

The cable project

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1 2

1.1 2a

1.2 2b

Boundary conditions:

$$\lim_{x \rightarrow \infty} \frac{\partial v(x, t)}{\partial x} = 0$$

and

$$\lim_{x \rightarrow \infty} \frac{\partial v(x, t)}{\partial x} = 0$$

Application of the change of variables $v(x, t) = V(\xi)$, where $\xi = x - ct$ to $\frac{\partial v(x, t)}{\partial t} = \frac{\partial^2 v(x, t)}{\partial x^2} - v(x, t) + H(v - \theta) + J_{ext}(x, t)$ yields the following second order ordinary differential equation. Assume that the external current. $J_{ext}(x, t) = 0$.

$$-cV'(\xi) = V''(\xi) - V(\xi) + H(V(\xi) - \theta) \quad (1)$$

1.3 2c

The two ordinary differential equations are:

$$-cV_1'(\xi) = V_1''(\xi) - V_1(\xi) \quad (2)$$

for $\xi \in (0, \infty)$ and

$$-cV_2'(\xi) = V_2''(\xi) - V_2(\xi) + 1 \quad (3)$$

for $\xi \in (-\infty, 0)$

The boundary conditions are

$$\begin{aligned} \lim_{\xi \rightarrow -\infty} \frac{dV_1(\xi)}{d\xi} &= 0 \\ \lim_{\xi \rightarrow \infty} \frac{dV_2(\xi)}{d\xi} &= 0 \\ \lim_{\xi \rightarrow -\infty} V_1(\xi) &= 1 \\ \lim_{\xi \rightarrow \infty} V_2(\xi) &= 0 \\ V_1(0) &= V_2(0) \\ \frac{dV_1}{d\xi}(0) &= \frac{dV_2}{d\xi}(0) \end{aligned}$$

1.4 2d

Equation 2 is a homogeneous ordinary differential equation. The corresponding characteristic equation, $r^2 + cr - 1 = 0$, has roots of $r = \frac{-c \pm \sqrt{c^2 + 4}}{2}$. Thus,

$$V_1 = c_1 e^{\frac{1}{2}(-c + \sqrt{c^2 + 4})\xi} + c_2 e^{-\frac{1}{2}(c + \sqrt{c^2 + 4})\xi}, \xi \in (0, \infty) \quad (4)$$

In order to solve equation 3, use the method of undetermined coefficients. First, determine the homogeneous solution of the differential equation by solving $cV_2'(\xi) = V_2''(\xi) - V_2(\xi)$ for V_2 . The characteristic equation, $r^2 + cr - 1 = 0$, has roots of $r = \frac{-c \pm \sqrt{c^2 + 4}}{2}$. Thus, the homogeneous solution is

$$V_{2,h} = c_3 e^{\frac{1}{2}(-c + \sqrt{c^2 + 4})\xi} + c_4 e^{-\frac{1}{2}(c + \sqrt{c^2 + 4})\xi} \quad (5)$$

Guess a particular solution of the form $V_{2,p} = A$. Plugging $V_{2,p}$ into equation 3 yields

$$-c(0) = 0 - A + 1$$

$$A = 1$$

$$V_{2,p} = 1$$

Thus, the solution to equation 3 is

$$V_2 = c_3 e^{\frac{1}{2}(-c+\sqrt{c^2+4})\xi} + c_4 e^{-\frac{1}{2}(c+\sqrt{c^2+4})\xi} + 1, \xi \in (-\infty, 0) \quad (6)$$

Next, use the boundary conditions to eliminate the arbitrary coefficients.

$$\begin{aligned} \lim_{\xi \rightarrow \infty} \frac{dV_1(\xi)}{d\xi} &= 0 \Rightarrow c_1 = 0 \\ \lim_{\xi \rightarrow -\infty} \frac{dV_2(\xi)}{d\xi} &= 0 \Rightarrow c_4 = 0 \\ V_1(0) &= V_2(0) \Rightarrow c_2 = c_3 + 1 \\ \frac{dV_1}{d\xi}(0) &= \frac{dV_2}{d\xi}(0) \Rightarrow -\frac{1}{2}(c + \sqrt{c^2 + 4})c_2 = \frac{1}{2}(-c + \sqrt{c^2 + 4})c_3 \end{aligned}$$

