

The IEEE Symposium on 3D User Interfaces focuses on the topic of 3D User Interfaces (3DUI). The event provides a unique opportunity for industrial and academic researchers to exchange ideas regarding 3DUI research. The symposium also hosts a 3DUI contest that is open to anyone interested in 3D user interfaces, from researchers to students, enthusiasts, and professionals. Participants can use any software or hardware for the contest. The purpose of the contest is to stimulate innovative and creative solutions to challenging 3D user interface problems.

This year, 2014, five teams competed in the competition: Slice-n-swipe, Bi-Manual Gesture Interaction for 3D Cloud Point Selection and Annotation using COTS, The Point Walker Multi-label Approach, Touching the Cloud, and Go'Then'Tag. Each team was faced with the challenge of building a system that allows users to annotate 3D point clouds obtained from 3D scanners. The system must support the accurate labeling of points or sets of points. It must also support overlapping hierarchies of annotations at varying scales. Lastly, contestants must create a 90-120 second video demoing their solution along with a two page abstract. This paper will compare and contrast three of these entries: Slice-n-swipe, Touching the Cloud, and Go'Then'Tag. The analysis will begin with a brief background of the three entries followed by a discussion on how well each team adheres to Jakob Neisen's 10 Usability Heuristics and the contest requirements. Special emphasis will be placed on why each team used the technique that they chose for a given task (i.e. camera/viewpoint manipulation, selection, annotation), and whether that technique was a good choice. If a team should have selected a different technique for any of their tasks, then this analysis will explain why, taking into account the other techniques used in that team's solution. Lastly, the analysis will consider how efficient, easy to use, and enjoyable the chosen techniques are.

Slice-n-swipe is a technique for 3D point cloud annotation based on free-hand gesture input (Bacim, Nabiyouni, & Bowman, 2014). The technique selects and manipulates objects using free-hand

gesture tools based on real word actions and metaphors, like a knife, bubble, or lasso. Point annotation is handled using a process called progressive refinement, which to allow the user to specify the points of interest and recursively edit and label subgroups of those points. Slice-n-Swipe uses a Leap Motion Controller for free-hand gesture input for the user's dominant hand, a 3DConnexion SpacePilot Pro 3D mouse for virtual camera control for the user's non-dominant hand, and a keyboard to annotate points or groups of points.

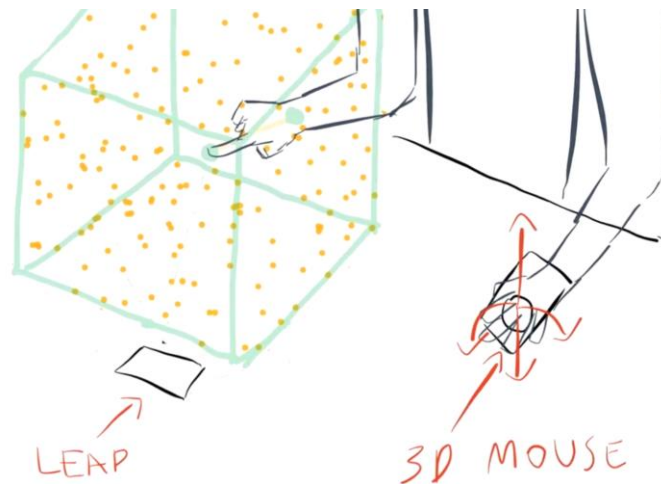


Figure 1: Hardware used for Slice-n-Swipe. Leap Motion Controller for free-hand gesture input for the user's dominant hand and a 3DConnexion SpacePilot Pro 3D mouse for virtual camera control for the user's non-dominant hand

Touching the Cloud is a bi-manual user interface for the interaction, selection, and annotation of immersive point cloud data (Lubos, Beimler, Lammers, & Steinicke, 2014). This team sets itself apart from the competition by developing a solution that does not require the user to manually interact with hardware, meaning that all actions are performed through speech or hand gestures. The setup involves three main components; an Oculus Rift head-mounted display (HMD), a PrimeSense Carmine 1.09 Sensor, and a laptop with an Intel Core i5 2.3 GHz processor. The Oculus Rift HMD allows users to immerse themselves in an environment optimized for natural interaction with point cloud data. The PrimeSense facilitates hand and finger tracking, providing an interaction volume of 60cm width and

50cm depth with the sensor at a height of 65cm. The laptop is used to process and display the scene on an Oculus Rift HMD and its attached microphone is used for annotation.

