

# Tutorial 3 - Lecture

```

A1 = {
  {1, 3, 5},
  {2, 10, 12},
  {15, 20, 25}
};
xvec = {
  {x1},
  {x2},
  {x3}
};
yvec = {{y1, y2, y3}};

Print[Dimensions[A1], Dimensions[xvec], Dimensions[yvec]]

Tr[A1];
Det[A1];
Inverse[A1] // MatrixForm;
Dimensions[A1];
IdentityMatrix[3] // MatrixForm;

a A1 + b * IdentityMatrix[3] + c * A1.A1 + Inverse[A1].A1 // MatrixForm

A2 = {
  {c, 3 - a i},
  {3 + a i, d}
};
A3 = {
  {c + a i, 3 - a i},
  {3 + a i, d - a i}
};

Simplify[Conjugate[Transpose[A2]], {a ∈ Reals, c ∈ Reals, d ∈ Reals}] - A2 //
MatrixForm
Simplify[Conjugate[Transpose[A3]], {a ∈ Reals, c ∈ Reals, d ∈ Reals}] - A3 // MatrixForm

{3, 3}{3, 1}{1, 3}

$$\begin{pmatrix} 1+a+b+82c & 3a+133c & 5a+166c \\ 2a+202c & 1+10a+b+346c & 12a+430c \\ 15a+430c & 20a+745c & 1+25a+b+940c \end{pmatrix}$$


$$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$


$$\begin{pmatrix} -2ia & 0 \\ 0 & 2ia \end{pmatrix}$$


```

```

A = {
  {a, b},
  {c, d}
};
A.A - Tr[A] A + Det[A] IdentityMatrix[2] // MatrixForm
Simplify[A.A - Tr[A] A + Det[A] IdentityMatrix[2]] // MatrixForm

$$\begin{pmatrix} a^2 + a d - a (a + d) & a b + b d - b (a + d) \\ a c + c d - c (a + d) & a d + d^2 - d (a + d) \end{pmatrix}$$


$$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$


```

## Tutorial 3 - Exercises

```

xvec = {
  {x1},
  {x2},
  {x3}
};

dotProd = (Transpose[xvec].xvec)[[1, 1]]
rotMatrixZ = {
  {Cos[θ], -Sin[θ], 0},
  {Sin[θ], Cos[θ], 0},
  {0, 0, 1}
};
rotMatrixY = {
  {Cos[φ], 0, -Sin[φ]},
  {0, 1, 0},
  {Sin[φ], 0, Cos[φ]}
};
rotMatrixX = {
  {1, 0, 0},
  {0, Cos[Ω], -Sin[Ω]},
  {0, Sin[Ω], Cos[Ω]}
};

rotVec = rotMatrixX.(rotMatrixY.(rotMatrixZ.xvec));
Simplify[Transpose[rotVec].rotVec][[1, 1]]


$$x1^2 + x2^2 + x3^2$$


$$x1^2 + x2^2 + x3^2$$


```





