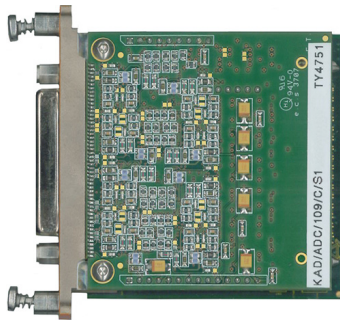


# KAD/ADC/109/S1

Full-bridge ADC (voltage excitation, programmable analog gain, 6kHz b/w) – 8ch at 24ksps

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## Key Features

- Eight full or ½-bridge, potentiometer or differential ended input channels
- Programmable input range ( $\pm 10\text{mV}$  to  $\pm 10\text{V}$ )
- High accuracy (max. 0.08% FSR at unity gain)
- Programmable voltage excitation and balance adjust
- High impedance ( $>10\text{M}\Omega$ ) when on/off
- Short on any channel does not affect others
- 16-bit simultaneous sampling on each channel

## Applications

- Bridge sensors
- Differential voltage measurement
- Strain gage measurement

## Overview

The KAD/ADC/109/S1 provides independent excitation for up to eight channels. Each channel has a separate programmable amplifier, programmable filter and A/D converter.

At the heart of the KAD/ADC/109/S1 is a hard-wired state-machine that over-samples all channels at a rate between 96ksps and 192ksps and digitally filters any noise above the user programmable cutoff frequency. This is achieved using cascaded, half-band, decimate by two, fifteen tap, finite-impulse-response (FIR) filters with 32-bit coefficients followed by an 8<sup>th</sup> order Butterworth IIR filter with a default cutoff point set at a quarter of the sampling frequency.

All signals are sampled simultaneously. Thus, when several channels are sampled at different sampling rates, at the start of an acquisition cycle all channels are aligned.

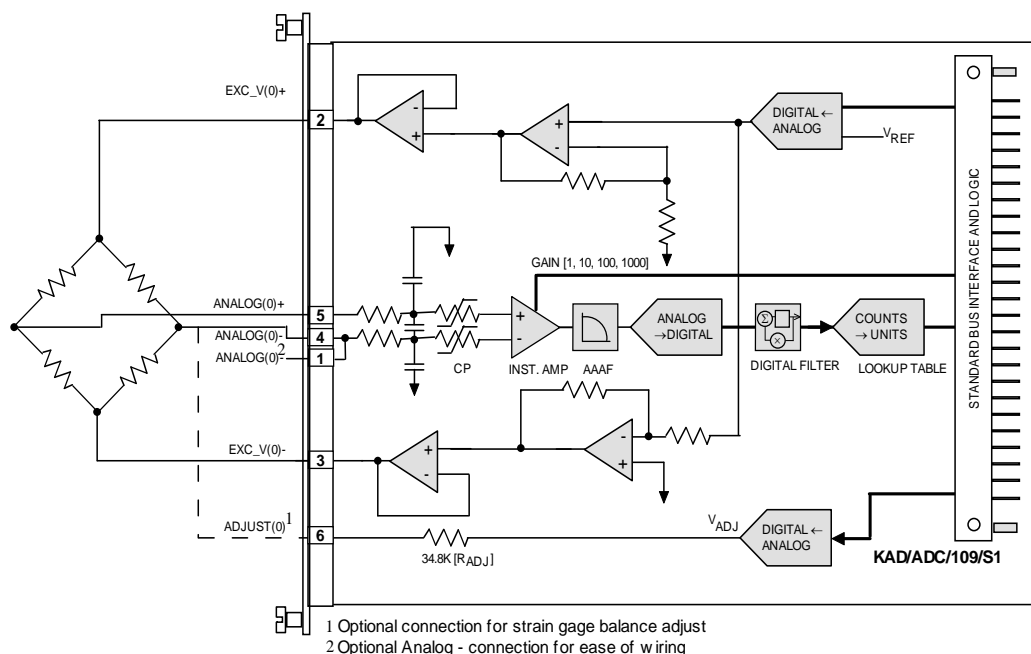


Figure 1: First of eight channels on the KAD/ADC/109/S1

## Specifications

All values provided in the following specification tables are valid within the operating temperature range specified under “Environmental ratings” in the “General specifications” table. Module specifications are met for up to 97% of Full Scale Range (FSR).

