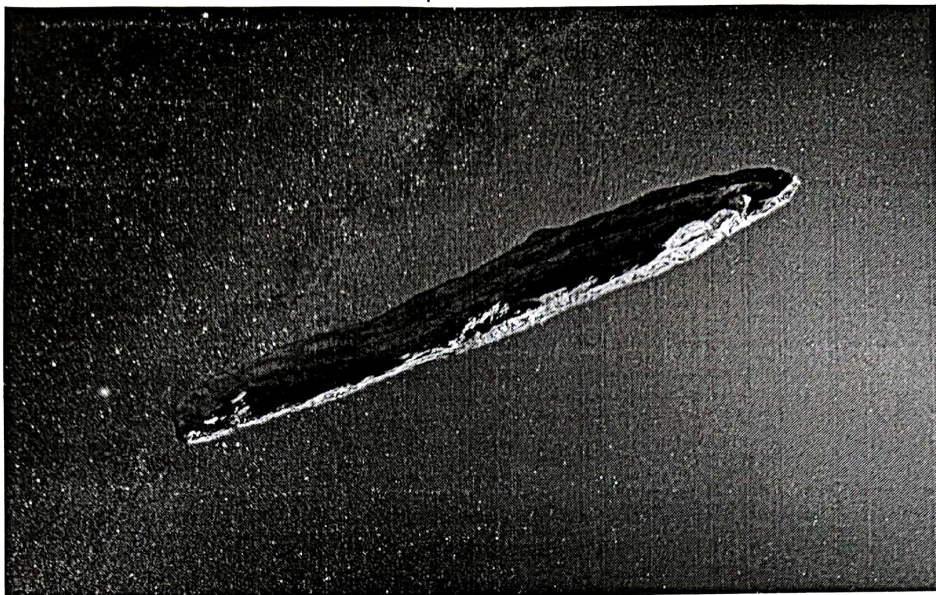


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IDSC 6490 Alien Space Probe Linear Edition



This is real ☺

I mean, it's an artist's rendering, but the science is real. It just happened. Did you hear about it?

Here is a link to the paper. Maybe just read the summary at the end ☺.

<https://arxiv.org/pdf/1810.11490.pdf>

1. OK, some equally as interesting stuff.

Please solve the system of linear equations by Gauss-Jordan elimination. I'll be looking for every detail please ☺. I'll leave lots of room.

$$x + 2y + 3z = 1$$

$$x + 3y + 6z = 3$$

$$2x + 6y + 13z = 5$$

Step 1:

① Subtract $2R_2$ from R_3 $2R_2 = [2 \ 6 \ 12 \ 6]$

② Subtract $R_2 - R_1$

③ $2 \ 6 \ 13 \ 5$ ④ $1 \ 3 \ 6 \ 3$

$-2 \ 6 \ 12 \ 6$ $-1 \ 2 \ 3 \ 1$

$\boxed{0 \ 0 \ 1 \ -1}$ $\boxed{0 \ 1 \ 3 \ 2}$

Some more space for you

$$\textcircled{2} \begin{pmatrix} 1 & 2 & 3 & | & 1 \\ 0 & 1 & 3 & | & 2 \\ 0 & 0 & 1 & | & -1 \end{pmatrix}$$

Step 2:

Subtract $3R_3$ from R_2 $3R_3 = [0 \ 0 \ 3 \ -3]$

$$\begin{array}{rrrr} 0 & 1 & 3 & 2 \\ - & 0 & 0 & 3 & -3 \\ \hline y & 0 & 1 & 0 & 5 \end{array}$$

$$\textcircled{3} \begin{pmatrix} 1 & 2 & 3 & | & 1 \\ 0 & 1 & 0 & | & 5 \\ 0 & 0 & 1 & | & -1 \end{pmatrix}$$

Step 3:

Subtract $2R_2$ from R_1 $2R_2 = [0 \ 2 \ 0 \ 10]$

$$\begin{array}{rrrr} 1 & 2 & 3 & 1 \\ - & 0 & 2 & 0 & 10 \\ \hline 1 & 0 & 3 & -9 \end{array}$$

$$\textcircled{4} \begin{pmatrix} 1 & 0 & 3 & | & -9 \\ 0 & 1 & 0 & | & 5 \\ 0 & 0 & 1 & | & -1 \end{pmatrix}$$

Step 4:

Subtract $3R_3$ from R_1 $3R_3 = [0 \ 0 \ 3 \ -3]$

$$\begin{array}{rrrr} 1 & 0 & 3 & -9 \\ - & 0 & 0 & 3 & -3 \\ \hline x & 1 & 0 & 0 & -6 \end{array} \text{ done!}$$

$$\textcircled{5} \begin{pmatrix} 1 & 0 & 0 & | & -6 \\ 0 & 1 & 0 & | & 5 \\ 0 & 0 & 1 & | & -1 \end{pmatrix} \quad \begin{array}{l} x = -6 \star \\ y = 5 \\ z = -1 \end{array}$$

$$\begin{array}{ll} \textcircled{1} -6 + 2(5) + 3(-1) = 1 & \textcircled{2} -6 + 3(5) + 6(-1) = 3 \\ -6 + 10 - 3 = 1 & -6 + 15 - 6 = 3 \\ 1 = 1 \checkmark & 3 = 3 \checkmark \end{array}$$

$$\begin{array}{l} \textcircled{3} 2(-6) + 6(5) + 13(-1) = 5 \\ -12 + 30 - 13 = 5 \\ 5 = 5 \checkmark \end{array}$$

2. Determine if the following matrix is symmetric or skew symmetric.

$$A = A^T$$

*Symmetric: $A = A^T$

Skew symmetric: $-A = A^T$

$$\begin{bmatrix} 5 & -7 & 1 \\ -7 & -8 & 2 \\ 1 & 2 & -4 \end{bmatrix}$$

$$A = \begin{bmatrix} 5 & -7 & 1 \\ -7 & -8 & 2 \\ 1 & 2 & -4 \end{bmatrix}$$

$$\text{Row 1} = [5 \ -7 \ 1]$$

$$\text{Row 2} = [-7 \ -8 \ 2]$$

$$\text{Row 3} = [1 \ 2 \ -4]$$

$$A^T = \begin{bmatrix} 5 & -7 & 1 \\ -7 & -8 & 2 \\ 1 & 2 & -4 \end{bmatrix}$$

This matrix A is symmetric.

3. Please determine whether or not the vectors form a basis for \mathbb{R}^4 . Show your methodology please ☺.

$$v_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$v_2 = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 2 \end{bmatrix}$$

$$v_3 = \begin{bmatrix} 2 \\ 5 \\ 6 \\ 4 \end{bmatrix}$$

$$v_4 = \begin{bmatrix} 2 \\ 6 \\ 8 \\ 5 \end{bmatrix}$$

If not, which of these vectors are

linearly dependent and what is the relationship of the dependent vectors to them? Numerically, that is.

I'll leave some space.

Gauss Jordan Elimination

$$A = \begin{bmatrix} 1 & 1 & 2 & 2 \\ 1 & 2 & 5 & 6 \\ 1 & 3 & 6 & 8 \\ 1 & 2 & 4 & 5 \end{bmatrix}$$

① Swap R_2 and R_4
Subtract R_2 from R_4

$$\begin{array}{l} \text{new } R_2 \rightarrow \\ R_4 \rightarrow \end{array} \begin{bmatrix} 1 & 1 & 2 & 2 \\ 1 & 2 & 4 & 5 \\ 1 & 3 & 6 & 8 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

② Subtract R_1 from R_2

$$\begin{bmatrix} 1 & 1 & 2 & 2 \\ 0 & 1 & 2 & 3 \\ 0 & 2 & 4 & 6 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

③ $R_3 - R_1$

$$\begin{bmatrix} 1 & 1 & 2 & 2 \\ 0 & 1 & 2 & 3 \\ 0 & 2 & 4 & 6 \\ 0 & 0 & 1 & 1 \end{bmatrix} \left. \begin{array}{l} \\ \\ \end{array} \right\} \text{dependence}$$

④ $R_3 - 2R_2$

$$\begin{bmatrix} 1 & 1 & 2 & 2 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

⑤ $R_1 - R_2$

$$\begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

⑥ $R_2 - 2R_4$

$$\begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

⑦ Swap R_3 and R_4

$$\begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Row reduced echelon form

row of zeroes signifies dependence.

Using my Gauss Jordan elimination, I noticed this:

$$R_3 - R_1 = 2[R_2 - R_1] \leftarrow \text{well, my "new" } R_2$$

$$R_1 = \begin{bmatrix} 1 & 1 & 2 & 2 \end{bmatrix}$$

$$R_2 = \begin{bmatrix} 1 & 2 & 4 & 5 \end{bmatrix}$$

$$R_3 = \begin{bmatrix} 1 & 3 & 6 & 8 \end{bmatrix}$$

Proof.

$$\begin{bmatrix} 1 & 3 & 6 & 8 \end{bmatrix} - \begin{bmatrix} 1 & 1 & 2 & 2 \end{bmatrix} = 2(\begin{bmatrix} 1 & 2 & 4 & 5 \end{bmatrix} - \begin{bmatrix} 1 & 1 & 2 & 2 \end{bmatrix})$$

$$\begin{bmatrix} 0 & 2 & 4 & 6 \end{bmatrix} = 2(\begin{bmatrix} 0 & 1 & 2 & 3 \end{bmatrix})$$

