# DAPHNE POON

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#### **EDUCATION**

Harvey Mudd College – Claremont, CA

Expected Graduation: May 2021

Bachelor of Science in Computer Science and Math

3.82 GPA

- · Hong Kong Scholarship for Excellence awardee (> \$30,000 USD per year).
- · Relevant coursework: Autonomous Vehicles, Engineering Systems, Engineering Mathematics, Experimental Engineering, Data Structures and Program Development, Computability and Logic, Algorithms (Spring 2020)

### WORK EXPERIENCE

Lyft Level 5 (Autonomous Vehicles Division) – Palo Alto, CA

June 2020 - August 2020

Incoming Software Engineer Intern - Data Infrastructure

· Exciting things to come!

**Dropbox** – San Francisco, CA

May 2019 - August 2019

 $Software\ Engineer\ Intern\ -\ Search\ Infrastructure$ 

- $\cdot$  Improved user experience for an estimated 10% of Dropbox searches by building backend functionality in Golang to allow filtering by co-workers' most recently edited files.
- · Achieved a 1000x speed up on an HBase backfill over trillions of edits on files by parallelizing batch runs.

 ${\bf Lab~for~Autonomous~and~Intelligent~Robotics}-{\it Claremont}, {\it CA}$ 

June 2018 - December 2019

Autonomous Vehicle Researcher

- · Incorporated autonomous navigation abilities into a confidential multinational tractor-trailer company's loader vehicles using NumPy/Python, saving up to  $\sim 80\%$  of man-hours dedicated to operating the vehicle.
- · Closed a path-following control loop to ensure accurate vehicle motion along a pre-defined path within a 0.5m horizontal error tolerance.
- · Implemented a smoothed RRT path-planning algorithm that prevents collisions and preserves efficiency.
- · Processed camera data using OpenCV to detect and avoid obstacles.

#### PROJECTS AND LEADERSHIP

Autonomous Ocean Robot - Claremont, CA

April 2019 - May 2019

- · Built an autonomous ocean robot to determine the wind-current relationship near shore.
- · Implemented PD control to have robot navigate autonomously to different waypoints and hold its position within a 1m radius of a waypoint while gathering data in turbulent conditions.
- · Designed sensor mounts that could rotate to track the heading of a weather vane using Python and Arduino.

**Autonomous Vehicle Competition** – Claremont, CA

September 2017 - November 2017

- · Designed, programmed and constructed two autonomous robots to play Capture the Flag using Arduino.
- · Placed second out of over twenty teams.

Committee for Activities Planning – Harvey Mudd College

April 2018 - Present

- Director
- · Increased the number of students going off-campus by over 110% within a year.

· Organize off-campus activities for students within our \$30,000 USD annual budget constraint.

## **SKILLS**

**Programming Languages** Python, C++, Go, C, Java.

Tools MATLAB, Git, AutoCAD, SolidWorks.

Native Languages English, Cantonese, Mandarin.

Other Languages French (fluent).