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# Time Series Analysis and Forecasting

Seminar 1: Stochastic Processes and Stationarity



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## Seminar Outline

### Today's Activities:

- 1. Quick Review** — Stationarity and key processes
- 2. Multiple Choice Quiz** — Test your understanding
- 3. True/False Questions** — Conceptual checks
- 4. Calculation Exercises** — Hands-on practice
- 5. Key Formulas** — Reference sheet



## Key Concepts to Remember

### Weak Stationarity:

- $\mathbb{E}[X_t] = \mu$  (constant mean)
- $\text{Var}(X_t) = \sigma^2$  (constant variance)
- $\text{Cov}(X_t, X_{t+h}) = \gamma(h)$  (depends only on lag)

### White Noise:

- $\mathbb{E}[\varepsilon_t] = 0$
- $\text{Var}(\varepsilon_t) = \sigma^2$
- $\text{Cov}(\varepsilon_t, \varepsilon_s) = 0$  for  $t \neq s$

### Random Walk:

- $X_t = X_{t-1} + \varepsilon_t$
- $\text{Var}(X_t) = t\sigma^2$  (grows!)
- Non-stationary

### AR(1) Process:

- $X_t = \phi X_{t-1} + \varepsilon_t$
- Stationary if  $|\phi| < 1$
- $\rho(h) = \phi^h$  (ACF)



## Quiz 1: Time Series Basics

### Question

Which of the following is NOT a characteristic of time series data?

- A. Observations are ordered in time
- B. Consecutive observations are usually correlated
- C. Observations are independent and identically distributed
- D. Data has a natural temporal ordering



## Quiz 1: Answer

Answer: C

Observations are independent and identically distributed

### Explanation:

Time series observations are typically **dependent** (autocorrelated), not independent.

This temporal dependence makes time series analysis unique.

ch1\_ts\_patterns.pdf

## Quiz 2: Stationarity (Random Walk)

### Question

A random walk process  $X_t = X_{t-1} + \varepsilon_t$  is:

- A. Strictly stationary
- B. Weakly stationary
- C. Non-stationary because variance grows with time
- D. Stationary after adding a constant



## Quiz 2: Answer

Answer: C

Non-stationary because variance grows with time

### Explanation:

For random walk:

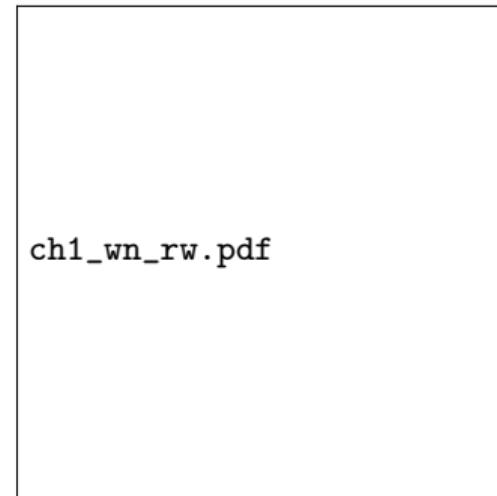
$$\text{Var}(X_t) = t\sigma^2$$

Variance depends on  $t \Rightarrow$  non-stationary.

**Solution:** Differencing gives  $\Delta X_t = \varepsilon_t$  which IS stationary.

ch1\_wn\_rw.pdf

## Visual: White Noise vs Random Walk



Left: White noise (stationary)   Right: Random walk (non-stationary, variance grows)



## Quiz 3: Unit Root Tests

### Question

You run ADF and KPSS tests. ADF fails to reject  $H_0$ , and KPSS rejects  $H_0$ . What do you conclude?

- A. The series is stationary
- B. The series has a unit root (non-stationary)
- C. Results are inconclusive
- D. You need to run more tests



### Quiz 3: Answer

Answer: B

The series has a unit root (non-stationary)

#### Explanation:

- ADF:  $H_0 = \text{unit root}$   
(fail to reject  $\Rightarrow$  evidence FOR)
- KPSS:  $H_0 = \text{stationary}$   
(reject  $\Rightarrow$  evidence AGAINST)

ADF	KPSS	Conclusion
Reject	No rej.	Stationary
No rej.	Reject	Non-stat.
Reject	Reject	Uncertain
No rej.	No rej.	Uncertain

Both tests: series is **non-stationary**.

