

# Delta hedging (BAP); Geometric Brownian Motion; Change of measure

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9:04 AM

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The power of action.

① BAP: A-hedging for European claims

- discounted value of the European claim is martingale
- self financing condition
- discrete stochastic integral

② GBM: definition ; limit of binomial models

③ Change of measure:

- in discrete setting  $\rightsquigarrow$  BAP
- in continuous setting  $\rightsquigarrow$  shift of a normal distr.

① at time  $n$ :  $S(n) = S(0) \prod_{i=0}^{n-1} u^{\eta_i}$

(where  $i=0,1,2,\dots,n$ )

- contingent claim pays  $C_{i,n}$  at time  $n$
- the cost of replicating portfolio = the cost of contingent claim

$$C_{0,0} := \frac{1}{1+r} \left[ C_{1,1} \frac{1+r-d}{u-d} + C_{0,1} \frac{u-1-r}{u-d} \right]$$

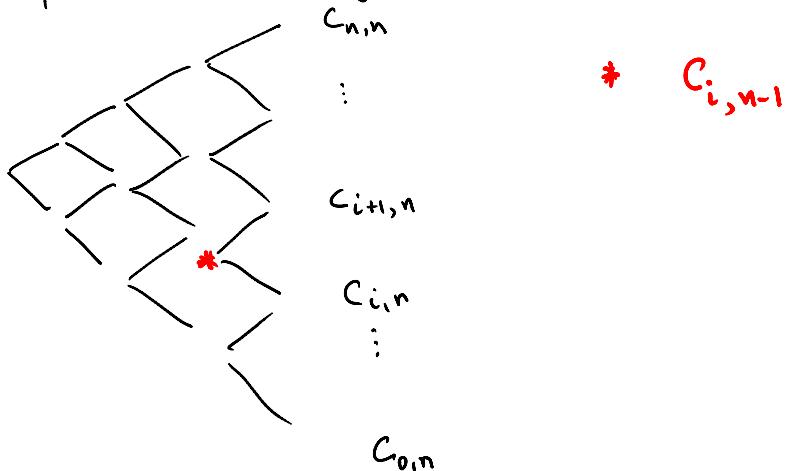
$$= \frac{1}{1+r} \left[ C_{1,1} \tilde{p} + C_{0,1} (1-\tilde{p}) \right]$$

for  $\tilde{p} = \frac{1+r-d}{u-d}$  : the risk neutral prob.

· the portfolio consists of:  
 $\Delta_{0,0} = \frac{C_{1,1} - C_{0,1}}{S(u-d)}$  shares of stock  
 $C_{0,0} - \Delta_{0,0} S$  shares of MMA

$$(C_{0,0} - \Delta_{0,0}S = -\frac{(C_{1,1}d - C_{0,1}u)}{(1+r)(u-d)})$$

. we shall extend this argument by adjusting the replicating portfolio as you travel along the tree  
 (that is , at every moment in time the replicating portfolio has to change to maintain the martingale prop.)



• working backwards along the tree :

$$\left\{ \begin{array}{l} C_{i,n-1} = \frac{1}{1+r} [C_{i+1,n} \tilde{p} + C_{i,n} (1-\tilde{p})] \\ \Delta_{i,n-1} = \frac{C_{i+1,n} - C_{i,n}}{S(n-1) (u-d)} \quad \text{nr of shares at } n-1 \end{array} \right.$$

$$\left\{ \begin{array}{l} C_{i,n-2} = \frac{1}{1+r} [C_{i+1,n-1} \tilde{p} + C_{i,n-1} (1-\tilde{p})] \\ = \frac{1}{(1+r)^2} \left[ C_{i+2,n} \tilde{p}^2 + 2C_{i+1,n} \tilde{p}(1-\tilde{p}) + C_{i,n} (1-\tilde{p})^2 \right] \\ \Delta_{i,n-2} = \frac{C_{i+1,n-1} - C_{i,n-1}}{S(n-2) (u-d)} \end{array} \right.$$

and so on ....

$$C_{0,0} = \frac{1}{(1+r)^n} \sum_{k=0}^n C_{k,n} \binom{n}{k} \tilde{p}^k (1-\tilde{p})^{n-k}$$

→ in general, if we call  $V_m$  the value of the replicating portfolio at time  $m$  then we have established that  $\left\{ \frac{V_m}{(1+r)^m} \right\}_{0 \leq m \leq n}$  is a martingale with respect to the risk neutral probability.

