# Lecture 19 Linear Temporal Logic (LTL)

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#### **This Lecture**

- Linear Temporal Logic
  - > safety & liveness review
  - > basic temporal logic (always, eventually, next)
  - > examples and common patterns

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#### **Recall: Safety versus Liveness**

- As we have noted, sometimes a distinction is made between safety and liveness properties of a model
  - > safety: a property that guarantees that no system invariant is violated
  - > liveness: a property that guarantees that something useful actually happens
- Thus far we have mostly concentrated on safety properties

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**All Behaviors** 

**Desired Behaviors** 

# **Safety**

#### **Safety:** "nothing bad happens"

- > This is usually phrased as an invariant of the system representing "good" states
  - » Then we show that each initial state is a good state, and that every transition takes us from a good state to another good state.
- > Notations like Z are particularly well-suited to this kind of property
- Note: a system that does nothing usually satisfies its safety properties
- > Examples
  - » the # of candies is never more than the # coins
  - » dom birthday = names
  - » no two threads can execute the same critical code at the same time

#### Liveness

#### **Liveness**: "something good happens"

- > Usually phrased as promise of an eventual outcome
  - » Then we must show that every/some trace of the system leads to desired state
- Note: these are statements about what a system will do over time
- > A stopped system will, in general, not satisfy these conditions
- > Examples
  - » the system will eventually halt
  - » whenever a happens b will eventually follow
  - » a system is in the ready state infinitely often
  - » if a certain transition is enabled, it will eventually occur

## **Temporal Logics**

- A "Temporal Logic" characterizes the behavior of systems by specifying some property about system traces
- We have already seen such specifications in FSP
- Examples

```
property PROP = (req -> reply -> PROP).
```

Guarantees that requests and replies strictly alternate

```
progress {heads}
```

Guarantees that the "heads" event happens infinitely often

## **Temporal Logics**

#### But now a couple of things will be different

1. We focus on state-based traces

 $\langle s_1, s_2, ..., s_{n,...} \rangle$ , where  $s_i$  is a state of the system, and traces start with index 1

- 2. We consider all traces to be infinite for finite traces, the final state is simply repeated
- 3. We then introduce new notation to express common kinds of properties about these traces such as
  - » Some property always holds
  - » Some property will eventually hold
  - » Some property always follows after another property becomes true
  - » Some property is true infinitely often

# (Linear) Temporal Logic: Syntax

```
tempformula =
   predicate
   l "∼", tempformula
   | "(", tempformula, "∨", tempformula, ")"
   | "(", tempformula, "∧", tempformula, ")"
   l "(", tempformula, "⇒", tempformula, ")"
   | "(", tempformula, "⇔", tempformula, ")"
   I "□", tempformula
   l "♦", tempformula
                                         Note: No
   tempformula, "U", tempformula
                                         Quantification
   tempformula, "Uw", tempformula
                                         over temporal
                                        formulae
   "o", tempformula;
```

# (Linear) Temporal Logic: Semantics

- Temporal formulae are interpreted over traces.
- Let  $\sigma = \langle s_1, s_2, ..., s_i, ... \rangle$  be a (state-based) trace, and P be a temporal logic formula
- We write
   (σ, i) ⊨ P and say "P holds in the i<sup>th</sup> state of trace σ".
- When we write just P, we will mean that P holds in the <u>first</u> state of the sequence σ
   that is, P is the same as (σ,1) ⊨ P

# Temporal Operators: Semantic Intuition

- □ P "always": P holds in every state of a trace.
- P "eventually": P holds in at least one state of a trace.
- OP "next": P holds in the next state in a trace.
- P U Q— "until": P holds until Q becomes true

## **Temporal Operators (always)**

- - > Pronounced "box", "henceforth", "always", "from now on", "forever"

When we write just 

 P, we will mean

 P holds for all states in the trace starting at
 i = 1

That is,  $\Box$  P is the same as  $(\sigma, 1) \models \Box$  P

# **Temporal Operators (eventually)**

- ◊
  - > Pronounced "diamond", "eventually", "sometime"

means 
$$(\sigma, i) \models \Diamond P$$
  
 $\exists j: i... \bullet (\sigma, j) \models P$ 

 When we write just ◊P, we will mean starting at i = 1, there is some state in the trace for which P holds

