

## **CSCE636 – PROJECT REPORT – 5**

**NAME: Darpit Dave**

**UIN – 126004742**

**NOTE: All sections with changes and new figures are highlighted in yellow and changed text is written in blue.**

### **Abstract**

In Submission 2 of my Project Report, I continue to work on detecting ‘dizziness’ using a neural network work. This can be an important addition in a smart home. Detecting dizziness among people with medical conditions can be used to send out alerts to the concerned personnel to take necessary actions. In order to overcome the challenge of having limited data available I make use of data augmentation techniques. This helped in improving accuracy over previously trained model and also similar model when used without using augmented data. The model used in this submission has linearly stacked LSTM layers.

### **Data Description and Processing**

The dataset consists of 160 self-made videos of roughly 5-6 seconds each. The training-validation split was 70-30 that is 112 for training and 48 videos for testing. Labels for each video have been generated framewise. For example, the video starts with a person sitting who gets up and starts feeling dizzy. So, the initial frames would be marked as a negative class whereas only the target part would be marked as positive labels.

The following steps were taken for processing the videos as input to the neural network model:

Step 1: OpenPose script was used to extract body landmarks from the videos for each frame. These were stored in a json format with x and y coordinates.

Step 2: The JSON files were further combined and stored as a .txt file for reading it as a matrix format.

```

def convert_data(start, end, output_json, output_json_key):
    """
        start - Starting video number to be added to text file
        end - Last video number to be added
        output_json - Path of json files for videos
        output_json_key - path of text file where the key-point values are to stored
    """

    with open(output_json_key, "w") as x:
        for i in range(start, end+1):
            json_files = glob.glob(output_json + '/' + str(i) + "/*")
            j=0
            for jfile in json_files:
                if j< 140:
                    j = j + 1
                    with open(jfile) as f:
                        data = json.load(f)
                        if data['people']:
                            kp= data['people'][0]['pose_keypoints_2d']
                            kp = [ str(v) for v in kp]
                            r = ','.join(kp)
                            x.write('{}\n'.format(r))

```

Step 3: Once the files are read, separate training and validation data are created in a 70-30 split for training.

```

##DATA CONVERSION (only required once for generating text files)####

#INITIALIZATION:
#TRAINING:
output_json = '/content/drive/My Drive/CSCE636/JSON_Output'
output_json_key_train = "/content/drive/My Drive/CSCE636/Train_Val_Test/X_train.txt"
start = 1 #training is from video 1 to video 70 --CHANGE
end = 70
Xtrain = convert_data(start, end, output_json, output_json_key_train)

#VALIDATION:
output_json = '/content/drive/My Drive/CSCE636/JSON_Output'
output_json_key_val = "/content/drive/My Drive/CSCE636/Train_Val_Test/X_val.txt"
start = 71 #validation is from video 70 to video 100 --CHANGE
end = 100
Xtrain = convert_data(start, end, output_json, output_json_key_val)
| ##EXTENSION OF DATASET##

#ADDING MORE TRAINING DATA:
output_json = '/content/drive/My Drive/CSCE636/JSON_Output'
output_json_key_train = "/content/drive/My Drive/CSCE636/Train_Val_Test/X_train_new.txt"
start = 119 #training is from video 119 to video 160 --CHANGE
end = 160
Xtrain_new = convert_data(start, end, output_json, output_json_key_train)

#ADDING MORE VALIDATION DATA:
output_json = '/content/drive/My Drive/CSCE636/JSON_Output'
output_json_key_val = "/content/drive/My Drive/CSCE636/Train_Val_Test/X_Val_new.txt"
start = 101 #validation is from video 101 to video 118 --CHANGE
end = 118
Xval_new = convert_data(start, end, output_json, output_json_key_val)

```

Step 4: The read files are reshaped into appropriate tensor dimensions to be used as the final input for the model training.

```
▶ #GENERATING TRAINING AND VALIDATION ARRAYS:  
  
#FOR X-file:  
train = "/content/drive/My Drive/CSCE636/Train_Val_Test/X_train.txt" ##  
X_train = read_data(train)  
  
train2 = "/content/drive/My Drive/CSCE636/Train_Val_Test/X_train_new.txt"  
X_train_new = read_data(train2)  
  
X_train = np.concatenate((X_train, X_train_new), axis=0)  
X_train = X_train.reshape(1568,10,50)  
  
val = "/content/drive/My Drive/CSCE636/Train_Val_Test/X_val.txt" ##CHAN  
X_val = read_data(val)  
val2 = "/content/drive/My Drive/CSCE636/Train_Val_Test/X_val_new.txt" #  
X_val_new = read_data(val2)  
X_val = np.concatenate((X_val, X_val_new), axis=0)  
X_val = X_val.reshape(672,10,50)  
  
#FOR Y-file:  
Y_train,Y_val = generate_label()  
Y_train = Y_train.reshape(1568,10,1)  
Y_val = Y_val.reshape(672,10,1)  
  
print('X_training = ', X_train.shape)  
print('X_validation = ', X_val.shape)  
print('Y_training = ', Y_train.shape)  
print('Y_validation = ', Y_val.shape)  
  
⇒ X_training = (1568, 10, 50)  
X_validation = (672, 10, 50)  
Y_training = (1568, 10, 1)  
Y_validation = (672, 10, 1)
```

Step 5: The training dataset was doubled up using data augmentation techniques. This allowed for better training and improved accuracy.

```

    ###DATA AUGMENTATION###
A = np.random.normal(0.0, 10.0, (1568,10,50) )
Xtrain_noise = np.add(Xtrain , A)
Xtrain = np.concatenate((Xtrain,Xtrain_noise), axis=0)
print('X-training shape after adding noise = ' , Xtrain.shape)

Ytrain = np.concatenate((Ytrain,Ytrain), axis=0)
print('Y-training shape after adding noise = ' , Ytrain.shape)

→ X-training shape after adding noise = (3136, 10, 50)
Y-training shape after adding noise = (3136, 10, 1)

```

## Model Architecture and Design

*The model used in this submission is a linear stack of sequential layers. It is a 11-layer model. The hidden layer has 3 LSTM layers, 5 time-distributed layers and 2 bi-directional layers. The output is also a time-distributed layer.*

