

# Quiz Assignment

## MS5033

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### Problem 1: Variational Derivative of a Functional

$$F[\phi] = \int_{\Omega} [f(\phi, \nabla\phi)] dV \quad (1)$$

Perturb  $\phi$  by  $\delta\phi$  such that  $\phi \rightarrow \phi + \delta\phi$  and  $\nabla\phi \rightarrow \nabla\phi + \nabla\delta\phi$ .

$$\begin{aligned} F[\phi + \delta\phi] &= \int_{\Omega} [f(\phi + \delta\phi, \nabla\phi + \nabla\delta\phi)] dV \\ &= \int_{\Omega} [f(\phi, \nabla\phi) + \delta\phi \frac{\partial f}{\partial \phi} + \nabla\delta\phi \cdot \frac{\partial f}{\partial \nabla\phi}] dV \end{aligned} \quad (2)$$

Subtracting (1) from (2) we get,

$$\begin{aligned} \delta F &= F[\phi + \delta\phi] - F[\phi] \\ &= \int_{\Omega} [\delta\phi \frac{\partial f}{\partial \phi} + \nabla\delta\phi \cdot \frac{\partial f}{\partial \nabla\phi}] dV \end{aligned} \quad (3)$$

Using integration by parts on the second term in (3),

$$\begin{aligned} \delta F &= \int_{\Omega} [\delta\phi \frac{\partial f}{\partial \phi}] dV + [\frac{\partial f}{\partial \nabla\phi} \delta\phi]_{\partial\Omega} - \int_{\Omega} [\nabla \cdot \frac{\partial f}{\partial \nabla\phi} \delta\phi] dV \\ &= \int_{\Omega} [\delta\phi \frac{\partial f}{\partial \phi} - \nabla \cdot \frac{\partial f}{\partial \nabla\phi} \delta\phi] dV \\ &= \int_{\Omega} [\frac{\partial f}{\partial \phi} - \nabla \cdot \frac{\partial f}{\partial \nabla\phi}] \delta\phi dV \end{aligned} \quad (4)$$

In (4), as  $\delta\phi$  is zero at the boundary, the second term vanishes.  
For stationary condition, integral must hold for all variations  $\delta\phi$ .

$$\boxed{\frac{\partial F}{\partial \phi} = \frac{\partial f}{\partial \phi} - \nabla \cdot \frac{\partial f}{\partial \nabla\phi}} \quad (5)$$

## Problem 2: Functional Derivative of Phase-Field Free Energy

### Part (a)

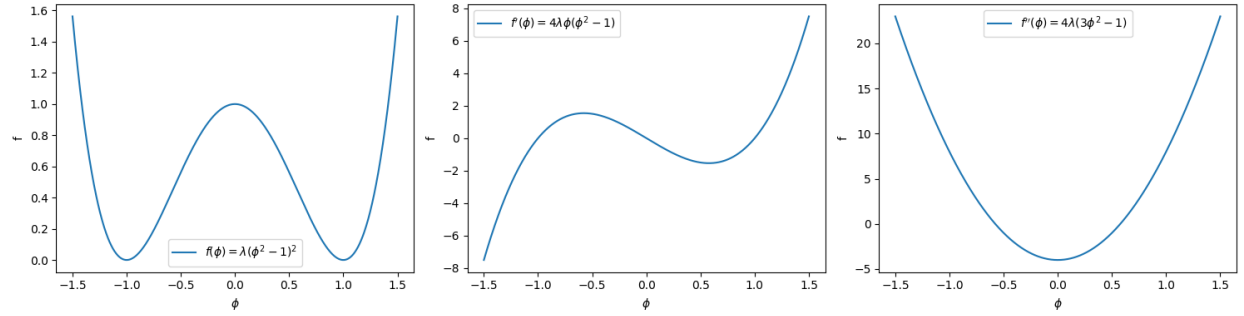


Figure 1: Function and its derivatives separately

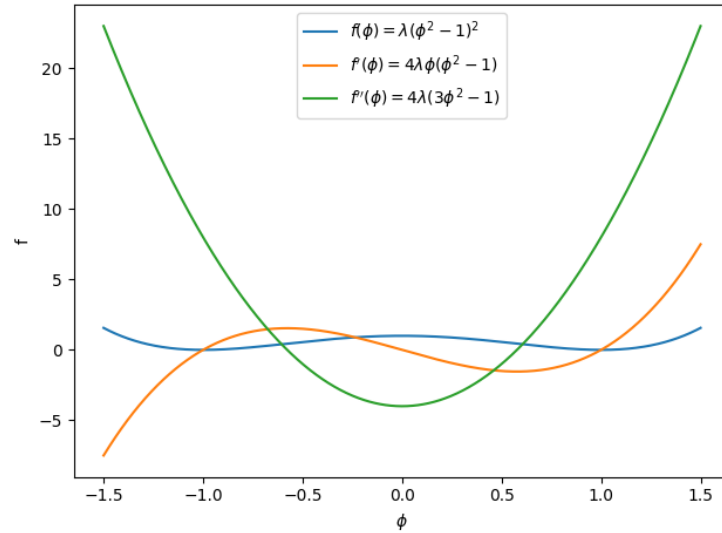


Figure 2: Function and its derivatives combined

### Part (b)

Refer to the python notebook for the code implementation.

