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CS 441 - HW 5: Deep Learning and Applications

Complete the sections below. You do not need to fill out the checklist. **Be sure to select all relevant pages in Gradescope.**

Total Points Available	[]/150
Applications of Al	
Describe the applications	[]/15
2. Positive impact	[]/7
Negative impact	[]/8
2. Fine-tune Model for Pets Classification	
 Qs about ResNet-34 structure 	[]/10
2. Epochs vs Loss Plots	[]/10
3. Best Performance / Question	[]/10
3. CLIP: Contrastive Language-Image Pretraining	
 Test CLIP zero-shot performance 	[]/20
2. Test CLIP linear probe performance	[]/10
KNN on CLIP features	[]/10
4. Stretch Goals	
 Compare word tokenizers 	[]/20
2. Implement/train custom network	[]/30

1. Answer "Applications of Al" Questions

 How is Al used in that application area? What is the problem that Al is trying to solve, and what are the key Al/ML technologies involved? What are the technical challenges? (100+ words)

The integration of AI into home monitoring systems offers a blend of enhanced security, energy optimization, and improved elderly care. Al's ability to analyze real-time video feeds in security systems revolutionizes the way we approach home safety. It identifies potential threats with precision, minimizing the reliance on constant human monitoring and providing a proactive approach to security.

In the realm of elderly care, Al's role is equally transformative. By monitoring health indicators and daily activities, Al systems can swiftly notify caregivers in the event of an emergency, ensuring timely intervention and support. This technological advancement is a beacon of hope for enhancing the quality of life for the elderly, providing them with a sense of independence while ensuring their safety.

Energy management is another area where AI dominates, demonstrating its ability to learn and adapt to household patterns. It intelligently adjusts heating, lighting, and other systems, leading to significant energy savings and contributing to a more sustainable future.

Despite these benefits, integrating AI into home monitoring is not without its challenges. Ensuring the privacy and security of data, achieving compatibility among various smart devices, maintaining the accuracy and reliability of AI decision-making, and managing the extensive data generated are critical issues that need addressing. These challenges underscore the importance of establishing stringent security protocols, ensuring seamless device integration, and implementing precise and dependable AI functionalities.

2. What is the actual or potential positive impact? Who is impacted? (50+ words)

Firstly, it enhances security by intelligently analyzing behavior and detecting anomalies, reducing the risk of intrusions and enabling quick responses to threats. Secondly, Al-driven systems optimize energy consumption, leading to significant savings and environmental benefits through smart management of resources like heating, cooling, and lighting. Thirdly, in the realm of healthcare, particularly for elderly care, Al enables continuous monitoring, facilitating immediate medical assistance when needed, thereby ensuring safety and promoting independence. Overall, Al in home monitoring promises a future where homes are not only safer and more efficient but also adapt to the individual needs and well-being of their inhabitants, reflecting a profound positive impact on daily living and resource management.

3. What is the actual or potential negative impact? Who is impacted? (50+ words)

The actual or potential negative impact of AI in home monitoring includes privacy concerns, as constant surveillance and data collection might lead to unauthorized data access and misuse. Individuals could feel their personal space is invaded, undermining trust in technology. Additionally, over-reliance on AI may result in complacency, where residents ignore manual checks and maintenance, potentially leading to system failures. Job displacement is another concern, as AI could replace human roles in security and monitoring. These impacts primarily affect homeowners, tenants, and workers in the security and property management sectors, highlighting the need for ethical and secure AI implementation.

4. What are your sources? (include full citations and links if available) [required; -15 pts if not provided] Format is not as important as being clear about what source is used.

Ferguson, Ann. "How Ai-Powered Smart Home Security Revolutionizes Home Safety." *DAVE*, 8 Sept. 2023, www.comeseedave.com/blog/ai-smart-home-security-revolution#

ThriveAdmin. "How AI Is Changing Home Security." *Aeon Systems*, 4 May 2023, www.aeonsystems.net/how-ai-is-changing-home-security/

"Exploring the Future Impact of AI in Home Security." *Vector Security*, www.vectorsecurity.com/exploring-the-future-impact-of-ai-in-home-security. Accessed 8 Apr. 2024.

2. CNN: Image Classification

- 1. Answer these questions about the network structure of your model based on ResNet-34
 - 1.1. How many parameters are there in total? (xx.x million)

21.3 million

- 1.2. Which of these layers **do not** have trainable parameters? (choose more than 1)
 - a) Convolutional
 - b) BatchNorm
 - c) ReLU
 - d) Max pooling
 - e) Fully connected

ReLU, Max pooling

1.3. True or false: In layers 1-4, whenever the feature map is downsampled by a factor of 2, the number of features is doubled.

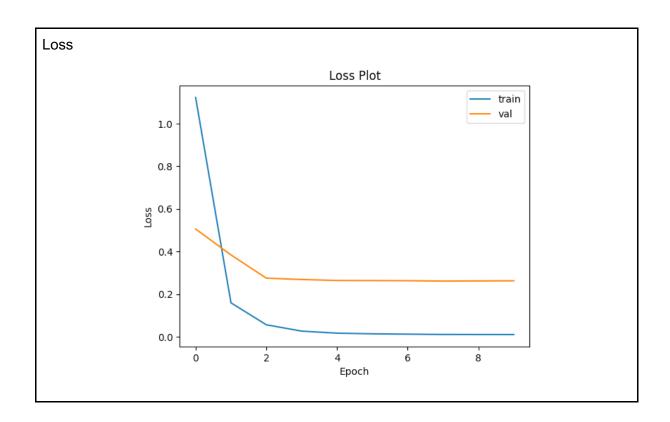
True.

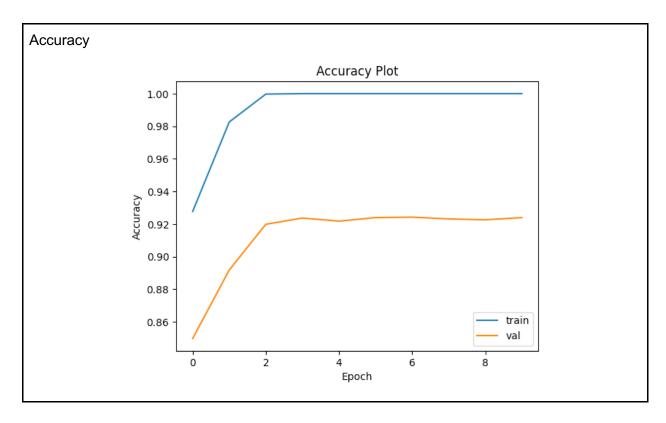
When transitioning from layer 1 to 2, the spatial dimension (stride) is downsampled by a factor of 2. The number of features is doubled (from 64 to 128). The same pattern is followed from layer 3 to 4.

- 1.4. Which of these are applied immediately before the final fully connected layer? (choose one)
 - a) Convolutional
 - b) BatchNorm
 - c) ReLU
 - d) Max pooling
 - e) Average pooling
 - f) Fully connected

Average pooling

2. Plot accuracy and loss for at least 10 epochs





3. Best accuracy / question

Your best val (test set) accuracy:

92.4%

True or False: Once the training accuracy reaches 100%, it's not possible to improve the model with further training.

