## **INDIVIDUALS**

fx: update\_choices

## **PERSON**

orig, dest

## **Trip opts:**

(choose from)

- [drive]
- [ondemand]
- [walk,transit,walk]
- [walk,transit,ondemand]
- [ondemand,transit,walk]
- [ondemand,transit,ondemand]
- [drive,transit,walk]
- [drive,transit,ondemand]

### **Preference Factors**

Relative pt & weight factor

- time
- money
- switching
- convenience
- (other)

fx: makeTrip queryTrip querySeg

# **WORLD**

fx: world\_of\_drive world\_of\_walk world\_of\_ondemand world\_of\_transit\_graph world\_of\_gtfs

### **DRIVE NETWORK**

Trip Segments (many)

(sources,target) edge flows,costs edge costs

Algorithm: Dijkstra, A\*

WALK NETWORK (same as DRIVE)

fx: planDijkstraSeg

### TRANSIT NETWORK

**Trip Segments** 

(sources,target) edge flows,costs edge costs

Algorithm: RAPTOR

fx: planGTFSSeg
raptor\_shortest\_path
get\_trip\_ids\_for\_stop
get\_trip\_profile
stop\_times\_for\_kth\_trip
compute\_footpath\_transfers
get\_trip\_lists
create\_chains
list\_inbetween\_stops

#### **ONDEMAND NETWORK**

Trip Segments (many)

(sources,target) edge flows, costs edge costs

Algorithm:

divideTrips, orderTrip, TSP

fx: planDelivSegs
divideDelivSegs
kmeans\_nodes
segment\_pickups
current\_pickups
next\_node
order\_pickups

# **GRAPHS**

#### **GRAPHS**

#### osmnx,networkx

- drive
- walk
- ondemand
- transit (graph)

### atfs feed

transit

fx: removeMassFromEdges addTripMassToEdges createEdgeCosts

# **NODES**

#### **NODE DATAFRAME**

- drive
- walk
- ondemand
- transit (graph)
- gtfs

Implemented: pandas

fx: nearest\_nodes
convertNode
findNode
find\_close\_node
find\_close\_node\_gtfs\_to\_graph
find\_close\_node\_graph\_to\_gtfs
gtfs\_to\_transit\_nodesNedges
addNodeToDF
updateNodesDF
drop\_duplicates

bus\_stop\_nodes bus\_stop\_nodes\_wgraph bus\_connection\_nodes