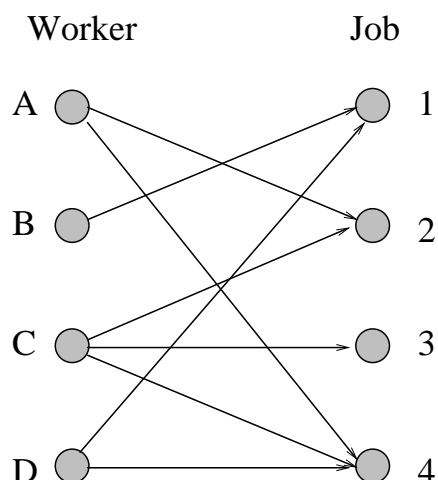


# Assignment and Matching

---

1. A matching is a pairing of nodes—*collection of disjoint edges*.



2. Bipartite graph. Two node classes, workers and jobs.
3. An edge  $(i, j)$  means worker  $i$  can do job  $j$ .
4. If weighted, then  $c(i, j)$  is the *proficiency* of  $i$  at job  $j$ . (In unweighted case,  $c(i, j) = 1$ .)
5. Workers to jobs assignment for *maximizing total proficiency*.
6. Each worker assigned to at most one job and vice versa, so this is a matching.

# Applications

---

1. [Rooming Problem.] Dorm room assignment. Graph  $G$  with students as nodes. Weight  $c_{ij}$  is *compatibility* of pair  $(i, j)$ .
2. [Airline Pilot Assignment.]
  - Airlines need to form teams of captain and first officer.
  - $\alpha_i$  is effectiveness of  $i$  as captain.
  - $\beta_i$  is effectiveness of  $i$  as 1st officer.
  - Seniority Rule: captain more senior.
  - Make edge weight

$$c_{ij} = \begin{cases} \alpha_i + \beta_j & \text{if } i \text{ more senior} \\ \alpha_j + \beta_i & \text{otherwise} \end{cases}$$

3. In these applications, the graph is *not* bipartite. We will only study the bipartite case.

# More Applications

---

## 4. [Stable Marriage.]

- Men  $\{A, B, \dots, Z\}$ , women  $\{a, b, \dots, z\}$ .
- Their preference tables.

Men's Preferences

A	b	c	a
B	b	a	c
C	c	a	b

Women's Preferences

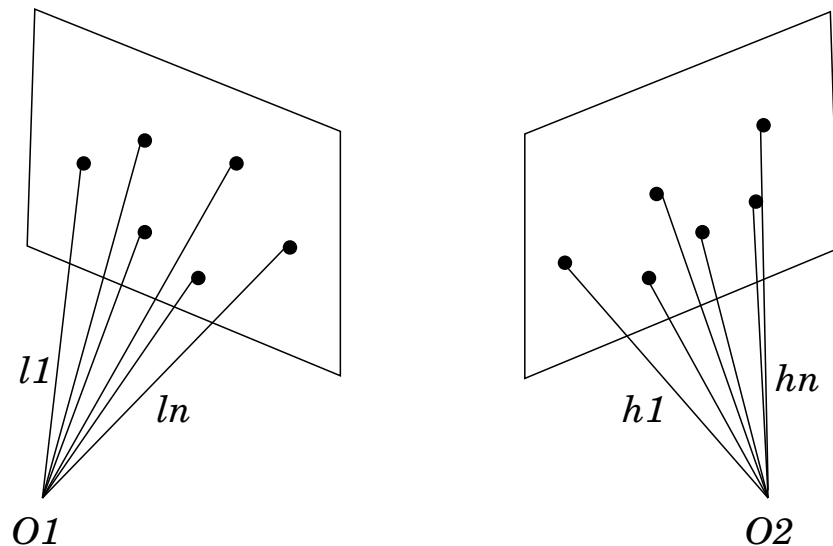
a	C	B	A
b	A	C	B
c	A	C	B

- A matching  $M$ .
- $M$  is unstable if  $\exists$  pair  $(Bob, Sally)$  who like each other more than their spouses.
- Is stable marriage always possible?
- Medical schools use this protocol.
- Gale-Shapely Theorem: A stable marriage always possible, and found in  $O(n^2)$  time.