TABLE 1		General specifications			
PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITION/DETAILS
Slots	–	–	1	–	Can be placed in any user-slot in any combination.
Mass					
	–	102	–	g	
	–	3.59	–	oz	Design metric is grams.
Height above chassis					For recommended clearance requirements, see the <i>CON/KAD/002/CP</i> data sheet.
bare connector	–	–	11	mm	
bare connector	–	–	0.43	in.	Design metric is millimeters.
Access rate	–	–	2	Msp/s	Maximum combined access rate for read and write.
Power consumption					
+5V	100	–	180	mA	
+7V	40	–	60	mA	Excludes current used by excitation.
-7V	30	–	50	mA	Excludes current used by excitation.
+12V	60	–	80	mA	
-12V	40	–	60	mA	
total power	2.19	–	3.35	W	Particular combinations of chassis and Acra KAM-500 modules may have power or current limitations. For details, see <i>TEC/NOT/016 - Power dissipation</i> , <i>TEC/NOT/049 - Power estimation</i> , and the relevant chassis data sheet.
Environmental ratings					See <i>Environmental Qualifications Handbook</i> .
operating temperature	-40	–	85	°C	Chassis base/side plate temperature.
storage temperature	-55	–	105	°C	

TABLE 2		Differential ended analog inputs			
PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITION/DETAILS
Inputs	–	–	8	–	
Sampling rate					While the sampling rate can be set individually, each must have a power of two times any other ( $\frac{1}{4}$ , $\frac{1}{2}$ ...2, 4).
ANALOG[7:0]	2	–	24,000	sps	
Input voltage					
operating range ( $G_p = 1$ )	-10	–	10	V	Primary gain = 1
operating range ( $G_p = 10$ )	-1	–	1	V	Primary gain = 10
operating range ( $G_p = 100$ )	-100	–	100	mV	Primary gain = 100
operating range ( $G_p = 1000$ )	-10	–	10	mV	Primary gain = 1000
overvoltage protection	-40	–	40	V	Voltages outside of this range can damage input.

**TABLE 2** Differential ended analog inputs (continued)

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITION/DETAILS
DC error					DC signal averaged over 200 samples without excitation.
gain = 1, 10, 100	–	–	0.08	%FSR	
gain = 2, 20, 200	–	–	0.14	%FSR	
gain = 4, 40, 400	–	–	0.25	%FSR	
gain = 8, 80, 800	–	–	0.44	%FSR	
gain = 1000	–	–	0.3	%FSR	
gain = 2000	–	–	0.6	%FSR	
gain = 4000	–	–	1.2	%FSR	
Effective number of bits					
gain = 1, 10	13.5	–	–	bits	$f_c \leq 2\text{kHz}$ and secondary gain of 1 ( $f_c$ : filter cutoff frequency).
gain = 100	11	–	–	bits	$f_c \leq 2\text{kHz}$ and secondary gain of 1.
gain = 1000	8	–	–	bits	$f_c \leq 2\text{kHz}$ and secondary gain of 1.
Crosstalk					
gain = 1, 10, 100	–	–	-60	dB	
gain = 1000	–	–	-45	dB	
Common mode					
voltage range	-10	–	10	V	Operational voltage range.
rejection ratio	50	–	–	dB	Applies within the above common mode voltage range, $0 \leq f \leq f_c$ .
Analog filter					Analog filter is Butterworth.
poles	–	–	4	–	
filter cutoff -3dB	11.4	12	12.6	kHz	
Digital filter					Digital filter is Butterworth.
poles	–	–	8	–	
filter cutoff -3dB	0.25	–	16	$f_s$	The maximum value is limited to 6kHz ( $f_s$ : sampling frequency).
0.1dB bandwidth	–	0.8	–	$f_c$	
aliasing to 0.1dB band	–	–	-72	dB	
aliasing to $f_c$	–	–	-74	dB	
Filter delay	–	0.33	–	ms	Where $f_{in} = f_c = 6\text{kHz}$ ( $f_{in}$ : input signal frequency). See “Understanding filter delays” on page 8.
Input resistance					
between inputs	10	–	–	M $\Omega$	Module powered off.
between inputs	10	–	–	M $\Omega$	Module powered on.
each input to GND	10	–	–	M $\Omega$	Module powered off.
each input to GND	10	–	–	M $\Omega$	Module powered on.