- More formally, we have a sample space  $\Omega$  which consists of all paths of length  $n$  on the binomial tree  
 $w = (w_1, w_2, \dots, w_n) \in \Omega$

$$w_i = \begin{cases} 1 & \text{if stock goes up} \\ 0 & \text{if stock goes down} \end{cases}$$

$$\tilde{P}(w) = \tilde{p}^{\sum_{i=1}^m w_i} (1-\tilde{p})^{n-\sum_{i=1}^m w_i}$$

$$V_m(w) = C_{i,m} \quad \text{if } \sum_{j=1}^m w_j = i$$

$$\Rightarrow \frac{V_m}{(1+r)^m} = \tilde{E} \left[ \frac{V_{m+1}}{(1+r)^{m+1}} \mid S(0), S(1), \dots, S(m) \right]$$

### Conclusions:

- By the Law of One Price the time  $m$  value of a European claim with payoff vector  $(C_{i,m})_{0 \leq i \leq n}$  is equal to  $V_m$  the cost of replicating portfolio ;  $0 \leq m \leq n$

- the discounted value of such claim is a martingale under the risk neutral measure.

## Self-financing condition :

$$V_m = \Delta_m S(m) + (V_m - \Delta_m S(m))$$

- $\Delta_m$  = nr of shares of stock in the replicating portfolio held between time  $m$  and  $m+1$
- at time  $m+1$  the value of this portfolio
  - before rebalancing :  $\Delta_m S(m+1) + (1+r)(V_m - \Delta_m S(m))$
  - after rebalancing :  $\Delta_{m+1} S(m+1) + (V_{m+1} - \Delta_{m+1} S(m+1))$
- the self-financing condition is :

Value before rebalancing = Value after rebalancing

$$\Delta_m S(m+1) + (1+r)(V_m - \Delta_m S(m)) = \Delta_{m+1} S(m+1) + (V_{m+1} - \Delta_{m+1} S(m+1))$$

$$\Rightarrow \Delta_m \frac{S(m+1)}{(1+r)^{m+1}} + \frac{V_m}{(1+r)^m} - \Delta_m \frac{S(m)}{(1+r)^m} = \frac{V_{m+1}}{(1+r)^{m+1}}$$

that is : for all  $0 \leq m \leq n-1$

$$\frac{V_{m+1}}{(1+r)^{m+1}} - \frac{V_m}{(1+r)^m} = \Delta_m \left[ \frac{S(m+1)}{(1+r)^{m+1}} - \frac{S(m)}{(1+r)^m} \right]$$

- adding up these equalities

$$\Rightarrow \frac{V_n}{(1+r)^n} = V_0 + \sum_{m=0}^{n-1} \Delta_m \left[ \frac{S(m+1)}{(1+r)^{m+1}} - \frac{S(m)}{(1+r)^m} \right]$$

→ discounted value of the claim is represented as

stochastic integral with respect to the discounted

## stock price (discrete version of S.I)

Definition : Suppose  $X = \{X_n\}_{n \geq 0}$  is a martingale with respect to  $P$  and the history of  $X$ . Let for each  $n \geq 0$  a random variable  $\Delta_n$  be a function of  $X_0, \dots, X_n$ .

$$Y_n := Y_0 + \sum_{m=0}^{n-1} \Delta_m (X_{m+1} - X_m) \rightarrow Y_t = Y_0 + \int_0^t \Delta_s dX_s$$

where  $Y_0$  is a constant.

We say that  $\{Y_n\}_{n \geq 0}$  is a **discrete stochastic integral** of  $\{\Delta_n\}_{n \geq 0}$  with respect to  $\{X_n\}_{n \geq 0}$

Lemma :  $\{Y_n\}_{n \geq 0}$  is a martingale with respect to the history of  $\{X_n\}_{n \geq 0}$ .

