

Calabi-Yau theorem

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1 Calabi conjecture

We start with the following fact (which is an exercise in Daniel Huybrechts, *Complex geometry - an introduction*)

Proposition 0.1 (Ricci and first Chern class). *Let (X, g) be a compact Kahler manifold, then $i\text{Ric}(X, g)$ is the curvature of the Chern connection on the canonical bundle K_X . In other words, $\text{Ric}(X, g)$ is in $\text{Ric}(X, g) \in -2\pi c_1(K_X)$ where $c_1(K_X)$ is the first Chern class of K_X .*

The Calabi conjecture asked whether there exists for each form $R \in c_1(K_X)$ a metric g' with $\text{Ric}(X, g') = R$. We prefer to work with the fundamental form instead of the metric g as the former is antisymmetric.

Definition 1. *The quadruple (h, g, ω, J) is said to be compatible if $g \circ J = g$ and $\omega(a, b) = g(Ja, b)$ and $h = g - i\omega$.*

Remark 1. 1. *When J is fixed, one of h, g, ω that is invariant by J determines the two others.*

2. *For a compatible quadruple, the condition $\nabla J = 0$ is equivalent to $d\omega = 0$. The fundamental form ω that satisfies $d\omega = 0$ is called a Kahler form.*

2 Reduction to local charts, Yau theorem

h, g, ω in local coordinates. We note by $h_{i\bar{j}} = h(\partial_{x_i}, \partial_{x_j}) = 2g_{\mathbb{C}}(\partial_{z_i}, \partial_{z_j})$. By straightforward calculation one has

$$\begin{aligned}\omega &= -\frac{1}{2} \text{Im} h_{i\bar{j}} (dx^i \wedge dx^j + dy^i \wedge dy^j) + \text{Re} h_{i\bar{j}} dx^i \wedge dy^j \\ &= \frac{i}{2} h_{i\bar{j}} dz^i \wedge d\bar{z}^j\end{aligned}$$

and the condition $d\omega = 0$ is equivalent to

$$\frac{\partial h_{i\bar{j}}}{\partial z_k} = \frac{\partial h_{k\bar{j}}}{\partial z_i}$$

We also note by $h^{i\bar{j}}$ the inverse transposed of $h_{i\bar{j}}$, i.e. $h^{i\bar{j}} h_{k\bar{j}} = \delta_j^k$

Definition 2. Let X be an almost complex manifold (manifold with an almost complex structure). Then $d : \wedge^n T^*X \rightarrow \wedge^{n+1} T^*X$ sends $\wedge^{p,q} T^*M$ to $\wedge^{p+1,q} T^*M \oplus \wedge^{p,q+1} T^*M$. We denote by ∂ and $\bar{\partial}$ the component of d in $\wedge^{p+1,q} T^*M$ and $\wedge^{p,q+1} T^*M$ respectively.

It would be convenient to define $d^c = i(\bar{\partial} - \partial)$ then obviously $dd^c = 2i\partial\bar{\partial}$.

The Ricci curvature. The Ricci curvature is given by

$$\text{Ric}_\omega = -\frac{1}{2} dd^c \log \det(h_{i\bar{j}})$$

dd^c lemma . We then can state the dd^c lemma

Lemma 1. Let α be a real, $(1,1)$ -form on a compact Kahler manifold M . Then α is d -exact if and only if there exists $\eta \in C^\infty(M)$ globally defined such that $\alpha = dd^c \eta$.

Yau theorem. The dd^c lemma tells us every form $R \in c_1(K_X)$ is of form $\text{Ric}_\omega + dd^c \eta$. If one varies the Hermitian product $h_{i\bar{j}}$ to $h_{i\bar{j}} + \phi_{i\bar{j}}$ then the new Ricci curvature is $dd^c \log \det(h_{i\bar{j}} + \phi_{i\bar{j}})$. The Calabi conjecture can be restated as the existence of ϕ such that $h_{i\bar{j}} + \phi_{i\bar{j}}$ is definite positive and

$$dd^c (\log \det(h_{i\bar{j}} + \phi_{i\bar{j}}) - \log \det(h_{i\bar{j}}) - \eta) = 0 \quad (1)$$

The functions f that satisfies $dd^c f = 0$ are called *pluriharmonic*. They also satisfy the maximum principle. By compactness of X , these functions on X are exactly constant functions. Therefore 1 is equivalent to

$$\det(h_{i\bar{j}} + \phi_{i\bar{j}}) = e^{c+\eta} \det(h_{i\bar{j}})$$

or

$$(\omega + dd^c \phi)^n = e^{c+\eta} \omega^n$$

where ω^n denotes the repeated wedge product. Note that $(\omega + dd^c \phi)^n - \omega^n = 0$, one has $\int_M (\omega + dd^c \phi)^n = V$, the conjecture of Calabi is therefore a consequence of the following theorem.

Theorem 2 (Yau). *Given a function $f \in C^\infty(M)$, $f > 0$ such that $\int_M f \omega^n = V$. There exists, and unique up to constant, $\phi \in C^\infty(M)$ such that $\omega + dd^c \phi > 0$ and*

$$(\omega + dd^c \phi)^n = f \omega^n$$

3 A sketch of proof

The uniqueness is straightforward. We will prove the existence of ϕ under the constraint $\int_M \phi \omega^n = 0$ (which will be useful to prove that (N) is locally diffeomorphism later). We will prove that the set S of $t \in [0, 1]$ such that there exists $\phi_t \in C^{k+2, \alpha}(M)$ with $\int_M \phi_t \omega^n = 0$ that satisfies

$$(\omega + dd^c \phi_t)^n = (tf + 1 - t) \omega^n \tag{2}$$

is both open and close in $[0, 1]$, therefore is the entire interval as $0 \in S$ is non empty.

To see that S is open, one only has to prove that the function \mathcal{N} defined by

$$\phi \mapsto \mathcal{N}(\phi) = \frac{\det(h_{i\bar{j}} + \phi_{i\bar{j}})}{\det(h_{i\bar{j}})}$$

or in other words $(\omega + dd^c \phi)^n = \mathcal{N}(\phi) \omega^n$, is a local diffeomorphism. The differential of \mathcal{N} is given by

$$D\mathcal{N}(\phi) \cdot \eta = \mathcal{N} \tilde{\Delta} \eta$$

with η varies in $\{\eta \in C^{k, \alpha}(M) : \int_M \eta \omega^n = 0\}$. But it is known that Δ is bijective between

$$\left\{ \eta \in C^{k+2, \alpha}(M) : \int_M \eta = 0 \right\} \longrightarrow \left\{ f \in C^{k, \alpha}(M) : \int_M f = 0 \right\}$$

Therefore \mathcal{N} is a local diffeomorphism and S is open.

The proof that S is closed is more technical. The idea in general is to do 3 things:

1. Using Arzela-Ascoli, it suffices to show that $\{\phi_t : t \in S\}$ is bounded in $C^{k+2,\alpha}$. Therefore up to a subsequence, one has the uniform convergence of ϕ_{t_n} to all partial derivatives of order $\leq k+1$. The $k+2$ -th order follows from (2).
2. Using Schauder theory, prove that the above bound follows from a priori estimate: There exists $\alpha \in (0, 1)$ and $C(X, \|f\|_{1,1}, 1/\inf_M f) > 0$ such that every $\phi \in C^4(X)$ satisfying $(\omega + dd^c \phi)^n = f\omega^n$ and $\int_M \phi \omega^n = 0$ has

$$\|\phi\|_{2,\alpha} \leq C$$

3. Establish the priori estimate.