### LSTM architecture

```

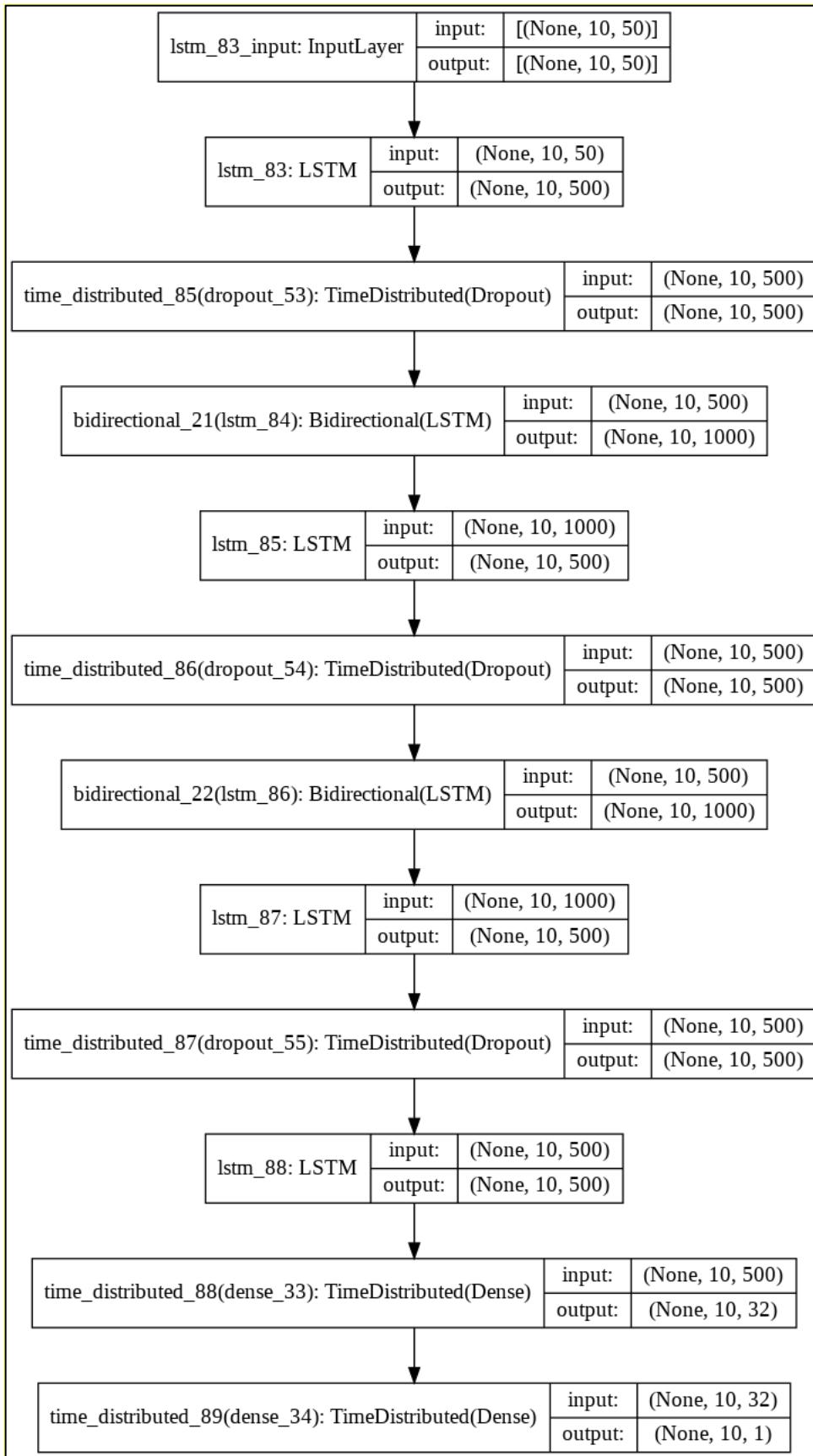
#Main model
model = tf.keras.models.Sequential()
model.add(tf.keras.layers.LSTM(500, input_shape=(10,50), return_sequences=True))
model.add(tf.keras.layers.TimeDistributed(tf.keras.layers.Dropout(0.2)))
model.add(tf.keras.layers.Bidirectional(tf.keras.layers.LSTM(500, input_shape=(10,50), return_sequences=True)))
model.add(tf.keras.layers.LSTM(500, input_shape=(10,50), return_sequences=True))
model.add(tf.keras.layers.TimeDistributed(tf.keras.layers.Dropout(0.2)))
model.add(tf.keras.layers.Bidirectional(tf.keras.layers.LSTM(500, input_shape=(10,50), return_sequences=True)))
model.add(tf.keras.layers.LSTM(500, input_shape=(10,50), return_sequences=True))
model.add(tf.keras.layers.TimeDistributed(tf.keras.layers.Dropout(0.5)))
model.add(tf.keras.layers.LSTM(500, return_sequences=True))
model.add(tf.keras.layers.TimeDistributed(tf.keras.layers.Dense(32, activation='relu', kernel_regularizer=regularizers.l2(0.01))))
model.add(tf.keras.layers.TimeDistributed(tf.keras.layers.Dense(1, activation='sigmoid')))

adam = tf.keras.optimizers.Adam(lr = 0.0001)
model.compile(loss = 'binary_crossentropy', optimizer=adam ,metrics = ['accuracy'])
print(model.summary())

```

Model: "sequential\_17"

Layer (type)	Output Shape	Param #
=====		
lstm_89 (LSTM)	(None, 10, 500)	1102000
time_distributed_90 (TimeDis)	(None, 10, 500)	0
bidirectional_23 (Bidirectio)	(None, 10, 1000)	4004000
lstm_91 (LSTM)	(None, 10, 500)	3002000
time_distributed_91 (TimeDis)	(None, 10, 500)	0
bidirectional_24 (Bidirectio)	(None, 10, 1000)	4004000
lstm_93 (LSTM)	(None, 10, 500)	3002000
time_distributed_92 (TimeDis)	(None, 10, 500)	0
lstm_94 (LSTM)	(None, 10, 500)	2002000
time_distributed_93 (TimeDis)	(None, 10, 32)	16032
time_distributed_94 (TimeDis)	(None, 10, 1)	33
=====		
Total params: 17,132,065		
Trainable params: 17,132,065		
Non-trainable params: 0		



