## Digital Communications and Laboratory Second Homework

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## MATLAB code

```
clc; close all; clear global; clearvars;
N = [1:1:20];
L = [31 \ 63 \ 127 \ 255 \ 511 \ 1023];
sigdB = -8;
sigmaw = 10^{(sigdB/10)};
a1 = -0.9635;
a2 = 0.4642;
noise = wgn(4*max(L), 1, sigdB);
\% \ save ( \ 'good\_noise3 \ ', \ 'noise \ ')
                                                                10
load good_noise3
%%
index = 0;
for l=1:length(L)
                                                                15
    index = index + 1;
for n=1:length(N)
    w = noise(1:4*L(1));
    w_0 = w([1:2:end]);
    w_1 = w([2:2:end]);
    PN = PNSeq(L(1));
                                % ML sequence repeated once
    x=[PN ; PN];
    h = impz(1, [1 a1 a2]); % Analytical h
   [h\_even, h\_odd] = polyphase(h, length(h));
                                                                25
    % scheme pag 239
    z_0=filter(h_even, 1, x);
    z_1 = filter(h_odd, 1, x);
    d_0 = z_0 + w_0;
                                                                30
    d_1 = z_1 + w_1;
    d = PS(d_0, d_1);
```

```
% Correlation method
    h0\_cor=corr\_method(x, d\_0);
                                                                 35
    h1_cor=corr_method(x, d_1);
    if N(n)<L(1)
        h0_{cor} = h0_{cor} (1 : ceil(N(n)/2));
        h1_{cor} = h1_{cor} (1: floor(N(n)/2));
    end
                                                                 40
    h_{cor} = PS(h0_{cor}, h1_{cor});
    % Cost function
    d0_hat = filter(h0_cor,1,x);
    d1_hat = filter(h1_cor,1,x);
                                                                 45
    d_hat_cor = PS(d0_hat, d1_hat);
    error\_cor = d - d\_hat\_cor;
    E_{cor} = sum(error_{cor}(L(1):2*L(1)).^2);
    E_L_{cor}(1,n) = 10*log10(E_{cor}/L(1));
    % ls method
    h0_ls=LS(x, d_0, L(l));
    h1_ls=LS(x, d_1, L(l));
    if N(n)<L(1)
        h0_{ls}=h0_{ls} (1: ceil(N(n)/2));
                                                                 55
        h1_{ls}=h1_{ls} (1: floor(N(n)/2));
    h_ls = PS(h0_ls, h1_ls);
    % Cost Function
                                                                 60
    d0_{hat} = filter(h0_{ls}, 1, x);
    d1\_hat = filter(h1\_ls, 1, x);
    d_hat_ls = PS(d0_hat, d1_hat);
    error ls = d - d hat ls;
    E_ls = sum(error_ls(L(1):2*L(1)).^2);
    E_L_ls(1,n) = 10*log10(E_ls/L(1));
end
Cost\_cor(:,index) = E\_L\_cor;
Cost_ls(:,index) = E_L_ls;
plot_est(Cost_cor, Cost_ls, sigdB);
```

```
clc; close all; clear global; clearvars;
```

```
L=63;
                      % length of PN sequence
Nh=6:
                    % Bound on the length of h
\% \ A\,d\,d\,i\,t\,i\,v\,e \quad n\,o\,i\,s\,e
sigdB = -8;
\operatorname{sigmaw} = 10^{(\operatorname{sigdB}/10)};
load good_noise3.mat
w = noise(1:4*L)
\% \ w = wgn(4*L,1,sigdB);
                                                                  10
w 0 = w([1:2:end-1]);
w_1 = w([2:2:end]);
PN = PNSeq(L);
                      % ML sequence repeated once
x=[PN ; PN];
                                                                  15
%% POLYPHASE REALIZATION
a1 = -0.9635;
a2 = 0.4642;
h = impz(1, [1 a1 a2]);
                                                                  20
[h_even, h_odd] = polyphase(h, Nh);
% ESTIMATE OF h0 WITH THE CORRELATION METHOD
z_0=filter (h_even, 1, x);
d_0 = z_0 + w_0;
                                                                  25