The solution to this linear system of equations is $c_1 = 0, c_2 = \frac{\frac{1}{2}(-c+\sqrt{c^2+4})}{\frac{1}{2}(-c+\sqrt{c^2+4})+\frac{1}{2}(c+\sqrt{c^2+4})} = \frac{-c+\sqrt{c^2+4}}{2\sqrt{c^2+4}}, c_3 = \frac{-\frac{1}{2}(c+\sqrt{c^2+4})}{\frac{1}{2}(-c+\sqrt{c^2+4})+\frac{1}{2}(c+\sqrt{c^2+4})} = \frac{-c-\sqrt{c^2+4}}{2\sqrt{c^2+4}},$ and $c_4 = 0$.

The solution to equation 2 is

$$V_1(\xi) = \frac{-c + \sqrt{c^2 + 4}}{2\sqrt{c^2 + 4}} e^{-\frac{1}{2}(c+\sqrt{c^2+4})\xi}, \xi \in (0, \infty). \quad (7)$$

The solution to equation 3 is

$$V_2(\xi) = \frac{-c - \sqrt{c^2 + 4}}{2\sqrt{c^2 + 4}} e^{\frac{1}{2}(-c+\sqrt{c^2+4})\xi} + 1, \xi \in (-\infty, 0). \quad (8)$$

1.5 2e

In order to understand the relationship between the speed of the traveling front and the threshold value θ , apply the threshold condition that $V(0) = \theta$. Application of this threshold condition to the traveling wave solutions gives $\frac{-c}{2\sqrt{c^2+4}} + \frac{1}{2} = \theta$.

$$\begin{aligned} \frac{-c}{\sqrt{c^2 + 4}} + 1 &= 2\theta \\ \frac{-c}{\sqrt{c^2 + 4}} &= 2\theta - 1 \\ \frac{c^2}{c^2 + 4} &= (2\theta - 1)^2 \\ c^2(1 - (2\theta - 1)^2) &= 4(2\theta - 1)^2 \end{aligned}$$

$$c = \sqrt{\frac{4(2\theta - 1)^2}{1 - (2\theta - 1)^2}}$$

$$c = \sqrt{\frac{-(2\theta - 1)^2}{\theta^2 - \theta}}$$

1.6 2f

Partial differential equation:

$$\frac{\partial v}{\partial t} = \frac{\partial^2 v}{\partial x^2} + f(v(x, t)) \quad (9)$$

where $f(v) = -v + H(v - \theta)$.

In order to analyze the stability of the traveling wave solution found, let $v(x, t) = V(\xi) + \epsilon\psi(\xi, t)$, where $0 < \epsilon \ll 1$ and $\psi(\xi, t)$ represents a small perturbation to the traveling wave solution.

$$\begin{aligned} \frac{\partial v}{\partial t} &= \frac{\partial \xi}{\partial t} \frac{dV}{d\xi} + \epsilon \left(\frac{\partial \psi}{\partial \xi} \frac{\partial \xi}{\partial t} + \frac{\partial \psi}{\partial t} \right) \\ \Rightarrow \frac{\partial v}{\partial t} &= -c \frac{dV}{d\xi} + \epsilon \left(-c \frac{\partial \psi}{\partial \xi} + \frac{\partial \psi}{\partial t} \right) \\ \frac{\partial v}{\partial x} &= \frac{\partial \xi}{\partial x} \frac{dV}{d\xi} + \epsilon \frac{\partial \xi}{\partial x} \frac{\partial \psi}{\partial \xi} \\ \Rightarrow \frac{\partial v}{\partial x} &= \frac{dV}{d\xi} + \epsilon \frac{\partial \psi}{\partial \xi} \\ \frac{\partial^2 v}{\partial x^2} &= \frac{\partial \xi}{\partial x} \frac{d^2 V}{d\xi^2} + \epsilon \frac{\partial^2 \psi}{\partial \xi^2} \frac{\partial \xi}{\partial x} \\ \Rightarrow \frac{\partial^2 v}{\partial x^2} &= \frac{d^2 V}{d\xi^2} + \epsilon \frac{\partial^2 \psi}{\partial \xi^2} \end{aligned}$$

