Section 3.3

Linear Transformations

Section 3.3 Outline

- Understand the definition of a linear transformation
- Linear transformations are the same as matrix transformations
- Find the matrix for a linear transformation

Linear transformations

A function $T : \mathbb{R}^n \to \mathbb{R}^m$ is a linear transformation if

- $T(u + v) = T(u) + T(v)$ for all u, v in $\mathbb{R}^n$.
- $T(cv) = cT(v)$ for all v in $\mathbb{R}^n$ and c in $\mathbb{R}$.

First examples: matrix transformations.

Linear transformations

A function $T : \mathbb{R}^n \to \mathbb{R}^m$ is a linear transformation if

- $T(u+v) = T(u) + T(v)$ for all u, v in $\mathbb{R}^n$.
- $T(cv) = cT(v)$ for all v in $\mathbb{R}^n$ and c in $\mathbb{R}$.

Notice that $T(0) = 0$. *Why?*

We have the standard basis vectors for $\mathbb{R}^n$:

$$\begin{aligned} e_1 &= (1, 0, 0, \ldots, 0) \\ e_2 &= (0, 1, 0, \ldots, 0) \\ &\vdots \end{aligned}$$

If we know $T(e_1), \ldots, T(e_n)$, then we know every $T(v)$. *Why?*

In engineering, this is called the principle of superposition.

Which are linear transformations?

And why?

$$T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x+y \\ y \\ x-y \end{pmatrix}$$

$$T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x+y+1 \\ y \\ x-y \end{pmatrix}$$

$$T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} xy \\ y \\ x-y \end{pmatrix}$$

A function $\mathbb{R}^n \to \mathbb{R}^m$ is linear exactly when the coordinates are linear (linear combinations of the variables, no constant terms).

Linear transformations

Which properties of a linear transformation fail for this function $T : \mathbb{R}^2 \to \mathbb{R}^2$?

$$T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ |y| \end{pmatrix}$$

Linear transformations are matrix transformations

Theorem. Every linear transformation is a matrix transformation.

This means that for any linear transformation $T : \mathbb{R}^n \to \mathbb{R}^m$ there is an $m \times n$ matrix A so that

$$T(v) = Av$$

for all v in $\mathbb{R}^n$.

The matrix for a linear transformation is called the standard matrix.

Linear transformations are matrix transformations

Theorem. Every linear transformation is a matrix transformation.

Given a linear transformation $T : \mathbb{R}^n \to \mathbb{R}^m$ the standard matrix is:

$$A = \begin{pmatrix} | & | & & | \\ T(e_1) & T(e_2) & \cdots & T(e_n) \\ | & | & & | \end{pmatrix}$$

Why? Notice that $Ae_i = T(e_i)$ for all i. Then it follows from linearity that $T(v) = Av$ for all v.

The identity

The identity linear transformation $T : \mathbb{R}^n \to \mathbb{R}^n$ is

$$T(v) = v$$

What is the standard matrix?

This standard matrix is called I_n or I.

Linear transformations are matrix transformations

Suppose $T : \mathbb{R}^2 \to \mathbb{R}^3$ is the function given by:

$$T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x+y \\ y \\ x-y \end{pmatrix}$$

What is the standard matrix for T?

Linear transformations are matrix transformations

Find the standard matrix for the linear transformation of $\mathbb{R}^2$ that stretches by 2 in the x-direction and 3 in the y-direction, and then reflects over the line $y = x$.

Linear transformations are matrix transformations

Find the standard matrix for the linear transformation of $\mathbb{R}^2$ that projects onto the y-axis and then rotates counterclockwise by $\pi/2$.

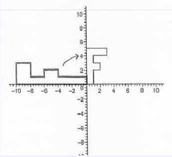
Linear transformations are matrix transformations

Find the standard matrix for the linear transformation of $\mathbb{R}^3$ that reflects through the xy-plane and then projects onto the yz-plane.

Discussion

Discussion Question

Find a matrix that does this.



Summary of Section 3.3

- A function $T : \mathbb{R}^n \to \mathbb{R}^m$ is linear if
  - $T(u+v) = T(u) + T(v)$ for all u, v in $\mathbb{R}^n$.
  - $T(cv) = cT(v)$ for all $v \in \mathbb{R}^n$ and c in $\mathbb{R}$.
- **Theorem.** Every linear transformation is a matrix transformation (and vice versa).
- The standard matrix for a linear transformation has its ith column equal to $T(e_i)$.

Typical Exam Questions Section 3.3

- Is the function $T : \mathbb{R} \to \mathbb{R}$ given by $T(x) = x + 1$ a linear transformation?
- Suppose that $T : \mathbb{R}^2 \to \mathbb{R}^3$ is a linear transformation and that

$$T\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 3 \\ 1 \end{pmatrix} \quad \text{and} \quad T\begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix}$$

  What is

$$T\begin{pmatrix} 1 \\ 0 \end{pmatrix}?$$

- Find the matrix for the linear transformation $T : \mathbb{R}^3 \to \mathbb{R}^3$ that rotates about the z-axis by π and then scales by 2.
- Suppose $T : \mathbb{R}^3 \to \mathbb{R}^3$ is the function given by:

$$T\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} z \\ 0 \\ x \end{pmatrix}$$

  Is this a linear transformation? If so, what is the standard matrix for T?
- Is the identity transformation one-to-one?