RealView Compilation Tools

Version 4.0

Compiler Reference Guide



RealView Compilation Tools Compiler Reference Guide

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Preface

This preface introduces the *RealView Compilation Tools Compiler Reference Guide*. It contains the following sections:

- About this book on page viii
- Feedback on page xii.

About this book

This book provides reference information for *RealView Compilation Tools* (RVCT), and describes the command-line options to the ARM compiler. The book also gives reference material on the ARM implementation of C and C++ in the compiler. For general information on using and controlling the ARM compiler, see the *RVCT Compiler User Guide*.

Intended audience

This book is written for all developers who are producing applications using RVCT. It assumes that you are an experienced software developer. See the *RealView Compilation Tools Essentials Guide* for an overview of the ARM development tools provided with RVCT.

Using this book

This book is organized into the following chapters and appendixes:

Chapter 1 Introduction

Read this chapter for an overview of the ARM compiler, the conformance standards and the C and C++ Libraries.

Chapter 2 Compiler Command-line Options

Read this chapter for a list of all command-line options accepted by the ARM compiler.

Chapter 3 Language Extensions

Read this chapter for a description of the language extensions provided by the ARM compiler, and for information on standards conformance and implementation details.

Chapter 4 Compiler-specific Features

Read this chapter for a detailed list of ARM specific keywords, operators, pragmas, intrinsic functions, macros and semihosting *Supervisor Calls* (SVCs).

Chapter 5 C and C++ Implementation Details

Read this chapter for a description of the language implementation details for the ARM compiler.

Appendix A Via File Syntax

Read this appendix for a description of the syntax for via files. You can use via files to specify command-line arguments to many ARM tools.

Appendix B Standard C Implementation Definition

Read this appendix for information on the ARM C implementation that relates directly to the ISO C requirements.

Appendix C Standard C++ Implementation Definition

Read this appendix for information on the ARM C++ implementation.

Appendix D C and C++ Compiler Implementation Limits

Read this appendix for implementation limits of C and C++ in the ARM compiler.

Appendix E Using NEON Support

Read this appendix for information on the NEON™ intrinsics supported in this release of RVCT.

This book assumes that the ARM software is installed in the default location. For example, on Windows this might be *volume*:\Program Files\ARM. This is assumed to be the location of *install_directory* when referring to path names, for example *install_directory*\Documentation\.... You might have to change this if you have installed your ARM software in a different location.

Typographical conventions

The following typographical conventions are used in this book:

monospace Denotes text that can be entered at the keyboard, such as commands, file

and program names, and source code.

monospace Denotes a permitted abbreviation for a command or option. The

underlined text can be entered instead of the full command or option

name.

monospace italic

Denotes arguments to commands and functions where the argument is to be replaced by a specific value.

monospace bold

Denotes language keywords when used outside example code.

italic Highlights important notes, introduces special terminology, denotes

internal cross-references, and citations.

bold Highlights interface elements, such as menu names. Also used for

emphasis in descriptive lists, where appropriate, and for ARM processor

signal names.

Further reading

This section lists publications from both ARM and third parties that provide additional information on developing code for the ARM family of processors.

ARM periodically provides updates and corrections to its documentation. See http://infocenter.arm.com/help/index.jsp for current errata sheets and addenda, and the ARM *Frequently Asked Questions* (FAQs).

ARM publications

This book contains reference information that is specific to development tools supplied with RVCT. Other publications included in the suite are:

- *RVCT Essentials Guide* (ARM DUI 0202)
- RVCT Compiler User Guide (ARM DUI 0205)
- RVCT Libraries and Floating Point Support Guide (ARM DUI 0349)
- RVCT Linker User Guide (ARM DUI 0206)
- RVCT Linker Reference Guide (ARM DUI 0381)
- *RVCT Utilities Guide* (ARM DUI 0382)
- RVCT Assembler Guide (ARM DUI 0204)
- *RVCT Developer Guide* (ARM DUI 0203).

For full information about the base standard, software interfaces, and standards supported by ARM, see <code>install_directory\Documentation\Specifications\....</code>

In addition, see the following documentation for specific information relating to ARM products:

- ARM Architecture Reference Manual, ARMv7-A and ARMv7-R edition (ARM DDI 0406)
- ARM7-M Architecture Reference Manual (ARM DDI 0403)
- *ARM6-M Architecture Reference Manual* (ARM DDI 0419)
- ARM datasheet or technical reference manual for your hardware device.

Other publications

The following publications provide information about the ETSI basic operations. They are all available from the telecommunications bureau of the *International Telecommunications Union* (ITU) at http://www.itu.int.

- ETSI Recommendation G.191: Software tools for speech and audio coding standardization
- ITU-T Software Tool Library 2005 User's manual, included as part of ETSI Recommendation G.191
- ETSI Recommendation G723.1: Dual rate speech coder for multimedia communications transmitting at 5.3 and 6.3 kbit/s
- ETSI Recommendation G.729: Coding of speech at 8 kbit/s using conjugate-structure algebraic-code-excited linear prediction (CS-ACELP).

Publications providing information about TI compiler intrinsics are available from Texas Instruments at http://www.ti.com.

Feedback

ARM welcomes feedback on both RealView Compilation Tools and the documentation.

Feedback on RealView Compilation Tools

If you have any problems with RVCT, contact your supplier. To help them provide a rapid and useful response, give:

- your name and company
- the serial number of the product
- details of the release you are using
- details of the platform you are running on, such as the hardware platform, operating system type and version
- a small standalone sample of code that reproduces the problem
- a clear explanation of what you expected to happen, and what actually happened
- the commands you used, including any command-line options
- sample output illustrating the problem
- the version string of the tools, including the version number and build numbers.

Feedback on this book

If you notice any errors or omissions in this book, send email to errata@arm.com giving:

- the document title
- the document number
- the page number(s) to which your comments apply
- a concise explanation of the problem.

General suggestions for additions and improvements are also welcome.

Chapter 1 Introduction

This chapter introduces the ARM compiler provided with *RealView Compilation Tools* (RVCT). It describes the standards of conformance and gives an overview of the runtime libraries provided with RVCT. It contains the following sections:

- *About the ARM compiler* on page 1-2
- *Source language modes* on page 1-3
- Language extensions and language compliance on page 1-5
- The C and C++ libraries on page 1-8.

1.1 About the ARM compiler

The ARM compiler, armcc, enables you to compile your C and C++ code.

The compiler:

- Is an optimizing compiler. Command-line options enable you to control the level of optimization.
- Compiles:
 - ISO Standard C:1990 source
 - ISO Standard C:1999 source
 - ISO Standard C++:2003 source

into:

- 32-bit ARM code
- 16/32-bit Thumb-2 code
- 16-bit Thumb code.
- Complies with the *Base Standard Application Binary Interface for the ARM Architecture* (BSABI). In particular, the compiler:
 - Generates output objects in ELF format.
 - Generates DWARF Debugging Standard Version 3 (DWARF 3) debug information. RVCT also contains support for DWARF 2 debug tables.

See ABI for the ARM Architecture compliance on page 1-4 in the Libraries and Floating Point Support Guide for more information.

• Can generate an assembly language listing of the output code, and can interleave an assembly language listing with source code.

If you are upgrading to RVCT from a previous release or are new to RVCT, ensure that you read *RealView Compilation Tools Essentials Guide* for the latest information.

1.2 Source language modes

The ARM compiler has three distinct source language modes that you can use to compile different varieties of C and C++ source code. These are:

- ISO C90
- ISO C99
- ISO C++.

1.2.1 ISO C90

The ARM compiler compiles C as defined by the 1990 C standard and addenda:

- ISO/IEC 9899:1990. The 1990 International Standard for C.
- ISO/IEC 9899 AM1. The 1995 Normative Addendum 1, adding international character support through wchar.h and wtype.h.

The ARM compiler also supports several extensions to ISO C90. See *Language* extensions and language compliance on page 1-5 for more information.

Throughout this document, the term:

C90 Means ISO C90, together with the ARM extensions.

Use the compiler option --c90 to compile C90 code. This is the default.

Strict C90 Means C as defined by the 1990 C standard and addenda.

See also

- --*c90* on page 2-22
- *Language extensions and language compliance* on page 1-5
- Appendix B Standard C Implementation Definition.

1.2.2 ISO C99

The ARM compiler compiles C as defined by the 1999 C standard and addenda:

• ISO/IEC 9899:1999. The 1999 International Standard for C.

The ARM compiler also supports several extensions to ISO C99. See *Language extensions and language compliance* on page 1-5 for more information.

Throughout this document, the term:

C99 Means ISO C99, together with the ARM and GNU extensions.

Use the compiler option --c99 to compile C99 code.

Strict C99 Means C as defined by the 1999 C standard and addenda.

Standard C Means C90 or C99 as appropriate.

C Means any of C90, strict C90, C99, and Standard C.

See also

- --*c*99 on page 2-22
- Language extensions and language compliance on page 1-5
- Appendix B Standard C Implementation Definition.

1.2.3 ISO C++

The ARM compiler compiles C++ as defined by the 2003 standard, excepting wide streams and export templates:

• ISO/IEC 14822:2003. The 2003 International Standard for C++.

The ARM compiler also supports several extensions to ISO C++. See *Language extensions and language compliance* on page 1-5 for more information.

Throughout this document, the term:

strict C++ Means ISO C++, excepting wide streams and export templates.

Standard C++ Means strict C++.

C++ Means ISO C++, excepting wide streams and export templates,

either with or without the ARM extensions.

Use the compiler option --cpp to compile C++ code.

- --cpp on page 2-30
- Language extensions and language compliance on page 1-5
- Appendix C Standard C++ Implementation Definition.

1.3 Language extensions and language compliance

The compiler supports numerous extensions to its various source languages. It also provides several command-line options for controlling compliance with the available source languages.

1.3.1 Language extensions

The language extensions supported by the compiler are categorized as follows:

C99 features

The compiler makes some language features of C99 available:

- as extensions to strict C90, for example, //-style comments
- as extensions to both Standard C++ and strict C90, for example, **restrict** pointers.

For more information see:

- C99 language features available in C90 on page 3-5
- C99 language features available in C++ and C90 on page 3-7.

Standard C extensions

The compiler supports numerous extensions to strict C99, for example, function prototypes that override old-style non-prototype definitions. See *Standard C language extensions* on page 3-10 for more information.

These extensions to Standard C are also available in C90.

Standard C++ extensions

The compiler supports numerous extensions to strict C++, for example, qualified names in the declaration of class members. See *Standard C++ language extensions* on page 3-15 for more information.

These extensions are not available in either Standard C or C90.

Standard C and Standard C++ extensions

The compiler supports some extensions specific to strict C++ and strict C90, for example, anonymous classes, structures, and unions. See *Standard C and standard C++ language extensions* on page 3-19 for more information.

GNU extensions

The compiler supports some extensions offered by the GNU compiler, for example, GNU-style extended lvalues and GNU builtin functions. For more information see:

- Language compliance
- GNU language extensions on page 3-25
- Chapter 4 Compiler-specific Features.

ARM-specific extensions

The compiler supports a range of extensions specific to the ARM compiler, for example, instruction intrinsics and other builtin functions. See Chapter 4 Compiler-specific Features for more information.

1.3.2 Language compliance

The compiler has several modes where compliance to a source language is either enforced or relaxed:

Strict mode In strict mode the compiler enforces compliance with the language standard relevant to the source language. For example, the use of //-style comments results in an error when compiling strict C90.

To compile in strict mode, use the command-line option --strict.

GNU mode In GNU mode all the GNU compiler extensions to the relevant source language are available. For example, in GNU mode:

- case ranges in **switch** statements are available when the source language is any of C90, C99 or nonstrict C++
- C99-style designated initializers are available when the source language is either C90 or nonstrict C++.

To compile in GNU mode, use the compiler option -- anu.

r	1 1 1 1
Note	
Some GNU extensions are also availa mode.	able when you are in a nonstrict

Example

The following examples illustrate combining source language modes with language compliance modes:

Compiling a .cpp file with the command-line option --strict compiles Standard C++

- Compiling a C source file with the command-line option --gnu compiles GNU mode C90
- Compiling a .c file with the command-line options --strict and --gnu is an error.

- -- *gnu* on page 2-67
- --strict, --no_strict on page 2-119
- *GNU language extensions* on page 3-25
- File naming conventions on page 2-12 in the Compiler User Guide.

1.4 The C and C++ libraries

RVCT provides the following runtime C and C++ libraries:

The ARM C libraries

The ARM C libraries provide standard C functions, and helper functions used by the C and C++ libraries. The C libraries also provide target-dependent functions that are used to implement the standard C library functions such as printf in a semihosted environment. The C libraries are structured so that you can redefine target-dependent functions in your own code to remove semihosting dependencies.

The ARM libraries comply with:

- the C Library ABI for the ARM Architecture (CLIBABI)
- the C++ ABI for the ARM Architecture (CPPABI).

See ABI for the ARM Architecture compliance on page 1-4 in the Libraries and Floating Point Support Guide for more information.

Rogue Wave Standard C++ Library version 2.02.03

The Rogue Wave Standard C++ Library, as supplied by Rogue Wave Software, Inc., provides standard C++ functions and objects such as cout. It includes data structures and algorithms known as the *Standard Template Library* (STL). The C++ libraries use the C libraries to provide target-specific support. The Rogue Wave Standard C++ Library is provided with C++ exceptions enabled.

For more information on the Rogue Wave libraries, see the Rogue Wave HTML documentation and the Rogue Wave web site at: http://www.roguewave.com

Support libraries

The ARM C libraries provide additional components to enable support for C++ and to compile code for different architectures and processors.

The C and C++ libraries are provided as binaries only. There is a variant of the 1990 ISO Standard C library for each combination of major build options, such as the byte order of the target system, whether interworking is selected, and whether floating-point support is selected.

See Chapter 2 *The C and C++ Libraries* in the *Libraries and Floating Point Support Guide* for more information.

Chapter 2 **Compiler Command-line Options**

This chapter lists the command-line options accepted by the ARM compiler, armcc. It includes the following section:

• *Command-line options* on page 2-2.

2.1 Command-line options

This section lists the command-line options supported by the compiler in alphabetical order.

2.1.1 -Aopt

This option specifies command-line options to pass to the assembler when it is invoked by the compiler to assemble either .s input files or embedded assembly language functions.

Syntax

-Aopt

Where:

opt

is a command-line option to pass to the assembler.

—— Note ——

Some compiler command-line options are passed to the assembler automatically whenever it is invoked by the compiler. For example, if the option --cpu is specified on the compiler command line, then this option is passed to the assembler whenever it is invoked to assemble .s files or embedded assembler.

To see the compiler command-line options passed by the compiler to the assembler, use the compiler command-line option -A--show_cmdline.

Example

armcc -A--predefine="NEWVERSION SETL {TRUE}" main.c

Restrictions

If an unsupported option is passed through using -A, an error is generated.

- --*cpu=name* on page 2-30
- *-Lopt* on page 2-79
- --show_cmdline on page 2-116.

2.1.2 --allow_null_this, --no_allow_this

These options allow and disallow null this pointers in C++.

Usage

Allowing null **this** pointers gives well-defined behavior when a nonvirtual member function is called on a null object pointer.

Disallowing null **this** pointers enables the compiler to perform optimizations, and conforms with the C++ standard.

Default

The default is --no_allow_null_this.

See also

• --gnu_defaults on page 2-68.

2.1.3 --alternative_tokens, --no_alternative_tokens

This option enables or disables the recognition of alternative tokens in C and C++.

Usage

In C and C++, use this option to control recognition of the digraphs. In C++, use this option to control recognition of operator keywords, for example, **and** and **bitand**.

Default

The default is --alternative_tokens.

2.1.4 --anachronisms, --no_anachronisms

This option enables or disables anachronisms in C++.

Mode

This option is effective only if the source language is C++.

Default

The default is --no_anachronisms.

Example

```
typedef enum { red, white, blue } tricolor;
inline tricolor operator++(tricolor c, int)
{
    int i = static_cast<int>(c) + 1;
    return static_cast<tricolor>(i);
}
void foo(void)
{
    tricolor c = red;
    C++; // okay
    ++c; // anachronism
}
```

Compiling this code with the option --anachronisms generates a warning message.

Compiling this code without the option --anachronisms generates an error message.

See also

- --*cpp* on page 2-30
- --strict, --no_strict on page 2-119
- --strict_warnings on page 2-120
- Anachronisms on page 5-14.

2.1.5 --apcs=qualifer...qualifier

This option controls interworking and position independence when generating code.

By specifying qualifiers to the --apcs command-line option, you can define the variant of the *Procedure Call Standard for the ARM architecture* (AAPCS) used by the compiler.

Syntax

```
--apcs=qualifer...qualifier
```

Where *qualifier*...*qualifier* denotes a list of qualifiers. There must be:

- at least one qualifier present
- no spaces separating individual qualifiers in the list.

Each instance of	gualifier must	be on	e of:
------------------	----------------	-------	-------

		, .		
/inter	work.	/noir	nterwork	

Generates code with or without ARM/Thumb [™] interworking
support. The default is /nointerwork, except for ARMv6 and later
where the default is /interwork.

/ropi, /noropi Enables or disables the generation of *Read-Only*

Position-Independent (ROPI) code. The default is /noropi.

/[no]pic is an alias for /[no]ropi.

/rwpi, /norwpi Enables or disables the generation of *Read/Write*

Position-Independent (RWPI) code. The default is /norwpi.

/[no]pid is an alias for /[no]rwpi.

/fpic, /nofpic Enables or disables the generation of read-only

position-independent code where relative address references are

independent of the location where your program is loaded.

_____ Note _____

You can alternatively specify multiple qualifiers. For example,

--apcs=/nointerwork/noropi/norwpi is equivalent to --apcs=/nointerwork

--apcs=noropi/norwpi.

Default

If you do not specify an --apcs option, the compiler assumes

--apcs=/nointerwork/noropi/norwpi/nofpic.

Usage

<u>/interwork, /nointerwork</u>

By default, code is generated:

- without interworking support, that is /nointerwork, unless you specify a --cpu option that corresponds to architecture ARMv5T or later
- with interworking support, that is /interwork, on ARMv5T and later. Interworking happens automatically on ARMv5T and later ARM architectures.

/ropi, /noropi

If you select the /ropi qualifier to generate ROPI code, the compiler:

• addresses read-only code and data PC-relative

	• sets the <i>Position Independent</i> (PI) attribute on read-only output sections.
	Note
	apcs=/ropi is not supported when compiling C++.
/rwpi,/norwpi	If you select the /rwpi qualifier to generate RWPI code, the compiler:
	 addresses writable data using offsets from the static base register sb. This means that:
	 the base address of the RW data region can be fixed at runtime
	 data can have multiple instances
	 data can be, but does not have to be, position-independent.
	• sets the PI attribute on read/write output sections.
	Note
	Because thelower_rwpi option is the default, code that is not RWPI is automatically transformed into equivalent code that is RWPI. This static initialization is done at runtime by the C++ constructor mechanism, even for C.
/fpic,/nofpic	If you select this option, the compiler:
	 accesses all static data using PC-relative addressing
	• accesses all imported or exported read-write data using a Global Offset Table (GOT) entry created by the linker
	 accesses all read-only data relative to the PC.
	You must compile your code with /fpic if it uses shared objects. This is because relative addressing is only implemented when

The use of /fpic is supported when compiling C++. In this case, virtual function tables and typeinfo are placed in read-write areas so that they can be accessed relative to the location of the PC.

You do not have to compile with /fpic if you are building either a

your code makes use of System V shared libraries.

static image or static library.

Note

When building a System V or ARM Linux shared library, use --apcs /fpic together with --no_hide_all.

Restrictions

There are restrictions when you compile code with /ropi, or /rwpi, or /fpic.

/ropi The main restrictions when compiling with /ropi are:

- The use of --apcs=/ropi is not supported when compiling C++.
- Some constructs that are legal C do not work when compiled for --apcs=/ropi. For example:

To enable such static initializations to work, compile your code using the --lower_ropi option. For example:

```
armcc --apcs=/ropi --lower_ropi
```

/rwpi The main restrictions when compiling with /rwpi are:

 Some constructs that are legal C do not work when compiled for --apcs=/rwpi. For example:

To enable such static initializations to work, compile your code using the --lower_rwpi option. For example:

```
armcc --apcs=/rwpi

Note
```

You do not have to specify --lower_rwpi, because this is the default.

/fpic The main restrictions when compiling with /fpic are:

- If you use --apcs=/fpic, the compiler exports only functions and data marked __declspec(dllexport).
- If you use --apcs=/fpic and --no_hide_all on the same command line, the compiler uses default ELF dynamic visibility for all extern variables and functions that do not use __declspec(dll*). The compiler disables auto-inlining for functions with default ELF visibility.

 If you use --apcs=/fpic in GNU mode, you must also use --no hide all.

See also

- --hide all, --no hide all on page 2-71
- --lower_ropi, --no_lower_ropi on page 2-87
- --lower_rwpi, --no_lower_rwpi on page 2-87
- __declspec(dllexport) on page 4-24
- Writing reentrant and thread-safe code on page 2-4 in the Libraries and Floating Point Support Guide
- Veneers on page 3-23 in the Linker User Guide
- Chapter 4 BPABI and SysV Shared Libraries and Executables in the Linker Reference Guide
- Procedure Call Standard for the ARM architecture in install_directory\Documentation\Specifications\....

2.1.6 --arm

This option is a request to the compiler to target the ARM instruction set. The compiler is permitted to generate both ARM and Thumb code, but recognizes that ARM code is preferred.

This option is not relevant for Thumb-only processors such as Cortex-M4, Cortex-M3, Cortex-M1, and Cortex-M0.

Default

This is the default option for targets supporting the ARM instruction set.

- --arm_only on page 2-15
- --cpu=list on page 2-30
- --cpu=name on page 2-30

- --thumb on page 2-122
- #pragma arm on page 4-59
- Specifying the target processor or architecture on page 2-23 in the Compiler User Guide.

2.1.7 --arm_linux

This option configures a set of other options with defaults that are suitable for ARM Linux compilation.

Usage

These defaults are enabled automatically when you use one of the following ARM Linux options:

- --arm_linux_paths
- --translate_gcc in full GCC emulation mode
- --translate_g++ in full GCC emulation mode
- --translate_gld in full GCC emulation mode.

Typical use of this option is to aid the migration of legacy code. It enables you to simplify the compiler options used in existing makefiles, while retaining full and explicit control over the header and library search paths used.

When migrating from a build earlier than RVCT v4.0, you can replace all of these options supplied to the compiler with a single --arm_linux option.

Default

By default, the configured set of options is:

- --apcs=/interwork
- --enum_is_int
- --qnu
- --library_interface=aeabi_glibc
- --no_hide_all
- --preinclude=linux_rvct.h
- --wchar32.

Example

To apply the default set of options, use --arm_linux.

To override any of the default options, specify them separately. For example, --arm linux --hide all.

In the latter example, --hide_all overrides the --no_hide_all encompassed by --arm_linux.

See also

- --arm_linux_config_file=path
- --arm_linux_configure on page 2-12
- --arm_linux_paths on page 2-13
- --configure_cpp_headers=path on page 2-24
- --configure_extra_includes=paths on page 2-25
- --configure_extra_libraries=paths on page 2-26
- --configure_gcc=path on page 2-27
- --configure_gld=path on page 2-28
- --configure_sysroot=path on page 2-29
- -- *gnu_defaults* on page 2-68
- --shared on page 2-115
- $--translate_g++$ on page 2-122
- --translate_gcc on page 2-124
- --translate_gld on page 2-125
- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
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2.1.8 --arm_linux_config_file=path

This option specifies the location of the configuration file that is created for ARM Linux builds. It enables the use of standard Linux configuration settings when compiling your code.

Syntax

--arm_linux_config_file=path

Where path is the path and filename of the configuration file.

Restrictions

You must use this option both when generating the configuration file and when using the configuration during compilation and linkage.

If you specify an ARM Linux configuration file on the command line and you use --translate_gcc, --translate_g++, or --translate_gld, you affect the default settings for certain other options. The default value for --bss_threshold becomes zero, the default for --signed_bitfields and --unsigned_bitfields becomes --signed_bitfields, and --enum_is_int and --wchar32 are switched on.

- --arm linux on page 2-9
- --arm_linux_configure on page 2-12
- --arm_linux_paths on page 2-13
- --bss_threshold=num on page 2-20
- --configure_cpp_headers=path on page 2-24
- --configure_extra_includes=paths on page 2-25
- --configure_extra_libraries=paths on page 2-26
- --configure_gcc=path on page 2-27
- --configure_gld=path on page 2-28
- --configure_sysroot=path on page 2-29
- --enum_is_int on page 2-53
- --gnu_defaults on page 2-68
- --shared on page 2-115
- --signed bitfields, --unsigned bitfields on page 2-116
- $--translate_g++$ on page 2-122
- --translate_gcc on page 2-124
- --translate_gld on page 2-125
- --wchar32 on page 2-135
- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
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2.1.9 --arm_linux_configure

This option configures RVCT for use with ARM Linux by creating a configuration file describing include paths, library paths, and standard libraries for the GNU C library, glibc. The created configuration file is used when you build your code.

Usage

Automatic and manual methods of configuration apply. Automatic configuration attempts to automatically locate an installation of the GNU toolchain on your PATH environment variable, and query it to determine the configuration settings to use. Manual configuration can be used to specify your own locations for header files and libraries. It can be used if you do not have a complete GNU toolchain installed.

If you use automatic configuration, the GCC version number of the GNU toolchain is added to the configuration file. The corresponding --gnu_version=version option is passed to the compiler from the configuration file when using any of the translation options or --arm_linux_paths.

To perform automatic configuration:

armcc --arm_linux_configure --arm_linux_config_file=config_file_path
 --configure_gcc=path --configure_gld=path

where *config_file_path* is the path and filename of the configuration file that is created. You can optionally specify the location of the *GNU Compiler Collection* (GCC) driver, and optionally the location of the GNU linker, to override the locations determined from the system PATH environment variable.

To perform manual configuration:

armcc --arm_linux_configure --arm_linux_config_file=path
 --configure_cpp_headers=path --configure_sysroot=path
 where the paths to the GNU libstdc++ Standard Template Library (STL) header
 files, and the system root path that libraries and header files are found from, are
 specified.

Restrictions

A GNU toolchain must exist on your system to use automatic configuration.

If using the automatic method of configuration, an ARM Linux GCC must be located with the system PATH environment variable. If you do not have a suitable GCC on your system path, you can either add one to your path, or use --configure_gcc (and optionally --configure_gld) to manually specify the location of a suitable GCC.

Default

Automatic configuration applies unless you specify the location of GCC or the GNU linker using additional options. That is, the compiler attempts to locate an ARM Linux GCC using your system path environment variable, unless you use additional options to specify otherwise.

See also

- --arm_linux on page 2-9
- --arm_linux_config_file=path on page 2-10
- --arm_linux_paths
- --configure_gcc=path on page 2-27
- --configure_gld=path on page 2-28
- --configure_sysroot=path on page 2-29
- --configure_cpp_headers=path on page 2-24
- --configure_extra_includes=paths on page 2-25
- --configure_extra_libraries=paths on page 2-26
- --gnu_defaults on page 2-68
- --gnu_version=version on page 2-69
- --shared on page 2-115
- $--translate_g++$ on page 2-122
- --translate_gcc on page 2-124
- --translate_gld on page 2-125
- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
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2.1.10 --arm_linux_paths

This option enables you to build code for ARM Linux.

Usage

You can use this option after you have configured RVCT for use with ARM Linux.

This is a compiler option only. It follows the typical GCC usage model, where the compiler driver is used to direct linkage and selection of standard system object files and libraries.

This option can also be used to aid migration from versions of RVCT earlier than RVCT v4.0. After you have created a configuration file using --arm_linux_configure, you can modify an existing build by replacing the list of standard options and search paths with the --arm_linux_paths option. That is, --arm_linux_paths can be used to replace:

- all of the default options listed for --arm_linux
- header paths
- library paths
- standard libraries.

Restrictions

You must specify the location of the configuration file by using --arm_linux_config_file=filename.

Examples

Compile and link application code:

```
armcc --arm_linux_paths --arm_linux_config_file=my_config_file -o hello -02
-0time -g hello.c
```

Compile a source file source.c for use in a shared library:

```
armcc --arm_linux_paths --arm_linux_config_file=my_config_file --apcs=/fpic -c
source.c
```

Link two object files, obj1 and obj2, into a shared library called my_shared_lib.so, using the compiler:

```
armcc --arm_linux_paths --arm_linux_config_file=my_config_file --shared -o
my_shared_lib.so obj1.o obj2.o
```

- --arm_linux on page 2-9
- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --configure_gcc=path on page 2-27
- --configure_gld=path on page 2-28
- --configure sysroot=path on page 2-29

- --configure cpp headers=path on page 2-24
- --configure_extra_includes=paths on page 2-25
- --configure_extra_libraries=paths on page 2-26
- --gnu_defaults on page 2-68
- --shared on page 2-115
- --translate_g++ on page 2-122
- --translate gcc on page 2-124
- --translate_gld on page 2-125
- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
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2.1.11 --arm_only

This option enforces ARM-only code. The compiler behaves as if Thumb is absent from the target architecture.

The compiler propagates the --arm_only option to the assembler and the linker.

Example

armcc --arm_only myprog.c

Note

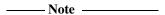
If you specify armcc --arm_only --thumb myprog.c, this does *not* mean that the compiler checks your code to ensure that no Thumb code is present. It means that --thumb overrides --arm_only.

- --*arm* on page 2-8
- --thumb on page 2-122
- Command syntax on page 3-2 in the Assembler Guide for information on --16 and --32.

2.1.12 --asm

This option instructs the compiler to write a listing to a file of the disassembly of the machine code generated by the compiler.

Object code is generated when this option is selected. The link step is also performed, unless the -c option is chosen.



To produce a disassembly of the machine code generated by the compiler, without generating object code, select -S instead of --asm.

Usage

The action of --asm, and the full name of the disassembly file produced, depends on the combination of options used:

Table 2-1 Compiling with the --asm option

Compiler option	Action
asm	Writes a listing to a file of the disassembly of the compiled source. The link step is also performed, unless the -c option is used. The disassembly is written to a text file whose name defaults to the name of the input file with the filename extension .s.
asm -c	As forasm, except that the link step is not performed.
asminterleave	As forasm, except that the source code is interleaved with the disassembly. The disassembly is written to a text file whose name defaults to the name of the input file with the filename extension .txt.
asmmultifile	As forasm, except that the compiler produces empty object files for the files merged into the main file.
asm -o filename	As forasm, except that the object file is named filename. The disassembly is written to the file filename.s. The name of the object file must not have the filename extension.s. If the filename extension of the object file is .s, the disassembly is written over the top of the object file. This might lead to unpredictable results.

See also

• -c on page 2-21

- --interleave on page 2-76
- --multifile, --no_multifile on page 2-92
- -o filename on page 2-95
- -S on page 2-114
- File naming conventions on page 2-12 in the Compiler User Guide.

2.1.13 --autoinline, --no_autoinline

This option enables or disables automatic inlining of functions.

The compiler automatically inlines functions at the higher optimization levels where it is sensible to do so. The -0space and -0time options, together with some other factors such as function size, influence how the compiler automatically inlines functions.

Selecting -0time, in combination with various other factors, increases the likelihood that functions are inlined.

Default

For optimization levels -00 and -01, the default is --no_autoinline.

For optimization levels -02 and -03, the default is --autoinline.

See also

- --forceinline on page 2-58
- --inline, --no_inline on page 2-75
- -*Onum* on page 2-96
- -Ospace on page 2-99
- -*Otime* on page 2-99.

2.1.14 --bigend

This option instructs the compiler to generate code for an ARM processor using big-endian memory.

The ARM architecture defines the following big-endian modes:

BE8 Byte Invariant Addressing mode (ARMv6 and later).

BE32 Legacy big-endian mode.

The selection of BE8 versus BE32 is specified at link time.

Default

The compiler assumes --littleend unless --bigend is explicitly specified.

See also

- --littleend on page 2-85
- Endian support on page 2-14 in the Developer Guide
- --be8 on page 2-15 in the Linker Reference Guide
- --be32 on page 2-16 in the Linker Reference Guide.

2.1.15 --bitband

This option bit-bands all non **const** global structure objects. It enables a word of memory to be mapped to a single bit in the bit-band region. This enables efficient atomic access to single-bit values in SRAM and Peripheral regions of the memory architecture.

For peripherals that are sensitive to the memory access width, byte, halfword, and word stores or loads to the alias space are generated for **char**, **short**, and **int** types of bitfields of bit-banded structs respectively.

Restrictions

The following restrictions apply:

- This option only affects **struct** types. Any union type or other aggregate type with a union as a member cannot be bit-banded.
- Members of structs cannot be bit-banded individually.
- Bit-banded accesses are generated only for single-bit bitfields.
- Bit-banded accesses are not generated for const objects, pointers, and local objects.

Example

In Example 2-1 on page 2-19, the writes to bitfields i and k are bit-banded when compiled using the--bitband command-line option.

Example 2-1 Bit-banding example

```
typedef struct {
  int i : 1;
  int j : 2;
  int k : 1;
} BB;

BB value;

void update_value(void)
{
  value.i = 1;
  value.k = 1;
}
```

See also

- __attribute__((bitband)) on page 4-43
- Bit-banding on page 4-16 in the Compiler User Guide
- Technical Reference Manual for your processor.

2.1.16 --brief_diagnostics, --no_brief_diagnostics

This option enables or disables the output of brief diagnostic messages by the compiler.

When enabled, the original source line is not displayed, and error message text is not wrapped if it is too long to fit on a single line.

Default

The default is --no_brief_diagnostics.

Example

```
/* main.c */
#include <stdio.h>
int main(void)
{
   printf(""Hello, world\n");
   return 0;
}
```

Compiling this code with --brief_diagnostics produces a warning message.

See also

- --diag_error=tag[,tag,...] on page 2-44
- --diag_remark=tag[,tag,...] on page 2-45
- --diag_style={arm|ide|gnu} on page 2-46
- --diag_suppress=tag[,tag,...] on page 2-47
- --diag_warning=tag[,tag,...] on page 2-48
- --errors=filename on page 2-53
- -- *remarks* on page 2-111
- -W on page 2-134
- --wrap_diagnostics, --no_wrap_diagnostics on page 2-137
- Chapter 6 Diagnostic Messages in the Compiler User Guide.

2.1.17 --bss_threshold=num

This option controls the placement of small global ZI data items in sections. A *small global ZI data item* is an uninitialized data item that is eight bytes or less in size.

Syntax

--bss_threshold=num

Where:

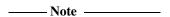
num is either:

- 0 place small global ZI data items in ZI data sections
- 8 place small global ZI data items in RW data sections.

Usage

In the current version of RVCT, the compiler might place small global ZI data items in RW data sections as an optimization. In RVCT 2.0.1 and earlier, small global ZI data items were placed in ZI data sections by default.

Use this option to emulate the behavior of RVCT 2.0.1 and earlier with respect to the placement of small global ZI data items in ZI data sections.



Selecting the option --bss_threshold=0 instructs the compiler to place *all* small global ZI data items in the current compilation module in a ZI data section. To place specific variables in:

• a ZI data section, use __attribute__((zero_init))

 a specific ZI data section, use a combination of __attribute__((section)) and __attribute__((zero_init)).

Default

If you do not specify a --bss_threshold option, the compiler assumes --bss threshold=8.

If you specify an ARM Linux configuration file on the command line and you use --translate_gcc or --translate_g++, the compiler assumes --bss_threshold=0.

Example

```
int glob1;  /* ZI (.bss) in RVCT 2.0.1 and earlier */  /* RW (.data) in RVCT 2.1 and later */
```

Compiling this code with --bss_threshold=0 places glob1 in a ZI data section.

See also

- #pragma arm section [section_sort_list] on page 4-59
- --arm linux config file=path on page 2-10
- --arm_linux_configure on page 2-12
- __attribute__((section("name"))) on page 4-52
- *attribute* ((zero init)) on page 4-57.

2.1.18 -c

This option instructs the compiler to perform the compilation step, but not the link step.

_____ Note _____

This option is different from the uppercase -C option.

Usage

The use of the -c option is recommended in projects with more than one source file.

- --*asm* on page 2-16
- -- *list* on page 2-82
- -o filename on page 2-95

		• -S on page 2-114.
2.1.19	-C	
		This option instructs the compiler to retain comments in preprocessor output.
		Choosing this option implicitly selects the option -E.
		Note
		This option is different from the lowercase -c option.
		See also
		• -E on page 2-52.
2.1.20	c90	
		This option enables the compilation of C90 source code.
		Default
		This option is implicitly selected for files having a suffix of .c, .ac, or .tc.
		Note
		Filename extensions .ac and .tc are deprecated.
		Coo alos
		See also <i>c</i> 99
		• <i>c99</i> • <i>gnu</i> on page 2-67
		•strict,no_strict on page 2-119
		5to.,birior on page 2 117

2.1.21 --c99

This option enables the compilation of C99 source code.

File naming conventions on page 2-12 in the Compiler User Guide.

Source language modes on page 1-3

- --*c*90
- --*gnu* on page 2-67

- --strict, --no strict on page 2-119
- *Source language modes* on page 1-3.

2.1.22 --code_gen, --no_code_gen

This option enables or disables the generation of object code.

When generation of object code is disabled, the compiler performs syntax-checking only, without creating an object file.

Default

The default is --code_gen.

2.1.23 --compatible=*name*

This option enables code generated by the compiler to be compatible with multiple processors or architectures.

The valid combinations are shown in Table 2-2. You can match any of the processors or architectures from Group 1 with any of the processors or architectures from Group 2.

Table 2-2 Compatible processor or architecture combinations

Group 1	ARM7TDMI, 4T
Group 2	Cortex-M0, Cortex-M1, Cortex-M3, Cortex-M4, 7-M, 6-M, 6S-M

Syntax

--compatible=name

Where:

name

is the name of a processor or architecture, or NONE. Processor and architecture names are not case-sensitive.

If multiple instances of this option are present on the command line, the last one specified overrides the previous instances.

Specify --compatible=NONE at the end of the command line to turn off all other instances of the option.

Example

armcc --cpu=arm7tdmi --compatible=cortex-m3 myprog.c

See also

• --cpu=name on page 2-30.

2.1.24 --compile_all_input, --no_compile_all_input

This option enables or disables the suppression of filename extension processing.

When enabled, the compiler suppresses filename extension processing entirely, treating all input files as if they have the suffix .c.

Default

The default is --no_compile_all_input.

See also

• File naming conventions on page 2-12 in the Compiler User Guide.

2.1.25 --configure_cpp_headers=path

This option specifies the path to the GNU libstdc++ STL header files, when configuring RVCT for use with ARM Linux.

Syntax

--configure_cpp_headers=path

Where:

path is the path to the GNU C++ STL header files.

Usage

This option overrides any path that is automatically detected. It can be used as part of a manual approach to configuring RVCT for use with ARM Linux.

See also

2-24

- --arm_linux on page 2-9
- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --arm_linux_paths on page 2-13
- --configure_gcc=path on page 2-27

- --configure gld=path on page 2-28
- --configure_sysroot=path on page 2-29
- --configure_extra_includes=paths
- --configure extra libraries=paths on page 2-26
- --gnu_defaults on page 2-68
- --shared on page 2-115
- --translate g++ on page 2-122
- --translate_gcc on page 2-124
- --translate_gld on page 2-125
- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
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2.1.26 --configure_extra_includes=paths

This option specifies any additional system include paths when configuring RVCT for use with ARM Linux.

Syntax

--configure_extra_includes=paths

Where:

paths

is a comma separated list of pathnames denoting the locations of the additional system include paths.

- --arm_linux on page 2-9
- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --arm_linux_paths on page 2-13
- --configure cpp headers=path on page 2-24
- --configure_extra_libraries=paths on page 2-26
- --configure_gcc=path on page 2-27
- --configure_gld=path on page 2-28
- --configure_sysroot=path on page 2-29

- -- gnu defaults on page 2-68
- --shared on page 2-115
- --translate_g++ on page 2-122
- --translate_gcc on page 2-124
- --translate_gld on page 2-125
- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
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2.1.27 --configure_extra_libraries=paths

This option specifies any additional system library paths when configuring RVCT for use with ARM Linux.

Syntax

--configure_extra_libraries=paths

Where:

paths

is a comma separated list of pathnames denoting the locations of the additional system library paths.

- --arm_linux on page 2-9
- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --arm_linux_paths on page 2-13
- --configure_cpp_headers=path on page 2-24
- --configure_extra_includes=paths on page 2-25
- --configure_gcc=path on page 2-27
- --configure_gld=path on page 2-28
- --configure sysroot=path on page 2-29
- --gnu_defaults on page 2-68
- -- *shared* on page 2-115
- $--translate_g++$ on page 2-122
- --translate_gcc on page 2-124

- --translate gld on page 2-125
- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
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2.1.28 --configure_gcc=path

This option specifies the location of the GCC driver, when configuring RVCT for use with ARM Linux.

Syntax

--configure_gcc=path

Where:

path is the path and filename of the GCC driver.

Usage

Use this option if you want to override the default location of the GCC driver specified during configuration, or if the automatic configuration method of --arm_linux_configure fails to find the driver.

- --arm linux on page 2-9
- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --arm_linux_paths on page 2-13
- --configure_cpp_headers=path on page 2-24
- --configure_extra_includes=paths on page 2-25
- --configure_extra_libraries=paths on page 2-26
- --configure_gld=path on page 2-28
- --configure_sysroot=path on page 2-29
- -- gnu defaults on page 2-68
- --shared on page 2-115
- $--translate_g++$ on page 2-122
- --translate gcc on page 2-124

- --translate gld on page 2-125
- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
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2.1.29 --configure_gld=path

This option specifies the location of the GNU linker, ld.

Syntax

--configure_gld=path

Where:

path

is the path and filename of the GNU linker.

Usage

During configuration, the compiler attempts to determine the location of the GNU linker used by GCC. If the compiler is unable to determine the location, or if you want to override the normal path to the GNU linker, you can specify its location by using the --configure_gld=path option. The path is the full path and filename of the GNU ld binary.

- --arm linux on page 2-9
- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --arm linux paths on page 2-13
- --configure_cpp_headers=path on page 2-24
- --configure_extra_includes=paths on page 2-25
- --configure_extra_libraries=paths on page 2-26
- --configure_gcc=path on page 2-27
- --configure_sysroot=path on page 2-29
- --gnu_defaults on page 2-68
- --shared on page 2-115
- --translate_g++ on page 2-122

- --translate gcc on page 2-124
- --translate_gld on page 2-125
- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
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2.1.30 --configure_sysroot=*path*

This option specifies the system root path to use when configuring RVCT for use with ARM Linux.

Syntax

--configure_sysroot=path

Where path is the system root path to use.

Usage

This option overrides any system root path that is automatically detected. It can be used as part of a manual approach to configuring RVCT for use with ARM Linux, if you want to use a different path to your normal system root path.

The system root path is the base path that libraries and header files are normally found from. On a standard Linux system, this is typically the root of the filesystem. In a cross compilation GNU toolchain, it is usually the parent directory of the GNU C library installation. This directory contains the lib, usr/lib, and usr/include subdirectories that hold the C libraries and header files.

- --arm_linux on page 2-9
- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --arm_linux_paths on page 2-13
- --configure_cpp_headers=path on page 2-24
- --configure_extra_includes=paths on page 2-25
- --configure_extra_libraries=paths on page 2-26
- --configure_gcc=path on page 2-27

- --configure gld=path on page 2-28
- --gnu_defaults on page 2-68
- --shared on page 2-115
- $--translate_g++$ on page 2-122
- --translate_gcc on page 2-124
- --translate_gld on page 2-125
- --arm linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
- Application Note 212 Building Linux applications using RVCT v4.0 and the GNU Tools and Libraries.

2.1.31 --cpp

This option enables the compilation of C++ source code.

Default

This option is implicitly selected for files having a suffix of .cpp, .cxx, .c++, .cc, or .CC.

See also

- --anachronisms, --no_anachronisms on page 2-3
- --*c90* on page 2-22
- --*c*99 on page 2-22
- --*gnu* on page 2-67
- --strict, --no_strict on page 2-119
- *Source language modes* on page 1-3.

2.1.32 --cpu=list

This option lists the supported architecture and processor names that can be used with the --cpu=name option.

See also

• --cpu=name.

2.1.33 --cpu=name

This option enables code generation for the selected ARM processor or architecture.

Syntax

--cpu=name

Where:

name

is the name of a processor or architecture.

If name is the name of a processor, enter it as shown on ARM data sheets,

for example, ARM7TDMI, ARM1176JZ-S, MPCore.

If name is the name of an architecture, it must belong to the list of

architectures shown in Table 2-3.

Processor and architecture names are not case-sensitive.

Wildcard characters are not accepted.

Table 2-3 Supported ARM architectures and example processors

Architecture	Description	Example processors
4	ARMv4 without Thumb	SA-1100
4T	ARMv4 with Thumb	ARM7TDMI, ARM9TDMI, ARM720T, ARM740T, ARM920T, ARM922T, ARM940T, SC100
5T	ARMv5 with Thumb and interworking	
5TE	ARMv5 with Thumb, interworking, DSP multiply, and double-word instructions	ARM9E, ARM946E-S, ARM966E-S
5TEJ	ARMv5 with Thumb, interworking, DSP multiply, double-word instructions, and Jazelle® extensionsa	ARM926EJ-S, ARM1026EJ-S, SC200
6	ARMv6 with Thumb, interworking, DSP multiply, double-word instructions, unaligned and mixed-endian support, Jazelle, and media extensions	ARM1136J-S, ARM1136JF-S
6-M	ARMv6 micro-controller profile with Thumb only plus processor state instructions	Cortex-M1 without OS extensions, Cortex-M0
6S-M	ARMv6 micro-controller profile with Thumb only, plus processor state instructions and OS extensions	Cortex-M1 with OS extensions
6K	ARMv6 with SMP extensions	MPCore
6T2	ARMv6 with Thumb-2	ARM1156T2-S, ARM1156T2F-S

Table 2-3 Supported ARM architectures and example processors (continued)

Architecture	Description	Example processors
6Z	ARMv6 with Security Extensions	ARM1176JZF-S, ARM1176JZ-S
7	ARMv7 with Thumb-2 only and without hardware divide	
7-A	ARMv7 application profile supporting virtual MMU-based memory systems, with ARM, Thumb-2, and Thumb-2EE instruction sets, DSP support, and 32-bit SIMD support	Cortex-A8, Cortex-A9
7-R	ARMv7 real-time profile with ARM, Thumb-2, DSP support, and 32-bit SIMD support	Cortex-R4, Cortex-R4F
7-M	ARMv7 micro-controller profile with Thumb-2 only and hardware divide	Cortex-M3, SC300

a. The ARM compiler cannot generate Java bytecodes.



ARMv7 is not an actual ARM architecture. --cpu=7 denotes the features that are common to all of the ARMv7-A, ARMv7-R, and ARMv7-M architectures. By definition, any given feature used with --cpu=7 exists on all of the ARMv7-A, ARMv7-R, and ARMv7-M architectures.

Default

If you do not specify a --cpu option, the compiler assumes --cpu=ARM7TDMI.

To get a full list of CPU architectures and processors, use the --cpu=list option.

Usage

The following general points apply to processor and architecture options:

Processors

- Selecting the processor selects the appropriate architecture, *Floating-Point Unit* (FPU), and memory organization.
- The supported --cpu values include all current ARM product names or architecture versions.
 - Other ARM architecture-based processors, such as the Marvell Feroceon and the Intel XScale, are also supported.

• If you specify a processor for the --cpu option, the compiled code is optimized for that processor. This enables the compiler to use specific coprocessors or instruction scheduling for optimum performance.

Architectures

• If you specify an architecture name for the --cpu option, the code is compiled to run on any processor supporting that architecture. For example, --cpu=5TE produces code that can be used by the ARM926EJ-S®.

FPU

• Some specifications of --cpu imply an --fpu selection. For example, when compiling with the --arm option, --cpu=ARM1136JF-S implies --fpu=vfpv2. Similarly, --cpu=Cortex-R4F implies --fpu=vfpv3_d16.

_____Note _____

Any *explicit* FPU, set with -- fpu on the command line, overrides an *implicit* FPU.

• If no --fpu option is specified and no --cpu option is specified, --fpu=softvfp is used.

ARM/Thumb

• Specifying a processor or architecture that supports Thumb instructions, such as --cpu=ARM7TDMI, does not make the compiler generate Thumb code. It only enables features of the processor to be used, such as long multiply. Use the --thumb option to generate Thumb code, unless the processor is a Thumb-only processor, for example Cortex-M3. In this case, --thumb is not required.

Specifying the target processor or architecture might make the
object code generated by the compiler incompatible with other
ARM processors. For example, code compiled for architecture
ARMv6 might not run on an ARM920T processor, if the compiled
code includes instructions specific to ARMv6. Therefore, you must
choose the lowest common denominator processor suited to your

purpose.

_____ Note ____

- If you are compiling code that is intended for mixed ARM/Thumb systems for processors that support ARMv4T or ARMv5T, then you must specify the interworking option --apcs=/interwork. By default, this is enabled for processors that support ARMv5T or above.
- If you compile for Thumb, that is with the --thumb option on the
 command line, the compiler compiles as much of the code as
 possible using the Thumb instruction set. However, the compiler
 might generate ARM code for some parts of the compilation. For
 example, if you are compiling code for a Thumb-1 processor and
 using VFP, any function containing floating-point operations is
 compiled for ARM.
- If you are compiling code for ARMv7-M, for example

 -cpu=Cortex-M3, you do not have to specify --thumb on the command line, because ARMv7-M supports Thumb-2 only.

Restrictions

You cannot specify both a processor and an architecture on the same command-line.

See also

- --apcs=qualifer...qualifier on page 2-4
- --*cpu*=*list* on page 2-30
- --fpu=name on page 2-62
- --thumb on page 2-122.

2.1.34 --create_pch=*filename*

This option instructs the compiler to create a *PreCompiled Header* (PCH) file with the specified filename.

This option takes precedence over all other PCH options.

Syntax

--create_pch=filename

Where:

filename is the name of the PCH file to be created.

See also

- --pch on page 2-101
- --pch_dir=dir on page 2-101
- --pch_messages, --no_pch_messages on page 2-102
- --pch_verbose, --no_pch_verbose on page 2-102
- --use_pch=filename on page 2-129
- #pragma hdrstop on page 4-64
- #pragma no_pch on page 4-67
- *Precompiled header files* on page 2-17 in the *Compiler User Guide*.

2.1.35 -Dname[(parm-list)][=def]

This option defines the macro name.

Syntax

-Dname[(parm-list)][=def]

Where:

name

Is the name of the macro to be defined.

parm-list

Is an optional list of comma-separated macro parameters. By appending a macro parameter list to the macro name, you can define function-style macros.

The parameter list must be enclosed in parentheses. When specifying multiple parameters, do not include spaces between commas and parameter names in the list.

_____ Note _____

Parentheses might require escaping on UNIX systems.

=def

Is an optional macro definition.

If =def is omitted, the compiler defines name as the value 1.

To include characters recognized as tokens on the command line, enclose the macro definition in double quotes.

Usage

Specifying -Dname has the same effect as placing the text #define name at the head of each source file.

Restrictions

The compiler defines and undefines macros in the following order:

- 1. compiler predefined macros
- 2. macros defined explicitly, using -Dname
- 3. macros explicitly undefined, using -Uname.

Example

Specifying the option:

```
-DMAX(X,Y)="((X > Y) ? X : Y)"
```

on the command line is equivalent to defining the macro:

```
#define MAX(X, Y) ((X > Y) ? X : Y)
```

at the head of each source file.

See also

- -C on page 2-22
- -*E* on page 2-52
- *-Uname* on page 2-127
- *Compiler predefines* on page 4-198.

2.1.36 --data_reorder, --no_data_reorder

This option enables or disables automatic reordering of top-level data items, for example global variables.

The compiler can save memory by eliminating wasted space between data items. However, --data_reorder can break legacy code, if the code makes invalid assumptions about ordering of data by the compiler.

The ISO C Standard does not guarantee data order, so you must avoid writing code that depends on any assumed ordering. If you require data ordering, place the data items into a structure.

Default

The default is --data_reorder.

2.1.37 --debug, --no_debug

This option enables or disables the generation of debug tables for the current compilation.

The compiler produces the same code regardless of whether --debug is used. The only difference is the existence of debug tables.

Default

The default is --no_debug.

Using --debug does not affect optimization settings. By default, using the --debug option alone is equivalent to:

--debug --dwarf3 --debug_macros

See also

- --debug_macros, --no_debug_macros
- --dwarf2 on page 2-51
- --dwarf3 on page 2-51
- -*Onum* on page 2-96.

2.1.38 --debug_macros, --no_debug_macros

This option enables or disables the generation of debug table entries for preprocessor macro definitions.

Usage

Using --no_debug_macros might reduce the size of the debug image.

This option must be used with the --debug option.

Default

The default is --debug_macros.

- --debug, --no_debug
- -- *gnu_defaults* on page 2-68.

2.1.39 --default_definition_visibility=*visibility*

This option controls the default ELF symbol visibility of **extern** variable and function definitions.

Syntax

--default_definition_visibility=visibility

Where:

visibility is default, hidden, internal, or protected.

Usage

Use --default_definition_visibility=visibility to force the compiler to use the specified ELF symbol visibility for all extern variables and functions defined in the source file, if they do not use __declspec(dll*) or __attribute__((visibility("visibility_type"))). Unlike --hide_all, --no_hide_all,

Default

By default, --default_definition_visibility=hidden.

See also

• --hide all, --no hide all on page 2-71

this does not affect extern references.

- __attribute__((visibility("visibility_type"))) on page 4-40
- __attribute__((visibility("visibility_type"))) on page 4-55
- Symbol visibility on page 4-5 in Using the Linker.

2.1.40 --default extension=ext

This option enables you to change the filename extension for object files from the default extension (.o) to an extension of your choice.

Syntax

--default_extension=ext

Where:

ext is the filename extension of your choice.

Example

The following example creates an object file called test.obj, instead of test.o:

armcc --default_extension=obj -c test.c

_____ Note _____

The -o *filename* option overrides this. For example, the following command results in an object file named test.o:

armcc --default_extension=obj -o test.o -c test.c

2.1.41 --dep_name, --no_dep_name

This option enables or disables dependent name processing in C++.

The C++ standard states that lookup of names in templates occurs:

- at the time the template is parsed, if the name is non dependent
- at the time the template is parsed, or at the time the template is instantiated, if the name is dependent.

When the option --no_dep_name is selected, the lookup of dependent names in templates can occur only at the time the template is instantiated. That is, the lookup of dependent names at the time the template is parsed is disabled.

 Note	

The option --no_dep_name is provided only as a migration aid for legacy source code that does not conform to the C++ standard. Its use is not recommended.

Mode

This option is effective only if the source language is C++.

Default

The default is --dep_name.

Restrictions

The option --dep_name cannot be combined with the option --no_parse_templates, because parsing is done by default when dependent name processing is enabled.

Errors

When the options --dep_name and --no_parse_templates are combined, the compiler generates an error.

See also

- --parse_templates, --no_parse_templates on page 2-100
- *Template instantiation* on page 5-15.

2.1.42 --depend=*filename*

This option instructs the compiler to write makefile dependency lines to a file during compilation.

Syntax

--depend=filename

Where:

filename is the name of the dependency file to be output.

Restrictions

If you specify multiple source files on the command line then any --depend option is ignored. No dependency file is generated in this case.

Usage

The output file is suitable for use by a make utility. To change the output format to be compatible with UNIX make utilities, use the --depend_format option.

- --depend_format=string on page 2-41
- --depend_system_headers, --no_depend_system_headers on page 2-42
- --depend_target=target on page 2-43
- --ignore_missing_headers on page 2-72
- -- *list* on page 2-82
- -M on page 2-88
- --md on page 2-89
- --phony_targets on page 2-103

2.1.43 --depend_format=*string*

This option changes the format of output dependency files, for compatibility with some UNIX make programs.

Syntax

--depend_format=string

Where *string* is one of:

unix generate dependency file entries using UNIX-style path

separators.

unix_escaped is the same as unix, but escapes spaces with \.

unix_quoted is the same as unix, but surrounds path names with double quotes.

Usage

unix On Windows systems, --depend_format=unix forces the use of

UNIX-style path names. That is, the UNIX-style path separator

symbol / is used in place of \.

On UNIX systems, --depend_format=unix has no effect.

unix_escaped On Windows systems, --depend_format=unix_escaped forces

unix-style path names, and escapes spaces with \.

On UNIX systems, --depend_format=unix_escaped with escapes

spaces with \setminus .

unix_quoted On Windows systems, --depend_format=unix_quoted forces

unix-style path names and surrounds them with "".

On UNIX systems, --depend_format=unix_quoted surrounds path

names with "".

Default

If you do not specify a --depend_format option, then the format of output dependency files depends on your choice of operating system:

Windows On Windows systems, the default is to use either Windows-style

paths or UNIX-style paths, whichever is given.

UNIX On UNIX systems, the default is --depend_format=unix.

Example

On a Windows system, compiling a file main.c containing the line:

```
#include "..\include\header files\common.h"
```

using the options --depend=depend.txt --depend_format=unix_escaped produces a dependency file depend.txt containing the entries:

```
main.axf: main.c
main.axf: ../include/header\ files/common.h
```

See also

- --depend=filename on page 2-40
- --depend_system_headers, --no_depend_system_headers
- --depend target=target on page 2-43
- --ignore_missing_headers on page 2-72
- -*M* on page 2-88
- --md on page 2-89
- --phony_targets on page 2-103

2.1.44 --depend_system_headers, --no_depend_system_headers

This option enables or disables the output of system include dependency lines when generating makefile dependency information using either the -M option or the --md option.

Default

The default is --depend_system_headers.

Example

```
/* hello.c */
#include <stdio.h>
int main(void)
{
   printf("Hello, world!\n");
   return 0;
}
```

Compiling this code with the option -M produces:

```
__image.axf: hello.c
__image.axf: ...\include\...\stdio.h
```

Compiling this code with the options -M --no_depend_system_headers produces:

__image.axf: hello.c

See also

- --depend=filename on page 2-40
- --depend_format=string on page 2-41
- --depend_target=target
- --ignore_missing_headers on page 2-72
- -*M* on page 2-88
- --md on page 2-89
- --phony_targets on page 2-103

2.1.45 --depend_target=target

This option sets the target for makefile dependency generation.

Usage

Use this option to override the default target.

Restriction

This option is analogous to -MT in GCC. However, behavior differs when specifying multiple targets. For example, gcc -M -MT target1 -MT target2 file.c might give a result of target1 target2: file.c header.h, whereas --depend_target=target1 --depend_target=target2 treats target2 as the target.

See also

- --depend=filename on page 2-40
- --depend_format=string on page 2-41
- --depend system headers, --no depend system headers on page 2-42
- --ignore_missing_headers on page 2-72
- -*M* on page 2-88
- --md on page 2-89
- --phony_targets on page 2-103

2.1.46 --device=list

This option lists the supported device names that can be used with the --device=name option.

See also

• --device=name.

2.1.47 --device=name

This option enables you to compile code for a specific microcontroller or *System-on-Chip* (SoC) device.

Syntax

--device=name

Where:

name

is the name of a target microcontroller or SoC device.

Usage

When you specify a particular device name, the device inherits the default endianness and floating-point architecture from the corresponding CPU. You can use the --bi, --li, and --fpu options to alter the default settings for endianness and target floating-point architecture.

See also

- --bigend on page 2-17
- --device=list on page 2-43
- --fpu=name on page 2-62
- --littleend on page 2-85
- --device=list on page 2-27 in the Linker Reference Guide
- --device=name on page 2-27 in the Linker Reference Guide
- *Using the C preprocessor* on page 3-47 in the *Assembler Guide*.

2.1.48 --diag_error=tag[,tag,...]

This option sets the diagnostic messages that have the specified tags to Error severity.



This option has the #pragma equivalent #pragma diag_error.

Syntax

--diag_error=tag[,tag,...]

Where:

tag[,tag,...]

is a comma-separated list of diagnostic message numbers specifying the messages whose severities are to be changed.

At least one diagnostic message number must be specified.

When specifying multiple diagnostic message numbers, do not include spaces between commas and numbers in the list.

Usage

The severity of the following types of diagnostic messages can be changed:

- Messages with the number format #nnnn-D.
- Warning messages with the number format CnnnnW.

See also

• --diag_remark=tag[,tag,...]

- Note -----

- --diag_suppress=tag[,tag,...] on page 2-47
- --diag_warning=tag[,tag,...] on page 2-48
- #pragma diag_error tag[,tag,...] on page 4-62
- Changing the severity of diagnostic messages on page 6-5 in the Compiler User Guide.

2.1.49 --diag_remark=tag[,tag,...]

This option sets the diagnostic messages that have the specified tags to Remark severity.

The --diag_remark option behaves analogously to --diag_errors, except that the compiler sets the diagnostic messages having the specified tags to Remark severity rather than Error severity.

Note	-	
Remarks are not displayed by remarks.	y default. To see remark messages, use the	compiler option

This option has the $\mbox{\tt\#pragma}$ equivalent $\mbox{\tt\#pragma}$ diag_remark.

Syntax

```
--diag_remark=tag[,tag,...]
```

Where:

is a comma-separated list of diagnostic message numbers specifying the messages whose severities are to be changed.

See also

- --diag_error=tag[,tag,...] on page 2-44
- --diag_suppress=tag[,tag,...] on page 2-47
- --diag_warning=tag[,tag,...] on page 2-48
- --remarks on page 2-111
- #pragma diag_remark tag[,tag,...] on page 4-62
- Changing the severity of diagnostic messages on page 6-5 in the Compiler User Guide.

2.1.50 --diag_style={arm|ide|gnu}

This option specifies the style used to display diagnostic messages.

Syntax

--diag_style=string

Where *string* is one of:

arm Display messages using the ARM compiler style.

ide Include the line number and character count for any line that is in error.

These values are displayed in parentheses.

gnu Display messages in the format used by gcc.

Default

If you do not specify a --diag_style option, the compiler assumes --diag_style=arm.

Usage

Choosing the option --diag_style=ide implicitly selects the option --brief_diagnostics. Explicitly selecting --no_brief_diagnostics on the command line overrides the selection of --brief_diagnostics implied by --diag_style=ide.

Selecting either the option --diag_style=arm or the option --diag_style=gnu does not imply any selection of --brief_diagnostics.

See also

- --diag_error=tag[,tag,...] on page 2-44
- --diag_remark=tag[,tag,...] on page 2-45
- --diag_suppress=tag[,tag,...]
- --diag_warning=tag[,tag,...] on page 2-48
- Changing the severity of diagnostic messages on page 6-5 in the Compiler User Guide.

2.1.51 --diag_suppress=tag[,tag,...]

This option disables diagnostic messages that have the specified tags.

The --diag_suppress option behaves analogously to --diag_errors, except that the compiler suppresses the diagnostic messages having the specified tags rather than setting them to have Error severity.



This option has the #pragma equivalent #pragma diag_suppress.

Syntax

```
--diag_suppress=tag[,tag,...]
```

Where:

is a comma-separated list of diagnostic message numbers specifying the messages to be suppressed.

See also

- --diag_error=tag[,tag,...] on page 2-44
- --diag_remark=tag[,tag,...] on page 2-45
- --diag_warning=tag[,tag,...] on page 2-48
- #pragma diag suppress tag[,tag,...] on page 4-63
- Suppressing diagnostic messages on page 6-6 in the Compiler User Guide.

2.1.52 --diag_suppress=optimizations

This option suppresses diagnostic messages for high-level optimizations.

Default

By default, optimization messages have Remark severity. Specifying --diag_suppress=optimizations suppresses optimization messages.



Use the --remarks option to see optimization messages having Remark severity.

Usage

The compiler performs certain high-level vector and scalar optimizations when compiling at the optimization level -03, for example, loop unrolling. Use this option to suppress diagnostic messages relating to these high-level optimizations.

Example

```
int factorial(int n)
{
    int result=1;
    while (n > 0)
        result *= n--;
    return result;
}
```

Compiling this code with the options -03 -0time --remarks --diag_suppress=optimizations suppresses optimization messages.

See also

- --diag_suppress=tag[,tag,...] on page 2-47
- --diag_warning=optimizations on page 2-49
- -*Onum* on page 2-96
- -*Otime* on page 2-99
- --remarks on page 2-111.

2.1.53 --diag_warning=tag[,tag,...]

This option sets the diagnostic messages that have the specified tags to Warning severity.

The --diag_warning option behaves analogously to --diag_errors, except that the compiler sets the diagnostic messages having the specified tags to Warning severity rather than Error severity.

_____Note _____

This option has the #pragma equivalent #pragma diag_warning.

Syntax

See also

- --diag_error=tag[,tag,...] on page 2-44
- --diag_remark=tag[,tag,...] on page 2-45
- --diag_suppress=tag[,tag,...] on page 2-47
- #pragma diag_warning tag[, tag, ...] on page 4-64
- Changing the severity of diagnostic messages on page 6-5 in the Compiler User Guide.

2.1.54 --diag_warning=optimizations

This option sets high-level optimization diagnostic messages to have Warning severity.

Default

By default, optimization messages have Remark severity.

Usage

The compiler performs certain high-level vector and scalar optimizations when compiling at the optimization level -03 -0time, for example, loop unrolling. Use this option to display diagnostic messages relating to these high-level optimizations.

Example

```
int factorial(int n)
{
    int result=1;
    while (n > 0)
```

```
result *= n--;
return result;
}
```

Compiling this code with the options --vectorize --cpu=Cortex-A8 -03 -0time --diag_warning=optimizations generates optimization warning messages.

See also

- --diag_suppress=optimizations on page 2-47
- --diag_warning=tag[,tag,...] on page 2-48
- -*Onum* on page 2-96
- *-Otime* on page 2-99.

2.1.55 --dllexport_all, --no_dllexport_all

This option enables you to control symbol visibility when building DLLs.

Default

The default is --no_dllexport_all.

Usage

Use the option --dllexport_all to mark all extern definitions as __declspec(dllexport).

See also

- --apcs=qualifer...qualifier on page 2-4
- __declspec(dllexport) on page 4-24.

2.1.56 --dllimport_runtime, --no_dllimport_runtime

This option enables you to control symbol visibility when using the runtime library as a shared library.

Default

The default is --no_dllimport_runtime.

Usage

Use the option --dllimport_runtime to mark:

all builtin symbols as __declspec(dllimport)

- RunTime Type Information (RTTI) generated in the cpprt runtime libraries for import
- any optimized printf() and __hardfp_ functions for import, provided that the original function is marked as __declspec(dllimport).

See also

- --guiding_decls, --no_guiding_decls on page 2-70
- --rtti, --no rtti on page 2-114
- __declspec(dllimport) on page 4-26.

2.1.57 --dollar, --no_dollar

This option instructs the compiler to accept or reject dollar signs, \$, in identifiers.

Default

If the options --strict or --strict_warnings are specified, the default is --no_dollar. Otherwise, the default is --dollar.

See also

- *Dollar signs in identifiers* on page 3-13
- --strict, --no_strict on page 2-119.

2.1.58 --dwarf2

This option instructs the compiler to use DWARF 2 debug table format.

Default

The compiler assumes --dwarf3 unless --dwarf2 is explicitly specified.

See also

--dwarf3.

2.1.59 --dwarf3

This option instructs the compiler to use DWARF 3 debug table format.

Default

The compiler assumes --dwarf3 unless --dwarf2 is explicitly specified.

See also

• --dwarf2 on page 2-51.

2.1.60 -F

This option instructs the compiler to execute only the preprocessor step.

By default, output from the preprocessor is sent to the standard output stream and can be redirected to a file using standard UNIX and MS-DOS notation.

You can also use the -o option to specify a file for the preprocessed output. By default, comments are stripped from the output. The preprocessor accepts source files with any extension, for example, .o, .s, and .txt.

Example

```
armcc -E source.c > raw.c
```

See also

- -C on page 2-22
- -o filename on page 2-95.

2.1.61 --emit_frame_directives, --no_emit_frame_directives

This option instructs the compiler to place DWARF FRAME directives into disassembly output.

Default

The default is --no_emit_frame_directives.

Examples

```
armcc --asm --emit_frame_directives foo.c
armcc -S emit_frame_directives foo.c
```

- --asm on page 2-16
- -S on page 2-114
- *Using frame directives* on page 2-51 in the *Assembler Guide*.

2.1.62 --enum_is_int

This option forces the size of all enumeration types to be at least four bytes.

This option is switched off by default and the smallest data type is used that can hold the values of all enumerators.

If you specify an ARM Linux configuration file on the command line, this option is switched on by default.

_____ Note _____

The --enum_is_int option is not recommended for general use.

See also

- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --interface_enums_are_32_bit on page 2-76.

2.1.63 --errors=filename

This option redirects the output of diagnostic messages from stderr to the specified errors file.

Syntax

--errors=filename

Where:

filename is the name of the file to which errors are to be redirected.

Diagnostics that relate to problems with the command options are not redirected, for example, if you type an option name incorrectly. However, if you specify an invalid argument to an option, for example --cpu=999, the related diagnostic is redirected to the specified *filename*.

- --brief_diagnostics, --no_brief_diagnostics on page 2-19
- --diag error=tag[,tag,...] on page 2-44
- --diag_remark=tag[,tag,...] on page 2-45
- --diag_style={arm|ide|gnu} on page 2-46
- --diag_suppress=tag[,tag,...] on page 2-47

- --diag_warning=tag[,tag,...] on page 2-48
- -- *remarks* on page 2-111
- -W on page 2-134
- --wrap_diagnostics, --no_wrap_diagnostics on page 2-137
- Chapter 6 *Diagnostic Messages* in the *Compiler User Guide*.

2.1.64 --exceptions, --no_exceptions

This option enables or disables exception handling.

In C++, the --exceptions option enables the use of throw and try/catch, causes function exception specifications to be respected, and causes the compiler to emit unwinding tables to support exception propagation at runtime.

In C++, when the --no_exceptions option is specified, throw and try/catch are not permitted in source code. However, function exception specifications are still parsed, but most of their meaning is ignored.

In C, the behavior of code compiled with --no_exceptions is undefined if an exception is thrown through the compiled functions. You must use --exceptions, if you want exceptions to propagate correctly though C functions.

Default

The default is --no_exceptions. However, if you specify an ARM Linux configuration file on the command line and you use --translate_g++, the default changes to --exceptions.

See also

- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --exceptions_unwind, --no_exceptions_unwind.

2.1.65 --exceptions_unwind, --no_exceptions_unwind

This option enables or disables function unwinding for exception-aware code. This option is only effective if --exceptions is enabled.

When you use --no_exceptions_unwind and --exceptions then no exception can propagate through the compiled functions. std::terminate is called instead.

Default

The default is --exceptions_unwind.

See also

- --exceptions, --no_exceptions on page 2-54
- Function unwinding at runtime on page 5-18.

2.1.66 --export_all_vtbl, --no_export_all_vtbl

This option controls how dynamic symbols are exported in C++.

Mode

This option is effective only if the source language is C++.

Default

The default is --no_export_all_vtbl.

Usage

Use the option --export_all_vtbl to export all virtual function tables and RTTI for classes with a key function. A *key function* is the first virtual function of a class, in declaration order, that is not inline, and is not pure virtual.

_____Note _____

You can disable export for specific classes by using __declspec(notshared).

See also

- __declspec(notshared) on page 4-29.
- **2.1.67** --export_defs_implicitly, --no_export_defs_implicitly

This option controls how dynamic symbols are exported.

Default

The default is --no_export_defs_implicitly.

Usage

Use the option --export_defs_implicitly to export definitions where the prototype is marked __declspec(dllimport).

See also

• __declspec(dllimport) on page 4-26.

2.1.68 --extended_initializers, --no_extended_initializers

These options enable and disable the use of extended constant initializers even when compiling with --strict or --strict_warnings.

When certain non-portable but widely supported constant initializers such as the cast of an address to an integral type are used, --extended_initializers causes the compiler to produce the same general warning concerning constant initializers that it normally produces in nonstrict mode, rather than specific errors stating that the expression must have a constant value or have arithmetic type.

Default

The default is --no_extended_initializers when compiling with --strict or --strict_warnings.

The default is --extended_initializers when compiling in non-strict mode.

See also

- --strict, --no strict on page 2-119
- --strict_warnings on page 2-120
- *Constant expressions* on page 3-10.

2.1.69 --feedback=filename

This option enables the efficient elimination of unused functions, and on ARMv4T architectures, enables reduction of compilation required for interworking.

Syntax

--feedback=filename

Where:

filename is the feedback file created by a previous execution of the ARM linker.

Usage

You can perform multiple compilations using the same feedback file. The compiler places each unused function identified in the feedback file into its own ELF section in the corresponding object file.

The feedback file contains information about a previous build. Because of this:

• The feedback file might be out of date. That is, a function previously identified as being unused might be used in the current source code. The linker removes the code for an unused function only if it is not used in the current source code.



- For this reason, eliminating unused functions using linker feedback is a safe optimization, but there might be a small impact on code size.
- The usage requirements for reducing compilation required for interworking are more strict than for eliminating unused functions. If you are reducing interworking compilation, it is critical that you keep your feedback file up to date with the source code that it was generated from.
- You have to do a full compile and link at least twice to get the maximum benefit
 from linker feedback. However, a single compile and link using feedback from a
 previous build is usually sufficient.

See also

- --split sections on page 2-118
- --feedback_type=type on page 2-39 in the Linker Reference Guide
- *Using linker feedback* on page 2-26 in the *Compiler User Guide*.

2.1.70 --force_new_nothrow, --no_force_new_nothrow

This option controls the behavior of new expressions in C++.

The C++ standard states that only a no throw operator new declared with throw() is permitted to return NULL on failure. Any other operator new is never permitted to return NULL and the default operator new throws an exception on failure.

If you use --force_new_nothrow, the compiler treats expressions such as new T(...args...), that use the global ::operator new or ::operator new[], as if they are new (std::nothrow) T(...args...).

 $-\mbox{--force_new_nothrow}$ also causes any class-specific operator \mbox{new} or any overloaded global operator \mbox{new} to be treated as no throw.

_____ Note _____

The option --force_new_nothrow is provided only as a migration aid for legacy source code that does not conform to the C++ standard. Its use is not recommended.

Mode

This option is effective only if the source language is C++.

Default

The default is --no_force_new_nothrow.

Example

```
struct S
{
    void* operator new(std::size_t);
    void* operator new[](std::size_t);
};
void *operator new(std::size_t, int);
With the --force_new_nothrow option in effect, this is treated as:
struct S
{
    void* operator new(std::size_t) throw();
    void* operator new[](std::size_t) throw();
};
void *operator new(std::size_t, int) throw();
```

See also

• *Using the ::operator new function* on page 5-13.

2.1.71 --forceinline

This option forces all inline functions to be treated as if they are qualified with __forceinline.

Inline functions are functions that are qualified with inline or __inline. In C++, inline functions are functions that are defined inside a struct, class, or union definition.

If you use --forceinline, the compiler always attempts to inline those functions, if possible. However, it does not inline a function if doing so causes problems. For example, a recursive function is inlined into itself only once.

See also

- --autoinline, --no_autoinline on page 2-17
- --inline, --no_inline on page 2-75
- __forceinline on page 4-6
- __inline on page 4-9
- *Managing inlining* on page 5-19 in the *Compiler User Guide*.

2.1.72 --fp16_format=format

This option enables the use of half-precision floating-point numbers as an optional extension to the VFPv3 architecture. If a format is not specified, use of the __fp16 data type is faulted by the compiler.

Syntax

--fp16_format=format

Where format is one of:

alternative An alternative to ieee that provides additional range, but has no NaN or

inifinity values.

ieee Half-precision binary floating-point format defined by IEEE 754r, a

revision to the IEEE 754 standard.

none This is the default setting. It is equivalent to not specifying a format and

means that the compiler faults use of the __fp16 data type.

See also

- *Intrinsics* on page E-4
- Half-precision floating-point number support on page 5-35 of the Compiler User Guide.

2.1.73 --fpmode=*mode1*

This option specifies the floating-point conformance, and sets library attributes and floating-point optimizations.

Syntax

--fpmode=mode1

Where model is one of:

ieee_full

All facilities, operations, and representations guaranteed by the IEEE standard are available in single and double-precision. Modes of operation can be selected dynamically at runtime.

This defines the symbols:

- __FP_IEEE
- __FP_FENV_EXCEPTIONS
- __FP_FENV_ROUNDING
- __FP_INEXACT_EXCEPTION

ieee fixed

IEEE standard with round-to-nearest and no inexact exceptions.

This defines the symbols:

__FP_IEEE

__FP_FENV_EXCEPTIONS

ieee_no_fenv

IEEE standard with round-to-nearest and no exceptions. This mode is stateless and is compatible with the Java floating-point arithmetic model.

This defines the symbol __FP_IEEE.

std

IEEE finite values with denormals flushed to zero, round-to-nearest, and no exceptions. This is compatible with standard C and C++ and is the default option.

Normal finite values are as predicted by the IEEE standard. However:

- NaNs and infinities might not be produced in all circumstances defined by the IEEE model. When they are produced, they might not have the same sign.
- The sign of zero might not be that predicted by the IEEE model.

fast

Perform more aggressive floating-point optimizations that might cause a small loss of accuracy to provide a significant performance increase. This option defines the symbol __FP_FAST.

This option results in behavior that is not fully compliant with the ISO C or C++ standard. However, numerically robust floating-point programs are expected to behave correctly.

A number of transformations might be performed, including:

Double-precision math functions might be converted to single
precision equivalents if all floating-point arguments can be exactly
represented as single precision values, and the result is immediately
converted to a single-precision value.

This transformation is only performed when the selected library contains the single-precision equivalent functions, for example, when the selected library is rvct or aeabi_qlibc.

For example:

```
float f(float a)
{
    return sqrt(a);
}
is transformed to
float f(float a)
{
    return sqrtf(a);
}.
```

- Double-precision floating-point expressions that are narrowed to single-precision are evaluated in single-precision when it is beneficial to do so. For example, float y = (float)(x + 1.0) is evaluated as float y = (float)x + 1.0f.
- Division by a floating-point constant is replaced by multiplication with the inverse. For example, x / 3.0 is evaluated as x * (1.0 / 3.0).
- It is not guaranteed that the value of errno is compliant with the ISO C or C++ standard after math functions have been called. This enables the compiler to inline the VFP square root instructions in place of calls to sqrt() or sqrtf().

Noto	

Initialization code might be required to enable the VFP. See *VFP support* on page 5-34 in the *Compiler User Guide* for more information.

See also

• ARM Application Note 133 - Using VFP with RVDS in install_directory\RVDS\Examples\...\vfpsupport.

2.1.74 --fpu=list

This option lists the supported FPU architecture names that you can use with the --fpu=name option.

Deprecated options are not listed.

See also

--fpu=name.

2.1.75 --fpu=name

This option enables you to determine the target FPU architecture.

If you specify this option, it overrides any implicit FPU option that appears on the command line, for example, where you use the --cpu option.

To obtain a full list of FPU architectures use the --fpu=list option.

Syntax

--fpu=name

Where name is one of:

none Selects no floating-point option. No floating-point code is to be used.

This produces an error if your code contains float types.

vfpv This is a synonym for vfpv2.

vfpv2 Selects a hardware vector floating-point unit conforming to architecture

VFPv2.

—— Note ———

If you enter armcc --thumb --fpu=vfpv2 on the command line, the compiler compiles as much of the code using the Thumb instruction set as possible, but hard floating-point sensitive functions are compiled to ARM code. In this case, the value of the predefine __thumb is not correct.

If you specify either vfp or vfpv2 with the --arm option for ARM C code you must use the __softfp keyword to ensure that your interworking ARM code is compiled to use software floating-point linkage.

vfpv3 Selects a hardware vector floating-point unit conforming to architecture VFPv3. VFPv3 is backwards compatible with VFPv2 except that VFPv3 cannot trap floating-point exceptions. vpfv3 is available in RealView Development Suite 3.0 and later only.

vfpv3_fp16 Selects a hardware vector floating-point unit conforming to architecture VFPv3 that also provides the half-precision extensions. vfpv3_fp16 is available in RealView Development Suite 4.0 and later only.

vfpv3_d16 Selects a hardware vector floating-point unit conforming to VFPv3-D16 architecture. vfpv3_d16 is available in RealView Development Suite 4.0 and later only.

vfpv3_d16_fp16

Selects a hardware vector floating-point unit conforming to VFPv3-D16 architecture, that also provides the half-precision extensions. vfpv3_d16_fp16 is available in RealView Development Suite 4.0 and later only.