Weird that the possible space probe barely cracked the news huh? Or is it ☺ Maniacal laugh!!!!!!

$$\begin{bmatrix} 0 & 2 & 4 & 6 \end{bmatrix} = \begin{bmatrix} 0 & 2 & 4 & 6 \end{bmatrix}$$

$$R_3 = 2[R_2 - R_1] - R_1$$

4. Consider the exciting matrix $A = \begin{bmatrix} 2 & 4 \\ 3 & 13 \end{bmatrix}$.

By hand 100% please find the eigenvalues and the eigenvectors and decompose A into PDP^{-1} where D is the diagonal matrix composed of the eigenvalues and P is constructed with the eigenvectors. I'll leave LOT's of space ☺.

② Find λ or eigenvalues

$$A = \begin{pmatrix} 2 & 4 \\ 3 & 13 \end{pmatrix} - \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix} = \begin{pmatrix} 2-\lambda & 4 \\ 3 & 13-\lambda \end{pmatrix}$$

$$\det \begin{vmatrix} 2-\lambda & 4 \\ 3 & 13-\lambda \end{vmatrix} = (2-\lambda)(13-\lambda) - 12 = 0$$

$$26 - 13\lambda - 2\lambda + \lambda^2 - 12 = 0$$

$$14 - 15\lambda + \lambda^2 = 0$$

$$\lambda^2 - 15\lambda + 14 = 0$$

$$(\lambda - 1)(\lambda - 14) = 0 \quad \boxed{\lambda = 1 \text{ or } \lambda = 14} \text{ Eigenvalues}$$

③ Find eigenvectors

$$(A - \lambda I)(\vec{v}) = 0 \quad \text{Start w/ } \lambda = 1 \text{ (easier :))}$$

$$\begin{pmatrix} 2-\lambda & 4 & 0 \\ 3 & 13-\lambda & 0 \end{pmatrix} = \begin{pmatrix} 2-1 & 4 & 0 \\ 3 & 13-1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 4 & 0 \\ 3 & 12 & 0 \end{pmatrix}$$

Use Gauss Jordan and row reduce

$$\text{① } R_2 - 3R_1 \rightarrow \begin{pmatrix} 1 & 4 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Done

This says $v_1 + 4v_2 = 0$

$$v_1 = -4v_2$$

$$v_2 = t \text{ (any value)}$$

I will use 1

$$\vec{v}_1 = \begin{pmatrix} v_1 \\ -v_2 \end{pmatrix}$$

$$\vec{v}_1 = \begin{pmatrix} -4t \\ t \end{pmatrix}$$

$$\boxed{\vec{v}_1 = \begin{pmatrix} -4 \\ 1 \end{pmatrix}}$$

First Eigenvector

Now use $\lambda = 14$

$$\begin{pmatrix} 2-\lambda & 4 & 0 \\ 3 & 13-\lambda & 0 \end{pmatrix} = \begin{pmatrix} -12 & 4 & 0 \\ 3 & -1 & 0 \end{pmatrix}$$

Use Gauss Jordan and row reduce
Swap $R_1 + R_2$

$$\begin{pmatrix} 3 & -1 & 0 \\ -12 & 4 & 0 \end{pmatrix} \xrightarrow{\text{Then } R_2 + 4R_1} \begin{pmatrix} 3 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \xrightarrow{\text{Then } \frac{R_1}{3} \text{ to get 1 in Pivot}} \begin{pmatrix} 1 & -\frac{1}{3} & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$V_1 - \frac{1}{3}V_2 = 0$$

$$V_1 = \frac{1}{3}V_2$$

$$V_2 = t \text{ (again, we'll use 1)}$$

$$\vec{V}_2 = \begin{pmatrix} \frac{1}{3}t \\ t \end{pmatrix}$$

$$\vec{V}_2 = \begin{pmatrix} \frac{1}{3} \\ 1 \end{pmatrix}$$

Second Eigenvector

① Decompose A into PDP-1

$$A = \begin{pmatrix} -4 & \frac{1}{3} \\ 1 & 1 \end{pmatrix} = P \cdot D \cdot P^{-1}$$

$$A = -\frac{3}{13} \begin{pmatrix} -4 & \frac{1}{3} \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 14 \end{pmatrix} \begin{pmatrix} 1 & -\frac{1}{3} \\ -1 & -4 \end{pmatrix}$$