## HYPERPARAMETERS

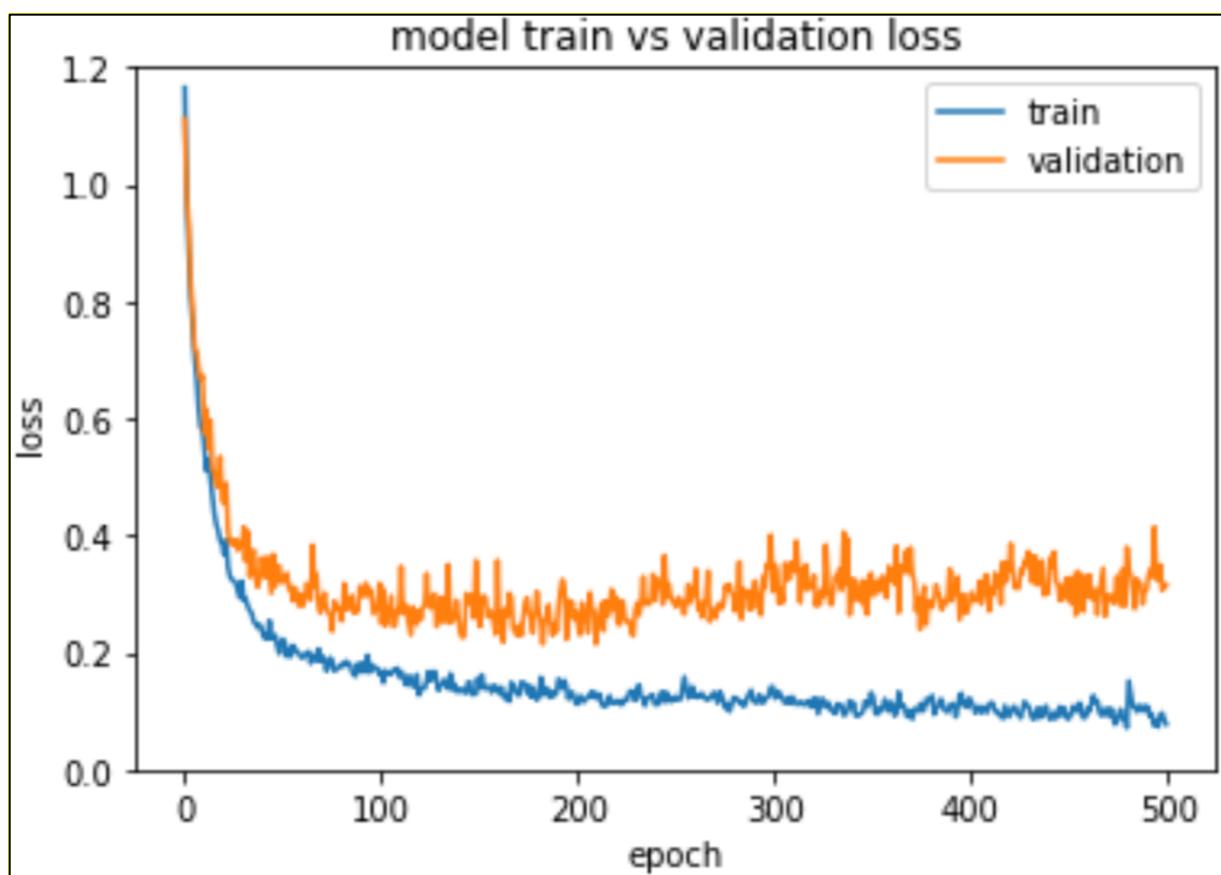
The following hyperparameters were tuned: units, batch\_size, epochs, learning rate. The below table summarizes the different values used and the optimal values found.

Hyperparameter	Values Tried	Optimal
Batch Size	50, 100, 200, 500, 1000	100
Units	100, 150, 200, 250, 333, 350, 400, 500	500
Learning rate	0.001, 0.0001, 0.01	0.0001

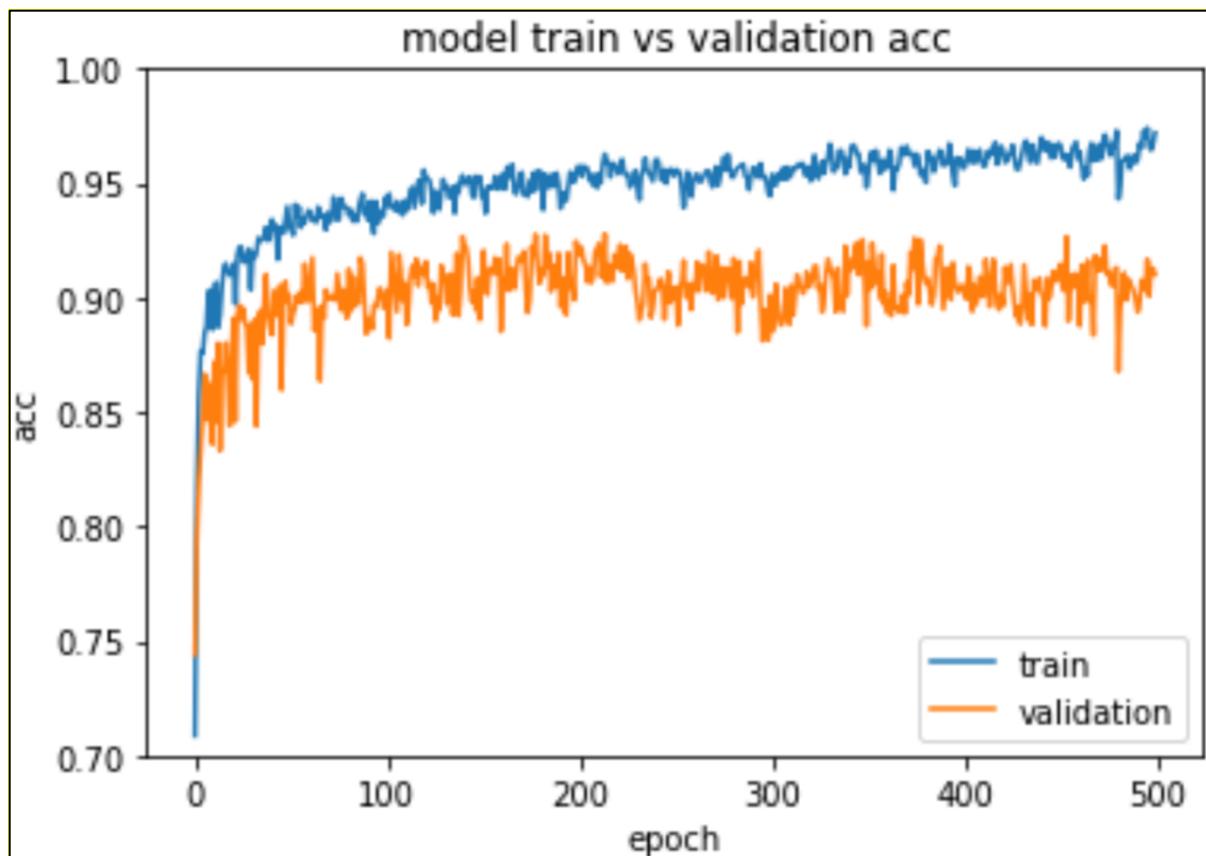
The above 2 hyperparameters were manually tried for various combinations to select the best output. For choosing the optimal epochs, keras features like early stopping and model checkpoint were utilized with 'validation\_loss' to be the monitoring metric.

