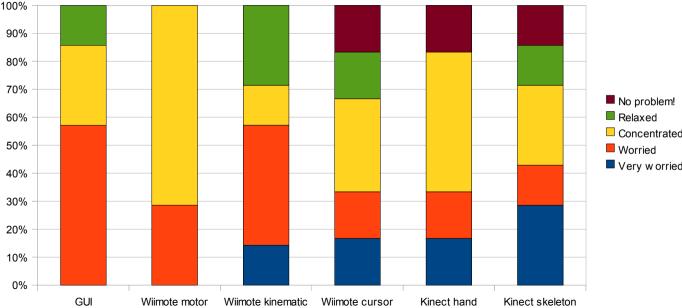
Did the interface do what you expect? 100% 90% 80% 70% 60% Alw ays ■ Most of the times 50% Sometimes Never 40% 30% 20% 10% 0% GUI Wiimote motor Wiimote kinematic Wiimote cursor Kinect hand Kinect skeleton

Were you preoccupied about operating the robot through this interface? (about breaking the robot or making errors) No problem! Relaxed Concentrated



How did you like the experience? 100% 90% 80% 70% Loved it 60% Interesting Indeferent 50% Boring Hated it 40% 30% 20% 10% 0% GUI Wiimote motor Wiimote kinematic Wiimote cursor Kinect hand Kinect skeleton

Did you felt disorientation (felt little control over the robot)? 100% 90% 80% 70% It can read my thaughts It was very close to what I 60% w anted ☐ It seemed to w ork as I 50% w anted Sometimes it moved as I 40% w anted 30% Was i controlling the robot? 20% 10% 0% Wiimote motor Wiimote cursor Kinect skeleton GUI Wiimote kinematic Kinect hand

Which input method was the most precise? 100% 90% 80% 70% ■ This could be used in 60% surgeries Close to the exact points 50% Depends on the task Precise if your'e lucky 40% No precision at all 30% 20% 10% 0% GUI Wiimote motor Wiimote kinematic Wiimote cursor Kinect hand Kinect skeleton

Which input method was the best for you (for the task you had to do)? 6 5 4 Rating 3 2 0 GUI Wiimote kinematic Kinect hand Kinect skeleton Wiimote motor Wiimote cursor Control type

Which of the input methods did you prefer? (not which one is the best, but which one did you like to use more)