③ Multiply P and D

$$A \cdot P \cdot D = \begin{pmatrix} -4 & \frac{1}{3} \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 14 \end{pmatrix} = \begin{pmatrix} -4 & \frac{14}{3} \\ 1 & 14 \end{pmatrix}$$

$$A = -\frac{3}{13} \begin{pmatrix} -4 & \frac{14}{3} \\ 1 & 14 \end{pmatrix} \begin{pmatrix} 1 & -\frac{1}{3} \\ -1 & -4 \end{pmatrix}$$

$$P \cdot D \cdot P^{-1} = \begin{pmatrix} -4 & \frac{14}{3} \\ 1 & 14 \end{pmatrix} \begin{pmatrix} 1 & -\frac{1}{3} \\ -1 & -4 \end{pmatrix} = \begin{pmatrix} -\frac{26}{3} & -\frac{52}{3} \\ -13 & -\frac{169}{3} \end{pmatrix}$$

$$A = -\frac{3}{13} \begin{pmatrix} -\frac{26}{3} & -\frac{52}{3} \\ -13 & -\frac{169}{3} \end{pmatrix} = \begin{pmatrix} \left(-\frac{3}{13}\right)\left(-\frac{26}{3}\right) & \left(-\frac{3}{13}\right)\left(-\frac{52}{3}\right) \\ \left(-\frac{3}{13}\right)(-13) & \left(-\frac{3}{13}\right)\left(-\frac{169}{3}\right) \end{pmatrix} = \begin{pmatrix} \frac{26}{13} & \frac{52}{13} \\ \frac{3 \cdot 13}{13} & \frac{169}{13} \end{pmatrix} = \begin{pmatrix} 2 & 4 \\ 3 & 13 \end{pmatrix}$$

Eigenvalues

$$\lambda = 1$$

$$\lambda = 14$$

Eigenvectors

$$\vec{V}_1 = \begin{pmatrix} -4 \\ 1 \end{pmatrix}$$

$$\vec{V}_2 = \begin{pmatrix} \frac{1}{3} \\ 1 \end{pmatrix}$$

* Find P^{-1}

$$P^{-1} = \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

$$P^{-1} = \frac{1}{(-4)(1) - (\frac{1}{3})(1)} \begin{pmatrix} 1 & -\frac{1}{3} \\ -1 & -4 \end{pmatrix}$$

$$P^{-1} = -\frac{1}{-4 - \frac{1}{3}} \begin{pmatrix} 1 & -\frac{1}{3} \\ -1 & -4 \end{pmatrix}$$

$$P^{-1} = -\frac{3}{13} \begin{pmatrix} 1 & -\frac{1}{3} \\ -1 & -4 \end{pmatrix}$$

$$P = \begin{pmatrix} -4 & \frac{1}{3} \\ 1 & 1 \end{pmatrix} \quad D = \begin{pmatrix} 1 & 0 \\ 0 & 14 \end{pmatrix} \quad P^{-1} = -\frac{3}{13} \begin{pmatrix} 1 & -\frac{1}{3} \\ -1 & -4 \end{pmatrix}$$

$$\begin{aligned} \lambda &= 1 & \vec{v}_1 &= \begin{pmatrix} -4 \\ 1 \end{pmatrix} \\ \lambda &= 14 & \vec{v}_2 &= \begin{pmatrix} \frac{1}{3} \\ 1 \end{pmatrix} \end{aligned}$$

5. Following in my footsteps is uncovering the matrix U from the svd of $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & -1 \end{bmatrix}$ please be good enough to find the matrix V where $A = U\Sigma V$. Hint: Use R *LOL*. Cut and paste your code as well as clearly stating the answer 😊.

The matrix V = [-0.4082 -0.8165 0.4082]

[-0.7071 0 -0.7071]

[-0.5774 0.5774 0.5774]

```
In [17]: import numpy as np
import scipy as sp

In [22]: a = [1, 1, 0]
b = [0, 1, -1]

A = np.array([a, b])
M, N = A.shape

u, s, v = np.linalg.svd(A)
Sigma = sp.linalg.diagsvd(s, M, N)
```

Here is U

```
In [19]: print(np.round(u, 4))

[[-0.7071 -0.7071]
 [-0.7071  0.7071]]
```

This is Σ

```
In [20]: print(Sigma)

[[1.73205081 0. 0. ]
 [0. 1. 0. ]]
```

This is V

```
In [21]: print(np.round(v, 4))

[[-0.4082 -0.8165  0.4082]
 [-0.7071  0. -0.7071]
 [-0.5774  0.5774  0.5774]]
```

This is the reconstructed matrix

```
In [26]: print(np.round(u @ (Sigma @ v)))

[[ 1.  1.  0.]
 [ 0.  1. -1.]]
```