

Rule Induction and Reasoning in Knowledge Graphs

Daria Stepanova

Bosch Center for Artificial Intelligence, Renningen, Germany

ODSC 2020, 17.09.2020



Motivation

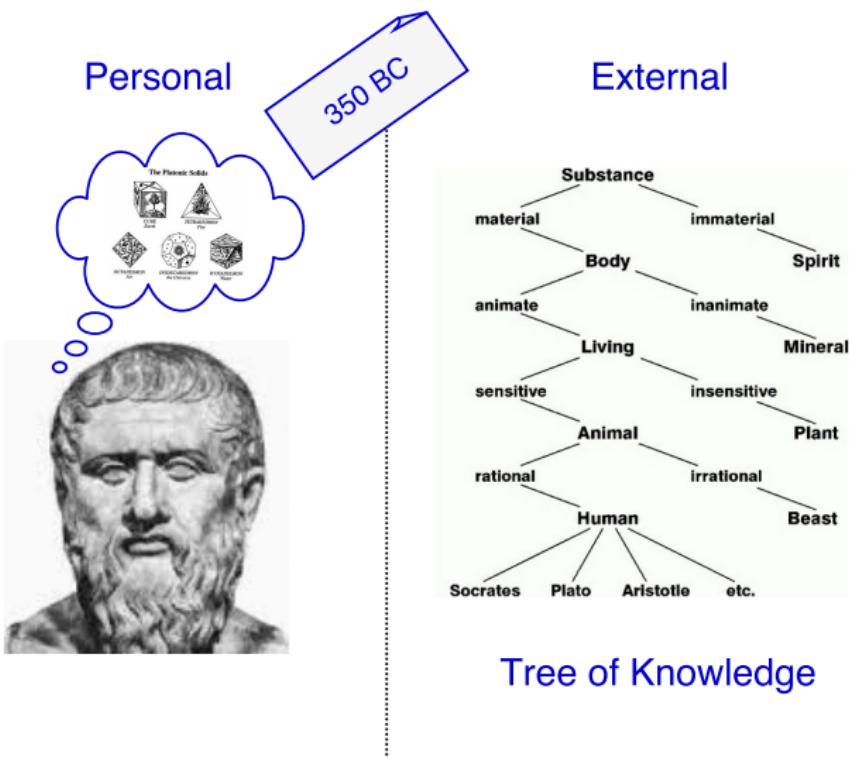
Rule Induction under Incompleteness

Numerical Rule Learning

Rule-based Fact Checking

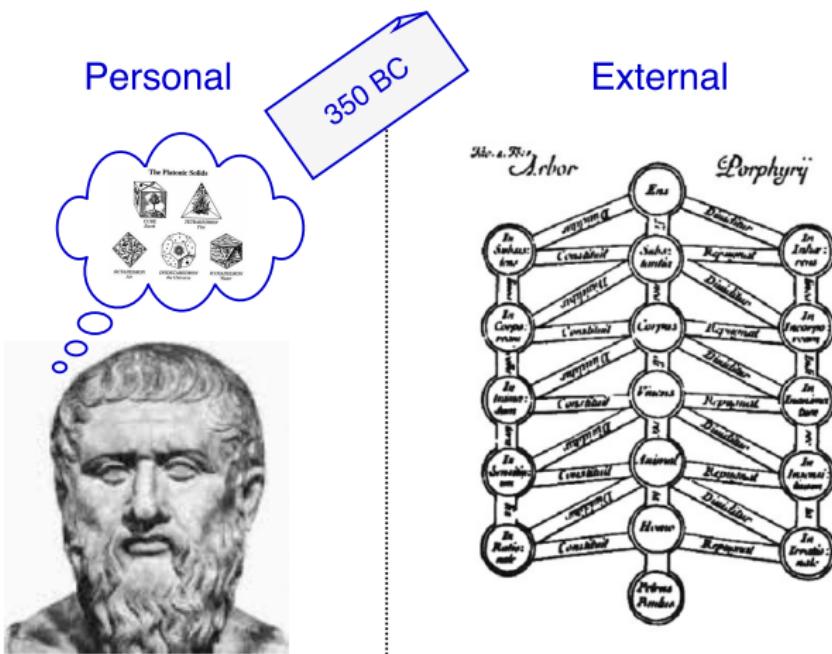
What is Knowledge?

Plato: “*Knowledge is justified true belief*”



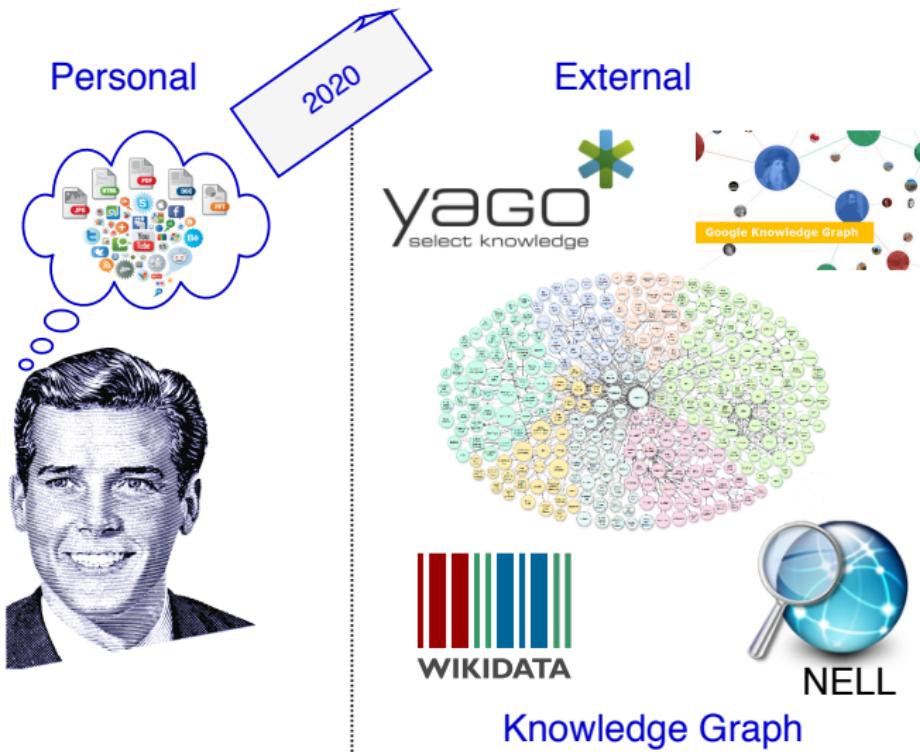
What is Knowledge?

Plato: “*Knowledge is justified true belief*”



Knowledge Graphs as Digital Knowledge

“Digital knowledge is semantically enriched machine processable data”



Semantic Web Search



winner of Australian Open 2018



Roger Federer

Tennis player



rogerfederer.com

Roger Federer is a Swiss professional tennis player who is currently ranked world No. 10 by the Association of Tennis Professionals. Many players and analysts have called him the greatest tennis player of all time. [Wikipedia](#)

Born: August 8, 1981 (age 35 years), Basel, Switzerland

Height: 1.85 m

Weight: 85 kg

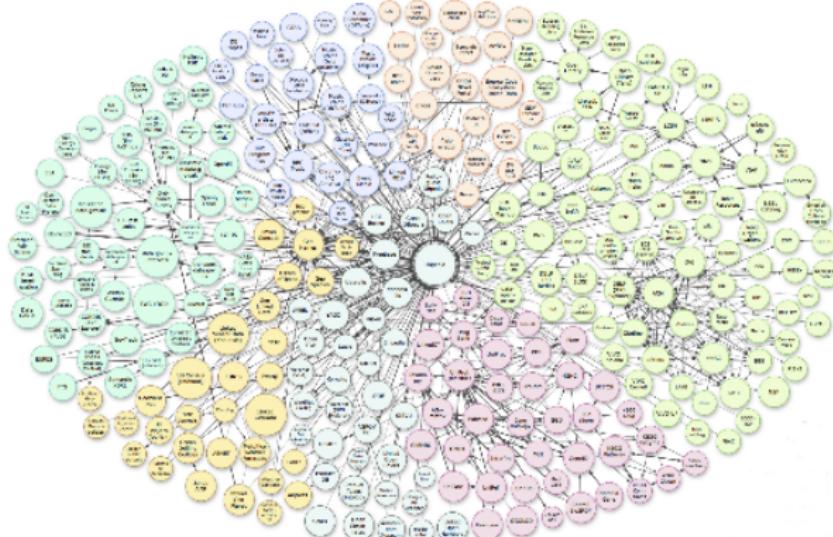
Spouse: Mirka Federer (m. 2009)

Children: Lenny Federer, Myla Rose Federer, Charlene Riva Federer, Leo Federer



Semantic Web Search

Google

 $\exists X \text{ winnerOf}(X, \text{AustralianOpen2018})$ 

Roger Federer

Tennis player

rogerfederer.com

Roger Federer is a Swiss professional tennis player who is currently ranked world No. 10 by the Association of Tennis Professionals. Many players and analysts have called him the greatest tennis player of all time. [Wikipedia](#)

Born: August 8, 1981 (age 35 years), Basel, Switzerland

Height: 1.85 m

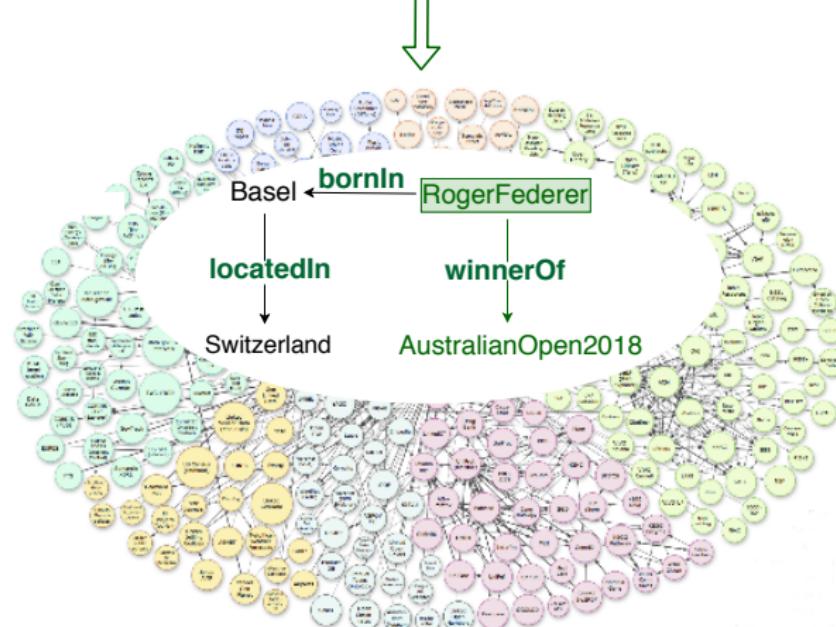
Weight: 85 kg

Spouse: Mirka Federer (m. 2009)

Children: Lenny Federer, Myla Rose Federer, Charlene Riva Federer, Leo Federer

Semantic Web Search

Google

 $\exists X \text{ winnerOf}(X, \text{AustralianOpen2018})$ **Roger Federer**

Tennis player

rogerfederer.com

Roger Federer is a Swiss professional tennis player who is currently ranked world No. 10 by the Association of Tennis Professionals. Many players and analysts have called him the greatest tennis player of all time. [Wikipedia](#)

Born: August 8, 1981 (age 35 years), Basel, Switzerland

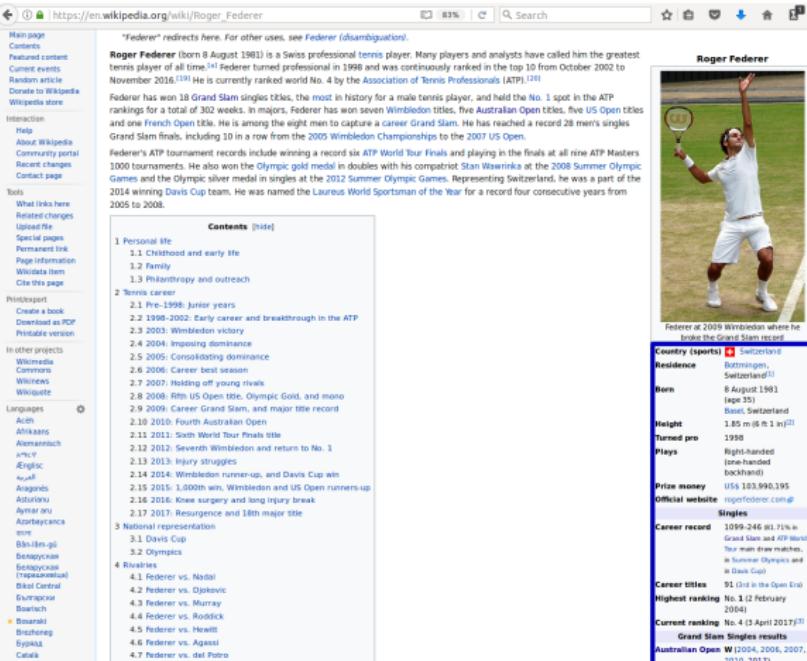
Height: 1.85 m

Weight: 85 kg

Spouse: Mirka Federer (m. 2009)

Children: Lenny Federer, Myla Rose Federer, Charlene Riva Federer, Leo Federer

Knowledge Graphs

A screenshot of a Wikipedia article page for "Roger Federer". The page title is "Roger Federer" and the URL is https://en.wikipedia.org/wiki/Roger_Federer. The page content includes a summary, a photo of Federer playing tennis, and a detailed table of his career statistics and achievements.

"Federer" redirects here. For other uses, see [Federer \(disambiguation\)](#).

Roger Federer (born 8 August 1981) is a Swiss professional tennis player. Many players and analysts have called him the greatest tennis player of all time.^[1] Federer turned professional in 1998 and was continuously ranked in the top 10 from October 2002 to November 2013.^[2] He is currently ranked world No. 4 by the [Association of Tennis Professionals \(ATP\)](#).^[3]

Federer has won 18 Grand Slam singles titles, the most in history for a male tennis player, and held the No. 1 spot in the ATP rankings for a total of 302 weeks. In majors, Federer has won seven Wimbledon titles, five Australian Open titles, five US Open titles and one French Open title. He is among the eight men to capture a career Grand Slam. He has reached a record 28 men's singles Grand Slam finals, including 10 in a row from the 2005 [Wimbledon Championships](#) to the 2007 US Open.

Federer's ATP tournament records include winning a record six ATP World Tour Finals and playing in the finals at all nine ATP Masters 1000 tournaments. He also won the Olympic gold medal in doubles with his compatriot Stan Wawrinka at the 2008 Summer Olympic Games and the Olympic silver medal in singles at the 2012 Summer Olympic Games. Representing Switzerland, he was a part of the 2014 winning Davis Cup team. He was named the Laureus World Sportman of the Year for a record four consecutive years from 2005 to 2008.

