#### **INTRODUCTION**

AVW is a comprehensive set of imaging functions which facilitates full exploration and analysis of multidimensional, multimodality biomedical image data sets. The software also facilitates the development and implementation of advanced imaging algorithms and techniques and easy integration of these into specific applications solutions by imaging software developers. The extensive functionality and interactive speed of this software are unequivocally the key features which distinguish it from other image processing and visualization packages.

# LIBRARY ORGANIZATION AND FUNCTIONALITY DESCRIPTIONS

The AVW imaging functions are packaged into a library that provides developers with the power of its predecessor, the ANALYZE system, at a callable C language function level. It is extensible, allowing developers to write their own specialized code while still making full use of the imaging capabilities of the package. The functions are completely user-interface independent, allowing for implementation at the applications level in different interface and operating environments. Each library function has a well defined calling sequence utilizing standardized AVW parameters and data structures, described in the next section. While only one linkable library is provided, the functionality in AVW can be separated into six distinct functional groups: ImageIO, Transform, Process, Segment, Analysis and Visualize. The contents of these groups are briefly outlined next.

#### **Resource Functions**

The Resource functions include the basic routines to create and destroy many of the *AVW* structures. Also included are list management, verification, and byte swapping routines.

#### **ImageIO Functions**

The ImageIO functions provide a user extendable interface which allows the reading and writing of images in many common formats.

# Transform Functions

The Transform functions include 2-D and 3-D spatial transformations, densitometric transformations and mathematical transformations. The functions necessary for oblique and curved sectioning, wavelet enhancement and compression transformations, and image registration/fusion are also included in this group.

# **Process Functions**

The Process functions provide a wide variety of histogram operations, spatial/convolution filtering, 3-D FFT's, 3-D Fourier domain filtering and 3-D deconvolution, including fast nonlinear iterative methods.

#### **Segment Functions**

The Segment functions include thresholding, 2-D and 3-D region growing, automated boundary detection, creation of object maps, multiresolution decomposition, morphological processing and multispectral classification.

#### **Analysis Functions**

The Analysis functions include extraction of line profiles, sampling of ROI's which includes the computation of size, density, shape and texture parameters (e.g., area, mean, circularity, fractal signature).

# Visualize Functions

The Visualize functions provide all operations necessary to support 3-D display using volume and surface rendering. Supported algorithms for volume rendering include depth-only shading, depth gradient shading, voxel gradient shading, integrated surface projection, maximum intensity projection and summation projection. Multiple object creation and rendering, color transparency (24-bit), image extraction tools, and image measurement tools are supported in conjunction with the volume rendering functions.

# IMAGE DATA TYPES AND DATA STRUCTURES

The AVW library of functions was designed to handle image and volume data in a fast and efficient manner while providing the functions useful for image display, processing, and measurement. An image is a 2-D array of values called pixels which are ordered in lines, and a volume is a 3-D array of values called voxels ordered in images. In this design, multiple types of volumes, referred to as bands, spectra or timepoints, are represented by an array of volumes. Since in multi-volume data sets each volume has its own structure, multiple bands are not required to have the same dimensions or data type. Image and volume structures have been designed to make function calls simple by requiring fewer parameters. These structures all assume that an image or volume is stored in contiguous memory.

# **AVW\_Image**

Images are represented by the following structure:

```
typedef struct
  void *Mem;
                                        /* Pointer to the first pixel of the image */
                                        /* Identifies the data type, unsigned char, int, etc... */
  int DataType;
  unsigned int Width, Height;
                                        /* Number of columns and rows in an image */
  unsigned int BytesPerPixel;
                                        /* Number of bytes per pixel */
  unsigned int BytesPerLine;
                                        /* BytesPerPixel * Width */
  unsigned int BytesPerImage;
                                        /* BytesPerPixel * Width * Height */
  unsigned int PixelsPerImage;
                                        /* Width * Height */
  AVW_Colormap *Colormap;
                                        /* Pointer to colormap structure */
  char *Info;
                    /* Pointer to information character string */
  unsigned int *YTable; /* Array of offsets to each row of an image */
  } AVW_Image;
```