### Training and Validation Performance

#### 1. Validation Loss



## 2. Validation Accuracy



## Prediction Results

*The prediction accuracy on test samples increased only marginally in Submission 5 with the test samples being the same.*

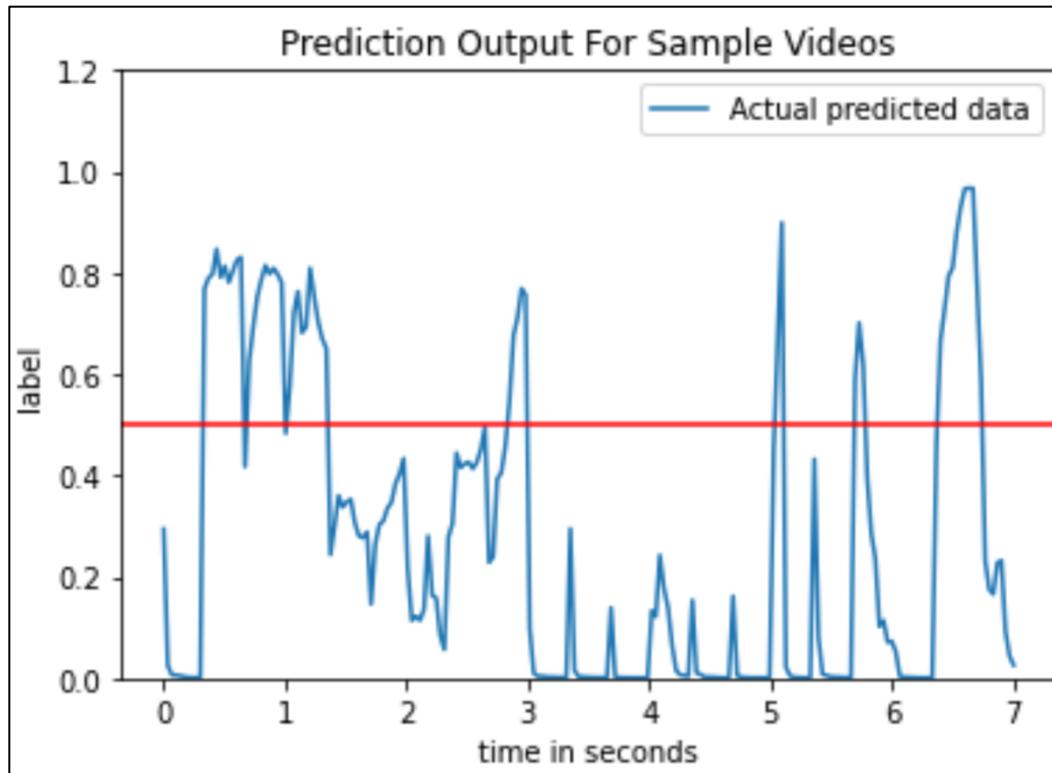
```
[98] import sklearn
     from sklearn.metrics import accuracy_score
     sklearn.metrics.accuracy_score(predicted_class, true)

     0.9183035714285714
```

