



# Position: Do pretrained transformers learn in-context by Gradient Descent?

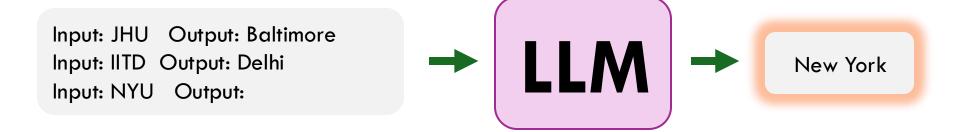
Lingfeng Shen\*, Aayush Mishra\*, Daniel Khashabi

I have a dream that one day ...

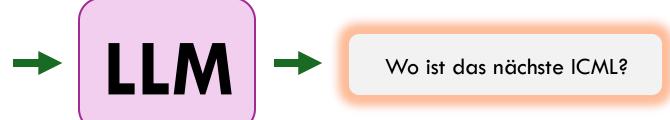


this nation will rise up ...

## In-Context Learning (ICL)



Good evening  $\rightarrow$  Guten Abend Vienna is great  $\rightarrow$  Wien ist großartig Where is the next ICML?  $\rightarrow$ 



### Langua

### Transformers Learn Nonlinear Features In Context: Nonconvex Mean-field Dynamics on the Attention Landscape

Damai Dai<sup>†</sup>\*, Y

Juno Kim<sup>12</sup> Taiji Suzuki<sup>12</sup>

### ING? INVESTIGATIONS WITH LINEAR MODELS

Ekin Akyürek<sup>1,2,a</sup> Dale Schuurmans<sup>1</sup> Jacob Andreas\*<sup>2</sup> Tengyu Ma\*<sup>1,3,b</sup> Denny Zhou\*<sup>1</sup>

#### **Transformers Learn In-Context by Gradient Descent**

Johannes von Oswald <sup>12</sup> Eyvind Niklasson <sup>2</sup> Ettore Randazzo <sup>2</sup> João Sacramento <sup>1</sup> Alexander Mordvintsev <sup>2</sup> Andrey Zhmoginov <sup>2</sup> Max Vladymyrov <sup>2</sup>

<sup>1.</sup> Dai, Damai, et al. "Why can gpt learn in-context? language models implicitly perform gradient descent as meta-optimizers." arXiv preprint arXiv:2212.10559 (2022).

<sup>2.</sup> Akyürek, Ekin, et al. "What learning algorithm is in-context learning? investigations with linear models." arXiv preprint arXiv:2211.15661 (2022).

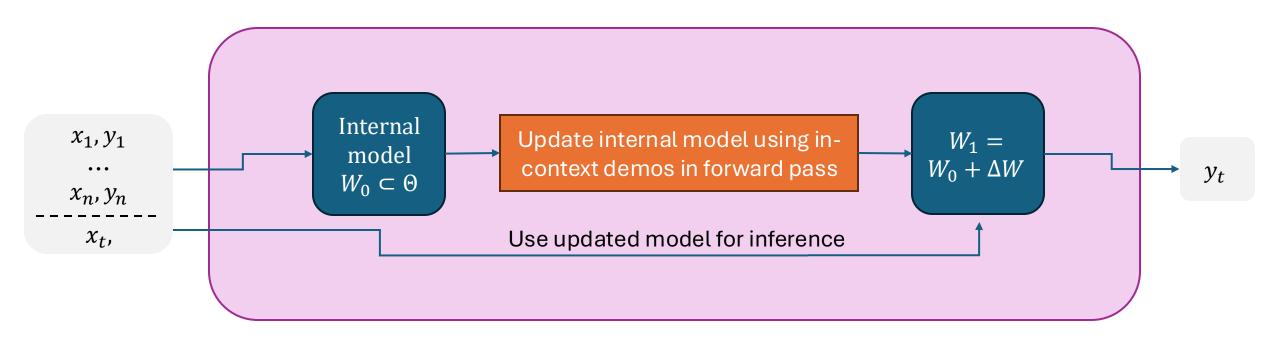
<sup>3.</sup> Von Oswald, Johannes, et al. "Transformers learn in-context by gradient descent." International Conference on Machine Learning. PMLR, 2023.

Kim, Juno, and Taiji Suzuki. "Transformers learn nonlinear features in context: Nonconvex mean-field dynamics on the attention landscape." arXiv preprint arXiv:2402.01258 (2024).

## The argument

LLM (weights Θ)

## The argument



## But here's the thing ...

These theories make oversimplified and sometimes unrealistic assumptions.