# Stereo Vision

---

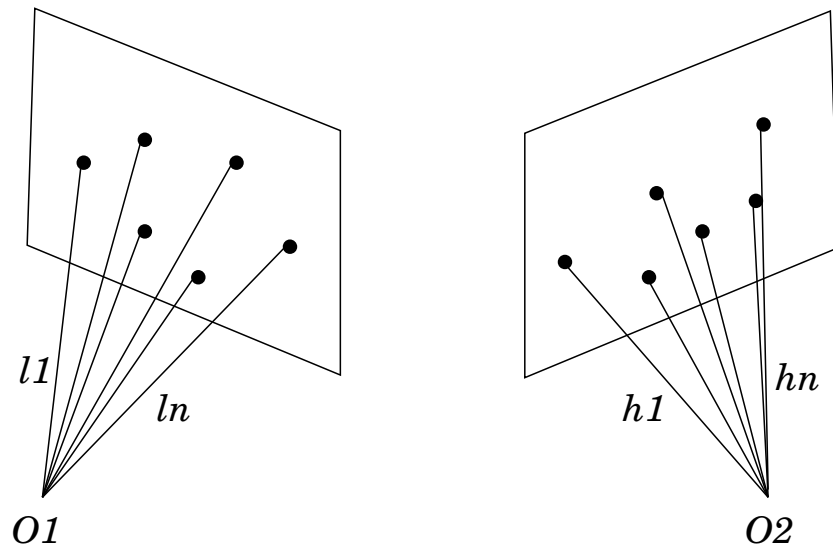
1. Stereo matching to locate objects in space.
2. Infrared sensors at two different locations.
3. Each sensor gives the angle of sight (line) on which the object lies.



4. If  $p$  objects, we get two sets of lines:  
 $\{L_1, L_2, \dots, L_p\}$  and  $\{L'_1, L'_2, \dots, L'_p\}$ .

# Stereo Vision

---



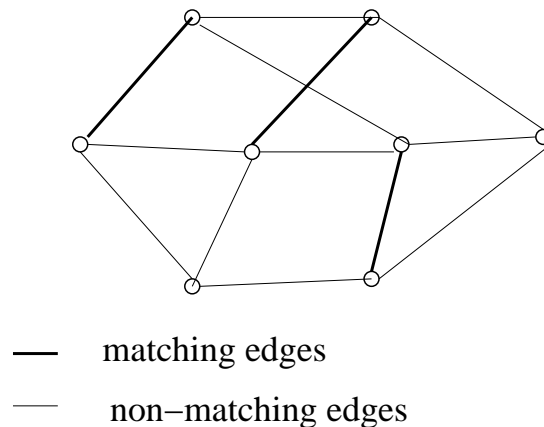
1. Two problems: (1) a line from one sensor might intersect multiple lines from the other; (2) due to noise, the lines for the same object may not intersect.
2. Solve the problem using assignment.  
Nodes are lines. Cost  $c_{ij}$  is the distance between  $L_i$  and  $L'_j$ .
3. Distance between lines of the same object should be close to zero.
4. Optimal assignment should give excellent matching of line.

# Definitions

---

1. A matching  $M \subseteq E$ , in graph  $G = (V, E)$ , is a set of edges no two sharing a vertex.

A matching M

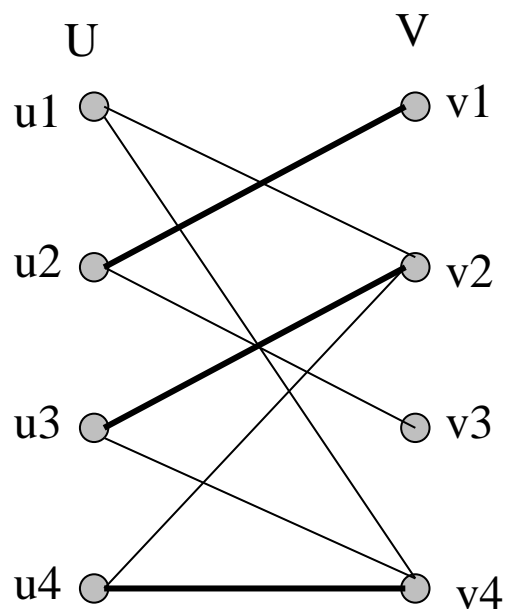


2.  $|M|$  is the *cardinality* of  $M$ .
3. In unweighted graphs, find max cardinality matching.
4. In weighted graphs, find max weight matching.
5. A matching is perfect if all vertices are matched.

# Perfect Matching

---

1. Consider a bipartite graph  $G = (U, V, E)$ .
2. When does  $G$  have a perfect matching?

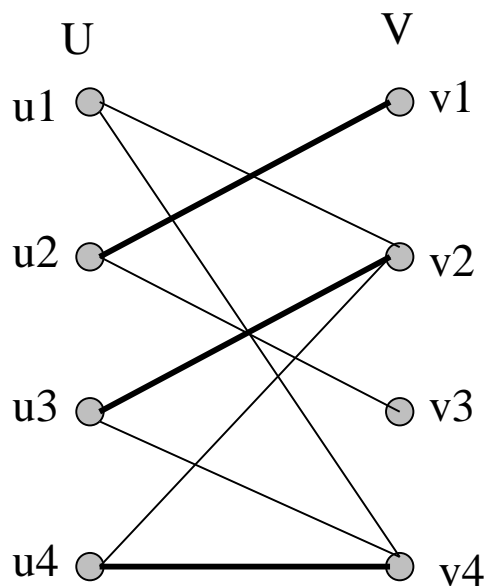


# Neighborhoods

---

1. A subset  $S \subseteq U$ .
2. Neighborhood  $N(S)$  is vertices of  $V$  adjacent to any vertex in  $S$ .
3. For example,  $N(u_1) = \{v_2, v_4\}$ .

