

1a let $u_j^n = T^n e^{ikx_j} = T^n e^{ikjh}$ ✓

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$u_j^{n+1} = u_j^n - v \frac{\tau}{h} (u_{j+1}^n - u_{j-1}^n)$$

$$\Rightarrow T^{n+1} e^{ikjh} = T^n e^{ikjh} - v \frac{\tau}{h} (T^n e^{ik(j+1)h} - T^n e^{ik(j-1)h})$$

$$\Rightarrow T^2 = 1 - v \frac{\tau}{h} (T e^{ikh} - T e^{-ikh})$$

$$\Rightarrow T^2 + T v \frac{\tau}{h} (e^{ikh} - e^{-ikh}) - 1 = 0$$

$$-4v^2 \frac{\tau^2}{h^2} \sin^2(kh) + 4$$

$$\Rightarrow T^2 + T v \frac{\tau}{h} (2i \sin(kh)) - 1 = 0$$
 ✓

$$T = \frac{-v \frac{\tau}{h} (2i \sin(kh)) \pm \sqrt{(v \frac{\tau}{h} (2i \sin(kh)))^2 + 4}}{2}$$

$$= -vi \frac{\tau}{h} \sin(kh) \pm \sqrt{1 - v^2 \frac{\tau^2}{h^2} \sin^2(kh)}$$
 ✓

$$|T| = \sqrt{v^2 \frac{\tau^2}{h^2} \sin^2(kh) \pm 1 - v^2 \frac{\tau^2}{h^2} \sin^2(kh)} \quad \text{let } r = v^2 \frac{\tau^2}{h^2}$$

$$\Rightarrow \cancel{\frac{\tau^2}{h^2} \sin^2(kh)} = \sin^2(kh) \quad \uparrow \text{complex?}$$

so $v \frac{\tau}{h} < 1$ ✓

7 $|T| = 1$ if $v^2 \frac{\tau^2}{h^2} < 1$

$$\Rightarrow v \frac{\tau}{h} < 1 \Rightarrow \frac{\tau}{h} < \frac{1}{v}$$

so $C = \frac{1}{v}$, C is the courant number.

$$1b \quad T_j^n = \frac{1}{\tau} (u(x_j, t_{n+1}) - u(x_j, t_n)) + v \frac{1}{h} (u(x_{j+1}, t_n) - u(x_{j-1}, t_n))$$

$$u(x_j, t_{n+1}) = u + \tau u_t + \frac{1}{2} \tau^2 u_{tt} + \cancel{O(\tau^3)}$$

$$u(x_j, t_{n-1}) = u - \tau u_t + \frac{1}{2} \tau^2 u_{tt} + O(\tau^3)$$

$$u(x_{j+1}, t_n) = u + h u_x + \frac{1}{2} h^2 u_{xx} + O(h^3)$$

$$u(x_{j-1}, t_n) = u - h u_x + \frac{1}{2} h^2 u_{xx} + O(h^3)$$

$$\frac{1}{6} \tau^3 u_{ttt}$$

$$T_j^n = \frac{1}{\tau} \left[u + \tau u_t + \frac{1}{2} \tau^2 u_{tt} + \dots - u + \tau u_t - \frac{1}{2} \tau^2 u_{tt} + \dots \right]$$

$$+ v \frac{1}{h} \left[u + h u_x + \frac{1}{2} h^2 u_{xx} + \dots - u + h u_x - \frac{1}{2} h^2 u_{xx} + \dots \right]$$

$$= 2u_t + \frac{1}{3} \tau^2 u_{ttt} + 2v u_x + \frac{1}{3} h^2 u_{xxx} + \dots$$

$$\text{pde: } u_t + v u_x = 0$$

$$\Rightarrow T_j^n = \frac{1}{3} \tau^2 u_{ttt} + \frac{1}{3} h^2 u_{xxx} + \dots$$

8 Hence the truncation error has order $O(h^2, \tau^2)$ second-order in space and time.

1c since we only have initial condition u_0 , we cannot perform the leapfrog scheme on the first timestep. as we don't have $n-1$. We could use ~~FTCS~~ ^{centred differencing}, for example, on the first and ~~use~~ last and use leapfrog everywhere else.

E.g.

$$n=1: \frac{u_j^2 - u_j^1}{\tau}$$

$$\frac{u_{j+1}^1 - u_{j-1}^1}{h}$$

$$u_j^2 = u_{j+1}^1 - 2u_j^1 + u_{j-1}^1 ?$$

$$n=2: u_2$$

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15¹²

$$2a \quad \frac{u_j^{n+1} - u_j^n}{\tau} = \frac{1}{2h^2} \left[D_{j+1/2} (u_{j+1}^{n+1} - u_j^{n+1}) - D_{j-1/2} (u_j^{n+1} - u_{j-1}^{n+1}) \right] \quad (*)$$

$$+ \frac{1}{2h^2} \left[D_{j+1/2} (u_{j+1}^n - u_j^n) - D_{j-1/2} (u_j^n - u_{j-1}^n) \right]$$

4 $h = \frac{1}{N+1}$, with N unknowns.

The main advantage is that the Crank-nicolson scheme is unconditionally stable. ✓

2b. Let $\alpha = \frac{\tau}{2h^2}$. Then $(*) \Rightarrow$

$$-\alpha D_{j-1/2} u_{j-1}^{n+1} + (1 + \alpha(D_{j+1/2} + D_{j-1/2})) u_j^{n+1} = \alpha D_{j+1/2} u_{j+1}^{n+1}$$

$$= -\alpha D_{j-1/2} u_{j-1}^n + (1 - \alpha(D_{j+1/2} + D_{j-1/2})) u_j^n + \alpha D_{j+1/2} u_{j+1}^n$$

At $x=0, j=0 \Rightarrow u = \beta(t)$

$\Rightarrow -\alpha D_{1/2}$

introduce u_{j-1} term

$$u_{-1} = \frac{u_1 - u_0}{2}$$

$$u_0 = \frac{u_1 - u_{-1}}{2h}$$

$$\Rightarrow u_1 = u_1 - 2u_0$$

So $a_j = -\alpha D_{j-1/2}$ $b_j = 1 + \alpha(D_{j+1/2} + D_{j-1/2})$ $c_j = \alpha D_{j+1/2}$

$$-\alpha D_{j-1/2} u_{j-1}^{n+1} + (1 + \alpha(D_{j+1/2} + D_{j-1/2})) u_j^{n+1} = \alpha D_{j+1/2} u_{j+1}^{n+1}$$

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$$d_j = \alpha D_{j-1/2} u_{j-1}^n + (1 - \alpha(D_{j+1/2} + D_{j-1/2})) u_j^n + \alpha D_{j+1/2} u_{j+1}^n$$

$$1 - 2\beta\alpha$$

$x=0, j=0$

introduce u_{-1} term. $u' = u^{-1} - \alpha(u^0_{j+1} - u^0_{j-1})$

$$u_0 = \frac{1}{h}(u_1 - u_{-1})$$

$$u^{-1} = u'$$

$$hu_0 - u_1 = u_{-1}$$

$$d_0 = \alpha(D_{1/2} - \alpha) u_{j-1}^0$$

$$b_0 = (1 - \alpha(D_{1/2} + D_{-1/2})) u_0^1 + \alpha D_{1/2} u_1^1$$

$$c_0 = \alpha D_{1/2}$$

$$d_0 = \alpha D_{1/2} u_{j+1}^0$$

$$2c \quad u_{k-1}^{n+1} - e_{k-1} u_k^{n+1} = f_{k-1} \Rightarrow u_{k-1}^{n+1} = e_{k-1} u_k^{n+1} + f_{k-1}.$$

$$-a_k u_{k-1}^{n+1} + b_k u_k^{n+1} - c_k u_{k+1}^{n+1} = d_k. \quad \checkmark$$

$$\Rightarrow -a_k (e_{k-1} u_k^{n+1} + f_{k-1}) + b_k u_k^{n+1} - c_k u_{k+1}^{n+1} = d_k.$$

$$\Rightarrow (b_k - a_k e_{k-1}) u_k^{n+1} - c_k u_{k+1}^{n+1} = d_k + a_k f_{k-1}$$

$$\Rightarrow u_k^{n+1} - \frac{c_k}{b_k - a_k e_{k-1}} u_{k+1}^{n+1} = \frac{d_k + a_k f_{k-1}}{b_k - a_k e_{k-1}} \quad \checkmark$$

$$\text{Hence } e_k = \frac{c_k}{b_k - a_k e_{k-1}} \quad \checkmark \quad \text{and} \quad f_k = \frac{d_k + a_k f_{k-1}}{b_k - a_k e_{k-1}} \quad \checkmark$$

$$6 \quad e_0 = \frac{c_0}{b_0 - a_0 e_{-1}} \quad f_0 = \frac{d_0 + a_0 f_{-1}}{b_0 - a_0 e_{-1}} \quad \checkmark$$

$$= \frac{\alpha \beta}{1 - \alpha \beta} \left(\frac{1}{1 - \alpha \beta} \right) u$$