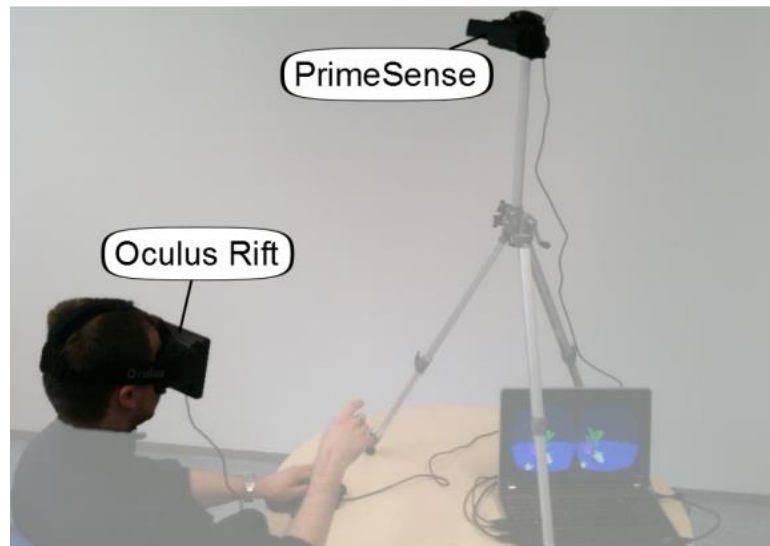


Figure 2: Touching the Cloud setup with a tripod-mounted PrimeSense sensor and a user wearing an Oculus Rift HMD.

Go'Then'Tag is a tool-set that helps users to edit complex 3-D data sets, and tag them at different levels (Veit & Capobianco, 2014). All interaction is handled through a tracked multi-touch device that combines 2-D and 3-D interaction techniques on a single device. Like Slice-n-Swipe, Go'Then'Tag also uses progressive refinement to reduce the complexity of the selection process. The environment is composed of one 3-D stereoscopic display with an optical tracking system capturing the head and device positions. The multi-touch device used for this demo is a Galaxy Note 2 running Android 4.3.



Figure 3: Go'Then'Tag's setup involves a 3-D stereoscopic display and a multi-touch device.

According to Nielsen's first heuristic for interface design, the state of the system should always be visible to the user. Meaning that when a user interacts with the system, he or she requires some sort of audio or visual feedback indicating that the system is working or that what he has done is either correct or incorrect. Slice-n-swipe and Touching the Cloud focus on hand gestures for manipulation, thus the initial state for both project seems to be scenes in which the user can visibly see their tracked hand movements. It is assumed that the user can perform selection and manipulation in this state.

Go'Then'Tag has a similar initial state except that the scene shows multi-touch device's position and orientation to the user. At any time during the interaction with the data set, the multi-touch device can provide vibrotactile feedback, a type of feedback that is unavailable for the other two interfaces. Each interface allows the user to switch between various selection tools, which will change selection state/behavior. Slice-n-Swipe switches tools using an onscreen GUI after performing an open-hand gesture. Touching the Cloud switches tools using voice commands and Go'Then'Tag switches using multi-touch touchscreen. The only other significant state is the annotation state. Annotation will be discussed in greater detail later.

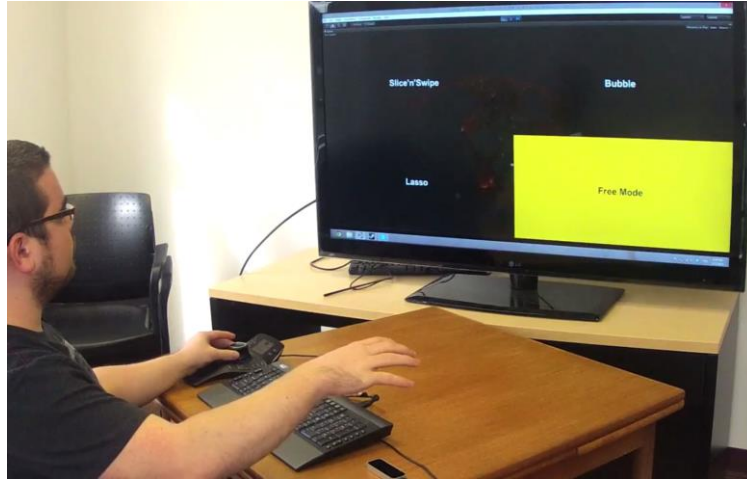


Figure 4: Switching tools using Slice-n-Swipe. The tools GUI appears after the user performs an open hand gesture.