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## Quiz 4: ACF Interpretation

### Question

If the ACF of a time series decays very slowly (remains significant for many lags), this suggests:

- A. The series is white noise
- B. The series is likely non-stationary
- C. The series has no autocorrelation
- D. The series is perfectly predictable



## Quiz 4: Answer

Answer: B

The series is likely non-stationary

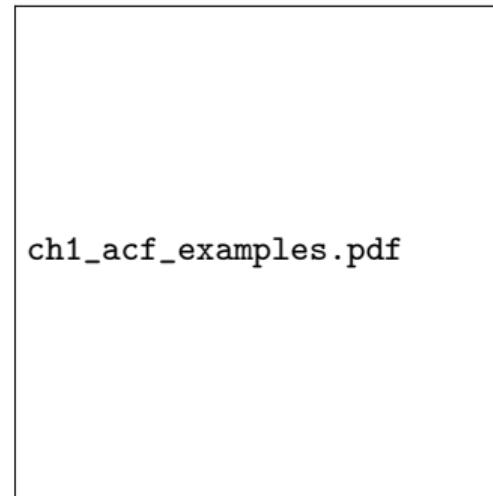
### Explanation:

- Stationary:** ACF decays rapidly ( $\rho_k = \phi^k \rightarrow 0$ )
- Non-stationary:** ACF stays close to 1

⇒ Differencing needed.

ch1\_acf\_examples.pdf

## Visual: ACF Stationary vs Non-Stationary



Left: ACF decays rapidly (stationary)

Right: ACF decays slowly (non-stationary)



## Quiz 5: White Noise Properties

### Question

Which property is NOT required for a process to be white noise?

- A.  $\mathbb{E}[\varepsilon_t] = 0$
- B.  $\text{Var}(\varepsilon_t) = \sigma^2$  (constant)
- C.  $\text{Cov}(\varepsilon_t, \varepsilon_s) = 0$  for  $t \neq s$
- D.  $\varepsilon_t \sim N(0, \sigma^2)$



## Quiz 5: Answer

Answer: D

$$\varepsilon_t \sim N(0, \sigma^2) \text{ (normality)}$$

**White noise** requires only:

- $\mathbb{E}[\varepsilon_t] = 0$  (zero mean)
- $\text{Var}(\varepsilon_t) = \sigma^2$  (constant variance)
- $\text{Cov}(\varepsilon_t, \varepsilon_s) = 0$  for  $t \neq s$

Normality is NOT required – Gaussian white noise is a special case.

ch1\_wn\_rw.pdf

## Quiz 6: Trend Types

### Question

A deterministic trend can be removed by:

- A. Differencing
- B. Regression on time
- C. Seasonal adjustment
- D. Moving average smoothing



## Quiz 6: Answer

Answer: B

Regression on time

**Deterministic trend:**

$$Y_t = \alpha + \beta t + \varepsilon_t$$

Removal: regress on  $t$ , analyze residuals.

**Stochastic trend (unit root):**

$$Y_t = Y_{t-1} + \varepsilon_t$$

Requires **differencing**.

Trend type	Method
Deterministic	Regression
Stochastic	Differencing

**Warning:** Using wrong method can introduce problems!

[qlts\\_differencing\\_and\\_types](#)



## Quiz 7: MA(1) Process

### Question

For the MA(1) process  $X_t = \varepsilon_t + \theta\varepsilon_{t-1}$ , the autocorrelation function is:

- A.  $\rho(h) = \theta^h$  for all  $h$
- B.  $\rho(1) = \frac{\theta}{1+\theta^2}$ ,  $\rho(h) = 0$  for  $h > 1$
- C.  $\rho(h) = 0$  for all  $h \geq 1$
- D.  $\rho(h) = \theta$  for all  $h$



## Quiz 7: Answer

Answer: B

$$\rho(1) = \frac{\theta}{1+\theta^2}, \rho(h) = 0 \text{ for } h > 1$$

### Explanation:

MA(1) has **finite memory**: autocorrelation cuts off after lag 1.