That is,  $\lozenge P$  is the same as  $(\sigma, 1) \models \lozenge P$ 

## **Note on Operators**

- Note that we have just introduced a new way to define predicates
  - > The difference is that the predicates are applied to traces: i.e., to sequences of states (not to individual states)
- Operators such as □ and ◊ are sometimes called "modalities"
  - > they are similar to existential and universal "quantifiers" in "quantified expressions" for FOPL
- A predicate of the form OP is called an "eventuality"

#### **Precedence Rules**

- □ and ◊ bind tighter than other logical operators
- So if we want to say that the predicate
   P ⇒ Q is true in every state, we would
   write □ (P ⇒ Q)
- In contrast, □ P ⇒ Q means (□ P) ⇒ Q,
   which as a very different meaning
  - > We'll see what that is in a few slides

#### Formally Defining ⊨

(σ, i) ⊨ P ⇔ P(σ (i)) is true
 provided P contains no modalities
 (i.e., P is a FOPL predicate, may include quantifiers)

$$(\sigma, i) \models P \lor Q \Leftrightarrow (\sigma, i) \models P \lor (\sigma, i) \models Q$$
  
 $(\sigma, i) \models P \Rightarrow Q \Leftrightarrow (\sigma, i) \models P \Rightarrow (\sigma, i) \models Q$   
other operators  $(\sim, \land, \text{ etc.})$  are similar

$$(\sigma, i) \models \Box P \Leftrightarrow \forall j: i... \bullet (\sigma, j) \models P$$
  
 $(\sigma, i) \models \Diamond P \Leftrightarrow \exists j: i... \bullet (\sigma, j) \models P$ 

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## **Example**

- Suppose we our state consists of two values: x, y: Z
- Consider the following two predicates:

$$P(x,y) == x > 0 \text{ and } Q(x,y) == x > y$$

- Let  $\sigma == <(-1,0), (0,1), (1,2), (2,3), ... >$ (increments both x and y)
- Which of the following are true of  $\sigma$ ?
  - 1. P

- 2. Q
- 3. 🗆 P

4. ♦ P

- 5. ♦ P
- 6.  $P \wedge Q$  7.  $\square (P \wedge Q)$  8.  $\square P \wedge Q$
- 9.  $\square P \vee Q$  10.  $\sim \square P$  10.  $P \Rightarrow Q$
- 11.  $\square$  (P  $\Rightarrow$  Q)

## **Examples using Box**

```
• \Box (x > 0)
    an invariant of the model
• \Box ( ~ ( in_crit(p<sub>1</sub>) \land in_crit(p<sub>2</sub>) ) )
    mutual exclusion
• (\sigma, 2) \models \sim at(init)
• (\sigma, 2) \models \Box (\sim at(init))
• (\sigma, 2) \models \neg \Box (at(init))
                                                       Is this really
                                                     what we want?
• at(halt) \Rightarrow \Box ( at(halt) )
• \square (P \Rightarrow \square P)
    once P, always P
```

#### **Nested Modalities**

```
at(halt) \Rightarrow \Box at(halt)
   = (\sigma, 1) \models at(halt) \Rightarrow \Box at(halt)
   = (\sigma, 1) \models at(halt) \Rightarrow (\sigma, 1) \models \Box at(halt)
   = (\sigma, 1) \models at(halt) \Rightarrow \forall j: 1... \bullet (\sigma, j) \models at(halt)
Compare this to
\square (at(halt) \Rightarrow \square at(halt))
   = (\sigma, 1) \models \Box (at(halt) \Rightarrow \Box at(halt)
   = \forall i: 1... \bullet (\sigma, i) \models (at(halt)) \Rightarrow \Box at(halt))
   = \forall i: 1... \bullet (\sigma, i) \models at(halt)) \Rightarrow (\sigma, i) \models \Box at(halt)
   = \forall i: 1... \bullet (\sigma, i) \models at(halt) \Rightarrow
                                             \forall j: i... • (\sigma, j) \models at(halt)
```

#### **Partial Correctness**

For systems characterized in terms of

```
pre: P
post: Q

• P \Rightarrow \Box ( at(halt) \Rightarrow Q )

Note operator precedence requires ()
```

