

Getting and Cleaning Data Codebook

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Introduction:

The Getting and Cleaning Data Codebook project is based on The Human Activity Recognition Dataset (for a description of the dataset see Sources). Starting from this dataset I wrote a script that performs the following operations:

1. Merges the training and the test sets to create one data set.
2. Extracts only the measurements on the mean and standard deviation for each measurement.
3. Uses descriptive activity names to name the activities in the data set
4. Appropriately labels the data set with descriptive variable names.
5. From the data set in step 4, creates a second, independent tidy data set with the average of each variable for each activity and each subject.

More details on how to use the script in the readme.md file.

Note: As I have no admin rights on this computer and the time to submit the project is running out, I created this pdf with word – I could not install Latex that is needed to print pdfs from an R Markdown document. In the project description, it was not specified how the pdf should be produced, however I included an Rmd version of the Codebook.

Variables Description

- | | |
|---|---------------|
| 1. Subjects | Integer 1..30 |
| Identifier of the subject who carried out the experiment. | |
| 2. ActivityLabels | String |
| Labels of the six activities performed by each of the subjects wearing a smartphone (Samsung Galaxy S II) on the waist. | |
| LAYING | |
| SITTING | |
| STANDING | |
| WALKING | |
| WALKING_DOWNSTAIRS | |
| WALKING_UPSTAIRS | |
| 3. TimeBodyAccelerationStandardDeviationX | Decimal |
| Standard Deviation of the accelerometer body signal measured along the Axis X | |
| 4. TimeBodyAccelerationStandardDeviationY | Decimal |
| Standard Deviation of the accelerometer body signal measured along the Axis Y | |
| 5. TimeBodyAccelerationStandardDeviationZ | Decimal |
| Standard Deviation of the accelerometer body signal measured along the Axis Z | |
| 6. TimeGravityAccelerationStandardDeviationX | Decimal |
| Standard Deviation of the accelerometer Gravity signal measured along the Axis X | |
| 7. TimeGravityAccelerationStandardDeviationY | Decimal |

Standard Deviation of the accelerometer Gravity signal measured along the Axis Y

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|-----|--|---------|
| 8. | TimeGravityAccelerationStandardDeviationZ | Decimal |
| | Standard Deviation of the accelerometer Gravity signal measured along the Axis Z | |
| 9. | TimeBodyAccelerationJerkStandardDeviationX | Decimal |
| | Standard Deviation of the accelerometer body Jerk signal measured along the Axis X | |
| 10. | TimeBodyAccelerationJerkStandardDeviationY | Decimal |
| | Standard Deviation of the accelerometer body Jerk signal measured along the Axis Y | |
| 11. | TimeBodyAccelerationJerkStandardDeviationZ | Decimal |
| | Standard Deviation of the accelerometer body Jerk signal measured along the Axis Z | |
| 12. | TimeBodyGyroscopeStandardDeviationX | Decimal |
| | Standard Deviation of the Gyroscope body signal measured along the Axis X | |
| 13. | TimeBodyGyroscopeStandardDeviationY | Decimal |
| | Standard Deviation of the Gyroscope body signal measured along the Axis Y | |
| 14. | TimeBodyGyroscopeStandardDeviationZ | Decimal |
| | Standard Deviation of the Gyroscope body signal measured along the Axis Z | |
| 15. | TimeBodyGyroscopeJerkStandardDeviationX | Decimal |
| | Standard Deviation of the Gyroscope body Jerk signal measured along the Axis X | |
| 16. | TimeBodyGyroscopeJerkStandardDeviationY | Decimal |
| | Standard Deviation of the Gyroscope body Jerk signal measured along the Axis Y | |
| 17. | TimeBodyGyroscopeJerkStandardDeviationZ | Decimal |
| | Standard Deviation of the Gyroscope body Jerk signal measured along the Axis Z | |
| 18. | TimeBodyAccelerationMagnitudeStandardDeviation | Decimal |
| | Standard Deviation of the Magnitude accelerometer body signal | |
| 19. | TimeGravityAccelerationMagnitudeStandardDeviation | Decimal |
| | Standard Deviation of the Magnitude accelerometer Gravity signal | |
| 20. | TimeBodyAccelerationJerkMagnitudeStandardDeviation | Decimal |
| | Standard Deviation of the Magnitude accelerometer body Jerk signal | |
| 21. | TimeBodyGyroscopeMagnitudeStandardDeviation | Decimal |
| | Standard Deviation of the Magnitude Gyroscope body signal | |
| 22. | TimeBodyGyroscopeJerkMagnitudeStandardDeviation | Decimal |
| | Standard Deviation of the Magnitude Gyroscope body Jerk signal | |
| 23. | FrequencyBodyAccelerationStandardDeviationX | Decimal |
| | Standard Deviation of the accelerometer body signal measured along the Axis X | |

