

Daniel Slovich

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EDUCATION

George Mason University <i>Bachelor of Science in Electrical Engineering</i>	Fairfax, VA August 2018 – May 2021
Northern Virginia Community College <i>Associate of Science in Electrical Engineering</i>	Annandale, VA May 2017 – August 2018

TECHNICAL SKILLS

Programming Languages Python, C/C++, Java, VHDL, Assembly, ROS/RViz/MoveIt, XML, Bash, Lua, LaTeX
Software Programs Linux, MATLAB, Simulink, PSpice, Multisim, Vivado, EAGLE, Fusion 360, Copellia Sim, Gazebo Sim
Hardware Design Competencies Circuit/PCB/ASIC, FPGA, Embedded Systems, Control Systems, Robotics, Signal Processing, 3D-Printing

EXPERIENCE

Instrument Repair and Technician <i>Alvas Music</i>	November 2015 – December 2016 San Pedro, California
• Developed and instated standards for customer records, instrument check-in and check-out, logging, and pricing • Performed repair, set-up, and modifications of customer instruments to various customer-defined specifications • Generated new repair income stream, and increased customer base	
Information Technology Operations Analyst <i>Red Bull</i>	February 2015 – June 2015 Santa Monica, California
• Imaged corporate employee devices and provided on site support in person, over the phone, and via email or ticket • Ensured proper training for users, on-boarding of new employees, handling incidents, service requests and installs • Provided deployment and support of Cisco, Xerox and Crestron A/V and teleconference hardware	
Genius, Service Specialist, Visuals Specialist, Sales Specialist <i>Apple Inc.</i>	February 2011 – November 2014 Fairfax, Virginia
• Apple Certified Mac Technician with service qualifications in Apple computers, mobile devices, OS X and iOS • Performed triage and repair of computers, devices and networks in large volume appointment-based environment • Facilitated and conducted company held classroom training of technicians and sales employees • Conducted customer training workshops on Apple products and services	

PROJECTS

Subaqueous Optoelectronic Sensor <i>Python, MATLAB, Fusion 360, EAGLE, Embedded Systems, SMT/Point-toPoint Solder, Optics</i>	August 2020 – June 2021
• Top-down design of a fiberoptic based water sensor measuring sample turbidity, temperature, and salinity • Solely researched, designed, and modeled temperature sensor harnessing semi-conductor properties • Performed device design, modeling, and simulation utilizing MATLAB and PSpice • Designed 3D printed components for each sensor using Fusion 360 • Designed and created all circuits, schematics, and PCB laydowns in EAGLE • Part of a six member team collaboration with periodic meetings and progress reporting • Final desktop device created with full sensing capabilities with extensive testing, calibration, and measurement completed, recorded, and documented.	
5-DOF Robotic Arm <i>Python, Gazebo/Coppellia Sim, Embedded Systems, Kinematics, Fusion, 3D Printing</i>	January 2021 – June 2021
• Development and creation of a physical 5 degree of freedom robotic arm • Forward and Inverse Kinematics fully modeled in Copellia sim • Utilizes Dynamixel XL330 smart servos with internal position, force, and torque sensing for a closed loop design • Final construction completed using Arduino, printed parts, and servos with functional testing performed	