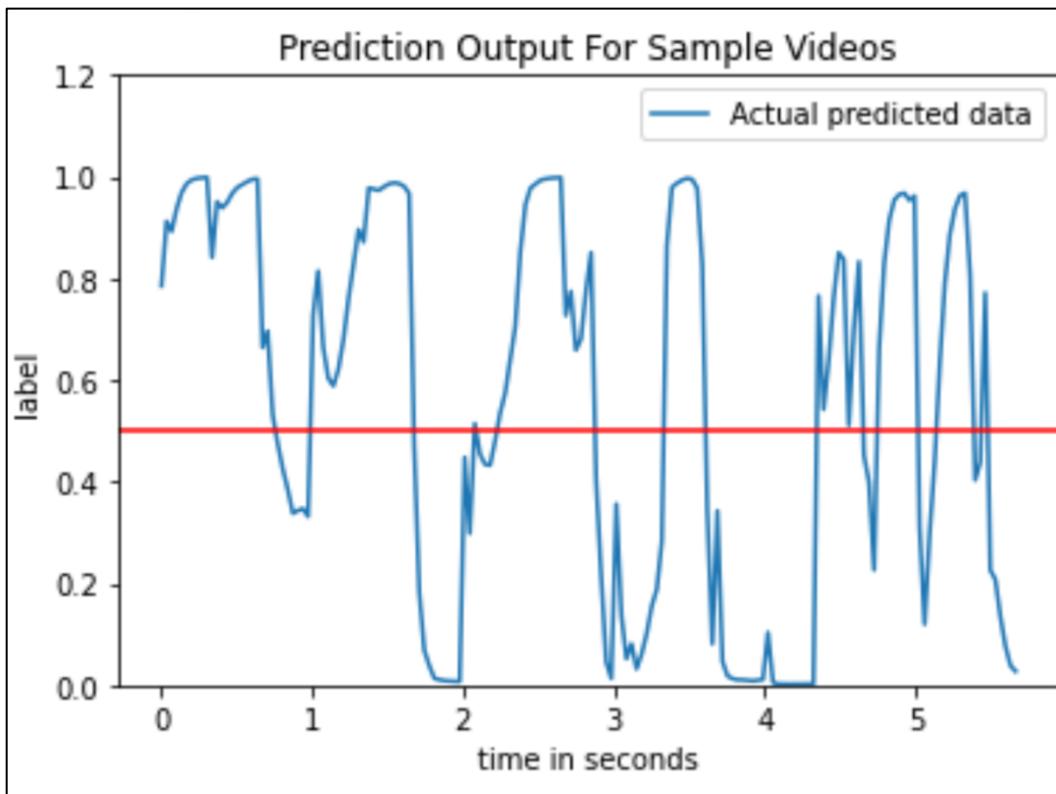
The following are a few sample results for positive (contains target action) and negative classes (does not have target action).

### Positive Class

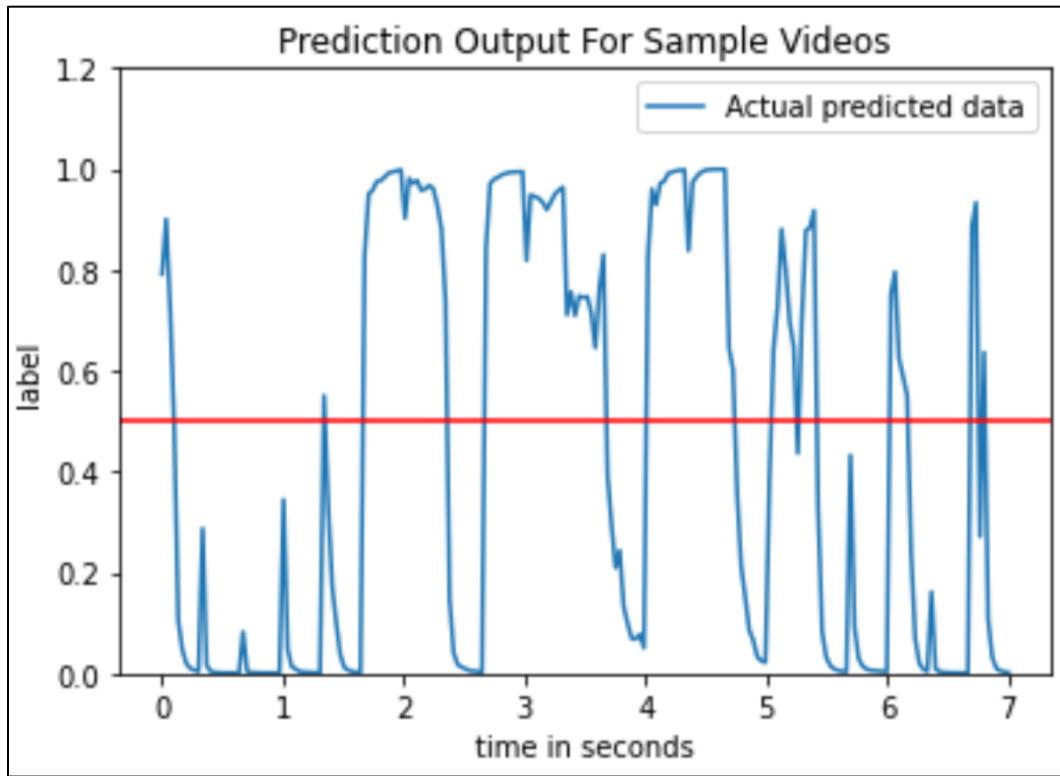
1. Positive Sample – 1 (Video #: 1)



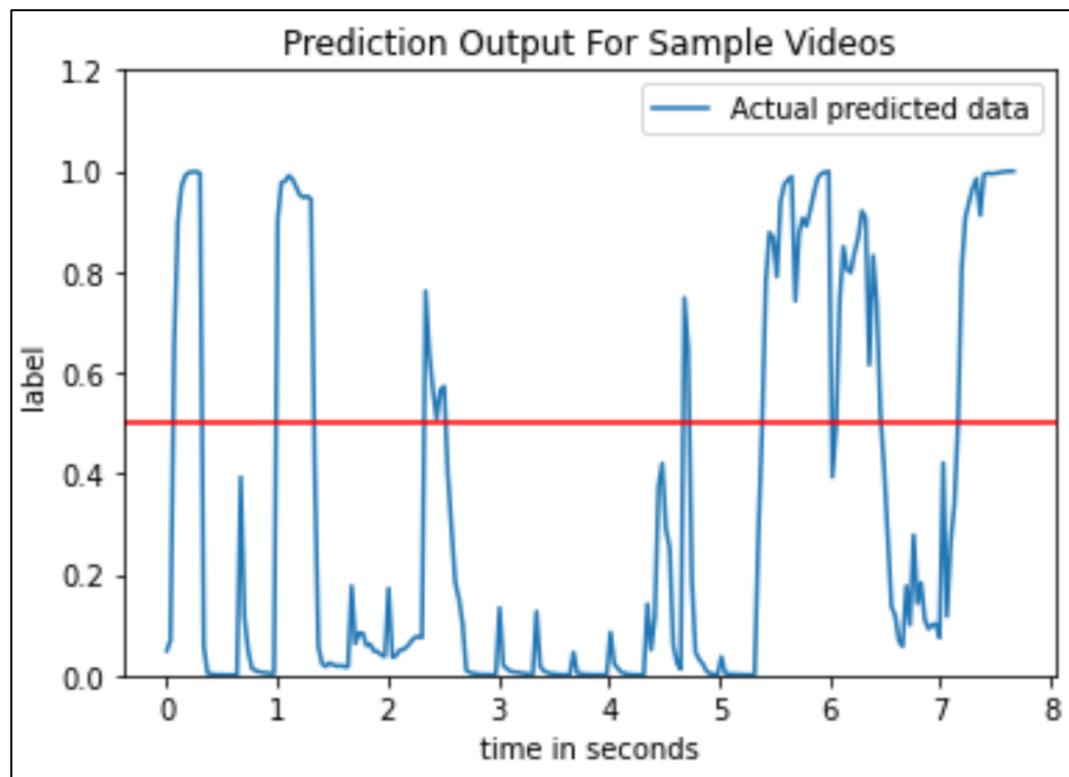
2. Positive Sample – 2 (Video #: 2)