**TABLE 3** Bipolar DC voltage excitation outputs

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITION/DETAILS
Outputs	–	–	8	–	
Output voltage					
operating range	0	–	5.1	V	Bi-polar excitation: 5V is 10V across the bridge.
resolution	–	–	1.8	mV	Bi-polar excitation: 1.8mV is 3.6mV across the bridge.
compliance	–	–	30	mA	Per channel.
short circuit current	–	–	125	mA	
short circuit duration	∞	–	–	s	To GND.
DC error					
error	–	–	0.3	%FSR	With a constant 350Ω load.
noise (gain = 1)	–	–	0.5	mV <sub>rms</sub>	As measured on analog input.
noise (gain = 10)	–	–	0.05	mV <sub>rms</sub>	As measured on analog input.
noise (gain = 100, 1000)	–	–	0.01	mV <sub>rms</sub>	As measured on analog input.
Output resistance	–	0.5	–	Ω	

**TABLE 4** Bridge adjust DC current outputs<sup>1</sup>

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITION/DETAILS
Outputs	–	–	8	–	
Output current					
operating range	-71	–	71	μA	
resolution	–	35	–	nA	
DC error					
error	–	–	2	%FSR	With a constant 175Ω load. The impact of this error on the channel reading is less than 0.01%FSR (200 times lower than the error specified here).
drift	–	–	0.15	%FSR	Over temperature.
noise (gain = 1)	–	–	0.5	mV <sub>rms</sub>	As measured on analog input.
noise (gain = 10)	–	–	0.05	mV <sub>rms</sub>	As measured on analog input.
noise (gain = 100, 1000)	–	–	0.01	mV <sub>rms</sub>	As measured on analog input.
Output resistance	–	34.8	–	kΩ	

1. The adjust line is intended for use in balancing strain gages and should not be used for asymmetric bridge transducers such as accelerometers or pressure transducers unless sensor re-calibration is carried out on a channel-by-channel basis.

## Setting up the KAD/ADC/109/S1

All module setup can be defined in XML using XidML® schemas (see <http://www.xidml.org>).

### Instrument settings

SETUP DATA	CHOICE	DEFAULT	NOTES
Manufacturer	-	-	-
Name	ACRA CONTROL	ACRA CONTROL	Name of manufacturer.
PartReference	KAD/ADC/109/C/S1	KAD/ADC/109/C/S1	The instrument part reference.
SerialNumber	AB1234	AB1234	Unique name for each module.
Channels	-	-	-
AnalogIn(7:0)	-	-	-
Analog Input Settings	-	-	-
Filter Cutoff	0.25 0.5 1 2 4 8 16	0.25	Required cutoff point for the filter is the chosen value multiplied by the user sampling frequency. 0.25 is recommended as any higher may lead to aliasing. 1 is the sampling rate.
Excitation Amplitude	0 to 5.1	0.2	Required excitation (in V) for the top of the bridge. Excitation is bipolar so entering 5V means 10V across the bridge.
Balance.Type	CurrentShunt	CurrentShunt	Specifies the balance type to be carried out on the bridge.
Balance.Applied	-71e-6 to 71e-6	0	Shunt current (in A) applied to the bridge.
Balance.BalanceThisTime	True False	False	Specifies if balancing should be carried out this time by software.
Balance.Tolerance	0.01 to 99.99	0.1	Specifies acceptable tolerance of achieved value vs. target value, expressed as percentage of defined input range.
Balance.Target	-10 to 10	0	Specifies a value. that the channel should be balanced to.
ShuntCurrent.Applied	-71e-6 to 71e-6	0	Shunt mode current (in A) added to the bridge.

### Parameter definitions

NAME/DESCRIPTION	BASE UNIT	DATA FORMAT	BITS	REGISTER DEFINITION
AnalogIn(7:0) Parameters				
AnalogIn Analog signal data	Volt	OffsetBinary	16	R[15:0]

### Configurable parameters

#### AnalogIn(7:0)

SETUP DATA	CHOICE	DEFAULT	NOTES
Range Maximum	-10 to 10	10	Range maximum for analog channel
Range Minimum	-10 to 10	-10	Range minimum for analog channel

**NOTE:** It is recommended that names are less than 20 characters, have no white space or contain any of the following five characters "</>\.