False, having a training accuracy of 100% does not necessarily mean that no further improvements can be made. The model could be overfitting the data and including noise or outliers. Just because the training accuracy is 100% it may not perform well on the validation or test data and generalization may need to be improved through methods like hyperparameter adjusting or regularization.

3. CLIP: Contrastive Language-Image Pretraining

1. CLIP zero-shot performance

Your test accuracy (xx.x%)

67.6%

What is the key idea that provides zero-shot ability to CLIP? (choose one)

- a. The visual model is trained to predict the most likely word based on a large dataset of labeled images.
- b. A text model is trained to map words into a vector and a visual model to map patches into an equal sized vector, such that the vectors of image and its textual description are much more similar than those of non-corresponding images and descriptions.
- c. CLIP learns to generate the most likely textual description, given the image.

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1 ()			

2. CLIP linear probe performance

Your test accuracy (xx.x%)

93.4%

3. KNN on CLIP feature

Your test accuracy: (xx.x%)

85.8%			

Best K:

9			

4. Stretch Goals

a. Compare word tokenizers

Report encodings for "I am learning about word tokenizers. They are not very complicated, and they are a good way to convert natural text into tokens." and one additional sentence of your choice. 20 points for reporting trained encodings of at least two models. 10 points for one model. You must train the models on WikiText-2 (should be included in notebook code).

BPE Encoding: ['I', 'am', 'lear', 'ning', 'about', 'word', 'to', 'k', 'en', 'iz', 'er', 's', '. They', 'are not', 'very', 'compl', 'ic', 'at', 'ed', ', and ', 'they are ', 'a ', 'good', 'way to ', 'conver', 't', 'natural', 'text', 'into', 'to', 'k', 'ens', '.']

WordPiece Encoding: ['[UNK]']

Additional BPE Encoding: ['I ', 'have ', 'lear', 'n', 't ', 'a ', 'I', 'ot ', 'from ', 'Ap', 'pl', 'ied ', 'M', 'ach', 'ine ', 'L', 'ear', 'ning ', 'at ', 'U', 'I', 'U', 'C']

Additional WordPiece Encoding: ['I', '## ', '##have ', '##lear', '##n', '##t ', '##a ', '##lo', '##t ', '##from ', '##Ap', '##pl', '##led ', '##Mac', '##hi', '##ne ', '##Le', '##ar', '##ning ', '##at ', '##U', '##U', '##U', '##U', '##C']

b. Custom network implementation and evaluation

- i. Display the structure of the network you implemented
- ii. Plot accuracy and loss
- iii. Best test accuracy:

Acknowledgments / Attribution

List any outside sources for code or improvement ideas or "None".

https://www.techtarget.com/searchcustomerexperience/definition/virtual-assistant-Al-assistant

https://mobidev.biz/blog/ai-virtual-assistant-technology-guide

CS441: Applied ML - HW 5

Part 1: Applications of Al

Nothing to code for this part.

Part 2: Fine-Tune for Pets Image Classification

Include all the code for Part 2 in this section

2.1 Prepare Data

```
In [1]: import torch
import torch.nn as nn
import torch.optim.lr_scheduler as lrs
from torch.utils.data import DataLoader
import torchvision
from torchvision import datasets
from torchvision import transforms
import matplotlib.pyplot as plt
from tqdm import tqdm

import os
from pathlib import Path
import numpy as np
```

```
In [2]: # Mount and define data dir

datadir = "/Users/darian/Desktop/UIUC/Applied ML/HW5/Code/"
    save_dir = "/Users/darian/Desktop/UIUC/Applied ML/HW5/Code/"
```

```
In [3]: | def load_pet_dataset(train_transform = None, test_transform = None)
        e):
            OxfordIIITPet = datasets.OxfordIIITPet
            if os.path.isdir(datadir+ "oxford-iiit-pet"):
              do_download = False
            else:
              do download = True
            training_set = OxfordIIITPet(root = datadir,
                                      split = 'trainval',
                                      transform = train transform,
                                      download = do_download)
            test_set = OxfordIIITPet(root = datadir,
                                    split = 'test',
                                    transform = test_transform,
                                    download = do_download)
            return training_set, test_set
```

```
In [4]: train_set, test_set = load_pet_dataset()

# Display a sample in OxfordIIIPet dataset
sample_idx = 0 # Choose an image index that you want to display
print("Label:", train_set.classes[train_set[sample_idx][1]])
train_set[sample_idx][0]
```

Label: Abyssinian





2.2 Data Preprocess

```
In [5]: from torchvision import transforms
from torch.utils.data import DataLoader
```

```
In [6]: # Feel free to add augmentation choices
        # Apply data augmentation
        train transform = transforms.Compose([
                    transforms.Resize(224),
                    transforms.CenterCrop(224),
                    transforms.ToTensor(),
                    transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                          std= [0.229, 0.224, 0.225]),
                1)
        test transform = transforms.Compose([
                    transforms.Resize(224), # resize to 224x224 because th
        at's the size of ImageNet images
                    transforms.CenterCrop(224),
                    transforms.ToTensor(),
                    transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                          std= [0.229, 0.224, 0.225]),
                ])
In [7]: # Feel free to change
        train_set, test_set = load_pet_dataset(train_transform, test_transf
        orm)
        train loader = DataLoader(dataset=train set,
                                   batch size=128,
                                   shuffle=True,
                                   num_workers=2)
        test loader = DataLoader(dataset=test set,
                                   batch size=128,
                                   shuffle=False,
```

num workers=2)

2.3 Helper Functions

```
In [8]: # Display the number of parameters and model structure
        def display model(model):
          # Check number of parameters
          summary_dict = {}
          num_params = 0
          summary str = ['='*80]
          for module name, module in model.named children():
              summary count = 0
              for name, param in module.named parameters():
                   if(param.requires_grad):
                       summary count += param.numel()
                       num_params += param.numel()
              summary_dict[module_name] = [summary_count]
              summary str+= [f'- {module name: <40} : {str(summary count):^</pre>
        34s}']
          summary dict['total'] = [num params]
          # print summary string
          summary_str += ['='*80]
          summary_str += ['--' + f'{"Total":<40} : {str(num_params) + " pa</pre>
        rams":^34s}' +'--']
          print('\n'.join(summary_str))
          # print model structure
          print(model)
```

```
In [9]: # Plot loss or accuracy
        def plot losses(train, val, test frequency, num epochs):
            plt.plot(train, label="train")
            indices = [i for i in range(num epochs) if ((i+1)%test frequenc
        y == 0 or i == 0 or i == 1)
            plt.plot(indices, val, label="val")
            plt.title("Loss Plot")
            plt.ylabel("Loss")
            plt.xlabel("Epoch")
            plt.legend()
            plt.show()
        def plot accuracy(train, val, test frequency, num epochs):
            indices = [i for i in range(num epochs) if ((i+1)%test frequenc
        y == 0 or i == 0 or i == 1)
            plt.plot(indices, train, label="train")
            plt.plot(indices, val, label="val")
            plt.title("Accuracy Plot")
            plt.ylabel("Accuracy")
            plt.xlabel("Epoch")
            plt.legend()
            plt.show()
        def save checkpoint(save dir, model, save name = 'best model.pth'):
            save path = os.path.join(save dir, save name)
            torch.save(model.state_dict(), save_path)
        def load model(model, save dir, save name = 'best model.pth'):
            save path = os.path.join(save dir, save name)
            model.load_state_dict(torch.load(save_path))
            return model
```