- > specifies partial correctness, assuming that at(halt) means the program has terminated
- > i.e., if P is true initially, and the program terminates, then Q will be true
- P ∧ □ (at(halt) ⇒ Q)
   alternative partial correctness definition

**Qn: What is the difference?** 

# **Examples using Diamond**

•  $\Diamond (x > 0)$ •  $\Diamond$  (  $\sim$  in\_crit(p<sub>1</sub>)  $\land$   $\sim$  in\_crit(p<sub>2</sub>) ) •  $(\sigma, 2) \models \Diamond (\sim at(init))$  at(init) ⇒ ◊ ( at(halt) ) •  $in_{crit}(p_1) \Rightarrow \Diamond (\sim in_{crit}(p_1))$ • (P  $\Rightarrow$  ( $\square$  (at(halt)  $\Rightarrow$  Q ))  $\wedge$  ( $\lozenge$  at(halt) )) > total correctness

# **Combining Box and Diamond**

- ◊ □ P
  - "Eventually P will be true forever"
  - > Example: ♦ 🗆 at(halt)
- □ ◊P
  - "Henceforth P will eventually be true"
  - > In every state from now on P will eventually become true
  - P is true infinitely often
  - Note that if traces are finite, then P must hold in the final state

# **Example: Expanding ◊ □ P**

```
\Diamond \square P
=
(\sigma, 1) \models \Diamond \square P
=
\exists j: 1 ... \bullet (\sigma, j) \models \square P
=
\exists j: 1 ... \bullet (\forall k: j ... \bullet (\sigma, k) \models P)
```

# **Example: Expanding** □ **◊P**

#### **Leads To**

- $\Box$  (P  $\Rightarrow$   $\Diamond$  Q)
- If P is true then eventually Q will be true
- This is sometimes read: P leads to Q
- Examples:
  - > P might be "makes a request" and Q might be "receives a reply"
  - > P might be "enters a critical region" and Q might be "exits that region"

Qn: how is this different from  $P \Rightarrow \Diamond Q$ ?

Qn: how is this different from  $\Diamond P \Rightarrow \Diamond Q$ ?

#### **Box and Diamond are "Dual"**

- Temporal logic has a number of important algebraic properties
- Two of the most useful are

Sometimes you see G for □
 F for ◊

## **Summary of Some Common Forms**

- P ⇒ ◊ Q
  - > if initially P then eventually Q
- $\Box$  (P  $\Rightarrow$   $\Diamond$  Q)
  - > every P-position is followed by a Q-position
- □ ◊ Q
  - > Q happens infinitely often
- ◊ □ **Q** 
  - > eventually permanently Q
  - > alt: the sequence contains only finitelymany ~Q-positions
- □ (P ⇒ □ P)
  - > once P, always P

#### Until

We can express "P is true until Q holds"

```
(\sigma, i) \models P \cup Q \Leftrightarrow

\exists k: i... \bullet (\sigma, k) \models Q \land (\forall j: i... k-1 \bullet (\sigma, j) \models P)
```

- Example
  - □ (request\_made ⇒
     (request\_registered U request\_answered))
- Until requires that Q becomes true eventually
- We also have weak version U<sub>w</sub>, defined as P U<sub>w</sub> Q ⇔ □ P ∨ (P U Q) sometimes written P W Q

#### What's Next?

Circle: the Next state operator

$$(\sigma, i) \models O P \Leftrightarrow (\sigma, i+1) \models P$$

- That is, P is true at position i ⇔ P is true at position i+1
- As usual,  $\bigcirc$  P, by itself, means  $(\sigma, 1) \models \bigcirc$  P
- Sometimes Ois represented by the letter "X"
- Some argue people that Ois not a good operator for specification
  - > specifications should be insensitive to orderings, particularly when concurrency is represented by interleaving

## **Other Temporal Logics**

- We have presented a particular temporal logic called "Linear Temporal Logic" (LTL)
- But there are other varieties
- One that is often used with model checkers is "Computation Tree Logic" (CTL)
  - > It views the behavior of a state machine as a tree in which each node is a state and branches represent possible next states
  - > One can then quantify over paths in the tree
  - > Neither LTL nor CTL is strictly more expressive