## Getting the most from the KAD/ADC/109/S1

### Wiring configurations

Figures 2 to 4 show possible wiring configurations for the KAD/ADC/109/S1.

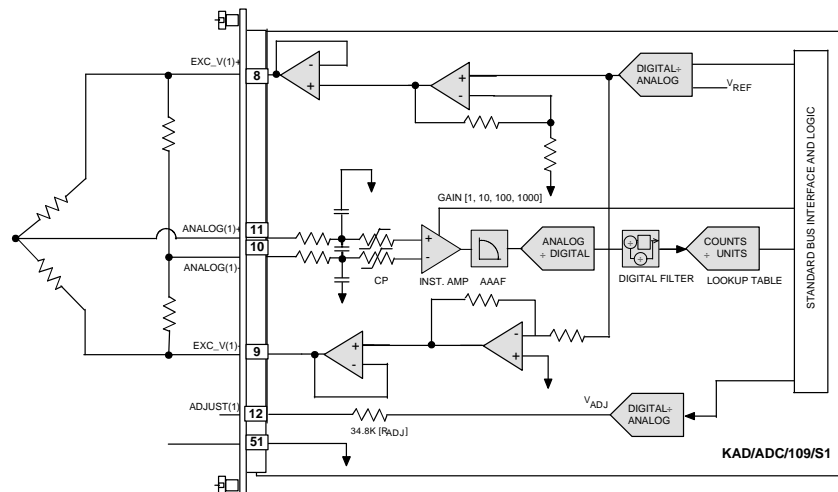


Figure 2: Second of eight independent 1/2-bridge channels with matched pair completion resistors