Selects the software floating-point library fplib. This is the default if you do not specify a --fpu option, or if you select a CPU that does not have an FPU.

In previous releases of RVCT, if you specified --fpu=softvfp and a CPU with implicit VFP hardware, the linker chose a library that implemented the software floating-point calls using VFP instructions. This is no longer the case. If you require this legacy behavior, use --fpu=softvfp+vfp.

softvfp+vfpv2

Selects a floating-point library with software floating-point linkage that can use VFPv2 instructions. Select this option if you are interworking Thumb code with ARM code on a system that implements a VFP unit.

If you select this option:

- Compiling with --thumb behaves in a similar way to --fpu=softvfp except that it links with floating-point libraries that use VFP instructions.
- Compiling with --arm behaves in a similar way to --fpu=vfpv2
 except that all functions are given software floating-point linkage.
 This means that functions pass and return floating-point arguments
 and results in the same way as --fpu=softvfp, but use VFP
 instructions internally.

If you specify softvfp+vfpv2 with the --arm or --thumb option for C code, it ensures that your interworking floating-point code is compiled to use software floating-point linkage.

softvfp+vfpv3

Selects a floating-point library with software floating-point linkage that targets the VFPv3 architecture. Select this option if you are interworking Thumb code with ARM code on a system that implements a VFPv3 unit. softvfp+vfpv3 is is available in RealView Development Suite 3.0 and later only.

softvfp+vfpv3_fp16

Selects a floating-point library with software floating-point linkage that targets the VFPv3 architecture with half-precision floating-point extension support. softvfp+vfpv3_fp16 is available in RealView Development Suite 4.0 and later only.

softvfp+vfpv3_d16

Selects a floating-point library with software floating-point linkage that targets the VFPv3-D16 architecture. softvfp+vfpv3_d16 is available in RealView Development Suite 4.0 and later only.

softvfp+vfpv3_d16_fp16

Selects a floating-point library with software floating-point linkage that targets the VFPv3-D16 architecture, with half-precision floating-point extension support. softvfp+vfpv3_d16_fp16 is available in RealView Development Suite 4.0 and later only.

Usage

Any FPU explicitly selected using the --fpu option always overrides any FPU implicitly selected using the --cpu option. For example, the option cpu=ARM1136JF-S --fpu=softvfp generates code that uses the software floating-point library fplib, even though the choice of CPU implies the use of architecture VFPv2.

Restrictions

For every CPU that can be specified with --cpu=name, the compiler permits any hardware VFP architecture to be specified using --fpu=name, providing that the target architecture inside the processor core is 5TE or later. Beyond the scope of the compiler, additional architectural constraints apply. For example, VFPv3 is not supported with architectures prior to ARMv7.

The combination of --fpu and --cpu options permitted by the compiler does not necessarily translate to the actual device in use.

If you specify an FPU implicitly using the --cpu option, that is incompatible with an FPU chosen explicitly using --fpu, the compiler generates an error.

The compiler only generates scalar floating-point operations. If you want to use VFP vector operations, you must do this using assembly code.

NEON support is disabled for softvfp.

Default

If a VFP coprocessor is present, VFP instructions are generated. If there is no VFP corprocessor, the compiler generates code that makes calls to the software floating-point library fplib to carry out floating-point operations.

——— Note -	
------------	--

By default, some choices of processor or architecture imply the selection of a particular floating-point unit. For example, the option --cpu ARM1136JF-S implies the option --fpu vfpv2.

- --*arm* on page 2-8
- --cpu=name on page 2-30
- --thumb on page 2-122
- __*softfp* on page 4-15
- *Using floating-point arithmetic* on page 5-31 in the *Compiler User Guide*
- Floating-point build options on page 2-5 in the Developer Guide.

2.1.76 --friend_injection, --no_friend_injection

This option controls the visibility of friend declarations in C++.

In C++, it controls whether or not the name of a class or function that is declared only in friend declarations is visible when using the normal lookup mechanisms.

When friend names are declared, they are visible to these lookups. When friend names are not declared as required by the standard, function names are visible only when using argument-dependent lookup, and class names are never visible.

Note	
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The option --friend_injection is provided only as a migration aid for legacy source code that does not conform to the C++ standard. Its use is not recommended.

Mode

This option is effective only if the source language is C++.

Default

The default is --no_friend_injection.

See also

• *friend* on page 3-15.

2.1.77 -q

This option enables the generation of debug tables for the current compilation.

The compiler produces the same code regardless of whether -g is used. The only difference is the existence of debug tables.

Using -g does not affect optimization settings. By default, using the -g option alone is equivalent to:

```
-q --dwarf3 --debug_macros
```

- --debug, --no_debug on page 2-37
- --debug_macros, --no_debug_macros on page 2-37
- --dwarf2 on page 2-51
- --dwarf3 on page 2-51

• -*Onum* on page 2-96.

2.1.78 --global_reg=reg_name[, reg_name,...]

This option treats the specified register names as fixed registers.

Syntax

```
--global_reg=reg_name[, reg_name,...]
```

Where *reg_name* is the APCS or TPCS name of the register, denoted by an integer value in the range 1 to 8.

Register names 1 to 8 map sequentially onto registers r4 to r11.

Restrictions

This option has the same restrictions as the __global_reg storage class specifier.

Example

--global_reg=1,4,5 // reserve registers r4, r7 and r8 respectively.

See also

- __global_reg on page 4-7
- *ARM Software Development Toolkit Reference Guide.*

2.1.79 --qnu

This option enables the GNU compiler extensions supported by the ARM compiler. The version of GCC the extensions are compatible with can be determined by inspecting the predefined macros __GNUC__ and __GNUC_MINOR__.

- --*c90* on page 2-22
- -c99 on page 2-22
- --*cpp* on page 2-30
- --gnu_defaults on page 2-68
- --strict, --no_strict on page 2-119
- *GNU language extensions* on page 3-25
- *Compiler predefines* on page 4-198.

2.1.80 --gnu_defaults

This option alters the default settings of certain other options to match the default behavior found in GCC. Platform-specific settings, such as those targeting ARM Linux, are unaffected.

Usage

When you use --arm_linux and other ARM Linux-targeting options, --gnu_defaults is automatically implied.

--gnu_defaults does not imply specific targeting of ARM Linux.

When you use --gnu_defaults, the following options are enabled:

- --allow_null_this
- --gnu
- --no_debug_macros
- --no_hide_all
- --no_implicit_include
- --signed_bitfields
- --wchar32.
- --gnu does not set these defaults. It only enables the GNU compiler extensions.

See also

- --allow_null_this, --no_allow_this on page 2-3
- --arm_linux on page 2-9
- --debug_macros, --no_debug_macros on page 2-37
- -- *gnu* on page 2-67
- --hide all, --no hide all on page 2-71
- --implicit_include, --no_implicit_include on page 2-73
- --signed_bitfields, --unsigned_bitfields on page 2-116
- --wchar32 on page 2-135.

2.1.81 --gnu_instrument, --no_gnu_instrument

This option inserts GCC-style instrumentation calls for profiling entry and exit to functions.

Usage

After function entry and before function exit, the following profiling functions are called with the address of the current function and its call site:

```
void __cyg_profile_func_enter(void *current_func, void *callsite);
void __cyg_profile_func_exit(void *current_func, void *callsite);
```

Restrictions

```
You must provide definitions of __cyg_profile_func_enter() and __cyg_profile_func_exit().

It is necessary to explicitly mark __cyg_profile_func_enter() and
```

__cyg_profile_func_exit() with __attribute__((no_instrument_function)).

See also

• __attribute__((no_instrument_function)) on page 4-35.

2.1.82 --qnu_version=version

This option attempts to make the compiler compatible with a particular version of GCC.

Syntax

```
--gnu_version=version
```

Where *version* is a decimal number denoting the version of GCC that you are attempting to make the compiler compatible with.

Mode

This option is for when GNU compatibility mode is being used.

Usage

This option is for expert use. It is provided for dealing with legacy code. You are not normally required to use it.

Default

In RVCT v4.0, the default is 40200. This corresponds to GCC version 4.2.0.

Example

--gnu_version=30401 makes the compiler compatible with GCC 3.4.1 as far as possible.

See also

- --arm_linux_configure on page 2-12
- -- *gnu* on page 2-67.

2.1.83 --guiding_decls, --no_guiding_decls

This option enables or disables the recognition of guiding declarations for template functions in C++.

A *guiding declaration* is a function declaration that matches an instance of a function template but has no explicit definition because its definition derives from the function template.

If --no_guiding_decls is combined with --old_specializations, a specialization of a non-member template function is not recognized. It is treated as a definition of an independent function.



The option --guiding_decls is provided only as a migration aid for legacy source code that does not conform to the C++ standard. Its use is not recommended.

Mode

This option is effective only if the source language is C++.

Default

The default is --no_quiding_decls.

Example

```
template <class T> void f(T)
{
    ...
}
void f(int);
```

When regarded as a guiding declaration, f(int) is an instance of the template. Otherwise, it is an independent function so you must supply a definition.

See also

- --apcs=qualifer...qualifier on page 2-4
- --old_specializations, --no_old_specializations on page 2-98.

2.1.84 --help

This option displays a summary of the main command-line options.

This is the default if you do not specify any options or source files.

See also

- --show_cmdline on page 2-116.
- --vsn on page 2-134

2.1.85 --hide_all, --no_hide_all

This option enables you to control symbol visibility when building SVr4 shared objects.

Usage

Use --no_hide_all to force the compiler to use STV_DEFAULT visibility for all extern variables and functions if they do not use __declspec(dll*) or __attribute__((visibility("visibility_type"))). This also forces them to be preemptible at runtime by a dynamic loader.

When building a System V or ARM Linux shared library, use --no_hide_all together with --apcs /fpic.

Default

The default is --hide_all.

- --apcs=qualifer...qualifier on page 2-4
- attribute ((visibility("visibility type"))) on page 4-40
- __attribute__((visibility("visibility_type"))) on page 4-55
- __declspec(dllexport) on page 4-24
- __declspec(dllimport) on page 4-26
- --gnu_defaults on page 2-68
- Symbol visibility on page 4-5 in the Linker Reference Guide
- --symver_script=file on page 2-90 in the Linker Reference Guide.

2.1.86 -Idir[,dir,...]

This option adds the specified directory, or comma-separated list of directories, to the list of places that are searched to find included files.

If you specify more than one directory, the directories are searched in the same order as the -I options specifying them.

Syntax

-Idir[,dir,...]

Where:

dir[,dir,...]

is a comma-separated list of directories to be searched for included files.

At least one directory must be specified.

When specifying multiple directories, do not include spaces between commas and directory names in the list.

See also

- -*Jdir*[,*dir*,...] on page 2-77
- --kandr include on page 2-78
- --preinclude=filename on page 2-105
- --sys_include on page 2-121
- Header files on page 2-14 in the Compiler User Guide.

2.1.87 --ignore_missing_headers

This option instructs the compiler to print dependency lines for header files even if the header files are missing.

Warning and error messages on missing header files are suppressed, and compilation continues where it would otherwise fail in this case.

Usage

This option is used for automatically updating makefiles. It is analogous to the GCC -MG command-line option.

- --depend=filename on page 2-40
- --depend_format=string on page 2-41

- --depend_system_headers, --no_depend_system_headers on page 2-42
- --depend_target=target on page 2-43
- -*M* on page 2-88
- --md on page 2-89
- --phony_targets on page 2-103.

2.1.88 --implicit_include, --no_implicit_include

This option controls the implicit inclusion of source files as a method of finding definitions of template entities to be instantiated in C++.

Mode

This option is effective only if the source language is C++.

Default

The default is --implicit_include.

See also

- --implicit_include_searches, --no_implicit_include_searches
- *Implicit inclusion* on page 5-15.

2.1.89 --implicit_include_searches, --no_implicit_include_searches

This option controls how the compiler searches for implicit include files for templates in C++.

When the option --implicit_include_searches is selected, the compiler uses the search path to look for implicit include files based on partial names of the form *filename*.*. The search path is determined by -I, -J, and the RVCT40INC environment variable.

When the option --no_implicit_include_searches is selected, the compiler looks for implicit include files based on the full names of files, including path names.

Mode

This option is effective only if the source language is C++.

Default

The default is --no_implicit_include_searches.

See also

- -*Idir*[,*dir*,...] on page 2-72
- --implicit_include, --no_implicit_include on page 2-73
- -*Jdir*[,*dir*,...] on page 2-77
- Implicit inclusion on page 5-15
- The search path on page 2-15 in the Compiler User Guide.

2.1.90 --implicit_typename, --no_implicit_typename

This option controls the implicit determination, from context, whether a template parameter dependent name is a type or nontype in C++.

_____ Note _____

The option --implicit_typename is provided only as a migration aid for legacy source code that does not conform to the C++ standard. Its use is not recommended.

Mode

This option is effective only if the source language is C++.

Default

The default is --no_implicit_typename.

Mata	
——Note	

The $--implicit_typename$ option has no effect unless you also specify $--no_parse_templates$.

See also

- --dep_name, --no_dep_name on page 2-39
- --parse_templates, --no_parse_templates on page 2-100
- *Template instantiation* on page 5-15.

2.1.91 --info=totals

This option instructs the compiler to give totals of the object code and data size for each object file.

The compiler returns the same totals that fromelf returns when fromelf -z is used, in a similar format. The totals include embedded assembler sizes when embedded assembly exists in the source code.

Example

Code (inc. data)	RO Data	RW Data	ZI Data	Debug	File Name
3308 1556	0	44	10200	8402	dhry_1.o
Code (inc. data)	RO Data	RW Data	ZI Data	Debug	File Name
416 28	0	0	0	7722	dhry_2.o

The (inc. data) column gives the size of constants, string literals, and other data items used as part of the code. The Code column, shown in the example, *includes* this value.

See also

- --*list* on page 2-82
- --info=topic[,topic,...] on page 2-44 in the Linker Reference Guide
- *Code metrics* on page 5-10 in the *Compiler User Guide*
- *Using command-line options* on page 2-7 in the *Utilities Guide*.

2.1.92 --inline, --no_inline

This option enables or disables the inlining of functions. Disabling the inlining of functions can help to improve the debug illusion.

When the option --inline is selected, the compiler considers inlining each function. Compiling your code with --inline does not guarantee that all functions are inlined. See *When is it practical for the compiler to inline?* on page 5-19 in the *Compiler User Guide* for more information about how the compiler decides to inline functions.

When the option --no_inline is selected, the compiler does not attempt to inline functions, other than functions qualified with __forceinline.

Default

The default is --inline.

- --autoinline, --no_autoinline on page 2-17
- --forceinline on page 2-58
- -*Onum* on page 2-96
- -Ospace on page 2-99
- *-Otime* on page 2-99

- __forceinline on page 4-6
- __inline on page 4-9
- Using linker feedback on page 2-26 in the Compiler User Guide
- Function inlining on page 5-18 in the Compiler User Guide.

2.1.93 --interface_enums_are_32_bit

This option helps to provide compatibility between external code interfaces, with regard to the size of enumerated types.

Usage

It is not possible to link an object file compiled with --enum_is_int, with another object file that is compiled without --enum_is_int. The linker is unable to determine whether or not the enumerated types are used in a way that affects the external interfaces, so on detecting these build differences, it produces a warning or an error. You can avoid this by compiling with --interface_enums_are_32_bit. The resulting object file can then be linked with any other object file, without the linker-detected conflict that arises from different enumeration type sizes.



When you use this option, you are making a promise to the compiler that all the enumerated types used in your external interfaces are 32 bits wide. For example, if you ensure that every enum you declare includes at least one value larger than 2 to the power of 16, the compiler is forced to make the enum 32 bits wide, whether or not you use --enum_is_int. It is up to you to ensure that the promise you are making to the compiler is true. (Another method of satisfying this condition is to ensure that you have no enums in your external interface.)

See also

• --enum is int on page 2-53.

2.1.94 --interleave

This option interleaves C or C++ source code line by line as comments within an assembly listing generated using the --asm option or -S option.

Usage

The action of --interleave depends on the combination of options used:

Table 2-4 Compiling with the ---interleave option

Compiler option	Action
asminterleave	Writes a listing to a file of the disassembly of the compiled source, interleaving the source code with the disassembly. The link step is also performed, unless the -c option is used. The disassembly is written to a text file whose name defaults to the name of the input file with the filename extension .txt
-Sinterleave	Writes a listing to a file of the disassembly of the compiled source, interleaving the source code with the disassembly. The disassembly is written to a text file whose name defaults to the name of the input file with the filename extension .txt

Restrictions

- You cannot reassemble an assembly listing generated with --asm --interleave or -S --interleave.
- Preprocessed source files contain #line directives. When compiling preprocessed
 files using --asm --interleave or -S --interleave, the compiler searches for the
 original files indicated by any #line directives, and uses the correct lines from
 those files. This ensures that compiling a preprocessed file gives exactly the same
 output and behavior as if the original files were compiled.

If the compiler cannot find the original files, it is unable to interleave the source. Therefore, if you have preprocessed source files with #line directives, but the original unpreprocessed files are not present, you must remove all the #line directives before you compile with --interleave.

See also

- --asm on page 2-16
- -S on page 2-114.

2.1.95 -Jdir[,dir,...]

This option adds the specified directory, or comma-separated list of directories, to the list of system includes.

Warnings and remarks are suppressed, even if --diaq_error is used.

The RVCT40INC environment variable is set to the default system include path unless you use -J to override it. Angle-bracketed include files are searched for first in the list of system includes, followed by any include list specified with the option -I.



On Windows systems, you must enclose RVCT40INC in double quotes if you specify this environment variable on the command line, because the default path defined by the variable contains spaces. For example:

```
armcc -J"%RVCT40INC%" -c main.c
```

Syntax

-Jdir[,dir,...]

Where:

dir[, *dir*,...]

is a comma-separated list of directories to be added to the list of system includes.

At least one directory must be specified.

When specifying multiple directories, do not include spaces between commas and directory names in the list.

See also

- -*Idir[,dir,...]* on page 2-72
- --kandr_include
- --preinclude=filename on page 2-105
- --sys include on page 2-121
- *Header files* on page 2-14 in the *Compiler User Guide*.

2.1.96 --kandr include

This option ensures that Kernighan and Ritchie search rules are used for locating included files.

The current place is defined by the original source file and is not stacked. If you do not use this option, Berkeley-style searching is used.

- -*Idir*[,*dir*,...] on page 2-72
- -Jdir[,dir,...] on page 2-77

- --preinclude=filename on page 2-105
- --sys_include on page 2-121
- *Header files* on page 2-14 in the *Compiler User Guide*
- The current place on page 2-14 in the Compiler User Guide.

2.1.97 -Lopt

This option specifies command-line options to pass to the linker when a link step is being performed after compilation. Options can be passed when creating a partially-linked object or an executable image.

Syntax

-Lopt

Where:

opt

is a command-line option to pass to the linker.

Restrictions

If an unsupported Linker option is passed to it using -L, an error is generated.

Example

armcc main.c -L--map

See also

- -*Aopt* on page 2-2
- --show_cmdline on page 2-116.

2.1.98 --library_interface=*lib*

This option enables the generation of code that is compatible with the selected library type.

Syntax

--library_interface=lib

Where 1ib is one of:

rvct

Specifies that the compiler output works with the RVCT runtime libraries.

rvct_c90	Behaves similarly tolibrary_interface=rvct. The difference is that references in the input source code to function names that are not reserved by C90, are not modified by the compiler. Otherwise, some C99 math.h function names might be prefixed withhardfp_, for examplehardfp_tgamma.
aeabi_clib90	Specifies that the compiler output works with any ISO C90 library compliant with the <i>ARM Embedded Application Binary Interface</i> (AEABI).
aeabi_clib99	Specifies that the compiler output works with any ISO C99 library compliant with the <i>ARM Embedded Application Binary Interface</i> (AEABI).
aeabi_clib	Specifies that the compiler output works with any ISO C library compliant with the <i>ARM Embedded Application Binary Interface</i> (AEABI).
	Selecting the optionlibrary_interface=aeabi_clib is equivalent to specifying eitherlibrary_interface=aeabi_clib90 orlibrary_interface=aeabi_clib99, depending on the choice of source language used.
	The choice of source language is dependent both on the command-line options selected and on the filename suffixes used.
aeabi_glibc	Specifies that the compiler output works with an AEABI-compliant version of the GNU C library.

Default

If you do not specify --library_interface, the compiler assumes --library_interface=rvct.

Usage

- Use the option --library_interface=rvct to exploit the full range of compiler and library optimizations when linking.
- Use an option of the form --library_interface=aeabi_* when linking with an ABI-compliant C library. Options of the form --library_interface=aeabi_* ensure that the compiler does not generate calls to any optimized functions provided by the RVCT C library.

Example

When your code calls functions provided by an embedded operating system that replace functions provided by the RVCT C library, compile your code with

--library_interface=aeabi_clib to disable calls to any special RVCT variants of the library functions replaced by the operating system.

See also

• ABI for the ARM Architecture compliance on page 1-4 in the Libraries and Floating Point Support Guide.

2.1.99 --library_type=*lib*

This option enables the selected library to be used at link time.

_____ Note ______
Use this option with the linker to override all other --library_type options.

Syntax

--library_type=lib

Where 1ib is one of:

standardlib Specifies that the full RVCT runtime libraries are selected at link time.

Use this option to exploit the full range of compiler optimizations when linking.

microlib Specifies that the C micro-library (microlib) is selected at link time.

Default

If you do not specify --library_type, the compiler assumes --library_type=standardlib.

- Building an application with microlib on page 3-4 in the Libraries and Floating Point Support Guide
- --library_type=lib on page 2-55 in the Linker Reference Guide.

2.1.100 --licretry

If you are using floating licenses, this option makes up to 10 attempts to obtain a license when you invoke armcc.

Usage

A typical build process, such as an overnight build, might contain many thousands of ARM compilation tool invocations. Each tool invocation involves network communication between the client (build) machine and the license server. However, if a temporary network glitch occurs when the build machine is attempting to obtain a license from the license server, the tool might fail to obtain a license. Therefore, you can use --licretry to attempt to overcome problems of this nature.

It is recommended that you place this option in the RVCT40_CCOPT environment variable. In this way, you do not have to modify your build files.

 Note	 	

Use this option only after you have ruled out any other problems with the network or the license server setup.

See also

- --licretry on page 2-56 in the Linker Reference Guide
- *Command syntax* on page 3-2 in the *Assembler Guide*
- --licretry on page 2-40 in the *Utilities Guide*
- Environment variables used by RVCT on page 1-7 in the RealView Compilation Tools Essentials Guide
- FLEXnet for ARM Tools License Management Guide.

2.1.101 --list

This option instructs the compiler to generate raw listing information for a source file. The name of the raw listing file defaults to the name of the input file with the filename extension .1st.

If you specify multiple source files on the command line then raw listing information is generated for only the first of the specified files.

Usage

Typically, raw listing information is used to generate a formatted listing. The raw listing file contains raw source lines, information on transitions into and out of include files, and diagnostics generated by the compiler. Each line of the listing file begins with any of the following key characters that identifies the type of line:

- N A normal line of source. The rest of the line is the text of the line of source.
- X The expanded form of a normal line of source. The rest of the line is the text of the line. This line appears following the N line, and only if the line contains nontrivial modifications. Comments are considered trivial modifications, and macro expansions, line splices, and trigraphs are considered nontrivial modifications. Comments are replaced by a single space in the expanded-form line.
- S A line of source skipped by an #if or similar. The rest of the line is text.

_____Note _____

The #else, #elseif, or #endif that ends a skip is marked with an N.

L Indicates a change in source position. That is, the line has a format similar to the # line-identifying directive output by the preprocessor:

L line-number "filename" key

where key can be:

- 1 For entry into an include file.
- 2 For exit from an include file.

Otherwise, *key* is omitted. The first line in the raw listing file is always an L line identifying the primary input file. L lines are also output for #line directives where *key* is omitted. L lines indicate the source position of the following source line in the raw listing file.

R/W/E Indicates a diagnostic, where:

R Indicates a remark.

W Indicates a warning.

E Indicates an error.

The line has the form:

type "filename" line-number column-number message-text

where type can be R, W,or E.

Errors at the end of file indicate the last line of the primary source file and a column number of zero.

Command-line errors are errors with a filename of "<command line>". No line or column number is displayed as part of the error message.

Internal errors are errors with position information as usual, and message-text beginning with (Internal fault).

When a diagnostic message displays a list, for example, all the contending routines when there is ambiguity on an overloaded call, the initial diagnostic line is followed by one or more lines with the same overall format. However, the code letter is the lowercase version of the code letter in the initial line. The source position in these lines is the same as that in the corresponding initial line.

Example

```
/* main.c */
#include <stdbool.h>
int main(void)
{
    return(true);
}
```

Compiling this code with the option --list produces the raw listing file:

```
L 1 "main.c"
N#include <stdbool.h>
L 1 "...\include\...\stdbool.h" 1
N/* stdbool.h */
N
N #ifndef __cplusplus /* In C++, 'bool', 'true' and 'false' and keywords */
     #define bool Bool
     #define true 1
     #define false 0
N #endif
I 2 "main.c" 2
Nint main(void)
NΥ
N
    return(true):
Χ
    return(1);
N}
```

See also

• --asm on page 2-16

- -c on page 2-21
- --depend=filename on page 2-40
- --depend_format=string on page 2-41
- --info=totals on page 2-74
- --interleave on page 2-76
- --md on page 2-89
- -S on page 2-114
- Severity of diagnostic messages on page 6-3 in the Compiler User Guide.

2.1.102 --list_macros

This option lists macro definitions to stdout after processing a specified source file. The listed output contains macro definitions that are used on the command line, predefined by the compiler, and found in header and source files, depending on usage.

Usage

To list macros that are defined on the command line, predefined by the compiler, and found in header and source files, use --list_macros with a non-empty source file.

To list only macros predefined by the compiler and specified on the command line, use --list_macros with an empty source file.

Restrictions

Code generation is suppressed.

See also

- Compiler predefines on page 4-198
- -Dname[(parm-list)][=def] on page 2-35
- -*E* on page 2-52
- --show_cmdline on page 2-116
- --via=filename on page 2-132.

2.1.103 --littleend

This option instructs to the compiler to generate code for an ARM processor using little-endian memory.

With little-endian memory, the least significant byte of a word has the lowest address.

Default

The compiler assumes --littleend unless --bigend is explicitly specified.

See also

• *--bigend* on page 2-17.

2.1.104 --locale=lang_country

This option switches the default locale for source files to the one you specify in *lang_country*.

Syntax

```
--locale=lang_country
```

Where:

lang_country is the new default locale.

Use this option in combination with --multibyte_chars.

Restrictions

The locale name might be case-sensitive, depending on the host platform.

The permitted settings of locale are determined by the host platform.

Ensure that you have installed the appropriate locale support for the host platform.

Example

To compile Japanese source files on an English-based Windows workstation, use:

```
--multibyte_chars --locale=japanese
```

and on a UNIX workstation use:

```
--multibyte_chars --locale=ja_JP
```

- --message_locale=lang_country[.codepage] on page 2-90
- --multibyte_chars, --no_multibyte_chars on page 2-92.

2.1.105 -- loose_implicit_cast

This option makes illegal implicit casts legal, such as implicit casts of a non-zero integer to a pointer.

Example

int *p = 0x8000;

Compiling this example without the option --loose_implicit_cast, generates an error.

Compiling this example with the option --loose_implicit_cast, generates a warning message, that you can suppress.

2.1.106 --lower_ropi, --no_lower_ropi

This option enables or disables less restrictive C when compiling with --apcs=/ropi.

Default

The default is --no_lower_ropi.

Note	
------	--

If you compile with --lower_ropi, then the static initialization is done at runtime by the C++ constructor mechanism for both C and C++ code. This enables these static initializations to work with ROPI code.

See also

- --apcs=qualifer...qualifier on page 2-4
- --lower rwpi, --no lower rwpi
- *Position independence qualifiers* on page 2-24 in the *Compiler User Guide*.

2.1.107 --lower_rwpi, --no_lower_rwpi

This option enables or disables less restrictive C and C++ when compiling with --apcs=/rwpi.

Default

The default is --lower_rwpi.

If you compile with --lower_rwpi, then the static initialization is done at runtime by the C++ constructor mechanism, even for C. This enables these static initializations to work with RWPI code.

See also

- --apcs=qualifer...qualifier on page 2-4
- --lower_ropi, --no_lower_ropi on page 2-87
- *Position independence qualifiers* on page 2-24 in the *Compiler User Guide*.

2.1.108 -- ltcq

This option instructs the compiler to create objects in an intermediate format so that link-time code generation optimizations can be performed. The optimizations applied include cross-module inlining to improve performance, and sharing of base addresses to reduce code size.



This option might significantly increase link time and memory requirements. For large applications it is recommended that you do the code generation in partial link steps with a subset of the objects.

Example

The following example shows how to use the --ltcg option.

```
armcc -c --ltcg file1.c
armcc -c --ltcg file2.c
armlink --ltcg file1.o file2.o -o prog.axf
```

See also

- --multifile, --no_multifile on page 2-92
- -Onum on page 2-96
- --ltcg on page 2-59 in the Linker Reference Guide.

2.1.109 -M

This option instructs the compiler to produce a list of makefile dependency lines suitable for use by a make utility.

The compiler executes only the preprocessor step of the compilation. By default, output is on the standard output stream.

If you specify multiple source files, a single dependency file is created.

If you specify the -o *filename* option, the dependency lines generated on standard output make reference to filename.o, and not to source.o. However, no object file is produced with the combination of -M -o *filename*.

Use the --md option to generate dependency lines and object files for each source file.

Example

You can redirect output to a file by using standard UNIX and MS-DOS notation, for example:

armcc -M source.c > Makefile

See also

- -C on page 2-22
- --depend=filename on page 2-40
- --depend_system_headers, --no_depend_system_headers on page 2-42
- -*E* on page 2-52
- --md
- -o filename on page 2-95.

2.1.110 --md

This option instructs the compiler to compile the source and write makefile dependency lines to a file.

The output file is suitable for use by a make utility.

The compiler names the file *filename*.d, where *filename* is the name of the source file. If you specify multiple source files, a dependency file is created for each source file.

- --depend=filename on page 2-40
- --depend_format=string on page 2-41
- --depend_system_headers, --no_depend_system_headers on page 2-42
- -*M* on page 2-88
- -o filename on page 2-95.

2.1.111 --message_locale=lang_country[.codepage]

This option switches the default language for the display of error and warning messages to the one you specify in *lang_country* or *lang_country.codepage*.

Syntax

```
--message_locale=lang_country[.codepage]
```

Where:

lang_country[.codepage]

is the new default language for the display of error and warning messages.

The permitted languages are independent of the host platform.

The following settings are supported:

- en_US
- zh_CN
- ko_KR
- ja_JP.

Default

If you do not specify --message_locale, the compiler assumes --message_locale=en_US.

Restrictions

Ensure that you have installed the appropriate locale support for the host platform.

The locale name might be case-sensitive, depending on the host platform.

The ability to specify a codepage, and its meaning, depends on the host platform.

Errors

If you specify a setting that is not supported, the compiler generates an error message.

Example

To display messages in Japanese, use:

```
--message_locale=ja_JP
```

See also

- --locale=lang_country on page 2-86
- --multibyte_chars, --no_multibyte_chars on page 2-92.

2.1.112 --min_array_alignment=opt

This option enables you to specify the minimum alignment of arrays.

Syntax

```
--min_array_alignment=opt
```

Where:

opt specifies the minimum alignment of arrays. The value of opt is:

- 1 byte alignment, or unaligned
- 2 two-byte, halfword alignment
- 4 four-byte, word alignment
- 8 eight-byte, doubleword alignment.

Default

If you do not specify a --min_array_alignment option, the compiler assumes --min_array_alignment=1.

Example

Compiling the following code with --min_array_alignment=8 gives the alignment described in the comments:

```
char arr_c1[1];  // alignment == 8
char c1;  // alignment == 1
```

See also

- __*align* on page 4-2
- __ALIGNOF__ on page 4-4.

2.1.113 --mm

This option has the same effect as -M --no_depend_system_headers.

See also

- --depend_system_headers, --no_depend_system_headers on page 2-42
- -*M* on page 2-88.

2.1.114 --multibyte_chars, --no_multibyte_chars

This option enables or disables processing for multibyte character sequences in comments, string literals, and character constants.

Default

The default is --no_multibyte_chars.

Usage

Multibyte encodings are used for character sets such as the Japanese *Shift-Japanese Industrial Standard* (Shift-JIS).

See also

- --locale=lang_country on page 2-86
- --message_locale=lang_country[.codepage] on page 2-90.

2.1.115 --multifile, --no_multifile

This option enables or disables multifile compilation.

When --multifile is selected, the compiler performs optimizations across all files specified on the command line, instead of on each individual file. The specified files are compiled into one single object file.

The combined object file is named after the first source file you specify on the command line. To specify a different name for the combined object file, use the -o filename option.

An empty object file is created for each subsequent source file specified on the command line to meet the requirements of standard make systems.

Note	
Compiling withmultifile has no effect if only a single source command line.	file is specified on the

Default

The default is --no_multifile, unless the option -03 is specified.

If the option -03 is specified, then the default is --multifile.

Usage

When --multifile is selected, the compiler might be able to perform additional optimizations by compiling across several source files.

There is no limit to the number of source files that can be specified on the command line, but ten files is a practical limit, because --multifile requires large amounts of memory while compiling. For the best optimization results, choose small groups of functionally related source files.

Example

```
armcc -c --multifile test1.c ... testn.c -o test.o
```

The resulting object file is named test.o, instead of test1.c, and empty object files test2.o to testn.o are created for each source file test1.c ... testn.c specified on the command line.

See also

- -c on page 2-21
- --default_extension=ext on page 2-38
- --*ltcg* on page 2-88
- -o filename on page 2-95
- -*Onum* on page 2-96
- --whole_program on page 2-136.

2.1.116 --multiply_latency=cycles

This option tells the compiler the number of cycles used by the hardware multiplier.

Syntax

```
--multiply_latency=cycles
```

Where *cycles* is the number of cycles used.

Usage

Use this option to tell the compiler how many cycles the MUL instruction takes to use the multiplier block and related parts of the chip. Until finished, these parts of the chip cannot be used for another instruction and the result of the MUL is not available for any later instructions to use.

It is possible that a processor might have two or more multiplier options that are set for a given hardware implementation. For example, one implementation might be configured to take one cycle to execute. The other implementation might take 33 cycles to execute. This option is used to convey the correct number of cycles for a given processor.

Example

--multiply_latency=33

See also

Cortex[™]-M1 Technical Reference Manual.

2.1.117 -- narrow volatile bitfields

The AEABI specifies that volatile bitfields are accessed as the size of their container type. However, some versions of GCC instead use the smallest access size that contains the entire bitfield. --narrow_volatile_bitfields emulates this non-AEABI compliant behavior.

See also

 Application Binary Interface (ABI) for the ARM Architecture, http://infocenter.arm.com/help/index.jsp?topic=/com.arm.doc.subset.swdev.abi/index.html

2.1.118 --nonstd_qualifier_deduction, --no_nonstd_qualifier_deduction

This option controls whether or not nonstandard template argument deduction is to be performed in the qualifier portion of a qualified name in C++.

With this feature enabled, a template argument for the template parameter T can be deduced in contexts like A<T>::B or T::B. The standard deduction mechanism treats these as non deduced contexts that use the values of template parameters that were either explicitly specified or deduced elsewhere.

The option --nonstd_qualifier_deduction is provided only as a migration aid for legacy source code that does not conform to the C++ standard. Its use is not recommended.

Mode

This option is effective only if the source language is C++.

Default

The default is --no_nonstd_qualifier_deduction.

2.1.119 -o filename

This option specifies the name of the output file. The full name of the output file produced depends on the combination of options used, as described in Table 2-5 and Table 2-6 on page 2-96.

Syntax

If you specify a -o option, the compiler names the output file according to the conventions of Table 2-5.

Table 2-5 Compiling with the -o option

Compiler option	Action	Usage notes
-0-	writes output to the standard output stream	filename isS is assumed unless -E is specified.
-o filename	produces an executable image with name filename	
-c -o filename	produces an object file with name filename	
-S -o filename	produces an assembly language file with name filename	
-E -o filename	produces a file containing preprocessor output with name <i>filename</i>	

If you do not specify a -o option, the compiler names the output file according to the conventions of Table 2-6.

Table 2-6 Compiling without the -o option

Compiler option	Action	Usage notes
-C	produces an object file whose name defaults to the name of the input file with the filename extension .0	
-\$	produces an output file whose name defaults to the name of the input file with the filename extension .s	
-E	writes output from the preprocessor to the standard output stream	
(No option)	produces an executable image with the default name ofimage.axf	none of -o, -c, -E or -S is specified on the command line

_____Note _____

This option overrides the --default_extension option.

See also

- --asm on page 2-16
- -c on page 2-21
- --default_extension=ext on page 2-38
- --depend=filename on page 2-40
- --depend_format=string on page 2-41
- -*E* on page 2-52
- --interleave on page 2-76
- -- *list* on page 2-82
- --md on page 2-89
- -S on page 2-114.

2.1.120 -Onum

This option specifies the level of optimization to be used when compiling source files.

Syntax

-0num

Where *num* is one of the following:

- Minimum optimization. Turns off most optimizations. It gives the best possible debug view and the lowest level of optimization.
- 1 Restricted optimization. Removes unused inline functions and unused static functions. Turns off optimizations that seriously degrade the debug view. If used with --debug, this option gives a satisfactory debug view with good code density.
- High optimization. If used with --debug, the debug view might be less satisfactory because the mapping of object code to source code is not always clear.

This is the default optimization level.

- Maximum optimization. -03 performs the same optimizations as -02 however the balance between space and time optimizations in the generated code is more heavily weighted towards space or time compared with -02. That is:
 - -03 -0time aims to produce faster code than -02 -0time, at the risk of increasing your image size
 - -03 -0space aims to produce smaller code than -02 -0space, but performance might be degraded.

In addition, -03 performs extra optimizations that are more aggressive, such as:

- High-level scalar optimizations, including loop unrolling, for -03
 -0time. This can give significant performance benefits at a small code size cost, but at the risk of a longer build time.
- More aggressive inlining and automatic inlining for -03 -0time.
- Multifile compilation by default.

Note
The performance of floating-point code can be influenced by selecting an appropriate
numerical model using thefpmode option.

Note
Do not rely on the implementation details of

Do not rely on the implementation details of these optimizations, because they might change in future releases.

Default

If you do not specify -0num, the compiler assumes -02.

See also

- --autoinline, --no_autoinline on page 2-17
- --debug, --no_debug on page 2-37
- --forceinline on page 2-58
- --fpmode=model on page 2-59
- --inline, --no_inline on page 2-75
- --*ltcg* on page 2-88
- --multifile, --no_multifile on page 2-92
- -Ospace on page 2-99
- -*Otime* on page 2-99
- *Optimizing code* on page 5-2 in the *Compiler User Guide*.

2.1.121 --old_specializations, --no_old_specializations

This option controls the acceptance of old-style template specializations in C++.

Old-style template specializations do not use the template syntax.

Note —
The optionold_specializations is provided only as a migration aid for legacy source
code that does not conform to the C++ standard. Its use is not recommended.

Mode

This option is effective only if the source language is C++.

Default

The default is --no_old_specializations.

2.1.122 -Ospace

This option instructs the compiler to perform optimizations to reduce image size at the expense of a possible increase in execution time.

Use this option if code size is more critical than performance. For example, when the -0space option is selected, large structure copies are done by out-of-line function calls instead of inline code.

If required, you can compile the time-critical parts of your code with -0time, and the rest with -0space.

Default

If you do not specify either -Ospace or -Otime, the compiler assumes -Ospace.

See also

- -Otime
- -*Onum* on page 2-96
- #pragma Onum on page 4-67
- #pragma Ospace on page 4-68
- #pragma Otime on page 4-68.

2.1.123 -Otime

This option instructs the compiler to perform optimizations to reduce execution time at the expense of a possible increase in image size.

Use this option if execution time is more critical than code size. If required, you can compile the time-critical parts of your code with -0time, and the rest with -0space.

Default

If you do not specify -0time, the compiler assumes -0space.

Example

When the -0time option is selected, the compiler compiles:

while (expression) body;

as:

```
if (expression)
{
    do body;
    while (expression);
}
```

See also

- --multifile, --no_multifile on page 2-92
- -*Onum* on page 2-96
- -Ospace on page 2-99
- #pragma Onum on page 4-67
- #pragma Ospace on page 4-68
- #pragma Otime on page 4-68.

2.1.124 --parse_templates, --no_parse_templates

This option enables or disables the parsing of non class templates in their generic form in C++, that is, when the template is defined and before it is instantiated.

The option --no_parse_templates is provided only as a migration aid for legacy source code that does not conform to the C++ standard. Its use is not recommended.

Mode

This option is effective only if the source language is C++.

Default

The default is --parse_templates.

Note	

--no_parse_templates cannot be used with --dep_name, because parsing is done by default if dependent name processing is enabled. Combining these options generates an error.

- --dep_name, --no_dep_name on page 2-39
- *Template instantiation* on page 5-15.

2.1.125 --pch

This option instructs the compiler to use a PCH file if it exists, and to create a PCH file otherwise.

When the option --pch is specified, the compiler searches for a PCH file with the name *filename*.pch, where *filename*.* is the name of the primary source file. The compiler uses the PCH file *filename*.pch if it exists, and creates a PCH file named *filename*.pch in the same directory as the primary source file otherwise.

Restrictions

This option has no effect if you include either the option --use_pch=filename or the option --create_pch=filename on the same command line.

See also

- --create_pch=filename on page 2-34
- --pch_dir=dir
- --pch_messages, --no_pch_messages on page 2-102
- --pch_verbose, --no_pch_verbose on page 2-102
- --use_pch=filename on page 2-129
- #pragma hdrstop on page 4-64
- #pragma no_pch on page 4-67
- Precompiled header files on page 2-17 in the Compiler User Guide.

2.1.126 --pch_dir=*dir*

This option enables you to specify the directory where PCH files are stored. The directory is accessed whenever PCH files are created or used.

You can use this option with automatic or manual PCH mode.

Syntax

--pch_dir=dir

Where:

dir is the name of the directory where PCH files are stored.

Errors

If the specified directory *dir* does not exist, the compiler generates an error.

See also

- --create_pch=filename on page 2-34
- --pch on page 2-101
- --pch_messages, --no_pch_messages
- --pch_verbose, --no_pch_verbose
- --use_pch=filename on page 2-129
- #pragma hdrstop on page 4-64
- #pragma no_pch on page 4-67
- *Precompiled header files* on page 2-17 in the *Compiler User Guide*.

2.1.127 --pch_messages, --no_pch_messages

This option enables or disables the display of messages indicating that a PCH file is used in the current compilation.

Default

The default is --pch_messages.

See also

- --create_pch=filename on page 2-34
- --pch on page 2-101
- --pch_dir=dir on page 2-101
- --pch_verbose, --no_pch_verbose
- --use_pch=filename on page 2-129
- #pragma hdrstop on page 4-64
- #pragma no_pch on page 4-67
- Precompiled header files on page 2-17 in the Compiler User Guide.

2.1.128 --pch_verbose, --no_pch_verbose

This option enables or disables the display of messages giving reasons why a file cannot be precompiled.

In automatic PCH mode, this option ensures that for each PCH file that cannot be used for the current compilation, a message is displayed giving the reason why the file cannot be used.

Default

The default is --no_pch_verbose.

See also

- --create_pch=filename on page 2-34
- --pch on page 2-101
- --pch dir=dir on page 2-101
- --pch_messages, --no_pch_messages on page 2-102
- --use_pch=filename on page 2-129
- #pragma hdrstop on page 4-64
- #pragma no_pch on page 4-67
- *Precompiled header files* on page 2-17 in the *Compiler User Guide*.

2.1.129 --pending_instantiations=*n*

This option specifies the maximum number of concurrent instantiations of a template in C++.

Syntax

--pending_instantiations=n

Where:

n is the maximum number of concurrent instantiations permitted.If n is zero, there is no limit.

Mode

This option is effective only if the source language is C++.

Default

If you do not specify a --pending_instantations option, then the compiler assumes --pending_instantiations=64.

Usage

Use this option to detect runaway recursive instantiations.

2.1.130 --phony_targets

This option instructs the compiler to emit dummy makefile rules. These rules work around make errors that are generated if you remove header files without a corresponding update to the makefile.

This option is analogous to the GCC command-line option, -MP.

Example

Example output:

```
source.o: source.c
source.o: header.h
header.h:
```

See also

- --depend=filename on page 2-40
- --depend_format=string on page 2-41
- --depend system headers, --no depend system headers on page 2-42
- --depend_target=target on page 2-43
- --ignore_missing_headers on page 2-72
- -*M* on page 2-88
- --md on page 2-89

2.1.131 --pointer_alignment=num

This option specifies the unaligned pointer support required for an application.

Syntax

--pointer_alignment=num

Where *num* is one of:

- 1 Treats accesses through pointers as having an alignment of one, that is, byte-aligned or unaligned.
- 2 Treats accesses through pointers as having an alignment of at most two, that is, at most halfword aligned.
- Treats accesses through pointers as having an alignment of at most four, that is, at most word aligned.
- 8 Accesses through pointers have normal alignment, that is, at most doubleword aligned.

Usage

This option can help you port source code that has been written for architectures without alignment requirements. You can achieve finer control of access to unaligned data, with less impact on the quality of generated code, using the __packed qualifier.

Restrictions

De-aligning pointers might increase the code size, even on CPUs with unaligned access support. This is because only a subset of the load and store instructions benefit from unaligned access support. The compiler is unable to use multiple-word transfers or coprocessor-memory transfers, including hardware floating-point loads and stores, directly on unaligned memory objects.



- Code size might increase significantly when compiling for CPUs without hardware support for unaligned access, for example, pre-v6 architectures.
- This option does not affect the placement of objects in memory, nor the layout and padding of structures.

See also

- __packed on page 4-11
- #pragma pack(n) on page 4-68
- *Aligning data* on page 5-25 in the *Compiler User Guide*.

2.1.132 --preinclude=*filename*

This option instructs the compiler to include the source code of the specified file at the beginning of the compilation.

Syntax

--preinclude=filename

Where:

filename is the name of the file whose source code is to be included.

Usage

This option can be used to establish standard macro definitions. The *filename* is searched for in the directories on the include search list.

It is possible to repeatedly specify this option on the command line. This results in preincluding the files in the order specified.

Example

armcc --preinclude file1.h --preinclude file2.h -c source.c

See also

- -*Idir*[,*dir*,...] on page 2-72
- -Jdir[,dir,...] on page 2-77
- --kandr_include on page 2-78
- --sys_include on page 2-121
- Header files on page 2-14 in the Compiler User Guide.

2.1.133 --preprocessed

This option forces the preprocessor to handle files with .i filename extensions as if macros have already been substituted.

Usage

This option gives you the opportunity to use a different preprocessor. Generate your preprocessed code and then give the preprocessed code to the compiler in the form of a *filename*.i file, using --preprocessed to inform the compiler that the file has already been preprocessed.

Restrictions

This option only applies to macros. Trigraphs, line concatenation, comments and all other preprocessor items are preprocessed by the preprocessor in the normal way.

If you use --compile_all_input, the .i file is treated as a .c file. The preprocessor behaves as if no prior preprocessing has occurred.

Example

armcc --preprocessed foo.i -c -o foo.o

- --compile_all_input, --no_compile_all_input on page 2-24
- -*E* on page 2-52.

2.1.134 --profile=filename

This option instructs the compiler to use feedback from the ARM Profiler, to generate code that is smaller is size and faster in terms of performance.

Syntax

--profile=filename

Where:

filename is the name of an ARM Profiler analysis file.

Example

This example uses the ARM Profiler feedback provided in hello_001.apa when generating the code for hello.c.

armcc -c -O3 -Otime --profile=hello_001.apa hello.c

See also

• the ARM Profiler User Guide.

2.1.135 --project=*filename*, --no_project

The option --project=filename instructs the compiler to load the project template file specified by filename.

—— Note ———

To use filename as a default project file, set the RVDS_PROJECT environment variable to filename.

The option --no_project prevents the default project template file specified by the environment variable RVDS_PROJECT from being used.

Syntax

--project=filename

--no_project

Where:

filename is the name of a project template file.

Restrictions

Options from a project template file are only set when they do not conflict with options already set on the command line. If an option from a project template file conflicts with an existing command-line option, the command-line option takes precedence.

Example

Consider the following project template file:

When the RVDS_PROJECT environment variable is set to point to this file, the command:

```
armcc -c foo.c
```

results in an actual command line of:

```
armcc --cpu=ARM926EJ-S --fpu=VFPv2 -c foo.c
```

See also

- --reinitialize workdir on page 2-110
- --workdir=directory on page 2-136.

2.1.136 -- reassociate-saturation

This option enables more aggressive optimization when vectorizing loops that use saturating addition, by permitting reassociation of saturation arithmetic.

Restriction

Saturation addition is not associative, so enabling reassociation could affect the result with a reduction in accuracy.

Example

The following code does not vectorize unless --reassociate-saturation is specified.

```
#include <dspfns.h>
int f(short *a, short *b)
{
    int i;
    int r = 0;
    for (i = 0; i < 100; i++)
        r=L_mac(r,a[i],b[i]);
    return r;
}</pre>
```

2.1.137 --reduce_paths, --no_reduce_paths

This option enables or disables the elimination of redundant path name information in file paths.

When elimination of redundant path name information is enabled, the compiler removes sequences of the form xyz\.. from directory paths passed to the operating system. This includes system paths constructed by the compiler itself, for example, for #include searching.

Note	
Tiole	

The removal of sequences of the form xyz\.. might not be valid if xyz is a link.

Mode

This option is effective on Windows systems only.

Usage

Windows systems impose a 260 character limit on file paths. Where path names exist whose absolute names expand to longer than 260 characters, you can use the --reduce_paths option to reduce absolute path name length by matching up directories with corresponding instances of . . and eliminating the directory/. . sequences in pairs.

It is recommended that you avoid using long and deeply nested file paths, in preference to minimizing path lengths using the --reduce_paths option.

Default

The default is --no_reduce_paths.

Example

Compiling the file

..\..\xyzzy\xyzzy\objects\file.c

from the directory

\foo\bar\baz\gazonk\quux\bop

results in an actual path of

\foo\bar\baz\gazonk\quux\bop\..\..\xyzzy\xyzzy\objects\file.o

Compiling the same file from the same directory using the option --reduce_paths results in an actual path of

\foo\bar\baz\xyzzy\xyzzy\objects\file.c

2.1.138 --reinitialize_workdir

This option enables you to reinitialize the project template working directory set using --workdir.

When the directory set using --workdir refers to an existing working directory containing modified project template files, specifying this option causes the working directory to be deleted and recreated with new copies of the original project template files.

Restrictions

This option must be used in combination with the --workdir option.

See also

- --project=filename, --no project on page 2-107
- --workdir=directory on page 2-136.

2.1.139 --relaxed_ref_def, --no_relaxed_ref_def

This option permits multiple object files to use tentative definitions of global variables. Some traditional programs are written using this declaration style.

Usage

This option is primarily provided for compatibility with GNU C. It is not recommended for new application code.

Default

The default is strict references and definitions. (Each global variable can only be declared in one object file.) However, if you specify an ARM Linux configuration file on the command line and you use --translate_qcc, the default is --relaxed_ref_def.

Restrictions

This option is not available in C++.

See also

- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --translate_gcc on page 2-124
- Rationale for International Standard Programming Languages C.

2.1.140 -- remarks

This option instructs the compiler to issue remark messages, such as warning of padding in structures.

The compiler does not issue remarks by default.

See also

- --brief_diagnostics, --no_brief_diagnostics on page 2-19
- --diag_error=tag[,tag,...] on page 2-44
- --diag remark=tag[,tag,...] on page 2-45
- --diag_style={arm|ide|gnu} on page 2-46
- --diag_suppress=tag[,tag,...] on page 2-47
- --diag_warning=tag[,tag,...] on page 2-48
- --errors=filename on page 2-53
- -W on page 2-134
- --wrap diagnostics, --no wrap diagnostics on page 2-137.

2.1.141 --remove_unneeded_entities, --no_remove_unneeded_entities

These options control whether debug information is generated for all source symbols, or only for those symbols actually used.

Usage

Use --remove_unneeded_entities to reduce debug object and image file sizes. Faster linkage times can also be achieved.



Although --remove_unneeded_entities can help to reduce the amount of debug information generated per file, it has the disadvantage of reducing the number of debug sections that are common to many files. This reduces the number of common debug sections that the linker is able to remove at final link time, and can result in a final debug image that is larger than necessary. For this reason, use --remove_unneeded_entities only when necessary.

Restrictions

The effects of these options are restricted to debug information.

Default

Removal of unneeded entities is disabled by default.

See also

• The DWARF Debugging Standard, http://dwarfstd.org/

2.1.142 --restrict, --no_restrict

This option enables or disables the use of the C99 keyword restrict.

Note -	
--------	--

The alternative keywords __restrict and __restrict__ are supported as synonyms for restrict. These alternative keywords are always available, regardless of the use of the --restrict option.

Default

When compiling ISO C99 source code, use of the C99 keyword **restrict** is enabled by default.

When compiling ISO C90 or ISO C++ source code, use of the C99 keyword **restrict** is disabled by default.

See also

• restrict on page 3-8.

2.1.143 --retain=option

This option enables you to restrict the optimizations performed by the compiler, and might be useful when performing validation, debugging, and coverage testing.

Syntax

--retain=option

Where *option* is one of the following:

fns prevents the removal of unused functions

inlinefns prevents the removal of unused inline functions

noninlinefns prevents the removal of unused non-inline functions

paths prevents path-removing optimizations, such as a | | b transformed to a | b.

This supports *Modified Condition Decision Coverage* (MCDC) testing.

calls prevents calls being removed, for example by inlining or tailcalling.

calls:distinct

prevents calls being merged, for example by cross-jumping (that is,

common tail path merging).

libcalls prevents calls to library functions being removed, for example by inline

expansion.

data prevents data being removed.

rodata prevents read-only data being removed.

rwdata prevents read-write data being removed.

data:order prevents data being reordered.

- __attribute__((nomerge)) on page 4-35
- __attribute__((notailcall)) on page 4-37.

2.1.144 --rtti, --no_rtti

This option controls support for the RTTI features dynamic_cast and typeid in C++.

Mode

This option is effective only if the source language is C++.

Default

The default is --rtti.

See also

• --dllimport_runtime, --no_dllimport_runtime on page 2-50.

2.1.145 -S

This option instructs the compiler to output the disassembly of the machine code generated by the compiler to a file.

Unlike the --asm option, object modules are not generated. The name of the assembly output file defaults to *filename*.s in the current directory, where *filename* is the name of the source file stripped of any leading directory names. The default filename can be overridden with the -o option.

You can use armasm to assemble the output file and produce object code. The compiler adds ASSERT directives for command-line options such as AAPCS variants and byte order to ensure that compatible compiler and assembler options are used when reassembling the output. You must specify the same AAPCS settings to both the assembler and the compiler.

- --apcs=qualifer...qualifier on page 2-4
- --asm on page 2-16
- -c on page 2-21
- --info=totals on page 2-74
- --interleave on page 2-76
- --*list* on page 2-82
- -o filename on page 2-95
- Assembler Guide.

2.1.146 --shared

This option enables a shared library to be generated when building for ARM Linux with the --arm_linux_paths option. It enables the selection of libraries and intialization code suitable for use in a shared library, based on the ARM Linux configuration.

Restrictions

You must use this option in conjunction with --arm_linux_paths and --apcs=/fpic.

Example

Link two object files, obj1.0 and obj2.0, into a shared library named libexample.0:

armcc --arm_linux_paths --arm_linux_config_file=my_config_file --shared -o
libexample.so obj1.o obj2.o

- --arm_linux on page 2-9
- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --arm_linux_paths on page 2-13
- --configure_cpp_headers=path on page 2-24
- --configure_extra_includes=paths on page 2-25
- --configure_extra_libraries=paths on page 2-26
- --configure_gcc=path on page 2-27
- --configure_gld=path on page 2-28
- --configure_sysroot=path on page 2-29
- -- gnu defaults on page 2-68
- --translate_g++ on page 2-122
- --translate_gcc on page 2-124
- --translate_gld on page 2-125
- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
- Application Note 212 Building Linux applications using RVCT v4.0 and the GNU Tools and Libraries.

2.1.147 --show_cmdline

This option shows how the command-line options are processed.

The commands are shown in their preferred form, and the contents of any via files are expanded.

See also

- -*Aopt* on page 2-2
- *-Lopt* on page 2-79
- --via=filename on page 2-132.

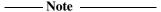
2.1.148 --signed_bitfields, --unsigned_bitfields

This option makes bitfields of type int signed or unsigned.

The C Standard specifies that if the type specifier used in declaring a bitfield is either int, or a typedef name defined as int, then whether the bitfield is signed or unsigned is dependent on the implementation.

Default

The default is --unsigned_bitfields. However, if you specify an ARM Linux configuration file on the command line and you use --translate_gcc or --translate_g++, the default is --signed_bitfields.



The AAPCS requirement for bitfields to default to unsigned on ARM, is relaxed in version 2.03 of the standard.

Example

```
typedef int integer;
struct
{
    integer x : 1;
} bf;
```

Compiling this code with --signed_bitfields causes to be treated as a signed bitfield.

- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12

• -- *gnu_defaults* on page 2-68.

2.1.149 --signed_chars, --unsigned_chars

This option makes the **char** type signed or unsigned.

When **char** is signed, the macro __FEATURE_SIGNED_CHAR is defined by the compiler.

_____ Note _____

Care must be taken when mixing translation units that have been compiled with and without this option, and that share interfaces or data structures.

The ARM ABI defines **char** as an unsigned byte, and this is the interpretation used by the C++ libraries supplied with RVCT.

Default

The default is --unsigned_chars.

See also

• *Predefined macros* on page 4-198.

2.1.150 --split_ldm

This option instructs the compiler to split LDM and STM instructions into two or more LDM or STM instructions.

When --split_ldm is selected, the maximum number of register transfers for an LDM or STM instruction is limited to:

- five, for all STMs
- five, for LDMs that do not load the PC
- four, for LDMs that load the PC.

Where register transfers beyond these limits are required, multiple LDM or STM instructions are used.

Usage

The --split_ldm option can be used to reduce interrupt latency on ARM systems that:

- do not have a cache or a write buffer, for example, a cacheless ARM7TDMI
- use zero-wait-state, 32-bit memory.

Note	-	
Usingsplit_ldm increases	code size and decreases performance slig	ghtly

Restrictions

- Inline assembler LDM and STM instructions are split by default when --split_ldm is
 used. However, the compiler might subsequently recombine the separate
 instructions into an LDM or STM.
- Only LDM and STM instructions are split when --split_ldm is used.
- Some target hardware does not benefit from code built with --split_ldm. For example:
 - It has no significant benefit for cached systems, or for processors with a write buffer.
 - It has no benefit for systems with non zero-wait-state memory, or for systems with slow peripheral devices. Interrupt latency in such systems is determined by the number of cycles required for the slowest memory or peripheral access. Typically, this is much greater than the latency introduced by multiple register transfers.

See also

• Instruction expansion on page 7-9 in the Compiler User Guide.

2.1.151 --split_sections

This option instructs the compiler to generate one ELF section for each function in the source file.

Output sections are named with the same name as the function that generates the section, but with an i. prefix.

——Note ———
If you want to place specific data items or structures in separate sections, mark them
<pre>individually withattribute((section())).</pre>

If you want to remove unused functions, it is recommended that you use the linker feedback optimization in preference to this option. This is because linker feedback produces smaller code by avoiding the overhead of splitting all sections.

Restrictions

This option reduces the potential for sharing addresses, data, and string literals between functions. Consequently, it might increase code size slightly for some functions.

Example

```
int f(int x)
{
    return x+1;
}
```

Compiling this code with --split_sections produces:

```
AREA ||i.f||, CODE, READONLY, ALIGN=2
f PROC
ADD r0,r0,#1
BX lr
ENDP
```

See also

- --data_reorder, --no_data_reorder on page 2-36
- --feedback=filename on page 2-56
- --multifile, --no_multifile on page 2-92
- __attribute__((section("name"))) on page 4-38
- #pragma arm section [section_sort_list] on page 4-59
- *Using linker feedback* on page 2-26 in the *Compiler User Guide*.

2.1.152 --strict, --no_strict

This option enforces or relaxes strict C or strict C++, depending on the choice of source language used.

When --strict is selected:

- features that conflict with ISO C or ISO C++ are disabled
- error messages are returned when nonstandard features are used.

Default

The default is --no_strict.

Usage

--strict enforces compliance with:

```
ISO/IEC 9899:1990, the 1990 International Standard for C.
```

• ISO/IEC 9899 AM1, the 1995 Normative Addendum 1.

ISO C99 ISO/IEC 9899:1999, the 1999 International Standard for C.

ISO C++ ISO/IEC 14822:2003, the 2003 International Standard for C++.

Errors

When --strict is in force and a violation of the relevant ISO standard occurs, the compiler issues an error message.

The severity of diagnostic messages can be controlled in the usual way.

Example

```
void foo(void)
{
    long long i; /* okay in nonstrict C90 */
}
```

Compiling this code with --strict generates an error.

See also

- --*c90* on page 2-22
- --*c*99 on page 2-22
- --*cpp* on page 2-30
- -- *gnu* on page 2-67
- --strict warnings
- *Dollar signs in identifiers* on page 3-13
- *Source language modes* on page 1-4 in the *Compiler User Guide*.

2.1.153 --strict_warnings

Diagnostics that are errors in --strict mode are downgraded to warnings, where possible. It is sometimes not possible for the compiler to downgrade a strict error, for example, where it cannot construct a legitimate program to recover.

Errors

When --strict_warnings is in force and a violation of the relevant ISO standard occurs, the compiler normally issues a warning message.

The severity of diagnostic messages can be controlled in the usual way.



In some cases, the compiler issues an error message instead of a warning when it detects something that is strictly illegal, and terminates the compilation. For example:

```
#ifdef $Super$
extern void $Super$$__aeabi_idiv0(void); /* intercept __aeabi_idiv0 */
#endif
```

Compiling this code with --strict_warnings generates an error if you do not use the --dollar option.

Example

```
void foo(void)
{
    long long i; /* okay in nonstrict C90 */
}
```

Compiling this code with --strict_warnings generates a warning message.

Compilation continues, even though the expression long long is strictly illegal.

See also

- Source language modes on page 1-3
- *Dollar signs in identifiers* on page 3-13
- --*c90* on page 2-22
- --c99 on page 2-22
- --*cpp* on page 2-30
- -- *gnu* on page 2-67
- --strict, --no strict on page 2-119.

2.1.154 --sys_include

This option removes the current place from the include search path.

Quoted include files are treated in a similar way to angle-bracketed include files, except that quoted include files are always searched for first in the directories specified by -I, and angle-bracketed include files are searched for first in the -J directories.

See also

- -*Idir*[,*dir*,...] on page 2-72
- -Jdir[,dir,...] on page 2-77
- --kandr_include on page 2-78
- --preinclude=filename on page 2-105
- The current place on page 2-14 in the Compiler User Guide
- The search path on page 2-15 in the Compiler User Guide.

2.1.155 -- thumb

This option configures the compiler to target the Thumb instruction set.

Default

This is the default option for targets that do not support the ARM instruction set.

See also

- --*arm* on page 2-8
- #pragma arm on page 4-59
- #pragma thumb on page 4-73
- Specifying the target processor or architecture on page 2-23 in the Compiler User Guide
- Selecting the target CPU on page 5-3 in the Compiler User Guide.

2.1.156 --translate_g++

This option helps to emulate the GNU compiler in C++ mode by enabling the translation of command lines from the GNU tools.

Usage

You can use this option to provide either of the following:

• a full GCC emulation targeting ARM Linux.

 a subset of full GCC emulation in the form of translating individual GCC command-line arguments into their RVCT equivalents.

To provide a full ARM Linux GCC emulation, you must also use --arm_linux_config_file. This combination of options selects the appropriate GNU header files and libraries specified by the configuration file, and includes changes to some default behaviors.

To translate GCC command-line arguments into their RVCT equivalents without aiming for full GCC emulation, use --translate_g++ to emulate g++, but do not use it with --arm_linux_config_file. Because you are not aiming for full GCC emulation with this method, RVCT default behavior is retained, and no defaults are set for targeting ARM Linux. RVCT library paths and option defaults remained unchanged.

Restrictions

If you specify an ARM Linux configuration file on the command line and you use --translate_g++, this alters the default settings for --exceptions and --no_exceptions, --bss_threshold, --relaxed_ref_def and --no_relaxed_ref_def, and --signed_bitfields and --unsigned_bitfields.

- --arm_linux on page 2-9
- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --arm_linux_paths on page 2-13
- --bss_threshold=num on page 2-20
- --configure_cpp_headers=path on page 2-24
- --configure_extra_includes=paths on page 2-25
- --configure extra libraries=paths on page 2-26
- --configure_gcc=path on page 2-27
- --configure_gld=path on page 2-28
- --configure_sysroot=path on page 2-29
- --exceptions, --no_exceptions on page 2-54
- --gnu_defaults on page 2-68
- --relaxed_ref_def, --no_relaxed_ref_def on page 2-110
- --shared on page 2-115
- --signed_bitfields, --unsigned_bitfields on page 2-116
- --translate gcc on page 2-124
- --translate_gld on page 2-125

- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
- Application Note 212 Building Linux applications using RVCT v4.0 and the GNU Tools and Libraries.

2.1.157 --translate_qcc

This option helps to emulate gcc by enabling the translation of command lines from the GNU tools.

Usage

You can use this option to provide either of the following:

- a full GCC emulation targeting ARM Linux
- a subset of full GCC emulation in the form of translating individual GCC command-line arguments into their RVCT equivalents.

To provide a full GCC emulation, you must also use --arm_linux_config_file. This combination of options selects the appropriate GNU header files and libraries specified by the configuration file, and includes changes to some default behaviors.

To translate individual GCC command-line arguments into their RVCT equivalents without aiming for full GCC emulation, use --translate_gcc to emulate gcc, but do not use it with --arm_linux_config_file. Because you are not aiming for full GCC emulation with this method, RVCT default behavior is retained, and no defaults are set for targeting ARM Linux. RVCT library paths and option defaults remained unchanged.

Restrictions

If you specify an ARM Linux configuration file on the command line and you use --translate_gcc, this alters the default settings for --bss_threshold, --relaxed_ref_def and --no_relaxed_ref_def, and --signed_bitfields and --unsigned_bitfields.

- --arm_linux on page 2-9
- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --arm_linux_paths on page 2-13
- --configure_cpp_headers=path on page 2-24

- --configure_extra_includes=paths on page 2-25
- --configure_extra_libraries=paths on page 2-26
- --configure_gcc=path on page 2-27
- --configure gld=path on page 2-28
- --configure_sysroot=path on page 2-29
- --gnu_defaults on page 2-68
- --relaxed ref def, --no relaxed ref def on page 2-110
- --shared on page 2-115
- --signed_bitfields, --unsigned_bitfields on page 2-116
- $--translate_g++$ on page 2-122
- --translate_gld
- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
- Application Note 212 Building Linux applications using RVCT v4.0 and the GNU Tools and Libraries.

2.1.158 --translate_gld

This option helps to emulate GNU 1d by enabling the translation of command lines from the GNU tools.

Usage

You can use this option to provide either of the following:

- a full GNU 1d emulation targeting ARM Linux
- a subset of full GNU 1d emulation in the form of translating individual GNU 1d command-line arguments into their RVCT equivalents.

To provide a full GNU 1d emulation, you must also use --arm_linux_config_file. This combination of options selects the appropriate GNU header files and libraries specified by the configuration file, and includes changes to some default behaviors.

To translate individual GNU 1d command-line arguments into their RVCT equivalents without aiming for full GNU 1d emulation, use --translate_gld to emulate GNU 1d, but do not use it with --arm_linux_config_file. Because you are not aiming for full GNU 1d emulation with this method, RVCT default behavior is retained, and no defaults are set for targeting ARM Linux. RVCT library paths and option defaults remained unchanged.

— Note -

- --translate_gld is used by invoking armcc as if it were the GNU linker. This is
 intended only for use by existing build scripts that involve the GNU linker
 directly.
- In gcc and g++ modes, armcc reports itself with --translate_gld as the linker it uses. For example, gcc -print-file-name=ld.

See also

- --arm linux on page 2-9
- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --arm linux paths on page 2-13
- --configure_cpp_headers=path on page 2-24
- --configure_extra_includes=paths on page 2-25
- --configure_extra_libraries=paths on page 2-26
- --configure_gcc=path on page 2-27
- --configure_gld=path on page 2-28
- --configure sysroot=path on page 2-29
- -- gnu defaults on page 2-68
- --shared on page 2-115
- --translate g++ on page 2-122
- --translate gcc on page 2-124
- --arm_linux on page 2-11 in the Linker Reference Guide
- --library=name on page 2-54 in the Linker Reference Guide
- --search_dynamic_libraries, --no_search_dynamic_libraries on page 2-78 in the Linker Reference Guide
- Application Note 212 Building Linux applications using RVCT v4.0 and the GNU Tools and Libraries.

2.1.159 --trigraphs, --no_trigraphs

This option enables and disables trigraph recognition.

Default

The default is --trigraphs, except in GNU mode, where the default is --no_trigraphs.

See also

ISO/IEC 9899:TC2.

2.1.160 -Uname

This option removes any initial definition of the macro name.

The macro name can be either:

- a predefined macro
- a macro specified using the -D option.

Note

Not all compiler predefined macros can be undefined.

Syntax

-Uname

Where:

name

is the name of the macro to be undefined.

Usage

Specifying -Uname has the same effect as placing the text #undef name at the head of each source file.

Restrictions

The compiler defines and undefines macros in the following order:

- 1. compiler predefined macros
- 2. macros defined explicitly, using -Dname
- 3. macros explicitly undefined, using -Uname.

See also

- -*C* on page 2-22
- -*Dname[(parm-list)][=def]* on page 2-35
- -*E* on page 2-52
- -*M* on page 2-88
- *Compiler predefines* on page 4-198.

2.1.161 --unaligned_access, --no_unaligned_access

These options enable and disable unaligned accesses to data on ARM architecture-based processors.

Default

The default is --unaligned_access on ARM-architecture based processors that support unaligned accesses to data. This includes:

- all ARMv6 architecture-based processors
- ARMv7-A, ARMv7-R, and ARMv7-M architecture-based processors.

The default is --no_unaligned_access on ARM-architecture based processors that do not support unaligned accesses to data. This includes:

- all pre-ARMv6 architecture-based processors
- ARMv6-M architecture-based processors.

Usage

--unaligned_access

Use --unaligned_access on processors that support unaligned accesses to data, for example --cpu=ARM1136J-S, to speed up accesses to packed structures.

To enable unaligned support, you must:

- Clear the A bit, bit 1, of CP15 register 1 in your initialization code.
- Set the U bit, bit 22, of CP15 register 1 in your initialization code. The initial value of the U bit is determined by the **UBITINIT** input to the core.

The RVCT libraries include special versions of certain library functions designed to exploit unaligned accesses. When unaligned access support is enabled, the RVCT tools use these library functions to take advantage of unaligned accesses.

--no_unaligned_access

Use --no_unaligned_access to disable the generation of unaligned word and halfword accesses on ARMv6 processors.

To enable modulo four-byte alignment checking on an ARMv6 target without unaligned accesses, you must:

- Set the A bit, bit 1, of CP15 register 1 in your initialization code.
- Set the U bit, bit 22, of CP15 register 1 in your initialization code.

The initial value of the U bit is determined by the **UBITINIT** input to the core.



Unaligned doubleword accesses, for example unaligned accesses to **long long** integers, are not supported by ARM processor cores. Doubleword accesses must be either eight-byte or four-byte aligned.

The compiler does not provide support for modulo eight-byte alignment checking. That is, the configuration $U = \emptyset$, A = 1 in CP15 register 1 is not supported by the compiler, or more generally, by the RVCT toolset.

The RVCT libraries include special versions of certain library functions designed to exploit unaligned accesses. To prevent these enhanced library functions being used when unaligned access support is disabled, you have to specify --no_unaligned_access on both the compiler command line and the assembler command line when compiling a mixture of C and C++ source files and asssembly language source files.

Restrictions

Code compiled for processors supporting unaligned accesses to data can run correctly only if the choice of alignment support in software matches the choice of alignment support on the processor core.

See also

- --*cpu=name* on page 2-30
- Command syntax on page 3-2 in the Assembler Guide
- *Alignment support* on page 2-13 in the *Developer Guide*.

2.1.162 --use_pch=filename

This option instructs the compiler to use a PCH file with the specified filename as part of the current compilation.

This option takes precedence if you include --pch on the same command line.

Syntax

--use_pch=filename

Where:

filename is the PCH file to be used as part of the current compilation.

Restrictions

The effect of this option is negated if you include --create_pch=filename on the same command line.

Errors

If the specified file does not exist, or is not a valid PCH file, then the compiler generates an error.

See also

- --create_pch=filename on page 2-34
- --pch on page 2-101
- --pch_dir=dir on page 2-101
- --pch_messages, --no_pch_messages on page 2-102
- --pch_verbose, --no_pch_verbose on page 2-102
- Precompiled header files on page 2-17 in the Compiler User Guide.

2.1.163 --using_std, --no_using_std

This option enables or disables implicit use of the std namespace when standard header files are included in C++.

Note	

This option is provided only as a migration aid for legacy source code that does not conform to the C++ standard. Its use is not recommended.

Mode

This option is effective only if the source language is C++.

Default

The default is --no_using_std.

See also

Namespaces on page 5-16.

2.1.164 --vectorize, --no_vectorize

This option enables or disables the generation of NEON vector instructions directly from C or C++ code.

Default

The default is --no_vectorize.

Restrictions

The following options must be specified for loops to vectorize:

--cpu=name Target processor must have NEON capability.

-0time Type of optimization to reduce execution time.

-0*num* Level of optimization. One of the following must be used:

- -02 High optimization. This is the default.
- -03 Maximum optimization.

_____Note _____

NEON is an implementation of the ARM Advanced *Single Instruction, Multiple Data* (SIMD) extension.

A separate *FLEXnet* license is needed to enable the use of vectorization. This license is provided with RVDS 4.0 Professional.

Example

armcc --vectorize --cpu=Cortex-A8 -03 -0time -c file.c

See also

- --cpu=name on page 2-30
- -*Onum* on page 2-96
- -*Otime* on page 2-99
- Introducing NEON™ Development Article, http://infocenter.arm.com/help/index.jsp?topic=/com.arm.doc.dht0002-
- Chapter 3 *Using the NEON Vectorizing Compiler* in the *Compiler User Guide*.

2.1.165 --vfe, --no_vfe

This option enables or disables Virtual Function Elimination (VFE) in C++.

VFE enables unused virtual functions to be removed from code. When VFE is enabled, the compiler places the information in special sections with the prefix .arm_vfe_. These sections are ignored by linkers that are not VFE-aware, because they are not referenced by the rest of the code. Therefore, they do not increase the size of the executable. However, they increase the size of the object files.

Mode

This option is effective only if the source language is C++.

Default

The default is --vfe, except for the case where legacy object files compiled with a pre-RVCT v2.1 compiler do not contain VFE information.

See also

- Calling a pure virtual function on page C-3
- *Unused virtual function elimination* on page 3-15 in the *Linker User Guide*.

2.1.166 --via=filename

This option instructs the compiler to read additional command-line options from a specified file. The options read from the file are added to the current command line.

Via commands can be nested within via files.

Syntax

--via=filename

Where:

filename

is the name of a via file containing options to be included on the command line.

Example

Given a source file main.c, a via file apcs.txt containing the line:

--apcs=/rwpi --no_lower_rwpi --via=L_apcs.txt

and a second via file L_apcs.txt containing the line:

```
-L--rwpi -L--callgraph
compiling main.c with the command line:
armcc main.c -L-o"main.axf" --via=apcs.txt
compiles main.c using the command line:
```

See also

- Appendix A Via File Syntax
- Reading compiler options from a file on page 2-11 in the Compiler User Guide.

armcc --no_lower_rwpi --apcs=/rwpi -L--rwpi -L--callgraph -L-o"main.axf" main.c

2.1.167 --vla, --no_vla

This option enables or disables support for variable length arrays.

Default

C90 and Standard C++ do not support variable length arrays by default. Select the option --vla to enable support for variable length arrays in C90 or Standard C++.

Variable length arrays are supported both in Standard C and the GNU compiler extensions. The option --vla is implicitly selected either when the source language is C99 or the option --gnu is specified.

Example

See also

- -c90 on page 2-22
- --*c*99 on page 2-22
- --*cpp* on page 2-30
- -- *gnu* on page 2-67.

2.1.168 --vsn

This option displays the version information and the license details.

See also

• --help on page 2-71.

2.1.169 -W

This option instructs the compiler to suppress all warning messages.

See also

- --brief_diagnostics, --no_brief_diagnostics on page 2-19
- --diag_error=tag[,tag,...] on page 2-44
- --diag_remark=tag[,tag,...] on page 2-45
- --diag_style={arm|ide|gnu} on page 2-46
- --diag_suppress=tag[,tag,...] on page 2-47
- --diag_warning=tag[,tag,...] on page 2-48
- --errors=filename on page 2-53
- --remarks on page 2-111
- --wrap diagnostics, --no wrap diagnostics on page 2-137

2.1.170 --wchar, --no_wchar

This option permits or forbids the use of wchar_t. It does not necessarily fault declarations, providing they are unused.

Usage

Use this option to create an object file that is independent of wchar_t size.

Restrictions

If --no_wchar is specified:

- wchar_t fields in structure declarations are faulted by the compiler, regardless of whether or not the structure is used
- wchar_t in a typedef is faulted by the compiler, regardless of whether or not the typedef is used.

Default

The default is --wchar.

See also

- --wchar16
- --wchar32.

2.1.171 --wchar16

This option changes the type of wchar_t to unsigned short.

Selecting this option modifies both the type of the defined type wchar_t in C and the type of the native type wchar_t in C++. It also affects the values of WCHAR_MIN and WCHAR_MAX.

Default

The compiler assumes --wchar16 unless --wchar32 is explicitly specified.

See also

- --wchar, --no wchar on page 2-134
- --wchar32
- Predefined macros on page 4-198.

2.1.172 --wchar32

This option changes the type of wchar_t to unsigned int.

Selecting this option modifies both the type of the defined type wchar_t in C and the type of the native type wchar_t in C++. It also affects the values of WCHAR_MIN and WCHAR_MAX.

Default

The compiler assumes --wchar16 unless --wchar32 is explicitly specified, or unless you specify an ARM Linux configuration file on the command line. Specifying an ARM Linux configuration file on the command line turns --wchar32 on.

See also

- --arm_linux_config_file=path on page 2-10
- --arm_linux_configure on page 2-12
- --signed_bitfields, --unsigned_bitfields on page 2-116
- --wchar, --no_wchar on page 2-134

- --wchar16 on page 2-135
- *Predefined macros* on page 4-198.

2.1.173 --whole_program

This option promises the compiler that the source files specified on the command line form the whole program. The compiler is then able to apply optimizations based on the knowledge that the source code visible to it is the complete set of source code for the program being compiled. Without this knowledge, the compiler is more conservative when applying optimizations to the code.

Usage

Use this option to gain maximum performance from a small program.

Restriction

Do not use this option if you do not have all of the source code to give to the compiler.

See also

• --multifile, --no_multifile on page 2-92.

2.1.174 --workdir=*directory*

Note ————
Project templates only require working directories if they include files, for example,

This option enables you to provide a working directory for a project template.

Syntax

--workdir=directory

RVD configuration files.

Where:

directory is the name of the project directory.

Restrictions

If you specify a project working directory using --workdir, then you must specify a project file using --project.

Errors

An error message is produced if you try to use --project without --workdir and --workdir is required.

See also

- --project=filename, --no_project on page 2-107
- --reinitialize_workdir on page 2-110.

2.1.175 --wrap_diagnostics, --no_wrap_diagnostics

This option enables or disables the wrapping of error message text when it is too long to fit on a single line.

Default

The default is --no_wrap_diagnostics.

See also

- --brief_diagnostics, --no_brief_diagnostics on page 2-19
- --diag_error=tag[,tag,...] on page 2-44
- --diag_remark=tag[,tag,...] on page 2-45
- --diag_style={arm|ide|gnu} on page 2-46
- --diag_suppress=tag[,tag,...] on page 2-47
- --diag_warning=tag[,tag,...] on page 2-48
- --errors=filename on page 2-53
- --remarks on page 2-111
- -W on page 2-134
- Chapter 6 *Diagnostic Messages* in the *Compiler User Guide*.

