

# Linnaeus University

## 1DT301 - Computer Technology Laboration 3

### Students:

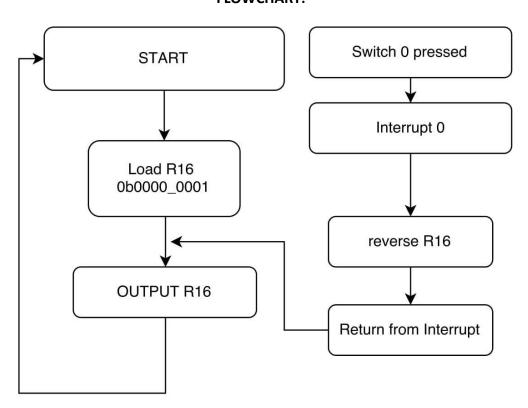
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Write a program that turns ON and OFF a LED with a push button. The LED will be extinguished when pressing the button. The program will use Interrupt.

Connect the push buttons to PORT D. The program should have a main program that runs in a loop and wait for the interrupts. An interrupt routine is called when the push button is pressed. Each time the button is pressed, the lamp should switch from 'OFF' to 'ON', or from 'ON' to 'OFF'.

#### FLOWCHART:



#### CODE:

```
; 1DT301, Computer Technology I
; Date: 07/10 Date: 07/10 /2017
; Authors:
; Alexander Risteski
; Dimitrios Argyriou
; Hardware: STK600, CPU ATmega2560
; Function: This program lights on when off and off when on
; led 0 when interrupt is called.
; Input ports: On-board switches connected to PORTD.
; Output ports: On -board LEDs connected to PORTB.
; Included files: m2560def.inc
.include "m2560def.inc"
.org 0x00
rimp start
```



```
.org INTOaddr
rjmp interrupt_0
```

.org 0x72 start:

; Initialize SP, Stack Pointer

ldi r20, HIGH(RAMEND) ; R20 = high part of RAMEND address out SPH,R20 ; SPH = high part of RAMEND address ldi R20, low(RAMEND) ; R20 = low part of RAMEND address ; SPL = low part of RAMEND address out SPL,R20

ldi r16, 0x00 out DDRD,r16

ldi r16, 0x01 out DDRB, r16

ldi r16, 0b00000001 out EIMSK, r16

ldi r16, 0b00000100 sts EICRA, r16 sei

;main program ldi r16, 1 main\_program: nop rjmp main\_program

interrupt\_0: com r16 out PORTB, r16

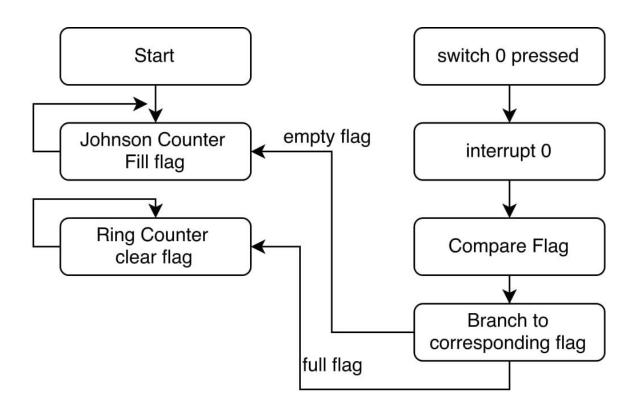
ldi r22, 200 delay int: dec r22 cpi r22,0 brne delay int

reti



Write a program that by means of a switch can choose to flash 8 LEDs either in the form of a ring counter or in the form of a Johnson counter. Use the switch SWO connected to PORTD to switch between the two counters. Each time the button is pressed, a shift between the two counters should take place. By using interrupts you'll swap directly with no delay.

#### FLOWCHART:



#### CODE:

```
; 1DT301, Computer Technology I
; Date: 07/10 Date: 07/10 /2017
; Authors:
; Alexander Risteski
; Dimitrios Argyriou
; Hardware: STK600, CPU ATmega2560
; Function: This program switches from ring counter to Johnson counter
; by calling interrupt (INTOaddr) on switch 0
; Input ports: On-board switches connected to PORTD.
; Output ports: On -board LEDs connected to PORTB.
; Included files: m2560def.inc
.include "m2560def.inc"
```



.org 0x00 rjmp start

.org INT0addr rjmp interrupt 0

.org 0x72 start:

ldi mr, 0b00000011 out EIMSK, mr

ldi mr, 0b00001000 sts EICRA, mr

ldi mr, 0x00 out DDRD, mr

sei

ldi r20, HIGH(RAMEND) ; R20 = high part of RAMEND address out SPH,R20 ; SPH = high part of RAMEND address Idi R20, low(RAMEND) ; R20 = low part of RAMEND address out SPL,R20 ; SPL = low part of RAMEND address

