The local truncation error involved with a predictor-corrector method of the Milne-Simpson type is generally smaller than that of the Adams-Bashforth-Moulton method. But the technique has limited use because of round-off error problems, which do not occur with the Adams procedure. Elaboration on this difficulty is given in Section 5.10.

## **EXERCISE SET 5.6**

- 1. Use all the Adams-Bashforth methods to approximate the solutions to the following initial-value problems. In each case use exact starting values, and compare the results to the actual values.
  - **a.**  $y' = te^{3t} 2y$ ,  $0 \le t \le 1$ , y(0) = 0, with h = 0.2; actual solution  $y(t) = \frac{1}{5}te^{3t} \frac{1}{25}e^{3t} + \frac{1}{25}e^{-2t}$ .
  - **b.**  $y' = 1 + (t y)^2$ ,  $2 \le t \le 3$ , y(2) = 1, with h = 0.2; actual solution  $y(t) = t + \frac{1}{1 t}$ .
  - **c.** y' = 1 + y/t,  $1 \le t \le 2$ , y(1) = 2, with h = 0.2; actual solution  $y(t) = t \ln t + 2t$ .
  - **d.**  $y' = \cos 2t + \sin 3t$ ,  $0 \le t \le 1$ , y(0) = 1, with h = 0.2; actual solution  $y(t) = \frac{1}{2} \sin 2t \frac{1}{3} \cos 3t + \frac{4}{3}$ .
- Use each of the Adams-Bashforth methods to approximate the solutions to the following initial-value
  problems. In each case use starting values obtained from the Runge-Kutta method of order four.
  Compare the results to the actual values.
  - **a.**  $y' = \frac{2 2ty}{t^2 + 1}$ ,  $0 \le t \le 1$ , y(0) = 1, with h = 0.1 actual solution  $y(t) = \frac{2t + 1}{t^2 + 2}$ .
  - **b.**  $y' = \frac{y^2}{1+t}$ ,  $1 \le t \le 2$ ,  $y(1) = -(\ln 2)^{-1}$ , with h = 0.1 actual solution  $y(t) = \frac{-1}{\ln(t+1)}$ .
  - **c.**  $y' = (y^2 + y)/t$ ,  $1 \le t \le 3$ , y(1) = -2, with h = 0.2 actual solution  $y(t) = \frac{2t}{1-t}$
  - **d.** y' = -ty + 4t/y,  $0 \le t \le 1$ , y(0) = 1, with h = 0.1 actual solution  $y(t) = \sqrt{4 3e^{-t^2}}$ .
- 3. Use each of the Adams-Bashforth methods to approximate the solutions to the following initial-value problems. In each case use starting values obtained from the Runge-Kutta method of order four. Compare the results to the actual values.
  - **a.**  $y' = y/t (y/t)^2$ ,  $1 \le t \le 2$ , y(1) = 1, with h = 0.1; actual solution  $y(t) = \frac{t}{1 + \ln t}$ .
  - **b.**  $y' = 1 + y/t + (y/t)^2$ ,  $1 \le t \le 3$ , y(1) = 0, with h = 0.2; actual solution  $y(t) = t \tan(\ln t)$ .
  - **c.** y' = -(y+1)(y+3),  $0 \le t \le 2$ , y(0) = -2, with h = 0.1; actual solution  $y(t) = -3 + 2/(1 + e^{-2t})$ .
  - **d.**  $y' = -5y + 5t^2 + 2t$ ,  $0 \le t \le 1$ , y(0) = 1/3, with h = 0.1; actual solution  $y(t) = t^2 + \frac{1}{3}e^{-5t}$ .
- **4.** Use all the Adams-Moulton methods to approximate the solutions to the Exercises 1(a), 1(c), and 1(d). In each case use exact starting values, and explicitly solve for  $w_{i+1}$ . Compare the results to the actual values.
- 5. Use Algorithm 5.4 to approximate the solutions to the initial-value problems in Exercise 1.
- **6.** Use Algorithm 5.4 to approximate the solutions to the initial-value problems in Exercise 2.
- 7. Use Algorithm 5.4 to approximate the solutions to the initial-value problems in Exercise 3.
- **8.** Change Algorithm 5.4 so that the corrector can be iterated for a given number p iterations. Repeat Exercise 7 with p = 2, 3, and 4 iterations. Which choice of p gives the best answer for each initial-value problem?
- **9.** The initial-value problem