                                    % correlation method
h0\_cor=corr\_method(x, d\_0);
var_h0_cor = sigmaw/(L/2);
                                        % variance of the
      estimate
%% ESTIMATE OF h1 WITH THE CORRELATION METHOD
z_1=filter(h_odd, 1, x);
                                                                  30
d_1 = z_1 + w_1;
                                       % correlation method
h1\_cor=corr\_method(x, d\_1);
var_h1_cor = sigmaw/(L/2);
                                       % variance of the
      estimate
% Estimated impulse response
                                                                  35
h_{cor}=zeros(Nh,1);
h0\_spaced=zeros(Nh,1);
h1\_spaced = zeros(Nh, 1);
for i=1:Nh
    if (i<=L)
                                                                  40
    h_{cor}(2*i-1)=h0_{cor}(i);
    h_{cor}(2*i)=h1_{cor}(i);
    h0\_spaced(2*i-1) = h0\_cor(i);
    h1\_spaced(2*i) = h1\_cor(i);
    end
                                                                  45
end
```

```
h_{cor} = h_{cor} (1:Nh);
var_cor = var_h0_cor + var_h1_cor;
h0_spaced=h0_spaced(1:Nh);
                                                                    50
h1_spaced=h1_spaced(1:Nh);
\% Plot
figure,
stem(0:Nh-1,h0\_spaced, 'ro'), hold on
                                                                    55
stem(0:Nh-1,h1_spaced, 'ko'), hold on plot([0:Nh-1],h(1:Nh), 'bx', 'LineWidth',1.5); legend('h_0 component', 'h_1 component', 'Analytic impulse
      response');
xlabel('n'), ylim([-0.4 1.2]);
title ('Polyphase components with the Correlation method')
grid on
%% ESTIMATE WITH THE LS METHOD
h0_{ls}=LS(x, d_0, L);
h1_{ls}=LS(x, d_1, L);
                                                                    65
h_{ls}=zeros(Nh,1);
h0\_spaced\_ls=zeros(Nh,1);
h1 spaced ls=zeros(Nh,1);
for i=1:Nh
                                                                    70
     if (i<=L)
    h_ls(2*i-1)=h0_ls(i);
    h ls(2*i)=h1 ls(i);
    h0\_spaced\_ls(2*i-1) = h0\_ls(i);
     h1\_spaced\_ls(2*i) = h1\_ls(i);
                                                                    75
    \mathbf{end}
end
h_ls=h_ls (1:Nh);
h0_spaced_ls=h0_spaced_ls(1:Nh);
h1_spaced_ls=h1_spaced_ls(1:Nh);
                                                                     80
% Plot
figure,
stem(0:Nh-1,h0_spaced_ls, 'ro'), hold on
stem(0:Nh-1,h1_spaced_ls,'ko'), hold on
                                                                    85
plot ([0:Nh-1],h(1:Nh), 'bx', 'LineWidth',1.5);
legend('h_0 component', 'h_1 component', 'Analytic impulse
      response');
xlabel('n'), ylim([-0.4 1.2]);
title ('Polyphase components with the LS method')
grid on
                                                                    90
```

```
% comparison cor vs ls
figure,
stem (0:Nh-1,h_cor, 'bo')
hold on
                                                               95
stem (0:Nh-1,h_ls,'ro')
grid on
plot ([0:Nh-1],h,'bx','LineWidth',1.5);
legend('h_cor', 'h_ls', 'Analytic impulse response');
                                                               100
% VALUES FOR THE TABLE
table = zeros(Nh, 3)
for i=1:Nh
    table(i,:) = [h(i) h\_cor(i) h\_ls(i)];
end
                                                               105
table;
```

```
function [rx]=autocorrelation Unb(x)
\% Unbiased autocorrelation estimator
MNPUT: r.p. x, length of the autocorrelation Lcorr
\mbox{\it MOUTPUT:} autocorrelation estimate vector \mbox{\it rx} of length \mbox{\it K}\!\!=\!
      length(x)
Wevery index is augmented by 1 because matlab starts from 5
       1 and not 0
K=length(x);
rx = zeros(K, 1);
   for n=1:K
      \% first x that has k as argument
      xnk=x(n:K);
                                                                   10
      \%second\ x\ that\ has\ k-n\ as\ argument\ and\ the
            conjugate
       x conj = conj(x(1:(K-n+1)));
       rx(n) = (xnk. *xconj)/(K-n+1);
   end
end
                                                                   15
```

```
function [rx]=corr_method(x,d)
% INPUT
% x the input sequence of length 2*L
% r the output of the filter
% OUTPUT
% rx the cross correlation of d and x of length L=length(x)/2
L=length(x)/2;
```

```
function [h_ls]=LS(x,d,L)
% INPUT
\% x the input seq
\% d filter output
% L half length PN seq
% OUTPUT
\% h_ls the least squares estimate of h
%build matrix Phi and theta by I and o (page 246)
I=zeros(L);
                                                             10
for k=1:L
    I(:,k)=x(L-k+1:(2*L-k));
end
o=d(L:2*L-1);
Phi=I'*I;
                                                             15
theta=I'*o;
h_ls=inv(Phi)*theta;
%h_ls=h_ls(1:N);
end
```

```
function [pn] = PNSeq(L)

r = log2(L+1);
pn = zeros(L,1);

% Initial conditions (set to one, arbitrary)
% Must not be ALL zeros
pn(1:r) = ones(1,r).';

for l=r+1:L
    switch r
    case 1
```

```
pn(1) = pn(1-1);
          case 2
               pn(1) = xor(pn(1-1), pn(1-2));
                                                                            15
          case 3
               pn(1) = xor(pn(1-2), pn(1-3));
          case 4
               pn(1) = xor(pn(1-3), pn(1-4));
          case 5
                                                                            20
               pn(1) = xor(pn(1-3), pn(1-5));
          case 6
               pn(1) = xor(pn(1-5), pn(1-6));
          case 7
               pn(1) = xor(pn(1-6), pn(1-7));
                                                                            25
          case 8
               \operatorname{pn}(1) = \operatorname{xor}(\operatorname{xor}(\operatorname{pn}(1-2), \operatorname{pn}(1-3)), \operatorname{xor}(\operatorname{pn}(1-4),
                      pn(1-8));
          case 9
               pn(1) = xor(pn(1-5), pn(1-9));
          case 10
                                                                            30
               pn(1) = xor(pn(1-7), pn(1-10));
     end
                                                                            35
end
\% Bits are \{-1, 1\}
pn = 2*pn -1;
                                                                            40
end
```

```
function [h_even h_odd] = polyphase(h,Nlim)

% Even samples
h_even=zeros(ceil(Nlim/2),1);
for k=1:(Nlim/2)
    h_even(k)=h(2*k-1);
end

% Odd samples
h_odd=zeros(floor(Nlim/2),1);
for k=1:Nlim/2
    h_odd(k)=h(2*k);
end
```

end

```
function [h] = PS(h0, h1)
temp = length(h0) + length(h1);
h=zeros(temp,1);
if mod(temp, 2) == 0
    for i=1:temp/2
        h(2*i-1)=h0(i);
        h(2*i)=h1(i);
    end
elseif
        length(h0)==1
        h(1)=h0(1);
else
    for i=1:length(h0)-1
        h(2*i-1)=h0(i);
        h(2*i)=h1(i);
                                                               15
    end
    h(2*(i+1)-1) = h0(i+1);
end
end
                                                               20
```

```
function plot_est(cor, ls, sigdB)
set(0, 'defaultTextInterpreter', 'latex')
\% figure()
scrsz = get(0, 'ScreenSize');
figure ('Position', [15 \text{ scrsz}(4)/5 \text{ scrsz}(3)/1.5 \text{ scrsz}(4)]
         /1.5])
[N, lengL] = size(cor);
N = [1:1:N];
a = sigdB*ones(1,20);
plot(N, ls(:,1), 'b-*')
hold on, plot (N, ls(:,2), 'c*-')
hold on, plot (N, ls(:,3), 'g-*')
hold on, plot (N, ls(:,4), 'y-*')
hold on, plot (N, ls(:,5), 'm-*')
                                                                                                          15
\mathbf{hold} \ \mathrm{on} \, , \ \mathbf{plot} \, (N, \mathbf{ls} \, (\, : \, , 6\, ) \, \, , \, {}^{\backprime}r - \! * \, {}^{\backprime})
hold on, plot (N, cor (:,1), 'bo—')
hold on, \mathbf{plot}(N, \operatorname{cor}(:,2), '\operatorname{co--}')
\mathbf{hold} \ \ \mathbf{on} \ , \ \ \mathbf{plot} \ (\mathrm{N}, \mathrm{cor} \ (::,3) \ , \ '\mathrm{go} \underline{\hspace{1cm}}')
\mathbf{hold} \ \mathrm{on} \, , \ \mathbf{plot} \, (\mathrm{N}, \mathrm{cor} \, (:, 4) \, , \text{'yo} \underline{\hspace{1em}')}
                                                                                                          20
hold on, \mathbf{plot}(N, \operatorname{cor}(:,5), \operatorname{'mo-'})
```

```
hold on, plot(N, cor(:,6), 'ro—')
hold on, plot(a, 'b—', 'LineWidth',2);
text(2,-7.7, '$\sigma_w^2$', 'FontSize',16, 'Color', 'blue');

xlabel('$N_h$');
ylabel('$\mathcal{E}/L$ [dB]')
xlim([1 20]);
legend('L31', 'L63', 'L127', 'L255', 'L511', 'L1023')
set(gca, 'FontSize',15);
grid on
end
```

```
clc
clearvars
close all
set (0, 'defaultTextInterpreter', 'latex') % latex format
% Given Parameters
Tc = 1;
fd = (40*10^-5)/Tc;
                                       % Doppler spread given
Tp = 1/10*(1/fd);
N_h0 = 7500;
                                       % samples first plot
N_t = 80000;
                                       % samples of second plot
K dB = 2;
                                       % Rice Factor in dB
K = 10^{(K_dB/10)};
                                       % Rice Factor in linear
      units
C = \mathbf{sqrt}(K/(K+1));
                                                                       15
[a_ds, b_ds] = ClassicalDS();
                                          % Parameters of the
      IIR filter which implement
                                          \% the classical
                                                 Doppler Spectrum
                                                 (page 317)
h_dopp = impz(b_ds, a_ds);
                                          % Impulse response of
E_d = sum(h_dopp.^2);
                                          % Energy of the
                                                                       20
      impulse\ response
b_ds = b_ds/sqrt(E_d);
Md = 1-C^2;
                                          % normalization of the
       statistical power
% Doppler spectrum
[H_dopp, w] = freqz(h_dopp, 1, 1024, 'whole', 1/Tp);
                                                                       25
DS = abs(H_dopp).^2;
% figure
{\bf subplot}\,(121)\;,\;\;{\bf plot}\,(\,h\_{\rm dopp}\,,\,\,{}^{\prime}{\rm r}\,\,{}^{\prime}\,)\;,\;\;{\bf ylabel}(\,\,{}^{\prime}\,\$\,|\,h\_\{\,{\rm ds}\,\}\,|\,\$\,\,{}^{\prime}\,)\;,
      hold on
stem(1:length(h_dopp), real(h_dopp));
axis([0 \text{ Tp } -0.15 \text{ } 0.25]), grid on
\textbf{legend}(\ 'continuous\ |h_{ds}|\ ',\ 'sampled\ |h_{ds}|\ ');
title ('Impulse response of the IIR filter');
subplot (122), plot (w,10*log10 (DS)), ylabel ('$|D(f)|$'),
      grid on;
hold on, plot ([fd fd], [-60 20], 'r-'), text (4.1e-4, 10, |35
       '$f_d$');
```

```
xlim([0 3*fd]), xlabel('f');
ylim ([-60 \ 20]);
legend('Doppler Spectrum');
title ('Doppler Spectrum')
% Transient is determined by the pole closest to the unit
      circle
poles = abs(roots(a ds));
                                        % poles 'magnitude
most imp = max(poles);
tr = 5*Tp*ceil(-1/log(most_imp));
                                        \% transient as 5*
     Neq*Tp
h_samples_needed = N_t+tr;
                                        % total length
     including the transient
w_samples_needed = ceil(h_samples_needed/Tp);
\% \ w = wgn(w\_samples\_needed, 1, 0, 'complex');
                                                   \% \ w \sim CN
     (0,1)
load ex2_noise
hprime = filter (b_ds, a_ds, w);
                                                              50
t = 1: length(hprime);
                                        % interpolation to
     Tq
Tq = Tc/Tp;
t_fine = Tq:Tq:length(hprime);
h_fine = interp1(t, hprime, t_fine, 'spline');
                                                              55
sigma = sqrt(Md);
h_fine = h_fine*sigma;
                                        % impose the
     desired power delay profile
                                        % remove the
h0 = h_fine(tr+1:end)+C;
     transient and add C
\% figure, plot(abs(h0(1:N_h0)))
                                                              60
\% x label(`\$nT_c\$')
% ylabel('$/h_0(nT_c)/$')
% xlim([1 N_h0]), grid on
% title ('Impulse response of the channel')
                                                              65
% ESTIMATE OF THE PDF OF H_p=|h0|/sqrt(M)
h p = h0/sqrt(C^2+Md);
                               % the normalization here
     does not make much sense
                                \% as M_h0=1-C^2, but it's
                                     to keep the formulas
                                     as in the book
abs_h = abs(h_p);
                                % magnitude
a = linspace(0, 10, 3000);
                                                              70
% Rice distribution
```

```
th\_pdf = 2*(1+K).*a.*exp(-K-(1+K).*a.^2).*besseli(0,2.*a*
      sqrt (K*(1+K)));
\% Estimate of the pdf
[y, t] = hist(abs_h, 30);
\operatorname{est} \operatorname{pdf} = \operatorname{y/max}(\operatorname{y});
                                                                         75
figure
bar(t, est pdf, 'g'), hold on, plot(a, th pdf, 'r—', '
      LineWidth',2);
ylabel('Number of samples')
xlabel ('Value')
title ('Histogram of \frac{h_0}{frac} \left\{ |h_0| \right\} \left\{ \sqrt{M_{h_0}} \right\} ')
legend('estimate pdf', 'theoretical pdf');
axis([0 3 0 1.3]);
grid on
                                                                         85
% SPECTRUM ESTIMATION
% Theoretical PSD
Npoints=N t*1/Tp;
[H_dopp, w] = freqz(h_dopp, 1, Npoints, 'whole');
H dopp=(1/Npoints)*abs(H dopp).^2;
                                                                         90
DS = \mathbf{fftshift}(H_{dopp});
% Welch estimator
D = \mathbf{ceil}(N_t/2);
                            % window length
D = 40000;
S = D/2;
                                 % overlap
w welch=window(@bartlett,D);
[Welch_P, N] = welchPSD(h0', w_welch, S);
Welch_P = Welch_P/N;
Welch_cent=fftshift (Welch_P);
                                                                         100
C_{\text{comp}} = 10*\log 10 (C^2);
PSD\_theo = 10*log10 (Md*DS);
PSD_{theo}(length(PSD_{theo})/2) = C_{comp};
                                                                         105
f1 = [-N/2 + 1:N/2];
f2 = [-Npoints/2 + 1: Npoints/2];
figure,
                                                                         110
\mathbf{plot}(f1-1, 10*\mathbf{log10}(Welch\_cent)), \mathbf{hold} on, \mathbf{plot}(f2,
      PSD_theo, 'r')
y\lim([-40 \ 0])
x \lim ( [-5*N*fd \quad 5*N*fd]);
xticks([-5*N*fd -4*N*fd -3*N*fd -2*N*fd -1*N*fd 0 1*N*fd
```

```
2*N*fd 3*N*fd 4*N*fd 5*N*fd
xticklabels ({ '-5f_d', '-4f_d', '-3f_d', '-2f_d', '-f_d', '0', '|_115
     f_d','2f_d','3f_d','4f_d','5f_d'});
ylabel('H(f) [dB]')
xlabel('f')
legend('Welch Periodogram', 'Theoretical PSD')
title ('Spectrum Estimate')
grid on
                                                              120
%%
f1 = [-N/2 + 1:N/2];
f2 = [-Npoints/2 + 1: Npoints/2];
                                                              125
\% Comparison of different S,D
D = [10000 \ 15000 \ 20000 \ 40000];
S = D./2;
for i=1:length(S)
    w_welch=window(@hamming,D(i));
                                                              130
    [Welch_P(:,i), N] = welchPSD(h0', w_welch, S(i));
Welch P = Welch P/N:
Welch_cent=fftshift (Welch_P);
                                                              135
figure,
\mathbf{plot}(f1, 10*\mathbf{log10}(Welch\_cent)), \mathbf{hold} on
plot (f2, 10*log10 (Md*DS), 'r', 'LineWidth', 1.5)
y \lim ([-50 \ 0])
x \lim ([-5*N*fd \quad 5*N*fd]);
                                                              140
x \text{ ticks} ([-5*N*fd -4*N*fd -3*N*fd -2*N*fd -1*N*fd 0 1*N*fd
     2*N*fd \ 3*N*fd \ 4*N*fd \ 5*N*fd
xticklabels({ '-5f_d', '-4f_d', '-3f_d', '-2f_d', '-f_d', '0', '
     f_d', '2f_d', '3f_d', '4f_d', '5f_d'});
ylabel('H(f) [dB]')
xlabel('f')
D = int2str(DS(3)), and D = int2str(DS(3)),
     D = ' int2str(DS(4))' and S = ' int2str(S(4))]);
clc; close all; clear global; clearvars;
N = [1:1:20];
L = [31 \ 63 \ 127 \ 255 \ 511 \ 1023];
sigdB = -8;
sigmaw = 10^(sigdB/10);
```

```
a1 = -0.9635;
a2 = 0.4642;
noise = wgn(4*max(L), 1, sigdB);
% save('good_noise3', 'noise')
                                                                   10
load good_noise3
%%
index = 0;
for l=1:length(L)
                                                                   15
    index = index + 1;
for n=1:length(N)
    w = noise(1:4*L(1));
    w_0 = w([1:2:end]);
    w_1 = w([2:2:end]);
                                  % ML sequence repeated once
    PN = PNSeq(L(1));
    x=[PN ; PN];
    h = impz(1, [1 a1 a2]);  % A nalytical h
   [h_even,h_odd] = polyphase(h,length(h));
    % scheme pag 239
    z\_0 = \mathbf{filter} (h\_even, 1, x);
    z_1 = filter(h_odd, 1, x);
    d_0 = z_0 + w_0;
                                                                   30
    d_1 = z_1 + w_1;
    d = PS(d_0, d_1);
    % Correlation method
    h0\_cor=corr\_method(x, d\_0);
                                                                   35
    {\tt h1\_cor=corr\_method}\,(\,x\,,\ d\_1\,)\,;
    if N(n)<L(1)
         h0 cor=h0 cor(1:ceil(N(n)/2));
         h1\_cor=h1\_cor(1:floor(N(n)/2));
    end
    h_{cor} = PS(h0_{cor}, h1_{cor});
    \% Cost function
    d0_hat = filter(h0_cor,1,x);
    d1 \text{ hat} = \mathbf{filter}(h1 \text{ cor}, 1, x);
                                                                   45
    d_hat_cor = PS(d0_hat, d1_hat);
    error_cor = d - d_hat_cor;
    E_{cor} = sum(error_{cor}(L(1):2*L(1)).^2);
    E_L_{cor}(1,n) = 10*log10(E_{cor}/L(1));
                                                                  50
    % ls method
    h0_{ls}=LS(x, d_0, L(1));
```

```
h1_ls=LS(x, d_1, L(l));
    if N(n)<L(1)
         h0_{ls}=h0_{ls} (1 : ceil(N(n)/2));
                                                                  55
         h1_ls=h1_ls(1:floor(N(n)/2));
    h_ls = PS(h0_ls, h1_ls);
    % Cost Function
                                                                  60
    d0 \text{ hat} = \text{filter}(h0 \text{\_ls}, 1, x);
    d1_hat = filter(h1_ls,1,x);
    d_hat_ls = PS(d0_hat, d1_hat);
