Convex Optimization (MA401) B.S. VII Sem (2024-2025) Practical Sheet 1-2

Note:- When the domain of a function is unspecified, it is conventionally considered to be the largest subset of \mathbb{R} or \mathbb{R}^2 or \mathbb{R}^3 for which the function is defined.

- 1. Given a vector A = [1, 4, -9, 7, 9, 4], write a MATLAB code to create a matrix B with two rows. The first row should contain the elements of A in descending order, and the second row should contain the corresponding original indices of the elements in A.
- 2. Let $f(x,y) = x^2 + y^2$ and $g(x,y) = x\cos(y)$. Define h(x,y) as the maximum of f(x,y) and g(x,y). Calculate the directional derivative of h at the points (0,0), (0,0.5), and (1,3) in the direction of the vector (1,-2).
- 3. Check whether the given function is convex or not.

a.
$$f_1(x) = x^2$$
 (using epigraph)

b.
$$f_2(x,y) = e^x + y^2$$
 (using second ordered sufficient condition)

c.
$$f_3(x, y) = \sin x + \cos y$$

d.
$$f_4(x,y) = x^3 + y^3$$

e.
$$f_5(x,y) = x^3 + y^3$$
, $(x,y) \in [4,7] \times [4,7]$.