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## Homework 2

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### PROBLEM 1

Suppose  $f : X \rightarrow Y$  is a submersion. Prove that if  $X$  is compact and  $Y$  is connected, then  $f$  is surjective.

*Proof.* Recall from the earlier homework that  $f$  is an open map. Thus, the image  $f(X)$  is open. Furthermore, since  $X$  is compact,  $f(X)$  is compact as well. Since  $Y$  is Hausdorff,  $f(X)$  is closed, and so  $f(X)$  is a nonempty clopen set. Since  $Y$  is connected,  $f(X) = Y$  as desired.  $\square$

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### PROBLEM 2

#### PART A

Calculate the Lie algebra of  $SO(n)$ .

*Proof.* Consider the smooth function

$$\begin{aligned}\Phi : GL(n) &\rightarrow GL(n) \\ \Phi(A) &= AA^T\end{aligned}$$

Now,  $O(n)$  is defined to be  $\Phi^{-1}(I)$ . We calculate the differential directly. Let  $B \in T_A(O(n))$ , and let  $\gamma : [0, 1] \rightarrow O(n)$  be

$$\gamma(t) = A + tB$$

Then,

$$\begin{aligned}
d\Phi_A(B) &= d\Phi_A(\gamma'(0)) \\
&= \partial_t(\Phi(\gamma(t)))|_0 \\
&= \partial_t((A + tB)(A + tB)^T)|_0 \\
&= \partial_t(AA^T + tAB^T + tBA^T + t^2BB^T)|_0 \\
&= AB^T + BA^T
\end{aligned}$$

Now, to show that  $I$  is a regular value, we need to show that for all  $A \in O(n)$ , and for all  $C \in T_{\Phi(A)}(GL(n))$ , there is some  $B \in T_A(O(n))$  with  $d\Phi(B) = C$ .

Take  $B = \frac{1}{2}CA$ , we see that

$$d\Phi_A(B) = \frac{1}{2}(A(CA)^T + CAA^T) = C$$

as desired. Thus,  $I$  is a regular value.

We next appeal to the fact that the tangent space of a level curve is the kernel of the differential. Thus,  $T_I(O(n))$  is the set of all matrices for which

$$d\Phi_I(B) = B + B^T = 0$$

which is exactly  $\mathfrak{o}(n)$  the set of all skew-symmetric matrices.

Now, we will observe that  $SO(n)$  is open. Consider the determinant map, a continuous map from  $O(n)$  to the two-point set  $\{-1, 1\}$  with the discrete topology. This defines a separation of  $O(n)$  into connected components. Specifically, the inverse image of 1 is  $SO(n)$ , and thus  $SO(n)$  is both open and closed.

Thus, since  $SO(n)$  is open,  $T_I(SO(n)) = T_I(O(n)) = \mathfrak{o}(n)$  as desired.  $\square$

## PART B

Show  $SO(n)$  is compact.

*Proof.* To show  $SO(n)$  is compact, we will show it is a closed subspace of  $O(n)$ , and show that  $O(n)$  is compact. We have already observed before that  $SO(n)$  is clopen in  $O(n)$ , so all we need to show is that  $O(n)$  is compact. First, we recall that  $O(n)$  is a level set, and thus is closed. Next, we show it is bounded. Recall that in finite-dimensional normed spaces, all norms are equivalent. So, we just need to show  $O(n)$  is bounded with respect to some norm.

Take the operator norm on  $M(n)$ . Then, for any  $A \in O(n)$ ,

$$\|Ax\|^2 = g(Ax, Ax) = g(A^T Ax, x) = g(x, x) = \|x\|^2$$

and so  $\|A\| = 1$ . Thus,  $O(n)$  is bounded by 1 in operator norm. So,  $O(n)$  is compact. Since  $SO(n)$  is a closed subgroup of  $O(n)$ ,  $SO(n)$  is compact as well, as desired.  $\square$

## PROBLEM 3

### PART A

Let  $G$  be a subgroup of  $\text{Diff}(M)$ , and suppose  $p$  is fixed by  $G$ . Show the map

$$g \mapsto dg_p$$

is a group homomorphism  $G \rightarrow GL(T_p M)$ .