Compiler Command-line Options

Chapter 3 **Language Extensions**

This chapter describes the language extensions supported by the ARM compiler, and includes:

- *Preprocessor extensions* on page 3-2
- C99 language features available in C90 on page 3-5
- C99 language features available in C++ and C90 on page 3-7
- Standard C language extensions on page 3-10
- Standard C++ language extensions on page 3-15
- Standard C and standard C++ language extensions on page 3-19
- GNU language extensions on page 3-25.

For additional reference material on the ARM compiler see also:

- Appendix B Standard C Implementation Definition
- Appendix C Standard C++ Implementation Definition
- Appendix D *C* and C++ Compiler Implementation Limits.

3.1 Preprocessor extensions

The compiler supports several extensions to the preprocessor, including the #assert preprocessing extensions of System V release 4.

3.1.1 #assert

The #assert preprocessing extensions of System V release 4 are permitted. These enable definition and testing of predicate names.

Such names are in a namespace distinct from all other names, including macro names.

Syntax

#assert name

#assert name[(token-sequence)]

Where:

name is a predicate name

token-sequence is an optional sequence of tokens.

If the token sequence is omitted, name is not given a value.

If the token sequence is included, name is given the value

token-sequence.

Example

A predicate name defined using #assert can be tested in a #if expression, for example:

#if #name(token-sequence)

This has the value 1 if a #assert of the name *name* with the token-sequence *token-sequence* has appeared, and 0 otherwise. A given predicate can be given more than one value at a given time.

See also

• #unassert on page 3-3.

3.1.2 #include_next

This preprocessor directive is a variant of the #include directive. It searches for the named file only in the directories on the search path that follow the directory where the current source file is found, that is, the one containing the #include_next directive.

____ Note _____

This preprocessor directive is a GNU compiler extension that is supported by the ARM compiler.

3.1.3 #unassert

A predicate name can be deleted using a #unassert preprocessing directive.

Syntax

#unassert name

#unassert name[(token-sequence)]

Where:

name is a predicate name

token-sequence is an optional sequence of tokens.

If the token sequence is omitted, all definitions of *name* are

removed.

If the token sequence is included, only the indicated definition is

removed. All other definitions are left intact.

See also

• #assert on page 3-2.

3.1.4 #warning

The preprocessing directive #warning is supported. Like the #error directive, this produces a user-defined warning at compilation time. However, it does not halt compilation.

Restrictions

The #warning directive is not available if the --strict option is specified. If used, it produces an error.

See also

• --strict, --no_strict on page 2-119.

3.2 C99 language features available in C90

The compiler supports numerous extensions to the ISO C90 standard, for example, C99-style // comments.

These extensions are available if the source language is C90 and you are compiling in non strict mode.

These extensions are not available if the source language is C90 and the compiler is restricted to compiling strict C90 using the --strict compiler option.



Language features of Standard C and Standard C++, for example C++-style // comments, might be similar to the C90 language extensions described in this section. Such features continue to remain available if you are compiling strict Standard C or strict Standard C++ using the --strict compiler option.

3.2.1 // comments

The character sequence // starts a one line comment, like in C99 or C++.

// comments in C90 have the same semantics as // comments in C99.

Example

```
// this is a comment
```

See also

• *New features of C99* on page 5-45 in the *Compiler User Guide*.

3.2.2 Subscripting struct

In C90, arrays that are not Ivalues still decay to pointers, and can be subscripted. However, you must not modify or use them after the next sequence point, and you must not apply the unary & operator to them. Arrays of this kind can be subscripted in C90, but they do not decay to pointers outside C99 mode.

Example

```
struct Subscripting_Struct
{
    int a[4];
};
```

```
extern struct Subscripting_Struct Subscripting_0(void);
int Subscripting_1 (int index)
{
    return Subscripting_0().a[index];
}
```

3.2.3 Flexible array members

The last member of a **struct** can have an incomplete array type. The last member must not be the only member of the **struct**, otherwise the **struct** is zero in size.

Example

```
typedef struct
{
   int len;
   char p[]; // incomplete array type, for use in a malloced data structure
} str;
```

See also

• New features of C99 on page 5-45 in the Compiler User Guide.

3.3 C99 language features available in C++ and C90

The compiler supports numerous extensions to the ISO C++ standard and to the C90 language, for example, function prototypes that override old-style non prototype definitions.

These extensions are available if:

- the source language is C++ and you are compiling in non strict mode
- the source language is C90 and you are compiling in non strict mode.

These extensions are not available if:

- the source language is C++ and the compiler is restricted to compiling strict C90 using the --strict compiler option.
- the source language is C90 and the compiler is restricted to compiling strict Standard C using the --strict compiler option.



Language features of Standard C, for example **long long** integers, might be similar to the language extensions described in this section. Such features continue to remain available if you are compiling strict standard C++ or strict C90 using the --strict compiler option.

3.3.1 Variadic macros

In C90 and C++ you can declare a macro to accept a variable number of arguments.

The syntax for declaring a variadic macro in C90 and C++ follows the C99 syntax for declaring a variadic macro, unless the option --gnu is selected. If the option --gnu is specified, the syntax follows GNU syntax for variadic macros.

Example

```
#define debug(format, ...) fprintf (stderr, format, __VA_ARGS__)
void variadic_macros(void)
{
    debug ("a test string is printed out along with %x %x %x\n", 12, 14, 20);
}
```

See also

- -- *gnu* on page 2-67
- *New features of C99* on page 5-45 in the *Compiler User Guide*.

3.3.2 long long

The ARM compiler supports 64-bit integer types through the type specifiers **long long** and **unsigned long long**. They behave analogously to **long** and **unsigned long** with respect to the usual arithmetic conversions. __int64 is a synonym for **long long**.

Integer constants can have:

- an 11 suffix to force the type of the constant to long long, if it fits, or to unsigned long long if it does not fit
- a ull or llu suffix to force the type of the constant to **unsigned long long**.

Format specifiers for printf() and scanf() can include 11 to specify that the following conversion applies to a **long long** argument, as7 in %11d or %11u.

Also, a plain integer constant is of type long long or unsigned long long if its value is large enough. There is a warning message from the compiler indicating the change. For example, in strict 1990 ISO Standard C 2147483648 has type unsigned long. In ARM C and C++ it has the type long long. One consequence of this is the value of an expression such as:

2147483648 > -1

This expression evaluates to 0 in strict C and C++, and to 1 in ARM C and C++.

The long long types are accommodated in the usual arithmetic conversions.

See also

• *int64* on page 4-10.

3.3.3 restrict

The **restrict** keyword is a C99 feature. It enables you to convey a declaration of intent to the compiler that different pointers and function parameter arrays do not point to overlapping regions of memory at runtime. This enables the compiler to perform optimizations that can otherwise be prevented because of possible aliasing.

Usage

The keywords __restrict and __restrict__ are supported as synonyms for **restrict** and are always available.

You can specify --restrict to allow the use of the **restrict** keyword in C90 or C++.

Restrictions

The declaration of intent is effectively a promise to the compiler that, if broken, results in undefined behavior.

Example

```
void copy_array(int n, int *restrict a, int *restrict b)
{
    while (n-- > 0)
        *a++ = *b++;
}
```

See also

- --restrict, --no_restrict on page 2-112
- New features of C99 on page 5-45 in the Compiler User Guide.

3.3.4 Hex floats

C90 and C++ support floating-point numbers that can be written in hexadecimal format.

Example

```
float hex_floats(void)
{
    return 0x1.fp3; // 1.55e1
}
```

See also

• *New features of C99* on page 5-45 in the *Compiler User Guide*.

3.4 Standard C language extensions

The compiler supports numerous extensions to the ISO C99 standard, for example, function prototypes that override old-style non prototype definitions.

These extensions are available if:

- the source language is C99 and you are compiling in non strict mode
- the source language is C90 and you are compiling in non strict mode.

None of these extensions is available if:

- the source language is C90 and the compiler is restricted to compiling strict C90 using the --strict compiler option.
- the source language is C99 and the compiler is restricted to compiling strict Standard C using the --strict compiler option.
- the source language is C++.

3.4.1 Constant expressions

Extended constant expressions are supported in initializers. The following examples show the compiler behavior for the default, --strict_warnings, and --strict compiler modes.

Example 1, assigning the address of variable

Your code might contain constant expressions that assign the address of a variable at file scope, for example:

```
int i;
int j = (int)&i; /* but not allowed by ISO */
```

When compiling for C, this produces the following behavior:

- In default mode a warning is produced.
- In --strict_warnings mode a warning is produced.
- In --strict mode, an error is produced.

Example 2, constant value initializers

The compiler behavior when you have expressions that include constant values in C code is summarized in the following example:

```
/* Std RVCT v3.1 */
extern int const c = 10; /* ok ok */
extern int const x = c + 10; /* error ext */
```

```
static int
                 y = c + 10;
                                     /* error
                                                   ext
                                                           */
static int const z = c + 10;
                                     /* error
                                                   ext
                                                           */
extern int *const cp = (int*)0x100;
                                     /∗ ok
                                                   ok
                                                           */
extern int *const xp = cp + 0x100;
                                     /* error
                                                   ext
                                                           */
                 yp = cp + 0x100;
static int *
                                     /* error
                                                   ext
                                                           */
static int *const zp = cp + 0x100;
                                     /* error
                                                   ext
```

This indicates the behavior defined by the ISO C Standard, Std, and the behavior in RVCT:

- ok indicates that the statement is accepted in all C modes.
- ext is an extension to the ISO C Standard. The behavior depends on the strict mode used when compiling C:

Non strict

Accepted, without a warning.

--strict_warnings

Accepted, but gives a warning.

--strict

Conforms to the ISO C Standard, but gives an error.

See also

- --extended_initializers, --no_extended_initializers on page 2-56
- --strict, --no_strict on page 2-119
- --strict_warnings on page 2-120.

3.4.2 Array and pointer extensions

The following array and pointer extensions are supported:

- Assignment and pointer differences are permitted between pointers to types that
 are interchangeable but not identical, for example, unsigned char * and char *.
 This includes pointers to same-sized integral types, typically, int * and long *. A
 warning is issued.
 - Assignment of a string constant to a pointer to any kind of character is permitted without a warning.
- Assignment of pointer types is permitted in cases where the destination type has
 added type qualifiers that are not at the top level, for example, assigning int ** to
 const int **. Comparisons and pointer difference of such pairs of pointer types
 are also permitted. A warning is issued.

- In operations on pointers, a pointer to void is always implicitly converted to another type if necessary. Also, a null pointer constant is always implicitly converted to a null pointer of the right type if necessary. In ISO C, some operators permit these, and others do not.
- Pointers to different function types can be assigned or compared for equality (==) or inequality (!=) without an explicit type cast. A warning or error is issued.

 This extension is prohibited in C++ mode.
- A pointer to **void** can be implicitly converted to, or from, a pointer to a function type.
- In an initializer, a pointer constant value can be cast to an integral type if the integral type is big enough to contain it.
- A non lvalue array expression is converted to a pointer to the first element of the array when it is subscripted or similarly used.

3.4.3 Block scope function declarations

Two extensions to block scope function declarations are supported:

- a block-scope function declaration also declares the function name at file scope
- a block-scope function declaration can have static storage class, thereby causing the resulting declaration to have internal linkage by default.

Example

3.4.4 Dollar signs in identifiers

Dollar (\$) signs are permitted in identifiers.	
Note	

When compiling with the --strict option, you can use the --dollar command-line option to permit dollar signs in identifiers.

Example

#define DOLLAR\$

See also

- --dollar, --no dollar on page 2-51
- --strict, --no_strict on page 2-119.

3.4.5 Top-level declarations

A C input file can contain no top-level declarations.

Errors

A remark is issued if a C input file contains no top-level declarations.

 Note	

Remarks are not displayed by default. To see remark messages, use the compiler option --remarks.

See also

• --remarks on page 2-111.

3.4.6 Benign redeclarations

Benign redeclarations of **typedef** names are permitted. That is, a **typedef** name can be redeclared in the same scope as the same type.

Example

typedef int INT; typedef int INT; /* redeclaration */

3.4.7 External entities

External entities declared in other scopes are visible.

Errors

The compiler generates a warning if an external entity declared in another scope is visible.

Example

```
void f1(void)
{
    extern void f();
}
void f2(void)
{
    f(); /* Out of scope declaration */
}
```

3.4.8 Function prototypes

The compiler recognizes function prototypes that override old-style non prototype definitions that appear at a later position in your code, for example:

Errors

The compiler generates a warning message if you use old-style function prototypes.

Example

```
int function_prototypes(char);
// Old-style function definition.
int function_prototypes(x)
    char x;
{
    return x == 0;
}
```

3.5 Standard C++ language extensions

The compiler supports numerous extensions to the ISO C++ standard, for example, qualified names in the declaration of class members.

These extensions are available if the source language is C++ and you are compiling in non strict mode.

These extensions are not available if the source language is C++ and the compiler is restricted to compiling strict Standard C++ using the --strict compiler option.

3.5.1 ? operator

A ? operator whose second and third operands are string literals or wide string literals can be implicitly converted to char * or wchar_t *. In C++ string literals are const. There is an implicit conversion that enables conversion of a string literal to char * or wchar_t *, dropping the const. That conversion, however, applies only to simple string literals. Permitting it for the result of a ? operation is an extension.

Example

```
char *p = x ? "abc" : "def";
```

3.5.2 Declaration of a class member

A qualified name can be used in the declaration of a class member.

Errors

A warning is issued if a qualified name is used in the declaration of a class member.

Example

```
struct A
{
    int A::f(); // is the same as int f();
};
```

3.5.3 friend

A friend declaration for a class can omit the class keyword.

Access checks are not carried out on **friend** declarations by default. Use the --strict command-line option to force access checking.

Example

```
class B;
class A
{
    friend B; // is the same as "friend class B"
};
```

See also

• --strict, --no_strict on page 2-119.

3.5.4 Read/write constants

A linkage specification for external constants indicates that a constant can be dynamically initialized or have mutable members.



The use of "C++:read/write" linkage is only necessary for code compiled with --apcs /rwpi. If you recompile existing code with this option, you must change the linkage specification for external constants that are dynamically initialized or have mutable members.

Compiling C++ with the --apcs /rwpi option deviates from the ISO C++ Standard. The declarations in Example 3-1 assume that x is in a read-only segment.

Example 3-1 External access

```
extern const T x;
extern "C++" const T x;
extern "C" const T x;
```

Dynamic initialization of x including user-defined constructors is not possible for constants and T cannot contain mutable members. The new linkage specification in Example 3-2 on page 3-17 declares that x is in a read/write segment even if it is initialized with a constant. Dynamic initialization of x is permitted and T can contain mutable members. The definitions of x, y, and z in another file must have the same linkage specifications.

Example 3-2 Linkage specification

```
/* in read-only segment, cannot */
extern const int z;
                                      /* be dynamically initialized
                                                                       */
extern "C++:read/write" const int y; /* in read/write segment */
                                      /* can be dynamically initialized */
extern "C++:read/write"
    const int i=5;
                                      /* placed in read-only segment, */
                                      /* not extern because implicitly static */
    extern const T = 6;
                                     /* placed in read/write segment */
    struct S
                                      /* placed in read/write segment */
        static const T T x;
    }:
}
```

Constant objects must not be redeclared with another linkage. The code in Example 3-3 produces a compile error.

Example 3-3 Compiler error

Because C does not have the linkage specifications, you cannot use a **const** object declared in C++ as extern "C++:read/write" from C.

See also

• --apcs=qualifer...qualifier on page 2-4.

3.5.5 Scalar type constants

Constants of scalar type can be defined within classes. This is an old form. The modern form uses an initialized static data member.

Errors

A warning is issued if you define a member of constant integral type within a class.

Example

```
class A
{
    const int size = 10; // must be static const int size = 10;
    int a[size];
}:
```

3.5.6 Specialization of nonmember function templates

As an extension, it is permitted to specify a storage class on a specialization of a nonmember function template.

3.5.7 Type conversions

Type conversion between a pointer to an extern "C" function and a pointer to an extern "C++" function is permitted.

Example

3.6 Standard C and standard C++ language extensions

The compiler supports numerous extensions to both the ISO C99 and the ISO C++ Standards, such as various integral type extensions, various floating-point extensions, hexadecimal floating-point constants, and anonymous classes, structures, and unions.

These extensions are available if:

- the source language is C++ and you are compiling in non strict mode
- the source language is C99 and you are compiling in non strict mode
- the source language is C90 and you are compiling in non strict mode.

These extensions are not available if:

- the source language is C++ and the compiler is restricted to compiling strict C++ using the --strict compiler option.
- the source language is C99 and the compiler is restricted to compiling strict Standard C using the --strict compiler option.
- the source language is C90 and the compiler is restricted to compiling strict C90 using the --strict compiler option.

3.6.1 Address of a register variable

The address of a variable with **register** storage class can be taken.

Errors

The compiler generates a warning if you take the address of a variable with **register** storage class.

Example

```
void foo(void)
{
    register int i;
    int *j = &i;
}
```

3.6.2 Arguments to functions

Default arguments can be specified for function parameters other than those of a top-level function declaration. For example, they are accepted on typedef declarations and on pointer-to-function and pointer-to-member-function declarations.

3.6.3 Anonymous classes, structures and unions

Anonymous classes, structures, and unions are supported as an extension. Anonymous structures and unions are supported in C and C++.

Anonymous unions are available by default in C++. However, you must specify the anon_unions pragma if you want to use:

- anonymous unions and structures in C
- anonymous classes and structures in C++.

An anonymous union can be introduced into a containing class by a **typedef** name. Unlike a true anonymous union, it does not have to be declared directly. For example:

The extension also enables anonymous classes and anonymous structures, as long as they have no C++ features. For example, no static data members or member functions, no non public members, and no nested types (except anonymous classes, structures, or unions) are allowed in anonymous classes and anonymous structures. For example:

See also

- *Unnamed fields* on page 3-32
- #pragma anon unions, #pragma no anon unions on page 4-58.

3.6.4 Assembler labels

Assembler labels specify the assembler name to use for a C symbol. For example, you might have assembler code and C code that uses the same symbol name, such as counter. Therefore, you can export a different name to be used by the assembler:

```
int counter __asm__("counter_v1") = 0;
```

This exports the symbol counter_v1 and not the symbol counter.

See also

• __*asm* on page 4-5.

3.6.5 Empty declaration

An empty declaration, that is a semicolon with nothing before it, is permitted.

Example

; // do nothing

3.6.6 Hexadecimal floating-point constants

The ARM compiler implements an extension to the syntax of numeric constants in C to enable explicit specification of floating-point constants as IEEE bit patterns.

Syntax

The syntax for specifying floating-point constants as IEEE bit patterns is:

0f_*n* Interpret an 8-digit hex number *n* as a **float** constant. There must be exactly eight digits.

0d_nn Interpret a 16-digit hex number nn as a **double** constant. There must be exactly 16 digits.

3.6.7 Incomplete enums

Forward declarations of enums are supported.

Example

```
enum Incomplete_Enums_0;
int Incomplete_Enums_2 (enum Incomplete_Enums_0 * passon)
{
    return 0;
}
int Incomplete_Enums_1 (enum Incomplete_Enums_0 * passon)
{
```

```
return Incomplete_Enums_2(passon);
}
enum Incomplete_Enums_0 { ALPHA, BETA, GAMMA };
```

3.6.8 Integral type extensions

In an integral constant expression, an integral constant can be cast to a pointer type and then back to an integral type.

3.6.9 Label definitions

In Standard C and Standard C++, a statement must follow a label definition. In C and C++, a label definition can be followed immediately by a right brace.

Errors

The compiler generates a warning if a label definition is followed immediately by a right brace.

Example

```
void foo(char *p)
{
    if (p)
    {
        /* ... */
label:
    }
}
```

3.6.10 Long float

long float is accepted as a synonym for double.

3.6.11 Non static local variables

Non static local variables of an enclosing function can be referenced in a non evaluated expression, for example, a sizeof expression inside a local class. A warning is issued.

3.6.12 Structure, union, enum, and bitfield extensions

The following structure, union, enum, and bitfield extensions are supported:

- In C, the element type of a file-scope array can be an incomplete **struct** or **union** type. The element type must be completed before its size is needed, for example, if the array is subscripted. If the array is not **extern**, the element type must be completed by the end of the compilation.
- The final semicolon preceding the closing brace } of a **struct** or **union** specifier can be omitted. A warning is issued.
- An initializer expression that is a single value and is used to initialize an entire static array, struct, or union, does not have to be enclosed in braces. ISO C requires the braces.
- An extension is supported to enable constructs similar to C++ anonymous unions, including the following:
 - not only anonymous unions but also anonymous structs are permitted. The
 members of anonymous structs are promoted to the scope of the containing
 struct and looked up like ordinary members.
 - they can be introduced into the containing struct by a typedef name. That is, they do not have to be declared directly, as is the case with true anonymous unions.
 - a tag can be declared but only in C mode.

To enable support for anonymous structures and unions, you must use the anon_unions pragma.

- An extra comma is permitted at the end of an **enum** list but a remark is issued.
- **enum** tags can be incomplete. You can define the tag name and resolve it later, by specifying the brace-enclosed list.
- The values of enumeration constants can be given by expressions that evaluate to unsigned quantities that fit in the unsigned int range but not in the int range. For example:

```
/* When ints are 32 bits: */
enum a { w = -2147483648 }; /* No error */
enum b { x = 0x80000000 }; /* No error */
enum c { y = 0x80000001 }; /* No error */
enum d { z = 2147483649 }; /* Error */
```

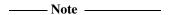
• Bit fields can have base types that are **enum** types or integral types besides **int** and **unsigned int**.

See also

- *Pragmas* on page 4-58
- Structure, union, enum, and bitfield extensions on page 3-23
- New features of C99 on page 5-45 in the Compiler User Guide.

3.7 GNU language extensions

This section describes GNU compiler extensions that are supported by the ARM compiler. These extensions are supported only in GNU mode, that is, when you compile your source code with the --gnu option. See *Language compliance* on page 1-6 and --gnu on page 2-67 for more information.



Not all GNU compiler extensions are supported for all languages. For example, extended pointer arithmetic is not supported for C++.

For more information on the use of the GNU extensions, see the GNU compiler documentation online at http://gcc.gnu.org.

For additional reference material on the ARM compiler see also:

- Appendix B Standard C Implementation Definition
- Appendix C Standard C++ Implementation Definition
- Appendix D C and C++ Compiler Implementation Limits.

3.7.1 Alternate keywords

The compiler recognizes alternate keywords of the form __keyword__. These alternate keywords have the same behavior as the original keywords.

Example

```
\_const\_ int pi = 3.14; // same as const int pi = 3.14
```

3.7.2 asm keyword

This keyword is a synonym for the __asm keyword.

Mode

Supported in GNU mode for C90 and C99 only.

See also

• *asm* on page 4-5.

3.7.3 Case ranges

You can specify ranges of values in **switch** statements.

Example

```
int Case_Ranges_0(int arg)
{
    int aLocal;
    int bLocal =arg;
    switch (bLocal)
    {
        case 0 ... 10:
            aLocal= 1;
            break;
        case 11 ... 100:
            aLocal = 2;
            break;
        default:
            aLocal=-1;
    }
    return aLocal;
}
```

3.7.4 Cast of a union

A cast to a union type is similar to other casts, except that the type specified is a union type. You can specify the type either with a union tag or with a typedef name.

Mode

Supported in GNU mode for C90 and C99 only.

Example

```
typedef union
{
    double d;
    int i;
} foo_t;
int Cast_to_Union_0(int a, double b)
{

    foo_t u;
    if (a>100)
        u = (foo_t) a ; // automatically equivalent to u.i=a;
    else
        u = (foo_t) b ; // automatically equivalent to u.d=b;
    return u.i;
}
```

3.7.5 Character escape sequences

In strings, the escape sequence '\e' is accepted for the escape character <ESC> (ASCII 27).

Example

```
void foo(void)
{
    printf("Escape sequence is: \e\n");
}
```

3.7.6 Compound literals

As in C99, compound literals are supported. All compound literals are Ivalues.

Example

```
int y[] = (int []) \{1, 2, 3\}; // error in strict C99, okay in C99 --gnu int <math>z[] = (int [3]) \{1\};
```

Mode

Supported in GNU mode for C90 and C99 only.



Compound literals can also be used as initializers in C99. However, the compiler is more relaxed about which compound literals it accepts as initializers in GNU mode than it is when compiling C99 source code.

3.7.7 Conditionals

The middle operand in a conditional statement can be omitted, if the result is to be the same as the test.

for example:

Example

The following statements are equivalent:

```
c = i ? : j; // middle operand omitted c = i ? i : j; if (i) c = i; else c = j; // expanded in full
```

This is most useful if the test modifies the value in some way, for example:

```
i++ ? : j;
```

where i++ comes from a macro. If you write code in this way, then i++ is evaluated only once.

If the original value of i is nonzero, the result is the original value of i. Regardless of this, i is incremented once.

Mode

Supported in GNU mode only. Supported languages are C90, C99 and C++.

3.7.8 Designated inits

As in C99, designated initializers are supported.

Example

```
int a[6] = \{ [4] = 29, [2] = 15 \};
int b[6] = \{ 0,0,15,0,29,0 \}; // a[] is equivalent to b[]
```

Mode

Supported in GNU mode for C90 and C++ only.

See also

• New features of C99 on page 5-45 in the Compiler User Guide.

3.7.9 Extended Ivalues

The definition of what constitutes an Ivalue when looking at comma expressions and ?: constructs is relaxed in GNU mode. You can use compound expressions, conditional expressions, and casts as follows:

• You can assign a compound expression:

```
(a++, b) += x;
This is equivalent to:
```

temp =
$$(a++,b)$$
;
b = temp + x

• You can get the address of a compound expression &(a, b). This is equivalent to (a, &b).

• You can use conditional expressions, for example:

```
(a ? b : c) = a;
```

This picks b or c as the destination dependent on a.

Mode

Supported in GNU mode only for C90 and C99 only.

3.7.10 Initializers

As in standard C++ and ISO C99, the elements of an aggregate initializer for an automatic variable are not required to be constant expressions.

Mode

Supported in GNU mode only for C90.

Example

```
float Initializers_0 (float f, float g)
{
    float beat_freqs[2] = { f-g, f+g };
    float aLocal;
    int i=0;
    for (; i<2; i++)
        aLocal += beat_freqs[i];
    return aLocal;
}</pre>
```

3.7.11 Inline

The inline function qualifier is a hint to the compiler that the function is to be inlined.

```
static inline foo (){...}
```

foo is used internally to the file, and the symbol is not exported.

```
inline foo(){...}
```

foo is used internally to the file and an out of line version is made available and the name foo exported.

```
extern inline foo (){...}
```

In GNU mode, foo is used internally if it is inlined. If it is not inlined then an external version is referenced rather than using a call to the internal version. Also, the foo symbol is not emitted.

In non-GNU mode, **extern** is ignored and the functionality is the same as **inline** foo() for C++. In C, you must use __inline. See *Extern inline* functions on page 5-19 for more information.

Mode

Supported in GNU mode only for C90.

3.7.12 Labels as values

The compiler supports GCC labels as values using the && operator.

Mode

Supported in GNU mode for C and C++.

Examples

```
A table of labels:
int f(int n)
{
    void *const table[] = { &&a1, &&a2};
    goto *table[n];
a1: return 1;
a2: return 2;
}
A label used for continuation:
void *toggle(void *lab, int *x)
{
    if (lab) goto *lab;
a1: *x = 1; return &&a2;
a2: *x = 0; return &&a1;
}
```

3.7.13 Pointer arithmetic

You can perform arithmetic on void pointers and function pointers.

The size of a void type or a function type is defined to be 1.

Mode

Supported in GNU mode for C90 and C99 only.

Errors

The compiler generates a warning if it detects arithmetic on **void** pointers or function pointers.

Example

```
int ptr_arith_0(void)
{
    void * pointer;
    return sizeof *pointer;
}
int ptr_arith_1(void)
{
    static int diff;
    diff = ptr_arith_0 - ptr_arith_1;
    return sizeof ptr_arith_0;
}
```

3.7.14 Statement expressions

Statement expressions enable you to place whole sections of code, including declarations, within braces ({ }).

The result of a statement expression is the final item in the statement list.

Restrictions

Branches into a statement expression are not allowed.

In C++ mode, branches out are also not allowed. Variable-length arrays, destructible entities, try, catch, local non-POD class definitions, and dynamically initialized local static variables are not allowed inside a statement expression.

Example

```
int bar(int b, int foo)
{
    if (({
        int y = foo;
        int z;
        if (y > 0) z = y;
        else z = -y;
        z>b;
    }))
```

```
b++;
return b;
}
```

3.7.15 Unnamed fields

When embedding a structure or union within another structure or union, you do not have to name the internal structure. You can access the contents of the unnamed structure without using .name to reference it.

Unnamed fields are the same as anonymous unions and structures.

Mode

Supported in GNU mode for C90 and C99 only.

Example

```
struct
{
    int a;
    union
    {
        int b;
        float c;
    };
    int d;
} Unnamed_Fields_0;
int Unnamed_Fields_1()
{
    return Unnamed_Fields_0.b;
}
```

See also

• *Anonymous classes, structures and unions* on page 3-20.

Chapter 4 Compiler-specific Features

This chapter describes the ARM compiler-specific features, and includes:

- *Keywords and operators* on page 4-2
- __declspec attributes on page 4-24
- Function attributes on page 4-31
- Type attributes on page 4-43
- *Variable attributes* on page 4-47
- *Pragmas* on page 4-58
- *Instruction intrinsics* on page 4-75
- *VFP status intrinsic* on page 4-191
- *Named register variables* on page 4-192
- GNU builtin functions on page 4-195
- *Compiler predefines* on page 4-198.

4.1 Keywords and operators

This section describes the function keywords and operators supported by the ARM compiler armcc.

Table 4-1 lists keywords that are ARM extensions to the C and C++ Standards. Standard C and Standard C++ keywords that do not have behavior or restrictions specific to the ARM compiler are not documented in the table.

Table 4-1 Keyword extensions supported by the ARM compiler

Keywords		
align	int64	svc
ALIGNOF	INTADDR	svc_indirect
asm	irq	svc_indirect_r7
declspec	packed	value_in_regs
forceinline	pure	weak
global_reg	softfp	writeonly
inline	smc	

4.1.1 __align

The __align keyword instructs the compiler to align a variable on an *n*-byte boundary.

__align is a storage class modifier. It does not affect the type of the function.

Syntax

__align(n)

Where:

n is the alignment boundary.

For local variables, *n* can take the values 1, 2, 4, or 8.

For global variables, n can take any value up to 0x80000000 in powers of 2.

The keyword __align comes immediately before the variable name.

Usage

 $_$ align(n) is useful when the normal alignment of the variable being declared is less than n. Eight-byte alignment can give a significant performance advantage with VFP instructions.

__align can be used in conjunction with extern and static.

Restrictions

Because __align is a storage class modifier, it cannot be used on:

- types, including typedefs and structure definitions
- function parameters.

You can only overalign. That is, you can make a two-byte object four-byte aligned but you cannot align a four-byte object at 2 bytes.

Examples

See also

• --min_array_alignment=opt on page 2-91 in the Compiler User Guide.

4.1.2 __alignof__

The __alignof__ keyword enables you to enquire about the alignment of a type or variable.



This keyword is a GNU compiler extension that is supported by the ARM compiler.

Syntax

Return value

__alignof__(*type*) returns the alignment requirement for the type *type*, or 1 if there is no alignment requirement.

__alignof__(expr) returns the alignment requirement for the type of the lvalue expr, or 1 if there is no alignment requirement.

Example

```
int Alignment_0(void)
{
    return __alignof__(int);
}
```

See also

__ALIGNOF___.

4.1.3 __ALIGNOF__

The __ALIGNOF__ keyword returns the alignment requirement for a specified type, or for the type of a specified object.

Syntax

```
__ALIGNOF__(type)
__ALIGNOF__(expr)

Where:
type is a type
expr is an lyalue.
```

Return value

__ALIGNOF__(*type*) returns the alignment requirement for the type *type*, or 1 if there is no alignment requirement.

__ALIGNOF__(*expr*) returns the alignment requirement for the type of the lvalue *expr*, or 1 if there is no alignment requirement. The lvalue itself is not evaluated.

Example

```
typedef struct s_foo { int i; short j; } foo;
typedef __packed struct s_bar { int i; short j; } bar;
return __ALIGNOF(struct s_foo); // returns 4
return __ALIGNOF(foo); // returns 4
return __ALIGNOF(bar); // returns 1
```

See also

• __alignof__ on page 4-3.

4.1.4 __asm

This keyword is used to pass information from the compiler to the ARM assembler armasm.

The precise action of this keyword depends on its usage.

Usage

Embedded assembler

The __asm keyword can be used to declare or define an embedded assembly function. For example:

```
__asm void my_strcpy(const char *src, char *dst);
```

See *Embedded assembler* on page 7-17 in the *Compiler User Guide* for more information.

Inline assembler

The __asm keyword can be used to incorporate inline assembly into a function. For example:

```
int qadd(int i, int j)
{
    int res;
    __asm
    {
```

```
QADD res, i, j
}
return res;
}
```

See Inline assembler on page 7-2 in the Compiler User Guide for more information.

Assembler labels

The __asm keyword can be used to specify an assembler label for a C symbol. For example:

```
int count __asm__("count_v1"); // export count_v1, not count See Assembler labels on page 3-20 for more information.
```

Named register variables

The __asm keyword can be used to declare a named register variable. For example:

```
register int foo __asm("r0");
```

See *Named register variables* on page 4-192 for more information.

See also

asm keyword on page 3-25.

4.1.5 forceinline

The __forceinline keyword forces the compiler to compile a C or C++ function inline.

The semantics of __forceinline are exactly the same as those of the C++ inline keyword. The compiler attempts to inline a function qualified as __forceinline, regardless of its characteristics. However, the compiler does not inline a function if doing so causes problems. For example, a recursive function is inlined into itself only once.

__forceinline is a storage class qualifier. It does not affect the type of a function.

—— Note ———			
This keyword has the function attribute equivalent	attribute	((alwavs	inline))

Example

```
__forceinline static int max(int x, in y)
{
    return x > y ? x : y; // always inline if possible
}
```

See also

- --forceinline on page 2-58
- __attribute__((always_inline)) on page 4-33.

4.1.6 __global_reg

The __global_reg storage class specifier allocates the declared variable to a global variable register.

Syntax

```
__global_reg(n) type varName
```

Where:

n Is an integer between one and eight.

type Is one of the following types:

- any integer type, except long long
- any char type
- any pointer type.

varName Is the name of a variable.

Restrictions

If you use this storage class, you cannot use any additional storage class such as **extern**, **static**, or **typedef**.

In C, global register variables cannot be qualified or initialized at declaration. In C++, any initialization is treated as a dynamic initialization.

The number of available registers varies depending on the variant of the AAPCS being used, there are between five and seven registers available for use as global variable registers.

In practice, it is recommended that you do not use more than:

• three global register variables in ARM or Thumb-2

- one global register variable in Thumb-1
- half the number of available floating-point registers as global floating-point register variables.

If you declare too many global variables, code size increases significantly. In some cases, your program might not compile.



You must take care when using global register variables because:

- There is no check at link time to ensure that direct calls between different compilation units are sensible. If possible, define global register variables used in a program in each compilation unit of the program. In general, it is best to place the definition in a global header file. You must set up the value in the global register early in your code, before the register is used.
- A global register variable maps to a callee-saved register, so its value is saved and restored across a call to a function in a compilation unit that does not use it as a global register variable, such as a library function.
- Calls back into a compilation unit that uses a global register variable are
 dangerous. For example, if a function using a global register is called from a
 compilation unit that does not declare the global register variable, the function
 reads the wrong values from its supposed global register variables.
- This storage class can only be used at file scope.

Example

Example 4-1 declares a global variable register allocated to r5.

Example 4-1 Declaring a global integer register variable

 $__global_reg(2)$ int x; v2 is the synonym for r5

Example 4-2 on page 4-9 produces an error because global registers must be specified in all declarations of the same variable.

Example 4-2 Global register - declaration error

```
int x;
__global_reg(1) int x; // error
```

In C, __global_reg variables cannot be initialized at definition. Example 4-3 produces an error in C, but not in C++.

Example 4-3 Global register - initialization error

```
\__global_reg(1) int x=1; // error in C, OK in C++
```

See also

• --global_reg=reg_name[,reg_name,...] on page 2-67.

4.1.7 __inline

The __inline keyword suggests to the compiler that it compiles a C or C++ function inline, if it is sensible to do so.

The semantics of __inline are exactly the same as those of the **inline** keyword. However, **inline** is not available in C90.

__inline is a storage class qualifier. It does not affect the type of a function.

Example

```
__inline int f(int x)
{
    return x*5+1;
}
int g(int x, int y)
{
    return f(x) + f(y);
}
```

See also

• Function inlining on page 5-18 in the Compiler User Guide.

4.1.8 __int64

The __int64 keyword is a synonym for the keyword sequence long long.

__int64 is accepted even when using --strict.

See also

- --strict, --no_strict on page 2-119
- *long long* on page 3-8.

4.1.9 __INTADDR__

The __INTADDR__ operation treats the enclosed expression as a constant expression, and converts it to an integer constant.

-----Note ------

This is used in the offsetof macro.

Syntax

__INTADDR(expr)

Where:

expr is an integral constant expression.

Return value

__INTADDR__(expr) returns an integer constant equivalent to expr.

See also

• Restrictions on embedded assembly on page 7-19 in the Compiler User Guide.

4.1.10 __irq

The __irq keyword enables a C or C++ function to be used as an interrupt routine.

__irq is a function qualifier. It affects the type of the function.

Restrictions

All corrupted registers except floating-point registers are preserved, not only those that are normally preserved under the AAPCS. The default AAPCS mode must be used.

The function exits by setting the program counter to 1r-4 and the CPSR to the value in
SPSR. No arguments or return values can be used withirq functions.

No	te —	
—— No	te —	

When compiling for a Thumb-only processor, the code is compiled to Thumb code because interrupt handlers are entered in Thumb state. Otherwise, even when compiling for Thumb using the --thumb option or #pragma thumb, any functions specified as __irq are compiled for ARM.

See also

- --thumb on page 2-122
- #pragma thumb on page 4-73
- Chapter 6 *Handling Processor Exceptions* in the *Developer Guide*.

4.1.11 __packed

The __packed qualifier sets the alignment of any valid type to 1. This means that:

- there is no padding inserted to align the packed object
- objects of packed type are read or written using unaligned accesses.

The __packed qualifier applies to all members of a structure or union when it is declared using __packed. There is no padding between members, or at the end of the structure. All substructures of a packed structure must be declared using __packed. Integral subfields of an unpacked structure can be packed individually.

Usage

The __packed qualifier is useful to map a structure to an external data structure, or for accessing unaligned data, but it is generally not useful to save data size because of the relatively high cost of access. Only packing fields in a structure that requires packing can reduce the number of unaligned accesses.



On ARM processors that do not support unaligned access in hardware, for example, pre-ARMv6, access to unaligned data can be costly in terms of code size and execution speed. Data accesses through packed structures must be minimized to avoid increase in code size and performance loss.

Restrictions

The following restrictions apply to the use of __packed:

- The __packed qualifier cannot be used on structures that were previously declared without __packed.
- Unlike other type qualifiers you cannot have both a __packed and non-__packed version of the same structure type.
- The __packed qualifier does not affect local variables of integral type.
- A packed structure or union is not assignment-compatible with the corresponding unpacked structure. Because the structures have a different memory layout, the only way to assign a packed structure to an unpacked structure is by a field-by-field copy.
- The effect of casting away __packed is undefined. The effect of casting a non
 packed structure to a packed structure is undefined. A pointer to an integral type
 can be legally cast, explicitly or implicitly, to a pointer to a packed integral type.
 You can also cast away the __packed on char types.
- There are no packed array types. A packed array is an array of objects of packed type. There is no padding in the array.

Example

Example 4-4 shows that a pointer can point to a packed type.

Example 4-4 Pointer to packed

```
typedef __packed int* PpI;
   __packed int *p;
PpI p2;
/* pointer to a __packed int */
/* pointer to a __packed int */
/* 'p2' has the same type as 'p' */
/* __packed is a qualifier */
/* like 'const' or 'volatile' */
typedef int *PI;
/* pointer to int */
/* pointer to a normal int */
/* -- not the same type as 'p' and 'p2' */
int *_packed p4;
/* 'p4' has the same type as 'p3' */
```

Example 4-5 on page 4-13 shows that when a packed object is accessed using a pointer, the compiler generates code that works and that is independent of the pointer alignment.

Example 4-5 Packed structure

```
typedef __packed struct
                              // all fields inherit the __packed qualifier
    char x;
    int y;
} X;
                              // 5 byte structure, natural alignment = 1
int f(X *p)
                              // does an unaligned read
    return p->y;
typedef struct
    short x;
    char y;
                              // only pack this field
    __packed int z;
    char a;
                              // 8 byte structure, natural alignment = 2
} Y;
int g(Y *p)
                              // only unaligned read for z
    return p->z + p->x;
```

See also

- __attribute__((packed)) on page 4-51
- #pragma pack(n) on page 4-68
- Packed structures on page 5-10
- The __packed qualifier and unaligned data access on page 5-27 in the Compiler User Guide
- __packed structures versus individually __packed fields on page 5-28 in the Compiler User Guide.

4.1.12 __pure

The __pure keyword asserts that a function declaration is pure.

A function is *pure* only if:

- the result depends exclusively on the values of its arguments
- the function has no side effects.

__pure is a function qualifier. It affects the type of a function.



This keyword has the function attribute equivalent __attribute__((const)).

Default

By default, functions are assumed to be impure.

Usage

Pure functions are candidates for common subexpression elimination.

Restrictions

A function that is declared as pure can have no side effects. For example, pure functions:

- cannot call impure functions
- cannot use global variables or dereference pointers, because the compiler assumes that the function does not access memory, except stack memory
- must return the same value each time when called twice with the same parameters.

Example

```
int factr(int n) __pure
{
    int f = 1;
    while (n > 0)
        f *= n--;
    return f;}
```

See also

- __attribute__((const)) on page 4-33
- __pure on page 5-14 in the Compiler User Guide
- Placing ARM function qualifiers on page 5-16 in the Compiler User Guide.

4.1.13 __smc

The __smc keyword declares an SMC (*Secure Monitor Call*) function. A call to the SMC function inserts an SMC instruction into the instruction stream generated by the compiler at the point of function invocation.

—— Note	

The SMC instruction replaces the SMI instruction used in previous versions of the ARM assembly language.

__smc is a function qualifier. It affects the type of a function.

Syntax 1 4 1

```
__smc(int smc_num) return-type function-name([argument-list]);
```

Where:

smc_num

Is a 4-bit immediate value used in the SMC instruction.

The value of smc_num is ignored by the ARM processor, but can be used by the SMC exception handler to determine what service is

being requested.

Restrictions

The SMC instruction is available for selected ARM architecture-based processors, if they have the Security Extensions. See SMC on page 4-140 in the Assembler Guide for more information.

The compiler generates an error if you compile source code containing the __smc keyword for an architecture that does not support the SMC instruction.

Example

```
__smc(5) void mycall(void); /* declare a name by which SMC #5 can be called */
                            /* invoke the function */
mycall();
```

See also

SMC on page 4-140 in the Assembler Guide.

4.1.14 softfp

The __softfp keyword asserts that a function uses software floating-point linkage.

__softfp is a function qualifier. It affects the type of the function.

Note		
This keyword has	the #pragma equivalent #pragma	softfp_linkage

Usage

Calls to the function pass floating-point arguments in integer registers. If the result is a floating-point value, the value is returned in integer registers. This duplicates the behavior of compilation targeting software floating-point.

This keyword enables the same library to be used by sources compiled to use hardware and software floating-point.

Note	
------	--

In C++, if a virtual function qualified with the __softfp keyword is to be overridden, the overriding function must also be declared as __softfp. If the functions do not match, the compiler generates an error.

See also

- --fpu=name on page 2-62
- #pragma softfp_linkage, #pragma no_softfp_linkage on page 4-70
- Floating-point computations and linkage on page 5-37 in the Compiler User Guide.

4.1.15 __svc

The __svc keyword declares a *SuperVisor Call* (SVC) function taking up to four integer-like arguments and returning up to four results in a value_in_regs structure.

__svc is a function qualifier. It affects the type of a function.

Syntax

```
__svc(int svc_num) return-type function-name([argument-list]);
```

Where:

svc_num

Is the immediate value used in the SVC instruction.

It is an expression evaluating to an integer in the range:

- 0 to 2^{24} –1 (a 24-bit value) in an ARM instruction
- 0-255 (an 8-bit value) in a 16-bit Thumb instruction.

Usage

This causes function invocations to be compiled inline as an AAPCS-compliant operation that behaves similarly to a normal call to a function.

The __value_in_regs qualifier can be used to specify that a small structure of up to 16 bytes is returned in registers, rather than by the usual structure-passing mechanism defined in the AAPCS.

Example

Errors

When an ARM architecture variant or ARM architecture-based processor that does not support an SVC instruction is specified on the command line using the --cpu option, the compiler generates an error.

See also

- --cpu=name on page 2-30
- __value_in_regs on page 4-20
- *SVC* on page 4-133 in the *Assembler Guide*.

4.1.16 svc indirect

The __svc_indirect keyword passes an operation code to the SVC handler in r12.

__svc_indirect is a function qualifier. It affects the type of a function.

Syntax

```
__svc_indirect(int svc_num)
    return-type function-name(int real_num[, argument-list]);
```

Where:

svc_num

Is the immediate value used in the SVC instruction.

It is an expression evaluating to an integer in the range:

- 0 to 2²⁴–1 (a 24-bit value) in an ARM instruction
- 0-255 (an 8-bit value) in a 16-bit Thumb instruction.

real_num

Is the value passed in r12 to the handler to determine the function

to perform.

To use the indirect mechanism, your system handlers must make use of the r12 value to select the required operation.

Usage

You can use this feature to implement indirect SVCs.

Example

```
int __svc_indirect(0) ioctl(int svcino, int fn, void *argp);
Calling:
ioctl(IOCTL+4, RESET, NULL);
compiles to SVC #0 with IOCTL+4 in r12.
```

Errors

When an ARM architecture variant or ARM architecture-based processor that does not support an SVC instruction is specified on the command line using the --cpu option, the compiler generates an error.

See also

- --cpu=name on page 2-30
- __value_in_regs on page 4-20
- SVC on page 4-133 in the Assembler Guide.

4.1.17 __svc_indirect_r7

```
The __svc_indirect_r7 keyword behaves like __svc_indirect, but uses r7 instead of r12.
```

__svc_indirect_r7 is a function qualifier. It affects the type of a function.

Syntax

```
__svc_indirect_r7(int svc_num)
    return-type function-name(int real_num[, argument-list]);
```

Where:

svc_num

Is the immediate value used in the SVC instruction.

It is an expression evaluating to an integer in the range:

- 0 to 2²⁴–1 (a 24-bit value) in an ARM instruction
- 0-255 (an 8-bit value) in a 16-bit Thumb instruction.

real_num

Is the value passed in r7 to the handler to determine the function to perform.

Usage

Thumb applications on ARM Linux use __svc_indirect_r7 to make kernel syscalls.

You can also use this feature to implement indirect SVCs.

Example

```
long __svc_indirect_r7(0) \
          SVC_write(unsigned, int fd, const char * buf, size_t count);
#define write(fd, buf, count) SVC_write(4, (fd), (buf), (count))
Calling:
write(fd, buf, count);
compiles to SVC #0 with r0 = fd, r1 = buf, r2 = count, and r7 = 4.
```

Errors

When an ARM architecture variant or ARM architecture-based processor that does not support an SVC instruction is specified on the command line using the --cpu option, the compiler generates an error.

See also

- __value_in_regs on page 4-20
- --cpu=name on page 2-30
- *SVC* on page 4-133 in the *Assembler Guide*.

4.1.18 __value_in_regs

The __value_in_regs qualifier instructs the compiler to return a structure of up to four integer words in integer registers or up to four floats or doubles in floating-point registers rather than using memory.

__value_in_regs is a function qualifier. It affects the type of a function.

Syntax

```
__value_in_regs return-type function-name([argument-list]);
Where:
return-type is the type of a structure of up to four words in size.
```

Usage

Declaring a function __value_in_regs can be useful when calling functions that return more than one result.

Restrictions

A C++ function cannot return a __value_in_regs structure if the structure requires copy constructing.

If a virtual function declared as __value_in_regs is to be overridden, the overriding function must also be declared as __value_in_regs. If the functions do not match, the compiler generates an error.

Errors

Where the structure returned in a function qualified by __value_in_regs is too big, a warning is produced and the __value_in_regs structure is then ignored.

Example

```
typedef struct int64_struct
{
    unsigned int lo;
    unsigned int hi;
} int64_struct;
__value_in_regs extern
    int64_struct mul64(unsigned a, unsigned b);
```

See also

• __value_in_regs on page 5-13 in the Compiler User Guide.

4.1.19 __weak

This keyword instructs the compiler to export symbols weakly.

The __weak keyword can be applied to function and variable declarations, and to function definitions.

Usage

Functions and variable declarations

For declarations, this storage class specifies an **extern** object declaration that, even if not present, does not cause the linker to fault an unresolved reference.

For example:

```
__weak void f(void);
...
f(); // call f weakly
```

If the reference to a missing weak function is made from code that compiles to a branch or branch link instruction, then either:

- The reference is resolved as branching to the next instruction. This effectively makes the branch a NOP.
- The branch is replaced by a NOP instruction.

Function definitions

Functions defined with __weak export their symbols weakly. A weakly defined function behaves like a normally defined function unless a non weakly defined function of the same name is linked into the same image. If both a non weakly defined function and a weakly defined function exist in the same image then all calls to the function resolve to call the non weak function. If multiple weak definitions are available, the linker chooses one for use by all calls.

Functions declared with __weak and then defined without __weak behave as non weak functions.

Restrictions

There are restrictions when you qualify function and variable declarations, and function definitions, with __weak.

Functions and variable declarations

A function or variable cannot be used both weakly and non weakly in the same compilation. For example the following code uses f() weakly from g() and h():

```
void f(void);
void g()
{
    f();
}
__weak void f(void);
void h()
{
    f();
}
```

It is not possible to use a function or variable weakly from the same compilation that defines the function or variable. The following code uses f() non weakly from h():

```
__weak void f(void);
void h()
{
    f();
}
void f() {}
```

The linker does not load the function or variable from a library unless another compilation uses the function or variable non weakly. If the reference remains unresolved, its value is assumed to be NULL. Unresolved references, however, are not NULL if the reference is from code to a position-independent section or to a missing __weak function.

Function definitions

Weakly defined functions cannot be inlined.

Example

4-22

See also

• Chapter 3 *Using armar* in the *Utilities Guide* for more information on library searching.

4.1.20 __writeonly

The __writeonly type qualifier indicates that a data object cannot be read from.

In the C and C++ type system it behaves as a cv-qualifier like **const** or **volatile**. Its specific effect is that an lvalue with __writeonly type cannot be converted to an rvalue.

Assignment to a __writeonly bitfield is not allowed if the assignment is implemented as read-modify-write. This is implementation-dependent.

Example

4.2 __declspec attributes

The __declspec keyword enables you to specify special attributes of objects and functions. For example, you can use the __declspec keyword to declare imported or exported functions and variables, or to declare *Thread Local Storage* (TLS) objects.

The __declspec keyword must prefix the declaration specification. For example:

```
__declspec(noreturn) void overflow(void);
__declspec(thread) int i;
```

Table 4-2 summarizes the available __declspec attributes. __declspec attributes are storage class modifiers. They do not affect the type of a function or variable.

Table 4-2 decispec attributes supported by the compiler and their equivalents

decispec attribute	nondeclspec equivalent
declspec(dllexport)	-
declspec(dllimport)	-
declspec(noinline)	attribute((noinline))
declspec(noreturn)	attribute((noreturn))
declspec(nothrow)	-
declspec(notshared)	-
declspec(thread)	-

4.2.1 __declspec(dllexport)

The __declspec(dllexport) attribute exports the definition of a symbol through the dynamic symbol table when building DLL libraries. On classes, it controls the visibility of class impedimenta such as vtables, construction vtables and RTTI, and sets the default visibility for member functions and static data members.

Usage

You can use __declspec(dllexport) on a function, a class, or on individual members of a class.

When an inline function is marked __declspec(dllexport), the function definition might be inlined, but an out-of-line instance of the function is always generated and exported in the same way as for a non-inline function.

When a class is marked __declspec(dllexport), for example, class __declspec(dllexport) S { ... }; its static data members and member functions are all exported. When individual static data members and member functions are marked with __declspec(dllexport), only those members are exported. vtables,

construction vtable tables and RTTI are also exported.

```
– Note –
```

The following declaration is correct:

```
class __declspec(dllexport) S { ... };
```

The following declaration is incorrect:

```
__declspec(dllexport) class S { ... };
```

In conjunction with --export_all_vtbl, you can use __declspec(notshared) to exempt a class or structure from having its vtable, construction vtable table and RTTI exported. --export_all_vtbl and __declspec(dllexport) are typically not used together.

Restrictions

If you mark a class with __declspec(dllexport), you cannot then mark individual members of that class with __declspec(dllexport).

If you mark a class with __declspec(dllexport), ensure that all of the base classes of that class are marked __declspec(dllexport).

If you export a virtual function within a class, ensure that you either export all of the virtual functions in that class, or that you define them inline so that they are visible to the client.

Example

The __declspec() required in a declaration depends on whether or not the definition is in the same shared library.

```
/* This is the declaration for use in the same shared library as the */
/* definition */
__declspec(dllexport) extern int mymod_get_version(void);
/* Translation unit containing the definition */
__declspec(dllexport) extern int mymod_get_version(void)
{
   return 42;
}
```

```
/* This is the declaration for use in a shared library that does not contain */
/* the definition */
__declspec(dllimport) extern int mymod_get_version(void);
```

As a result of the following macro, a non-defining translation unit in a defining link unit sees __declspec(dllexport).

```
/* mymod.h - interface to my module */
#ifdef BUILDING_MYMOD
#define MYMOD_API __declspec(dllexport)
#else /* not BUILDING_MYMOD */
#define MYMOD_API __declspec(dllimport)
#endif
```

MYMOD_API int mymod_get_version(void);

See also

- __declspec(dllimport)
- *declspec(notshared)* on page 4-29
- --export_all_vtbl, --no_export_all_vtbl on page 2-55
- --use_definition_visibility on page 2-95 in the Linker Reference Guide.

4.2.2 __declspec(dllimport)

The __declspec(dllimport) attribute imports a symbol through the dynamic symbol table when building DLL libraries.

Usage

When an inline function is marked __declspec(dllimport), the function definition in this compilation unit might be inlined, but is never generated out-of-line. An out-of-line call or address reference uses the imported symbol.

You can only use __declspec(dllimport) on **extern** functions and variables, and on classes.

When a class is marked __declspec(dllimport), its static data members and member functions are all imported. When individual static data members and member functions are marked with __declspec(dllimport), only those members are imported.

Restrictions

If you mark a class with __declspec(dllimport), you cannot then mark individual members of that class with __declspec(dllimport).

Examples

```
__declspec(dllimport) int i;
class __declspec(dllimport) X
{
  void f();
}:
```

See also

• __declspec(dllexport) on page 4-24.

4.2.3 __declspec(noinline)

The __declspec(noinline) attribute suppresses the inlining of a function at the call points of the function.

__declspec(noinline) can also be applied to constant data, to prevent the compiler from using the value for optimization purposes, without affecting its placement in the object. This is a feature that can be used for patchable constants, that is, data that is later patched to a different value. It is an error to try to use such constants in a context where a constant value is required. For example, an array dimension.

_____Note _____

This __declspec attribute has the function attribute equivalent __attribute__((noinline)).

Examples

```
/* Prevent y being used for optimization */
__declspec(noinline) const int y = 5;
/* Suppress inlining of foo() wherever foo() is called */
__declspec(noinline) int foo(void);
```

See also

- #pragma inline, #pragma no_inline on page 4-66
- __attribute__((noinline)) on page 4-34.
- *attribute ((noinline)) constant variable attribute* on page 4-51.

4.2.4 __declspec(noreturn)

The __declspec(noreturn) attribute asserts that a function never returns.



This attribute has the function equivalent __attribute((noreturn)). However, __attribute((noreturn)) and __declspec(noreturn) differ in that when compiling a function definition, if the function reaches an explicit or implicit return, __attribute((noreturn)) is ignored and the compiler generates a warning. This does not apply to __declspec(noreturn).

Usage

Use this attribute to reduce the cost of calling a function that never returns, such as exit(). If a noreturn function returns to its caller, the behavior is undefined.

Restrictions

The return address is not preserved when calling the noreturn function. This limits the ability of a debugger to display the call stack.

Example

```
__declspec(noreturn) void overflow(void); // never return on overflow
int negate(int x)
{
    if (x == 0x80000000) overflow();
    return -x;
}
```

See also

• __attribute__((noreturn)) on page 4-36.

4.2.5 __declspec(nothrow)

The __declspec(nothrow) attribute asserts that a call to a function never results in a C++ exception being propagated from the call into the caller.

The ARM library headers automatically add this qualifier to declarations of C functions that, according to the ISO C Standard, can never throw.

Usage

If the compiler knows that a function can never throw out, it might be able to generate smaller exception-handling tables for callers of that function.

Restrictions

If a call to a function results in a C++ exception being propagated from the call into the caller, the behavior is undefined.

This modifier is ignored when not compiling with exceptions enabled.

Example

```
struct S
{
     ~S();
};
__declspec(nothrow) extern void f(void);
void g(void)
{
     S s;
     f();
}
```

See also

- --force_new_nothrow, --no_force_new_nothrow on page 2-57
- *Using the ::operator new function* on page 5-13.

4.2.6 __declspec(notshared)

The __declspec(notshared) attribute prevents a specific class from having its virtual functions table and RTTI exported. This holds true regardless of other options you apply. For example, the use of --export_all_vtbl does not override __declspec(notshared).

Example

4.2.7 __declspec(thread)

The __declspec(thread) attribute asserts that variables are thread-local and have *thread storage duration*, so that the linker arranges for the storage to be allocated automatically when a thread is created.

— Note — The keyword __thread is supported as a synonym for __declspec(thread).

Restrictions

File-scope thread-local variables cannot be dynamically initialized.

Example

```
__declspec(thread) int i;
__thread int j;  // same as __decspec(thread) int j;
```

4.3 Function attributes

The __attribute__ keyword enables you to specify special attributes of variables or structure fields, functions, and types. The keyword format is either:

```
__attribute__ ((attribute1, attribute2, ...))
__attribute__ ((__attribute1__, __attribute2__, ...))
For example:

void * Function_Attributes_malloc_0(int b) __attribute__ ((malloc));
static int b __attribute__ ((__unused__));
```

Table 4-3 summarizes the available function attributes.

Table 4-3 Function attributes supported by the compiler and their equivalents

Function attribute	non-attribute equivalent
attribute((alias))	-
attribute((always_inline))	forceinline
attribute((const))	pure
attribute((deprecated))	-
attribute((malloc))	-
attribute((noinline))	declspec(noinline)
attribute((no_instrument_function))	
attribute((nomerge))	-
attribute((nonnull))	
attribute((noreturn))	declspec(noreturn))
attribute((notailcall))	-
attribute((pure))	-
attribute((unused))	-
attribute((used))	-
attribute((visibility("visibility_type")))	
attribute((weak))	weak
attribute((weakref(" <i>target</i> ")))	

4.3.1 __attribute__((alias))

This function attribute enables you to specify multiple aliases for functions.

Where a function is defined in the current translation unit, the alias call is replaced by a call to the function, and the alias is emitted alongside the original name. Where a function is not defined in the current translation unit, the alias call is replaced by a call to the real function. Where a function is defined as **static**, the function name is replaced by the alias name and the function is declared external if the alias name is declared external.

Note	
This function attribute is a G	NU compiler extension supported by the ARM compile
Note	
Variables names might also b	be aliased using the corresponding variable attribute
attribute((alias)).	

Syntax

```
return-type newname([argument-list]) __attribute__((alias("oldname")));

Where:

oldname is the name of the function to be aliased

newname is the new name of the aliased function.
```

Example

```
#include <stdio.h>
void foo(void)
{
    printf("%s\n", __FUNCTION__);
}
void bar(void) __attribute__((alias("foo")));
void gazonk(void)
{
    bar(); // calls foo
}
```

See also

• __attribute__((alias)) on page 4-47.

4.3.2 __attribute__((always_inline))

This function attribute indicates that a function must be inlined.

The compiler attempts to inline the function, regardless of the characteristics of the function. However, the compiler does not inline a function if doing so causes problems. For example, a recursive function is inlined into itself only once.



This function attribute is a GNU compiler extension that is supported by the ARM compiler. It has the keyword equivalent __forceinline.

Example

```
static int max(int x, int y) __attribute__((always_inline))
{
    return x > y ? x : y; // always inline if possible
}
```

See also

- --forceinline on page 2-58
- __forceinline on page 4-6.

4.3.3 __attribute__((const))

Many functions examine only the arguments passed to them, and have no effects except for the return value. This is a much stricter class than __attribute__((pure)), because a function is not permitted to read global memory. If a function is known to operate only on its arguments then it can be subject to common sub-expression elimination and loop optimizations.



This function attribute is a GNU compiler extension that is supported by the ARM compiler. It has the keyword equivalent __pure.

Example

```
int Function_Attributes_const_0(int b) __attribute__ ((const));
int Function_Attributes_const_2(int b)
{
   int aLocal=0;
   aLocal += Function_Attributes_const_0(b);
```

```
aLocal += Function_Attributes_const_0(b);
return aLocal;
}
```

In this code Function_Attributes_const_0 might be called once only, with the result being doubled to obtain the correct return value.

See also

- __attribute__((pure)) on page 4-37
- __pure on page 5-14 in the Compiler User Guide.

4.3.4 __attribute__((deprecated))

This function attribute indicates that a function exists but the compiler must generate a warning if the deprecated function is used.

_____Note _____

This function attribute is a GNU compiler extension that is supported by the ARM compiler.

Example

int Function_Attributes_deprecated_0(int b) __attribute__ ((deprecated));

4.3.5 __attribute__((malloc))

This function attribute indicates that the function can be treated like malloc and the associated optimizations can be performed.

_____Note _____

This function attribute is a GNU compiler extension that is supported by the ARM compiler.

Example

void * Function_Attributes_malloc_0(int b) __attribute__ ((malloc));

4.3.6 __attribute__((noinline))

This function attribute suppresses the inlining of a function at the call points of the function.

Note	

This function attribute is a GNU compiler extension that is supported by the ARM compiler. It has the __declspec equivalent __declspec(noinline).

Example

```
int fn(void) __attribute__((noinline));
int fn(void)
{
    return 42;
}
```

See also

- #pragma inline, #pragma no_inline on page 4-66
- __attribute__((noinline)) constant variable attribute on page 4-51
- __declspec(noinline) on page 4-27.

4.3.7 __attribute__((no_instrument_function))

This function attribute excludes the function from the instrumentation that is achieved with --qnu_instrument.

See also

• -- gnu instrument, -- no gnu instrument on page 2-68.

4.3.8 __attribute__((nomerge))

This function attribute prevents calls to the function that are distinct in the source from being combined in the object code.

See also

- __attribute__((notailcall)) on page 4-37
- --retain=option on page 2-113.

4.3.9 __attribute__((nonnull))

This function attribute specifies function parameters that are not supposed to be null pointers. This enables the compiler to generate a warning on encountering such a parameter.

This function attribute is a GNU compiler extension that is supported by the ARM compiler.

Syntax

```
__attribute__((nonnull(arg-index, ...)))
```

Where arg-index, ... denotes the argument index list.

If no argument index list is specified, all pointer arguments are marked as nonnull.

Example

The following declarations are equivalent:

```
void * my_memcpy (void *dest, const void *src, size_t len)
__attribute__((nonnull (1, 2)));

void * my_memcpy (void *dest, const void *src, size_t len)
__attribute__((nonnull));
```

4.3.10 __attribute__((noreturn))

This function attribute informs the compiler that the function does not return. The compiler can then perform optimizations by removing the code that is never reached.

Noto	

This function attribute is a GNU compiler extension that is supported by the ARM compiler. It has the __declspec equivalent __declspec(noreturn). However, __attribute((noreturn)) and __declspec(noreturn) differ in that when compiling a function definition, if the function reaches an explicit or implicit return, __attribute((noreturn)) is ignored and the compiler generates a warning. This does not apply to __declspec(noreturn).

Example

int Function_Attributes_NoReturn_0(void) __attribute__ ((noreturn));

See also

• __declspec(noreturn) on page 4-28.

4.3.11 __attribute__((notailcall))

This function attribute prevents tailcalling of the function. That is, the function is always called with a branch-and-link even if (because the call occurs at the end of a function) it could be transferred to by a branch.

See also

- __attribute__((nomerge)) on page 4-35
- --retain=option on page 2-113.

4.3.12 __attribute__((pure))

Many functions have no effects except to return a value, and that the return value depends only on the parameters and global variables. Functions of this kind can be subject to data flow analysis and might be eliminated.



This function attribute is a GNU compiler extension that is supported by the ARM compiler.

Although related, this function attribute is *not* equivalent to the __pure keyword. The function attribute equivalent to __pure is __attribute__((const)).

Example

```
int Function_Attributes_pure_0(int b) __attribute__ ((pure));
int Function_Attributes_pure_0(int b)
{
    static int aStatic;
    aStatic++;
    return b++;
}

int Function_Attributes_pure_2(int b)
{
    int aLocal=0;
    aLocal += Function_Attributes_pure_0(b);
    return 0;
}
```

The call to Function_Attributes_pure_0 in this example might be eliminated because its result is not used.

4.3.13 __attribute__((section("name")))

The section function attribute enables you to place code in different sections of the image.

_____Note _____

This function attribute is a GNU compiler extension that is supported by the ARM compiler.

Example

In the following example, Function_Attributes_section_0 is placed into the RO section new section rather than .text.

```
void Function_Attributes_section_0 (void)
    __attribute__ ((section ("new_section")));
void Function_Attributes_section_0 (void)
{
    static int aStatic =0;
    aStatic++;
}
```

In the following example, section function attribute overrides the #pragma arm section setting.

See also

• #pragma arm section [section sort list] on page 4-59.

4.3.14 __attribute__((unused))

The unused function attribute prevents the compiler from generating warnings if the function is not referenced. This does not change the behavior of the unused function removal process.

_____Note _____

This function attribute is a GNU compiler extension that is supported by the ARM compiler.

Example

static int Function_Attributes_unused_0(int b) __attribute__ ((unused));

4.3.15 __attribute__((used))

This function attribute informs the compiler that a static function is to be retained in the object file, even if it is unreferenced.

Static functions marked as used are emitted to a single section, in the order they are declared. You can specify the section functions are placed in using __attribute__((section)).

—— Note ———

This function attribute is a GNU compiler extension that is supported by the ARM compiler.

—— Note ———

Static variables can also be marked as used using __attribute__((used)).

Example

```
static int lose_this(int);
static int keep_this(int) __attribute__((used));  // retained in object file
static int keep_this_too(int) __attribute__((used)); // retained in object file
```

See also

- __attribute__((section("name"))) on page 4-38.
- __*attribute*__((*used*)) on page 4-54.

4.3.16 __attribute__((visibility("visibility_type")))

This function attribute affects the visibility of ELF symbols.

_____Note _____

This attribute is a GNU compiler extension supported by the ARM compiler.

Syntax

```
__attribute__((visibility("visibility_type")))
```

Where *visibility_type* is one of the following:

default The assumed visibility of symbols can be changed by other options.

Default visibility overrides such changes. Default visibility corresponds

to external linkage.

hidden The symbol is not placed into the dynamic symbol table, so no other

executable or shared library can directly reference it. Indirect references

are possible using function pointers.

internal Unless otherwise specified by the processor-specific Application Binary

Interface (psABI), internal visibility means that the function is never

called from another module.

protected The symbol is placed into the dynamic symbol table, but references

within the defining module bind to the local symbol. That is, the symbol

cannot be overridden by another module.

Usage

Except when specifying default visibility, this attribute is intended for use with declarations that would otherwise have external linkage.

You can use this attribute in C and C++. In C++, it can also be applied to types, member functions, and namespace declarations.

Example

```
void __attribute__((visibility("internal"))) foo()
{
    ...
}
```

See also

- --arm_linux on page 2-9
- --hide_all, --no_hide_all on page 2-71
- __attribute__((visibility("visibility_type"))) on page 4-55.

4.3.17 __attribute__((weak))

Functions defined with __attribute__((weak)) export their symbols weakly.

Functions declared with __attribute__((weak)) and then defined without __attribute__((weak)) behave as *weak* functions. This is not the same behavior as the __weak keyword.

----- Note ------

This function attribute is a GNU compiler extension that is supported by the ARM compiler.

Example

extern int Function_Attributes_weak_0 (int b) __attribute__ ((weak));

See also

• weak on page 4-21.

4.3.18 __attribute__((weakref("target")))

This function attribute marks a function declaration as an alias that does not by itself require a function definition to be given for the target symbol.

----- Note ------

This function attribute is a GNU compiler extension supported by the ARM compiler.

Syntax

__attribute__((weakref("target")))

Where target is the target symbol.

Example

In the following example, foo() calls y() through a weak reference:

```
extern void y(void);
static void x(void) __attribute__((weakref("y")));
void foo (void)
{
    ...
    x();
    ...
}
```

Restrictions

This attribute can only be used on functions with internal linkage.

4.4 Type attributes

The __attribute__ keyword enables you to specify special attributes of variables or structure fields, functions, and types. The keyword format is either:

```
__attribute__ ((attribute1, attribute2, ...))
__attribute__ ((__attribute1__, __attribute2__, ...))
For example:
void * Function_Attributes_malloc_0(int b) __attribute__ ((malloc));
static int b __attribute__ ((__unused__));
```

Table 4-4 summarizes the available type attributes.

Table 4-4 Type attributes supported by the compiler and their equivalents

Type attribute	non-attribute equivalent
attribute((bitband))	-
attribute((aligned))	align
attribute((packed))	packed ^a
attribute((transparent_union))	-

a. The __packed qualifier does not affect type in GNU mode.

4.4.1 __attribute__((bitband))

__attribute__((bitband)) is a type attribute that gives you efficient atomic access to single-bit values in SRAM and Peripheral regions of the memory architecture. It is possible to set or clear a single bit directly with a single memory access in certain memory regions, rather than having to use the traditional read, modify, write approach. It is also possible to read a single bit directly rather than having to use the traditional read then shift and mask operation. Example 4-6 illustrates the use of __attribute__((bitband)).

Example 4-6 Using __attribute__((bitband))

```
typedef struct {
   int i: 1;
   int j: 2;
   int k: 3;
} BB __attribute__((bitband));
```

```
BB bb __attribute__((at(0x20000004)));
void foo(void)
{
    bb.i = 1;
}
```

For peripherals that are width-sensitive, byte, halfword, and word stores or loads to the alias space are generated for **char**, **short**, and **int** types of bitfields of bit-banded structs respectively.

In Example 4-7 bit-banded access is generated for bb.i.

Example 4-7 Bitfield bit-band access

```
typedef struct {
    char i: 1;
    int j: 2;
    int k: 3;
} BB __attribute__((bitband));

BB bb __attribute__((at(0x20000004)));

void foo()
{
    bb.i = 1;
}
```

If you do not use __attribute__((at())) to place the bit-banded variable in the bit-band region then you must relocate it using another method. You can do this by either using an appropriate scatter-loading description file or by using the --rw_base linker command-line option. See the *Linker Reference Guide* for more information.

Restrictions

The following restrictions apply:

- This type attribute can only be used with struct. Any union type or other aggregate type with a union as a member cannot be bit-banded.
- Members of structs cannot be bit-banded individually.
- Bit-banded accesses are generated only for single-bit bitfields.

 Bit-banded accesses are not generated for const objects, pointers, and local objects.

See also

- __attribute__((at(address))) on page 4-48
- *Bit-banding* on page 4-16 in the *Compiler User Guide*
- Technical Reference Manual for your processor.

4.4.2	attribute	((aligned))

The aligned type attribute specifies a minimum alignment for the type.

_____ Note _____

This type attribute is a GNU compiler extension that is supported by the ARM compiler.

4.4.3 __attribute((packed))

The packed type attribute specifies that a type must have the smallest possible alignment.

_____Note _____

This type attribute is a GNU compiler extension that is supported by the ARM compiler.

Errors

The compiler generates a warning message if you use this attribute in a typedef.

See also

- __packed on page 4-11
- #pragma pack(n) on page 4-68
- *Packed structures* on page 5-10
- The __packed qualifier and unaligned data access on page 5-27 in the Compiler User Guide
- __packed structures versus individually __packed fields on page 5-28 in the Compiler User Guide.

4.4.4 __attribute__((transparent_union))

The transparent_union type attribute enables you to specify a *transparent_union type*, that is, a union data type qualified with __attribute__((transparent_union))__.

When a function is defined with a parameter having transparent union type, a call to the function with an argument of any type in the union results in the initialization of a union object whose member has the type of the passed argument and whose value is set to the value of the passed argument.

When a union data type is qualified with __attribute__((transparent_union)), the transparent union applies to all function parameters with that type.

This type attribute is a GNU compiler extension that is supported by the ARM compiler.

_____ Note _____

Individual function parameters might also be qualified with the corresponding __attribute__((transparent_union)) variable attribute.

Example

```
typedef union { int i; float f; } U __attribute__((transparent_union));
void foo(U u)
{
    static int s;
    s += u.i;    /* Use the 'int' field */
}void caller(void)
{
    foo(1);    /* u.i is set to 1 */
    foo(1.0f);    /* u.f is set to 1.0f */
}
```

Mode

Supported in GNU mode only.

See also

• __attribute__((transparent_union)) on page 4-52.

4.5 Variable attributes

The __attribute__ keyword enables you to specify special attributes of variables or structure fields, functions, and types. The keyword format is either:

```
__attribute__ ((attribute1, attribute2, ...))
__attribute__ ((__attribute1__, __attribute2__, ...))
For example:

void * Function_Attributes_malloc_0(int b) __attribute__ ((malloc));
static int b __attribute__ ((__unused__));
```

Table 4-3 on page 4-31 summarizes the available variable attributes.

Table 4-5 Variable attributes supported by the compiler and their equivalents

Variable attribute	non-attribute equivalent
attribute((alias))	-
attribute((at(address)))	-
attribute((aligned))	-
attribute((deprecated))	-
attribute((noinline))	-
attribute((packed))	-
attribute((section("name")))	-
attribute((transparent_union))	-
attribute((unused))	-
attribute((used))	-
attribute((weak))	weak
attribute((weakref(" <i>target</i> ")))	-
attribute((visibility("visibility_type")))	-
attribute((zeroinit))	-

4.5.1 __attribute__((alias))

This variable attribute enables you to specify multiple aliases for variables.

Where a variable is defined in the current translation unit, the alias reference is replaced by a reference to the variable, and the alias is emitted alongside the original name. Where a variable is not defined in the current translation unit, the alias reference is replaced by a reference to the real variable. Where a variable is defined as **static**, the variable name is replaced by the alias name and the variable is declared external if the alias is declared external.



Function names might also be aliased using the corresponding function attribute __attribute__((alias)).

Syntax

```
type newname __attribute__((alias("oldname")));
Where:
oldname is the name of the variable to be aliased
newname is the new name of the aliased variable.
```

Example

```
#include <stdio.h>
int oldname = 1;
extern int newname __attribute__((alias("oldname"))); // declaration
void foo(void)
{
    printf("newname = %d\n", newname); // prints 1
}
```

See also

• __attribute__((alias)) on page 4-32.

4.5.2 __attribute__((at(address)))

This variable attribute enables you to specify the absolute address of a variable.

The variable is placed in its own section, and the section containing the variable is given an appropriate type by the compiler:

- Read-only variables are placed in a section with type RO.
- Initialized read-write variables are placed in a section with type RW.

In particular, variables explicitly initialized to zero are placed in RW not ZI. Such variables are not candidates for the ZI-to-RW optimization of the compiler.

• Uninitialized variables are placed in a section with type ZI.

_____ Note _____

This variable attribute is not supported by GNU compilers.

Syntax

```
__attribute__((at(address)))
```

Where:

address

is the desired address of the variable.

Restrictions

The linker is not always able to place sections produced by the at variable attribute.

Errors

The linker gives an error message if it is not possible to place a section at a specified address.

Example

```
const int x1 __attribute__((at(0x10000))) = 10; /* R0 */
int x2 __attribute__((at(0x12000))) = 10; /* RW */
int x3 __attribute__((at(0x14000))) = 0; /* RW, not ZI */
int x4 __attribute__((at(0x16000))); /* ZI */
```

See also

 Using __at sections to place sections at a specific address on page 5-22 in the Linker User Guide.

4.5.3 __attribute__((aligned))

The aligned variable attribute specifies a minimum alignment for the variable or structure field, measured in bytes.

This variable attribute is a GNU compiler extension that is supported by the ARM compiler.

Example

```
int Variable_Attributes_aligned_0 __attribute__ ((aligned (16)));
/* aligned on 16 byte boundary */
short Variable_Attributes_aligned_1[3] __attribute__ ((aligned));
/* aligns on 4 byte boundary for ARM */
```

See also

• __*align* on page 4-2.

4.5.4 __attribute__((deprecated))

The deprecated variable attribute enables the declaration of a deprecated variable without any warnings or errors being issued by the compiler. However, any access to a deprecated variable creates a warning but still compiles. The warning gives the location where the variable is used and the location where it is defined. This helps you to determine why a particular definition is deprecated.

Note

This variable attribute is a GNU compiler extension that is supported by the ARM compiler.

Example

```
extern int Variable_Attributes_deprecated_0 __attribute__ ((deprecated));
extern int Variable_Attributes_deprecated_1 __attribute__ ((deprecated));
void Variable_Attributes_deprecated_2()
{
    Variable_Attributes_deprecated_0=1;
    Variable_Attributes_deprecated_1=2;
}
```

Compiling this example generates two warning messages.

4.5.5 __attribute__((noinline)) **constant variable attribute**

The noinline variable attribute prevents the compiler from making any use of a constant data value for optimization purposes, without affecting its placement in the object. This feature can be used for patchable constants, that is, data that is later patched to a different value. It is an error to try to use such constants in a context where a constant value is required. For example, an array dimension.

Example

```
__attribute__((noinline)) const int m = 1;
```

See also

- #pragma inline, #pragma no_inline on page 4-66
- __attribute__((noinline)) on page 4-34
- __declspec(noinline) on page 4-27.

4.5.6 __attribute__((packed))

The packed variable attribute specifies that a variable or structure field has the smallest possible alignment. That is, one byte for a variable, and one bit for a field, unless you specify a larger value with the aligned attribute.

_____ Note _____

This variable attribute is a GNU compiler extension that is supported by the ARM compiler.

Example

```
struct
{
    char a;
    int b __attribute__ ((packed));
} Variable_Attributes_packed_0;
```

See also

- $\#pragma\ pack(n)$ on page 4-68
- Packed structures on page 5-10
- The __packed qualifier and unaligned data access on page 5-27 in the Compiler User Guide

• __packed structures versus individually __packed fields on page 5-28 in the Compiler User Guide.

4.5.7 __attribute__((section("name")))

Normally, the ARM compiler places the objects it generates in sections like data and bss. However, you might require additional data sections or you might want a variable to appear in a special section, for example, to map to special hardware. The section attribute specifies that a variable must be placed in a particular data section. If you use the section attribute, read-only variables are placed in RO data sections, read-write variables are placed in RW data sections unless you use the zero_init attribute. In this case, the variable is placed in a ZI section.

——— Note	
----------	--

This variable attribute is a GNU compiler extension supported by the ARM compiler.

Example

```
/* in RO section */
const int descriptor[3] __attribute__ ((section ("descr"))) = { 1,2,3 };
/* in RW section */
long long rw[10] __attribute__ ((section ("RW")));
/* in ZI section *
long long altstack[10] __attribute__ ((section ("STACK"), zero_init));/
```

4.5.8 __attribute__((transparent_union))

The transparent_union variable attribute, attached to a function parameter that is a union, means that the corresponding argument can have the type of any union member, but the argument is passed as if its type were that of the first union member.

The C specification states that the value returned when a union is written as one type and read back with another is undefined. Therefore, a method of distinguishing which type a transparent_union is written in must also be passed as an argument.

