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# Midterm

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## PROBLEM 1

### PART A

Use the standard charts on  $S^n$  to calculate the matrix representation of  $di : T_p S^n \rightarrow T_p \mathbb{R}^{n+1}$ , and show that  $di$  is injective, and thus  $i$  is an embedding.

*Proof.* For this calculation, we will use the chart given by hemisphere projection. That is, the domains for the charts will be the open sets  $U_i^\pm = \{(x^1, \dots, x^{n+1}) \mid x^i > 0 (x^i < 0 \text{ resp.})\}$  with maps

$$\phi_i^\pm(x^1, \dots, x^{n+1}) = (x^1, \dots, \hat{x}^i, \dots, x^{n+1})$$

Where a hat denotes omission of the variable.

Now, suppose  $p \in U_i^+$  (without loss of generality, we take the positive hemisphere of  $x^i$ , but the argument can be repeated exactly with the negative hemisphere as well.) and let the coordinate representation of  $p$  be

$$\phi(p) = (x^1, \dots, \hat{x}^i, \dots, x^{n+1})$$

Then, the inclusion map looks like

$$\begin{aligned} i \circ \phi^{-1}((x^1, \dots, \hat{x}^i, \dots, x^{n+1})) &= (y^1, \dots, y^{n+1}) \\ &= (x^1, \dots, x^{i-1}, \sqrt{1 - x^a x_a}, \dots, x^{n+1}) \end{aligned}$$

and the Jacobian  $di$  can be calculated directly using the identity  $di_j^k = \partial_j(y^k)$ . Which gives the matrix (for  $j = 1, \dots, i-1, i+1, \dots, n+1$  and  $k = 1, \dots, n$ )

$$\partial_j(y^k) = \delta_j^k - \frac{1}{\sqrt{1 - x^a x_a}} \delta^{ik} x_j$$

Which is clearly injective, since the rows  $k \neq i$  are the basis covectors for  $\mathbb{R}^n$ , and thus  $\partial_j(y^k)$  has rank  $n$  as desired.

Furthermore, since  $S^n$  is compact, and the inclusion is injective, it follows that  $i$  defines an embedding of  $S^n$  into  $\mathbb{R}^{n+1}$ .  $\square$

## PART B

Show that  $T_p S^n$ , when identified with  $di(T_p S^n)$  is the subspace of  $\mathbb{R}^{n+1}$  consisting of all vectors perpendicular to the radial vector to  $p$ .

*Proof.* This follows by direct calculation. To see this, let  $v \in T_p S^n$ . Then,

$$\begin{aligned} di(v) &= \partial_j y^k v^j = \delta_j^k v^j - \frac{1}{\sqrt{1 - x^a x_a}} \delta^{ik} x_j v^j \\ &= v^k - \frac{x^a v_a}{\sqrt{1 - x^a x_a}} \delta^{ik} \end{aligned}$$

where it is assumed that  $x_a v^a$  does not sum over the  $i^{th}$  component of  $v$ .

Recalling earlier that the embedding sends

$$p = (x^1, \dots, \hat{x}^i, \dots, x^{n+1})$$

to

$$(y^1, \dots, y^{n+1}) = (x^1, \dots, x^{i-1}, \sqrt{1 - x^a x_a}, \dots, x^{n+1})$$

we can compute the inner product  $g_{jk} v^j y^k$  directly.

$$\begin{aligned} g_{jk} v^j y^k &= v^k x_k + \delta_{ij}^{ik} v^j y_k \\ &= v^k x_k + v^i y_i \\ &= v^k x_k - \frac{v^a x_a}{\sqrt{1 - x^a x_a}} \sqrt{1 - x^a x_a} \\ &= v^k x_k - v^a x_a \\ &= 0 \end{aligned}$$

Thus,  $di(v)$  is perpendicular to  $p$ , as desired. □

## PART C

For  $F$  a smooth map from  $\mathbb{R}^{n+1}$  to  $\mathbb{R}^{m+1}$  such that  $F(S^n) \subset S^m$ , show that  $d(F|_{S^n}) = dF|_{T_p S^n}$ .

*Proof.* To begin with, let  $\gamma$  be a curve in  $S^n$  such that  $\gamma(0) = p$  and  $\gamma'(0) = v$ . Then,

$$\begin{aligned} d(F|_{S^n})(\gamma'(0)) &= \partial_t|_0 F|_{S^n}(\gamma(t)) \\ &= \partial_t|_0 F(\gamma(t)) \\ &= dF(\gamma'(0)) \\ &= dF(\gamma'(0))|_{T_p S^n} \end{aligned}$$

Here, the equality from line 2 to line 3 comes from the fact that  $F$  maps  $S^n$  into  $S^m$ , and the equality from line 3 to line 4 comes from the fact that  $\gamma'(0)$  started in  $T_p S^n$  to begin with. □

## PROBLEM 2

Show that the tangent bundle  $TM$  is always orientable.