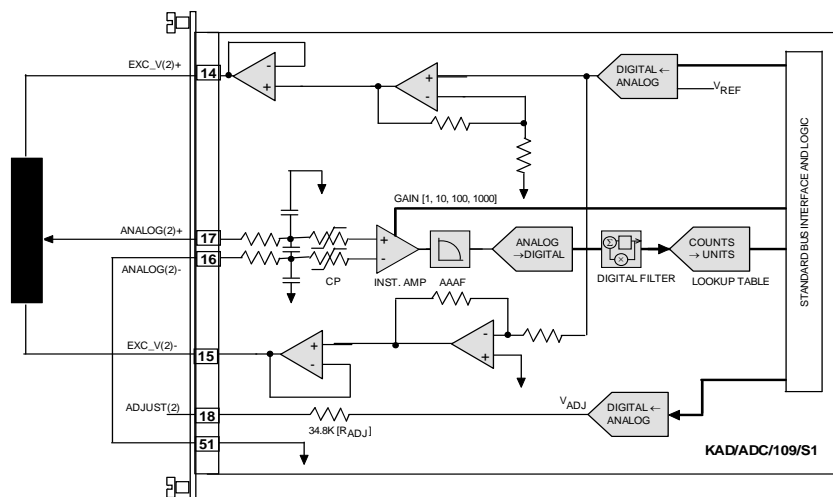


Figure 3: Third of eight independent potentiometer channels

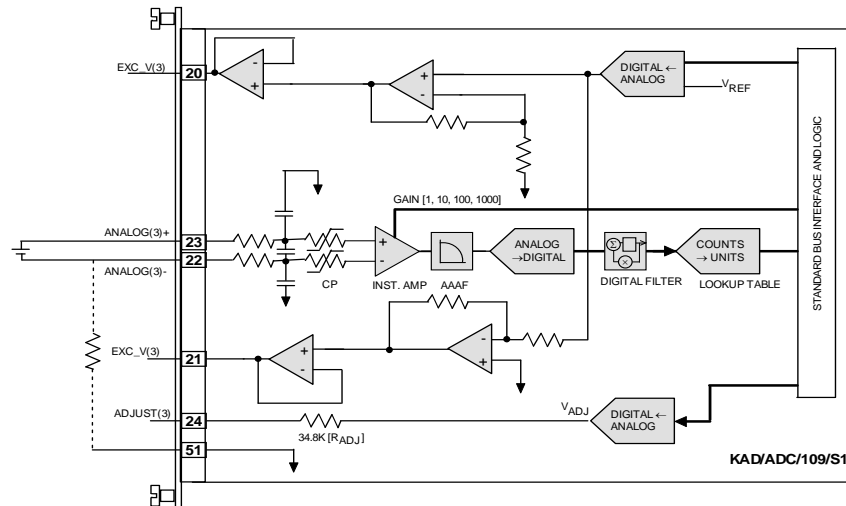


Figure 4: Fourth of eight independent differential ended channels

### Bias current return path

As shown in Figure 4 on page 7, the analog inputs can be used as differential inputs (that is, not from a bridge). In this case, if the signal source is isolated with respect to the KAM-500 (for example a battery), a common-mode resistance between the negative input and ground (GND) should be used to provide a return for bias currents and reduce common-mode noise pick-up. Because the bias currents are in the order of nAs, resistors up to 10kΩ can be used. In most cases a short (0Ω) is recommended.

**NOTE:** When analog inputs are used as differential inputs, setting the excitation and balance to zero reduces quiescent currents of the module.

### Using high primary gains

For gains above 1,000, the gain-bandwidth product of the amplifier reduces the bandwidth to 1,000 Hz.

### Excitation setup

Excitation can contribute error to the overall measurement, so it is recommended to use as close as possible to full-scale excitation, to minimize the percentage error.

For optimal accuracy ensure each channel uses its corresponding excitation. If the excitation is not used, it should be set to the minimum value.

### Excitation drift on potentiometer configurations

Curtiss-Wright recommends a full-bridge input configuration for the KAD/ADC/109/S1. With this configuration the differential input amplifier removes common mode voltage or common mode pickup noise on the input lines.

For potentiometer circuits where the negative input is tied to ground, excitation drift can have a direct impact on the input signal either as a gain or an offset error. Note that excitation can drift up to 0.3% on an FSR of 5.1V. In the case where both excitation lines drift in the same direction, an offset error is seen in the measurement. The worst case offset is 0.3% of 5.1V and results in a 5.3mV offset of the measurement. This does not happen when full-bridge configurations.

Curtiss-Wright recommends that the negative input is tied to GND as shown in Figure 3 on page 6.

### Compensation for lead resistance (Excitation Mode set to Voltage)

In bridge applications, if the lead resistance can be measured or estimated, add the voltage drop across the leads to the excitation voltage. For example, for 0.5Ω leads in a 350Ω full-bridge, where ±2.5V (5V) is desired across the bridge, the excitation should be set to  $2.5V + (0.5 \times 5 / 350) = 2.507$ .

**NOTE:** When Excitation Mode is set to Current, the lead's resistance does not need to be compensated for.  
If sense lines are required, see the KAD/ADC/109/S2.

## Understanding filter delays

The Acra KAM-500 uniquely samples all signals at the start of an acquisition cycle and at equal intervals of time thereafter. Signals sampled at the same sample rate will always be sampled at the same time independently of how they are stored or transmitted. (This has significant advantages for issues such as time correlation.) However, before signals are sampled they are filtered to remove noise components that might alias. The recommended cutoff point is one quarter the sampling frequency, as this results in the maximum filtering of aliasing frequencies.

The Acra KAM-500 filters signals using over-sampling signal processing techniques. The following figure shows a delay for an 8<sup>th</sup> order filter where  $f_c = 1\text{kHz}$ . All filters cause a delay inversely proportional to the filter cutoff frequency ( $f_c$ ), so to calculate the delay for other  $f_c$  values, multiply the delay by  $1\text{kHz} / f_c$ . The frequency axis then needs to be rescaled to the new  $f_c$  by dividing the frequency values by  $(1\text{kHz} / f_c)$ . For example, an 8<sup>th</sup> order Butterworth filter with an  $f_c$  of  $1\text{kHz}$  delays a  $1\text{kHz}$  signal by  $1\text{ms}$ ; a filter with an  $f_c$  of  $10\text{Hz}$  delays a  $10\text{Hz}$  signal by  $0.1\text{s}$ . The delay for IIR filters (for example Butterworth) varies with the input frequency.