2.4 YOUR TASK: Fine-Tune Pre-trained Network on Pets

Read and understand the code and then uncomment it. Then, set up your learning rate, learning scheduler, and train/evaluate. Adjust as necessary to reach target performance.

```
# TO DO: read this documentation and then uncomment the line be
low; https://pypi.org/project/tqdm/
   it train = tqdm(enumerate(train loader), total=len(train loade
r), desc="Training ...", position = 0) # progress bar
   for i, (images, labels) in it train:
        # TO DO: read/understand these lines and then uncomment the
code below
        images, labels = images.to(device), labels.to(device)
        # zero the gradient
        optimizer.zero_grad()
        # predict labels
        prediction = model(images)
        # compute loss
        loss = criterion(prediction, labels)
        # set text to display
        it train.set description(f'loss: {loss:.3f}')
        # compute gradients
        loss.backward()
        # update weights
        optimizer.step()
        # keep track of losses
        losses.append(loss)
   return torch.stack(losses).mean().item()
def test(test loader, model, criterion):
    Test network.
    :param test loader: testing dataloader
    :param model: model to be tested
    :param criterion: criterion used to calculate loss (should be C
rossEntropyLoss from torch.nn)
    :return: mean_accuracy: mean accuracy of predicted labels
             test loss: mean test loss during testing
    11 11 11
   model.eval()
   losses = []
   correct = 0
   total = 0
   # TO DO: read this documentation and then uncomment the line be
low; https://pypi.org/project/tqdm/
    it test = tqdm(enumerate(test loader), total=len(test loader),
desc="Validating ...", position = 0)
   for i, (images, labels) in it test:
      # TO DO: read/understand and then uncomment these lines
```

```
images, labels = images.to(device), labels.to(device)
    with torch.no_grad(): # https://pytorch.org/docs/stable/gene
rated/torch.no_grad.html
    output = model(images) # do not compute gradient when perfor
ming prediction
    preds = torch.argmax(output, dim=-1)
    loss = criterion(output, labels)
    losses.append(loss.item())
    correct += (preds == labels).sum().item()
    total += len(labels)

mean_accuracy = correct / total
    test_loss = np.mean(losses)
    print('Mean Accuracy: {0:.4f}'.format(mean_accuracy))
    print('Avg loss: {}'.format(test_loss))
return mean_accuracy, test_loss
```

```
In [12]: import torch
         import torchvision.models as models
         # loads a pre-trained ResNet-34 model
         model = torch.hub.load('pytorch/vision:v0.10.0', 'resnet34', pretra
         ined=True)
         # Number of target classes in the Pet dataset
         num target classes = 37
         # Replace the last layer (classification head) with a new linear la
         yer for Pet classification
         model.fc = torch.nn.Linear(in features=model.fc.in features, out fe
         atures=num target classes)
         # Assuming 'device' is defined (e.g., device = torch.device("cuda"
         if torch.cuda.is available() else "cpu"))
         model = model.to(device)
         # Function to display the model structure; ensure it is correctly d
         efined elsewhere in your code
         # This function might simply be a print(model) or more detailed log
         ging of model parameters
         def display model(model):
             print(model)
         display model(model) # Displays the model structure and parameter
         count
```

```
Using cache found in /Users/darian/.cache/torch/hub/pytorch vision
v0.10.0
/opt/homebrew/lib/python3.8/site-packages/torchvision/models/ util
s.py:208: UserWarning: The parameter 'pretrained' is deprecated si
nce 0.13 and may be removed in the future, please use 'weights' in
stead.
  warnings.warn(
/opt/homebrew/lib/python3.8/site-packages/torchvision/models/ util
s.py:223: UserWarning: Arguments other than a weight enum or `None
 for 'weights' are deprecated since 0.13 and may be removed in th
e future. The current behavior is equivalent to passing `weights=R
esNet34 Weights.IMAGENET1K V1. You can also use `weights=ResNet34
Weights.DEFAULT to get the most up-to-date weights.
 warnings.warn(msg)
ResNet(
  (conv1): Conv2d(3, 64, kernel size=(7, 7), stride=(2, 2), paddin
g=(3, 3), bias=False)
  (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, tra
ck running stats=True)
  (relu): ReLU(inplace=True)
  (maxpool): MaxPool2d(kernel size=3, stride=2, padding=1, dilatio
n=1, ceil mode=False)
  (layer1): Sequential(
    (0): BasicBlock(
      (conv1): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), p
adding=(1, 1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), p
adding=(1, 1), bias=False)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    (1): BasicBlock(
      (conv1): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), p
adding=(1, 1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), p
adding=(1, 1), bias=False)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    (2): BasicBlock(
      (conv1): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), p
adding=(1, 1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), p
adding=(1, 1), bias=False)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    )
```

```
(layer2): Sequential(
    (0): BasicBlock(
      (conv1): Conv2d(64, 128, kernel size=(3, 3), stride=(2, 2),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (downsample): Sequential(
        (0): Conv2d(64, 128, kernel size=(1, 1), stride=(2, 2), bi
as=False)
        (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=Tru
e, track_running_stats=True)
    (1): BasicBlock(
      (conv1): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
    (2): BasicBlock(
      (conv1): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
    (3): BasicBlock(
      (conv1): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
    )
  (layer3): Sequential(
    (0): BasicBlock(
      (conv1): Conv2d(128, 256, kernel_size=(3, 3), stride=(2, 2),
padding=(1, 1), bias=False)
```

```
(bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (downsample): Sequential(
        (0): Conv2d(128, 256, kernel size=(1, 1), stride=(2, 2), b
ias=False)
        (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
    (1): BasicBlock(
      (conv1): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
    (2): BasicBlock(
      (conv1): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track_running_stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
    (3): BasicBlock(
      (conv1): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
    (4): BasicBlock(
      (conv1): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track_running_stats=True)
```

```
(5): BasicBlock(
      (conv1): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
  )
  (layer4): Sequential(
    (0): BasicBlock(
      (conv1): Conv2d(256, 512, kernel size=(3, 3), stride=(2, 2),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
      (downsample): Sequential(
        (0): Conv2d(256, 512, kernel size=(1, 1), stride=(2, 2), b
ias=False)
        (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
    )
    (1): BasicBlock(
      (conv1): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=Tru
e, track_running_stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
    )
    (2): BasicBlock(
      (conv1): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=Tru
e, track running_stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=Tru
e, track running stats=True)
  )
  (avgpool): AdaptiveAvgPool2d(output size=(1, 1))
  (fc): Linear(in_features=512, out_features=37, bias=True)
)
```

```
In [13]: # Training Setting. Feel free to change.
         num epochs = 10
         test interval = 1
         # TO DO: set initial learning rate
         learn rate = 0.1
         optimizer = torch.optim.SGD(model.parameters(), lr=learn rate)
         # TO DO: define your learning rate scheduler, e.g. StepLR
         # https://pytorch.org/docs/stable/optim.html#module-torch.optim.lr
         scheduler
         # Setting up CosineAnnealingLR
         T max = 10 # Duration of a single learning rate cycle
         eta min = 0.00001 # Minimum learning rate
         lr scheduler = torch.optim.lr scheduler.CosineAnnealingLR(optimize
         r, T_max=T_max, eta_min=eta_min)
         criterion = torch.nn.CrossEntropyLoss()
         train losses = []
         train accuracy list = []
         test losses = []
         test accuracy list = []
         # Iterate over the DataLoader for training data
         for epoch in tqdm(range(num epochs), total=num epochs, desc="Traini
         ng ...", position=1):
             # Train the network for one epoch
             train loss = train(train loader, model, criterion, optimizer)
             # TO DO: uncomment the line below. It should be called each epo
         ch to apply the lr scheduler
             lr scheduler.step()
             train losses.append(train loss)
             print(f'Loss for Training on epoch {str(epoch)} is {str(train l
         oss) \ \ \ \ \ \ )
             # Get the train accuracy and test loss/accuracy
             if(epoch%test interval==0 or epoch==1 or epoch==num epochs-1):
                 print('Evaluating Network')
                 train_accuracy, _ = test(train_loader, model, criterion) #
         Get training accuracy
                 train accuracy list.append(train accuracy)
                 print(f'Training accuracy on epoch {str(epoch)} is {str(tra
         test accuracy, test loss = test(test loader, model, criteri
```

```
on) # Get testing accuracy and error
       test losses.append(test loss)
       test accuracy list.append(test accuracy)
       print(f'Test (val) accuracy on epoch {str(epoch)} is {str(t
est accuracy)} \n')
        # Checkpoints are used to save the model with best validati
on accuracy
        if test accuracy >= max(test accuracy list):
         print("Saving Model")
         save checkpoint(save dir, model, save name = 'best model.
pth') # Save model with best performance
        # if test accuracy >= 0.9:
              print("Desired accuracy reached. Saving Model.")
              save checkpoint(save dir, model, save name='best mo
del.pth')
               success = True
               break # Exit the loop early if the desired accurac
y is met
loss: 0.356: 100% 2006 2006 29/29 [00:48<00:00, 1.66s/it]
Loss for Training on epoch 0 is 1.1219996213912964
Evaluating Network
Validating ...: 100% 29/29 [00:21<00:00, 1.34it/s]
Mean Accuracy: 0.9277
Avg loss: 0.2854201726872346
Training accuracy on epoch 0 is 0.9277173913043478
Validating ...: 100% 29/29 [00:20<00:00, 1.39it/s]
Mean Accuracy: 0.8498
Avg loss: 0.5052560028331033
Test (val) accuracy on epoch 0 is 0.8498228400109021
Saving Model
loss: 0.126: 100% 29/29 [00:47<00:00, 1.63s/it]
Loss for Training on epoch 1 is 0.15913696587085724
Evaluating Network
Validating ...: 100% 29/29 [00:20<00:00, 1.42it/s]
Mean Accuracy: 0.9826
Avg loss: 0.10214457943521697
Training accuracy on epoch 1 is 0.9826086956521739
Validating ...: 100% 29/29 [00:20<00:00, 1.42it/s]
```