**Hall's Theorem:**  $G$  has a perfect matching  
iff  $|N(S)| \geq |S|$ , for all  $S \subseteq U$ .

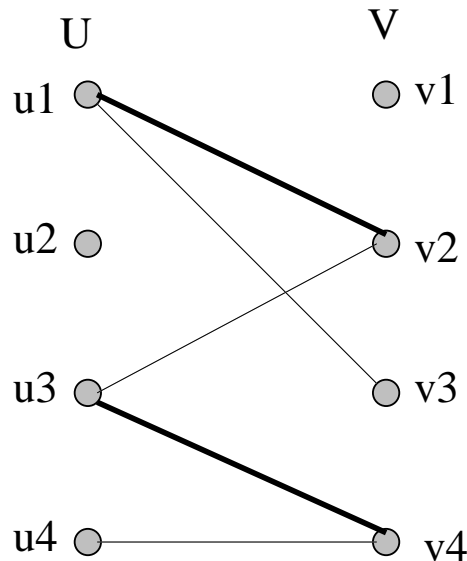




# Alternating Paths

---

1. A matching  $M$  has some *matched* and some *unmatched* (free) vertices.
2. *Alternating path* has edges alternating between  $M$  and  $E - M$ .

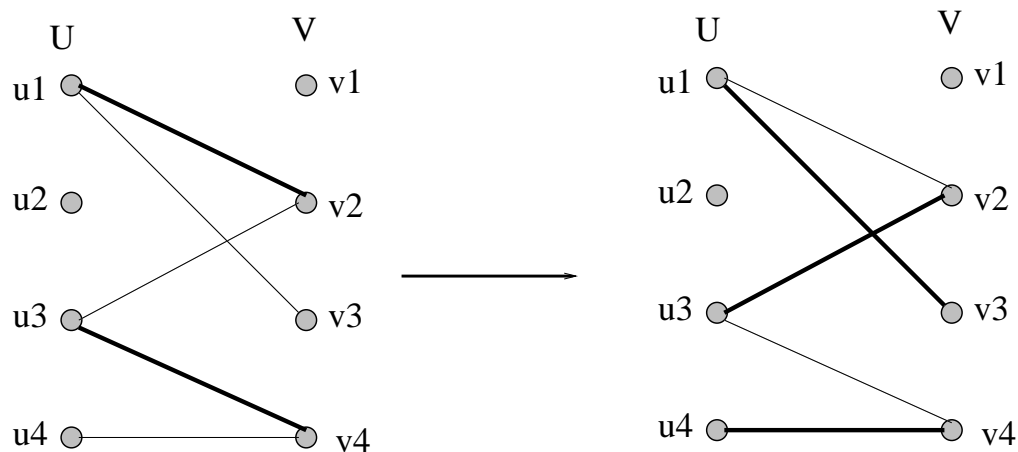


3.  $u_2, u_4$  are free, while  $u_1, u_3$  are matched.
4. Path  $u_4, v_4, u_3, v_2, u_1, v_3$  is alternating.
5. An alternating path is *augmenting* if both of its endpoints are *free* vertices.
6. Path  $u_4, v_4, u_3, v_2, u_1, v_3$  is also augmenting.

# Augmenting Matching

---

1. If a matching  $M$  has an augmenting path, then we get a larger matching  $M'$  by swapping the edges on the augmenting path.