Contents [edit]

- 1 Personal life
 - 1.1 Childhood and early life
 - 1.2 Family
 - 1.3 Philanthropy and outreach
- 2 Tennis career
 - 2.1 Pre-1998: Junior years
 - 2.2 1998–2002: Early career and breakthrough in the ATP
 - 2.3 2003: Wimbledon victory
 - 2.4 2004: Career year
 - 2.5 2005: Consolidating dominance
 - 2.6 2006: Career best season
 - 2.7 2007: Holding off young rivals
 - 2.8 2008: Fifth US Open title, Olympic Gold, and mono
 - 2.9 2009: Career Grand Slam, and major title record
 - 2.10 2010: Fourth Australian Open
 - 2.11 2011: Sixth World Tour Finals title
 - 2.12 2012: Seventh Wimbledon and return to No. 1
 - 2.13 2013: Injury struggles
 - 2.14 2014: Wimbledon runner-up, and Davis Cup win
 - 2.15 2015: 1,000th win, Wimbledon and US Open runners-up
 - 2.16 2016: Knee surgery and long injury break
 - 2.17 2017: Resurgence and 18th major title
- 3 National representation
 - 3.1 Davis Cup
 - 3.2 Olympics
- 4 Records and titles
 - 4.1 Federer vs. Nadal
 - 4.2 Federer vs. Djokovic
 - 4.3 Federer vs. Murray
 - 4.4 Federer vs. Roddick
 - 4.5 Federer vs. Hewitt
 - 4.6 Federer vs. Agassi
 - 4.7 Federer vs. del Potro
 - 4.8 Federer vs. Safin

Roger Federer



Federer at 2009 Wimbledon where he broke the Grand Slam record

Country (sports)	Switzerland
Residence	Binningen, Switzerland ^[4]
Born	8 August 1981 Zürich, Switzerland
Height	1.85 m (6 ft 1 in) ^[5]
Turned pro	1998
Plays	Right-handed (one-handed backhand)
Prize money	US\$ 103,990,195
Official website	rogerfederer.com
Singles	
Career record	1099–246 (31.1%), Grand Slams and ATP World Tour main draw matches, in Summer Olympics and in Davis Cup
Career titles	91 (1st in the Open Era)
Highest ranking	No. 1 (2 February 2004)
Current ranking	No. 4 (3 April 2017) ^[3]
Grand Slam Singles results	
Australian Open	Winning: 2001, 2006, 2007, 2012, 2017

Industrial Knowledge Graphs



amazon



SIEMENS

Thousands of companies are developing their own KGs, not only for search and indexing but advanced reasoning tasks on top of machine learning

KG Incompleteness

living place of the winner of australian open 2018

All News Images Videos Maps More Settings Tools

About 1,220,000,000 results (1.10 seconds)

2018 Australian Open - Wikipedia

https://en.wikipedia.org/wiki/2018_Australian_Open ▾

Roger Federer was the defending **champion** in the men's singles event and successfully retained his title (his sixth), defeating Marin Čilić in the final, while Caroline Wozniacki **won** the women's title, defeating Simona Halep in the final.

Venue: [Melbourne Park](#)

Prize money: A\$55,000,000

Location: [Melbourne, Victoria, Australia](#)

Draw: 128S / 64D /

Missing: [living](#) | Must include: [living](#)

Semantic Web Search

wife of Roger Federer



All

Images

News

Videos

Maps

More

Settings

Tools

About 42,200,000 results (0.50 seconds)

Roger Federer / Wife

Mirka Federer

m. 2009



Miroslava "Mirka" Federer is a Slovak-born Swiss former professional tennis player. She reached her career-high WTA singles ranking of world No. 76 on 10 September 2001 and a doubles ranking of No. 215 on 24 August 1998. She is the wife of tennis player Roger Federer, having first met him at the 2000 Summer Olympics. [Wikipedia](#)

Semantic Web Search

living place of Mirka Federer



All Images News Shopping Videos More Settings Tools

About 1.910.000 results (0,92 seconds)

Mirka Federer / Residence



Map data ©2017 GeoBasis-DE/BKG (©2009), Google

Bottmingen, Switzerland

Human Reasoning

*livesIn(Y, Z) ← marriedTo(X, Y),
livesIn(X, Z)* *Married people live together*

marriedTo(mirka, roger) *Mirka is married to Roger*

livesIn(mirka, bottmingen) *Mirka lives in Bottmingen*

Human Reasoning

*livesIn(Y, Z) ← marriedTo(X, Y),
livesIn(X, Z)*

Married people live together

marriedTo(mirka, roger)

Mirka is married to Roger

livesIn(mirka, bottmingen)

Mirka lives in Bottmingen

livesIn(roger, bottmingen)

Roger lives in Bottmingen



livesIn →



Human Reasoning

*livesIn(Y, Z) ← marriedTo(X, Y),
livesIn(X, Z)*

Married people live together

marriedTo(mirka, roger)

Mirka is married to Roger

livesIn(mirka, bottmingen)

Mirka lives in Bottmingen

livesIn(roger, bottmingen)

Roger lives in Bottmingen



livesIn →



But where can a machine get such rules from?

Applications of Rule Learning

- Fact prediction
- Fact checking
- Data cleaning
- Finding trends in KGs
- ...

Motivation

Rule Induction under Incompleteness

Numerical Rule Learning

Rule-based Fact Checking

Horn Rules

Rule: $\underbrace{a}_{\text{head}} \leftarrow \underbrace{b_1, \dots, b_m}_{\text{body}}$.

Informal semantics: If b_1, \dots, b_m are true, then a must be true.

Logic program: Set of rules

Example: ground rule

```
% If Mirka is married to Roger and lives in B., then Roger lives there too  
livesIn(roger, bottmingen) ← isMarried(mirka, roger), livesIn(mirka, bottmingen)
```

Horn Rules

Rule: $\underbrace{a}_{\text{head}} \leftarrow \underbrace{b_1, \dots, b_m}_{\text{body}}$.

Informal semantics: If b_1, \dots, b_m are true, then a must be true.

Logic program: Set of rules

Example: non-ground rule

```
% Married people live together  
livesIn(Y, Z) ← isMarried(X, Y), livesIn(X, Z)
```

Rules with Negation

Rule: $\underbrace{a}_{\text{head}} \leftarrow \underbrace{b_1, \dots, b_m, \text{not } b_{m+1}, \dots, \text{not } b_n.}_{\text{body}}$

Informal semantics: If b_1, \dots, b_m are true and none of b_{m+1}, \dots, b_n is known, then a must be true.

Default reasoning: Facts not known to be true are assumed to be false

Example: rule with negation

% Two married live together unless one is a researcher

$livesIn(Y, Z) \leftarrow isMarried(X, Y), livesIn(X, Z), \text{not researcher}(Y)$

Reasoning with Incomplete Information

Default Reasoning

Assume normal state of affairs, unless there is evidence to the contrary

By default married people live together.

Reasoning with Incomplete Information

Default Reasoning

Assume normal state of affairs, unless there is evidence to the contrary

By default married people live together.

Abduction

Choose between several explanations that explain an observation

John and Mary live together. They must be married.

Reasoning with Incomplete Information

Default Reasoning

Assume normal state of affairs, unless there is evidence to the contrary

By default married people live together.

Abduction

Choose between several explanations that explain an observation

John and Mary live together. They must be married.

Induction

Generalize a number of similar observations into a hypothesis

Given many examples of spouses living together generalize this knowledge.

Reasoning with Incomplete Information

Default Reasoning

Assume normal state of affairs, unless there is evidence to the contrary

By default married people live together.

Abduction

Choose between several explanations that explain an observation

John and Mary live together. They must be married.

Induction

Generalize a number of similar observations into a hypothesis

Given many examples of spouses living together generalize this knowledge.

History of Inductive Learning

- AI & Machine Learning 1960s-70s:
Banerji, Plotkin, Vere, Michalski, ...
- AI & Machine Learning 1980s:
Shapiro, Sammut, Muggleton, ...
- Inductive Logic Programming (ILP) 1990s:
Muggleton, Quinlan, De Raedt, ...
- Statistical Relational Learning 2000s:
Getoor, Koller, Domingos, Sato, ...

Learning from Examples

Inductive Learning from Examples [Muggleton, 1991]

Given:

- $E^+ = \{fatherOf(john, mary), fatherOf(david, steve)\}$
- $E^- = \{fatherOf(kathy, ellen), fatherOf(john, steve)\}$
- $T = \{parentOf(john, mary), male(john),
parentOf(david, steve), male(david),
parentOf(kathy, ellen), female(kathy)\}$
- Language bias: Horn rules with 2 body atoms

Learning from Examples

Inductive Learning from Examples [Muggleton, 1991]

Given:

- $E^+ = \{fatherOf(john, mary), fatherOf(david, steve)\}$
- $E^- = \{fatherOf(kathy, ellen), fatherOf(john, steve)\}$
- $T = \{parentOf(john, mary), male(john),
parentOf(david, steve), male(david),
parentOf(kathy, ellen), female(kathy)\}$
- Language bias: Horn rules with 2 body atoms

Possible hypothesis:

- $Hyp : fatherOf(X, Y) \leftarrow parentOf(X, Y), male(X)$

Common Techniques in ILP

- Generality (Σ): essential component of symbolic learning systems

Common Techniques in ILP

- Generality (\succeq): essential component of symbolic learning systems
- Generalization as θ -subsumption
 - $person(X) \succeq person(roger), \theta = \{X/roger\}$

Common Techniques in ILP

- **Generality (\succeq)**: essential component of symbolic learning systems
- Generalization as θ -subsumption
 - $person(X) \succeq person(roger), \theta = \{X/roger\}$
 - $\{worksAt(X, Y)\} \succeq \{worksAt(Z, bosch), researcher(Z)\},$

Common Techniques in ILP

- **Generality (\succeq)**: essential component of symbolic learning systems
- Generalization as θ -subsumption
 - $person(X) \succeq person(roger)$, $\theta = \{X/roger\}$
 - $\{worksAt(X, Y)\} \succeq \{worksAt(Z, bosch), researcher(Z)\}$,
 $\theta = \{X/Z, Y/bosch\}$

Common Techniques in ILP

- **Generality (\succeq)**: essential component of symbolic learning systems
- Generalization as θ -subsumption
 - $person(X) \succeq person(roger)$, $\theta = \{X/roger\}$
 - $\{worksAt(X, Y)\} \succeq \{worksAt(Z, bosch), researcher(Z)\}$,
 $\theta = \{X/Z, Y/bosch\}$
- Generalization as entailment
 - $$\underbrace{person(X) \leftarrow researcher(X)}_{Hyp1} \quad \underbrace{person(mat) \leftarrow researcher(mat)}_{Hyp2}$$

Common Techniques in ILP

- **Generality (\succeq)**: essential component of symbolic learning systems
- Generalization as θ -subsumption
 - $person(X) \succeq person(roger)$, $\theta = \{X/roger\}$
 - $\{worksAt(X, Y)\} \succeq \{worksAt(Z, bosch), researcher(Z)\}$,
 $\theta = \{X/Z, Y/bosch\}$
- Generalization as entailment
 - $$\underbrace{person(X) \leftarrow researcher(X)}_{Hyp1} \underbrace{person(mat) \leftarrow researcher(mat)}_{Hyp2}$$
$$Hyp1 \succeq Hyp2$$

Common Techniques in ILP

- **Generality (\succeq)**: essential component of symbolic learning systems
- Generalization as θ -subsumption
 - $person(X) \succeq person(roger)$, $\theta = \{X/roger\}$
 - $\{worksAt(X, Y)\} \succeq \{worksAt(Z, bosch), researcher(Z)\}$,
 $\theta = \{X/Z, Y/bosch\}$
- Generalization as entailment
 - $\underbrace{person(X) \leftarrow researcher(X)}_{Hyp1} \underbrace{person(X) \leftarrow researcher(X), alive(X)}_{Hyp2}$

Common Techniques in ILP

- **Generality (\succeq)**: essential component of symbolic learning systems
- Generalization as θ -subsumption
 - $person(X) \succeq person(roger)$, $\theta = \{X/roger\}$
 - $\{worksAt(X, Y)\} \succeq \{worksAt(Z, bosch), researcher(Z)\}$,
 $\theta = \{X/Z, Y/bosch\}$
- Generalization as entailment
 - $\underbrace{person(X) \leftarrow researcher(X)}_{Hyp1} \underbrace{person(X) \leftarrow researcher(X), alive(X)}_{Hyp2}$

Common Techniques in ILP

- **Generality (\succeq)**: essential component of symbolic learning systems
- Generalization as θ -subsumption
 - $person(X) \succeq person(roger)$, $\theta = \{X/roger\}$
 - $\{worksAt(X, Y)\} \succeq \{worksAt(Z, bosch), researcher(Z)\}$,
 $\theta = \{X/Z, Y/bosch\}$
- Generalization as entailment
 - $\underbrace{person(X) \leftarrow researcher(X)}_{Hyp1} \underbrace{person(X) \leftarrow researcher(X), alive(X)}_{Hyp2}$
 $Hyp1 \succeq Hyp2$
 - $livesIn(roger, bottmingen) ? livesIn(roger, switzerland)$

Common Techniques in ILP

- **Generality (\succeq)**: essential component of symbolic learning systems
- Generalization as θ -subsumption
 - $person(X) \succeq person(roger)$, $\theta = \{X/roger\}$
 - $\{worksAt(X, Y)\} \succeq \{worksAt(Z, bosch), researcher(Z)\}$,
 $\theta = \{X/Z, Y/bosch\}$
- Generalization as entailment
 - $$\underbrace{person(X) \leftarrow researcher(X)}_{Hyp1} \underbrace{person(X) \leftarrow researcher(X), alive(X)}_{Hyp2}$$

$$Hyp1 \succeq Hyp2$$
 - $livesIn(roger, bottmingen) ? livesIn(roger, switzerland)$
 $T : livesIn(X, switzerland) \leftarrow livesIn(X, bottmingen)$