Mean Accuracy: 0.8918

Avg loss: 0.3837804488580802

Test (val) accuracy on epoch 1 is 0.8917961297356228

Saving Model

loss: 0.040: 100% 29/29 [00:46<00:00, 1.61s/it]

Loss for Training on epoch 2 is 0.056164197623729706

Evaluating Network

Validating ...: 100% 29/29 [00:20<00:00, 1.40it/s]

Mean Accuracy: 0.9997

Avg loss: 0.024761343631764937

Training accuracy on epoch 2 is 0.9997282608695652

Validating ...: 100% 29/29 [00:20<00:00, 1.44it/s]

Mean Accuracy: 0.9199

Avg loss: 0.2748762646625782

Test (val) accuracy on epoch 2 is 0.919869174161897

Saving Model

loss: 0.017: 100% 29/29 [00:46<00:00, 1.59s/it]

Loss for Training on epoch 3 is 0.026439199224114418

Evaluating Network

Validating ...: 100% 29/29 [00:20<00:00, 1.43it/s]

Mean Accuracy: 1.0000

Avg loss: 0.013861465299951619 Training accuracy on epoch 3 is 1.0

Validating ...: 100% 29/29 [00:20<00:00, 1.44it/s]

Mean Accuracy: 0.9237

Avg loss: 0.2685117555846428

Test (val) accuracy on epoch 3 is 0.9236849277732352

Saving Model

loss: 0.018: 100% | 29/29 [00:46<00:00, 1.60s/it]

Loss for Training on epoch 4 is 0.016797997057437897

Evaluating Network

Validating ...: 100% 29/29 [00:20<00:00, 1.43it/s]

Mean Accuracy: 1.0000

Avg loss: 0.010497034398903107

Training accuracy on epoch 4 is 1.0

Validating ...: 100% 29/29 [00:20<00:00, 1.45it/s]

Mean Accuracy: 0.9218

Avg loss: 0.2639962213820425

Test (val) accuracy on epoch 4 is 0.9217770509675661

loss: 0.011: 100% 29/29 [00:46<00:00, 1.61s/it]

Loss for Training on epoch 5 is 0.013916683383286

Evaluating Network

Validating ...: 100% 29/29 [00:21<00:00, 1.34it/s]

Mean Accuracy: 1.0000

Avg loss: 0.008532094271403962

Training accuracy on epoch 5 is 1.0

Validating ...: 100% 29/29 [00:20<00:00, 1.43it/s]

Mean Accuracy: 0.9240

Avg loss: 0.26364428614234103

Test (val) accuracy on epoch 5 is 0.9239574816026165

Saving Model

loss: 0.013: 100% | 29/29 [00:47<00:00, 1.64s/it]

Loss for Training on epoch 6 is 0.012299755588173866

Evaluating Network

Validating ...: 100% 29/29 [00:20<00:00, 1.43it/s]

Mean Accuracy: 1.0000

Avg loss: 0.007661389395723055

Training accuracy on epoch 6 is 1.0

Validating ...: 100% 29/29 [00:20<00:00, 1.43it/s]

Mean Accuracy: 0.9242

Avg loss: 0.26288495277022494

Test (val) accuracy on epoch 6 is 0.9242300354319978

Saving Model

loss: 0.010: 100% | 29/29 [00:46<00:00, 1.59s/it]

Loss for Training on epoch 7 is 0.010628700256347656

Evaluating Network

Validating ...: 100% 29/29 [00:20<00:00, 1.43it/s]

Mean Accuracy: 1.0000

Avg loss: 0.007380804384191488

Training accuracy on epoch 7 is 1.0

Validating ...: 100% 29/29 [00:20<00:00, 1.44it/s]

Mean Accuracy: 0.9231

Avg loss: 0.2611089857487843

Test (val) accuracy on epoch 7 is 0.9231398201144726

loss: 0.014: 100% | 29/29 [00:46<00:00, 1.59s/it]

Loss for Training on epoch 8 is 0.01050286553800106

Evaluating Network

Validating ...: 100% 29/29 [00:20<00:00, 1.43it/s]

Mean Accuracy: 1.0000

Avg loss: 0.007227688128578252 Training accuracy on epoch 8 is 1.0

Validating ...: 100% 29/29 [00:20<00:00, 1.44it/s]