Nielsen's second heuristic states that there should be a match between the system and the real world, meaning that the system should speak the users' language, with words, phrases and concepts familiar to the user, rather than system-oriented terms. Judging from each team's demo video, none of the interfaces seem to use any words at all, other than typical modeling terms like selection, translation, rotation, etc. However, a key aspect of Slice-n-Swipe is that its tools are metaphors that correspond to real world concepts. It is worth mentioning that teams Touching the Cloud and Go'Then'Tag mentioned in the evaluation section of their write-up that they tested their interface on novice users. These inexperienced users did not mention any issues regarding confusion or ambiguities of terms.

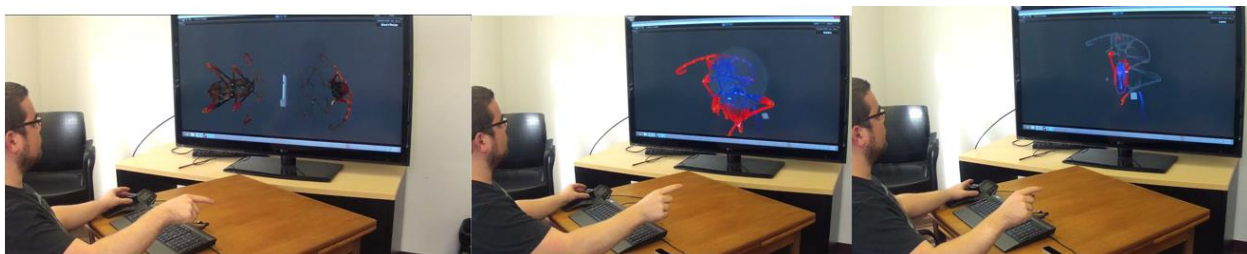


Figure 5: Slice-n-Swipe's three tools knife(left), bubble(middle), and lasso(right) correspond to real world concepts.

Nielsen's third heuristic states that systems must grant user control and freedom, meaning that users should be able to easily undo/redo mistakes. In Slice-n-Swipe when an action is performed, the user can undo the slice by waiting a couple of seconds without performing any gestures. This seems like a poor way to implement undo because it slows down the user's progress. An accelerator like a keyboard shortcut or undo gesture would be more efficient. Touching the Cloud handles undo through voice commands. Like Slice-n-Swipe, implementing a gesture accelerator would add speed and greater functionality to the interface. Go'Then'Tag does not mention error correction in its documentation but it would make sense that it would be handled through its touchscreen GUI.

Nielsen's fourth heuristic deals with consistency and standards. Users should not have to wonder whether different words, situations, or actions mean the same thing. The system should follow platform conventions. Since modeling software typically has a steep learning curve, consistency allows users to learn commands and techniques faster and interact with the system more efficiently. Using natural user interface technologies to manipulate and label point cloud data seems to be a relatively new problem so there are not many standards associated with this concept. For now, each interface only needs to implement features typically found in modeling software (i.e. camera and object manipulation). Overall, each team seems to perform selection and annotation in consistent, unambiguous manor.

