Final Project - Code

This notebook serves as the final code utilized for the ASL classification project for EEL5840.

Team - FML_Party

Members - Darian Jennings and Ashley Hart

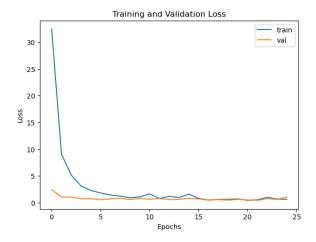
Model used - VGG19

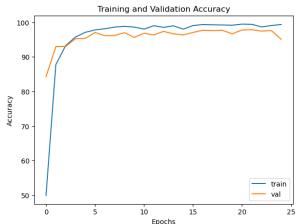
- You should expect the test dataset to have the same format as the training data: $270,000 \times M$ numpy array, where M is the number of test samples.
- This means that *any* pre-processing applied in the training data should also be applied in the test data.

In [2]: %run training.py

```
---TRAINING COMPLETE---
Unknown indices: []
```

Best model info: {'epoch': 21, 'train_loss': 0.021766129745325696, 'train_accuracy': 99.42470389170897, 'val_loss': 0.08525952994823456, 'val_accuracy': 97.86729857819905}





```
In [7]: import os
        import qc
        import numpy as np
        import matplotlib.pyplot as plt
        from joblib import dump
        from PIL import Image
        import torch
        import torch.nn as nn
        from torch.utils.data import DataLoader, Dataset, random_split
        from torchvision.transforms import AutoAugment, AutoAugmentPolicy
        from torchvision.transforms import transforms as T
        import torch.optim as optim
        from torchvision.models import vgg19
        from torchvision.models import VGG19_Weights
        from sklearn.metrics import recall_score, f1_score, precision_score
        from tqdm import tqdm
        data train = np.load('data train.npy')
        labels_train = np.load('labels_train.npy')
        data_train.shape, labels_train.shape
```

Out[7]: ((270000, 8443), (8443,))

```
In [8]: # Standard IMAGENET vals sourced from google
        imagenet means = [0.485, 0.456, 0.406]
        imagenet stds = [0.229, 0.224, 0.225]
        # Define AutoAugment transform
        # - automatically augments data based on a given auto-augmentation policy
        augmenter = AutoAugment(policy=AutoAugmentPolicy.IMAGENET)
        # Resize, augment,...
        # NOTE - In PyTorch, T.ToTensor() is a transformation that converts a PI
        # tensor and scales the values to the range [0.0, 1.0]
        # NOTE - Normalize expects Tensor - so convert to tensor then normalize
        # create a Tensor dataset (performs transformations AND augmentation)
        class TensorDataset(Dataset):
            def init (self, data, labels, transform=None):
                self.data = data
                self.labels = labels
                self.transform = transform
            def len (self):
                return self.data.shape[1]
            def getitem (self, idx):
                image = self.data[:, idx].reshape(300, 300, 3)
                image = Image.fromarray(image)
                if self.transform:
                    image = self.transform(image)
                label = self.labels[idx]
                return image, label
        preprocess = T.Compose([
            augmenter,
            T.Resize((224, 224)),
            T.ToTensor(),
            T.Normalize(imagenet means, imagenet stds)
        1)
        dataset = TensorDataset(data_train, labels_train, transform=preprocess)
        print("Created Tensor Dataset")
```

Created Tensor Dataset

```
In [10]: # Create split sizes for training-validation-test, ---- use 70-15-15 rule
    train_size = int(0.7 * len(dataset))
    temp_size = len(dataset) - train_size
    val_size = int(0.5 * temp_size)
    test_size = temp_size - val_size

# Split dataset into training-validation-test using sizes (random_split)
    train_dataset, temp_dataset = random_split(dataset, [train_size, temp_six_val_dataset, test_dataset = random_split(temp_dataset, [val_size, test_s])

# Use DataLoader - load data into model - flexible for memory constraints
    train_dataflow = DataLoader(train_dataset, batch_size=256, shuffle=True)
    val_dataflow = DataLoader(val_dataset, batch_size=256)
    test_dataflow = DataLoader(test_dataset, batch_size=256)
    print("Created Dataflows")
```