Mean Accuracy: 0.9226

Avg loss: 0.26182977829513876

Test (val) accuracy on epoch 8 is 0.92259471245571

loss: 0.009: 100% 29/29 [00:46<00:00, 1.59s/it]

Loss for Training on epoch 9 is 0.010310512967407703

Evaluating Network

Validating ...: 100% 29/29 [00:20<00:00, 1.43it/s]

Mean Accuracy: 1.0000

Avg loss: 0.007085385106118588
Training accuracy on epoch 9 is 1.0

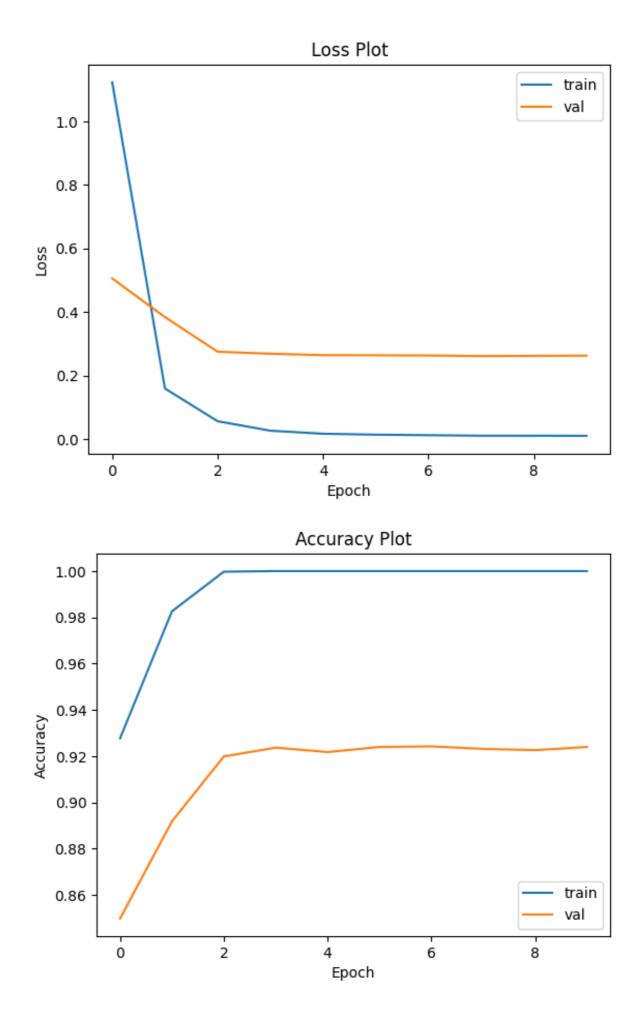
Mean Accuracy: 0.9240

Avg loss: 0.2624028641088256

Test (val) accuracy on epoch 9 is 0.9239574816026165

2.5 Plotting of losses and accuracy

In [14]: plot_losses(train_losses, test_losses, test_interval, num_epochs)
 plot_accuracy(train_accuracy_list, test_accuracy_list, test_interval, num_epochs)



Part 3: CLIP: Contrastive Language-Image Pretraining

Include all the code for Part 3 in this section

3.1 Prepare data

<u>Here (https://drive.google.com/file/d/1zJ1KfymSfsbmD6QS-F0eUC8T1PkqW0_j/view?usp=sharing)</u> is the json file you need for labels of flowers 102

```
In [ ]: import json
import os
import os.path as osp
import numpy as np
from google.colab import drive
import torch
from torchvision.datasets import Flowers102
%matplotlib inline
from matplotlib import pyplot as plt
```

Mounted at /content/drive

```
In [ ]: def load_flower_data(img_transform=None):
    if os.path.isdir(datadir+ "flowers-102"):
        do_download = False
    else:
        do_download = True
        train_set = Flowers102(root=datadir, split='train', transform=i
    mg_transform, download=do_download)
        test_set = Flowers102(root=datadir, split='val', transform=img_
        transform, download=do_download)
        classes = json.load(open(osp.join(datadir, "flowers102_classes.
        json")))
    return train_set, test_set, classes
```

```
In [ ]: # READ ME! This takes some time (a few minutes), so if you are usi
        ng Colabs and want to use GPU for speed,
                    first set to use GPU: Edit->Notebook Settings->Hardware
        Accelerator=GPU, and restart instance
        # Data structure details
          flower train[n][0] is the nth train image
            flower train[n][1] is the nth train label
        # flower test[n][0] is the nth test image
        # flower test[n][1] is the nth test label
            flower classes[k] is the name of the kth class
        flower train, flower test, flower classes = load flower data()
In [ ]: len(flower_train), len(flower_test) # output should be (1020, 102
        0)
Out[]: (1020, 1020)
In [ ]: # Display a sample in Flowers 102 dataset
        sample idx = 0 # Choose an image index that you want to display
        print("Label:", flower_classes[flower_train[sample_idx][1]])
        flower train[sample idx][0]
        Label: pink primrose
Out[]:
```



