

Conditional Expectations relative to σ -algebras

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Def: Let (Ω, \mathcal{F}, P) be a prob. space, $\mathcal{G} \subset \mathcal{F}$ be a σ -algebra, and $X \in L^1(\Omega, \mathcal{F}, P)$

The conditional expectation of X given \mathcal{G} : $E[X|\mathcal{G}]$
is a random variable such that

(i) $E[X|\mathcal{G}]$ is \mathcal{G} measurable

(ii) $\int_A E[X|\mathcal{G}] dP = \int_A X dP \quad \text{for all } A \in \mathcal{G}$

Remark: if $\mathcal{G} = \sigma(Y)$ for some random variable Y
we define $E[X|Y] := E[X|\sigma(Y)]$

examples:

(1) $\mathcal{G} = \mathcal{F} \Rightarrow E[X|\mathcal{G}] = X$

(2) $\mathcal{G} = \{\emptyset, \Omega\} \Rightarrow E[X|\mathcal{G}] = EX$

(i) EX is a constant, thus it is \mathcal{G} measurable

(ii) if $A \in \mathcal{G}$ then $A = \Omega$ or \emptyset

$$\int_{\Omega} EX dP = EX \cdot \int_{\Omega} 1 dP = EX = \int_{\Omega} X dP$$

(3) let $D \in \mathcal{F}$: $\mathcal{G} = \sigma(1_D) = \{\emptyset, D, D^c, \Omega\}$

$\Rightarrow E[X|\mathcal{G}] = E[X|1_D]$ is a random variable
measurable with respect to \mathcal{G} .

$\leadsto E[X|\mathcal{G}]$ should be constant on D and on D^c

Recall : if σ -algebra \mathcal{G} is generated by a finite or countably infinite partition of Ω then

[X is \mathcal{G} measurable iff X is constant on each element of this partition]

$$E[X|1_D] = \begin{cases} c_1 & \text{on } D \\ c_2 & \text{on } D^c \end{cases}$$

How to find c_1, c_2 ?

$$\int_{\Omega} E[X|1_D] dP = \int_{\Omega} X dP \quad \left\{ \Rightarrow c_1 = \frac{\int_X dP}{P(D)} \right.$$

$$\int_{\Omega} E[X|1_D] dP = \int_{\Omega} c_1 dP = c_1 \cdot P(D) \quad \left. \right\}$$

similarly $c_2 = \frac{\int_{\Omega^c} X dP}{P(\Omega^c)}$

- in particular : if $\Omega = [0,1]$; $\mathcal{F} = \mathcal{B}_{[0,1]}$; $P = m_{[0,1]}$
and $D = [0, \frac{1}{3}]$; $X(\omega) = \underset{1/3}{w}$, then

$$\rightsquigarrow E[X|1_D](\omega) = \frac{1}{P([0, \frac{1}{3}])} \cdot \int_0^{1/3} w dw = 3 \cdot \frac{w^2}{2} \Big|_0^{1/3} = \frac{1}{6}$$