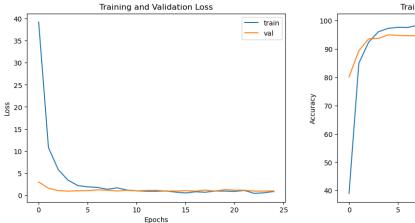
Created Dataflows

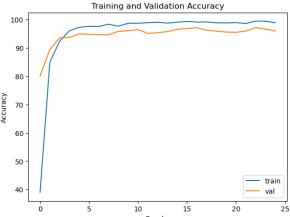
```
In [11]: # Create instance of pre-trained VGG19 model
         def pretrainedVGG19(num classes):
             model = vgg19(weights=VGG19 Weights.DEFAULT)
                                                                     # pre-trained
             num_ftrs = model.classifier[6].in_features
                                                                     # extract n f
             model.classifier[6] = nn.Linear(num ftrs, num classes) # n output fe
             return model
         # Define device to utilize and num of classes for model
         device = torch.device("cuda" if torch.cuda.is available() else "cpu")
         # Call model with give number of classes
         nclasses = 9
         model = pretrainedVGG19(nclasses)
         model.to(device)
         # Define loss, add weight decay to optimizer (standard is 1e_05) - L2 pel
         criterion = nn.CrossEntropyLoss()
         optimizer = optim.Adam(model.parameters(), lr=0.0001, weight decay=1e-05
         # Setup save path
         save path = '/blue/eel5840/darian.jennings/final proj/'
         os.makedirs(save_path, exist_ok=True)
         # Track epoch with highest accuracy for epochs 1-N
         highest val accuracy = 0
         # Track which indices were marked as the unknown class — should be 0 at
         # Store vals for train, loss, and accuracies respectively
         unknown indices = []
         train losses = []
         val losses = []
         train accuracies = []
         val accuracies = []
         # Initialize dictionary to store information about best model
         best model info = {
             'epoch': None,
             'train_loss': None,
             'train accuracy': None,
             'val loss': None,
             'val accuracy': None,
         # Collect garbage
         collected = qc.collect()
         num epochs = 25
         for epoch in range(num epochs):
             model.train()
             # reset for each epoch
             train_loss, train_correct, train_total = 0.0, 0, 0
             for images, labels in tgdm(train dataflow, desc=f"Epoch {epoch+1}/{n
                 images, labels = images.to(device, dtype=torch.float), labels.to
                 # raw output scores
                 outputs = model(images)
                 # calculate the probabilities
```

```
probabilities = torch.nn.functional.softmax(outputs, dim=1)
    #max_prob, _ = torch.max(probabilities, dim=1)
    #print(max prob)
    # check if all probabilities are below 0.1
    unknown = (probabilities < 0.1).all(dim=1)
    # get the predicted classes
    _, predicted = torch.max(outputs.data, 1)
    # assign -1 to the unknown class
    predicted[unknown] = -1
    unknown indices.extend(i for i, x in enumerate(predicted) if x =
    # calculate loss petween predicted outputs and labels
    loss = criterion(outputs, labels)
    # set grads to zero, make suere we don't accumulate gradients from
    optimizer.zero_grad()
    # computes the gradients of the loss function
    loss.backward()
    # updates the parameters of the neural network
    optimizer.step()
    train loss += loss.item()
    _, predicted = torch.max(outputs.data, 1)
    train total += labels.size(0)