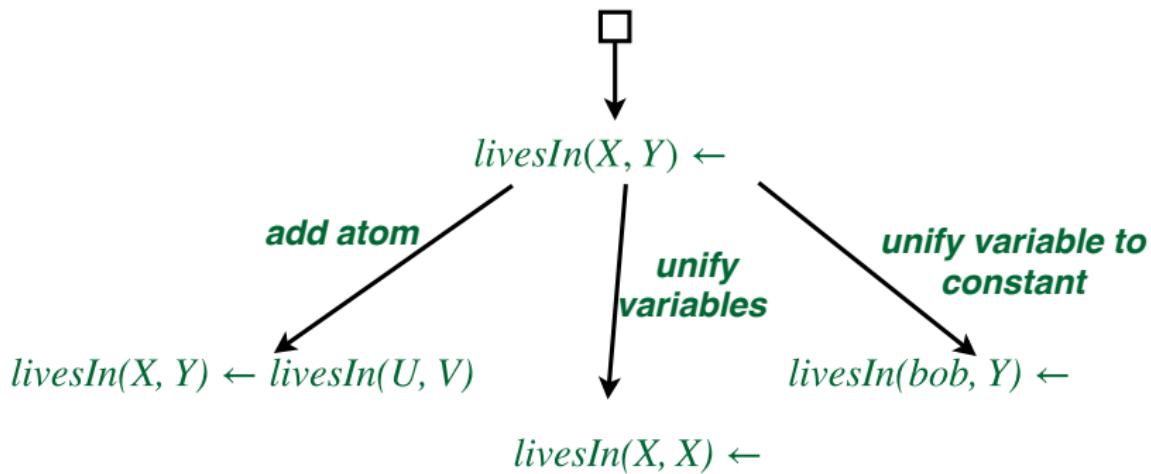
Common Techniques in ILP

- **Generality (\succeq)**: essential component of symbolic learning systems
- Generalization as θ -subsumption
 - $person(X) \succeq person(roger)$, $\theta = \{X/roger\}$
 - $\{worksAt(X, Y)\} \succeq \{worksAt(Z, bosch), researcher(Z)\}$,
 $\theta = \{X/Z, Y/bosch\}$
- Generalization as entailment
 - $$\underbrace{person(X) \leftarrow researcher(X)}_{Hyp1} \underbrace{person(X) \leftarrow researcher(X), alive(X)}_{Hyp2}$$

$$Hyp1 \succeq Hyp2$$
 - $livesIn(roger, bottmingen) \succeq livesIn(roger, switzerland)$
 $T : livesIn(X, switzerland) \leftarrow livesIn(X, bottmingen)$

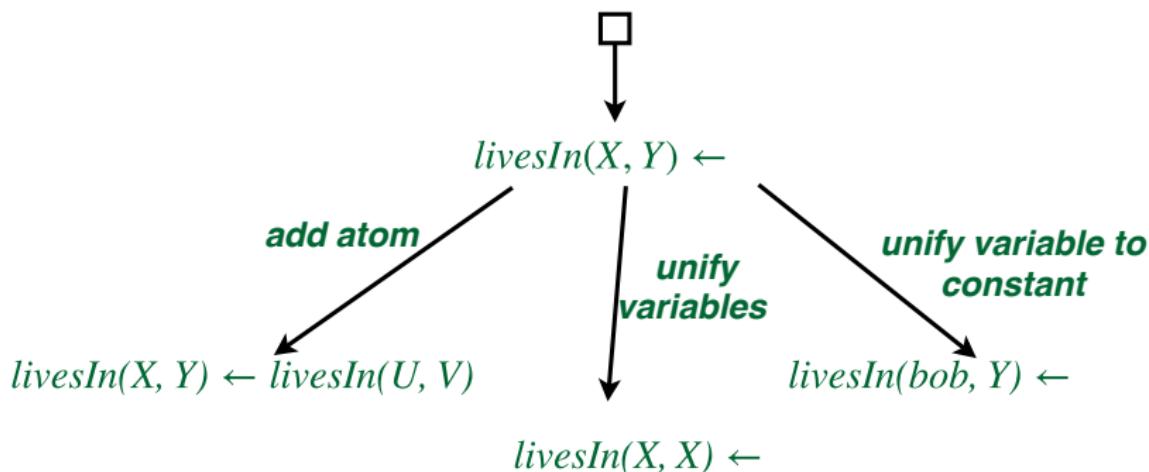
Common Techniques in ILP

- Clause refinement [Shapiro, 1991]: e.g., MIS, FOIL, etc.
 - Explore clause search space from general to specific or vice versa to find a hypothesis that covers all examples.



Common Techniques in ILP

- **Clause refinement** [Shapiro, 1991]: e.g., MIS, FOIL, etc.
 - Explore clause search space from general to specific or vice versa to find a hypothesis that covers all examples.



- **Inverse entailment** [Muggleton, 1995]: e.g., Progol, etc.
 - Properties of deduction to make hypothesis search space finite

Zoo of Other ILP Tasks

ILP tasks can be classified along several dimensions:

- type of the data source, e.g., positive/negative examples, interpretations, answer sets [Law *et al.*, 2015]
- type of the output knowledge, e.g., rules, ontologies [Lehmann, 2009]
- the way the data is given as input, e.g., all at once, incrementally [Katzouris *et al.*, 2015]
- availability of an oracle, e.g., human in the loop
- quality of the data source, e.g., noisy [Evans and Grefenstette, 2018]
- data (in)completeness, e.g., complete, incomplete, partially complete
- background knowledge, e.g., ontology [d'Amato *et al.*, 2016], hybrid theories [Lisi, 2010]

Challenges of Rule Induction from KGs

Open World Assumption: negative facts cannot be easily derived

Challenges of Rule Induction from KGs

Open World Assumption: negative facts cannot be easily derived

Maybe R. Federer is a researcher and A. Einstein was a dancer?

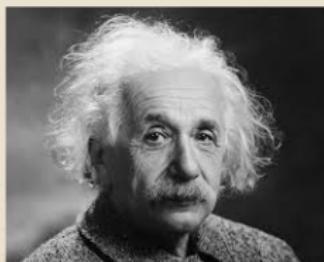
Challenges of Rule Induction from KGs

Open World Assumption: negative facts cannot be easily derived

Maybe R. Federer is a researcher and A. Einstein was a dancer?

We dance for laughter,
we dance for tears,
we dance for madness,
we dance for fears,
we dance for hopes,
we dance for screams,
we are the dancers,
we create the dreams.

-Albert Einstein



Challenges of Rule Induction from KGs

Data bias: KGs are extracted from text, which typically mentions only popular entities and interesting facts about them.

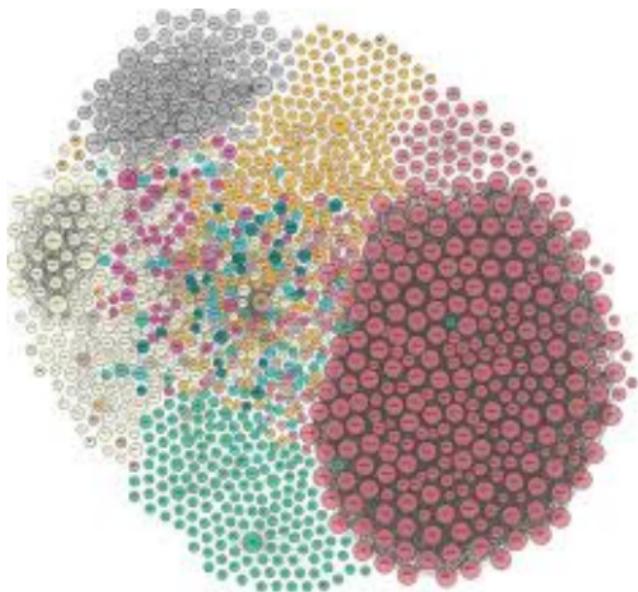
“Man bites dog phenomenon”¹



¹[https://en.wikipedia.org/wiki/Man_bites_dog_\(journalism\)](https://en.wikipedia.org/wiki/Man_bites_dog_(journalism))

Challenges of Rule Induction from KGs

Huge size: Modern KGs contain billions of facts
E.g., Google KG stores 70 billion facts



Challenges of Rule Induction from KGs

World knowledge is complex, none of its “models” is perfect



Exploratory Data Analysis

Question:

How can we still learn rules from KGs, which do not perfectly fit the data, but still reflect interesting correlations that can predict sufficiently many correct facts?

Answer:

Relational association rule mining! Roots in classical datamining.



Association Rules

- Classical data mining task: Given a transaction database, find out products (called itemsets) that are frequently bought together and form recommendation rules.

Transaction 1	🍎	🍺	⌚	🌯
Transaction 2	🍎	🍺	⌚	
Transaction 3	🍎	🍺		
Transaction 4	🍎	🍐		
Transaction 5	🍼	🍺	⌚	🌯
Transaction 6	🍼	🍺	⌚	
Transaction 7	🍼	🍺		
Transaction 8	🍼	🍐		

Out of 4 people who bought apples, 3 also bought beer.

Some Rule Measures

Support, confidence, lift

Support [apple] = 4

Transaction 1	apple	beer	bowl	meat
Transaction 2	apple	beer	bowl	
Transaction 3	apple	beer		
Transaction 4	apple	pear		
Transaction 5	milk	beer	bowl	meat
Transaction 6	milk	beer	bowl	
Transaction 7	milk	beer		
Transaction 8	milk	pear		

Some Rule Measures

Support, confidence, lift

Support [🍎] = 4

$$\text{Confidence } \{ \text{🍎} \rightarrow \text{🍺} \} = \frac{\text{Support } \{ \text{🍎}, \text{🍺} \}}{\text{Support } \{ \text{🍎} \}}$$

Transaction 1	🍎	🍺	一碗	一块肉
Transaction 2	🍎	🍺	一碗	
Transaction 3	🍎	🍺		
Transaction 4	🍎	🍐		
Transaction 5	🍼	🍺	一碗	一块肉
Transaction 6	🍼	🍺	一碗	
Transaction 7	🍼	🍺		
Transaction 8	🍼	🍐		

Some Rule Measures

Support, confidence, lift

$$\text{Support } \{\text{apple}\} = 4$$

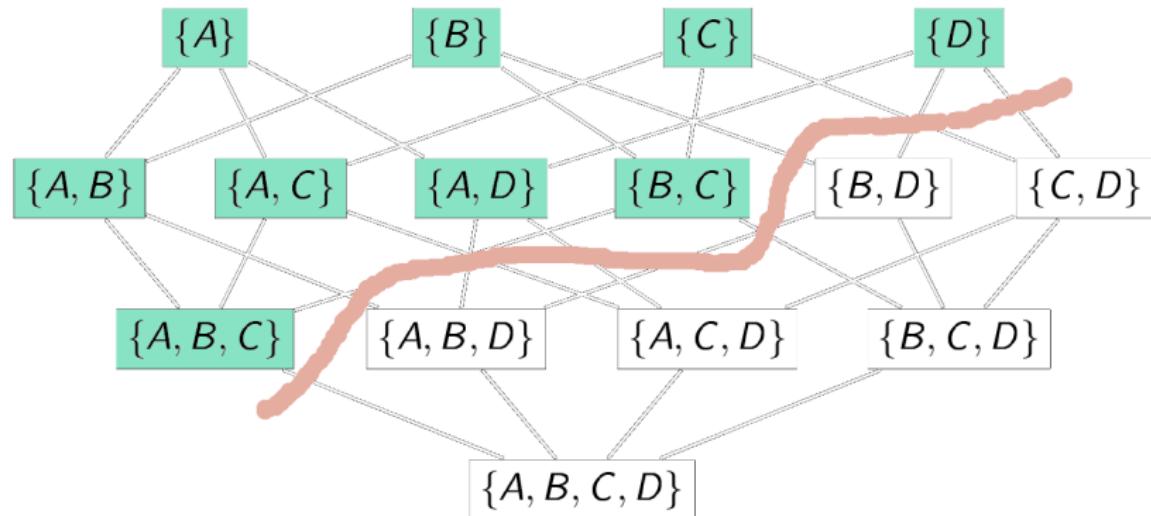
$$\text{Confidence } \{\text{apple} \rightarrow \text{beer}\} = \frac{\text{Support } \{\text{apple}, \text{beer}\}}{\text{Support } \{\text{apple}\}}$$

$$\text{Lift } \{\text{apple} \rightarrow \text{beer}\} = \frac{\text{Support } \{\text{apple}, \text{beer}\}}{\text{Support } \{\text{apple}\} \times \text{Support } \{\text{beer}\}}$$

Transaction 1	
Transaction 2	
Transaction 3	
Transaction 4	
Transaction 5	
Transaction 6	
Transaction 7	
Transaction 8	

Frequent Itemset Mining

- A=apple, B=beer... Frequent patterns are in green.
- Monotonicity: any superset of an infrequent pattern is infrequent
At the heart of frequent itemset mining algorithm



How to Apply this to Relational Data?

- **DOWNGRADING DATA:** Can we change the representation from richer representations to simpler ones? (So we can use systems working with simpler representations)
- **UPGRADING SYSTEMS:** Can we develop systems that work with richer representations (starting from systems for simpler representations)?

Downgrading the Data

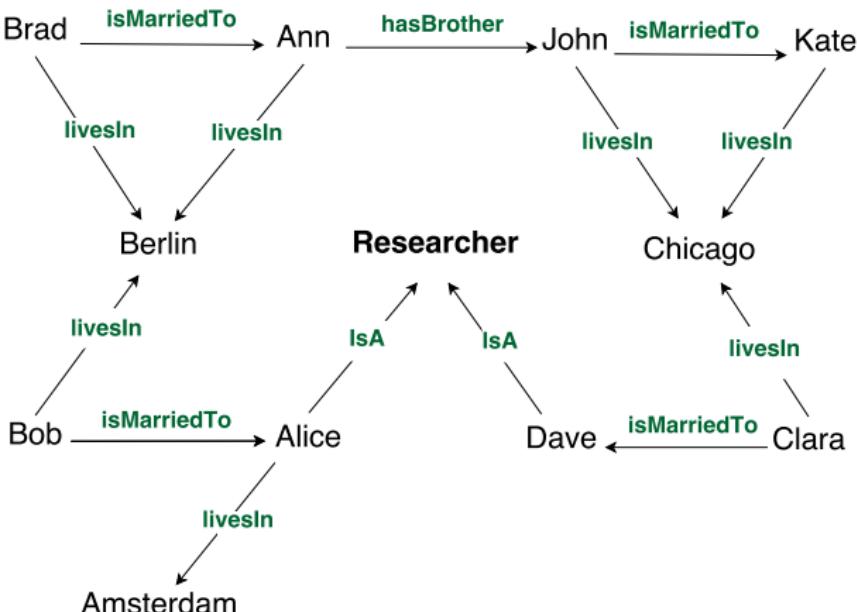
- **Propositionalization** [Krogel *et al.*, 2003]: transform a KG into a transaction database

	<i>bornInUS</i>	<i>livesInUS</i>	<i>isMarriedToSinger</i>	<i>researcher</i>	<i>sportsman</i>
<i>p1</i>	✓	✓			✓
<i>p2</i>	✓	✓		✓	
<i>p3</i>	✓	✓			
<i>p4</i>	✓	✓			
<i>p5</i>	✓		✓		
<i>p6</i>	✓		✓		✓
<i>p7</i>	✓			✓	
<i>p8</i>	✓	✓			