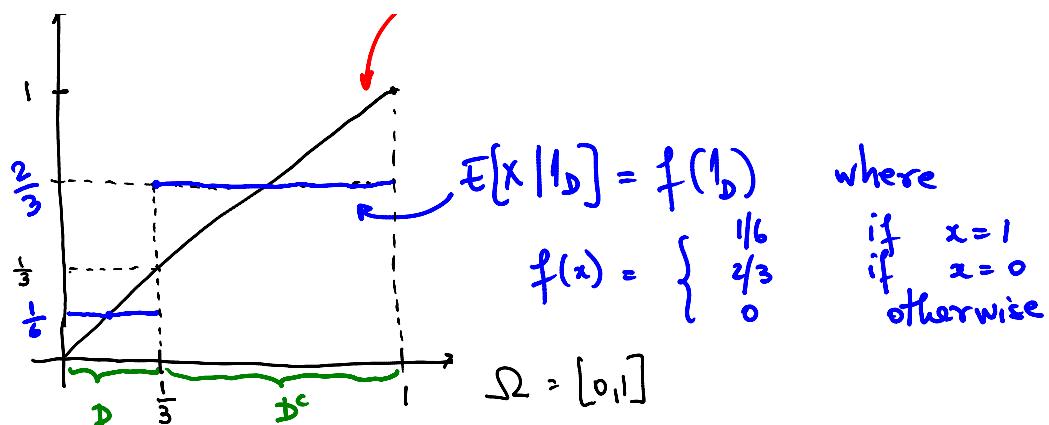
if $w \in [0, \frac{1}{3}]$

$$\rightsquigarrow E[X|1_D](\omega) = \frac{1}{P([\frac{1}{3}, 1])} \int_{1/3}^1 w dw = \frac{3}{2} \cdot \frac{w^2}{2} \Big|_{1/3}^1 = \frac{2}{3}$$

if $w \in (\frac{1}{3}, 1]$

$X(\omega)$

↑



(4) This example can be generalized to the case when \mathcal{G} is generated by a finite or countably infinite partition. $\Leftrightarrow \mathcal{G} = \sigma(Y)$ where Y is discrete r.v.

- More precisely, let D_1, D_2, \dots form a partition of Ω : $D_i \in \mathcal{F}$, $P(D_i) > 0$

\Rightarrow let $\mathcal{G} = \sigma(D_1, D_2, \dots)$, $X \in L^1(\Omega, \mathcal{F}, P)$ then

$$E[X|\mathcal{G}](\omega) = \frac{\int_{D_i} X dP}{P(D_i)} \quad \text{for } \omega \in D_i$$

- if $\mathcal{G} = \sigma(Y)$, where Y is discrete then

$$E[X|Y](\omega) = \frac{\int_{\{Y=y_i\}} X dP}{P(Y=y_i)} \quad \text{for } \omega : Y(\omega) = y_i$$

- let's get back to the general def.

Questions regarding $E[X|\mathcal{G}]$: Existence ; Uniqueness

\Rightarrow the answers come from Radon-Nikodym th.

- Let $X \geq 0$, s.t. $E[X] \neq 0$; define $\Omega : \mathcal{G} \rightarrow [0,1]$ s.t.

$$\int_X dP$$

$$Q(A) = \frac{\int_A X dP}{\int \infty} \quad \text{for all } A \in \mathcal{G}$$

$\Rightarrow Q$ is a prob. measure and $Q \ll P$.
(easy to check)

By R-N th. there exists a r.v. $Z(\omega)$ which is \mathcal{G} measurable, such that

$$Q(A) = \int_A Z(\omega) dP(\omega)$$

thus: $\int_A Z(\omega) dP(\omega) = \int_A \frac{X(\omega)}{E[X]} dP(\omega) \quad (\dagger) \quad A \in \mathcal{G}$

def of $E[X|G]$

$\Rightarrow Z(\omega) \cdot E[X]$ satisfies (i) & (ii)

since $Z(\omega)$ is unique $\Rightarrow E[X|G]$ exists and is unique.

② In general: $X = X^+ - X^-$ so we use the existence & uniqueness for X^+, X^-

$$E[X|G] = E[X^+|G] - E[X^-|G]$$

Corollary: If $X \geq 0$ then $E[X|G] \geq 0$ a.s.

If $X \geq Y \geq 0$ then $E[X|G] \geq E[Y|G]$ a.s.

MCT If $X_n \geq 0$, $X_n \uparrow X$ a.s. then $E[X_n|G] \uparrow E[X|G]$ a.s.

DCT If $\lim_{n \rightarrow \infty} X_n = X$ a.s. and $|X_n| \leq Y$ a.s., $Y \in L^1$

then $E[X|G] = E[Y|G]$ a.s.

$$\text{then } \lim_{n \rightarrow \infty} E[X_n | \mathcal{G}] = E[X | \mathcal{G}] \quad \text{a.s.}$$

Proof of MCT.

- Let $Y_n = E[X_n | \mathcal{G}]$; $Y = \lim_{n \rightarrow \infty} Y_n$ (a.s.)