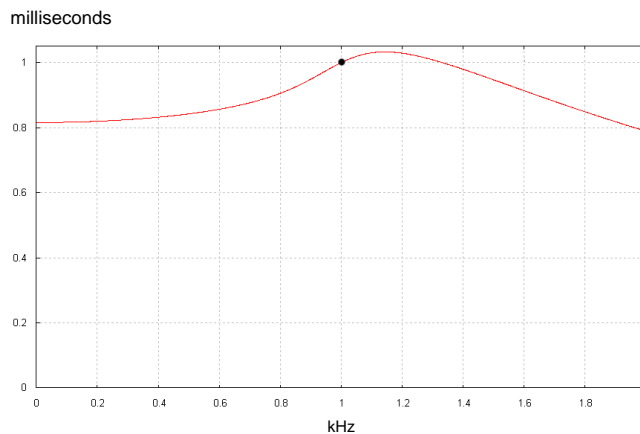


Figure 5: Filter delay for 8<sup>th</sup> order Butterworth filter where  $f_c = 1\text{kHz}$

The filter delay for the KAD/ADC/109/S1 is:

$$T_D \approx T_A + \frac{1}{f_c} + T_{\text{Butterworth}8}(f)$$

$T_D$  is the filter delay

$T_A$  (analog filter delay)  $\approx 0$

$f_c$  is the filter cutoff frequency.

## Additional delay sources

Primary gains higher than 1 cause an additional delay from 1<sup>st</sup> order filters in the instrumentation amplifier. That additional delay is  $2\mu\text{s}$  for a gain of 10,  $15\mu\text{s}$  for a gain of 100, and  $150\mu\text{s}$  for a gain of 1,000. In applications where time correlation is more important than suppression of aliasing, set the same cutoff point on all channels, even if the sampling rates are different.



## Connector pinout of the KAD/ADC/109/S1

PIN	NAME	SEE SPECIFICATIONS TABLE	COMMENT
1	ANALOG(0)-	Differential ended analog inputs	Analog input
2	EXC_V(0)+	Bipolar DC voltage excitation outputs	Excitation to top of bridge for channel 0
3	EXC_V(0)-	Bipolar DC voltage excitation outputs	Excitation to bottom of bridge for channel 0
4	ANALOG(0)-	Differential ended analog inputs	Analog input
5	ANALOG(0)+	Differential ended analog inputs	Analog input
6	ADJUST(0)	Bridge adjust DC current outputs	Used to balance/calibrate bridge
7	ANALOG(1)-	Differential ended analog inputs	Analog input
8	EXC_V(1)+	Bipolar DC voltage excitation outputs	Excitation to top of bridge for channel 1
9	EXC_V(1)-	Bipolar DC voltage excitation outputs	Excitation to bottom of bridge for channel 1
10	ANALOG(1)-	Differential ended analog inputs	Analog input
11	ANALOG(1)+	Differential ended analog inputs	Analog input
12	ADJUST(1)	Bridge adjust DC current outputs	Used to balance/calibrate bridge
13	ANALOG(2)-	Differential ended analog inputs	Analog input
14	EXC_V(2)+	Bipolar DC voltage excitation outputs	Excitation to top of bridge for channel 2
15	EXC_V(2)-	Bipolar DC voltage excitation outputs	Excitation to bottom of bridge for channel 2
16	ANALOG(2)-	Differential ended analog inputs	Analog input
17	ANALOG(2)+	Differential ended analog inputs	Analog input
18	ADJUST(2)	Bridge adjust DC current outputs	Used to balance/calibrate bridge
19	ANALOG(3)-	Differential ended analog inputs	Analog input
20	EXC_V(3)+	Bipolar DC voltage excitation outputs	Excitation to top of bridge for channel 3
21	EXC_V(3)-	Bipolar DC voltage excitation outputs	Excitation to bottom of bridge for channel 3
22	ANALOG(3)-	Differential ended analog inputs	Analog input
23	ANALOG(3)+	Differential ended analog inputs	Analog input
24	ADJUST(3)	Bridge adjust DC current outputs	Used to balance/calibrate bridge
25	ANALOG(4)-	Differential ended analog inputs	Analog input
26	EXC_V(4)+	Bipolar DC voltage excitation outputs	Excitation to top of bridge for channel 4
27	EXC_V(4)-	Bipolar DC voltage excitation outputs	Excitation to bottom of bridge for channel 4
28	ANALOG(4)-	Differential ended analog inputs	Analog input
29	ANALOG(4)+	Differential ended analog inputs	Analog input
30	ADJUST(4)	Bridge adjust DC current outputs	Used to balance/calibrate bridge
31	ANALOG(5)-	Differential ended analog inputs	Analog input
32	EXC_V(5)+	Bipolar DC voltage excitation outputs	Excitation to top of bridge for channel 5
33	EXC_V(5)-	Bipolar DC voltage excitation outputs	Excitation to bottom of bridge for channel 5
34	ANALOG(5)-	Differential ended analog inputs	Analog input
35	ANALOG(5)+	Differential ended analog inputs	Analog input
36	ADJUST(5)	Bridge adjust DC current outputs	Used to balance/calibrate bridge
37	ANALOG(6)-	Differential ended analog inputs	Analog input
38	EXC_V(6)+	Bipolar DC voltage excitation outputs	Excitation to top of bridge for channel 6
39	EXC_V(6)-	Bipolar DC voltage excitation outputs	Excitation to bottom of bridge for channel 6
40	ANALOG(6)-	Differential ended analog inputs	Analog input
41	ANALOG(6)+	Differential ended analog inputs	Analog input
42	ADJUST(6)	Bridge adjust DC current outputs	Used to balance/calibrate bridge
43	ANALOG(7)-	Differential ended analog inputs	Analog input
44	EXC_V(7)+	Bipolar DC voltage excitation outputs	Excitation to top of bridge for channel 7
45	EXC_V(7)-	Bipolar DC voltage excitation outputs	Excitation to bottom of bridge for channel 7
46	ANALOG(7)-	Differential ended analog inputs	Analog input
47	ANALOG(7)+	Differential ended analog inputs	Analog input
48	ADJUST(7)	Bridge adjust DC current outputs	Used to balance/calibrate bridge
49	DNC		Do not connect
50	DNC		Do not connect
51	GND	Internal ground	
52	CHASSIS	Chassis	Double-density connector only