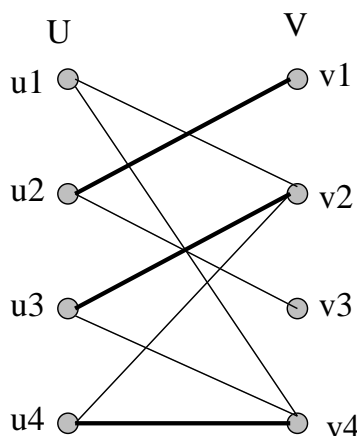


# Hall's Theorem

---

**Hall's Theorem:**  $G$  has a perfect matching iff  $|N(S)| \geq |S|$ , for all  $S \subseteq U$ .

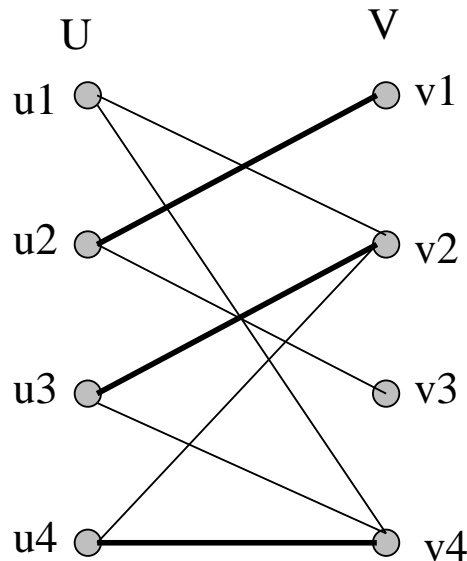
1. The direction **PM**  $\Rightarrow |N(S)| \geq |S|$  is easy.
2. Consider any set  $S \subseteq U$ .
3. Let  $mate(u)$  be the vertex matched with  $u$ .
4. Since  $mate(u_i) \neq mate(u_j)$ , it follows that  $|\cup_{u \in S} mate(u)| \geq |S|$ .
5. Since  $mate(u) \in N(u) \subseteq V$ , we must have  $|N(S)| \geq |S|$ .



# Hall's Proof

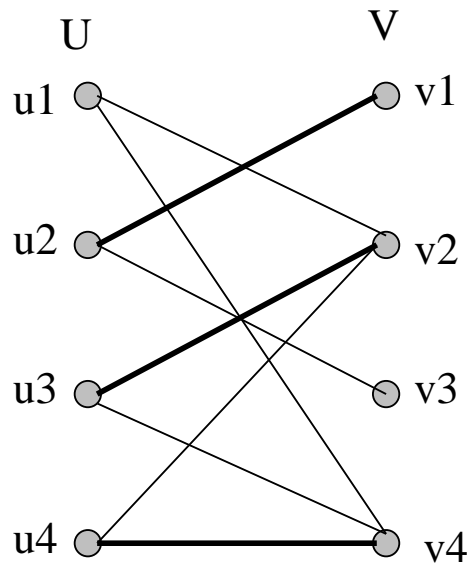
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1. Now, suppose  $|N(S)| \geq |S|$  holds, for all  $S \subseteq U$ .
2. Consider a max matching  $M$ , and let  $u$  be a free vertex in it.
3. Let  $Z$  be the set of all vertices *reachable* from  $u$  with an *alternating* path.
4. There is no free vertex in  $Z$  (except  $u$ )—otherwise, an augmenting path, which contradicts  $M$ 's max size.
5. Let  $L = Z \cap U$ , and  $R = Z \cap V$ .



# Hall's Proof

---

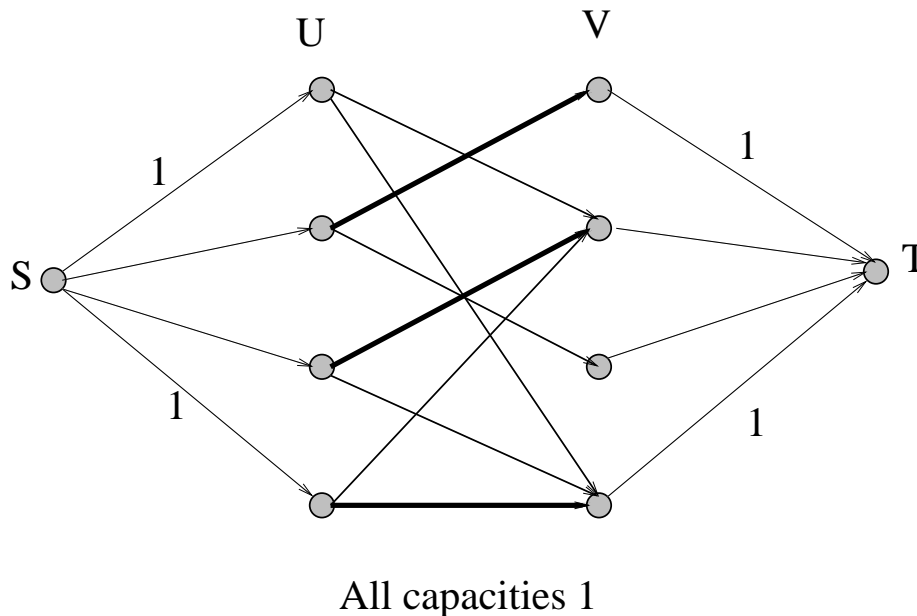


1. Observe that  $N(L) = R$ .
2. Each vertex in  $L$  (except  $u$ ) is matched with someone in  $R$ , and the mates are distinct.
3. So,  $|R| = |L| - 1$ .
4. But then  $|N(L)| < |L|$ , a contradiction!