- | | |
|--|---------|
| 24. FrequencyBodyAccelerationStandardDeviationY | Decimal |
| Standard Deviation of the accelerometer body signal measured along the Axis Y | |
| 25. FrequencyBodyAccelerationStandardDeviationZ | Decimal |
| Standard Deviation of the accelerometer body signal measured along the Axis Z | |
| 26. FrequencyBodyAccelerationJerkStandardDeviationX | Decimal |
| Standard Deviation of the accelerometer body Jerk signal measured along the Axis X | |
| 27. FrequencyBodyAccelerationJerkStandardDeviationY | Decimal |
| Standard Deviation of the accelerometer body Jerk signal measured along the Axis Y | |
| 28. FrequencyBodyAccelerationJerkStandardDeviationZ | Decimal |
| Standard Deviation of the accelerometer body Jerk signal measured along the Axis Z | |
| 29. FrequencyBodyGyroscopeStandardDeviationX | Decimal |
| Standard Deviation of the Gyroscope body signal measured along the Axis X | |
| 30. FrequencyBodyGyroscopeStandardDeviationY | Decimal |
| Standard Deviation of the Gyroscope body signal measured along the Axis Y | |
| 31. FrequencyBodyGyroscopeStandardDeviationZ | Decimal |
| Standard Deviation of the Gyroscope body signal measured along the Axis Z | |
| 32. FrequencyBodyAccelerationMagnitudeStandardDeviation | Decimal |
| Standard Deviation of the Magnitude accelerometer body signal | |
| 33. FrequencyBodyBodyAccelerationJerkMagnitudeStandardDeviation | Decimal |
| Standard Deviation of the Magnitude accelerometer body Jerk signal | |
| 34. FrequencyBodyBodyGyroscopeMagnitudeStandardDeviation | Decimal |
| Standard Deviation of the Magnitude Gyroscope body signal | |
| 35. FrequencyBodyBodyGyroscopeJerkMagnitudeStandardDeviation | Decimal |
| Standard Deviation of the Magnitude Gyroscope body Jerk signal | |
| 36. TimeBodyAccelerationmeanX | Decimal |
| Mean of the accelerometer body signal measured along the Axis X | |
| 37. TimeBodyAccelerationmeanY | Decimal |
| Mean of the accelerometer body signal measured along the Axis Y | |
| 38. TimeBodyAccelerationmeanZ | Decimal |
| Mean of the accelerometer body signal measured along the Axis Z | |
| 39. TimeGravityAccelerationmeanX | Decimal |
| Mean of the accelerometer Gravity signal measured along the Axis X | |

40. TimeGravityAccelerationmeanY	Decimal
Mean of the accelerometer Gravity signal measured along the Axis Y	
41. TimeGravityAccelerationmeanZ	Decimal
Mean of the accelerometer Gravity signal measured along the Axis Z	
42. TimeBodyAccelerationJerkmeanX	Decimal
Mean of the accelerometer body Jerk signal measured along the Axis X	
43. TimeBodyAccelerationJerkmeanY	Decimal
Mean of the accelerometer body Jerk signal measured along the Axis Y	
44. TimeBodyAccelerationJerkmeanZ	Decimal
Mean of the accelerometer body Jerk signal measured along the Axis Z	
45. TimeBodyGyroskopemeanX	Decimal
Mean of the Gyroscope body signal measured along the Axis X	
46. TimeBodyGyroskopemeanY	Decimal
Mean of the Gyroscope body signal measured along the Axis Y	
47. TimeBodyGyroskopemeanZ	Decimal
Mean of the Gyroscope body signal measured along the Axis Z	
48. TimeBodyGyroscopeJerkmeanX	Decimal
Mean of the Gyroscope body Jerk signal measured along the Axis X	
49. TimeBodyGyroscopeJerkmeanY	Decimal
Mean of the Gyroscope body Jerk signal measured along the Axis Y	
50. TimeBodyGyroscopeJerkmeanZ	Decimal
Mean of the Gyroscope body Jerk signal measured along the Axis Z	
51. TimeBodyAccelerationMagnitudemean	Decimal
Mean of the Magnitude accelerometer body signal	
52. TimeGravityAccelerationMagnitudemean	Decimal
Mean of the Magnitude accelerometer Gravity signal	
53. TimeBodyAccelerationJerkMagnitudemean	Decimal
Mean of the Magnitude accelerometer body Jerk signal	
54. TimeBodyGyroscopeMagnitudemean	Decimal
Mean of the Magnitude Gyroscope body signal	
55. TimeBodyGyroscopeJerkMagnitudemean	Decimal
Mean of the Magnitude Gyroscope body Jerk signal	
56. FrequencyBodyAccelerationmeanX	Decimal

