

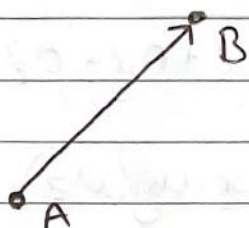
Vectors

12/10/21

A vector is a quantity that has a "direction" as well as "length".

In general, a vector is a quantity with multiple components.

You must declare a quantity to be a vector. Commonly \underline{a} or \vec{a} or bold.



A vector between two points - direction vector - often written \vec{AB}

An n -component vector has n -dimensions,

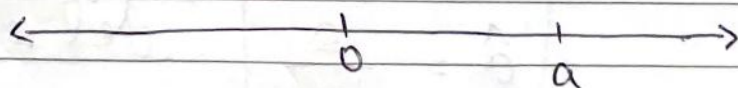
$$\underline{a} = (a_1, a_2, a_3, \dots, a_n) \quad \text{"row vector"}$$

$$\underline{a} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ \vdots \\ a_n \end{pmatrix}$$

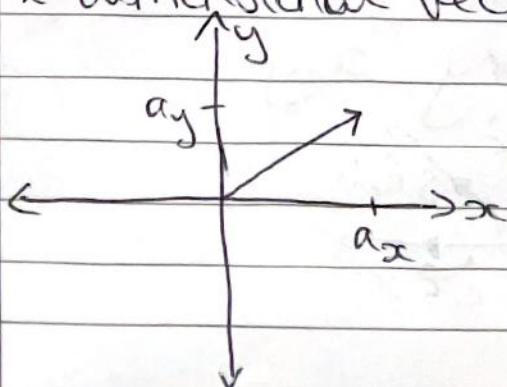
"column vector"

Visual Rep.

1-dimensional vector, $a \in \mathbb{R}$



2-dimensional vector, $a \in \mathbb{R}^2$



$$\underline{a} = (a_x, a_y)$$

length of \underline{a} often written as $|\underline{a}|$

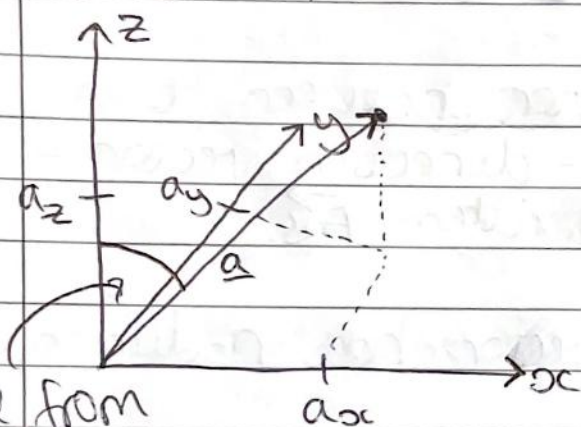
$$|\underline{a}| = \sqrt{a_x^2 + a_y^2} = \text{modulus of } \underline{a}$$

$$\theta = \arctan\left(\frac{a_y}{a_x}\right) = \arg(\underline{a})$$

$$\cos \theta = \frac{a_x}{|\underline{a}|}$$

$$\sin \theta = \frac{a_y}{|\underline{a}|}$$

3D vector, $\underline{a} \in \mathbb{R}^3$



angle from
z-axis to \underline{a}

$$|\underline{a}| = \sqrt{a_x^2 + a_y^2 + a_z^2}$$

$$\underline{a} = (a_x, a_y, a_z)$$

$$\cos \theta = \frac{a_z}{|\underline{a}|}$$

$$\cos \theta_n = \frac{a_n}{|\underline{a}|}$$

Basis Vectors

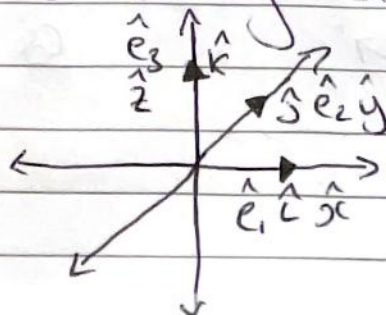
The vector of unit length in the direction of vector \underline{a} is called a normalised vector $\hat{\underline{a}}$.

$$\underline{a} = |\underline{a}| \hat{\underline{a}}$$

$$\hat{\underline{a}} = \frac{\underline{a}}{|\underline{a}|}$$

def.

The unit vectors along x, y, z

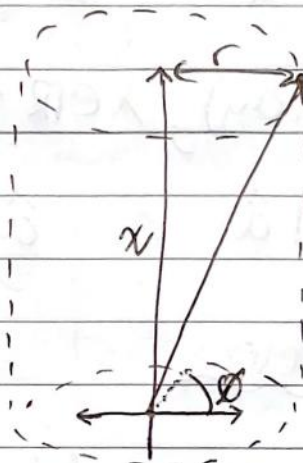


Other basis vectors exist! (don't have to be orthogonal)

Cylinder coordinates:

z : height of cylinder

r : radius of cylinder

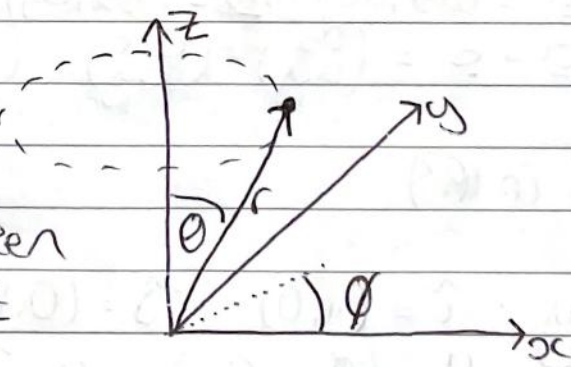


ϕ : angle between x axis and vector projection

basis vectors: $(\hat{\phi}, \hat{z}, \hat{r})$

Spherical coordinates:

θ : angle between vector and z axis



basis vectors: $(\hat{\phi}, \hat{\theta}, \hat{r})$