——Note	
11010	

This variable attribute is a GNU compiler extension that is supported by the ARM compiler.

You can also use this attribute on a typedef for a union data type. In this case it applies to all function parameters with that type.

Mode

Supported in GNU mode only.

Example

```
typedef union
{
    int myint;
    float myfloat;
} transparent_union_t;
void Variable_Attributes_transparent_union_0(transparent_union_t aUnion
__attribute__ ((transparent_union)))
{
    static int aStatic;
    aStatic +=aUnion.myint;
}
void Variable_Attributes_transparent_union_1()
{
    int aLocal =0;
    float bLocal =0;
    Variable_Attributes_transparent_union_0(aLocal);
    Variable_Attributes_transparent_union_0(bLocal);
}
```

See also

• __attribute__((transparent_union)) on page 4-46.

4.5.9 __attribute__((unused))

Normally, the compiler warns if a variable is declared but is never referenced. This attribute informs the compiler that you expect a variable to be unused and tells it not issue a warning if it is not used.

This variable attribute is a GNU compiler extension that is supported by the ARM compiler.

Example

```
void Variable_Attributes_unused_0()
{
    static int aStatic =0;
    int aUnused __attribute__ ((unused));
    int bUnused;
    aStatic++;
}
```

In this example, the compiler warns that bUnused is declared but never referenced, but does not warn about aUnused.

—— Note ———

The GNU compiler does not give any warning.

4.5.10 __attribute__((used))

This variable attribute informs the compiler that a static variable is to be retained in the object file, even if it is unreferenced.

Static variables marked as used are emitted to a single section, in the order they are declared. You can specify the section that variables are placed in using __attribute__((section)).

_____ Note _____

This variable attribute is a GNU compiler extension that is supported by the ARM compiler.

_____ Note _____

Static functions can also be marked as used using __attribute__((used)).

Usage

You can use __attribute__((used)) to build tables in the object.

Example

See also

- __attribute__((section("name"))) on page 4-52
- __attribute__((used)) on page 4-39.

4.5.11 __attribute__((visibility("visibility_type")))

This variable attribute affects the visibility of ELF symbols.

_____Note _____

This attribute is a GNU compiler extension supported by the ARM compiler.

The possible values for *visibility_type* are the same as those specified for the function attribute of the same name.

Example

int i __attribute__((visibility("hidden")));

See also

- --arm linux on page 2-9
- --hide all, --no hide all on page 2-71
- attribute ((visibility("visibility type"))) on page 4-40.

4.5.12 __attribute__((weak))

The declaration of a weak variable is permitted, and acts in a similar way to __weak.

- in GNU mode:
 - extern int Variable_Attributes_weak_1 __attribute__((weak));
- the equivalent in non-GNU mode is:

__weak int Variable_Attributes_weak_compare;

Nota	

The extern qualifier is required in GNU mode. In non-GNU mode the compiler assumes that if the variable is not extern then it is treated like any other non weak variable.

This variable attribute is a GNU compiler extension that is supported by the ARM compiler.

See also

• __weak on page 4-21.

4.5.13 __attribute__((weakref("target")))

This variable attribute marks a variable declaration as an alias that does not by itself require a definition to be given for the target symbol.

_____ Note _____

This variable attribute is a GNU compiler extension supported by the ARM compiler.

Syntax

```
__attribute__((weakref("target")))
```

Where target is the target symbol.

Example

In the following example, a is assigned the value of y through a weak reference:

```
extern int y;
static int x __attribute__((weakref("y")));

void foo (void)
{
  int a = x;
  ...
}
```

Restrictions

This attribute can only be used on variables that are declared as static.

4.5.14 __attribute__((zero_init))

The section attribute specifies that a variable must be placed in a particular data section. The zero_init attribute specifies that a variable with no initializer is placed in a ZI data section. If an initializer is specified, an error is reported.

Example

See also

• __attribute__((section("name"))) on page 4-52.

4.6 Pragmas

The ARM compiler recognizes a number of ARM-specific pragmas. Table 4-6 summarizes the available pragmas.

_____Note _____

Pragmas override related command-line options. For example, #pragma arm overrides the command-line option --thumb.

Table 4-6 Pragmas supported by the compiler

Pragmas				
<pre>#pragma anon_unions, #pragma no_anon_unions</pre>	#pragma hdrstop	#pragma Otime		
#pragma arm	#pragma import symbol_name	#pragma pack(n)		
<pre>#pragma arm section [section_sort_list]</pre>	<pre>#pragma import(use_full_stdio)</pre>	#pragma pop		
#pragma diag_default tag[,tag,]	<pre>#pragma import(use_smaller_memcp y)</pre>	#pragma push		
<pre>#pragma diag_error tag[,tag,]</pre>	#pragma inline, #pragma no_inline	<pre>#pragma softfp_linkage, no_softfp_linkage</pre>		
#pragma diag_remark tag[,tag,]	#pragma no_pch	#pragma unroll [(n)]		
<pre>#pragma diag_suppress tag[,tag,]</pre>	#pragma O <i>num</i>	<pre>#pragma unroll_completely</pre>		
#pragma diag_warning tag[,tag,]	#pragma once	#pragma thumb		
#pragma [no_]exceptions_unwind	#pragma Ospace			

4.6.1 #pragma anon_unions, #pragma no_anon_unions

These pragmas enable and disable support for anonymous structures and unions.

Default

The default is #pragma no_anon_unions.

See also

- Anonymous classes, structures and unions on page 3-20
- __attribute__((transparent_union)) on page 4-46.

4.6.2 #pragma arm

This pragma switches code generation to the ARM instruction set. It overrides the --thumb compiler option.

See also

- --arm on page 2-8
- --thumb on page 2-122
- #pragma thumb on page 4-73.

4.6.3 #pragma arm section [section_sort_list]

This pragma specifies a section name to be used for subsequent functions or objects. This includes definitions of anonymous objects the compiler creates for initializations.

You can use __attribute__((section(..))) for functions or variables as an alternative to #pragma arm section.

Syntax

#pragma arm section [section_sort_list]

Where:

section_sort_list specifies an optional list of section names to be used for subsequent functions or objects. The syntax of section_sort_list is:

section_type[[=]"name"] [,section_type="name"]*

Valid section types are:

- code
- rodata

- rwdata
- zidata.

Usage

Use a scatter-loading description file with the ARM linker to control how to place a named section at a particular address in memory.

Restrictions

This option has no effect on:

- Inline functions and their local static variables.
- Template instantiations and their local static variables.
- Elimination of unused variables and functions. However, using #pragma arm section enables the linker to eliminate a function or variable that might otherwise be kept because it is in the same section as a used function or variable.
- The order that definitions are written to the object file.

Example

```
int x1 = 5;
                              // in .data (default)
                              // in .bss (default)
int v1[100]:
int const z1[3] = {1,2,3}; // in .constdata (default)
#pragma arm section rwdata = "foo", rodata = "bar"
                             // in foo (data part of region)
int x2 = 5;
                              // in .bss
int y2[100];
int const z2[3] = \{1,2,3\}; // in bar
                              // s2 in foo, "abc" in .conststring
char *s2 = "abc";
#pragma arm section rodata
int x3 = 5;
                              // in foo
int y3[100];
                              // in .bss
int const z3[3] = \{1,2,3\}; // in .constdata
char *s3 = "abc";
                              // s3 in foo, "abc" in .conststring
#pragma arm section code = "foo"
int add1(int x)
                               // in foo (code part of region)
{
    return x+1;
#pragma arm section code
```

See also

• __attribute__((section("name"))) on page 4-38

• Chapter 5 *Using Scatter-loading Description Files* in the *Linker User Guide*.

4.6.4 #pragma diag_default tag[,tag,...]

This pragma returns the severity of the diagnostic messages that have the specified tags to the severities that were in effect before any pragmas were issued.

Syntax

```
#pragma diag_default tag[,tag,...]

Where:

tag[,tag,...] is a comma-separated list of diagnostic message numbers specifying the messages whose severities are to be changed.

At least one diagnostic message number must be specified.
```

Example

```
// <stdio.h> not #included deliberately
#pragma diag_error 223
void hello(void)
{
    printf("Hello ");
}
#pragma diag_default 223
void world(void)
{
    printf("world!\n");
}
```

Compiling this code with the option --diag_warning=223 generates diagnostic messages to report that the function printf() is declared implicitly.

The effect of #pragma diag_default 223 is to return the severity of diagnostic message 223 to Warning severity, as specified by the --diag_warning command-line option.

See also

- --diag_warning=tag[,tag,...] on page 2-48
- #pragma diag_error tag[,tag,...] on page 4-62
- #pragma diag_remark tag[,tag,...] on page 4-62
- #pragma diag suppress tag[,tag,...] on page 4-63
- #pragma diag_warning tag[, tag, ...] on page 4-64

 Controlling the output of diagnostic messages on page 6-4 in the Compiler User Guide.

4.6.5 #pragma diag_error tag[,tag,...]

This pragma sets the diagnostic messages that have the specified tags to Error severity.

Syntax

```
#pragma diag_error tag[,tag,...]
```

Where:

tag[, tag, ...]

is a comma-separated list of diagnostic message numbers specifying the messages whose severities are to be changed.

At least one diagnostic message number must be specified.

See also

- --diag_error=tag[,tag,...] on page 2-44
- #pragma diag_default tag[,tag,...] on page 4-61
- #pragma diag remark tag[,tag,...]
- #pragma diag_suppress tag[,tag,...] on page 4-63
- #pragma diag_warning tag[, tag, ...] on page 4-64
- Changing the severity of diagnostic messages on page 6-5 in the Compiler User Guide.

4.6.6 #pragma diag_remark tag[,tag,...]

This pragma sets the diagnostic messages that have the specified tags to Remark severity.

#pragma diag_remark behaves analogously to #pragma diag_errors, except that the compiler sets the diagnostic messages having the specified tags to Remark severity rather than Error severity.

—— Note ———
Remarks are not displayed by default. Use theremarks compiler option to see remark
messages.

Syntax

#pragma diag_remark tag[,tag,...]

Where:

is a comma-separated list of diagnostic message numbers specifying the messages whose severities are to be changed.

See also

- --diag_remark=tag[,tag,...] on page 2-45
- --remarks on page 2-111
- #pragma diag_default tag[,tag,...] on page 4-61
- #pragma diag_error tag[,tag,...] on page 4-62
- #pragma diag_suppress tag[,tag,...]
- #pragma diag_warning tag[, tag, ...] on page 4-64
- Changing the severity of diagnostic messages on page 6-5 in the Compiler User Guide.

4.6.7 #pragma diag_suppress tag[,tag,...]

This pragma disables all diagnostic messages that have the specified tags.

#pragma diag_suppress behaves analogously to #pragma diag_errors, except that the compiler suppresses the diagnostic messages having the specified tags rather than setting them to have Error severity.

Syntax

```
#pragma diag_suppress tag[,tag,...]
```

Where:

is a comma-separated list of diagnostic message numbers specifying the messages to be suppressed.

- --diag_suppress=tag[,tag,...] on page 2-47
- #pragma diag_default tag[,tag,...] on page 4-61
- #pragma diag_error tag[,tag,...] on page 4-62
- #pragma diag_remark tag[,tag,...] on page 4-62
- #pragma diag_warning tag[, tag, ...] on page 4-64
- Suppressing diagnostic messages on page 6-6 in the Compiler User Guide.

4.6.8 #pragma diag_warning tag[, tag, ...]

This pragma sets the diagnostic messages that have the specified tag(s) to Warning severity.

#pragma diag_remark behaves analogously to #pragma diag_errors, except that the compiler sets the diagnostic messages having the specified tags to Remark severity rather than Error severity.

Syntax

```
#pragma diag_warning tag[,tag,...]
```

Where:

tag[,tag,...] is a comma-separated list of diagnostic message numbers specifying the messages whose severities are to be changed.

See also

- --diag_warning=tag[,tag,...] on page 2-48
- #pragma diag_default tag[,tag,...] on page 4-61
- #pragma diag_error tag[,tag,...] on page 4-62
- #pragma diag_remark tag[,tag,...] on page 4-62
- #pragma diag_suppress tag[,tag,...] on page 4-63
- Changing the severity of diagnostic messages on page 6-5 in the Compiler User Guide.

4.6.9 #pragma exceptions_unwind, #pragma no_exceptions_unwind

These pragmas enable and disable function unwinding at runtime.

Default

The default is #pragma exceptions_unwind.

See also

- --exceptions, --no_exceptions on page 2-54
- --exceptions_unwind, --no_exceptions_unwind on page 2-54
- Function unwinding at runtime on page 5-18.

4.6.10 #pragma hdrstop

This pragma enables you to specify where the set of precompilation header files end.

This pragma must appear before the first token that does not belong to a preprocessing directive.

See also

• *Precompiled header files* on page 2-17 in the *Compiler User Guide*.

4.6.11 #pragma import symbol_name

This pragma generates an importing reference to *symbol_name*. This is the same as the assembler directive:

IMPORT symbol_name

Syntax

#pragma import symbol_name

Where:

symbol_name is a symbol to be imported.

Usage

You can use this pragma to select certain features of the C library, such as the heap implementation or real-time division. If a feature described in this book requires a symbol reference to be imported, the required symbol is specified.

See also

• Building an application with the C library on page 2-19 in the Libraries and Floating Point Support Guide.

4.6.12 #pragma import(__use_full_stdio)

This pragma selects an extended version of microlib that uses full standard ANSI C input and output functionality.

The following exceptions apply:

- feof() and ferror() always return 0
- setvbuf() and setbuf() are guaranteed to fail.

feof() and ferror() always return 0 because the error and end-of-file indicators are not supported.

setvbuf() and setbuf() are guaranteed to fail because all streams are unbuffered.

This version of microlib stdio can be retargeted in the same way as the standardlib stdio functions.

See also

- --library type=lib on page 2-81
- Chapter 3 The C Micro-library in the Libraries and Floating Point Support Guide
- Tailoring the input/output functions on page 2-78 in the Libraries and Floating Point Support Guide.

4.6.13 #pragma import(__use_smaller_memcpy)

This pragma selects a smaller, but slower, version of memcpy() for use with the C micro-library (microlib). A byte-by-byte implementation of memcpy() using LDRB and STRB is used.

Default

The default version of memcpy() used by microlib is a larger, but faster, word-by-word implementation using LDR and STR.

See also

- --library_type=lib on page 2-81
- Chapter 3 The C Micro-library in the Libraries and Floating Point Support Guide.

4.6.14 #pragma inline, #pragma no_inline

These pragmas control inlining, similar to the --inline and --no_inline command-line options. A function defined under #pragma no_inline is not inlined into other functions, and does not have its own calls inlined.

The effect of suppressing inlining into other functions can also be achieved by marking the function as __declspec(noinline) or __attribute__((noinline)).

Default

The default is #pragma inline.

See also

• --inline, --no_inline on page 2-75

- __attribute__((noinline)) constant variable attribute on page 4-51
- __declspec(noinline) on page 4-27
- __attribute__((noinline)) on page 4-34.

4.6.15 #pragma no_pch

This pragma suppresses PCH processing for a given source file.

See also

- --pch on page 2-101
- Precompiled header files on page 2-17 in the Compiler User Guide.

4.6.16 #pragma Onum

This pragma changes the optimization level.

Syntax

#pragma Onum

Where:

num

is the new optimization level.

The value of num is 0, 1, 2 or 3.

See also

-Onum on page 2-96.

4.6.17 #pragma once

This pragma enables the compiler to skips subsequent includes of that header file.

#pragma once is accepted for compatibility with other compilers, and enables you to use other forms of header guard coding. However, it is preferable to use #ifndef and #define coding because this is more portable.

Example

The following example shows the placement of a #ifndef guard around the body of the file, with a #define of the guard variable after the #ifndef.

The #pragma once is marked as optional in this example. This is because the compiler recognizes the #ifndef header guard coding and skips subsequent includes even if #pragma once is absent.

4.6.18 #pragma Ospace

This pragma instructs the compiler to perform optimizations to reduce image size at the expense of a possible increase in execution time.

See also

- #pragma Otime
- -Ospace on page 2-99

4.6.19 #pragma Otime

This pragma instructs the compiler to perform optimizations to reduce execution time at the expense of a possible increase in image size.

See also

- #pragma Ospace
- -Otime on page 2-99.

4.6.20 #pragma pack(n)

This pragma aligns members of a structure to the minimum of n and their natural alignment. Packed objects are read and written using unaligned accesses.

Syntax

```
#pragma pack(n)
```

Where:

n is the alignment in bytes, valid alignment values being 1, 2, 4 and 8.

Default

The default is #pragma pack(8).

Example

This example demonstrates how pack(2) aligns integer variable b to a 2-byte boundary.

```
typedef struct
{
    char a;
    int b;
} S;

#pragma pack(2)

typedef struct
{
    char a;
    int b;
} SP;

S var = { 0x11, 0x44444444 };
SP pvar = { 0x11, 0x44444444 };
```

The layout of S is as shown in Figure 4-1, while the layout of SP is as shown in Figure 4-2. In Figure 4-2, x denotes one byte of padding.

0	1	2	3
a		paddin	g
4	5	6	7
b	b	b	b

Figure 4-1 Nonpacked structure S

0	1	2	3
а	х	b	b
4	5		
b	b		

Figure 4-2 Packed structure SP

_____Note _____

SP is a 6-byte structure. There is no padding after b.

See also

• __*packed* on page 4-11

- attribute ((packed)) on page 4-51
- Packed structures on page 5-10
- The __packed qualifier and unaligned data access on page 5-27 in the Compiler User Guide
- __packed structures versus individually __packed fields on page 5-28 in the Compiler User Guide.

4.6.21 #pragma pop

This pragma restores the previously saved pragma state.

See also

#pragma push.

4.6.22 #pragma push

This pragma saves the current pragma state.

See also

• #pragma pop.

4.6.23 #pragma softfp_linkage, #pragma no_softfp_linkage

These pragmas control software floating-point linkage.

#pragma softfp_linkage asserts that all function declarations up to the next #pragma no_softfp_linkage describe functions that use software floating-point linkage.

Note	
This pragma has the keyword equivalent _	_softfp.

Usage

This pragma can be useful when applied to an entire interface specification, located in the header file, without altering that file.

Default

The default is #pragma no_softfp_linkage.

See also

- ___*softfp* on page 4-15
- Floating-point computations and linkage on page 5-37 in the Compiler User Guide.

4.6.24	#pragma	unroll	[((n))	1

This pragma instructs the compiler to unroll a loop by n interations.

Note Both vectorized and non vectorized loops can be unrolled using #pragma unroll [(n)]. That is, #pragma unroll [(n)] applies to both --vectorize and --no_vectorize.

Syntax

#pragma unroll

#pragma unroll (n)

Where:

n is an optional value indicating the number of iterations to unroll.

Default

If you do not specify a value for *n*, the compiler assumes #pragma unroll (4).

Usage

When compiling at -03 -0time, the compiler automatically unrolls loops where it is beneficial to do so. You can use this pragma to request that the compiler to unroll a loop that has not been unrolled automatically.

Note	

Use this #pragma only when you have evidence, for example from --diag_warning=optimizations, that the compiler is not unrolling loops optimally by itself.

Restrictions

#pragma unroll [(n)] can be used only immediately before a **for** loop, a **while** loop, or a **do** ... **while** loop.

Example

In this example, the compiler does not normally complete its loop analysis because src2 is indexed as src2[j][k] but the loops are nested in the opposite order, that is, with j inside k. When #pragma unroll is uncommented in the example, the compiler proceeds to unroll the loop four times.

If the intention is to multiply a matrix that is not a multiple of four in size, for example an n * n matrix, #pragma unroll (m) might be used instead, where m is some value so that n is an integral multiple of m.

See also

- --diag_warning=optimizations on page 2-49
- -*Onum* on page 2-96
- *-Otime* on page 2-99
- --vectorize, --no vectorize on page 2-131
- #pragma unroll_completely
- *Optimizing loops* on page 5-4 in the *Compiler User Guide*.

4.6.25 #pragma unroll_completely

This pragma instructs the compiler to completely unroll a loop. It has an effect only if the compiler can determine the number of iterations the loop has.

Both vectorized and non vectorized loops can be unrolled using #pragma unroll_completely. That is, #pragma unroll_completely applies to both --no_vectorize and --vectorize.

Usage

When compiling at -03 -0time, the compiler automatically unrolls loops where it is beneficial to do so. You can use this pragma to request that the compiler completely unroll a loop that has not automatically been unrolled completely.

Note	
------	--

Use this #pragma only when you have evidence, for example from --diag_warning=optimizations, that the compiler is not unrolling loops optimally by itself.

Restrictions

#pragma unroll_completely can only be used immediately before a **for** loop, a **while** loop, or a **do** ... **while** loop.

Using #pragma unroll_completely on an outer loop can prevent vectorization. On the other hand, using #pragma unroll_completely on an inner loop might help in some cases.

See also

- --diag_warning=optimizations on page 2-49
- -*Onum* on page 2-96
- -*Otime* on page 2-99
- --vectorize, --no_vectorize on page 2-131
- #pragma unroll [(n)] on page 4-71
- *Optimizing loops* on page 5-4 in the *Compiler User Guide*.

4.6.26 #pragma thumb

This pragma switches code generation to the Thumb instruction set. It overrides the --arm compiler option.

If you are compiling code for a pre-Thumb-2 processor and using VFP, *any* function containing floating-point operations is compiled for ARM.

- --arm on page 2-8
- --thumb on page 2-122
- #pragma arm on page 4-59.

4.7 Instruction intrinsics

This section describes instruction intrinsics for realizing ARM machine language instructions from C or C++ code. Table 4-7 summarizes the available intrinsics.

Table 4-7 Instruction intrinsics supported by the ARM compiler

Instruction intrinsics		
breakpoint	ldrt	schedule_barrier
cdp	memory_changed	semihost
clrex	nop	sev
clz	pld	sqrt
current_pc	pldw	sqrtf
current_sp	pli	ssat
disable_fiq	promise	strex
disable_irq	qadd	strexd
enable_fiq	qdb1	strt
enable_irq	qsub	swp
fabs	rbit	usat
fabsf	rev	wfe
force_stores	return_address	wfi
ldrex	ror	yield
ldrexd		

See also GNU builtin functions on page 4-195.

4.7.1 __breakpoint

This intrinsic inserts a BKPT instruction into the instruction stream generated by the compiler. It enables you to include a breakpoint instruction in your C or C++ code.

Syntax

void __breakpoint(int val)

Where:

is a compile-time constant integer whose range is:

0... 65535 if you are compiling source as ARM code0... 255 if you are compiling source as Thumb code.

Errors

The compiler does not recognize the __breakpoint intrinsic when compiling for a target that does not support the BKPT instruction. The compiler generates either a warning or an error in this case.

The undefined instruction trap is taken if a BKPT instruction is executed on an architecture that does not support it.

Example

```
void func(void)
{
    ...
    __breakpoint(0xF02C);
    ...
}
```

See also

• BKPT on page 4-132 in the Assembler Guide.

4.7.2 cdp

This intrinsic inserts a CDP or CDP2 instruction into the instruction stream generated by the compiler. It enables you to include coprocessor data operations in your C or C++ code.

Syntax

```
__cdp(unsigned int coproc, unsigned int opcode1, unsigned int opcode2)
```

Where:

coproc Identifies the coprocessor the instruction is for.

coproc must be an integer in the range 0 to 15.

opcode1 Is a coprocessor-specific opcode.

Add 0x100 to the opcode to generate a CDP2 instruction.

opcode2 Is a coprocessor-specific opcode.

Usage

The use of these instructions depends on the coprocessor. See your coprocessor documentation for more information.

See also

• *CDP and CDP2* on page 4-124 in the *Assembler Guide*.

4.7.3 __clrex

This intrinsic inserts a CLREX instruction into the instruction stream generated by the compiler. It enables you to include a CLREX instruction in your C or C++ code.

Syntax

void __clrex(void)

Errors

The compiler does not recognize the __clrex intrinsic when compiling for a target that does not support the CLREX instruction. The compiler generates either a warning or an error in this case.

See also

• *CLREX* on page 4-39 in the *Assembler Guide*.

4.7.4 __clz

This intrinsic inserts a CLZ instruction or an equivalent code sequence into the instruction stream generated by the compiler. It enables you to count the number of leading zeros of a data value in your C or C++ code.

Syntax

unsigned char __clz(unsigned int val)

Where:

val is an unsigned int.

Return value

The __clz intrinsic returns the number of leading zeros in *val*.

See also

- Other builtin functions on page 4-197
- *CLZ* on page 4-54 in the *Assembler Guide*.

4.7.5 __current_pc

This intrinsic enables you to determine the current value of the program counter at the point in your program where the intrinsic is used.

Syntax

unsigned int __current_pc(void)

Return value

The __current_pc intrinsic returns the current value of the program counter at the point in the program where the intrinsic is used.

See also

- __current_sp
- return address on page 4-95
- Legacy inline assembler that accesses sp, lr, or pc on page 7-27 in the Compiler User Guide.

4.7.6 __current_sp

This intrinsic returns the value of the stack pointer at the current point in your program.

Syntax

```
unsigned int __current_sp(void)
```

Return value

The __current_sp intrinsic returns the current value of the stack pointer at the point in the program where the intrinsic is used.

See also

- Other builtin functions on page 4-197
- __current_pc on page 4-78
- __return_address on page 4-95
- Legacy inline assembler that accesses sp, lr, or pc on page 7-27 in the Compiler User Guide.

4.7.7 __disable_fig

This intrinsic disables FIQ interrupts.

—— Note ———

Typically, this intrinsic disables FIQ interrupts by setting the F-bit in the CPSR. However, for v7-M it sets the fault mask register (FAULTMASK). FIQ interrupts are not supported in v6-M.

Syntax

```
int __disable_fiq(void);
void __disable_fiq(void);
```

Usage

The function prototype to use for this intrinsic depends on the target architecture you are compiling for. For ARMv7 (--cpu=7), use **void** __disable_fiq(**void**);. For all other architectures, including ARMv7-A, ARMv7-R, and ARMv7-M, you can use int __disable_fiq(**void**); or **void** __disable_fiq(**void**);.

Return value

int __disable_fiq(void); returns the value the FIQ interrupt mask has in the PSR prior
to the disabling of FIQ interrupts.

Restrictions

The difference in function prototypes between the generic ARMv7 architecture and the ARMv7 A, R, and M-profiles exists because the way that the previous FIQ state is returned differs between the M-profile and the A and R-profiles. This means that when you compile with --cpu=7, the compiler is unable to generate an instruction sequence that works on all ARMv7 processors, so you must use the **void** __disable_fiq(**void**); function prototype with --cpu=7.

The __disable_fiq intrinsic can only be executed in privileged modes, that is, in non user modes. In User mode this intrinsic does not change the interrupt flags in the CPSR.

Example

See also

• __enable_fiq on page 4-82.

4.7.8 __disable_irq

This intrinsic disables IRQ interrupts.

_____ Note _____

Typically, this intrinsic disables IRQ interrupts by setting the I-bit in the CPSR. However, for M-profile it sets the exception mask register (PRIMASK).

Syntax

```
int __disable_irq(void);
void __disable_irq(void);
```

Usage

The function prototype to use for this intrinsic depends on the target architecture you are compiling for. For ARMv7 (--cpu=7), use **void** __disable_irq(**void**);. For all other architectures, including ARMv7-A, ARMv7-R, and ARMv7-M, you can use **int** __disable_irq(**void**); or **void** __disable_irq(**void**);.

Return value

int __disable_irq(void); returns the value the IRQ interrupt mask has in the PSR prior
to the disabling of IRQ interrupts.

Example

```
void foo(void)
{
   int was_masked = __disable_irq();
   /* ... */
   if (!was_masked)
        __enable_irq();
}
```

Restrictions

The difference in function prototypes between the generic ARMv7 architecture and the ARMv7 A, R, and M-profiles exists because the way that the previous IRQ state is returned differs between the M-profile and the A and R-profiles. This means that when you compile with --cpu=7, the compiler is unable to generate an instruction sequence that works on all ARMv7 processors, so you must use the **void** __disable_irq(**void**); function prototype with --cpu=7.

The following example illustrates the difference between compiling for ARMv7-M and ARMv7-R:

```
/* test.c */
void DisableIrg(void)
  __disable_irq();
int DisableIrq2(void)
  return __disable_irq();
}
armcc -c --cpu=Cortex-M3 --thumb -o m3.o test.c
  DisableIrq
                                           i
    0x00000000: b672
                            r.
                                  CPSID
                                           1r
    0x00000002: 4770
                            рG
                                  BX
  DisableIrq2
    0x00000004: f3ef8010
                                           r0.PRIMASK
                            . . . .
                                  MRS
    0x00000008: f0000001
                                  AND
                                           r0, r0, #1
                           . . . .
                                  CPSID
    0x0000000c:
                 b672
                                           ٦r
    0x0000000e: 4770
                                  BX
                            рG
armcc -c --cpu=Cortex-R4 --thumb -o r4.o test.c
  DisableIrg
    0x00000000:
                 b672
                                  CPSID
                                           i
                            r.
    0x00000002: 4770
                                  BX
                                           ٦r
                            pG
  DisableIrg2
```

```
      0x00000004:
      f3ef8000
      ....
      MRS
      r0,APSR; formerly CPSR

      0x00000008:
      f00000000
      ....
      AND
      r0,r0,#0x80

      0x00000000c:
      b672
      r.
      CPSID
      i

      0x0000000e:
      4770
      pG
      BX
      lr
```

In all cases, the __disable_irq intrinsic can only be executed in privileged modes, that is, in non user modes. In User mode this intrinsic does not change the interrupt flags in the CPSR.

See also

__enable_irq.

4.7.9 __enable_fig

This intrinsic enables FIQ interrupts.

_____Note _____

Typically, this intrinsic enables FIQ interrupts by clearing the F-bit in the CPSR. However, for v7-M, it clears the fault mask register (FAULTMASK). FIQ interrupts are not supported in v6-M.

Syntax

void __enable_fig(void)

Restrictions

The __enable_fiq intrinsic can only be executed in privileged modes, that is, in non user modes. In User mode this intrinsic does not change the interrupt flags in the CPSR.

See also

__disable_fiq on page 4-79.

4.7.10 __enable_irg

This intrinsic enables IRQ interrupts.

_____Note _____

Typically, this intrinsic enables IRQ interrupts by clearing the I-bit in the CPSR. However, for Cortex M-profile processors, it clears the exception mask register (PRIMASK).

Syntax

void __enable_irq(void)

Restrictions

The __enable_irq intrinsic can only be executed in privileged modes, that is, in non user modes. In User mode this intrinsic does not change the interrupt flags in the CPSR.

See also

• __disable_irq on page 4-80.

4.7.11 __fabs

This intrinsic inserts a VABS instruction or an equivalent code sequence into the instruction stream generated by the compiler. It enables you to obtain the absolute value of a double-precision floating-point value from within your C or C++ code.

The __fabs intrinsic is an analogue of the standard C library function fabs. It differs from the standard library function in that a call to __fabs is guaranteed to be compiled into a single, inline, machine instruction on an ARM architecture-based processor equipped with a VFP coprocessor.

Syntax

double __fabs(double val)

Where:

val is a double-precision floating-point value.

Return value

The __fabs intrinsic returns the absolute value of *va1* as a **double**.

- __*fabsf* on page 4-84
- *VABS, VNEG, and VSQRT* on page 5-95 in the *Assembler Guide*.

4.7.12 __fabsf

This intrinsic is a single-precision version of the __fabs intrinsic. It is functionally equivalent to __fabs, except that:

- it takes an argument of type float instead of an argument of type double
- it returns a **float** value instead of a **double** value.

See also

- __*fabs* on page 4-83
- $V{Q}ABS$ and $V{Q}NEG$ on page 5-56 in the Assembler Guide.

4.7.13 force stores

This intrinsic causes all variables that are visible outside the current function, such as variables that have pointers to them passed into or out of the function, to be written back to memory if they have been changed.

This intrinsic also acts as a scheduling barrier.

Syntax

void __force_stores(void)

See also

- __memory_changed on page 4-88
- __schedule_barrier on page 4-96.

4.7.14 __ldrex

This intrinsic inserts an instruction of the form LDREX[size] into the instruction stream generated by the compiler. It enables you to load data from memory in your C or C++ code using an LDREX instruction. size in LDREX[size] is B for byte stores or H for halfword stores. If no size is specified, word stores are performed.

Syntax

unsigned int __ldrex(volatile void *ptr)

Where:

ptr

points to the address of the data to be loaded from memory. To specify the type of the data to be loaded, cast the parameter to an appropriate pointer type.

Table 4-8 Access widths supported by the __Idrex intrinsic

Instruction	Size of data loaded	C cast
LDREXB	unsigned byte	(unsigned char *)
LDREXB	signed byte	(signed char *)
LDREXH	unsigned halfword	(unsigned short *)
LDREXH	signed halfword	(short *)
LDREX	word	(int *)

Return value

The __ldrex intrinsic returns the data loaded from the memory address pointed to by ptr.

Errors

The compiler does not recognize the __ldrex intrinsic when compiling for a target that does not support the LDREX instruction. The compiler generates either a warning or an error in this case.

The __ldrex intrinsic does not support access to doubleword data. The compiler generates an error if you specify an access width that is not supported.

Example

```
int foo(void)
{
    int loc = 0xff;
    return __ldrex((volatile char *)loc);
}
```

Compiling this code with the command-line option --cpu=6k produces

See also

- ldrexd
- __*strex* on page 4-101
- __*strexd* on page 4-102
- LDREX and STREX on page 4-36 in the Assembler Guide.

4.7.15 __ldrexd

This intrinsic inserts an LDREXD instruction into the instruction stream generated by the compiler. It enables you to load data from memory in your C or C++ code using an LDREXD instruction. It supports access to doubleword data.

Syntax

```
unsigned long long __ldrexd(volatile void *ptr)
```

Where:

ptr

points to the address of the data to be loaded from memory. To specify the type of the data to be loaded, cast the parameter to an appropriate pointer type.

Table 4-9 Access widths supported by the __ldrex intrinsic

Instruction	Size of data loaded	C cast
LDREXD	unsigned long long	(unsigned long long *)
LDREXD	signed long long	(signed long long *)

Return value

The __ldrexd intrinsic returns the data loaded from the memory address pointed to by ptr.

Errors

The compiler does not recognize the __ldrexd intrinsic when compiling for a target that does not support the LDREXD instruction. The compiler generates either a warning or an error in this case.

The __ldrexd intrinsic only supports access to doubleword data. The compiler generates an error if you specify an access width that is not supported.

See also

- __*ldrex* on page 4-84
- __*strex* on page 4-101
- __*strexd* on page 4-102
- LDREX and STREX on page 4-36 in the Assembler Guide.

4.7.16 __ldrt

This intrinsic inserts an assembly language instruction of the form LDR{size}T into the instruction stream generated by the compiler. It enables you to load data from memory in your C or C++ code using an LDRT instruction.

Syntax

unsigned int __ldrt(const volatile void *ptr)

Where:

ptr

Points to the address of the data to be loaded frommemory. To specify the size of the data to be loaded, cast the parameter to an appropriate integral type.

Table 4-10 Access widths supported by the __ldrt intrinsic

Instructiona	Size of data loaded	C cast
LDRSBT	signed byte	(signed char *)
LDRBT	unsigned byte	(char *)
LDRSHT	signed halfword	(signed short int *)
LDRHT	unsigned halfword	(short int *)
LDRT	word	(int *)

a. Or equivalent.

Return value

The __ldrt intrinsic returns the data loaded from the memory address pointed to by ptr.

Errors

The compiler does not recognize the __ldrt intrinsic when compiling for a target that does not support the LDRT instruction. The compiler generates either a warning or an error in this case.

The __ldrt intrinsic does not support access to doubleword data. The compiler generates an error if you specify an access width that is not supported.

Example

```
int foo(void)
{
    int loc = 0xff;
    return __ldrt((const volatile int *)loc);
}
```

Compiling this code with the default options produces:

See also

- --thumb on page 2-122
- LDR and STR (User mode) on page 4-18 in the Assembler Guide.

4.7.17 __memory_changed

This intrinsic causes all variables that are visible outside the current function, such as variables that have pointers to them passed into or out of the function, to be written back to memory if they have been changed, and then to be read back from memory.

This intrinsic also acts as a scheduling barrier.

Syntax

void __memory_changed(void)

See also

- __force_stores on page 4-84
- schedule barrier on page 4-96.

4.7.18 __nop

This intrinsic inserts a NOP instruction or an equivalent code sequence into the instruction stream generated by the compiler. One NOP instruction is generated for each __nop intrinsic in the source.

The compiler does not optimize-away the NOP instructions, except for normal unreachable-code elimination. The __nop intrinsic also acts as a barrier for instruction scheduling in the compiler. That is, instructions are not moved from one side of the NOP to the other as a result of optimization.

Note	
11016	

You can use the __schedule_barrier intrinsic to insert a scheduling barrier without generating a NOP instruction.

Syntax

void __nop(void)

See also

- *sev* on page 4-98
- __schedule_barrier on page 4-96
- __wfe on page 4-107
- *wfi* on page 4-107
- *yield* on page 4-108
- NOP, SEV, WFE, WFI, and YIELD on page 4-142 in the Assembler Guide
- *Generic intrinsics* on page 4-3 in the *Compiler User Guide*.

4.7.19 __pld

This intrinsic inserts a data prefetch, for example PLD, into the instruction stream generated by the compiler. It enables you to signal to the memory system from your C or C++ program that a data load from an address is likely in the near future.

Syntax

```
\mathsf{void} \ \_\mathsf{pld}(\dots)
```

Where:

.. denotes any number of pointer or integer arguments specifying addresses of memory to prefetch.

Restrictions

If the target architecture does not support data prefetching, this intrinsic has no effect.

Example

See also

- __pldw
- __*pli* on page 4-91
- PLD, PLDW, and PLI on page 4-25 in the Assembler Guide.

4.7.20 __pldw

This intrinsic inserts a PLDW instruction into the instruction stream generated by the compiler. It enables you to signal to the memory system from your C or C++ program that a data load from an address with an intention to write is likely in the near future.

Syntax

```
void __pldw(...)
```

Where:

.. denotes any number of pointer or integer arguments specifying addresses of memory to prefetch.

Restrictions

If the target architecture does not support data prefetching, this intrinsic has no effect.

This intrinsic only takes effect in ARMv7 architectures and above that provide Multiprocessing Extensions. That is, when the predefined macro __TARGET_FEATURE_MULTIPROCESSING is defined.

Example

```
void foo(int *bar)
{
    __pldw(bar);
}
```

See also

- Compiler predefines on page 4-198
- __*pld* on page 4-89
- __pli
- PLD, PLDW, and PLI on page 4-25 in the Assembler Guide.

4.7.21 __pli

This intrinsic inserts an instruction prefetch, for example PLI, into the instruction stream generated by the compiler. It enables you to signal to the memory system from your C or C++ program that an instruction load from an address is likely in the near future.

Syntax

```
void __pli(...)
```

Where:

... denotes any number of pointer or integer arguments specifying addresses of instructions to prefetch.

Restrictions

If the target architecture does not support instruction prefetching, this intrinsic has no effect.

- __pld on page 4-89
- __pldw on page 4-90

• PLD, PLDW, and PLI on page 4-25 in the Assembler Guide.

4.7.22 __promise

This intrinsic promises the compiler that a given expression is nonzero. This enables the compiler to perform more aggressive optimization when vectorizing code.

Syntax

```
void __promise(expr)
```

Where *expr* is an expression that evaluates to nonzero.

See also

 Using __promise to improve vectorization on page 3-17 in the Compiler User Guide.

4.7.23 __qadd

This intrinsic inserts a QADD instruction or an equivalent code sequence into the instruction stream generated by the compiler. It enables you to obtain the saturating add of two integers from within your C or C++ code.

Syntax

```
int __qadd(int val1, int val2)
```

Where:

vall is the first summand of the saturating add operationvall is the second summand of the saturating add operation.

Return value

The __qadd intrinsic returns the saturating add of val1 and val2.

- __*qdbl* on page 4-93
- __*qsub* on page 4-93
- QADD, QSUB, QDADD, and QDSUB on page 4-94 in the Assembler Guide.

4.7.24 __qdb1

This intrinsic inserts instructions equivalent to the saturating add of an integer with itself into the instruction stream generated by the compiler. It enables you to obtain the saturating double of an integer from within your C or C++ code.

Syntax

```
int __qdbl(int val)
```

Where:

va1

is the data value to be doubled.

Return value

The __qdbl intrinsic returns the saturating add of *val* with itself, or equivalently, __qadd(*val*, *val*).

See also

• __*qadd* on page 4-92.

4.7.25 __qsub

This intrinsic inserts a QSUB instruction or an equivalent code sequence into the instruction stream generated by the compiler. It enables you to obtain the saturating subtraction of two integers from within your C or C++ code.

Syntax

```
int __qsub(int val1, int val2)
```

Where:

vall is the minuend of the saturating subtraction operation vall is the subtrahend of the saturating subtraction operation.

Return value

The __qsub intrinsic returns the saturating subtraction of *val1* and *val2*.

- *gadd* on page 4-92
- QADD, QSUB, QDADD, and QDSUB on page 4-94 in the Assembler Guide.

4.7.26 __rbit

This intrinsic inserts an RBIT instruction into the instruction stream generated by the compiler. It enables you to reverse the bit order in a 32-bit word from within your C or C++ code.

Syntax

Return value

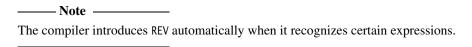
The __rbit intrinsic returns the value obtained from val by reversing its bit order.

See also

• REV, REV16, REVSH, and RBIT on page 4-65 in the Assembler Guide.

4.7.27 __rev

This intrinsic inserts a REV instruction or an equivalent code sequence into the instruction stream generated by the compiler. It enables you to convert a 32-bit big-endian data value into a little-endian data value, or a 32-bit little-endian data value into big-endian data value from within your C or C++ code.



Syntax

```
unsigned int __rev(unsigned int val)
Where:
val is an unsigned int.
```

Return value

The __rev intrinsic returns the value obtained from val by reversing its byte order.

See also

• REV, REV16, REVSH, and RBIT on page 4-65 in the Assembler Guide.

4.7.28 __return_address

This intrinsic returns the return address of the current function.

Syntax

unsigned int __return_address(void)

Return value

The __return_address intrinsic returns the value of the link register that is used in returning from the current function.

Restrictions

The __return_address intrinsic does *not* affect the ability of the compiler to perform optimizations such as inlining, tail-calling, and code sharing. Where optimizations are made, the value returned by __return_address reflects the optimizations performed:

No optimization

When no optimizations are performed, the value returned by __return_address from within a function foo is the return address of foo.

Inline optimization

If a function foo is inlined into a function bar then the value returned by __return_address from within foo is the return address of bar.

Tail-call optimization

If a function foo is tail-called from a function bar then the value returned by __return_address from within foo is the return address of bar.

- Other builtin functions on page 4-197
- __current_pc on page 4-78
- __current_sp on page 4-78
- Legacy inline assembler that accesses sp, lr, or pc on page 7-27 in the Compiler User Guide.

4.7.29 __ror

This intrinsic inserts a ROR instruction or operand rotation into the instruction stream generated by the compiler. It enables you to rotate a value right by a specified number of places from within your C or C++ code.

_____Note _____

The compiler introduces ROR automatically when it recognizes certain expressions.

Syntax

unsigned int __ror(unsigned int val, unsigned int shift)

Where:

val is the value to be shifted right

shift is a constant shift in the range 1-31.

Return value

The __ror intrinsic returns the value of val rotated right by shift number of places.

See also

• ASR, LSL, LSR, ROR, and RRX on page 4-67 in the Assembler Guide.

4.7.30 __schedule_barrier

This intrinsic creates a sequence point where operations before and operations after the sequence point are not merged by the compiler. A scheduling barrier does not cause memory to be updated. If variables are held in registers they are updated in place, and not written out.

This intrinsic is similar to the __nop intrinsic, except that no NOP instruction is generated.

Syntax

void __schedule_barrier(void)

See also

• __*nop* on page 4-89

4.7.31 __semihost

This intrinsic inserts an SVC or BKPT instruction into the instruction stream generated by the compiler. It enables you to make semihosting calls from C or C++ that are independent of the target architecture.

Syntax

int __semihost(int val, const void *ptr)

Where:

val Is the request code for the semihosting request.

See Chapter 8 Semihosting in the Developer Guide for more information.

ptr Is a pointer to an argument/result block.

See Chapter 8 Semihosting in the Developer Guide for more information.

Return value

See Chapter 8 *Semihosting* in the *Developer Guide* for more information on the results of semihosting calls.

Usage

Use this intrinsic from C or C++ to generate the appropriate semihosting call for your target and instruction set:

SVC 0x123456 In ARM state for all architectures.

SVC 0xAB In Thumb state, excluding ARMv7-M. This behavior is not

guaranteed on all debug targets from ARM or from third parties.

BKPT 0xAB For ARMv7-M, Thumb-2 only.

Restrictions

ARM processors prior to ARMv7 use SVC instructions to make semihosting calls. However, if you are compiling for a Cortex M-profile processor, semihosting is implemented using the BKPT instruction.

Example

Compiling this code with the option -- thumb generates:

```
||foo|| PROC
...
LDR r1,|L1.12|
MOVS r0,#1
SVC #0xab
...
|L1.12|
...
buffer
% 400
```

See also

- --cpu=list on page 2-30
- --thumb on page 2-122
- __*svc* on page 4-16
- BKPT on page 4-132 in the Assembler Guide
- SVC on page 4-133 in the Assembler Guide
- Chapter 8 Semihosting in the Developer Guide.

4.7.32 __sev

This intrinsic inserts a SEV instruction into the instruction stream generated by the compiler.

Syntax

```
void __sev(void)
```

Errors

The compiler does not recognize the __sev intrinsic when compiling for a target that does not support the SEV instruction. The compiler generates either a warning or an error in this case.

See also

- __*nop* on page 4-89
- __wfe on page 4-107
- __wfi on page 4-107
- __yield on page 4-108
- NOP, SEV, WFE, WFI, and YIELD on page 4-142 in the Assembler Guide.

4.7.33 __sqrt

This intrinsic inserts a VFP VSQRT instruction into the instruction stream generated by the compiler. It enables you to obtain the square root of a double-precision floating-point value from within your C or C++ code.

_____Note _____

The __sqrt intrinsic is an analogue of the standard C library function sqrt. It differs from the standard library function in that a call to __sqrt is guaranteed to be compiled into a single, inline, machine instruction on an ARM architecture-based processor equipped with a VFP coprocessor.

Syntax

double __sqrt(double val)

Where:

val is a double-precision floating-point value.

Return value

The __sqrt intrinsic returns the square root of *va1* as a **double**.

Errors

The compiler does not recognize the __sqrt intrinsic when compiling for a target that is not equipped with a VFP coprocessor. The compiler generates either a warning or an error in this case.

See also

- __sqrtf
- VABS, VNEG, and VSQRT on page 5-95 in the Assembler Guide.

4.7.34 __sqrtf

This intrinsic is a single-precision version of the __sqrtf intrinsic. It is functionally equivalent to __sqrt, except that:

- it takes an argument of type float instead of an argument of type double
- it returns a **float** value instead of a **double** value.

See also

- __*sqrt* on page 4-99
- VABS, VNEG, and VSQRT on page 5-95 in the Assembler Guide.

4.7.35 __ssat

This intrinsic inserts an SSAT instruction into the instruction stream generated by the compiler. It enables you to saturate a signed value from within your C or C++ code.

Syntax

```
int __ssat(int val, unsigned int sat)
```

Where:

Is the value to be saturated. va1

sat Is the bit position to saturate to.

sat must be in the range 1 to 32.

Return value

The __ssat intrinsic returns va7 saturated to the signed range $-2^{sat-1} \le x \le 2^{sat-1} - 1$.

Errors

The compiler does not recognize the __ssat intrinsic when compiling for a target that does not support the SSAT instruction. The compiler generates either a warning or an error in this case.

See also

- __*usat* on page 4-106
- SSAT and USAT on page 4-96 in the Assembler Guide.

4.7.36 __strex

This intrinsic inserts an instruction of the form STREX[size] into the instruction stream generated by the compiler. It enables you to use an STREX instruction in your C or C++ code to store data to memory.

Syntax

int __strex(unsigned int val, volatile void *ptr)

Where:

val is the value to be written to memory.

ptr points to the address of the data to be written to in memory. To specify

the size of the data to be written, cast the parameter to an appropriate

integral type.

Table 4-11 Access widths supported by the __strex intrinsic

Instruction	Size of data stored	C cast
STREXB	unsigned byte	(char *)
STREXH	unsigned halfword	(short *)
STREX	word	(int *)

Return value

The __strex intrinsic returns:

0 if the STREX instruction succeeds

1 if the STREX instruction is locked out.

Errors

The compiler does not recognize the __strex intrinsic when compiling for a target that does not support the STREX instruction. The compiler generates either a warning or an error in this case.

The __strex intrinsic does not support access to doubleword data. The compiler generates an error if you specify an access width that is not supported.

Example

```
int foo(void)
{
    int loc=0xff;
    return(!__strex(0x20, (volatile char *)loc));
}
```

Compiling this code with the command-line option --cpu=6k produces

See also

- __*ldrex* on page 4-84
- __ldrexd on page 4-86
- __strexd
- LDREX and STREX on page 4-36 in the Assembler Guide.

4.7.37 __strexd

This intrinsic inserts an STREXD instruction into the instruction stream generated by the compiler. It enables you to use an STREXD instruction in your C or C++ code to store data to memory. It supports exclusive stores of doubleword data to memory.

Syntax

```
int \_strexd(unsigned long long val, volatile void *ptr) Where:

val is the value to be written to memory.
```

ptr

points to the address of the data to be written to in memory. To specify the size of the data to be written, cast the parameter to an appropriate integral type.

Table 4-12 Access widths supported by the __strexd intrinsic

Instruction	Size of data stored	C cast
STREXD	unsigned long long	(unsigned long long *)
STREXD	signed long long	(signed long long *)

Return value

Errors

The compiler does not recognize the __strexd intrinsic when compiling for a target that does not support the STREXD instruction. The compiler generates either a warning or an error in this case.

The __strexd intrinsic only supports access to doubleword data. The compiler generates an error if you specify an access width that is not supported.

See also

- __*ldrex* on page 4-84
- __ldrexd on page 4-86
- __*strex* on page 4-101
- LDREX and STREX on page 4-36 in the Assembler Guide.

4.7.38 __strt

This intrinsic inserts an assembly language instruction of the form STR{size}T into the instruction stream generated by the compiler. It enables you to store data to memory in your C or C++ code using an STRT instruction.

Syntax

void __strt(unsigned int val, volatile void *ptr)

Where:

Is the value to be written to memory.

Points to the address of the data to be written to in memory. To specify the size of the data to be written, cast the parameter to an appropriate

integral type.

Table 4-13 Access widths supported by the __strt intrinsic

Instruction	Size of data loaded	C cast
STRBT	unsigned byte	(char *)
STRHT	unsigned halfword	(short int *)
STRT	word	(int *)

Errors

The compiler does not recognize the __strt intrinsic when compiling for a target that does not support the STRT instruction. The compiler generates either a warning or an error in this case.

The __strt intrinsic does not support access either to signed data or to doubleword data. The compiler generates an error if you specify an access width that is not supported.

Example

```
void foo(void)
{
    int loc=0xff;
    __strt(0x20, (volatile char *)loc);
}
```

Compiling this code produces:

```
||foo|| PROC

MOV r0,#0xff

MOV r1,#0x20

STRBT r1,[r0],#0

BX lr

ENDP
```

- --thumb on page 2-122
- *LDR and STR (User mode)* on page 4-18 in the *Assembler Guide*.

4.7.39 __swp

This intrinsic inserts a SWP{size} instruction into the instruction stream generated by the compiler. It enables you to swap data between memory locations from your C or C++ code.

_____Note _____

The use of SWP and SWPB is deprecated in ARMv6 and above.

Syntax

```
unsigned int __swp(unsigned int val, volatile void *ptr)
```

where:

Val Is the data value to be written to memory.

ptr

Points to the address of the data to be written to in memory. To specify the size of the data to be written, cast the parameter to an appropriate integral type.

Table 4-14 Access widths supported by the __swp intrinsic

Instruction	Size of data loaded	C cast
SWPB	unsigned byte	(char *)
SWP	word	(int *)

Return value

The __swp intrinsic returns the data value that previously, is in the memory address pointed to by *ptr*, before this value is overwitten by *va1*.

Example

```
int foo(void)
{
    int loc=0xff;
    return(__swp(0x20, (volatile int *)loc));
}
```

Compiling this code produces

```
||foo|| PROC

MOV r1, #0xff

MOV r0, #0x20

SWP r0, r0, [r1]

BX lr

ENDP
```

See also

• *SWP and SWPB* on page 4-40 in the *Assembler Guide*.

4.7.40 __usat

This intrinsic inserts a USAT instruction into the instruction stream generated by the compiler. It enables you to saturate an unsigned value from within your C or C++ code.

Syntax

Return value

The _usat intrinsic returns *va1* saturated to the unsigned range $0 \le x \le 2^{sat-1} - 1$.

Errors

The compiler does not recognize the __usat intrinsic when compiling for a target that does not support the USAT instruction. The compiler generates either a warning or an error in this case.

- __ssat on page 4-100
- SSAT and USAT on page 4-96 in the Assembler Guide.

4.7.41 wfe

This intrinsic inserts a WFE instruction into the instruction stream generated by the compiler.

On the v6T2 architecture, the WFE instruction is executed as a NOP instruction.

Syntax

```
void __wfe(void)
```

Errors

The compiler does not recognize the __wfe intrinsic when compiling for a target that does not support the WFE instruction. The compiler generates either a warning or an error in this case.

See also

- __wfi
- __*nop* on page 4-89
- __*sev* on page 4-98
- __yield on page 4-108
- NOP, SEV, WFE, WFI, and YIELD on page 4-142 in the Assembler Guide.

4.7.42 __wfi

This intrinsic inserts a WFI instruction into the instruction stream generated by the compiler.

On the v6T2 architecture, the WFI instruction is executed as a NOP instruction.

Syntax

```
void __wfi(void)
```

Errors

The compiler does not recognize the __wfi intrinsic when compiling for a target that does not support the WFI instruction. The compiler generates either a warning or an error in this case.

See also

• ___yield on page 4-108

- __*nop* on page 4-89
- __*sev* on page 4-98
- __wfe on page 4-107
- NOP, SEV, WFE, WFI, and YIELD on page 4-142 in the Assembler Guide.

4.7.43 __yield

This intrinsic inserts a YIELD instruction into the instruction stream generated by the compiler.

Syntax

void __yield(void)

Errors

The compiler does not recognize the __yield intrinsic when compiling for a target that does not support the YIELD instruction. The compiler generates either a warning or an error in this case.

- __*nop* on page 4-89
- __*sev* on page 4-98
- __wfe on page 4-107
- __wfi on page 4-107
- NOP, SEV, WFE, WFI, and YIELD on page 4-142 in the Assembler Guide.

4.7.44 ARMv6 SIMD intrinsics

The ARM Architecture v6 Instruction Set Architecture adds many *Single Instruction Multiple Data* (SIMD) instructions to ARMv6 for the efficient software implementation of high-performance media applications.

The ARM compiler supports intrinsics that map to the ARMv6 SIMD instructions. These intrinsics are available when compiling your code for an ARMv6 architecture or processor. If the chosen architecture does not support the ARMv6 SIMD instructions, compilation generates a warning and subsequent linkage fails with an undefined symbol reference.

Note	
------	--

Each ARMv6 SIMD intrinsic is guaranteed to be compiled into a single, inline, machine instruction for an ARM v6 architecture or processor. However, the compiler might use optimized forms of underlying instructions when it detects opportunities to do so.

The ARMv6 SIMD instructions can set the GE[3:0] bits in the *Application Program Status Register* (APSR). Some SIMD instructions update these flags to indicate the *greater than or equal to* status of each 8 or 16-bit slice of an SIMD operation.

The ARM compiler treats the GE[3:0] bits as a global variable. To access these bits from within your C or C++ program, either:

- access bits 16-19 of the APSR through a named register variable
- use the __sel intrinsic to control a SEL instruction.

See also

Reference

- ARMv6 SIMD intrinsics according to prefix on page 4-110
- ARMv6 SIMD intrinsics, summary descriptions, byte lanes, side-effects on page 4-112
- ARMv6 SIMD intrinsics, compatible processors and architectures on page 4-117
- ARMv6 SIMD instruction intrinsics and APSR GE flags on page 4-118
- ARMv6 SIMD instruction intrinsics by alphabetical listing on page 4-120
- Named register variables on page 4-192
- Registers on page 2-6 in the Assembler Guide
- SEL on page 4-63 in the Assembler Guide
- Chapter 5 NEON and VFP Programming in the Assembler Guide.

4.7.45 ARMv6 SIMD intrinsics according to prefix

Table 4-15

	ARMv6 SIMD instruction intrinsics grouped by prefix					refix
Intrinsic classification	S ^a	q b	shc	ud	uqe	uhf
Byte addition	sadd8	qadd8	shadd8	usadd8	uqadd8	uhadd8
Byte subtraction	ssub8	qsub8	shsub8	usub8	uqsub8	uhsub8
Halfword addition	sadd16	qadd16	shadd16	uadd16	uqadd16	uhadd16
Halfword subtraction	ssub16	qsub16	shsub16	usub16	uqsub16	uhsub16
Exchange halfwords within one operand, add high halfwords, subtract low halfwords	sasx	qasx	shasx	uasx	uqasx	uhasx
Exchange halfwords within one operand, subtract high halfwords, add low halfwords	ssax	qsax	shsax	usax	uqsax	uhsax
Unsigned sum of absolute difference	-	-	-	usad8	-	-
Unsigned sum of absolute difference and accumulate	-	-	-	usada8	-	-
Signed saturation to selected width	ssat16	-	-	-	-	-
Extract values (bit positions [23:16][7:0]), zero-extend to 16 bits	-	-	-	uxtb16	-	-
Extract values (bit positions [23:16][7:0]) from second operand, zero-extend to 16 bits, add to first operand	-	-	-	uxtab16	-	-
Sign-extend	sxtb16	-	-	-	-	-
Sign-extend, add	sxtab16	-	-	-	-	-
Signed multiply, add products	smuad	-	-	-	-	-
Signed multiply, subtract products	smusd	-	-	-	-	-
Exchange halfwords of one operand, signed multiply, subtract products	smusdx	-	-	-	-	-
Signed multiply, add both results to another operand	smlad	-	-	-	-	-

Table 4-15 (continued)

	ARMv6 SIMD instruction intrinsics grouped by prefix					prefix
Intrinsic classification	S a	q b	shc	ud	uq ^e	uhf
Exchange halfwords of one operand, perform 2x16-bit multiplication, add both results to another operand	smladx	-	-	-	-	-
Perform 2x16-bit multiplication, add both results to another operand	smlald	-	-	-	-	-
Exchange halfwords of one operand, perform 2x16-bit multiplication, add both results to another operand	smlaldx	-	-	-	-	-
Exchange halfwords of one operand, perform two signed 16-bit multiplications, add difference of products to a 32-bit accumulate operand.	smlsdx	-	-	-	-	-

- a. Signed
- b. Signed saturating
- c. Signed halving
- d. Unsigned
- e. Unsigned saturating
- f. Unsigned halving.

4.7.46 ARMv6 SIMD intrinsics, summary descriptions, byte lanes, side-effects

Table 4-16

Intrinsic	Summary description	Byte	lanes	Side-effects
intrinsic	Summary description	Returns	Operands	
qadd16	2 x 16-bit addition, saturated to range $-2^{15} \le x \le 2^{15} - 1$	int16x2	int16x2, int16x2	None
qadd8	4 x 8-bit addition, saturated to range $-2^7 \le x \le 2^7 - 1$	int8x4	int8x4, int8x4	None
qasx	Exchange halfwords of second operand, add high halfwords, subtract low halfwords, saturating in each case	int16x2	int16x2, int16x2	None
qsax	Exchange halfwords of second operand, subtract high halfwords, add low halfwords, saturating in each case	int16x2	int16x2, int16x2	None
qsub16	2 x 16-bit subtraction with saturation	int16x2	int16x2, int16x2	None
qsub8	4 x 8-bit subtraction with saturation	int8x4	int8x4, int8x4	None
sadd16	2 x 16-bit signed addition.	int16x2	int16x2, int16x2	APSR.GE bits
sadd8	4 x 8-bit signed addition	int8x4	int8x4, int8x4	APSR.GE bits
sasx	Exchange halfwords of second operand, add high halfwords, subtract low halfwords	int16x2	int16x2, int16x2	APSR.GE bits
sel	Select each byte of the result from either the first operand or the second operand, according to the values of the GE bits. For each result byte, if the corresponding GE bit is set, the byte from the first operand is selected, otherwise the byte from the second operand is selected. Because of the way that int16x2 operations set two (duplicate) GE bits per value, thesel intrinsic works equally well on (u)int16x2 and (u)int8x4 data.	uint8x4	uint8x4, uint8x4	None
shadd16	2x16-bit signed addition, halving the results	int16x2	int16x2, int16x2	None
shadd8	4x8-bit signed addition, halving the results	int8x4	int8x4, int8x4	None

Table 4-16 (continued)

Intrinsic	Summary description	Byte	lanes	Side-effects
IIIIIIIISIC		Returns	Operands	
shasx	Exchange halfwords of the second operand, add high halfwords and subtract low halfwords, halving the results	int16x2	int16x2, int16x2	None
shsax	Exchange halfwords of the second operand, subtract high halfwords and add low halfwords, halving the results	int16x2	int16x2, int16x2	None
shsub16	2x16-bit signed subtraction, halving the results	int16x2	int16x2, int16x2	None
shsub8	4x8-bit signed subtraction, halving the results	int8x4	int8x4, int8x4	None
smlad	2x16-bit multiplication, adding both results to third operand	int32	int16x2, int16x2, int32	Q bit
smladx	Exchange halfwords of the second operand, 2x16-bit multiplication, adding both results to third operand	int16x2	int16x2, int16x2	Q bit
smlald	2x16-bit multiplication, adding both results to third operand. Overflow in addition is not detected.	int64	int16x2, int16x2, int64	None
smlaldx	Exchange halfwords of second operand, perform 2x16-bit multiplication, adding both results to third operand. Overflow in addition is not detected.	int64	int16x2, int16x2, int64	None
smlsd	2x16-bit signed multiplications. Take difference of products, subtract high halfword product from low halfword product, add difference to third operand.	int32	int16x2, int16x2, int32	Q bit
smlsdx	Exchange halfwords of second operand, then 2x16-bit signed multiplications. Product difference is added to a third accumulate operand.	int32	int16x2, int16x2, int32	Q bit
smlsld	2x16-bit signed multiplications. Take difference of products, subtracting high halfword product from low halfword product, and add difference to third operand. Overflow in addition is not detected.	int64	int16x2, int16x2, int64	None

Table 4-16 (continued)

Induire a ! a	Cummany description	Byte	Byte lanes		
Intrinsic	Summary description	Returns	Operands		
smlsldx	Exchange halfwords of second operand, then 2x16-bit signed multiplications. Take difference of products, subtracting high halfword product from low halfword product, and add difference to third operand. Overflow in addition is not detected.	int64	int16x2, int16x2, u64	None	
smuad	2x16-bit signed multiplications, adding the products together.	int32	int16x2, int16x2	Q bit	
smusd	2x16-bit signed multiplications. Take difference of products, subtracting high halfword product from low halfword product.	int32	int16x2, int16x2	None	
smusdx	2x16-bit signed multiplications. Product of high halfword of first operand and low halfword of second operand is subtracted from product of low halfword of first operand and high halfword of second operand, and difference is added to third operand.	int32	int16x2, int16x2	None	
ssat16	2x16-bit signed saturation to a selected width	int16x2	int16x2, /*constant* / unsigned int	Q bit	
ssax	Exchange halfwords of second operand, subtract high halfwords and add low halfwords	int16x2	int16x2, int16x2	APSR.GE bits	
ssub16	2x16-bit signed subtraction	int16x2	int16x2, int16x2	APSR.GE bits	
ssub8	4x8-bit signed subtraction	int8x4	int8x4	APSR.GE bits	
smuadx	Exchange halfwords of second operand, perform 2x16-bit signed multiplications, and add products together	int32	int16x2, int16x2	Q bit	
sxtab16	Two values at bit positions [23:16][7:0] are extracted from second operand, sign-extended to 16 bits, and added to first operand	int16x2	int8x4, int16x2	None	
sxtb16	Two values at bit positions [23:16][7:0] are extracted from the operand and sign-extended to 16 bits	int16x2	int8x4	None	
uadd16	2x16-bit unsigned addition	uint16x2	uint16x2, uint16x2	APSR.GE bits	

Table 4-16 (continued)

Intrinsic	Summary description	Byte	lanes	Side-effects
mumsic	Summary description	Returns	Operands	
uadd8	4x8-bit unsigned addition	uint8x4	uint8x4, uint8x4	APSR.GE bits
uasx	Exchange halfwords of second operand, add high halfwords and subtract low halfwords	uint16x2	uint16x2, uint16x2	APSR.GE bits
uhadd16	2x16-bit unsigned addition, halving the results	uint16x2	uint16x2, uint16x2	None
uhadd8	4x8-bit unsigned addition, halving the results	uint8x4	uint8x4, uint8x4	None
uhasx	Exchange halfwords of second operand, add high halfwords and subtract low halfwords, halving the results	uint16x2	uint16x2, uint16x2	None
uhsax	Exchange halfwords of second operand, subtract high halfwords and add low halfwords, halving the results	uint16x2	uint16x2, uint16x2	None
uhsub16	2x16-bit unsigned subtraction, halving the results	uint16x2	uint16x2, uint16x2	None
uhsub8	4x8-bit unsigned subtraction, halving the results	uint8x4	uint8x4	None
uqadd16	2x16-bit unsigned addition, saturating to range $0 \le x \le 2^{16}$ - 1	uint16x2	uint16x2, uint16x2	None
uqadd8	4x8-bit unsigned addition, saturating to range $0 \le x \le 2^8 - 1$	uint8x4	uint8x4, uint8x4	None
uqasx	Exchange halfwords of second operand, perform saturating unsigned addition on high halfwords and saturating unsigned subtraction on low halfwords	uint16x2	uint16x2, uint16x2	None
uqsax	Exchange halfwords of second operand, perform saturating unsigned subtraction on high halfwords and saturating unsigned addition on low halfwords	uint16x2	uint16x2, uint16x2	None
uqsub16	2x16-bit unsigned subtraction, saturating to range $0 \le x \le 2^{16} - 1$	uint16x2	uint16x2, uint16x2	None
uqsub8	4x8-bit unsigned subtraction, saturating to range $0 \le x \le 2^8$ - 1	uint8x4	uint8x4, uint8x4	None

Table 4-16 (continued)

Intrincia	Summary description	Byte	lanes	Side-effects
Intrinsic		Returns	Operands	
usad8	4x8-bit unsigned subtraction, add absolute values of the differences together, return result as single unsigned integer	uint32	uint8x4, uint8x4	None
usada8	4x8-bit unsigned subtraction, add absolute values of the differences together, and add result to third operand	uint32	uint8x4, uint8x4, uint32	None
usax	Exchange halfwords of second operand, subtract high halfwords and add low halfwords	uint16x2	uint16x2, uint16x2	APSR.GE bits
usat16	Saturate two 16-bit values to a selected unsigned range. Input values are signed and output values are non-negative.	int16x2	int16x2, /*constant* / unsigned int	Q flag
usub16	2x16-bit unsigned subtraction	uint16x2	uint16x2, uint16x2	APSR.GE bits
usub8	4x8-bit unsigned subtraction	uint8x4	uint8x4, uint8x4	APSR.GE bits
uxtab16	Two values at bit positions [23:16][7:0] are extracted from the second operand, zero-extended to 16 bits, and added to the first operand	uint16x2	uint8x4, uint16x2	None
uxtb16	Two values at bit positions [23:16][7:0] are extracted from the operand and zero-extended to 16 bits	uint16x2	uint8x4	None

4.7.47 ARMv6 SIMD intrinsics, compatible processors and architectures

Table 4-17 lists some ARMv6 SIMD instruction intrinsics and compatible processors and architectures, as examples of compatibility.

Use of intrinsics that are not available on your target platform results in linkage failure with undefined symbols.

Table 4-17

Intrinsics	Compatiblecpu options
qadd16, qadd8, qasx	6, 6K, 6T2, 6Z, 7-A, 7-R, 7-A.security, Cortex-R4, Cortex-R4F, Cortex-A8, Cortex-A8.no_neon, Cortex-A8NoNEON, Cortex-A9, Cortex-A9.no_neon, Cortex-A9.no_neon.no_vfp, ARM1136J-S, ARM1136JF-S, ARM1136J-S-rev1, ARM1136JF-S-rev1, ARM1156T2-S, ARM1156T2F-S, ARM1176JZ-S, ARM1176JZF-S, MPCore, MPCore.no_vfp, MPCoreNoVFP, 88FR111, 88FR111.no_hw_divide, QSP, QSP.no_neon, QSP.no_neon.no_vfp

See also

Reference

- --cpu=list on page 2-30
- --cpu=name on page 2-30.

4.7.48 ARMv6 SIMD instruction intrinsics and APSR GE flags

Table 4-18

Intrinsic	APSR.GE flag action	APSR.GE operation
sel	Reads GE flags	<pre>if APSR.GE[0] == 1 then res[7:0] = val1[7:0] else val2[7:0] if APSR.GE[1] == 1 then res[15:8] = val1[15:8] else val2[15:8] if APSR.GE[2] == 1 then res[23:16] = val1[23:16] else val2[23:16] if APSR.GE[3] == 1 then res[31:24] = val1[31:24] else val2[31:24]</pre>
sadd16	Sets or clears GE flags	<pre>if sum1 ≥ 0 then APSR.GE[1:0] = 11 else 00 if sum2 ≥ 0 then APSR.GE[3:2] = 11 else 00</pre>
sadd8	Sets or clears GE flags	if sum1 ≥ 0 then APSR.GE[0] = 1 else 0 if sum2 ≥ 0 then APSR.GE[1] = 1 else 0 if sum3 ≥ 0 then APSR.GE[2] = 1 else 0 if sum4 ≥ 0 then APSR.GE[3] = 1 else 0
sasx	Sets or clears GE flags	if diff ≥ 0 then APSR.GE[1:0] = 11 else 00 if sum ≥ 0 then APSR.GE[3:2] = 11 else 00
ssax	Sets or clears GE flags	if sum ≥ 0 then APSR.GE[1:0] = 11 else 00 if diff ≥ 0 then APSR.GE[3:2] = 11 else 00
ssub16	Sets or clears GE flags	if diff1 ≥0 then APSR.GE[1:0] = 11 else 00 if diff2 ≥0 then APSR.GE[3:2] = 11 else 00
ssub8	Sets or clears GE flags	if diff1 ≥ 0 then APSR.GE[0] = 1 else 0 if diff2 ≥ 0 then APSR.GE[1] = 1 else 0 if diff3 ≥ 0 then APSR.GE[2] = 1 else 0 if diff4 ≥ 0 then APSR.GE[3] = 1 else 0
uadd16	Sets or clears GE flags	if sum1 ≥ 0x10000 then APSR.GE[1:0] = 11 else 00 if sum2 ≥ 0x10000 then APSR.GE[3:2] = 11 else 00
uadd8	Sets or clears GE flags	if sum1 \ge 0x100 then APSR.GE[0] = 1 else 0 if sum2 \ge 0x100 then APSR.GE[1] = 1 else 0 if sum3 \ge 0x100 then APSR.GE[2] = 1 else 0 if sum4 \ge 0x100 then APSR.GE[3] = 1 else 0
uasx	Sets or clears GE flags	if diff ≥ 0 then APSR.GE[1:0] = 11 else 00 if sum ≥ 0 x10000 then APSR.GE[3:2] = 11 else 00

Table 4-18 (continued)

Intrinsic	APSR.GE flag action	APSR.GE operation
usax	Sets or clears GE flags	if sum ≥0x10000 then APSR.GE[1:0] = 11 else 00 if diff ≥0 then APSR.GE[3:2] = 11 else 00
usub16	Sets or clears GE flags	if diff1 ≥ 0 then APSR.GE[1:0] = 11 else 00 if diff2 ≥ 0 then APSR.GE[3:2] = 11 else 00
usub8	Sets or clears GE flags	if diff1 ≥ 0 then APSR.GE[0] = 1 else 0 if diff2 ≥ 0 then APSR.GE[1] = 1 else 0 if diff3 ≥ 0 then APSR.GE[2] = 1 else 0 if diff4 ≥ 0 then APSR.GE[3] = 1 else 0

4.7.49 ARMv6 SIMD instruction intrinsics by alphabetical listing

- __qadd16 intrinsic on page 4-122
- __qadd8 intrinsic on page 4-123
- __qasx intrinsic on page 4-124
- __qsax intrinsic on page 4-126
- __qsub16 intrinsic on page 4-128
- __qsub8 intrinsic on page 4-129
- __sadd16 intrinsic on page 4-130
- __sadd8 intrinsic on page 4-131
- __sasx intrinsic on page 4-133
- __sel intrinsic on page 4-134
- __shadd16 intrinsic on page 4-136
- __shadd8 intrinsic on page 4-137
- __shasx intrinsic on page 4-138
- __shsax intrinsic on page 4-139
- shsub16 intrinsic on page 4-140
- __shsub8 intrinsic on page 4-141
- __smlad intrinsic on page 4-142
- *smladx intrinsic* on page 4-143
- __smlald intrinsic on page 4-144
- __smlaldx intrinsic on page 4-145
- __smlsd intrinsic on page 4-146
- __smlsdx intrinsics on page 4-147
- __smlsld intrinsic on page 4-148
- __smlsldx intrinsic on page 4-149
- __smuad intrinsic on page 4-150
- __smusd intrinsic on page 4-151
- __smuadx intrinsic on page 4-153
- __ssat16 intrinsic on page 4-154
- __ssax intrinsic on page 4-155
- __ssub16 intrinsic on page 4-156
- __ssub8 intrinsic on page 4-157
- __sxtab16 intrinsic on page 4-159
- __sxtb16 intrinsic on page 4-160
- __uadd16 intrinsic on page 4-161
- __uadd8 intrinsic on page 4-162
- *uasx intrinsic* on page 4-164

- __uhadd16 intrinsic on page 4-165
- __uhadd8 intrinsic on page 4-166
- __uhasx intrinsic on page 4-167
- __uhsax intrinsic on page 4-168
- __uhsub16 intrinsic on page 4-169
- __uhsub8 intrinsic on page 4-170
- __uqadd16 intrinsic on page 4-171
- __uqadd8 intrinsic on page 4-172
- __uqasx intrinsic on page 4-173
- __uqsax intrinsic on page 4-174
- __uqsub16 intrinsic on page 4-175
- __uqsub8 intrinsic on page 4-176
- __usad8 intrinsic on page 4-177
- __usada8 intrinsic on page 4-179
- __usax intrinsic on page 4-181
- __usat16 intrinsic on page 4-182
- __usub16 intrinsic on page 4-183
- <u>usub8 intrinsic</u> on page 4-184
- __uxtab16 intrinsic on page 4-186
- __uxtb16 intrinsic on page 4-187.

4.7.50 __qadd16 intrinsic

This intrinsic inserts a QADD16 instruction into the instruction stream generated by the compiler. It enables you to perform two 16-bit integer arithmetic additions in parallel, saturating the results to the 16-bit signed integer range $-2^{15} \le x \le 2^{15} - 1$.

```
unsigned int __gadd16(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first two 16-bit summands holds the second two 16-bit summands.

The __qadd16 intrinsic returns:

- the saturated addition of the low halfwords in the low halfword of the return value
- the saturated addition of the high halfwords in the high halfword of the return value.

The returned results are saturated to the 16-bit signed integer range $-2^{15} \le x \le 2^{15} - 1$.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Saturating instructions on page 4-93 in the Assembler Guide
- OADD, OSUB, ODADD, and ODSUB on page 4-94 in the Assembler Guide.

4.7.51 __qadd8 intrinsic

This intrinsic inserts a QADD8 instruction into the instruction stream generated by the compiler. It enables you to perform four 8-bit integer additions, saturating the results to the 8-bit signed integer range $-2^7 \le x \le 2^7 - 1$.

```
unsigned int __gadd8(unsigned int val1, unsigned int val2)
```

Where:

vall holds the first four 8-bit summands holds the other four 8-bit summands.

The __qadd8 intrinsic returns:

- the saturated addition of the first byte of each operand in the first byte of the return value
- the saturated addition of the second byte of each operand in the second byte of the return value
- the saturated addition of the third byte of each operand in the third byte of the return value
- the saturated addition of the fourth byte of each operand in the fourth byte of the return value.

The returned results are saturated to the 16-bit signed integer range $-2^7 \le x \le 2^7 - 1$.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Saturating instructions on page 4-93 in the Assembler Guide
- QADD, QSUB, QDADD, and QDSUB on page 4-94 in the Assembler Guide.

4.7.52 __qasx intrinsic

This intrinsic inserts a QASX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords of the one operand, then add the high halfwords and subtract the low halfwords, saturating the results to the 16-bit signed integer range $-2^{15} \le x \le 2^{15} - 1$.

```
unsigned int __gasx(unsigned int val1, unsigned int val2)
```

Where:

holds the first operand for the subtraction in the low halfword, and the first operand for the addition in the high halfword

holds the second operand for the subtraction in the high halfword, and the second operand for the addition in the low halfword.

The __qasx intrinsic returns:

- the saturated subtraction of the high halfword in the second operand from the low halfword in the first operand, in the low halfword of the return value
- the saturated addition of the high halfword in the first operand and the low halfword in the second operand, in the high halfword of the return value.

The returned results are saturated to the 16-bit signed integer range $-2^{15} \le x \le 2^{15} - 1$.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Saturating instructions on page 4-93 in the Assembler Guide

Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.53 __qsax intrinsic

This intrinsic inserts a QSAX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords of one operand, then subtract the high halfwords and add the low halfwords, saturating the results to the 16-bit signed integer range $-2^{15} \le x \le 2^{15} - 1$.

```
unsigned int __qsax(unsigned int val1, unsigned int val2)
```

Where:

vall holds the first operand for the addition in the low halfword, and the first operand for the subtraction in the high halfword

holds the second operand for the addition in the high halfword, and the second operand for the subtraction in the low halfword.

The __qsax intrinsic returns:

- the saturated addition of the low halfword of the first operand and the high halfword of the second operand, in the low halfword of the return value
- the saturated subtraction of the low halfword of the second operand from the high halfword of the first operand, in the high halfword of the return value.

The returned results are saturated to the 16-bit signed integer range $-2^{15} \le x \le 2^{15} - 1$.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Saturating instructions on page 4-93 in the Assembler Guide

Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.54 __qsub16 intrinsic

This intrinsic inserts a QSUB16 instruction into the instruction stream generated by the compiler. It enables you to perform two 16-bit integer subtractions, saturating the results to the 16-bit signed integer range $-2^{15} \le x \le 2^{15} - 1$.

```
unsigned int __qsub16(unsigned int val1, unsigned int val2)
```

Where:

vall holds the first halfword operands

val2 holds the second halfword operands.

The __qsub16 intrinsic returns:

- the saturated subtraction of the low halfword in the second operand from the low halfword in the first operand, in the low halfword of the returned result
- the saturated subtraction of the high halfword in the second operand from the high halfword in the first operand, in the high halfword of the returned result.

The returned results are saturated to the 16-bit signed integer range $-2^{15} \le x \le 2^{15} - 1$.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Saturating instructions on page 4-93 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.55 __qsub8 intrinsic

This intrinsic inserts a QSUB8 instruction into the instruction stream generated by the compiler. It enables you to perform four 8-bit integer subtractions, saturating the results to the 8-bit signed integer range $-2^7 \le x \le 2^7 - 1$.

```
unsigned int __qsub8(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first four 8-bit operandsval2 holds the second four 8-bit operands.

The __qsub8 intrinsic returns:

- the subtraction of the first byte in the second operand from the first byte in the first operand, in the first byte of the return value
- the subtraction of the second byte in the second operand from the second byte in the first operand, in the second byte of the return value
- the subtraction of the third byte in the second operand from the third byte in the first operand, in the third byte of the return value
- the subtraction of the fourth byte in the second operand from the fourth byte in the first operand, in the fourth byte of the return value.