; Assigning names to the registers .DEF mr = r16.DEF mri = r17.DEF flag =r23

;================Johnson counter=============================

JohnsonCounter:

ser flag ldi mr, 0xff out DDRB, mr

forward:

out PORTB, mr Isl mr call delay cpi mr, 0b00000000 brne forward rjmp reset

reset: out PORTB,mr



Technology call delay ldi mri,0b10000000 rjmp backwards backwards: Isr mr add mr, mri out PORTB,mr call delay cpi mr, 0xFF brne backwards rjmp JohnsonCounter RingCounter: clr flag start1: ldi mr, 0x01 com mr ; complements the register so that it will be showed correctly out PORTB, mr ;complements again to return to its original form com mr rcall delay myloop: Isl mr com mr out PORTB, mr com mr cpi mr, 0b00000000 breq equal rcall delay rjmp myloop equal: rjmp RingCounter interrupt 0: ldi r22,200 delay\_int: dec r22 cpi r22,0 brne delay\_int



sei

1DT301 – Computer

1DT301-ComputerTechnology

cpi flag, 0xff breq RingCounter brne JohnsonCounter

delay:

ldi r18, 5

ldi r19, 15

ldi r20, 242

L1: dec r20

brne L1

dec r19

brne L1

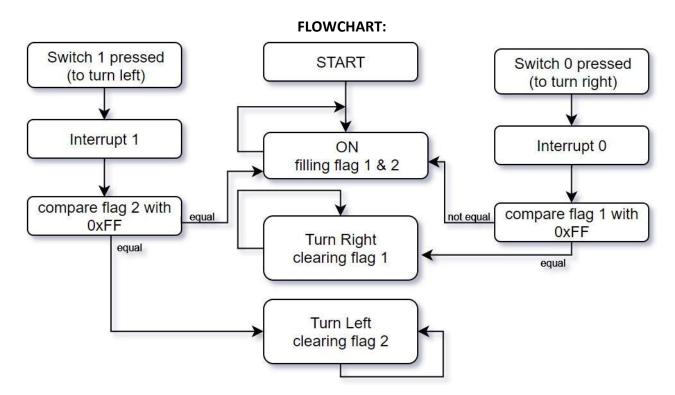
dec r18

brne L1

ret



Rear lights on a car Interrupt. Program that simulates the rear lights on a car The 8 LEDs should behave like the rear lights. Function: Normal light: LED 0, 1, 6 and 7 'ON'. Turning right: LED 6 -7 on, LED 0 –3 blinking as RING counter. Turning left: LED 0 –1 on, LED 4 –7 blinking as RING counter.



#### **CODE:**

```
; 1DT301, Computer Technology I
; Date: 07/10 Date: 07/10 /2017
; Authors:
; Alexander Risteski
; Dimitrios Argyriou
; Hardware: STK600, CPU ATmega2560
; Function: This program simulates the rear lights on a car.
; It has 3 states and changes between them by calling interrupt_0 and _1
; ON (Leds 7,8 & 0,1).
;Turn right: Leds 6 – 7 on, led 0 –3 blinking as RING counter.
;Turn left :led 0 – 1 on, led 4 – 7 blinking as RING counter.
; Input ports: On-board switches connected to PORTD.
; Output ports: On -board LEDs connected to PORTB.
; Included files: m2560def.inc
```

.include "m2560def.inc"



```
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Technology
.org 0x00
rjmp start
.org INTOaddr
rjmp interrupt 0
.org INT1addr
rjmp interrupt 1
.org 0x72
start:
ldi mr, 0b00000011
out EIMSK, mr
ldi mr, 0b00001000
sts EICRA, mr
ldi mr, 0x00
out DDRD, mr
sei
ldi r20, HIGH(RAMEND) ; R20 = high part of RAMEND address
out SPH,R20
                      ; SPH = high part of RAMEND address
ldi R20, low(RAMEND)
                      ; R20 = low part of RAMEND address
out SPL,R20
                      ; SPL = low part of RAMEND address
.DEF mr = r16
.DEF mri = r17
.DEF flag1 = r22
.DEF flag2 = r23
; Filling up the flags1,2 so that it can branch to one of the states
; and when branches clear the appropriate flag so that it can branch here again.
on:
ser flag1
ser flag2
ldi mr,0xFF
out DDRB, mr
 ldi r16, 0b00111100
 out PORTB, mr
 rjmp on
; Initialize SP, Stack Pointer
turnRight:
clr flag1 // clear the flag1
ldi r20, HIGH(RAMEND) ; R20 = high part of RAMEND address
```



out SPH,R20 ; SPH = high part of RAMEND address ldi R20, low(RAMEND) ; R20 = low part of RAMEND address out SPL,R20 ; SPL = low part of RAMEND address

ldi mr , 0xFF out DDRB, mr

RingCounter:

start1:

ldi mri, 0b00110111

out PORTB, mri rcall delay

ldi mr, 0b0000\_1100

myloop:

eor mri, mr out PORTB,mri

Isr mr

cpi mri, 0b0011\_1111 breq RingCounter

rcall delay rjmp myloop

; Initialize SP, Stack Pointer

turnLeft:

clr flag2 // clear the flag2

ldi r20, HIGH(RAMEND) ; R20 = high part of RAMEND address out SPH,R20 ; SPH = high part of RAMEND address ldi R20, low(RAMEND) ; R20 = low part of RAMEND address out SPL,R20 ; SPL = low part of RAMEND address

ldi mr , 0xFF out DDRB, mr

RingCounter2:

start2:

ldi mri, 0b1110\_1100 out PORTB, mri rcall delay

ldi mr, 0b0011\_0000

myloop2:

eor mri, mr out PORTB,mri

Isl mr



cpi mri, 0b1111\_1100 breq RingCounter2 rcall delay rjmp myloop2

interrupt\_0: sei // set interrupt enabled cpi flag1, 0xff breq turnRight brne on

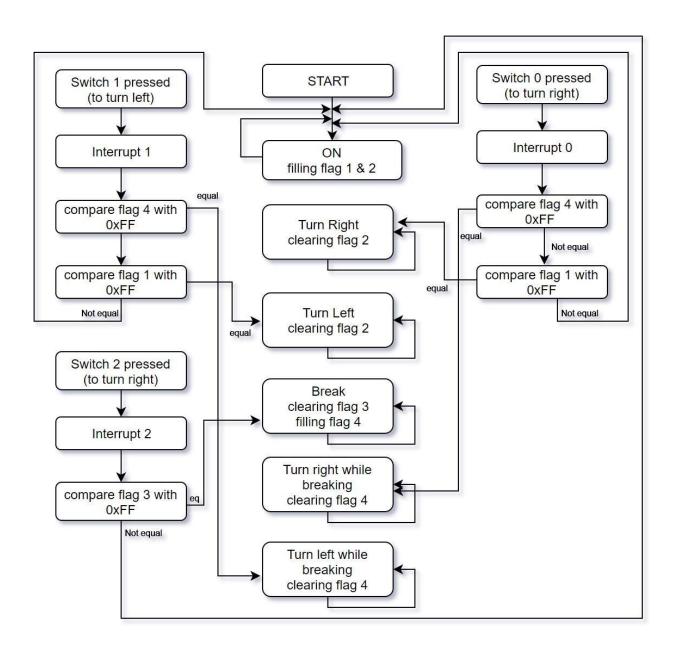
interrupt\_1: sei // set interrupt enabled cpi flag2, 0xff breq turnLeft brne on

delay: ldi r18, 5 ldi r19, 15 ldi r20, 242 L1: dec r20 brne L1 dec r19 brne L1 dec r18 brne L1

ret

Rear lights on a car, with light for brakes Add function for the stop light to the previous task. When braking, all LED slight up, if blink on the right or left is not going on. Turning right and brake: LED 4 -7 on, LED 0 -3 blinking as RING counter. Turning left and brake: LED 0 -3 on, LED 4 -7 blinking as RING counter. Use INT2 for the Brake.

