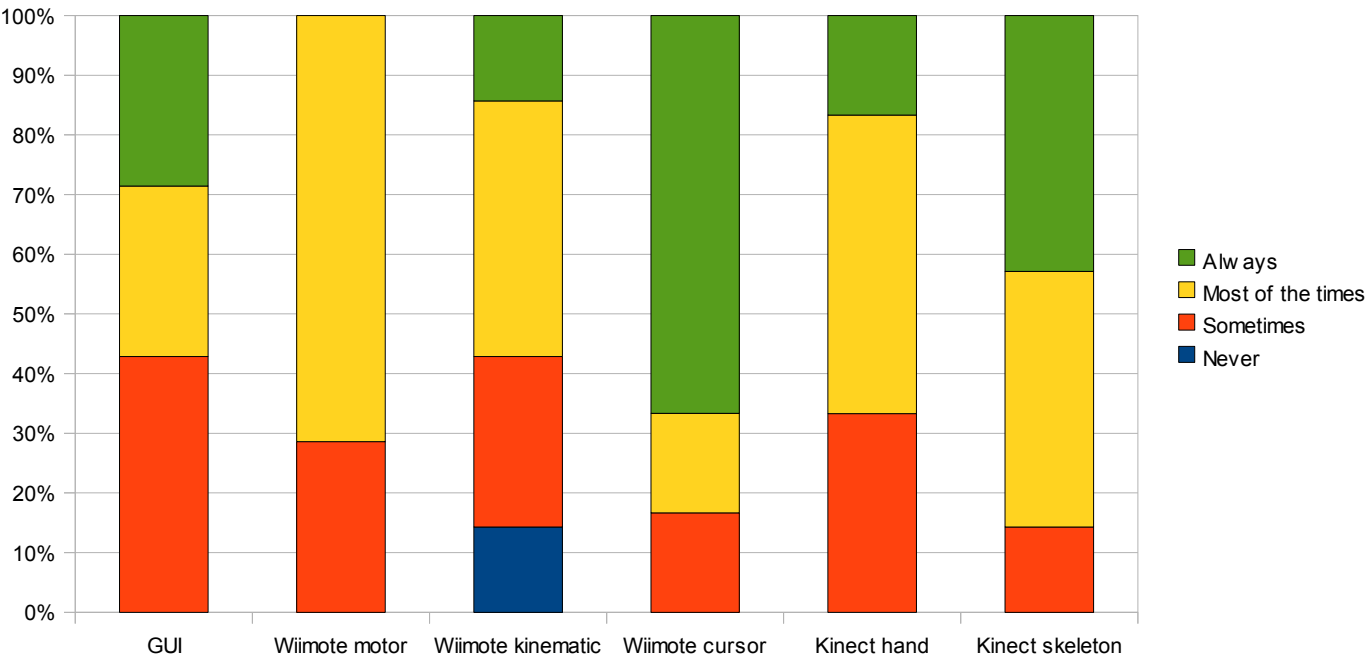
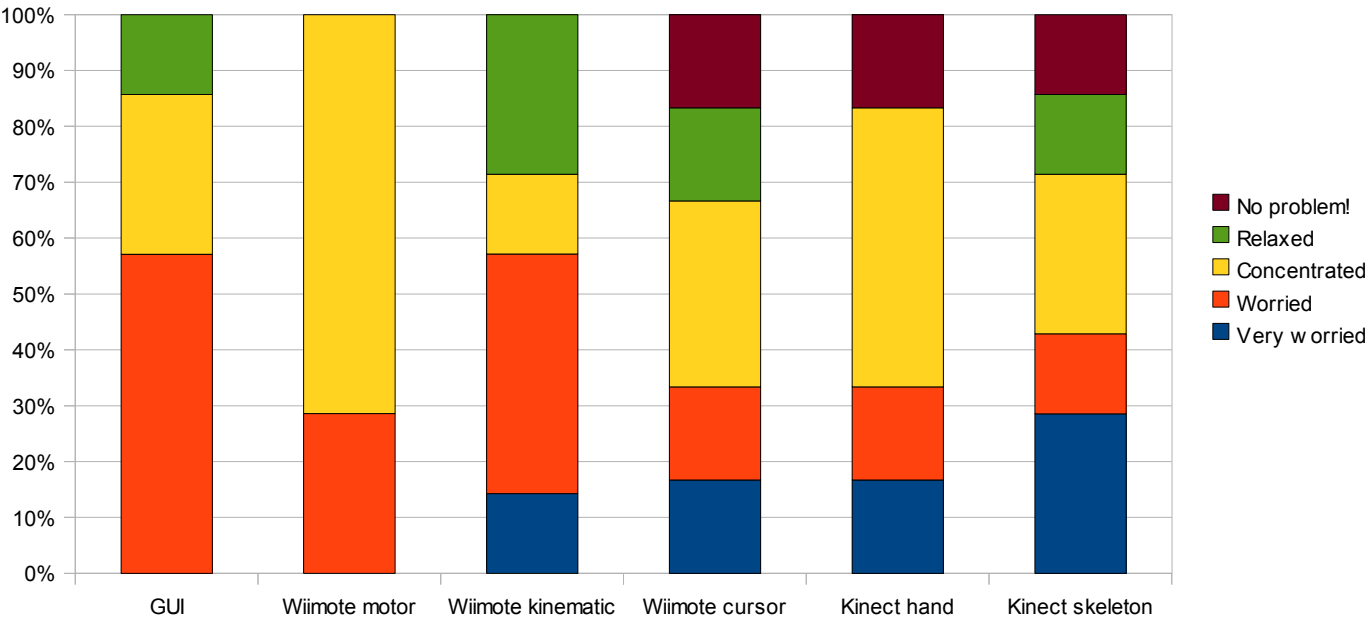


