Community Identification in Weighted Networks

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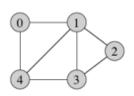
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Outline

1 Introduction: The Stochastic Block Model (SBM)

2 Bayesian Formulation of the SBM

Networks and Adjacency Matrices



			2		
0	0	1	0	0	1
1	1	0	1	1	1
2	0	1	0	1	0
			1		
4	1	1	0	1	0

Figure: Undirected Binary Graph and Adjacency Matrix from Stack Exchange

Notation

- Observe a graph G = (V, E), n = |V|
- Adjacency matrix $A \in \{0,1\}^{n \times n}$
- $A_{i,j} = 1 \iff (i,j) \in E$

Stochatic Block Model

Classical SBM

- Proposed in (Holland, Laskey, and Leinhardt 1983)
- Suppose each $v \in V$ can be assigned to one of K communities
- Let $z \in \{1, 2, ..., K\}^n$ give community assignments
- $z_i \sim \mathsf{Categorical}(p_1, p_2, \dots, p_K)$
- $A_{i,j} \mid \mathbf{z} \stackrel{ind}{\sim} \operatorname{Bernoulli}(P_{z(i),z(j)})$
- ullet $P \in [0,1]^{K imes K}$ parameterizes the blocks

Weighted SBM

- All edges present: $E = \{(i,j) : i \neq j, \in [n]\}$
- Entries of A take values in $S \subseteq \mathbb{R}$
- $A_{i,i}|\mathbf{z} \stackrel{ind}{\sim} F(\theta_{z(i),z(i)})$
- ullet F is some law parameterized by heta

Bayesian Formulation of the SBM

- Proposed in (Aicher, Jacobs, and Clauset 2013; Aicher, Jacobs, and Clauset 2015)
- Suppose that all edge distributions come from common exponential family
- Use conjugate priors: $\pi_{\tau_r}(\theta_r) = \frac{1}{Z(\tau_r)} \exp(\tau_r \cdot \eta(\theta_r))$
- Prior (flat) for z: $\pi_i(z_i) = \text{Categorical}\left(\frac{1}{K}, \dots, \frac{1}{K}\right)$
- ullet Suppose $oldsymbol{z} \perp oldsymbol{ heta}$ (based on DAG from paper)
- $\pi(z, \theta \mid \tau) = \prod_{i=K}^{n} \frac{1}{K} \prod_{r=K}^{R} \frac{1}{Z(\tau_r)} \exp(\tau_r \cdot \eta(\theta_r))$
- Let $\pi^*(\mathbf{z}, \theta)$ be the posterior

$$\pi^{\star} \propto P(A \mid \mathbf{z}, \theta) \pi(\mathbf{z}, \theta)$$

Formal Model

- $\pi(\theta_r \mid \tau_r) = \frac{1}{Z(\tau_r)} \exp(\tau_r \eta(\theta_r))$
- $\pi(z_i \mid \mu_i) = \mu_i(z_i) : \sum_{k=1}^K \mu_i(k) = 1$
- In practice, $\mu_i = \frac{1}{K} \implies \pi(z_i \mid \mu_i) = \frac{1}{K}$
- $\pi(\mathbf{z}, \theta) = \pi(\mathbf{z})\pi(\theta) = \prod_{i < j} \frac{1}{K} \prod_{r} \frac{1}{Z(\tau_r)} \exp(\tau_r \cdot \eta(\theta_r))$
- $P(A \mid \mathbf{z}, \theta) = \left[\prod_{i < j} h(A_{i,j})\right] \exp\left(\sum_{i < j} T(A_{i,j}) \eta(\theta_{z_i, z_j})\right)$
- Posterior $\pi^*(\mathbf{z}, \theta) = \frac{P(A|\mathbf{z}, \theta)\pi(\mathbf{z})\pi(\theta)}{\int_{\Theta} \sum_{\mathbf{z} \in \mathcal{Z}} P(A|\mathbf{z}, \theta)\pi(\mathbf{z})\pi(\theta)d\theta}$
- Approximation q to π^* $q(\mathbf{z}, \theta \mid \boldsymbol{\mu}^*, \boldsymbol{\tau}^*) = \prod_i \mu_i^*(z_i) \times \prod_r \frac{1}{Z(\tau_r^*)} \exp(\tau_r^* \cdot \eta(\theta_r))$

Variational Estimation

This approach proposed in (Aicher, Jacobs, and Clauset 2013; Aicher, Jacobs, and Clauset 2015) (and subsequent derivations adapted therefrom)

- $\pi^*(\mathbf{z}, \theta) \propto \Pr(A \mid \mathbf{z}, \theta) \pi(\mathbf{z}, \theta)$
- Approximate $\pi^{\star}(\mathbf{z}, \theta)$ by factorizable $q(\mathbf{z}, \theta) = q_{\mathbf{z}}(\mathbf{z})q_{\theta}(\theta)$
- Choose q that minimizes KL-divergence with posterior

$$D_{\mathcal{KL}}(q \parallel \pi^\star) = -\int q \log rac{\pi^\star}{q}$$

• Doing this directly is hard, but there's another way...