Upgrading the Systems

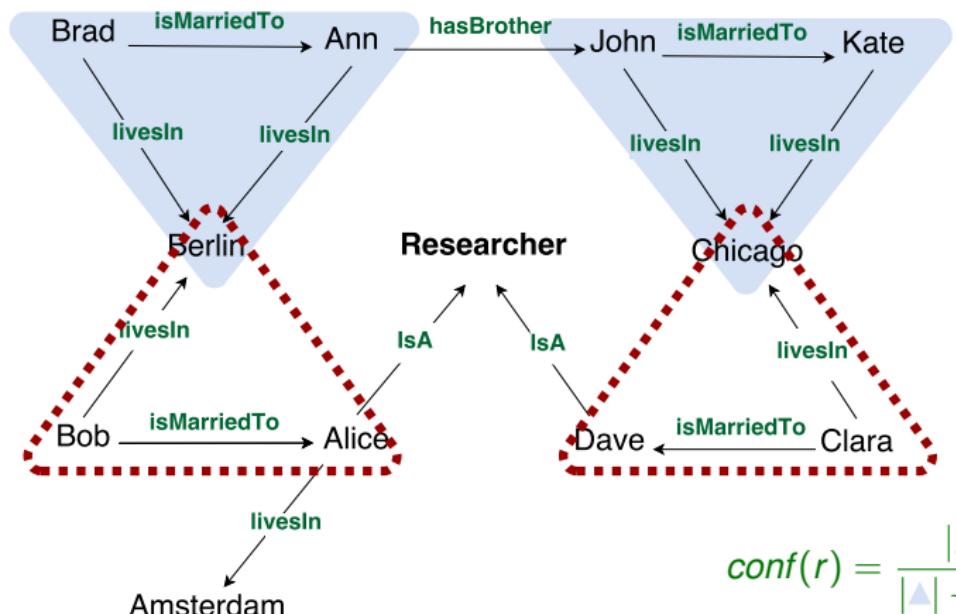
- Start from existing system for simpler representation
- Extend it for use with richer representation (while trying to keep the original system as a special case)

Relational Association Rule Learning



Relational Association Rule Learning

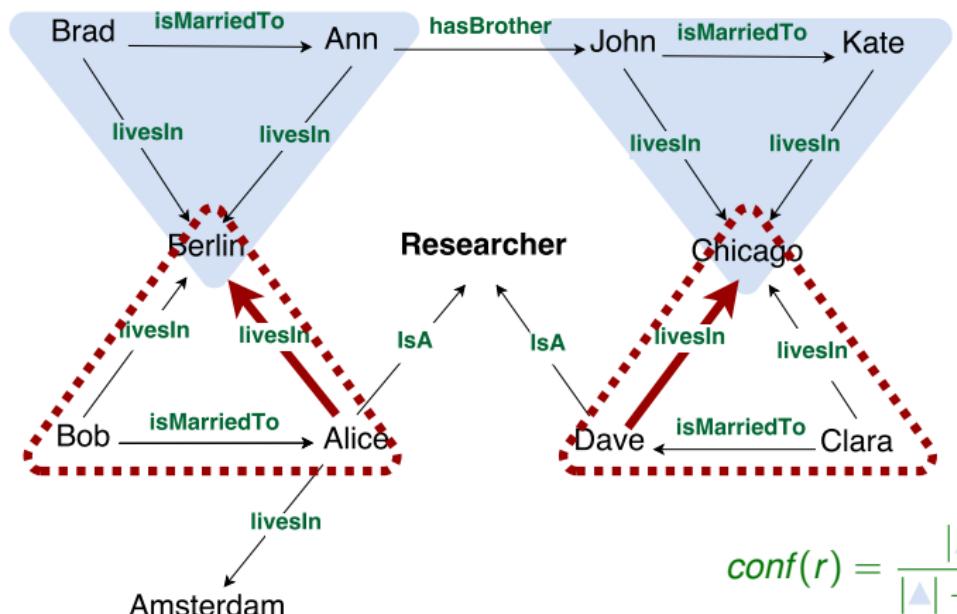
Confidence, e.g., WARMER [Goethals and den Bussche, 2002]
 Closed World Assumption (CWA): Whatever is missing is false



$r : livesIn(X, Y) \leftarrow isMarriedTo(Z, X), livesIn(Z, Y)$

Relational Association Rule Learning

Confidence, e.g., WARMER [Goethals and den Bussche, 2002]
 Closed World Assumption (CWA): Whatever is missing is false

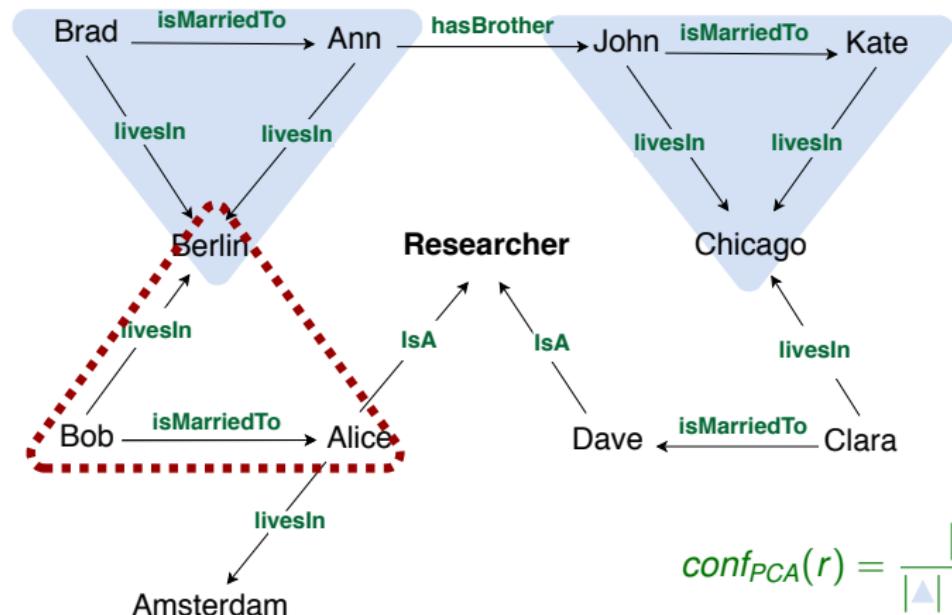


$r : livesIn(X, Y) \leftarrow isMarriedTo(Z, X), livesIn(Z, Y)$

Relational Association Rule Learning

PCA confidence AMIE [Galarraga *et al.*, 2015]

Partial CA: Since Alice has a living place already, all others are incorrect.

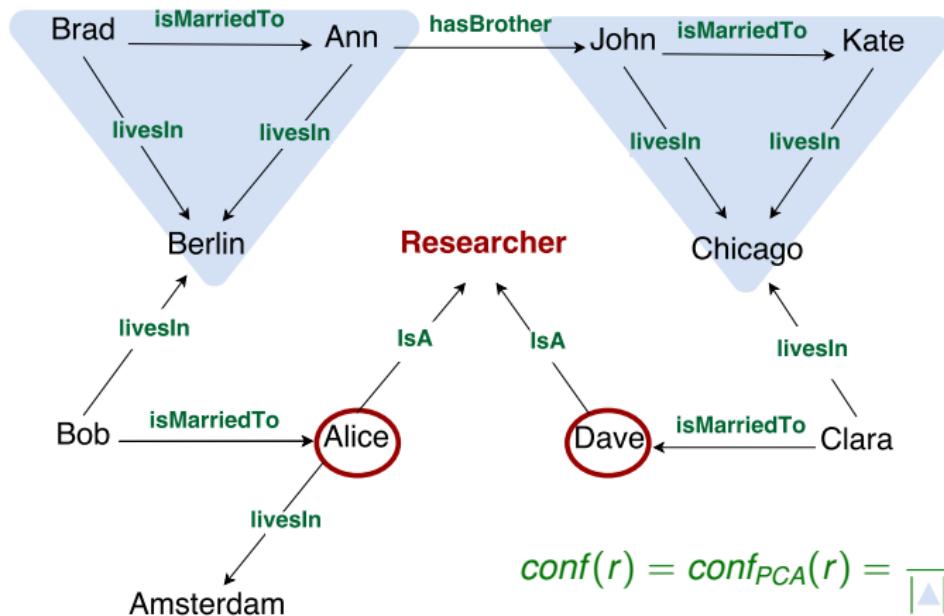


$$conf_{PCA}(r) = \frac{|\triangle|}{|\triangle| + |\triangle|} = \frac{2}{3}$$

$r : livesIn(X, Y) \leftarrow isMarriedTo(Z, X), livesIn(Z, Y)$

Relational Association Rule Learning

Exception-enriched rules: **Open World Assumption** is a challenge!



$$conf(r) = conf_{PCA}(r) = \frac{|\Delta|}{|\Delta| + |\Delta^c|} = 1$$

$r : livesIn(X, Y) \leftarrow isMarriedTo(Z, X), livesIn(Z, Y), \text{not } isA(X, researcher)$

Horn Theory Revision

Quality-based Horn Theory Revision

Given:

- Available KG

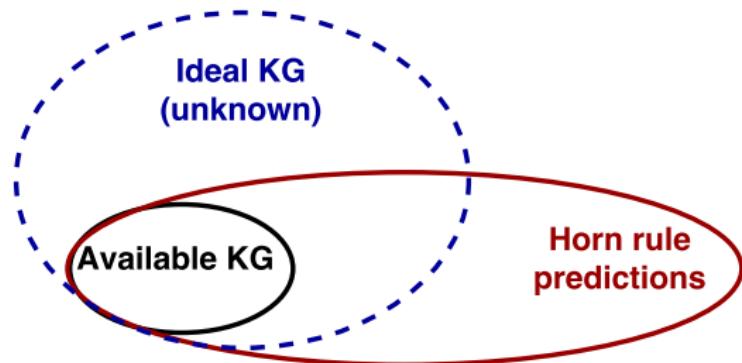


Horn Theory Revision

Quality-based Horn Theory Revision

Given:

- Available KG
- Horn rule set

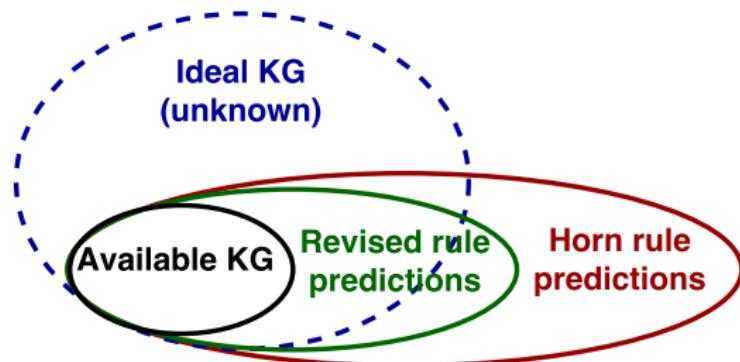


Horn Theory Revision

Quality-based Horn Theory Revision

Given:

- Available KG
- Horn rule set



Find:

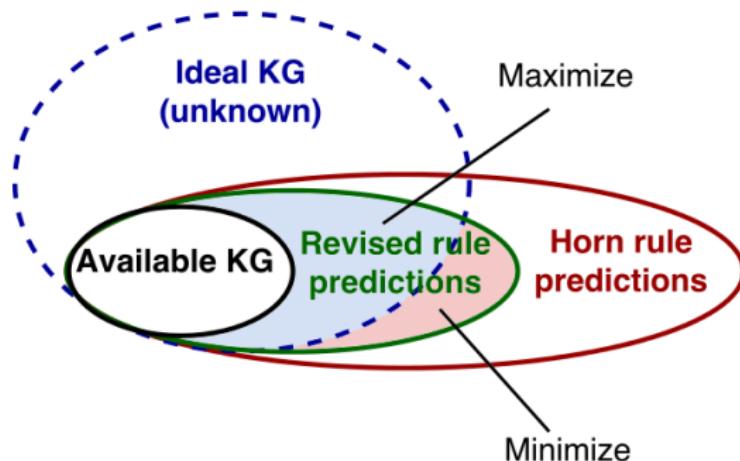
- Nonmonotonic revision of Horn rule set

Horn Theory Revision

Quality-based Horn Theory Revision

Given:

- Available KG
- Horn rule set



Find:

- Nonmonotonic revision of Horn rule set with better predictive quality

Avoid Data Overfitting

How to distinguish exceptions from noise?

$r1 : \text{livesIn}(X, Z) \leftarrow \text{isMarriedTo}(Y, X), \text{livesIn}(Y, Z), \text{not researcher}(X)$

Avoid Data Overfitting

How to distinguish exceptions from noise?

$r1 : \text{livesIn}(X, Z) \leftarrow \text{isMarriedTo}(Y, X), \text{livesIn}(Y, Z), \text{not researcher}(X)$
 $\text{not_livesIn}(X, Z) \leftarrow \text{isMarriedTo}(Y, X), \text{livesIn}(Y, Z), \text{researcher}(X)$

Avoid Data Overfitting

How to distinguish exceptions from noise?

$r1 : \text{livesIn}(X, Z) \leftarrow \text{isMarriedTo}(Y, X), \text{livesIn}(Y, Z), \text{not researcher}(X)$
 $\text{not_livesIn}(X, Z) \leftarrow \text{isMarriedTo}(Y, X), \text{livesIn}(Y, Z), \text{researcher}(X)$

$r2 : \text{livesIn}(X, Z) \leftarrow \text{bornIn}(X, Z), \text{not moved}(X)$
 $\text{not_livesIn}(X, Z) \leftarrow \text{bornIn}(X, Z), \text{moved}(X)$

Avoid Data Overfitting

How to distinguish exceptions from noise?