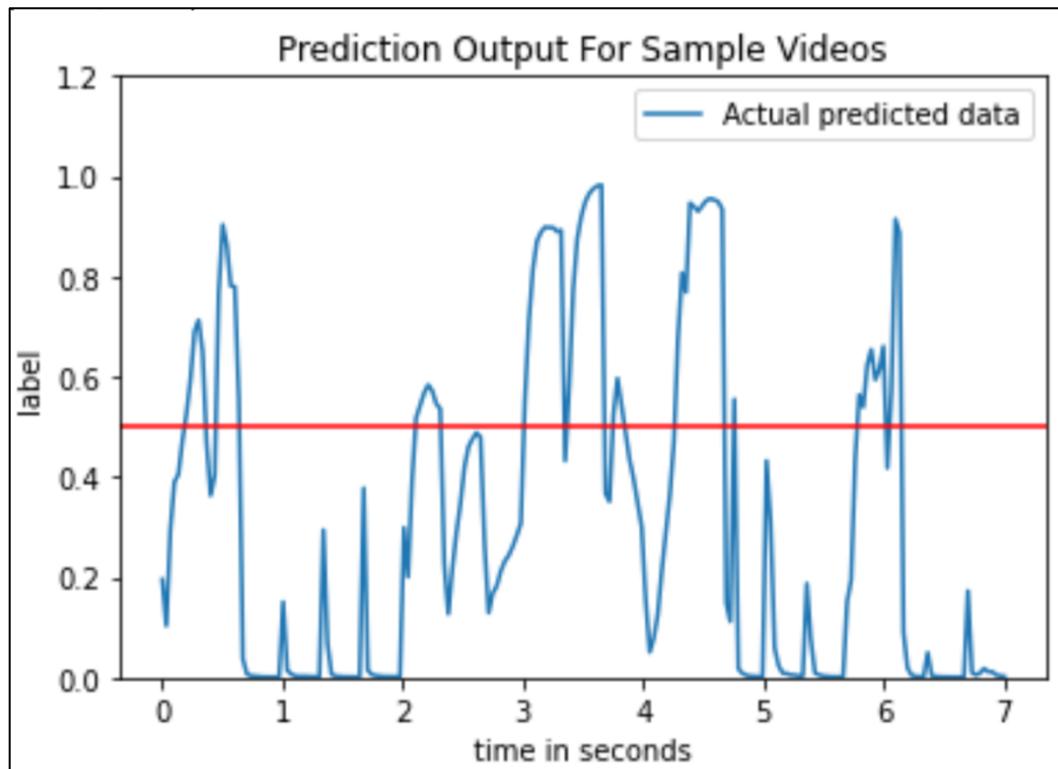
3. Positive Sample - 3 (Video #: 3)



