

## 13.1 Bubble sort

**Bubble sort** is a sorting algorithm that iterates through a list, comparing and swapping adjacent elements if the second element is less than the first element. Bubble sort uses nested loops. Given a list with  $N$  elements, the outer  $i$ -loop iterates  $N$  times. Each iteration moves the  $i^{th}$  largest element into sorted position. The inner  $j$ -loop iterates through all adjacent pairs, comparing and swapping adjacent elements as needed, except for the last  $i$  pairs that are already in the correct position,.

Because of the nested loops, bubble sort has a runtime of  $O(N^2)$ . Bubble sort is often considered impractical for real-world use because many faster sorting algorithms exist.

Figure 13.1.1: Bubble sort algorithm.

```
BubbleSort(numbers, numbersSize) {  
    for (i = 0; i < numbersSize - 1; i++) {  
        for (j = 0; j < numbersSize - i - 1; j++) {  
            if (numbers[j] > numbers[j+1]) {  
                temp = numbers[j]  
                numbers[j] = numbers[j + 1]  
                numbers[j + 1] = temp  
            }  
        }  
    }  
}
```

### PARTICIPATION ACTIVITY

#### 13.1.1: Bubble sort.

1) Bubble sort uses a single loop to sort the list.

- ☐ True  
☐ False

2) Bubble sort only swaps adjacent elements.

- ☐ True  
☐ False

3) Bubble sort's best and worst runtime complexity is  $O(N^2)$ .

- ☐ True

☐ False

How was this section?



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## 13.2 Quickselect

**Quickselect** is an algorithm that selects the  $k^{\text{th}}$  smallest element in a list. Ex: Running quickselect on the list (15, 73, 5, 88, 9) with  $k = 0$ , returns the smallest element in the list, or 5.

For a list with  $N$  elements, quickselect uses quicksort's partition function to partition the list into a low partition containing the  $X$  smallest elements and a high partition containing the  $N-X$  largest elements. The  $k^{\text{th}}$  smallest element is in the low partition if  $k$  is  $\leq$  the last index in the low partition, and in the high partition otherwise. Quickselect is recursively called on the partition that contains the  $k^{\text{th}}$  element. When a partition of size 1 is encountered, quickselect has found the  $k^{\text{th}}$  smallest element.

Quickselect partially sorts the list when selecting the  $k^{\text{th}}$  smallest element.

The best case and average runtime complexity of quickselect are both  $O(N)$ . In the worst case, quickselect may sort the entire list, resulting in a runtime of  $O(N^2)$ .

Figure 13.2.1: Quickselect algorithm.

```
// Selects kth smallest element, where k is 0-based
Quickselect(numbers, first, last, k) {
    if (first >= last)
        return numbers[first]

    lowLastIndex = Partition(numbers, first, last)

    if (k <= lowLastIndex)
        return Quickselect(numbers, first, lowLastIndex, k)
    return Quickselect(numbers, lowLastIndex + 1, last, k)
}
```

### PARTICIPATION ACTIVITY

#### 13.2.1: Quickselect.

- 1) Calling quickselect with argument  $k$  equal to 1 returns the smallest element in the list.

☐ True

☐ False

- 2) The following function produces the same result as quickselect, albeit with a different runtime complexity.

```
Quickselect(numbers, first, last, k)
{
    Quicksort(numbers, first, last)
    return numbers[k]
}
```

☐ True

☐ False

- 3) Given  $k = 4$ , if the quickselect call `Partition(numbers, 0, 10)` returns 4, then the element being selected is in the low partition.

☐ True

☐ False

How was this section?



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## 13.3 Bucket sort

**Bucket sort** is a numerical sorting algorithm that distributes numbers into buckets, sorts each bucket with an additional sorting algorithm, and then concatenates buckets together to build the sorted result. A **bucket** is a container for numerical values in a specific range. Ex: All numbers in the range 0 to 50 may be stored in a bucket representing this range. Bucket sort is designed for arrays with non-negative numbers.

Bucket sort first creates a list of buckets, each representing a range of numerical values. Collectively, the buckets represent the range from 0 to the maximum value in the array. For  $N$  buckets and a maximum value of  $M$ , each bucket represents  $\frac{M}{N}$  values. Ex: For 10 buckets and a maximum value of 50, each bucket represents a range of 5 value; the first bucket will hold values ranging from 0 to 4, the second bucket 5 to 9, and so on. Each array element is placed in the appropriate bucket. The bucket index is calculated as  $\left\lfloor \text{number} * \frac{N-1}{M} \right\rfloor$ . Then, each bucket is sorted with an additional sorting algorithm. Lastly, all buckets are concatenated together in order, and copied to the original array.

