Announcements Sep 8

- Please turn on your camera if you are able and comfortable doing so
- Current plan: Class on Monday in Howey L1/Teams (email forthcoming)
 - attendance optional
 - masks + distance from me expected
 - testing encouraged
- Quiz on 1.2 & 1.3 Friday. Open 6:30a–8p on Canvas/Assignments, 15 mins
- WeBWorK 1.2 & 1.3 due Thursday nite
- WeBWorK 2.1 & 2.2 due Tuesday nite
- Use Piazza for general questions
- Office hrs: Tue 4-5 Teams + Thu 1-2 Skiles courtyard/Teams + Pop-ups
- Many, many TA office hours listed on Canvas
- Studio this Friday online; Studio for M02 will be recorded/streamed
- Section M web site: Google "Dan Margalit math", click on 1553
 - ▶ future blank slides, past lecture slides, old quizzes/exams
- Tutoring: http://tutoring.gatech.edu/tutoring
- PLUS sessions: http://tutoring.gatech.edu/plus-sessions
- Math Lab: http://tutoring.gatech.edu/drop-tutoring-help-desks
- Counseling center: https://counseling.gatech.edu
- You can do it!

Chapter 2

System of Linear Equations: Geometry

Where are we?

In Chapter 1 we learned to solve any system of linear equations in any number of variables. The answer is row reduction, which gives an algebraic solution. In Chapter 2 we put some geometry behind the algebra. It is the geometry that gives us intuition and deeper meaning. There are three main points:

Sec 2.3: Ax = b is consistent $\Leftrightarrow b$ is in the span of the columns of A.

Sec 2.4: The solutions to Ax = b are parallel to the solutions to Ax = 0.

Sec 2.9: The dim's of $\{b: Ax=b \text{ is consistent}\}$ and $\{\text{solutions to } Ax=b\}$ add up to the number of columns of A.

Section 2.1

Vectors

Outline

- Think of points in \mathbb{R}^n as vectors.
- Learn how to add vectors and multiply them by a scalar
- Understand the geometry of adding vectors and multiplying them by a scalar
- Understand linear combinations algebraically and geometrically

Vectors

A vector is a matrix with one row or one column. We can think of a vector with n rows as:

- ullet a point in \mathbb{R}^n
- ullet an arrow in \mathbb{R}^n

To go from an arrow to a point in \mathbb{R}^n , we subtract the tip of the arrow from the starting point. Note that there are many arrows representing the same vector.

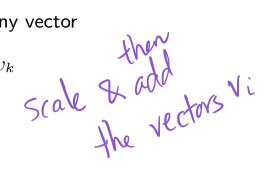
A scalar is just a real number. We use this term to indicate that we are scaling a vector by this number.

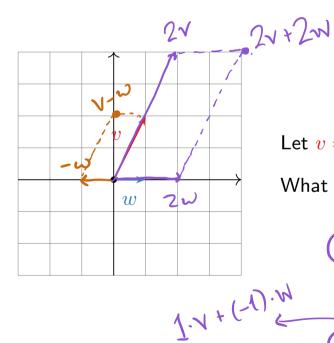
Linear Combinations

A linear combination of the vectors v_1, \ldots, v_k is any vector

$$c_1v_1 + c_2v_2 + \dots + c_kv_k$$

where c_1, \ldots, c_k are real numbers.





Let
$$v = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$
 and $w = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$.

What are some linear combinations of v and w?