3.2 Prepare CLIP model

```
In []: | # !conda install --yes -c pytorch pytorch=1.7.1 torchvision cudatoo
        1kit=11.0
        # !pip install ftfy regex tqdm
        !pip install pytorch==1.7.1 torchvision cudatoolkit==11.0
        ERROR: Could not find a version that satisfies the requirement pyt
        orch==1.7.1 (from versions: 0.1.2, 1.0.2)
        ERROR: No matching distribution found for pytorch==1.7.1
In []: | !pip install git+https://github.com/openai/CLIP.git
        Collecting git+https://github.com/openai/CLIP.git
          Cloning https://github.com/openai/CLIP.git to /tmp/pip-req-build
        -ucqbvr91
          Running command git clone --filter=blob:none --quiet https://git
        hub.com/openai/CLIP.git /tmp/pip-req-build-ucqbvr91
          Resolved https://github.com/openai/CLIP.git to commit ald071733d
        7111c9c014f024669f959182114e33
          Preparing metadata (setup.py) ... done
        Collecting ftfy (from clip==1.0)
          Downloading ftfy-6.2.0-py3-none-any.whl (54 kB)
                                                  54.4/54.4 kB 413.7 k
        B/s eta 0:00:00
        Requirement already satisfied: regex in /usr/local/lib/python3.10/
        dist-packages (from clip==1.0) (2023.12.25)
        Requirement already satisfied: tqdm in /usr/local/lib/python3.10/d
        ist-packages (from clip==1.0) (4.66.2)
        Requirement already satisfied: torch in /usr/local/lib/python3.10/
        dist-packages (from clip==1.0) (2.2.1+cu121)
        Requirement already satisfied: torchvision in /usr/local/lib/pytho
        n3.10/dist-packages (from clip==1.0) (0.17.1+cu121)
        Requirement already satisfied: wcwidth<0.3.0,>=0.2.12 in /usr/loca
        1/lib/python3.10/dist-packages (from ftfy->clip==1.0) (0.2.13)
        Requirement already satisfied: filelock in /usr/local/lib/python3.
        10/dist-packages (from torch->clip==1.0) (3.13.4)
        Requirement already satisfied: typing-extensions>=4.8.0 in /usr/lo
        cal/lib/python3.10/dist-packages (from torch->clip==1.0) (4.11.0)
        Requirement already satisfied: sympy in /usr/local/lib/python3.10/
        dist-packages (from torch->clip==1.0) (1.12)
        Requirement already satisfied: networkx in /usr/local/lib/python3.
        10/dist-packages (from torch->clip==1.0) (3.3)
        Requirement already satisfied: jinja2 in /usr/local/lib/python3.1
        0/dist-packages (from torch->clip==1.0) (3.1.3)
        Requirement already satisfied: fsspec in /usr/local/lib/python3.1
        0/dist-packages (from torch->clip==1.0) (2023.6.0)
        Collecting nvidia-cuda-nvrtc-cu12==12.1.105 (from torch->clip==1.
          Using cached nvidia cuda nvrtc cu12-12.1.105-py3-none-manylinux1
        _x86_64.whl (23.7 MB)
        Collecting nvidia-cuda-runtime-cu12==12.1.105 (from torch->clip==
        1.0)
          Using cached nvidia cuda runtime cu12-12.1.105-py3-none-manylinu
        x1 x86 64.whl (823 kB)
        Collecting nvidia-cuda-cupti-cu12==12.1.105 (from torch->clip==1.
          Using cached nvidia cuda cupti cu12-12.1.105-py3-none-manylinux1
```

```
_x86_64.whl (14.1 MB)
Collecting nvidia-cudnn-cu12==8.9.2.26 (from torch->clip==1.0)
  Using cached nvidia cudnn cu12-8.9.2.26-py3-none-manylinux1 x86
64.whl (731.7 MB)
Collecting nvidia-cublas-cu12==12.1.3.1 (from torch->clip==1.0)
  Using cached nvidia cublas cu12-12.1.3.1-py3-none-manylinux1 x86
64.whl (410.6 MB)
Collecting nvidia-cufft-cu12==11.0.2.54 (from torch->clip==1.0)
  Using cached nvidia cufft cu12-11.0.2.54-py3-none-manylinux1 x86
64.whl (121.6 MB)
Collecting nvidia-curand-cu12==10.3.2.106 (from torch->clip==1.0)
  Using cached nvidia curand cu12-10.3.2.106-py3-none-manylinux1 x
86_64.whl (56.5 MB)
Collecting nvidia-cusolver-cu12==11.4.5.107 (from torch->clip==1.
  Using cached nvidia cusolver cu12-11.4.5.107-py3-none-manylinux1
x86 64.whl (124.2 MB)
Collecting nvidia-cusparse-cu12==12.1.0.106 (from torch->clip==1.
  Using cached nvidia_cusparse_cu12-12.1.0.106-py3-none-manylinux1
x86 64.whl (196.0 MB)
Collecting nvidia-nccl-cu12==2.19.3 (from torch->clip==1.0)
  Using cached nvidia nccl cu12-2.19.3-py3-none-manylinux1 x86 64.
whl (166.0 MB)
Collecting nvidia-nvtx-cu12==12.1.105 (from torch->clip==1.0)
  Using cached nvidia_nvtx_cu12-12.1.105-py3-none-manylinux1_x86_6
4.whl (99 kB)
Requirement already satisfied: triton==2.2.0 in /usr/local/lib/pyt
hon3.10/dist-packages (from torch->clip==1.0) (2.2.0)
Collecting nvidia-nvjitlink-cu12 (from nvidia-cusolver-cu12==11.4.
5.107->torch->clip==1.0)
  Using cached nvidia nvjitlink cu12-12.4.127-py3-none-manylinux20
14 x86 64.whl (21.1 MB)
Requirement already satisfied: numpy in /usr/local/lib/python3.10/
dist-packages (from torchvision->clip==1.0) (1.25.2)
Requirement already satisfied: pillow!=8.3.*,>=5.3.0 in /usr/loca
1/lib/python3.10/dist-packages (from torchvision->clip==1.0) (9.4.
Requirement already satisfied: MarkupSafe>=2.0 in /usr/local/lib/p
ython3.10/dist-packages (from jinja2->torch->clip==1.0) (2.1.5)
Requirement already satisfied: mpmath>=0.19 in /usr/local/lib/pyth
on3.10/dist-packages (from sympy->torch->clip==1.0) (1.3.0)
Building wheels for collected packages: clip
  Building wheel for clip (setup.py) ... done
  Created wheel for clip: filename=clip-1.0-py3-none-any.whl size=
1369499 sha256=2fb43b46e13a41a2ea3f90c30f17034f27ed626dd9fce379274
3fbc4fb07c984
  Stored in directory: /tmp/pip-ephem-wheel-cache-h1n9iwtz/wheels/
da/2b/4c/d6691fa9597aac8bb85d2ac13b112deb897d5b50f5ad9a37e4
Successfully built clip
Installing collected packages: nvidia-nvtx-cu12, nvidia-nvjitlink-
cu12, nvidia-nccl-cu12, nvidia-curand-cu12, nvidia-cufft-cu12, nvi
dia-cuda-runtime-cul2, nvidia-cuda-nvrtc-cul2, nvidia-cuda-cupti-c
```

u12, nvidia-cublas-cu12, ftfy, nvidia-cusparse-cu12, nvidia-cudnn-

Successfully installed clip-1.0 ftfy-6.2.0 nvidia-cublas-cu12-12. 1.3.1 nvidia-cuda-cupti-cu12-12.1.105 nvidia-cuda-nvrtc-cu12-12.1.

cu12, nvidia-cusolver-cu12, clip

105 nvidia-cuda-runtime-cu12-12.1.105 nvidia-cudnn-cu12-8.9.2.26 n vidia-cufft-cu12-11.0.2.54 nvidia-curand-cu12-10.3.2.106 nvidia-cu solver-cu12-11.4.5.107 nvidia-cusparse-cu12-12.1.0.106 nvidia-nccl-cu12-2.19.3 nvidia-nvjitlink-cu12-12.4.127 nvidia-nvtx-cu12-12.1.105

3.3 CLIP zero-shot prediction

```
"""The following is an example of using CLIP pre-trained model for
In [ ]:
        zero-shot prediction task"""
        # Prepare the inputs
        n = 100 # image index to use
        image, class_id = flower_train[n]
        image input = clip preprocess(image).unsqueeze(0).to(device) # extr
        act image and put in device memory
        text_inputs = torch.cat([clip.tokenize(f"a photo of a {c}, a type o
        f flower.") for c in flower classes]).to(device) # put text to matc
        h to image in device memory
        # Calculate features
        with torch.no grad():
            image features = clip model.encode image(image input) # compute
        image features with CLIP model
            text features = clip model.encode text(text inputs) # compute t
        ext features with CLIP model
        image features /= image features.norm(dim=-1, keepdim=True) # unit-
        normalize image features
        text features /= text features.norm(dim=-1, keepdim=True) # unit-no
        rmalize text features
        # Pick the top 5 most similar labels for the image
        similarity = (100.0 * image features @ text features.T) # score is
        cosine similarity times 100
        p class given image= similarity.softmax(dim=-1) # P(y|x) is score
        through softmax
        values, indices = p class given image[0].topk(5) # gets the top 5 1
        abels
        # Print the probability of the top five labels
        print("Ground truth:", flower classes[class id])
        print("\nTop predictions:\n")
        for value, index in zip(values, indices):
            print(f"{flower classes[index]:>16s}: {100 * value.item():.2
        f}%")
        image
```

Ground truth: snapdragon

Top predictions:

sweet pea: 30.35%
garden phlox: 26.37%
snapdragon: 25.95%
wallflower: 4.24%
bougainvillea: 1.91%

Out[]:



3.4 YOUR TASK: Test CLIP zero-shot performance on Flowers 102

Use pre-trained text and image representations to classify images. For zero-shot recognition, text features are computed from the CLIP model for phrases such as "An image of [flower_name], a type of flower" for varying [flower_name] inserts. Then, image features are computed using the CLIP model for an image, and the cosine similarity between each text and image is computed. The label corresponding to the most similar text is assigned to the image. You'll get that working using a data loader, which enables faster batch processing; then, compute the accuracy over the test set. You should see top-1 accuracy in the 60-70% range.