Key difference from AR: ACF cuts off sharply (doesn't decay gradually).

ch2\_ma1\_acf\_pacf.pdf

## Quiz 8: Differencing

### Question

If  $X_t$  follows a random walk with drift:  $X_t = \mu + X_{t-1} + \varepsilon_t$ , what is  $\Delta X_t = X_t - X_{t-1}$ ?

- A. A random walk
- B. A non-stationary process
- C. White noise plus a constant:  $\Delta X_t = \mu + \varepsilon_t$
- D. An AR(1) process



## Quiz 8: Answer

Answer: C

White noise plus a constant:  $\Delta X_t = \mu + \varepsilon_t$

### Explanation:

Differencing removes the unit root.

The result is **stationary**:

- Constant mean  $\mu$
- Constant variance  $\sigma^2$
- No autocorrelation

ch1\_stationarity.pdf

Top: prices (non-stat.)

Bottom: returns (stat.)

## Quiz 9: Strict vs Weak Stationarity

### Question

Which statement about stationarity is TRUE?

- A. Weak stationarity implies strict stationarity
- B. Strict stationarity implies weak stationarity (if moments exist)
- C. They are equivalent concepts
- D. Neither implies the other



## Quiz 9: Answer

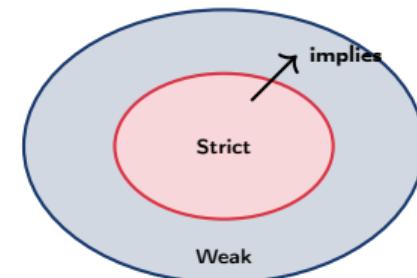
Answer: B

Strict stationarity implies weak stationarity (if moments exist)

### Explanation:

- Strict:** All joint distributions invariant
- Weak:** Only 1st and 2nd moments

Strict  $\Rightarrow$  Weak, but NOT vice versa.



**Strict  $\subset$  Weak (when moments exist)**



## True or False? — Questions

Statement	T/F?
1. A time series with constant mean is always stationary.	?
2. Random walk variance increases linearly with time.	?
3. ADF and KPSS have the same null hypothesis.	?
4. Autocorrelation at lag 0 is always equal to 1.	?
5. White noise is always normally distributed.	?
6. The ACF of AR(1) decays exponentially.	?
7. Differencing can make a non-stationary series stationary.	?
8. $ \phi  = 1$ in AR(1) gives a random walk.	?



## True or False? — Answers

Statement	T/F	Explanation
1. A time series with constant mean is always stationary.	F	Also needs constant variance, covariance
2. Random walk variance increases linearly with time.	T	$\text{Var}(X_t) = t\sigma^2$
3. ADF and KPSS have the same null hypothesis.	F	Opposite hypotheses
4. Autocorrelation at lag 0 is always equal to 1.	T	$\rho(0) = 1$
5. White noise is always normally distributed.	F	Gaussian WN = special case
6. The ACF of AR(1) decays exponentially.	T	$\rho(h) = \phi^h$
7. Differencing can make a non-stationary series stationary.	T	Removes stochastic trends
8. $ \phi  = 1$ in AR(1) gives a random walk.	T	Unit root



## Exercise 1: Autocovariance

**Problem:** For a stationary process with:  $\mathbb{E}[X_t] = 5$ ,  $\gamma(0) = 4$ ,  $\gamma(1) = 2$ ,  $\gamma(2) = 1$

Calculate:

- a) Autocorrelation function  $\rho(0), \rho(1), \rho(2)$
- b)  $\text{Cov}(X_t, X_{t-1})$
- c)  $\text{Corr}(X_5, X_7)$
- d) If  $X_t = 6$ , what is  $\mathbb{E}[X_{t+1}|X_t = 6]$  assuming AR(1)?

