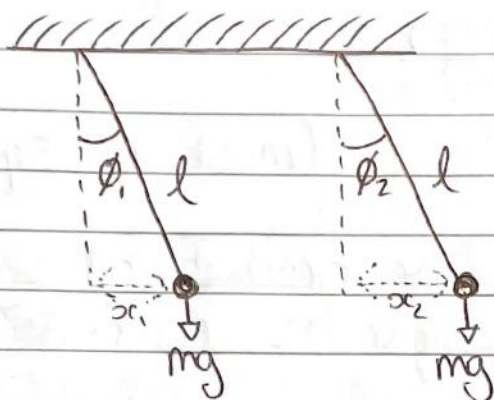


# Vectors 16

## Normal Modes

### Linearisation



We know that in the limit  $\phi_1, \phi_2$  are small

$$\star x_i \approx l\phi_i$$

$$\star F_x \approx -mg \sin \phi_i \approx -mg \phi_i$$

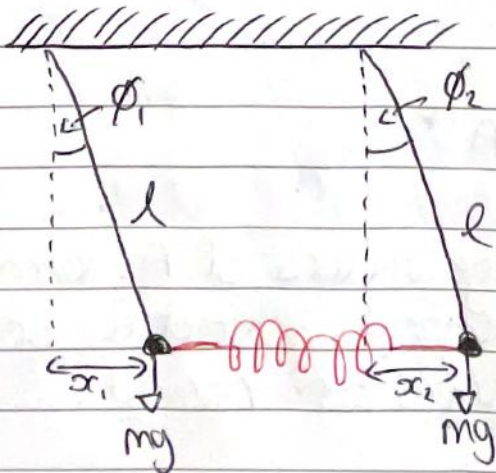
For small amplitudes, Newton's law

$$m \frac{d^2 x_i}{dt^2} = m \frac{d^2}{dt^2} (l\phi_i) = -mg \phi_i$$

$$\ddot{\phi}_i + \left(\frac{g}{l}\right) \phi_i = 0 \quad \left(\text{SHM with } \omega = \sqrt{\frac{g}{l}}\right)$$

The process of taking only the first (linear) term of Taylor series around equilibrium is called linearising.

### Coupled Differential Equations



now we'll couple the masses together with a spring.

$$m \frac{d^2 x_1}{dt^2} = m \frac{d^2 (l\phi_1)}{dt^2} = -mg\phi_1 - k(x_1 - x_2)$$

$$\frac{d^2 \phi_1}{dt^2} = -\left(\frac{g}{l}\right) \phi_1 - \left(\frac{k}{m}\right) (\phi_1 - \phi_2)$$

$$\frac{d^2 \phi_2}{dt^2} = -\left(\frac{g}{l}\right) \phi_2 - \left(\frac{k}{m}\right) (\phi_2 - \phi_1)$$

$$\omega_l^2 = \frac{g}{l} \quad \omega_k^2 = \frac{k}{m}$$

$$\frac{d^2}{dt^2} \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix} = \begin{pmatrix} -\omega_l^2 - \omega_k^2 & \omega_k^2 \\ \omega_k^2 & -\omega_l^2 - \omega_k^2 \end{pmatrix} \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix}$$

$$\frac{d^2}{dt^2} \underline{\phi} = \underline{M} \underline{\phi}$$

↑ dynamical matrix
↑ dynamical matrix

Trail solution:  $\underline{\phi} = \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix} = \underline{n} e^{\nu t}$

$\underline{n}$  is called the normal mode.

$$\frac{d^2 \underline{\phi}}{dt^2} = \underline{n} \frac{d^2}{dt^2} (e^{\nu t}) = \underline{n} \nu^2 e^{\nu t} = \underline{M} \underline{n} e^{\nu t}$$

$$\underline{M} \underline{n} = \nu^2 \underline{n} \quad (\text{eigenvalue problem})$$

$$(\underline{M} - \nu^2 \underline{I}) \underline{n} = 0$$

$$\det(\underline{M} - \nu^2 \underline{I}) = 0$$

$$\begin{vmatrix} -\omega_l^2 - \omega_k^2 - \nu^2 & \omega_k^2 \\ \omega_k^2 & -\omega_l^2 - \omega_k^2 - \nu^2 \end{vmatrix} = 0$$

$$(-\omega_l^2 - \omega_k^2 - \nu^2)^2 - (\omega_k^2)^2 = 0$$

$$-\omega_l^2 - \omega_k^2 - \nu^2 = \pm \omega_k^2$$

$$\nu^2 = \pm \omega_k^2 - \omega_l^2 - \omega_k^2$$



$$\mu^2 = \begin{cases} -\omega_0^2 \\ -\omega_0^2 - 2\omega_1^2 \end{cases}$$

$$\mu_1, \mu_2 = \begin{cases} \pm i\omega_0 \\ \pm i\sqrt{\omega_0^2 + 2\omega_1^2} \end{cases}$$

This gives us two modes with four solutions.

Normal Modes

$$\mu_1, (\mu^2 = -\omega_0^2) \quad \begin{pmatrix} -\omega_0^2 & \omega_0^2 \\ \omega_0^2 & -\omega_0^2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

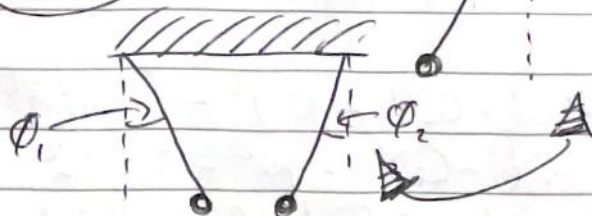
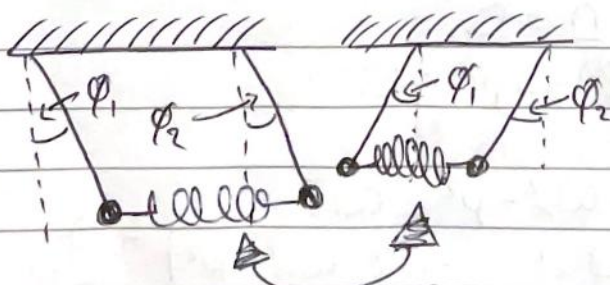
$$\text{sol. } x = y. \quad \hat{n}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\mu_2, \mu^2 = (-\omega_0^2 - 2\omega_1^2) \quad \begin{pmatrix} \omega_0^2 & \omega_0^2 \\ \omega_0^2 & \omega_0^2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

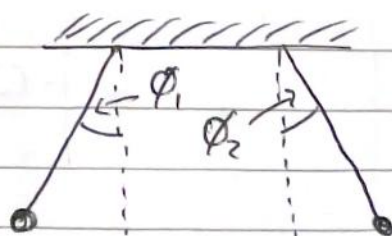
$$\text{sol. } x = -y \quad \hat{n}_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

N.B.  $\hat{n}_1 \cdot \hat{n}_2 = 0$  i.e. modes are orthogonal.

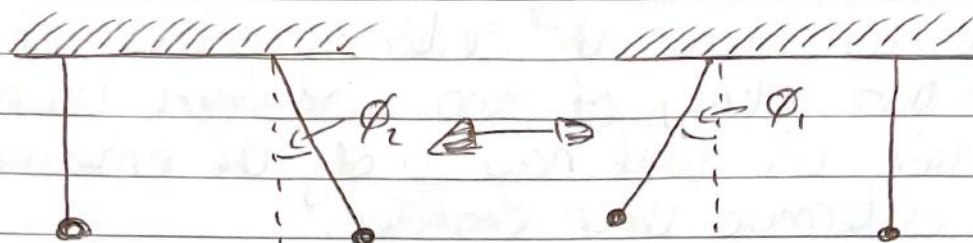
for  $\hat{n}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$   $\omega = \omega_0$



for  $\hat{n}_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$   
 $\omega = \sqrt{\omega_0^2 + 2\omega_1^2}$



Every displacement of the system can be written as a combination of these models.



Example the 'R' number infection rate

$$\begin{aligned} \text{asymptomatic } \frac{dI_1}{dt} &= \beta_1 I + \beta_2 I_2 - \eta I_1 - \gamma I_1 \\ \text{symptomatic } \frac{dI_2}{dt} &= \eta I_1 - \gamma I_2 \end{aligned}$$

recovery rate

We can write this with matrix notation

$$\frac{d\underline{I}}{dt} = \underline{A}\underline{I}$$

$$\underline{A} = \begin{pmatrix} \beta_1 - \eta - \gamma & \beta_2 \\ \eta & -\gamma \end{pmatrix} \quad \underline{I} = \begin{pmatrix} I_1 \\ I_2 \end{pmatrix}$$

We could look at this day-by-day.

$$1^{\text{st}} \text{ day: } I(1) = \underline{A}I(0) \quad 2^{\text{nd}} \text{ day: } I(2) = \underline{A}I(1) = \underline{A}^2 I(0)$$

$$\text{after } n \text{ days: } I(n) = \underline{A}^n I(0)$$

$$I(n) = \underline{A}^n I(0) = \underline{S} \underline{\Lambda}^n \underline{S}^{-1} I(0) = \underline{S} \begin{pmatrix} R_0^n & 0 \\ 0 & R_1^n \end{pmatrix} \underline{S}^{-1} I(0)$$

the largest eigenvalue becomes the dominant solution, which is the growth rate 'R'.