$$y' = e^y$$
,  $0 \le t \le 0.20$ ,  $y(0) = 1$ 

has solution

$$y(t) = 1 - \ln(1 - et).$$

Applying the three-step Adams-Moulton method to this problem is equivalent to finding the fixed point  $w_{i+1}$  of

$$g(w) = w_i + \frac{h}{24} (9e^w + 19e^{w_i} - 5e^{w_{i-1}} + e^{w_{i-2}}).$$

- **a.** With h = 0.01, obtain  $w_{i+1}$  by functional iteration for i = 2, ..., 19 using exact starting values  $w_0, w_1$ , and  $w_2$ . At each step use  $w_i$  to initially approximate  $w_{i+1}$ .
- **b.** Will Newton's method speed the convergence over functional iteration?
- 10. Use the Milne-Simpson Predictor-Corrector method to approximate the solutions to the initial-value problems in Exercise 3.
- a. Derive the Adams-Bashforth Two-Step method by using the Lagrange form of the interpolating polynomial.
  - b. Derive the Adams-Bashforth Four-Step method by using Newton's backward-difference form of the interpolating polynomial.
- 12. Derive the Adams-Bashforth Three-Step method by the following method. Set

$$y(t_{i+1}) = y(t_i) + ah f(t_i, y(t_i)) + bh f(t_{i-1}, y(t_{i-1})) + ch f(t_{i-2}, y(t_{i-2})).$$

Expand  $y(t_{i+1})$ ,  $f(t_{i-2}, y(t_{i-2}))$ , and  $f(t_{i-1}, y(t_{i-1}))$  in Taylor series about  $(t_i, y(t_i))$ , and equate the coefficients of h,  $h^2$  and  $h^3$  to obtain a, b, and c.

- 13. Derive the Adams-Moulton Two-Step method and its local truncation error by using an appropriate form of an interpolating polynomial.
- 14. Derive Simpson's method by applying Simpson's rule to the integral

$$y(t_{i+1}) - y(t_{i-1}) = \int_{t_{i-1}}^{t_{i+1}} f(t, y(t)) dt.$$

15. Derive Milne's method by applying the open Newton-Cotes formula (4.29) to the integral

$$y(t_{i+1}) - y(t_{i-3}) = \int_{t_{i-3}}^{t_{i+1}} f(t, y(t)) dt.$$

**16.** Verify the entries in Table 5.12 on page 305.

## 5.7 Variable Step-Size Multistep Methods

The Runge-Kutta-Fehlberg method is used for error control because at each step it provides, at little additional cost, *two* approximations that can be compared and related to the local truncation error. Predictor-corrector techniques always generate two approximations at each step, so they are natural candidates for error-control adaptation.

To demonstrate the error-control procedure, we construct a variable step-size predictor-corrector method using the four-step explicit Adams-Bashforth method as predictor and the three-step implicit Adams-Moulton method as corrector.

The Adams-Bashforth four-step method comes from the relation

$$y(t_{i+1}) = y(t_i) + \frac{h}{24} [55 f(t_i, y(t_i)) - 59 f(t_{i-1}, y(t_{i-1})) + 37 f(t_{i-2}, y(t_{i-2})) - 9 f(t_{i-3}, y(t_{i-3}))] + \frac{251}{720} y^{(5)}(\hat{\mu}_i) h^5,$$

for some  $\hat{\mu}_i \in (t_{i-3}, t_{i+1})$ . The assumption that the approximations  $w_0, w_1, \dots, w_i$  are all exact implies that the Adams-Bashforth local truncation error is

$$\frac{y(t_{i+1}) - w_{i+1,p}}{h} = \frac{251}{720} y^{(5)}(\hat{\mu}_i) h^4.$$
 (5.40)