### Part (c)

$$F[\phi] = \int_{\Omega} \left[ \frac{\kappa}{2} (\nabla \phi)^2 + f(\phi) \right] dV$$

Here,  $f(\phi, \nabla\phi) = \frac{\kappa}{2}(\nabla\phi)^2 + f(\phi)$ .

We know that,

$$\begin{aligned}\frac{\partial F}{\partial\phi} &= \frac{\partial f}{\partial\phi} - \nabla \cdot \frac{\partial f}{\partial\nabla\phi} \\ &= \frac{\partial f}{\partial\phi} - \nabla \cdot \frac{\partial(\frac{\kappa}{2}(\nabla\phi)^2)}{\partial\nabla\phi}\end{aligned}$$

$$\boxed{\frac{\partial F}{\partial\phi} = \frac{\partial f}{\partial\phi} - \nabla \cdot \kappa\nabla\phi}$$

### Part (d)

$\frac{\partial f}{\partial\phi}$ : local energy density of the phase-field variable  $\phi$ . Represents phase separation behavior using a double-well potential  $f(\phi)$ .

$\nabla \cdot \kappa\nabla\phi$ : Introduces diffusion of the phase-field variable  $\phi$  with a diffusivity  $\kappa$ . Acts as a smoothing term, ensuring that  $\phi$  transitions gradually between phases.

## Case Study 1: Derivation of the Cahn-Hilliard Equation

### Part (a)

$$F[\phi] = \int_{\Omega} [\frac{\kappa}{2}(\nabla\phi)^2 + f(\phi)]dV$$

Here,  $f(\phi, \nabla\phi) = \frac{\kappa}{2}(\nabla\phi)^2 + f(\phi)$ .

We know that,

$$\begin{aligned}\frac{\partial F}{\partial\phi} &= \frac{\partial f}{\partial\phi} - \nabla \cdot \frac{\partial f}{\partial\nabla\phi} \\ &= \frac{\partial f}{\partial\phi} - \nabla \cdot \frac{\partial(\frac{\kappa}{2}(\nabla\phi)^2)}{\partial\nabla\phi}\end{aligned}$$

$$\boxed{\mu = \frac{\partial F}{\partial\phi} = \frac{\partial f}{\partial\phi} - \nabla \cdot \kappa\nabla\phi}$$

### Part (b)

By conservative law,

$$\frac{\partial\phi}{\partial t} = \nabla \cdot (M\nabla\mu)$$

$$\boxed{\frac{\partial\phi}{\partial t} = \nabla \cdot (M\nabla(\frac{\partial f}{\partial\phi} - \nabla \cdot \kappa\nabla\phi))}$$

## Case Study 2: Boundary Conditions in Cahn-Hilliard Equation

### Part (a)

Consider the Cahn-Hilliard equation,

$$\frac{\partial \phi}{\partial t} = \nabla \cdot (M \nabla (\frac{\partial f}{\partial \phi} - \nabla \cdot \kappa \nabla \phi))$$

where  $F[\phi] = \int_{\Omega} [\frac{\kappa}{2} (\nabla \phi)^2 + f(\phi)] dV$ .

Variational principle by considering first variation of  $F[\phi]$ ,

$$\delta F = \int_{\Omega} [\delta \phi \frac{\partial f}{\partial \phi} - \nabla \cdot \kappa \nabla \delta \phi] dV + \int_{\partial \Omega} [\kappa \nabla \phi \cdot \delta \phi] dS$$

- **No-flux boundary condition:**  $n \cdot \nabla \phi = 0$  at  $\partial \Omega$ . This ensures no transport of  $\phi$  across the boundary. As  $\mu = \frac{\partial f}{\partial \phi} - \nabla \cdot \kappa \nabla \phi$ , implies  $\nabla \cdot (\nabla f' - \nabla \cdot \kappa \nabla \phi) = 0$ .
- **Dirichlet boundary condition:**  $\phi = \phi_0$  at  $\partial \Omega$ . This ensures a fixed value of  $\phi$  at the boundary.
- **Neumann boundary condition:**  $\nabla \phi \cdot n = g$  at  $\partial \Omega$ . This ensures a fixed flux of  $\phi$  at the boundary.
- **Periodic boundary condition:** Ensures that  $\phi$  and its derivatives repeat across boundaries, often used for systems without explicit boundaries:  $\phi(x) = \phi(x + L)$ , and  $\nabla \phi(x) = \nabla \phi(x + L)$ .

