Alvaro Daniel Callata Suxo

Mechatronics Engineer — Robotics, Machine Learning & Computer Vision

Summary

Mechatronics engineer with experience in robotics, AI, and applied research. Contributed to national and academic projects, including Bolivia's first CubeSat (UNOOSA) and neural network-based trajectory prediction for NASA's Astrobee. Founder and lead engineer of the Robotic Chess project integrating a KUKA arm with ROS and electronic circuits design. Authored and presented peer-reviewed papers on additive manufacturing and STEM outreach at international conferences. Skilled in CAD design, prototyping, and system simulation, with SolidWorks certifications (CSWA, additive manufacturing, sustainability). Completed a specialization in Supply Chain Management (Rutgers University) that complements technical expertise with knowledge in logistics, operations, and strategic planning. Seeking opportunities to advance interdisciplinary research in robotics, intelligent systems, and computer vision.

Education

Universidad Católica Boliviana "San Pablo"

Sep. 2025 - Present

 $Postgraduate\ Diploma\ in\ Robotics$

La Paz, Bolivia

• Training in robot kinematics and dynamics, intelligent control (PID, fuzzy, neural, adaptive, and robust), perception and motion planning, computer vision, collaborative manipulation, and programming of mobile and industrial robots.

Universidad Católica Boliviana "San Pablo"

Feb. 2019 - Jul. 2024

Bachelor of Engineering in Mechatronics Engineering GPA: 3.06/4.0

La Paz, Bolivia

- Graduated Magna Cum Laude. Thesis Score: 3.88/4.0.
- Long-time member of the university's R&D Center, participation in multiple robotics and software development projects.
- Team representative at NASA Human Exploration Rover Challenge, awarded 'Most Improved Performance'.

Rutgers University — Coursera

Sep. 2025

Supply Chain Management Specialization

Online

• Comprehensive specialization including logistics, operations, sourcing, and strategy for supply chain optimization and management.

Research & Conference Publications

1st Author: Mechanical Design and Testing of 3D-Printed Non-Pneumatic Wheels for Human-Powered Vehicles: A NASA HERC Case Study.

Presented at the 23rd LACCEI International Multi-Conference for Engineering, Education and Technology, 2025.

2nd Author: Additive Manufacturing for Tire Treads Design for Outer Space Challenging Terrains. Case: NASA HERC. Presented at the Casablanca International Conference on Additive Manufacturing (CASICAM), 2025.

4th Author: STEM Program Management and Outreach in Different Locations of a Country. Case: Bolivian NASA HERC STEM Activities.

Presented at the IEEE Integrated STEM Education Conference (ISEC), 2025.

Experience

PRINT3D

Limnology Unit - Universidad Mayor de San Andrés

La Paz, Bolivia

 $Engineering\ Consultant$

Jul. 2025 – Present

- Contributed to the design of a low-cost zebrafish research facility with IoT-based monitoring and automation.
- · Provided technical guidance on instrumentation and system development in interdisciplinary projects.

Research Associate (Biology)

Jul. 2025 - Present

- \bullet Worked on projects integrating robotics, computer vision, and AI with freshwater biology.
- Applied neural networks and image processing to biological imaging and classification tasks.

FIAB – Fundación de Investigación Aeroespacial

La Paz, Bolivia

 $R \mathcal{E}D \ Engineer - Structural \ \mathcal{E} \ Thermal \ Analysis$

Jul. 2024 – Present

- $\bullet \ \ Designed \ thermal \ and \ structural \ subsystems \ for \ Bolivia's \ first \ Cube Sat \ (UNOOSA \ Access \ to \ Space \ initiative).$
- Simulated orbital thermal conditions in ANSYS; contributed to EXOpod integration documentation.
- Developed mechanical interfaces following CubeSat standards for deployment and material selection.

Additive Manufacturing Intern

La Paz, Bolivia

• Maintained and upgraded 15+ FDM 3D printers, improving print quality by 60%.

- Upgraded firmware using Sonic-Pad controllers and put old equipment back into operation.
- Modeled 100+ functional mechanical parts for clients in SolidWorks.

Thesis Researcher - ABS Printing Optimization

Jul. 2023 - Jul. 2024

Feb. 2023 - Jul. 2023

- Led a research–industry collaboration with PRINT3D to improve manufacturing quality in additive manufacturing.
- Designed and Implemented post-processing tools adopted by PRINT3D for internal use and graded 97/100 (Magna Cum Laude).

SEDNA SRL La Paz, Bolivia

 $Software\ Development\ Intern$

Jul. 2022 - Jan. 2023

- Developed biometric access control software using C#/.NET and SQL Server.
- Contributed to full-stack solutions in Java and JavaScript for healthcare and business systems.

Computer Vision Segmentation Project | Python, OpenCV, Machine Learning

Aug. 2025 - Present

- Creating custom datasets and implementing semantic segmentation and ML detection models, evaluated on real-world
- Integrating IoT-sourced environmental data from in-house prototypes for model validation.