The returned results are saturated to the 8-bit signed integer range $-2^7 \le x \le 2^7 - 1$.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Saturating instructions on page 4-93 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.56 __sadd16 intrinsic

This instrinsic inserts an SADD16 instruction into the instruction stream generated by the compiler. It enables you to perform two 16-bit signed integer additions. The GE bits in the APSR are set according to the results of the additions.

```
unsigned int __sadd16(unsigned int val1, unsigned int val2)
```

Where:

vall holds the first two 16-bit summands holds the second two 16-bit summands.

The __sadd16 intrinsic returns:

- the addition of the low halfwords in the low halfword of the return value
- the addition of the high halfwords in the high halfword of the return value.

Each bit in APSR.GE is set or cleared for each byte in the return value, depending on the results of the operation. If *res* is the return value, then:

- if $res[15:0] \ge 0$ then APSR.GE[1:0] = 11 else 00
- if $res[31:16] \ge 0$ then APSR.GE[3:2] = 11 else 00.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- __sel intrinsic on page 4-134
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Saturating instructions on page 4-93 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.57 sadd8 intrinsic

This intrinsic inserts an SADD8 instruction into the instruction stream generated by the compiler. It enables you to perform four 8-bit signed integer additions. The GE bits in the APSR are set according to the results of the additions.

unsigned int __sadd8(unsigned int *val1*, unsigned int *val2*)

Where:

vall holds the first four 8-bit summands holds the second four 8-bit summands.

The __sadd8 intrinsic returns:

- the addition of the first bytes from each operand, in the first byte of the return value
- the addition of the second bytes of each operand, in the second byte of the return value
- the addition of the third bytes of each operand, in the third byte of the return value
- the addition of the fourth bytes of each operand, in the fourth byte of the return value.

Each bit in APSR.GE is set or cleared for each byte in the return value, depending on the results of the operation. If *res* is the return value, then:

- if $res[7:0] \ge 0$ then APSR.GE[0] = 1 else 0
- if $res[15:8] \ge 0$ then APSR.GE[1] = 1 else 0.
- if $res[23:16] \ge 0$ then APSR.GE[2] = 1 else 0.
- if $res[31:24] \ge 0$ then APSR.GE[3] = 1 else 0.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- __sel intrinsic on page 4-134
- Instruction summary on page 4-2 in the Assembler Guide
- Saturating instructions on page 4-93 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.58 sasx intrinsic

This intrinsic inserts an SASX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords of the second operand, add the high halfwords and subtract the low halfwords. The GE bits in the APRS are set according to the results.

```
unsigned int __sasx(unsigned int val1, unsigned int val2)
```

Where:

holds the first operand for the subtraction in the low halfword, and the first operand for the addition in the high halfword

holds the second operand for the subtraction in the high halfword, and the second operand for the addition in the low halfword.

The __sasx intrinsic returns:

- the subtraction of the high halfword in the second operand from the low halfword in the first operand, in the low halfword of the return value
- the addition of the high halfword in the first operand and the low halfword in the second operand, in the high halfword of the return value.

Each bit in APSR.GE is set or cleared for each byte in the return value, depending on the results of the operation. If *res* is the return value, then:

- if $res[15:0] \ge 0$ then APSR.GE[1:0] = 11 else 00
- if $res[31:16] \ge 0$ then APSR.GE[3:2] = 11 else 00.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- __sel intrinsic on page 4-134
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.59 __sel intrinsic

This intrinsic inserts a SEL instruction into the instruction stream generated by the compiler. It enables you to select bytes from the input parameters, whereby the bytes that are selected depend upon the results of previous SIMD instruction intrinsics. The results of previous SIMD instruction intrinsics are represented by the *Greater than or Equal* flags in the *Application Program Status Register* (APSR).

The __sel intrinsic works equally well on both halfword and byte operand intrinsic results. This is because halfword operand operations set two (duplicate) GE bits per value. For example, the __sasx intrinsic.

```
unsigned int __sel(unsigned int val1, unsigned int val2)
```

Where:

val1 holds four selectable bytesval2 holds four selectable bytes.

The __sel intrinsic selects bytes from the input parameters and returns them in the return value, *res*, according to the following criteria:

```
if APSR.GE[0] == 1 then res[7:0] = va11[7:0] else res[7:0] = va12[7:0]
if APSR.GE[1] == 1 then res[15:8] = val1[15:8] else res[15:8] = val2[15:8]
if APSR.GE[2] == 1 then res[23:16] = va11[23:16] else res[23:16] = va12[23:16]
if APSR.GE[3] == 1 then res[31;24] = val1[31:24] else res = val2[31:24]
Example:
unsigned int ge_filter(unsigned int val1, unsigned int val2)
  unsigned int res;
    res = __sel(val1,val2);
    return res;
}
unsigned int foo(unsigned int a, unsigned int b)
  int res;
  int filtered_res;
    res = __sasx(a,b); /* This intrinsic sets the GE flags */
    filtered_res = ge_filter(res); /* Filter the results of the __sasx */
                                   /* intrinsic. Some results are filtered */
                                   /* out based on the GE flags. */
    return filtered_res:
}
```

- __sadd16 intrinsic on page 4-130
- __sasx intrinsic on page 4-133
- __ssax intrinsic on page 4-155
- __ssub8 intrinsic on page 4-157
- __ssub16 intrinsic on page 4-156
- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- *SEL* on page 4-63 in the *Assembler Guide*.

4.7.60 __shadd16 intrinsic

This intrinsic inserts a SHADD16 instruction into the instruction stream generated by the compiler. It enables you to perform two signed 16-bit integer additions, halving the results.

unsigned int __shadd16(unsigned int val1, unsigned int val2)

Where:

val1 holds the first two 16-bit summands

val2 holds the second two 16-bit summands.

The __shadd16 intrinsic returns:

- the halved addition of the low halfwords from each operand, in the low halfword
 of the return value
- the halved addition of the high halfwords from each operand, in the high halfword
 of the return value.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.61 shadd8 intrinsic

This intrinsic inserts a SHADD8 instruction into the instruction stream generated by the compiler. It enables you to perform four signed 8-bit integer additions, halving the results.

unsigned int __shadd8(unsigned int *val1*, unsigned int *val2*)

Where:

vall holds the first four 8-bit summands holds the second four 8-bit summands.

The __shadd8 intrinsic returns:

- the halved addition of the first bytes from each operand, in the first byte of the return value
- the halved addition of the second bytes from each operand, in the second byte of the return value
- the halved addition fo the third bytes from each operand, in the third byte of the return value
- the halved addition of the fourth bytes from each operand, in the fourth byte of the return value.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.62 __shasx intrinsic

This intrinsic inserts a SHASX instruction into the instruction stream generated by the compiler. It enables you to exchange the two halfwords of one operand, perform one signed 16-bit integer addition and one signed 16-bit subtraction, and halve the results.

```
unsigned int __shasx(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first halfword operandsval2 holds the second halfword operands.

The __shasx intrinsic returns:

- the halved subtraction of the high halfword in the second operand from the low halfword in the first operand, in the low halfword of the return value
- the halved subtraction of the low halfword in the second operand from the high halfword in the first operand, in the high halfword of the return value.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.63 __shsax intrinsic

This intrinsic inserts a SHSAX instruction into the instruction stream generated by the compiler. It enables you to exchange the two halfwords of one operand, perform one signed 16-bit integer subtraction and one signed 16-bit addition, and halve the results.

unsigned int __shsax(unsigned int val1, unsigned int val2)

Where:

vall holds the first halfword operandsvall holds the second halfword operands.

The __shsax intrinsic returns:

- the halved addition of the low halfword in the first operand and the high halfword in the second operand, in the low halfword of the return value
- the halved subtraction of the low halfword in the second operand from the high halfword in the first operand, in the high halfword of the return value.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.64 __shsub16 intrinsic

This intrinsic inserts a SHSUB16 instruction into the instruction stream generated by the compiler. It enables you to perform two signed 16-bit integer subtractions, halving the results.

unsigned int __shsub16(unsigned int *val1*, unsigned int *val2*)

Where:

val1 holds the first halfword operandsval2 holds the second halfword operands.

The __shsub16 intrinsic returns:

- the halved subtraction of the low halfword in the second operand from the low halfword in the first operand, in the low halfword of the return value
- the halved subtraction of the high halfword in the second operand from the high halfword in the first operand, in the high halfword of the return value.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.65 shsub8 intrinsic

This intrinsic inserts a SHSUB8 instruction into the instruction stream generated by the compiler. It enables you to perform four signed 8-bit integer subtractions, halving the results.

unsigned int __shsub8(unsigned int *val1*, unsigned int *val2*)

Where:

val1 holds the first four operandsval2 holds the second four operands.

The __shsub8 intrinsic returns:

- the halved subtraction of the first byte in the second operand from the first byte in the first operand, in the first byte of the return value
- the halved subtraction of the second byte in the second operand from the second byte in the first operand, in the second byte of the return value
- the halved subtraction of the third byte in the second operand from the third byte in the first operand, in the third byte of the return value
- the halved subtraction of the fourth byte in the second operand from the fourth byte in the first operand, in the fourth byte of the return value

Example:

- ARMv6 SIMD intrinsics on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.66 __smlad intrinsic

This intrinsic inserts an SMLAD instruction into the instruction stream generated by the compiler. It enables you to perform two signed 16-bit multiplications, adding both results to a 32-bit accumulate operand. The Q bit is set if the addition overflows. Overflow cannot occur during the multiplications.

```
unsigned int __smlad(unsigned int vall, unsigned int vall, unsigned int vall)
```

Where:

val1 holds the first halfword operands for each multiplicationval2 holds the second halfword operands for each multiplication

va13 holds the accumulate value.

The __smlad intrinsic returns the product of each multiplication added to the accumulate value, as a 32-bit integer.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- SMLAD and SMLSD on page 4-86 in the Assembler Guide.

4.7.67 smladx intrinsic

This intrinsic inserts an SMLADX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords of the second operand, perform two signed 16-bit multiplications, adding both results to a 32-bit accumulate operand. The Q bit is set if the addition overflows. Overflow cannot occur during the multiplications.

unsigned int __smladx(unsigned int val1, unsigned int val2, unsigned int val3)

Where:

val1 holds the first halfword operands for each multiplicationval2 holds the second halfword operands for each multiplication

va13 holds the accumulate value.

The __smladx intrinsic returns the product of each multiplication added to the accumulate value, as a 32-bit integer.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- *SMLAD and SMLSD* on page 4-86 in the *Assembler Guide*.

4.7.68 __smlald intrinsic

This intrinsic inserts an SMLALD instruction into the instruction stream generated by the compiler. It enables you to perform two signed 16-bit multiplications, adding both results to a 64-bit accumulate operand. Overflow is only possible as a result of the 64-bit addition. This overflow is not detected if it occurs. Instead, the result wraps around $modulo2^{64}$.

unsigned long long_smlald(unsigned int val1, unsigned int val2, unsigned long long val3)

Where:

val1 holds the first halfword operands for each multiplication
 val2 holds the second halfword operands for each multiplication
 val3 holds the accumulate value.

The __smlald intrinsic returns the product of each multiplication added to the accumulate value.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- SMLALD and SMLSLD on page 4-88 in the Assembler Guide.

4.7.69 smlaldx intrinsic

This intrinsic inserts an SMLALDX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords of the second operand, and perform two signed 16-bit multiplications, adding both results to a 64-bit accumulate operand. Overflow is only possible as a result of the 64-bit addition. This overflow is not detected if it occurs. Instead, the result wraps around modulo²⁶⁴.

unsigned long long_smlaldx(unsigned int val1, unsigned int val2, unsigned long long val3)

Where:

val1 holds the first halfword operands for each multiplication
 val2 holds the second halfword operands for each multiplication
 val3 holds the accumulate value.

The __smlald intrinsic returns the product of each multiplication added to the accumulate value.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- SMLALD and SMLSLD on page 4-88 in the Assembler Guide.

4.7.70 __smlsd intrinsic

This intrinsic inserts an SMLSD instruction into the instruction stream generated by the compiler. It enables you to perform two 16-bit signed multiplications, take the difference of the products, subtracting the high halfword product from the low halfword product, and add the difference to a 32-bit accumulate operand. The Q bit is set if the accumulation overflows. Overflow cannot occur during the multiplications or the subtraction.

unsigned int_smlsd(unsigned int val1, unsigned int val2, unsigned int val3)

Where:

val1 holds the first halfword operands for each multiplication
 val2 holds the second halfword operands for each multiplication
 val3 holds the accumulate value.

The __smlsd intrinsic returns the difference of the product of each multiplication, added to the accumulate value.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- *SMLAD and SMLSD* on page 4-86 in the *Assembler Guide*.

4.7.71 smlsdx intrinsics

This intrinsic inserts an SMLSDX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords in the second operand, then perform two 16-bit signed multiplications. The difference of the products is added to a 32-bit accumulate operand. The Q bit is set if the addition overflows. Overflow cannot occur during the multiplications or the subtraction.

unsigned int_smlsdx(unsigned int val1, unsigned int val2, unsigned int val3)

Where:

val1 holds the first halfword operands for each multiplicationval2 holds the second halfword operands for each multiplication

val3 holds the accumulate value.

The __smlsd intrinsic returns the difference of the product of each multiplication, added to the accumulate value.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- *SMLAD and SMLSD* on page 4-86 in the *Assembler Guide*.

4.7.72 __smlsld intrinsic

This intrinsic inserts an SMLSLD instruction into the instruction stream generated by the compiler. It enables you to perform two 16-bit signed multiplications, take the difference of the products, subtracting the high halfword product from the low halfword product, and add the difference to a 64-bit accumulate operand. Overflow cannot occur during the multiplications or the subtraction. Overflow can occur as a result of the 64-bit addition, and this overflow is not detected. Instead, the result wraps round to modulo⁶⁴.

unsigned long long_smlsld(unsigned int val1, unsigned int val2, unsigned long long val3)

Where:

val1 holds the first halfword operands for each multiplicationval2 holds the second halfword operands for each multiplication

va13 holds the accumulate value.

The __smlsld intrinsic returns the difference of the product of each multiplication, added to the accumulate value.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- *SMLALD and SMLSLD* on page 4-88 in the *Assembler Guide*.

4.7.73 smlsldx intrinsic

This intrinsic inserts an SMLSLDX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords of the second operand, perform two 16-bit multiplications, adding the difference of the products to a 64-bit accumulate operand. Overflow cannot occur during the multiplications or the subtraction. Overflow can occur as a result of the 64-bit addition, and this overflow is not detected. Instead, the result wraps round to modulo⁶⁴.

unsigned long long_smlsldx(unsigned int val1, unsigned int val2, unsigned long long val3)

Where:

val1 holds the first halfword operands for each multiplication
 val2 holds the second halfword operands for each multiplication
 val3 holds the accumulate value.

The __smlsld intrinsic returns the difference of the product of each multiplication, added to the accumulate value.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- *SMLALD and SMLSLD* on page 4-88 in the *Assembler Guide*.

4.7.74 __smuad intrinsic

This intrinsic inserts an SMUAD instruction into the instruction stream generated by the compiler. It enables you to perform two 16-bit signed multiplications, adding the products together. The Q bit is set if the addition overflows.

```
unsigned int_smuad(unsigned int vall, unsigned int vall)
```

Where:

val1 holds the first halfword operands for each multiplicationval2 holds the second halfword operands for each multiplication.

The __smuad intrinsic returns the products of the two 16-bit signed multiplications.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- *SMUAD{X} and SMUSD{X}* on page 4-82 in the *Assembler Guide*.

4.7.75 __smusd intrinsic

This intrinsic inserts an SMUSD instruction into the instruction stream generated by the compiler. It enables you to perform two 16-bit signed multiplications, taking the difference of the products by subtracting the high halfword product from the low halfword product.

unsigned int__smusd(unsigned int val1, unsigned int val2)

Where:

val1 holds the first halfword operands for each multiplicationval2 holds the second halfword operands for each multiplication.

The __smusd intrinsic returns the difference of the products of the two 16-bit signed multiplications.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- *SMUAD{X} and SMUSD{X}* on page 4-82 in the *Assembler Guide*.

4.7.76 __smusdx intrinsic

This intrinsic inserts an SMUSDX instruction into the instruction stream generated by the compiler. It enables you to perform two 16-bit signed multiplications, subtracting one of the products from the other. The halfwords of the second operand are exchanged before performing the arithmetic. This produces top \times bottom and bottom \times top multiplication.

unsigned int_smusdx(unsigned int val1, unsigned int val2)

Where:

val1 holds the first halfword operands for each multiplicationval2 holds the second halfword operands for each multiplication.

The __smusdx intrinsic returns the difference of the products of the two 16-bit signed multiplications.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- *SMUAD{X} and SMUSD{X}* on page 4-82 in the *Assembler Guide*.

4.7.77 smuadx intrinsic

This intrinsic inserts an SMUADX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords of the second operand, perform two 16-bit signed integer multiplications, and add the products together. Exchanging the halfwords of the second operand produces top \times bottom and bottom \times top multiplication. The Q flag is set if the addition overflows. The multiplications cannot overflow.

unsigned int_smuadx(unsigned int val1, unsigned int val2)

Where:

val1 holds the first halfword operands for each multiplicationval2 holds the second halfword operands for each multiplication.

The __smuadx intrinsic returns the products of the two 16-bit signed multiplications.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- *SMUAD{X} and SMUSD{X}* on page 4-82 in the *Assembler Guide*.

4.7.78 ssat16 intrinsic

This intrinsic inserts an SSAT16 instruction into the instruction stream generated by the compiler. It enables you to saturate two signed 16-bit values to a selected signed range.

The Q bit is set if either operation saturates.

```
unsigned int __saturate_halfwords(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the two signed 16-bit values to be saturated

val2 is the bit position for saturation, an integral constant expression in the range 1 to 16.

The __ssat16 intrinsic returns:

- the signed saturation of the low halfword in *val1*, saturated to the bit position specified in *val2* and returned in the low halfword of the return value
- the signed saturation of the high halfword in *va11*, saturated to the bit position specified in *va12* and returned in the high halfword of the return value.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Saturating instructions on page 4-93 in the Assembler Guide
- SSAT16 and USAT16 on page 4-104 in the Assembler Guide.

4.7.79 ssax intrinsic

This intrinsic inserts an SSAX instruction into the instruction stream generated by the compiler. It enables you to exchange the two halfwords of one operand and perform one 16-bit integer subtraction and one 16-bit addition.

The GE bits in the APSR are set according to the results.

unsigned int __ssax(unsigned int val1, unsigned int val2)

Where:

vall holds the first operand for the addition in the low halfword, and the first operand for the subtraction in the high halfword

holds the second operand for the addition in the high halfword, and the second operand for the subtraction in the low halfword.

The __ssax intrinsic returns:

- the addition of the low halfword in the first operand and the high halfword in the second operand, in the low halfword of the return value
- the subtraction of the low halfword in the second operand from the high halfword in the first operand, in the high halfword of the return value.

Each bit in APSR.GE is set or cleared for each byte in the return value, depending on the results of the operation. If *res* is the return value, then:

- if $res[15:0] \ge 0$ then APSR.GE[1:0] = 11 else 00
- if $res[31:16] \ge 0$ then APSR.GE[3:2] = 11 else 00.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.80 ssub16 **intrinsic**

This intrinsic inserts an SSUB16 instruction into the instruction stream generated by the compiler. It enables you to perform two 16-bit signed integer subtractions.

The GE bits in the APSR are set according to the results.

```
unsigned int __ssub16(unsigned int val1, unsigned int val2)
```

Where:

- vall holds the first operands of each addition in the low and the high halfwords
- val2 holds the second operands for each addition in the low and the high halfwords.

The __ssub16 intrinsic returns:

- the subtraction of the low halfword in the second operand from the low halfword in the first operand, in the low halfword of the return value
- the subtraction of the high halfword in the second operand from the high halfword in the first operand, in the high halfword of the return value.

Each bit in APSR.GE is set or cleared for each byte in the return value, depending on the results of the operation. If *res* is the return value, then:

- if $res[15:0] \ge 0$ then APSR.GE[1:0] = 11 else 00
- if $res[31:16] \ge 0$ then APSR.GE[3:2] = 11 else 00.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- __sel intrinsic on page 4-134
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.81 ssub8 intrinsic

This intrinsic inserts an SSUB8 instruction into the instruction stream generated by the compiler. It enables you to perform four 8-bit signed integer subtractions.

The GE bits in the APSR are set according to the results.

```
unsigned int __ssub8(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first four 8-bit operands of each subtractionval2 holds the second four 8-bit operands of each subtraction.

The __ssub8 intrinsic returns:

- the subtraction of the first byte in the second operand from the first byte in the first operand, in the first bytes of the return value
- the subtraction of the second byte in the second operand from the second byte in the first operand, in the second byte of the return value
- the subtraction of the third byte in the second operand from the third byte in the first operand, in the third byte of the return value
- the subtraction of the fourth byte in the second operand from the fourth byte in the first operand, in the fourth byte of the return value.

Each bit in APSR.GE is set or cleared for each byte in the return value, depending on the results of the operation. If *res* is the return value, then:

- if $res[8:0] \ge 0$ then APSR.GE[0] = 1 else 0
- if $res[15:8] \ge 0$ then APSR.GE[1] = 1 else 0
- if $res[23:16] \ge 0$ then APSR.GE[2] = 1 else 0
- if $res[31:24] \ge 0$ then APSR.GE[3] = 1 else 0.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- __sel intrinsic on page 4-134
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.82 __sxtab16 intrinsic

This intrinsic inserts an SXTAB16 instruction into the instruction stream generated by the compiler. It enables you to extract two 8-bit values from the second operand (at bit positions [7:0] and [23:16]), sign-extend them to 16-bits each, and add the results to the first operand.

```
unsigned int __sxtab16(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the values that the extracted and sign-extended values are added to

holds the two 8-bit values to be extracted and sign-extended.

The __sxtab16 intrinsic returns the addition of va11 and va12, where the 8-bit values in va12[7:0] and va12[23:16] have been extracted and sign-extended prior to the addition.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- SXT, SXTA, UXT, and UXTA on page 4-109 in the Assembler Guide.

4.7.83 __sxtb16 intrinsic

This intrinsic inserts an SXTB16 instruction into the instruction stream generated by the compiler. It enables you to extract two 8-bit values from an operand and sign-extend them to 16 bits each.

```
unsigned int __sxtb16(unsigned int val)
```

Where va7[7:0] and va7[23:16] hold the two 8-bit values to be sign-extended.

The __sxtb16 intrinsic returns the 8-bit values sign-extended to 16-bit values.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- SXT, SXTA, UXT, and UXTA on page 4-109 in the Assembler Guide.

4.7.84 uadd16 intrinsic

This intrinsic inserts a UADD16 instruction into the instruction stream generated by the compiler. It enables you to perform two 16-bit unsigned integer additions.

The GE bits in the APSR are set according to the results.

```
unsigned int __uadd16(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first two halfword summands for each additionval2 holds the second two halfword summands for each addition.

The __uadd16 intrinsic returns:

- the addition of the low halfwords in each operand, in the low halfword of the return value
- the addition of the high halfwords in each operand, in the high halfword of the return value.

Each bit in APSR.GE is set or cleared for each byte in the return value, depending on the results of the operation. If *res* is the return value, then:

- if $res[15:0] \ge 0x10000$ then APSR.GE[0] = 11 else 00
- if $res[31:16] \ge 0x10000$ then APSR.GE[1] = 11 else 00.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.85 __uadd8 intrinsic

This intrinsic inserts a UADD8 instruction into the instruction stream generated by the compiler. It enables you to perform four unsigned 8-bit integer additions.

The GE bits in the APSR are set according to the results.

```
unsigned int __uadd8(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first four 8-bit summands for each additionval2 holds the second four 8-bit summands for each addition.

The __uadd8 intrinsic returns:

- the addition of the first bytes in each operand, in the first byte of the return value
- the addition of the second bytes in each operand, in the second byte of the return value
- the addition of the third bytes in each operand, in the third byte of the return value
- the addition of the fourth bytes in each operand, in the fourth byte of the return value.

Each bit in APSR.GE is set or cleared for each byte in the return value, depending on the results of the operation. If *res* is the return value, then:

- if $res[7:0] \ge 0x100$ then APSR.GE[0] = 1 else 0
- if $res[15:8] \ge 0x100$ then APSR.GE[1] = 1 else 0
- if $res[23:16] \ge 0x100$ then APSR.GE[2] = 1 else 0
- if $res[31:24] \ge 0x100$ then APSR.GE[3] = 1 else 0.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.86 uasx intrinsic

This intrinsic inserts a UASX instruction into the instruction stream generated by the compiler. It enables you to exchange the two halfwords of the second operand, add the high halfwords and subtract the low halfwords.

The GE bits in the APSR are set according to the results.

```
unsigned int __uasx(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first operand for the subtraction in the low halfword, and the first operand for the addition in the high halfword

holds the second operand for the subtraction in the high halfword and the second operand for the addition in the low halfword.

The __uasx intrinsic returns:

- the subtraction of the high halfword in the second operand from the low halfword in the first operand, in the low halfword of the return value
- the addition of the high halfword in the first operand and the low halfword in the second operand, in the high halfword of the return value.

Each bit in APSR.GE is set or cleared for each byte in the return value, depending on the results of the operation. If *res* is the return value, then:

- if $res[15:0] \ge 0$ then APSR.GE[1:0] = 11 else 00
- if $res[31:16] \ge 0x10000$ then APSR.GE[3:2] = 11 else 00.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.87 __uhadd16 intrinsic

This intrinsic inserts a UHADD16 instruction into the instruction stream generated by the compiler. It enables you to perform two unsigned 16-bit integer additions, halving the results.

unsigned int __uhadd16(unsigned int val1, unsigned int val2)

Where:

vall holds the first two 16-bit summands holds the second two 16-bit summands.

The __uhadd16 intrinsic returns:

- the halved addition of the low halfwords in each operand, in the low halfword of the return value
- the halved addition of the high halfwords in each operand, in the high halfword
 of the return value.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.88 __uhadd8 intrinsic

This intrinsic inserts a UHADD8 instruction into the instruction stream generated by the compiler. It enables you to perform four unsigned 8-bit integer additions, halving the results.

unsigned int __uhadd8(unsigned int *val1*, unsigned int *val2*)

Where:

val1 holds the first four 8-bit summandsval2 holds the second four 8-bit summands.

The __uhadd8 intrinsic returns:

- the halved addition of the first bytes in each operand, in the first byte of the return value
- the halved addition of the second bytes in each operand, in the second byte of the return value
- the halved addition of the third bytes in each operand, in the third byte of the return value
- the halved addition of the fourth bytes in each operand, in the fourth byte of the return value.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.89 __uhasx intrinsic

This intrinsic inserts a UHASX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords of the second operand, add the high halfwords and subtract the low halfwords, halving the results.

```
unsigned int __uhasx(unsigned int val1, unsigned int val2)
```

Where:

holds the first operand for the subtraction in the low halfword, and the first operand for the addition in the high halfword

holds the second operand for the subtraction in the high halfword, and the second operand for the addition in the low halfword.

The __uhasx intrinsic returns:

- the halved subtraction of the high halfword in the second operand from the low halfword in the first operand
- the halved addition of the high halfword in the first operand and the low halfword in the second operand.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.90 __uhsax intrinsic

This intrinsic inserts a UHSAX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords of the second operand, subtract the high halfwords and add the low halfwords, halving the results.

```
unsigned int __uhsax(unsigned int val1, unsigned int val2)
```

Where:

holds the first operand for the addition in the low halfword, and the first

operand for the subtraction in the high halfword

val2 holds the second operand for the addition in the high halfword, and the

second operand for the subtraction in the low halfword.

The __uhsax intrinsic returns:

- the halved addition of the high halfword in the second operand and the low halfword in the first operand, in the low halfword of the return value
- the halved subtraction of the low halfword in the second operand from the high halfword in the first operand, in the high halfword of the return value.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.91 __uhsub16 intrinsic

This intrinsic inserts a UHSUB16 instruction into the instruction stream generated by the compiler. It enables you to perform two unsigned 16-bit integer subtractions, halving the results.

unsigned int __uhsub16(unsigned int val1, unsigned int val2)

Where:

vall holds the first two 16-bit operands holds the second two 16-bit operands.

The __uhsub16 intrinsic returns:

- the halved subtraction of the low halfword in the second operand from the low halfword in the first operand, in the low halfword of the return value
- the halved subtraction of the high halfword in the second operand from the high halfword in the first operand, in the high halfword of the return value.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.92 __uhsub8 intrinsic

This intrinsic inserts a UHSUB8 instruction into the instruction stream generated by the compiler. It enables you to perform four unsigned 8-bit integer subtractions, halving the results.

unsigned int __uhsub8(unsigned int *val1*, unsigned int *val2*)

Where:

val1 holds the first four 8-bit operandsval2 holds the second four 8-bit operands.

The __uhsub8 intrinsic returns:

- the halved subtraction of the first byte in the second operand from the first byte in the first operand, in the first byte of the return value
- the halved subtraction of the second byte in the second operand from the second byte in the first operand, in the second byte of the return value
- the halved subtraction of the third byte in the second operand from the third byte in the first operand, in the third byte of the return value
- the halved subtraction of the fourth byte in the second operand from the fourth byte in the first operand, in the fourth byte of the return value.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.93 __ugadd16 intrinsic

This intrinsic inserts a UQADD16 instruction into the instruction stream generated by the compiler. It enables you to perform two unsigned 16-bit integer additions, saturating the results to the 16-bit unsigned integer range $0 \le x \le 2^{16}$ - 1.

```
unsigned int __ugadd16(unsigned int val1, unsigned int val2)
```

Where:

vall holds the first two halfword summands holds the second two halfword summands.

The __uqadd16 intrinsic returns:

- the addition of the low halfword in the first operand and the low halfword in the second operand
- the addition of the high halfword in the first operand and the high halfword in the second operand, in the high halfword of the return value.

The results are saturated to the 16-bit unsigned integer range $0 \le x \le 2^{16} - 1$.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.94 __uqadd8 intrinsic

This intrinsic inserts a UQADD8 instruction into the instruction stream generated by the compiler. It enables you to perform four unsigned 8-bit integer additions, saturating the results to the 8-bit unsigned integer range $0 \le x \le 2^8 - 1$.

```
unsigned int __uqadd8(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first four 8-bit summandsval2 holds the second four 8-bit summands.

The __uqadd8 intrinsic returns:

- the addition of the first bytes in each operand, in the first byte of the return value
- the addition of the second bytes in each operand, in the second byte of the return value
- the addition of the third bytes in each operand, in the third byte of the return value
- the addition of the fourth bytes in each operand, in the fourth byte of the return value.

The results are saturated to the 8-bit unsigned integer range $0 \le x \le 2^8 - 1$.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.95 __ugasx intrinsic

This intrinsic inserts a UQASX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords of the second operand and perform one unsigned 16-bit integer addition and one unsigned 16-bit subtraction, saturating the results to the 16-bit unsigned integer range $0 \le x \le 2^{16} - 1$.

```
unsigned int __ugasx(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first two halfword operandsval2 holds the second two halfword operands.

The __ugasx intrinsic returns:

- the subtraction of the high halfword in the second operand from the low halfword in the first operand, in the low halfword of the return value
- the subtraction of the low halfword in the second operand from the high halfword in the first operand, in the high halfword of the return value.

The results are saturated to the 16-bit unsigned integer range $0 \le x \le 2^{16}$ - 1.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.96 __uqsax intrinsic

This intrinsic inserts a UQSAX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords of the second operand and perform one unsigned 16-bit integer subtraction and one unsigned 16-bit addition, saturating the results to the 16-bit unsigned integer range $0 \le x \le 2^{16}$ - 1.

```
unsigned int __ugsax(unsigned int val1, unsigned int val2)
```

Where:

holds the first 16-bit operand for the addition in the low halfword, and the first 16-bit operand for the subtraction in the high halfword

val2 holds the second 16-bit halfword for the addition in the high halfword, and the second 16-bit halfword for the subtraction in the low halfword.

The __uqsax intrinsic returns:

- the addition of the low halfword in the first operand and the high halfword in the second operand, in the low halfword of the return value
- the subtraction of the low halfword in the second operand from the high halfword in the first operand, in the high halfword of the return value.

The results are saturated to the 16-bit unsigned integer range $0 \le x \le 2^{16}$ - 1.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.97 __uqsub16 intrinsic

This intrinsic inserts a UQSUB16 instruction into the instruction stream generated by the compiler. It enables you to perform two unsigned 16-bit integer subtractions, saturating the results to the 16-bit unsigned integer range $0 \le x \le 2^{16} - 1$.

```
unsigned int __uqsub16(unsigned int val1, unsigned int val2)
```

Where:

vall holds the first halfword operands for each subtractionholds the second halfword operands for each subtraction.

The __uqsub16 intrinsic returns:

- the subtraction of the low halfword in the second operand from the low halfword in the first operand, in the low halfword of the return value
- the subtraction of the high halfword in the second operand from the high halfword in the first operand, in the high halfword of the return value.

The results are saturated to the 16-bit unsigned integer range $0 \le x \le 2^{16} - 1$.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.98 __uqsub8 intrinsic

This intrinsic inserts a UQSUB8 instruction into the instruction stream generated by the compiler. It enables you to perform four unsigned 8-bit integer subtractions, saturating the results to the 8-bit unsigned integer range $0 \le x \le 2^8 - 1$.

```
unsigned int __uqsub8(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first four 8-bit operandsval2 holds the second four 8-bit operands.

The __uqsub8 intrinsic returns:

- the subtraction of the first byte in the second operand from the first byte in the first operand, in the first byte of the return value
- the subtraction of the second byte in the second operand from the second byte in the first operand, in the second byte of the return value
- the subtraction of the third byte in the second operand from the third byte in the first operand, in the third byte of the return value
- the subtraction of the fourth byte in the second operand from the fourth byte in the first operand, in the fourth byte of the return value.

The results are saturated to the 8-bit unsigned integer range $0 \le x \le 2^8 - 1$.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.99 usad8 intrinsic

This intrinsic inserts a USAD8 instruction into the instruction stream generated by the compiler. It enables you to perform four unsigned 8-bit subtractions, and add the absolute values of the differences together, returning the result as a single unsigned integer.

```
unsigned int __usad8(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first four 8-bit operands for the subtractionsval2 holds the second four 8-bit operands for the subtractions.

The __usad8 intrinsic returns the sum of the absolute differences of:

- the subtraction of the first byte in the second operand from the first byte in the first operand
- the subtraction of the second byte in the second operand from the second byte in the first operand
- the subtraction of the third byte in the second operand from the third byte in the first operand
- the subtraction of the fourth byte in the second operand from the fourth byte in the first operand.

The sum is returned as a single unsigned integer.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- *Instruction summary* on page 4-2 in the *Assembler Guide*

• USAD8 and USADA8 on page 4-102 in the Assembler Guide.

4.7.100 usada8 intrinsic

This intrinsic inserts a USADA8 instruction into the instruction stream generated by the compiler. It enables you to perform four unsigned 8-bit subtractions, and add the absolute values of the differences to a 32-bit accumulate operand.

unsigned int __usada8(unsigned int val1, unsigned int val2, unsigned int val3)

Where:

val1 holds the first four 8-bit operands for the subtractions
 val2 holds the second four 8-bit operands for the subtractions
 val3 holds the accumulation value.

The __usada8 intrinsic returns the sum of the absolute differences of the following bytes, added to the accumulation value:

- the subtraction of the first byte in the second operand from the first byte in the first operand
- the subtraction of the second byte in the second operand from the second byte in the first operand
- the subtraction of the third byte in the second operand from the third byte in the first operand
- the subtraction of the fourth byte in the second operand from the fourth byte in the first operand.

Example:

See also

• *ARMv6 SIMD intrinsics* on page 4-109

- Instruction summary on page 4-2 in the Assembler Guide
- USAD8 and USADA8 on page 4-102 in the Assembler Guide.

4.7.101 usax intrinsic

This intrinsic inserts a USAX instruction into the instruction stream generated by the compiler. It enables you to exchange the halfwords of the second operand, subtract the high halfwords and add the low halfwords.

The GE bits in the APSR are set according to the results.

unsigned int __usax(unsigned int val1, unsigned int val2)

Where:

holds the first operand for the addition in the low halfword, and the first operand for the subtraction in the high halfword

holds the second operand for the addition in the high halfword, and the second operand for the subtraction in the low halfword.

The __usax intrinsic returns:

- the addition of the low halfword in the first operand and the high halfword in the second operand, in the low halfword of the return value
- the subtraction of the low halfword in the second operand from the high halfword in the first operand, in the high halfword of the return value.

Each bit in APSR.GE is set or cleared for each byte in the return value, depending on the results of the operation. If *res* is the return value, then:

- if $res[15:0] \ge 0x10000$ then APSR.GE[1:0] = 11 else 00
- if $res[31:16] \ge 0$ then APSR.GE[3:2] = 11 else 00.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.102 __usat16 intrinsic

This intrinsic inserts a USAT16 instruction into the instruction stream generated by the compiler. It enables you to saturate two signed 16-bit values to a selected unsigned range. The Q flag is set if either operation saturates.

```
unsigned int __usat16(unsigned int val1, /* constant */ unsigned int val2)
```

Where:

val1 holds the two 16-bit values that are to be saturated

val2 specifies the bit position for saturation, and must be an integral constant expression.

The __usat16 intrinsic returns the saturation of the two signed 16-bit values, as non-negative values.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- SSAT16 and USAT16 on page 4-104 in the Assembler Guide.

4.7.103 __usub16 intrinsic

This intrinsic inserts a USUB16 instruction into the instruction stream generated by the compiler. It enables you to perform two 16-bit unsigned integer subtractions.

The GE bits in the APSR are set according to the results.

```
unsigned int __usub16(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first two halfword operandsval2 holds the second two halfword operands.

The __usub16 intrinsic returns:

- the subtraction of the low halfword in the second operand from the low halfword in the first operand, in the low halfword of the return value
- the subtraction of the high halfword in the second operand from the high halfword in the first operand, in the high halfword of the return value.

Each bit in APSR.GE is set or cleared for each byte in the return value, depending on the results of the operation. If *res* is the return value, then:

- if $res[15:0] \ge 0$ then APSR.GE[1:0] = 11 else 00
- if $res[31:16] \ge 0$ then APSR.GE[3:2] = 11 else 00.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.104 __usub8 intrinsic

This intrinsic inserts a USUB8 instruction into the instruction stream generated by the compiler. It enables you to perform four 8-bit unsigned integer subtractions.

The GE bits in the APSR are set according to the results.

```
unsigned int __usub8(unsigned int val1, unsigned int val2)
```

Where:

val1 holds the first four 8-bit operandsval2 holds the second four 8-bit operands.

The __usub8 intrinsic returns:

- the subtraction of the first byte in the second operand from the first byte in the first operand, in the first byte of the return value
- the subtraction of the second byte in the second operand from the second byte in the first operand, in the second byte of the return value
- the subtraction of the third byte in the second operand from the third byte in the first operand, in the third byte of the return value
- the subtraction of the fourth byte in the second operand from the fourth byte in the first operand, in the fourth byte of the return value.

Each bit in APSR.GE is set or cleared for each byte in the return value, depending on the results of the operation. If *res* is the return value, then:

- if $res[7:0] \ge 0$ then APSR.GE[0] = 1 else 0
- if $res[15:8] \ge 0$ then APSR.GE[1] = 1 else 0
- if $res[23:16] \ge 0$ then APSR.GE[2] = 1 else 0
- if $res[31:24] \ge 0$ then APSR.GE[3] = 1 else 0.

Example:

- *ARMv6 SIMD intrinsics* on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- Parallel add and subtract on page 4-99 in the Assembler Guide.

4.7.105 __uxtab16 intrinsic

This intrinsic inserts a UXTAB16 instruction into the instruction stream generated by the compiler. It enables you to extract two 8-bit values from one operand, zero-extend them to 16 bits each, and add the results to two 16-bit values from another operand.

```
unsigned int __uxtab16(unsigned int val1, unsigned int val2)
```

Where va12[7:0] and va12[23:16] hold the two 8-bit values to be zero-extended.

The __uxtab16 intrinsic returns the 8-bit values in *va12*, zero-extended to 16-bit values and added to *va11*.

Example:

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- SXT, SXTA, UXT, and UXTA on page 4-109 in the Assembler Guide.

4.7.106 uxtb16 intrinsic

This intrinsic inserts a UXTB16 instruction into the instruction stream generated by the compiler. It enables you to extract two 8-bit values from an operand and zero-extend them to 16 bits each.

```
unsigned int __uxtb16(unsigned int val)
```

Where va7[7:0] and va7[23:16] hold the two 8-bit values to be sign-extended.

The __uxtb16 intrinsic returns the 8-bit values zero-extended to 16-bit values.

Example:

See also

- ARMv6 SIMD intrinsics on page 4-109
- Instruction summary on page 4-2 in the Assembler Guide
- SXT, SXTA, UXT, and UXTA on page 4-109 in the Assembler Guide.

4.7.107 ETSI basic operations

RVCT supports for the original ETSI family of basic operations described in the ETSI G.729 recommendation *Coding of speech at 8 kbit/s using conjugate-structure algebraic-code-excited linear prediction (CS-ACELP)*.

To make use of the ETSI basic operations in your own code, include the standard header file dspfns.h. The intrinsics supplied in dspfns.h are listed in Table 4-19.

Table 4-19 ETSI basic operations supported in RVCT

Intrinsics				
abs_s	L_add_c	L_mult	L_sub_c	norm_1
add	L_deposit_h	L_negate	mac_r	round
div_s	L_deposit_1	L_sat	msu_r	saturate

Table 4-19 ETSI basic operations supported in RVCT (continued)

Intrinsics				
extract_h	L_mac	L_sh1	mult	shl
extract_1	L_macNs	L_shr	mult_r	shr
L_abs	L_msu	L_shr_r	negate	shr_r
L_add	L_msuNs	L_sub	norm_s	sub

The header file dspfns.h also exposes certain status flags as global variables for use in your C or C++ programs. The status flags exposed by dspfns.h are listed in Table 4-20.

Table 4-20 ETSI status flags exposed in RVCT

Status flag	Description
Overflow	Overflow status flag. Generally, saturating functions have a sticky effect on overflow.
Carry	Carry status flag.

Example

```
#include <limits.h>
#include <stdint.h>
#include <dspfns.h>
                           // include ETSI basic operations
int32_t C_L_add(int32_t a, int32_t b)
{
    int32_t c = a + b;
    if (((a \land b) \& INT_MIN) == 0)
        if ((c \land a) \& INT_MIN)
            c = (a < 0) ? INT_MIN : INT_MAX;
    return c;
}
__asm int32_t asm_L_add(int32_t a, int32_t b)
    qadd r0, r0, r1
    bx 1r
int32_t foo(int32_t a, int32_t b)
```

See also

- the header file dspfns.h for definitions of the ETSI basic operations as a combination of C code and intrinsics
- ETSI basic operations on page 4-6 in the Compiler User Guide
- ETSI Recommendation G.191: Software tools for speech and audio coding standardization
- ITU-T Software Tool Library 2005 User's manual, included as part of ETSI Recommendation G.191
- ETSI Recommendation G723.1 : Dual rate speech coder for multimedia communications transmitting at 5.3 and 6.3 kbit/s
- ETSI Recommendation G.729: Coding of speech at 8 kbit/s using conjugate-structure algebraic-code-excited linear prediction (CS-ACELP).

4.7.108 C55x intrinsics

The ARM compiler supports the emulation of selected TI C55x compiler intrinsics.

To make use of the TI C55x intrinsics in your own code, include the standard header file c55x.h. The intrinsics supplied in c55x.h are listed in Table 4-21.

Table 4-21 TI C55x intrinsics supported in RVCT

Intrinsics				
_abss	_lshrs	_rnd	_smas	
_count	_1sadd	_norm	_smpy	
_divs	_lsmpy	_round	_sneg	
_labss	_lsneg	_roundn	_sround	
_lmax	_lsshl	_sadd	_sroundn	

Table 4-21 TI C55x intrinsics supported in RVCT (continued)

Intrinsics			
_lmin	_lssub	_sh1	_sshl
_lnorm	_max	_shrs	_ssub
_lshl	_min	_smac	

Example

- the header file c55x.h for more information on the ARM implementation of the C55x intrinsics
- Publications providing information about TI compiler intrinsics are available from Texas Instruments at http://www.ti.com.

4.8 VFP status intrinsic

The compiler provides an intrinsic for reading the *Floating Point and Status Control Register* (FPSCR).

—— Note —

It is preferable to use a named register variable as an alternative method of reading this register. This provides a more efficient method of access. See *Named register variables* on page 4-192.

4.8.1 __vfp_status

This intrinsic reads the FPSCR.

Syntax

unsigned int __vfp_status(unsigned int mask, unsigned int flags);

Errors

The compiler generates an error if you attempt to use this intrinsic when compiling for a target that does not have VFP.

See also

• the ARM Architecture Reference Manual for information about the FPSCR register.

4.9 Named register variables

The compiler enables you to access registers of an ARM architecture-based processor using named register variables.

4.9.1 Syntax

register type var-name __asm(reg);

Where:

type is the type of the named register variable.

Any type of the same size as the register being named can be used in the declaration of a named register variable. The type can be a structure, but

bitfield layout is sensitive to endianness.

var-name is the name of the named register variable.

reg is a character string denoting the name of a register on an ARM

architecture-based processor.

Registers available for use with named register variables on ARM

architecture-based processors are shown in Table 4-22.

Table 4-22 Named registers available on ARM architecture-based processors

Register	Character string forasm	Processors
CPSR	"cpsr" or "apsr"	All processors
BASEPRI	"basepri"	Cortex-M3, Cortex-M4
BASEPRI_MAX	"basepri_max"	Cortex-M3, Cortex-M4
CONTROL	"control"	Cortex-M0, Cortex-M1, Cortex-M3, Cortex-M4
EAPSR	"eapsr"	Cortex-M0, Cortex-M1, Cortex-M3, Cortex-M4
EPSR	"epsr"	Cortex-M0, Cortex-M1, Cortex-M3, Cortex-M4
FAULTMASK	"faultmask"	Cortex-M3, Cortex-M4
IAPSR	"iapsr"	Cortex-M0, Cortex-M1, Cortex-M3, Cortex-M4

Table 4-22 Named registers available on ARM architecture-based processors

Register	Character string forasm	Processors
IEPSR	"iepsr"	Cortex-M0, Cortex-M1, Cortex-M3, Cortex-M4
IPSR	"ipsr"	Cortex-M0, Cortex-M1, Cortex-M3, Cortex-M4
MSP	"msp"	Cortex-M0, Cortex-M1, Cortex-M3, Cortex-M4
PRIMASK	"primask"	Cortex-M0, Cortex-M1, Cortex-M3, Cortex-M4
PSP	"psp"	Cortex-M0, Cortex-M1, Cortex-M3, Cortex-M4
r0 to r12	"r0" to "r12"	All processors
r13 or sp	"r13" or "sp"	All processors
r14 or 1r	"r14" or "lr"	All processors
r15 or pc	"r15" or "pc"	All processors
SPSR	"spsr"	All processors
XPSR	"xpsr"	Cortex-M0, Cortex-M1, Cortex-M3, Cortex-M4

On targets with a VFP, the registers of Table 4-23 are also available for use with named register variables.

Table 4-23 Named registers available on targets with a VFP

Register	Character string forasm
FPSID	"fpsid"
FPSCR	"fpscr"
FPEXC	"fpexc"

4.9.2 Usage

You can declare named register variables as global variables. You can declare some, but not all, named register variables as local variables. In general, do not declare VFP registers and core registers as local variables. Do not declare caller-save registers, such as R0, as local variables.

4.9.3 Example

In the following example, foo is declared globally as a named register variable for the register r0.

```
register int foo __asm("r0");
void func(void)
{
    ....
}
```

4.9.4 See also

• Named register variables on page 4-12 in the Compiler User Guide.

4.10 GNU builtin functions

These functions provide compatibility with GNU library header files. The functions are described in the GNU documentation. See http://gcc.gnu.org. See also --gnu_version=version on page 2-69.

4.10.1 Nonstandard functions

```
__builtin_alloca(), __builtin_bcmp(), __builtin_exit(), __builtin_gamma(),
__builtin_gammaf(), __builtin_gammal(), __builtin_index(), __builtin_rindex(),
__builtin_strcasecmp(), __builtin_strncasecmp().
```

4.10.2 **C99** functions

```
__builtin_Exit(), __builtin_acoshf(), __builtin_acosh(), __builtin_acosh(),
__builtin_asinhf(), __builtin_asinhl(), __builtin_asinh(), __builtin_atanhf(),
__builtin_atanhl(), __builtin_atanh(), __builtin_cabsf(), __builtin_cabsl(),
__builtin_cabs(), __builtin_cacosf(), __builtin_cacoshf(), __builtin_cacoshl(),
__builtin_cacosh(), __builtin_cacos(), __builtin_cacos(), __builtin_cargf(),
__builtin_cargl(), __builtin_carg(), __builtin_casinf(), __builtin_casinhf(),
__builtin_casinhl(), __builtin_casinh(), __builtin_casinl(), __builtin_casin(),
__builtin_catanf(), __builtin_catanhf(), __builtin_catanhl(),
__builtin_catanh(), __builtin_catanl(), __builtin_catan(), __builtin_cbrtf(),
__builtin_cbrtl(), __builtin_cbrt(), __builtin_ccosf(), __builtin_ccoshf(),
__builtin_ccoshl(), __builtin_ccosh(), __builtin_ccosl(), __builtin_ccos(),
__builtin_cexpf(), __builtin_cexpl(), __builtin_cexp(), __builtin_cimagf(),
__builtin_cimagl(), __builtin_cimag(), __builtin_clogf(), __builtin_clogl(),
__builtin_clog(), __builtin_conjf(), __builtin_conjl(), __builtin_conj(),
__builtin_copysignf(), __builtin_copysignl(), __builtin_copysign(),
__builtin_cpowf(), __builtin_cpowl(), __builtin_cpow(), __builtin_cprojf(),
__builtin_cprojl(), __builtin_cproj(), __builtin_crealf(), __builtin_creall(),
__builtin_creal(), __builtin_csinf(), __builtin_csinhf(), __builtin_csinhl(),
__builtin_csinh(), __builtin_csinl(), __builtin_csin(), __builtin_csqrtf(),
__builtin_csqrtl(), __builtin_csqrt(), __builtin_ctanf(), __builtin_ctanhf(),
__builtin_ctanhl(), __builtin_ctanh(), __builtin_ctanl(), __builtin_ctan(),
__builtin_erfcf(), __builtin_erfcl(), __builtin_erfc(), __builtin_erff(),
__builtin_erfl(), __builtin_erf(), __builtin_exp2f(), __builtin_exp2l(),
__builtin_exp2(), __builtin_expm1f(), __builtin_expm1l(), __builtin_expm1(),
__builtin_fdimf(), __builtin_fdiml(), __builtin_fdim(), __builtin_fmaf(),
__builtin_fmal(), __builtin_fmaxf(), __builtin_fmaxl(), __builtin_fmax(),
__builtin_fma(), __builtin_fminf(), __builtin_fmin1(), __builtin_fmin(),
__builtin_hypotf(), __builtin_hypotl(), __builtin_hypot(), __builtin_ilogbf(),
__builtin_ilogbl(), __builtin_ilogb(), __builtin_imaxabs(), __builtin_isblank(),
__builtin_isfinite(), __builtin_isinf(), __builtin_isnan(), __builtin_isnanf(),
__builtin_isnanl(), __builtin_isnormal(), __builtin_iswblank(),
__builtin_lgammaf(), __builtin_lgammal(), __builtin_lgamma(), __builtin_llabs(),
__builtin_llrintf(), __builtin_llrintl(), __builtin_llrint(),
__builtin_llroundf(), __builtin_llroundl(), __builtin_llround(),
```

```
__builtin_log1pf(), __builtin_log1pl(), __builtin_log1p(), __builtin_log2f(),
__builtin_log2l(), __builtin_log2(), __builtin_logbf(), __builtin_logbl(),
__builtin_logb(), __builtin_lrintf(), __builtin_lrintl(), __builtin_lrint(),
__builtin_lroundf(), __builtin_lroundl(), __builtin_lround(),
__builtin_nearbyintf(), __builtin_nearbyintl(), __builtin_nearbyint(),
__builtin_nextafterf(), __builtin_nextafterl(), __builtin_nextafter(),
__builtin_nexttowardf(), __builtin_nexttowardl(), __builtin_nexttoward(),
__builtin_remainderf(), __builtin_remainderl(), __builtin_remainder(),
__builtin_remquof(), __builtin_remquol(), __builtin_remquo(), __builtin_rintf(),
__builtin_rintl(), __builtin_rint(), __builtin_roundf(), __builtin_roundl(),
__builtin_round(), __builtin_scalblnf(), __builtin_scalblnl(),
__builtin_scalbln(), __builtin_scalbnf(), __builtin_calbnl(),
__builtin_scalbn(), __builtin_signbit(), __builtin_signbitf(),
__builtin_signbitl(), __builtin_snprintf(), __builtin_tgammaf(),
__builtin_tgammal(), __builtin_tgamma(), __builtin_truncf(), __builtin_truncl(),
__builtin_trunc(), __builtin_vfscanf(), __builtin_vscanf(),
__builtin_vsnprintf(), __builtin_vsscanf().
```

4.10.3 C99 functions in the C90 reserved namespace

```
__builtin_acosf(), __builtin_acosl(), __builtin_asinf(), __builtin_asinl(),
__builtin_atan2f(), __builtin_atan2l(), __builtin_atanf(), __builtin_atanl(),
__builtin_ceilf(), __builtin_ceill(), __builtin_cosf(), __builtin_coshf(),
__builtin_coshl(), __builtin_cosl(), __builtin_expf(), __builtin_expl(),
__builtin_fabsf(), __builtin_fabsl(), __builtin_floorf(), __builtin_floorl(),
__builtin_fmodf(), __builtin_fmodl(), __builtin_frexpf(), __builtin_frexpl(),
__builtin_ldexpf(), __builtin_ldexpl(), __builtin_logl0f(), __builtin_logl0l(),
__builtin_logf(), __builtin_logl(), __builtin_sinf(), __builtin_sinhf(),
__builtin_sinhl(), __builtin_sinl(), __builtin_sqrtf(), sqrtl, __builtin_tanf(),
__builtin_tanhf(), __builtin_tanhl(), __builtin_tanl().
```

4.10.4 **C94** functions

```
__builtin_swalnum(), __builtin_iswalpha(), __builtin_iswcntrl(),
__builtin_iswdigit(), __builtin_iswgraph(), __builtin_iswlower(),
__builtin_iswprint(), __builtin_iswpunct(), __builtin_iswspace(),
__builtin_iswupper(), __builtin_iswxdigit(), __builtin_towlower(),
__builtin_towupper().
```

4.10.5 **C90** functions

```
__builtin_abort(), __builtin_abs(), __builtin_acos(), __builtin_asin(),
__builtin_atan2(), __builtin_atan(), __builtin_calloc(), __builtin_ceil(),
__builtin_cosh(), __builtin_cos(), __builtin_exit(), __builtin_exp(),
__builtin_fabs(), __builtin_floor(), __builtin_fmod(), __builtin_fprintf(),
__builtin_fputc(), __builtin_fputs(), __builtin_frexp(), __builtin_fscanf(),
__builtin_isalnum(), __builtin_isalpha(), __builtin_iscntrl(),
```

```
__builtin_isdigit(), __builtin_isgraph(), __builtin_islower(),
__builtin_isprint(), __builtin_ispunct(), __builtin_isspace(),
__builtin_isupper(), __builtin_isxdigit(), __builtin_tolower(),
__builtin_toupper(), __builtin_labs(), __builtin_ldexp(), __builtin_log10(),
__builtin_log(), __builtin_malloc(), __builtin_memchr(), __builtin_memcp(),
__builtin_memcpy(), __builtin_memset(), __builtin_modf(), __builtin_pow(),
__builtin_printf(), __builtin_putchar(), __builtin_puts(), __builtin_scanf(),
__builtin_sinh(), __builtin_sin(), __builtin_snprintf(), __builtin_sprintf(),
__builtin_sqrt(), __builtin_scanf(), __builtin_strcat(), __builtin_strchr(),
__builtin_strcmp(), __builtin_strcpy(), __builtin_strcspn(),
__builtin_strncpy(), __builtin_strpbrk(), __builtin_strrchr(),
__builtin_strspn(), __builtin_strstr(), __builtin_tanh(), __builtin_tan(),
__builtin_vfprintf(), __builtin_vprintf(), __builtin_vsprintf().
```

4.10.6 C99 floating-point functions

```
__builtin_huge_val(), __builtin_huge_valf(), __builtin_huge_vall(),
__builtin_inf(), __builtin_nan(), __builtin_nanf(), __builtin_nanl(),
__builtin_nans(), __builtin_nansf(), __builtin_nansl().
```

4.10.7 Other builtin functions

```
__builtin_clz(), __builtin_constant_p(), __builtin_ctz(), __builtin_ctzl(),
__builtin_ctzll(), __builtin_expect(), __builtin_ffs(), __builtin_ffsl(),
__builtin_ffsll(), __builtin_frame_address(), __builtin_return_address(),
__builtin_popcount(), __builtin_signbit().
```

4.11 Compiler predefines

This section documents the predefined macros of the ARM compiler.

4.11.1 Predefined macros

Table 4-24 lists the macro names predefined by the ARM compiler for C and C++. Where the value field is empty, the symbol is only defined.

Table 4-24 Predefined macros

Name	Value	When defined
arm	-	Always defined for the ARM compiler, even when you specify thethumb option.
		See alsoARMCC_VERSION.
ARMCC_VERSION	ver	Always defined. It is a decimal number, and is guaranteed to increase between releases. The format is <i>PVbbbb</i> where:
		• P is the major version
		• V is the minor version
		• <i>bbbb</i> is the build number.
		Note
		Use this to distinguish between RVCT and other tools that definearm
APCS_INTERWORK	-	When you specify theapcs /interwork option or set the CPU architecture to ARMv5T or later.
APCS_ROPI	_	When you specify theapcs /ropi option.
APCS_RWPI	_	When you specify theapcs /rwpi option.
APCS_FPIC	_	When you specify theapcs /fpic option.
ARRAY_OPERATORS	-	In C++ compiler mode, to specify that array new and delete are enabled.
BASE_FILE	name	Always defined. Similar toFILE, but indicates the primary source file rather than the current one (that is, when the current file is an included file).
BIG_ENDIAN	_	If compiling for a big-endian target.
_B00L	_	In C++ compiler mode, to specify that bool is a keyword.
cplusplus	_	In C++ compiler mode.

Table 4-24 Predefined macros (continued)

Name	Value	When defined
CC_ARM	1	Always set to 1 for the ARM compiler, even when you specify thethumb option.
CHAR_UNSIGNED	-	In GNU mode. It is defined if and only if char is an unsigned type.
DATE	date	Always defined.
EDG	_	Always defined.
EDG_IMPLICIT_USING_STD	_	In C++ mode when you specify theimplicit_using_std option.
EDG_VERSION	-	Always set to an integer value that represents the version number of the <i>Edison Design Group</i> (EDG) front-end. For example, version 3.8 is represented as 308.
		The version number of the EDG front-end does not necessarily match the RVCT or RealView Development Suite version number.
EXCEPTIONS	1	In C++ mode when you specify theexceptions option.
FEATURE_SIGNED_CHAR	_	When you specify thesigned_chars option (used by CHAR_MIN and CHAR_MAX).
FILE	name	Always defined as a string literal.
FP_FAST	_	When you specify thefpmode=fast option.
FP_FENV_EXCEPTIONS	_	When you specify thefpmode=ieee_full orfpmode=ieee_fixed options.
FP_FENV_ROUNDING	_	When you specify thefpmode=ieee_full option.
FP_IEEE	_	When you specify thefpmode=ieee_full,fpmode=ieee_fixed, orfpmode=ieee_no_fenv options.
FP_INEXACT_EXCEPTION	_	When you specify thefpmode=ieee_full option.
GNUC	ver	When you specify thegnu option. It is an integer that shows the current major version of the GNU mode being used.
GNUC_MINOR ver		When you specify thegnu option. It is an integer that shows the current minor version of the GNU mode being used.
		current minor version of the Give mode being used.
GNUG	ver	In GNU mode when you specify thecpp option. It has the same value asGNUC

Table 4-24 Predefined macros (continued)

Name	Value	When defined
INTMAX_TYPE	-	In GNU mode. It defines the correct underlying type for the intmax_t typedef.
LINE	num	Always set. It is the source line number of the line of code containing this macro.
MODULE	mod	Contains the filename part of the value ofFILE
NO_INLINE	_	When you specify theno_inline option in GNU mode.
OPTIMISE_LEVEL	num	Always set to 2 by default, unless you change the optimization level using the -0num option.
OPTIMISE_SPACE	_	When you specify the -0space option.
OPTIMISE_TIME	_	When you specify the -Otime option.
OPTIMIZE	-	When -01, -02, or -03 is specified in GNU mode.
OPTIMIZE_SIZE	_	When -0space is specified in GNU mode.
PLACEMENT_DELETE	-	In C++ mode to specify that placement delete (that is, an operator delete corresponding to a placement operator new , to be called if the constructor throws an exception) is enabled. This is only relevant when using exceptions.
PTRDIFF_TYPE	-	In GNU mode. It defines the correct underlying type for the ptrdiff_t typedef.
RTTI	-	In C++ mode when RTTI is enabled.
sizeof_int	4	For sizeof(int), but available in preprocessor expressions.
sizeof_long	4	For sizeof(long), but available in preprocessor expressions.
sizeof_ptr	4	For sizeof(void *), but available in preprocessor expressions.
SIZE_TYPE	-	In GNU mode. It defines the correct underlying type for the size_t typedef.
SOFTFP	-	If compiling to use the software floating-point calling standard and library. Set when you specify thefpu=softvfp option for ARM or Thumb, or when you specifyfpu=softvfp+vfpv2 for Thumb.
STDC	_	In all compiler modes.
STDC_VERSION	-	Standard version information.

Table 4-24 Predefined macros (continued)

Name	Value	When defined
STRICT_ANSI	_	When you specify thestrict option.
SUPPORT_SNAN	-	Support for signalling NaNs when you specifyfpmode=ieee_fixed orfpmode=ieee_full.
TARGET_ARCH_ARM	num	The number of the ARM base architecture of the target CPU irrespective of whether the compiler is compiling for ARM or Thumb. For possible values ofTARGET_ARCH_ARM in relation to the ARM architecture versions, see Table 4-25 on page 4-204.
TARGET_ARCH_THUMB	num	The number of the Thumb base architecture of the target CPU irrespective of whether the compiler is compiling for ARM or Thumb. The value is defined as zero if the target does not support Thumb. For possible values ofTARGET_ARCH_THUMB in relation to the ARM architecture versions, see Table 4-25 on page 4-204.
TARGET_ARCH_XX	-	XX represents the target architecture and its value depends on the target architecture. For example, if you specify the compiler optionscpu=4T orcpu=ARM7TDMI thenTARGET_ARCH_4T is defined.
TARGET_CPU_ <i>XX</i>	-	XX represents the target CPU. The value of XX is derived from thecpu compiler option, or the default if none is specified. For example, if you specify the compiler optioncpu=ARM7TM thenTARGET_CPU_ARM7TM is defined and no other symbol starting withTARGET_CPU_ is defined.
		If you specify the target architecture, thenTARGET_CPU_generic is defined.
		If the CPU name specified withcpu is in lowercase, it is converted to uppercase. For example,cpu=Cortex-R4 results inTARGET_CPU_CORTEX_R4 being defined (rather thanTARGET_CPU_Cortex_R4).
		If the processor name contains hyphen (-) characters, these are mapped to an underscore (_). For example,cpu=ARM1136JF-S is mapped toTARGET_CPU_ARM1136JF_S.
TARGET_FEATURE_DOUBLEWORD	-	ARMv5T and above.
TARGET_FEATURE_DSPMUL	_	If the DSP-enhanced multiplier is available, for example ARMv5TE.
TARGET_FEATURE_MULTIPLY	_	If the target architecture supports the long multiply instructions MULL and MULAL.
TARGET_FEATURE_DIVIDE	-	If the target architecture supports the hardware divide instruction (that is, ARMv7-M or ARMv7-R).

Table 4-24 Predefined macros (continued)

Name	Value	When defined
TARGET_FEATURE_MULTIPROCESSING	_	When you specify any of the following options:
		•cpu=Cortex-A9
		•cpu=Cortex-A9.no_neon
		•cpu=Cortex-A9.no_neon.no_vfp
TARGET_FEATURE_THUMB	_	If the target architecture supports Thumb, ARMv4T or later.
TARGET_FPU_xx	_	One of the following is set to indicate the FPU usage:
		•TARGET_FPU_NONE
		 TARGET_FPU_VFP
		TARGET_FPU_SOFTVFP
		In addition, if compiling with one of the followingfpu options, the corresponding target name is set:
		 fpu=softvfp+vfpv2,TARGET_FPU_SOFTVFP_VFPV2
		 fpu=softvfp+vfpv3,TARGET_FPU_SOFTVFP_VFPV3
		 fpu=softvfp+vfpv3_fp16,TARGET_FPU_SOFTVFP_VFPV3_FP16
		 fpu=softvfp+vfpv3_d16,TARGET_FPU_SOFTVFP_VFPV3_D16
		 fpu=softvfp+vfpv3_d16_fp16,
		TARGET_FPU_SOFTVFP_VFPV3_D16_FP16
		 fpu=vfpv2,TARGET_FPU_VFPV2
		 fpu=vfpv3,TARGET_FPU_VFPV3
		 fpu=vfpv3_fp16,TARGET_FPU_VFPV3_FP16
		fpu=vfpv3_d16,TARGET_FPU_VFPV3_D16
		 fpu=vfpv3_d16_fp16,TARGET_FPU_VFPV3_D16_FP16
		Seefpu=name on page 2-62 for more information.
TARGET_PROFILE_A		When you specify thecpu=7-A option.
TARGET_PROFILE_R		When you specify thecpu=7-R option.
TARGET_PROFILE_M		When you specify any of the following options:
		•cpu=6-M
		•cpu=6S-M
		•cpu=7-M

Table 4-24 Predefined macros (continued)

Name	Value	When defined	
thumb	-	When the compiler is in Thumb mode. That is, you have either specified thethumb option on the command-line or #pragma thumb your source code.	
		Note	
		• The compiler might generate some ARM code even if it is compiling for Thumb.	
		 thumb andthumb become defined or undefined when using #pragma thumb or #pragma arm, but do not change in cases where Thumb functions are generated as ARM code for other reasons (for example, a function specified asirq). 	
TIME	time	Always defined.	
UINTMAX_TYPE	_	In GNU mode. It defines the correct underlying type for the uintmax_t typedef.	
USER_LABEL_PREFIX		In GNU mode. It defines an empty string. This macro is used by some of the Linux header files.	
VERSION	ver	When you specify thegnu option. It is a string that shows the current version of the GNU mode being used.	
_WCHAR_T	-	In C++ mode, to specify that wchar_t is a keyword.	
WCHAR_TYPE	-	In GNU mode. It defines the correct underlying type for the wchar_t typedef.	
WCHAR_UNSIGNED	-	In GNU mode when you specify thecpp option. It is defined if and only if wchar_t is an unsigned type.	
WINT_TYPE	-	In GNU mode. It defines the correct underlying type for the wint_t typedef.	

Table 4-25 shows the possible values for __TARGET_ARCH_THUMB (see Table 4-24 on page 4-198), and how these values relate to versions of the ARM architecture.

Table 4-25 Thumb architecture versions in relation to ARM architecture versions

ARM architecture	TARGET_ARCH_ARM	TARGET_ARCH_THUMB
v4	4	0
v4T	4	1
v5T, v5TE, v5TEJ	5	2
v6, v6K, v6Z	6	3
v6T2	6	4
v6-M, v6S-M	0	3
v7-A, v7-R	7	4
v7-M	0	4

4.11.2 Function names

Table 4-26 lists builtin variables supported by the ARM compiler for C and C++.

Table 4-26 Builtin variables

Name	Value
FUNCTION	Holds the name of the function as it appears in the sourceFUNCTION is a constant string literal. You cannot use the preprocessor to join the contents to other text to form new tokens.
PRETTY_FUNCTION	Holds the name of the function as it appears pretty printed in a language-specific fashion. PRETTY_FUNCTION is a constant string literal. You cannot use the preprocessor to join the contents to other text to form new tokens.

Chapter 5 C and C++ Implementation Details

This chapter describes the language implementation details for the ARM compiler. It includes:

- *C and C++ implementation details* on page 5-2
- C++ *implementation details* on page 5-13.

5.1 C and C++ implementation details

This section describes language implementation details common to both C and C++.

5.1.1 Character sets and identifiers

The following points apply to the character sets and identifiers expected by the compiler:

- Uppercase and lowercase characters are distinct in all internal and external identifiers. An identifier can also contain a dollar (\$) character unless the --strict compiler option is specified. To permit dollar signs in identifiers with the --strict option, also use the --dollar command-line option.
- Calling setlocale(LC_CTYPE, "IS08859-1") makes the isupper() and islower() functions behave as expected over the full 8-bit Latin-1 alphabet, rather than over the 7-bit ASCII subset. The locale must be selected at link-time.
- Source files are compiled according to the currently selected locale. You might have to select a different locale, with the --locale command-line option, if the source file contains non-ASCII characters. See *Invoking the ARM compiler* on page 2-2 in the *Compiler User Guide* for more information.
- The ARM compiler supports multibyte character sets, such as Unicode.
- Other properties of the source character set are host-specific.

The properties of the execution character set are target-specific. The ARM C and C++ libraries support the ISO 8859-1 (Latin-1 Alphabet) character set with the following consequences:

- The execution character set is identical to the source character set.
- There are eight bits in a character in the execution character set.
- There are four characters (bytes) in an **int**. If the memory system is:

Little-endian The bytes are ordered from least significant at the lowest

address to most significant at the highest address.

Big-endian The bytes are ordered from least significant at the highest

address to most significant at the lowest address.

• In C all character constants have type int. In C++ a character constant containing one character has the type char and a character constant containing more than one character has the type int. Up to four characters of the constant are represented in

the integer value. The last character in the constant occupies the lowest-order byte of the integer value. Up to three preceding characters are placed at higher-order bytes. Unused bytes are filled with the NULL $(\0)$ character.

 Table 5-1 lists all integer character constants, that contain a single character or character escape sequence, are represented in both the source and execution character sets.

Table 5-1 Character escape codes

Escape sequence	Char value	Description
\a	7	Attention (bell)
\b	8	Backspace
\t	9	Horizontal tab
\n	10	New line (line feed)
\v	11	Vertical tab
\f	12	Form feed
\r	13	Carriage return
\xnn	0xnn	ASCII code in hexadecimal
\nnn	0nnn	ASCII code in octal

- Characters of the source character set in string literals and character constants map identically into the execution character set.
- Data items of type **char** are unsigned by default. They can be explicitly declared as **signed char** or **unsigned char**:
 - the --signed_chars option can be used to make the **char** signed
 - the --unsigned_chars option can be used to make the **char** unsigned.

Note	Note	
------	------	--

Care must be taken when mixing translation units that have been compiled with and without the --signed_chars and --unsigned_chars options, and that share interfaces or data structures.

The ARM ABI defines **char** as an unsigned byte, and this is the interpretation used by the C++ libraries supplied with RVCT.

 No locale is used to convert multibyte characters into the corresponding wide characters for a wide character constant. This is not relevant to the generic implementation.

5.1.2 Basic data types

This section describes how the basic data types are implemented in ARM C and C++.

Size and alignment of basic data types

Table 5-2 gives the size and natural alignment of the basic data types.

Table 5-2 Size and alignment of data types

Туре	Size in bits	Natural alignment in bytes
char	8	1 (byte-aligned)
short	16	2 (halfword-aligned)
int	32	4 (word-aligned)
long	32	4 (word-aligned)
long long	64	8 (doubleword-aligned)
float	32	4 (word-aligned)
doub1 e	64	8 (doubleword-aligned)
long double	64	8 (doubleword-aligned)
All pointers	32	4 (word-aligned)
bool (C++ only)	8	1 (byte-aligned)
_Bool (C only ^a)	8	1 (byte-aligned)
wchar_t (C++ only)	16	2 (halfword-aligned)

a. stdbool, h can be used to define the bool macro in C.

Type alignment varies according to the context:

- Local variables are usually kept in registers, but when local variables spill onto the stack, they are always word-aligned. For example, a spilled local **char** variable has an alignment of 4.
- The natural alignment of a packed type is 1.

See Structures, unions, enumerations, and bitfields on page 5-7 for more information.

Integer

Integers are represented in two's complement form. The low word of a long long is at the low address in little-endian mode, and at the high address in big-endian mode.

Float

Floating-point quantities are stored in IEEE format:

- float values are represented by IEEE single-precision values
- double and long double values are represented by IEEE double-precision values.

For **double** and **long double** quantities the word containing the sign, the exponent, and the most significant part of the mantissa is stored with the lower machine address in big-endian mode and at the higher address in little-endian mode. See *Operations on floating-point types* on page 5-6 for more information.

Arrays and pointers

The following statements apply to all pointers to objects in C and C++, except pointers to members:

- Adjacent bytes have addresses that differ by one.
- The macro NULL expands to the value 0.
- Casting between integers and pointers results in no change of representation.
- The compiler warns of casts between pointers to functions and pointers to data.
- The type size_t is defined as unsigned int.
- The type ptrdiff_t is defined as signed int.

5.1.3 Operations on basic data types

The ARM compiler performs the usual arithmetic conversions set out in relevant sections of the ISO C99 and ISO C++ standards. The following subsections describe additional points that relate to arithmetic operations.

See also *Expression evaluation* on page B-7.

Operations on integral types

The following statements apply to operations on the integral types:

• All signed integer arithmetic uses a two's complement representation.

- Bitwise operations on signed integral types follow the rules that arise naturally from two's complement representation. No sign extension takes place.
- Right shifts on signed quantities are arithmetic.
- For values of type int,
 - Shifts outside the range 0 to 127 are undefined.
 - Left shifts of more than 31 give a result of zero.
 - Right shifts of more than 31 give a result of zero from a shift of an unsigned value or positive signed value. They yield -1 from a shift of a negative signed value.
- For values of type long long, shifts outside the range 0 to 63 are undefined.
- The remainder on integer division has the same sign as the numerator, as mandated by the ISO C99 standard.
- If a value of integral type is truncated to a shorter signed integral type, the result is obtained by discarding an appropriate number of most significant bits. If the original number is too large, positive or negative, for the new type, there is no guarantee that the sign of the result is going to be the same as the original.
- A conversion between integral types does not raise an exception.
- Integer overflow does not raise an exception.
- Integer division by zero returns zero by default.

Operations on floating-point types

The following statements apply to operations on floating-point types:

- Normal IEEE 754 rules apply.
- Rounding is to the nearest representable value by default.
- Floating-point exceptions are disabled by default.

Also, see --fpmode=model on page 2-59.

Note
The IEEE 754 standard for floating-point processing states that the default action to an
exception is to proceed without a trap. You can modify floating-point error handling by
tailoring the functions and definitions in fenv.h. See Tailoring error signaling, error
handling, and program exit on page 2-59 for more information.

Pointer subtraction

The following statements apply to all pointers in C. They also apply to pointers in C++, other than pointers to members:

 When one pointer is subtracted from another, the difference is the result of the expression:

```
((int)a - (int)b) / (int)sizeof(type pointed to)
```

- If the pointers point to objects whose alignment is the same as their size, this alignment ensures that division is exact.
- If the pointers point to objects whose alignment is less than their size, such as packed types and most **structs**, both pointers must point to elements of the same array.

5.1.4 Structures, unions, enumerations, and bitfields

This section describes the implementation of the structured data types union, enum, and struct. It also discusses structure padding and bitfield implementation.

See Anonymous classes, structures and unions on page 3-20 for more information.

Unions

When a member of a **union** is accessed using a member of a different type, the resulting value can be predicted from the representation of the original type. No error is given.

Enumerations

An object of type **enum** is implemented in the smallest integral type that contains the range of the **enum**. The storage type of an **enum** is the first of the following, according to the range of the enumerators in the **enum**:

- unsigned char if not using --enum_is_int
- signed char if not using --enum_is_int
- unsigned short if not using --enum_is_int
- signed short if not using --enum_is_int
- signed int
- **unsigned int** except C with --strict
- **signed long long** except C with --strict
- unsigned long long except C with --strict.

Implementing **enum** in this way can reduce data size. The command-line option --enum_is_int forces the underlying type of **enum** to at least as wide as **int**.

See the description of C language mappings in the *Procedure Call Standard for the ARM Architecture* specification for more information.



Care must be taken when mixing translation units that have been compiled with and without the --enum_is_int option, and that share interfaces or data structures.

Handling values that are out of range

In strict C, enumerator values must be representable as **ints**, for example, they must be in the range -2147483648 to +2147483647, inclusive. In previous releases of RVCT out-of-range values were cast to **int** without a warning (unless you specified the --strict option).

In RVCT v2.2 and later, a Warning is issued for out-of-range enumerator values:

#66: enumeration value is out of "int" range

Such values are treated the same way as in C++, that is, they are treated as **unsigned int**, long long, or **unsigned long long**.

To ensure that out-of-range Warnings are reported, use the following command to change them into Errors:

armcc --diag_error=66 ...

Structures

The following points apply to:

- all C structures
- all C++ structures and classes not using virtual functions or base classes.

Structure alignment

The alignment of a non-packed structure is the maximum alignment required by any of its fields.

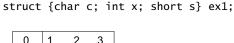
Field alignment

Structures are arranged with the first-named component at the lowest address. Fields are aligned as follows:

- A field with a **char** type is aligned to the next available byte.
- A field with a **short** type is aligned to the next even-addressed byte.

- In RVCT v2.0 and above, double and long long data types are eight-byte aligned. This enables efficient use of the LDRD and STRD instructions in ARMv5TE and above.
- Bitfield alignment depends on how the bitfield is declared. See *Bitfields in packed structures* on page 5-12 for more information.
- All other types are aligned on word boundaries.

Structures can contain padding to ensure that fields are correctly aligned and that the structure itself is correctly aligned. Figure 5-1 shows an example of a conventional, non-packed structure. Bytes 1, 2, and 3 are padded to ensure correct field alignment. Bytes 11 and 12 are padded to ensure correct structure alignment. The sizeof() function returns the size of the structure including padding.



0	٠.	_	0
С	p	addir	ng
4	5	7	8
	Х		
9	10	11	12
s	3	pad	ding

Figure 5-1 Conventional non-packed structure example

The compiler pads structures in one of the following ways, according to how the structure is defined:

- Structures that are defined as **static** or **extern** are padded with zeros.
- Structures on the stack or heap, such as those defined with malloc() or **auto**, are padded with whatever is previously stored in those memory locations. You cannot use memcmp() to compare padded structures defined in this way (see Figure 5-1).

Use the --remarks option to view the messages that are generated when the compiler inserts padding in a **struct**.

Structures with empty initializers are permitted in C++:

```
struct
{
    int x;
} X = { };
```

However, if you are compiling C, or compiling C++ with the -cpp and--c90 options, an error is generated.

Packed structures

A packed structure is one where the alignment of the structure, and of the fields within it, is always 1.

You can pack specific structures with the __packed qualifier. Alternatively, you can use #pragma pack(n) to make sure that any structures with unaligned data are packed. There is no command-line option to change the default packing of structures.

Bitfields

In non-packed structures, the ARM compiler allocates bitfields in *containers*. A container is a correctly aligned object of a declared type.

Bitfields are allocated so that the first field specified occupies the lowest-addressed bits of the word, depending on configuration:

Little-endian Lowest addressed means least significant.

Big-endian Lowest addressed means most significant.

A bitfield container can be any of the integral types.

_____Note _____

In strict 1990 ISO Standard C, the only types permitted for a bit field are int, signed int, and unsigned int. For non int bitfields, the compiler displays an error.

A plain bitfield, declared without either **signed** or **unsigned** qualifiers, is treated as **unsigned**. For example, int x:10 allocates an unsigned integer of 10 bits.

A bitfield is allocated to the first container of the correct type that has a sufficient number of unallocated bits, for example:

```
struct X
{
    int x:10;
    int y:20;
};
```

The first declaration creates an integer container and allocates 10 bits to x. At the second declaration, the compiler finds the existing integer container with a sufficient number of unallocated bits, and allocates y in the same container as x.

A bitfield is wholly contained within its container. A bitfield that does not fit in a container is placed in the next container of the same type. For example, the declaration of z overflows the container if an additional bitfield is declared for the structure:

```
struct X
{
    int x:10;
    int y:20;
    int z:5;
};
```

The compiler pads the remaining two bits for the first container and assigns a new integer container for z.

