



Forward Process

$$q = W^1 X + b^1$$

$$h = \text{ReLU}(q)$$

$$o = W^2 h + b^2$$

$$p = \text{softmax}(o), \text{ where } p_i = \frac{e^{o_i}}{\sum_{k=1}^M e^{o_k}}$$

$$L(p, y) = - \sum_{i=1}^M y_i \log p_i$$

Backward Process

$$\frac{\partial p_i}{\partial o_j} = \frac{\partial \left(\frac{e^{o_i}}{\sum_{k=1}^M e^{o_k}} \right)}{\partial o_j} = \delta_{ij} \frac{e^{o_i}}{\sum_{k=1}^M e^{o_k}} - \frac{e^{o_i}}{\left(\sum_{k=1}^M e^{o_k} \right)^2} \cdot e^{o_j}$$

$$\delta_{ij} = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

$$= p_i (\delta_{ij} - p_j)$$

$$\frac{\partial L}{\partial o_j} = \sum_{i=1}^M \frac{\partial L}{\partial p_i} \frac{\partial p_i}{\partial o_j} = \sum_{i=1}^M \frac{\partial \left(- \sum_{k=1}^M y_k \log p_k \right)}{\partial p_i} \cdot \frac{\partial p_i}{\partial o_j}$$

$$= \sum_{i=1}^M -y_i \frac{1}{p_i} \cdot p_i (\delta_{ij} - p_j)$$

$$= \sum_{i=1}^M y_i p_j - \sum_{i=1}^M y_i \delta_{ij}$$

$$= p_j - y_j$$

$$\frac{\partial O_i}{\partial b_j^{(2)}} = \delta_{ij}$$

$$\frac{\partial L}{\partial b_j^{(2)}} = \frac{\partial L}{\partial O_j} \frac{\partial O_j}{\partial b_j} = p_j - y_j$$

$$\frac{\partial O_i}{\partial h_j} = \frac{\partial \left(\sum_{k=1}^H W_{ik} h_k + b_i \right)}{\partial h_j} = W_{ij}$$

$$\frac{\partial L}{\partial h_j} = \sum_{i=1}^M \frac{\partial L}{\partial O_i} \frac{\partial O_i}{\partial h_j} = \sum_{i=1}^M (p_i - y_i) \cdot W_{ij}$$

$$\frac{\partial O_k}{\partial W_{ij}^{(2)}} = \frac{\partial \left(\sum_{n=1}^H W_{kn} \cdot h_n + b_k \right)}{\partial W_{ij}^{(2)}} = \sum_{n=1}^H \delta_{ik} \delta_{nj} h_n = \delta_{ki} h_j$$

$$\frac{\partial L}{\partial W_{ij}} = \sum_{k=1}^M \frac{\partial L}{\partial O_k} \frac{\partial O_k}{\partial W_{ij}^{(2)}} = \sum_{k=1}^M (p_k - y_k) \cdot \delta_{ki} h_j = (p_i - y_i) h_j$$

$$\frac{\partial h_i}{\partial q_j} = \delta_{ij} \cdot a \quad a = \begin{cases} 1 & \text{if } q_j \geq 0 \\ 0 & \text{if } q_j < 0 \end{cases}$$

$$\frac{\partial L}{\partial q_i} = \frac{\partial L}{\partial h_i} \frac{\partial h_i}{\partial q_j} = \frac{\partial L}{\partial h_j} \cdot a$$