The functional nature of ICL (and its equivalence to GD) remains unclear.

## **Evolution of this theory**

1. In-context Learning can be interpreted as implicit finetuning. [Dai+, 2022]

Show that transformer attention has a dual form of gradient descent:

$$\mathcal{F}(x) = (W_0 + \Delta W)x = W_0x + LinearAttn(E, X', x)$$

2. Hand crafted transformer weights that simulate gradient descent. [Akyurek+, 2022]

These weights can **imitate** GD in the forward pass of the transformer.



Compare actual trained weights with their new construction.

Claim: Gradient-based optimization and attention-based in-context learning are equivalent.





<sup>1.</sup> Dai, Damai, et al. "Why can gpt learn in-context? language models implicitly perform gradient descent as meta-optimizers." arXiv preprint arXiv:2212.10559 (2022).

<sup>2.</sup> Akyürek, Ekin, et al. "What learning algorithm is in-context learning? investigations with linear models." arXiv preprint arXiv:2211.15661 (2022).

Von Oswald, Johannes, et al. "Transformers learn in-context by gradient descent." International Conference on Machine Learning. PMLR, 2023.

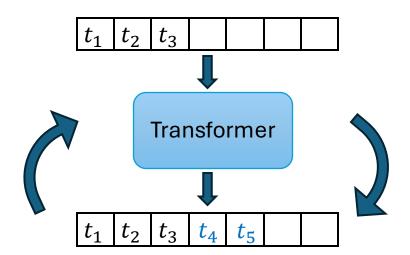
## The "ICL Objective" problem

#### ICL

Given an unsupervised corpus of tokens  $\{t_1, t_2, \dots t_n\}$ , causal language modeling (CLM) objective is used to train the model (with a context window of size k):

$$arg \max_{\Theta} \sum_{i} \log P(t_i | t_{i-k}, \dots, t_{i-1}; \Theta)$$

- Models trained on unstructured sequences
- Emergent phenomenon



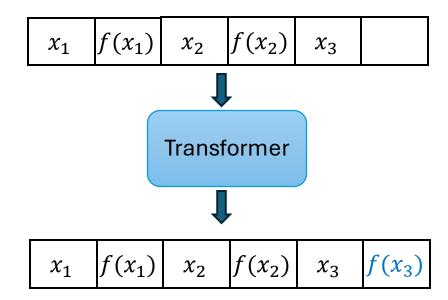
Transformers, pretrained with CLM objective, yield emergent ICL.



Given an input domain  $x \sim X$ , and a function class  $f \sim F$ , ICL objective is used to train the model by giving it structured paired inputs:

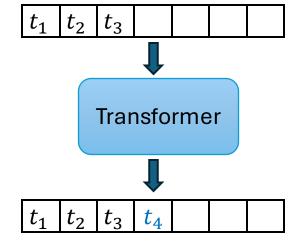
$$arg\ max_{\Theta} \sum \log P(f(x_{n+1})|\ x_1, f(x_1), \dots, x_n \circ f(x_n) \circ x_{n+1}; \Theta)$$

- Models trained on structured sequences
- Non-Emergent phenomenon

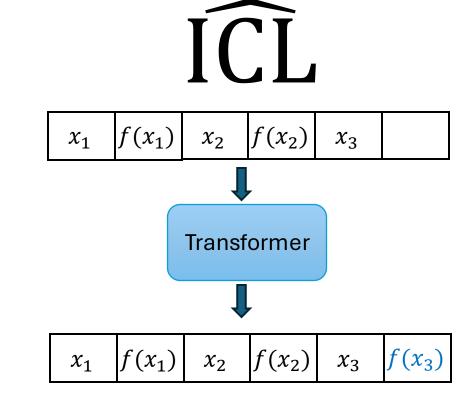


Transformers trained with ICL objective, yield non-emergent meta learning.

## ICL







Non-emergent

What they show

What they imply

### $ICL \approx GD$ equivalence

**For any** Transformer weights resulting from self-supervised pretraining and **for any** well-defined task, ICL is algorithmically equivalent to GD.