For zero-shot, you do not use the training set at all. You should only have to compute the text vectors once and re-use them for all test images.

Basic steps:

- 1. Create the normalized CLIP text vectors for each class label.
- 2. For each batch:
 - · Create normalized CLIP image vectors
 - Compute similarity between text and image vectors
 - Get index of most likely class label and check whether it matches the ground truth
 - · Keep a count of number correct and number total
- 3. Return accuracy = # correct / # total

```
In [ ]: from tqdm import tqdm
    from torch.utils.data import DataLoader

In [ ]: # Load flowers dataset again. This time, with clip_preprocess as tr
    ansform (you don't have to call clip_preprocess again)
    flower_train_trans, flower_test_trans, flower_classes = load_flower
    _data(img_transform=clip_preprocess)
```

```
In [ ]: def clip zero shot(data set, classes):
            data loader = DataLoader(data set, batch size=32, shuffle=Fals
        e) # dataloader lets you process in batch which is way faster (whe
        n using GPU)
            # TO DO: Needs code here
            total correct = 0
            total images = 0
            class descriptions = [f"a photo of a {c}, a type of flower" for
        c in classes]
            text tokens = clip.tokenize(class descriptions).to(device)
            with torch.no grad():
                text features = clip model.encode text(text tokens)
                text_features /= text_features.norm(dim=-1, keepdim=True)
                # Iterate over all batches
                for images, labels in tqdm(data loader, desc="Evaluating"):
                    images = images.to(device)
                    labels = labels.to(device)
                    # Calculate image features
                    image features = clip model.encode image(images)
                    image features /= image features.norm(dim=-1, keepdim=T
        rue)
                    # Calculate similarity and predictions
                    similarity = image features @ text features.T
                    predictions = similarity.argmax(dim=-1)
                    # Update correct predictions counter
                    total correct += (predictions == labels).sum().item()
                    total images += labels.size(0)
            # Calculate accuracy
            accuracy = total correct / total images
            return accuracy
In [ ]: torch.cuda.empty cache()
In [ ]: accuracy = clip zero shot(data set=flower test trans, classes=flowe
        r classes)
        print(f"\nAccuracy = {100*accuracy:.3f}%")
        Evaluating: 100% 32/32 [00:14<00:00, 2.23it/s]
```

Accuracy = 67.647%

3.5 YOUR TASK: Test CLIP linear probe performance on Flowers 102

We do not use text features for the linear probe method. Train on the train set, and evaluate on the test set and report your performance. You can get top-1 accuracy in the 90-95% range. If you're getting in the 80's, try both normalizing and not normalizing the features.

```
from sklearn.linear model import LogisticRegression
In [ ]:
In [ ]:
        Returns image features and labels in numpy format.
        The labels should just be integers representing class index, not te
        xt vectors.
        def get features(data set):
            # TO DO: Needs code here to extract features and labels
            all features = []
            all labels = []
            with torch.no grad():
                for images, labels in tqdm(DataLoader(data set, batch size=
        100)):
                    features = clip_model.encode_image(images.to(device))
                    all features.append(features)
                    all labels.append(labels)
            return torch.cat(all features).cpu().numpy(), torch.cat(all lab
        els).cpu().numpy()
In [ ]: # Calculate the image features
        train_features, train_labels = get_features(flower_train_trans)
        test features, test labels = get features(flower test trans)
        # TO DO: Needs code here
        # Train logistic regression model with train features, train labels
        classifier = LogisticRegression(random state=0, C=0.316, max iter=1
        000, verbose=1)
        classifier.fit(train features, train labels)
        # Evaluate accuracy on test features, test labels
        predictions = classifier.predict(test features)
        accuracy = np.mean((test_labels == predictions).astype(float))
        print(f"\nAccuracy = {100*accuracy:.3f}%")
        100%
                       11/11 [06:48<00:00, 37.18s/it]
                       11/11 [06:47<00:00, 37.03s/it]
        Accuracy = 93.431%
```

3.6 YOUR TASK: Evaluate a nearest-neighbor classifier on CLIP features

Extract features based on the pre-trained model (can be the same features as 3.5) and apply a nearest neighbor classifier. You can use your own implementation of nearest neighbor or a library like sklearn or FAISS for this. Try K={1, 3, 5, 7, 11, 21}. If using sklearn, you can also experiment with 'uniform' and 'distance' weighting. Report performance for best K on the test set. You can also experiment with using unnormalized or normalized features. You should see top-1 accuracy in the 80-90% range.

Part 4: Stretch Goals

Include any new code needed for Part 4 here.

4.a Compare word tokenizers

Train at least two 8K token word tokenizers (e.g. BPE, WordPiece, SentencePiece) on the WikiText-2, and compare their encodings. You can use existing libraries, such as those linked below to train and encode/decode. Report the encodings for "I am learning about word tokenizers. They are not very complicated, and they are a good way to convert natural text into tokens." E.g. "I am the fastest planet" may end up being tokenized as [I, _am, _the, _fast, est, _plan, et]. Also, report the tokenizations of an additional sentence of your choice that results in different encodings by the two models.