#### FLOWCHART:



#### CODE:

; 1DT301, Computer Technology I ; Date: 07/10 Date: 07/10 /2017 ; Authors: ; Alexander Risteski ; Dimitrios Argyriou



```
; Hardware: STK600, CPU ATmega2560
; Function: This program simulates the rear lights on a car from task3 plus
; introducing more states for breaking.
; Breaking : all LEDS on
; Breaking and turning right: LED 4 – 7 on, LED 0 – 3 blinking as RING counter..
; Breaking and turning left :LED 0 - 1 on, led 4 - 7 blinking as RING counter.
; Input ports: On-board switches connected to PORTD.
; Output ports: On -board LEDs connected to PORTB.
; Included files: m2560def.inc
.include "m2560def.inc"
.org 0x00
rjmp start
.org INTOaddr
rjmp interrupt 0
.org INT1addr
rjmp interrupt 1
.org INT2addr
rjmp interrupt_2
.org 0x72
start:
ldi mr, 0b00000111
out EIMSK, mr
ldi mr, 0b00001000
sts EICRA, mr
ldi mr, 0x00
out DDRD, mr
sei
ldi r20, HIGH(RAMEND) ; R20 = high part of RAMEND address
                                               ; SPH = high part of RAMEND address
out SPH,R20
                       ; R20 = low part of RAMEND address
ldi R20, low(RAMEND)
out SPL,R20
                                               ; SPL = low part of RAMEND address
;================= DEFINING REGISTERS =======================
.DEF mr = r16
.DEF mri = r17
```



```
1DT301 – Computer
Technology
.DEF flag1 = r22
.DEF flag2 = r23
.DEF flag3 = r24
.DEF flag4 = r25
ser flag1
ser flag2
ser flag3
clr flag4 // clear flag4
;======== ON state (Leds 7,8,0,1 are on)=====================
ldi mr,0xFF
out DDRB, mr
ldi r16, 0b00111100
out PORTB, mr
rjmp on
; Initialize SP, Stack Pointer
turnRight:
clr flag1
ldi r20, HIGH(RAMEND)
                ; R20 = high part of RAMEND address
out SPH,R20
                                   ; SPH = high part of RAMEND address
ldi R20, low(RAMEND) ; R20 = low part of RAMEND address
out SPL,R20
                                   ; SPL = low part of RAMEND address
ldi mr, 0xFF
out DDRB, mr
RingCounter:
start1:
        ldi mri, 0b00110111
        out PORTB, mri
        rcall delay
                 ldi mr,
                           0b0000 1100
myloop:
        eor mri, mr
        out PORTB, mri
        Isr mr
        cpi mri, 0b0011 1111
        breq RingCounter
        rcall delay
        rjmp myloop
; Initialize SP, Stack Pointer
turnLeft:
```



```
1DT301 – Computer
Technology
clr flag2
ldi r20, HIGH(RAMEND) ; R20 = high part of RAMEND address
out SPH,R20
                                       ; SPH = high part of RAMEND address
ldi R20, low(RAMEND)
                   ; R20 = low part of RAMEND address
out SPL,R20
                                        ; SPL = low part of RAMEND address
ldi mr, 0xFF
out DDRB, mr
RingCounter2:
start2:
         ldi mri, 0b1110 1100
         out PORTB, mri
         rcall delay
         ldi mr,
                    0b0011 0000
myloop2:
         eor mri, mr
         out PORTB, mri
         Isl mr
         cpi mri, 0b1111 1100
         breq RingCounter2
         rcall delay
         rjmp myloop2
;============= Helper subroutines for branching==============
         turnRightBridge:
         rjmp turnRight
         turnLeftBridge:
         rimp turnLeft
         turnOnBridge:
         rjmp on
breakWhenOn:
clr flag3 // Clearing flag3
ser flag4 // Filling flag4 to xFF
ldi mr,0xFF
out DDRB, mr
ldi r16, 0x00
out PORTB, mr
rjmp breakWhenOn
turnLeftBreak:
clr flag4 //claring flag4
; Initialize SP, Stack Pointer
ldi r20, HIGH(RAMEND)
                  ; R20 = high part of RAMEND address
out SPH,R20
                                        ; SPH = high part of RAMEND address
ldi R20, low(RAMEND) ; R20 = low part of RAMEND address
```



out SPL,R20

; SPL = low part of RAMEND address

```
1DT301 – Computer
Technology
ldi mr, 0xFF
out DDRB, mr
RingWithBreak1:
start3:
           ldi mri, 0b1110 0000
           out PORTB, mri
           rcall delay
           ldi mr,
                       0b0011 0000
myloop3:
           eor mri, mr
           out PORTB, mri
           Isl mr
           cpi mri, 0b1111 0000
           breq RingWithBreak1
           rcall delay
           rjmp myloop3
turnRightBreak:
clr flag4 //Clearing flag4
; Initialize SP, Stack Pointer
ldi r20, HIGH(RAMEND) ; R20 = high part of RAMEND address
out SPH,R20
                                              ; SPH = high part of RAMEND address
ldi R20, low(RAMEND)
                    ; R20 = low part of RAMEND address
out SPL,R20
.DEF mr = r16
           .DEF mri = r17
ldi mr, 0xFF
out DDRB, mr
RingWithBreak2:
start4:
           ldi mri, 0b0000_0111 ;OBS!!! ob1110_0000 for task 4 break 00000111
           out PORTB, mri
           rcall delay
           ldi mr,
                       0b0000 1100
myloop4:
           eor mri, mr
           out PORTB, mri
           Isr mr
           cpi mri, 0b0000_1111
```

breq RingWithBreak2 rcall delay

rjmp myloop4

:============== INTERRUPT SUBROUTINES ======================= interrupt 0:



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sei cpi flag4, 0xff breq turnRightBreak cpi flag1, 0xff breq turnRightBridge brne turnOnBridge

interrupt 1:

sei

cpi flag4, 0xff//0x00 breq turnLeftBreak cpi flag2, 0xff breq turnLeftBridge

brne turnOnBridge

interrupt\_2:

sei

cpi flag3 ,0xff

breq breakWhenOn

brne turnOnBridge

delay:

ldi r18, 5

ldi r19, 15

ldi r20, 242

L1: dec r20

brne L1

dec r19

brne L1

dec r18

brne L1

ret