# AVW\_Volume

The volume structure is as follows:

```
typedef struct
                                       /* Pointer to the first voxel of the volume*/
  void *Mem;
  int DataType;
                                       /* Identifies the data type, unsigned char, int, etc... */
  int Width, Height, Depth;
                                       /* Number of columns, rows, and images in a volume*/
                                       /* Number of bytes per pixel */
  unsigned int BytesPerPixel
  unsigned int BytesPerLine;
                                       /* BytesPerPixel * Width */
  unsigned int BytesPerImage;
                                       /* BytesPerPixel * Width * Height */
  unsigned int PixelsPerImage;
                                       /* Width * Height */
  unsigned int BytesPerVolume;
                                       /* BytesPerImage * Depth */
  unsigned int VoxelsPerVolume;
                                       /* Width * Height * Depth */
  AVW_Colormap *Colormap;
                                       /* Pointer to colormap structure */
                   /* Pointer to information character string */
  unsigned int *ZTable; /* Array of offsets to each image in the volume */
  unsigned int *YTable; /* Array of offsets to each row of an image */
  } AVW_Volume;
```

#### AVW\_Colormap

The AVW\_Colormap structure, which is a part of the AVW\_Image and AVW\_Volume structures, contains a color lookup table, which is NULL for grey scale data. This structure is defined as:

} AVW\_Colormap;

#### **Info Strings**

The character Info string is used to store any relevant information about the volume or image which is not contained in the AVW\_Volume or AVW\_Image structures themselves. Character strings and numeric values may be stored in this string with the following functions:

```
int AVW_PutStringInfo(MatchString, String, InfoString)
char *MatchString;
char *string;
char *InfoString;

int AVW_PutNumericInfo(MatchString, Value, InfoString)
char *MatchString;
double Value;
char *InfoString;
```

The MatchString is used to identify the information so that it can be retrieved upon request. Examples of values which would be stored in this string include voxel dimensions, units of measurement, maximum and minimum intensity values, processing history, and patient information. Functions to extract values or strings from the Info string are also provided:

```
char *AVW_GetStringInfo(MatchString, InfoString)
char *MatchString, *InfoString;
double AVW_GetNumericInfo(MatchString, InfoString)
char *MatchString, *InfoString;
```

# Create

Functions also exist for creating an AVW\_Image or AVW\_Volume structure from parameters supplied by the user:

```
AVW_Image *AVW_CreateImage(mem, width, height, type) void *mem; int width, height, type;

AVW_Volume *AVW_CreateVolume(mem, width, height, depth, type) void *mem; int width, height, depth, type;
```

Mem is a pointer to the raw image or volume. If mem is equal to NULL the memory is allocated by the function and returned. The type parameter refers to the supported data types. This value is the same as the DataType element of the AVW\_Image and AVW\_Volumes structures and can have the following values.

```
#define AVW_UNSIGNED_CHAR
                                       (1 << 0) /* 1 */
#define AVW_SIGNED_CHAR
                                       (1 << 1) /* 2 */
#define AVW_UNSIGNED_SHORT
                                       (1 << 2) /* 4 */
                                       (1<<3) /* 8 */
#define AVW_SIGNED_SHORT
#define AVW_UNSIGNED_INT
                                       (1<<4) /* 16 */
#define AVW_SIGNED_INT
                                       (1<<5) /* 32 */
#define AVW_FLOAT
                                       (1 << 6) /* 64 */
#define AVW COMPLEX
                                       (1 << 7) /* 128 */
#define AVW_COLOR
                                       (1 << 8) /* 256 */
```

Most of the data types are self explanatory.

Complex pixels or voxels are represented by two floating point values, the real and imaginary components.

# **Color Images**

Color images are represented by three consecutive bands which correspond to the red, green, and blue components of the color image. Each value is an unsigned char. The *Mem* element of the image structure points to the first value of the red band. This is followed by the rest of the red band values, which are followed by the green and blue band values.

#### **Destroy**

Images and volumes are released by the following functions:

```
void AVW_DestroyImage(image)
AVW_Image *image;
```

void AVW\_DestroyVolume(volume) AVW\_Volume \*volume;

#### **MEMORY USAGE**

*AVW* provides a mechanism for reusing and allocating structures. Though this document will only discuss *AVW\_Images*, the same rules apply to *AVW\_Volumes* and other *AVW* structures.

Many AVW functions return an AVW\_Image and also have an out\_image as part of the function's parameter list.

```
AVW_Image *AVW_Function(in_image, out_image)
```

Out\_image is provided as a method of reusing an existing AVW\_Image.

Reuse is possible if, and only if, the size and data type of the provided *out\_image* meet the requirements of the function. In this case the pointer to *out\_image* is returned by the function. If not reuseable and not *NULL*, *out\_image* will be released and reallocated.

A *NULL out\_image* passed in as a parameter, guarantees creation of a satisfactory *AVW\_Image* which is returned by the function.

Two typical ways of using this capability through the function calls are:

```
out_image = AVW_Function(in_image, out_image);
```

and

```
out_image = AVW_Function(in_image, NULL);
```

In the first call *out\_image* may be reused and in the second call it is created. In any case the returned pointer should always be used as the results of the function.

*Out\_image* will be freed if an error occurs in the function and *NULL* will be returned.

In the following example *image* appears as both the returned pointer and as an input parameter. The first time  $AVW\_GetOrthogonal()$  is called, *image* will be NULL, and  $AVW\_GetOrthogonal()$  will call  $AVW\_CreateImage()$  to allocate the required  $AVW\_Image$ . On successive calls to  $AVW\_GetOrthogonal()$ , *image* will contain a valid

# FUNCTION SPECIFICATION and CALLING CONVENTIONS

The AVW library function names start with AVW\_ followed by the name of the function which has the first letter of each word capitalized. The parameters for the functions follow the pattern:

AVW\_FunctionName(input parameters, ..., output parameter(s))

A pointer to the output image or volume is also returned by most functions. If the output image or volume had not been allocated prior to the subroutine call, it would be created, copied into and returned to the user. If the output image or volume already existed but was the wrong size or type it would be freed, reallocated and returned to the user. In the case where the output image or volume could not be allocated, a NULL would be returned and the appropriate error number and error message would be set.

# **ERROR** HANDLING

All of the AVW functions support error checking in a consistent manner, providing the user with an error number and an error message if a function fails. See the AVW\_Error.h include file for a detailed list of each error code which may be returned.

#### **AVW IMAGE I/O**

The AVW Image IO functions are designed to provide a single programmer interface to images of all file types. For supported file formats the files are opened without regard to the data format and images are read and returned in the AVW\_Image or AVW\_Volume structure. In addition the developer can add support for other formats to the Image IO functions.

A listing and short description of all of the AVW Image IO functions is provided.

AVW\_OpenImageFile - opens a named image file
AVW\_SeekImageFile - seeks to a specified image
AVW\_ReadImageFile - reads an image from the file
AVW\_ReadVolume - reads a volume from the file
AVW\_WriteImageFile - writes an image to a file
AVW\_WriteVolume - writes a volume to a file
AVW\_CreateImageFile - creates an image file of specified format

AVW\_ExtendImageFile - extends AVW ImageIO functions to support additional image file formats.

# **Image File Formats**

The following file formats are directly supported by AVW Image File IO routines:

AnalyzeImage

AnalyzeScreen

SunRaster

AVW\_VolumeFile

GE9800 (Read Only)

GESigna (Read Only)

GE Advantage (Read Only)

Imatron (Read Only)

SiemensCT (Read Only)

INTERFILE (Read Only)

ACRNEMA (Read Only)

PAPYRUS (Read Only)

**SGIrgb** 

**SGIbw** 

PPM

**PGM** 

YUV

**BMP** 

PIC

PICKERMRI (Read Only)

SMIS (Read Only)

CTI (Read Only)

AVW\_ImageFile

Support for some of the formats is limited to Read Only. Files cannot be created or written in these formats.

#### AVW\_VolumeFile

Most medical image formats do not support 3-D directly, since each slice in a study is written to a separate file. The AVW ImageIO routines provide a psuedo format for treating such groups of files as a single 3-D entity.

A text file which lists the files to be used for each slice in the file can be created. The first line of the file must be "AVW\_VolumeFile", and each subsequent line the name of a file. For example:

AVW VolumeFile

ST001SER002.001

ST001SER002.002

ST001SER002.003

ST001SER002.004

The name of this textfile is passed to AVW\_OpenImageFile(), and it checks the rest of the files for consistancy. Alternatively, all the image files may be placed in a subdirectory (with no other files) and the name of the directory can be passed to the same routine. Wildcard strings can also be used.

sdb = AVW\_OpenImageFile("ST001SER001.???", "r");

When a directory name or wild card is used as a file name the file list is sorted alphabetically.