    error_ls = d - d_hat_ls;
    E_ls = sum(error_ls(L(1):2*L(1)).^2);
                                                                  65
    E_L_{ls}(1,n) = 10*log10(E_{ls}/L(1));
end
Cost\_cor(:,index) = E\_L\_cor;
Cost_ls(:,index) = E_L_ls;
                                                                  70
end
plot_est(Cost_cor, Cost_ls, sigdB);
```

```
clc; close all; clear global; clearvars;
N = [1:1:20];
L = [31 \ 63 \ 127 \ 255 \ 511 \ 1023];
sigdB = -8;
sigmaw = 10^{(sigdB/10)};
a1 = -0.9635;
a2 = 0.4642;
noise = wgn(4*max(L), 1, sigdB);
% save('good_noise3', 'noise')
                                                               10
load good_noise3
%%
index = 0;
for l=1:length(L)
                                                               15
    index = index + 1;
for n=1:length(N)
    w = noise(1:4*L(1));
    w_0 = w([1:2:end]);
    w_1 = w([2:2:end]);
    PN = PNSeq(L(1));
                               % ML sequence repeated once
    x=[PN ; PN];
```

```
h = impz(1, [1 a1 a2]); % A nalytical h
   [h_{even}, h_{odd}] = polyphase(h, length(h));
                                                                   25
    % scheme pag 239
    z_0=filter(h_even, 1, x);
    z_1 = filter(h_odd, 1, x);
    d 0 = z 0 + w 0;
                                                                   30
    d_1 = z_1 + w_1;
    d = PS(d_0, d_1);
    % Correlation method
    h0\_cor=corr\_method(x, d\_0);
                                                                   35
    h1\_cor=corr\_method(x, d\_1);
    if N(n) < L(1)
         h0_{cor} = h0_{cor} (1 : ceil(N(n)/2));
         h1_{cor} = h1_{cor} (1: floor (N(n)/2));
    end
    h_{cor} = PS(h0_{cor}, h1_{cor});
    % Cost function
    d0_hat = filter (h0_cor, 1, x);
    d1_hat = filter (h1_cor, 1, x);
                                                                   45
    d_hat_cor = PS(d0_hat, d1_hat);
    error\_cor = d - d\_hat\_cor;
    E_{cor} = sum(error_{cor}(L(1):2*L(1)).^2);
    E_L_{cor}(1,n) = 10*log10(E_{cor}/L(1));
                                                                   50
    % ls method
    h0_ls=LS(x, d_0, L(l));
    h1_{ls}=LS(x, d_1, L(1));
    if N(n) < L(1)
         h0_{ls}=h0_{ls} (1: ceil(N(n)/2));
                                                                   55
         h1_ls=h1_ls(1:floor(N(n)/2));
    end
    h_ls = PS(h0_ls, h1_ls);
    \% Cost Function
    d0 \text{ hat} = \mathbf{filter} (h0 \text{ ls}, 1, x);
    d1_hat = filter(h1_ls,1,x);
    d_hat_ls = PS(d0_hat, d1_hat);
    error_ls = d - d_hat_ls;
    E_ls = sum(error_ls(L(1):2*L(1)).^2);
                                                                   65
    E_L_{ls}(1,n) = 10*log10(E_{ls}/L(1));
end
```

```
| Cost_cor(:,index) = E_L_cor;
| Cost_ls(:,index) = E_L_ls;
| end
| plot_est(Cost_cor, Cost_ls, sigdB);
```

```
function [welch_est, Ns] = welchPSD(inputsig, window,
     overlaps)
% REQUIRES COLUMN VECTOR FOR THE INPUT DATA
% Length of the window
D = length(window);
% Length of input signal
K = length(inputsig);
% Normalized energy of the window
Mw = \mathbf{sum}(window .^2) * (1/D);
% Number of subsequences
                                                                10
N_s = floor((K-D)/(D-overlaps) + 1);
%Initialization of each periodogram
P_{per} = zeros(K, N_s);
for s = 0:(N_s-1)
    \% \ Windowed \ input
    x_s = window .* inputsig(s*(D-overlaps)+1:s*(D-overlaps))
          overlaps)+D);
    % DFT on K samples of windowed input
    X s = \mathbf{fft}(x s, K);
    % Periodogram for the window
    P_{per}(:, s+1) = (abs(X_s)).^2 * (1/(D*Mw)); \% Tc = 1;
\mathbf{end}
```