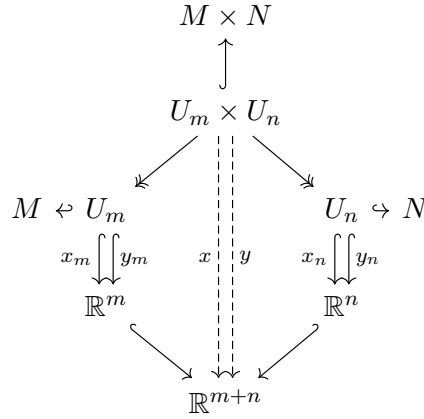
*Proof.* For this problem, we will use that fact that a manifold is orientable if there exist charts such that the coordinate transition maps have a Jacobian of positive determinant.

Before proceeding further, we prove the following lemma:

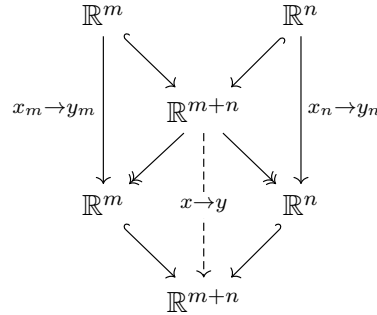
**Lemma.** Suppose  $M$  and  $N$  are smooth manifolds. In particular, their product  $M \times N$  is a smooth manifold. Furthermore, for pairs of coordinates  $x_m, y_m$  on  $U_m \subset M$  and  $x_n, y_n$  on  $U_n \subset N$ , the product coordinates  $x = (x_m, x_n)$  and  $y = (y_m, y_n)$  are smooth coordinates on  $U_m \times U_n$ , and the Jacobian  $J(x \rightarrow y)$  is given componentwise. That is,

$$J(x \rightarrow y) = (J(x_m \rightarrow y_m), J(x_n \rightarrow y_n))$$

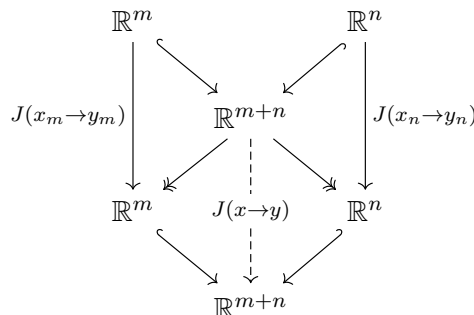
*Proof.* That  $M \times N$  is a smooth manifold follows almost immediately by taking products of coordinate charts on  $M$  and  $N$ . Now, we have the following diagram:



which implies that the induced coordinates  $x$  and  $y$  are smooth. Now, let's expand the lower half of the commutative diagram to get the transition maps  $x_m \rightarrow y_m$  and  $x_n \rightarrow y_n$ :



Differentiating this diagram (applying the differential functor) yields:



Thus,  $J(x \rightarrow y) = (J(x_m \rightarrow y_m), J(x_n \rightarrow y_n))$  as desired.  $\square$

We are now ready to prove the general result.

So, let  $M$  be a smooth manifold with tangent bundle  $TM$ . Furthermore, for a point  $p$ , suppose there are two coordinate charts  $x^i$  and  $y^i$  on a neighborhood of  $p$ . We wish to calculate the Jacobian of the induced coordinate transformations on the tangent bundle.

To do so, we first appeal to the fact that  $TM$  is locally trivializable. That is, on some neighborhood  $U$  containing  $p$ ,  $\pi^{-1}(U) \cong M \times T_p M$ , where  $\pi$  is the canonical projection of  $TM$  onto  $M$ . In particular, this means that in  $\pi^{-1}(U)$ , we have the coordinate charts  $x^i \times dx^i$  and  $y^i \times dy^i$ .

Thus, the transition map is just  $(x \rightarrow y, dx \rightarrow dy)$ , where  $x \rightarrow y$  is the transition map from the  $x$  coordinate system to the  $y$  coordinate system, and  $dx \rightarrow dy$  is the transition map from the  $\partial_x|_p$  coordinate system to the  $\partial_y|_p$  coordinate system.