**Solution:**

- $\rho(0) = 1$ ,  $\rho(1) = 2/4 = 0.5$ ,  $\rho(2) = 1/4 = 0.25$
- $\text{Cov}(X_t, X_{t-1}) = \gamma(1) = 2$
- $\text{Corr}(X_5, X_7) = \rho(2) = 0.25$
- $\mathbb{E}[X_{t+1}|X_t] = 5 + 0.5(6 - 5) = 5.5$



## Exercise 2: Random Walk Properties

**Problem:**  $X_t = X_{t-1} + \varepsilon_t$  where  $\varepsilon_t \sim WN(0, 4)$  and  $X_0 = 100$ .

Calculate:

- a)  $\mathbb{E}[X_{10}]$
- b)  $\text{Var}(X_{10})$
- c)  $\text{Cov}(X_5, X_{10})$
- d) 95% confidence interval for  $X_{100}$

**Solution:**

- $\mathbb{E}[X_{10}] = X_0 = 100$
- $\text{Var}(X_{10}) = 10 \times 4 = 40$
- $\text{Cov}(X_5, X_{10}) = \min(5, 10) \times 4 = 20$
- 95% CI:  $100 \pm 1.96 \times 20 = [60.8, 139.2]$



## Exercise 3: AR(1) Process

**Problem:** Consider  $X_t = 0.8X_{t-1} + \varepsilon_t$  where  $\varepsilon_t \sim WN(0, 9)$ .

Calculate:

- a) Is this process stationary? Why?
- b) The unconditional variance  $\text{Var}(X_t)$
- c) The autocorrelations  $\rho(1), \rho(2), \rho(3)$
- d) If  $X_t = 10$ , find  $\mathbb{E}[X_{t+1}|X_t]$  and  $\mathbb{E}[X_{t+2}|X_t]$

**Solution:**

- Yes,  $|\phi| = 0.8 < 1$  (root outside unit circle)
- $\text{Var}(X_t) = \frac{\sigma^2}{1-\phi^2} = \frac{9}{1-0.64} = 25$
- $\rho(1) = 0.8, \rho(2) = 0.64, \rho(3) = 0.512$
- $\mathbb{E}[X_{t+1}|X_t = 10] = 8, \mathbb{E}[X_{t+2}|X_t = 10] = 6.4$



## Exercise 4: MA(1) Process

**Problem:** Consider  $X_t = \varepsilon_t + 0.6\varepsilon_{t-1}$  where  $\varepsilon_t \sim WN(0, 4)$ .

Calculate:

- a)  $\mathbb{E}[X_t]$
- b)  $\text{Var}(X_t)$
- c)  $\gamma(1) = \text{Cov}(X_t, X_{t-1})$
- d)  $\rho(1)$  and  $\rho(2)$

**Solution:**

- $\mathbb{E}[X_t] = 0$  (white noise has zero mean)
- $\text{Var}(X_t) = (1 + \theta^2)\sigma^2 = (1 + 0.36) \times 4 = 5.44$
- $\gamma(1) = \theta\sigma^2 = 0.6 \times 4 = 2.4$
- $\rho(1) = \frac{\theta}{1+\theta^2} = \frac{0.6}{1.36} = 0.44, \rho(2) = 0$



## Python Exercise 1: Loading and Visualization

**Task:** Load S&P 500 data and create a plot.

### Starter Code

```
import yfinance as yf
import matplotlib.pyplot as plt

# Download S&P 500 data
sp500 = yf.download('^GSPC', start='2020-01-01', end='2025-01-01')

# TODO: Plot closing prices
# TODO: Calculate and display basic statistics
# TODO: Does the series appear stationary? Why or why not?
```

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## Python Exercise 2: Stationarity Testing

