# Problem Set #3

Danny Edgel Econ 714: Macroeconomics II Spring 2021

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Discussed and/or compared answers with Sarah Bass, Emily Case, Katherine Kwok, Michael Nattinger, and Alex Von Hafften

For all of the problems below, all computational work is performed in edgel\_ps3.m, which is attached. This code is heavily commented so as to mostly stand on its own. As a result, I will provide little explicit information about the code in this document, leaving it only for answering justifications, deriving relationships, etc.

### Questions 1 and 2

See first two sections of the attached code.

### Question 3

Since both capital and investment have moving steady states, it is reasonable to pick an arbitrary date to assume a steady state at some period prior to the sample period, then carrying the variables forward. With enough periods, the effect of assuming a steady state in the prior period is minimal-to-nonexistent. By the time the sample period begins, the steady state that  $k_t$  is relative to actually comes from the data rather than the earlier assumption.

#### Question 4

The table below displays the persistence parameters from the three wedges,  $a_t$ ,  $g_t$ , and  $\tau_{Lt}$ .

$\rho_a$	0.801
$\rho_q$	0.954
$ ho_{ au_L}$	0.911

### Question 5

Implementing Blanchard-Kahn to solve this model results in a linear relationship between  $c_t$  and  $k_t$  in the saddle path of the model. Log-linearizing the Euler equation and resource constraint, results in (after some serious algebra) a system of the following form:

$$x_{t+1} = \begin{pmatrix} k_{t+1} \\ c_{t+1} \end{pmatrix} = A \begin{pmatrix} k_t \\ c_t \end{pmatrix} + B \begin{pmatrix} a_t \\ g_t \\ \tau_{It} \\ \tau_{Lt} \end{pmatrix} = Ax_t + Bz_t$$

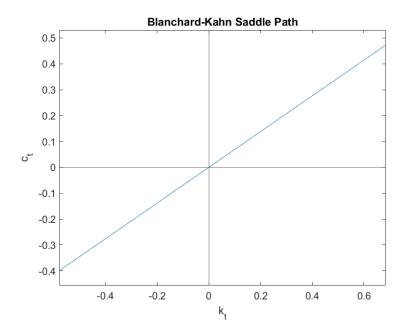
Where B does not need to be directly parametrically solved, and:

$$A = \begin{pmatrix} \frac{\alpha \delta \overline{Y}}{\overline{I}} + 1 - \delta + \frac{\delta(1-\alpha)\alpha \overline{Y}}{\overline{I}(\phi+\alpha)} & \frac{\delta(\alpha-1)\sigma \overline{Y}}{\overline{I}(\phi+\alpha)} - \frac{\delta \overline{C}}{\overline{I}} \\ \left(\frac{\phi \Gamma}{1-\Gamma}\right) \left(\frac{\alpha \delta \overline{Y}}{\overline{I}} + 1 - \delta + \frac{\delta(1-\alpha)\alpha \overline{Y}}{\overline{I}(\phi+\alpha)}\right) & \frac{1}{1-\Gamma} \left(\sigma + \phi \Gamma \left(\frac{\delta(\alpha-1)\sigma \overline{Y}}{\overline{I}(\phi+\alpha)} - \frac{\delta \overline{C}}{\overline{I}}\right)\right) \end{pmatrix}$$

Where  $\overline{X}$  is the steady state of everything in the parentheses of the RHS of the Euler equation and:

$$\theta = \alpha \overline{AK}^{\alpha-1} \overline{L}^{1-\alpha}, \ \Gamma = \frac{\theta(1-\alpha)}{\overline{X}(\phi+\alpha)}$$

The saddle path, holding all wedges constant, is displayed in the chart below.

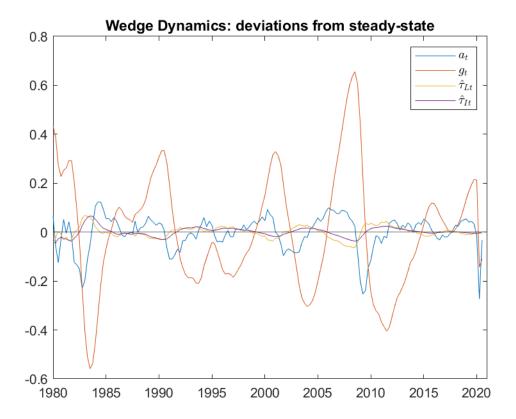


### Question 6

include equations used to solve for  $\tau_{It}$  and its steady state

Solving for the fixed-point estimate of  $\tau_{It}$  results in a persistence parameter of  $\rho_{\tau_I}=0.944$  .

# ${\bf Question} \ {\bf 7}$



# Question 8

Edgel, 3