Y_n is \mathcal{G} measurable $\Rightarrow Y$ is \mathcal{G} measurable also

- Moreover, for all $A \in \mathcal{G}$ we have

$$1_A Y_n \uparrow 1_A Y \text{ a.s. as } n \rightarrow \infty$$

- Monotone Convergence Th. gives :

$$E[1_A Y_n] = \int_A Y_n dP = \int_A X_n dP \xrightarrow{\substack{\text{(ii)} \\ \uparrow}} \int_A X dP \quad \left. \begin{array}{l} \xrightarrow{\text{MCT}} \\ \Rightarrow \end{array} \right.$$

also $E[1_A Y_n] \rightarrow E[1_A Y] = \int_A Y dP$

$$\Rightarrow Y = E[X | \mathcal{G}] \quad \text{a.s.}$$

Theorem : Let $X_1, X_2, X \in L^1(\Omega, \mathcal{F}, P)$, $\mathcal{G}, \mathcal{H} \subset \mathcal{F}$ σ -alg.

(A) Linearity: $E[c_1 X_1 + c_2 X_2 | \mathcal{G}] = c_1 E[X_1 | \mathcal{G}] + c_2 E[X_2 | \mathcal{G}]$

(B) "Taking out what is known":

assume X_1 is \mathcal{G} measurable, $X_1 X_2 \in L^1(\Omega, \mathcal{F}, P)$, then

$$E[X_1 X_2 | \mathcal{G}] = X_1 \cdot E[X_2 | \mathcal{G}]$$

(C) Tower Property : if $\mathcal{H} \subset \mathcal{G}$, then

** $E[E[X | \mathcal{G}] | \mathcal{H}] = E[X | \mathcal{H}]$

$$\textcircled{*} \quad E\left[E[X|G] | G \right] = E[X|G]$$

D) If X is independent of G then: $E[X|G] = EX$

E) Conditional Jensen's inequality: $\varphi(\cdot)$ convex

$$\varphi(E[X|G]) \leq E[\varphi(X)|G]$$

F) $\begin{cases} \cdot \|E(X|G)\|_p \leq \|X\|_p & \text{for } p \geq 1 \\ \cdot X_n \xrightarrow{L^2} X \Rightarrow E(X_n|G) \xrightarrow{L^2} E(X|G) \end{cases}$

G) Repeated Conditioning: assume

$$G_0 \subset G_1 \subset G_2 \subset \dots \subset G_\infty = \sigma\left(\bigcup_{n=1}^\infty G_n\right)$$

$X \in L^p$ with $p \geq 1$. Then

$$E[X|G_n] \rightarrow E[X|G_\infty] \quad \text{a.s.}$$

$$E[X|G_n] \rightarrow E[X|G_\infty] \quad \text{in } L^p$$

Proofs: A) follows from the uniqueness of the cond. expectation

B) standard argument:

$$\text{Step 1: } X_1 = I_D, D \in G \Rightarrow$$

$$E(X_1 X_2 | G) = E(I_D X_2 | G) \quad \text{and for all } A \in G$$

$$\int_A E(I_D X_2 | G) dP = \int_A I_D X_2 dP - \int_A X_2 dP = \int_A E(X_2 | G) dP$$

$$= \int_A I_D E(X_2 | G) dP$$

- since both $E(I_D X_2 | G)$ and $I_D E(X_2 | G)$ are G meas.
and both satisfy (ii) by the uniqueness of th..

and both satisfy (ii), by the uniqueness of the conditional expectation we have

$$E(1_D X_2 | \mathcal{G}) = 1_D E(X_2 | \mathcal{G}) \text{ a.s}$$

Step 2: extends the equality by linearity to the case where X_i is a linear combination of indicator functions of some sets in \mathcal{G} . (X_i = simple r.v \mathcal{G} meas.)

Step 3: extends to all $X_i \geq 0$ by MCT

Step 4: extends to all $X_i \in L^1(\Omega, \mathcal{G}, P)$ by
 $X_i = X_i^+ - X_i^-$