### Part (b)

Physical interpretation of the boundary conditions are as follows:

- **No-flux boundary condition:** Used in closed systems where the total amount of  $\phi$  is conserved. It ensures that there is no transport of  $\phi$  across the boundary ensuring mass conservation.
- **Dirichlet boundary condition:** Used when the value of  $\phi$  is known at the boundary. It ensures that the value of  $\phi$  is fixed at the boundary.
- **Neumann boundary condition:** Used when the flux of  $\phi$  is known at the boundary. Controls the rate of phase separation at boundaries, often used in systems with external driving forces.
- **Periodic boundary condition:** Used in systems without explicit boundaries. It ensures that the system is translationally invariant, often used in systems with periodic structures.

## Part (c)

Periodic boundary conditions are widely used to approximate infinite systems by eliminating boundary effects.

- Seamless continuation of the phase separation process without artificial walls.
- Efficient implementation of Fourier transforms for solving the Cahn-Hilliard equation.
- Eliminates the need for explicit boundary conditions, simplifying the problem.

## Problem 5: Interpretation of the Cahn-Hilliard Equation

### Part (a)

**Diffusive term  $\nabla \cdot (M \nabla \mu)$**

- The diffusive term is responsible for the diffusion of the phase-field variable  $\phi$ .
- Unlike regular diffusion, the diffusive term includes chemical potential gradient  $\nabla \mu$ , which drives phase separation rather than simple concentration gradient.
- The diffusive term is proportional to the mobility  $M$  and the Laplacian of the chemical potential  $\mu$ . The Laplacian of the chemical potential  $\mu$  is the driving force for the diffusion of the phase-field variable  $\phi$ .

**$\nabla^2 \frac{\partial f}{\partial \phi}$  term**

- The higher-order term  $-\kappa \nabla^2 \phi$  introduces interfacial effects, penalizing sharp gradients and enforcing a smooth transition between phases.
- The bulk free energy density  $f(\phi)$  contributes  $\frac{\partial f}{\partial \phi}$  dictating the preferred phases.
- This term leads to phase separation with surface tension effects, unlike ordinary diffusion which homogenizes concentration.

### Part (b)

- The diffusion equation leads to smooth spreading of  $\phi$ , whereas the Cahn-Hilliard equation leads to phase separation and domain formation due to the higher-order derivative term.
- Diffusion equation uses Fick's second law, whereas Cahn-Hilliard equation uses phase separation dynamics.
- The diffusion equation is a linear equation, whereas the Cahn-Hilliard equation is a nonlinear equation.
- The Cahn-Hilliard equation ensures conserved dynamics, meaning the total amount of each phase remains fixed, unlike the diffusion equation.

## Part (c)

Application of Cahn-Hilliard equation are as follows:

- **Image Impainting:** Image inpainting is the filling in of damaged or missing regions of an image with the use of information from surrounding areas. Let  $f(x)$ , where  $x = (x, y)$ , be a given binary image in a domain  $\Omega$  and  $D \subset \Omega$  be the inpainting domain. The image is scaled so that  $0 \leq f \leq 1$ . Let  $c(x, t)$  be a phase-field which is governed by the following modified CH equation:

$$c_t(x, t) = \nabla \mu(x, t) + \lambda(f(x) - c(x, t))$$
$$\mu(x, t) = F'(c(x, t)) - \epsilon^2 \nabla^2 c(x, t), \text{ where } F(c) = \frac{1}{4} c^2 (1 - c)^2$$

- **Tumor Growth Simulation:** To provide optimal strategies for treatments, a mathematical modeling is very useful since it gives systematic investigation. Let  $\Omega$  be a computational domain. Let  $\Omega_H, \Omega_V, \Omega_D$  be the healthy, viable, and dead tumor tissues, respectively. The Cahn-Hilliard equation naturally captures the evolution of these phases over time, leading to the formation of distinct tumor boundaries.
- **Spinodal Decomposition:** A system of the CH equations is the leading model of spinodal decomposition in binary alloys. Spinodal decomposition is a process by which a mixture of two materials can separate into distinct regions with different material concentrations.
- **Two Phase Fluid Flows:** In the two-phase fluid flow problem, we use the CH equation for capturing the interface location between two immiscible fluids. The CH equation provides a good mass conservation property. We model the variable quantities such as viscosity and density by using the phase-field. Also, we model the surface tension effect with the phase-field. The velocity field is governed by the modified Navier-Stokes equation.

## Problem 6: Computing Variational Derivative using SymPy

Refer to the python notebook for the code implementation.