	Mean of the accelerometer body signal measured along the Axis X	
57. FrequencyBodyAccelerationmeanY	Mean of the accelerometer body signal measured along the Axis Y	Decimal
58. FrequencyBodyAccelerationmeanZ	Mean of the accelerometer body signal measured along the Axis Z	Decimal
59. FrequencyBodyAccelerationMeanFrequencyX	Mean Frequency of the accelerometer body signal measured along the Axis X	Decimal
60. FrequencyBodyAccelerationMeanFrequencyY	Mean Frequency of the accelerometer body signal measured along the Axis Y	Decimal
61. FrequencyBodyAccelerationMeanFrequencyZ	Mean Frequency of the accelerometer body signal measured along the Axis Z	Decimal
62. FrequencyBodyAccelerationJerkmeanX	Mean of the accelerometer body Jerk signal measured along the Axis X	Decimal
63. FrequencyBodyAccelerationJerkmeanY	Mean of the accelerometer body Jerk signal measured along the Axis Y	Decimal
64. FrequencyBodyAccelerationJerkmeanZ	Mean of the accelerometer body Jerk signal measured along the Axis Z	Decimal
65. FrequencyBodyAccelerationJerkMeanFrequencyX	Mean Frequency of the accelerometer body Jerk signal measured along the Axis X	Decimal
66. FrequencyBodyAccelerationJerkMeanFrequencyY	Mean Frequency of the accelerometer body Jerk signal measured along the Axis Y	Decimal
67. FrequencyBodyAccelerationJerkMeanFrequencyZ	Mean Frequency of the accelerometer body Jerk signal measured along the Axis Z	Decimal
68. FrequencyBodyGyroscopemeanX	Mean of the Gyroscope body signal measured along the Axis X	Decimal
69. FrequencyBodyGyroscopemeanY	Mean of the Gyroscope body signal measured along the Axis Y	Decimal
70. FrequencyBodyGyroscopemeanZ	Mean of the Gyroscope body signal measured along the Axis Z	Decimal
71. FrequencyBodyGyroscopeMeanFrequencyX	Mean Frequency of the Gyroscope body signal measured along the Axis X	Decimal
72. FrequencyBodyGyroscopeMeanFrequencyY		Decimal

Mean Frequency of the Gyroscope body signal measured along the Axis Y

73. FrequencyBodyGyroscopeMeanFrequencyZ	Decimal
Mean Frequency of the Gyroscope body signal measured along the Axis Z	
74. FrequencyBodyAccelerationMagnitudemean	Decimal
Mean Frequency of the Magnitude accelerometer body signal	
75. FrequencyBodyAccelerationMagnitudeMeanFrequency	Decimal
Mean Frequency of the Magnitude accelerometer body signal	
76. FrequencyBodyBodyAccelerationJerkMagnitudemean	Decimal
Mean of the Magnitude accelerometer body Jerk signal	
77. FrequencyBodyBodyAccelerationJerkMagnitudeMeanFrequency	Decimal
Mean Frequency of the Magnitude accelerometer body Jerk signal	
78. FrequencyBodyBodyGyroscopeMagnitudemean	Decimal
Mean of the Magnitude Gyroscope body signal	
79. FrequencyBodyBodyGyroscopeMagnitudeMeanFrequency	Decimal
Mean Frequency of the Magnitude Gyroscope body signal	
80. FrequencyBodyBodyGyroscopeJerkMagnitudemean	Decimal
Mean of the Magnitude Gyroscope body Jerk signal	
81. FrequencyBodyBodyGyroscopeJerkMagnitudeMeanFrequency	Decimal
Mean Frequency of the Magnitude Gyroscope body Jerk signal	