(c) ~~obvious~~ obvious

**

- for any $G \in \mathcal{G}$: $\int_G E(X|G) dP = \int_G X dP$
- for any $H \in \mathcal{H}$: $\int_H E(X|\mathcal{H}) dP = \int_H X dP$
- but $\mathcal{H} \subseteq \mathcal{G} \Rightarrow H \in \mathcal{G}$

$$\int_H E(X|G) dP = \int_H E(X|\mathcal{H}) dP \quad (\forall) H \in \mathcal{H}$$

$$\Rightarrow E(E(X|G) | \mathcal{H}) = E(X|\mathcal{H}) \text{ a.s.}$$

(D) X is independent of $\mathcal{G} \Leftrightarrow (\forall A \in \mathcal{G}), X$ and 1_A are independent

$$\Rightarrow E(X|1_A) = E(X) \cdot E(1_A)$$

- for an arbitrary $A \in \mathcal{G}$

$$\begin{aligned}
 \int_A E(X|G) dP &= \int_{\Omega} X dP = \int_{\Omega} X \cdot 1_A dP = E(X \cdot 1_A) \\
 &= EX \cdot E 1_A = EX \cdot P(A) = \int_A EX dP \\
 \Rightarrow \int_A [E(X|G) - EX] dP &= 0 \quad (\forall A \in G)
 \end{aligned}$$

- since $E(X|G) - EX$ is G measurable \Rightarrow it has to be equal to 0. a.s.

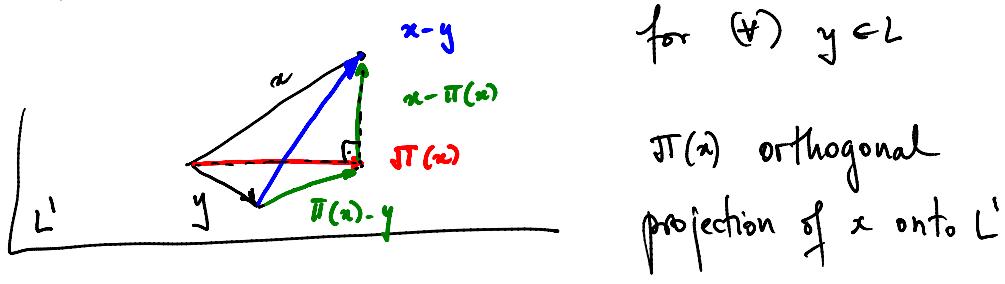
- (E) proof is omitted.
(F) easy consequence of Jensen's ineq.
(G) proof is omitted.

Theorem : let $X \in L^2(\Omega, \mathcal{F}, P)$, $G \subset \mathcal{F}$ σ -algebra, $Y \in L^1(\Omega, G, P)$

$$\Rightarrow E(X - E(X|G))^2 \leq E(X - Y)^2$$

$\rightarrow E(X|G)$ is the best approximation to X in L^2 sense among all G measurable and square integrable r.v.

Analogy with : $\|x - y\|^2 = \|x - \pi(x)\|^2 + \|\pi(x) - y\|^2$



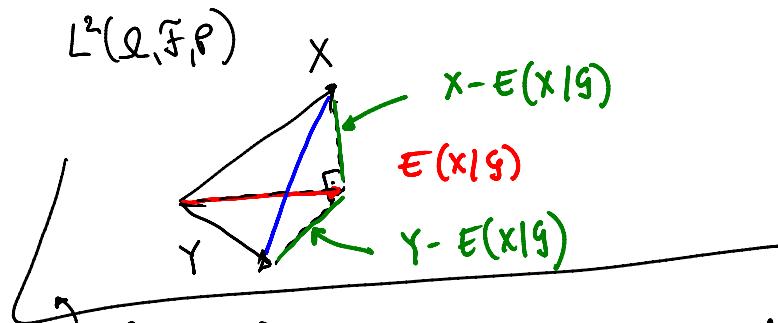
$\pi(x)$ orthogonal projection of x onto L'

$$\|x - y\|^2 = \|x - \pi(x)\|^2 + \|\pi(x) - y\|^2$$

$$\|x-y\|^2 \geq \|x-\pi(x)\|^2 \text{ for all } y \in L$$

$$\Rightarrow \|x-\pi(x)\|^2 = \min_{y \in L} \|x-y\|^2$$

• in terms of conditional expectation



$L^2(S, G, P)$ is a closed subspace of $L^2(Q, F, P)$

$\langle X, Y \rangle := E(XY) \rightsquigarrow$ scalar product in L^2

$$E(X|G) - Y \perp X - E(X|G)$$

which means $E\left[\overbrace{(E(X|G) - Y)}^{\rightarrow} (X - E(X|G))\right] = 0$

$$E\left[X \cdot E(X|G) - [E(X|G)]^2 - XY + YE(X|G)\right] =$$

$$E\left[\overbrace{X \cdot E(X|G)}^{=0} - (E(X|G))^2\right] - EXY + E(YE(X|G)) \stackrel{=} 0$$