Variational Inference Trick

Recall that the marginal log likelihood of the data is a fixed quantity (since A) has been observed

$$C = \log P(A)$$

$$= \int_{\Theta} \sum_{\mathbf{z} \in \mathcal{Z}} q(\mathbf{z}, \theta) d\theta \log P(A) \qquad \text{(Multiply by 1)}$$

$$= \int_{\Theta} \sum_{\mathbf{z} \in \mathcal{Z}} q(\mathbf{z}, \theta) \log \frac{P(A, \mathbf{z}, \theta)}{P(\mathbf{z}, \theta \mid A)} d\theta \qquad \text{(Conditioning tricks)}$$

$$= \underbrace{\int_{\Theta} \sum_{\mathbf{z} \in \mathcal{Z}} q(\mathbf{z}, \theta) \log \frac{P(A, \mathbf{z}, \theta)}{P(\mathbf{z}, \theta \mid A)} d\theta}_{\mathcal{G}(q)} - \underbrace{\int_{\Theta} \sum_{\mathbf{z} \in \mathcal{Z}} q(\mathbf{z}, \theta) \frac{P(\mathbf{z}, \theta \mid A)}{q(\mathbf{z}, \theta)} d\theta}_{D_{\mathsf{KL}}(q \parallel \pi^*)}$$

$$D_{\mathsf{KL}}(q \parallel \pi^*) = \underbrace{\log P(A)}_{\mathsf{Constant}} - \mathcal{G}(q)$$
, so maximizing \mathcal{G} minimizes KL



Maximizing $\mathcal{G}(q)$

$$\begin{split} \mathcal{G}(q) &= \int_{\Theta} \sum_{\mathbf{Z} \in \mathcal{Z}} q(\mathbf{z}, \theta) \log \frac{P(A, \mathbf{z}, \theta)}{q(\mathbf{z}, \theta)} d\theta \\ &= \int_{\Theta} \sum_{\mathbf{Z} \in \mathcal{Z}} q(\mathbf{z}, \theta) \log \frac{P(A \mid \mathbf{z}, \theta) \pi(\mathbf{z}, \theta)}{q(\mathbf{z}, \theta)} d\theta \\ &= \int_{\Theta} \sum_{\mathbf{Z} \in \mathcal{Z}} q(\mathbf{z}, \theta) \log P(A \mid \mathbf{z}, \theta) d\theta + \int_{\Theta} \sum_{\mathbf{Z} \in \mathcal{Z}} q(\mathbf{z}, \theta) \log \frac{\pi(\mathbf{z}, \theta)}{q(\mathbf{z}, \theta)} d\theta \\ &= \mathbb{E}_{q} \left[\log P(A \mid \mathbf{z}, \theta) \right] + \underbrace{\mathbb{E}_{q} \left[\log \frac{\pi(\mathbf{z}, \theta)}{q(\mathbf{z}, \theta)} \right]}_{-D_{\mathsf{KL}}(q \mid \pi)} \end{split}$$

We want to choose a q that maximizes our log likelihood, but without straying too far from the prior π



Algorithm and Updates

- We have that $G \propto \sum_{r}^{R} E_q(T_r + \tau_r \tau_r^*) E_q(\eta(\theta_r)) + \sum_{r}^{R} \log \frac{Z(\tau_r)}{Z(\tau_r^*)} + \sum_{i} + \sum_{z_i \in [K]} \mu_i^* \log \frac{\mu_i(z_i)}{\mu_i^*(z_i)}$
- $E_q T_r = \sum_{i < j} \sum_{(z_i, z_j) = r} \mu_i^*(z_i) \mu_j^*(z_j) T(A_{i,j})$
- $E_q \eta(\theta_r) = \frac{\partial}{\partial \tau} \log Z(\tau) \mid_{\tau = \tau_r^*}$
- Taking gradients yields update rules
- $\tau_r^* = \tau_r + E_q T_r$: makes sense given conjugacy
- $\mu_i^*(z) \propto \exp\left(\sum_r \frac{\partial E_q T_r}{\partial \mu_i(z)} \cdot E_q \eta(\theta_r)\right)$
- Normalize the μ_i^* to sum to 1

Results and Next Steps

- (Aicher, Jacobs, and Clauset 2015) Provides a MATLAB-based implementation
- Experiments with small graphs show good recovery of true labels

Work in Progress (See final report)

- (Naïve) Sampling-Based Approach to find MAP
- Compare sampling-approach with recent github package recent github package by Jean-Gabriel Young (Postdoc at UMich)
- More comprehensive experiments
- Comparison of Variational Method with Sampling-Based Methods (in terms of runtime/efficiency as well as accuracy)

References I



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