## Ordering information

PART NUMBER	DESCRIPTION
KAD/ADC/109/C/S1	Full-bridge ADC (voltage excitation, programmable analog gain, 6kHz b/w) – 8ch at 24ksps (with 52-way double-density connector)
KAM/ADC/109/C/S1	Full-bridge ADC (voltage excitation, programmable analog gain, 6kHz b/w) – 8ch at 24ksps (with 51-way micro-miniature connector)

By default, the standard mating connector (CON/KAD/002/CP for KAD modules; ACC/CON/008/04 for KAM modules) is included with each module in the shipment. Its part number will be added to the Confirmation of Order unless an alternative option is specified (see the *Cables* data sheet). In this data sheet, KAD/ADC/109/S1 refers to both the KAD and KAM version of the module.

The KAD/ADC/109/S1 uses power from the  $\pm 7V$  power line for excitation and therefore cannot be used with the KAM/CHS/04L, KAM/CHS/05F or KAM/CHS/03F chassis.

## Revision history

REVISION	DIFFERENCES	STATUS
KAD/ADC/109/C/S1	High impedance per channel when powered off, enhanced mechanical strength and improved format switching	Recommended for new programs
KAD/ADC/109/B/S1	Reduced power consumption on the $\pm 7V$ power lines	Not recommended for new programs
KAD/ADC/109/S1	8 channel bridge A/D converter with excitation and signal conditioning	Not recommended for new programs

## Supporting software

SOFTWARE	DETAILS
DAS Studio 3	User interface for setup and management of data acquisition, network switches, recorders and ground stations in an integrated environment
KSM-500	This module is supported by the KSM-500 suite of software tools

## Related documentation

DOCUMENT	DETAILS
DOC/DBK/001	KAM-500 Databook
DOC/HBK/002	Environmental Qualification Handbook
DOC/MAN/018	KSM-500 Databook
DOC/MAN/030	DAS Studio 3 User Manual
TEC/NOT/001	Strain gages and ideal bridges
TEC/NOT/016	Power dissipation
TEC/NOT/049	Power estimation