Proof :  $E[Y_{n+1} | X_0, \dots, X_n] = Y_n$  for all  $n$ .

$$\begin{aligned} & E \left[ Y_0 + \sum_{m=0}^n \Delta_m (X_{m+1} - X_m) \mid X_0, \dots, X_n \right] = \\ & = E \left[ Y_n + \Delta_n (X_{n+1} - X_n) \mid X_0, \dots, X_n \right] \\ & = Y_n + \Delta_n E[X_{n+1} - X_n \mid X_n] = Y_n \end{aligned}$$

### ① GBM.

Definition :  $\{S(t)\}_{t \geq 0}$  continuous process is a Geometric Brownian Motion  $(\mu, \sigma)$  if

$$S(t) = S(0) e^{(\mu - \frac{\sigma^2}{2})t + \sigma B(t)}$$

(i)  $\frac{S(t+y)}{S(t)}$  independent of all history up to time  $t$   
 $(y > 0)$

(ii)  $\ln\left(\frac{S(t+y)}{S(t)}\right) \sim N(\mu_y, \sigma_y^2)$

$Z \sim N(0, 1)$

$$\ln\left(\frac{S(t+y)}{S(t)}\right) = \mu_y + Z \cdot \sigma_y$$

$$\Rightarrow S(t+y) = S(t) \cdot \exp\{\mu_y + Z \cdot \sigma_y\}$$

• in particular :  $S(t) = S(0) \exp\{\mu t + Z \cdot \sigma \sqrt{t}\}$

Ex :  $P(S(t+2) > S(t+1) > S(t)) = ?$

$$= P\left(\frac{S(t+2)}{S(t+1)} > 1 > \frac{S(t+1)}{S(t)}\right)$$

$$= P\left(\frac{S(t+2)}{S(t+1)} > 1 ; \frac{S(t+1)}{S(t)} > 1\right)$$

independent events

$$= P\left(\frac{S(t+2)}{S(t+1)} > 1\right) \cdot P\left(\frac{S(t+1)}{S(t)} > 1\right)$$

$$\ln\left(\frac{S(t+2)}{S(t+1)}\right), \ln\left(\frac{S(t+1)}{S(t)}\right) \sim N(\mu, \sigma^2)$$

$$\Rightarrow E S(t) = \exp\{\mu t + \frac{\sigma^2 t}{2}\}$$

$$\Rightarrow \text{Var } S(t) = \exp\{2\mu t + \sigma^2 t\} \cdot (e^{\sigma^2 t} - 1)$$

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GBM ( $\mu, \sigma$ ) as limit of BAP

$h$  = small time increment

$$u = e^{\sigma\sqrt{h}} ; \quad d = e^{-\sigma\sqrt{h}} ; \quad p = \frac{1}{2} \left( 1 + \frac{\mu}{\sigma} \cdot \sqrt{h} \right)$$

- for  $i = 0, 1, 2, \dots$  assume the process  $\{S(ih)\}_{i \geq 0}$  is defined such that  $S(0) > 0$  (constant) and

$$S((i+1)h) = \begin{cases} u S(ih) & \text{with probability } p \\ d S(ih) & \text{with probability } 1-p \end{cases}$$

Moreover, assume that the successive movements are independent. Notice that the independence assumption can be rephrased as follows :

$\frac{S((i+k)h)}{S(ih)}$  is independent of  $S(h), S(2h), \dots, S(ih)$   
(for all  $, k \geq 0$ )

$$\text{Define : } X_i = \begin{cases} 1 & \text{if } S((i+1)h) = u S(ih) \\ 0 & \text{if } S((i+1)h) = d S(ih) \end{cases}$$

Then  $\{X_i\}_{i=0}^n$  are independent and

- $S(nh) = S(0) u^{\sum_{i=1}^n X_i} d^{n - \sum_{i=1}^n X_i}$
- if  $t = nh \Rightarrow n = \frac{t}{h}$  so we can rewrite  $S(nh)$  as

