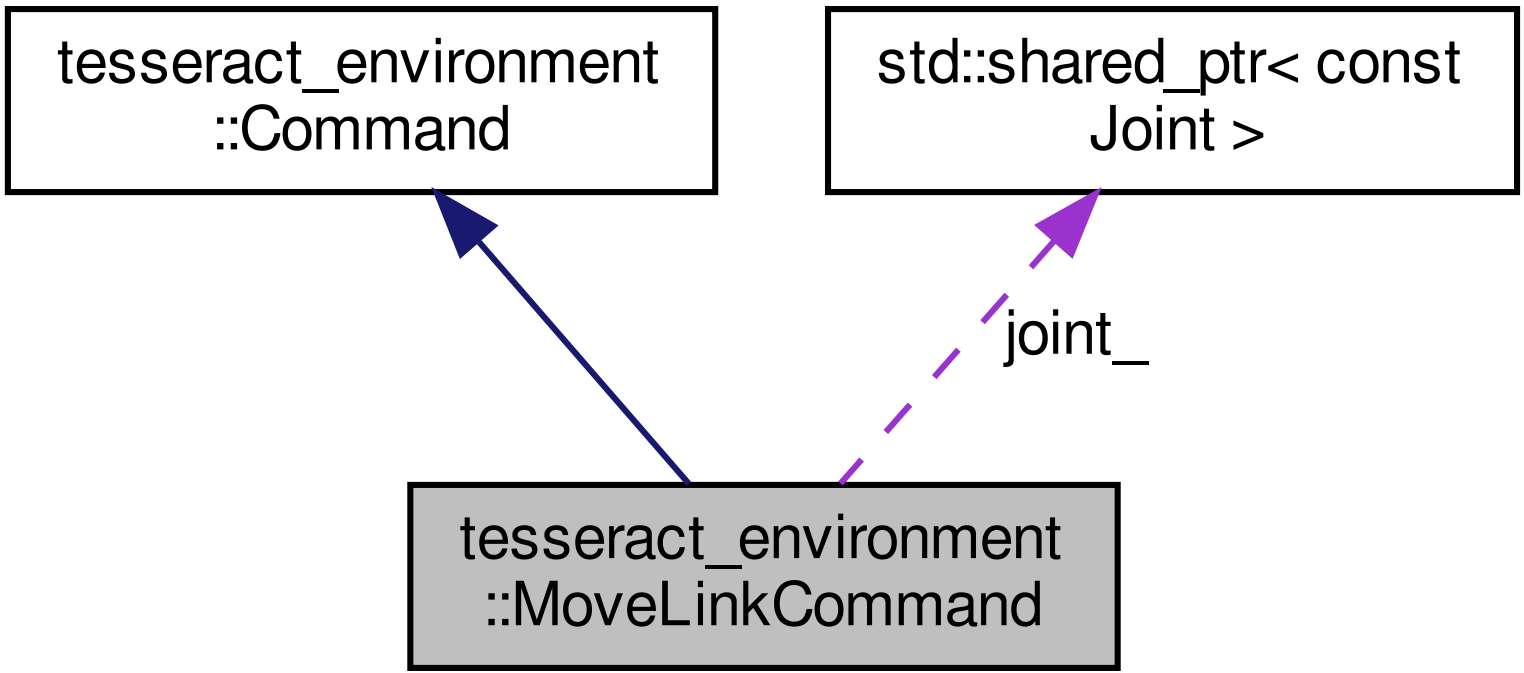
tesseract_environment
::Command
std::shared_ptr< const
Joint >
joint_
tesseract_environment
::MoveLinkCommand