



EventGenerators

*Master Thesis in Physics and Astronomy*

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Gothenburg, Sweden 2015



# EventGenerators

MASTER'S THESIS

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Gothenburg, Sweden 2015

EventGenerators  
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FUFX03 - Master's thesis at Fundamental Physics  
Master's Thesis No. FUFX03-15-??

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Printed by Chalmers Reproservice  
Göteborg, Sweden 2015

**Cover:** Describe the cover picture

## **Abstract**

This thesis describes...

## **Sammandrag**

Denna tes beskriver...

# Acknowledgements

Thanks to Heinz!

Stefan Buller, Gothenburg, May 2015

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# 1. Introduction



## 2. Theoretical Background

### 2.1. Nuclear Collisions

From a macroscopic perspective, nuclei can be viewed as charged particles, and thus collisions (here in a loose sense) between them is essentially governed by the Rutherford scattering formula. This is how the nucleus was discovered in the first place. However, this simple picture breaks down at higher energies, when the de Broglie wave-length ( $\lambda \sim p^{-1}$ ) becomes sufficiently small to resolve the inner structure of the nuclei. At even higher energies, it becomes feasible to model the collision as not taking place between the two nuclei, but by individual protons and neutrons (nucleons).

This leads us to the *participant-spectator* picture of nuclear collisions, in which the collision is viewed as if taking place between a few *participant* nucleons, while the remaining *spectator* nucleons remain mostly unaffected. Such a reaction is known as *quasi-elastic scattering*, since the kinetic energy of the projectile will be much greater than the binding energy of the participants, which further motivates treating them as approximately free particles, and means that the kinetic energy will almost be conserved, hence *quasi-elastic*. !!!POSSIBLY DISCUSS LIMITATIONS!!! The collision between the participant nucleons takes place at a time scale of about  $10^{-23}$  s [1], and is sometimes called a *fireball* or *firestreak*.

However, this is just the first part of the collision. The participant nucleons may have gone unaffected through it, but the resulting system (a so-called pre-fragment) will be highly excited, and will decay to the actual fragment—often by ejecting nucleons, in this context known as evaporating them. The characteristic time-scale for these ejections vary between  $10^{-21} - 10^{-16}$  s, depending on the energies and emitted particle [1].

In this picture, we thus have a two-step process to describe nuclear fragmentation. Various models to describe both steps exist in the literature, which can be combined more or less freely—they do not necessarily use the same parameters to describe the nuclei. Models which mainly use parameters like  $A$ , the number of nucleons,  $Z$  the number of protons, the total nuclear-spin  $J$  and the excitation energy  $E$  of the nucleus are termed *macroscopic*, while models that directly treat the states of individual nucleons are called *microscopic*. Examples of the former are the *abrasion-ablation model* [2], while the *intranuclear-cascade model* [3] is an example of a microscopic model. As is often the case in nuclear physics, no one model is valid of all range of nucleon number  $A$  and incident energies [4].

Since the focus on this report is to describe an event-generator for a physics experiment, we do not need a state of the art model (see !!!AUTOREF TO SECTION!!! for the arguments). Since the macroscopic properties of nuclei are more easily related to experimental observables, we will restrict our attention to those.

### 2.1.1. The fast processes—the Goldhaber model

To mimic existing code !!!CITE LEONID?!!! and to allow the user to study a reaction of their interest, the outcome of the first stage of the process is largely determined by user input: the participant projectile nucleons—the cluster—as well as its invariant mass, and the excitation energy of the pre-fragment are both specified by user input. The only specific model used is to determine the momentum of the participant system relative to the projectile, everything else is just conservation of momentum, and an isotropic cross-section. The *Goldhaber model* states that the momentum distribution is given by a Gaussian with the width determined by the expectation value of the momentum of an individual nucleon, explicitly

$$\sigma^2 = \langle \mathbf{p}^2 \rangle A \frac{A_p - A}{A_p - 1}, \quad (2.1)$$

where  $A_p$  is the number of nucleons in the projectile,  $A$  in the pre-fragment, and  $\langle \mathbf{p}^2 \rangle$  is the expectation value of the momentum of an individual nucleon. For a Fermi-gas,  $\langle \mathbf{p}^2 \rangle$  may be written in terms of the Fermi-momentum  $\mathbf{p}_f$  as  $\frac{3}{5}\mathbf{p}_f^2$  [5]. !!!THIS IS NOT THE MODEL USED IN LEONID CODE!!!