Bitfield containers can *overlap* each other, for example:

```
struct X
{
    int x:10;
    char y:2;
};
```

The first declaration creates an integer container and allocates 10 bits to x. These 10 bits occupy the first byte and two bits of the second byte of the integer container. At the second declaration, the compiler checks for a container of type **char**. There is no suitable container, so the compiler allocates a new correctly aligned **char** container.

Because the natural alignment of **char** is 1, the compiler searches for the first byte that contains a sufficient number of unallocated bits to completely contain the bitfield. In the example structure, the second byte of the **int** container has two bits allocated to x, and six bits unallocated. The compiler allocates a **char** container starting at the second byte of the previous **int** container, skips the first two bits that are allocated to x, and allocates two bits to y.

If y is declared char y:8, the compiler pads the second byte and allocates a new **char** container to the third byte, because the bitfield cannot overflow its container. Figure 5-2 shows the bitfield allocation for the following example structure:

```
struct X
{
    int x:10;
    char y:8;
};
```

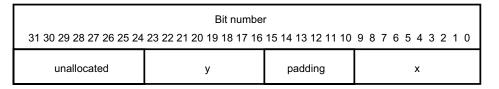
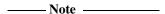


Figure 5-2 Bitfield allocation 1



The same basic rules apply to bitfield declarations with different container types. For example, adding an **int** bitfield to the example structure gives:

```
struct X
{
    int x:10;
    char y:8;
    int z:5;
}
```

The compiler allocates an **int** container starting at the same location as the int x:10 container and allocates a byte-aligned **char** and 5-bit bitfield, see Figure 5-3.

		Bit number		
31 30 29	28 27 26 25 24	23 22 21 20 19 18 17 16	15 14 13 12 11 10	9 8 7 6 5 4 3 2 1 0
free	Z	у	padding	x

Figure 5-3 Bitfield allocation 2

You can explicitly pad a bitfield container by declaring an unnamed bitfield of size zero. A bitfield of zero size fills the container up to the end if the container is not empty. A subsequent bitfield declaration starts a new empty container.

Bitfields in packed structures

Bitfield containers in packed structures have an alignment of 1. Therefore, the maximum bit padding for a bitfield in a packed structure is 7 bits. For an unpacked structure, the maximum padding is 8*sizeof(container-type)-1 bits.

5.2 C++ implementation details

This section describes language implementation details specific to C++.

5.2.1 Using the ::operator new function

In accordance with the ISO C++ Standard, the ::operator new(std::size_t) throws an exception when memory allocation fails rather than raising a signal. If the exception is not caught, std::terminate() is called.

The compiler option --force_new_nothrow turns all new calls in a compilation into calls to ::operator new(std::size_t, std::nothrow_t&) or :operator new[](std::size_t, std::nothrow_t&). However, this does not affect operator new calls in libraries, nor calls to any class-specific operator new. See --force_new_nothrow, --no_force_new_nothrow on page 2-57 for more information.

Legacy support

In RVCT v2.0, when the :: operator new function ran out of memory, it raised the signal **SIGOUTOFHEAP**, instead of throwing a C++ exception. See *ISO C library implementation definition* on page 2-97 in the *Libraries and Floating Point Support Guide*.

In the current release, it is possible to install a new_handler to raise a signal and so restore the RVCT v2.0 behavior.

Note
Do not rely on the implementation details of this behavior, because it might change in
future releases.

5.2.2 Tentative arrays

The ADS v1.2 and RVCT v1.2 C++ compilers enabled you to use tentative, that is, incomplete array declarations, for example, int a[]. You cannot use tentative arrays when compiling C++ with the RVCT v2.x compilers or above.

5.2.3 Old-style C parameters in C++ functions

The ADS v1.2 and RVCT v1.2 C++ compilers enabled you to use old-style C parameters in C++ functions. That is,

```
void f(x) int x; { }
```

In the RVCT v2.x compilers or above, you must use the --anachronisms compiler option if your code contains any old-style parameters in functions. The compiler warns you if it finds any instances.

5.2.4 Anachronisms

The following anachronisms are accepted when you enable anachronisms using the --anachronisms option:

- **overload** is permitted in function declarations. It is accepted and ignored.
- Definitions are not required for static data members that can be initialized using default initialization. The anachronism does not apply to static data members of template classes, because these must always be defined.
- The number of elements in an array can be specified in an array delete operation. The value is ignored.
- A single operator++() and operator--() function can be used to overload both prefix and postfix operations.
- The base class name can be omitted in a base class initializer if there is only one immediate base class.
- Assignment to the this pointer in constructors and destructors is permitted.
- A bound function pointer, that is, a pointer to a member function for a given object, can be cast to a pointer to a function.
- A nested class name can be used as a non-nested class name provided no other class of that name has been declared. The anachronism is not applied to template classes.
- A reference to a non-const type can be initialized from a value of a different type.
 A temporary is created, it is initialized from the converted initial value, and the reference is set to the temporary.
- A reference to a non const class type can be initialized from an rvalue of the class type or a class derived from that class type. No, additional, temporary is used.
- A function with old-style parameter declarations is permitted and can participate in function overloading as if it were prototyped. Default argument promotion is not applied to parameter types of such functions when the check for compatibility is done, so that the following declares the overloading of two functions named f: int f(int):

```
int f(x) char x; { return x; }
```

Note	
In C, this code is legal but has a different followed by its definition.	rent meaning. A tentative declaration of f is

5.2.5 Template instantiation

The ARM compiler does all template instantiations automatically, and makes sure there is only one definition of each template entity left after linking. The compiler does this by emitting template entities in named common sections. Therefore, all duplicate common sections, that is, common sections with the same name, are eliminated by the linker.

Note
You can limit the number of concurrent instantiations of a given template with thepending_instantiations compiler option.
pending_instantiations compiler option.

See also *--pending_instantiations=n* on page 2-103 for more information.

Implicit inclusion

When implicit inclusion is enabled, the compiler assumes that if it requires a definition to instantiate a template entity declared in a .h file it can implicitly include the corresponding .cc file to get the source code for the definition. For example, if a template entity ABC::f is declared in file xyz.h, and an instantiation of ABC::f is required in a compilation but no definition of ABC::f appears in the source code processed by the compilation, then the compiler checks to see if a file xyz.cc exists. If this file exists, the compiler processes the file as if it were included at the end of the main source file.

To find the template definition file for a given template entity the compiler has to know the full path name of the file where the template is declared and whether the file is included using the system include syntax, for example, #include <file.h>. This information is not available for preprocessed source containing #line directives. Consequently, the compiler does not attempt implicit inclusion for source code containing #line directives.

The compiler looks for the definition-file suffixes .cc and .CC.

You can turn implicit inclusion mode on or off with the command-line options --implicit_include and --no_implicit_include.

Implicit inclusions are only performed during the normal compilation of a file, that is, when not using the -E command-line option.

See *Command-line options* on page 2-2 for more information.

5.2.6 Namespaces

When doing name lookup in a template instantiation, some names must be found in the context of the template definition. Other names can be found in the context of the template instantiation. The compiler implements two different instantiation lookup algorithms:

- the algorithm mandated by the standard, and referred to as dependent name lookup.
- the algorithm that exists before dependent name lookup is implemented.

Dependent name lookup is done in strict mode, unless explicitly disabled by another command-line option, or when dependent name processing is enabled by either a configuration flag or a command-line option.

Dependent name lookup processing

When doing dependent name lookup, the compiler implements the instantiation name lookup rules specified in the standard. This processing requires that non class prototype instantiations be done. This in turn requires that the code be written using the typename and template keywords as required by the standard.

Lookup using the referencing context

When not using dependent name lookup, the compiler uses a name lookup algorithm that approximates the two-phase lookup rule of the standard, but in a way that is more compatible with existing code and existing compilers.

When a name is looked up as part of a template instantiation, but is not found in the local context of the instantiation, it is looked up in a synthesized instantiation context. This synthesized instantiation context includes both names from the context of the template definition and names from the context of the instantiation. For example:

```
namespace N
{
    int g(int);
    int x = 0;
    template <class T> struct A
    {
        T f(T t) { return g(t); }
        T f() { return x; }
    };
}
```

The lookup of names in template instantiations does not conform to the rules in the standard in the following respects:

- Although only names from the template definition context are considered for names that are not functions, the lookup is not limited to those names visible at the point where the template is defined.
- Functions from the context where the template is referenced are considered for all function calls in the template. Functions from the referencing context are only visible for dependent function calls.

Argument-dependent lookup

When argument-dependent lookup is enabled, functions that are made visible using argument-dependent lookup can overload with those made visible by normal lookup. The standard requires that this overloading occur even when the name found by normal lookup is a block extern declaration. The compiler does this overloading, but in default mode, argument-dependent lookup is suppressed when the normal lookup finds a block extern.

This means a program can have different behavior, depending on whether it is compiled with or without argument-dependent lookup, even if the program makes no use of namespaces. For example:

5.2.7 C++ exception handling

C++ exception handling is fully supported in RVCT. However, the compiler does not support this by default. You must enable C++ exception handling with the --exceptions option. See --exceptions, --no_exceptions on page 2-54 for more information.

Note			
The Rogue Wave S	Standard C++ Library is p	provided with C++ ex	ceptions enabled

You can exercise limited control over exception table generation.

Function unwinding at runtime

By default, functions compiled with --exceptions can be unwound at runtime. See --exceptions, --no_exceptions on page 2-54 for more information. Function unwinding includes destroying C++ automatic variables, and restoring register values saved in the stack frame. Function unwinding is implemented by emitting an exception table describing the operations to be performed.

You can enable or disable unwinding for specific functions with the pragmas #pragma exceptions_unwind and #pragma no_exceptions_unwind, see *Pragmas* on page 4-58 for more information. The --exceptions_unwind option sets the initial value of this pragma.

Disabling function unwinding for a function has the following effects:

- Exceptions cannot be thrown through that function at runtime, and no stack unwinding occurs for that throw. If the throwing language is C++, then std::terminate is called.
- A very compact exception table representation can be used to describe the function, that assists smart linkers with table optimization.
- Function inlining is restricted, because the caller and callee must interact correctly.

Therefore, #pragma no_exceptions_unwind can be used to forcibly prevent unwinding in a way that requires no additional source decoration.

By contrast, in C++ an empty function exception specification permits unwinding as far as the protected function, then calls std::unexpected() in accordance with the ISO C++ Standard.

5.2.8 Extern inline functions

The ISO C++ Standard requires inline functions to be defined wherever you use them. To prevent the clashing of multiple out-of-line copies of inline functions, the C++ compiler emits out-of-line extern functions in common sections.

Out-of-line inline functions

The compiler emits inline functions out-of-line, in the following cases:

• The address of the function is taken, for example:

```
inline int g()
{
    return 1;
}
int (*fp)() = &g;
```

• The function cannot be inlined, for example, a recursive function:

```
inline unsigned int fact(unsigned int n) {
    return n < 2 ? 1 : n * fact(n - 1);
}</pre>
```

• The heuristic used by the compiler decides that it is better not to inline the function. This heuristic is influenced by -0space and -0time. If you use -0time, the compiler inlines more functions. You can override this heuristic by declaring a function with __forceinline. For example:

```
__forceinline int g()
{
    return 1;
}
```

See also --forceinline on page 2-58 for more information.

C and C++ Implementation Details

Appendix A Via File Syntax

This appendix describes the syntax of via files accepted by all the ARM development tools. It contains the following sections:

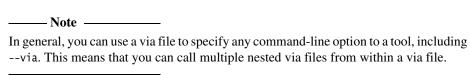
- Overview of via files on page A-2
- *Syntax* on page A-3.

A.1 Overview of via files

Via files are plain text files that contain command-line arguments and options to ARM development tools. You can use via files with all the ARM command-line tools, that is, you can specify a via file from the command line using the --via command-line option with:

- armcc
- armasm
- armlink
- fromelf
- armar.

See the documentation for the individual tool for more information.



This section includes:

• Via file evaluation.

A.1.1 Via file evaluation

When a tool that supports via files is invoked it:

- 1. Replaces the first specified --via *via_file* argument with the sequence of argument words extracted from the via file, including recursively processing any nested --via commands in the via file.
- 2. Processes any subsequent --via *via_file* arguments in the same way, in the order they are presented.

That is, via files are processed in the order you specify them, and each via file is processed completely including processing nested via files before processing the next via file.

A.2 Syntax

Via files must conform to the following syntax rules:

- A via file is a text file containing a sequence of words. Each word in the text file is converted into an argument string and passed to the tool.
- Words are separated by whitespace, or the end of a line, except in delimited strings. For example:

```
--c90 --strict (two words)
--c90--strict (one word)
```

• The end of a line is treated as whitespace. For example:

```
--c90
--strict
is equivalent to:
--c90 --strict
```

 Strings enclosed in quotation marks ("), or apostrophes (') are treated as a single word. Within a quoted word, an apostrophe is treated as an ordinary character.
 Within an apostrophe delimited word, a quotation mark is treated as an ordinary character.

Quotation marks are used to delimit filenames or path names that contain spaces. For example:

```
-I C:\My Project\includes (three words) -I "C:\My Project\includes" (two words)
```

Apostrophes can be used to delimit words that contain quotes. For example:

```
-DNAME='"RealView Compilation Tools"' (one word)
```

• Characters enclosed in parentheses are treated as a single word. For example:

```
--option(x, y, z) (one word)
--option (x, y, z) (two words)
```

- Within quoted or apostrophe delimited strings, you can use a backslash (\) character to escape the quote, apostrophe, and backslash characters.
- A word that occurs immediately next to a delimited word is treated as a single word. For example:

```
-I"C:\Project\includes"
```

is treated as the single word:

-IC:\Project\includes

- Lines beginning with a semicolon (;) or a hash (#) character as the first non whitespace character are comment lines. If a semicolon or hash character appears anywhere else in a line, it is not treated as the start of a comment. For example:
 - -o objectname.axf ; this is not a comment

A comment ends at the end of a line, or at the end of the file. There are no multi-line comments, and there are no part-line comments.

- Lines that include the preprocessor option -Dsymbol="value" must be delimited with a single quote, either as '-Dsymbol="value"' or as -Dsymbol='"value"'. For example:
 - -c -DF00_VALUE='"F00_VALUE"'

Appendix B **Standard C Implementation Definition**

This appendix gives information required by the ISO C standard for conforming C implementations. It contains the following section:

- *Implementation definition* on page B-2
- *Behaviors considered undefined by the ISO C Standard* on page B-9.

B.1 Implementation definition

Appendix G of the ISO C standard (ISO/IEC 9899:1990 (E)) collates information about portability issues. Sub-clause G3 lists the behavior that each implementation must document.
Note
This appendix does not duplicate information that is part of Chapter 4
Compiler-specific Features. This appendix provides references where applicable.

The following subsections correspond to the relevant sections of sub-clause G3. They
describe aspects of the ARM C compiler and C library, not defined by the ISO C
standard, that are implementation-defined:
Note
The support for the wctype.h and wchar.h headers excludes wide file operations.

B.1.1 Translation

Diagnostic messages produced by the compiler are of the form:

source-file, line-number: severity: error-code: explanation

where severity is one of:

[blank] If the severity is blank, this is a remark and indicates common, but

sometimes unconventional, use of C or C++. Remarks are not displayed by default. Use the --remarks option to display remark messages. See *Controlling the output of diagnostic messages* on page 6-4 for more

information. Compilation continues.

Warning Flags unusual conditions in your code that might indicate a problem.

Compilation continues.

Error Indicates a problem that causes the compilation to stop. For example,

violations in the syntactic or semantic rules of the C or C++ language.

Internal fault

Indicates an internal problem with the compiler. Contact your supplier

with the information listed in *Feedback* on page xii.

Here:

error-code Is a number identifying the error type.

explanation Is a text description of the error.

See Chapter 6 Diagnostic Messages in the Compiler User Guide for more information.

B.1.2 Environment

The mapping of a command line from the ARM architecture-based environment into arguments to main() is implementation-specific. The generic ARM C library supports the following:

- main()
- *Interactive device* on page B-4
- Redirecting standard input, output, and error streams on page B-4.

main()

The arguments given to main() are the words of the command line not including input/output redirections, delimited by whitespace, except where the whitespace is contained in double quotes.

____ Note _____

- A whitespace character is any character where the result of isspace() is true.
- A double quote or backslash character \ inside double quotes must be preceded by a backslash character.
- An input/output redirection is not recognized inside double quotes.

Interactive device

In a non hosted implementation of the ARM C library, the term *interactive device* might be meaningless. The generic ARM C library supports a pair of devices, both called :tt, intended to handle keyboard input and VDU screen output. In the generic implementation:

- no buffering is done on any stream connected to :tt unless input/output redirection has occurred
- if input/output redirection other than to:tt has occurred, full file buffering is used
 except that line buffering is used if both stdout and stderr were redirected to the
 same file.

Redirecting standard input, output, and error streams

Using the generic ARM C library, the standard input, output and error streams can be redirected at runtime. For example, if mycopy is a program running on a host debugger that copies the standard input to the standard output, the following line runs the program:

```
mycopy < infile > outfile 2> errfile
```

and redirects the files as follows:

stdin The standard input stream is redirected to infile.

stdout The standard output stream is redirected to outfile.

stderr The standard error stream is redirected to errfile.

The permitted redirections are:

0< filename Reads stdin from filename.

< filename Reads stdin from filename.

1> filename Writes stdout to filename.

> filename Writes stdout to filename.

2> filename Writes stderr to filename.

2>&1 Writes stderr to the same place as stdout.

>& file Writes both stdout and stderr to filename.

>> filename Appends stdout to filename.

>>& filename Appends both stdout and stderr to filename.

To redirect stdin, stdout, and stderr on the target, you must define:

#pragma import(_main_redirection)

File redirection is done only if either:

- the invoking operating system supports it
- the program reads and writes characters and has not replaced the C library functions fputc() and fgetc().

B.1.3 Identifiers

See Character sets and identifiers on page 5-2 for more information.

B.1.4 Characters

See *Character sets and identifiers* on page 5-2 for more information.

B.1.5 Integers

See *Integer* on page 5-5 for more information.

B.1.6 Floating-point

See *Float* on page 5-5 for more information.

B.1.7 Arrays and pointers

See *Arrays and pointers* on page 5-5 for more information.

B.1.8 Registers

Using the ARM compiler, you can declare any number of local objects to have the storage class **register**.

B.1.9 Structures, unions, enumerations, and bitfields

The ISO/IEC C standard requires the following implementation details to be documented for structured data types:

- the outcome when a member of a union is accessed using a member of different type
- the padding and alignment of members of structures
- whether a plain int bitfield is treated as a signed int bitfield or as an unsigned int bitfield
- the order of allocation of bitfields within a unit
- whether a bitfield can straddle a storage-unit boundary
- the integer type chosen to represent the values of an enumeration type.

See Chapter 5 *C* and *C*++ *Implementation Details* for more information.

Unions

See *Unions* on page 5-7 for information.

Enumerations

See *Enumerations* on page 5-7 for information.

Padding and alignment of structures

See *Structures* on page 5-8 for information.

Bitfields

See *Bitfields* on page 5-10 for information.

B.1.10 Qualifiers

An object that has a volatile-qualified type is accessed as a word, halfword, or byte as determined by its size and alignment. For volatile objects larger than a word, the order of accesses to the parts of the object is undefined. Updates to volatile bitfields generally require a read-modify-write. Accesses to aligned word, halfword and byte types are atomic. Other volatile accesses are not necessarily atomic.

Otherwise, reads and writes to volatile qualified objects occur as directly implied by the source code, in the order implied by the source code.

B.1.11 Expression evaluation

The compiler can re-order expressions involving only associative and commutative operators of equal precedence, even in the presence of parentheses. For example, a + (b + c) might be evaluated as (a + b) + c if a, b, and c are integer expressions.

Between sequence points, t

he compiler can evaluate expressions in any order, regardless of parentheses. Therefore, side effects of expressions between sequence points can occur in any order.

The compiler can evaluate function arguments in any order.

Any aspect of evaluation order not prescribed by the relevant standard can be varied by:

- the optimization level you are compiling at
- the release of the compiler you are using.

B.1.12 Preprocessing directives

The ISO standard C header files can be referred to as described in the standard, for example, #include <stdio.h>.

Quoted names for includable source files are supported. The compiler accepts host filenames or UNIX filenames. For UNIX filenames on non-UNIX hosts, the compiler tries to translate the filename to a local equivalent.

The recognized #pragma directives are shown in *Pragmas* on page 4-58.

B.1.13 Library functions

The ISO C library variants are listed in *About the runtime libraries* on page 1-2 in the *Libraries and Floating Point Support Guide*.

The precise nature of each C library is unique to the particular implementation. The generic ARM C library has, or supports, the following features:

- The macro NULL expands to the integer constant 0.
- If a program redefines a reserved external identifier such as printf, an error might occur when the program is linked with the standard libraries. If it is not linked with standard libraries, no error is detected.
- The __aeabi_assert() function prints details of the failing diagnostic on stderr and then calls the abort() function:

*** assertion failed: expression, file name, line number
Note
The behavior of the assert macro depends on the conditions in operation at the
most recent occurrence of #include <assert.h>. See Exiting from the program on</assert.h>
page 2-38 in the Libraries and Floating Point Support Guide for more
information.

For implementation details of mathematical functions, macros, locale, signals, and input/output see Chapter 2 *The C and C++ Libraries* in the *Libraries and Floating Point Support Guide*.

B.2 Behaviors considered undefined by the ISO C Standard

The following are considered undefined behavior by the ISO C Standard:

- In character and string escapes, if the character following the \ has no special meaning, the value of the escape is the character itself. For example, a warning is generated if you use \s because it is the same as s.
- A **struct** that has no named fields but at least one unnamed field is accepted by default, but generates an error in strict 1990 ISO Standard C.

Standard C Implementation Definition

Appendix C Standard C++ Implementation Definition

The ARM compiler supports the majority of the language features described in the ISO/IEC standard for C++ when compiling C++. This appendix lists the C++ language features defined in the standard, and states whether or not that language feature is supported by ARM C++. It contains the following sections:

- Integral conversion on page C-2
- Calling a pure virtual function on page C-3
- *Major features of language support* on page C-4
- *Standard C++ library implementation definition* on page C-5.

Note	
This appendix does not duplicate information that is part of the stand	dard C
implementation. See Appendix B Standard C Implementation Defini	ition.

When compiling C++ in ISO C mode, the ARM compiler is identical to the ARM C compiler. Where there is an implementation feature specific to either C or C++, this is noted in the text. For extensions to standard C++, see:

- Standard C++ language extensions on page 3-15
- C99 language features available in C++ and C90 on page 3-7
- *Standard C and standard C++ language extensions* on page 3-19.

C.1 Integral conversion

During integral conversion, if the destination type is signed, the value is unchanged if
can be represented in the destination type and bitfield width. Otherwise, the value is
truncated to fit the size of the destination type.
——Note ———
This section is related to Section 4.7 Integral conversions, in the ISO/IEC standard.

C.2 Calling a pure virtual function

Calling a pure virtual function is illegal. If your code calls a pure virtual function, then the compiler includes a call to the library function __cxa_pure_virtual.

__cxa_pure_virtual raises the signal **SIGPVFN**. The default signal handler prints an error message and exits. See __default_signal_handler() on page 2-62 in the Libraries and Floating Point Support Guide for more information.

C.3 Major features of language support

Table C-1 shows the major features of the language supported by this release of ARM C++.

Table C-1 Major feature support for language

Major feature	ISO/IEC standard section	Support
Core language	1 to 13	Yes.
Templates	14	Yes, with the exception of export templates.
Exceptions	15	Yes.
Libraries	17 to 27	See the Standard C++ library implementation definition on page C-5 and the Libraries and Floating Point Support Guide.

C.4 Standard C++ library implementation definition

Version 2.02.03 of the Rogue Wave library provides a subset of the library defined in the standard. There are small differences from the 1999 ISO C standard. For information on the implementation definition, see *Standard C++ library implementation definition* on page 2-105 in the *Libraries and Floating Point Support Guide*.

The library can be used with user-defined functions to produce target-dependent applications. See *About the runtime libraries* on page 1-2 in the *Libraries and Floating Point Support Guide*.

Standard C++ Implementation Definition

Appendix D

C and C++ Compiler Implementation Limits

This appendix lists the implementation limits when using the ARM compiler to compile C and C++. It contains the following sections:

- *C++ ISO/IEC standard limits* on page D-2
- Limits for integral numbers on page D-4
- *Limits for floating-point numbers* on page D-5.

D.1 C++ ISO/IEC standard limits

The ISO/IEC C++ standard recommends minimum limits that a conforming compiler must accept. You must be aware of these when porting applications between compilers. Table D-1 gives a summary of these limits.

In this table, a limit of memory indicates that the ARM compiler imposes no limit, other than that imposed by the available memory.

Table D-1 Implementation limits

Description	Recommended	ARM
Nesting levels of compound statements, iteration control structures, and selection control structures.	256	memory
Nesting levels of conditional inclusion.	256	memory
Pointer, array, and function declarators (in any combination) modifying an arithmetic, structure, union, or incomplete type in a declaration.	256	memory
Nesting levels of parenthesized expressions within a full expression.	256	memory
Number of initial characters in an internal identifier or macro name.	1024	memory
Number of initial characters in an external identifier.	1024	memory
External identifiers in one translation unit.	65536	memory
Identifiers with block scope declared in one block.	1024	memory
Macro identifiers simultaneously defined in one translation unit.	65536	memory
Parameters in one function declaration.	256	memory
Arguments in one function call.	256	memory
Parameters in one macro definition.	256	memory
Arguments in one macro invocation.	256	memory
Characters in one logical source line.	65536	memory
Characters in a character string literal or wide string literal after concatenation.	65 536	memory
Size of a C or C++ object (including arrays).	262144	4294967296
Nesting levels of #include file.	256	memory

Table D-1 Implementation limits (continued)

Description	Recommended	ARM
Case labels for a switch statement, excluding those for any nested switch statements.	16384	memory
Data members in a single class, structure, or union.	16384	memory
Enumeration constants in a single enumeration.	4096	memory
Levels of nested class, structure, or union definitions in a single struct declaration-list.	256	memory
Functions registered by atexit().	32	33
Direct and indirect base classes.	16384	memory
Direct base classes for a single class.	1024	memory
Members declared in a single class.	4096	memory
Final overriding virtual functions in a class, accessible or not.	16384	memory
Direct and indirect virtual bases of a class.	1024	memory
Static members of a class.	1024	memory
Friend declarations in a class.	4096	memory
Access control declarations in a class.	4096	memory
Member initializers in a constructor definition.	6144	memory
Scope qualifications of one identifier.	256	memory
Nested external specifications.	1024	memory
Template arguments in a template declaration.	1024	memory
Recursively nested template instantiations.	17	memory
Handlers per try block.	256	memory
Throw specifications on a single function declaration.	256	memory

D.2 Limits for integral numbers

Table D-2 gives the ranges for integral numbers in ARM C and C++. The Endpoint column of the table gives the numerical value of the range endpoint. The Hex value column gives the bit pattern (in hexadecimal) that is interpreted as this value by the ARM compiler. These constants are defined in the limits.h include file.

When entering a constant, choose the size and sign with care. Constants are interpreted differently in decimal and hexadecimal/octal. See the appropriate C or C++ standard, or any of the recommended C and C++ textbooks for more information, as described in *Further reading* on page x.

Table D-2 Integer ranges

Constant	Meaning	Value	Hex value
CHAR_MAX	Maximum value of char	255	0xFF
CHAR_MIN	Minimum value of char	0	0x00
SCHAR_MAX	Maximum value of signed char	127	0x7F
SCHAR_MIN	Minimum value of signed char	-128	0x80
UCHAR_MAX	Maximum value of unsigned char	255	0xFF
SHRT_MAX	Maximum value of short	32767	0x7FFF
SHRT_MIN	Minimum value of short	-32768	0x8000
USHRT_MAX	Maximum value of unsigned short	65535	0xFFFF
INT_MAX	Maximum value of int	2147483647	0x7FFFFFF
INT_MIN	Minimum value of int	-2147483648	0x80000000
LONG_MAX	Maximum value of long	2147483647	0x7FFFFFF
LONG_MIN	Minimum value of long	-2147483648	0x80000000
ULONG_MAX	Maximum value of unsigned long	4294967295	0xFFFFFFF
LLONG_MAX	Maximum value of long long	9.2E+18	0x7FFFFFFF FFFFFFFF
LLONG_MIN	Minimum value of long long	-9.2E+18	0x80000000 00000000
ULLONG_MAX	Maximum value of unsigned long long	1.8E+19	0xFFFFFFF FFFFFFFF

D.3 Limits for floating-point numbers

This section describes the characteristics of floating-point numbers.

Table D-3 gives the characteristics, ranges, and limits for floating-point numbers. These constants are defined in the float.h include file.

Table D-3 Floating-point limits

Constant	Meaning	Value
FLT_MAX	Maximum value of float	3.40282347e+38F
FLT_MIN	Minimum normalized positive floating-point number value of float	1.175494351e–38F
DBL_MAX	Maximum value of double	1.79769313486231571e+308
DBL_MIN	Minimum normalized positive floating-point number value of double	2.22507385850720138e-308
LDBL_MAX	Maximum value of long double	1.79769313486231571e+308
LDBL_MIN	Minimum normalized positive floating-point number value of long double	2.22507385850720138e-308
FLT_MAX_EXP	Maximum value of base 2 exponent for type float	128
FLT_MIN_EXP	Minimum value of base 2 exponent for type float	-125
DBL_MAX_EXP	Maximum value of base 2 exponent for type double	1024
DBL_MIN_EXP	Minimum value of base 2 exponent for type double	-1021
LDBL_MAX_EXP	Maximum value of base 2 exponent for type long double	1024
LDBL_MIN_EXP	Minimum value of base 2 exponent for type long double	-1021
FLT_MAX_10_EXP	Maximum value of base 10 exponent for type float	38
FLT_MIN_10_EXP	Minimum value of base 10 exponent for type float	-37
DBL_MAX_10_EXP	Maximum value of base 10 exponent for type double	308
DBL_MIN_10_EXP	Minimum value of base 10 exponent for type double	-307
LDBL_MAX_10_EXP	Maximum value of base 10 exponent for type long double	308
LDBL_MIN_10_EXP	Minimum value of base 10 exponent for type long double	-307

Table D-4 describes other characteristics of floating-point numbers. These constants are also defined in the float.h include file.

Table D-4 Other floating-point characteristics

Constant	Meaning	Value
FLT_RADIX	Base (radix) of the ARM floating-point number representation	2
FLT_ROUNDS	Rounding mode for floating-point numbers	(nearest) 1
FLT_DIG	Decimal digits of precision for float	6
DBL_DIG	Decimal digits of precision for double	15
LDBL_DIG	Decimal digits of precision for long double	15
FLT_MANT_DIG	Binary digits of precision for type float	24
DBL_MANT_DIG	Binary digits of precision for type double	53
LDBL_MANT_DIG	Binary digits of precision for type long double	53
FLT_EPSILON	Smallest positive value of x that $1.0 + x = 1.0$ for type float	1.19209290e-7F
DBL_EPSILON	Smallest positive value of x that $1.0 + x = 1.0$ for type double	2.2204460492503131e-16
LDBL_EPSILON	Smallest positive value of x that $1.0 + x = 1.0$ for type long double	2.2204460492503131e-16L

— Note ———

- When a floating-point number is converted to a shorter floating-point number, it is rounded to the nearest representable number.
- Floating-point arithmetic conforms to IEEE 754.

Appendix E **Using NEON Support**

This appendix describes NEON intrinsics support in this release of the *RealView Compilation Tools* (RVCT).

This appendix contains the following sections:

- *Introduction* on page E-2
- *Vector data types* on page E-3
- *Intrinsics* on page E-4.

E.1 Introduction

RVCT provides intrinsics to generate NEON code for the Cortex-A8 processor in both ARM and Thumb state. The NEON intrinsics are defined in the header file arm_neon.h. The header file defines both the intrinsics and a set of vector types.

There is no support for NEON intrinsics for architectures before ARMv7. When building for earlier architectures, or for ARMv7 architecture profiles that do not include NEON, the compiler treats NEON intrinsics as ordinary function calls. This results in an error at link time.

E.2 Vector data types

The following types are defined to represent vectors. NEON vector data types are named according to the following pattern:

```
<type><size>x<number of lanes>_t
```

For example, int16x4_t is a vector containing four lanes each containing a signed 16-bit integer. Table E-1 lists the vector data types.

Table E-1 Vector data types

int8x8_t	int8x16_t
int16x4_t	int16x8_t
int32x2_t	int32x4_t
int64x1_t	int64x2_t
uint8x8_t	uint8x16_t
uint16x4_t	uint16x8_t
uint32x2_t	uint32x4_t
uint64x1_t	uint64x2_t
float16x4_t	float16x8_t
float32x2_t	float32x4_t
poly8x8_t	poly8x16_t
poly16x4_t	poly16x8_t
	·

Some intrinsics use an array of vector types of the form:

<type><size>x<number of lanes>x<length of array>_t

These types are treated as ordinary C structures containing a single element named val.

An example structure definition is:

```
struct int16x4x2_t
{
    int16x4_t val[2];
};
```

There are array types defined for array lengths between 2 and 4, with any of the vector types listed in Table E-1.

E.3 Intrinsics

The intrinsics described in this section map closely to NEON instructions. Each section begins with a list of function prototypes, with a comment specifying an equivalent assembler instruction. The compiler selects an instruction that has the required semantics, but there is no guarantee that the compiler produces the listed instruction.

The intrinsics use a naming scheme that is similar to the NEON unified assembler syntax. That is, each intrinsic has the form:

```
<opname><flags>_<type>
```

An additional q flag is provided to specify that the intrinsic operates on 128-bit vectors.

For example:

- vmul_s16, multiplies two vectors of signed 16-bit values.
 This compiles to VMUL.I16 d2, d0, d1.
- vaddl_u8, is a long add of two 64-bit vectors containing unsigned 8-bit values, resulting in a 128-bit vector of unsigned 16-bit values.

This compiles to VADDL.U8 q1, d0, d1.

——Note	· ————
The intrinsic	function prototypes in this section use the following type annotations:
const(<i>n</i>)	the argument n must be a compile-time constant
constrange	e(min, max)
	the argument must be a compile-time constant in the range min to max
transfers	ize(n)
	the intrinsic loads <i>n</i> bytes from this pointer.
-	
Note	·
The NEON	intrinsic function prototypes that usefp16 are only available for targets
that have the	NEON half-precision VFP extension. To enable use offp16, use the

E.3.1 Addition

These intrinsics add vectors. Each lane in the result is the consequence of performing the addition on the corresponding lanes in each operand vector. The operations performed are as follows:

--fp16_format command-line option. See --fp16_format=format on page 2-59.

• *Vector add: vadd -> Vr[i]:=Va[i]+Vb[i]* on page E-5

- Vector long add: $vadd \rightarrow Vr[i] = Va[i] + Vb[i]$
- *Vector wide add: vadd -> Vr[i]:=Va[i]+Vb[i]* on page E-6
- Vector halving add: vhadd -> Vr[i]:=(Va[i]+Vb[i])>>1 on page E-6
- *Vector rounding halving add: vrhadd -> Vr[i]:=(Va[i]+Vb[i]+1)>>1* on page E-6
- Vector saturating add: vqadd -> Vr[i]:=sat<size>(Va[i]+Vb[i]) on page E-6
- Vector add high half -> Vr[i]:=Va[i]+Vb[i] on page E-7
- *Vector rounding add high half* on page E-7.

Vector add: vadd -> Vr[i]:=Va[i]+Vb[i]

Vr, Va, Vb have equal lane sizes.

```
int8x8_t
            vadd_s8(int8x8_t a, int8x8_t b);
                                                    // VADD.I8 d0,d0,d0
int16x4_t
           vadd_s16(int16x4_t a, int16x4_t b);
                                                    // VADD.I16 d0,d0,d0
int32x2_t
           vadd_s32(int32x2_t a, int32x2_t b);
                                                    // VADD.I32 d0,d0,d0
           vadd_s64(int64x1_t a, int64x1_t b);
int64x1_t
                                                    // VADD.I64 d0,d0,d0
float32x2_t vadd_f32(float32x2_t a, float32x2_t b); // VADD.F32 d0,d0,d0
           vadd_u8(uint8x8_t a, uint8x8_t b);
                                                    // VADD.I8 d0,d0,d0
uint8x8_t
uint16x4_t vadd_u16(uint16x4_t a, uint16x4_t b);
                                                    // VADD.I16 d0,d0,d0
uint32x2_t vadd_u32(uint32x2_t a, uint32x2_t b);
                                                    // VADD.I32 d0,d0,d0
uint64x1_t vadd_u64(uint64x1_t a, uint64x1_t b);
                                                    // VADD.I64 d0,d0,d0
           vaddq_s8(int8x16_t a, int8x16_t b);
                                                    // VADD.I8 q0,q0,q0
int8x16_t
int16x8_t
           vaddq_s16(int16x8_t a, int16x8_t b);
                                                    // VADD.I16 q0,q0,q0
           vaddq_s32(int32x4_t a, int32x4_t b);
int32x4_t
                                                    // VADD.I32 q0,q0,q0
int64x2_t
            vaddq_s64(int64x2_t a, int64x2_t b);
                                                    // VADD.I64 q0,q0,q0
float32x4_t vaddq_f32(float32x4_t a, float32x4_t b); // VADD.F32 q0,q0,q0
uint8x16_t vaddq_u8(uint8x16_t a, uint8x16_t b);
                                                    // VADD.I8 q0,q0,q0
uint16x8_t vaddq_u16(uint16x8_t a, uint16x8_t b);
                                                    // VADD.I16 q0,q0,q0
uint32x4_t vaddq_u32(uint32x4_t a, uint32x4_t b);
                                                    // VADD.I32 q0,q0,q0
uint64x2_t vaddg_u64(uint64x2_t a, uint64x2_t b);
                                                    // VADD.I64 q0,q0,q0
```

Vector long add: vadd -> Vr[i]:=Va[i]+Vb[i]

Va, Vb have equal lane sizes, result is a 128 bit vector of lanes that are twice the width.

Vector wide add: vadd -> Vr[i]:=Va[i]+Vb[i]

Vector halving add: vhadd -> Vr[i]:=(Va[i]+Vb[i])>>1

```
int8x8_t
          vhadd_s8(int8x8_t a, int8x8_t b);
                                                  // VHADD.S8 d0,d0,d0
int16x4_t vhadd_s16(int16x4_t a, int16x4_t b);
                                                  // VHADD.S16 d0,d0,d0
int32x2_t vhadd_s32(int32x2_t a, int32x2_t b);
                                                  // VHADD.S32 d0,d0,d0
uint8x8_t vhadd_u8(uint8x8_t a, uint8x8_t b);
                                                  // VHADD.U8 d0,d0,d0
uint16x4_t vhadd_u16(uint16x4_t a, uint16x4_t b); // VHADD.U16 d0,d0,d0
uint32x2_t vhadd_u32(uint32x2_t a, uint32x2_t b); // VHADD.U32 d0,d0,d0
int8x16_t vhaddq_s8(int8x16_t a, int8x16_t b);
                                                  // VHADD.S8 q0,q0,q0
int16x8_t vhaddq_s16(int16x8_t a, int16x8_t b);
                                                 // VHADD.S16 q0,q0,q0
int32x4_t vhaddq_s32(int32x4_t a, int32x4_t b);
                                                 // VHADD.S32 q0,q0,q0
uint8x16_t vhaddq_u8(uint8x16_t a, uint8x16_t b); // VHADD.U8 q0,q0,q0
uint16x8_t vhaddg_u16(uint16x8_t a, uint16x8_t b); // VHADD.U16 q0,q0,q0
uint32x4_t vhaddg_u32(uint32x4_t a, uint32x4_t b); // VHADD.U32 q0,q0,q0
```

Vector rounding halving add: vrhadd -> Vr[i]:=(Va[i]+Vb[i]+1)>>1

```
int8x8_t
         vrhadd_s8(int8x8_t a, int8x8_t b);
                                                   // VRHADD.S8 d0,d0,d0
int16x4_t vrhadd_s16(int16x4_t a, int16x4_t b);
                                                   // VRHADD.S16 d0,d0,d0
int32x2_t vrhadd_s32(int32x2_t a, int32x2_t b);
                                                   // VRHADD.S32 d0,d0,d0
uint8x8_t vrhadd_u8(uint8x8_t a, uint8x8_t b);
                                                   // VRHADD.U8 d0,d0,d0
uint16x4_t vrhadd_u16(uint16x4_t a, uint16x4_t b); // VRHADD.U16 d0,d0,d0
uint32x2_t vrhadd_u32(uint32x2_t a, uint32x2_t b); // VRHADD.U32 d0,d0,d0
int8x16_t vrhaddq_s8(int8x16_t a, int8x16_t b);
                                                   // VRHADD.S8 q0,q0,q0
int16x8_t vrhaddq_s16(int16x8_t a, int16x8_t b);
                                                   // VRHADD.S16 q0,q0,q0
int32x4_t vrhaddq_s32(int32x4_t a, int32x4_t b);
                                                  // VRHADD.S32 q0,q0,q0
uint8x16_t vrhaddq_u8(uint8x16_t a, uint8x16_t b); // VRHADD.U8 q0,q0,q0
uint16x8_t vrhaddg_u16(uint16x8_t a, uint16x8_t b); // VRHADD.U16 q0,q0,q0
uint32x4_t vrhaddg_u32(uint32x4_t a, uint32x4_t b); // VRHADD.U32 q0,q0,q0
```

Vector saturating add: vqadd -> Vr[i]:=sat<size>(Va[i]+Vb[i])

```
uint64x1_t vqadd_u64(uint64x1_t a, uint64x1_t b);  // VQADD.U64 d0,d0,d0
int8x16_t vqaddq_s8(int8x16_t a, int8x16_t b);  // VQADD.S8 q0,q0,q0
int16x8_t vqaddq_s16(int16x8_t a, int16x8_t b);  // VQADD.S16 q0,q0,q0
int32x4_t vqaddq_s32(int32x4_t a, int32x4_t b);  // VQADD.S32 q0,q0,q0
int64x2_t vqaddq_s64(int64x2_t a, int64x2_t b);  // VQADD.S64 q0,q0,q0
uint8x16_t vqaddq_u8(uint8x16_t a, uint8x16_t b);  // VQADD.U8 q0,q0,q0
uint16x8_t vqaddq_u16(uint16x8_t a, uint16x8_t b);  // VQADD.U16 q0,q0,q0
uint32x4_t vqaddq_u32(uint32x4_t a, uint32x4_t b);  // VQADD.U32 q0,q0,q0
uint64x2_t vqaddq_u64(uint64x2_t a, uint64x2_t b);  // VQADD.U64 q0,q0,q0
```

Vector add high half -> Vr[i]:=Va[i]+Vb[i]

Vector rounding add high half

E.3.2 Multiplication

These intrinsics provide operations including multiplication.

Vector multiply: vmul -> Vr[i] := Va[i] * Vb[i]

```
int8x8_t
            vmul_s8(int8x8_t a, int8x8_t b);
                                                     // VMUL.I8 d0,d0,d0
           vmul_s16(int16x4_t a, int16x4_t b);
int16x4_t
                                                     // VMUL.I16 d0,d0,d0
int32x2_t
           vmul_s32(int32x2_t a, int32x2_t b);
                                                     // VMUL.I32 d0,d0,d0
float32x2_t vmul_f32(float32x2_t a, float32x2_t b); // VMUL.F32 d0,d0,d0
uint8x8_t
           vmul_u8(uint8x8_t a, uint8x8_t b);
                                                     // VMUL.I8 d0,d0,d0
uint16x4_t vmul_u16(uint16x4_t a, uint16x4_t b);
                                                     // VMUL.I16 d0,d0,d0
uint32x2_t vmul_u32(uint32x2_t a, uint32x2_t b);
                                                     // VMUL.I32 d0,d0,d0
           vmul_p8(poly8x8_t a, poly8x8_t b);
                                                     // VMUL.P8 d0,d0,d0
poly8x8_t
           vmulq_s8(int8x16_t a, int8x16_t b);
int8x16_t
                                                     // VMUL.I8 q0,q0,q0
int16x8_t
            vmulq_s16(int16x8_t a, int16x8_t b);
                                                     // VMUL.I16 q0,q0,q0
int32x4 t
            vmulg_s32(int32x4_t a, int32x4_t b);
                                                     // VMUL.I32 q0,q0,q0
float32x4_t vmulq_f32(float32x4_t a, float32x4_t b); // VMUL.F32 q0,q0,q0
uint8x16_t vmulg_u8(uint8x16_t a, uint8x16_t b);
                                                    // VMUL.I8 q0,q0,q0
```

```
uint16x8_t vmulq_u16(uint16x8_t a, uint16x8_t b);  // VMUL.I16 q0,q0,q0
uint32x4_t vmulq_u32(uint32x4_t a, uint32x4_t b);  // VMUL.I32 q0,q0,q0
poly8x16_t vmulq_p8(poly8x16_t a, poly8x16_t b);  // VMUL.P8 q0,q0,q0
```

Vector multiply accumulate: vmla -> Vr[i] := Va[i] + Vb[i] * Vc[i]

```
int8x8_t
           vmla_s8(int8x8_t a, int8x8_t b, int8x8_t c);
                                                                   // VMLA.I8 d0,d0,d0
int16x4_t
           vmla_s16(int16x4_t a, int16x4_t b, int16x4_t c);
                                                                   // VMLA.I16 d0,d0,d0
int32x2_t
           vmla_s32(int32x2_t a, int32x2_t b, int32x2_t c);
                                                                   // VMLA.I32 d0,d0,d0
float32x2_t vmla_f32(float32x2_t a, float32x2_t b, float32x2_t c); // VMLA.F32 d0,d0,d0
           vmla_u8(uint8x8_t a, uint8x8_t b, uint8x8_t c);
                                                                   // VMLA.I8 d0,d0,d0
uint8x8 t
uint16x4_t vmla_u16(uint16x4_t a, uint16x4_t b, uint16x4_t c);
                                                                   // VMLA.I16 d0,d0,d0
uint32x2_t vmla_u32(uint32x2_t a, uint32x2_t b, uint32x2_t c);
                                                                   // VMLA.I32 d0,d0,d0
int8x16_t
           vmlaq_s8(int8x16_t a, int8x16_t b, int8x16_t c);
                                                                   // VMLA.I8 q0,q0,q0
int16x8_t
           vmlaq_s16(int16x8_t a, int16x8_t b, int16x8_t c);
                                                                   // VMLA.I16 q0,q0,q0
int32x4_t
           vmlaq_s32(int32x4_t a, int32x4_t b, int32x4_t c);
                                                                   // VMLA.I32 q0,q0,q0
float32x4_t vmlaq_f32(float32x4_t a, float32x4_t b, float32x4_t c); // VMLA.F32 q0,q0,q0
uint8x16_t vmlag_u8(uint8x16_t a, uint8x16_t b, uint8x16_t c);
                                                                   // VMLA.I8 q0,q0,q0
uint16x8_t vmlag_u16(uint16x8_t a, uint16x8_t b, uint16x8_t c);
                                                                   // VMLA.I16 q0,q0,q0
uint32x4_t vmlaq_u32(uint32x4_t a, uint32x4_t b, uint32x4_t c);
                                                                   // VMLA.I32 q0,q0,q0
```

Vector multiply accumulate long: vmla -> Vr[i] := Va[i] + Vb[i] * Vc[i]

Vector multiply subtract: vmls -> Vr[i] := Va[i] - Vb[i] * Vc[i]

```
int8x8_t
           vmls_s8(int8x8_t a, int8x8_t b, int8x8_t c);
                                                                   // VMLS.I8 d0,d0,d0
           vmls_s16(int16x4_t a, int16x4_t b, int16x4_t c);
int16x4_t
                                                                   // VMLS.I16 d0,d0,d0
           vmls_s32(int32x2_t a, int32x2_t b, int32x2_t c);
int32x2_t
                                                                   // VMLS.I32 d0,d0,d0
float32x2_t vmls_f32(float32x2_t a, float32x2_t b, float32x2_t c); // VMLS.F32 d0,d0,d0
uint8x8_t vmls_u8(uint8x8_t a, uint8x8_t b, uint8x8_t c);
                                                                   // VMLS.I8 d0,d0,d0
uint16x4_t vmls_u16(uint16x4_t a, uint16x4_t b, uint16x4_t c);
                                                                   // VMLS.I16 d0,d0,d0
uint32x2_t vmls_u32(uint32x2_t a, uint32x2_t b, uint32x2_t c);
                                                                   // VMLS.I32 d0,d0,d0
           vmlsq_s8(int8x16_t a, int8x16_t b, int8x16_t c);
                                                                   // VMLS.I8 q0,q0,q0
int8x16_t
int16x8_t
           vmlsq_s16(int16x8_t a, int16x8_t b, int16x8_t c);
                                                                   // VMLS.I16 q0,q0,q0
int32x4_t
           vmlsq_s32(int32x4_t a, int32x4_t b, int32x4_t c);
                                                                   // VMLS.I32 q0,q0,q0
float32x4_t vmlsq_f32(float32x4_t a, float32x4_t b, float32x4_t c); // VMLS.F32 q0,q0,q0
uint8x16_t vmlsq_u8(uint8x16_t a, uint8x16_t b, uint8x16_t c);
                                                                   // VMLS.I8 q0,q0,q0
uint16x8_t vmlsq_u16(uint16x8_t a, uint16x8_t b, uint16x8_t c);
                                                                   // VMLS.I16 q0,q0,q0
uint32x4_t vmlsq_u32(uint32x4_t a, uint32x4_t b, uint32x4_t c);
                                                                   // VMLS.I32 q0,q0,q0
```

Vector multiply subtract long

Vector saturating doubling multiply high

```
int16x4_t vqdmulh_s16(int16x4_t a, int16x4_t b);  // VQDMULH.S16 d0,d0,d0
int32x2_t vqdmulh_s32(int32x2_t a, int32x2_t b);  // VQDMULH.S32 d0,d0,d0
int16x8_t vqdmulhq_s16(int16x8_t a, int16x8_t b);  // VQDMULH.S16 q0,q0,q0
int32x4_t vqdmulhq_s32(int32x4_t a, int32x4_t b);  // VQDMULH.S32 q0,q0,q0
```

Vector saturating rounding doubling multiply high

```
int16x4_t vqrdmulh_s16(int16x4_t a, int16x4_t b);  // VQRDMULH.S16 d0,d0,d0
int32x2_t vqrdmulh_s32(int32x2_t a, int32x2_t b);  // VQRDMULH.S32 d0,d0,d0
int16x8_t vqrdmulhq_s16(int16x8_t a, int16x8_t b);  // VQRDMULH.S16 q0,q0,q0
int32x4_t vqrdmulhq_s32(int32x4_t a, int32x4_t b);  // VQRDMULH.S32 q0,q0,q0
```

Vector saturating doubling multiply accumulate long

```
int32x4_t vqdmlal_s16(int32x4_t a, int16x4_t b, int16x4_t c); // VQDMLAL.S16 q0,d0,d0
int64x2_t vqdmlal_s32(int64x2_t a, int32x2_t b, int32x2_t c); // VQDMLAL.S32 q0,d0,d0
```

Vector saturating doubling multiply subtract long

```
int32x4_t vqdmlsl_s16(int32x4_t a, int16x4_t b, int16x4_t c); // VQDMLSL.S16 q0,d0,d0 int64x2_t vqdmlsl_s32(int64x2_t a, int32x2_t b, int32x2_t c); // VQDMLSL.S32 q0,d0,d0
```

Vector long multiply

Vector saturating doubling long multiply

```
int32x4_t vqdmull_s16(int16x4_t a, int16x4_t b); // VQDMULL.S16 q0,d0,d0 int64x2_t vqdmull_s32(int32x2_t a, int32x2_t b); // VQDMULL.S32 q0,d0,d0
```

E.3.3 Subtraction

These intrinsics provide operations including subtraction.

Vector subtract

```
int8x8_t
           vsub_s8(int8x8_t a, int8x8_t b);
                                                    // VSUB.I8 d0,d0,d0
int16x4_t vsub_s16(int16x4_t a, int16x4_t b);
                                                    // VSUB.I16 d0,d0,d0
int32x2_t vsub_s32(int32x2_t a, int32x2_t b);
                                                    // VSUB.I32 d0,d0,d0
int64x1_t vsub_s64(int64x1_t a, int64x1_t b);
                                                    // VSUB.I64 d0,d0,d0
float32x2_t vsub_f32(float32x2_t a, float32x2_t b); // VSUB.F32 d0,d0,d0
uint8x8_t vsub_u8(uint8x8_t a, uint8x8_t b);
                                                    // VSUB.I8 d0,d0,d0
uint16x4_t vsub_u16(uint16x4_t a, uint16x4_t b);
                                                    // VSUB.I16 d0,d0,d0
uint32x2_t vsub_u32(uint32x2_t a, uint32x2_t b);
                                                    // VSUB.I32 d0,d0,d0
uint64x1_t vsub_u64(uint64x1_t a, uint64x1_t b);
                                                    // VSUB.I64 d0,d0,d0
int8x16_t vsubq_s8(int8x16_t a, int8x16_t b);
                                                    // VSUB.I8 q0,q0,q0
int16x8_t vsubq_s16(int16x8_t a, int16x8_t b);
                                                    // VSUB.I16 q0,q0,q0
int32x4_t vsubq_s32(int32x4_t a, int32x4_t b);
                                                    // VSUB.I32 q0,q0,q0
int64x2_t vsubq_s64(int64x2_t a, int64x2_t b);
                                                    // VSUB.I64 q0,q0,q0
float32x4_t vsubq_f32(float32x4_t a, float32x4_t b); // VSUB.F32 q0,q0,q0
uint8x16_t vsubg_u8(uint8x16_t a, uint8x16_t b);
                                                    // VSUB.I8 q0,q0,q0
uint16x8_t vsubq_u16(uint16x8_t a, uint16x8_t b);
                                                    // VSUB.I16 q0,q0,q0
uint32x4_t vsubq_u32(uint32x4_t a, uint32x4_t b);
                                                    // VSUB.I32 q0,q0,q0
uint64x2_t vsubq_u64(uint64x2_t a, uint64x2_t b);
                                                    // VSUB.I64 q0,q0,q0
```

Vector long subtract: vsub -> Vr[i]:=Va[i]+Vb[i]

Vector wide subtract: vsub -> Vr[i]:=Va[i]+Vb[i]

Vector saturating subtract

```
int64x1_t vqsub_s64(int64x1_t a, int64x1_t b);
                                                  // VQSUB.S64 d0,d0,d0
uint8x8_t vgsub_u8(uint8x8_t a, uint8x8_t b);
                                                  // VQSUB.U8 d0,d0,d0
uint16x4_t vqsub_u16(uint16x4_t a, uint16x4_t b);
                                                  // VQSUB.U16 d0,d0,d0
uint32x2_t vqsub_u32(uint32x2_t a, uint32x2_t b); // VQSUB.U32 d0,d0,d0
uint64x1_t vqsub_u64(uint64x1_t a, uint64x1_t b); // VQSUB.U64 d0,d0,d0
int8x16_t vqsubq_s8(int8x16_t a, int8x16_t b);
                                                  // VQSUB.S8 q0,q0,q0
                                                  // VQSUB.S16 q0,q0,q0
int16x8_t vqsubq_s16(int16x8_t a, int16x8_t b);
int32x4_t vqsubq_s32(int32x4_t a, int32x4_t b);
                                                  // VQSUB.S32 q0,q0,q0
int64x2_t vgsubg_s64(int64x2_t a, int64x2_t b);
                                                  // VQSUB.S64 q0,q0,q0
uint8x16_t vqsubq_u8(uint8x16_t a, uint8x16_t b); // VQSUB.U8 q0,q0,q0
uint16x8_t vqsubq_u16(uint16x8_t a, uint16x8_t b); // VQSUB.U16 q0,q0,q0
uint32x4_t vqsubq_u32(uint32x4_t a, uint32x4_t b); // VQSUB.U32 q0,q0,q0
uint64x2_t vqsubq_u64(uint64x2_t a, uint64x2_t b); // VQSUB.U64 q0,q0,q0
```

Vector halving subtract

```
int8x8_t
          vhsub_s8(int8x8_t a, int8x8_t b);
                                                  // VHSUB.S8 d0,d0,d0
int16x4_t vhsub_s16(int16x4_t a, int16x4_t b);
                                                  // VHSUB.S16 d0,d0,d0
int32x2_t vhsub_s32(int32x2_t a, int32x2_t b);
                                                  // VHSUB.S32 d0,d0,d0
uint8x8_t vhsub_u8(uint8x8_t a, uint8x8_t b);
                                                  // VHSUB.U8 d0,d0,d0
uint16x4_t vhsub_u16(uint16x4_t a, uint16x4_t b); // VHSUB.U16 d0,d0,d0
uint32x2_t vhsub_u32(uint32x2_t a, uint32x2_t b); // VHSUB.U32 d0,d0,d0
int8x16_t vhsubq_s8(int8x16_t a, int8x16_t b);
                                                  // VHSUB.S8 q0,q0,q0
int16x8_t vhsubq_s16(int16x8_t a, int16x8_t b);
                                                  // VHSUB.S16 q0,q0,q0
int32x4_t vhsubq_s32(int32x4_t a, int32x4_t b);
                                                  // VHSUB.S32 q0,q0,q0
uint8x16_t vhsubg_u8(uint8x16_t a, uint8x16_t b); // VHSUB.U8 q0,q0,q0
uint16x8_t vhsubq_u16(uint16x8_t a, uint16x8_t b); // VHSUB.U16 q0,q0,q0
uint32x4_t vhsubg_u32(uint32x4_t a, uint32x4_t b); // VHSUB.U32 q0,q0,q0
```

Vector subtract high half

Vector rounding subtract high half

E.3.4 Comparison

A range of comparison intrinsics are provided. If the comparison is true for a lane, the result in that lane is all bits set to one. If the comparison is false for a lane, all bits are set to zero. The return type is an unsigned integer type. This means that you can use the result of a comparison as the first argument for the vbsl intrinsics.

Vector compare equal

```
uint8x8_t vceq_s8(int8x8_t a, int8x8_t b);
                                                    // VCEQ.I8 d0, d0, d0
uint16x4_t vceq_s16(int16x4_t a, int16x4_t b);
                                                    // VCEQ.I16 d0, d0, d0
uint32x2_t vceq_s32(int32x2_t a, int32x2_t b);
                                                    // VCEQ.I32 d0, d0, d0
uint32x2_t vceq_f32(float32x2_t a, float32x2_t b); // VCEQ.F32 d0, d0, d0
uint8x8_t vceq_u8(uint8x8_t a, uint8x8_t b);
                                                    // VCEQ.I8 d0, d0, d0
uint16x4_t vceq_u16(uint16x4_t a, uint16x4_t b);
                                                    // VCEQ.I16 d0, d0, d0
uint32x2_t vceq_u32(uint32x2_t a, uint32x2_t b);
                                                    // VCEQ.I32 d0, d0, d0
uint8x8_t vceq_p8(poly8x8_t a, poly8x8_t b);
                                                    // VCEQ.I8 d0, d0, d0
uint8x16_t vceqq_s8(int8x16_t a, int8x16_t b);
                                                    // VCEQ.I8 q0, q0, q0
uint16x8_t vceqq_s16(int16x8_t a, int16x8_t b);
                                                    // VCEQ.I16 q0, q0, q0
uint32x4_t vcegg_s32(int32x4_t a, int32x4_t b);
                                                    // VCEQ.I32 q0, q0, q0
uint32x4_t vceqq_f32(float32x4_t a, float32x4_t b); // VCEQ.F32 q0, q0, q0
uint8x16_t vcegg_u8(uint8x16_t a, uint8x16_t b);
                                                    // VCEQ.I8 q0, q0, q0
uint16x8_t vceqq_u16(uint16x8_t a, uint16x8_t b);
                                                    // VCEQ.I16 q0, q0, q0
uint32x4_t vcegg_u32(uint32x4_t a, uint32x4_t b);
                                                    // VCEQ.I32 q0, q0, q0
uint8x16_t vceqq_p8(poly8x16_t a, poly8x16_t b);
                                                    // VCEQ.I8 q0, q0, q0
```

Vector compare greater-than or equal

```
uint8x8_t vcqe_s8(int8x8_t a, int8x8_t b);
                                                    // VCGE.S8 d0, d0, d0
uint16x4_t vcge_s16(int16x4_t a, int16x4_t b);
                                                    // VCGE.S16 d0, d0, d0
                                                    // VCGE.S32 d0, d0, d0
uint32x2_t vcge_s32(int32x2_t a, int32x2_t b);
uint32x2_t vcge_f32(float32x2_t a, float32x2_t b); // VCGE.F32 d0, d0, d0
uint8x8_t vcge_u8(uint8x8_t a, uint8x8_t b);
                                                    // VCGE.U8 d0, d0, d0
uint16x4_t vcge_u16(uint16x4_t a, uint16x4_t b);
                                                    // VCGE.U16 d0, d0, d0
uint32x2_t vcge_u32(uint32x2_t a, uint32x2_t b);
                                                    // VCGE.U32 d0, d0, d0
uint8x16_t vcgeq_s8(int8x16_t a, int8x16_t b);
                                                    // VCGE.S8 q0, q0, q0
uint16x8_t vcgeq_s16(int16x8_t a, int16x8_t b);
                                                    // VCGE.S16 q0, q0, q0
uint32x4_t vcgeq_s32(int32x4_t a, int32x4_t b);
                                                    // VCGE.S32 q0, q0, q0
uint32x4_t vcgeg_f32(float32x4_t a, float32x4_t b); // VCGE.F32 q0, q0, q0
uint8x16_t vcgeq_u8(uint8x16_t a, uint8x16_t b);
                                                    // VCGE.U8 q0, q0, q0
uint16x8_t vcgeq_u16(uint16x8_t a, uint16x8_t b);
                                                    // VCGE.U16 q0, q0, q0
uint32x4_t vcgeq_u32(uint32x4_t a, uint32x4_t b);
                                                    // VCGE.U32 q0, q0, q0
```

Vector compare less-than or equal

```
uint32x2_t vcle_f32(float32x2_t a, float32x2_t b);
                                                    // VCGE.F32 d0, d0, d0
uint8x8_t vcle_u8(uint8x8_t a, uint8x8_t b);
                                                    // VCGE.U8 d0, d0, d0
                                                    // VCGE.U16 d0, d0, d0
uint16x4_t vcle_u16(uint16x4_t a, uint16x4_t b);
uint32x2_t vcle_u32(uint32x2_t a, uint32x2_t b);
                                                    // VCGE.U32 d0, d0, d0
                                                    // VCGE.S8 q0, q0, q0
uint8x16_t vcleq_s8(int8x16_t a, int8x16_t b);
uint16x8_t vcleq_s16(int16x8_t a, int16x8_t b);
                                                    // VCGE.S16 q0, q0, q0
uint32x4_t vcleq_s32(int32x4_t a, int32x4_t b);
                                                    // VCGE.S32 q0, q0, q0
uint32x4_t vcleq_f32(float32x4_t a, float32x4_t b); // VCGE.F32 q0, q0, q0
uint8x16_t vcleq_u8(uint8x16_t a, uint8x16_t b);
                                                    // VCGE.U8 q0, q0, q0
uint16x8_t vcleq_u16(uint16x8_t a, uint16x8_t b);
                                                    // VCGE.U16 q0, q0, q0
uint32x4_t vcleq_u32(uint32x4_t a, uint32x4_t b);
                                                    // VCGE.U32 q0, q0, q0
```

Vector compare greater-than

```
uint8x8_t vcgt_s8(int8x8_t a, int8x8_t b);
                                                    // VCGT.S8 d0, d0, d0
uint16x4_t vcgt_s16(int16x4_t a, int16x4_t b);
                                                    // VCGT.S16 d0, d0, d0
                                                    // VCGT.S32 d0, d0, d0
uint32x2_t vcqt_s32(int32x2_t a, int32x2_t b);
uint32x2_t vcgt_f32(float32x2_t a, float32x2_t b);
                                                    // VCGT.F32 d0, d0, d0
uint8x8_t vcqt_u8(uint8x8_t a, uint8x8_t b);
                                                    // VCGT.U8 d0, d0, d0
uint16x4_t vcgt_u16(uint16x4_t a, uint16x4_t b);
                                                    // VCGT.U16 d0, d0, d0
uint32x2_t vcgt_u32(uint32x2_t a, uint32x2_t b);
                                                    // VCGT.U32 d0, d0, d0
uint8x16_t vcgtq_s8(int8x16_t a, int8x16_t b);
                                                    // VCGT.S8 q0, q0, q0
uint16x8_t vcgtq_s16(int16x8_t a, int16x8_t b);
                                                    // VCGT.S16 q0, q0, q0
uint32x4_t vcqtq_s32(int32x4_t a, int32x4_t b);
                                                    // VCGT.S32 q0, q0, q0
uint32x4_t vcgtq_f32(float32x4_t a, float32x4_t b); // VCGT.F32 q0, q0, q0
uint8x16_t vcqtq_u8(uint8x16_t a, uint8x16_t b);
                                                    // VCGT.U8 q0, q0, q0
uint16x8_t vcgtq_u16(uint16x8_t a, uint16x8_t b);
                                                    // VCGT.U16 q0, q0, q0
uint32x4_t vcqtq_u32(uint32x4_t a, uint32x4_t b);
                                                    // VCGT.U32 q0, q0, q0
```

Vector compare less-than

```
uint8x8_t vclt_s8(int8x8_t a, int8x8_t b);
                                                    // VCGT.S8 d0, d0, d0
uint16x4_t vclt_s16(int16x4_t a, int16x4_t b);
                                                    // VCGT.S16 d0, d0, d0
                                                    // VCGT.S32 d0, d0, d0
uint32x2_t vclt_s32(int32x2_t a, int32x2_t b);
                                                    // VCGT.F32 d0, d0, d0
uint32x2_t vclt_f32(float32x2_t a, float32x2_t b);
uint8x8_t vclt_u8(uint8x8_t a, uint8x8_t b);
                                                    // VCGT.U8 d0, d0, d0
uint16x4_t vclt_u16(uint16x4_t a, uint16x4_t b);
                                                    // VCGT.U16 d0, d0, d0
uint32x2_t vclt_u32(uint32x2_t a, uint32x2_t b);
                                                    // VCGT.U32 d0, d0, d0
uint8x16_t vcltg_s8(int8x16_t a, int8x16_t b);
                                                    // VCGT.S8 q0, q0, q0
uint16x8_t vcltq_s16(int16x8_t a, int16x8_t b);
                                                    // VCGT.S16 q0, q0, q0
uint32x4_t vcltg_s32(int32x4_t a, int32x4_t b);
                                                    // VCGT.S32 q0, q0, q0
uint32x4_t vcltq_f32(float32x4_t a, float32x4_t b); // VCGT.F32 q0, q0, q0
uint8x16_t vcltg_u8(uint8x16_t a, uint8x16_t b);
                                                    // VCGT.U8 q0, q0, q0
uint16x8_t vcltq_u16(uint16x8_t a, uint16x8_t b);
                                                    // VCGT.U16 q0, q0, q0
uint32x4_t vcltq_u32(uint32x4_t a, uint32x4_t b);
                                                    // VCGT.U32 q0, q0, q0
```

Vector compare absolute greater-than or equal

```
uint32x2_t vcage_f32(float32x2_t a, float32x2_t b); // VACGE.F32 d0, d0, d0
uint32x4_t vcageq_f32(float32x4_t a, float32x4_t b); // VACGE.F32 q0, q0, q0
```

Vector compare absolute less-than or equal

```
uint32x2_t vcale_f32(float32x2_t a, float32x2_t b); // VACGE.F32 d0, d0, d0
uint32x4_t vcaleq_f32(float32x4_t a, float32x4_t b); // VACGE.F32 q0, q0, q0
```

Vector compare absolute greater-than

```
uint32x2_t vcagt_f32(float32x2_t a, float32x2_t b); // VACGT.F32 d0, d0, d0
uint32x4_t vcagtq_f32(float32x4_t a, float32x4_t b); // VACGT.F32 q0, q0, q0
```

Vector compare absolute less-than

```
uint32x2_t vcalt_f32(float32x2_t a, float32x2_t b); // VACGT.F32 d0, d0, d0
uint32x4_t vcaltq_f32(float32x4_t a, float32x4_t b); // VACGT.F32 q0, q0, q0
```

Vector test bits

```
uint8x8_t vtst_s8(int8x8_t a, int8x8_t b);
                                                // VTST.8 d0, d0, d0
uint16x4_t vtst_s16(int16x4_t a, int16x4_t b);
                                                // VTST.16 d0, d0, d0
                                                // VTST.32 d0, d0, d0
uint32x2_t vtst_s32(int32x2_t a, int32x2_t b);
                                                // VTST.8 d0, d0, d0
uint8x8_t vtst_u8(uint8x8_t a, uint8x8_t b);
uint16x4_t vtst_u16(uint16x4_t a, uint16x4_t b); // VTST.16 d0, d0, d0
uint32x2_t vtst_u32(uint32x2_t a, uint32x2_t b); // VTST.32 d0, d0, d0
uint8x8_t vtst_p8(poly8x8_t a, poly8x8_t b);
                                                // VTST.8 d0, d0, d0
uint8x16_t vtstq_s8(int8x16_t a, int8x16_t b);
                                                // VTST.8 q0, q0, q0
uint16x8_t vtstq_s16(int16x8_t a, int16x8_t b);
                                                // VTST.16 q0, q0, q0
uint32x4_t vtstg_s32(int32x4_t a, int32x4_t b);
                                                // VTST.32 q0, q0, q0
uint8x16_t vtstq_u8(uint8x16_t a, uint8x16_t b); // VTST.8 q0, q0, q0
uint16x8_t vtstq_u16(uint16x8_t a, uint16x8_t b); // VTST.16 q0, q0, q0
uint32x4_t vtstq_u32(uint32x4_t a, uint32x4_t b); // VTST.32 q0, q0, q0
uint8x16_t vtstq_p8(poly8x16_t a, poly8x16_t b); // VTST.8 q0, q0, q0
```

E.3.5 Absolute difference

These intrinsics provide operations including absolute difference.

Absolute difference between the arguments: Vr[i] = | Va[i] - Vb[i] |

```
uint16x4_t vabd_u16(uint16x4_t a, uint16x4_t b);
                                                    // VABD.U16 d0,d0,d0
uint32x2_t vabd_u32(uint32x2_t a, uint32x2_t b);
                                                    // VABD.U32 d0,d0,d0
float32x2_t vabd_f32(float32x2_t a, float32x2_t b);
                                                  // VABD.F32 d0,d0,d0
int8x16_t
           vabdq_s8(int8x16_t a, int8x16_t b);
                                                    // VABD.S8 q0,q0,q0
int16x8_t
           vabdq_s16(int16x8_t a, int16x8_t b);
                                                    // VABD.S16 q0,q0,q0
int32x4_t
           vabdq_s32(int32x4_t a, int32x4_t b);
                                                    // VABD.S32 q0,q0,q0
uint8x16_t vabdq_u8(uint8x16_t a, uint8x16_t b);
                                                    // VABD.U8 q0,q0,q0
uint16x8_t vabdq_u16(uint16x8_t a, uint16x8_t b);
                                                    // VABD.U16 q0,q0,q0
uint32x4_t vabdq_u32(uint32x4_t a, uint32x4_t b);
                                                    // VABD.U32 q0,q0,q0
float32x4_t vabdq_f32(float32x4_t a, float32x4_t b); // VABD.F32 q0,q0,q0
```

Absolute difference - long

Absolute difference and accumulate: Vr[i] = Va[i] + | Vb[i] - Vc[i] |

```
int8x8_t vaba_s8(int8x8_t a, int8x8_t b, int8x8_t c);
                                                               // VABA.S8 d0,d0,d0
int16x4_t vaba_s16(int16x4_t a, int16x4_t b, int16x4_t c);
                                                               // VABA.S16 d0,d0,d0
int32x2_t vaba_s32(int32x2_t a, int32x2_t b, int32x2_t c);
                                                               // VABA.S32 d0,d0,d0
uint8x8_t vaba_u8(uint8x8_t a, uint8x8_t b, uint8x8_t c);
                                                               // VABA.U8 d0,d0,d0
uint16x4_t vaba_u16(uint16x4_t a, uint16x4_t b, uint16x4_t c); // VABA.U16 d0,d0,d0
uint32x2_t vaba_u32(uint32x2_t a, uint32x2_t b, uint32x2_t c); // VABA.U32 d0,d0,d0
                                                               // VABA.S8 q0,q0,q0
int8x16_t vabaq_s8(int8x16_t a, int8x16_t b, int8x16_t c);
int16x8_t vabaq_s16(int16x8_t a, int16x8_t b, int16x8_t c);
                                                               // VABA.S16 q0,q0,q0
int32x4_t vabaq_s32(int32x4_t a, int32x4_t b, int32x4_t c);
                                                               // VABA.S32 q0,q0,q0
uint8x16_t vabag_u8(uint8x16_t a, uint8x16_t b, uint8x16_t c); // VABA.U8 q0,q0,q0
uint16x8_t vabaq_u16(uint16x8_t a, uint16x8_t b, uint16x8_t c); // VABA.U16 q0,q0,q0
uint32x4_t vabaq_u32(uint32x4_t a, uint32x4_t b, uint32x4_t c); // VABA.U32 q0,q0,q0
```

Absolute difference and accumulate - long

E.3.6 Max/Min

These intrinsics provide maximum and minimum operations.

vmax -> Vr[i] := (Va[i] >= Vb[i]) ? Va[i] : Vb[i]

```
vmax_s8(int8x8_t a, int8x8_t b);
int8x8_t
                                                    // VMAX.S8 d0,d0,d0
           vmax_s16(int16x4_t a, int16x4_t b);
int16x4_t
                                                    // VMAX.S16 d0,d0,d0
int32x2_t
           vmax_s32(int32x2_t a, int32x2_t b);
                                                    // VMAX.S32 d0,d0,d0
uint8x8_t
           vmax_u8(uint8x8_t a, uint8x8_t b);
                                                    // VMAX.U8 d0,d0,d0
                                                    // VMAX.U16 d0,d0,d0
uint16x4_t vmax_u16(uint16x4_t a, uint16x4_t b);
uint32x2_t vmax_u32(uint32x2_t a, uint32x2_t b);
                                                    // VMAX.U32 d0,d0,d0
float32x2_t vmax_f32(float32x2_t a, float32x2_t b); // VMAX.F32 d0,d0,d0
int8x16_t vmaxq_s8(int8x16_t a, int8x16_t b);
                                                    // VMAX.S8 q0,q0,q0
int16x8_t
           vmaxq_s16(int16x8_t a, int16x8_t b);
                                                    // VMAX.S16 q0,q0,q0
int32x4_t vmaxq_s32(int32x4_t a, int32x4_t b);
                                                    // VMAX.S32 q0,q0,q0
uint8x16_t vmaxq_u8(uint8x16_t a, uint8x16_t b);
                                                    // VMAX.U8 q0,q0,q0
uint16x8_t vmaxg_u16(uint16x8_t a, uint16x8_t b);
                                                    // VMAX.U16 q0,q0,q0
uint32x4_t vmaxg_u32(uint32x4_t a, uint32x4_t b);
                                                    // VMAX.U32 q0,q0,q0
float32x4_t vmaxq_f32(float32x4_t a, float32x4_t b); // VMAX.F32 q0,q0,q0
```

vmin -> Vr[i] := (Va[i] >= Vb[i]) ? Vb[i] : Va[i]

```
int8x8_t
           vmin_s8(int8x8_t a, int8x8_t b);
                                                    // VMIN.S8 d0,d0,d0
int16x4 t
           vmin_s16(int16x4_t a, int16x4_t b);
                                                    // VMIN.S16 d0,d0,d0
int32x2_t
           vmin_s32(int32x2_t a, int32x2_t b);
                                                    // VMIN.S32 d0,d0,d0
uint8x8_t
           vmin_u8(uint8x8_t a, uint8x8_t b);
                                                    // VMIN.U8 d0,d0,d0
uint16x4_t vmin_u16(uint16x4_t a, uint16x4_t b);
                                                    // VMIN.U16 d0,d0,d0
uint32x2_t vmin_u32(uint32x2_t a, uint32x2_t b);
                                                    // VMIN.U32 d0,d0,d0
float32x2_t vmin_f32(float32x2_t a, float32x2_t b);
                                                    // VMIN.F32 d0,d0,d0
int8x16_t vminq_s8(int8x16_t a, int8x16_t b);
                                                    // VMIN.S8 q0,q0,q0
int16x8_t vminq_s16(int16x8_t a, int16x8_t b);
                                                    // VMIN.S16 q0,q0,q0
int32x4_t
           vming_s32(int32x4_t a, int32x4_t b);
                                                    // VMIN.S32 q0,q0,q0
                                                    // VMIN.U8 q0,q0,q0
uint8x16_t vming_u8(uint8x16_t a, uint8x16_t b);
uint16x8_t vming_u16(uint16x8_t a, uint16x8_t b);
                                                    // VMIN.U16 q0,q0,q0
uint32x4_t vminq_u32(uint32x4_t a, uint32x4_t b);
                                                    // VMIN.U32 q0,q0,q0
float32x4_t vminq_f32(float32x4_t a, float32x4_t b); // VMIN.F32 q0,q0,q0
```

E.3.7 Pairwise addition

These intrinsics provide pairwise addition operations.

Pairwise add

```
int8x8_t
           vpadd_s8(int8x8_t a, int8x8_t b);
                                                    // VPADD.I8 d0,d0,d0
int16x4_t
           vpadd_s16(int16x4_t a, int16x4_t b);
                                                    // VPADD.I16 d0,d0,d0
int32x2_t
           vpadd_s32(int32x2_t a, int32x2_t b);
                                                    // VPADD.I32 d0,d0,d0
uint8x8_t
           vpadd_u8(uint8x8_t a, uint8x8_t b);
                                                    // VPADD.I8 d0,d0,d0
uint16x4_t vpadd_u16(uint16x4_t a, uint16x4_t b);
                                                    // VPADD.I16 d0,d0,d0
uint32x2_t vpadd_u32(uint32x2_t a, uint32x2_t b);
                                                    // VPADD.I32 d0,d0,d0
float32x2_t vpadd_f32(float32x2_t a, float32x2_t b); // VPADD.F32 d0,d0,d0
```

Long pairwise add

```
int16x4_t vpaddl_s8(int8x8_t a);
                                      // VPADDL.S8 d0,d0
int32x2_t vpaddl_s16(int16x4_t a);
                                      // VPADDL.S16 d0,d0
int64x1_t vpaddl_s32(int32x2_t a);
                                      // VPADDL.S32 d0,d0
uint16x4_t vpaddl_u8(uint8x8_t a);
                                      // VPADDL.U8 d0,d0
uint32x2_t vpaddl_u16(uint16x4_t a);
                                      // VPADDL.U16 d0,d0
uint64x1_t vpaddl_u32(uint32x2_t a);
                                      // VPADDL.U32 d0,d0
int16x8_t vpaddlq_s8(int8x16_t a);
                                      // VPADDL.S8 q0,q0
int32x4_t vpaddlq_s16(int16x8_t a);
                                      // VPADDL.S16 q0,q0
int64x2_t vpaddlq_s32(int32x4_t a);
                                      // VPADDL.S32 q0,q0
uint16x8_t vpaddlq_u8(uint8x16_t a);
                                      // VPADDL.U8 q0,q0
uint32x4_t vpaddlq_u16(uint16x8_t a);
                                      // VPADDL.U16 q0,q0
uint64x2_t vpaddlq_u32(uint32x4_t a); // VPADDL.U32 q0,q0
```

Long pairwise add and accumulate

```
int16x4_t vpadal_s8(int16x4_t a, int8x8_t b);
                                                   // VPADAL.S8 d0,d0
int32x2_t vpadal_s16(int32x2_t a, int16x4_t b);
                                                   // VPADAL.S16 d0,d0
int64x1_t vpadal_s32(int64x1_t a, int32x2_t b);
                                                   // VPADAL.S32 d0,d0
uint16x4_t vpadal_u8(uint16x4_t a, uint8x8_t b);
                                                   // VPADAL.U8 d0,d0
uint32x2_t vpadal_u16(uint32x2_t a, uint16x4_t b); // VPADAL.U16 d0,d0
uint64x1_t vpadal_u32(uint64x1_t a, uint32x2_t b); // VPADAL.U32 d0,d0
int16x8_t vpadalq_s8(int16x8_t a, int8x16_t b);
                                                   // VPADAL.S8 q0,q0
int32x4_t vpadalq_s16(int32x4_t a, int16x8_t b);
                                                   // VPADAL.S16 q0,q0
int64x2_t vpadalq_s32(int64x2_t a, int32x4_t b);
                                                   // VPADAL.S32 q0,q0
uint16x8_t vpadalq_u8(uint16x8_t a, uint8x16_t b); // VPADAL.U8 q0,q0
uint32x4_t vpadalq_u16(uint32x4_t a, uint16x8_t b); // VPADAL.U16 q0,q0
uint64x2_t vpadalq_u32(uint64x2_t a, uint32x4_t b); // VPADAL.U32 q0.q0
```

E.3.8 Folding maximum

vpmax -> takes maximum of adjacent pairs

```
int8x8 t
            vpmax_s8(int8x8_t a, int8x8_t b);
                                                    // VPMAX.S8 d0,d0,d0
int16x4_t
           vpmax_s16(int16x4_t a, int16x4_t b);
                                                    // VPMAX.S16 d0,d0,d0
int32x2 t
           vpmax_s32(int32x2_t a, int32x2_t b);
                                                    // VPMAX.S32 d0,d0,d0
uint8x8_t
           vpmax_u8(uint8x8_t a, uint8x8_t b);
                                                    // VPMAX.U8 d0,d0.d0
uint16x4_t vpmax_u16(uint16x4_t a, uint16x4_t b);
                                                    // VPMAX.U16 d0,d0,d0
uint32x2_t vpmax_u32(uint32x2_t a, uint32x2_t b);
                                                   // VPMAX.U32 d0,d0,d0
float32x2_t vpmax_f32(float32x2_t a, float32x2_t b); // VPMAX.F32 d0,d0,d0
```

E.3.9 Folding minimum

vpmin -> takes minimum of adjacent pairs

E.3.10 Reciprocal/Sqrt

Reciprocal estimate/step and 1/sqrt estimate/step

```
float32x2_t vrecps_f32(float32x2_t a, float32x2_t b); // VRECPS.F32 d0, d0, d0 float32x4_t vrecpsq_f32(float32x4_t a, float32x4_t b); // VRECPS.F32 q0, q0, q0 float32x2_t vrsqrts_f32(float32x2_t a, float32x2_t b); // VRSQRTS.F32 d0, d0, d0 float32x4_t vrsqrtsq_f32(float32x4_t a, float32x4_t b); // VRSQRTS.F32 q0, q0, q0
```

E.3.11 Shifts by signed variable

These intrinsics provide operations including shift by signed variable.

