LAPORAN PEMROSESAN PARALEL "EKSEKUSI PROGRAM IMAGE STITCHING"

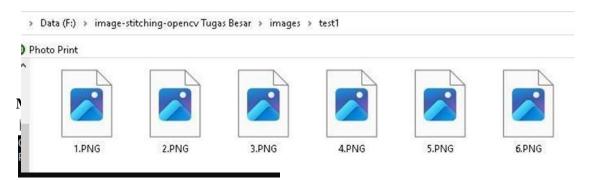


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Bahan/gambar untuk image stitching



Menginstall bebearapa program yang dibutuhkan

Imutil

```
C:\Users\USER>pip install imutils
Collecting imutils
Downloading imutils-0.5.4.tar.gz (17 kB)
Installing build dependencies ... done
Getting requirements to build wheel ... done
Preparing metadata (pyproject.toml) ... done
Building wheels for collected packages: imutils
Building wheel for imutils (pyproject.toml) ... done
Created wheel for imutils: filename=imutils-0.5.4-py3-none-any.whl s
Stored in directory: c:\users\user\appdata\local\pip\cache\wheels\31
Successfully built imutils
Installing collected packages: imutils
Successfully installed imutils-0.5.4
```

Opency

Command Prompt

```
C:\Users\USER>pip install opencv-python
Collecting opencv-python
Obtaining dependency information for opencv-python from https://files.pythonhoste
ncv_python-4.8.1.78-cp37-abi3-win_amd64.whl.metadata
Downloading opencv_python-4.8.1.78-cp37-abi3-win_amd64.whl.metadata (20 kB)
```

Numpy

```
[notice] To update, run: C:\Users\USER\AppData\Local\Microsoft\WindowsApps\R
C:\Users\USER>pip install numpy
Requirement already satisfied: numpy in c:\users\user\appdata\local\packages
-packages (1.26.2)
[notice] A new release of pip is available: 23.2.1 -> 23.3.1
[notice] To update, run: C:\Users\USER\AppData\Local\Microsoft\WindowsApps\R
```

Program yang diperlukan untuk melakukan image stitching

```
from imutils import paths
∰port argparse
import imutils
import cv2
ap = argparse.ArgumentParser()
ap.add_argument("-i", "--images", type=str, required=True,
 help="path to input directory of images to stitch")
ap.add_argument("-o", "--output", type=str, required=True,
 help="path to the output image")
args = vars(ap.parse_args())
print("[INFO] loading images...")
imagePaths = sorted(list(paths.list_images(args["images"])))
images = []
for imagePath in imagePaths:
   image = cv2.imread(imagePath)
    images.append(image)
```

```
print("[INFO] stitching images...")

# Create a Stitcher with a default ORB (feature-based) detector
stitcher = cv2.Stitcher_create(cv2.Stitcher_SCANS)

# Detect keypoints and set camera parameters manually
status, stitched = stitcher_oK:

print("[INFO] Camera parameters adjustment failed. Retrying with manual adjustment...")

# Manually set camera parameters
stitcher.setWaveCorrection(True)
stitcher.setWaveCorrection(True)
stitcher.setFeaturesFinder(cv2.Stitcher_createFeaturesFinder())

# Retry stitching
status, stitched = stitcher.stitch(images)

# print additional information
print("[INFO] Stitching Status:", status)

# if the status is '0', then OpenCV successfully performed image
# stitching
if status == cv2.Stitcher_OK:

# write the output stitched image to disk
cv2.imwrite(args["output"], stitched)

# display the output stitched image to our screen
cv2.Imshow("stitched", stitched)
cv2.waitKey(0)
```

```
# otherwise, the stitching failed
else:

print("[INFO] image stitching failed ({})".format(status))

# print additional information

f status == cv2.Stitcher_ERR_NEED_MORE_IMGS:

print("[INFO] Need more images for stitching.")

elif status == cv2.Stitcher_ERR_HOMOGRAPHY_EST_FAIL:

print("[INFO] Homography estimation failed.")

elif status == cv2.Stitcher_ERR_CAMERA_PARAMS_ADJUST_FAIL:

print("[INFO] Camera parameters adjustment failed.")

elif status == cv2.Stitcher_ERR_MATCH_CONFIDENCE_FAIL:

print("[INFO] Match confidence test failed.")

elif status == cv2.Stitcher_ERR_CAMERA_PARAMS_VERIFY_FAIL:

print("[INFO] Camera parameters verification failed.")

# ... (existing code)
```

Output