(1)
$$2v + 2u = 2(\frac{1}{2}) + 2(\frac{1}{6})$$

= $(\frac{2}{4}) + (\frac{2}{6}) = (\frac{4}{4})$

$$\boxed{2} V - \omega = \begin{pmatrix} 1 \\ 2 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \end{pmatrix}$$

(3)
$$2V - \omega = \binom{2}{4} - \binom{1}{6} = \binom{1}{4}$$
 et

Poll In language

In language

Sec 2.7:

The span of

(1)

(1)

& (3) Is there a vector in \mathbb{R}^2 that is not a linear combination Every pt in R is a lin combo of VIW. of v and w? yes Secretly: Solving system. $W = \begin{pmatrix} 9 \\ 9 \end{pmatrix}$ w 750.7 = (50) $\begin{pmatrix} 98 \\ 100 \end{pmatrix} = 50 \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} + 48 \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ $\begin{pmatrix} -1 \\ 0 \end{pmatrix} = O \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} + -1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

Linear Combinations

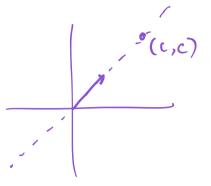
What are some linear combinations of (1,1)?

What are some linear combinations of (1,1) and (2,2)?

$$15 \cdot (1) + -9 \cdot (2) = -3 \cdot (1)$$

$$-18 \cdot (1)$$

What are some linear combinations of (0,0)?



Linear Combinations

What are all linear combinations of (1,0,0) and (0,0,1)?

What are all linear combinations of (1, 1, 0) and (0, 0, 1)?

Take plane from last example, rotate by ... 45°

about... Z-axis

What are all linear combinations of (3,2,4) and (-4,2,1)?

Summary of Section 2.1

- A vector is a point/arrow in \mathbb{R}^n
- We can add/scale vectors algebraically & geometrically (parallelogram rule)
- A linear combination of vectors v_1, \ldots, v_k is a vector

$$c_1v_1 + \cdots + c_kv_k$$

where c_1, \ldots, c_k are real numbers.

Typical exam questions

True/False: For any collection of vectors v_1, \ldots, v_k in \mathbb{R}^n , the zero vector in \mathbb{R}^n is a linear combination of v_1, \ldots, v_k .

True/False: The vector (1,1) can be written as a linear combination of (2,2) and (-2,-2) in infinitely many ways.

Describe geometrically the set of linear combinations of the vectors (1,0,0) and (1,2,3).

Suppose that v is a vector in \mathbb{R}^n , and consider the set of all linear combinations of v. What geometric shape is this?

Section 2.2

Vector Equations and Spans

Outline of Section 2.2

• Learn the equivalences:

vector equations \leftrightarrow augmented matrices \leftrightarrow linear systems

- Learn the definition of span
- Learn the relationship between spans and consistency

Linear Combinations

Is
$$\begin{pmatrix} 8 \\ 16 \\ 3 \end{pmatrix}$$
 a linear combination of $\begin{pmatrix} 1 \\ 2 \\ 6 \end{pmatrix}$ and $\begin{pmatrix} -1 \\ -2 \\ -1 \end{pmatrix}$? Supply fant.

Write down an equation in order to solve this problem. This is called a vector equation.

 $\nearrow \times \cdot \begin{pmatrix} 1 \\ 2 \\ 6 \end{pmatrix} + \cancel{?} \cdot \begin{pmatrix} -1 \\ -2 \\ -1 \end{pmatrix} = \begin{pmatrix} 16 \\ 3 \end{pmatrix} \nearrow$ Notice that the vector equation can be rewritten as a system of linear equations. Solve it!

$$\begin{array}{l} x - y = 8 \\ 2x - 2y = 16 \\ 6x - y = 3 \end{array} \longleftrightarrow \begin{array}{l} \begin{pmatrix} 1 & -1 & | & 8 \\ z & -2 & | & 16 \\ 6 & -1 & | & 3 \end{pmatrix} \end{array}$$

Now answer by row reduction. Is there a pivot on RHS? check!

Linear combinations, vector equations, and linear systems

In general, asking:

Is b a linear combination of v_1, \ldots, v_k ?

is the same as asking if the vector equation

$$x_1v_1 + \cdots + x_kv_k = b$$

Repeat of last Slide in general anguage.

is consistent, which is the same as asking if the system of linear equations corresponding to the augmented matrix

$$\begin{pmatrix} | & | & & | & | \\ v_1 & v_2 & \cdots & v_k & | & b \\ | & | & & | & | & | \end{pmatrix},$$

is consistent.