Vector shift left: Vr[i] := Va[i] << Vb[i] (negative values shift right)

```
int8x8_t
          vshl_s8(int8x8_t a, int8x8_t b);
                                                  // VSHL.S8 d0,d0,d0
int16x4_t vshl_s16(int16x4_t a, int16x4_t b);
                                                 // VSHL.S16 d0,d0,d0
int32x2_t vshl_s32(int32x2_t a, int32x2_t b);
                                                  // VSHL.S32 d0,d0,d0
int64x1_t vshl_s64(int64x1_t a, int64x1_t b);
                                                 // VSHL.S64 d0,d0,d0
uint8x8_t vshl_u8(uint8x8_t a, int8x8_t b);
                                                 // VSHL.U8 d0,d0,d0
uint16x4_t vshl_u16(uint16x4_t a, int16x4_t b);
                                                 // VSHL.U16 d0,d0,d0
uint32x2_t vshl_u32(uint32x2_t a, int32x2_t b);
                                                 // VSHL.U32 d0,d0,d0
uint64x1_t vshl_u64(uint64x1_t a, int64x1_t b);
                                                 // VSHL.U64 d0,d0,d0
int8x16_t vshlq_s8(int8x16_t a, int8x16_t b);
                                                 // VSHL.S8 q0,q0,q0
int16x8_t vshlq_s16(int16x8_t a, int16x8_t b);
                                                 // VSHL.S16 q0,q0,q0
int32x4_t vshlq_s32(int32x4_t a, int32x4_t b);
                                                  // VSHL.S32 q0,q0,q0
int64x2_t vshlq_s64(int64x2_t a, int64x2_t b);
                                                 // VSHL.S64 q0,q0,q0
uint8x16_t vshlq_u8(uint8x16_t a, int8x16_t b);
                                                 // VSHL.U8 q0,q0,q0
uint16x8_t vshlq_u16(uint16x8_t a, int16x8_t b); // VSHL.U16 q0,q0,q0
uint32x4_t vshlq_u32(uint32x4_t a, int32x4_t b);
                                                 // VSHL.U32 q0,q0,q0
uint64x2_t vshlq_u64(uint64x2_t a, int64x2_t b); // VSHL.U64 q0,q0,q0
```

Vector saturating shift left: (negative values shift right)

```
int8x8_t
         vqshl_s8(int8x8_t a, int8x8_t b);
                                                 // VQSHL.S8 d0,d0,d0
int16x4_t vqshl_s16(int16x4_t a, int16x4_t b);
                                                 // VQSHL.S16 d0,d0,d0
int32x2_t vqsh1_s32(int32x2_t a, int32x2_t b);
                                                 // VQSHL.S32 d0,d0,d0
int64x1_t vqsh1_s64(int64x1_t a, int64x1_t b);
                                                 // VQSHL.S64 d0,d0,d0
uint8x8_t vqshl_u8(uint8x8_t a, int8x8_t b);
                                                 // VQSHL.U8 d0,d0,d0
uint16x4_t vqshl_u16(uint16x4_t a, int16x4_t b);
                                                 // VQSHL.U16 d0,d0,d0
uint32x2_t vqsh1_u32(uint32x2_t a, int32x2_t b);
                                                 // VQSHL.U32 d0,d0,d0
uint64x1_t vqshl_u64(uint64x1_t a, int64x1_t b);
                                                 // VQSHL.U64 d0,d0,d0
int8x16_t vqsh1q_s8(int8x16_t a, int8x16_t b);
                                                 // VQSHL.S8 q0,q0,q0
```

```
int16x8_t vqshlq_s16(int16x8_t a, int16x8_t b);  // VQSHL.S16 q0,q0,q0
int32x4_t vqshlq_s32(int32x4_t a, int32x4_t b);  // VQSHL.S32 q0,q0,q0
int64x2_t vqshlq_s64(int64x2_t a, int64x2_t b);  // VQSHL.S64 q0,q0,q0
uint8x16_t vqshlq_u8(uint8x16_t a, int8x16_t b);  // VQSHL.U8 q0,q0,q0
uint16x8_t vqshlq_u16(uint16x8_t a, int16x8_t b);  // VQSHL.U16 q0,q0,q0
uint32x4_t vqshlq_u32(uint32x4_t a, int32x4_t b);  // VQSHL.U32 q0,q0,q0
uint64x2_t vqshlq_u64(uint64x2_t a, int64x2_t b);  // VQSHL.U64 q0,q0,q0
```

Vector rounding shift left: (negative values shift right)

```
int8x8_t
          vrshl_s8(int8x8_t a, int8x8_t b);
                                                 // VRSHL.S8 d0,d0,d0
int16x4_t vrsh1_s16(int16x4_t a, int16x4_t b);
                                                 // VRSHL.S16 d0,d0,d0
                                                 // VRSHL.S32 d0,d0,d0
int32x2_t vrsh1_s32(int32x2_t a, int32x2_t b);
                                                 // VRSHL.S64 d0,d0,d0
int64x1_t vrsh1_s64(int64x1_t a, int64x1_t b);
uint8x8_t vrshl_u8(uint8x8_t a, int8x8_t b);
                                                 // VRSHL.U8 d0,d0,d0
uint16x4_t vrshl_u16(uint16x4_t a, int16x4_t b); // VRSHL.U16 d0,d0,d0
uint32x2_t vrshl_u32(uint32x2_t a, int32x2_t b); // VRSHL.U32 d0,d0,d0
uint64x1_t vrshl_u64(uint64x1_t a, int64x1_t b); // VRSHL.U64 d0,d0,d0
int8x16_t vrshlq_s8(int8x16_t a, int8x16_t b);
                                                 // VRSHL.S8 q0,q0,q0
int16x8_t vrshlq_s16(int16x8_t a, int16x8_t b); // VRSHL.S16 q0,q0,q0
int32x4_t vrshlq_s32(int32x4_t a, int32x4_t b); // VRSHL.S32 q0,q0,q0
int64x2_t vrshlq_s64(int64x2_t a, int64x2_t b); // VRSHL.S64 q0,q0,q0
uint8x16_t vrshlq_u8(uint8x16_t a, int8x16_t b); // VRSHL.U8 q0,q0,q0
uint16x8_t vrshlq_u16(uint16x8_t a, int16x8_t b); // VRSHL.U16 q0,q0,q0
uint32x4_t vrshlq_u32(uint32x4_t a, int32x4_t b); // VRSHL.U32 q0,q0,q0
uint64x2_t vrshlq_u64(uint64x2_t a, int64x2_t b); // VRSHL.U64 q0,q0,q0
```

Vector saturating rounding shift left: (negative values shift right)

```
// VQRSHL.S8 d0,d0,d0
int8x8_t
          vqrshl_s8(int8x8_t a, int8x8_t b);
int16x4_t vqrshl_s16(int16x4_t a, int16x4_t b);
                                                  // VQRSHL.S16 d0,d0,d0
                                                  // VQRSHL.S32 d0,d0,d0
int32x2_t vgrsh1_s32(int32x2_t a, int32x2_t b);
int64x1_t vqrshl_s64(int64x1_t a, int64x1_t b);
                                                  // VQRSHL.S64 d0,d0,d0
uint8x8_t vgrshl_u8(uint8x8_t a, int8x8_t b);
                                                  // VQRSHL.U8 d0,d0,d0
uint16x4_t vqrshl_u16(uint16x4_t a, int16x4_t b);
                                                  // VQRSHL.U16 d0,d0,d0
uint32x2_t vqrsh1_u32(uint32x2_t a, int32x2_t b);
                                                  // VQRSHL.U32 d0,d0,d0
uint64x1_t vqrshl_u64(uint64x1_t a, int64x1_t b); // VQRSHL.U64 d0,d0,d0
int8x16_t vqrshlq_s8(int8x16_t a, int8x16_t b);
                                                  // VQRSHL.S8 q0,q0,q0
int16x8_t vqrshlq_s16(int16x8_t a, int16x8_t b); // VQRSHL.S16 q0,q0,q0
int32x4_t vqrshlq_s32(int32x4_t a, int32x4_t b); // VQRSHL.S32 q0,q0,q0
int64x2_t vgrshlq_s64(int64x2_t a, int64x2_t b); // VQRSHL.S64 q0,q0,q0
uint8x16_t vqrshlq_u8(uint8x16_t a, int8x16_t b); // VQRSHL.U8 q0,q0,q0
uint16x8_t vqrshlq_u16(uint16x8_t a, int16x8_t b); // VQRSHL.U16 q0,q0,q0
uint32x4_t vqrshlq_u32(uint32x4_t a, int32x4_t b); // VQRSHL.U32 q0,q0,q0
uint64x2_t vqrshlq_u64(uint64x2_t a, int64x2_t b); // VQRSHL.U64 q0,q0,q0
```

E.3.12 Shifts by a constant

These intrinsics provide operations for shifting by a constant.

Vector shift right by constant

```
int8x8_t vshr_n_s8(int8x8_t a, __constrange(1,8) int b);
                                                               // VSHR.S8 d0,d0,#8
int16x4_t vshr_n_s16(int16x4_t a, __constrange(1,16) int b);
                                                               // VSHR.S16 d0,d0,#16
int32x2_t vshr_n_s32(int32x2_t a, __constrange(1,32) int b);
                                                               // VSHR.S32 d0,d0,#32
int64x1_t vshr_n_s64(int64x1_t a, __constrange(1,64) int b);
                                                              // VSHR.S64 d0,d0,#64
uint8x8_t vshr_n_u8(uint8x8_t a, __constrange(1,8) int b);
                                                               // VSHR.U8 d0,d0,#8
uint16x4_t vshr_n_u16(uint16x4_t a, __constrange(1,16) int b); // VSHR.U16 d0,d0,#16
uint32x2_t vshr_n_u32(uint32x2_t a, __constrange(1,32) int b); // VSHR.U32 d0,d0,#32
uint64x1_t vshr_n_u64(uint64x1_t a, __constrange(1,64) int b); // VSHR.U64 d0,d0,#64
int8x16_t vshrq_n_s8(int8x16_t a, __constrange(1,8) int b);
                                                               // VSHR.S8 q0,q0,#8
int16x8_t vshrq_n_s16(int16x8_t a, __constrange(1,16) int b); // VSHR.S16 q0,q0,#16
int32x4_t vshrq_n_s32(int32x4_t a, __constrange(1,32) int b); // VSHR.S32 q0,q0,#32
int64x2_t vshrq_n_s64(int64x2_t a, __constrange(1,64) int b); // VSHR.S64 q0,q0,#64
uint8x16_t vshrq_n_u8(uint8x16_t a, __constrange(1,8) int b);
                                                               // VSHR.U8 q0,q0,#8
uint16x8_t vshrq_n_u16(uint16x8_t a, __constrange(1,16) int b); // VSHR.U16 q0,q0,#16
uint32x4_t vshrq_n_u32(uint32x4_t a, __constrange(1,32) int b); // VSHR.U32 q0,q0,#32
uint64x2_t vshrq_n_u64(uint64x2_t a, __constrange(1,64) int b); // VSHR.U64 q0,q0,#64
```

Vector shift left by constant

```
vshl_n_s8(int8x8_t a, __constrange(0,7) int b);
int8x8_t
                                                               // VSHL.I8 d0,d0,#0
int16x4_t vshl_n_s16(int16x4_t a, __constrange(0,15) int b);
                                                               // VSHL.I16 d0,d0.#0
int32x2_t vshl_n_s32(int32x2_t a, __constrange(0,31) int b);
                                                               // VSHL.I32 d0,d0,#0
int64x1_t vshl_n_s64(int64x1_t a, __constrange(0.63) int b);
                                                               // VSHL.I64 d0,d0,#0
uint8x8_t vshl_n_u8(uint8x8_t a, __constrange(0,7) int b);
                                                               // VSHL.I8 d0,d0,#0
uint16x4_t vshl_n_u16(uint16x4_t a, __constrange(0,15) int b); // VSHL.I16 d0,d0,#0
uint32x2_t vshl_n_u32(uint32x2_t a, __constrange(0,31) int b); // VSHL.I32 d0,d0,#0
uint64x1_t vshl_n_u64(uint64x1_t a, __constrange(0,63) int b); // VSHL.I64 d0,d0,#0
int8x16_t vshlq_n_s8(int8x16_t a, \__constrange(0,7) int b);
                                                               // VSHL.I8 q0,q0,#0
int16x8_t vshlq_n_s16(int16x8_t a, __constrange(0,15) int b); // VSHL.I16 q0,q0,#0
int32x4_t vshlq_n_s32(int32x4_t a, __constrange(0,31) int b); // VSHL.I32 q0,q0,#0
int64x2_t vshlq_n_s64(int64x2_t a, __constrange(0,63) int b); // VSHL.I64 q0,q0,#0
uint8x16_t vshlq_n_u8(uint8x16_t a, __constrange(0,7) int b); // VSHL.I8 q0,q0,#0
uint16x8_t vshlq_n_u16(uint16x8_t a, __constrange(0,15) int b); // VSHL.I16 q0,q0,#0
uint32x4_t vshlq_n_u32(uint32x4_t a, __constrange(0,31) int b); // VSHL.I32 q0,q0,#0
uint64x2_t vshlq_n_u64(uint64x2_t a, __constrange(0,63) int b); // VSHL.I64 q0,q0,#0
```

Vector rounding shift right by constant

Vector shift right by constant and accumulate

```
int8x8_t
          vsra_n_s8(int8x8_t a, int8x8_t b, \__constrange(1,8) int c);
                                                                             // VSRA.S8 d0,d0,#8
int16x4_t vsra_n_s16(int16x4_t a, int16x4_t b, __constrange(1,16) int c);
                                                                              // VSRA.S16 d0,d0,#16
int32x2_t vsra_n_s32(int32x2_t a, int32x2_t b, __constrange(1,32) int c);
                                                                             // VSRA.S32 d0,d0,#32
int64x1_t vsra_n_s64(int64x1_t a, int64x1_t b, __constrange(1,64) int c);
                                                                              // VSRA.S64 d0,d0,#64
uint8x8_t vsra_n_u8(uint8x8_t a, uint8x8_t b, __constrange(1,8) int c);
                                                                             // VSRA.U8 d0,d0,#8
uint16x4_t vsra_n_u16(uint16x4_t a, uint16x4_t b, __constrange(1,16) int c);
                                                                             // VSRA.U16 d0,d0,#16
uint32x2_t vsra_n_u32(uint32x2_t a, uint32x2_t b, __constrange(1,32) int c);
                                                                             // VSRA.U32 d0,d0,#32
uint64x1_t vsra_n_u64(uint64x1_t a, uint64x1_t b, __constrange(1,64) int c);
                                                                             // VSRA.U64 d0,d0,#64
int8x16_t vsraq_n_s8(int8x16_t a, int8x16_t b, __constrange(1,8) int c);
                                                                              // VSRA.S8 q0,q0,#8
int16x8_t vsraq_n_s16(int16x8_t a, int16x8_t b, __constrange(1,16) int c);
                                                                             // VSRA.S16 q0,q0,#16
int32x4_t vsraq_n_s32(int32x4_t a, int32x4_t b, __constrange(1,32) int c);
                                                                              // VSRA.S32 q0,q0,#32
int64x2_t vsraq_n_s64(int64x2_t a, int64x2_t b, __constrange(1,64) int c);
                                                                              // VSRA.S64 q0,q0,#64
uint8x16_t vsraq_n_u8(uint8x16_t a, uint8x16_t b, __constrange(1,8) int c);
                                                                             // VSRA.U8 q0,q0,#8
uint16x8_t vsraq_n_u16(uint16x8_t a, uint16x8_t b, __constrange(1,16) int c); // VSRA.U16 q0,q0,#16
uint32x4_t vsraq_n_u32(uint32x4_t a, uint32x4_t b, __constrange(1,32) int c); // VSRA.U32 q0,q0,#32
uint64x2_t vsraq_n_u64(uint64x2_t a, uint64x2_t b, __constrange(1,64) int c); // VSRA.U64 q0,q0,#64
```

Vector rounding shift right by constant and accumulate

```
int8x8_t vrsra_n_s8(int8x8_t a, int8x8_t b, __constrange(1,8) int c);
                                                                               // VRSRA.S8 d0,d0,#8
int16x4_t vrsra_n_s16(int16x4_t a, int16x4_t b, __constrange(1,16) int c);
                                                                               // VRSRA.S16 d0,d0,#16
int32x2_t vrsra_n_s32(int32x2_t a, int32x2_t b, __constrange(1,32) int c);
                                                                               // VRSRA.S32 d0,d0,#32
int64x1_t vrsra_n_s64(int64x1_t a, int64x1_t b, __constrange(1,64) int c);
                                                                               // VRSRA.S64 d0,d0,#64
uint8x8_t vrsra_n_u8(uint8x8_t a, uint8x8_t b, __constrange(1,8) int c);
                                                                               // VRSRA.U8 d0,d0,#8
uint16x4_t vrsra_n_u16(uint16x4_t a, uint16x4_t b, __constrange(1,16) int c);
                                                                               // VRSRA.U16 d0,d0,#16
uint32x2_t vrsra_n_u32(uint32x2_t a, uint32x2_t b, __constrange(1,32) int c);
                                                                               // VRSRA.U32 d0,d0,#32
uint64x1_t vrsra_n_u64(uint64x1_t a, uint64x1_t b, __constrange(1,64) int c);
                                                                               // VRSRA.U64 d0,d0,#64
int8x16_t vrsraq_n_s8(int8x16_t a, int8x16_t b, __constrange(1,8) int c);
                                                                               // VRSRA.S8 q0,q0,#8
int16x8_t vrsraq_n_s16(int16x8_t a, int16x8_t b, __constrange(1,16) int c);
                                                                               // VRSRA.S16 q0,q0,#16
int32x4_t vrsraq_n_s32(int32x4_t a, int32x4_t b, __constrange(1,32) int c);
                                                                               // VRSRA.S32 q0,q0,#32
int64x2_t vrsraq_n_s64(int64x2_t a, int64x2_t b, __constrange(1,64) int c);
                                                                               // VRSRA.S64 q0,q0,#64
uint8x16_t vrsraq_n_u8(uint8x16_t a, uint8x16_t b, __constrange(1,8) int c);
                                                                               // VRSRA.U8 q0,q0,#8
uint16x8_t vrsrag_n_u16(uint16x8_t a, uint16x8_t b, __constrange(1,16) int c); // VRSRA.U16 g0, g0, #16
```

```
uint32x4_t vrsraq_n_u32(uint32x4_t a, uint32x4_t b, __constrange(1,32) int c); // VRSRA.U32 q0,q0,#32 uint64x2_t vrsraq_n_u64(uint64x2_t a, uint64x2_t b, __constrange(1,64) int c); // VRSRA.U64 q0,q0,#64
```

Vector saturating shift left by constant

```
vqshl_n_s8(int8x8_t a, __constrange(0,7) int b);
                                                                // VQSHL.S8 d0,d0,#0
int8x8_t
int16x4_t vqshl_n_s16(int16x4_t a, __constrange(0,15) int b);
                                                                // VQSHL.S16 d0,d0,#0
int32x2_t vqshl_n_s32(int32x2_t a, __constrange(0,31) int b);
                                                                // VQSHL.S32 d0,d0,#0
int64x1_t vqshl_n_s64(int64x1_t a, __constrange(0,63) int b);
                                                                // VQSHL.S64 d0,d0,#0
uint8x8_t vqshl_n_u8(uint8x8_t a, __constrange(0,7) int b);
                                                                // VQSHL.U8 d0,d0,#0
uint16x4_t vgshl_n_u16(uint16x4_t a, __constrange(0.15) int b); // VOSHL.U16 d0.d0.#0
uint32x2_t vqsh1_n_u32(uint32x2_t a, __constrange(0,31) int b); // VQSHL.U32 d0,d0,#0
uint64x1_t vqsh1_n_u64(uint64x1_t a, __constrange(0,63) int b); // VQSHL.U64 d0,d0,#0
int8x16_t vqshlq_n_s8(int8x16_t a, __constrange(0,7) int b);
                                                                // VQSHL.S8 q0,q0,#0
int16x8_t vqshlq_n_s16(int16x8_t a, __constrange(0,15) int b); // VQSHL.S16 q0,q0,#0
int32x4_t vqshlq_n_s32(int32x4_t a, __constrange(0,31) int b); // VQSHL.S32 q0,q0,#0
int64x2_t vqshlq_n_s64(int64x2_t a, __constrange(0,63) int b); // VQSHL.S64 q0,q0,#0
uint8x16_t vgshlg_n_u8(uint8x16_t a, __constrange(0,7) int b);
                                                               // VQSHL.U8 q0,q0,#0
uint16x8_t vqshlq_n_u16(uint16x8_t a, __constrange(0.15) int b); // VQSHL.U16 q0.q0,#0
uint32x4_t vqshlq_n_u32(uint32x4_t a, __constrange(0,31) int b); // VQSHL.U32 q0,q0,#0
uint64x2_t vqshlq_n_u64(uint64x2_t a, __constrange(0,63) int b); // VQSHL.U64 q0,q0,#0
```

Vector signed->unsigned saturating shift left by constant

Vector narrowing saturating shift right by constant

```
int8x8_t    vshrn_n_s16(int16x8_t a, __constrange(1,8) int b);    // VSHRN.I16 d0,q0,#8
int16x4_t    vshrn_n_s32(int32x4_t a, __constrange(1,16) int b);    // VSHRN.I32 d0,q0,#16
int32x2_t    vshrn_n_s64(int64x2_t a, __constrange(1,32) int b);    // VSHRN.I64 d0,q0,#32
uint8x8_t    vshrn_n_u16(uint16x8_t a, __constrange(1,8) int b);    // VSHRN.I16 d0,q0,#8
uint16x4_t    vshrn_n_u32(uint32x4_t a, __constrange(1,16) int b);    // VSHRN.I32 d0,q0,#16
uint32x2_t    vshrn_n_u64(uint64x2_t a, __constrange(1,32) int b);    // VSHRN.I64 d0,q0,#32
```

Vector signed->unsigned narrowing saturating shift right by constant

Vector signed->unsigned rounding narrowing saturating shift right by constant

```
uint8x8_t vqrshrun_n_s16(int16x8_t a, __constrange(1,8) int b); // VQRSHRUN.S16 d0,q0,#8 uint16x4_t vqrshrun_n_s32(int32x4_t a, __constrange(1,16) int b); // VQRSHRUN.S32 d0,q0,#16 uint32x2_t vqrshrun_n_s64(int64x2_t a, __constrange(1,32) int b); // VQRSHRUN.S64 d0,q0,#32
```

Vector narrowing saturating shift right by constant

Vector rounding narrowing shift right by constant

```
int8x8_t vrshrn_n_s16(int16x8_t a, __constrange(1,8) int b);  // VRSHRN.I16 d0,q0,#8
int16x4_t vrshrn_n_s32(int32x4_t a, __constrange(1,16) int b);  // VRSHRN.I32 d0,q0,#16
int32x2_t vrshrn_n_s64(int64x2_t a, __constrange(1,32) int b);  // VRSHRN.I64 d0,q0,#32
uint8x8_t vrshrn_n_u16(uint16x8_t a, __constrange(1,8) int b);  // VRSHRN.I16 d0,q0,#8
uint16x4_t vrshrn_n_u32(uint32x4_t a, __constrange(1,16) int b);  // VRSHRN.I32 d0,q0,#16
uint32x2_t vrshrn_n_u64(uint64x2_t a, __constrange(1,32) int b);  // VRSHRN.I64 d0,q0,#32
```

Vector rounding narrowing saturating shift right by constant

Vector widening shift left by constant

E.3.13 Shifts with insert

These intrinsics provide operations including shifts with insert.

Vector shift right and insert

```
int8x8_t
         vsri_n_s8(int8x8_t a, int8x8_t b, __constrange(1,8) int c);
                                                                             // VSRI.8 d0,d0,#8
int16x4_t vsri_n_s16(int16x4_t a, int16x4_t b, __constrange(1,16) int c);
                                                                             // VSRI.16 d0,d0,#16
int32x2_t vsri_n_s32(int32x2_t a, int32x2_t b, __constrange(1,32) int c);
                                                                             // VSRI.32 d0,d0,#32
int64x1_t vsri_n_s64(int64x1_t a, int64x1_t b, __constrange(1,64) int c);
                                                                             // VSRI.64 d0,d0,#64
uint8x8_t vsri_n_u8(uint8x8_t a, uint8x8_t b, __constrange(1,8) int c);
                                                                             // VSRI.8 d0,d0,#8
uint16x4_t vsri_n_u16(uint16x4_t a, uint16x4_t b, __constrange(1,16) int c);
                                                                             // VSRI.16 d0,d0,#16
uint32x2_t vsri_n_u32(uint32x2_t a, uint32x2_t b, __constrange(1,32) int c);
                                                                             // VSRI.32 d0,d0,#32
uint64x1_t vsri_n_u64(uint64x1_t a, uint64x1_t b, __constrange(1.64) int c); // VSRI.64 d0.d0,#64
poly8x8_t vsri_n_p8(poly8x8_t a, poly8x8_t b, __constrange(1,8) int c);
                                                                             // VSRI.8 d0,d0,#8
poly16x4_t vsri_n_p16(poly16x4_t a, poly16x4_t b, __constrange(1,16) int c);
                                                                             // VSRI.16 d0,d0,#16
int8x16_t vsriq_n_s8(int8x16_t a, int8x16_t b, __constrange(1,8) int c);
                                                                             // VSRI.8 q0,q0,#8
int16x8_t vsrig_n_s16(int16x8_t a, int16x8_t b, __constrange(1,16) int c);
                                                                             // VSRI.16 q0,q0,#16
int32x4_t vsriq_n_s32(int32x4_t a, int32x4_t b, __constrange(1,32) int c);
                                                                             // VSRI.32 q0,q0,#32
int64x2_t vsrig_n_s64(int64x2_t a, int64x2_t b, __constrange(1,64) int c);
                                                                             // VSRI.64 q0,q0,#64
uint8x16_t vsriq_n_u8(uint8x16_t a, uint8x16_t b, __constrange(1,8) int c);
                                                                             // VSRI.8 q0,q0,#8
uint16x8_t vsriq_n_u16(uint16x8_t a, uint16x8_t b, __constrange(1,16) int c); // VSRI.16 q0,q0,#16
uint32x4_t vsriq_n_u32(uint32x4_t a, uint32x4_t b, __constrange(1,32) int c); // VSRI.32 q0,q0,#32
uint64x2_t vsriq_n_u64(uint64x2_t a, uint64x2_t b, __constrange(1,64) int c); // VSRI.64 q0,q0,#64
poly8x16_t vsriq_n_p8(poly8x16_t a, poly8x16_t b, __constrange(1,8) int c); // VSRI.8 q0,q0,#8
poly16x8_t vsriq_n_p16(poly16x8_t a, poly16x8_t b, __constrange(1,16) int c); // VSRI.16 q0,q0,#16
```

Vector shift left and insert

```
int8x8_t
          vsli_n_s8(int8x8_t a, int8x8_t b, __constrange(0,7) int c);
                                                                              // VSLI.8 d0,d0,#0
int16x4_t vsli_n_s16(int16x4_t a, int16x4_t b, __constrange(0,15) int c);
                                                                              // VSLI.16 d0,d0,#0
int32x2_t vsli_n_s32(int32x2_t a, int32x2_t b, __constrange(0,31) int c);
                                                                              // VSLI.32 d0,d0,#0
int64x1_t vsli_n_s64(int64x1_t a, int64x1_t b, __constrange(0,63) int c);
                                                                             // VSLI.64 d0,d0,#0
uint8x8_t vsli_n_u8(uint8x8_t a, uint8x8_t b, __constrange(0,7) int c);
                                                                              // VSLI.8 d0,d0,#0
                                                                             // VSLI.16 d0,d0,#0
uint16x4_t vsli_n_u16(uint16x4_t a, uint16x4_t b, __constrange(0,15) int c);
uint32x2_t vsli_n_u32(uint32x2_t a, uint32x2_t b, __constrange(0,31) int c);
                                                                             // VSLI.32 d0,d0,#0
uint64x1_t vsli_n_u64(uint64x1_t a, uint64x1_t b, __constrange(0,63) int c);
                                                                             // VSLI.64 d0,d0,#0
poly8x8_t vsli_n_p8(poly8x8_t a, poly8x8_t b, __constrange(0,7) int c);
                                                                              // VSLI.8 d0,d0,#0
poly16x4_t vsli_n_p16(poly16x4_t a, poly16x4_t b, __constrange(0,15) int c); // VSLI.16 d0,d0,#0
int8x16_t vsliq_n_s8(int8x16_t a, int8x16_t b, __constrange(0,7) int c);
                                                                              // VSLI.8 q0,q0,#0
int16x8_t vsliq_n_s16(int16x8_t a, int16x8_t b, __constrange(0,15) int c);
                                                                             // VSLI.16 q0,q0,#0
int32x4_t vslig_n_s32(int32x4_t a, int32x4_t b, __constrange(0,31) int c);
                                                                             // VSLI.32 q0,q0,#0
int64x2_t vsliq_n_s64(int64x2_t a, int64x2_t b, __constrange(0,63) int c);
                                                                             // VSLI.64 q0,q0,#0
uint8x16_t vsliq_n_u8(uint8x16_t a, uint8x16_t b, __constrange(0,7) int c);
                                                                             // VSLI.8 q0,q0,#0
uint16x8_t vsliq_n_u16(uint16x8_t a, uint16x8_t b, __constrange(0,15) int c); // VSLI.16 q0,q0,#0
uint32x4_t vsliq_n_u32(uint32x4_t a, uint32x4_t b, __constrange(0,31) int c); // VSLI.32 q0,q0,#0
uint64x2_t vsliq_n_u64(uint64x2_t a, uint64x2_t b, __constrange(0,63) int c); // VSLI.64 q0,q0,#0
poly8x16_t vsliq_n_p8(poly8x16_t a, poly8x16_t b, \_constrange(0,7) int c); // VslI.8 q0,q0,#0
poly16x8_t vsliq_n_p16(poly16x8_t a, poly16x8_t b, __constrange(0.15) int c); // VSLI.16 q0,q0,#0
```

E.3.14 Loads and stores of a single vector

Perform loads and stores of a single vector of some type.

```
uint8x16_t vld1q_u8(__transfersize(16) uint8_t const * ptr);
                                                // VLD1.8 {d0, d1}, [r0]
uint16x8_t vld1q_u16(__transfersize(8) uint16_t const * ptr);
                                                // VLD1.16 {d0, d1}, [r0]
uint32x4_t vld1q_u32(__transfersize(4) uint32_t const * ptr);
                                                // VLD1.32 {d0, d1}, [r0]
uint64x2_t vld1q_u64(__transfersize(2) uint64_t const * ptr);
                                                // VLD1.64 {d0, d1}, [r0]
int8x16_t
           vld1g_s8(__transfersize(16) int8_t const * ptr);
                                                // VLD1.8 {d0, d1}, [r0]
int16x8_t vld1g_s16(__transfersize(8) int16_t const * ptr);
                                                // VLD1.16 {d0, d1}, [r0]
int32x4_t vld1g_s32(__transfersize(4) int32_t const * ptr);
                                                // VLD1.32 {d0, d1}, [r0]
int64x2_t vld1q_s64(__transfersize(2) int64_t const * ptr);
                                                // VLD1.64 {d0, d1}, [r0]
float16x8_t vld1q_f16(__transfersize(8) __fp16 const * ptr);
                                                // VLD1.16 {d0, d1}, [r0]
float32x4_t vld1q_f32(__transfersize(4) float32_t const * ptr);
                                                // VLD1.32 {d0, d1}, [r0]
poly8x16_t vld1q_p8(__transfersize(16) poly8_t const * ptr);
                                                // VLD1.8 {d0, d1}, [r0]
poly16x8_t vld1q_p16(__transfersize(8) poly16_t const * ptr);
                                                // VLD1.16 {d0, d1}, [r0]
uint8x8_t vld1_u8(__transfersize(8) uint8_t const * ptr);
                                                // VLD1.8 {d0}, [r0]
uint16x4_t vld1_u16(__transfersize(4) uint16_t const * ptr);
                                                // VLD1.16 {d0}, [r0]
uint32x2_t vld1_u32(__transfersize(2) uint32_t const * ptr);
                                                // VLD1.32 {d0}, [r0]
uint64x1_t vld1_u64(__transfersize(1) uint64_t const * ptr);
                                                // VLD1.64 {d0}, [r0]
            vld1_s8(__transfersize(8) int8_t const * ptr);
int8x8_t
                                                // VLD1.8 {d0}, [r0]
int16x4_t vld1_s16(__transfersize(4) int16_t const * ptr);
                                                // VLD1.16 {d0}, [r0]
           vld1_s32(__transfersize(2) int32_t const * ptr);
int32x2_t
                                                // VLD1.32 {d0}, [r0]
int64x1_t vld1_s64(__transfersize(1) int64_t const * ptr);
                                                // VLD1.64 {d0}, [r0]
float16x4_t vld1_f16(__transfersize(4) __fp16 const * ptr);
                                                // VLD1.16 {d0}, [r0]
float32x2_t vld1_f32(__transfersize(2) float32_t const * ptr);
                                                // VLD1.32 {d0}, [r0]
poly8x8_t vld1_p8(__transfersize(8) poly8_t const * ptr);
                                                // VLD1.8 {d0}, [r0]
poly16x4_t vld1_p16(__transfersize(4) poly16_t const * ptr);
                                                // VLD1.16 {d0}, [r0]
uint8x16_t vld1q_lane_u8(__transfersize(1) uint8_t const * ptr, uint8x16_t vec, __constrange(0,15) int
lane);
```

```
// VLD1.8 {d0[0]}, [r0]
uint16x8_t vld1q_lane_u16(__transfersize(1) uint16_t const * ptr, uint16x8_t vec, __constrange(0.7)
int lane);
                                                // VLD1.16 {d0[0]}, [r0]
uint32x4_t vld1q_lane_u32(__transfersize(1) uint32_t const * ptr, uint32x4_t vec, __constrange(0,3)
int lane);
                                                // VLD1.32 {d0[0]}, [r0]
uint64x2_t vld1q_lane_u64(__transfersize(1) uint64_t const * ptr, uint64x2_t vec, __constrange(0,1)
int lane);
                                                // VLD1.64 {d0}, [r0]
int8x16_t
           vld1g_lane_s8(__transfersize(1) int8_t const * ptr, int8x16_t vec, __constrange(0.15) int
lane);
                                                // VLD1.8 {d0[0]}, [r0]
int16x8_t
           vld1q_lane_s16(__transfersize(1) int16_t const * ptr, int16x8_t vec, __constrange(0,7) int
lane);
                                                // VLD1.16 {d0[0]}, [r0]
int32x4_t
           vld1q_lane_s32(__transfersize(1) int32_t const * ptr, int32x4_t vec, __constrange(0,3) int
lane);
                                                // VLD1.32 {d0[0]}, [r0]
float16x4_t vld1q_lane_f16(__transfersize(1) __fp16 const * ptr, float16x4_t vec, __constrange(0,3) int
lane);
                                                // VLD1.16 {d0[0]}, [r0]
float16x8_t vld1q_lane_f16(__transfersize(1) __fp16 const * ptr, float16x8_t vec, __constrange(0,7) int
lane);
                                                // VLD1.16 {d0[0]}, [r0]
float32x4_t vld1q_lane_f32(__transfersize(1) float32_t const * ptr, float32x4_t vec, __constrange(0,3)
int lane);
                                                // VLD1.32 {d0[0]}, [r0]
int64x2_t
           vld1q_lane_s64(__transfersize(1) int64_t const * ptr, int64x2_t vec, __constrange(0,1) int
lane);
                                                // VLD1.64 {d0}, [r0]
poly8x16_t vld1q_lane_p8(__transfersize(1) poly8_t const * ptr, poly8x16_t vec, __constrange(0,15) int
lane);
                                                // VLD1.8 {d0[0]}, [r0]
poly16x8_t vld1q_lane_p16(__transfersize(1) poly16_t const * ptr, poly16x8_t vec, __constrange(0,7)
int lane);
                                                // VLD1.16 {d0[0]}, [r0]
           vld1_lane_u8(__transfersize(1) uint8_t const * ptr, uint8x8_t vec, __constrange(0,7) int
uint8x8_t
lane);
                                                // VLD1.8 {d0[0]}, [r0]
uint16x4_t vld1_lane_u16(__transfersize(1) uint16_t const * ptr, uint16x4_t vec, __constrange(0,3) int
lane);
                                                // VLD1.16 {d0[0]}, [r0]
uint32x2_t vld1_lane_u32(__transfersize(1) uint32_t const * ptr, uint32x2_t vec, __constrange(0,1) int
                                                // VLD1.32 {d0[0]}, [r0]
uint64x1_t vld1_lane_u64(__transfersize(1) uint64_t const * ptr, uint64x1_t vec, __constrange(0.0) int
lane);
                                                // VLD1.64 {d0}, [r0]
int8x8_t vld1_lane_s8(__transfersize(1) int8_t const * ptr, int8x8_t vec, __constrange(0,7) int lane);
```

```
// VLD1.8 {d0[0]}, [r0]
int16x4_t
            vld1_lane_s16(__transfersize(1) int16_t const * ptr, int16x4_t vec, __constrange(0,3) int
lane);
                                                // VLD1.16 {d0[0]}, [r0]
int32x2_t
           vld1_lane_s32(__transfersize(1) int32_t const * ptr, int32x2_t vec, __constrange(0,1) int
lane);
                                                // VLD1.32 {d0[0]}, [r0]
float32x2_t vld1_lane_f32(__transfersize(1) float32_t const * ptr, float32x2_t vec, __constrange(0,1)
int lane);
                                                // VLD1.32 {d0[0]}, [r0]
int64x1_t
            vld1_lane_s64(__transfersize(1) int64_t const * ptr, int64x1_t vec, __constrange(0,0) int
lane);
                                                // VLD1.64 {d0}, [r0]
poly8x8_t
            vld1_lane_p8(__transfersize(1) poly8_t const * ptr, poly8x8_t vec, __constrange(0,7) int
lane);
                                                // VLD1.8 {d0[0]}, [r0]
poly16x4_t vld1_lane_p16(__transfersize(1) poly16_t const * ptr, poly16x4_t vec, __constrange(0,3) int
lane);
                                                // VLD1.16 {d0[0]}, [r0]
uint8x16_t vld1q_dup_u8(__transfersize(1) uint8_t const * ptr);
                                                // VLD1.8 {d0[]}, [r0]
uint16x8_t vld1q_dup_u16(__transfersize(1) uint16_t const * ptr);
                                                // VLD1.16 {d0[]}, [r0]
uint32x4_t vld1q_dup_u32(__transfersize(1) uint32_t const * ptr);
                                                // VLD1.32 {d0[]}, [r0]
uint64x2_t vld1q_dup_u64(__transfersize(1) uint64_t const * ptr);
                                                // VLD1.64 {d0}, [r0]
int8x16 t
           vld1q_dup_s8(__transfersize(1) int8_t const * ptr);
                                                // VLD1.8 {d0[]}, [r0]
int16x8 t
           vld1q_dup_s16(__transfersize(1) int16_t const * ptr);
                                                // VLD1.16 {d0[]}, [r0]
int32x4 t
            vld1q_dup_s32(__transfersize(1) int32_t const * ptr);
                                                // VLD1.32 {d0[]}, [r0]
int64x2_t vld1q_dup_s64(__transfersize(1) int64_t const * ptr);
                                                // VLD1.64 {d0}, [r0]
float16x8_t vld1q_dup_f16(__transfersize(1) __fp16 const * ptr);
                                                // VLD1.16 {d0[]}, [r0]
float32x4_t vld1q_dup_f32(__transfersize(1) float32_t const * ptr);
                                                // VLD1.32 {d0[]}, [r0]
poly8x16_t vld1q_dup_p8(__transfersize(1) poly8_t const * ptr);
                                                // VLD1.8 {d0[]}, [r0]
poly16x8_t vld1q_dup_p16(__transfersize(1) poly16_t const * ptr);
                                                // VLD1.16 {d0[]}, [r0]
uint8x8_t vld1_dup_u8(__transfersize(1) uint8_t const * ptr);
                                                // VLD1.8 {d0[]}, [r0]
uint16x4_t vld1_dup_u16(__transfersize(1) uint16_t const * ptr);
                                                // VLD1.16 {d0[]}, [r0]
uint32x2_t vld1_dup_u32(__transfersize(1) uint32_t const * ptr);
                                                // VLD1.32 {d0[]}, [r0]
uint64x1_t vld1_dup_u64(__transfersize(1) uint64_t const * ptr);
```

```
// VLD1.64 {d0}, [r0]
int8x8_t vld1_dup_s8(__transfersize(1) int8_t const * ptr);
                                                // VLD1.8 {d0[]}, [r0]
int16x4_t
           vld1_dup_s16(__transfersize(1) int16_t const * ptr);
                                                // VLD1.16 {d0[]}, [r0]
int32x2_t
           vld1_dup_s32(__transfersize(1) int32_t const * ptr);
                                                // VLD1.32 {d0[]}, [r0]
int64x1_t
           vld1_dup_s64(__transfersize(1) int64_t const * ptr);
                                                // VLD1.64 {d0}, [r0]
float16x4_t vld1_dup_f16(__transfersize(1) __fp16 const * ptr);
                                                // VLD1.16 {d0[]}, [r0]
float32x2_t vld1_dup_f32(__transfersize(1) float32_t const * ptr);
                                                // VLD1.32 {d0[]}, [r0]
poly8x8_t vld1_dup_p8(__transfersize(1) poly8_t const * ptr);
                                                // VLD1.8 {d0[]}, [r0]
poly16x4_t vld1_dup_p16(__transfersize(1) poly16_t const * ptr);
                                                // VLD1.16 {d0[]}, [r0]
void vst1q_u8(__transfersize(16) uint8_t * ptr, uint8x16_t val);
                                                // VST1.8 {d0, d1}, [r0]
void vst1q_u16(__transfersize(8) uint16_t * ptr, uint16x8_t val);
                                                // VST1.16 {d0, d1}, [r0]
void vst1g_u32(__transfersize(4) uint32_t * ptr, uint32x4_t val);
                                                // VST1.32 {d0, d1}, [r0]
void vst1q_u64(__transfersize(2) uint64_t * ptr, uint64x2_t val);
                                                // VST1.64 {d0, d1}, [r0]
void vst1q_s8(__transfersize(16) int8_t * ptr, int8x16_t val);
                                                // VST1.8 {d0, d1}, [r0]
void vst1q_s16(__transfersize(8) int16_t * ptr, int16x8_t val);
                                                // VST1.16 {d0, d1}, [r0]
void vst1q_s32(__transfersize(4) int32_t * ptr, int32x4_t val);
                                                // VST1.32 {d0, d1}, [r0]
void vst1q_s64(__transfersize(2) int64_t * ptr, int64x2_t val);
                                                // VST1.64 {d0, d1}, [r0]
void vst1q_f16(__transfersize(8) __fp16 * ptr, float16x8_t val);
                                                // VST1.16 {d0, d1}, [r0]
void vst1q_f32(__transfersize(4) float32_t * ptr, float32x4_t val);
                                                // VST1.32 {d0, d1}, [r0]
void vst1q_p8(__transfersize(16) poly8_t * ptr, poly8x16_t val);
                                               // VST1.8 {d0, d1}, [r0]
void vstlg_p16(__transfersize(8) poly16_t * ptr, poly16x8_t val);
                                                // VST1.16 {d0, d1}, [r0]
void vst1_u8(__transfersize(8) uint8_t * ptr, uint8x8_t val);
                                                // VST1.8 {d0}, [r0]
void vst1_u16(__transfersize(4) uint16_t * ptr, uint16x4_t val);
                                                // VST1.16 {d0}, [r0]
void vst1_u32(__transfersize(2) uint32_t * ptr, uint32x2_t val);
                                                // VST1.32 {d0}, [r0]
void vst1_u64(__transfersize(1) uint64_t * ptr, uint64x1_t val);
                                                // VST1.64 {d0}, [r0]
void vst1_s8(__transfersize(8) int8_t * ptr, int8x8_t val);
```

```
// VST1.8 {d0}, [r0]
void vst1_s16(__transfersize(4) int16_t * ptr, int16x4_t val);
                                                // VST1.16 {d0}, [r0]
void vst1_s32(__transfersize(2) int32_t * ptr, int32x2_t val);
                                                // VST1.32 {d0}, [r0]
void vst1_s64(__transfersize(1) int64_t * ptr, int64x1_t val);
                                               // VST1.64 {d0}, [r0]
void vst1_f16(__transfersize(4) __fp16 * ptr, float16x4_t val);
                                               // VST1.16 {d0}, [r0]
void vst1_f32(__transfersize(2) float32_t * ptr, float32x2_t val);
                                               // VST1.32 {d0}, [r0]
void vst1_p8(__transfersize(8) poly8_t * ptr, poly8x8_t val);
                                               // VST1.8 {d0}, [r0]
void vst1_p16(__transfersize(4) poly16_t * ptr, poly16x4_t val);
                                                // VST1.16 {d0}, [r0]
void vstlq_lane_u8(__transfersize(1) uint8_t * ptr, uint8x16_t val, __constrange(0,15) int lane);
                                               // VST1.8 {d0[0]}, [r0]
void vst1g_lane_u16(__transfersize(1) uint16_t * ptr, uint16x8_t val, __constrange(0.7) int lane);
                                                // VST1.16 {d0[0]}, [r0]
void vst1q_lane_u32(__transfersize(1) uint32_t * ptr, uint32x4_t val, __constrange(0,3) int lane);
                                                // VST1.32 {d0[0]}, [r0]
void vst1q_lane_u64(__transfersize(1) uint64_t * ptr, uint64x2_t val, __constrange(0,1) int lane);
                                               // VST1.64 {d0}, [r0]
void vstlq_lane_s8(__transfersize(1) int8_t * ptr, int8x16_t val, __constrange(0,15) int lane);
                                               // VST1.8 {d0[0]}, [r0]
void vstlq_lane_s16(__transfersize(1) int16_t * ptr, int16x8_t val, __constrange(0,7) int lane);
                                               // VST1.16 {d0[0]}, [r0]
void vst1q_lane_s32(__transfersize(1) int32_t * ptr, int32x4_t val, __constrange(0,3) int lane);
                                               // VST1.32 {d0[0]}, [r0]
void vstlq_lane_s64(__transfersize(1) int64_t * ptr, int64x2_t val, __constrange(0,1) int lane);
                                               // VST1.64 {d0}, [r0]
void vst1q_lane_f16(__transfersize(1) __fp16 * ptr, float16x8_t val, __constrange(0,7) int lane);
                                                // VST1.16 {d0[0]}, [r0]
void vst1q_lane_f32(__transfersize(1) float32_t * ptr, float32x4_t val, __constrange(0,3) int lane);
                                                // VST1.32 {d0[0]}, [r0]
void vst1q_lane_p8(__transfersize(1) poly8_t * ptr, poly8x16_t val, __constrange(0,15) int lane);
                                                // VST1.8 {d0[0]}, [r0]
void vst1q_lane_p16(__transfersize(1) poly16_t * ptr, poly16x8_t val, __constrange(0,7) int lane);
                                               // VST1.16 {d0[0]}, [r0]
void vst1_lane_u8(__transfersize(1) uint8_t * ptr, uint8x8_t val, __constrange(0,7) int lane);
                                               // VST1.8 {d0[0]}, [r0]
void vst1_lane_u16(__transfersize(1) uint16_t * ptr, uint16x4_t val, __constrange(0,3) int lane);
                                               // VST1.16 {d0[0]}, [r0]
void vst1_lane_u32(__transfersize(1) uint32_t * ptr, uint32x2_t val, __constrange(0,1) int lane);
                                               // VST1.32 {d0[0]}, [r0]
void vst1_lane_u64(__transfersize(1) uint64_t * ptr, uint64x1_t val, __constrange(0,0) int lane);
                                                // VST1.64 {d0}, [r0]
void vst1_lane_s8(__transfersize(1) int8_t * ptr, int8x8_t val, __constrange(0,7) int lane);
                                                // VST1.8 {d0[0]}, [r0]
void vst1_lane_s16(__transfersize(1) int16_t * ptr, int16x4_t val, __constrange(0,3) int lane);
```

E.3.15 Loads and stores of an N-element structure

struct int16x4x2_t

These intrinsics load or store an *n*-element structure. The array structures are defined similarly, for example the int16x4x2_t structure is defined as:

```
int16x4_t val[2];
                       };
uint8x16x2_t vld2q_u8(__transfersize(32) uint8_t const * ptr);
                                                // VLD2.8 {d0, d2}, [r0]
uint16x8x2_t vld2q_u16(__transfersize(16) uint16_t const * ptr);
                                                // VLD2.16 {d0, d2}, [r0]
uint32x4x2_t v1d2q_u32(__transfersize(8) uint32_t const * ptr);
                                                // VLD2.32 {d0, d2}, [r0]
int8x16x2_t vld2q_s8(__transfersize(32) int8_t const * ptr);
                                                // VLD2.8 {d0, d2}, [r0]
int16x8x2_t vld2q_s16(__transfersize(16) int16_t const * ptr);
                                                // VLD2.16 {d0, d2}, [r0]
int32x4x2_t vld2g_s32(__transfersize(8) int32_t const * ptr);
                                                // VLD2.32 {d0, d2}, [r0]
float16x8x2_t vld2g_f16(__transfersize(16) __fp16 const * ptr);
                                                // VLD2.16 {d0, d2}, [r0]
float32x4x2_t vld2q_f32(__transfersize(8) float32_t const * ptr);
                                                // VLD2.32 {d0, d2}, [r0]
poly8x16x2_t vld2q_p8(__transfersize(32) poly8_t const * ptr);
                                                // VLD2.8 {d0, d2}, [r0]
poly16x8x2_t vld2q_p16(__transfersize(16) poly16_t const * ptr);
                                                // VLD2.16 {d0, d2}, [r0]
uint8x8x2_t vld2_u8(__transfersize(16) uint8_t const * ptr);
                                                // VLD2.8 {d0, d1}, [r0]
uint16x4x2_t vld2_u16(__transfersize(8) uint16_t const * ptr);
                                                // VLD2.16 {d0, d1}, [r0]
uint32x2x2_t vld2_u32(__transfersize(4) uint32_t const * ptr);
                                                // VLD2.32 {d0, d1}, [r0]
```

```
uint64x1x2_t vld2_u64(__transfersize(2) uint64_t const * ptr);
                                                // VLD1.64 {d0, d1}, [r0]
int8x8x2_t vld2_s8(__transfersize(16) int8_t const * ptr);
                                                // VLD2.8 {d0, d1}, [r0]
int16x4x2_t vld2_s16(__transfersize(8) int16_t const * ptr);
                                                // VLD2.16 {d0, d1}, [r0]
int32x2x2_t v1d2_s32(__transfersize(4) int32_t const * ptr);
                                                // VLD2.32 {d0, d1}, [r0]
int64x1x2_t vld2_s64(__transfersize(2) int64_t const * ptr);
                                                // VLD1.64 {d0, d1}, [r0]
float16x4x2_t vld2_f16(__transfersize(8) __fp16 const * ptr);
                                                // VLD2.16 {d0, d1}, [r0]
float32x2x2_t vld2_f32(__transfersize(4) float32_t const * ptr);
                                                // VLD2.32 {d0, d1}, [r0]
poly8x8x2_t vld2_p8(__transfersize(16) poly8_t const * ptr);
                                                // VLD2.8 {d0, d1}, [r0]
poly16x4x2_t vld2_p16(__transfersize(8) poly16_t const * ptr);
                                                // VLD2.16 {d0, d1}, [r0]
uint8x16x3_t vld3q_u8(__transfersize(48) uint8_t const * ptr);
                                                // VLD3.8 {d0, d2, d4}, [r0]
uint16x8x3_t vld3q_u16(__transfersize(24) uint16_t const * ptr);
                                                // VLD3.16 {d0, d2, d4}, [r0]
uint32x4x3_t vld3q_u32(__transfersize(12) uint32_t const * ptr);
                                                // VLD3.32 {d0, d2, d4}, [r0]
int8x16x3_t vld3q_s8(__transfersize(48) int8_t const * ptr);
                                                // VLD3.8 {d0, d2, d4}, [r0]
int16x8x3_t vld3q_s16(__transfersize(24) int16_t const * ptr);
                                                // VLD3.16 {d0, d2, d4}, [r0]
int32x4x3_t vld3q_s32(__transfersize(12) int32_t const * ptr);
                                                // VLD3.32 {d0, d2, d4}, [r0]
float16x8x3_t vld3q_f16(__transfersize(24) __fp16 const * ptr);
                                                // VLD3.16 {d0, d2, d4}, [r0]
float32x4x3_t vld3q_f32(__transfersize(12) float32_t const * ptr);
                                                // VLD3.32 {d0, d2, d4}, [r0]
poly8x16x3_t vld3q_p8(__transfersize(48) poly8_t const * ptr);
                                                // VLD3.8 {d0, d2, d4}, [r0]
poly16x8x3_t vld3q_p16(__transfersize(24) poly16_t const * ptr);
                                                // VLD3.16 {d0, d2, d4}, [r0]
uint8x8x3_t vld3_u8(__transfersize(24) uint8_t const * ptr);
                                                // VLD3.8 {d0, d1, d2}, [r0]
uint16x4x3_t vld3_u16(__transfersize(12) uint16_t const * ptr);
                                                // VLD3.16 {d0, d1, d2}, [r0]
uint32x2x3_t vld3_u32(__transfersize(6) uint32_t const * ptr);
                                                // VLD3.32 {d0, d1, d2}, [r0]
uint64x1x3_t v1d3_u64(__transfersize(3) uint64_t const * ptr);
                                                // VLD1.64 {d0, d1, d2}, [r0]
int8x8x3_t vld3_s8(__transfersize(24) int8_t const * ptr);
                                                // VLD3.8 {d0, d1, d2}, [r0]
int16x4x3_t vld3_s16(__transfersize(12) int16_t const * ptr);
                                                // VLD3.16 {d0, d1, d2}, [r0]
```

```
int32x2x3_t vld3_s32(__transfersize(6) int32_t const * ptr);
                                                // VLD3.32 {d0, d1, d2}, [r0]
int64x1x3_t v1d3_s64(__transfersize(3) int64_t const * ptr);
                                                // VLD1.64 {d0, d1, d2}, [r0]
float16x4x3_t vld3_f16(__transfersize(12) __fp16 const * ptr);
                                                // VLD3.16 {d0, d1, d2}, [r0]
float32x2x3_t vld3_f32(__transfersize(6) float32_t const * ptr);
                                                // VLD3.32 {d0, d1, d2}, [r0]
poly8x8x3_t vld3_p8(__transfersize(24) poly8_t const * ptr);
                                                // VLD3.8 {d0, d1, d2}, [r0]
poly16x4x3_t vld3_p16(__transfersize(12) poly16_t const * ptr);
                                                // VLD3.16 {d0, d1, d2}, [r0]
uint8x16x4_t vld4q_u8(__transfersize(64) uint8_t const * ptr);
                                                // VLD4.8 {d0, d2, d4, d6}, [r0]
uint16x8x4_t vld4q_u16(__transfersize(32) uint16_t const * ptr);
                                                // VLD4.16 {d0, d2, d4, d6}, [r0]
uint32x4x4_t vld4q_u32(__transfersize(16) uint32_t const * ptr);
                                                // VLD4.32 {d0, d2, d4, d6}, [r0]
int8x16x4_t vld4q_s8(__transfersize(64) int8_t const * ptr);
                                                // VLD4.8 {d0, d2, d4, d6}, [r0]
int16x8x4_t vld4q_s16(__transfersize(32) int16_t const * ptr);
                                                // VLD4.16 {d0, d2, d4, d6}, [r0]
int32x4x4_t vld4q_s32(__transfersize(16) int32_t const * ptr);
                                                // VLD4.32 {d0, d2, d4, d6}, [r0]
float16x8x4_t vld4q_f16(__transfersize(32) __fp16 const * ptr);
                                                // VLD4.16 {d0, d2, d4, d6}, [r0]
float32x4x4_t vld4q_f32(__transfersize(16) float32_t const * ptr);
                                                // VLD4.32 {d0, d2, d4, d6}, [r0]
poly8x16x4_t vld4q_p8(__transfersize(64) poly8_t const * ptr);
                                                // VLD4.8 {d0, d2, d4, d6}, [r0]
poly16x8x4_t vld4q_p16(__transfersize(32) poly16_t const * ptr);
                                                // VLD4.16 {d0, d2, d4, d6}, [r0]
uint8x8x4_t v1d4_u8(__transfersize(32) uint8_t const * ptr);
                                                // VLD4.8 {d0, d1, d2, d3}, [r0]
uint16x4x4_t vld4_u16(__transfersize(16) uint16_t const * ptr);
                                                // VLD4.16 {d0, d1, d2, d3}, [r0]
uint32x2x4_t vld4_u32(__transfersize(8) uint32_t const * ptr);
                                                // VLD4.32 {d0, d1, d2, d3}, [r0]
uint64x1x4_t vld4_u64(__transfersize(4) uint64_t const * ptr);
                                                // VLD1.64 {d0, d1, d2, d3}, [r0]
int8x8x4_t vld4_s8(__transfersize(32) int8_t const * ptr);
                                                // VLD4.8 {d0, d1, d2, d3}, [r0]
int16x4x4_t vld4_s16(__transfersize(16) int16_t const * ptr);
                                                // VLD4.16 {d0, d1, d2, d3}, [r0]
int32x2x4_t vld4_s32(__transfersize(8) int32_t const * ptr);
                                                // VLD4.32 {d0, d1, d2, d3}, [r0]
int64x1x4_t vld4_s64(__transfersize(4) int64_t const * ptr);
                                                // VLD1.64 {d0, d1, d2, d3}, [r0]
float16x4x4_t vld4_f16(__transfersize(16) __fp16 const * ptr);
                                                // VLD4.16 {d0, d1, d2, d3}, [r0]
```

```
float32x2x4_t vld4_f32(__transfersize(8) float32_t const * ptr);
                                                // VLD4.32 {d0, d1, d2, d3}, [r0]
poly8x8x4_t vld4_p8(__transfersize(32) poly8_t const * ptr);
                                                // VLD4.8 {d0, d1, d2, d3}, [r0]
poly16x4x4_t vld4_p16(__transfersize(16) poly16_t const * ptr);
                                                // VLD4.16 {d0, d1, d2, d3}, [r0]
uint8x8x2_t vld2_dup_u8(__transfersize(2) uint8_t const * ptr);
                                                // VLD2.8 {d0[], d1[]}, [r0]
uint16x4x2_t vld2_dup_u16(__transfersize(2) uint16_t const * ptr);
                                                // VLD2.16 {d0[], d1[]}, [r0]
uint32x2x2_t vld2_dup_u32(__transfersize(2) uint32_t const * ptr);
                                                // VLD2.32 {d0[], d1[]}, [r0]
uint64x1x2_t vld2_dup_u64(__transfersize(2) uint64_t const * ptr);
                                                // VLD1.64 {d0, d1}, [r0]
int8x8x2_t vld2_dup_s8(__transfersize(2) int8_t const * ptr);
                                                // VLD2.8 {d0[], d1[]}, [r0]
int16x4x2_t vld2_dup_s16(__transfersize(2) int16_t const * ptr);
                                                // VLD2.16 {d0[], d1[]}, [r0]
int32x2x2_t v1d2_dup_s32(__transfersize(2) int32_t const * ptr);
                                                // VLD2.32 {d0[], d1[]}, [r0]
int64x1x2_t vld2_dup_s64(__transfersize(2) int64_t const * ptr);
                                                // VLD1.64 {d0, d1}, [r0]
float16x4x2_t vld2_dup_f16(__transfersize(2) __fp16 const * ptr);
                                                // VLD2.16 {d0[], d1[]}, [r0]
float32x2x2_t vld2_dup_f32(__transfersize(2) float32_t const * ptr);
                                                // VLD2.32 {d0[], d1[]}, [r0]
poly8x8x2_t vld2_dup_p8(__transfersize(2) poly8_t const * ptr);
                                                // VLD2.8 {d0[], d1[]}, [r0]
poly16x4x2_t vld2_dup_p16(__transfersize(2) poly16_t const * ptr);
                                                // VLD2.16 {d0[], d1[]}, [r0]
uint8x8x3_t vld3_dup_u8(__transfersize(3) uint8_t const * ptr);
                                                // VLD3.8 {d0[], d1[], d2[]}, [r0]
uint16x4x3_t vld3_dup_u16(__transfersize(3) uint16_t const * ptr);
                                                // VLD3.16 {d0[], d1[], d2[]}, [r0]
uint32x2x3_t vld3_dup_u32(__transfersize(3) uint32_t const * ptr);
                                                // VLD3.32 {d0[], d1[], d2[]}, [r0]
uint64x1x3_t vld3_dup_u64(__transfersize(3) uint64_t const * ptr);
                                                // VLD1.64 {d0, d1, d2}, [r0]
int8x8x3_t vld3_dup_s8(__transfersize(3) int8_t const * ptr);
                                                // VLD3.8 {d0[], d1[], d2[]}, [r0]
int16x4x3_t vld3_dup_s16(__transfersize(3) int16_t const * ptr);
                                                // VLD3.16 {d0[], d1[], d2[]}, [r0]
int32x2x3_t vld3_dup_s32(__transfersize(3) int32_t const * ptr);
                                                // VLD3.32 {d0[], d1[], d2[]}, [r0]
int64x1x3_t vld3_dup_s64(__transfersize(3) int64_t const * ptr);
                                                // VLD1.64 {d0, d1, d2}, [r0]
float16x4x3_t vld3_dup_f16(__transfersize(3) __fp16 const * ptr);
                                                // VLD3.16 {d0[], d1[], d2[]}, [r0]
float32x2x3_t vld3_dup_f32(__transfersize(3) float32_t const * ptr);
                                                // VLD3.32 {d0[], d1[], d2[]}, [r0]
```

```
poly8x8x3_t vld3_dup_p8(__transfersize(3) poly8_t const * ptr);
                                                // VLD3.8 {d0[], d1[], d2[]}, [r0]
poly16x4x3_t vld3_dup_p16(__transfersize(3) poly16_t const * ptr);
                                                // VLD3.16 {d0[], d1[], d2[]}, [r0]
uint8x8x4_t vld4_dup_u8(__transfersize(4) uint8_t const * ptr);
                                                // VLD4.8 {d0[], d1[], d2[], d3[]}, [r0]
uint16x4x4_t vld4_dup_u16(__transfersize(4) uint16_t const * ptr);
                                                // VLD4.16 {d0[], d1[], d2[], d3[]}, [r0]
uint32x2x4_t vld4_dup_u32(__transfersize(4) uint32_t const * ptr);
                                                // VLD4.32 {d0[], d1[], d2[], d3[]}, [r0]
uint64x1x4_t vld4_dup_u64(__transfersize(4) uint64_t const * ptr);
                                                // VLD1.64 {d0, d1, d2, d3}, [r0]
int8x8x4_t vld4_dup_s8(__transfersize(4) int8_t const * ptr);
                                                // VLD4.8 {d0[], d1[], d2[], d3[]}, [r0]
int16x4x4_t vld4_dup_s16(__transfersize(4) int16_t const * ptr);
                                                // VLD4.16 {d0[], d1[], d2[], d3[]}, [r0]
int32x2x4_t vld4_dup_s32(__transfersize(4) int32_t const * ptr);
                                                // VLD4.32 {d0[], d1[], d2[], d3[]}, [r0]
int64x1x4_t vld4_dup_s64(__transfersize(4) int64_t const * ptr);
                                                // VLD1.64 {d0, d1, d2, d3}, [r0]
float16x4x4_t vld4_dup_f16(__transfersize(4) __fp16 const * ptr);
                                                // VLD4.16 {d0[], d1[], d2[], d3[]}, [r0]
float32x2x4_t vld4_dup_f32(__transfersize(4) float32_t const * ptr);
                                                // VLD4.32 {d0[], d1[], d2[], d3[]}, [r0]
poly8x8x4_t vld4_dup_p8(__transfersize(4) poly8_t const * ptr);
                                                // VLD4.8 {d0[], d1[], d2[], d3[]}, [r0]
poly16x4x4_t vld4_dup_p16(__transfersize(4) poly16_t const * ptr);
                                                // VLD4.16 {d0[], d1[], d2[], d3[]}, [r0]
uint16x8x2_t vld2q_lane_u16(__transfersize(2) uint16_t const * ptr, uint16x8x2_t src,
__constrange(0,7) int lane);
                                                // VLD2.16 {d0[0], d2[0]}, [r0]
uint32x4x2_t vld2q_lane_u32(__transfersize(2) uint32_t const * ptr, uint32x4x2_t src,
__constrange(0,3) int lane);
                                                // VLD2.32 {d0[0], d2[0]}, [r0]
int16x8x2_t vld2q_lane_s16(__transfersize(2) int16_t const * ptr, int16x8x2_t src, __constrange(0,7)
int lane);
                                                // VLD2.16 {d0[0], d2[0]}, [r0]
int32x4x2_t vld2q_lane_s32(__transfersize(2) int32_t const * ptr, int32x4x2_t src, __constrange(0,3)
int lane);
                                                // VLD2.32 {d0[0], d2[0]}, [r0]
float16x8x2_t vld2q_lane_f16(__transfersize(2) __fp16 const * ptr, float16x8x2_t src, __constrange(0,7)
int lane);
                                                // VLD2.16 {d0[0], d2[0]}, [r0]
float32x4x2_t vld2q_lane_f32(__transfersize(2) float32_t const * ptr, float32x4x2_t src,
__constrange(0,3) int lane);
                                                // VLD2.32 {d0[0], d2[0]}, [r0]
poly16x8x2_t vld2q_lane_p16(__transfersize(2) poly16_t const * ptr, poly16x8x2_t src,
__constrange(0,7) int lane);
                                                // VLD2.16 {d0[0], d2[0]}, [r0]
uint8x8x2_t vld2_lane_u8(__transfersize(2) uint8_t const * ptr, uint8x8x2_t src, __constrange(0,7) int
```

```
lane);
                                                // VLD2.8 {d0[0], d1[0]}, [r0]
uint16x4x2_t vld2_lane_u16(__transfersize(2) uint16_t const * ptr, uint16x4x2_t src, __constrange(0,3)
int lane);
                                                // VLD2.16 {d0[0], d1[0]}, [r0]
uint32x2x2_t vld2_lane_u32(__transfersize(2) uint32_t const * ptr, uint32x2x2_t src, __constrange(0,1)
int lane):
                                                // VLD2.32 {d0[0], d1[0]}, [r0]
int8x8x2_t vld2_lane_s8(__transfersize(2) int8_t const * ptr, int8x8x2_t src, __constrange(0,7) int
lane);
                                                // VLD2.8 {d0[0], d1[0]}, [r0]
int16x4x2_t vld2_lane_s16(__transfersize(2) int16_t const * ptr, int16x4x2_t src, __constrange(0,3) int
lane);
                                                // VLD2.16 {d0[0], d1[0]}, [r0]
int32x2x2_t vld2_lane_s32(__transfersize(2) int32_t const * ptr, int32x2x2_t src, __constrange(0,1) int
lane);
                                                // VLD2.32 {d0[0], d1[0]}, [r0]
float16x4x2_t vld2_lane_f32(__transfersize(2) __fp16 const * ptr, float16x4x2_t src, __constrange(0,3)
int lane);
                                                // VLD2.16 {d0[0], d1[0]}, [r0]
float32x2x2_t vld2_lane_f32(__transfersize(2) float32_t const * ptr, float32x2x2_t src,
__constrange(0,1) int lane);
                                                // VLD2.32 {d0[0], d1[0]}, [r0]
poly8x8x2_t vld2_lane_p8(__transfersize(2) poly8_t const * ptr, poly8x8x2_t src, __constrange(0,7) int
lane);
                                                // VLD2.8 {d0[0], d1[0]}, [r0]
poly16x4x2_t vld2_lane_p16(__transfersize(2) poly16_t const * ptr, poly16x4x2_t src, __constrange(0,3)
int lane);
                                                // VLD2.16 {d0[0], d1[0]}, [r0]
uint16x8x3_t vld3q_lane_u16(__transfersize(3) uint16_t const * ptr, uint16x8x3_t src,
__constrange(0,7) int lane);
                                                // VLD3.16 {d0[0], d2[0], d4[0]}, [r0]
uint32x4x3_t vld3q_lane_u32(__transfersize(3) uint32_t const * ptr, uint32x4x3_t src,
__constrange(0,3) int lane);
                                                // VLD3.32 {d0[0], d2[0], d4[0]}, [r0]
int16x8x3_t vld3q_lane_s16(__transfersize(3) int16_t const * ptr, int16x8x3_t src, __constrange(0,7)
int lane);
                                                // VLD3.16 {d0[0], d2[0], d4[0]}, [r0]
int32x4x3_t vld3q_lane_s32(__transfersize(3) int32_t const * ptr, int32x4x3_t src, __constrange(0,3)
int lane);
                                                // VLD3.32 {d0[0], d2[0], d4[0]}, [r0]
float16x8x3_t vld3q_lane_f32(__transfersize(3) __fp16 const * ptr, float16x8x3_t src, __constrange(0,7)
int lane):
                                                // VLD3.16 {d0[0], d2[0], d4[0]}, [r0]
float32x4x3_t vld3q_lane_f32(__transfersize(3) float32_t const * ptr, float32x4x3_t src,
__constrange(0,3) int lane);
                                                // VLD3.32 {d0[0], d2[0], d4[0]}, [r0]
poly16x8x3_t vld3q_lane_p16(__transfersize(3) poly16_t const * ptr, poly16x8x3_t src,
__constrange(0,7) int lane);
                                                // VLD3.16 {d0[0], d2[0], d4[0]}, [r0]
```

```
uint8x8x3_t vld3_lane_u8(__transfersize(3) uint8_t const * ptr, uint8x8x3_t src, __constrange(0,7) int
lane);
                                                // VLD3.8 {d0[0], d1[0], d2[0]}, [r0]
uint16x4x3_t vld3_lane_u16(__transfersize(3) uint16_t const * ptr, uint16x4x3_t src, __constrange(0,3)
int lane);
                                                // VLD3.16 {d0[0], d1[0], d2[0]}, [r0]
uint32x2x3_t vld3_lane_u32(__transfersize(3) uint32_t const * ptr, uint32x2x3_t src, __constrange(0,1)
int lane);
                                                // VLD3.32 {d0[0], d1[0], d2[0]}, [r0]
int8x8x3_t vld3_lane_s8(__transfersize(3) int8_t const * ptr, int8x8x3_t src, __constrange(0,7) int
lane);
                                                // VLD3.8 {d0[0], d1[0], d2[0]}, [r0]
int16x4x3_t vld3_lane_s16(__transfersize(3) int16_t const * ptr, int16x4x3_t src, __constrange(0,3) int
lane);
                                                // VLD3.16 {d0[0], d1[0], d2[0]}, [r0]
int32x2x3_t vld3_lane_s32(__transfersize(3) int32_t const * ptr, int32x2x3_t src, __constrange(0.1) int
                                                // VLD3.32 {d0[0], d1[0], d2[0]}, [r0]
float16x4x3_t vld3_lane_f16(__transfersize(3) __fp16 const * ptr, float16x4x3_t src, __constrange(0,3)
int lane);
                                               // VLD3.16 {d0[0], d1[0], d2[0]}, [r0]
float32x2x3_t vld3_lane_f32(__transfersize(3) float32_t const * ptr, float32x2x3_t src,
__constrange(0,1) int lane);
                                                // VLD3.32 {d0[0], d1[0], d2[0]}, [r0]
poly8x8x3_t vld3_lane_p8(__transfersize(3) poly8_t const * ptr, poly8x8x3_t src, __constrange(0,7) int
lane);
                                                // VLD3.8 {d0[0], d1[0], d2[0]}, [r0]
poly16x4x3_t vld3_lane_p16(__transfersize(3) poly16_t const * ptr, poly16x4x3_t src, __constrange(0,3)
int lane);
                                                // VLD3.16 {d0[0], d1[0], d2[0]}, [r0]
uint16x8x4_t vld4g_lane_u16(__transfersize(4) uint16_t const * ptr, uint16x8x4_t src,
__constrange(0,7) int lane);
                                                // VLD4.16 {d0[0], d2[0], d4[0], d6[0]}, [r0]
uint32x4x4_t vld4q_lane_u32(__transfersize(4) uint32_t const * ptr, uint32x4x4_t src,
__constrange(0,3) int lane);
                                                // VLD4.32 {d0[0], d2[0], d4[0], d6[0]}, [r0]
int16x8x4_t vld4q_lane_s16(__transfersize(4) int16_t const * ptr, int16x8x4_t src, __constrange(0,7)
int lane);
                                                // VLD4.16 {d0[0], d2[0], d4[0], d6[0]}, [r0]
int32x4x4_t vld4q_lane_s32(__transfersize(4) int32_t const * ptr, int32x4x4_t src, __constrange(0.3)
int lane);
                                                // VLD4.32 {d0[0], d2[0], d4[0], d6[0]}, [r0]
float16x8x4_t vld4q_lane_f32(__transfersize(4) __fp16 const * ptr, float16x8x4_t src, __constrange(0,7)
int lane);
                                                // VLD4.16 {d0[0], d2[0], d4[0], d6[0]}, [r0]
float32x4x4_t vld4q_lane_f32(__transfersize(4) float32_t const * ptr, float32x4x4_t src,
__constrange(0,3) int lane);
                                                // VLD4.32 {d0[0], d2[0], d4[0], d6[0]}, [r0]
poly16x8x4_t vld4g_lane_p16(__transfersize(4) poly16_t const * ptr, poly16x8x4_t src,
__constrange(0,7) int lane);
```

```
// VLD4.16 {d0[0], d2[0], d4[0], d6[0]}, [r0]
uint8x8x4_t vld4_lane_u8(__transfersize(4) uint8_t const * ptr, uint8x8x4_t src, __constrange(0.7) int
lane);
                                                // VLD4.8 {d0[0], d1[0], d2[0], d3[0]}, [r0]
uint16x4x4_t vld4_lane_u16(__transfersize(4) uint16_t const * ptr, uint16x4x4_t src, __constrange(0,3)
int lane);
                                                // VLD4.16 {d0[0], d1[0], d2[0], d3[0]}, [r0]
uint32x2x4_t vld4_lane_u32(__transfersize(4) uint32_t const * ptr, uint32x2x4_t src, __constrange(0,1)
int lane);
                                                // VLD4.32 {d0[0], d1[0], d2[0], d3[0]}, [r0]
int8x8x4_t vld4_lane_s8(__transfersize(4) int8_t const * ptr, int8x8x4_t src, __constrange(0,7) int
lane);
                                                // VLD4.8 {d0[0], d1[0], d2[0], d3[0]}, [r0]
int16x4x4_t vld4_lane_s16(__transfersize(4) int16_t const * ptr, int16x4x4_t src, __constrange(0,3) int
lane);
                                                // VLD4.16 {d0[0], d1[0], d2[0], d3[0]}, [r0]
int32x2x4_t vld4_lane_s32(__transfersize(4) int32_t const * ptr, int32x2x4_t src, __constrange(0,1) int
lane);
                                                // VLD4.32 {d0[0], d1[0], d2[0], d3[0]}, [r0]
float16x4x4_t vld4_lane_f16(__transfersize(4) __fp16 const * ptr, float16x4x4_t src, __constrange(0,3)
int lane);
                                                // VLD4.16 {d0[0], d1[0], d2[0], d3[0]}, [r0]
float32x2x4_t vld4_lane_f32(__transfersize(4) float32_t const * ptr, float32x2x4_t src,
__constrange(0,1) int lane);
                                                // VLD4.32 {d0[0], d1[0], d2[0], d3[0]}, [r0]
poly8x8x4_t vld4_lane_p8(__transfersize(4) poly8_t const * ptr, poly8x8x4_t src, __constrange(0,7) int
lane);
                                                // VLD4.8 {d0[0], d1[0], d2[0], d3[0]}, [r0]
poly16x4x4_t vld4_lane_p16(__transfersize(4) poly16_t const * ptr, poly16x4x4_t src, __constrange(0,3)
int lane);
                                                // VLD4.16 {d0[0], d1[0], d2[0], d3[0]}, [r0]
void vst2g_u8(__transfersize(32) uint8_t * ptr, uint8x16x2_t val);
                                                // VST2.8 {d0, d2}, [r0]
void vst2q_u16(__transfersize(16) uint16_t * ptr, uint16x8x2_t val);
                                                // VST2.16 {d0, d2}, [r0]
void vst2q_u32(__transfersize(8) uint32_t * ptr, uint32x4x2_t val);
                                                // VST2.32 {d0, d2}, [r0]
void vst2g_s8(__transfersize(32) int8_t * ptr, int8x16x2_t val);
                                                // VST2.8 {d0, d2}, [r0]
void vst2g_s16(__transfersize(16) int16_t * ptr, int16x8x2_t val);
                                                // VST2.16 {d0, d2}, [r0]
void vst2q_s32(__transfersize(8) int32_t * ptr, int32x4x2_t val);
                                                // VST2.32 {d0, d2}, [r0]
void vst2q_f16(__transfersize(16) __fp16 * ptr, float16x8x2_t val);
                                                // VST2.16 {d0, d2}, [r0]
void vst2q_f32(__transfersize(8) float32_t * ptr, float32x4x2_t val);
                                                // VST2.32 {d0, d2}, [r0]
void vst2q_p8(__transfersize(32) poly8_t * ptr, poly8x16x2_t val);
                                                // VST2.8 {d0, d2}, [r0]
void vst2q_p16(__transfersize(16) poly16_t * ptr, poly16x8x2_t val);
```

```
// VST2.16 {d0, d2}, [r0]
void vst2_u8(__transfersize(16) uint8_t * ptr, uint8x8x2_t val);
                                                // VST2.8 {d0, d1}, [r0]
void vst2_u16(__transfersize(8) uint16_t * ptr, uint16x4x2_t val);
                                                // VST2.16 {d0, d1}, [r0]
void vst2_u32(__transfersize(4) uint32_t * ptr, uint32x2x2_t val);
                                               // VST2.32 {d0, d1}, [r0]
void vst2_u64(__transfersize(2) uint64_t * ptr, uint64x1x2_t val);
                                                // VST1.64 {d0, d1}, [r0]
void vst2_s8(__transfersize(16) int8_t * ptr, int8x8x2_t val);
                                                // VST2.8 {d0, d1}, [r0]
void vst2_s16(__transfersize(8) int16_t * ptr, int16x4x2_t val);
                                                // VST2.16 {d0, d1}, [r0]
void vst2_s32(__transfersize(4) int32_t * ptr, int32x2x2_t val);
                                                // VST2.32 {d0, d1}, [r0]
void vst2_s64(__transfersize(2) int64_t * ptr, int64x1x2_t val);
                                                // VST1.64 {d0, d1}, [r0]
void vst2_f16(__transfersize(8) __fp16 * ptr, float16x4x2_t val);
                                                // VST2.16 {d0, d1}, [r0]
void vst2_f32(__transfersize(4) float32_t * ptr, float32x2x2_t val);
                                                // VST2.32 {d0, d1}, [r0]
void vst2_p8(__transfersize(16) poly8_t * ptr, poly8x8x2_t val);
                                                // VST2.8 {d0, d1}, [r0]
void vst2_p16(__transfersize(8) poly16_t * ptr, poly16x4x2_t val);
                                               // VST2.16 {d0, d1}, [r0]
void vst3q_u8(__transfersize(48) uint8_t * ptr, uint8x16x3_t val);
                                                // VST3.8 {d0, d2, d4}, [r0]
void vst3q_u16(__transfersize(24) uint16_t * ptr, uint16x8x3_t val);
                                                // VST3.16 {d0, d2, d4}, [r0]
void vst3q_u32(__transfersize(12) uint32_t * ptr, uint32x4x3_t val);
                                                // VST3.32 {d0, d2, d4}, [r0]
void vst3q_s8(__transfersize(48) int8_t * ptr, int8x16x3_t val);
                                                // VST3.8 {d0, d2, d4}, [r0]
void vst3q_s16(__transfersize(24) int16_t * ptr, int16x8x3_t val);
                                                // VST3.16 {d0, d2, d4}, [r0]
void vst3q_s32(__transfersize(12) int32_t * ptr, int32x4x3_t val);
                                                // VST3.32 {d0, d2, d4}, [r0]
void vst3q_f16(__transfersize(24) __fp16 * ptr, float16x8x3_t val);
                                               // VST3.16 {d0, d2, d4}, [r0]
void vst3q_f32(__transfersize(12) float32_t * ptr, float32x4x3_t val);
                                                // VST3.32 {d0, d2, d4}, [r0]
void vst3q_p8(__transfersize(48) poly8_t * ptr, poly8x16x3_t val);
                                                // VST3.8 {d0, d2, d4}, [r0]
void vst3q_p16(__transfersize(24) poly16_t * ptr, poly16x8x3_t val);
                                                // VST3.16 {d0, d2, d4}, [r0]
void vst3_u8(__transfersize(24) uint8_t * ptr, uint8x8x3_t val);
                                                // VST3.8 {d0, d1, d2}, [r0]
void vst3_u16(__transfersize(12) uint16_t * ptr, uint16x4x3_t val);
                                               // VST3.16 {d0, d1, d2}, [r0]
void vst3_u32(__transfersize(6) uint32_t * ptr, uint32x2x3_t val);
```

```
// VST3.32 {d0, d1, d2}, [r0]
void vst3_u64(__transfersize(3) uint64_t * ptr, uint64x1x3_t val);
                                                // VST1.64 {d0, d1, d2}, [r0]
void vst3_s8(__transfersize(24) int8_t * ptr, int8x8x3_t val);
                                                // VST3.8 {d0, d1, d2}, [r0]
void vst3_s16(__transfersize(12) int16_t * ptr, int16x4x3_t val);
                                                // VST3.16 {d0, d1, d2}, [r0]
void vst3_s32(__transfersize(6) int32_t * ptr, int32x2x3_t val);
                                                // VST3.32 {d0, d1, d2}, [r0]
void vst3_s64(__transfersize(3) int64_t * ptr, int64x1x3_t val);
                                                // VST1.64 {d0, d1, d2}, [r0]
void vst3_f16(__transfersize(12) __fp16 * ptr, float16x4x3_t val);
                                                // VST3.16 {d0, d1, d2}, [r0]
void vst3_f32(__transfersize(6) float32_t * ptr, float32x2x3_t val);
                                                // VST3.32 {d0, d1, d2}, [r0]
void vst3_p8(__transfersize(24) poly8_t * ptr, poly8x8x3_t val);
                                                // VST3.8 {d0, d1, d2}, [r0]
void vst3_p16(__transfersize(12) poly16_t * ptr, poly16x4x3_t val);
                                                // VST3.16 {d0, d1, d2}, [r0]
void vst4q_u8(__transfersize(64) uint8_t * ptr, uint8x16x4_t val);
                                                // VST4.8 {d0, d2, d4, d6}, [r0]
void vst4q_u16(__transfersize(32) uint16_t * ptr, uint16x8x4_t val);
                                                // VST4.16 {d0, d2, d4, d6}, [r0]
void vst4q_u32(__transfersize(16) uint32_t * ptr, uint32x4x4_t val);
                                                // VST4.32 {d0, d2, d4, d6}, [r0]
void vst4q_s8(__transfersize(64) int8_t * ptr, int8x16x4_t val);
                                                // VST4.8 {d0, d2, d4, d6}, [r0]
void vst4q_s16(__transfersize(32) int16_t * ptr, int16x8x4_t val);
                                                // VST4.16 {d0, d2, d4, d6}, [r0]
void vst4q_s32(__transfersize(16) int32_t * ptr, int32x4x4_t val);
                                                // VST4.32 {d0, d2, d4, d6}, [r0]
void vst4g_f16(__transfersize(32) __fp16 * ptr, float16x8x4_t val);
                                                // VST4.16 {d0, d2, d4, d6}, [r0]
void vst4q_f32(__transfersize(16) float32_t * ptr, float32x4x4_t val);
                                                // VST4.32 {d0, d2, d4, d6}, [r0]
void vst4q_p8(__transfersize(64) poly8_t * ptr, poly8x16x4_t val);
                                                // VST4.8 {d0, d2, d4, d6}, [r0]
void vst4q_p16(__transfersize(32) poly16_t * ptr, poly16x8x4_t val);
                                                // VST4.16 {d0, d2, d4, d6}, [r0]
void vst4_u8(__transfersize(32) uint8_t * ptr, uint8x8x4_t val);
                                                // VST4.8 {d0, d1, d2, d3}, [r0]
void vst4_u16(__transfersize(16) uint16_t * ptr, uint16x4x4_t val);
                                                // VST4.16 {d0, d1, d2, d3}, [r0]
void vst4_u32(__transfersize(8) uint32_t * ptr, uint32x2x4_t val);
                                                // VST4.32 {d0, d1, d2, d3}, [r0]
void vst4_u64(__transfersize(4) uint64_t * ptr, uint64x1x4_t val);
                                                // VST1.64 {d0, d1, d2, d3}, [r0]
void vst4_s8(__transfersize(32) int8_t * ptr, int8x8x4_t val);
                                                // VST4.8 {d0, d1, d2, d3}, [r0]
void vst4_s16(__transfersize(16) int16_t * ptr, int16x4x4_t val);
```

```
// VST4.16 {d0, d1, d2, d3}, [r0]
void vst4_s32(__transfersize(8) int32_t * ptr, int32x2x4_t val);
                                                // VST4.32 {d0, d1, d2, d3}, [r0]
void vst4_s64(__transfersize(4) int64_t * ptr, int64x1x4_t val);
                                                // VST1.64 {d0, d1, d2, d3}, [r0]
void vst4_f16(__transfersize(16) __fp16 * ptr, float16x4x4_t val);
                                               // VST4.16 {d0, d1, d2, d3}, [r0]
void vst4_f32(__transfersize(8) float32_t * ptr, float32x2x4_t val);
                                                // VST4.32 {d0, d1, d2, d3}, [r0]
void vst4_p8(__transfersize(32) poly8_t * ptr, poly8x8x4_t val);
                                               // VST4.8 {d0, d1, d2, d3}, [r0]
void vst4_p16(__transfersize(16) poly16_t * ptr, poly16x4x4_t val);
                                               // VST4.16 {d0, d1, d2, d3}, [r0]
void vst2q_lane_u16(__transfersize(2) uint16_t * ptr, uint16x8x2_t val, __constrange(0,7) int lane);
                                                // VST2.16 {d0[0], d2[0]}, [r0]
void vst2q_lane_u32(__transfersize(2) uint32_t * ptr, uint32x4x2_t val, __constrange(0,3) int lane);
                                                // VST2.32 {d0[0], d2[0]}, [r0]
void vst2g_lane_s16(__transfersize(2) int16_t * ptr, int16x8x2_t val, __constrange(0,7) int lane);
                                                // VST2.16 {d0[0], d2[0]}, [r0]
void vst2q_lane_s32(__transfersize(2) int32_t * ptr, int32x4x2_t val, __constrange(0,3) int lane);
                                                // VST2.32 {d0[0], d2[0]}, [r0]
void vst2q_lane_f16(__transfersize(2) __fp16 * ptr, float16x8x2_t val, __constrange(0,7) int lane);
                                                // VST2.16 {d0[0], d2[0]}, [r0]
void vst2q_lane_f32(__transfersize(2) float32_t * ptr, float32x4x2_t val, __constrange(0,3) int lane);
                                                // VST2.32 {d0[0], d2[0]}, [r0]
void vst2q_lane_p16(__transfersize(2) poly16_t * ptr, poly16x8x2_t val, __constrange(0,7) int lane);
                                               // VST2.16 {d0[0], d2[0]}, [r0]
void vst2_lane_u8(__transfersize(2) uint8_t * ptr, uint8x8x2_t val, __constrange(0,7) int lane);
                                               // VST2.8 {d0[0], d1[0]}, [r0]
void vst2_lane_u16(__transfersize(2) uint16_t * ptr, uint16x4x2_t val, __constrange(0,3) int lane);
                                                // VST2.16 {d0[0], d1[0]}, [r0]
void vst2_lane_u32(__transfersize(2) uint32_t * ptr, uint32x2x2_t val, __constrange(0,1) int lane);
                                                // VST2.32 {d0[0], d1[0]}, [r0]
void vst2_lane_s8(__transfersize(2) int8_t * ptr, int8x8x2_t val, __constrange(0,7) int lane);
                                                // VST2.8 {d0[0], d1[0]}, [r0]
void vst2_lane_s16(__transfersize(2) int16_t * ptr, int16x4x2_t val, __constrange(0,3) int lane);
                                                // VST2.16 {d0[0], d1[0]}, [r0]
void vst2_lane_s32(__transfersize(2) int32_t * ptr, int32x2x2_t val, __constrange(0,1) int lane);
                                               // VST2.32 {d0[0], d1[0]}, [r0]
void vst2_lane_f16(__transfersize(2) __fp16 * ptr, float16x4x2_t val, __constrange(0,3) int lane);
                                                // VST2.16 {d0[0], d1[0]}, [r0]
void vst2_lane_f32(__transfersize(2) float32_t * ptr, float32x2x2_t val, __constrange(0,1) int lane);
                                                // VST2.32 {d0[0], d1[0]}, [r0]
void vst2_lane_p8(__transfersize(2) poly8_t * ptr, poly8x8x2_t val, __constrange(0,7) int lane);
                                                // VST2.8 {d0[0], d1[0]}, [r0]
void vst2_lane_p16(__transfersize(2) poly16_t * ptr, poly16x4x2_t val, __constrange(0,3) int lane);
                                                // VST2.16 {d0[0], d1[0]}, [r0]
void vst3q_lane_u16(__transfersize(3) uint16_t * ptr, uint16x8x3_t val, __constrange(0,7) int lane);
                                                // VST3.16 {d0[0], d2[0], d4[0]}, [r0]
void vst3q_lane_u32(__transfersize(3) uint32_t * ptr, uint32x4x3_t val, __constrange(0,3) int lane);
```

```
// VST3.32 {d0[0], d2[0], d4[0]}, [r0]
void vst3q_lane_s16(__transfersize(3) int16_t * ptr, int16x8x3_t val, __constrange(0,7) int lane);
                                                // VST3.16 {d0[0], d2[0], d4[0]}, [r0]
void vst3g_lane_s32(__transfersize(3) int32_t * ptr, int32x4x3_t val, __constrange(0.3) int lane);
                                                // VST3.32 {d0[0], d2[0], d4[0]}, [r0]
void vst3q_lane_f16(__transfersize(3) __fp16 * ptr, float16x8x3_t val, __constrange(0,7) int lane);
                                                // VST3.16 {d0[0], d2[0], d4[0]}, [r0]
void vst3q_lane_f32(__transfersize(3) float32_t * ptr, float32x4x3_t val, __constrange(0,3) int lane);
                                                // VST3.32 {d0[0], d2[0], d4[0]}, [r0]
void vst3q_lane_p16(__transfersize(3) poly16_t * ptr, poly16x8x3_t val, __constrange(0,7) int lane);
                                                // VST3.16 {d0[0], d2[0], d4[0]}, [r0]
void vst3_lane_u8(__transfersize(3) uint8_t * ptr, uint8x8x3_t val, __constrange(0,7) int lane);
                                                // VST3.8 {d0[0], d1[0], d2[0]}, [r0]
void vst3_lane_u16(__transfersize(3) uint16_t * ptr, uint16x4x3_t val, __constrange(0,3) int lane);
                                                // VST3.16 {d0[0], d1[0], d2[0]}, [r0]
void vst3_lane_u32(__transfersize(3) uint32_t * ptr, uint32x2x3_t val, __constrange(0,1) int lane);
                                                // VST3.32 {d0[0], d1[0], d2[0]}, [r0]
void vst3_lane_s8(__transfersize(3) int8_t * ptr, int8x8x3_t val, __constrange(0,7) int lane);
                                                // VST3.8 {d0[0], d1[0], d2[0]}, [r0]
void vst3_lane_s16(__transfersize(3) int16_t * ptr, int16x4x3_t val, __constrange(0,3) int lane);
                                                // VST3.16 {d0[0], d1[0], d2[0]}, [r0]
void vst3_lane_s32(__transfersize(3) int32_t * ptr, int32x2x3_t val, __constrange(0,1) int lane);
                                                // VST3.32 {d0[0], d1[0], d2[0]}, [r0]
void vst3_lane_f16(__transfersize(3) __fp16 * ptr, float16x4x3_t val, __constrange(0,3) int lane);
                                                // VST3.16 {d0[0], d1[0], d2[0]}, [r0]
void vst3_lane_f32(__transfersize(3) float32_t * ptr, float32x2x3_t val, __constrange(0,1) int lane);
                                                // VST3.32 {d0[0], d1[0], d2[0]}, [r0]
void vst3_lane_p8(__transfersize(3) poly8_t * ptr, poly8x8x3_t val, __constrange(0,7) int lane);
                                                // VST3.8 {d0[0], d1[0], d2[0]}, [r0]
void vst3_lane_p16(__transfersize(3) poly16_t * ptr, poly16x4x3_t val, __constrange(0,3) int lane);
                                                // VST3.16 {d0[0], d1[0], d2[0]}, [r0]
void vst4q_lane_u16(__transfersize(4) uint16_t * ptr, uint16x8x4_t val, __constrange(0,7) int lane);
                                                // VST4.16 {d0[0], d2[0], d4[0], d6[0]}, [r0]
void vst4q_lane_u32(__transfersize(4) uint32_t * ptr, uint32x4x4_t val, __constrange(0,3) int lane);
                                                // VST4.32 {d0[0], d2[0], d4[0], d6[0]}, [r0]
void vst4q_lane_s16(__transfersize(4) int16_t * ptr, int16x8x4_t val, __constrange(0,7) int lane);
                                                // VST4.16 {d0[0], d2[0], d4[0], d6[0]}, [r0]
void vst4q_lane_s32(__transfersize(4) int32_t * ptr, int32x4x4_t val, __constrange(0,3) int lane);
                                                // VST4.32 {d0[0], d2[0], d4[0], d6[0]}, [r0]
void vst4q_lane_f16(__transfersize(4) __fp16 * ptr, float16x8x4_t val, __constrange(0,7) int lane);
                                                // VST4.16 {d0[0], d2[0], d4[0], d6[0]}, [r0]
void vst4q_lane_f32(__transfersize(4) float32_t * ptr, float32x4x4_t val, __constrange(0,3) int lane);
                                                // VST4.32 {d0[0], d2[0], d4[0], d6[0]}, [r0]
void vst4q_lane_p16(__transfersize(4) poly16_t * ptr, poly16x8x4_t val, __constrange(0,7) int lane);
                                                // VST4.16 {d0[0], d2[0], d4[0], d6[0]}, [r0]
void vst4_lane_u8(__transfersize(4) uint8_t * ptr, uint8x8x4_t val, __constrange(0,7) int lane);
                                                // VST4.8 {d0[0], d1[0], d2[0], d3[0]}, [r0]
void vst4_lane_u16(__transfersize(4) uint16_t * ptr, uint16x4x4_t val, __constrange(0,3) int lane);
                                                // VST4.16 {d0[0], d1[0], d2[0], d3[0]}, [r0]
void vst4_lane_u32(__transfersize(4) uint32_t * ptr, uint32x2x4_t val, __constrange(0,1) int lane);
```