# Unweighted Bipartite Matching

---

## 1. Unweighted matching via maxflow.

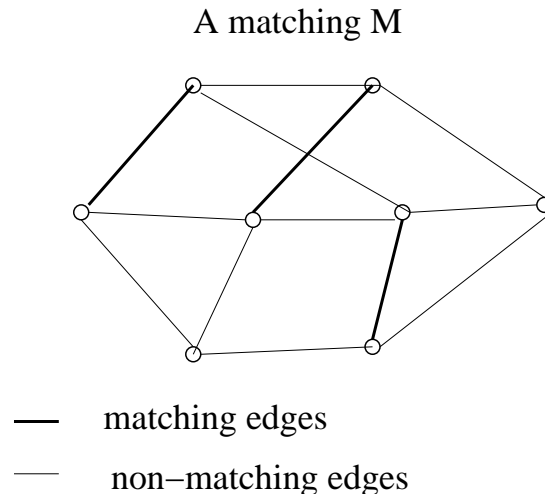


2. Maximum flow value equals  $|M|$ .
3. With integral flow, *matching*  $\Leftrightarrow$  *flows*.
4. With integer capacities, there always exists an integral flow. (Why?)
5. Think Ford-Fulkerson algorithm.
6. Max cardinality matching solved in  $O(n^3)$  time.

# Remarks

---

1. No such transformation for non-bipartite matching.



2. Actually, Hall's Theorem also invalid for general graphs. (Example: a triangle.)

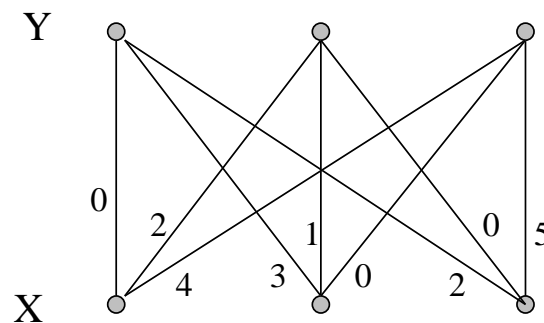
**Tutte's Theorem:**  $G$  has a perfect matching iff for all  $S \subseteq V$ ,  $oc(G - s) \leq |S|$ , where  $oc$  is number of odd-cardinality components.

3. For bipartite matching, specialized maxflow algorithm for unit networks runs in  $O(\sqrt{nm})$ . (Read Section 8.2.)

# Hungarian Method for Assignment

---

- Maxflow method does not work for weighted matching.
- $G = (X, Y, E)$ , with edge weights  $w(e)$ , which is weight or benefit of  $e$ .
- Find optimal (max weight) assignment.



- Assume complete graph—missing edges given  $w(e) = 0$ . So, want a max weight *perfect* matching in  $G$ .



# Feasible Vertex Labeling

---

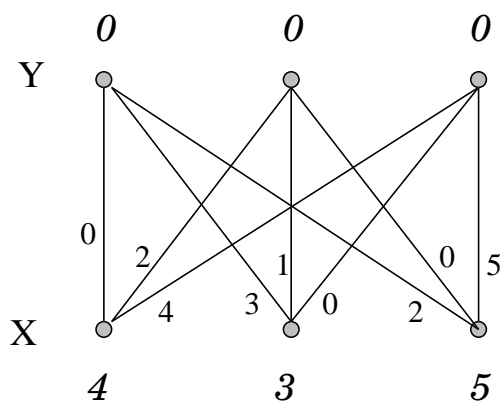
- Real-valued labels  $\ell()$  such that

$$\ell(x) + \ell(y) \geq w(x, y), \quad \forall x \in X, y \in Y.$$

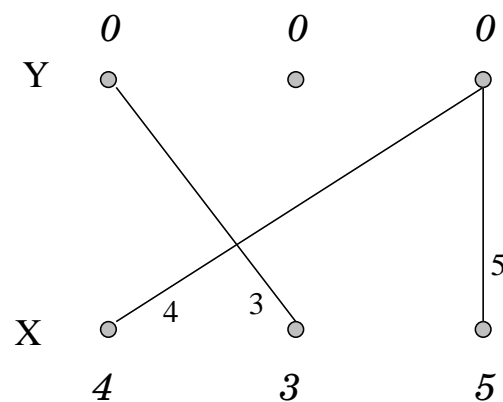
- Initial feasible labeling:

$$\ell(x) = \max_{y \in Y} \{w(x, y)\} \quad \text{for } x \in X$$

$$\ell(y) = 0 \quad \text{for } y \in Y$$



*Vertex Labeling*



*Equality Graph*

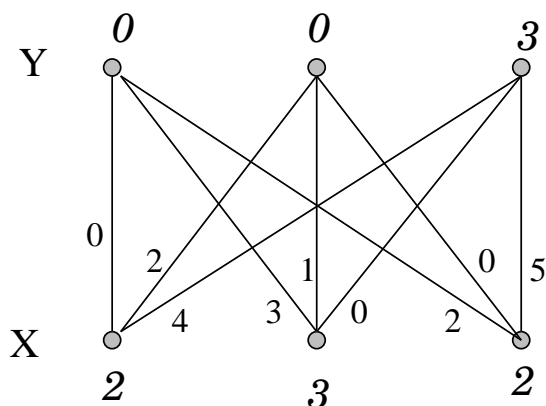
- [Equality Graph]  $G_\ell = (X, Y, E_\ell)$ , where

$$E_\ell = \{(x, y) \mid \ell(x) + \ell(y) = w(x, y)\}.$$

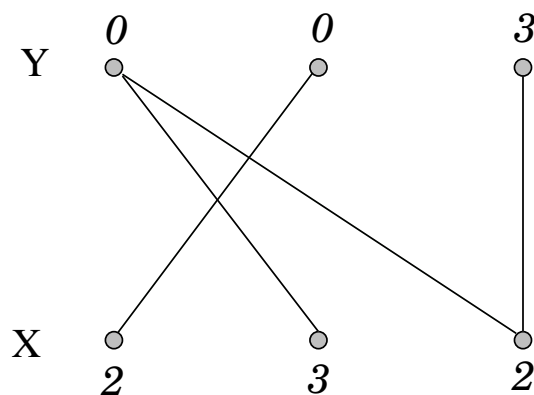
# Main Theorem

---

[Kuhn-Munkres.] *For any feasible labeling  $\ell$ , if  $G_\ell$  contains a perfect matching  $M$ , then  $M$  is an optimal assignment.*



*Vertex Labeling*



*Equality Graph*

1. In a PM, each vertex is covered exactly once, so  $w(M) = \sum_{e \in M} w(e) = \sum_{v \in V} \ell(v)$
2. Any other assignment  $M'$  in  $G$  satisfies  $w(M') = \sum_{e \in M'} w(e) \leq \sum_{v \in V} \ell(v)$
3. Thus,  $w(M') \leq w(M)$ , and  $M$  must be optimal.

# Hungarian Method

---

1. Initialize vertex labeling  $\ell$ . Determine  $G_\ell$ .

2. Pick any matching  $M$  in  $G_\ell$ .

3. If  $M$  perfect, stop. Otherwise, pick a free vertex  $u \in X$ . Set  $S = \{u\}$ , and  $T = \emptyset$ .

4. If  $N(S) = T$ , update labels:

$$\alpha_\ell = \min_{x \in S, y \notin T} \{\ell(x) + \ell(y) - w(x, y)\}$$

$$\ell'(v) = \left\{ \begin{array}{ll} \ell(v) - \alpha_\ell & \text{if } v \in S \\ \ell(v) + \alpha_\ell & \text{if } v \in T \\ \ell(v) & \text{otherwise} \end{array} \right\}$$

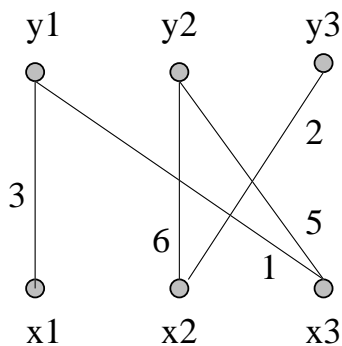
(Now  $N(S) \neq T$ .)

5. If  $N(S) \neq T$ , pick  $y \in N(S) - T$ .

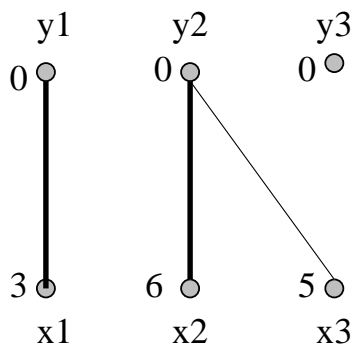
- If  $y$  free,  $u$ - $y$  is augmenting path; augment  $M$  and go to 3.
- If  $y$  matched, say, to  $z$ , then extend alternating tree:  $S = S \cup \{z\}$ ,  $T = T \cup \{y\}$ . Go to 4.