Compare with the previous slide! Make sure you are comfortable going back and forth between the specific case (last slide) and the general case (this slide).

Essential vocabulary word!

Span
$$\{\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \end{pmatrix} \} = \mathbb{R}^3$$

Span $\{\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \end{pmatrix} \} = \mathbb{R}^3$

Span $\{v_1, v_2, \dots, v_k\} = \{x_1v_1 + x_2v_2 + \dots + x_kv_k \mid x_i \text{ in } \mathbb{R}\} \leftarrow \text{(set builder notation)}$ = the set of all linear combinations of vectors v_1, v_2, \dots, v_k = plane through the origin and v_1, v_2, \dots, v_k .

What are the possibilities for the span of two vectors in \mathbb{R}^2 ? $\square(0,0)$ (both vectors) are zero)

What are the possibilities for the span of three vectors in \mathbb{R}^3 ? dector is in plane 2

Note that the possibilities for the span of three vectors in \mathbb{R}^3 ? dector is in plane 2

Spanned by first 2

Lall three vectors are multiples of each other

Conclusion: Spans are planes (of some dimension) through the origin, and the dimension of the plane is at most the number of vectors you started with and is at most the dimension of the space they're in.

Span

Essential vocabulary word!

$$\begin{pmatrix} 1 & -1 & 8 \\ 2 & -2 & 16 \\ 6 & -1 & 3 \end{pmatrix} \sim \begin{pmatrix} 1 & -1 & 8 \\ 0 & 6 & 6 \\ 0 & 5 & -45 \end{pmatrix} \quad \text{Consistent!}$$

$$\operatorname{Span}\{v_1,v_2,\ldots,v_k\} = \{x_1v_1 + x_2v_2 + \cdots x_kv_k \mid x_i \text{ in } \mathbb{R}\}$$

$$= \text{the set of all linear combinations of vectors } v_1,v_2,\ldots,v_k$$

$$= \text{plane through the origin and } v_1,v_2,\ldots,v_k.$$

$$= \operatorname{plane through the origin and } v_1,v_2,\ldots,v_k.$$

Four ways of saying the same thing:

- b is in Span $\{v_1, v_2, \dots, v_k\} \leftarrow \text{geometry}$
- $b \text{ is a linear combination of } v_1,\ldots,v_k$ the vector equation $x_1v_1+\cdots+x_kv_k=b$ has a solution \leftarrow algebra the system of linear equations corresponding to

• the system of linear equations corresponding to
$$\begin{pmatrix} |&|&&&|&|\\v_1&v_2&\cdots&v_k&b\\|&|&&|&|\end{pmatrix},$$

is consistent.







Application: Additive Color Theory

Consider now the two colors

$$\left(\begin{array}{c}180\\50\\200\end{array}\right), \left(\begin{array}{c}100\\150\\100\end{array}\right)$$



For which h is (116, 130, h) in the span of those two colors?



Summary of Section 2.2

- vector equations ↔ augmented matrices ↔ linear systems
- Checking if a linear system is consistent is the same as asking if the column vector on the end of an augmented matrix is in the span of the other column vectors.
- Spans are planes, and the dimension of the plane is at most the number of vectors you started with.

Typical exam questions

Is
$$\begin{pmatrix} 8 \\ 16 \\ 1 \end{pmatrix}$$
 in the span of $\begin{pmatrix} 1 \\ 2 \\ 6 \end{pmatrix}$ and $\begin{pmatrix} -1 \\ -2 \\ -1 \end{pmatrix}$?

Write down the vector equation for the previous problem.

True/False: The vector equation $x_1v_1 + \cdots + x_kv_k = 0$ is always consistent.

True/False: It is possible for the span of 3 vectors in \mathbb{R}^3 to be a line.

True/False: the plane z=1 in \mathbb{R}^3 is a span.