Point Optimization in NASA HERC | ML, Probabilistic Modeling, Graph Optimization

Jun. 2025 - Present

- Developing ML models to predict rover task success, time, energy, and points.
- Integrating probabilistic outputs into graph-based planners for optimized routes under user constraints.

1U CubeSat Development | CVXPy, Simulink, STM32, ROS

Jul. 2024 - Present

- Led GNC team developing a neural network-based trajectory predictor for Astrobee and integrated it into ROS/Gazebo simulator.
- Developed PIL/SIL environments and deployed payloads via STM32 in stratospheric balloon missions for sensor validation.

Robotic Chess System with KUKA Arm | ROS, Python, CAD, Embedded Systems

Jul. 2023 – Dec. 2024

- Founder and lead engineer of an autonomous chess system integrating KUKA robotic arm, ROS-based control, and a custom PCB chessboard.
- Implemented motion planning, inverse kinematics, and EKI communication.

Encapsulation and Post-Processing System for ABS | CAD, Firebase, MicroPython, IoT

Jul. 2023 - Jul. 2024

- Developed IoT-enabled systems for industrial ABS printing: a thermally controlled enclosure to prevent warping and an acetone vapor chamber to improve surface finish.
- Implemented remote parameter control via mobile interface and Firebase dashboards.

NASA HERC 2024 | SolidWorks, 3D Printing, CNC, Mechanical Design

Nov. 2023 - Apr. 2024

- Led rover tool design/fabrication, contributing to the "Most Improved Performance" Award.
- Produced components via CAD modeling, 3D printing, and CNC machining.
- Led the team to publish and present 3 peer-reviewed papers on NASA HERC innovations at international conferences.

Biometric Registration and Access Control System | C#/.NET, SQL Server, Embedded Systems Jul. 2022 - Jan. 2023

- \bullet Led implementation of biometric registration and entry/exit control at workplace arrival points.
- Integrated database, software, and hardware modules for reliable employee authentication.

Volunteering, Outreach & Lecture Experience

Casablanca International Conference on Additive Manufacturing

Casablanca, Morocco

Lecturer - Virtual Conference

Apr. 2024

• Presented "Additive Manufacturing for Tire Treads Design for Outer Space Challenging Terrains" to 300+ attendees, including ESA, Airbus, and universities across Europe and Africa.

International Multi-Conference on Engineering, Education and Technology

Mexico City, Mexico

Lecturer - Virtual Conference

Jul. 2025 ered Vehicles: A NASA

• Presented "Mechanical Design and Testing of 3D-Printed Non-Pneumatic Wheels for Human-Powered Vehicles: A NASA HERC Case Study" to Latin American engineering researchers and academic leaders.

Universidad Católica Boliviana "San Pablo" – ITEC 2024

La Paz, Bolivia

 $KUKA\ Robotic\ Arm\ Workshop\ Lecturer$

Oct. 2024

- Delivered practical sessions on KUKA arm operation, KRL programming, and safety protocols.
- Taught inverse kinematics, path planning, and Robot Operating System (ROS) integration.

Universidad Católica Boliviana "San Pablo" – VEMEC Team

La Paz, Bolivia

STEM Outreach Lecturer

Nov. 2023 - Apr. 2024

- Co-led outreach team delivering STEM workshops in 8 out of 9 Bolivian departments, reaching over 7,000 participants.
- Trained students in tech-related topics during national tour Gira STEM, with hands-on rover engineering activities.

Technical Skills & Certifications

Programming & Frameworks: Python (TensorFlow, OpenCV, CVXPy), C/C++, C#, Java, JavaScript, SQL, MAT-LAB/Simulink, ROS

Tools & Platforms: Git, Docker, STM32, Raspberry Pi, Jetson Nano, ESP32, Arduino, KUKA robots

CAD & Manufacturing: SolidWorks, Blender, Cura, PrusaSlicer, RDWorks, laser cutting, 3D printing (FDM, DLP) Languages: Spanish (native), English (B2)

Soft Skills: Leadership, teamwork, adaptability, self-motivation, quick learning, resilience

Certifications:

- SolidWorks CSWA CAD Design (Dassault Systèmes, 2024)
- Additive Manufacturing Associate (Dassault Systèmes, 2024)
- Sustainability Associate (Dassault Systèmes, 2023)
- In progress: Google Data Analytics (Coursera), Meta Full-Stack Developer (Coursera), IBM Databases and SQL for Data Science with Python (Coursera)

Awards & Recognitions

NASA HERC 2024 – Most Improved Performance Award (Huntsville, USA)

UNOOSA-EXOpod - Bolivia's First CubeSat Selected for Launch (Vienna, Austria)

LACCEI 2025 – Full Paper Presentation Certificate

Bolivian Senate – Recognition for NASA HERC Representation (2024)