https://github.com/huggingface/tokenizers (https://github.com/huggingface/tokenizers)

```
In [ ]: !pip install tokenizers
```

```
Requirement already satisfied: tokenizers in /usr/local/lib/python
3.10/dist-packages (0.15.2)
Requirement already satisfied: huggingface hub<1.0,>=0.16.4 in /us
r/local/lib/python3.10/dist-packages (from tokenizers) (0.20.3)
Requirement already satisfied: filelock in /usr/local/lib/python3.
10/dist-packages (from huggingface hub<1.0,>=0.16.4->tokenizers) (
3.13.4)
Requirement already satisfied: fsspec>=2023.5.0 in /usr/local/lib/
python3.10/dist-packages (from huggingface hub<1.0,>=0.16.4->token
izers) (2023.6.0)
Requirement already satisfied: requests in /usr/local/lib/python3.
10/dist-packages (from huggingface_hub<1.0,>=0.16.4->tokenizers) (
Requirement already satisfied: tqdm>=4.42.1 in /usr/local/lib/pyth
on3.10/dist-packages (from huggingface hub<1.0,>=0.16.4->tokenizer
s) (4.66.2)
Requirement already satisfied: pyyaml>=5.1 in /usr/local/lib/pytho
n3.10/dist-packages (from huggingface hub<1.0,>=0.16.4->tokenizer
Requirement already satisfied: typing-extensions>=3.7.4.3 in /usr/
local/lib/python3.10/dist-packages (from huggingface hub<1.0,>=0.1
6.4->tokenizers) (4.11.0)
Requirement already satisfied: packaging>=20.9 in /usr/local/lib/p
ython3.10/dist-packages (from huggingface_hub<1.0,>=0.16.4->tokeni
zers) (24.0)
Requirement already satisfied: charset-normalizer<4,>=2 in /usr/lo
cal/lib/python3.10/dist-packages (from requests->huggingface hub<
1.0,>=0.16.4->tokenizers) (3.3.2)
Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/pyth
on3.10/dist-packages (from requests->huggingface hub<1.0,>=0.16.4-
>tokenizers) (3.6)
Requirement already satisfied: urllib3<3,>=1.21.1 in /usr/local/li
b/python3.10/dist-packages (from requests->huggingface_hub<1.0,>=
0.16.4->tokenizers) (2.0.7)
Requirement already satisfied: certifi>=2017.4.17 in /usr/local/li
b/python3.10/dist-packages (from requests->huggingface hub<1.0,>=
0.16.4->tokenizers) (2024.2.2)
from tokenizers import Tokenizer
```

```
rd_language_model/data/wikitext-2/train.txt"
train file = download file(url)
# Initialize tokenizers
bpe tokenizer = Tokenizer(BPE(unk token="[UNK]"))
wordpiece tokenizer = Tokenizer(WordPiece(unk token="[UNK]"))
# Initialize trainers
bpe trainer = BpeTrainer(vocab size=8000, special tokens=["[UNK]",
"[CLS]", "[SEP]", "[PAD]", "[MASK]"])
wordpiece trainer = WordPieceTrainer(vocab size=8000, special token
s=["[UNK]", "[CLS]", "[SEP]", "[PAD]", "[MASK]"])
# Train BPE
bpe tokenizer.train([train file], bpe trainer)
# Train WordPiece
wordpiece tokenizer.train([train file], wordpiece trainer)
# Save tokenizers
bpe tokenizer.save("bpe tokenizer.json")
wordpiece tokenizer.save("wordpiece tokenizer.json")
sample text = "I am learning about word tokenizers. They are not ve
ry complicated, and they are a good way to convert natural text int
o tokens."
additional_text = "I have learnt a lot from Applied Machine Learnin
g at UIUC"
# Encode with BPE
bpe encoded = bpe tokenizer.encode(sample text)
print("BPE Encoding:", bpe encoded.tokens)
# Encode with WordPiece
wordpiece encoded = wordpiece tokenizer.encode(sample text)
print("WordPiece Encoding:", wordpiece encoded.tokens)
# Encode additional sentence
bpe_encoded_additional = bpe_tokenizer.encode(additional_text)
wordpiece encoded additional = wordpiece tokenizer.encode(additiona
1 text)
print("Additional BPE Encoding:", bpe encoded additional.tokens)
print("Additional WordPiece Encoding:", wordpiece encoded additiona
1.tokens)
```

```
BPE Encoding: ['I ', 'am ', 'lear', 'ning ', 'about ', 'word ', 't
o', 'k', 'en', 'iz', 'er', 's', '. They ', 'are not ', 'very ', 'c
ompl', 'ic', 'at', 'ed', ', and ', 'they are ', 'a ', 'good ', 'wa
y to ', 'conver', 't ', 'natural ', 'text ', 'into ', 'to', 'k', '
ens', '.']
WordPiece Encoding: ['[UNK]']
Additional BPE Encoding: ['I ', 'have ', 'lear', 'n', 't ', 'a ',
'l', 'ot ', 'from ', 'Ap', 'pl', 'ied ', 'M', 'ach', 'ine ', 'L',
'ear', 'ning ', 'at ', 'U', 'I', 'U', 'C']
Additional WordPiece Encoding: ['I', '## ', '##have ', '##lear',
'##n', '##t ', '##a ', '##lo', '##t ', '##from ', '##Ap', '##pl',
'##ied ', '##Mac', '##hi', '##ne ', '##Le', '##ar', '##ning ', '##
at ', '##U', '##I', '##U', '##C']
```

4.b Implement your own network

For the Oxford Pets dataset, try to write the network by yourself. You can get ideas from existing works, but you cannot directly import them using packages, and the parameter number should be lower than 20M. Train your network from scratch. You would get points if your network can reach an accuracy of 35% (15 pts), and another 15 pts if it reaches 45%. You would want to pay more attention to data augmentation and other hyper-parameters during this part. Feel free to re-use any functions defined in Part 2.

```
In [ ]: # example network definition that needs to be modified for custom n
        etwork stretch goal
        class Network(nn.Module):
            def __init__(self, num_classes=10, dropout = 0.5):
                super(Network, self). init ()
                self.features = nn.Sequential(
                    nn.Conv2d(3, 64, kernel size=11, stride=4, padding=2),
                    nn.ReLU(inplace=True),
                    nn.MaxPool2d(kernel size=3, stride=2),
                    nn.Conv2d(64, 256, kernel size=5, padding=2),
                    nn.ReLU(inplace=True),
                    nn.MaxPool2d(kernel_size=3, stride=2),
                    nn.Conv2d(256, 256, kernel size=3, padding=1),
                    nn.ReLU(inplace=True),
                    nn.MaxPool2d(kernel size=3, stride=2),
                )
                self.avgpool = nn.AdaptiveAvgPool2d((6, 6))
                self.classifier = nn.Sequential(
                    nn.Dropout(p=dropout),
                    nn.Linear(256 * 6 * 6, 512),
                    nn.ReLU(inplace=True),
                    nn.Dropout(p=dropout),
                    nn.Linear(512, 512),
                    nn.ReLU(inplace=True),
                    nn.Linear(512, num classes),
                )
            def forward(self, x):
                N, c, H, W = x.shape
                features = self.features(x)
                pooled features = self.avgpool(features)
                output = self.classifier(torch.flatten(pooled features, 1))
                return output
```

```
In []: | # from https://gist.github.com/jonathanagustin/b67b97ef12c53a8dec27
        b343dca4abba
        # install can take a minute
        import os
        # @title Convert Notebook to PDF. Save Notebook to given directory
        NOTEBOOKS DIR = "/content/drive/My Drive/CS441/24SP/hw2" # @param {
        type:"string"}
        NOTEBOOK NAME = "CS441 SP24 HW2 Solution.ipynb" # @param {type:"str
        ing"}
        #-----
        ----#
        from google.colab import drive
        drive.mount("/content/drive/", force_remount=True)
        NOTEBOOK PATH = f"{NOTEBOOKS DIR}/{NOTEBOOK NAME}"
        assert os.path.exists(NOTEBOOK PATH), f"NOTEBOOK NOT FOUND: {NOTEBO
        OK PATH}"
        !apt install -y texlive-xetex texlive-fonts-recommended texlive-pla
        in-generic > /dev/null 2>&1
        | jupyter nbconvert "$NOTEBOOK PATH" --to pdf > /dev/null 2>&1
        NOTEBOOK_PDF = NOTEBOOK_PATH.rsplit('.', 1)[0] + '.pdf'
        assert os.path.exists(NOTEBOOK PDF), f"ERROR MAKING PDF: {NOTEBOOK
        PDF}"
        print(f"PDF CREATED: {NOTEBOOK PDF}")
```

In []: