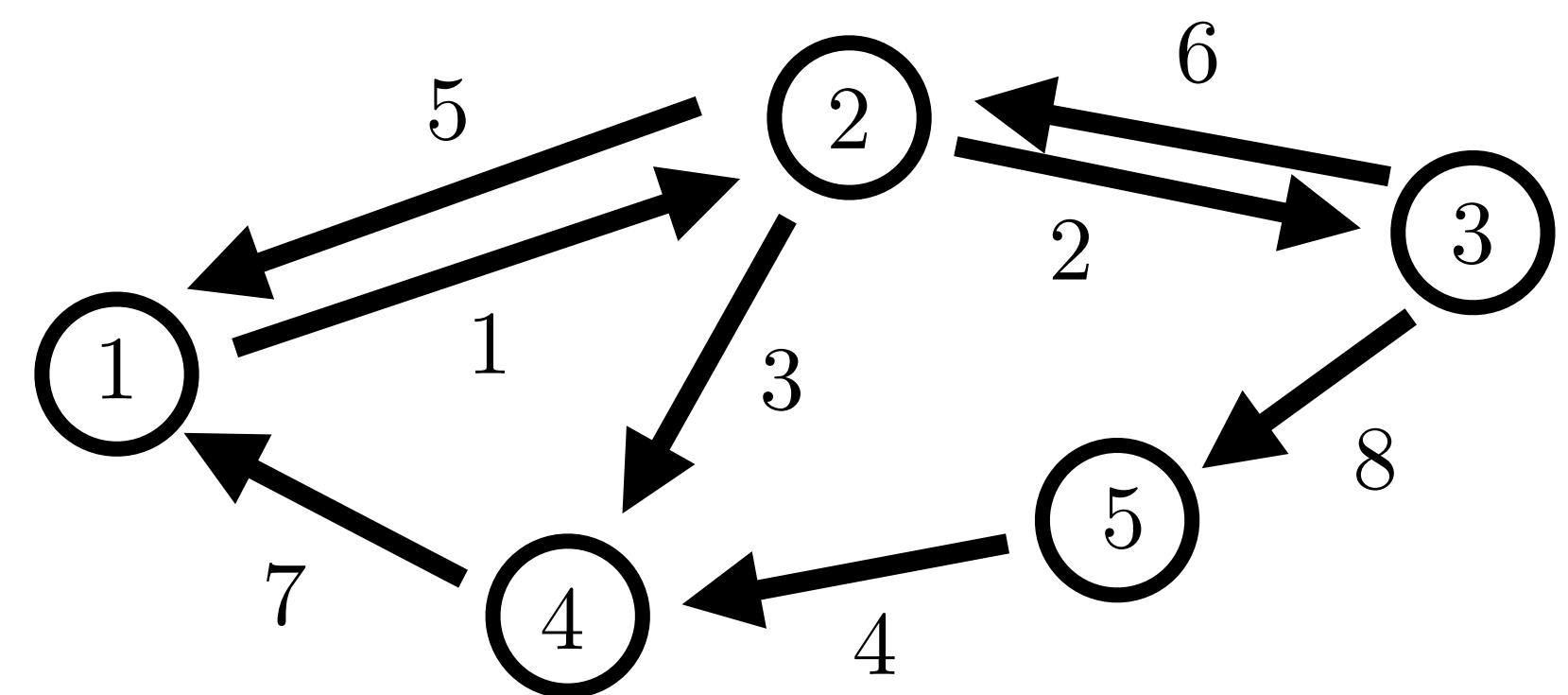
Vertices	$v \in \mathcal{V}$
Edges	$e \in \mathcal{E}$
	$e = (v, v')$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Incidence SVD $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

Laplacian $L = DD^T$



Laplacian row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Edge-Laplacian col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$

Graph Laplacians

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Incidence SVD

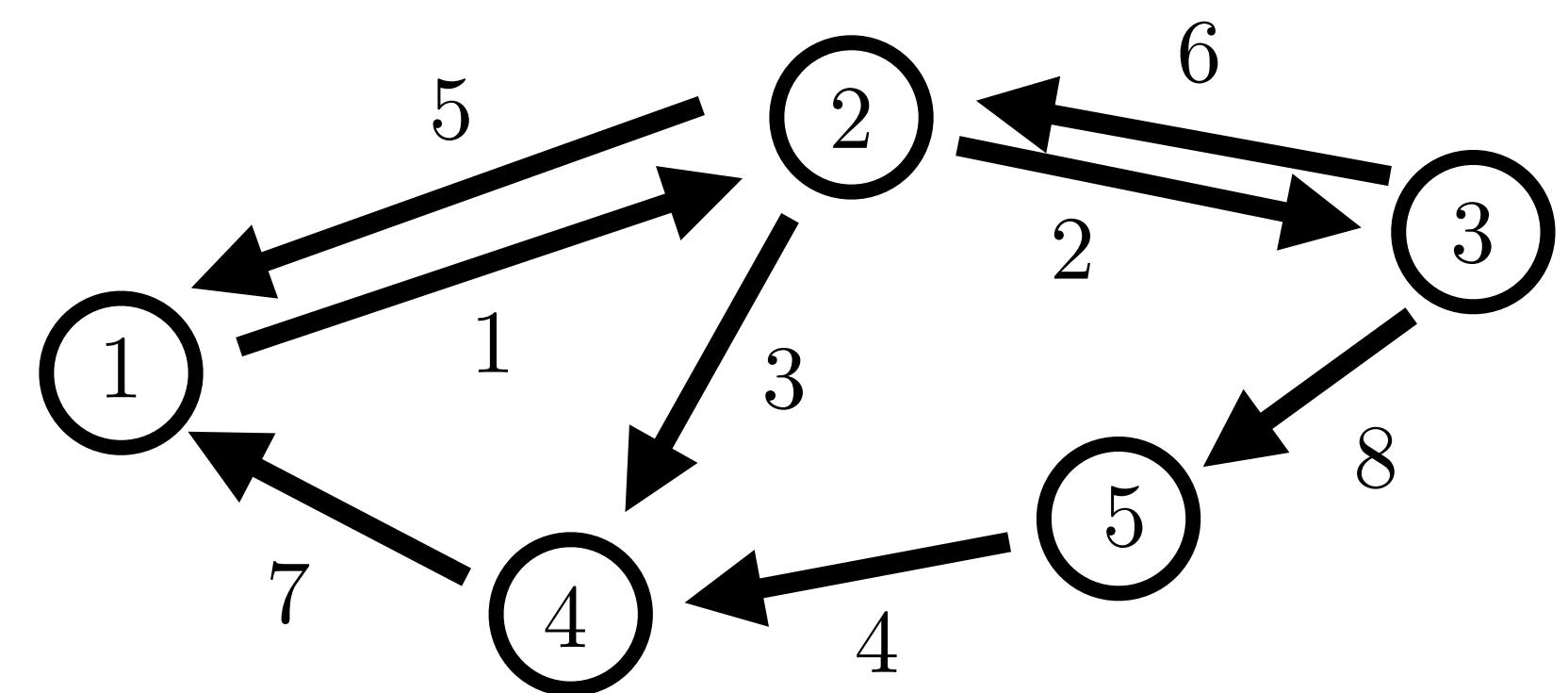
$$D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$$

Laplacian row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Edge-Laplacian col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



Laplacian $L = DD^T$

$$\text{Action: } Lu = \underbrace{\begin{bmatrix} D \\ D^T \end{bmatrix}}_{\text{...tension created in edges}} \begin{bmatrix} u \\ u \end{bmatrix} \quad \text{“heights” of nodes}$$

\dots summed resulting tension on nodes

Graph Laplacians

Graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

Vertices	$v \in \mathcal{V}$
Edges	$e \in \mathcal{E}$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

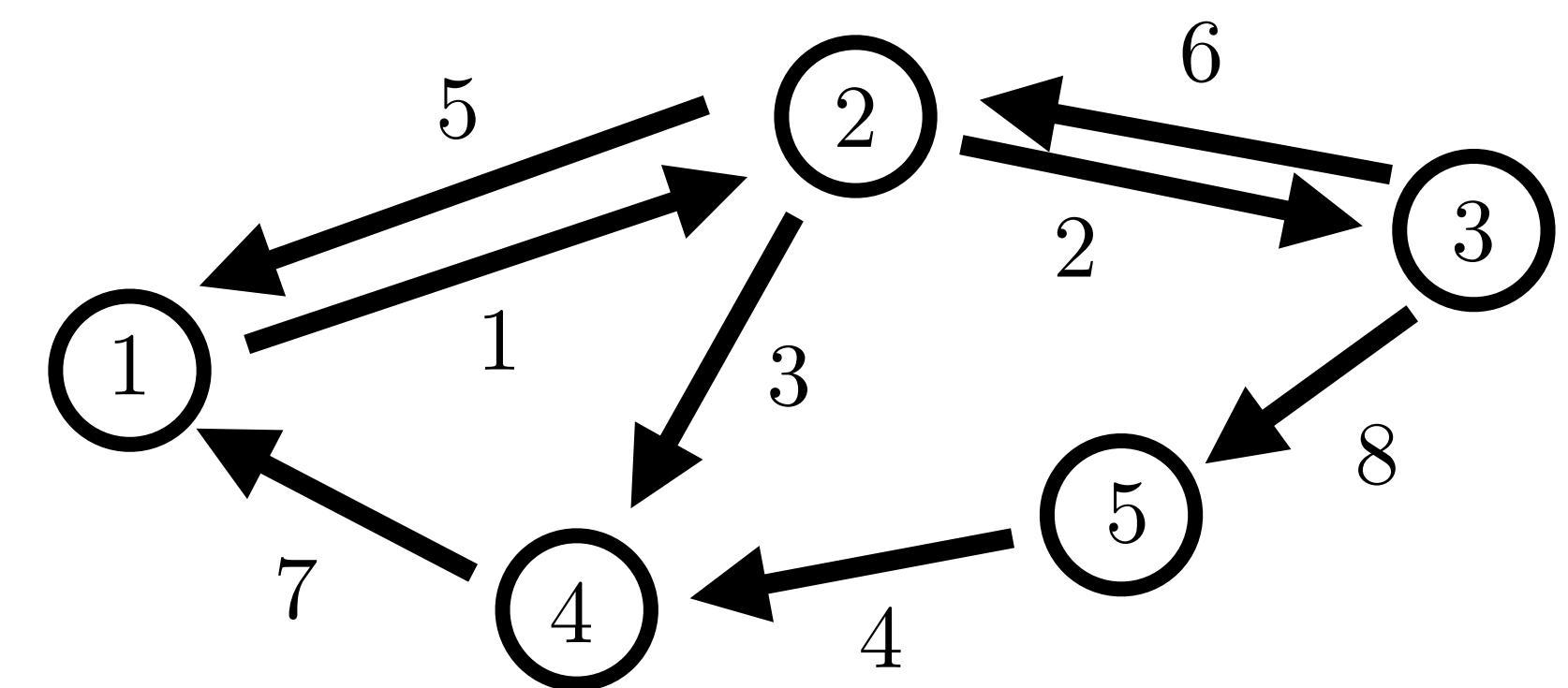
Incidence SVD $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

