# DAPHNE POON

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#### **EDUCATION**

Harvey Mudd College - Claremont, CA

Expected Graduation: May 2021

Bachelor of Science in Computer Science and Math – Dean's List

3.85 GPA

- · Hong Kong Scholarship for Excellence awardee (> \$30,000 USD per year).
- · Relevant coursework: Autonomous Vehicles, Computability and Logic, Algorithms and Data Structures, Scalable Systems, Combinatorial Optimization, State Estimation, Motion Planning and Control (Spring 2021).

## WORK EXPERIENCE

Lyft Level 5 – Palo Alto, CA

June 2020 - July 2020

 $Software\ Engineer\ Intern\ -\ Compute\ Infrastructure$ 

- · Designed and wrote a Kubernetes deployment controller in Go that adjusts replica counts and limits job scheduling, allowing systems upgrades and maintenance to avoid choking resources.
- · Implemented and onboarded all Compute Infrastructure engineers onto a Python-based CLI, which interacts with the controller's REST API to allow quick deployment scaling.
- $\cdot$  Reduced the time needed to scale Kubernetes deployments from 3 minutes to a matter of seconds.

**Dropbox** – San Francisco, CA

May 2019 - August 2019

Software Engineer Intern - Search Infrastructure

- · Built backend functionality in Go that allows users to filter by co-workers' most recently edited files, something an estimated 10% of Dropbox Business searches previously attempted and failed to do.
- · Parallelized an HBase backfill over 1000 nodes using an internal Hadoop MapReduce analog, to make processing a trillion file edits tractable.

Lab for Autonomous and Intelligent Robotics - Claremont, CA

June 2018 - December 2019

 $Research\ Intern$ 

- · Integrated realtime (200ms latency) autonomous navigation capabilities into a tractor-trailer company's loader vehicles as part of a 2-person team.
- · Developed a model predictive controller in Python that enabled autonomous waypoint navigation, using RRT (a continuous variant of breadth-first search) for the planning phase.
- · Integrated obstacle detection for the planning algorithm with OpenCV and an onboard camera interface.
- · Designed, printed, and installed 3D-printed mounts for the camera, GPS and IMU sensors.

#### LEADERSHIP AND PROJECTS

 ${\bf Committee \ for \ Activities \ Planning} - {\it Harvey \ Mudd \ College}$ 

April 2018 - April 2020

Director

- · Organized off-campus activities for students within our \$30,000 USD annual budget during my two-year term.
- $\cdot$  Increased the number of students going off-campus by over 110% within a year by subsidizing a larger variety of events and making events more accessible with additional transportation options.

Autonomous Ocean Robot - Claremont, CA

April 2019 - May 2019

- · Built an autonomous ocean robot to determine the wind-current relationship near shore
- · Implemented a PD controller and sensor readers in Python and C to maintain position within 1m.

## **SKILLS**

Programming Languages Native Languages Python, Golang (Go), C++, Java. English, Cantonese, Mandarin.