## Question 1 Robust Regression.

(a) Sketch the Huber loss  $L_{\delta}(y,t)$  and squared error loss  $L_{SE}(y,t) = \frac{1}{2}(y-t)^2$  for t=0, either by hand or using a plotting library. Based on your sketch, why would you expect the Huber loss to be more robust to outliers?

When t = 2,

$$L_{SE}(y,t) = \frac{1}{2}(y-t)^2 = \frac{1}{2}y^2$$

$$L_{\delta}(y,t) = H_{\delta}(y-t) = \begin{cases} \frac{1}{2}y^2 & \text{if } |a| \leq \delta \\ \delta \times (|y| - \frac{1}{2}\delta) & \text{if } |a| > \delta \end{cases}$$

With the help of matplotlib, their sketches are shown in Figure 1.

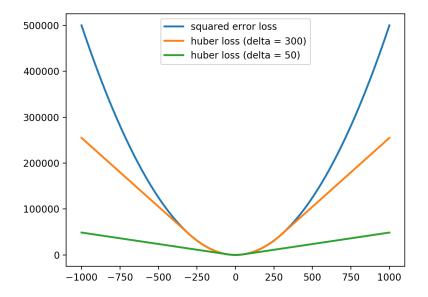


Figure 1: Sketches of squared error loss and Huber loss function.

As you can see from the Figure 1, for LSE functions, when the value |y| is large (which is also the case with outliers),  $L_{SE}(y,t)$  is very sensitive to |y| (and outliers). On the contrary, for Huber loss function, when |y| exceeds  $\delta$ ,  $L_{\delta}(y,t)$  increases linearly to |y|, which shows that it is relatively less sensitive to outliers.

**(b)** Give formulas for the partial derivatives  $\partial L_{\delta}/\partial \mathbf{w}$  and  $\partial L_{\delta}/\partial b$ .

The formula for the derivative  $H'_{\delta}(a)$  is

$$H'_{\delta}(a) = \begin{cases} a & \text{if } |a| \leq \delta \\ \delta & \text{if } a > \delta \\ -\delta & \text{if } a < -\delta \end{cases}$$

Then, in terms of a = y - t,

$$H'_{\delta}(y-t) = \begin{cases} y-t & \text{if } |y-t| \leq \delta \\ \delta & \text{if } y > t+\delta \\ -\delta & \text{if } y < t-\delta \end{cases}$$

As for the linear model, if **x** and **w** are both *D* dimensional vectors.

$$y = \mathbf{w}^{T} \mathbf{x} + b = \sum_{j} w_{j} x_{j} + b$$

$$H'_{\delta}(y - t) = \frac{\partial H_{\delta}}{\partial y} = \begin{cases} \sum_{j} w_{j} x_{j} + b - t & \text{if } |y - t| \leq \delta \\ \delta & \text{if } y > t + \delta \\ -\delta & \text{if } y < t - \delta \end{cases}$$

$$\frac{\partial L_{\delta}}{\partial w_{j}} = \frac{\partial H_{\delta}}{\partial w_{j}} = \frac{\partial H_{\delta}}{\partial y} \frac{\partial y}{\partial w_{j}} = \begin{cases} x_{j} (\sum_{j'} w_{j'} x_{j'} + b - t) & \text{if } |y - t| \leq \delta \\ \delta x_{j} & \text{if } y > t + \delta \\ -\delta x_{j} & \text{if } y < t - \delta \end{cases}$$

$$\frac{\partial L_{\delta}}{\partial b} = \frac{\partial H_{\delta}}{\partial b} = \frac{\partial H_{\delta}}{\partial y^{(i)}} \frac{\partial y^{(i)}}{\partial b} = \begin{cases} \sum_{j} w_{j} x_{j} + b - t & \text{if } |y - t| \leq \delta \\ \delta & \text{if } y > t + \delta \\ -\delta & \text{if } y < t - \delta \end{cases}$$

$$\frac{\partial L_{\delta}}{\partial \mathbf{w}} = \begin{cases} \mathbf{x} (\mathbf{x}^{T} \mathbf{w} + b - t) & \text{if } |y - t| \leq \delta \\ \delta \mathbf{x} & \text{if } y > t + \delta \\ -\delta \mathbf{x} & \text{if } y > t + \delta \end{cases}$$

When **X** is a  $N \times D$  matrix and **w** is a D dimensional vector. Then,

$$\mathbf{y} = \mathbf{X}\mathbf{w} + b\mathbf{1},$$
 $y^{(i)} = \sum_{j} w_{j}x_{j}^{(i)} + b$ 

We define  $\mathscr{E}$  as the model's cost function.

$$\mathscr{E}_{\delta} = rac{1}{N} \sum_{i=1}^{N} L_{\delta} = rac{1}{N} \sum_{i=1}^{N} H_{\delta}$$

