LEC-2: Types of OS

OS goals -

- Maximum CPU utilization
- Less process starvation
- Higher priority job execution

Types of operating systems -

- Single process operating system

- Batch-processing operating system

- Multiprogramming operating system

- Multitasking operating system

Multi-processing operating system

Distributed system

- Real time OS

[MS DOS, 1981]

[ATLAS, Manchester Univ., late 1950s - early 1960s]

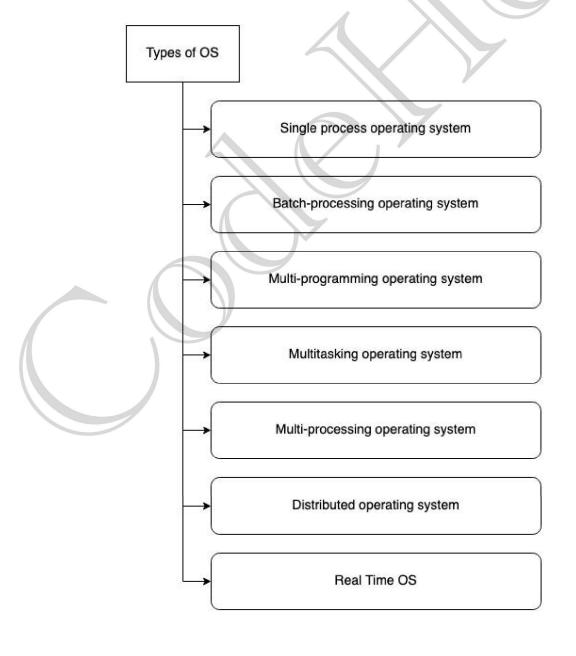
[THE, Dijkstra, early 1960s]

[CTSS, MIT, early 1960s]

[Windows NT]

[LOCUS]

[ATCS]

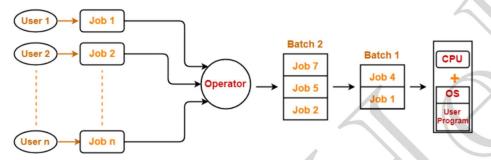




Single process OS, only 1 process executes at a time from the ready queue. [Oldest]

Batch-processing OS,

- 1. Firstly, user prepares his job using punch cards.
- 2. Then, he submits the job to the computer operator.
- 3. Operator collects the jobs from different users and sort the jobs into batches with similar needs.
- 4. Then, operator submits the batches to the processor one by one.
- 5. All the jobs of one batch are executed together.
 - Priorities cannot be set, if a job comes with some higher priority.
 - May lead to starvation. (A batch may take more time to complete)
 - CPU may become idle in case of I/O operations.



Multiprogramming increases CPU utilization by keeping multiple jobs (code and data) in the**memory** so that the CPU always has one to execute in case some job gets busy with I/O.

- Single CPU
- Context switching for processes.
- Switch happens when current process goes to wait state.
- CPU idle time reduced.

Multitasking is a logical extension of multiprogramming.

- Single CPU
- Able to run more than one task simultaneously.
- Context switching and time sharing used.
- Increases responsiveness.
- CPU idle time is further reduced.

Multi-processing OS, more than 1 CPU in a single computer.

- Increases reliability, 1 CPU fails, other can work
- Better throughput.
- Lesser process starvation, (if 1 CPU is working on some process, other can be executed on other CPU.



Distributed OS,

- OS manages many bunches of resources,
 >=1 CPUs, >=1 memory, >=1 GPUs, etc
- Loosely connected autonomous, interconnected computer nodes.
- collection of independent, networked, communicating, and physically separate computational nodes.

RTOS

- **Real time** error free, computations within tight-time boundaries.
- Air Traffic control system, ROBOTS etc.