!!!LEONID USES

$$\sigma^2 = 2(M + m - M_p) \frac{mM}{m + M} = 2Q\mu(m, M),$$

where  $m$  is the mass of the participant,  $M_p$  the mass of the projectile and  $M$  the mass of the pre-fragment. If we take  $Q = T = mv^2/2$ , we get  $\sigma^2 = m^2v^2$ , which could imply that this is just the Fermi-momentum? !!!

Momentum conservation implies that

$$p_p = p_i + q_{pf} \quad (2.2)$$

$$p_i + p_t = q_i + q_t \quad (2.3)$$

where  $p_p$  is the 4-momentum of the projectile,  $p_t$  the momentum of the target,  $p_i$  the internal momentum of the cluster;  $q_{pf}$  the final momentum of the pre-fragment  $q_i$  and  $q_t$  the final momentum of the target and cluster, respectively.

Solving the above equation and squaring for  $p_i$  and squaring gives an expression for the invariant mass of the cluster as

$$p_i^2 = p_p^2 + q_{pf}^2 - p_p \cdot q_{pf} = m_i^2 = M_p^2 + M_{pf}^2 - M_p \sqrt{M_{pf}^2 + \mathbf{p}_i^2}, \quad (2.4)$$

where we have evaluated  $p_p \cdot q_{pf}$  in the rest-frame of the pre-fragment.

## 2.2. The slow process—decay of a compound nucleus

## 3. The Code

The CODEZ code, based on CODEX [6], contains models for the various quantities needed in statistical models. It is written to be easily extendable and to a large extent modular, so that the various models can easily be replaced. Details on the specific models may be found in the corresponding sections below. To achieve this modularity, the code is written in C++ and makes use of *object-oriented* programming concepts.

The program is roughly structured as follows: Decay processes are specified by model objects, which contain models for calculating transition probabilities to possible final states. “Probabilities” here refers to  $d^2P_\nu/dtdE$ , roughly the probability to decay to a final state in energy interval  $dE$  during the time  $dt$  by the process  $\nu$ . The probabilities need not be normalized. The model objects implement a function that for a given energy discretization tabulates specific information about the decay, along with the corresponding cumulative probability. A complete table of transition probabilities and final states is generated by looping over all model objects.

A de-excitation step may then be performed by drawing a random number between 0 and the final cumulative probability, and looking up the corresponding decay in the table. Several one-step decays may thus be performed with little extra computational costs, which is valuable when verifying models.

### 3.0.1. Transition Probabilities

The transition probability  $d^2P_\nu/dtdE$  from an initial state  $i$  to a final state  $f$  by the process  $\nu$  is roughly given by

$$R \equiv \frac{d^2P_\nu}{dtdE} = \sum_j \frac{\rho_f}{\rho_i} T_{\nu,j}(E_i, E_f). \quad (3.1)$$

Here,  $\rho$  is the nuclear level density for the initial and final states,  $T_{\nu,j}(E_i, E_f)$  the transmission coefficient, with  $j$  being a collective index describing the different ways a process may carry the nucleus from  $i$  to  $f$ .

# Glossary

**intro** an introduction, page 1

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## A. Appendix 1

## B. Code

```
struct spec_POS_t
{
    SPEC_FLOAT(_dx,          2.5, "cm", "full_width_x_of_active_volume")
    ;
    SPEC_FLOAT(_dy,          2.5, "cm", "full_width_y_of_active_volume")
    ;
    SPEC_FLOAT(_dz,          0.03, "cm", "full_width_z_of_active_volume");
    SPEC_FLOAT(_lgheight,    2, "cm", "lightguide_height_over_active_
        volume");
    SPEC_FLOAT(_lgheadd,     0.70, "cm", "size_of_square-shaped_lightguide-
        heads");
    SPEC_MEDIA(_type,        "plastic", "", "POS_active_volume_material.");
    SPEC_MEDIA(_lgtype,     "plastic", "", "Lightguide_material");
};
```

```
#include "auto_gen/spec_info_pos.hh"
```

```
#define UNUSED_PARAM(x)
```

This function is called when GGLAND creates the detector.

```
gg_geom_obj *make_POS(void *vspec, uint32_t UNUSED_PARAM(mask_set)
, const transform_matrix *loc_rot
, det_name_no_info *name_no)
{
```

## C. Svenska här