Laplacian row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Edge-Laplacian col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



Laplacian $L = DD^T$

Action: $Lu = \underbrace{\begin{bmatrix} D \end{bmatrix}}_{\text{...tension created in edges}} \underbrace{\begin{bmatrix} D^T \end{bmatrix}}_{\text{... summed resulting tension on nodes}} \begin{bmatrix} u \\ \vdots \\ u \end{bmatrix}$ “heights” of nodes

Linear ODE

$$\dot{u} = -Lu$$

Eigenvectors are oscillation modes
“Vibration modes” of a graph

Graph Laplacians

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

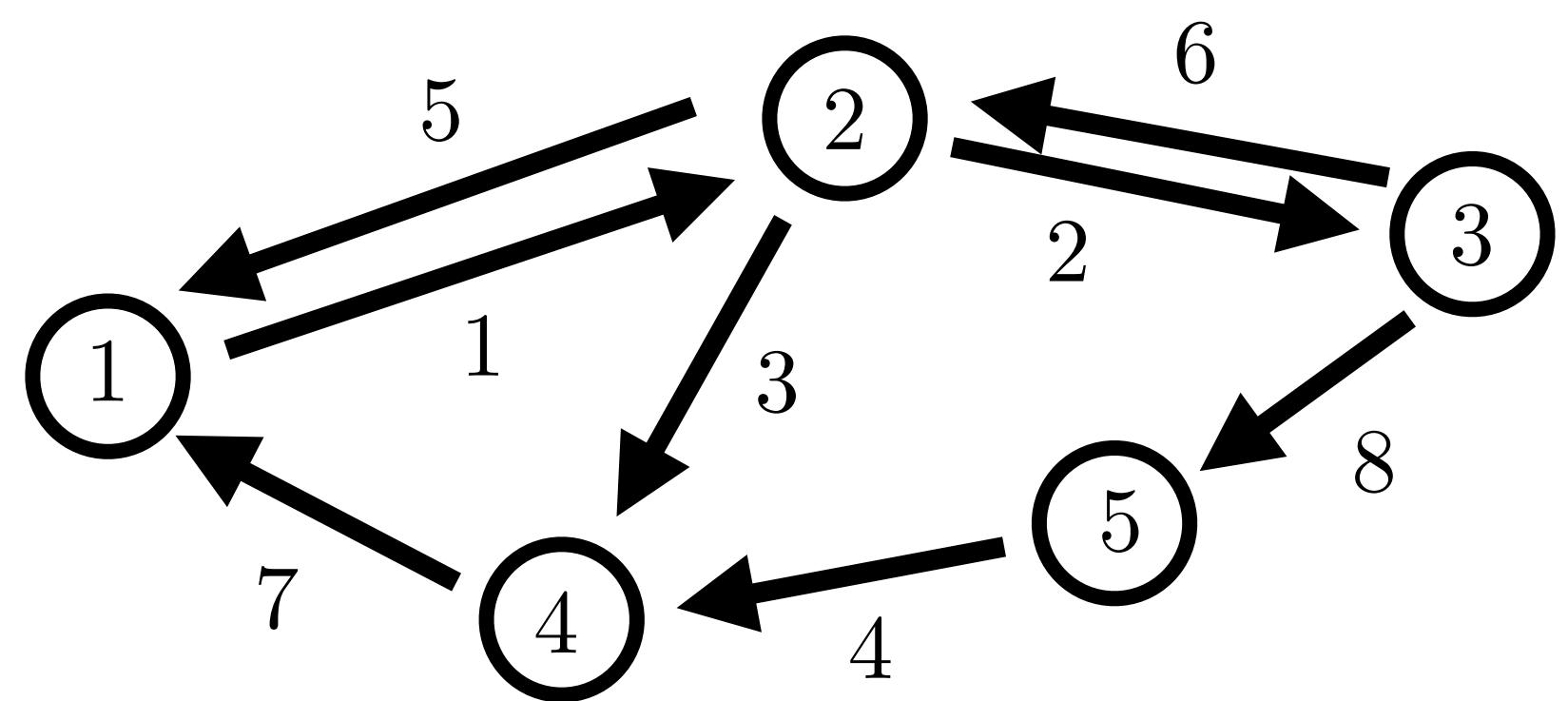
Incidence SVD $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