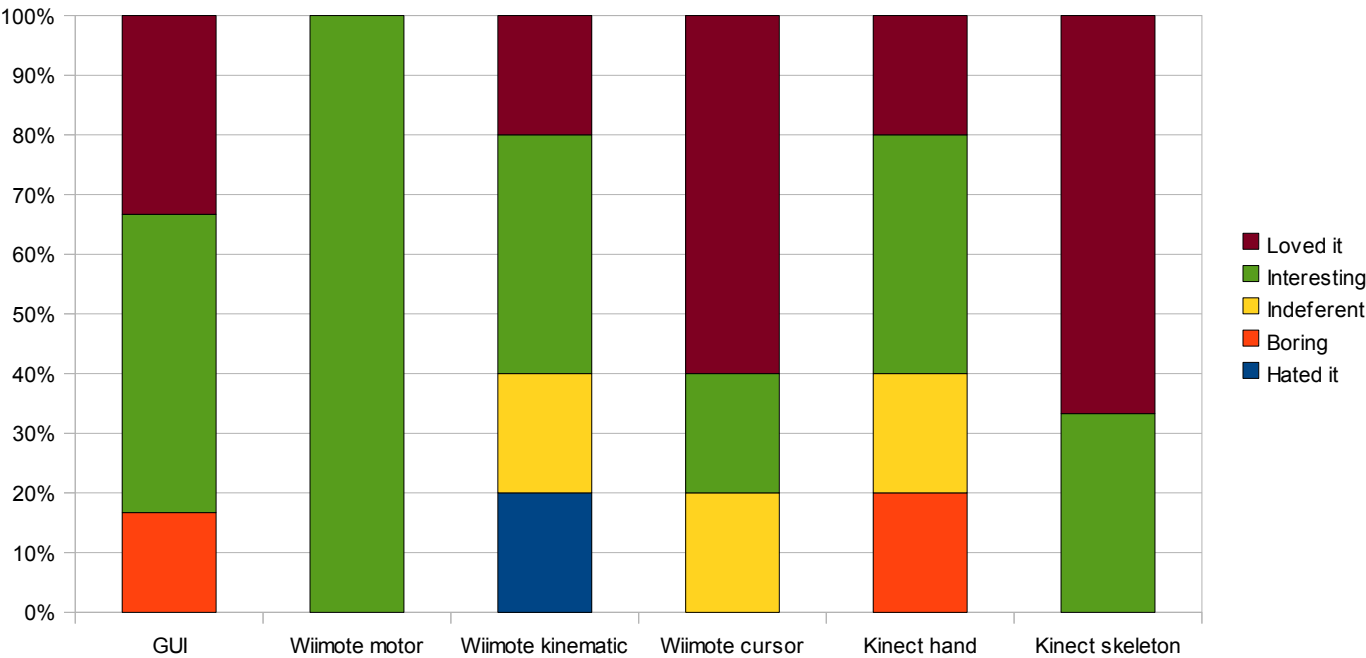
Did the interface do what you expect?