    train correct += (predicted == labels).sum().item()
    train accuracy = 100 * train correct / train total
# evaluate
model.eval()
# calculate validation loss and accuracy
val loss, val correct, val total = 0.0, 0, 0
# deactivate autograd engine - prevent updates & data leakage during
with torch.no grad():
    for inputs, labels in val_dataflow:
        inputs, labels = inputs.to(device, dtype=torch.float), label
        outputs = model(inputs)
        loss = criterion(outputs, labels)
        val loss += loss.item()
        _, predicted = torch.max(outputs.data, 1)
        val total += labels.size(0)
        val correct += (predicted == labels).sum().item()
        val_accuracy = 100 * val_correct / val_total
# check if current accuracy is higher than the highest accuracy
if val_accuracy > highest_val_accuracy:
    highest val accuracy = val accuracy
    # Send info to dictionary
    best model info['epoch'] = epoch
    best model info['train loss'] = train loss / len(train dataflow)
    best_model_info['train_accuracy'] = train_accuracy
    best_model_info['val_loss'] = val_loss / len(val_dataflow)
    best model info['val accuracy'] = val accuracy
    best model info['model state dict'] = model.state dict()
train losses.append(train loss)
train accuracies.append(train accuracy)
val_losses.append(val_loss)
```

```
val accuracies.append(val accuracy)
    print(f"Train Acc: {train accuracy:.2f}%, Train Loss: {train loss/le
# Save the best model --- information is stored in dictionary (best mode
torch.save(best_model_info['model_state_dict'], os.path.join(save_path,
# Pop off model.dict -- for printing purposes (clean)
best model info.popitem()
print("---TRAINING COMPLETE---")
print("Unknown indices: ", unknown_indices)
print("Best model info: ", best_model_info)
collected = gc.collect()
Irain Acc: 98.60%, Irain Loss: 0.0445650621/441832, Val Acc: 95.89%, Val
Loss: 0.22468238174915314
Epoch 23/25 [Training]: 100% | 24/24 [00:23<00:00, 1.01it/s]
Train Acc: 99.44%, Train Loss: 0.01685492018683969, Val Acc: 97.16%, Val
Loss: 0.18313270211219787
Epoch 24/25 [Training]: 100%| 24/24 [00:23<00:00, 1.01it/s]
Train Acc: 99.41%, Train Loss: 0.022397278575226665, Val Acc: 96.60%, Va
l Loss: 0.1855709046125412
Epoch 25/25 [Training]: 100% | 24/24 [00:23<00:00, 1.01it/s]
Train Acc: 98.87%, Train Loss: 0.034431916335355105, Val Acc: 95.97%, Va
l Loss: 0.19136399924755096
---TRAINING COMPLETE---
Unknown indices: []
Best model info: {'epoch': 22, 'train_loss': 0.01685492018683969, 'tra
in_accuracy': 99.44162436548223, 'val_loss': 0.18313270211219787, 'val_
```

```
In [12]:
         # Plot learning curves - training vs validation - for loss & accuracy
         fig, axs = plt.subplots(1, 2, figsize=(15, 5))
         axs[0].set_title("Training and Validation Loss")
         axs[0].plot(train_losses, label="train")
         axs[0].plot(val losses, label="val")
         axs[0].set_xlabel("Epochs")
         axs[0].set ylabel("Loss")
         axs[0].legend()
         axs[1].set title("Training and Validation Accuracy")
         axs[1].plot(train accuracies, label="train")
         axs[1].plot(val_accuracies, label="val")
         axs[1].set xlabel("Epochs")
         axs[1].set_ylabel("Accuracy")
         axs[1].legend()
         plt.show()
```