*Proof.* We just need to show that this map respects the group operation. That is, we need to show that

$$d(gh)_p = dg_p \circ dh_p$$

but this is just a restatement of the functoriality of the differential, which has already been proven.  $\square$

## PART B

Find a basis for  $\mathfrak{su}(2)$  and hence compute the dimension of  $SU(2)$ . Prove that for  $x, y \in \mathfrak{su}(2)$ ,

$$\text{trace}(x^*y)$$

is a nondegenerate inner product. Deduce that there is a homomorphism

$$\pi : SU(2) \rightarrow SO(3)$$

*Proof.* We first calculate  $\mathfrak{u}(2)$ . This is just the level set of  $I$  under the function

$$\Phi(A) = AA^*$$

and thus  $\mathfrak{u}(2)$  is the kernel of  $d\Phi_I$ . However, we've already calculated what  $d\Phi_I$  does in problem 2, so

$$d\Phi_I(A) = A + A^*$$

which has kernel  $\mathfrak{u}(2) = \{A \in M(2, \mathbb{C}) \mid A^* = -A\}$ .

Now, we observe that  $SU(2)$  is the level set of 1 under the determinant map. Now, we observe that

$$d(\det_I(A)) = \text{tr}(A)$$

We begin by noting that the determinant can be expressed as

$$\det(I + tA) = \sum_{\sigma \in S_n} \epsilon(\sigma) \prod_{i=1}^n (I + tA)_i^{\sigma(i)}$$

Now, if we single out the linear term in the product by multiplying by  $tA$  once and then by  $I$  the rest of the time, we end up with

$$\begin{aligned} \text{lin}(\det(I + tA)) &= \sum_{\sigma \in S_n} \epsilon(\sigma) \sum_{i=1}^m \left( \prod_{j \neq i} I_j^{\sigma(j)} \right) A_i^{\sigma(i)} t \\ &= \sum_{i=1}^n A_i^i t \\ &= t \text{tr}(A) \end{aligned}$$

and thus, the derivative at zero is  $\text{tr}(A)$ , as desired. Here, the equality from line 1 to line 2 is made by observing that  $I_j^{\sigma(j)}$  is nonzero only when  $\sigma(j) = j$ , or when  $\sigma = id$ .

Thus,  $\mathfrak{su}(2)$  is the subspace of  $\mathfrak{u}(2)$  such that  $\text{tr}(A) = 0$ .

Next, we compute a basis. Representing an arbitrary matrix as

$$\begin{bmatrix} a + bi & c + di \\ f + gi & h + ki \end{bmatrix}$$

the trace-free requirement says that  $a = -h$  and  $b = -k$ , and skew-symmetry says that  $a = h = 0$ ,  $c = -f$  and  $d = g$ . Thus, a typical matrix in  $\mathfrak{su}(2)$  is

$$\begin{bmatrix} bi & c + di \\ -c + di & -bi \end{bmatrix}$$

which has basis

$$\left\{ \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} i & 0 \\ 0 & i \end{bmatrix} \begin{bmatrix} 0 & i \\ i & 0 \end{bmatrix} \right\}$$

and thus has dimension 3.

Next, we show that  $\text{trace}(x^*y)$  is an inner product on this space. First, we show this is symmetric. To see this, we calculate

$$\text{trace}(x^*y) = \text{trace}(-xy) = \text{trace}(y(-x)) = \text{trace}(-yx) = \text{trace}(y^*x)$$

and so this is symmetric. Next, we show it is linear in the first term. This follows directly: let  $x, y, z \in \mathfrak{su}(2)$ . Then,

$$\text{trace}((x+z)^*y) = \text{trace}((-x-z)y) = \text{trace}(x^*y) + \text{trace}(z^*y)$$

and for  $\alpha \in \mathbb{R}$ ,

$$\text{trace}((\alpha x)^*y) = \text{trace}(\alpha x^*y) = \alpha \text{trace}(x^*y)$$

and thus this form is linear in the first term.

Finally, we need to show that this is a nondegenerate form. For nonzero  $x \in \mathfrak{su}(2)$ , let

$$x = \begin{bmatrix} bi & c+di \\ -c+di & -bi \end{bmatrix}$$

Then,

$$\text{trace}(x^*x) = 2(b^2 + c^2 + d^2) \geq 0$$

with equality if and only if  $x = 0$ .

Finally, we deduce that there is a homomorphism

$$\pi : SU(2) \rightarrow SO(3)$$

which is the well-known double cover of  $SO(3)$ . □

## PROBLEM 4

### PART A

Let  $p$  be a homogeneous polynomial. Prove that any  $a \neq 0$  is a regular value of  $p$ .