Nielsen's fifth heuristic deals with error prevention. In addition to providing the user with helpful error messages, the designer should try to avoid these errors in the first place. It is the designer's job to either eliminate error-prone conditions or check for them and present the user with a confirmation option before he commits to the action. Should an error occur, Nielsen's ninth heuristic

states that the system should help users recognize, diagnose, and recover from error. Each team's demo videos do not intentionally show errors within their interface, nor do they discuss error in their write-ups. However, one can still speculate on on errors that might occur when using each interface. How does the system notify users when hand/device tracking is malfunctioning? How does the system notify users when hardware is malfunctioning? How does the system tell the use to correct any malfunctions? Does this system restrict illegal annotations (Duplicate names, invalid symbols, etc.)? Does the system prevent the annotation of an empty set of points? Does the system prevent the user from applying more than one annotation to a point/set of points? How does each system handle device calibration, if necessary? Does the system prevent camera errors like gimbal lock? How does the system prevent the user from getting lost in the virtual environment and what kind of wayfinding techniques are implemented to guild the user back to the area of interest?

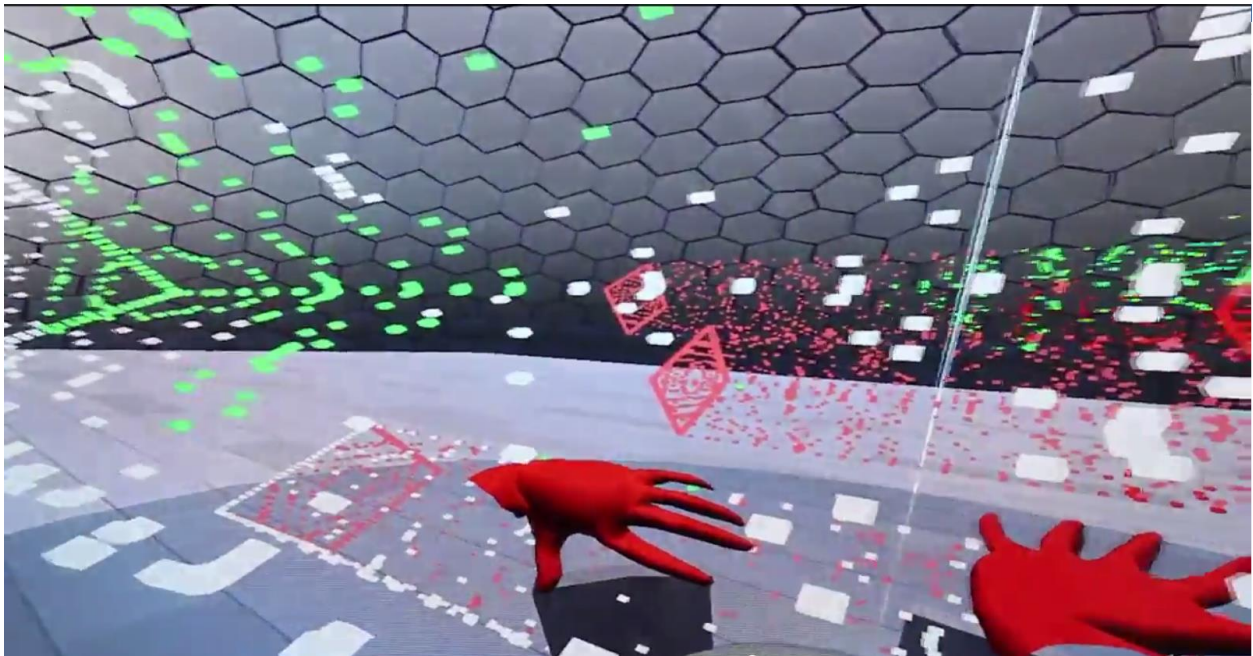


Figure 6: The image above shows a user in Touching the Cloud who is deep within the point cloud. Is there a way to guide the user in this disorienting environment?

Nielsen's sixth heuristic states that the system should emphasize user's recognition over the user's recollection. Designers should minimize the user's memory load by making objects, actions, and options visible. The user should not have to remember information from one part of the dialogue to another. Instructions for use of the system should be visible or easily retrievable whenever appropriate. In other words, users should not have to remember sequences of numbers, words, or long lists of items in a task. Instead, the interface should use easily recognizable pictures and symbols to communicate with the user. Slice-n-Swipe and especially Touching the Cloud will face difficulty with this heuristic because, gestures and voice commands must be memorized in order to use the interface efficiently. Forcing the user to remember these commands, sharply raises the learning curve for the interface. Go'Then'Tag circumvents these issues by making objects, actions, and options visible on the multi-touch display.