- if  $t = nh \Rightarrow n = \frac{t}{h}$  so we can rewrite  $S(nh)$  as

$$S(t) = S(0) \left(\frac{u}{d}\right)^n \cdot d^{\sum_{i=1}^{t/h} x_i}$$

$$\Rightarrow \log\left(\frac{S(t)}{S(0)}\right) = \frac{t}{h} \log d + \log \frac{u}{d} \left(\sum_{i=1}^{t/h} x_i\right)$$

$$= \frac{t}{h} \cdot (-\sigma\sqrt{h}) + 2\sigma\sqrt{h} \cdot \left(\sum_{i=1}^{t/h} x_i\right)$$

$$= -\frac{t\sigma}{\sqrt{h}} + 2\sigma\sqrt{h} \cdot \underbrace{\sum_{i=1}^{t/h} x_i}_{\sim \text{Normally distributed (CLT)}}$$

- let's calculate  $E \log \frac{S(t)}{S(0)}$ ,  $\text{Var} \log \frac{S(t)}{S(0)}$  to justify the GBM( $\mu, \sigma$ ) approximation of BAP as  $h \rightarrow 0$

$$\begin{aligned} E \log \frac{S(t)}{S(0)} &= -\frac{t\sigma}{\sqrt{h}} + 2\sigma\sqrt{h} \cdot \frac{t}{h} \cdot p \\ &= -\frac{t\sigma}{\sqrt{h}} + 2\sigma\sqrt{h} \cdot \frac{t}{h} \cdot \frac{1}{2} \left(1 + \frac{\mu}{\sigma} - \sqrt{h}\right) \\ &= \mu t \end{aligned}$$

$$\text{Var} \log \frac{S(t)}{S(0)} = 4\sigma^2 h \cdot \frac{t}{h} \cdot p \cdot (1-p) \xrightarrow{\text{as } h \rightarrow 0} \sigma^2 t$$

- Therefore, as  $h \rightarrow 0$ :  $\log \frac{S(t)}{S(0)} \sim N(\mu t, \sigma^2 t)$

which leads immediately to the conclusion that

which leads immediately to the conclusion that  
 $S(t)$  follows a GBM ( $\mu, \sigma$ ).

Risk neutral measure for the price process that follows  
GBM ( $\mu, \sigma$ )

- let  $S(t)$  follow GBM ( $\mu, \sigma$ ).

→ we know that in the BAP model the risk neutral probability is given by  $\tilde{p} = \frac{1+r^*-d}{u-d}$  where

$r^*$  is the one period rate

→ in our approximation :  $u = e^{\sigma\sqrt{h}}$ ;  $d = e^{-\sigma\sqrt{h}}$   
 and the one period rate becomes  $r^* = e^{\frac{rt}{n}} - 1$

→ let us continue to approximate  $u, d, r^*$  as follows

$$\left\{ \begin{array}{l} u = e^{\sigma\sqrt{h}} \approx 1 + \sigma\sqrt{h} + \frac{1}{2}\sigma^2 h \\ d = e^{-\sigma\sqrt{h}} \approx 1 - \sigma\sqrt{h} + \frac{1}{2}\sigma^2 h \\ 1+r^* \approx 1 + \frac{rt}{n} \end{array} \right.$$

use these approximations in the formula  $\tilde{p}$

$$\tilde{p} \approx \frac{1 + \frac{rt}{n} - (1 - \sigma\sqrt{h} + \frac{1}{2}\sigma^2 h)}{2\sigma\sqrt{h}}$$

$$= \frac{1}{2} \left( 1 + \frac{r - \frac{\sigma^2}{2}}{\sigma} \sqrt{\frac{t}{n}} \right)$$

also recall that while approximating BAP with GBM ( $\mu, \sigma$ ) we assumed also that

$$p = \frac{1}{2} \left( 1 + \frac{\mu - \frac{\sigma^2}{2}}{\sigma} \sqrt{\frac{T}{n}} \right)$$

$\rightsquigarrow$  this implies that if we start with the discrete risk neutral process, then as  $n \rightarrow \infty$  we shall obtain a GBM  $(r - \frac{\sigma^2}{2}, \sigma)$