**Task:** Test stationarity using ADF and KPSS tests.

### Starter Code

```
from statsmodels.tsa.stattools import adfuller, kpss

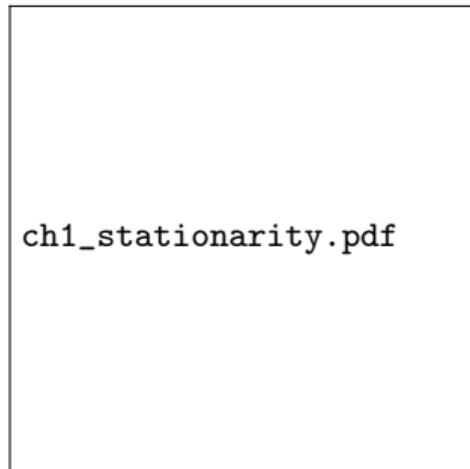
# Test S&P 500 prices
prices = sp500['Close']
returns = prices.pct_change().dropna()

# TODO: Run ADF test on prices and returns
# TODO: Run KPSS test on prices and returns
# TODO: Interpret the results
```

**Questions:** Are prices stationary? Are returns stationary?

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## Case Study: S&P 500 Index



**Top:** Prices – clear upward trend (non-stationary)    **Bottom:** Returns – stationary, fluctuate around zero

[TSA\\_ch1\\_stationarity](#)

q1\_log



## Stationarity Comparison: Prices vs Returns

### ADF Test Results

Series	ADF Statistic	p-value	Conclusion
S&P 500 Prices	-0.82	0.812	Non-stationary
S&P 500 Returns	-45.3	< 0.001	Stationary

### Key Observation

Financial prices are typically  $I(1)$  – integrated of order 1. Taking first differences (returns) achieves stationarity. That's why we model **returns**, not prices!



## Discussion Question 1

### Scenario

You are analyzing daily stock prices for a technology company. The ACF of the price series decays very slowly, remaining significant even at lag 50. The ADF test gives a p-value of 0.73.

### Discuss:

1. Is this series stationary? What evidence supports your answer?
2. What transformation would you apply before modeling?
3. After transformation, what properties would you expect the ACF to have?



## Discussion Question 2

### Scenario

A colleague claims: "I ran the ADF test on my stock price data and got a p-value of 0.65, so my data is stationary and I can fit an ARMA model directly."

### Discuss:

1. What is wrong with this interpretation?
2. What do the ADF hypotheses actually test?
3. What should the colleague do before fitting an ARMA model?



## Key Takeaways

1. **Time series are dependent** – not i.i.d. like cross-sectional data
2. **Stationarity is crucial** – constant mean, variance, and autocovariance
3. **Random walk is non-stationary** – variance grows with time ( $t\sigma^2$ )
4. **Test for stationarity** – use both ADF and KPSS together
5. **Differencing removes unit roots** – transforms  $I(1)$  to  $I(0)$
6. **ACF reveals structure** – slow decay suggests non-stationarity

### Next Seminar

ARMA/ARIMA model identification, estimation and forecasting



## Key Formulas Summary

Concept	Formula
Weak Stationarity	$\mathbb{E}[X_t] = \mu, \text{Var}(X_t) = \sigma^2, \text{Cov}(X_t, X_{t+h}) = \gamma(h)$
Autocorrelation	$\rho(h) = \gamma(h)/\gamma(0)$
White Noise	$\mathbb{E}[\varepsilon_t] = 0, \text{Var}(\varepsilon_t) = \sigma^2, \text{Cov}(\varepsilon_t, \varepsilon_s) = 0$
Random Walk	$X_t = X_{t-1} + \varepsilon_t, \text{Var}(X_t) = t\sigma^2$
AR(1)	$X_t = \phi X_{t-1} + \varepsilon_t$
AR(1) Stationarity	$ \phi  < 1$
AR(1) Variance	$\text{Var}(X_t) = \sigma^2/(1 - \phi^2)$
AR(1) ACF	$\rho(h) = \phi^h$
ADF Test	$H_0: \text{unit root (non-stationary)}$
KPSS Test	$H_0: \text{stationary}$



# Questions?

Good luck with the exercises!