We apply  $y^{(i)}$  in the partial derivatives,

$$\begin{split} \frac{\partial H_{\delta}}{\partial y^{(i)}} &= \left\{ \begin{array}{ll} \sum_{j} w_{j} x_{j}^{(i)} + b - t^{(i)} & if \ |y^{(i)} - t^{(i)}| \leq \delta \\ \delta & if \ y^{(i)} > t^{(i)} + \delta \\ -\delta & if \ y^{(i)} < t^{(i)} - \delta \end{array} \right. \\ \frac{\partial \mathcal{E}_{\delta}}{\partial w_{j}} &= \frac{\partial \mathcal{E}_{\delta}}{\partial y^{(i)}} \frac{\partial y^{(i)}}{\partial w_{j}} = \frac{1}{N} \sum_{i=1}^{N} \left\{ \begin{array}{ll} x_{j}^{(i)} (\sum_{j'} w_{j'} x_{j'}^{(i)} + b - t^{(i)}) & if \ |y^{(i)} - t^{(i)}| \leq \delta \\ \delta x_{j}^{(i)} & if \ y^{(i)} > t^{(i)} + \delta \\ -\delta x_{j}^{(i)} & if \ y^{(i)} < t^{(i)} - \delta \end{array} \right. \\ \frac{\partial \mathcal{E}_{\delta}}{\partial b} &= \frac{\partial \mathcal{E}_{\delta}}{\partial y^{(i)}} \frac{\partial y^{(i)}}{\partial b} = \frac{1}{N} \sum_{i=1}^{N} \left\{ \begin{array}{ll} (\sum_{j} w_{j} x_{j}^{(i)} + b - t^{(i)}) & if \ |y^{(i)} - t^{(i)}| \leq \delta \\ \delta & if \ y^{(i)} > t^{(i)} + \delta \\ -\delta & if \ y^{(i)} < t^{(i)} - \delta \end{array} \right. \end{split}$$

The partial derivatives can also be represented by matrix-vector format,

$$\frac{\partial \mathscr{E}_{\delta}}{\partial \mathbf{w}} = \begin{cases} \frac{1}{N} \mathbf{X}^{T} (\mathbf{X} \mathbf{w} + b \mathbf{1} - \mathbf{t}) & if -\delta \mathbf{1} \leq \mathbf{y} - \mathbf{t} \leq \delta \mathbf{1} \\ \frac{\delta}{N} \mathbf{X}^{T} \mathbf{1} & if \mathbf{y} > \mathbf{t} + \delta \mathbf{1} \\ -\frac{\delta}{N} \mathbf{X}^{T} \mathbf{1} & if \mathbf{y} < \mathbf{t} - \delta \mathbf{1} \end{cases}$$

(c) Write Python code to perform (full batch mode) gradient descent on this model.

The update rule of gradient descent method is as follows,

$$w_j \leftarrow w_j - \alpha \frac{\partial \mathcal{E}_{\delta}}{\partial w_j}$$
$$\mathbf{w} \leftarrow \mathbf{w} - \alpha \frac{\partial \mathcal{E}_{\delta}}{\partial \mathbf{w}}$$

Without using **for** loop, we applied the **np.where** function to realize the gradient descent on the Huber loss function. First, we generalized three vectors using  $\mathbf{y} - \mathbf{t}$ ,  $\delta \mathbf{1}$  and  $-\delta \mathbf{1}$  separately; then we used **np.where** to determine which line of the three vectors should be chosen.

I sampled 50000 samples through  $y = 3x_1 + 5x_2 - 9x_3 + 28x_4 - 10x_5 + 0$ . Through 1000 iterations, the loss dropped to 0.01384. The predicted w was [3.000181,5.00041, -9.00045, 28.000627, -10.000461, 0.000123]. However, I evaluated the efficiency of the algorithms with Huber loss function or square error loss function, and found that they took 6.6 and 0.24 seconds, respectively. I guessed the **np.where** function takes up most of the total time.

Code is in q1.py.

## Question 2 Locally Weighted Regression.

(a) Show the solution to the weighted least squares problem.

We define  $\mathscr{E}$  as the function of the weighted least squares problem.

$$\mathscr{E} = \frac{1}{2} \sum_{i=1}^{N} a^{(i)} (y^{(i)} - \mathbf{w}^{T} \mathbf{x}^{(i)})^{2} + \frac{\lambda}{2} ||\mathbf{w}||^{2}$$

To get solution for the problem,  $\mathbf{w}^*$ , we need partial derivatives to zero.

$$\begin{split} \frac{\partial \mathscr{E}}{\partial w_j} &= \sum_{i=1}^N a^{(i)} (y^{(i)} - \mathbf{w}^T \mathbf{x}^{(i)}) x_j^{(i)} + \lambda w_j = 0 \\ \sum_{i=1}^N a^{(i)} y^{(i)} x_j^{(i)} - \sum_{i=1}^N a^{(i)} x_j^{(i)} \mathbf{w}^T \mathbf{x}^{(i)} + \lambda w_j = 0 \\ \sum_{i=1}^N a^{(i)} x_j^{(i)} \mathbf{w}^T \mathbf{x}^{(i)} - \lambda w_j &= \sum_{i=1}^N a^{(i)} y^{(i)} x_j^{(i)} \\ \mathbf{X}^T \mathbf{A} \mathbf{X} \mathbf{w} - \lambda \mathbf{1} \mathbf{w} &= \mathbf{X}^T \mathbf{A} \mathbf{y} \\ \mathbf{w} &= (\mathbf{X}^T \mathbf{A} \mathbf{X} - \lambda \mathbf{1})^{-1} \mathbf{X}^T \mathbf{A} \mathbf{y} \end{split}$$

(b)

Question 3 AdaBoost.