E.3.16 Extract lanes from a vector

These intrinsics extract a single lane (element) from a vector.

```
uint8_t
         vget_lane_u8(uint8x8_t vec, __constrange(0,7) int lane);
                                                                       // VMOV.U8 r0, d0[0]
uint16_t vget_lane_u16(uint16x4_t vec, __constrange(0,3) int lane);
                                                                       // VMOV.U16 r0, d0[0]
         vget_lane_u32(uint32x2_t vec, __constrange(0,1) int lane);
uint32_t
                                                                       // VMOV.32 r0, d0[0]
int8_t
         vget_lane_s8(int8x8_t vec, __constrange(0,7) int lane);
                                                                       // VMOV.S8 r0, d0[0]
int16_t
         vget_lane_s16(int16x4_t vec, __constrange(0,3) int lane);
                                                                       // VMOV.S16 r0, d0[0]
int32_t
         vget_lane_s32(int32x2_t vec, __constrange(0,1) int lane);
                                                                       // VMOV.32 r0, d0[0]
poly8_t
         vget_lane_p8(poly8x8_t vec, __constrange(0,7) int lane);
                                                                       // VMOV.U8 r0, d0[0]
poly16_t vget_lane_p16(poly16x4_t vec, __constrange(0,3) int lane);
                                                                       // VMOV.U16 r0, d0[0]
float32_t vget_lane_f32(float32x2_t vec, __constrange(0,1) int lane);
                                                                      // VMOV.32 r0, d0[0]
         vgetq_lane_u8(uint8x16_t vec, __constrange(0,15) int lane); // VMOV.U8 r0, d0[0]
uint8_t
uint16_t vgetg_lane_u16(uint16x8_t vec, __constrange(0,7) int lane);
                                                                      // VMOV.U16 r0, d0[0]
uint32_t vgetq_lane_u32(uint32x4_t vec, __constrange(0,3) int lane);
                                                                      // VMOV.32 r0, d0[0]
int8_t
         vgetq_lane_s8(int8x16_t vec, __constrange(0,15) int lane);
                                                                       // VMOV.S8 r0, d0[0]
int16_t
         vgetq_lane_s16(int16x8_t vec, __constrange(0,7) int lane);
                                                                       // VMOV.S16 r0, d0[0]
         vgetq_lane_s32(int32x4_t vec, __constrange(0,3) int lane);
int32_t
                                                                       // VMOV.32 r0, d0[0]
         vgetq_lane_p8(poly8x16_t vec, __constrange(0,15) int lane);
poly8_t
                                                                       // VMOV.U8 r0, d0[0]
poly16_t vgetq_lane_p16(poly16x8_t vec, __constrange(0,7) int lane); // VMOV.U16 r0, d0[0]
float32_t vgetg_lane_f32(float32x4_t vec, __constrange(0.3) int lane); // VMOV.32 r0, d0[0]
int64_t
         vget_lane_s64(int64x1_t vec, __constrange(0,0) int lane);
                                                                       // VMOV r0,r0,d0
uint64_t vget_lane_u64(uint64x1_t vec, __constrange(0,0) int lane);
                                                                       // VMOV r0, r0, d0
int64_t
         vgetq_lane_s64(int64x2_t vec, __constrange(0,1) int lane);
                                                                       // VMOV r0, r0, d0
uint64_t
         vgetq_lane_u64(uint64x2_t vec, __constrange(0,1) int lane); // VMOV r0,r0,d0
```

E.3.17 Set lanes within a vector

These intrinsics set a single lane (element) within a vector.

```
uint8x8_t
           vset_lane_u8(uint8_t value, uint8x8_t vec, __constrange(0,7) int lane);
                                                // VMOV.8 d0[0],r0
uint16x4_t vset_lane_u16(uint16_t value, uint16x4_t vec, __constrange(0,3) int lane);
                                                // VMOV.16 d0[0],r0
uint32x2_t vset_lane_u32(uint32_t value, uint32x2_t vec, __constrange(0,1) int lane);
                                                // VMOV.32 d0[0],r0
int8x8 t
           vset_lane_s8(int8_t value, int8x8_t vec, __constrange(0,7) int lane);
                                                // VMOV.8 d0[0],r0
int16x4_t
           vset_lane_s16(int16_t value, int16x4_t vec, __constrange(0,3) int lane);
                                                // VMOV.16 d0[0],r0
int32x2_t
           vset_lane_s32(int32_t value, int32x2_t vec, __constrange(0.1) int lane);
                                                // VMOV.32 d0[0],r0
poly8x8_t vset_lane_p8(poly8_t value, poly8x8_t vec, __constrange(0,7) int lane);
                                                // VMOV.8 d0[0],r0
poly16x4_t vset_lane_p16(poly16_t value, poly16x4_t vec, __constrange(0,3) int lane);
                                                // VMOV.16 d0[0],r0
float32x2_t vset_lane_f32(float32_t value, float32x2_t vec, __constrange(0,1) int lane);
                                                // VMOV.32 d0[0],r0
uint8x16_t vsetq_lane_u8(uint8_t value, uint8x16_t vec, __constrange(0,15) int lane);
                                                // VMOV.8 d0[0],r0
uint16x8_t vsetq_lane_u16(uint16_t value, uint16x8_t vec, __constrange(0,7) int lane);
                                                // VMOV.16 d0[0],r0
uint32x4_t vsetq_lane_u32(uint32_t value, uint32x4_t vec, __constrange(0,3) int lane);
                                                // VMOV.32 d0[0],r0
           vsetq_lane_s8(int8_t value, int8x16_t vec, __constrange(0,15) int lane);
int8x16_t
                                                // VMOV.8 d0[0],r0
int16x8_t
           vsetq_lane_s16(int16_t value, int16x8_t vec, __constrange(0,7) int lane);
                                                // VMOV.16 d0[0],r0
int32x4_t vsetq_lane_s32(int32_t value, int32x4_t vec, __constrange(0,3) int lane);
                                                // VMOV.32 d0[0],r0
poly8x16_t vsetq_lane_p8(poly8_t value, poly8x16_t vec, __constrange(0,15) int lane);
                                                // VMOV.8 d0[0],r0
poly16x8_t vsetq_lane_p16(poly16_t value, poly16x8_t vec, __constrange(0,7) int lane);
                                                // VMOV.16 d0[0],r0
float32x4_t vsetq_lane_f32(float32_t value, float32x4_t vec, __constrange(0,3) int lane);
                                                // VMOV.32 d0[0],r0
int64x1_t vset_lane_s64(int64_t value, int64x1_t vec, __constrange(0,0) int lane);
                                                // VMOV d0,r0,r0
uint64x1_t vset_lane_u64(uint64_t value, uint64x1_t vec, __constrange(0,0) int lane);
                                                // VMOV d0,r0,r0
int64x2_t vsetq_lane_s64(int64_t value, int64x2_t vec, __constrange(0,1) int lane);
                                                // VMOV d0,r0,r0
uint64x2_t vsetq_lane_u64(uint64_t value, uint64x2_t vec, __constrange(0,1) int lane);
                                               // VMOV d0,r0,r0
```

E.3.18 Initialize a vector from bit pattern

These intrinsics create a vector from a literal bit pattern.

```
int8x8 t
           vcreate_s8(uint64_t a);
                                     // VMOV d0,r0,r0
int16x4_t
           vcreate_s16(uint64_t a);
                                     // VMOV d0,r0,r0
int32x2_t
           vcreate_s32(uint64_t a);
                                     // VMOV d0,r0,r0
float16x4_t vcreate_f16(uint64_t a); // VMOV d0,r0,r0
float32x2_t vcreate_f32(uint64_t a); // VMOV d0,r0,r0
uint8x8_t vcreate_u8(uint64_t a);
                                     // VMOV d0,r0,r0
uint16x4_t vcreate_u16(uint64_t a);
                                     // VMOV d0,r0,r0
uint32x2_t vcreate_u32(uint64_t a);
                                    // VMOV d0,r0,r0
uint64x1_t vcreate_u64(uint64_t a); // VMOV d0,r0,r0
poly8x8_t
           vcreate_p8(uint64_t a);
                                     // VMOV d0,r0,r0
poly16x4_t vcreate_p16(uint64_t a); // VMOV d0,r0,r0
int64x1_t
           vcreate_s64(uint64_t a); // VMOV d0,r0,r0
```

E.3.19 Set all lanes to same value

These intrinsics set all lanes to the same value.

Set all lanes to the same value

```
uint8x8_t
            vdup_n_u8(uint8_t value);
                                           // VDUP.8 d0,r0
uint16x4_t vdup_n_u16(uint16_t value);
                                           // VDUP.16 d0,r0
uint32x2_t vdup_n_u32(uint32_t value);
                                           // VDUP.32 d0,r0
int8x8_t
            vdup_n_s8(int8_t value);
                                           // VDUP.8 d0,r0
int16x4_t
            vdup_n_s16(int16_t value);
                                           // VDUP.16 d0,r0
            vdup_n_s32(int32_t value);
int32x2_t
                                           // VDUP.32 d0,r0
poly8x8_t
            vdup_n_p8(poly8_t value);
                                           // VDUP.8 d0,r0
poly16x4_t vdup_n_p16(poly16_t value);
                                           // VDUP.16 d0,r0
float32x2_t vdup_n_f32(float32_t value);
                                           // VDUP.32 d0,r0
uint8x16_t vdupq_n_u8(uint8_t value);
                                           // VDUP.8 q0,r0
uint16x8_t vdupg_n_u16(uint16_t value);
                                           // VDUP.16 q0,r0
uint32x4_t vdupq_n_u32(uint32_t value);
                                           // VDUP.32 q0,r0
int8x16_t
            vdupq_n_s8(int8_t value);
                                           // VDUP.8 q0,r0
int16x8_t
            vdupq_n_s16(int16_t value);
                                           // VDUP.16 q0,r0
int32x4_t
            vdupq_n_s32(int32_t value);
                                           // VDUP.32 q0,r0
poly8x16_t vdupq_n_p8(poly8_t value);
                                           // VDUP.8 q0,r0
poly16x8_t vdupq_n_p16(poly16_t value);
                                           // VDUP.16 q0,r0
float32x4_t vdupg_n_f32(float32_t value);
                                           // VDUP.32 q0,r0
int64x1_t
            vdup_n_s64(int64_t value);
                                           // VMOV d0,r0,r0
uint64x1_t vdup_n_u64(uint64_t value);
                                           // VMOV d0,r0,r0
int64x2_t
            vdupq_n_s64(int64_t value);
                                           // VMOV d0,r0,r0
uint64x2_t vdupq_n_u64(uint64_t value);
                                           // VMOV d0,r0,r0
uint8x8_t
            vmov_n_u8(uint8_t value);
                                           // VDUP.8 d0,r0
uint16x4_t vmov_n_u16(uint16_t value);
                                           // VDUP.16 d0,r0
uint32x2_t vmov_n_u32(uint32_t value);
                                           // VDUP.32 d0,r0
int8x8_t
            vmov_n_s8(int8_t value);
                                           // VDUP.8 d0,r0
int16x4_t
            vmov_n_s16(int16_t value);
                                           // VDUP.16 d0,r0
int32x2_t
            vmov_n_s32(int32_t value);
                                           // VDUP.32 d0,r0
poly8x8_t
            vmov_n_p8(poly8_t value);
                                           // VDUP.8 d0,r0
poly16x4_t vmov_n_p16(poly16_t value);
                                           // VDUP.16 d0,r0
```

```
float32x2_t vmov_n_f32(float32_t value);
                                           // VDUP.32 d0,r0
uint8x16_t vmovq_n_u8(uint8_t value);
                                           // VDUP.8 q0,r0
uint16x8_t vmovq_n_u16(uint16_t value);
                                           // VDUP.16 q0,r0
uint32x4_t vmovq_n_u32(uint32_t value);
                                           // VDUP.32 q0,r0
int8x16_t
            vmovq_n_s8(int8_t value);
                                           // VDUP.8 q0,r0
int16x8_t
            vmovq_n_s16(int16_t value);
                                           // VDUP.16 q0,r0
int32x4_t
            vmovq_n_s32(int32_t value);
                                           // VDUP.32 q0,r0
poly8x16_t vmovq_n_p8(poly8_t value);
                                           // VDUP.8 q0,r0
poly16x8_t vmovq_n_p16(poly16_t value);
                                           // VDUP.16 q0,r0
float32x4_t vmovq_n_f32(float32_t value);
                                           // VDUP.32 q0,r0
            vmov_n_s64(int64_t value);
int64x1_t
                                           // VMOV d0,r0,r0
uint64x1_t vmov_n_u64(uint64_t value);
                                           // VMOV d0,r0,r0
int64x2_t
            vmovg_n_s64(int64_t value);
                                           // VMOV d0,r0,r0
uint64x2_t vmovq_n_u64(uint64_t value);
                                           // VMOV d0,r0,r0
```

Set all lanes to the value of one lane of a vector

```
uint8x8_t
            vdup_lane_u8(uint8x8_t vec, __constrange(0,7) int lane);
                                                                         // VDUP.8 d0,d0[0]
            vdup_lane_u16(uint16x4_t vec, __constrange(0.3) int lane);
                                                                         // VDUP.16 d0,d0[0]
uint16x4_t
uint32x2_t
            vdup_lane_u32(uint32x2_t vec, __constrange(0,1) int lane);
                                                                         // VDUP.32 d0,d0[0]
int8x8_t
            vdup_lane_s8(int8x8_t vec, __constrange(0,7) int lane);
                                                                         // VDUP.8 d0,d0[0]
            vdup_lane_s16(int16x4_t vec, __constrange(0,3) int lane);
int16x4_t
                                                                         // VDUP.16 d0,d0[0]
int32x2_t
            vdup_lane_s32(int32x2_t vec, __constrange(0,1) int lane);
                                                                         // VDUP.32 d0,d0[0]
            vdup_lane_p8(poly8x8_t vec, __constrange(0,7) int lane);
poly8x8_t
                                                                         // VDUP.8 d0,d0[0]
           vdup_lane_p16(poly16x4_t vec, __constrange(0,3) int lane);
poly16x4_t
                                                                         // VDUP.16 d0,d0[0]
float32x2_t vdup_lane_f32(float32x2_t vec, __constrange(0,1) int lane);
                                                                         // VDUP.32 d0,d0[0]
           vdupq_lane_u8(uint8x8_t vec, __constrange(0,7) int lane);
uint8x16_t
                                                                         // VDUP.8 q0,d0[0]
            vdupq_lane_u16(uint16x4_t vec, __constrange(0,3) int lane);
                                                                         // VDUP.16 q0,d0[0]
uint16x8_t
            vdupq_lane_u32(uint32x2_t vec, __constrange(0,1) int lane);
uint32x4_t
                                                                         // VDUP.32 q0,d0[0]
int8x16_t
            vdupq_lane_s8(int8x8_t vec, __constrange(0,7) int lane);
                                                                         // VDUP.8 q0,d0[0]
            vdupq_lane_s16(int16x4_t vec, __constrange(0,3) int lane);
int16x8_t
                                                                         // VDUP.16 q0,d0[0]
int32x4_t
            vdupq_lane_s32(int32x2_t vec, __constrange(0,1) int lane);
                                                                         // VDUP.32 q0,d0[0]
           vdupq_lane_p8(poly8x8_t vec, __constrange(0,7) int lane);
poly8x16_t
                                                                         // VDUP.8 q0,d0[0]
            vdupq_lane_p16(poly16x4_t vec, __constrange(0,3) int lane);
poly16x8_t
                                                                         // VDUP.16 q0,d0[0]
float32x4_t vdupq_lane_f32(float32x2_t vec, __constrange(0,1) int lane); // VDUP.32 q0,d0[0]
            vdup_lane_s64(int64x1_t vec, __constrange(0,0) int lane);
int64x1_t
                                                                         // VMOV d0,d0
uint64x1_t vdup_lane_u64(uint64x1_t vec, __constrange(0,0) int lane);
                                                                         // VMOV d0,d0
            vdupq_lane_s64(int64x1_t vec, __constrange(0,0) int lane);
int64x2_t
                                                                         // VMOV q0,q0
uint64x2_t vdupq_lane_u64(uint64x1_t vec, __constrange(0,0) int lane); // VMOV q0,q0
```

E.3.20 Combining vectors

These intrinsics join two 64 bit vectors into a single 128bit vector.

```
float32x4_t vcombine_f32(float32x2_t low, float32x2_t high); // VMOV d0,d0 uint8x16_t vcombine_u8(uint8x8_t low, uint8x8_t high); // VMOV d0,d0 uint16x8_t vcombine_u16(uint16x4_t low, uint16x4_t high); // VMOV d0,d0 uint32x4_t vcombine_u32(uint32x2_t low, uint32x2_t high); // VMOV d0,d0 uint64x2_t vcombine_u64(uint64x1_t low, uint64x1_t high); // VMOV d0,d0 poly8x16_t vcombine_p8(poly8x8_t low, poly8x8_t high); // VMOV d0,d0 poly16x8_t vcombine_p16(poly16x4_t low, poly16x4_t high); // VMOV d0,d0
```

E.3.21 Splitting vectors

These intrinsics split a 128 bit vector into 2 component 64 bit vectors

```
int8x8_t
           vget_high_s8(int8x16_t a);
                                         // VMOV d0,d0
int16x4_t vget_high_s16(int16x8_t a);
                                         // VMOV d0.d0
int32x2_t vget_high_s32(int32x4_t a);
                                         // VMOV d0,d0
                                         // VMOV d0,d0
int64x1_t vget_high_s64(int64x2_t a);
float16x4_t vget_high_f16(float16x8_t a); // VMOV d0,d0
float32x2_t vget_high_f32(float32x4_t a); // VMOV d0.d0
uint8x8_t vget_high_u8(uint8x16_t a);
                                         // VMOV d0, d0
uint16x4_t vget_high_u16(uint16x8_t a);
                                         // VMOV d0,d0
                                         // VMOV d0.d0
uint32x2_t vget_high_u32(uint32x4_t a);
uint64x1_t vget_high_u64(uint64x2_t a);
                                         // VMOV d0,d0
                                         // VMOV d0,d0
poly8x8_t vget_high_p8(poly8x16_t a);
poly16x4_t vget_high_p16(poly16x8_t a);
                                         // VMOV d0,d0
int8x8_t
           vget_low_s8(int8x16_t a);
                                         // VMOV d0,d0
                                         // VMOV d0,d0
int16x4_t vget_low_s16(int16x8_t a);
int32x2_t vget_low_s32(int32x4_t a);
                                         // VMOV d0,d0
                                         // VMOV d0,d0
int64x1_t vget_low_s64(int64x2_t a);
float16x4_t vget_low_f16(float16x8_t a);
                                         // VMOV d0,d0
float32x2_t vget_low_f32(float32x4_t a);
                                         // VMOV d0,d0
uint8x8_t vget_low_u8(uint8x16_t a);
                                         // VMOV d0,d0
uint16x4_t vget_low_u16(uint16x8_t a);
                                         // VMOV d0,d0
uint32x2_t vget_low_u32(uint32x4_t a);
                                         // VMOV d0,d0
                                         // VMOV d0,d0
uint64x1_t vget_low_u64(uint64x2_t a);
                                         // VMOV d0,d0
poly8x8_t vget_low_p8(poly8x16_t a);
poly16x4_t vget_low_p16(poly16x8_t a);
                                         // VMOV d0,d0
```

E.3.22 Converting vectors

These intrinsics are used to convert vectors.

Convert from float

```
uint32x2_t vcvt_n_u32_f32(float32x2_t a, __constrange(1,32) int b); // VCVT.U32.F32 d0, d0, #32
int32x4_t vcvtq_n_s32_f32(float32x4_t a, __constrange(1,32) int b); // VCVT.S32.F32 q0, q0, #32
uint32x4_t vcvtq_n_u32_f32(float32x4_t a, __constrange(1,32) int b); // VCVT.U32.F32 q0, q0, #32
```

Convert to float

Convert between floats

```
float16x4_t vcvt_f16_f32(float32x4_t a); // VCVT.F16.F32 d0, q0 float32x4_t vcvt_f32_f16(float16x4_t a); // VCVT.F32.F16 q0, d0
```

Vector narrow integer

Vector long move

Vector saturating narrow integer

Vector saturating narrow integer signed->unsigned

```
uint8x8_t vqmovun_s16(int16x8_t a); // VQMOVUN.S16 d0,q0
uint16x4_t vqmovun_s32(int32x4_t a); // VQMOVUN.S32 d0,q0
uint32x2_t vqmovun_s64(int64x2_t a); // VQMOVUN.S64 d0,q0
```

E.3.23 Table look up

```
uint8x8_t vtbl1_u8(uint8x8_t a, uint8x8_t b);  // VTBL.8 d0, {d0}, d0
int8x8_t vtbl1_s8(int8x8_t a, int8x8_t b);  // VTBL.8 d0, {d0}, d0
poly8x8_t vtbl1_p8(poly8x8_t a, uint8x8_t b);  // VTBL.8 d0, {d0}, d0
uint8x8_t vtbl2_u8(uint8x8x2_t a, uint8x8_t b);  // VTBL.8 d0, {d0, d1}, d0
int8x8_t vtbl2_s8(int8x8x2_t a, int8x8_t b);  // VTBL.8 d0, {d0, d1}, d0
poly8x8_t vtbl2_p8(poly8x8x2_t a, uint8x8_t b);  // VTBL.8 d0, {d0, d1}, d0
uint8x8_t vtbl3_u8(uint8x8x3_t a, uint8x8_t b);  // VTBL.8 d0, {d0, d1}, d2}, d0
int8x8_t vtbl3_s8(int8x8x3_t a, int8x8_t b);  // VTBL.8 d0, {d0, d1, d2}, d0
poly8x8_t vtbl3_p8(poly8x8x3_t a, uint8x8_t b);  // VTBL.8 d0, {d0, d1, d2}, d0
uint8x8_t vtbl4_u8(uint8x8x4_t a, uint8x8_t b);  // VTBL.8 d0, {d0, d1, d2}, d0
uint8x8_t vtbl4_s8(int8x8x4_t a, uint8x8_t b);  // VTBL.8 d0, {d0, d1, d2, d3}, d0
poly8x8_t vtbl4_p8(poly8x8x4_t a, uint8x8_t b);  // VTBL.8 d0, {d0, d1, d2, d3}, d0
poly8x8_t vtbl4_p8(poly8x8x4_t a, uint8x8_t b);  // VTBL.8 d0, {d0, d1, d2, d3}, d0
```

E.3.24 Extended table look up intrinsics

```
// VTBX.8 d0, {d0}, d0
uint8x8_t vtbx1_u8(uint8x8_t a, uint8x8_t b, uint8x8_t c);
int8x8_t vtbx1_s8(int8x8_t a, int8x8_t b, int8x8_t c);
                                                           // VTBX.8 d0, {d0}, d0
poly8x8_t vtbx1_p8(poly8x8_t a, poly8x8_t b, uint8x8_t c);
                                                           // VTBX.8 d0, {d0}, d0
uint8x8_t vtbx2_u8(uint8x8_t a, uint8x8x2_t b, uint8x8_t c); // VTBX.8 d0, {d0, d1}, d0
                                                          // VTBX.8 d0, {d0, d1}, d0
int8x8_t vtbx2_s8(int8x8_t a, int8x8x2_t b, int8x8_t c);
poly8x8_t vtbx2_p8(poly8x8_t a, poly8x8x2_t b, uint8x8_t c); // VTBX.8 d0, {d0, d1}, d0
uint8x8_t vtbx3_u8(uint8x8_t a, uint8x8x3_t b, uint8x8_t c); // VTBX.8 d0, {d0, d1, d2}, d0
int8x8_t vtbx3_s8(int8x8_t a, int8x8x3_t b, int8x8_t c); // VTBX.8 d0, {d0, d1, d2}, d0
poly8x8_t vtbx3_p8(poly8x8_t a, poly8x8x3_t b, uint8x8_t c); // VTBX.8 d0, {d0, d1, d2}, d0
uint8x8_t vtbx4_u8(uint8x8_t a, uint8x8x4_t b, uint8x8_t c); // VTBX.8 d0, {d0, d1, d2, d3}, d0
int8x8_t vtbx4_s8(int8x8_t a, int8x8x4_t b, int8x8_t c); // VTBX.8 d0, {d0, d1, d2, d3}, d0
poly8x8_t vtbx4_p8(poly8x8_t a, poly8x8x4_t b, uint8x8_t c); // VTBX.8 d0, {d0, d1, d2, d3}, d0
```

E.3.25 Operations with a scalar value

Efficient code generation for these intrinsics is only guaranteed when the scalar argument is either a constant or a use of one of the vget_lane intrinsics.

Vector multiply accumulate with scalar

Vector widening multiply accumulate with scalar

Vector widening saturating doubling multiply accumulate with scalar

Vector multiply subtract with scalar

Vector widening multiply subtract with scalar

Vector widening saturating doubling multiply subtract with scalar

Vector multiply by scalar

```
int16x4_t
           vmul_n_s16(int16x4_t a, int16_t b);
                                                    // VMUL.I16 d0,d0,d0[0]
int32x2_t vmul_n_s32(int32x2_t a, int32_t b);
                                                    // VMUL.I32 d0,d0,d0[0]
float32x2_t vmul_n_f32(float32x2_t a, float32_t b); // VMUL.F32 d0,d0,d0[0]
uint16x4_t vmul_n_u16(uint16x4_t a, uint16_t b);
                                                    // VMUL.I16 d0,d0,d0[0]
uint32x2_t vmul_n_u32(uint32x2_t a, uint32_t b);
                                                    // VMUL.I32 d0,d0,d0[0]
int16x8_t vmulq_n_s16(int16x8_t a, int16_t b);
                                                    // VMUL.I16 q0,q0,d0[0]
int32x4_t
           vmulg_n_s32(int32x4_t a, int32_t b);
                                                    // VMUL.I32 q0,q0,d0[0]
float32x4_t vmulq_n_f32(float32x4_t a, float32_t b); // VMUL.F32 q0,q0,d0[0]
uint16x8_t vmulq_n_u16(uint16x8_t a, uint16_t b);
                                                   // VMUL.I16 q0,q0,d0[0]
uint32x4_t vmulq_n_u32(uint32x4_t a, uint32_t b);
                                                   // VMUL.I32 q0,q0,d0[0]
```

Vector long multiply with scalar

Vector long multiply by scalar

Vector saturating doubling long multiply with scalar

```
int32x4_t vqdmull_n_s16(int16x4_t vec1, int16_t val2); // VQDMULL.S16 q0,d0,d0[0] int64x2_t vqdmull_n_s32(int32x2_t vec1, int32_t val2); // VQDMULL.S32 q0,d0,d0[0]
```

Vector saturating doubling long multiply by scalar

Vector saturating doubling multiply high with scalar

Vector saturating doubling multiply high by scalar

Vector saturating rounding doubling multiply high with scalar

```
int16x4_t vqrdmulh_n_s16(int16x4_t vec1, int16_t val2);
int32x2_t vqrdmulh_n_s32(int32x2_t vec1, int32_t val2);
int16x8_t vqrdmulhq_n_s16(int16x8_t vec1, int16_t val2);
int32x4_t vqrdmulhq_n_s32(int32x4_t vec1, int32_t val2);
// VQRDMULH.S16 q0,q0,d0[0]
// VQRDMULH.S32 q0,q0,d0[0]
```

Vector rounding saturating doubling multiply high by scalar

Vector multiply accumulate with scalar

```
int16x4_t vmla_n_s16(int16x4_t a, int16x4_t b, int16_t c);
                                                                      // VMLA.I16 d0, d0, d0[0]
int32x2_t vmla_n_s32(int32x2_t a, int32x2_t b, int32_t c);
                                                                      // VMLA.I32 d0, d0, d0[0]
uint16x4_t vmla_n_u16(uint16x4_t a, uint16x4_t b, uint16_t c);
                                                                     // VMLA.I16 d0, d0, d0[0]
uint32x2_t vmla_n_u32(uint32x2_t a, uint32x2_t b, uint32_t c);
                                                                      // VMLA.I32 d0, d0, d0[0]
float32x2_t vmla_n_f32(float32x2_t a, float32x2_t b, float32_t c);
                                                                     // VMLA.F32 d0, d0, d0[0]
int16x8_t vmlaq_n_s16(int16x8_t a, int16x8_t b, int16_t c);
                                                                      // VMLA.I16 q0, q0, d0[0]
int32x4_t vmlaq_n_s32(int32x4_t a, int32x4_t b, int32_t c);
                                                                      // VMLA.I32 q0, q0, d0[0]
uint16x8_t vmlaq_n_u16(uint16x8_t a, uint16x8_t b, uint16_t c);
                                                                     // VMLA.I16 q0, q0, d0[0]
uint32x4_t vmlag_n_u32(uint32x4_t a, uint32x4_t b, uint32_t c);
                                                                      // VMLA.I32 q0, q0, d0[0]
float32x4_t vmlag_n_f32(float32x4_t a, float32x4_t b, float32_t c);
                                                                     // VMLA.F32 q0, q0, d0[0]
```

Vector widening multiply accumulate with scalar

Vector widening saturating doubling multiply accumulate with scalar

```
int32x4_t vqdmlal_n_s16(int32x4_t a, int16x4_t b, int16_t c); // VQDMLAL.S16 q0, d0 [0] int64x2_t vqdmlal_n_s32(int64x2_t a, int32x2_t b, int32_t c); // VQDMLAL.S32 q0, d0 [0]
```

Vector multiply subtract with scalar

```
int16x4_t vmls_n_s16(int16x4_t a, int16x4_t b, int16_t c);
                                                                   // VMLS.I16 d0, d0, d0[0]
int32x2_t vmls_n_s32(int32x2_t a, int32x2_t b, int32_t c);
                                                                   // VMLS.I32 d0, d0, d0[0]
uint16x4_t vmls_n_u16(uint16x4_t a, uint16x4_t b, uint16_t c);
                                                                   // VMLS.I16 d0, d0, d0[0]
uint32x2_t vmls_n_u32(uint32x2_t a, uint32x2_t b, uint32_t c);
                                                                   // VMLS.I32 d0, d0, d0[0]
float32x2_t vmls_n_f32(float32x2_t a, float32x2_t b, float32_t c); // VMLS.F32 d0, d0[0]
int16x8_t 	 vmlsq_n_s16(int16x8_t a, int16x8_t b, int16_t c);
                                                                   // VMLS.I16 q0, q0, d0[0]
int32x4_t vmlsq_n_s32(int32x4_t a, int32x4_t b, int32_t c);
                                                                   // VMLS.I32 q0, q0, d0[0]
uint16x8_t vmlsq_n_u16(uint16x8_t a, uint16x8_t b, uint16_t c);
                                                                   // VMLS.I16 q0, q0, d0[0]
uint32x4_t vmlsq_n_u32(uint32x4_t a, uint32x4_t b, uint32_t c);
                                                                   // VMLS.I32 q0, q0, d0[0]
float32x4_t vmlsq_n_f32(float32x4_t a, float32x4_t b, float32_t c); // VMLS.F32 q0, q0, d0[0]
```

Vector widening multiply subtract with scalar

Vector widening saturating doubling multiply subtract with scalar

```
int32x4_t vqdmlsl_n_s16(int32x4_t a, int16x4_t b, int16_t c); // VQDMLSL.S16 q0, d0 [0] int64x2_t vqdmlsl_n_s32(int64x2_t a, int32x2_t b, int32_t c); // VQDMLSL.S32 q0, d0, d0 [0]
```

E.3.26 Vector extract

```
vext_s8(int8x8_t a, int8x8_t b, __constrange(0,7) int c);
                                                                          // VEXT.8 d0,d0,d0,#0
uint8x8_t vext_u8(uint8x8_t a, uint8x8_t b, __constrange(0,7) int c);
                                                                          // VEXT.8 d0,d0,d0,#0
poly8x8_t vext_p8(poly8x8_t a, poly8x8_t b, __constrange(0,7) int c);
                                                                          // VEXT.8 d0,d0,d0,#0
int16x4_t vext_s16(int16x4_t a, int16x4_t b, __constrange(0,3) int c);
                                                                          // VEXT.16 d0,d0,d0,#0
uint16x4_t vext_u16(uint16x4_t a, uint16x4_t b, __constrange(0,3) int c); // VEXT.16 d0,d0,d0,#0
poly16x4_t vext_p16(poly16x4_t a, poly16x4_t b, __constrange(0,3) int c); // VEXT.16 d0,d0,d0,#0
int32x2_t vext_s32(int32x2_t a, int32x2_t b, __constrange(0,1) int c);
                                                                          // VEXT.32 d0,d0,d0,#0
uint32x2_t vext_u32(uint32x2_t a, uint32x2_t b, __constrange(0,1) int c); // VEXT.32 d0,d0,d0,#0
int64x1_t vext_s64(int64x1_t a, int64x1_t b, __constrange(0,0) int c);
                                                                          // VEXT.64 d0,d0,d0,#0
uint64x1_t vext_u64(uint64x1_t a, uint64x1_t b, __constrange(0,0) int c); // VEXT.64 d0,d0,d0,#0
int8x16_t vextq_s8(int8x16_t a, int8x16_t b, __constrange(0,15) int c); // VEXT.8 q0,q0,q0,#0
uint8x16_t vextq_u8(uint8x16_t a, uint8x16_t b, __constrange(0,15) int c); // VEXT.8 q0,q0,q0,#0
poly8x16_t vextq_p8(poly8x16_t a, poly8x16_t b, __constrange(0,15) int c); // VEXT.8 q0,q0,q0,#0
int16x8_t vextq_s16(int16x8_t a, int16x8_t b, __constrange(0,7) int c); // VEXT.16 q0,q0,q0,#0
uint16x8_t vextq_u16(uint16x8_t a, uint16x8_t b, __constrange(0,7) int c); // VEXT.16 q0,q0,q0,#0
poly16x8_t vextq_p16(poly16x8_t a, poly16x8_t b, __constrange(0,7) int c); // VEXT.16 q0,q0,q0,#0
int32x4_t vextq_s32(int32x4_t a, int32x4_t b, __constrange(0,3) int c); // VEXT.32 q0,q0,q0,#0
uint32x4_t vextq_u32(uint32x4_t a, uint32x4_t b, __constrange(0,3) int c); // VEXT.32 q0,q0,q0,#0
int64x2_t vextq_s64(int64x2_t a, int64x2_t b, __constrange(0,1) int c); // VEXT.64 q0,q0,q0,#0
uint64x2_t vextq_u64(uint64x2_t a, uint64x2_t b, __constrange(0,1) int c); // VEXT.64 q0,q0,q0,#0
```

E.3.27 Reverse vector elements (swap endianness)

VREVn.m reverses the order of the m-bit lanes within a set that is n bits wide.

```
int8x8 t
            vrev64_s8(int8x8_t vec);
                                          // VREV64.8 d0,d0
int16x4 t
            vrev64 s16(int16x4 t vec):
                                          // VREV64.16 d0.d0
int32x2_t
            vrev64_s32(int32x2_t vec);
                                          // VREV64.32 d0,d0
uint8x8 t
            vrev64_u8(uint8x8_t vec);
                                          // VREV64.8 d0,d0
uint16x4_t
            vrev64_u16(uint16x4_t vec);
                                          // VREV64.16 d0,d0
                                          // VREV64.32 d0.d0
uint32x2 t
            vrev64_u32(uint32x2_t vec);
poly8x8_t
            vrev64_p8(poly8x8_t vec);
                                          // VREV64.8 d0,d0
polv16x4 t
            vrev64_p16(poly16x4_t vec);
                                          // VREV64.16 d0.d0
float32x2_t vrev64_f32(float32x2_t vec); // VREV64.32 d0,d0
```

```
// VREV64.8 q0,q0
int8x16_t
             vrev64q_s8(int8x16_t vec);
int16x8_t
             vrev64g_s16(int16x8_t vec);
                                           // VREV64.16 q0,q0
int32x4_t
             vrev64q_s32(int32x4_t vec);
                                           // VREV64.32 q0,q0
uint8x16_t
             vrev64g_u8(uint8x16_t vec);
                                           // VREV64.8 q0,q0
                                           // VREV64.16 q0,q0
uint16x8_t
             vrev64q_u16(uint16x8_t vec);
uint32x4_t
             vrev64q_u32(uint32x4_t vec);
                                           // VREV64.32 q0,q0
poly8x16_t
             vrev64q_p8(poly8x16_t vec);
                                           // VREV64.8 q0,q0
poly16x8_t
             vrev64q_p16(poly16x8_t vec);
                                          // VREV64.16 q0,q0
float32x4_t
             vrev64g_f32(float32x4_t vec); // VREV64.32 g0.g0
int8x8_t
             vrev32_s8(int8x8_t vec);
                                           // VREV32.8 d0,d0
int16x4_t
             vrev32_s16(int16x4_t vec);
                                           // VREV32.16 d0,d0
uint8x8_t
             vrev32_u8(uint8x8_t vec);
                                           // VREV32.8 d0,d0
             vrev32_u16(uint16x4_t vec);
uint16x4_t
                                           // VREV32.16 d0,d0
poly8x8_t
             vrev32_p8(poly8x8_t vec);
                                           // VREV32.8 d0,d0
int8x16_t
             vrev32q_s8(int8x16_t vec);
                                           // VREV32.8 q0,q0
int16x8 t
             vrev32q_s16(int16x8_t vec);
                                           // VREV32.16 q0,q0
uint8x16_t
             vrev32q_u8(uint8x16_t vec);
                                           // VREV32.8 q0,q0
uint16x8_t
             vrev32g_u16(uint16x8_t vec);
                                          // VREV32.16 q0,q0
poly8x16_t
             vrev32q_p8(poly8x16_t vec);
                                           // VREV32.8 q0,q0
int8x8_t
                                           // VREV16.8 d0,d0
             vrev16_s8(int8x8_t vec);
uint8x8_t
             vrev16_u8(uint8x8_t vec);
                                           // VREV16.8 d0,d0
poly8x8_t
             vrev16_p8(poly8x8_t vec);
                                           // VREV16.8 d0,d0
int8x16_t
             vrev16q_s8(int8x16_t vec);
                                           // VREV16.8 q0,q0
uint8x16_t
             vrev16q_u8(uint8x16_t vec);
                                           // VREV16.8 q0,q0
poly8x16_t
             vrev16q_p8(poly8x16_t vec);
                                           // VREV16.8 q0,q0
```

E.3.28 Other single operand arithmetic

These intrinsics provide other single operand arithmetic.

Absolute: Vd[i] = |Va[i]|

```
int8x8_t
            vabs_s8(int8x8_t a);
                                       // VABS.S8 d0,d0
int16x4_t
           vabs_s16(int16x4_t a);
                                       // VABS.S16 d0,d0
int32x2_t
           vabs_s32(int32x2_t a);
                                      // VABS.S32 d0,d0
float32x2_t vabs_f32(float32x2_t a);
                                      // VABS.F32 d0,d0
int8x16_t
           vabsq_s8(int8x16_t a);
                                       // VABS.S8 q0,q0
int16x8_t
           vabsq_s16(int16x8_t a);
                                      // VABS.S16 q0,q0
int32x4_t
            vabsq_s32(int32x4_t a);
                                       // VABS.S32 q0,q0
float32x4_t vabsq_f32(float32x4_t a); // VABS.F32 q0,q0
```

Saturating absolute: Vd[i] = sat(|Va[i]|)

Negate: Vd[i] = - Va[i]

```
int8x8_t
           vneg_s8(int8x8_t a);
                                     // VNEG.S8 d0,d0
int16x4_t
           vneg_s16(int16x4_t a);
                                     // VNEG.S16 d0,d0
int32x2_t
           vneg_s32(int32x2_t a);
                                     // VNEG.S32 d0,d0
float32x2_t vneq_f32(float32x2_t a);
                                     // VNEG.F32 d0,d0
int8x16_t vnegq_s8(int8x16_t a);
                                     // VNEG.S8 q0,q0
int16x8_t
           vnegq_s16(int16x8_t a);
                                     // VNEG.S16 q0,q0
int32x4_t
           vnegq_s32(int32x4_t a);
                                     // VNEG.S32 q0,q0
float32x4_t vnegq_f32(float32x4_t a); // VNEG.F32 q0,q0
```

Saturating Negate: sat(Vd[i] = - Va[i])

Count leading sign bits

Count leading zeros

```
int8x8_t vclz_s8(int8x8_t a);
                                    // VCLZ.I8 d0,d0
int16x4_t vclz_s16(int16x4_t a);
                                    // VCLZ.I16 d0,d0
int32x2_t vclz_s32(int32x2_t a);
                                    // VCLZ.I32 d0,d0
                                   // VCLZ.I8 d0,d0
uint8x8_t vclz_u8(uint8x8_t a);
                                  // VCLZ.I16 d0,d0
uint16x4_t vclz_u16(uint16x4_t a);
uint32x2_t vclz_u32(uint32x2_t a); // VCLZ.I32 d0,d0
                                    // VCLZ.I8 q0,q0
int8x16_t vclzq_s8(int8x16_t a);
int16x8_t vclzq_s16(int16x8_t a);
                                  // VCLZ.I16 q0,q0
int32x4_t vclzq_s32(int32x4_t a);
                                   // VCLZ.I32 q0,q0
uint8x16_t vclzq_u8(uint8x16_t a);
                                   // VCLZ.I8 q0,q0
uint16x8_t vclzg_u16(uint16x8_t a); // VCLZ.I16 q0,q0
uint32x4_t vclzq_u32(uint32x4_t a); // VCLZ.I32 q0,q0
```

Count number of set bits

Reciprocal estimate

```
float32x2_t vrecpe_f32(float32x2_t a);  // VRECPE.F32 d0,d0
uint32x2_t vrecpe_u32(uint32x2_t a);  // VRECPE.U32 d0,d0
float32x4_t vrecpeq_f32(float32x4_t a);  // VRECPE.F32 q0,q0
uint32x4_t vrecpeq_u32(uint32x4_t a);  // VRECPE.U32 q0,q0
```

Reciprocal square root estimate

```
float32x2_t vrsqrte_f32(float32x2_t a); // VRSQRTE.F32 d0,d0 uint32x2_t vrsqrte_u32(uint32x2_t a); // VRSQRTE.U32 d0,d0 float32x4_t vrsqrteq_f32(float32x4_t a); // VRSQRTE.F32 q0,q0 uint32x4_t vrsqrteq_u32(uint32x4_t a); // VRSQRTE.U32 q0,q0
```

E.3.29 Logical operations

These intrinsics provide bitwise logical operations.

Bitwise not

```
int8x8_t vmvn_s8(int8x8_t a);
                                   // VMVN d0,d0
int16x4_t vmvn_s16(int16x4_t a);
                                   // VMVN d0,d0
int32x2_t vmvn_s32(int32x2_t a);
                                   // VMVN d0,d0
uint8x8_t vmvn_u8(uint8x8_t a);
                                   // VMVN d0,d0
uint16x4_t vmvn_u16(uint16x4_t a);
                                   // VMVN d0,d0
uint32x2_t vmvn_u32(uint32x2_t a);
                                   // VMVN d0,d0
                                   // VMVN d0,d0
poly8x8_t vmvn_p8(poly8x8_t a);
int8x16_t vmvnq_s8(int8x16_t a);
                                    // VMVN q0,q0
                                   // VMVN q0,q0
int16x8_t vmvnq_s16(int16x8_t a);
int32x4_t vmvnq_s32(int32x4_t a);
                                   // VMVN q0,q0
uint8x16_t vmvnq_u8(uint8x16_t a);
                                   // VMVN q0,q0
uint16x8_t vmvnq_u16(uint16x8_t a); // VMVN q0,q0
uint32x4_t vmvnq_u32(uint32x4_t a); // VMVN q0,q0
poly8x16_t vmvnq_p8(poly8x16_t a);
                                   // VMVN q0,q0
```

Bitwise and

```
int8x8_t
          vand_s8(int8x8_t a, int8x8_t b);
                                                  // VAND d0,d0,d0
int16x4_t vand_s16(int16x4_t a, int16x4_t b);
                                                   // VAND d0,d0,d0
int32x2_t vand_s32(int32x2_t a, int32x2_t b);
                                                  // VAND d0,d0,d0
int64x1_t vand_s64(int64x1_t a, int64x1_t b);
                                                   // VAND d0,d0,d0
                                                  // VAND d0,d0,d0
uint8x8_t vand_u8(uint8x8_t a, uint8x8_t b);
uint16x4_t vand_u16(uint16x4_t a, uint16x4_t b);
                                                  // VAND d0,d0,d0
uint32x2_t vand_u32(uint32x2_t a, uint32x2_t b);
                                                  // VAND d0,d0,d0
uint64x1_t vand_u64(uint64x1_t a, uint64x1_t b);
                                                  // VAND d0,d0,d0
int8x16_t vandq_s8(int8x16_t a, int8x16_t b);
                                                   // VAND q0,q0,q0
int16x8_t vandq_s16(int16x8_t a, int16x8_t b);
                                                   // VAND q0,q0,q0
int32x4_t vandq_s32(int32x4_t a, int32x4_t b);
                                                  // VAND q0,q0,q0
int64x2_t vandq_s64(int64x2_t a, int64x2_t b);
                                                  // VAND q0,q0,q0
uint8x16_t vandq_u8(uint8x16_t a, uint8x16_t b);
                                                   // VAND q0,q0,q0
uint16x8_t vandq_u16(uint16x8_t a, uint16x8_t b);
                                                  // VAND q0,q0,q0
uint32x4_t vandq_u32(uint32x4_t a, uint32x4_t b); // VAND q0,q0,q0
uint64x2_t vandq_u64(uint64x2_t a, uint64x2_t b); // VAND q0,q0,q0
```

Bitwise or

```
int8x8_t vorr_s8(int8x8_t a, int8x8_t b);
                                                   // VORR d0,d0,d0
int16x4_t vorr_s16(int16x4_t a, int16x4_t b);
                                                   // VORR d0,d0,d0
int32x2_t vorr_s32(int32x2_t a, int32x2_t b);
                                                   // VORR d0, d0, d0
int64x1_t vorr_s64(int64x1_t a, int64x1_t b);
                                                   // VORR d0, d0, d0
uint8x8_t vorr_u8(uint8x8_t a, uint8x8_t b);
                                                   // VORR d0, d0, d0
uint16x4_t vorr_u16(uint16x4_t a, uint16x4_t b);
                                                   // VORR d0, d0, d0
uint32x2_t vorr_u32(uint32x2_t a, uint32x2_t b);
                                                   // VORR d0,d0,d0
uint64x1_t vorr_u64(uint64x1_t a, uint64x1_t b);
                                                   // VORR d0, d0, d0
int8x16_t vorrg_s8(int8x16_t a, int8x16_t b);
                                                   // VORR q0,q0,q0
int16x8_t vorrg_s16(int16x8_t a, int16x8_t b);
                                                   // VORR q0,q0,q0
int32x4_t vorrq_s32(int32x4_t a, int32x4_t b);
                                                   // VORR q0,q0,q0
int64x2_t vorrq_s64(int64x2_t a, int64x2_t b);
                                                   // VORR q0,q0,q0
uint8x16_t vorrq_u8(uint8x16_t a, uint8x16_t b);
                                                   // VORR q0,q0,q0
uint16x8_t vorrq_u16(uint16x8_t a, uint16x8_t b); // VORR q0,q0,q0
uint32x4_t vorrg_u32(uint32x4_t a, uint32x4_t b);
                                                  // VORR q0,q0,q0
uint64x2_t vorrq_u64(uint64x2_t a, uint64x2_t b); // VORR q0,q0,q0
```

Bitwise exclusive or (EOR or XOR)

```
int8x8_t
          veor_s8(int8x8_t a, int8x8_t b);
                                                   // VEOR d0,d0,d0
int16x4_t veor_s16(int16x4_t a, int16x4_t b);
                                                   // VEOR d0,d0,d0
int32x2_t veor_s32(int32x2_t a, int32x2_t b);
                                                   // VEOR d0,d0,d0
int64x1_t veor_s64(int64x1_t a, int64x1_t b);
                                                   // VEOR d0,d0,d0
uint8x8_t veor_u8(uint8x8_t a, uint8x8_t b);
                                                   // VEOR d0,d0,d0
uint16x4_t veor_u16(uint16x4_t a, uint16x4_t b);
                                                   // VEOR d0,d0,d0
uint32x2_t veor_u32(uint32x2_t a, uint32x2_t b);
                                                   // VEOR d0,d0,d0
uint64x1_t veor_u64(uint64x1_t a, uint64x1_t b);
                                                   // VEOR d0, d0, d0
int8x16_t veorg_s8(int8x16_t a, int8x16_t b);
                                                   // VEOR q0,q0,q0
```

Blt Clear

```
int8x8_t
          vbic_s8(int8x8_t a, int8x8_t b);
                                                   // VBIC d0,d0,d0
int16x4_t vbic_s16(int16x4_t a, int16x4_t b);
                                                   // VBIC d0,d0,d0
int32x2_t vbic_s32(int32x2_t a, int32x2_t b);
                                                   // VBIC d0,d0,d0
int64x1_t vbic_s64(int64x1_t a, int64x1_t b);
                                                   // VBIC d0,d0,d0
uint8x8_t vbic_u8(uint8x8_t a, uint8x8_t b);
                                                   // VBIC d0,d0,d0
                                                   // VBIC d0,d0,d0
uint16x4_t vbic_u16(uint16x4_t a, uint16x4_t b);
uint32x2_t vbic_u32(uint32x2_t a, uint32x2_t b);
                                                   // VBIC d0,d0,d0
uint64x1_t vbic_u64(uint64x1_t a, uint64x1_t b);
                                                   // VBIC d0,d0,d0
int8x16_t vbicg_s8(int8x16_t a, int8x16_t b);
                                                   // VBIC q0,q0,q0
int16x8_t vbicq_s16(int16x8_t a, int16x8_t b);
                                                   // VBIC q0,q0,q0
int32x4_t vbicq_s32(int32x4_t a, int32x4_t b);
                                                   // VBIC q0,q0,q0
int64x2_t vbicq_s64(int64x2_t a, int64x2_t b);
                                                   // VBIC q0,q0,q0
uint8x16_t vbicq_u8(uint8x16_t a, uint8x16_t b);
                                                   // VBIC q0,q0,q0
uint16x8_t vbicg_u16(uint16x8_t a, uint16x8_t b);
                                                  // VBIC q0,q0,q0
uint32x4_t vbicq_u32(uint32x4_t a, uint32x4_t b); // VBIC q0,q0,q0
uint64x2_t vbicq_u64(uint64x2_t a, uint64x2_t b); // VBIC q0,q0,q0
```

Bitwise OR complement

```
// VORN d0,d0,d0
int8x8_t
         vorn_s8(int8x8_t a, int8x8_t b);
int16x4_t vorn_s16(int16x4_t a, int16x4_t b);
                                                   // VORN d0,d0,d0
                                                  // VORN d0,d0,d0
int32x2_t vorn_s32(int32x2_t a, int32x2_t b);
int64x1_t vorn_s64(int64x1_t a, int64x1_t b);
                                                  // VORN d0,d0,d0
                                                  // VORN d0,d0,d0
uint8x8_t vorn_u8(uint8x8_t a, uint8x8_t b);
                                                  // VORN d0,d0,d0
uint16x4_t vorn_u16(uint16x4_t a, uint16x4_t b);
uint32x2_t vorn_u32(uint32x2_t a, uint32x2_t b);
                                                  // VORN d0,d0,d0
uint64x1_t vorn_u64(uint64x1_t a, uint64x1_t b);
                                                  // VORN d0,d0,d0
int8x16_t vornq_s8(int8x16_t a, int8x16_t b);
                                                  // VORN q0,q0,q0
int16x8_t vorng_s16(int16x8_t a, int16x8_t b);
                                                  // VORN q0,q0,q0
                                                  // VORN q0,q0,q0
int32x4_t vornq_s32(int32x4_t a, int32x4_t b);
int64x2_t vorng_s64(int64x2_t a, int64x2_t b);
                                                  // VORN q0,q0,q0
uint8x16_t vornq_u8(uint8x16_t a, uint8x16_t b);
                                                  // VORN q0,q0,q0
uint16x8_t vorng_u16(uint16x8_t a, uint16x8_t b);
                                                  // VORN q0,q0,q0
uint32x4t vornq_u32(uint32x4t a, uint32x4t b); // VORN q0,q0,q0
uint64x2_t vornq_u64(uint64x2_t a, uint64x2_t b);
                                                  // VORN q0,q0,q0
```

Bitwise Select



This intrinsic can compile to any of VBSL/VBIF/VBIT depending on register allocation.

```
vbsl_s8(uint8x8_t a, int8x8_t b, int8x8_t c);
int8x8_t
                                                                   // VBSL d0,d0,d0
                                                                   // VBSL d0,d0,d0
int16x4_t
            vbsl_s16(uint16x4_t a, int16x4_t b, int16x4_t c);
int32x2_t
            vbsl_s32(uint32x2_t a, int32x2_t b, int32x2_t c);
                                                                   // VBSL d0,d0,d0
            vbsl_s64(uint64x1_t a, int64x1_t b, int64x1_t c);
                                                                   // VBSL d0,d0,d0
int64x1_t
uint8x8_t
            vbsl_u8(uint8x8_t a, uint8x8_t b, uint8x8_t c);
                                                                   // VBSL d0,d0,d0
uint16x4_t vbsl_u16(uint16x4_t a, uint16x4_t b, uint16x4_t c);
                                                                   // VBSL d0,d0,d0
uint32x2_t vbsl_u32(uint32x2_t a, uint32x2_t b, uint32x2_t c);
                                                                   // VBSL d0,d0,d0
uint64x1_t vbsl_u64(uint64x1_t a, uint64x1_t b, uint64x1_t c);
                                                                   // VBSL d0,d0,d0
float32x2_t vbs1_f32(uint32x2_t a, float32x2_t b, float32x2_t c);
                                                                  // VBSL d0,d0,d0
poly8x8_t
            vbsl_p8(uint8x8_t a, poly8x8_t b, poly8x8_t c);
                                                                   // VBSL d0,d0,d0
poly16x4_t vbsl_p16(uint16x4_t a, poly16x4_t b, poly16x4_t c);
                                                                   // VBSL d0,d0,d0
            vbslq_s8(uint8x16_t a, int8x16_t b, int8x16_t c);
                                                                   // VBSL q0,q0,q0
int8x16_t
            vbslq_s16(uint16x8_t a, int16x8_t b, int16x8_t c);
int16x8_t
                                                                   // VBSL q0,q0,q0
            vbslq_s32(uint32x4_t a, int32x4_t b, int32x4_t c);
                                                                   // VBSL q0,q0,q0
int32x4_t
            vbslq_s64(uint64x2_t a, int64x2_t b, int64x2_t c);
int64x2_t
                                                                   // VBSL q0,q0,q0
uint8x16_t vbslq_u8(uint8x16_t a, uint8x16_t b, uint8x16_t c);
                                                                   // VBSL q0,q0,q0
uint16x8_t vbslq_u16(uint16x8_t a, uint16x8_t b, uint16x8_t c);
                                                                   // VBSL q0,q0,q0
uint32x4_t vbslq_u32(uint32x4_t a, uint32x4_t b, uint32x4_t c);
                                                                   // VBSL q0,q0,q0
uint64x2_t vbslq_u64(uint64x2_t a, uint64x2_t b, uint64x2_t c);
                                                                   // VBSL q0,q0,q0
float32x4_t vbslq_f32(uint32x4_t a, float32x4_t b, float32x4_t c); // VBSL q0,q0,q0
poly8x16_t vbslg_p8(uint8x16_t a, poly8x16_t b, poly8x16_t c);
                                                                   // VBSL q0,q0,q0
poly16x8_t vbslq_p16(uint16x8_t a, poly16x8_t b, poly16x8_t c);
                                                                   // VBSL q0,q0,q0
```

E.3.30 Transposition operations

These intrinsics provide transposition operations.

Transpose elments

```
int8x8x2_t
             vtrn_s8(int8x8_t a, int8x8_t b);
                                                       // VTRN.8 d0,d0
int16x4x2_t
             vtrn_s16(int16x4_t a, int16x4_t b);
                                                       // VTRN.16 d0,d0
             vtrn_s32(int32x2_t a, int32x2_t b);
int32x2x2_t
                                                       // VTRN.32 d0,d0
uint8x8x2_t
             vtrn_u8(uint8x8_t a, uint8x8_t b);
                                                       // VTRN.8 d0,d0
uint16x4x2_t vtrn_u16(uint16x4_t a, uint16x4_t b);
                                                       // VTRN.16 d0,d0
uint32x2x2_t vtrn_u32(uint32x2_t a, uint32x2_t b);
                                                       // VTRN.32 d0,d0
float32x2x2_t vtrn_f32(float32x2_t a, float32x2_t b); // VTRN.32 d0,d0
             vtrn_p8(poly8x8_t a, poly8x8_t b);
poly8x8x2_t
                                                       // VTRN.8 d0,d0
poly16x4x2_t vtrn_p16(poly16x4_t a, poly16x4_t b);
                                                       // VTRN.16 d0,d0
int8x16x2_t
             vtrnq_s8(int8x16_t a, int8x16_t b);
                                                       // VTRN.8 q0,q0
int16x8x2_t
             vtrnq_s16(int16x8_t a, int16x8_t b);
                                                       // VTRN.16 q0,q0
int32x4x2_t
              vtrng_s32(int32x4_t a, int32x4_t b);
                                                       // VTRN.32 q0,q0
uint8x16x2_t vtrnq_u8(uint8x16_t a, uint8x16_t b);
                                                       // VTRN.8 q0,q0
```

```
uint16x8x2_t vtrnq_u16(uint16x8_t a, uint16x8_t b);  // VTRN.16 q0,q0
uint32x4x2_t vtrnq_u32(uint32x4_t a, uint32x4_t b);  // VTRN.32 q0,q0
float32x4x2_t vtrnq_f32(float32x4_t a, float32x4_t b);  // VTRN.32 q0,q0
poly8x16x2_t vtrnq_p8(poly8x16_t a, poly8x16_t b);  // VTRN.8 q0,q0
poly16x8x2_t vtrnq_p16(poly16x8_t a, poly16x8_t b);  // VTRN.16 q0,q0
```

Interleave elements

```
int8x8x2 t
             vzip_s8(int8x8_t a, int8x8_t b);
                                                      // VZIP.8 d0,d0
int16x4x2_t
             vzip_s16(int16x4_t a, int16x4_t b);
                                                      // VZIP.16 d0,d0
uint8x8x2_t
             vzip_u8(uint8x8_t a, uint8x8_t b);
                                                      // VZIP.8 d0,d0
                                                      // VZIP.16 d0,d0
uint16x4x2_t vzip_u16(uint16x4_t a, uint16x4_t b);
float32x2x2_t vzip_f32(float32x2_t a, float32x2_t b);
                                                      // VZIP.32 d0,d0
                                                      // VZIP.8 d0,d0
poly8x8x2_t
             vzip_p8(poly8x8_t a, poly8x8_t b);
poly16x4x2_t vzip_p16(poly16x4_t a, poly16x4_t b);
                                                      // VZIP.16 d0,d0
int8x16x2_t
             vzipq_s8(int8x16_t a, int8x16_t b);
                                                      // VZIP.8 q0,q0
             vzipq_s16(int16x8_t a, int16x8_t b);
                                                      // VZIP.16 q0,q0
int16x8x2_t
int32x4x2_t
             vzipq_s32(int32x4_t a, int32x4_t b);
                                                      // VZIP.32 q0,q0
uint8x16x2_t vzipq_u8(uint8x16_t a, uint8x16_t b);
                                                      // VZIP.8 q0,q0
uint16x8x2_t vzipq_u16(uint16x8_t a, uint16x8_t b);
                                                      // VZIP.16 q0,q0
uint32x4x2_t vzipq_u32(uint32x4_t a, uint32x4_t b);
                                                      // VZIP.32 q0,q0
float32x4x2_t vzipq_f32(float32x4_t a, float32x4_t b); // VZIP.32 q0,q0
poly8x16x2_t vzipq_p8(poly8x16_t a, poly8x16_t b);
                                                      // VZIP.8 q0,q0
poly16x8x2_t vzipq_p16(poly16x8_t a, poly16x8_t b);
                                                      // VZIP.16 q0,q0
```

De-Interleave elements

```
int8x8x2_t
             vuzp_s8(int8x8_t a, int8x8_t b);
                                                       // VUZP.8 d0,d0
                                                      // VUZP.16 d0,d0
int16x4x2_t
             vuzp_s16(int16x4_t a, int16x4_t b);
                                                      // VUZP.32 d0,d0
int32x2x2_t
             vuzp_s32(int32x2_t a, int32x2_t b);
uint8x8x2_t
             vuzp_u8(uint8x8_t a, uint8x8_t b);
                                                      // VUZP.8 d0,d0
uint16x4x2_t vuzp_u16(uint16x4_t a, uint16x4_t b);
                                                      // VUZP.16 d0,d0
uint32x2x2_t vuzp_u32(uint32x2_t a, uint32x2_t b);
                                                      // VUZP.32 d0,d0
float32x2x2_t vuzp_f32(float32x2_t a, float32x2_t b);
                                                      // VUZP.32 d0,d0
             vuzp_p8(poly8x8_t a, poly8x8_t b);
                                                      // VUZP.8 d0,d0
poly8x8x2_t
poly16x4x2_t vuzp_p16(poly16x4_t a, poly16x4_t b);
                                                      // VUZP.16 d0,d0
             vuzpq_s8(int8x16_t a, int8x16_t b);
                                                      // VUZP.8 q0,q0
int8x16x2_t
int16x8x2_t
             vuzpq_s16(int16x8_t a, int16x8_t b);
                                                      // VUZP.16 q0,q0
int32x4x2_t
             vuzpq_s32(int32x4_t a, int32x4_t b);
                                                      // VUZP.32 q0,q0
uint8x16x2_t vuzpq_u8(uint8x16_t a, uint8x16_t b);
                                                      // VUZP.8 q0,q0
uint16x8x2_t vuzpq_u16(uint16x8_t a, uint16x8_t b);
                                                      // VUZP.16 q0,q0
uint32x4x2_t vuzpq_u32(uint32x4_t a, uint32x4_t b);
                                                      // VUZP.32 q0,q0
float32x4x2_t vuzpq_f32(float32x4_t a, float32x4_t b); // VUZP.32 q0,q0
poly8x16x2_t vuzpq_p8(poly8x16_t a, poly8x16_t b);
                                                      // VUZP.8 q0,q0
poly16x8x2_t vuzpq_p16(poly16x8_t a, poly16x8_t b);
                                                      // VUZP.16 q0,q0
```

E.3.31 Vector reinterpret cast operations

In some situations, you might want to treat a vector as having a different type, without changing its value. A set of intrinsics is provided to perform this type of conversion.

Syntax

vreinterpret{q}_dsttype_srctype

Where:

q Specifies that the conversion operates on 128-bit vectors. If it is not

present, the conversion operates on 64-bit vectors.

dsttype Represents the type to convert to.

srctype Represents the type being converted.

Example

The following intrinsic reinterprets a vector of four signed 16-bit integers as a vector of four unsigned integers:

```
uint16x4_t vreinterpret_u16_s16(int16x4_t a);
```

The following intrinsic reinterprets a vector of four 32-bit floating point values integers as a vector of four signed integers.

```
int8x16_t vreinterpretq_s8_f32(float32x4_t a);
```

These conversions do not change the bit pattern represented by the vector.

Using NEON Support