Equation 9 can be rewritten as

$$-c \frac{dV(\xi)}{d\xi} + \epsilon \left(-c \frac{\partial \psi(\xi, t)}{\partial \xi} + \frac{\partial \psi(\xi, t)}{\partial t} \right) = \frac{d^2 V(\xi)}{d\xi^2} + \epsilon \frac{\partial^2 \psi(\xi, t)}{\partial \xi^2} + f(V(\xi) + \epsilon\psi(\xi, t)) \quad (10)$$

where $f(V(\xi) + \epsilon\psi) = -(V(\xi) + \epsilon\psi(\xi, t)) + H(V(\xi) + \epsilon\psi(\xi, t) - \theta)$.

Analysis of equation 10 can be simplified by using the Taylor expansion of $f(V(\xi) + \epsilon\psi)$ with respect to ϵ , about $\epsilon = 0$.

$$f(V(\xi) + \epsilon\psi) \approx f(V(\xi) + \epsilon\psi) \Big|_{\epsilon=0} + \left(\frac{\partial f(V(\xi) + \epsilon\psi)}{\partial \epsilon} \Big|_{\epsilon=0} \right) \epsilon + O(\epsilon^2)$$

$$f(V(\xi) + \epsilon\psi) \approx f(V(\xi)) + (-\psi(\xi, t) + \psi(\xi, t)\delta(V(\xi) - \theta))\epsilon$$

$$f(V(\xi) + \epsilon\psi) \approx -V(\xi) + H(V(\xi) - \theta) + \psi(\xi, t)\epsilon(-1 + \delta(V(\xi) - \theta))$$

Equation 10 becomes

$$-c \frac{dV(\xi)}{d\xi} + \epsilon(-c \frac{\partial\psi(\xi, t)}{\partial\xi} + \frac{\partial\psi(\xi, t)}{\partial t}) = \frac{d^2V(\xi)}{d\xi^2} + \epsilon \frac{\partial^2\psi(\xi, t)}{\partial\xi^2} - V(\xi) + H(V(\xi) - \theta) + \psi(\xi, t)\epsilon(-1 + \delta(V(\xi) - \theta))$$

In order to analyze the long term behavior of the disturbance, look only at the terms involving ψ and ϵ . The partial differential equation that models the behavior of the perturbation is:

$$\epsilon(-c \frac{\partial\psi(\xi, t)}{\partial\xi} + \frac{\partial\psi(\xi, t)}{\partial t}) = \epsilon \frac{\partial^2\psi(\xi, t)}{\partial\xi^2} + \psi(\xi, t)\epsilon(-1 + \delta(V(\xi) - \theta))$$

$$-c \frac{\partial\psi(\xi, t)}{\partial\xi} + \frac{\partial\psi(\xi, t)}{\partial t} = \frac{\partial^2\psi(\xi, t)}{\partial\xi^2} + \psi(\xi, t)(-1 + \delta(V(\xi) - \theta))$$

In order to further understand the behavior of the perturbation, solve the partial differential equation to the left and the right of $V(\xi) = \theta$. The governing equation for $V(\xi) \neq \theta$ is

$$-c \frac{\partial\psi(\xi, t)}{\partial\xi} + \frac{\partial\psi(\xi, t)}{\partial t} = \frac{\partial^2\psi(\xi, t)}{\partial\xi^2} - \psi(\xi, t) \quad (11)$$

since $\delta(V(\xi) - \theta) = 0$ whenever $V(\xi) \neq \theta$. This equation can be solved using separation of variables, which means solutions should have the form of $\psi(\xi, t) = F(\xi)G(t) \neq 0$. This proposed solution must satisfy the partial differential equation in equation 11.

$$-cG(t) \frac{dF(\xi)}{d\xi} + F(\xi) \frac{dG(t)}{dt} = G(t) \frac{d^2F(\xi)}{d\xi^2} - F(\xi)G(t)$$

$$-c \frac{1}{F(\xi)} \frac{dF}{d\xi} + \frac{1}{G(t)} \frac{dG}{dt} = \frac{1}{F(\xi)} \frac{d^2F(\xi)}{d\xi^2} - 1$$