

# BREAST CANCER SURVIVAL PREDICTION WITH NEURAL NETWORKS AND COX REGRESSION

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## Introduction

Survival analysis, also called time-to-event analysis, is used to estimate the lifespan of a specific study population. Applications of time-to-event prediction can be found in a variety of settings such as cancer patient survival prediction, customer churn, credit scoring, and system failure times. This project will focus on predicting breast cancer survival time using the following continuous-time survival analysis methodologies: Cox-Time, Cox-CC, and Cox-PH.

## Data Sources and Software

We gathered our data from the Molecular Taxonomy of Breast Cancer International Consortium (METABRIC) dataset which contains gene expression data and clinical features for 1,980 breast cancer patients. The analysis is made using the Python programming language and its packages PyTorch, pycox, and NumPy.

## Methods

In this project, we use methods proposed by Kvamme, Borgan, and Scheel [2] who proposed an alternative loss function that scales well for both the proportional and the non-proportional cases. The survival function is defined as

$$S(t) = P(T^* > t) = 1 - F(t) \quad (1)$$

where  $T^*$  is the time to the event and  $F(t)$  is the CDF of the probability distribution that the event happens at time  $t$ . In the case of the METABRIC dataset,  $T^*$  is the time until a certain patient will fail to survive while enduring breast cancer. The survival function can be retrieved through the cumulative hazard  $H(t)$  by

$$S(t) = \exp[-H(t)] = \exp[-\int_0^t h(s) ds] \quad (2)$$

We calculate the hazard function  $h(s)$  and the survival function  $S(t)$  using 3 regression methods: Cox-PH, Cox-Time and Cox-CC to predict whether the patient can survive in a certain number of months past the initial examination.

### 0.1 Cox-PH (DeepSurv)

The hazard function of the Cox proportional hazard, or Cox-PH, regression model is given by:

$$h(t | X) = h_0(t) \exp(X_1\beta_1 + \dots + X_p\beta_p) \quad (3)$$

In this model, the hazard is assumed "proportional" to a baseline hazard  $h_0(t)$ . That is, we note that  $\exp(X_1\beta_1 + \dots + X_p\beta_p)$  is a constant value with respect to time, hence the hazard at any given time is only a multiple of the baseline hazard. With this in mind, we can extend the Cox-PH model where instead of

$$(X_1\beta_1 + \dots + X_p\beta_p), \quad (4)$$

we use a neural network to approximate  $h_0(t)$ .

## Methods cont.

### 0.2 Cox-CC

Cox-MLP (CC) or Cox-CC is a proportional version of the Cox-Time model. We can approximate the risk set  $R_i$  with a sufficiently large subset  $\tilde{R}_i$ , and weight the likelihood accordingly with weights  $w_i$ .

$$loss = \prod_{n=1} (\frac{\exp[g(x_i)]}{w_i \sum_{j \in \tilde{R}_i} \exp[g(x_j)]}) \quad (5)$$

As the weights  $w_i$  do not contribute to the gradients of the logarithm of (5), we can simply drop them from the loss function, finally obtaining the following loss function for Cox-CC by averaging the loss to make it independent of the data set size,

$$loss = \frac{1}{n} \sum_{i:D_i=1} \log(\sum_{j \in \tilde{R}_i} \exp[g(x_j) - g(x_i)]) \quad (6)$$

### 0.3 Cox-Time

Cox-Time is a risk model proposed by Kvamme, Borgan and Scheel in [2] that attempts to remove the proportionality assumption from the Cox-CC model. That is, we no longer need to assume that the relative hazards in the Cox-CC model are constant over time with different patients. In exchange, we need to include time as a parameter for the relative hazard function  $g$ . The hazard function then becomes:

$$h(t|\mathbf{x}) = h_0(t)\exp[g(t, \mathbf{x})] \quad (7)$$

And the loss function becomes:

$$loss = \frac{1}{n} \sum_{i:D_i=1} \log(\sum_{j \in \tilde{R}_i} \exp[g(T_i, \mathbf{x}_j) - g(T_i, \mathbf{x}_i)]) \quad (8)$$

In practice, we only need to include the time value as a regular covariate to calculate the hazard at a certain time. However, since  $g$  is now time-dependent and we can no longer reuse the same  $g(\mathbf{x})$  for every time point, we need to recalculate  $g(t, \mathbf{x})$  for every time  $t$  when Cox-Time is used, making the Cox-Time method much more computationally expensive compared to Cox-CC.

## Analysis

For the project we used a python package called "pycox" designed for survival analysis and time-to-event prediction with PyTorch. After loading the METABRIC data set, splitting it in train, test and validation (where the test set and validation set each constitute 20% of the original dataset), and feature transforming, we created a simple MLP with two hidden layers: ReLU activations, batch norm and dropout. For this, we used the MLPVanilla function (for both Cox-CC and Cox-PH) and MLPVanillaCox-Time (for Cox-Time) from the "torchtuples" python package. We trained all three models and obtained survival estimates for the test set for prediction. For speed and visibility, we have also limited the prediction to predict the survival rate only on 5 individuals.

For the evaluation criteria, we used three metrics: time-dependent concordance index, the integrated IPCW Brier score (inverse probability of censoring weighted Brier score), and the integrated IPCW (negative) binomial log-likelihood.

## Results and Discussion

With all 3 methods, the 5 individuals have their survival rates flatten out (typically at 0.2 or below) past the 300 months mark, and have very low survival rates past the 350 months mark. Hence, there are no stark differences between the 3 methods in terms of how long a breast cancer patient is expected to survive. The experiment was then repeated 4 more times, each with a different (but consistent) seed for the program and the PyTorch package. The means of the scores received from all 5 simulations are compiled in Table 1 below:

Table 1: Means of evaluation scores of 5 simulations using Cox-Time, Cox-CC and Cox-PH.

Method	Concordance	IBS	INBLL
Cox-Time	0.673	0.166	0.499
Cox-CC	0.650	0.168	0.507
Cox-PH	0.648	0.169	0.511

The scores did not have large variations across the 5 simulations. For example, the concordance index for Cox-Time varied from 0.649 to 0.704, a difference of less than 10%.

The three models (Cox-Time, Cox-CC and Cox-PH) are very comparable in performance. Cox-Time is a more flexible version of Cox-CC, so naturally, Cox-Time returned slightly better results than Cox-CC with a higher Concordance Index, lower IBS and lower INBLL. However, Cox-Time is much more computationally expensive than Cox-CC and in this case, the difference in performance is so small that Cox-CC might still be worth considering for predicting the survival rate of breast cancer patients using the METABRIC data. We can deduce, then, that the hazard function is proportional for these 5 individuals in the METABRIC data. The Cox-CC model, in turn, performs very slightly better than the Cox-PH model.

## Conclusion

In this project, we explored extensions of the Cox proportional hazards model to predict breast cancer survival time using the METABRIC dataset. We used Cox-Time, Cox-CC, and Cox-PH.

After analyzing these models' performance using 3 different metrics, we conclude that the Cox-Time model has the best overall performance in terms of concordance index, integrated Brier score (IBS) and integrated binomial log-likelihood (IBLL), in exchange for using more computational resources. We can also note that all three models perform almost similarly.

## References

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