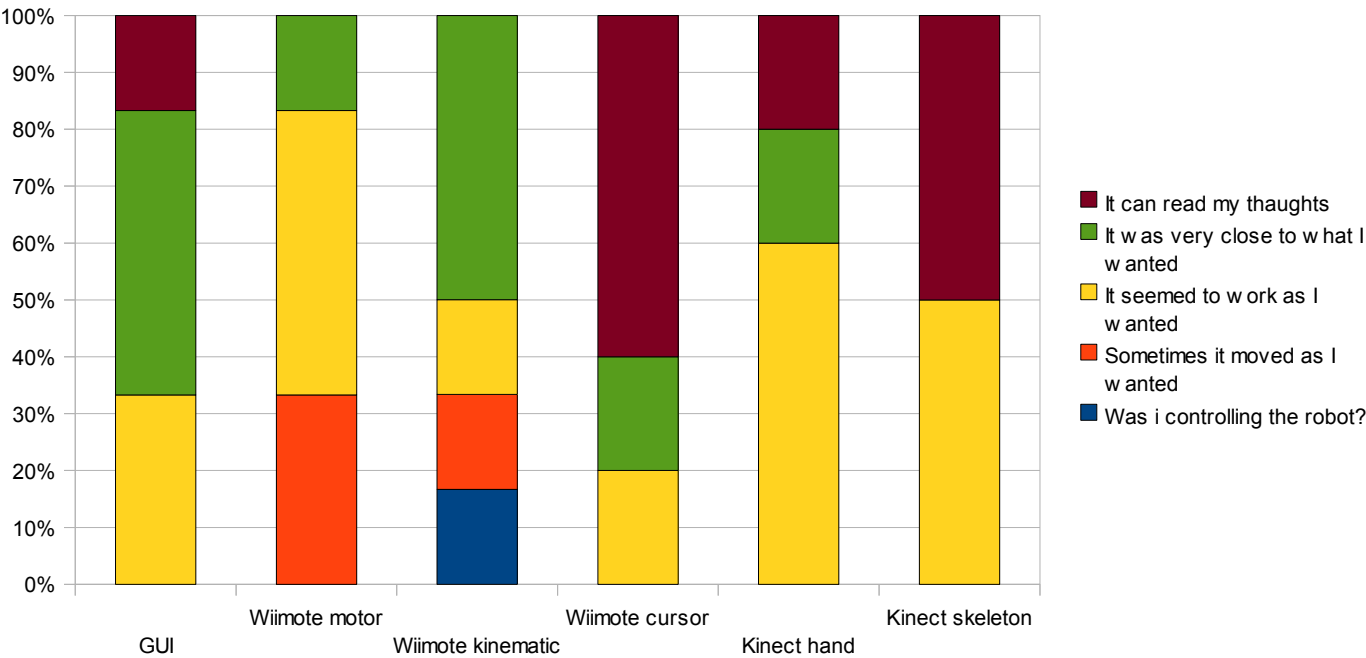
Were you preoccupied about operating the robot through this interface? (about breaking the robot or making errors)



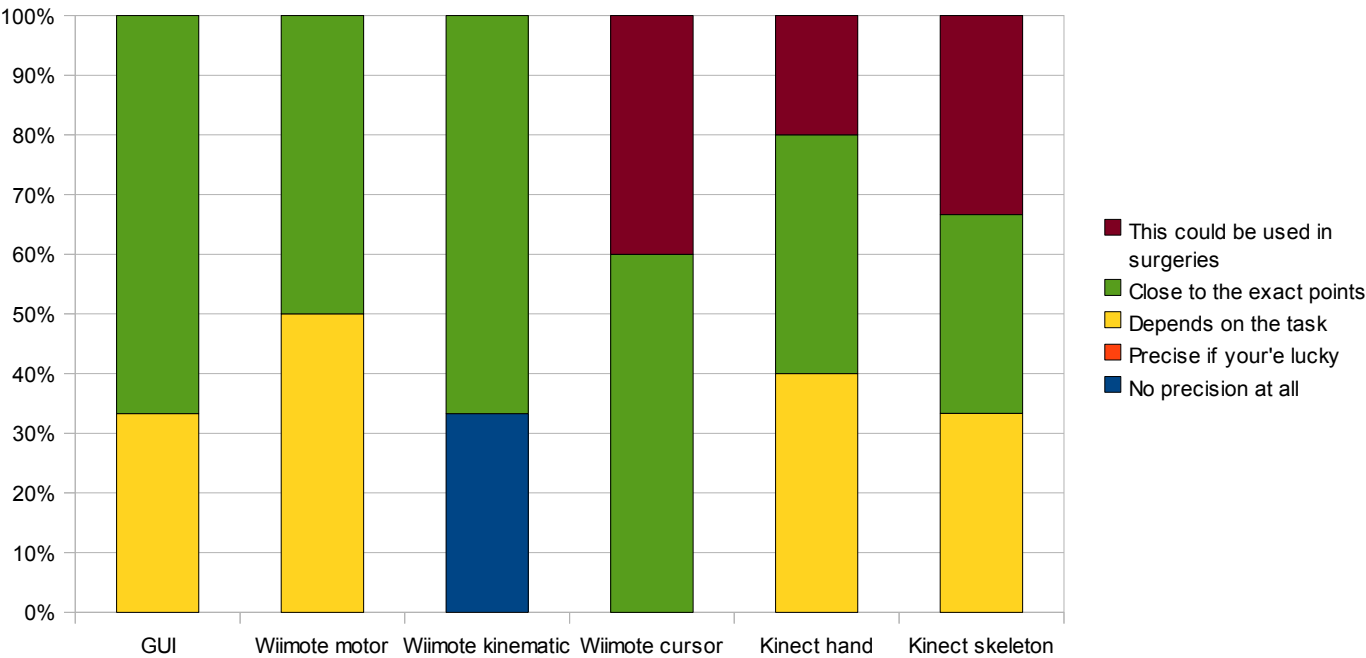
How did you like the experience?