• now recall Y is G measurable \Rightarrow

$$YE(X|G) = E(XY|G)$$

$$\text{and also } E(E(XY|G)) = E(XY)$$

(we have used "Tower" property & "Take out what is known")

• on the other hand

$\underbrace{g\text{-measurable (known)}}$

$$\{ E(XE(X|G)) = E(\underbrace{E(X \cdot E(X|G))}_{g\text{-measurable}}|G) \}$$

$$\left\{ \begin{array}{l} E(X \in (x|G)) = E(E(X \in (x|G) | G)) \\ = E(E(X|G) \cdot E(X|G)) = E((E(X|G))^2) \end{array} \right.$$

• suppose (X, Y) has a joint density $f(x,y)$
 $G = \sigma(Y)$. How to find $E(X|Y) = ?$

• answer: $f_{X|Y}(x|y) = \begin{cases} \frac{f(x,y)}{f_Y(y)} & \text{if } f_Y(y) \neq 0 \\ 0 & \text{if } f_Y(y) = 0 \end{cases}$

conditional density of X given $Y=y$

$$\Rightarrow E[X|Y=y] = \int_{-\infty}^{+\infty} x f_{X|Y}(x|y) dx$$

$$E[X|Y](w) = \int_{-\infty}^{+\infty} x f_{X|Y}(x|Y(w)) dx$$

↑ random, depends on w

example: X = Poisson r.v. with parameter λ

S = nr of successes in X independent Bernoulli trials with prob of success p :

Find $E(S|X)$ and $E(X|S)$

solution:

- given $X=n$: $P(S=k | X=n) = \binom{n}{k} p^k (1-p)^{n-k}$
 (Binomial distr. (n,p))

$$\Rightarrow E(S|X=n) = n \cdot p ; \quad E(S|X) = X \cdot p$$

• Given $S=k$ let's find $E(X|S=k)$

$$= \sum_{n=k}^{\infty} n \cdot P(X=n | S=k) =$$

$$= \sum_{n=k}^{\infty} n \cdot \frac{P(X=n, S=k)}{P(S=k)} =$$

$$= \sum_{n=k}^{\infty} n \cdot \frac{P(X=n) \cdot P(S=k | X=n)}{\sum_{m=k}^{\infty} P(X=m) \cdot P(S=k | X=m)}$$

$$= \sum_{n=k}^{\infty} n \cdot \frac{\cancel{e^{-\lambda}} \frac{\lambda^n}{n!} \cdot \binom{n}{k} p^k (1-p)^{n-k}}{\sum_{m=k}^{\infty} \cancel{e^{-\lambda}} \frac{\lambda^m}{m!} \binom{m}{k} p^k (1-p)^{m-k}}$$

$$= \sum_{n=k}^{\infty} n \cdot \frac{\frac{[(1-p)\lambda]^{n-k}}{(n-k)!} \cdot \cancel{\frac{\lambda^k}{k!}}}{\sum_{m=k}^{\infty} \frac{[(1-p)\lambda]^{m-k}}{(m-k)!} \cdot \cancel{\frac{\lambda^k}{k!}}}$$

$$= \sum_{n=k}^{\infty} n \cdot \frac{\frac{[(1-p)\lambda]^{n-k}}{(n-k)!}}{e^{(1-p)\lambda}}$$

$$= \sum_{n-k=0}^{\infty} (n-k) \frac{[(1-p)\lambda]^{n-k}}{(n-k)!} e^{-(1-p)\lambda} + \sum_{n-k=0}^{\infty} k \cdot \frac{[(1-p)\lambda]^{n-k}}{(n-k)!} \cdot e^{-(1-p)\lambda}$$

$$= \lambda(1-p) + k$$

$$\Rightarrow E(X|S) = \lambda(1-p) + S$$