

# Major Project Documentation

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# 1 First Section

dasd [2]  
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## References

- [1] N. Agmon, N. Hazon, and G.A. Kaminka. Constructing spanning trees for efficient multi-robot coverage. In Robotics and Automation, 2006. ICRA 2006. Proceedings 2006 IEEE International Conference on, pages 1698–1703, May 2006.
- [2] M. W M G Dissanayake, P. Newman, S. Clark, H.F. Durrant-Whyte, and M. Csorba. A solution to the simultaneous localization and map building (slam) problem. Robotics and Automation, IEEE Transactions on, 17(3):229–241, Jun 2001.