# Problem Set #5

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### Question 1

Let X and Y be normed vector spaces, where  $T \in L(X, Y)$ .

(a) Show that if there exists some m>0 such that  $m||x||\leq ||T(x)||,$  then T is one-to-one.

T is one-to-one if and only if  $T(x)=\vec{0}$  has only the trivial solution (i.e.  $x=\vec{0}$ ). If  $\exists m>0$  s.t.  $m||x||\leq ||T(X)||$ , then

$$m||0|| \le ||T(\vec{0})||$$
  
 $0 \le ||T(\vec{0})||$ 

Since  $||\cdot|| \ge 0$ ,  $T(\vec{0}) = 0$ . We can likewise show that this inequality requires  $x = \vec{0}$  if  $T(\vec{0}) = 0$ :

$$m||x|| \le ||T(\vec{0})||$$
  
$$m||x|| \le 0$$

Thus,  $T(\vec{0}) = \vec{0} \iff x = \vec{0}$ , so T is one-to-one.  $\therefore$  if  $\exists m > 0$  s.t.  $m||x|| \le ||T(X)||$ , then T is one-to-one.

(b) Use the theorem with five equivalent properties to show that  $T^{-1}(\cdot)$  is continuous on T(X)

We know that, for any linear  $T \in L(X,Y)$ , where X and Y are normed vector spaces, that "T is Lipschitz" and "T is continuous" are equivalent statements.  $T^{-1} \in L(T(X),X)$ , where X and  $T(X) \subseteq Y$  are normed

vector spaces, so this theorem applies to  $T^{-1}$ . From  $m||x|| \leq ||T(X)||$ , m > 0, we can derive:

$$m||T^{-1}(T(x))|| \le ||T(x)||$$
  
 $||T^{-1}(T(x))|| \le \frac{1}{m} \le ||T(x)||$ 

So  $\exists \beta = \frac{1}{m} \in \mathbb{R}$  such that  $||T^{-1}(T(x))|| \leq \beta \leq ||T(x)|| \ \forall x \in \text{Im} T(X)$ . Thus,  $T^{-1}$  is bounded on T(X).  $\therefore$ ,  $T^{-1}$  is continuous on T(X).

(c) Use the same theorem to show that if  $T^{-1}$  is continuous on T(X), then there exists some m > 0 such that  $m||x|| \le ||T(x)||$ 

Since the continuity of  $T^{-1}$  implies that  $T^{-1}$  is also Lipschitz, then if  $T^{-1}$  is continuous, if  $a, \vec{0} \in \text{Im}T(X)$ , T(x) = a, and k > 0:

$$||a - \vec{0}|| \le k||T(x) - T(\vec{0})||$$

$$||T^{-1}(T(x))|| \le k||T(x)||$$

$$\frac{1}{k}||x|| \le ||T(x)||$$

Thus,  $\exists m = \frac{1}{k} > 0$  such that  $m||x|| \le ||T(x)||$ .

#### Question 2

Define  $T: \mathbb{R}^2 \to \mathbb{R}^2$  as T(x,y) = (x+5y, 8x+7y).

(a) Calculate ||T|| given the norm  $||(x,y)||_1 = |x| + |y|$  in  $\mathbb{R}^2$ 

||T|| is the supremum of ||T|| using the norm function  $||(x,y)||_1 = |x| + |y|$ , where ||(x,y)|| = |x| + |y| = 1. Thus, we can rewrite the problem as:

$$||T|| = \max_{|x|+|y|=1} \left\{ |x+5y| + |8x+7y| \right\}$$

Since there is no multiplicative interaction between x and y in ||T||, the (x,y) that maximizes ||T|| will have one zero element and one element equal to one. y clearly maximizes ||T|| relative to x, so:

$$||T|| = ||T(0,1)|| = |5| + |7| = 12$$

(b) Calculate ||T|| given the norm  $||(x,y)||_{\infty} = \max\{|x|,|y|\}$  in  $\mathbb{R}^2$ 

