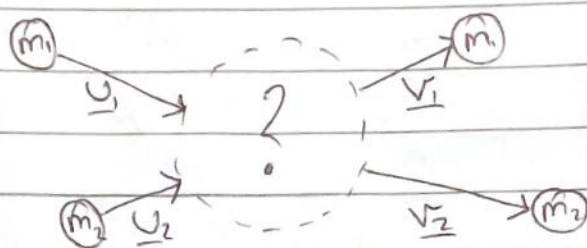


# Classical Mechanics 8

## Collisions

Describe interactions of two or more bodies via collisions.



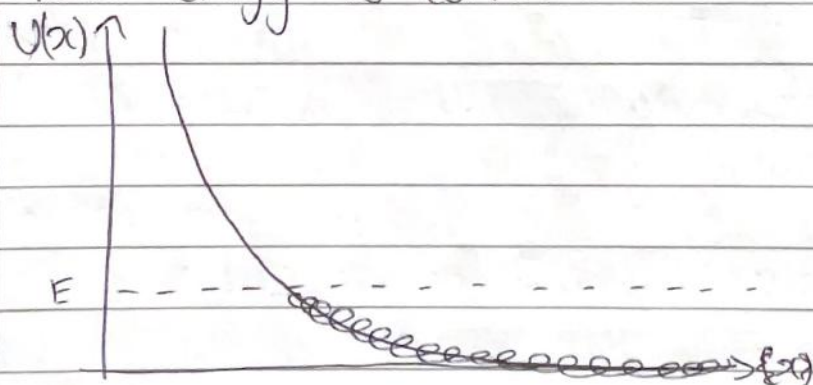
$$m_1 \dot{\underline{r}}_1 = F_{2 \text{ on } 1} = -F_{1 \text{ on } 2} = -m_2 \dot{\underline{r}}_2$$

$$m_1 \dot{\underline{v}}_1 + m_2 \dot{\underline{v}}_2 = \frac{d}{dt}(m_1 \underline{v}_1 + m_2 \underline{v}_2) = 0$$

The total momentum is conserved before, during and after the collision.

## Elastic Collisions

If the interaction is conservative ( $F(r) = -\frac{dU(r)}{dr}$ ), the total energy is conserved.



Outside the range of the interaction,  $U(r) = \text{const}$ , usually set to 0, so  $KE \text{ before} = KE \text{ after}$ .

We call this collision elastic. Most real world collisions are inelastic. Major exception: particle physics.

If the forces involved are conservative, then all collisions must be elastic.

### Inelastic Collisions

When the kinetic energy after the collision is less than the kinetic energy before the collision.

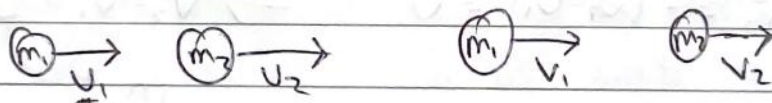
Inelastic collisions are not conservative as energy becomes heat.

### Collisions in 1D

#### Elastic

Before:

After:



- For a collision to occur:  $u_2 < u_1$
- To avoid  $m_1$  passing through  $m_2$ :  $v_2 > v_1$

### What we know: Conservation!

$$m_1 u_1 + m_2 u_2 = m_1 v_1 + m_2 v_2$$

$$\frac{1}{2} m_1 u_1^2 + \frac{1}{2} m_2 u_2^2 = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2$$

↓

$$m_1 (u_1 - v_1) = m_2 (v_1 - u_1)$$

$$m_1 (u_1^2 - v_1^2) = m_2 (v_1^2 - u_1^2)$$

$$u_1^2 - v_1^2 = v_1^2 - u_1^2$$

$$u_1 - v_1 = v_1 - u_1$$

$$u_1 + v_1 = u_2 + v_2$$

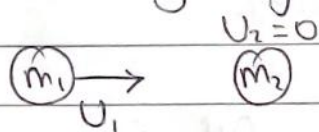


This can be equivalently,

$$\underbrace{V_2 - V_1}_{\text{relative velocity after collision}} = - \underbrace{(U_2 - U_1)}_{\text{relative velocity before collision}}$$

- Relative speed stays the same, relative velocity changes sign.
- This is generally true (even for vectors) for elastic collisions.

Example (stationary target)



$$V_2 - V_1 = -(U_2 - U_1) = U_1 \Rightarrow V_2 - V_1 = U_1$$

$$m_1 V_1 + m_2 V_2 = m_1 U_1 \Rightarrow V_1 + \frac{m_2}{m_1} V_2 = U_1$$

$$\left(1 + \frac{m_2}{m_1}\right) V_2 = 2U_1 \Rightarrow V_2 = \frac{2m_1}{m_1 + m_2} U_1$$

$$V_1 = \frac{2m_1}{m_1 + m_2} U_1 - U_1 \Rightarrow V_1 = \frac{m_1 - m_2}{m_1 + m_2} U_1$$

- $m_1 = m_2$

$V_1 = 0$ ,  $V_2 = U$ . Projectile stops, target picks up entire momentum & KE.

- $m_1 > m_2$

$V_1$  and  $V_2$  both positive, after collision particles move to the right

- $m_1 < m_2$

$V_1 < 0$  and  $V_2 > 0$ , incoming particle moves back to the left, target moves to the right.

•  $m_1 \ll m_2$

$v_1 \approx -u$ ,  $v_2 \approx 0$ . Incoming particle bounces off target, reversing momentum. final speed of target very small.

### Inelastic Collisions in 1D

Diagram showing two particles,  $m_1$  and  $m_2$ , moving to the right with initial velocities  $u_1$  and  $u_2$  respectively. After the collision, their final velocities are  $v_1$  and  $v_2$ .

Empirically, in many inelastic collisions,

$$v_2 - v_1 = -e(u_2 - u_1)$$

'e' is the 'coefficient of restitution' and is roughly constant. When  $e = 1$ , we have an elastic collision. When  $e = 0$ , the particles stick together.

If  $e > 1$ ,  $KE_{\text{after}} > KE_{\text{before}}$ , this could be due to an explosion (for example).

$$v_1 = \frac{m_1 - em_2}{m_1 + m_2} u_1$$

$$v_2 = \frac{(1+e)m_1}{m_1 + m_2} u_1$$