# Image File IO Data Structures

```
The following structures are defined in AVW_ImageFile.h:
typedef struct
        char *FileName:
        char *FileModes;
        int DataFormat;
        int DataType;
        int Width;
        int Height;
        int Depth;
        int NumVols;
        int BitsPerPixel;
        int BytesPerPixel;
        int BytesPerLine;
        int BytesPerImage;
        int BytesPerVolume;
        int BytesPerFile;
        int PixelsPerImage;
        int VoxelsPerVolume;
        int VoxelsPerFile;
        int CurrentSlice;
        int CurrentVolume;
        AVW_Colormap *Colormap;
        void *NativeData; /* a pointer to the native header,
               or other format specific data */
        char *Info;
} AVW_ImageFile;
```

A pointer to this structure is returned by AVW\_OpenImageFile() in the same way that fopen() returns a pointer to a FILE. The pointer is passed to the other AVW Image IO functions, in the same way that a FILE pointer is passed to fread(), fwrite(), fseek(), and fclose().

# Supporting other formats

The AVW\_ExtendImageFile() function is used to add support for additional formats. The elements of an AVW\_ExtendIO structure must be initialized. This structure contains a list of functions for interacting with the file format.

```
typedef struct
       char
                 *Extension:
       char
                 *Description;
       int
                 MagicNumber;
                 Properties;
       int
        AVW_ImageFile (*Open)();
                 (*Seek)();
       int
        AVW_Image
                       (*Read)();
                 (*Write)();
       int
                 (*Close)();
        AVW_ImageFile (*Create)();
                 (*Query)();
       int
} AVW_ExtendIO;
For example,
```

```
AVW_ReadImageFile()
calls the "(*Read)()" for for the appropriate format.
int AVW_ExtendImageFile(AVW_ExtendIO * fl)
char *Extension; /* text extension, if any by which
              the file is known */
char *Description; /* the text name by which the format
              will be known. */
int MagicNumber; /* magic number (if any) by which
              the file type is identified */
int Properties;
           /* an | mask of properties that are
              supported by the format or this
              implementation */
AVW_ImageFile (*Open)();
            /* the Open() function, should return
              a pointer to an AVW_ImageFile
              structure, AVW_OpenImageFile()
              invokes and returns the pointer
              returned by this function */
         (*Seek)();
int
            /* positions the file stream so that
             the next call to AVW_ReadImageFile()
             returns the specified image. */
AVW_Image
                (*Read)();
          /* reads and returns an AVW_Image
            from the file */
         (*Write)();
int
         /* writes an AW_Image to the file */
int
         (*Close)();
        /* closes the file, and releases
          format specific data structures */
AVW_ImageFile (*Create)();
        /* creates a file given format and image */
         (*Query)();
int
```

```
/* given a file name returns TRUE or
FALSE to indicate if file is of
this Format */
```

# Extending for the TIFF format.

In the \$BIR/AVW/extras/io/expand\_io/TIFF directory the file avw\_tif.c contains source and instructions for expanding the ImageIO support to include the Tiff format.

Extending AVW Image IO to support the TIFF format is done by initializing the elements of an AVW\_ExtendIO structure and passing a pointer to that structure to AVW\_ExtendImageFile().

For example, the following shows how AVW can be extended to support TIFF images.

```
AVW_ExtendIO *fl;
fl=(AVW_ExtendIO *)malloc(sizeof(AVW_ExtendIO));
                            = ".tif";
       fl->Extension
                            = "TIFF";
       fl->Description
       fl->MagicNumber
                                   = AVW_NO_MAGIC_NUMBER;
                            = AVW_SUPPORT_UNSIGNED_CHAR|
       fl->Properties
            AVW_SUPPORT_COLOR
            AVW_SUPPORT_READ|
            AVW_SUPPORT_WRITE;
                  = avw open tiff image;
       fl->Open
 fl->Seek
            = avw_seek_tiff_image;
 fl->Read
             = avw_read_tiff_image;
 fl->Write
             = avw_write_tiff_image;
 fl->Close
             = avw_close_tiff_image;
 fl->Create = avw_create_tiff_image;
 fl->Query
             = avw_query_tiff_image;
 AVW_ExtendImageFile(fl);
 free(fl);
```