$\rightsquigarrow$  it is not surprising that if  $S(t)$  follows GBM  $(\mu, \sigma)$  then all claims are priced using GBM  $(r - \frac{\sigma^2}{2}, \sigma)$  the **risk neutral GBM**

Example : Price an European Call Option with

$K$  = strike price     $T$  = maturity

$$\rightsquigarrow \text{payoff} = (S(T) - K)^+$$

$$\text{price at time } 0 = \tilde{E} \left[ e^{-rT} (S(T) - K)^+ \right]$$

• model under risk neutral measure : GBM  $(r - \frac{\sigma^2}{2}, \sigma)$

$$S(T) = S(0) \exp \left\{ (r - \frac{\sigma^2}{2})T + \sum_{i=1}^{+\infty} \sigma \sqrt{T} Z_i \right\}$$

$$\cdot \tilde{E} \left[ e^{-rT} (S(T) - K)^+ \right] = \int_0^{+\infty} \tilde{e}^{-rT} \left( S(0) \exp \left\{ (r - \frac{\sigma^2}{2})T + \sum_{i=1}^{+\infty} \sigma \sqrt{T} Z_i \right\} - K \right)^+ \cdot \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx$$

$$\text{Def: } E f(z) = \int_{-\infty}^{+\infty} f(x) \cdot \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx$$

### ③ Change of measure in the discrete setting

$\Omega$  = finite sample space.

- we can define 2 different probability measures on it

1) (†)  $w \in \Omega$  set its probability to be  $p_w$ ,  $p_w \geq 0$ ;  $\sum_{w \in \Omega} p_w = 1$

2) (f)  $w \in \Omega$  set its probability to be  $\tilde{p}_w$ ;  $\tilde{p}_w \geq 0$ ;  $\sum_{w \in \Omega} \tilde{p}_w = 1$

- if  $A \subseteq \Omega$  (is an event), then

$$P(A) = \sum_{w \in A} p_w \quad (\text{for measure } i) \quad \text{and}$$

$$\tilde{P}(A) = \sum_{w \in A} \tilde{p}_w \quad (\text{for measure 2})$$

- also, if  $X: S\mathcal{L} \rightarrow R$

$$E X = \sum'_{w \in Q} X(w) p_w \quad ; \quad \tilde{E} X = \sum'_{w \in Q} X(w) \tilde{p}_w$$

(for measure 1) (for measure 2)

- thus, naturally, the same event will have different measures and the same variable will have different distributions

- notice that if  $p_w > 0$  for all  $w$  we can always write

- notice that if  $p_w > 0$  for all  $w$  we can always write

$$\tilde{P}(A) = \sum'_{w \in A} \tilde{p}_w \cdot \frac{p_w}{\tilde{p}_w} = \sum'_{w \in A} \frac{\tilde{p}_w}{p_w} \cdot p_w$$

and

$$\tilde{E} X = \sum'_{w \in \Omega} X(w) \tilde{p}_w = \sum'_{w \in \Omega} X(w) \frac{\tilde{p}_w}{p_w} \cdot p_w = E[X \cdot Z]$$

where  $Z(w) = \frac{\tilde{p}_w}{p_w}$  for all  $w \in \Omega$

$Z : \Omega \rightarrow \mathbb{R}^+$  is called

**RADON - NIKODYM derivative of  $\tilde{P}$  with respect to  $P$**

- we will also use the following notations for the Radon-Nikodym derivative :

$$Z = \frac{d\tilde{P}}{dP} \quad \text{or} \quad d\tilde{P} = Z \cdot dP$$

Example : Consider two  $n$ -period BAP models with the same  $n, d$  but different probabilities, call them  $p$  and  $\tilde{p}$

$\Omega$  = set of all paths of length  $n$        $w = (w_1, w_2, \dots, w_n)$

$$1) P(w) = p^{\sum_{i=1}^n w_i} (1-p)^{n - \sum_{i=1}^n w_i} > 0$$

$$2) \tilde{P}(w) = \tilde{p}^{\sum_{i=1}^n w_i} (1-\tilde{p})^{n - \sum_{i=1}^n w_i} > 0$$

$$Z(w) = \frac{d\tilde{P}(w)}{dP(w)} = \left( \frac{\tilde{p}}{p} \right)^{\sum_{i=1}^n w_i} \left( \frac{1-\tilde{p}}{1-p} \right)^{n - \sum_{i=1}^n w_i}$$

- the random variable  $\sum_{i=1}^n w_i$  has binomial distribution with parameters  $(n, p)$  in case 1) and  $(n, \tilde{p})$  in case 2)

Definition : The probability measure  $\tilde{P}$  is said to be **absolutely continuous** with respect to measure  $P$  if

$$P(A) = 0 \Rightarrow \tilde{P}(A) = 0$$

Notation :  $\tilde{P} \ll P$  (or  $\tilde{P} \propto P$ )

Definition : If  $\tilde{P} \ll P$  and  $P \ll \tilde{P}$  we say that  $P$  and  $\tilde{P}$  are **equivalent**

Notation :  $\tilde{P} \sim P$

- in our simple setting  $\tilde{P} \ll P$  if  $p_w = 0$  implies  $\tilde{p}_w = 0$ .
- $\tilde{P} \sim P$  if they completely agree on "impossible" and "sure" events.

Example : Let  $\Omega = \{1, 2, 3, 4, 5\}$

$$P: p_1 = \frac{1}{4}, p_2 = \frac{1}{3}, p_3 = \frac{1}{4}, p_4 = \frac{1}{6}, p_5 = 0$$

$$\tilde{P}: \tilde{p}_1 = \frac{1}{3}, \tilde{p}_2 = \frac{1}{3}, \tilde{p}_3 = \frac{1}{3}, \tilde{p}_4 = \tilde{p}_5 = 0$$

Questions : Is  $P \ll \tilde{P}$ ? Is  $\tilde{P} \ll P$ ?

- $p_4 \neq 0, \tilde{p}_4 = 0 \Rightarrow P$  is not absolutely cont. w.r.t.  $\tilde{P}$   
 $\Rightarrow P$  and  $\tilde{P}$  are not equivalent

- on the other hand  $\tilde{P} \ll P$  since whenever  $P(w) = 0$   
 $\tilde{P}(w)$  is also 0.

- since  $\tilde{P} \ll P$  then  $\frac{d\tilde{P}}{dP}$  makes sense

$$\frac{d\tilde{P}}{dP}(1) = \frac{\tilde{P}_1}{P_1} = \frac{4}{3} ; \quad \frac{d\tilde{P}}{dP}(2) = 1 ; \quad \frac{d\tilde{P}}{dP}(3) = \frac{4}{3}$$

$$\frac{d\tilde{P}}{dP}(4) = \frac{\tilde{P}_4}{P_4} = 0$$

notice that  $\frac{dP}{d\tilde{P}}(4)$  is undefined

Theorem : Radon - Nikodym

let  $\tilde{P} \ll P$  then  $\frac{d\tilde{P}}{dP}$  exists and for every event A

$$\tilde{P}(A) = E \left[ 1_A \cdot \frac{d\tilde{P}}{dP} \right]$$

Continuous example (Shreve II p. 37-38)

- $X \sim N(0,1)$  on  $(\Omega, \mathcal{F}, P)$   
( $\mathcal{F}$  = set of all events)
- $\theta = \text{constant} \Rightarrow$  define  $Y = X + \theta \sim N(\theta, 1)$   
on the same probability space.

Goal : Find a probability  $\tilde{P}$  on the same sample space  
so that under  $\tilde{P}$  the random variable Y has standard  
normal distribution.

Question : What should  $Z = \frac{d\tilde{P}}{dP}$  be?

we want  $\tilde{P}(Y \leq y) = \phi(y) !!!$

$$\tilde{P}(Y \leq y) = E \left[ 1_{\{w: Y \leq y\}} \right] \stackrel{\text{R-N}}{=} E \left[ 1_{\{w: X+\theta \leq y\}} \cdot Z \right]$$

we want  $\tilde{P}(Y \leq y) = \phi(y)$  !!!

$$\begin{aligned}\tilde{P}(Y \leq y) &= \tilde{E} \left[ \mathbb{1}_{\{w: Y \leq y\}} \right] \stackrel{\text{R-N}}{=} E \left[ \mathbb{1}_{\{w: X+\theta \leq y\}} \cdot Z \right] \\ &= E \left[ \mathbb{1}_{\{w: X \leq y-\theta\}} \cdot Z \right]\end{aligned}$$

- if  $Z$  depends on  $X$  we can write the expectation

as

$$= \int_{-\infty}^{y-\theta} \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} \cdot f(x) dx$$

$\hookrightarrow$  represents  $Z = f(x)$

- and we want the result to be equal to  $\phi(y)$

we also recall that we must have  $\int_{-\infty}^{+\infty} f(x) dx = 1$

(as a consequence of it being a density).

$$\phi(y) = \int_{-\infty}^y \frac{1}{\sqrt{2\pi}} e^{-\frac{z^2}{2}} dz = \int_{-\infty}^{y-\theta} \frac{1}{\sqrt{2\pi}} e^{-\frac{(x+\theta)^2}{2}} dx$$

- change the variable  $z = x+\theta \Rightarrow dz = dx$

- to complete the example solve for:

$$\tilde{P}[Y \leq y] = \phi(y)$$

$$\Rightarrow \int_{-\infty}^{y-\theta} \frac{1}{\sqrt{2\pi}} e^{-\frac{z^2}{2}} f(z) dz = \int_{-\infty}^{y-\theta} \frac{1}{\sqrt{2\pi}} e^{-\frac{(x+\theta)^2}{2}} dx$$

- for a good guess as to  $f(x) = ?$  solve the following

$$\frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} f(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{(x+\theta)^2}{2}}$$

$$\frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} f(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{(x+\theta)^2}{2}}$$

$$\Rightarrow f(x) = e^{-x\theta - \frac{\theta^2}{2}}$$

$\Rightarrow$  the R-N derivative should be :

$$Z = f(x) = e^{-x\theta - \frac{\theta^2}{2}}$$

Check that it satisfies the requirement:

$$EZ = 1$$

$$EZ = \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} \cdot e^{-x\theta - \frac{\theta^2}{2}} d\theta = \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{(x+\theta)^2}{2}} dx = 1$$

$$\Rightarrow \tilde{P}(\Omega) = \tilde{E}1_{\Omega} = E[1_{\Omega} Z] = EZ = 1$$

Therefore  $\tilde{P}$  is an actual probability measure on  $(\Omega, \mathcal{F})$   
and under  $\tilde{P}$ ,  $Y$  has a standard normal distribution!

- another intuitive approach is to look for  $Z = \frac{d\tilde{P}}{dP}$   
simply by taking the ratio of the corresponding  
densities under  $\tilde{P}$  and  $P$

$$\Rightarrow \text{under } \tilde{P} : Y \sim N(0,1) \Rightarrow \tilde{f}(y) = \frac{1}{\sqrt{2\pi}} e^{-\frac{y^2}{2}}$$

$$\text{under } P : Y \sim N(\theta, 1) \Rightarrow f(y) = \frac{1}{\sqrt{2\pi}} e^{-\frac{(y-\theta)^2}{2}}$$

$$\Rightarrow \frac{\tilde{f}(y)}{f(y)} = e^{-\frac{y^2}{2} + \frac{(y-\theta)^2}{2}} = e^{-y\theta + \frac{\theta^2}{2}} =$$

- but recall that  $y = x + \theta$

$$\Rightarrow Z = \frac{\tilde{f}(x+\theta)}{f(x+\theta)} = e^{-x\theta - \frac{\theta^2}{2}}$$

(same result as before but much more intuitive)

the reason we can do this will be more clear as we shall

be able to represent  $\begin{cases} dP = f \cdot dm \\ d\tilde{P} = \tilde{f} \cdot dm \end{cases}$

(where  $dm$  = Lebesgue measure)

now we shall discuss this soon !!!