$r1 : \text{livesIn}(X, Z) \leftarrow \text{isMarriedTo}(Y, X), \text{livesIn}(Y, Z), \text{not researcher}(X)$
 $\text{not_livesIn}(X, Z) \leftarrow \text{isMarriedTo}(Y, X), \text{livesIn}(Y, Z), \text{researcher}(X)$

$r2 : \text{livesIn}(X, Z) \leftarrow \text{bornIn}(X, Z), \text{not moved}(X)$
 $\text{not_livesIn}(X, Z) \leftarrow \text{bornIn}(X, Z), \text{moved}(X)$

$\{\text{livesIn}(c, d), \text{not_livesIn}(c, d)\}$ are conflicting predictions

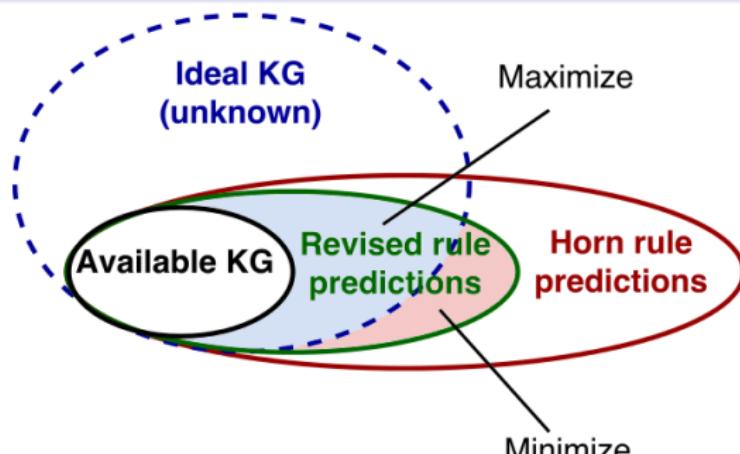
Intuition: Rules with good exceptions should make few conflicting predictions

Horn Theory Revision

Quality-based Horn Theory Revision

Given:

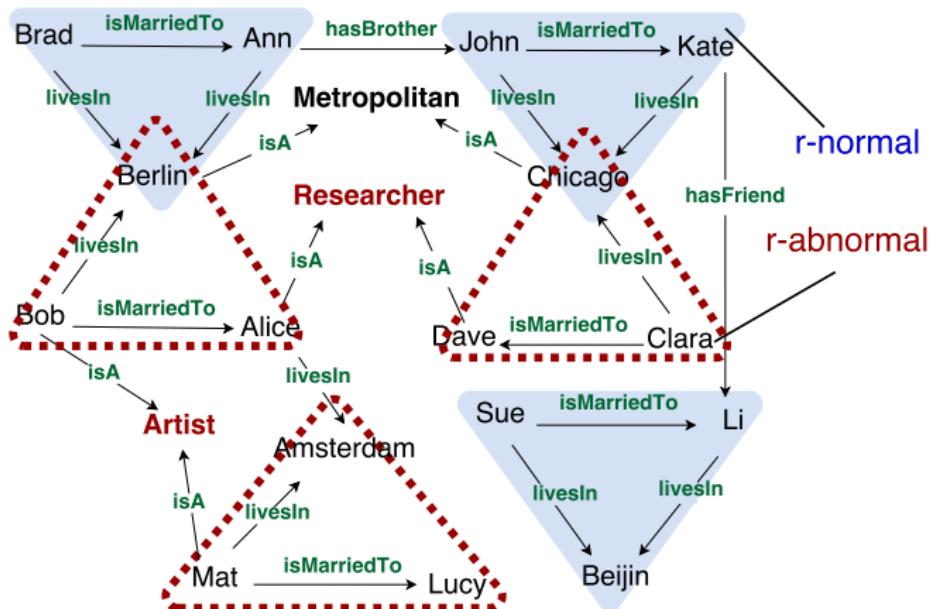
- Available KG
- Horn rule set



Find:

- Nonmonotonic revision of Horn rules, such that
 - number of **conflicting predictions** is **minimal**
 - average descriptive rule measure (e.g., confidence) is **maximal**

Exception Candidates

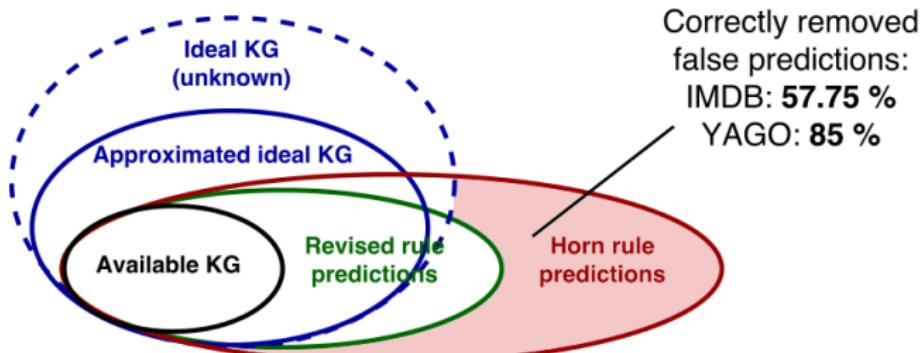


$r: \text{livesIn}(X, Z) \leftarrow \text{isMarriedTo}(Y, X), \text{livesIn}(Y, Z)$

$$\begin{cases} \text{not researcher}(X) \\ \text{not artist}(Y) \end{cases}$$

Experiments

- Approximated ideal KG: original KG
- Available KG: for every relation randomly remove 20% of facts from approximated ideal KG
- Horn rules: $h(X, Y) \leftarrow p(X, Z), q(Z, Y)$
- Exceptions: $e_1(X), e_2(Y), e_3(X, Y)$
- Predictions are computed using DLV reasoning system



Experiments

- Approximated ideal KG: original KG
- Available KG: for every relation randomly remove 20% of facts from approximated ideal KG
- Horn rules: $h(X, Y) \leftarrow p(X, Z), q(Z, Y)$
- Exceptions: $e_1(X), e_2(Y), e_3(X, Y)$
- Predictions are computed using DLV reasoning system

Examples of revised rules:

Plots of films in a sequel are written by the same writer, unless a film is American

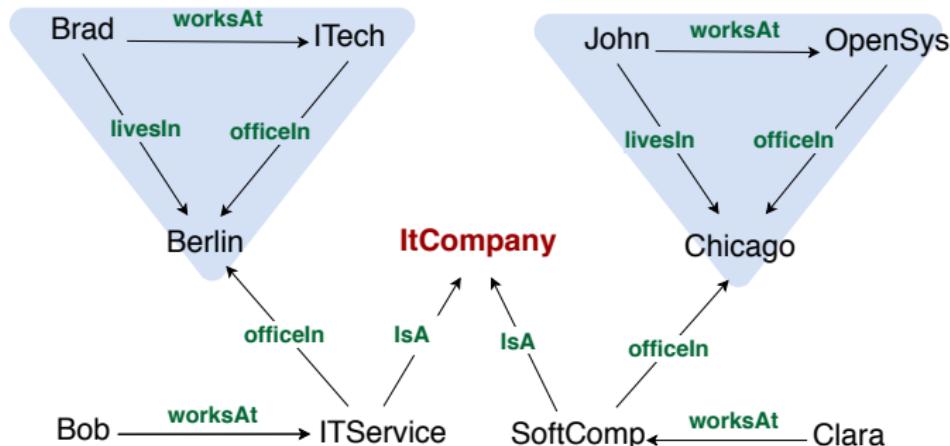
$r_1 : \text{writtenBy}(X, Z) \leftarrow \text{hasPredecessor}(X, Y), \text{writtenBy}(Y, Z), \text{not american_film}(X)$

Spouses of film directors appear on the cast, unless they are silent film actors

$r_2 : \text{actedIn}(X, Z) \leftarrow \text{isMarriedTo}(X, Y), \text{directed}(Y, Z), \text{not silent_film_actor}(X)$

Absurd Rules due to Data Incompleteness

Problem: rules learned from highly incomplete KGs might be absurd..

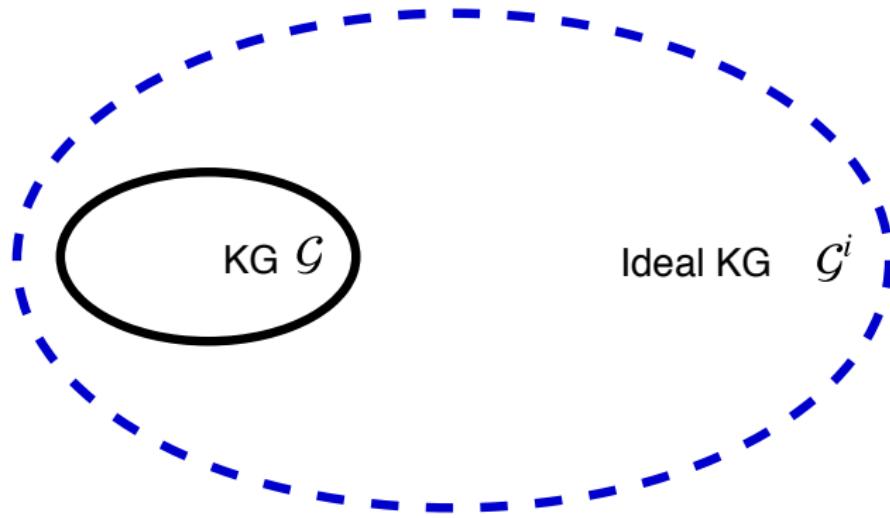


$$\text{conf}(r) = \text{conf}_{PCA}(r) = 1$$

$\text{livesIn}(X, Y) \leftarrow \text{worksAt}(X, Z), \text{officeln}(Z, Y), \text{not } \text{isA}(Z, \text{itCompany})$

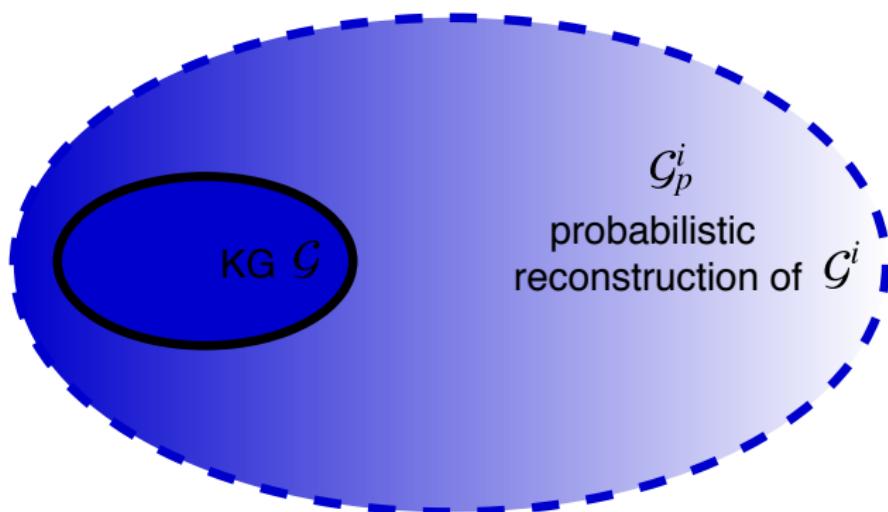
Ideal KG

$\mu(r, \mathcal{G}^i)$: measure quality of the rule r on \mathcal{G}^i , but \mathcal{G}^i is unknown



Probabilistic Reconstruction of Ideal KG

$\mu(r, \mathcal{G}_p^i)$: measure quality of r on \mathcal{G}_p^i



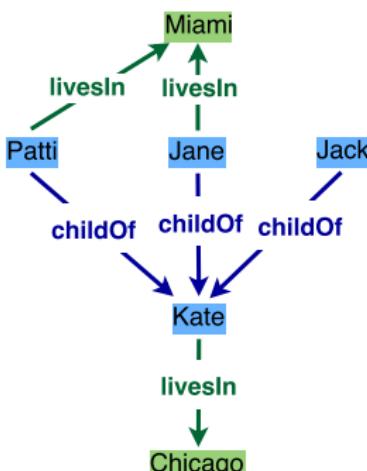
Hybrid Rule Measure

$$\mu(r, \mathcal{G}_p^i) = (1 - \lambda) \times \mu_1(r, \mathcal{G}) + \lambda \times \mu_2(r, \mathcal{G}_p^i)$$

- $\lambda \in [0..1]$: **weighting factor**
- μ_1 : **descriptive quality** of rule r over the available KG \mathcal{G}
 - confidence
 - PCA confidence
- μ_2 : **predictive quality** of r relying on \mathcal{G}_p^i (probabilistic reconstruction of the ideal KG \mathcal{G}^i)

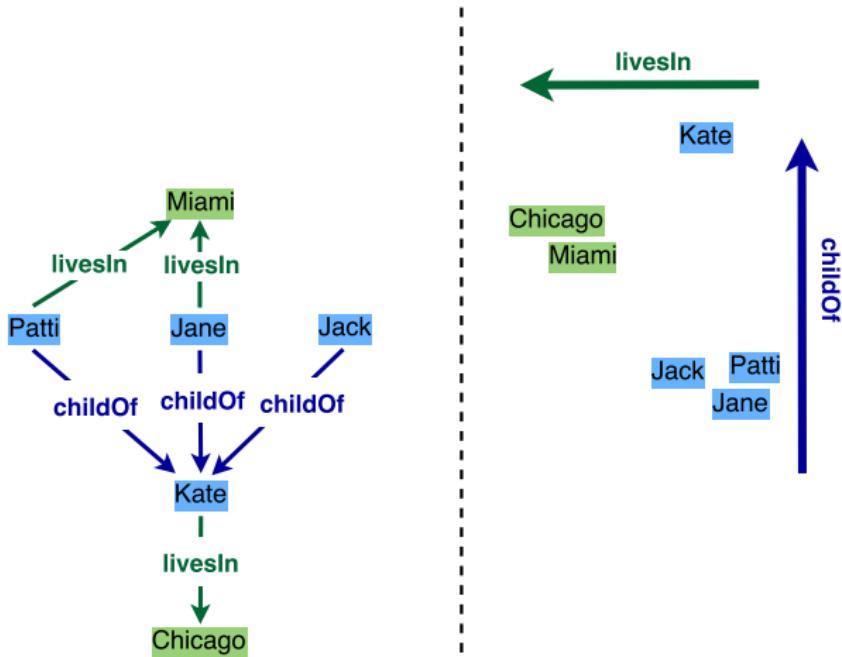
KG Embeddings

- **Intuition:** For $\langle s, p, o \rangle$ in KG, find s, p, o such that $s + p \approx o$
- The “error of translation” of a true KG fact should be smaller by a certain margin than the “error of translation” of an out-of-KG one



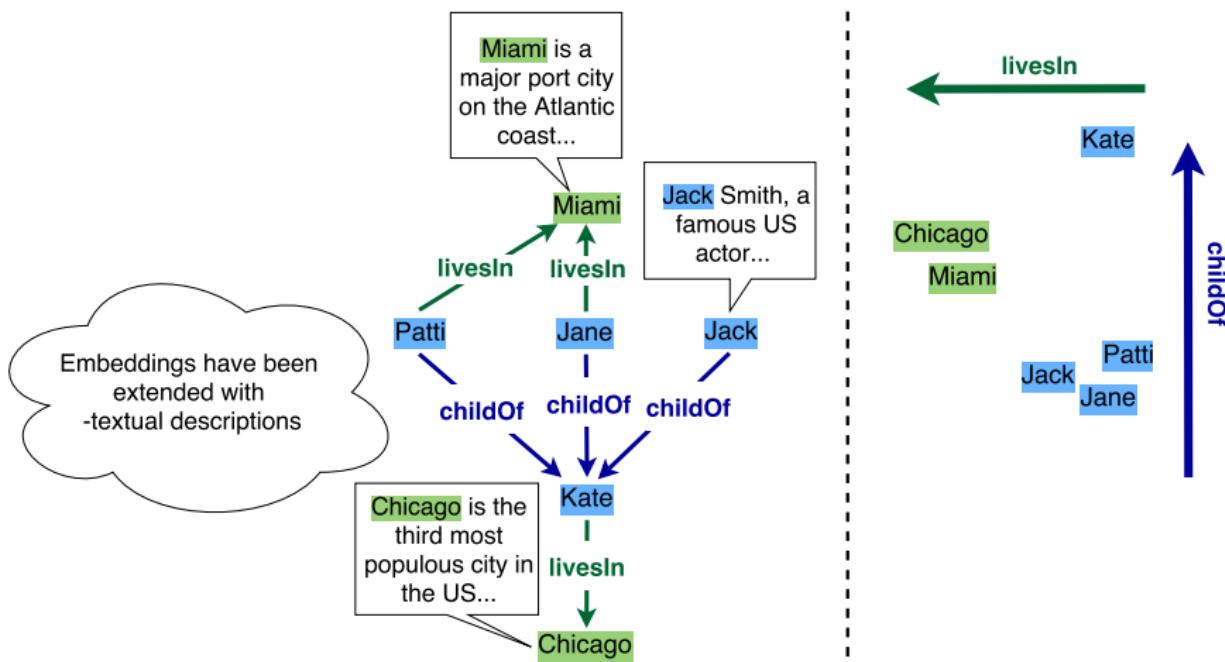
KG Embeddings

- **Intuition:** For $\langle s, p, o \rangle$ in KG, find s, p, o such that $s + p \approx o$
- The “error of translation” of a true KG fact should be smaller by a certain margin than the “error of translation” of an out-of-KG one