Where the following user supplied functions call functions in TiffLib. The application must link to TiffLib as well.

```
int avw_query_tiff_image(filename)
char *filename;
```

is a user supplied function which returns true if the named file is a Tiff file, otherwise false.

```
AVW_ImageFile *avw_open_tiff_image(filename, modes) char *filename; char *modes;
```

is a user supplied function which opens the tiff file and returns an initialized AVW\_ImageFile structure.

int avw\_seek\_tiff\_image(sdb,vol,slc)

AVW\_ImageFile \*sdb; int vol.slc;

is a user supplied function which seeks to the specified volume and slice in a tiff file. For file formats that do not support multiple slices per file, this routine does nothing.

AVW\_Image \*avw\_read\_tiff\_image(sdb, img)

AVW\_ImageFile \*sdb; AVW\_Image \*img;

is a user supplied function which returns the current image after being called by AVW\_OpenImage(). This routine assumes that sufficient memory for the entire image is at img->Mem.

int avw\_write\_tiff\_image(sdb, img)

AVW\_ImageFile \*sdb; AVW\_Image \*img;

is a user supplied function which writes the image to the file indicated by AVW\_ImageFile \*sdb.

int avw\_close\_tiff\_image(sdb)
AVW\_ImageFile \*sdb;

is a user supplied function which closes the file and frees any memory which was allocated for format specific data structures.

# ImageIO and Info Strings

The AVW\_ImageFile structure contains an information string which is used to hold information that is not contained in the structure. Info strings are used to hold additional information which may be present in some formats. VoxelWidth, VoxelHeight, and VoxelDepth are used to carry the voxel dimensions if available.

AVW++

The Biomedical Imaging Resource has developed a C++ version of AVW (currently referred to as AVW++) in the form of a class library. In general, classes are based on the AVW structures and the methods are based on the AVW functions. These functions have not been rewritten but rather are called directly from within the methods, making this library a C++ "wrapper" for AVW.

The private data for most of the classes consists only of the corresponding AVW structures. This construct provides a layer of protection against direct manipulation of the data, i.e. data encapsulation. Each of the AVW functions has been matched with the appropriate class and is called via public methods of the same name or through the constructors, destructors and operator overload methods (=, +, -, \*, /, ==, etc.) It should be noted since many of the methods consist of several lines of source code that do little more than call their corresponding AVW routines, the possible performance degradation brought on by the extra C++ layer can be limited by "inlining" the methods.

AVW++ was developed to support internal C++ projects, and does not have the same documentation and support found in AVW. It is, however, recommended that any C++ developers requiring AVW functionality consider looking into AVW++ first.

Classes

The following classes are found in AVW++:

A\_Colormap

A\_ObjectMap

```
A_FPoint2
                                                                A_Point2
                                                                A_Point3
                     A_FPoint3
                     A_FPointList2
                                                                A_PointList2
                     A_FPointList3
                                                                A_PointList3
                     A_FilterCoeffs
                                                                A_PointValueList
                     A_Histogram
                                                                A_Rect2
                     A_Image
                                                                A Rect3
                     A_ImageFile
                                                                A_RenderedImage
                     A_IntensityStats
                                                                A_Surface
                     A_Line2
                                                                A_Volume
                     A_Line3
                                                                A_VolumeRenderParms
                     A_Matrix
                                                                K_String
                     To inquire about acquiring AVW++ contact the Biomedical Imaging Resource, Mayo
                     Foundation.
PROGRAMMING
                     Creating and deleting an AVW_Image.
      EXAMPLES
                     #include "AVW.h"
                     main()
                       {
                       AVW_Image *image;
                       int w = 64, h = 64;
                       image = AVW_CreateImage(NULL, w, h, AVW_UNSIGNED_CHAR);
                       AVW_DestroyImage(image);
      Example #2
                     Wrapping an AVW_Volume structure around a block of memory.
                     #include "AVW.h"
                     sub(mem, xsize, ysize, zsize, datatype)
                     void *mem;
                     int xsize, ysize, zsize, datatype;
                       AVW_Volume *volume;
                       volume = AVW_CreateVolume(mem, xsize, ysize, zsize, datatype);
                       volume->Mem = NULL; /* prevents the freeing of memory */
                       AVW_DestroyVolume(volume);
      Example #3
                     Error Checking.
                     #include "AVW.h"
                     main()
                       AVW_Image *image;
```

```
int w = 64, h = 64;
                image = AVW_CreateImage(NULL, w, h, AVW_UNSIGNED_CHAR);
                if(image == NULL)
                  AVW_Error("program: AVW_CreateImage");
                  exit(1);
                if(!AVW_SetImage(image, 0.0))
                  AVW_Error("program: AVW_SetImage");
                  exit(1);
                }
Example #4
              Info Strings.
              #include "AVW.h"
              main()
                AVW_Volume *volume;
                double voxel_width;
                voxel_width = AVW_GetNumericInfo("VoxelWidth", volume->Info);
                volume->Info = AVW_PutStringInfo("Processed By",
                               "Your Name Here", volume->Info);
                }
Example #5
              Accessing a Volume Voxel. (Slow)
              #include "AVW.h"
              main()
                AVW_Volume *volume;
                AVW_Point3 point;
                double voxel_value;
                point.X = volume->Width/2;
                point.Y = volume->Height/2;
                point.Z = volume->Depth/2;
```

```
voxel_value = AVW_GetVoxel(volume, &point);
                }
Example #6
              Accessing Volume Voxels. (Fast)
              #include "AVW.h"
              sub(volume)
              AVW_Volume *volume;
                register int i;
                i = volume->VoxelsPerVolume;
                switch(volume->DataType)
                case AVW_UNSIGNED_CHAR:
                    register unsigned char *ptr;
                    ptr = (unsigned char *) volume->Mem;
                    while(i--) *ptr++ = 0;
                  break;
                case AVW_SIGNED_CHAR:
                    register char *ptr;
                    ptr = (char *) volume->Mem;
                    while(i--) *ptr++ = 0;
                  break;
                default:
                  return(AVW_FAIL);
                  break;
                return(AVW_SUCCESS);
Example #7
              Orthogonal Slices.
              #include "AVW.h"
              main()
                AVW_Image *image;
                AVW_Volume *volume;
                int slice = 0;
```

```
image = AVW\_GetOrthogonal(volume, AVW\_TRANSVERSE, slice, NULL);
               if(image)
                 {
                 AVW_PutOrthogonal(image, volume, AVW_TRANSVERSE, slice);
                 AVW_DestroyImage(image);
               }
Example #8
             Re-using Memory.
             #include "AVW.h"
             main()
               AVW_Image *image = NULL;
               AVW_Volume *volume;
               int slice = 0;
               for(slice = 0; slice < volume->Width; ++slice)
                 image = AVW_GetOrthogonal(volume, AVW_SAGITTAL, slice, image);
                 if(image)
                   {
                    AVW_PutOrthogonal(image, volume, AVW_SAGITTAL, slice);
               AVW_DestroyImage(image);
               image = NULL;
Example #9
             Volume Rendering.
             #include "AVW.h"
             #include "AVW_Render.h"
             #include "AVW_ObjectMap.h"
             main()
               AVW_Volume *vol = NULL;
