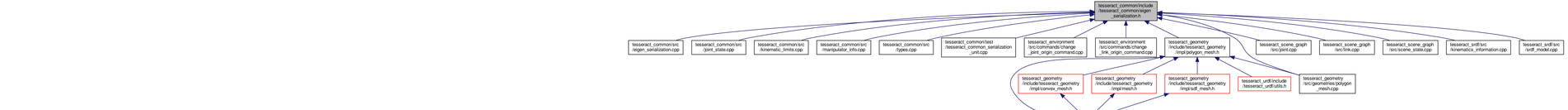
tesseract_common/include/tesseract_common/eigen_serialization.h
tesseract_common/src/eigen_serialization.cpp
tesseract_common/src/joint_state.cpp
tesseract_common/src/kinematic_limits.cpp
tesseract_common/src/manipulator_info.cpp
tesseract_common/src/types.cpp
tesseract_common/test/tesseract_common_serialization_unit.cpp
tesseract_environment/src/commands/change_joint_origin_command.cpp
tesseract_environment/src/commands/change_link_origin_command.cpp
tesseract_geometry/include/tesseract_geometry/impl/polygon_mesh.h
tesseract_scene_graph/src/joint.cpp
tesseract_scene_graph/src/link.cpp
tesseract_scene_graph/src/scene_state.cpp
tesseract_srdf/src/kinematics_information.cpp
tesseract_srdf/src/srdf_model.cpp
tesseract_geometry/include/tesseract_geometry/impl/convex_mesh.h
tesseract_geometry/include/tesseract_geometry/impl/mesh.h
tesseract_geometry/include/tesseract_geometry/impl/sdf_mesh.h
tesseract_urdf/include/tesseract_urdf/utils.h
tesseract_geometry/src/geometries/polygon_mesh.cpp
tesseract_geometry/include/tesseract_geometry/geometries.h
tesseract_collision/core/include/tesseract_collision/core/types.h
tesseract_collision/core/include/tesseract_collision/test_suite/benchmarks/large_dataset_benchmarks.hpp
tesseract_collision/core/include/tesseract_collision/test_suite/benchmarks/primitives_benchmarks.hpp
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tesseract_geometry/examples/create_geometries_example.cpp
tesseract_geometry/include/tesseract_geometry/utils.h
tesseract_geometry/test/tesseract_geometry_serialization_unit.cpp
tesseract_geometry/test/tesseract_geometry_unit.cpp
tesseract_scene_graph/test/tesseract_scene_graph_joint_unit.cpp
tesseract_scene_graph/test/tesseract_scene_graph_link_unit.cpp
tesseract_scene_graph/test/tesseract_scene_graph_serialization_unit.cpp
tesseract_scene_graph/test/tesseract_scene_graph_unit.cpp
tesseract_urdf/test/geometry.cpp
tesseract_urdf/test/tesseract_urdf_geometry_unit.cpp