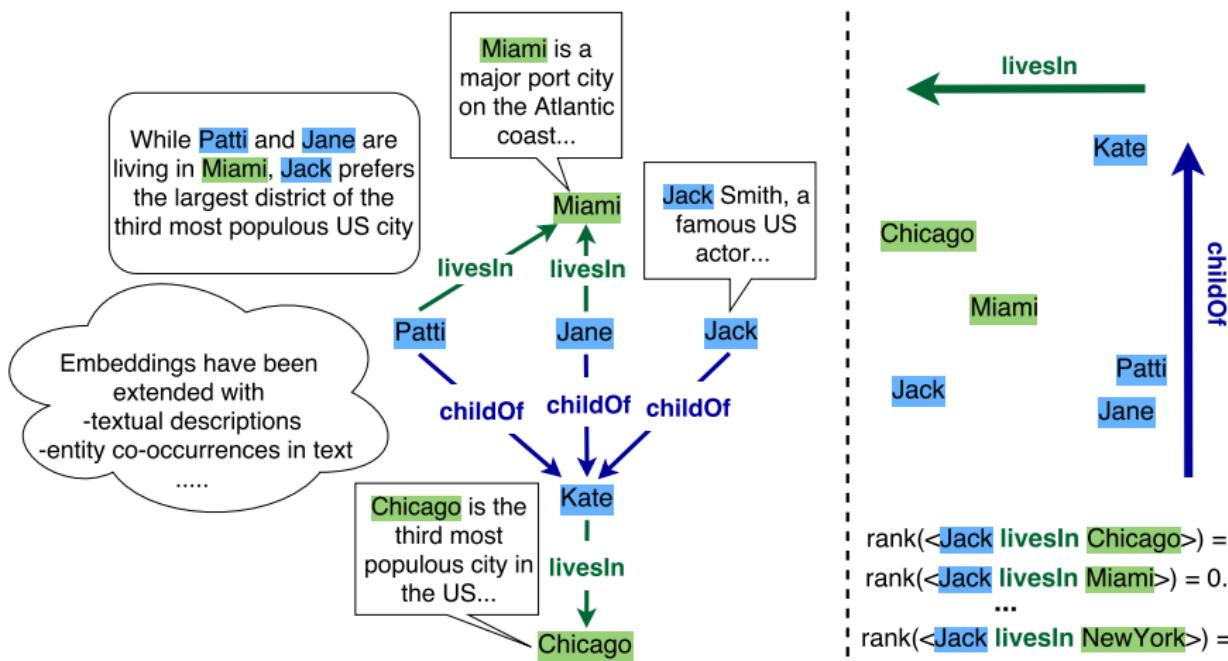
KG Embeddings

- **Intuition:** For $\langle s, p, o \rangle$ in KG, find s, p, o such that $s + p \approx o$
- The “error of translation” of a true KG fact should be smaller by a certain margin than the “error of translation” of an out-of-KG one

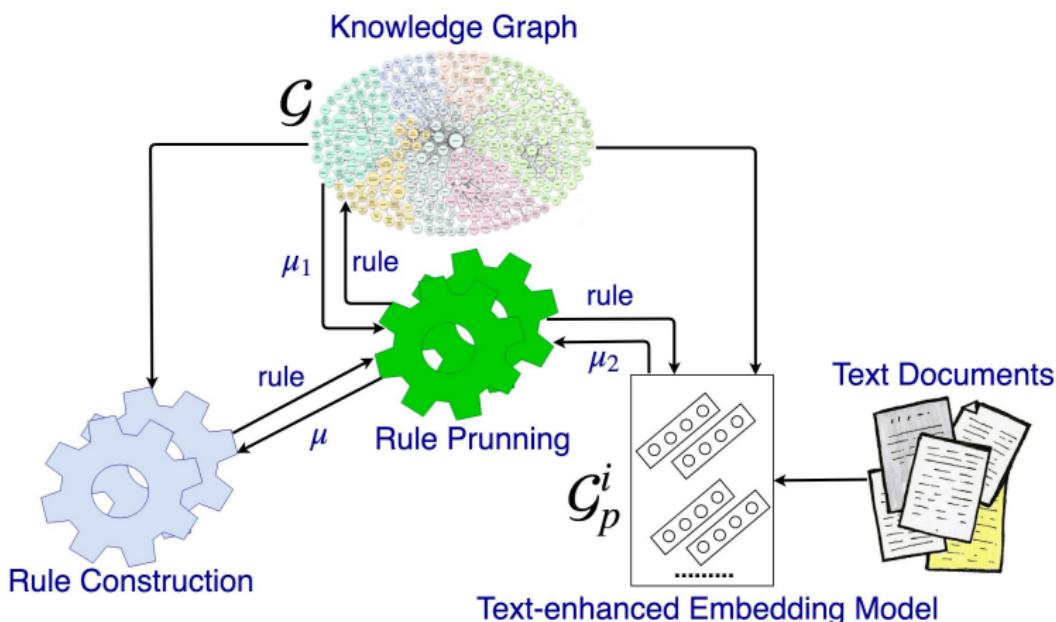


KG Embeddings

- **Intuition:** For $\langle s, p, o \rangle$ in KG, find s, p, o such that $s + p \approx o$
- The “error of translation” of a true KG fact should be smaller by a certain margin than the “error of translation” of an out-of-KG one



Embedding-based Rule Learning

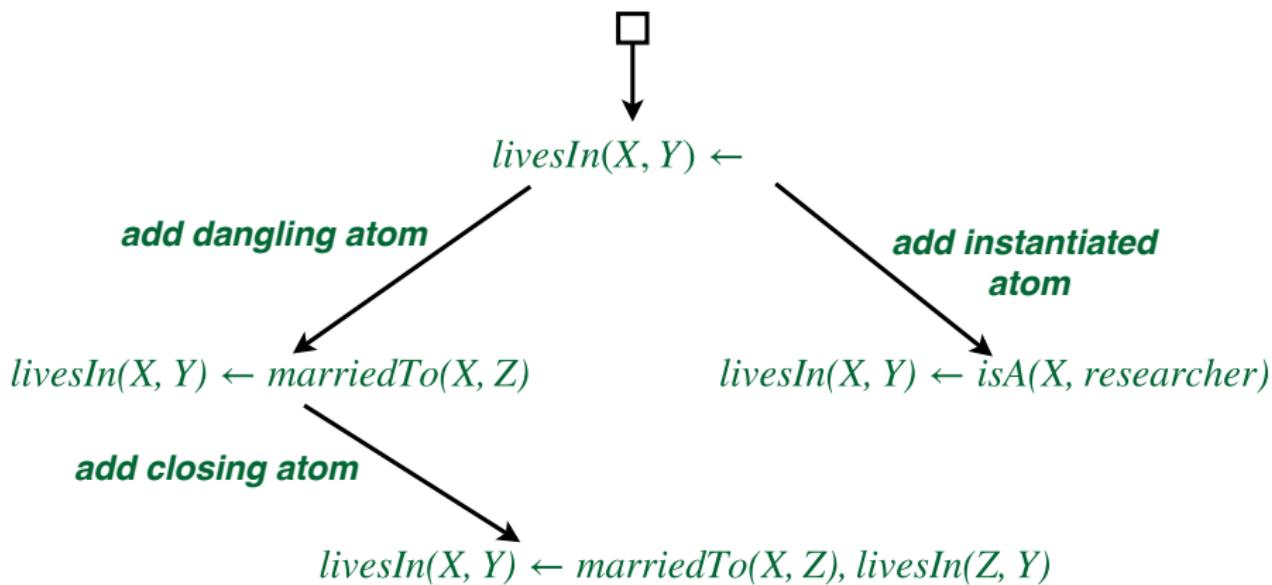


Rule Construction

- Clause exploration from general to specific

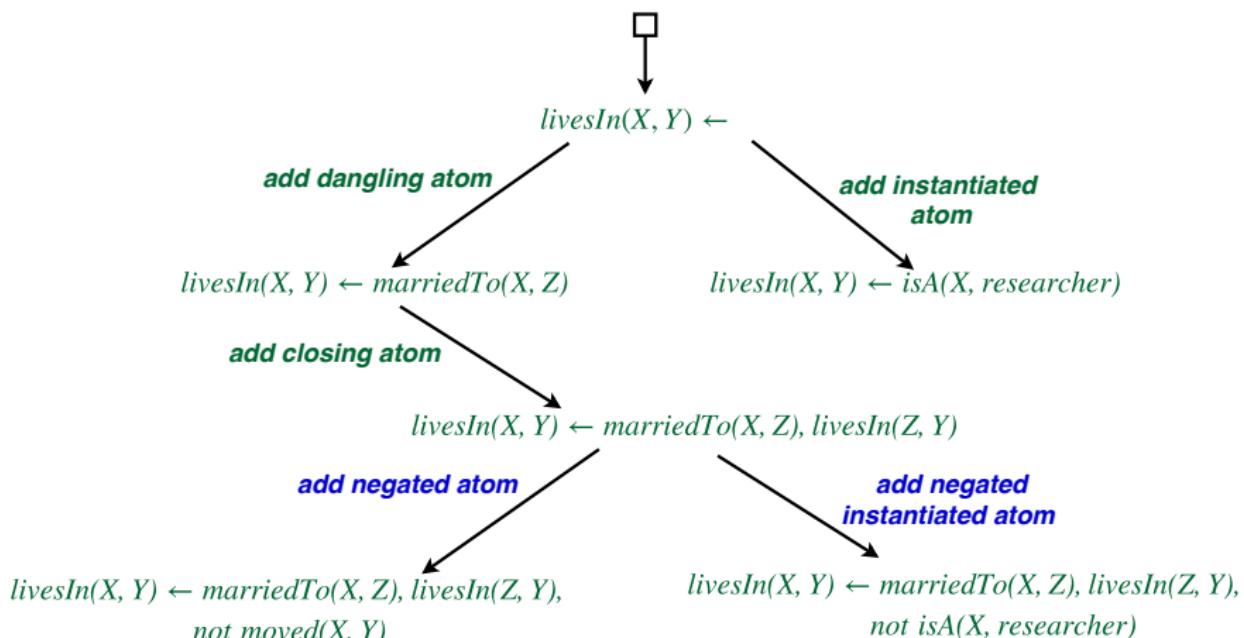
- Our work:** closed and safe rules with negation

$livesIn(X, Y) \leftarrow marriedTo(X, Z), livesIn(Z, Y), not\ isA(X, researcher)$

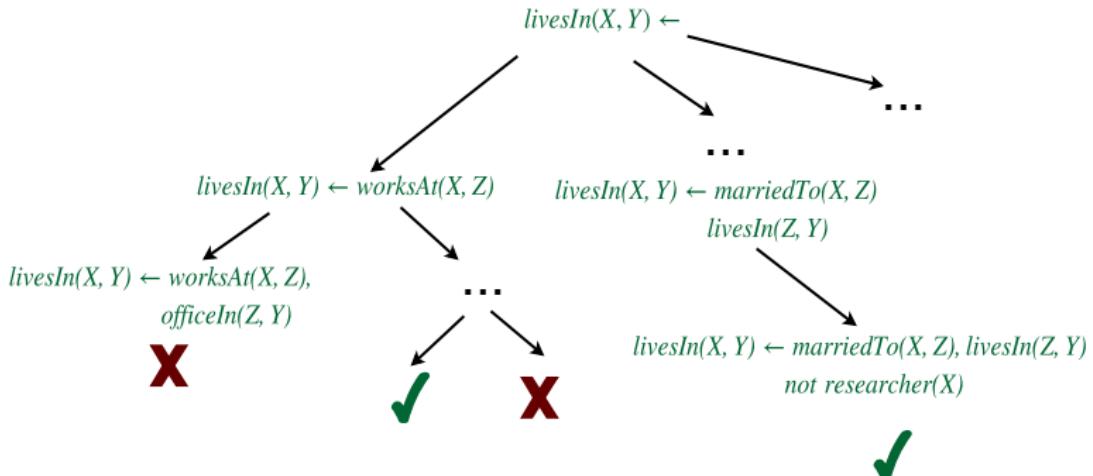


Rule Construction

- Clause exploration from general to specific
 - Our work:** closed and safe rules with negation
 $livesIn(X, Y) \leftarrow marriedTo(X, Z), livesIn(Z, Y), not\ isA(X, researcher)$



Rule Pruning



Prune rule search space relying on

- novel hybrid embedding-based rule measure

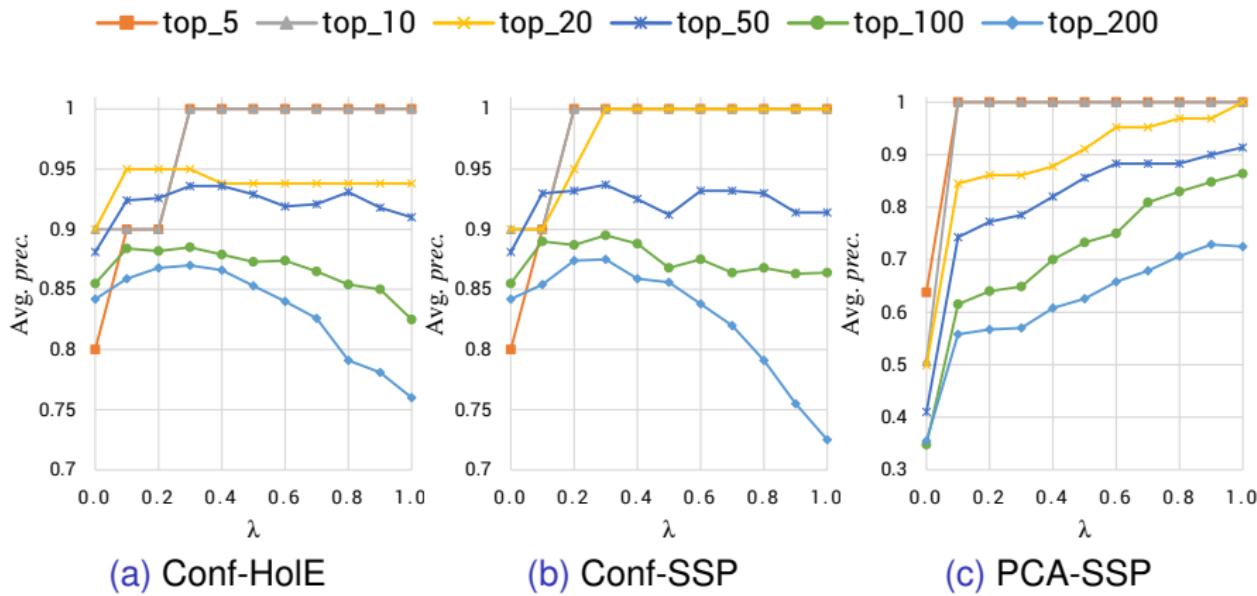
Evaluation Setup

- Datasets:
 - FB15K: 592K facts, 15K entities and 1345 relations
 - Wiki44K: 250K facts, 44K entities and 100 relations
- Training graph \mathcal{G} : remove 20% from the available KG
- Embedding models \mathcal{G}_p^i :
 - TransE [Bordes *et al.*, 2013], HolE [Nickel *et al.*, 2016]
 - With text: SSP [Xiao *et al.*, 2017]
- Goals:
 - Evaluate effectiveness of our hybrid rule measure

$$\mu(r, \mathcal{G}_p^i) = (1 - \lambda) \times \mu_1(r, \mathcal{G}) + \lambda \times \mu_2(r, \mathcal{G}_p^i)$$