Nielsen's seventh heuristic deals with flexibility and efficient use. Designers equip their system with accelerators which can often speed up the interaction for the expert user such that the system can cater to both inexperienced and experienced users. In more advanced systems that are capable of learning user patterns, as novice users get acquainted with the system and perform certain tasks frequently, the system will be able to let those frequently performed tasks be accessible more efficiently. Again, each group's write-ups do not discuss accelerators directly, but one can speculate which accelerators that would fit well in each project. Slice-n-Swipe would benefit from implementing keyboard shortcuts since the keyboard is already part of the interface. Slice-n-Swipe and Touching the Cloud could use additional gesture to accomplish more complex tasks that novice users would not need to perform. Go'Then'Tag could use touchscreen accelerators or allow the user to customize the touchscreen GUI. Each interface should also implement a smart selection tool, similar to the Magic Wand tool in Photoshop, which will be able to algorithmically determine points that might be related.

Nielsen's eight heuristic deals with creating aesthetically pleasing systems. The system should not contain information which is irrelevant or rarely needed. Every extra unit of information in the system competes with the relevant units of information and diminishes their relative visibility. Of the three teams, Slice-and-Swipe has the most minimalist design. Usually, only the point cloud is present on the screen and a toolbar at the top of the screen. Like Slice-n-Swipe, Touching the Cloud usually only shows the point cloud to the user. However, the immersion aspect of the interface inherently creates an additional layer of complexity. Also, Touching the Cloud uses a three color scheme for selection; red for marked points, green for selected points, and pink for marked and selected points. In comparison to the other two team which simple fade unselected points, Touching the Cloud's multicolor layout is distracting. Go'Then'Tag has the most complex interface because it uses two screens: one for point cloud and the multi-touch device. This does not mean that Go'Then'Tag has a bad interface, on the contrary two screens gives the user more workspace to make annotation simpler and more organized.

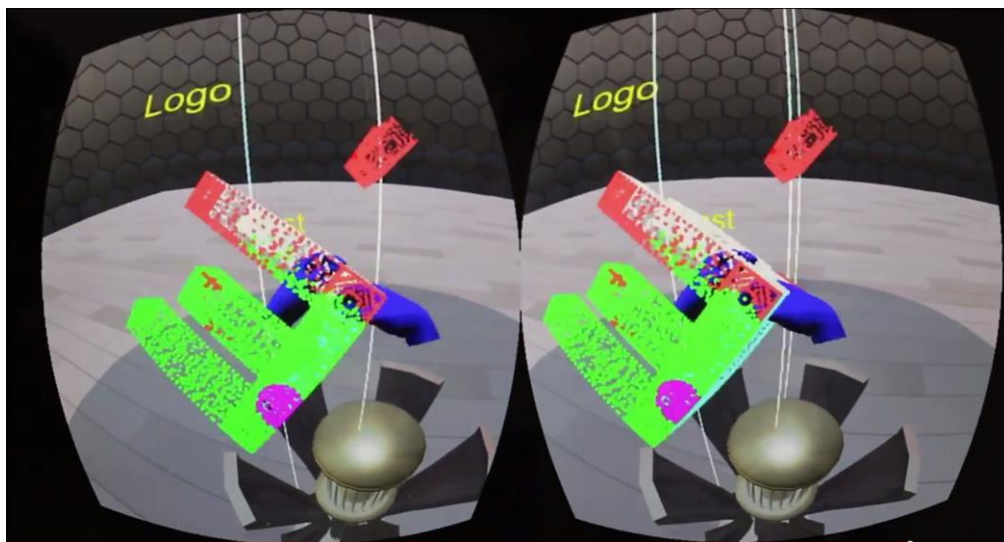


Figure 7: A screen shoot of Touching the Cloud during use. Notice how multiple colors and busy background complicate the interface

Nielsen's tenth heuristic states that the system should provide the user with a wide array of help and documentation. According to the 3DUI contest rules, each team is only required to submit a 60-120 second demo video and a short 2-page paper, with a description of the solution, details about the hardware and software used, a brief description of the closest related work and how the team's system is novel, and a description of how the team iterated upon the design. All other details are unavailable.

This analysis will now focus on how each team handles the three key interaction tasks: camera/viewpoint manipulation to obtain a reasonable view of the region of interest, text entry for the annotation, selection of the set of points to be annotated. In Slice-n-Swipe, camera control is handled by the 3D mouse. This mouse is intended to be used by the user's non-dominant hand, so to enable the user to perform the more precise task of selection with the Leap Motion Controller using his dominant hand. The mouse is type of isometric input device, meaning that it remains stationary during use (Bowman, pp. 94-95). It provides six-degree-of-freedom input, which enables camera translation and rotation in the 3D environment. Translational force causes the virtual camera to translate in the scene, while rotational force causes the camera to rotate about the center point of the 3D dataset (Bacim, Nabiyouni, & Bowman, 2014). The environment generated by the camera is presented to the user as exocentric view, meaning that user's body is external to the environment (Bowman, p. 232).

Instead of an exocentric view, Touching the Cloud's use of the Oculus Rift HMD allows the user to experience the scene from an egocentric perspective. An egocentric view means that the user experiences the scene as if he was actually inside the scene (Bowman, p. 232). This immersive experience results in an interface that is fundamentally different from Slice-n-Swipe and Go'Then'Tag. For instance, the scene camera is now attached to the position of the user's head which means the user will not need to use his hands to manipulate the camera. The user now has the ability to manipulate the point cloud through gestures. Those unfamiliar with immersive technology may find it disorienting. If

disorientation is common problem for Touching the Cloud users, then implementing wayfinding techniques could mitigate confusion.

Go'Then'Tag shifts back to the exocentric view. When a point or set of points is selected, the position and scale of the selected points are automatically calculated such that the camera can provide an adapted point of view to the current selection. The user can then finely adjust the orientation by rotating the selection around the x and y axis through sliding gestures on the touchscreen. Go'Then'Tag further improves on how the user perceives the point cloud by using a sphere-based rendering technique. The lighting and radii of the spheres that compose the point cloud can be changed be changed at any time by the user.

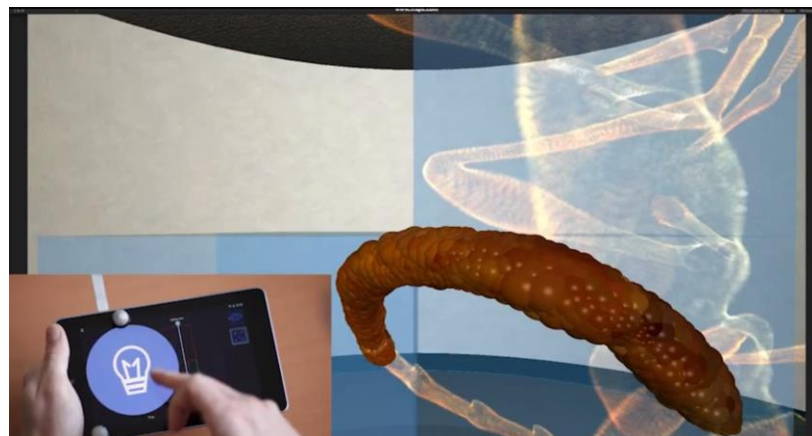


Figure 8: IN Go'Then'Tag, the user change the light on the sphere to see them better. The lighting command is indicated by the light bulb symbol.

For annotating the point cloud, each team used the method of progressive refinement. However, each team used a different method for text input and each method had benefits and drawbacks. With Slice-n-Swipe, user annotates by typing on the keyboard. The annotation appears in the 3D environment near the set of points to which it refers, and stays near those points as the user manipulates the virtual camera. The system allows as many annotations as desired, and points can have

multiple annotations. Out of all the text input methods, a keyboard is probably fast form of text input. However, Slice-n-Swipe's keyboard requires that the user remove his hands from the 3D mouse and Leap Motion's tracking area. Repeatedly switching between the keyboard and the other peripherals could quickly become tedious.