*Proof.* We calculate the differential directly.

$$(dp)_a X^a = X^a \nabla_a p = X^a \partial_a p$$

Now, let  $\beta \in p^{-1}(a)$ . We wish to show  $dp_\beta$  is surjective. Since its codomain has dimension one, we just need to show it has nontrivial image. So, we see that

$$((dp)_\beta)_a \beta^a = \beta^a \partial_a p|_\beta = ma$$

by Euler's identity for homogeneous polynomials. Thus, if  $a \neq 0$ , then  $a$  is a regular value, as desired.  $\square$

### PART B

Deduce that  $SL(n, \mathbb{R})$  is a Lie group.

*Proof.* Observe that  $SL(n)$  is the inverse image of 1 under the determinant map. Now, for arbitrary  $n \times n$  matrices, the determinant is a homogeneous polynomial of  $n^2$  variables (the entries of the matrix), and thus 1 is a regular value of the determinant. Thus,  $SL(n)$  is a submanifold of  $GL(n)$ , and is a Lie group, as desired.  $\square$

## PROBLEM 5

Suppose  $f : X \rightarrow Y$  is smooth,  $X, Y$  are compact with the same dimension, and  $y \in Y$  is a regular value. Show that  $f^{-1}(y)$  is a finite set  $\{x_i\}$  and that there is an open neighborhood  $U$  of  $y$  for which  $f^{-1}(U)$  is a finite disjoint union of open sets  $\{V_i\}$  such that  $V_i$  is a neighborhood of  $x_i$  and each  $V_i$  is mapped diffeomorphically onto  $U$ .

*Proof.* We first show  $f^{-1}(y)$  is a finite set. Since  $y$  is a regular value,  $f^{-1}(y)$  is a submanifold of  $X$  of dimension 0 (since it has codimension  $\dim(Y) = \dim(X)$ ). Now, the only submanifolds of dimension zero are discrete sets, so  $f^{-1}(y)$  is a closed discrete subset of  $X$ . However, since  $X$  is compact,  $f^{-1}(y)$  must be finite (since if  $f^{-1}(y)$  were infinite, each point by itself is open, and thus  $\{x_i\}$  forms an open cover of  $f^{-1}(y)$  with no finite subcover, a contradiction).

Now, since  $df_{x_i}$  is surjective for each  $x_i$  (definition of  $y$  being a regular value), and  $\dim(X) = \dim(Y)$ , it follows that  $df_{x_i}$  is an isomorphism for each  $x_i$ . Thus there are neighborhoods  $W_i$  around each  $x_i$  such that  $f|_{W_i}$  is a diffeomorphism onto its image. Without loss of generality, we take the  $W_i$  to be disjoint from each other; since  $X$  is Hausdorff, we can find open sets separating  $x_i$  and  $x_j$  for  $i \neq j$ , and intersect them with  $W_i$  to get disjoint open sets on which  $f$  is a diffeomorphism onto.

Take  $U = \bigcap_{x_i} f(W_i)$  an open neighborhood of  $y$ , and take  $V_i = f|_{W_i}^{-1}(U)$ . Then,  $V_i \subset W_i$  open and so  $f$  is a diffeomorphism on  $V_i$ , with each  $V_i$  a neighborhood of  $x_i$ . Finally, noting that  $(\cup V_i)^c$  is closed, and  $f$  is a closed map (taking compact sets to compact sets), we see that  $f((\cup V_i)^c)$  is closed and avoids  $y$ . So, if we let  $U' = f((\cup V_i)^c)^c$ , we see that  $U \cap U'$  is the desired neighborhood of  $y$  that is evenly covered. Let  $V'_i$  be the neighborhood of  $x_i$  that maps diffeomorphically to  $U \cap U'$ . Then, by construction we have that each  $V'_i$  is a neighborhood of  $x_i$ , all disjoint from each other, and furthermore for any  $z \in (\cup V'_i)^c$ , either  $z \in (\cup V_i)^c$  in which case  $f(z) \notin U \cap U'$ , or  $z$  is in some  $V_i$  but not  $V'_i$  for some  $i$ , in which case  $f(z) \notin U \cap U'$  since  $f$  is a diffeomorphism from  $V_i$  to  $U$ .  $\square$