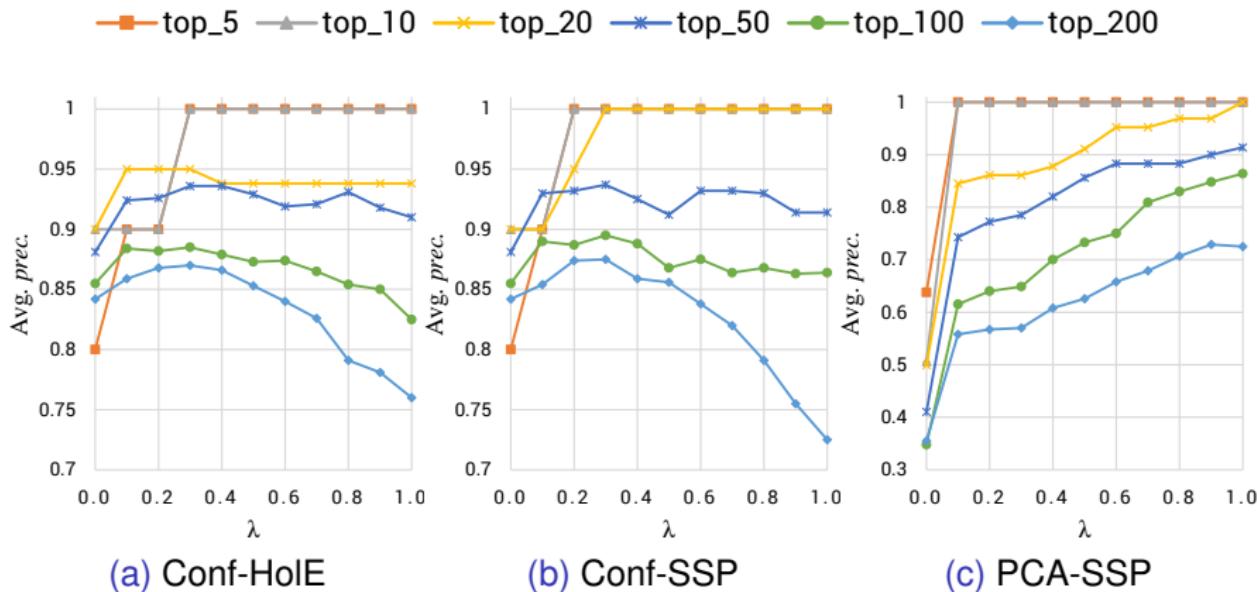
- Compare against state-of-the-art rule learning systems

Evaluation of Hybrid Rule Measure



Precision of *top-k* rules ranked using variations of μ on FB15K.

Evaluation of Hybrid Rule Measure



Precision of *top-k* rules ranked using variations of μ on FB15K.

- Positive impact of embeddings in all cases for $\lambda = 0.3$
- Note:** in (c) comparison to AMIE [Galarraga *et al.*, 2015] ($\lambda = 0$)

Meta-data about Missing Facts in the KG

- Mining cardinality assertions from the Web [Mirza *et al.*, 2016]
 - *... Albert Einstein had 3 children ...*
- Estimating recall of KGs by crowd sourcing [Razniewski *et al.*, 2016]
 - *20 % of Nobel laureates in physics are missing*
- Predicting completeness in KGs [Galárraga *et al.*, 2017]
 - $complete(X, hasChild) \leftarrow child(X)$

Exploiting Meta-data in Rule Learning

Goal: make use of topological constraints on edge counts in the KG to improve rule learning.



build here!

5 missing

0 missing

do not build here!

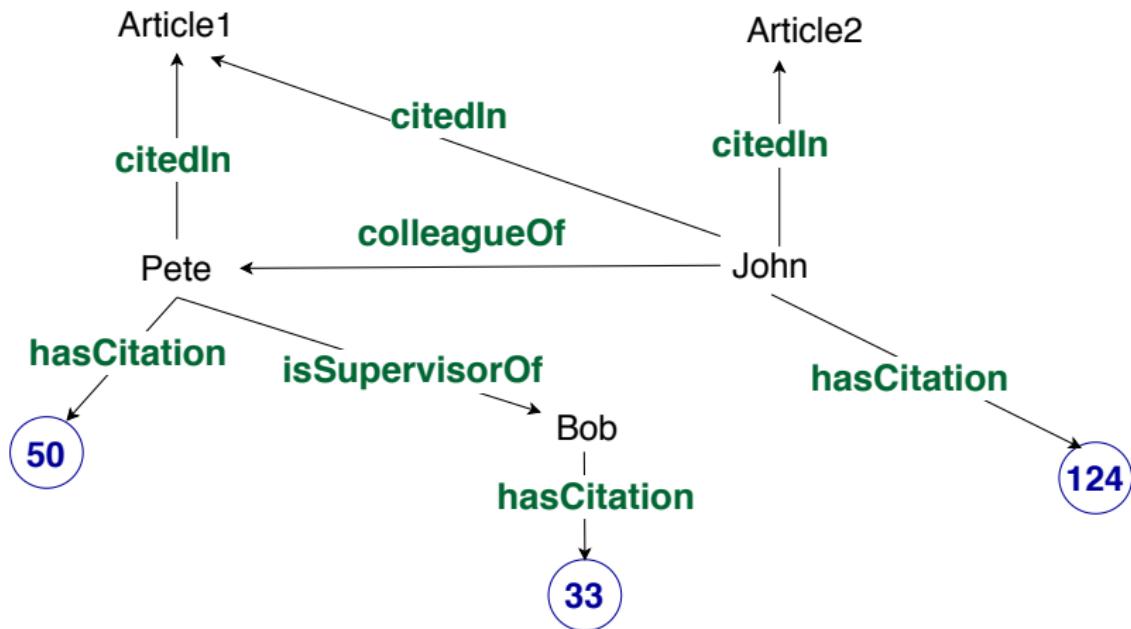
Motivation

Rule Induction under Incompleteness

Numerical Rule Learning

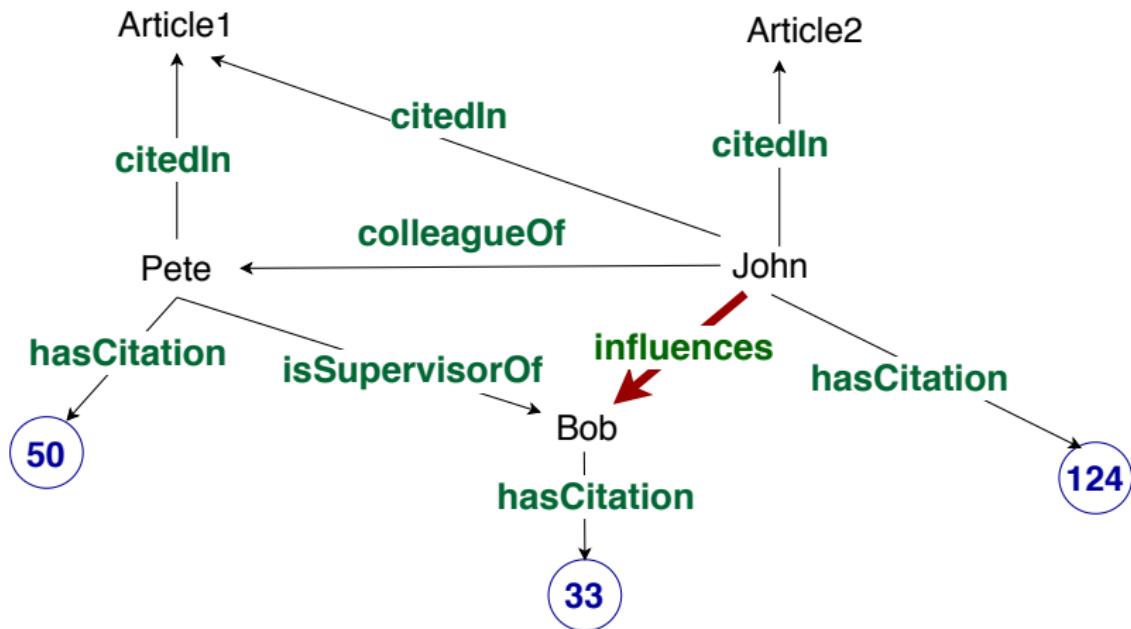
Rule-based Fact Checking

Numerical Rules



$influences(X, Y) \leftarrow colleagueOf(X, Z), supervisorOf(Z, Y), X.hasCitation > Z.hasCitation$

Numerical Rules

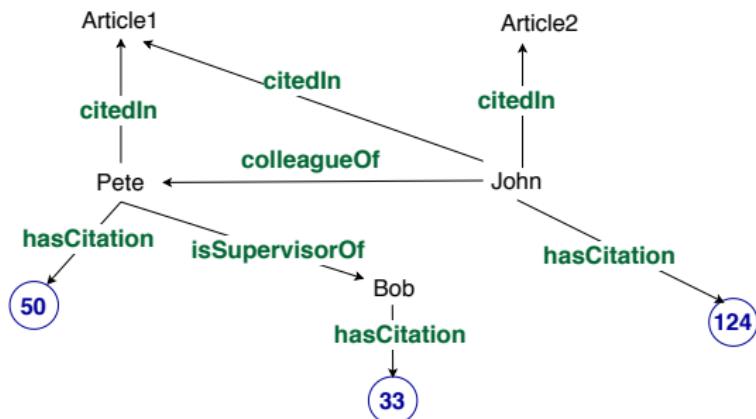


$$\text{influences}(X, Y) \leftarrow \text{colleagueOf}(X, Z), \text{supervisorOf}(Z, Y), X.\text{hasCitation} > Z.\text{hasCitation}$$

Rule Learning via Boolean Matrix Multiplication

NeuralLP [Yang *et al.*, 2017]: Differentiable rule learning

$$M_{\text{citedIn}} = \begin{bmatrix} \text{john} & \text{pete} & \text{bob} & \text{article1} & \text{article2} \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{array}{l} \text{john} \\ \text{pete} \\ \text{bob} \\ \text{article1} \\ \text{article2} \end{array}$$

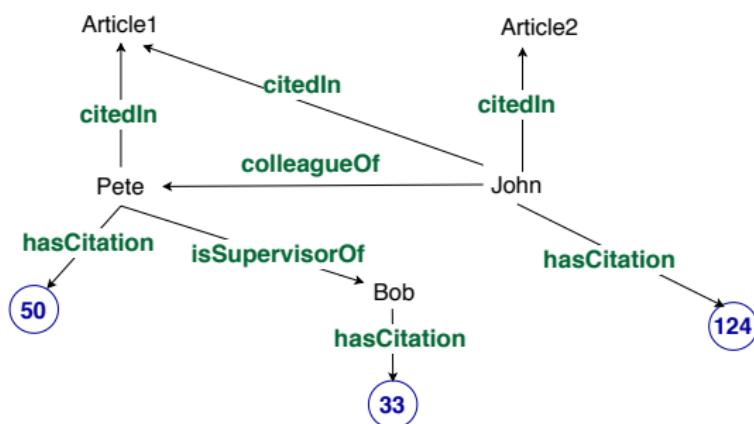


Rule Learning via Boolean Matrix Multiplication

NeuralLP [Yang *et al.*, 2017]: Differentiable rule learning

$$M_{\text{citedIn}} = \begin{bmatrix} \text{john} & \text{pete} & \text{bob} & \text{article1} & \text{article2} \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{array}{l} \text{john} \\ \text{pete} \\ \text{bob} \\ \text{article1} \\ \text{article2} \end{array}$$

$$v_{\text{john}} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \begin{array}{l} \text{john} \\ \text{pete} \\ \text{bob} \\ \text{article1} \\ \text{article2} \end{array}$$



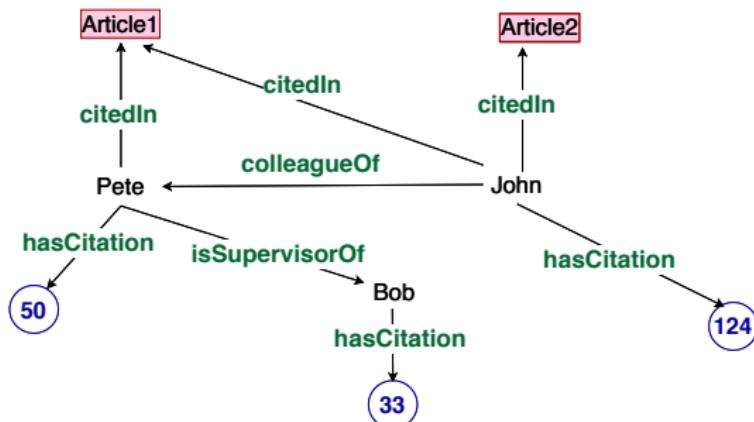
Rule Learning via Boolean Matrix Multiplication

NeuralLP [Yang *et al.*, 2017]: Differentiable rule learning

$$M_{\text{citedIn}} = \begin{bmatrix} \text{john} & \text{pete} & \text{bob} & \text{article1} & \text{article2} \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \begin{array}{l} \text{john} \\ \text{pete} \\ \text{bob} \\ \text{article1} \\ \text{article2} \end{array}$$

$$v_{\text{john}} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad \begin{array}{l} \text{john} \\ \text{pete} \\ \text{bob} \\ \text{article1} \\ \text{article2} \end{array}$$

$$M_{\text{citedIn}} v_{\text{john}} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$



Rule Learning via Boolean Matrix Multiplication

Differentiable learning framework via (**sparse**) matrix-vector multiplication

Rule Learning via Boolean Matrix Multiplication

Differentiable learning framework via (**sparse**) matrix-vector multiplication

$$\text{Adj matrix } (M_{\text{colleagueOf}})_{y,x} = \begin{cases} 1 & \text{if colleagueOf(} x, y \text{)} \\ 0 & \text{otherwise} \end{cases}$$