# Example of Hungarian

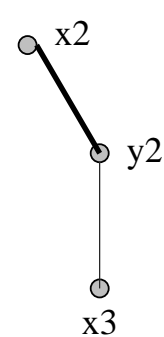
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Initial Graph



Equality Graph  
Matching M

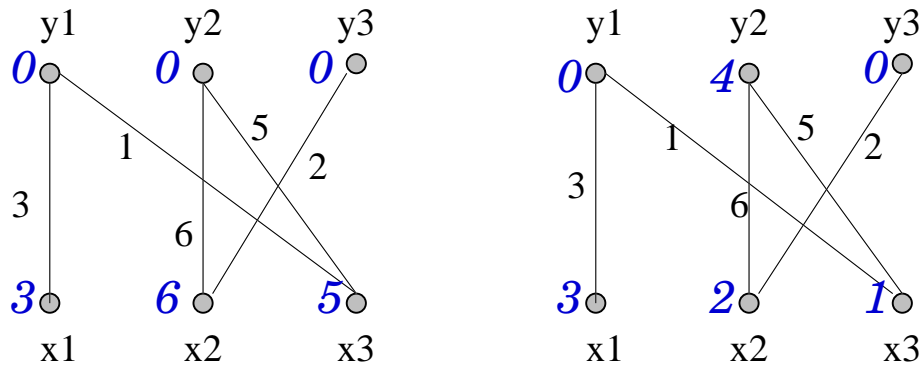


Alternating Tree  
wrt M

- A  $3 \times 3$  assignment problem.
- Initial labels and equality graph.
- Initial matching  $(x_1, y_1), (x_2, y_2)$ .
- $S = \{x_3\}$ ,  $T = \emptyset$ .
- Since  $N(S) \neq T$ , we do step 5. Choose  $y_2 \in N(S) - T$ .
- $y_2$  matched, add  $y_2x_2$  (grow tree).
- Since  $N(S) = T$ , do step 4.

# Example contd.

---



New Eq. Graph

- $S = \{x_2, x_3\}$ , and  $T = \{y_2\}$ .
- Calculate  $\alpha$ :

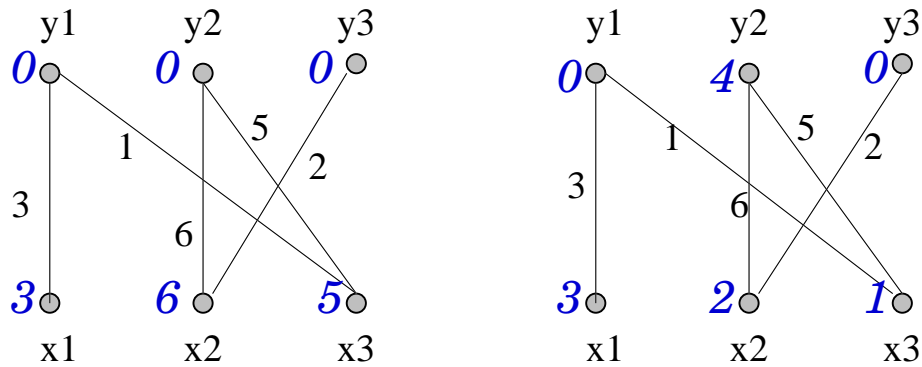
$$\alpha_\ell = \min_{x \in S, y \notin T} \begin{cases} 6 + 0 - 0 & x_2 y_1 \\ 6 + 0 - 2 & x_2 y_3 \\ 5 + 0 - 1 & x_3 y_1 \\ 5 + 0 - 0 & x_3 y_3 \end{cases}$$

$$= 4$$

- Reduce labels for  $S$ , increase for  $T$ , by 4.
- New equality graph has a perfect matching.

# Analysis

---

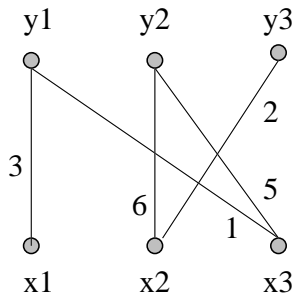


New Eq. Graph

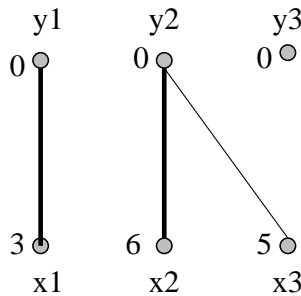
- Relabeling ensures that at least one new edge added to  $G_\ell$ .
- Relabeling ensures no edge of  $G_\ell$  removed.
- In a worst-case, all edges of  $G$  would eventually appear in  $G_\ell$ .
- Thus, a perfect matching guaranteed to be found.