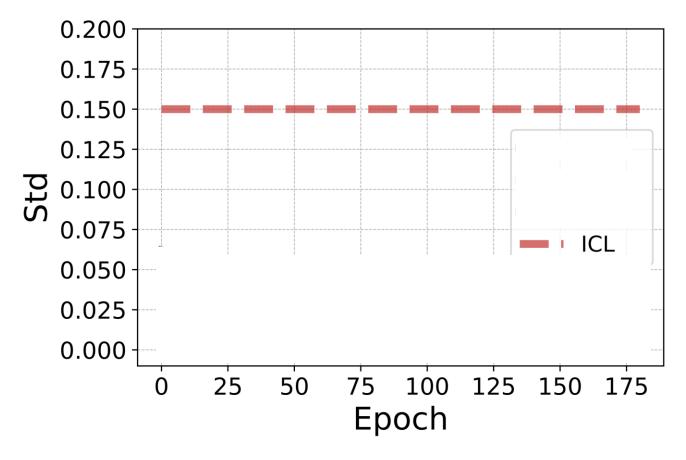
### $\widehat{ICL} \approx GD$ equivalence

For a **given** well-defined task, **there exist**Transformer weights such that ICL is algorithmically equivalent to GD.

Transformers have the expressive capacity to simulate GD.

This does not imply that LLMs actually do simulate it.

## Evidence against ICL ≈ GD: Order sensitivity



- ICL is known to be highly ordersensitive [Lu+].
- GD is order-insensitive. contradicts [Oswald+]
- Variants of GD are still not as sensitive as ICL.

undermines [Akyurek+]

ICL is likely **not** equivalent to GD based on order sensitivity.

Akyürek, Ekin, et al. "What learning algorithm is in-context learning? investigations with linear models." arXiv preprint arXiv:2211.15661 (2022).

Von Oswald, Johannes, et al. "Transformers leam in-context by gradient descent." International Conference on Machine Learning. PMLR, 2023.

Lu, Yao, et al. "Fantastically ordered prompts and where to find them: Overcoming few-shot prompt order sensitivity." arXiv preprint arXiv:2104.08786 (2021).

## Evidence against ICL ≈ GD: Weight Sparsity

- Hand constructed weights and inputs in [2] are highly sparse.
- Constructions of [3] are similarly sparse.

3.

$$H^{(0)} = \begin{bmatrix} \cdots & 0 & y_i & 0 & \cdots \\ x_i & 0 & x_n & \cdots \end{bmatrix} \quad W_e = \begin{pmatrix} I^{(d+1)\times(d+1)} & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$W_V = \begin{pmatrix} 0 & \cdots & & & \\ W_0 & -I_y \end{pmatrix}$$

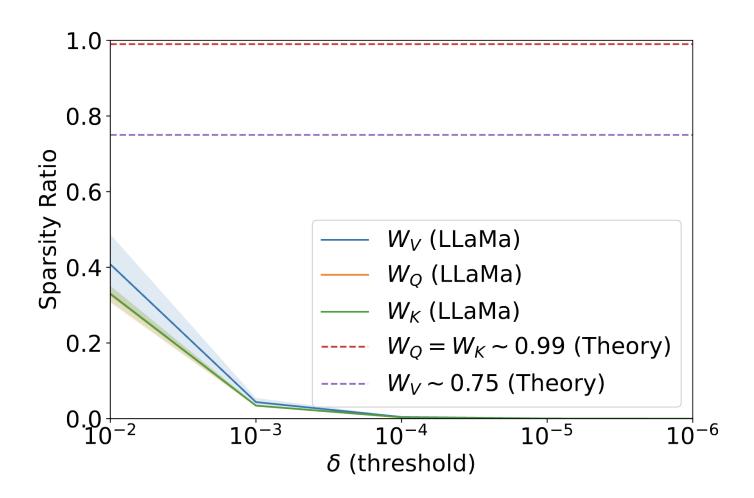
$$W_K = W_Q = \begin{pmatrix} I_x & 0 \\ 0 & 0 \end{pmatrix}$$

$$W_K = W_Q = \begin{pmatrix} I_x & 0 \\ 0 & 0 \end{pmatrix}$$

$$P = \frac{\eta}{N}I$$

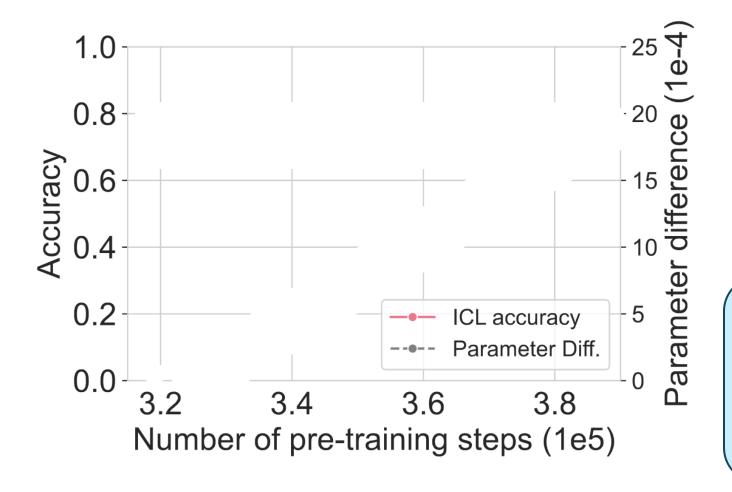
<sup>2.</sup> Akyürek, Ekin, et al. "What leaming algorithm is in-context learning? investigations with linear models." arXiv preprint arXiv:2211.15661 (2022).

