

LaserNumpy

August 29, 2017

1 Numpy with Lasers.

```
In [3]: import numpy as np
import GCode
import GRBL

cnc = GRBL.GRBL(port="/dev/cnc_3018")

print("Laser Mode: {}".format(cnc.laser_mode))
```

Laser Mode: 1.0

```
In [4]: from enum import IntEnum
class LaserPower(IntEnum):
    CONSTANT = 0
    DYNAMIC = 1

def init(power = LaserPower(0), feed = 200, laser = 25):
    program = GCode.GCode()
    program.G21() # Metric Units
    program.G91() # Rel positioning.
    program.G1(F=feed) # Set the feed rate
    program.G0() # But keep the laser off.
    if power==LaserPower.CONSTANT:
        program.M3(S=laser) # Laser settings
    else:
        program.M4(S=laser) # Laser settings
    return program

def end():
    program = GCode.GCode()
    program.M5() # Te
    return program
```

```
In [5]: Tmax = 150
T = np.arange(0, Tmax, 0.25)
```

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In [6]: # Plot Cycles
        cycles = 10

In [7]: T_period = Tmax / cycles
        freq_hz = 1/T_period

In [8]: amplitude = 25
        phase = 0

In [9]: %matplotlib inline

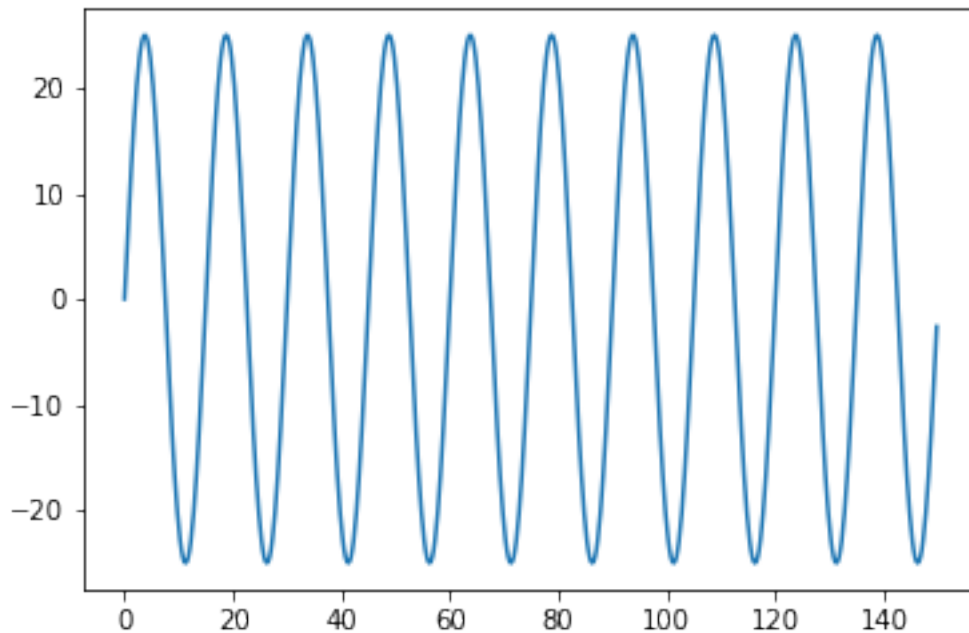
In [10]: import matplotlib.pyplot as plt

In [11]: Y = amplitude*np.sin(2*np.pi*freq_hz*T + phase)

In [12]: plt.plot(T, Y)

Out[12]: [<matplotlib.lines.Line2D at 0x7f99d1e65f98>]

```



```

In [13]: dT, dY = np.diff((T, Y))

In [14]: cnc_sin = GCode.GCode()
        for idx in range(len(dT)):
            cnc_sin.G1(X="{:.4f}".format(dT[idx]),
                       Y="{:.4f}".format(dY[idx]))

In [15]: class SoftKill(Exception):
        pass

```

```
In [16]: try:
            cnc.run(init(laser=255))
            cnc.run(cnc_sin)
            cnc.run(end())
        except KeyboardInterrupt:
            cnc.serial.flushOutput()
            cnc.cmd("!")
            cnc.reset()
            raise(SoftKill("Keyboard"))
```


Traceback (most recent call last)

```
<ipython-input-16-43c7226be5a3> in <module>()
      2      cnc.run(init(laser=255))
----> 3      cnc.run(cnc_sin)
      4      cnc.run(end())

~/python_cnc3018/python_rs274/GRBL/__init__.py in run(self, program, compact)
    120             print(".")
--> 121             results = self.read(multiline=True, timeout=0.1)
    122

~/python_cnc3018/python_rs274/GRBL/__init__.py in read(self, multiline, timeout)
    36         if multiline:
----> 37             responses = self.serial.readlines()
    38             responses = [response.decode().strip() for response in responses]
```

```

~/venv3/lib/python3.5/site-packages/serial/serialposix.py in read(self, size)
482         try:
--> 483             ready, _, _ = select.select([self.fd, self.pipe_abort_read_r], [], [
484                 if self.pipe_abort_read_r in ready:

```

KeyboardInterrupt:

During handling of the above exception, another exception occurred:

```

AssertionError                                Traceback (most recent call last)

<ipython-input-16-43c7226be5a3> in <module>()
      6     cnc.serial.flushOutput()
      7     cnc.cmd("!")
----> 8     cnc.reset()
      9     raise(SoftKill("Keyboard"))

~/python_cnc3018/python_rs274/GRBL/__init__.py in reset(self)
    55         """
    56         ret = self.cmd("\x18")
---> 57         assert(ret[-1] == 'ok')
    58
    59     def sleep(self):

```

AssertionError:

In []: