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# **CalSciPy**

***Release 0.3.5***

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## **CONTENTS:**



## INTRODUCTION

**CalSciPy** contains a variety of useful methods for handling, processing, and visualizing calcium imaging data. It's intended to be a collection of useful, well-documented functions often used in boilerplate code alongside software packages such as [Caiman](#), [SIMA](#), and [Suite2P](#).

### 1.1 Motivation

I noticed I was often re-writing or copy/pasting a lot of code between environments when working with calcium imaging data. I started this package so I don't have to so you don't have to. No more wasting time writing 6 lines to simply preview your tiff stack, extract a particular channel, or bin some spikes. No more vague exceptions or incomplete documentation when re-using a hastily-made function from 2 months ago. Alongside these time-savers, I've also included some more non-trivial methods that are particularly useful.

### 1.2 Limitations

The current distribution for the package is incomplete and partially tested. There may be breaking changes between versions.



## INSTALLATION

### 2.1 Full Install

Enter `pip install CalSciPy` in your terminal.

### 2.2 GPU Installation

An installation of CuPy & CUDA are required for gpu-parallelized functions





## CALSCIPY.BRUKER PACKAGE

### 3.1 Subpackages

#### 3.1.1 CalSciPy.bruker.xml\_mappings package

##### Submodules

##### CalSciPy.bruker.xml\_mappings.xml\_mapping module

CalSciPy.bruker.xml\_mappings.xml\_mapping.**load\_mapping**(*version: str*) → mappingproxy

Load mapping of prairieview xml objects to their respective pyprairieview objects from .json

**Parameters**

**version** (*str*) – version of prairieview

**Returns**

read-only mapping the xml tag and python object

**Return type**

MappingProxyType

CalSciPy.bruker.xml\_mappings.xml\_mapping.**write\_mapping**(*mapping: dict, version: str*) → None

Write mapping of prairieview xml objects to their respective pyprairieview objects to .json

**Parameters**

- **mapping** (*dict*) – dictionary mapping the xml tag and python object
- **version** (*str*) – version of prairieview

**Return type**

None

## Module contents

## 3.2 Submodules

### 3.2.1 CalSciPy.bruker.configuration\_values module

### 3.2.2 CalSciPy.bruker.data module

### 3.2.3 CalSciPy.bruker.factories module

### 3.2.4 CalSciPy.bruker.meta\_objects module

**class** CalSciPy.bruker.meta\_objects.**GroupMeta**

Bases: `object`

**class** CalSciPy.bruker.meta\_objects.**PhotostimulationMeta**(*root: ElementTree, factory: object, width: int = 512, height: int = 512*)

Bases: `_BrukerMeta`

**class** CalSciPy.bruker.meta\_objects.**ROIObject**(\*args)

Bases: `object`

ROI Object

**generate\_coordinates**(*width: int, height: int*) → `Tuple[float, float]`

Converts the normalized coordinates to image coordinates

**Parameters**

- **width** (`int`) – width of image
- **height** (`int`) – height of image

**Return type**

`Tuple[float, float]`

**Returns**

x,y coordinates

**generate\_hull\_vertices**() → `Tuple[Tuple[int, int]]`

Identifies the vertices of the Convex-Hull approximation

**Return type**

`Tuple[Tuple[int, int]]`

**Returns**

vertices (Nx2)

**generate\_mask**(*width: int, height: int*) → `Tuple[Tuple[int, int]]`

Converts spiral center & radii to a coordinate mask

**Parameters**

- **width** (`int`) – width of image
- **height** (`int`) – height of image

**Return type**

`Tuple[Tuple[int, int]]`

**Returns**

coordinate mask (y, x)

**3.2.5 CalSciPy.bruker.prairie\_link module****3.2.6 CalSciPy.bruker.protocols module****3.2.7 CalSciPy.bruker.validation module****exception** CalSciPy.bruker.validation.DingusException(*message: str*)Bases: `Exception`**class** CalSciPy.bruker.validation.DingusLogger(*exceptions: List[Exception] | None = None*)Bases: `object`**add\_exception**(*other: Exception*) → CalSciPy.bruker.validation.DingusLogger**Return type**`DingusLogger`**raise\_exceptions**() → CalSciPy.bruker.validation.DingusLogger**Return type**`DingusLogger`CalSciPy.bruker.validation.**field\_validator**(*key: str, value: Any, var: dataclasses.Field*) → `List[Exception]`**Return type**`List[Exception]`CalSciPy.bruker.validation.**format\_fields**(*var: object*) → `tuple`**Return type**`tuple`CalSciPy.bruker.validation.**type\_check\_nested\_types**(*var: Any, expected: str*) → `bool`

Checks type of nested types. WORKS FOR ONLY ONE NEST.

**Parameters**

- **var** (*Any*) – variable to check
- **expected** (*str*) – expected type

**Returns**

boolean type comparison

**Return type**`bool`CalSciPy.bruker.validation.**validate\_fields**(*data\_class: object*) → `bool`**Return type**`bool`

### 3.2.8 CalSciPy.bruker.xml\_objects module

```
class CalSciPy.bruker.xml_objects.GalvoPoint(*, x: float = 0.0, y: float = 0.0, name: str = 'Point 0',
                                             index: int = 0, activity_type: str = 'MarkPoints',
                                             uncaging_laser: str = 'Uncaging',
                                             uncaging_laser_power: int = 0, duration: float = 100.0,
                                             is_spiral: bool = True, spiral_size: float = 0.0,
                                             spiral_revolutions: float = 0.0, z: float = 0.0) → None
```

Bases: `_BrukerObject`

Dataclass for a specific point during galvo-stimulation for a specific marked point in a sequence of photostimulations

#### Variables

**z** – relative z-position of the motor + ETL offset (um)

**activity\_type:** `str` = 'MarkPoints'

**duration:** `float` = 100.0

**index:** `int` = 0

**is\_spiral:** `bool` = True

**name:** `str` = 'Point 0'

**spiral\_revolutions:** `float` = 0.0

**spiral\_size:** `float` = 0.0

**uncaging\_laser:** `str` = 'Uncaging'

**uncaging\_laser\_power:** `int` = 0

**x:** `float` = 0.0

**y:** `float` = 0.0

**z:** `float` = 0.0

```
class CalSciPy.bruker.xml_objects.GalvoPointElement(*, initial_delay: int = 0, inter_point_delay: float
                                                    = 0.0, duration: float = 0, spiral_revolutions:
                                                    float = 0, all_points_at_once: bool = False,
                                                    points: str = 'Point 0', indices: int = 0) → None
```

Bases: `_BrukerObject`

Dataclass for a specific galvo-stimulation for a specific marked point in a sequence of photostimulations

**all\_points\_at\_once:** `bool` = False

`bool`: whether to do all points at once

**duration:** `float` = 0

`int`: duration of stimulation in ms

**indices:** `int` = 0

`int`: index from galvo point list

```

initial_delay: int = 0
    int: initial delay for stimulation

inter_point_delay: float = 0.0
    float: inter point delay

points: str = 'Point 0'
    str: id from galvo point list

spiral_revolutions: float = 0
    int: number of spiral revolutions

class CalSciPy.bruker.xml_objects.GalvoPointList(*, galvo_points: Tuple[object]) → None
    Bases: _BrukerObject
    Dataclass for a list of galvo points
    galvo_points: Tuple[object]

class CalSciPy.bruker.xml_objects.MarkPointElement(*, points: Tuple[object], repetitions: int = 1,
    uncaging_laser: str = 'Uncaging',
    uncaging_laser_power: int = 0,
    trigger_frequency: str = 'None', trigger_selection:
    str = 'PFI0', trigger_count: int = 0,
    async_sync_frequency: str = 'FirstRepetition',
    voltage_output_category_name: str = 'None',
    voltage_rec_category_name: str = 'Current',
    parameter_set: str = 'CurrentSettings') → None

    Bases: _BrukerObject
    Dataclass for a specific marked point in a sequence of photostimulations

    async_sync_frequency: str = 'FirstRepetition'
        str: sync

    parameter_set: str = 'CurrentSettings'
        str: id of parameter set

    points: Tuple[object]
        object: Tuple of galvo point elements

    repetitions: int = 1
        int: repetitions of this stimulation event

    trigger_count: int = 0
        int: number of triggers

    trigger_frequency: str = 'None'
        str: trigger frequency

    trigger_selection: str = 'PFI0'

    uncaging_laser: str = 'Uncaging'
        str: identity of uncaging laser

    uncaging_laser_power: int = 0
        int: uncaging laser power

```

**voltage\_output\_category\_name:** `str = 'None'`

str: name of voltage output experiment

**voltage\_rec\_category\_name:** `str = 'Current'`

str: name of voltage recording experiment

**class** CalSciPy.bruker.xml\_objects.**MarkPointSeriesElements**(\*, marks: *Tuple[object]*, iterations: *int = 1*, iteration\_delay: *float = 0.0*, calc\_funcnt\_map: *bool = False*)  $\rightarrow$  None

Bases: `_BrukerObject`

Dataclass for a sequence of photostimulations

**calc\_funcnt\_map:** `bool = False`

bool: whether to calculate functional map

**iteration\_delay:** `float = 0.0`

float: delay between each series iteration (ms)

**iterations:** `int = 1`

int: number of times this series is iterated

**marks:** `Tuple[object]`

`Tuple[object]`: series of mark point elements

**class** CalSciPy.bruker.xml\_objects.**Point**(\*, index: *int = 0*, x: *float = 0.0*, y: *float = 0.0*, is\_spiral: *bool = True*, spiral\_width: *float = 0.0*, spiral\_height: *float = 0.0*, spiral\_size\_in\_microns: *float = 0.0*)  $\rightarrow$  None

Bases: `_BrukerObject`

Dataclass for a specific point during galvo-stimulation for a specific marked point in a sequence of photostimulations

**index:** `int = 0`

str: 1-order index in galvo point list

**is\_spiral:** `bool = True`

bool: boolean indicating whether point is spiral

**spiral\_height:** `float = 0.0`

float: height of spiral

**spiral\_size\_in\_microns:** `float = 0.0`

float: size of spiral in microns

**spiral\_width:** `float = 0.0`

float: width of spiral

**x:** `float = 0.0`

float: normalized x position

**y:** `float = 0.0`

float: normalized y position

## 3.3 Module contents





## CALSCIPLY.EVENT\_PROCESSING MODULE

CalSciPy.event\_processing.**bin\_data**(*data: pandas.core.frame.DataFrame | numpy.ndarray | Iterable,*  
*bin\_length: int, fun: Callable*) → pandas.core.frame.DataFrame |  
 numpy.ndarray

### Return type

Union[DataFrame, ndarray]

CalSciPy.event\_processing.**calculate\_firing\_rates**(*spike\_probability\_matrix: numpy.ndarray,*  
*frame\_rate: float = 30.0, in\_place: bool = False*) →  
 numpy.ndarray

Calculate firing rates

### Parameters

- **spike\_probability\_matrix** (ndarray) – matrix of n neuron x m samples where each element is the probability of a spike
- **frame\_rate** (float, default: 30.0) – frame rate of dataset
- **in\_place** (bool, default: False) – boolean indicating whether to perform calculation in-place

### Return type

ndarray

### Returns

firing matrix of n neurons x m samples where each element is a binary indicating presence of spike event

CalSciPy.event\_processing.**calculate\_mean\_firing\_rates**(*firing\_matrix: numpy.ndarray*) →  
 numpy.ndarray

Calculate mean firing rate

### Parameters

**firing\_matrix** (ndarray) – matrix of n neuron x m samples where each element is either a spike or an

instantaneous firing rate

### Return type

ndarray

### Returns

1-D vector of mean firing rates

CalSciPy.event\_processing.collect\_waveforms(*traces: numpy.ndarray, event\_indices: Iterable[Iterable[int]], pre: int = 150, post: int = 450*) → Tuple[numpy.ndarray]

Collect waveforms for each event

**Parameters**

- **traces** (ndarray) – a matrix of M neurons x N samples
- **event\_indices** (Iterable[Iterable[int]]) – a list of events
- **pre** (int, default: 150) – number of pre-event frames
- **post** (int, default: 450) – number of post-event frames

**Return type**

Tuple[ndarray]

**Returns**

a matrix of M events x N samples

CalSciPy.event\_processing.convert\_tau(*tau: float, dt: float*) → float

Converts a discrete tau to a continuous tau

**Parameters**

- **tau** (float) – decay constant
- **dt** (float) – time step (s)

**Return type**

float

**Returns**

continuous tau (s)

CalSciPy.event\_processing.get\_event\_onset\_intensities(*traces: numpy.ndarray, event\_indices: Iterable[Iterable[int]]*) → Tuple[numpy.ndarray]

Retrieve the signal intensity at event onset for each neuron in the event indices

**Parameters**

- **traces** (ndarray) – An M neuron by N sample matrix
- **event\_indices** (Iterable[Iterable[int]]) – An iterable of length M containing a sequence with a duration for each event

**Return type**

Tuple[ndarray]

**Returns**

An iterable of length M neurons containing the onset intensities for each event in the sequence

CalSciPy.event\_processing.get\_inter\_event\_intervals(*event\_indices: Iterable[Iterable[int]], frame\_rate: float = 30.0*) → Tuple[numpy.ndarray]

Calculate the inter event intervals for each neuron in the event indices

**Parameters**

- **event\_indices** (Iterable[Iterable[int]]) – An iterable of length M containing a sequence with a duration for each event

- **frame\_rate** (`float`, default: 30.0) – frame\_rate for trace matrix

**Return type**`Tuple[ndarray]`**Returns**

An iterable of length M neurons containing the inter-event intervals for each event in the sequence

CalSciPy.event\_processing.get\_num\_events(event\_indices: `Iterable[Iterable[int]]`) → `numpy.ndarray`

Determines the number of events for each neuron in the event indices

**Parameters****event\_indices** (`Iterable[Iterable[int]]`) – An iterable of length M neurons containing a sequence with a duration for each event**Return type**`ndarray`**Returns**

A 1-D vector of length M neurons containing the number of events for each neuron

CalSciPy.event\_processing.identify\_events(traces: `numpy.ndarray`, timeout: `int` = 15, frame\_rate: `float` = 30.0, smooth: `bool` = True, force\_nonneg: `bool` = True) → `Tuple[List[int]]`

Identify event onset for each neuron using the smoothed, non-negative first-time derivative. The threshold for noise is considered 1/2th the standard deviation of the derivative.

**Parameters**

- **traces** (`ndarray`) – An M neuron by N sample matrix
- **timeout** (`int`, default: 15) – timeout distance for peak finding (frames)
- **frame\_rate** (`float`, default: 30.0) – frame rate / time step for trace matrix
- **smooth** (`bool`, default: True) – boolean indicating whether to smooth first-time derivative
- **force\_nonneg** (`bool`, default: True) – boolean indicating whether to enforce non-negativity constraint on first-time derivative

**Return type**`Tuple[List[int]]`**Returns**

An iterable where each element contains a sequence of frames identified as event onsets

CalSciPy.event\_processing.normalize\_firing\_rates(firing\_matrix: `numpy.ndarray`, in\_place: `bool` = False) → `numpy.ndarray`

Normalize firing rates by scaling to a max of 1.0. Non-negativity constrained.

**Parameters**

- **firing\_matrix** (`ndarray`) – matrix of n neuron x m samples where each element is either a spike or an instantaneous firing rate
- **in\_place** (`bool`, default: False) – boolean indicating whether to perform calculation in-place

**Return type**`ndarray`**Returns**

normalized firing rate matrix of n neurons x m samples

```
CalSciPy.event_processing.scale_waveforms(waveforms: typing.Iterable[numpy.ndarray], scaler:
                                         typing.Callable = <class
                                         'sklearn.preprocessing._data.StandardScaler'>) →
                                         numpy.ndarray
```

Scale waveforms for cross-neuron comparisons

**Parameters**

- **waveforms** (`Iterable[numpy.ndarray]`) – An Iterable of M events by N samples matrices of waveforms
- **scaler** (`Callable`, default: `<class 'sklearn.preprocessing._data.StandardScaler'>`) – sklearn preprocessing object

**Return type**

`numpy.ndarray`

**Returns**

An Iterable of M event by N samples scaled matrices of waveforms

## CALSCIPLY.IMAGE\_PROCESSING MODULE

`CalSciPy.image_processing.gaussian_filter`(*images: np.ndarray, sigma: Number | np.ndarry = 1.0, block\_size: int = None, block\_buffer: int = 0, in\_place: bool = False*) → `np.ndarray`

GPU-parallelized multidimensional gaussian filter. Optional arguments for in-place calculation. Can be calculated blockwise with overlapping or non-overlapping blocks.

Designed for use on arrays larger than the available memory capacity.

Footprint is of the form `np.ones((frames, y pixels, x pixels))` with the origin in the center

### Parameters

- **images** – images stack to be filtered
- **sigma** (default: 1.0) – sigma for gaussian filter
- **block\_size** (default: None) – the size of each block. Must fit within memory
- **block\_buffer** (default: 0) – the size of the overlapping region between block
- **in\_place** (default: False) – whether to calculate in-place

### Returns

`images`: numpy array (frames, y pixels, x pixels)

`CalSciPy.image_processing.median_filter`(*images: numpy.ndarray, mask: numpy.ndarray = array([[1., 1., 1.], [1., 1., 1.], [1., 1., 1.]], dtype=float), block\_size: int | None = None, block\_buffer: int = 0, in\_place: bool = False*) → `numpy.ndarray`

GPU-parallelized multidimensional median filter. Optional arguments for in-place calculation. Can be calculated blockwise with overlapping or non-overlapping blocks.

Designed for use on arrays larger than the available memory capacity.

Footprint is of the form `np.ones((frames, y pixels, x pixels))` with the origin in the center

### Parameters

- **images** (`ndarray`) – images stack to be filtered
- **mask** (`ndarray`, default: `[[1., 1., 1.], [1., 1., 1.], [1., 1., 1.]], dtype=float`) – mask of the median filter
- **block\_size** (`Optional[int]`, default: None) – the size of each block. Must fit within memory

- **block\_buffer** (`int`, default: 0) – the size of the overlapping region between block
- **in\_place** (`bool`, default: False) – whether to calculate in-place

**Return type**

`ndarray`

**Returns**

images: numpy array (frames, y pixels, x pixels)

## CALSCIPLY.INTERACTIVE\_VISUALS MODULE

CalSciPy.interactive\_visuals.**plot\_spikes**(*spike\_prob*: *numpy.ndarray* | *None* = *None*, *spike\_times*: *numpy.ndarray* | *None* = *None*, *traces*: *numpy.ndarray* | *None* = *None*, *frame\_rate*: *float* | *None* = *None*, *y\_label*: *str* = 'f/f0') → *None*

Function to interactively visualize spike inference

### Parameters

- **spike\_prob** (*Optional*[*ndarray*], default: *None*) –
- **spike\_times** (*Optional*[*ndarray*], default: *None*) –
- **traces** (*Optional*[*ndarray*], default: *None*) –
- **frame\_rate** (*Optional*[*float*], default: *None*) –
- **y\_label** (*str*, default: 'f/f0') –

### Return type

*None*

CalSciPy.interactive\_visuals.**plot\_traces**(*traces*: *numpy.ndarray*, *frame\_rate*: *float* | *None* = *None*, *y\_label*: *str* = 'f/f0', *mode*: *str* = 'overlay') → *None*

### Parameters

- **traces** (*ndarray*) –
- **frame\_rate** (*Optional*[*float*], default: *None*) –
- **y\_label** (*str*, default: 'f/f0') –
- **mode** (*str*, default: 'overlay') –

### Return type

*None*

### Returns

CalSciPy.interactive\_visuals.**plot\_trials**(*data*: *numpy.ndarray*, *trials*: *numpy.ndarray*, *trial\_conditions*: *None*, *bin\_duration*: *float* | *None* = *None*, *y\_label*: *str* = 'Firing Rate (Hz)') → *None*

### Parameters

- **data** (*ndarray*) –
- **trials** (*ndarray*) –
- **trial\_conditions** (*None*) –

- **bin\_duration** (`Optional[float]`, default: `None`) –
- **y\_label** (`str`, default: `'Firing Rate (Hz)'`) –

**Return type**

`None`

**Returns**



## CALSCIPLY.IO\_TOOLS MODULE

`CalSciPy.io_tools.load_binary(path: str | pathlib.Path, mapped: bool = False, mode: str = 'r+', missing_metadata: Mapping | None = None) → numpy.ndarray | numpy.memmap`

This function loads images saved in language-agnostic binary format. Ideal for optimal read/write speeds and highly-robust to corruption. However, the downside is that the images and their metadata are split into two separate files. Images are saved with the *.bin* extension, while metadata is saved with extension *.json*. If for some reason you lose the metadata, you can still load the binary if you know three of the following: number of frames, y-pixels, x-pixels, and the datatype (`numpy.dtype`)

### Parameters

- **path** (`Union[str, Path]`) – folder containing binary file
- **mapped** (`bool`, default: `False`) – boolean indicating whether to load image using memory-mapping
- **mode** (`str`, default: `'r+'`) – indicates the level of access permitted to the original binary
- **missing\_metadata** (`Optional[Mapping]`, default: `None`) – if you have lost the metadata or otherwise wish to manually provide it

### Return type

`Union[ndarray, memmap]`

### Returns

image (frames, y-pixels, x-pixels)

`CalSciPy.io_tools.load_images(path: str | pathlib.Path) → numpy.ndarray`

Load images into a numpy array. If path is a folder, all *.tif* files found non-recursively in the directory will be compiled to a single array.

### Parameters

**path** (`Union[str, Path]`) – a file containing images or a folder containing several imaging stacks

### Return type

`ndarray`

### Returns

numpy array (frames, y-pixels, x-pixels)

`CalSciPy.io_tools.save_binary(path: str | pathlib.Path, images: numpy.ndarray, name: str = 'binary_video') → int`

Save images to language-agnostic binary format. Ideal for optimal read/write speeds and highly-robust to corruption. However, the downside is that the images and their metadata are split into two separate files. Images are saved with the *.bin* extension, while metadata is saved with extension *.json*. If for some reason you lose the metadata, you can still load the binary if you know three of the following: number of frames, y-pixels, x-pixels, and the

datatype. The datatype is almost always unsigned 16-bit (`numpy.uint16`) for all modern imaging systems—even if they are collected at 12 or 13-bit.

**Parameters**

**path** (`Union[str, Path]`) – path to save images to. The path stem is considered the filename if it doesn't have any extension. If

no filename is provided then the default filename is *binary\_video*.

**Parameters**

- **images** (`ndarray`) – images to save (frames, y-pixels, x-pixels)
- **name** (`str`, default: 'binary\_video') – specify filename for produced files

**Return type**

`int`

**Returns**

0 if successful

`CalSciPy.io_tools.save_images(path: str | pathlib.Path, images: numpy.ndarray, name: str = 'images', size_cap: float = 3.9) → int`

Save a numpy array to a single .tif file. If size > 4GB then saved as a series of files. If path is not a file and already exists the default filename will be *images*.

**Parameters**

- **path** (`Union[str, Path]`) – filename or absolute path
- **images** (`ndarray`) – numpy array (frames, y pixels, x pixels)
- **name** (`str`, default: 'images') – filename for saving images
- **size\_cap** (`float`, default: 3.9) – maximum size per file

**Return type**

`int`

**Returns**

returns 0 if successful

## CALSCIPY.MISC MODULE

**class** CalSciPy.misc.**PatternMatching**(*value: Any, comparison\_expressions: Iterable[Any]*)

Bases: `object`

CalSciPy.misc.**calculate\_frames\_per\_file**(*y\_pixels: int, x\_pixels: int, bit\_depth: numpy.dtype = <class 'numpy.uint16'>, size\_cap: numbers.Number = 3.9*) → `int`

Estimates the number of image frames to allocate to each file given some maximum size.

### Parameters

- **y\_pixels** (`int`) – number of y\_pixels in image
- **x\_pixels** (`int`) – number of x\_pixels in image
- **bit\_depth** (`dtype`, default: `<class 'numpy.uint16'>`) – bit-depth / type of image elements
- **size\_cap** (`Number`, default: 3.9) – maximum file size

### Return type

`int`

### Returns

the maximum number of frames to allocate for each file

CalSciPy.misc.**generate\_blocks**(*sequence: Iterable, block\_size: int, block\_buffer: int = 0*) → `Iterator`

Returns a generator of some arbitrary iterable sequence that yields m blocks with overlapping regions of size n

### Parameters

- **sequence** (`Iterable`) – Sequence to be split into overlapping blocks
- **block\_size** (`int`) – size of blocks
- **block\_buffer** (`int`, default: 0) – size of overlap between blocks

### Return type

`Iterator`

### Returns

generator yielding m blocks with overlapping regions of size n

CalSciPy.misc.**generate\_overlapping\_blocks**(*sequence: Iterable, block\_size: int, block\_buffer: int*) → `Iterator`

Returns a generator of some arbitrary iterable sequence that yields m blocks with overlapping regions of size n

### Parameters

- **sequence** (`Iterable`) – Sequence to be split into overlapping blocks

- **block\_size** (`int`) – size of blocks
- **block\_buffer** (`int`) – size of overlap between blocks

**Return type**`Iterator`**Returns**

generator yielding `m` blocks with overlapping regions of size `n`

`CalSciPy.misc.generate_padded_filename(output_folder: pathlib.Path, index: int, base: str = 'images', digits: int = 2, ext: str = '.tif') → pathlib.Path`

Generates a `pathlib.Path` whose name is defined as ‘{base}\_{index}{ext}’ where `index` is zero-padded if it is not equal to the number of digits

**Parameters**

- **output\_folder** (`Path`) – folder that will contain file
- **index** (`int`) – index of file
- **base** (`str`, default: 'images') – base tag of file
- **digits** (`int`, default: 2) – number of digits for representing index
- **ext** (`str`, default: '.tif') – file extension

**Return type**`Path`**Returns**

generated filename

`CalSciPy.misc.generate_sliding_window(sequence: Iterable, window_length: int, step_size: int = 1) → numpy.ndarray`

**Return type**`ndarray`

`CalSciPy.misc.generate_time_vector(num_samples: int, sampling_frequency: numbers.Number = 30.0, start: numbers.Number = 0.0, step: numbers.Number | None = None) → numpy.ndarray`

Generates a time vector for a number of samples collected at either

**Parameters**

- **num\_samples** (`int`) –
- **sampling\_frequency** (`Number`, default: 30.0) –
- **start** (`Number`, default: 0.0) –
- **step** (`Optional[Number]`, default: `None`) –

**Return type**`ndarray`**Returns**

`CalSciPy.misc.sliding_window(sequence: numpy.ndarray, window_length: int, function: Callable, *args, **kwargs) → numpy.ndarray`

**Return type**`ndarray`

CalSciPy.misc.**wrap\_cupy\_block**(*copy\_function*: *Callable*) → *Callable*

Wraps a cupy function such that incoming numpy arrays are converting to cupy arrays and swapped back on return

**Parameters**

**copy\_function** (*Callable*) – any cupy function that accepts numpy arrays

**Return type**

*Callable*

**Returns**

wrapped function

CalSciPy.misc.**zero\_pad\_num\_to\_string**(*idx*: *int*, *num\_zeros*: *int*) → *str*

**Return type**

*str*



## CALSCIPLY.REORGANIZATION MODULE

`CalSciPy.reorganization.generate_raster(event_frames: Iterable[Iterable[int]], total_frames: int | None = None) → numpy.ndarray`

Generate raster from an iterable of iterables containing the spike or event times for each neuron

### Parameters

- **event\_frames** (*Iterable[Iterable[int]]*) – iterable containing an iterable identifying the event frames for each neuron
- **total\_frames** (*Optional[int]*, default: *None*) – total number of frames

### Return type

*ndarray*

### Returns

event matrix of neurons x total frames

`CalSciPy.reorganization.generate_tensor(traces_as_matrix: numpy.ndarray, chunk_size: int) → numpy.ndarray`

Generates a tensor given chunk / trial indices

### Parameters

- **traces\_as\_matrix** (*ndarray*) – traces in matrix form (neurons x frames)
- **chunk\_size** (*int*) – size of each chunk

### Return type

*ndarray*

### Returns

traces as a tensor of trial x neurons x frames

`CalSciPy.reorganization.merge_factorized_matrices(factorized_traces: numpy.ndarray, components: int | Iterable[int] = 0) → numpy.ndarray`

Concatenate a neuron x chunk or trial array in which each element is a component x frame factorization of the original trace:

### Parameters

- **factorized\_traces** (*ndarray*) – neurons x chunks (trial, tif, etc) containing the neuron's trace factorized into several components
- **components** (*Union[int, Iterable[int]]*, default: 0) – specific component to extract

### Return type

*ndarray*

**Returns**

traces of specific component in matrix form

`CalSciPy.reorganization.merge_tensor(traces_as_tensor: numpy.ndarray) → numpy.ndarray`

Concatenate multiple trials or tiffs into single matrix:

**Parameters**

**traces\_as\_tensor** (*ndarray*) – chunk (trial, tif, etc) x neurons x frames

**Return type**

*ndarray*

**Returns**

traces in matrix form (neurons x frames)



## CALSCIPLY.TRACE\_PROCESSING MODULE

CalSciPy.trace\_processing.calculate\_dfof(traces: *numpy.ndarray*, frame\_rate: *float* = 30.0, in\_place: *bool* = False, offset: *float* = 0.0, external\_reference: *numpy.ndarray* | *None* = None, method: *str* = 'baseline') → *numpy.ndarray*

**Return type***numpy.ndarray*

CalSciPy.trace\_processing.calculate\_standardized\_noise(fold\_fluorescence\_over\_baseline: *numpy.ndarray*, frame\_rate: *float* = 30.0) → *numpy.ndarray*

Calculates a frame-rate independent standardized noise as defined as:

$$v = \frac{\sigma_{\frac{\Delta F}{F}}}{\sqrt{f}}$$

It is robust against outliers and approximates the standard deviation of  $f/f_0$  baseline fluctuations. For comparison, the more exquisite of the Allen Brain Institute's public datasets are approximately  $1\% \text{Hz}^{(-1/2)}$

**Parameters**

- **fold\_fluorescence\_over\_baseline** (*numpy.ndarray*) – fold fluorescence over baseline (i.e.,  $f/f_0$ )
- **frame\_rate** (*float*, default: 30.0) – frame rate of dataset

**Return type***numpy.ndarray***Returns**

standardized noise (units are  $1\% \text{Hz}^{(-1/2)}$ ) for each neuron

CalSciPy.trace\_processing.detrend\_polynomial(traces: *numpy.ndarray*, in\_place: *bool* = False) → *numpy.ndarray*

Detrend traces using a fourth-order polynomial

**Parameters**

- **traces** (*numpy.ndarray*) – matrix of traces in the form of neurons x frames
- **in\_place** (*bool*, default: False) – boolean indicating whether to perform calculation in-place

**Return type***numpy.ndarray*

**Returns**

detrended traces

CalSciPy.trace\_processing.perona\_malik\_diffusion(traces: *numpy.ndarray*, *iters*: *int* = 25, *kappa*: *float* = 0.15, *gamma*: *float* = 0.25, *sigma*: *float* = 0, *in\_place*: *bool* = False) → *numpy.ndarray*

Edge-preserving smoothing using perona malik diffusion. This is a non-linear smoothing technique that avoids the temporal distortion introduced onto traces by standard gaussian smoothing.

The parameter *kappa* controls the level of smoothing (“diffusion”) as a function of the derivative of the trace (or “gradient” in the case of 2D images where this algorithm is often used). This function is known as the diffusion coefficient. When the derivative for some portion of the trace is low, the algorithm will encourage smoothing to reduce noise. If the derivative is large like during a burst of activity, the algorithm will discourage smoothing to maintain its structure. Here, the argument *kappa* is multiplied by the dynamic range to generate the true kappa.

The diffusion coefficient implemented here is  $e^{-(\text{derivative}/\text{kappa})^2}$ .

Perona-Malik diffusion is an iterative process. The parameter *gamma* controls the rate of diffusion, while parameter *iters* sets the number of iterations to perform.

This implementation is currently situated to handle 1-D vectors because it gives us some performance benefits.

**Parameters**

- **traces** (*ndarray*) – matrix of M neurons by N samples
- **iters** (*int*, default: 25) – number of iterations
- **kappa** (*float*, default: 0.15) – used to calculate the true kappa, where true kappa = kappa \* dynamic range. range 0-1
- **gamma** (*float*, default: 0.25) – rate of diffusion for each iter. range 0-1
- **in\_place** (*bool*, default: False) – whether to calculate in-place

**Return type***ndarray***Returns**

smoothed traces

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