DataQueue

int mLengthOfQueue; // M+1 int mLengthOfWindow; // N+1

int mLengthOfRecord; // h, = 6 in this case

int mWindowStart; //
int mWindowEnd; //

public void wrapWindowToStart(); // takes last N+1 columns and deep copy to first N+1 columns

- GPU size frame passed to OpenCV -

wrapWindowToStart copies this to window0

				wrapwin	dow robtart copies tills to	WIIIGO W O
aanaan baadan						
sensor header	v v	V		V	V	v
Accelerometer.x	$X_{0,0}$ $X_{0,1}$	<i>X</i> _{0,2}	$X_{0,k}$	$X_{0,k+1}$	$X_{0,M-N}$	$X_{0,M}$
Accelerometer.y	$X_{1,0}$ $X_{1,1}$	<i>X</i> _{1,2}	$X_{1,k}$	$X_{1,k+1}$	$X_{1,M-N}$	$X_{1,M}$
Accelerometer.z	$X_{2,0}$ $X_{2,1}$	<i>X</i> _{2,2}	$X_{2,k}$	$X_{2,k+1}$	$X_{2,M-N}$	$X_{2,M}$
Gyro.x	$X_{3,0}$ $X_{3,1}$	$X_{3,2}$	$X_{3,k}$	$X_{3,k+1}$	$X_{3,M-N}$	$X_{3,M}$
Gyro.y	$X_{4,0}$ $X_{4,1}$	$X_{4,2}$	$X_{4,k}$	$X_{4,k+1}$	$X_{4,M-N}$	$X_{4,M}$
<i>Gyro.z</i>	$X_{5,0}$ $X_{5,1}$	<i>X</i> _{5,2}	$X_{5,k}$	$X_{5,k+1}$	$X_{5,M-N}$	$X_{5,M}$
	- wi	ndow0 window1	-	-	- <u>overla</u>	<u>p</u> -
SDFT	$W_{0,0}$ $W_{0,1}$		$W_{0,k}$	$w_{0,k+1}$	${w_{0,M-N}}$	$W_{0,M}$
	$W_{1,0} W_{1,1}$		$W_{1,k}$	$W_{1,k+1}$	$W_{1,M-N}$	$W_{1,M}$
	$W_{2,0}$ $W_{2,1}$		$W_{2,k}$	$W_{2,k+1}$	$W_{2,M-N}$	$W_{2,M}$
	$W_{3,0}$ $W_{3,1}$		$W_{3,k}$	$W_{3,k+1}$	$W_{3,M-N}$	$W_{3,M}$
	$W_{4,0} W_{4,1}$		$W_{4,k}$	$W_{4,k+1}$	$W_{4,M-N}$	$W_{4,M}$
	$W_{5,0}$ $W_{5,1}$	$W_{5,2}$	$W_{5,k}$	$W_{5,k+1}$	${W}_{5,M-N}$	$W_{5,M}$
filter	$a_{0,0}$ $a_{0,1}$	$a_{0,2}$	$a_{0,k}$			
	$a_{1,0}$ $a_{1,1}$		$a_{1,k}$		SDFT = Sliding Digital Fourrier Transfor	
	$a_{2,0}$ $a_{2,1}$		$a_{2,k}$	SDFT =		
	$a_{3,0}$ $a_{3,1}$	$a_{3,2}$	$a_{3,k}$	551 1 Shang Digital Fourier Transform		
	$a_{4,0}$ $a_{4,1}$	$a_{4,2}$	$a_{4,k}$			
	$a_{5,0}$ $a_{5,1}$	$a_{5,2}$	$a_{5,k}$			
ISDFT (filter * SDFT)	$X_{0,0}$ X_{0}	$X_{0.2}$	$X_{0,k}$	$X_{0,k+1}$	$X_{0,M-N}$	$X_{0,M}$
	$X_{1,0}$ X_1	$X_{1,2}$	$X_{1,k}$		$X_{1,M-N}$	$X_{1,M}$
	$X_{2,0} X_{2}$		$X_{2,k}$		$X_{2,M-N}$	$X_{2,M}$
		$X_{3,2}$		$X_{3,k+1}$	$X_{3,M-N}$	$X_{3,M}$
	$X_{4,0} X_{4}$		$X_{4,k}$		$X_{4,M-N}$	$X_{4,M}$
	$X_{5,0}$ $X_{5,0}$		$X_{5,k}$		$X_{5,M-N}$	$X_{5,M}$
	-,-	-,-	-,	-,	-,	-,