## Figure 13.3.1: Bucket sort algorithm.

```
BucketSort(numbers, numbersSize, bucketCount) {  
    if (numbersSize < 1)  
        return  
  
    buckets = Create list of bucketCount buckets  
  
    // Find the maximum value  
    maxValue = numbers[0]  
    for (i = 1; i < numbersSize; i++) {  
        if (numbers[i] > maxValue)  
            maxValue = numbers[i]  
    }  
  
    // Put each number in a bucket  
    for each (number in numbers) {  
        index = floor(number * (bucketCount - 1) / maxValue)  
        Append number to buckets[index]  
    }  
  
    // Sort each bucket  
    for each (bucket in buckets)  
        Sort(bucket)  
  
    // Combine all buckets back into numbers list  
    result = Concatenate all buckets together  
    Copy result to numbers  
}
```

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## 13.3.1: Bucket sort.



Suppose BucketSort is called to sort the list (71, 22, 99, 7, 14), using 5 buckets.

1) 71 and 99 will be placed into the same bucket



- ☐ True  
☐ False

2) No bucket will have more than 2 numbers.



- ☐ True  
☐ False

3) If 10 buckets were used instead of 5, no bucket would have more than 1 number.



- ☐ True  
☐ False

## Bucket sort terminology

The term "bucket sort" is sometimes used to refer to a category of sorting algorithms, instead of a specific sorting algorithm. When used as a categorical term, bucket sort refers to a sorting algorithm that places numbers into buckets based on some common attribute, and then combines bucket contents to produce a sorted array.

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## 13.4 List data structure

A common approach for implementing a linked list is using two data structures:

1. List data structure: A **list data structure** is a data structure containing the list's head and tail, and may also include additional information, such as the list's size.
2. List node data structure: The list node data structure maintains the data for each list element, including the element's data and pointers to the other list element.

A list data structure is not required to implement a linked list, but offers a convenient way to store the list's head and tail. When using a list data structure, functions that operate on a list can use a single parameter for the list's data structure to manage the list.

A linked list can also be implemented without using a list data structure, which minimally requires using separate list node pointer variables to keep track of the list's head.

### PARTICIPATION ACTIVITY

13.4.1: Linked lists can be stored with or without a list data structure.



### Animation content:

undefined

### Animation captions:

1. A linked list can be maintained without a list data structure, but a pointer to the head and tail of the list must be stored elsewhere, often as local variables.

2. A list data structure stores both the head and tail pointers in one object.

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13.4.2: Linked list data structure.



1) A linked list must have a list data structure.



☐ True

☐ False

2) A list data structure can have additional information besides the head and tail pointers.



☐ True

☐ False

3) A linked list has  $O(n)$  space complexity, whether a list data structure is used or not.



☐ True

☐ False

How was this section?



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## 13.5 Circular lists

A **circular linked list** is a linked list where the tail node's next pointer points to the head of the list, instead of null. A circular linked list can be used to represent repeating processes. Ex: Ocean water evaporates, forms clouds, rains down on land, and flows through rivers back into the ocean. The head of a circular linked list is often referred to as the *start* node.

A traversal through a circular linked list is similar to traversal through a standard linked list, but must terminate after reaching the head node a second time, as opposed to terminating when reaching null.

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13.5.1: Circular list structure and traversal.



## Animation captions:

1. In a circular linked list, the tail node's next pointer points to the head node.
2. A circular doubly-linked list's head node's previous pointer points to the tail node.
3. Instead of stopping when the "current" pointer is null, traversal through a circular list stops when current comes back to the head node.

### PARTICIPATION ACTIVITY

#### 13.5.2: Circular list concepts.



- 1) Only a doubly-linked list can be circular.  
☐ True  
☐ False
- 2) In a circular doubly-linked list with at least 2 nodes, where does the head node's previous pointer point to?  
☐ List head  
☐ List tail  
☐ null
- 3) In a circular linked list with at least 2 nodes, where does the tail node's next pointer point to?  
☐ List head  
☐ List tail  
☐ null
- 4) In a circular linked list with 1 node, the tail node's next pointer points to the tail.  
☐ True  
☐ False
- 5) The following code can be used to traverse a circular, doubly-linked list in



reverse order.

```
CircularListTraverseReverse(tail) {  
    current = tail  
    do {  
        visit current  
        current = current->previous  
    } while (current != tail)  
}
```

- ☐ True
- ☐ False

How was this section?



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