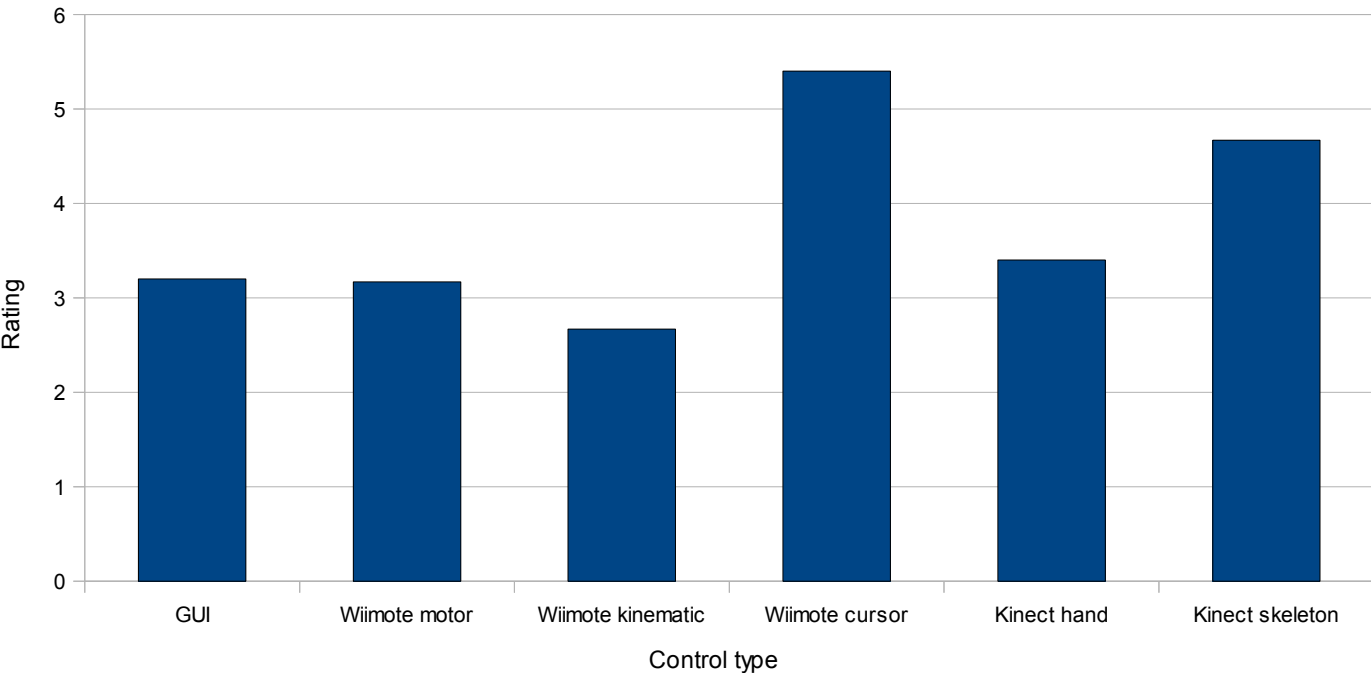
Did you felt disorientation (felt little control over the robot)?



Which input method was the most precise?



Which input method was the best for you (for the task you had to do)?



Which of the input methods did you prefer?
(not which one is the best, but which one did you like to use more)

