Tutorial 3 - Lecture

```
A1 = \{
              \{1, 3, 5\},\
              {2, 10, 12},
              {15, 20, 25}
         };
xvec = {
            {x1},
             {x2},
             {x3}
         };
yvec = \{ \{y1, y2, y3\} \};
Print[Dimensions[A1], Dimensions[xvec], Dimensions[yvec]]
Tr[A1];
Det[A1];
Inverse[A1] // MatrixForm;
Dimensions[A1];
IdentityMatrix[3] // MatrixForm;
a A1 + b * IdentityMatrix[3] + c * A1.A1 + Inverse[A1].A1 // MatrixForm
A2 = {
           \{c, 3 - ai\},\
            {3 + a i, d}
        };
A3 = {
            \{c + ai, 3 - ai\},\
            \{3 + ai, d - ai\}
Simplify [Conjugate [Transpose [A2]], \{ a \in Reals, c \in Reals, d \in Reals \} ] - A2 // A2 /
   MatrixForm
 Simplify [Conjugate [Transpose [A3]], \{a \in Reals, c \in Reals, d \in Reals\}\}] - A3 // MatrixForm
 {3, 3}{3, 1}{1, 3}
  (1+a+b+82c 3 a + 133 c
                                                                                                                                          5 a + 166 c
          2 a + 202 c 1 + 10 a + b + 346 c
15 a + 430 c 20 a + 745 c 1 +
                                                                                                                                         12 a + 430 c
                                                                20 a + 745 c 1 + 25 a + b + 940 c
  15 a + 430 c
 \left(\begin{array}{cc} 0 & 0 \\ 0 & 0 \end{array}\right)
 \left(\begin{array}{ccc} -2 & \text{i} & \text{a} & 0 \\ 0 & 2 & \text{i} & \text{a} \end{array}\right)
```

```
A = {
  \{a, b\},\
   \{c, d\}
A.A - Tr[A] A + Det[A] IdentityMatrix[2] // MatrixForm
Simplify [A.A - Tr[A] A + Det[A] IdentityMatrix[2]] // MatrixForm
(a^2 + ad - a(a + d) ab + bd - b(a + d)
ac+cd-c(a+d) ad+d<sup>2</sup>-d(a+d)
\left(\begin{array}{cc} 0 & 0 \\ 0 & 0 \end{array}\right)
```

Tutorial 3 - Exercises

```
xvec = {
    {x1},
    {x2},
    {x3}
dotProd = (Transpose[xvec].xvec)[[1, 1]]
rotMatrixZ = {
    \{Cos[\theta], -Sin[\theta], 0\},\
    \{Sin[\theta], Cos[\theta], 0\},\
    {0, 0, 1}
  };
rotMatrixY = {
    \{Cos[\phi], 0, -Sin[\phi]\},
    {0, 1, 0},
    \{\sin[\phi], 0, \cos[\phi]\}
  };
rotMatrixX = {
   {1, 0, 0},
    \{0, \cos[\Omega], -\sin[\Omega]\},\
    \{0, \sin[\Omega], \cos[\Omega]\}
rotVec = rotMatrixX. (rotMatrixY. (rotMatrixZ.xvec));
Simplify[Transpose[rotVec].rotVec][[1, 1]]
x1^2 + x2^2 + x3^2
x1^2 + x2^2 + x3^2
```

```
n = 15;
newMatrix1 = ConstantArray[0, {n, n}];
For [i=1, i \le n, i=i+1,
  For [j = 1, j \le n, j = j+1,
     If[i == 1 || i == n || j == 1 || j == n,
      newMatrix1[[i, j]] = i + j;
   ];
 ];
MatrixForm[newMatrix1]
newMatrix2 = ConstantArray[0, {n, n}];
For [i=1, i \le n, i=i+1,
  For [j = 1, j \le n, j = j+1,
    If[i+j = n+1 \mid | i = j,
      newMatrix2[[i, j]] = i;
   ];
 ];
MatrixForm[newMatrix2]
MatrixPlot[newMatrix1, ColorFunction → "TemperatureMap"]
MatrixPlot[newMatrix2, ColorFunction → "TemperatureMap"]
MatrixPlot[newMatrix2 + newMatrix1, ColorFunction → "Monochrome"]
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                                   11
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