## 1 Labelled Transition System for repeated Head Linear Reduction

## 1.1 Notes

State is a tuple  $\langle \lambda$ -term with underlined node, context, list of arguments  $\rangle$ , where

- $\lambda$ -term (a tree; by considering  $\lambda$ -term as a tree it becomes possible to cross arguments out of tree (... without term)) with underlined node is a usual lambda term with one underlined position;
- context  $\Gamma$  is an unordered list of pair (variable : term);
- list of arguments  $\Delta$  is an ordere list of  $\lambda$ -terms. (one can also think about  $\Delta$  as unordered list of pointers to the corresponding subtree)

## 1.2 Rules

$$\langle A [e_1 @ e_2] ; \Gamma; \Delta \rangle \longrightarrow \langle A [e_1 @ e_2] ; \Gamma; e_2 \bullet \Delta \rangle$$

$$\langle A [\underline{\lambda x}.e] ; \Gamma; B \bullet \Delta \rangle \longrightarrow \langle A_{\cancel{K}} [\underline{\lambda x}.e] ; x : B, \Gamma; \Delta \rangle$$

$$\langle A [\underline{\lambda x}.e] ; \Gamma; \epsilon \rangle \longrightarrow \langle A [\lambda x.e] ; \Gamma; \epsilon \rangle$$

$$\langle A [\underline{x}] ; x : B, \Gamma; \Delta \rangle \longrightarrow \langle A [\underline{B}] ; x : B, \Gamma; \Delta \rangle$$

$$[LAM-NON-ELIM]$$

$$\langle A [\underline{x}] ; x : B, \Gamma; \Delta \rangle \longrightarrow \langle A [\underline{B}] ; x : B, \Gamma; \Delta \rangle$$

$$[BVAR]$$