CMU 17-651

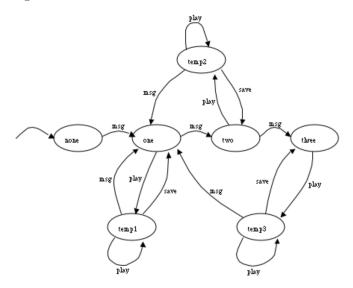
Models of Software Systems

Fall 2018

Homework #5: State Machines

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1. A certain, simple, answering machine has two buttons, "play" and "save" and can, of course, receive messages. If someone plays the messages and doesn't save them, they are erased/overwritten when the next incoming message is received. The answering machine only holds a specified number of messages; when it reaches full capacity it refuses to accept new messages. The answering machine can be modeled by the state machine, **AnsMachine**, whose state transition diagram is attached.



(a) Give a 4-tuple description for this state machine.

```
AnsweringMachine == ( \{none, one, two, three, temp1, temp2, temp3\}, \{none\}, \{msg, play, save\}, \{(none, msg, one), (one, msg, two), (one, play, temp1), (two, msg, three), (two, play, temp2), (temp1, save, one), (temp1, msg, one), (temp1, play, temp1), (temp2, save, two), (temp2, play, temp2), (temp2, msg, one), (temp3, play, temp3), (temp3, save, tree), temp3, msg, one) \}
```

(b) Give three execution fragments of AnsMachine, at least one of which is not an execution.

Given the GWC10 definition of execution fragment and execution:

"Definition 3. An execution fragment is a finite or infinite sequence $\langle s0,a1,s1,a2,s3,... \rangle$ of alternating states and actions such that for all i (si,ai+1,si+1) is a step of M."

"Definition 4. An execution is an execution fragment starting with an initial state of M (and ending in a state if finite)"

- i. $\langle none, msg, one, play, temp1, msg, one, msg, two \rangle$
- ii. $\langle none, msg, one, msg, two, play, temp2, save, two \rangle$
- iii. Execution which is not an execution frament: $\langle two, msg, three, play, temp3, play, temp3, msg, one \rangle$ It is not an execution fragment because it starts at state two as opposed to none
- (c) Give both a finite and an infinite execution of **AnsMachine**.
 - i. finite $== \langle none, msq, one, play, temp1, save \rangle$
 - ii. infinite == $\langle none, msg, one, play, temp1, msg, one, play, temp1, ... \rangle$ I am not sure if I am using the right notation for the infinite execution, since none is not repeated, only the $\{msg, one, play, temp1\}$
- (d) For each of the following, indicate whether or not it is an event-based trace of AnsMachine.

Logic used to answer: I determined if the presented sequences of actions are valid or not for AnsMachine:

- i. $\langle play, save, msg, msg, play \rangle$ Not valid because the initial state none does not handle the play event.
- ii. $\langle msg, msg, msg, play, save, msg, msg, msg \rangle$ Not valid because after the element 5 you end up in three which does not handle msg
- iii. $\langle msg, play, save, msg, msg, play, msg, msg, msg \rangle$ It is a valid event-based trace, the final state is three
- (e) Give two examples of state-based traces of **AnsMachine**.
 - i. $\langle none, one, two, three \rangle$
 - ii. $\langle none, one, temp1, one, two, temp2 \rangle$
- (f) Give two sequences of states that are not state-based traces of **AnsMachine**.
 - i. $\langle temp3, temp2, two \rangle$
 - ii. $\langle none, three, two, temp3 \rangle$
- (g) What are the reachable states of this machine?

The reachable states are the ones that we can get to given the set of state transition relations.

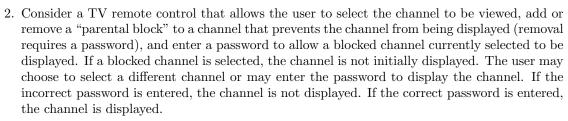
For **AnsMachine**, reachableStates $== \{none, one, two, three, temp1, temp2, temp3\}$

(h) Is **AnsMachine**'s event-based behavior finite or infinite?

It is event-based behavior infinite because we can create an infinite traces if we send the play message repeatedly while in any of the following states { one, twothree, temp1, temp2, temp3}

(i) Can a state machine $M = (S, I, A, \delta)$ with an infinite trace have finite behavior? Give an example or explain why not.

did not answer



Your task is to model the described functionality of the remote control. That is,

- (a) Specify the set of states
- (b) Specify the pre- and post-conditions for each action

Your solution should satisfy the following requirements:

- i. Do *not* model any functionality other than that described above. In particular, assume that the correct password is fixed and cannot be changed.
- ii. Assume that the set of channels is Channels == $\{n : \mathbb{N} \mid 1 \le n \le 100\}$.
- iii. You may only use the following actions in your model:
 - select: Select a channel for viewing
 - correctpw: Enter correct password
 - incorrectpw: Enter incorrect password
 - addblock: Block selected channel
 - removeblock: Unblock selected channel
- iv. If (and only if) the requirements are ambiguous, state any assumptions that you made to resolve those ambiguities.

Assumptions:

(a) TV power modes are out of scope.

 $pre: current_channel \notin blocked_channels$

(b) Communication errors between the tv and the remote are out of scope.

```
S = \{current\_channel : Channels, \\ current\_channel\_visible : \{true, false\}, \\ blocked\_channels : \{Channels\}\}
select(c:Channels)
pre true
post current\_channel = c, \\ `current\_channel\_visible = c \in blocked\_channel
`blocked\_channels = blocked\_channels
addblock
```



post: 'blocked_channels = blocked_channels \cap current_channel,
'current_channel_visible = current_channel_visible,
'current_channel = current_channel

My remove block function calls correctpw or incorrectpw to determine if it should remove
the block:
removeblock
pre: current_channel \in blocked_channels
post: (correctpw \(\infty \) {'blocked_channels} = blocked_channels / {current_channel}, 'current_channel
= current_channel, current_channel_visible = true \}) \(\) (incorrectpw \(\infty \) {'current_channel = current_channel, 'current_channel_visible} = current_channel_visible, 'blocked_channel})

correctpw
pretrue
posttrue

incorrectpw

 $egin{array}{c} \mathbf{pret} rue \ \mathbf{post} false \end{array}$