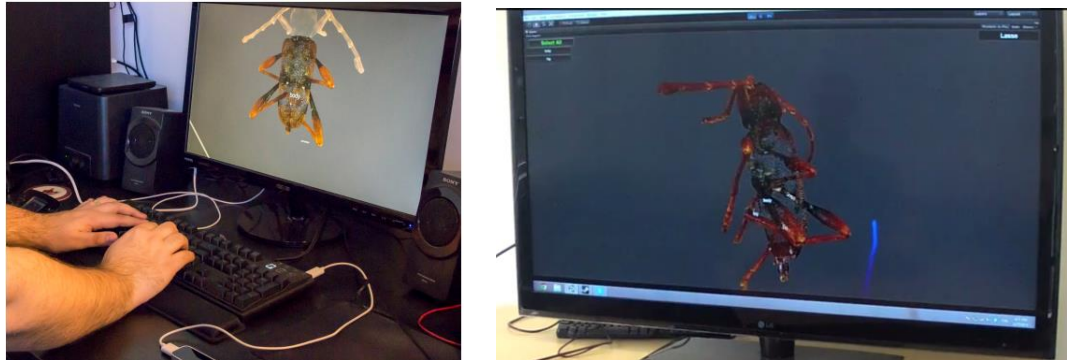


Figure 9: (left) A user performing annotation on the selected points in Slice-n-Swipe. (Right) The user viewing the label hierarchy from the toolbar on the upper left-hand side of the screen.

Since Touching the Cloud's HMD obstructs the user's view of the real world, a keyboard is not a viable option for text input. So stay in line with the theme of natural interaction, Touching the Cloud's speech recognition feature allows the user to simply say the annotation after the predefined keyword *annotate*. The user can also use enumerated annotations. Speech recognition free up the user's hands, but it is slower than a keyboard for short words, the software may need to be trained to the user's speech patterns, and requires a quiet environment.

What sets Go'Then'Tag apart from its competitors is that its interface is centered on providing the most efficient annotation, not necessarily the best selection. Even though manipulation and selection must be done in 3-D, this team recognized that annotating data sets, manipulating tags and editing text are more easily achieved using a 2-D interface. The 2-D interface runs on the multi-touch device and implements a GUI that helps the user manage the hierarchy generated from possessive refinement. There are two drawback to this method. The first is that the trackers on the multi-touch

device does not allow the user to hold the device with both hands. As a result, typing is done slowly with one hand. Second, the user must constantly switch between two screens, the multi-touch device and the 3-D stereoscopic display, which may hinder the user's focus.



Figure 10: When using Go'Then'Tag, the user can only type with one hand.

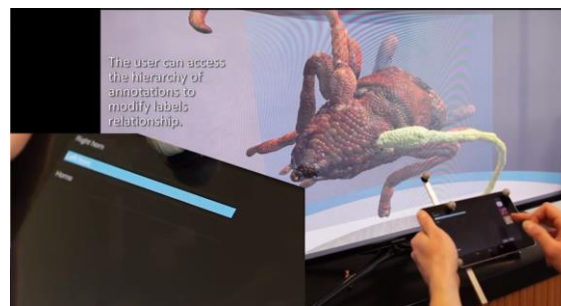


Figure 11: When using Go'Then'Tag's touchscreen GUI, the user can access the hierarchy of annotations to modify labels' relationships.

Of three key interaction tasks, selection is the most difficult and complex. The selection technique used by Slice-n-Swipe based on free-hand gestures detected by a Leap Motion device. The interface's main tool, the knife, allows users to iteratively cut the dataset (slice) and remove all unwanted points (swipe) until the desired selection is achieved. Each selection tool; knife, lasso, and bubble, utilizes a concept called hand ray casting. Hand ray casting is a unimanual technique in which the user emits a virtual ray from their finger into the environment, usually for object selection or manipulation (Bowman, p. 151). These selection tools form the foundation for Slice-n-Swipe because: 1) they do not require extreme precision; 2) they are easy to understand; 3) they avoid the specification of

parameters like shape and size; and 4) they do not require tracking of the orientation of the the hand or the position of multiple fingers.