14 14²

3a Start with centred differencing on points

~~x, y~~

~~$u_{i,j}$~~

$$x_i = ih_x, y_j = jh_y, h_x = \frac{1}{N_x}, h_y = \frac{1}{N_y} \quad \checkmark$$

$$u_{i,j} = u(x_i, y_j)$$

where N_x, N_y are the number of points in x and y respectively.

Then $u(x_i, y_j)$ can be approximated by

$$\frac{u_{i-1,j} - 2u_{i,j} + u_{i+1,j}}{h_x^2} + \frac{u_{i,j-1} - 2u_{i,j} + u_{i,j+1}}{h_y^2} = -k^2 u_{i,j} \quad \checkmark$$

This forms a ^{block} linear system

$$Ax = b$$

with $A = \begin{bmatrix} [A_{11}] & [A_{12}] \\ [A_{21}] & [A_{22}] & [A_{23}] \\ \vdots & \vdots & \vdots \end{bmatrix} \quad \checkmark$

with diagonal blocks

$$A_{i,i} = \begin{bmatrix} -\frac{2}{h_x^2} - \frac{2}{h_y^2} & \frac{1}{h_x^2} & 0 \\ \frac{1}{h_x^2} & \ddots & \vdots \\ \vdots & \ddots & \ddots \end{bmatrix} \quad \text{with } N_x \times N_x \quad \checkmark$$

and off-diagonal blocks

$$A_{i-1,i} = A_{i+1,i} = \begin{bmatrix} \frac{1}{h_y^2} & 0 \\ 0 & \ddots \end{bmatrix} \quad \text{with } N_y \text{ such rows or this block.} \quad \checkmark$$

3a $\underline{b} = -k^2 u(x,y) + \text{boundary conditions}$

Here we have boundary conditions $u=0$, so

6 $\underline{b} = -k^2 u(x,y)$ with $u(x,y)$ having entries $u(x_i, y_j) = u_{ij} \in \mathbb{R}$.

3b First we decompose A into D - diagonal, $-L$ - lower triangular and $-U$ - upper triangular.

$$A = D - U - L$$

for jacobi ~~matrix~~ method we form an iterative sequence

$$x_{n+1} = [D]^{-1} (L+U)x_n + \underline{b}$$

hence $G = -Ux_n[D]^{-1}$ $C = L[D]^{-1}$.

when $x_{n+1} = x_n$ then $Ax_n = \underline{b}$
 D^{-1} is trivial

3c $\rho(G) = \max_i |\lambda_i(G)|$

Assume G has a full set of eigenvectors

Then

$$G = S \Lambda S^{-1}$$

by ~~divergence~~ Theorem

$$x_{n+1} = [D]^{-1} (Ux_n + \underline{b})$$

8

8

4x
Sa for local basis functions we have

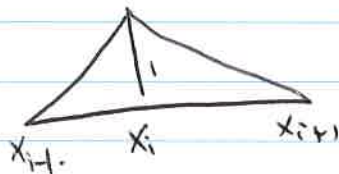
$$u(x) = \sum_{i=0}^N u_i \phi_i(x)$$

with ϕ_i being local basis functions

we have

$$\phi_i = \begin{cases} \frac{x_{i+1} - x}{x_{i+1} - x_i} & , x_i < x < x_{i+1} \\ \frac{x - x_{i-1}}{x_i - x_{i-1}} & , x_{i-1} < x < x_i \\ 0 & , \text{otherwise} \end{cases}$$

with $x \in [a, b]$ we have $[a = x_0, \dots, x_{N+1} = b]$.



5b for weak form multiply by ϕ_i and integrate w.r.t Ω

$$\int_{\Omega} \phi \nabla^2 u \, dA = \int f(x, y) \, dA$$

integration by parts.

$$\phi \int_{\Omega} \nabla^2 u \, dA - \int \phi' \left(\int \nabla^2 u \, dA \right) dA$$

\Rightarrow by

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4R