Laplacian row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Edge-Laplacian col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



Edge Laplacian $L_e = D^T D$

Graph Laplacians

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Incidence SVD

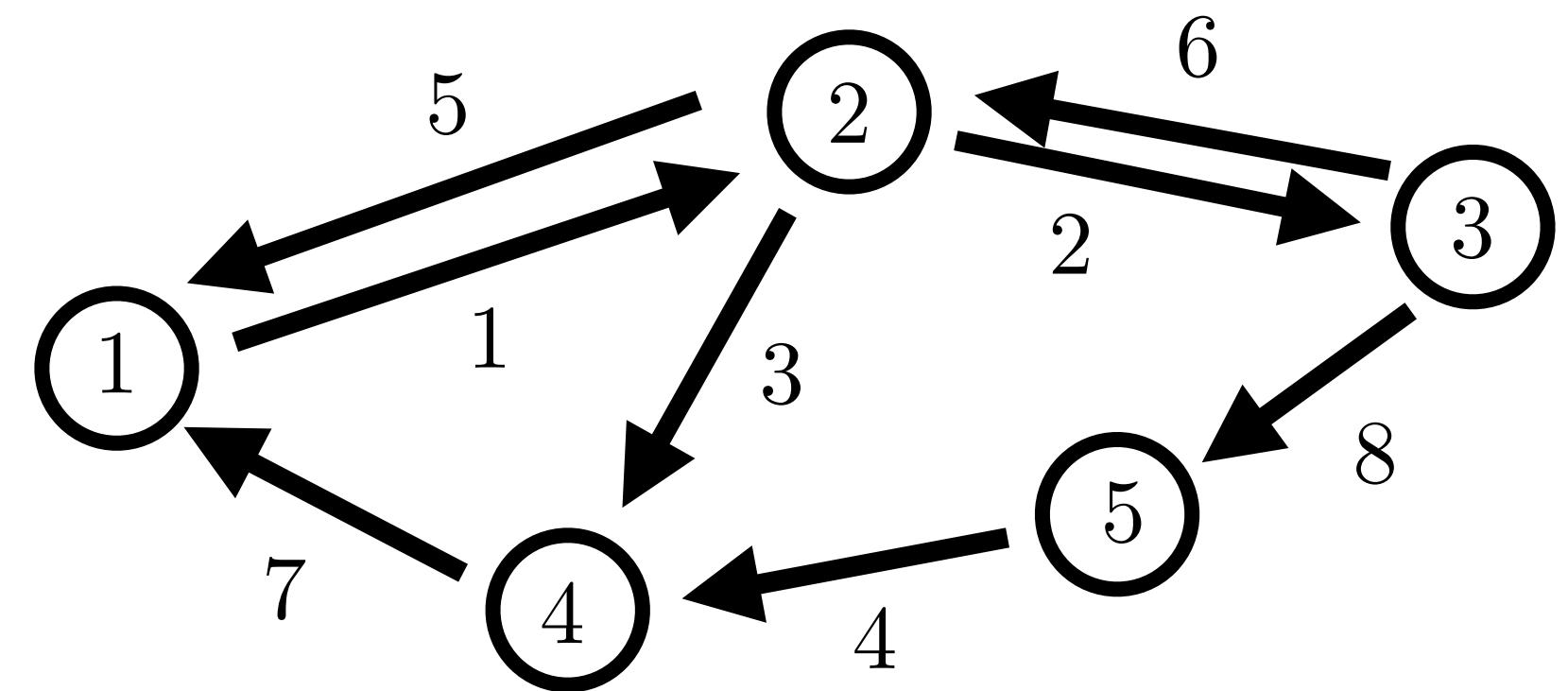
$$D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$$

Laplacian row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Edge-Laplacian col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



