TIGHT GEODESICS

Problems with C(S): @ not locally finite ~ hard to do algorithms

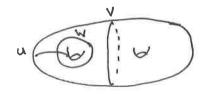
@ MCG action not prop disc ~ hard to glean into about MCG.

Will remedy this somewhat.

Tight geodesics

A tight geodesic from v to w is a seq. of simplices $v = T_0, ..., T_n = W$ 5.t. ① $\forall i = \partial F(T_{i-1}, T_{i+1})$ $F = \text{span of } T_{i-1}, T_{i+1} = \text{smallest subsurface}$ ② $d(v_i, v_j) = |i-j| \forall v_i \in T_i, v_j \in T_j \ i \neq j$. containing both

example.



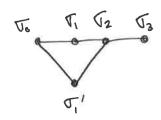
v is the canonical choice to get from u to w.

Tightening

Given a geodesic $V_0, ..., V_n$ can tighten at V_i : replace V_i by $\partial F(V_{i-1}, V_{i+1})$

Prop. If we tighten at vi then tighten at vi-1, result is still & tight at vi. In particular, tight geodesics exist.

Pf. Say To, TI, Tz, T3 already tight at T2 and we tighten at Ti:



New path is still geodesic (it has same length as a geodesic). \Rightarrow all components of ∇_1 ' & ∇_3 intersect $\Rightarrow F(\nabla_1', \nabla_3)$ connected.

 $i(\nabla_1', \nabla_2) = 0 \implies \nabla_1' \subseteq F(\nabla_1, \nabla_3)$ since $\nabla_2 = \partial F(\nabla_1, \nabla_3)$ $\implies F(\nabla_1', \nabla_3) \subseteq F(\nabla_1, \nabla_3)$ (use connectedness).

Need: T', T3 fill F(T1, T3).

So let $\alpha \subseteq F(\tau_1, \tau_3)$ and say $i(\alpha, \tau_3) = 0$.

~ need i(x, v,') \$0.

 $i(\alpha, \nabla_3) = 0 \implies i(\alpha, \nabla_1) \neq 0$ Since these pairs fill $i(\alpha, \nabla_0) \neq 0$ $F(\nabla_1, \nabla_3)$ and S resp.

But J, \$ F(J0, J2)

~ of must cross of (To, T2) to get from ♥ T, to To
T,'.

Prop. There are finitely many tight geodesics between two vertices v, w.

IF. Say d(V,W)=n.

Suffices to show \exists finitely many choices for $\forall \tau$ on a light $V = \tau_0, \tau_1, \ldots, \tau_n = W$

Cut S along v.

In = w ~ filling simplex of arc complex In

Vn-1 also gives Filling simplex In-1

Note: i(In, In-1) = 0.

Fact: Given a filling simplex T in arc complex T only finitely many simplices T' with i(T,T')=0.

By induction, finitely many choices for Tz.

By tightness, one choice of T, for each choice of T2.

In the above argument, we can algorithmically list all the Ti & J, 's.

Cor. I algorithm to compute distance in C(S).

IF. Assume have algorithm to distinguish distances 1,...,n-1 and > n-1.

Want on alg to dist. • distances 1,...,n and > n.

Let $v, w \in C(S)$. By induction we can tell if d(v,w) is 1,...,n-1 or > n-1.

If it is 1,...,n-1 we are done so assume d(v,w) > n.

Need to tell if d(v,w) is n or > n.

List all cardidate T_1 's on a tight path of length n as above.

If any such T_1 has $d(T_1,w)=n-1$ (using induction), d(v,w)=n.

Otherwise d(v,w) > n.

Applications of tight geodesics

Thm. Any pA in MCG(S) has , an honest geodesic oxis. bight!

Pf Sketch. Say f is pA with limit pts $a,b \in \partial C(S)$. $L_T = \text{ set of all tight geodesics from } a \text{ to } b$. | locally | G = subgraph of C(S) given by union of elts of L_T . $L_G = \text{ set of geodesics contained in } G$. Note $L_T \nsubseteq L_G$! $G/\langle f \rangle$ is finite

Say Je LG is lexicographically least if Y x, y ∈ J

the sequence of labels along I is lex. least among all geodesics from x to y in G.

L = set of lex. least gods = LG.

-> this is f-invariant.

Claim 1. Li = # p.

Pf. Take longer and longer lex. least goods local finiteness => some seq. converges.

Claim 2. | he / Loo.

Now take any $g \in L_L$. The finitely many elts are permuted by f so some power of f fixes a geodesic.

Cor. Stable translation length for a pA on C(S) is rational.

 $T(f) = \lim_{n \to \infty} \inf \frac{d(f^n(x), x)}{n}$