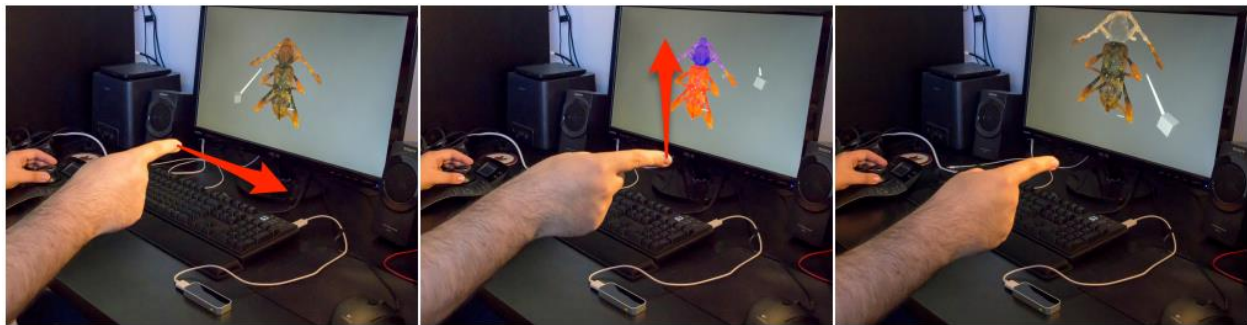


Figure 12: Three stages of the Slice-n-Swipe technique: the user prepares to slice the dataset (left); the user slices the dataset, resulting in two

Touching the Cloud improves upon the hand gesture selection approach by using virtual hand techniques. A virtual hand is a hand-shaped 3D cursor that maps to the position and orientation of the user's hand (Bowman, p. 160). This allows to interface to implement a wide array of symmetric and asymmetric bimanual tasks. For instance, point cloud rotation, scaling, and translation all implement symmetric bimanual pinch gestures.

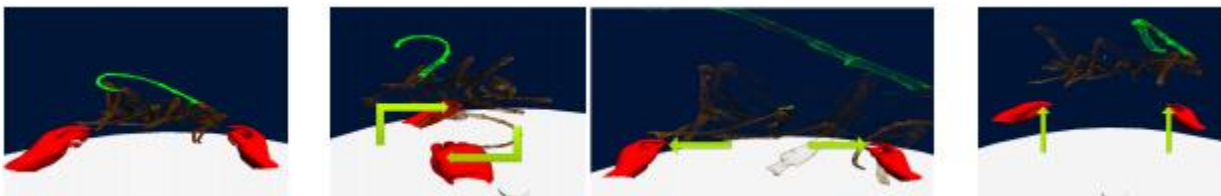


Figure 13: Supported transformations: (a) initial position, (b) rotation, (c), scaling, and (d) translation.

The user can also mark points by touching them with his fingertip given a customizable tolerance radius. Marked points can be set as selected or, should the user accidentally select too many points, they can be easily unselected, as well. Once the selection is finished, the user can finalize it and annotate it.

Unlike the other two teams, Go'Then'Tag does not have the ability to track hand gestures. Instead, all manipulation and selection is handled by the isotonic trackers attached to the multi-touch

device. Isotonic devices move with the user's body in order to measure the user's position and orientation (Bowman, p. 94). Selection is performed through a 3-D selection tool: a sphere attached to a ray controlled by the tracked device. Radius of the selection tool can be modified at will. The original point cloud is automatically divided using an octree. The user can navigate in this hierarchy. When the desired subpart is reached, only the points contained in the current node can be edited or annotated.



Figure 14: In Go'Then'Tag, the user selects successive nodes in the pre-selection to navigate through the data. Green boxes represent nodes that contains other pre-selections and red boxes represent leaves.

The final results of the contest show that Go'Then'Tag was the best interface followed by Slice-n-Swipe. Prior to starting this analysis, I was disappointed to see that Go'Then'Tag had won, mostly because it was the only team that did not use natural user interface technology. But as I reviewed the contest rules, I realized that successful annotation of the point cloud was the most important aspect of this contest. While Go'Then'Tag has the least impressive selection technique, it does have the most efficient annotation technique, because it combines 3-D and 2-D user interface designs. However, I will mention that I think the trackers on the multi-touch device might make the device difficult to hold and that Go'Then'Tag requires the user to move his body the most out of all the team I analyzed. Overall, I think each team did a great job implementing their interface. I would not say that one is better or worse than other, but there are tradeoffs can give an interface an advantage over another. The best interface would be one that incorporates the gesture metaphors of Slice-n-Swipe, the immersion of Touching the Cloud, and the annotation management of Go'Then'Tag.

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