Rule Learning via Boolean Matrix Multiplication

Differentiable learning framework via (**sparse**) matrix-vector multiplication

$$\text{Adj matrix } (M_{\text{colleagueOf}})_{y,x} = \begin{cases} 1 & \text{if colleagueOf(} x, y \text{)} \\ 0 & \text{otherwise} \end{cases}$$

Apply rules (*path counting*) by **sparse** matrix-vector multiplication

$$\text{influences(} X, Z \text{)} \leftarrow \text{colleagueOf(} X, Y \text{), supervisorOf(} Y, Z \text{)}$$

$$\text{influences(} \text{john}, Z \text{)} = \text{one_hot(} \text{john} \text{)} \quad M_{\text{colleagueOf}}^T \quad M_{\text{supervisorOf}}^T$$

Rule Learning via Boolean Matrix Multiplication

Differentiable learning framework via (**sparse**) matrix-vector multiplication

$$\text{Adj matrix } (M_{\text{colleagueOf}})_{y,x} = \begin{cases} 1 & \text{if colleagueOf(} x, y \text{)} \\ 0 & \text{otherwise} \end{cases}$$

Apply rules (*path counting*) by **sparse** matrix-vector multiplication

$$\text{influences(} X, Z \text{)} \leftarrow \text{colleagueOf(} X, Y \text{), supervisorOf(} Y, Z \text{)}$$

$$\text{influences(} \text{john}, Z \text{)} = \text{one_hot(} \text{john} \text{)} \quad M_{\text{colleagueOf}}^T \quad M_{\text{supervisorOf}}^T$$

For numerical rules, we can similarly create the comparison matrix

$$\text{Adj matrix } (M_{\text{cmp}})_{y,x} = \begin{cases} 1 & \text{if } x.\text{numCitation} < y.\text{numCitation} \\ 0 & \text{otherwise} \end{cases}$$

Rule Learning via Boolean Matrix Multiplication

Differentiable learning framework via (**sparse**) matrix-vector multiplication

$$\text{Adj matrix } (M_{\text{colleagueOf}})_{y,x} = \begin{cases} 1 & \text{if colleagueOf(} \mathbf{x}, \mathbf{y} \text{)} \\ 0 & \text{otherwise} \end{cases}$$

Apply rules (*path counting*) by **sparse** matrix-vector multiplication

$$\text{influences(} \mathbf{X}, \mathbf{Z} \text{)} \leftarrow \text{colleagueOf(} \mathbf{X}, \mathbf{Y} \text{), supervisorOf(} \mathbf{Y}, \mathbf{Z} \text{)}$$

$$\text{influences(} \mathbf{john}, \mathbf{Z} \text{)} = \text{one_hot(} \mathbf{john} \text{)} \quad M_{\text{colleagueOf}}^T \quad M_{\text{supervisorOf}}^T$$

For numerical rules, we can similarly create the comparison matrix

$$\text{Adj matrix } (M_{\text{cmp}})_{y,x} = \begin{cases} 1 & \text{if } \mathbf{x}.\text{numCitation} < \mathbf{y}.\text{numCitation} \\ 0 & \text{otherwise} \end{cases}$$

Problem: may be a **dense matrix** \Rightarrow cannot be materialized on GPU

Efficient Matrix Vector Multiplication for Numerical Operators

Trick: assume values are sorted by the permutation matrices P_p and P_q , resp.

$$\text{NaN} \dots \text{NaN} \ \tilde{g}_1 \leq \dots \leq \tilde{g}_n$$

$$\tilde{M}_{r_{pq}^{\leq}} = \left[\begin{array}{cccc|cc} 0 & \cdots & 0 & \cdots & & 0 \\ \vdots & & \vdots & & & \vdots \\ 0 & \cdots & & & & 0 \\ \vdots & & 1 & \cdots & & 1 \\ 0 & 1 & \cdots & & & \\ \vdots & 0 & 1 & \cdots & & \\ 0 & 1 & \cdots & & & \\ 0 & \cdots & 0 & 1 & 1 \end{array} \right] \quad \begin{array}{l} \text{NaN} \\ \vdots \\ \text{NaN} \\ \tilde{f}_1 \\ \mid \wedge \\ \vdots \\ \mid \wedge \\ \tilde{f}_m \end{array}$$

Monotonic borderline:

γ_i : position of the first non-zero element in the i^{th} row

$$(\tilde{M}_{r_{pq}^{\leq}} v)_i = \sum_{\gamma_i \leq j \leq |\mathcal{C}|} v_j = \text{cumsum}(v)_{\gamma_i}$$

$$Mv = P_q^T \text{cumsum}(P_p v)_{\gamma}$$

Complexity: $O(n^2) \Rightarrow O(n \log n)$

Evaluation of Numerical Rule Learning

Hit@10: number of correct head atoms predicted out of the top 10 predictions

Dataset	Synthetic1	Synthetic2	FB15K-237-num	DBP15K-num
AnyBurl	0.031	0.685	0.426	0.522
NeuralLP	0.240	0.295	0.362	0.436
ours	1.000	1.000	0.415	0.682

Evaluation of Numerical Rule Learning

Hit@10: number of correct head atoms predicted out of the top 10 predictions

Dataset	Synthetic1	Synthetic2	FB15K-237-num	DBP15K-num
AnyBurl	0.031	0.685	0.426	0.522
NeuralLP	0.240	0.295	0.362	0.436
ours	1.000	1.000	0.415	0.682

Rules learned from Freebase and DBpedia:

Some symptoms provoke risk factors inherited from diseases with these symptoms

$\text{symptomHasRiskFactors}(X, Y) \leftarrow f(X), \text{symptomOfDisease}(X, Z),$
 $\text{diseaseHasRiskFactors}(Z, Y)$

Minister of defense with certain properties is the general of military of the given country

$\text{general}(X, Y) \leftarrow \text{ministerOfDefense}(X, Z), f(Z), \text{militaryBranchOfCountry}(Z, Y)$

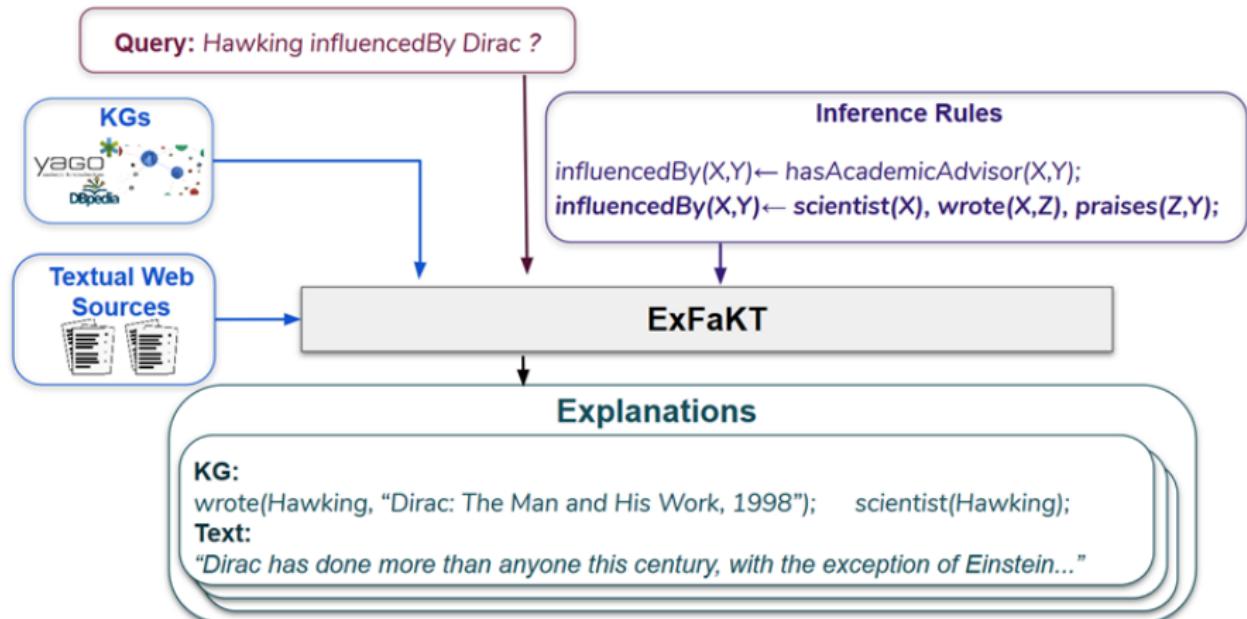
Motivation

Rule Induction under Incompleteness

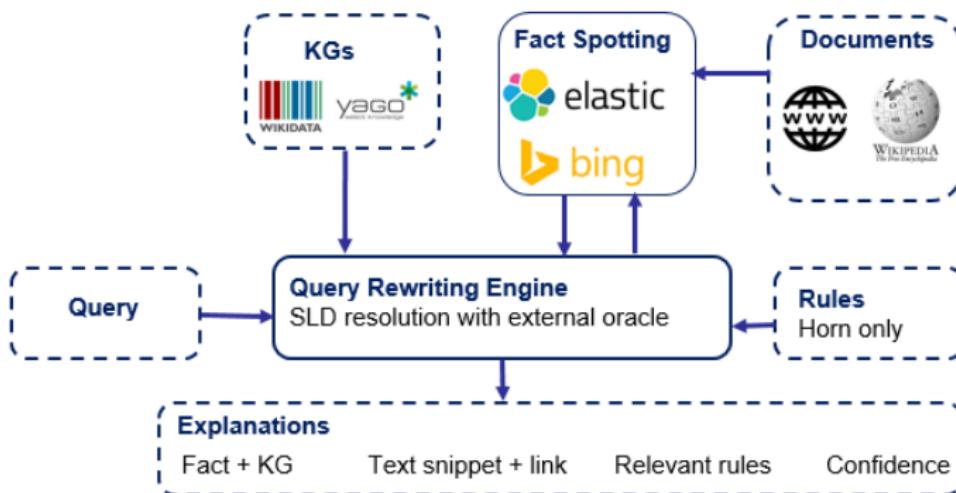
Numerical Rule Learning

Rule-based Fact Checking

Rule-based Fact Checking



Rule-based Fact Checking

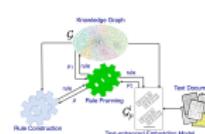
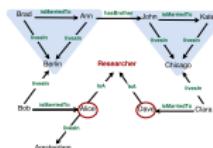


M. Gad-Elrab, D. Stepanova, J. Urbani, G. Weikum. *ExFakt: A Framework for Explaining Facts over KGs and Text*. WSDM 2019.

M. Gad-Elrab, D. Stepanova, J. Urbani, G. Weikum. *Tracy: Tracing Facts over Knowledge Graphs and Text*. WWW 2019.

Summary

- Horn rule learning
 - Exploiting embeddings to guide rule learning
 - Numerical rule learning
 - Rule-based fact checking



Huge Thanks!

- For collaborations on the presented work:
 - Mohamed Gad-elrab, Thinh Vinh Ho, Hai Dang Tran, Thomas Pellissier-Tanon, Gerhard Weikum, Jacopo Urbani, Evgeny Kharlamov, Francesca A. Lisi, Simon Razniewski, Paramita Mirza,
- For fruitful discussions and/or making slides available online:
 - Thomas Eiter, Stephen Muggleton, Luc De Raedt, Fabian Suchanek
- For providing amazing working atmosphere:
 - Bosch Center for AI

References I

-  Antoine Bordes, Nicolas Usunier, Alberto García-Durán, Jason Weston, and Oksana Yakhnenko.
Translating Embeddings for Modeling Multi-relational Data.
In *Proceedings of NIPS*, pages 2787–2795, 2013.
-  Claudia d'Amato, Steffen Staab, Andrea GB Tettamanzi, Tran Duc Minh, and Fabien Gandon.
Ontology enrichment by discovering multi-relational association rules from ontological knowledge bases.
In *SAC*, pages 333–338, 2016.
-  Richard Evans and Edward Grefenstette.
Learning explanatory rules from noisy data.
J. Artif. Intell. Res., 61:1–64, 2018.
-  Luis Galarraga, Christina Teflioudi, Katja Hose, and Fabian M. Suchanek.
Fast rule mining in ontological knowledge bases with AMIE+.
In *VLDB*, volume 24, pages 707–730, 2015.
-  Luis Galárraga, Simon Razniewski, Antoine Amarilli, and Fabian M Suchanek.
Predicting completeness in knowledge bases.
WSDM, 2017.
-  Bart Goethals and Jan Van den Bussche.
Relational association rules: Getting warmer.
In *PDD*, 2002.
-  Nikos Katzouris, Alexander Artikis, and Georgios Paliouras.
Incremental learning of event definitions with inductive logic programming.
Machine Learning, 100(2-3):555–585, 2015.
-  Mark-A. Krogel, Simon Alan Rawles, Filip Zelezný, Peter A. Flach, Nada Lavrac, and Stefan Wrobel.
Comparative evaluation of approaches to propositionalization.
In *ILP*, pages 197–214, 2003.

References II



Mark Law, Alessandra Russo, and Krysia Broda.

The ILASP system for learning answer set programs.

<https://www.doc.ic.ac.uk/~ml1909/ILASP>, 2015.



Jens Lehmann.

DL-Learner: Learning concepts in description logics.

Journal of Machine Learning Research, pages 2639–2642, 2009.



Francesca A. Lisi.

Inductive Logic Programming in Databases: From Datalog to DL+log.

TPLP, 10(3):331–359, 2010.



Paramita Mirza, Simon Razniewski, and Werner Nutt.

Expanding wikidata's parenthood information by 178%, or how to mine relation cardinality information.

In *ISWC 2016 Posters & Demos*, 2016.



Stephen Muggleton.

Inductive logic programming.

New Generation Comput., 8(4):295–318, 1991.



Stephen Muggleton.

Inverse entailment and prolog.

New Generation Comput., 13(3&4):245–286, 1995.



Maximilian Nickel, Lorenzo Rosasco, and Tomaso A. Poggio.

Holographic embeddings of knowledge graphs.

In *AAAI*, 2016.



Simon Razniewski, Fabian M. Suchanek, and Werner Nutt.

But what do we actually know?

In *Proceedings of the 5th Workshop on Automated Knowledge Base Construction, AKBC@NAACL-HLT 2016, San Diego, CA, USA, June 17, 2016*, pages 40–44, 2016.

References III



Ehud Y. Shapiro.

Inductive inference of theories from facts.

In *Computational Logic - Essays in Honor of Alan Robinson*, pages 199–254, 1991.



Han Xiao, Minlie Huang, Lian Meng, and Xiaoyan Zhu.

SSP: semantic space projection for knowledge graph embedding with text descriptions.

In *AAAI*, 2017.



Fan Yang, Zhilin Yang, and William W. Cohen.

Differentiable learning of logical rules for knowledge base reasoning.

In Isabelle Guyon, Ulrike von Luxburg, Samy Bengio, Hanna M. Wallach, Rob Fergus, S. V. N. Vishwanathan, and Roman Garnett, editors, *Advances in Neural Information Processing Systems 30: Annual Conference on Neural Information Processing Systems 2017, 4-9 December 2017, Long Beach, CA, USA*, pages 2319–2328, 2017.