Since both x and y contribute positively to ||T|| and our constraint is  $\max\{|x|,|y|\}=1$ , the vector that maximizes ||T|| is (1,1). Therefore,

$$||T|| = ||T(1,1)|| = \max\{|1+5|, |8+7|\} = 15$$

#### Question 3

Define  $V = \{(a_1, a_2), (b_1, b_2)\}$  as an orthonormal basis of  $\mathbb{R}^2$ . Define W as the standard basis of  $\mathbb{R}^2$ . For some x = (x, y), define  $x = [x]_W$ . Then, for some orthogonal matrix P,  $x = P[x]_V$ . Since P'P = I,

$$x = P[x]_V$$

$$P'x = (P'P)[x]_V$$

$$P'x = [x]_V$$

Let  $v = [x]_V$ . Then, we can derive:

$$||[x]_V|| = ||v|| = \sqrt{v'v} = \sqrt{(Px)'(Px)} = \sqrt{(x'P'Px)} = \sqrt{x'x} = ||x||$$

 $\therefore$  the length of x does not depend on the choice of orthonormal basis

### Question 4

Define:

$$\frac{d}{dt}y(t) = \begin{pmatrix} 1 & 1\\ 3 & -1 \end{pmatrix} y(t), \ y(0) \begin{pmatrix} 1\\ 3 \end{pmatrix}$$

Then, to solve for  $y(t) = Pdiag\{e^{t\lambda_1}, ..., e^{t\lambda_n}\}P^{-1}y(0)$ , we begin by finding A's eigenvalues and eigenvectors:

$$|A - \lambda I| = 0$$
$$(1 - \lambda)(-1 - \lambda) - 3 = 0$$
$$\lambda^2 - 4 = 0$$

Thus,  $\lambda_1 = 2$  and  $\lambda_2 = -2$ .

$$(A - \lambda_1 I)v_1 = 0$$

$$\begin{bmatrix} -1 & 1 & 0 \\ 3 & -3 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 1 & 0 \\ 3 & 1 & 0 \end{bmatrix}$$

$$v_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$v_2 = \begin{pmatrix} 3 \\ -1 \end{pmatrix}$$

Now, define:

$$A = Pdiag\{\lambda_1, \lambda_2\}P^{-1} = \begin{pmatrix} 1 & 3 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & -2 \end{pmatrix} \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ -\frac{1}{4} & \frac{1}{4} \end{pmatrix}$$

Letting  $y(t) = Pdiag\{e^{t\lambda_1}, ..., e^{t\lambda_n}\}P^{-1}$ , we can solve:

$$y(t) = \frac{1}{4} \begin{pmatrix} 1 & 3 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & -2 \end{pmatrix} \begin{pmatrix} 4 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$y(t) = \frac{1}{4} \begin{pmatrix} 1 & 3 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 3e^{2t} & e^{2t} \\ -e^{-2t} & e^{-2t} \end{pmatrix} \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$y(t) = \frac{1}{4} \begin{pmatrix} 3e^{2t} - 3e^{-2t} & e^{2t} + 3e^{-2t} \\ 3e^{2t} + e^{-2t} & e^{2t} - e^{-2t} \end{pmatrix} \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$y(t) = \frac{1}{4} \begin{pmatrix} 6e^{2t} + 6e^{-2t} \\ 6e^{2t} - 2e^{-2t} \end{pmatrix}$$

$$y(t) = \frac{1}{2} \begin{pmatrix} 3e^{2t} + 3e^{-2t} \\ 3e^{2t} - e^{-2t} \end{pmatrix}$$

## Question 5

The solution to question 4 is not stable because  $\lambda_1 = 2 > 0$ , so the solution:

$$y(t) = \frac{1}{2} \begin{pmatrix} 3e^{2t} + 3e^{-2t} \\ 3e^{2t} - e^{-2t} \end{pmatrix}$$

Is not stable. A small change in y(0) will cause infinitely large swings in  $e^{2t}$  as  $t \to \infty$ .