Edge Laplacian $L_e = D^T D$

$$\text{Action: } L_e \tau = \underbrace{\begin{bmatrix} D^T \end{bmatrix}}_{\dots \text{ summed tension on nodes}} \underbrace{\begin{bmatrix} D \end{bmatrix}}_{\dots \text{ differential in tension along edges}} \begin{bmatrix} \tau \\ \vdots \\ \tau \end{bmatrix} \quad \text{“Tension” in edges}$$

... differential in tension along edges

Graph Laplacians

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Incidence SVD

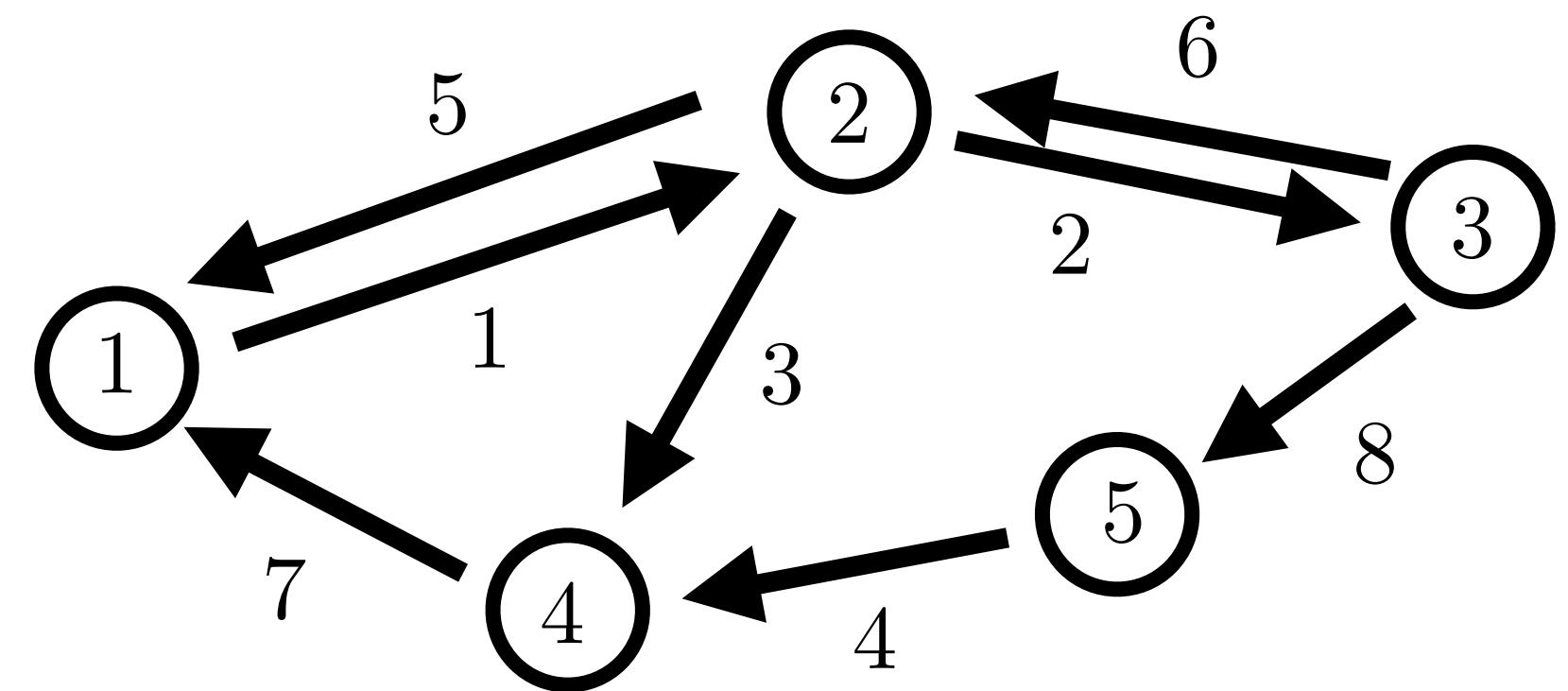
$$D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$$

Laplacian row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Edge-Laplacian col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



Edge Laplacian $L_e = D^T D$

$$\text{Action: } L_e \tau = [D^T] [D] \begin{bmatrix} | \\ \tau \\ | \end{bmatrix}$$