Recall that  $dx \rightarrow dy$  is simply the Jacobian of the original coordinate transform. That is,  $dx \rightarrow dy = J(x \rightarrow y)$ . Now, from the above lemma,

$$J(x \rightarrow y, dx \rightarrow dy) = J(x \rightarrow y, J(x \rightarrow y)) = (J(x \rightarrow y), J(J(x \rightarrow y)))$$

It should be clear that  $J^2 = J$ , since the Jacobian of a transformation is linear. Thus, we have that

$$J(x \rightarrow y, dx \rightarrow dy) = (J(x \rightarrow y), J(x \rightarrow y))$$

To calculate the determinant of this, we appeal to the fact that the determinant of a linear transformation of the form  $(A, B)$  is the product of the determinants of  $A$  and  $B$ . Thus,

$$\begin{aligned} \det J(x \rightarrow y, dx \rightarrow dy) &= \det(J(x \rightarrow y)) \det(J(x \rightarrow y)) \\ &= (\det(J(x \rightarrow y)))^2 \end{aligned}$$

Which is always positive.

Since this can be done at any point  $p$  in the manifold, we have an atlas for  $TM$  where the determinant of the coordinate transforms is always positive, and thus  $TM$  is orientable.  $\square$

### PROBLEM 3

Show that for  $M$  a smooth manifold, and  $S \subset M$  a smooth submanifold,  $S$  is embedded if and only if for every  $f \in C^\infty(S)$ ,  $f$  has a smooth extension to a neighborhood of  $S$  in  $M$ .

*Proof.* (  $\implies$  ) Suppose  $S$  is embedded. In particular, this means that each point  $s \in S$  has a neighborhood  $U_s$  on which there is a slice chart  $\phi$  of  $S$  on  $M$ . In particular, if  $\dim(M) = m$  and  $\dim(S) = k$ , and  $x^i$  are the coordinate functions of  $\phi$ , then there is a chart on  $U_s$  centered at  $s$  for which  $(x^1, \dots, x^m)|_S = (x^1, \dots, x^k, 0, \dots, 0)$ .

Now, let  $f \in C^\infty(S)$ . Since  $U_s$  has a slice chart, it is possible to extend  $f$  locally to a function  $\tilde{f}_s \in C^\infty(U_s)$  such that  $\tilde{f}_s|_S = f$ . This is possible through the use of smooth bump functions on the coordinates  $m - k$  to  $k$ .

So, choose a countable number of such  $U_s$ , call them  $U_i$ , that cover  $S$ , and let  $\Psi = \sum_{i=1}^\infty \psi_i$  be a partition of unity subordinate to  $\{U_i\}$ . Then, the function

$$\tilde{f}(x) = \sum_{i=1}^\infty \psi_i(x) \tilde{f}_i(x)$$

is a smooth extension of  $f$  that restricts to  $f$ .

(  $\impliedby$  ) Suppose for the converse that each  $f \in C^\infty(S)$  had a smooth extension to a neighborhood  $U$  of  $S$ . Now, in particular for each open set  $U$  in  $S$ , we can construct a smooth function  $f$  on  $S$  for which  $\text{supp}(f) = U$ . This function has a smooth extension  $\tilde{f}$  on some  $U' \subset M$  for which  $\tilde{f}|_U = f$ . Furthermore,  $\text{supp}(\tilde{f})$  is open in  $M$ , and the intersection

$$\text{supp}(\tilde{f}) \cap S = \text{supp}(f) = U$$

Thus, each open set in  $S$  is the intersection of  $S$  with an open set in  $M$ , and  $S$  has the subspace topology, making  $S$  an embedding. □

## PROBLEM 4

Let  $M$  be a manifold, and  $p \in M$ .

### PART A

Show that  $I_p = \{f \in C^\infty(M) \mid f(p) = 0\}$  is a maximal ideal in  $C^\infty(M)$ .

*Proof.* Suppose  $I_p \subsetneq I$  for some ideal  $I$ . In particular, this means that there is some  $f \in I$  with  $f(p) \neq 0$ . Without loss of generality, let  $f(p) > 0$ .

Now, by theorem 2.29 of Lee, there exists a nonnegative function  $g$  for which  $g^{-1}(0) = \{p\}$ . Since this function vanishes at  $p$ , it is in the ideal, as well as the function  $f + g$ . In particular,  $f + g > 0$  at every point.

Thus, the function  $\frac{1}{f+g}$  is well-defined, and by the multiplicatively absorbing property of ideals, the function  $\frac{1}{f+g}(f + g) = 1$  is in the ideal as well. Since 1 is the unit, it follows that  $I = C^\infty(M)$ . Thus,  $I_p$  is maximal.  $\square$

### PART B

Show that if  $M$  is compact, any maximal ideal in  $C^\infty(M)$  is of this form.