# Complexity

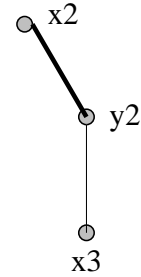
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Initial Graph



Equality Graph  
Matching M



Alternating Tree  
wrt M

- Algorithm has  $n$  phases, in each phase matching size grows by 1.
- Keep track of edge with smallest slack:  $\ell(x) + \ell(y) - w(x, y)$ , where  $x \in S, y \notin T$ .
- Initial slack calculation takes  $O(n^2)$  time.
- When a vertex moves from  $\bar{S}$  to  $S$ , we compute slacks for all  $y \notin T$ .
- In each phase, at most  $n$  vertices go from  $\bar{S}$  to  $S$ , so  $n$  slack re-calculations, each at  $O(n)$  time, for a total of  $O(n^2)$ .
- Total algorithm takes  $O(n^3)$ .

# Other Results on Matching

---

- [Bipartite Cardinality Matching:]  
 $O(\sqrt{nm})$  time. Maxflow on unit capacity networks. [Even-Tarjan]
- [Non-Bipartite Cardinality Matching:]  
First polynomial time,  $O(n^4)$ , algorithm in 1957 by Edmonds.  
Current best  $O(\sqrt{nm})$  [Micali-Vazirani].
- [Bipartite Weighted Matching:]  
 $O(nm + n^2 \log n)$  strongly poly.  
 $O(\sqrt{nm} \log(nC))$  scaling algorithm.
- [Non-Bipartite Weighted Matching:]  
 $O(n^3)$  by Edmonds+Gabow '75.  
Current best  $O(nm + n^2 \log n)$ .



# Stable Matching Problem

---

- Society of  $n$  men ( $A, B, \dots, Z$ ) and  $n$  women ( $a, b, \dots, z$ ).
- Each man (woman) ranks all women (man), in descending order of preference.

Men's Preferences				Women's Preferences			
A	c	a	b	a	C	B	A
B	c	b	a	b	B	A	C
C	a	b	c	c	B	C	A

- A matching is a 1-to-1 correspondence (monogamous, heterosexual marriage).
- A pair  $(M, w)$  is *unstable* if  $M$  and  $w$  like each other more than their assigned partners.
- A matching is called unstable if it has a unstable pair (risks elopement).
- Determine a stable matching.

# Stable Matching

---

- The matching  $\{(A, c), (B, b), (C, a)\}$  leads to an unstable pair  $(B, c)$ .

Men's Preferences				Women's Preferences			
A	c	a	b	a	C	B	A
B	c	b	a	b	B	A	C
C	a	b	c	c	B	C	A

- The matching  $\{(A, b), (B, c), (C, a)\}$  is stable.

## Applications:

- The method used by Medical Schools for selecting residents.
- Hong Kong state universities use stable matching for admissions.
- Several books just on stable marriage.

# Stable Matching Theorem

---

Theorem: Stable matching is always possible. [Gale Shapely 1955]

- We will prove this theorem by presenting an algorithm that always returns a stable matching.
- Basic principle: *Man proposes, woman disposes.*
- Each unattached man proposes to the highest-ranked woman in his list, *who has not already rejected him.*
- If the man proposing to her is better than her current mate, the woman dumps her current partner, and becomes engaged to the new proposer.
- Since no man proposes to the same woman twice, the algorithm terminates, and we prove the result is a stable matching.

# Stable Matching Algorithm

---

- $LIST$ : list of unattached men.
- $cur(m)$ : highest ranked woman in  $m$ 's list, who has not rejected him.
- Initialize  $LIST = \{1, 2, \dots, n\}$  and  $cur(i) = M(i, 1)$ .
- Choose a man, say, Bob, from  $LIST$ . Bob proposes to Alice, where  $Alice = cur(\text{Bob})$ .
- If Alice unattached, Bob and Alice are engaged.
- If Alice is engaged to, say, John, but prefers Bob, she dumps John, and Bob and Alice are engaged. Otherwise, she rejects Bob.
- The rejected man rejoins  $LIST$ , and updates his  $cur$ .
- Output the engaged pairs when  $LIST = \emptyset$ .

# Illustration of the Algorithm

---

Men's Preferences

A	c	a	b
B	c	b	a
C	a	b	c

Women's Preferences

a	C	B	A
b	B	A	C
c	B	C	A

- Final matching  $\{(A, b), (B, c), (C, a)\}$ .
- The algorithm terminates in  $O(n^2)$  steps, since each step moves one *cur* pointer, and there are at most  $n^2$  preferences.
- Remains to prove the matching is always stable.

# Correctness

---

- Suppose the resulting matching has a unstable pair (Dick, Laura).
- Dick must have proposed to Laura at some point.
- During the algorithm, Laura also rejected Dick in favor of some she prefers more.
- Since no woman ever switches to a man less desirable than her current partner, Laura's current partner must be more desirable than Dick.
- Thus, the pair (Dick, Laura) is not unstable.