4. Positive Sample - 4 (Video #:4)

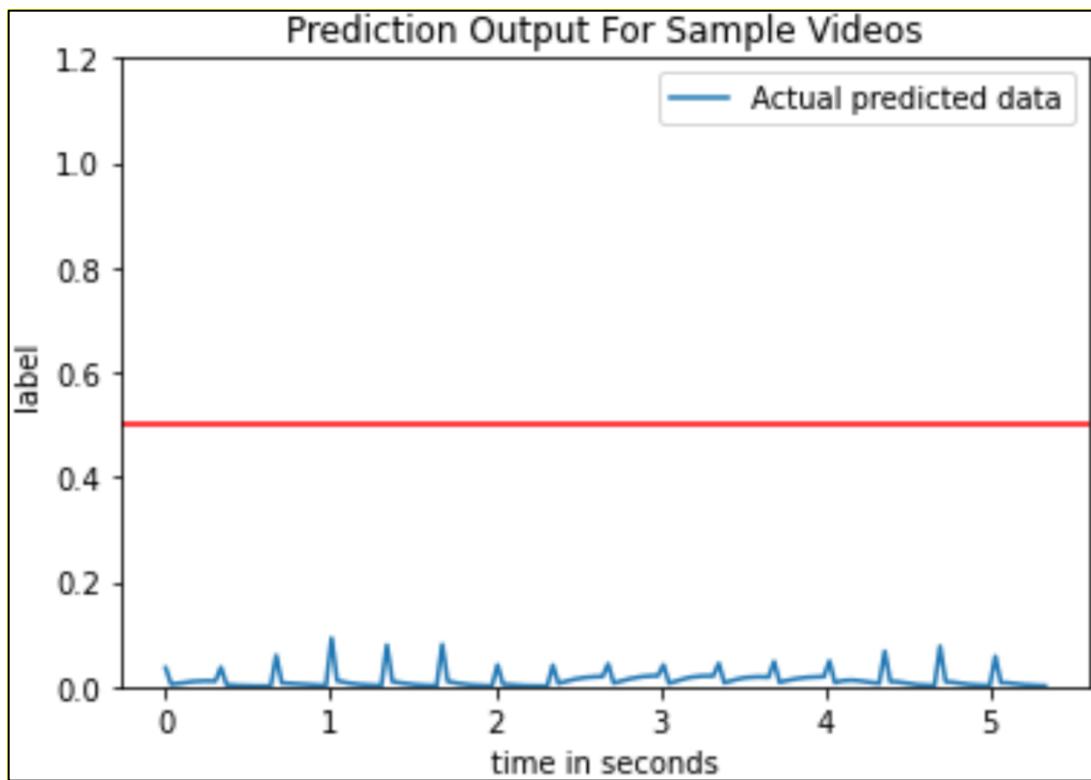


5. Positive Sample - 5 (Video #: 5)

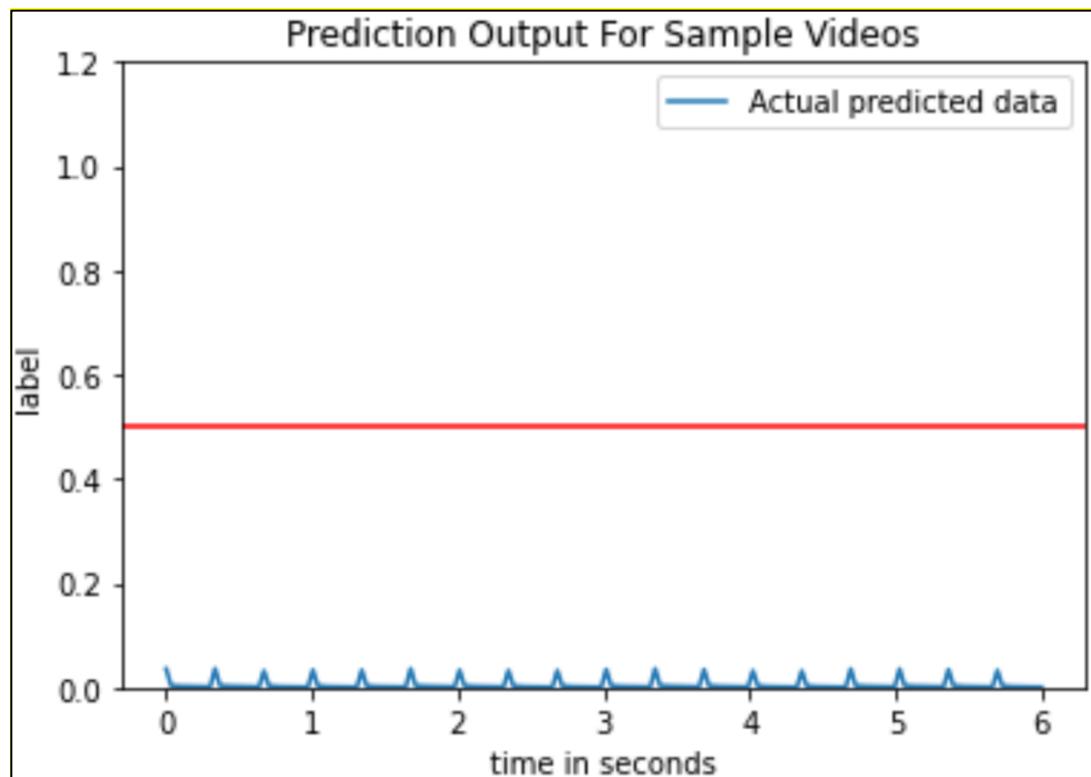


Negative Class

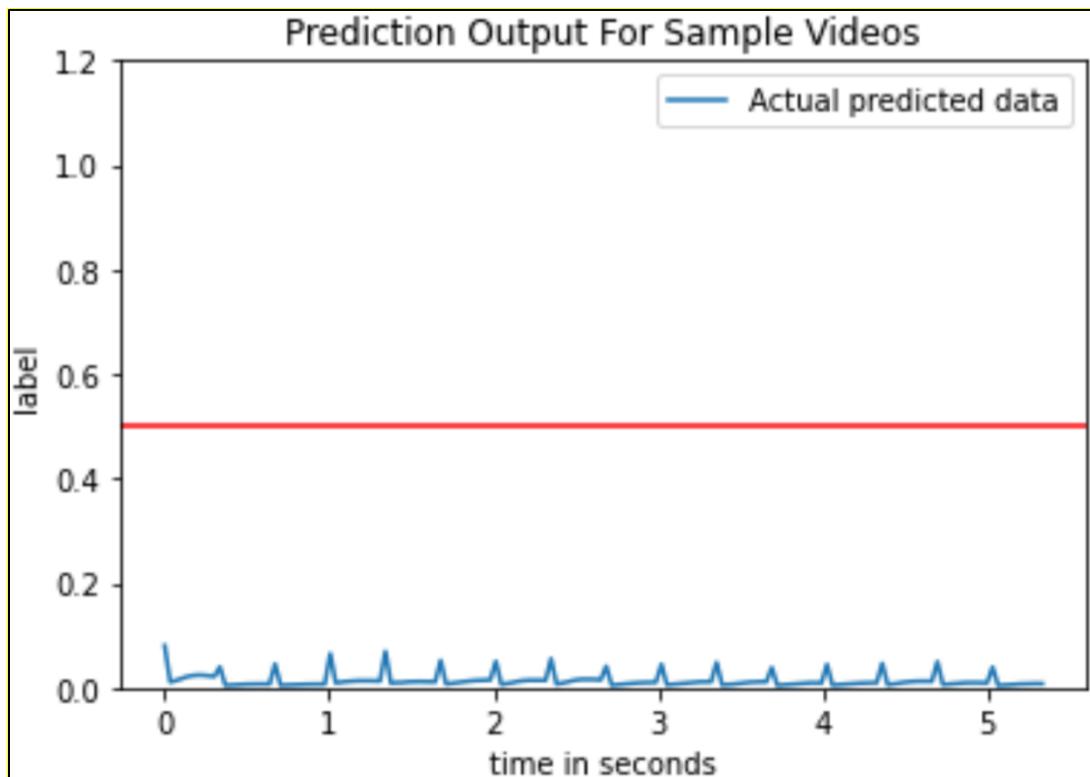
1. Negative Sample – 1 (Video #: 78)