“Tension”
in edges

... summed tension on nodes

... differential in tension along edges

Graph Laplacians

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$

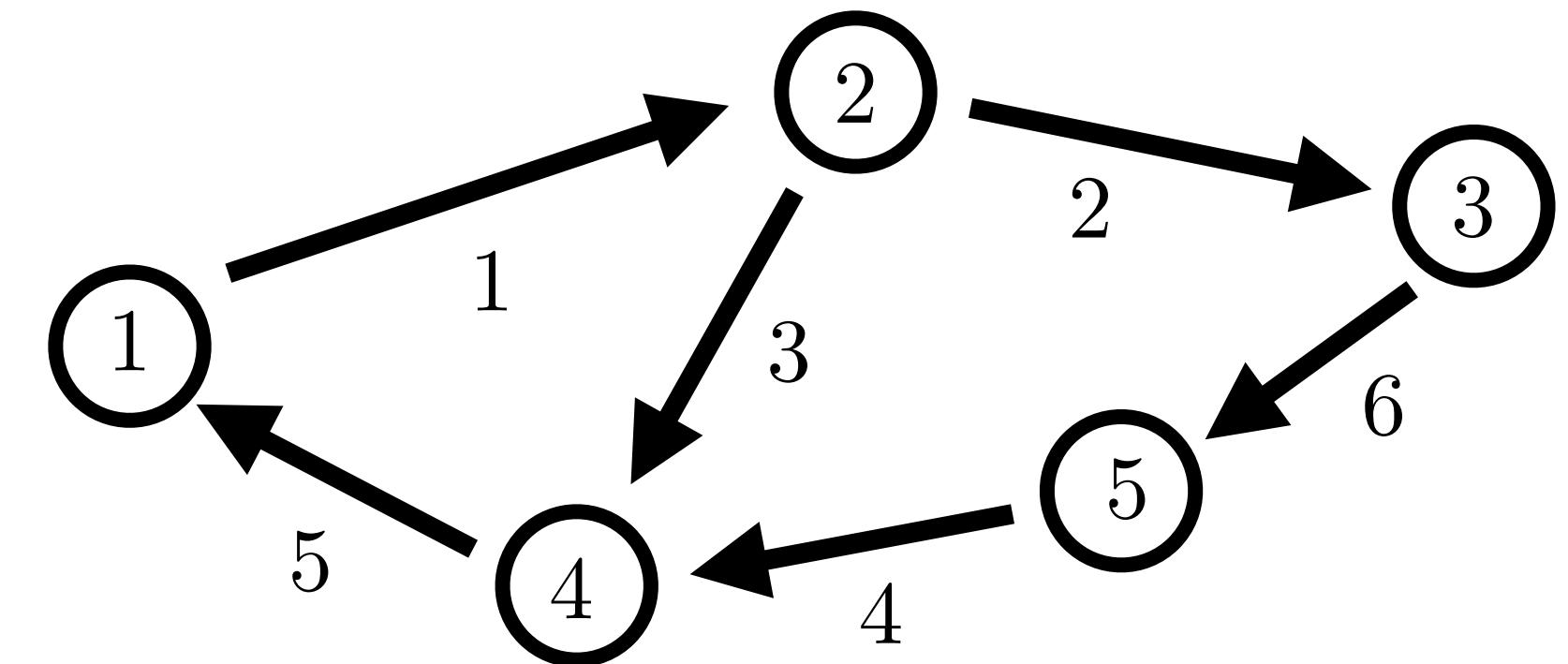
Incidence SVD $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

Laplacian row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Edge-Laplacian col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



Laplacian $L = DD^T$

$$L = \begin{bmatrix} 2 & -1 & 0 & -1 & 0 \\ -1 & 3 & -1 & -1 & 0 \\ 0 & -1 & 2 & 0 & -1 \\ -1 & -1 & 0 & 3 & -1 \\ 0 & 0 & -1 & -1 & 2 \end{bmatrix}$$

Graph Laplacians

Graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

Vertices	$v \in \mathcal{V}$
Edges	$e \in \mathcal{E}$
	$e = (v, v')$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$