## Evidence against ICL ≈ GD: Weight Sparsity



Real LLMs are rather dense.

## Evidence against ICL $\approx$ GD: Weight Evolution



ICL ability remains stable even when weights keep evolving.

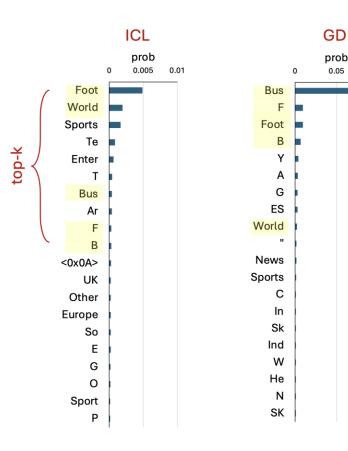
To claim ICL  $\approx$  GD, showing it for a single sparse choice of parameters is **not** enough.

## Evidence against ICL ≈ GD: Performance

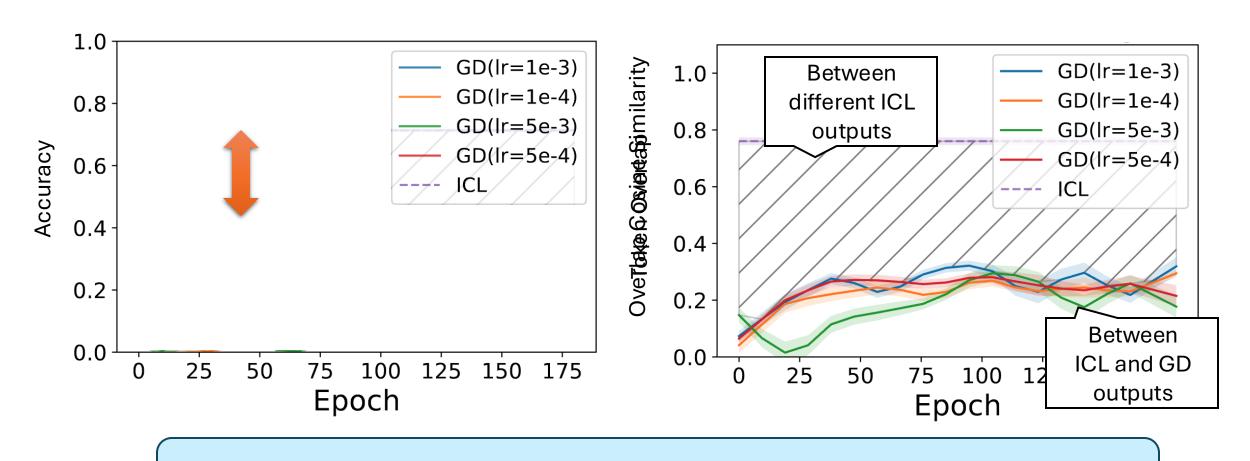
We use three coarse-to-fine metrics to compare ICL and GD:

- **1. Accuracy**: compare top predicted tokens against the ground truth (instead of top predicted label).
- **2. Token Overlap:** compare overlap in top-K tokens of two distributions.

**3. Overlap Cosine Similarity**: compare the individual agreement between top-K tokens.



## Evidence against ICL ≈ GD: Outputs



ICL performs differently and does not align with GD.

## Summary

- Recent works studying ICL do not align with emergent ICL in LLMs.
   In-Context Learning → Learning to Learn, Meta Learning, etc.
   Transformers learn in-context by gradient descent → Transformers can perform gradient descent in their forward pass when trained appropriately.
- 2. Expressivity of the Transformer architecture to simulate GD does not imply that LLMs actually do it.
  - We present arguments and evidence against the [current] ICL  $\approx$  GD equivalence theory.

3. Maintain parallels to real world settings when developing. It is OK to study ICL in a simpler setting like Linear Regression, but need to find a corresponding pretraining distribution to elicit ICL.

## Thank you!



Paper



Contact