Sources:

The Human Activity Recognition Dataset

The experiments have been carried out with a group of 30 volunteers within an age bracket of 19-48 years. Each person performed six activities (WALKING, WALKING_UPSTAIRS, WALKING_DOWNSTAIRS, SITTING, STANDING, LAYING) wearing a smartphone (Samsung Galaxy S II) on the waist. Using its embedded accelerometer and gyroscope, we captured 3-axial linear acceleration and 3-axial angular velocity at a constant rate of 50Hz. The experiments have been video-recorded to label the data manually. The obtained dataset has been randomly partitioned into two sets, where 70% of the volunteers was selected for generating the training data and 30% the test data.

The sensor signals (accelerometer and gyroscope) were pre-processed by applying noise filters and then sampled in fixed-width sliding windows of 2.56 sec and 50% overlap (128 readings/window). The sensor acceleration signal, which has gravitational and body motion components, was separated using a Butterworth low-pass filter into body acceleration and gravity. The gravitational force is assumed to have only low frequency components, therefore a filter with 0.3 Hz cutoff frequency was used. From each window, a vector of features was obtained by calculating variables from the time and frequency domain. See 'features_info.txt' for more details.

For each record it is provided:

- Triaxial acceleration from the accelerometer (total acceleration) and the estimated body acceleration.
- Triaxial Angular velocity from the gyroscope.
- A 561-feature vector with time and frequency domain variables.
- Its activity label.
- An identifier of the subject who carried out the experiment.

The features selected for this database come from the accelerometer and gyroscope 3-axial raw signals tAcc-XYZ and tGyro-XYZ. These time domain signals (prefix 't' to denote time) were captured at a constant rate of 50 Hz. Then they were filtered using a median filter and a 3rd order low pass Butterworth filter with a corner frequency of 20 Hz to remove noise. Similarly, the acceleration signal was then separated into body and gravity acceleration signals (tBodyAcc-XYZ and tGravityAcc-XYZ) using another low pass Butterworth filter with a corner frequency of 0.3 Hz.

Subsequently, the body linear acceleration and angular velocity were derived in time to obtain Jerk signals (tBodyAccJerk-XYZ and tBodyGyroJerk-XYZ). Also the magnitude of these three-dimensional signals were calculated using the Euclidean norm (tBodyAccMag, tGravityAccMag, tBodyAccJerkMag, tBodyGyroMag, tBodyGyroJerkMag).

Finally a Fast Fourier Transform (FFT) was applied to some of these signals producing fBodyAcc-XYZ, fBodyAccJerk-XYZ, fBodyGyro-XYZ, fBodyAccJerkMag, fBodyGyroMag, fBodyGyroJerkMag. (Note the 'f' to indicate frequency domain signals).

These signals were used to estimate variables of the feature vector for each pattern: '-XYZ' is used to denote 3-axial signals in the X, Y and Z directions.

tBodyAcc-XYZ
tGravityAcc-XYZ
tBodyAccJerk-XYZ
tBodyGyro-XYZ
tBodyGyroJerk-XYZ
tBodyAccMag
tGravityAccMag
tBodyAccJerkMag
tBodyGyroMag
tBodyGyroJerkMag
fBodyAcc-XYZ
fBodyAccJerk-XYZ
fBodyGyro-XYZ
fBodyAccMag
fBodyAccJerkMag
fBodyGyroMag
fBodyGyroJerkMag

The set of variables that were estimated from these signals are:

mean(): Mean value

std(): Standard deviation
mad(): Median absolute deviation
max(): Largest value in array
min(): Smallest value in array
sma(): Signal magnitude area
energy(): Energy measure. Sum of the squares divided by the number of values.
iqr(): Interquartile range
entropy(): Signal entropy
arCoeff(): Autorregresion coefficients with Burg order equal to 4
correlation(): correlation coefficient between two signals
maxInds(): index of the frequency component with largest magnitude
meanFreq(): Weighted average of the frequency components to obtain a mean frequency
skewness(): skewness of the frequency domain signal
kurtosis(): kurtosis of the frequency domain signal
bandsEnergy(): Energy of a frequency interval within the 64 bins of the FFT of each window.
angle(): Angle between two vectors.

Additional vectors obtained by averaging the signals in a signal window sample. These are used on the angle() variable:

gravityMean
tBodyAccMean
tBodyAccJerkMean
tBodyGyroMean
tBodyGyroJerkMean