In [13]: # Call model instance (if not previously called) and load the saved model
model = pretrainedVGG19(nclasses)
model.load_state_dict(torch.load('/blue/eel5840/darian.jennings/final_pre)

Move the model on the same device as the data, either CPU or GPU, for model = model.to(device)
model.eval()

```
Out[13]: VGG(
           (features): Sequential(
              (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
         1))
              (1): ReLU(inplace=True)
             (2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1)
         1))
              (3): ReLU(inplace=True)
              (4): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil
         _mode=False)
             (5): Conv2d(64, 128, \text{kernel size}=(3, 3), \text{stride}=(1, 1), \text{padding}=(1, 1)
         1))
              (6): ReLU(inplace=True)
             (7): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=
         (1, 1)
              (8): ReLU(inplace=True)
              (9): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil
         mode=False)
              (10): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=
         (1, 1)
              (11): ReLU(inplace=True)
             (12): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=
         (1, 1)
              (13): ReLU(inplace=True)
             (14): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=
         (1, 1)
             (15): ReLU(inplace=True)
             (16): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=
         (1, 1)
             (17): ReLU(inplace=True)
             (18): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, cei
         l mode=False)
              (19): Conv2d(256, 512, kernel size=(3, 3), stride=(1, 1), padding=
         (1, 1)
              (20): ReLU(inplace=True)
             (21): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=
         (1, 1)
              (22): ReLU(inplace=True)
              (23): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=
         (1, 1)
              (24): ReLU(inplace=True)
             (25): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=
         (1, 1)
              (26): ReLU(inplace=True)
             (27): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, cei
         l mode=False)
             (28): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=
         (1, 1)
              (29): ReLU(inplace=True)
             (30): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=
         (1, 1))
             (31): ReLU(inplace=True)
              (32): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=
         (1, 1)
              (33): ReLU(inplace=True)
             (34): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=
         (1, 1)
```

```
(35): ReLU(inplace=True)
  (36): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, cei
l_mode=False)
)
  (avgpool): AdaptiveAvgPool2d(output_size=(7, 7))
  (classifier): Sequential(
     (0): Linear(in_features=25088, out_features=4096, bias=True)
     (1): ReLU(inplace=True)
     (2): Dropout(p=0.5, inplace=False)
     (3): Linear(in_features=4096, out_features=4096, bias=True)
     (4): ReLU(inplace=True)
     (5): Dropout(p=0.5, inplace=False)
     (6): Linear(in_features=4096, out_features=9, bias=True)
)
)
```

```
In [14]: | test_accuracy, test_loss = 0, 0
         correct, total = 0, 0
         unknown indices = []
         test losses = []
         test accuracies = []
         with torch.no grad():
             for data, target in test dataflow:
                 data, target = data.to(device, dtype=torch.float), target.to(dev
                 output = model(data)
                 # calculate the probabilities
                 probabilities = torch.nn.functional.softmax(output, dim=1)
                 #max_prob, _ = torch.max(probabilities, dim=1)
                 #print(max prob)
                 # creates a boolean tensor unknown where each element is True if
                 # probabilities in the corresponding row of the probabilities tell
                 # and False otherwise
                 unknown = (probabilities < 0.25).all(dim=1)
                 _, predicted = torch.max(output.data, 1)
                 #print(predicted)
                 # classify unknown images to the unknown class (-1)
                 predicted[unknown] = -1
                 unknown indices.extend(i for i, x in enumerate(predicted) if x =
                 test_loss += criterion(output, target).item()
                 _, predicted = torch.max(output.data, 1)
                 total += target.size(0)
                 correct += (predicted == target).sum().item()
                 test losses.append(test loss)
                 test_accuracies.append(test_accuracy)
         # Calculate test metrics
         test loss /= len(test dataflow.dataset)
         test_accuracy = 100 * correct / total
         y true = target.cpu().numpy()
         y pred = predicted.cpu().numpy()
         f1 = f1_score(y_true, y_pred, average='weighted')
         recall = recall score(y true, y pred, average='weighted')
         precision = precision score(y true, y pred, average='weighted')
         print(f'Test Accuracy: {test accuracy:.2f}%, Test Loss: {test loss:.4f},
         print("---TEST COMPLETE---")
         print("Unknown indices: ", set(unknown_indices))
         Test Accuracy: 96.29%, Test Loss: 0.0006, F1-score: 0.9710, Recall: 0.9
         712. Precision: 0.9732
```

```
Test Accuracy: 96.29%, Test Loss: 0.0006, F1-score: 0.9710, Recall: 0.9712, Precision: 0.9732
---TEST COMPLETE---
Unknown indices: set()
```