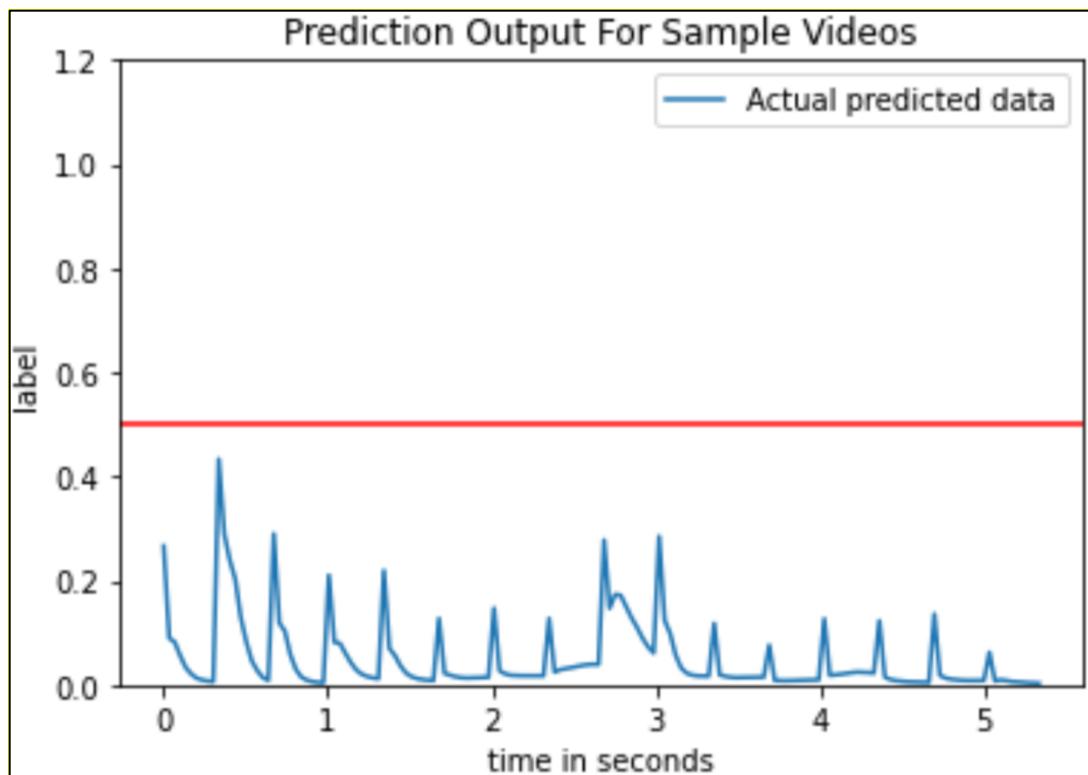
2. Negative Sample – 2 (Video #: 77)



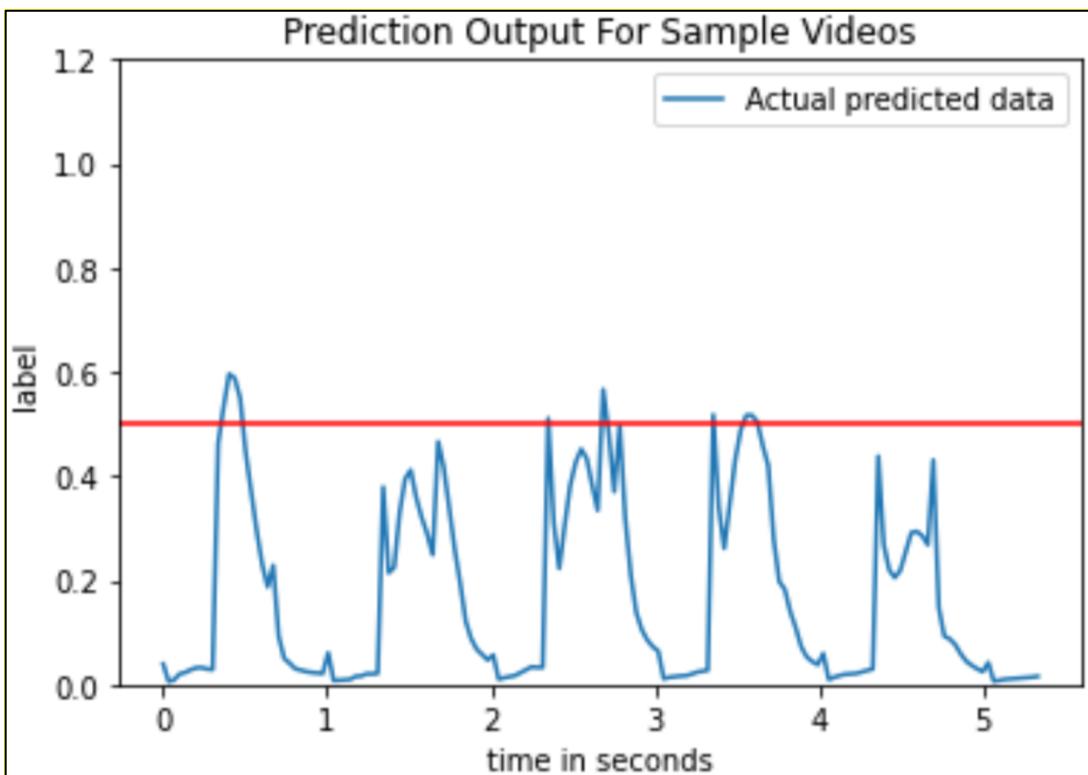
3. Negative Sample – 3 Video #: 75)



4. Negative Sample – 4 (Video #: 73)



5. Negative Sample – 5 (Video #: 71)



## INSTRUCTION ON HOW TO RUN THE PREDICTION MODEL:

1. Download CSCE636\_Submission3\_Prediction.ipynb from shared github repository:  
<https://github.com/darpitdavetamu/CSCE636-DeepLearning/tree/main/Submission3>.
2. Upload the file to google colab.
3. JSON files and text file required to run the code can also be accessed at  
<https://drive.google.com/drive/folders/1Ua297X--JqXMMfB33V4TeSG0rxCbzRZP?usp=sharing>
4. The path written in the code is same as the google drive link shared.

LINK TO DEMO VIDEO:

<https://www.youtube.com/watch?v=cK1aSOpTAn4>