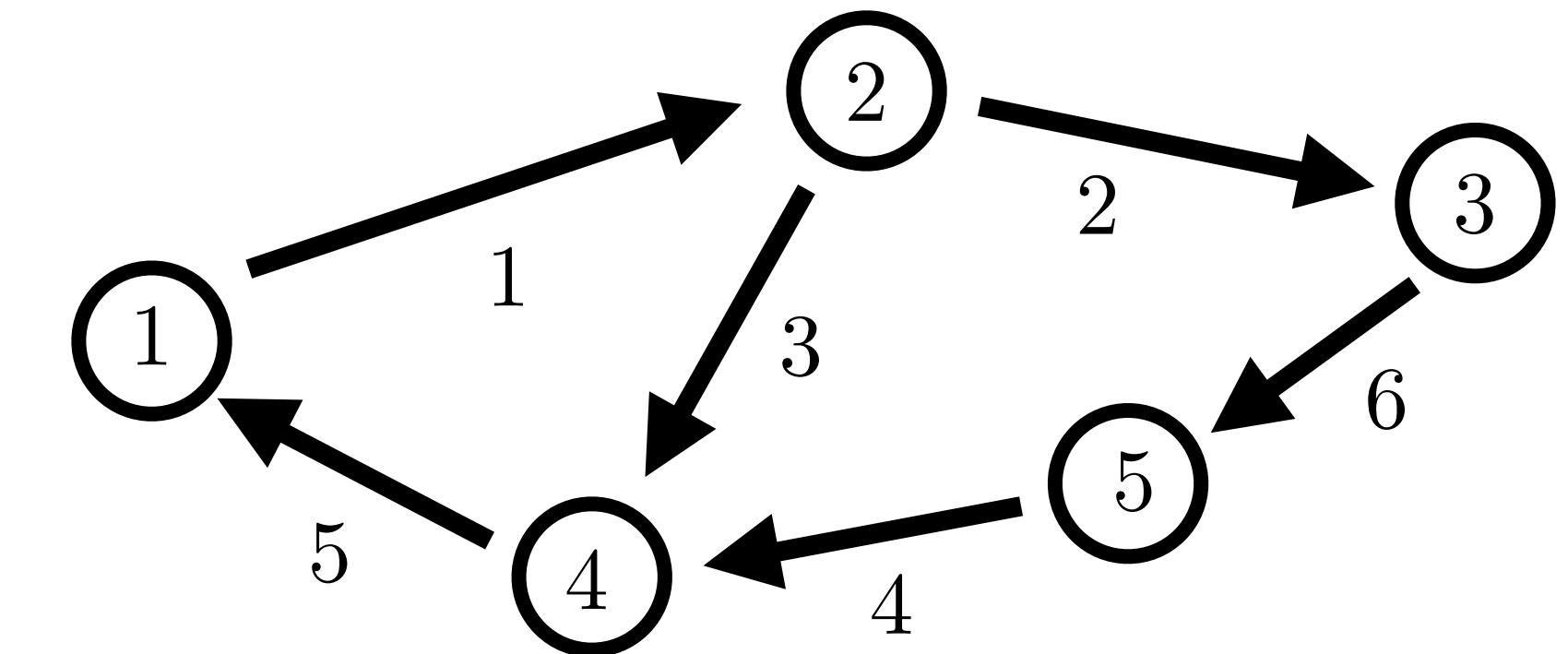
Incidence SVD $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

Laplacian row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Edge-Laplacian col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



Laplacian $L = DD^T$

$$L = \Delta - A = \begin{bmatrix} 2 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix} - \begin{bmatrix} 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 \end{bmatrix}$$

Degree Matrix $[\Delta]_{vv} = |\mathcal{N}_v|$ **diagonal** $\# \text{edges} \text{ (in \& out)}$

Adjacency Matrix $[\mathcal{A}]_{vv'} = \begin{cases} 1 & ; \text{ if } e = (v, v') \in \mathcal{E} \\ 0 & ; \text{ otherwise} \end{cases}$

Graph Laplacians

Graph:

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Vertices

$$v \in \mathcal{V}$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Incidence SVD $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

Laplacian $L = D D^T$

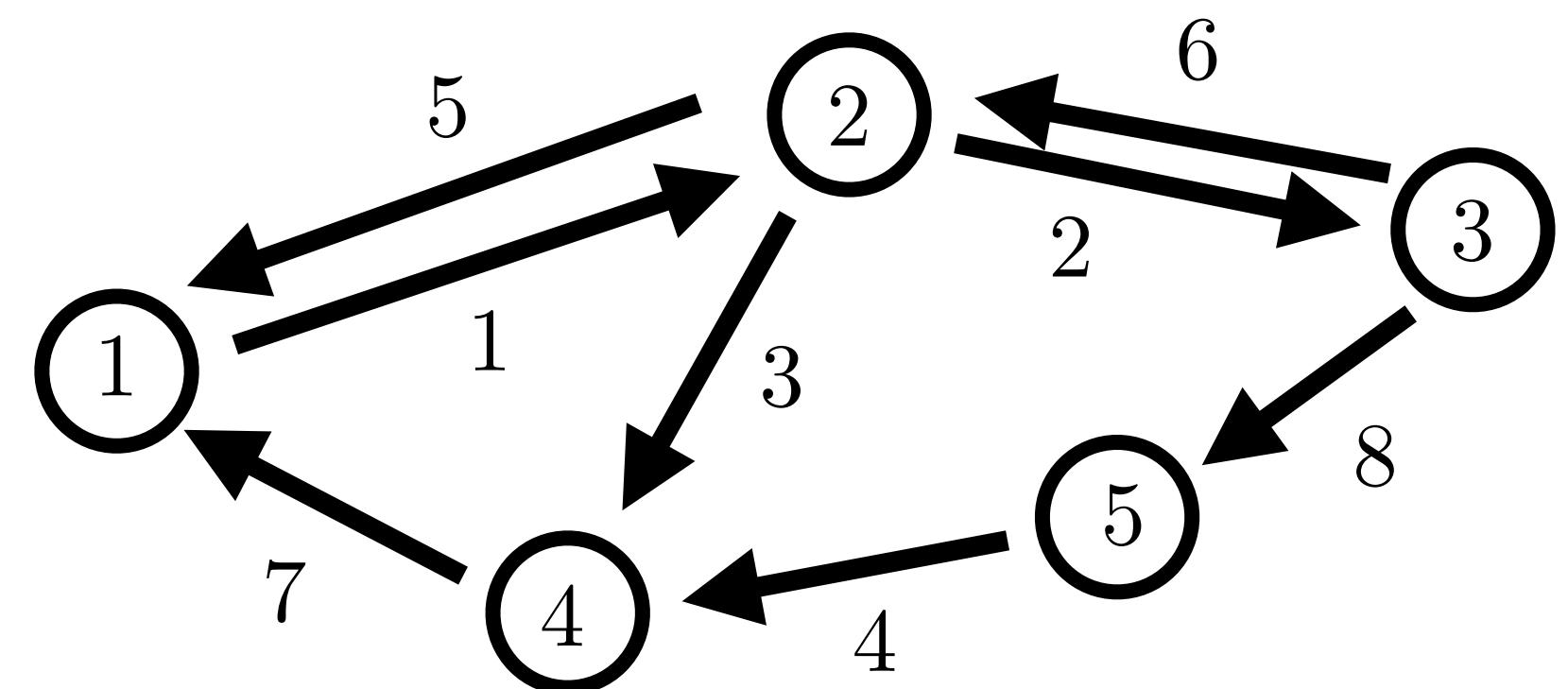
$$L = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Laplacian row “shape” matrix (squared)