*Proof.* Suppose for a contradiction that some maximal ideal  $I$  such that at each point  $p \in M$ , there is some  $f_p$  such that  $f_p \notin I$ .

In particular, this means that there is a neighborhood  $U_p$  of  $p$  for which  $f_p$  is nonzero. The neighborhoods  $U_p$  form an open cover of  $M$ , of which there is a finite subcover  $\{U_i\}_{i=1}^n$ . Then, the function  $F = \sum_{i=1}^n (f_i)^2$  is everywhere nonzero, and in the ideal since  $I$  is additively closed. Thus, the function  $\frac{F}{F} = 1$  is well-defined everywhere, and in the ideal  $I$ . Thus,  $I = C^\infty(M)$ , which contradicts  $I$  being (nontrivially) maximal.

Thus, for each ideal  $I$  in  $C^\infty(M)$ ,  $I$  must have all functions vanish at at least one point  $p$ . Considering only the maximal ideals, it must follow that for a maximal ideal  $I$ , the functions in  $I$  vanish at exactly one point  $p$ , so  $I = I_p$ . This follows by observing that if functions in  $I$  vanished at two points  $p$  and  $q$ , then  $I$  would be contained in  $I_p$  and  $I_q$ , and would not be maximal.

Thus, every maximal ideal in  $C^\infty(M)$  is of the form  $I_p$ .  $\square$

## PROBLEM 5

### PART A

Show that, for a quaternion  $q = a + bi + cj + dk$ ,  $|q|^2 = q\bar{q}$  is equal to  $a^2 + b^2 + c^2 + d^2$ . Conclude that  $S^3$  can be identified with the unit quaternions.

*Proof.* This follows from direct computation.

$$\begin{aligned}
 q\bar{q} &= (a + bi + cj + dk)(a - bi - cj - dk) \\
 &= a^2 - abi - acj - adk + abi - (bi)^2 - bcij - bdik \\
 &\quad + acj - bcji - (cj)^2 - cdjk + adk - bdk i - cdkj - (dk)^2 \\
 &= a^2 + b^2 + c^2 + d^2 - bcij - bcji - bdik - bdk i - cdjk - cdkj - bdik - bdik \\
 &= a^2 + b^2 + c^2 + d^2
 \end{aligned}$$

where the last equality was obtained by observing that  $ij = -ji$  and  $jk = -kj$ .

Thus, the norm on  $\mathbb{H}$  coincides with the norm on  $\mathbb{R}^4$ , and so the topologies agree. Thus,  $S^3$  can be identified with the unit quaternions in an isometric way.  $\square$

### PART B

Show that  $S^3$  is a Lie group with quaternion multiplication.

*Proof.* We will first show that the operation of quaternion multiplication is smooth in the ambient space  $\mathbb{R}^4 \setminus \{0\} \cong \mathbb{H} \setminus \{0\}$ , and conclude that since  $S^3$  is a closed embedded subgroup of  $\mathbb{H} \setminus \{0\}$ , it is a Lie group under the same operation.

We will show that the operation of multiplication is smooth by directly calculating the multiplication in the standard coordinates on  $\mathbb{R}^4$ .

So, let  $q_1 = (x^1, x^2, x^3, x^4)$  and  $q^2 = (y^1, y^2, y^3, y^4)$ . Then,

$$\begin{aligned}
 q_1 q_2 &= (x^1 + x^2 i + x^3 j + x^4 k)(y^1 + y^2 i + y^3 j + y^4 k) \\
 &= x^1 y^1 + x^1 y^2 i + x^1 y^3 j + x^1 y^4 k \\
 &\quad + x^2 y^1 i + x^2 y^2 ii + x^2 y^3 ij + x^2 y^4 ik \\
 &\quad + x^3 y^1 j + x^3 y^2 ji + x^3 y^3 jj + x^3 y^4 jk \\
 &\quad + x^4 y^1 k + x^4 y^2 ki + x^4 y^3 kj + x^4 y^4 kk \\
 &= x^1 y^1 - x^2 y^2 - x^3 y^3 - x^4 y^4 \\
 &\quad + (x^1 y^2 + x^2 y^1 + x^3 x^4 - x^4 x^3) i \\
 &\quad + (x^1 y^3 - x^2 y^4 + x^3 y^1 + x^4 y^2) j \\
 &\quad + (x^1 y^4 + x^2 y^3 - x^3 y^2 + x^4 y^1) k
 \end{aligned}$$

which is clearly a smooth operation. Thus,  $S^3$  is a Lie group under quaternion multiplication.  $\square$