$$L = D D^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Edge-Laplacian col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



Graph Laplacians

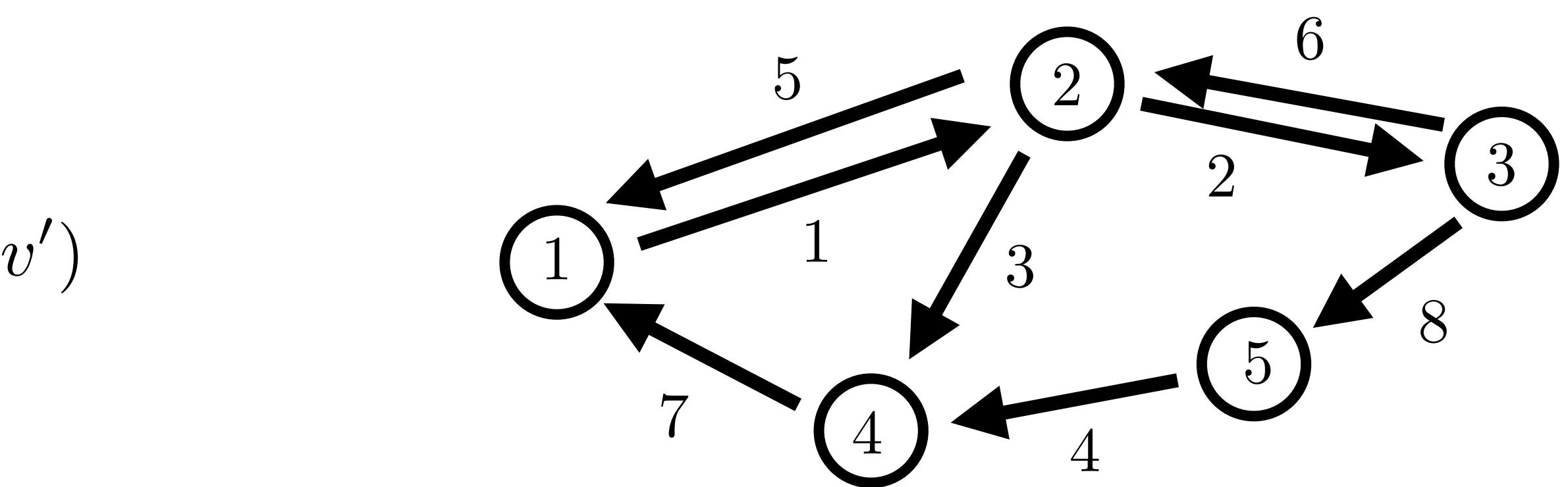
Graph: $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

Vertices	$v \in \mathcal{V}$
Edges	$e \in \mathcal{E}$

Incidence Matrix: $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Incidence SVD $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$



Laplacian $L = DD^T$

$$L = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Laplacian row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

Edge-Laplacian col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$

$$= \begin{bmatrix} | & | \\ U' & \bar{\mathbf{1}} \\ | & | \end{bmatrix} \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} - & U'^T & - \\ - & \bar{\mathbf{1}}^T & - \end{bmatrix} \quad \bar{\mathbf{1}} = \begin{bmatrix} \mathbf{1}_{|\mathcal{V}_1|} & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \mathbf{1}_{|\mathcal{V}_k|} \end{bmatrix}$$

Laplacian
eigenvectors

(Incidence matrix
left singular vectors)