               AVW_ObjectMap *omap = NULL;
               AVW_RenderParameters *r_param = NULL;
               float xangle = -90., yangle = 0., zangle = 0.;
```

```
* AVW_InitializeRenderParameters() usually called when volume is loaded
                  r_param = AVW_InitializeRenderParameters(vol, omap, r_param);
                  while(something_to_do)
                    r_param->ThresholdMinimum = 135;
                    r_param->Matrix = AVW_RotateMatrix(r_param->Matrix, xangle, yangle, zangle, r_param->Matrix
                    if((rendered = AVW_RenderVolume(r_param, rendered)) == NULL)
                      AVW_Error("AVW_RenderVolume");
                      break;
                      }
                      else
                      YourDisplayRoutine(rendered->Image);
                    if(option_to_load_object_map_selected)
                      if((omap = AVW_LoadObjectMap("filename.obj")))
                        r_param = AVW_InitializeRenderParameters(vol, omap, r_param);
Example #10
               Converting specified volume from one file format to another.
               convert_vol infile invol outfile outformat
               #include <stdio.h>
                              "AVW.h"
               #include
               #include "AVW_ImageFile.h"
```

```
main(ac,av)
int ac:
char **av;
AVW_ImageFile *sdbi= AVW_NULL, *sdbo= AVW_NULL;
AVW_Volume *rvol = AVW_NULL;
int i, invol;
char *infilename, *outfilename, *outformat, mess[80];;
if(ac!=5)
 printf("Usage: cv infile infile_number outfilename outformat \n");
exit(0);
infilename = av[1];
        /* Allow user to reference volumes from 1 to n */
        = atoi(av[2]) - 1;
invol
if(invol <= 0)
       printf("positive non-zero volume number 0);
       exit(0);
outfilename = av[3];
/* "AnalyzeImage", "SunRaster", "PPM", etc.*/
outformat = av[4];
if((sdbi = AVW_OpenImageFile(infilename, "r"))==AVW_NULL)
       sprintf(mess, "Open of <%s> failed\n", infilename);
        AVW_Error(mess);
       exit(0);
if(invol >= sdbi->NumVols)
       sprintf(mess, "%s only has %d volumes \n",
         infilename,sdbi->NumVols);
        AVW_Error(mess);
        exit(0);
if((rvol = AVW_ReadVolume(sdbi,invol,rvol))==AVW_NULL)
        AVW_Error("ReadVolume failed\n");
       exit(0);
}
if((sdbo = AVW_CreateImageFile(outfilename,
      outformat, rvol->Width,
      rvol->Height,rvol->Depth,
      rvol->DataType)) == AVW_FAIL)
{
 sprintf(mess, "Create of %s fails. \n",outfilename );
 AVW_Error(mess);
```

```
exit(0);
                if((i = AVW\_WriteVolume(sdbo, 0, rvol))!=AVW\_SUCCESS)
                 sprintf(mess, "WriteVolume to %s fails. \n",outfilename );
                 AVW_Error(mess);
                 exit(0);
                AVW_CloseImageFile(sdbi);
                AVW_CloseImageFile(sdbo);
Example #11
                Converting the first image from any file to PPM format.
                toppm infile outfile
                #include <stdio.h>
                #include <fcntl.h>
                #include <string.h>
                #include <memory.h>
                #include "AVW.h"
                #include "AVW_ImageFile.h"
                main(ac,av)
                int ac;
                char **av;
                AVW_ImageFile *sdb_in=AVW_NULL, *sdb_out=AVW_NULL;
                AVW_Image *Img=AVW_NULL;
                int i,j,ret;
                char *infile, outfile[128], mess[80];
                if(ac!=3)
                        printf("usage: toppm infile outfile");
                        exit(0);
                infile = av[1];
                /* Open input file */
                if((sdb_in = (AVW_ImageFile *)AVW_OpenImageFile(infile, "r"))==NULL)
                        sprintf(mess, "Error opening:<%s> \n",infile);
                        AVW_Error(mess);
                        exit(0);
                /* Seek to First Image */
                if((ret = AVW_SeekImageFile(sdb_in, 0, 0))!=AVW_SUCCESS)
                        sprintf(mess,"Error seeking v:%d s:%d\n",0,0);
```

```
AVW_Error(mess);
                       exit(0);
               }
                if((Img=AVW_ReadImageFile(sdb_in,Img))==AVW_NULL)
                       sprintf(mess, "Error reading v:%d s:%d",i,j);
                       AVW_Error(mess);
                       exit(0);
                }
                sprintf(outfile, "%s.PPM", av[2]);
                if((sdb_out = AVW_CreateDB(outfile, "PPM",
                                                Img->Width, Img->Height,
                                                1,Img->DataType))==AVW_NULL)
               {
                       sprintf(mess,"Error Creating:<%s> \n", outfile);
                       AVW_Error(mess);
                       exit(0);
                AVW_WriteImageFile (sdb_out, Img);
                AVW_CloseImageFile(sdb_out);
                AVW_CloseImageFile(sdb_in);
                }
Example #12
                C++ code fragments that use AVW++.
                 K_String fileName("/images/demos/sample.hdr");
                                                                     // creates file name string
                 A_ImageFile myImageFile(fileName);
                                                                      // opens specified image file
                 A_Image currImage(myImageFile.getImage(4, 2));
                                                                      // constructor: slice 4, vol 2
                 A_Image oldImage = currImage;
                                                                      // makes a copy of currImage
                // the following flips currImage vertically, resizes it 4x, then dithers it to 64 colors
                 currImage.flip(AVW_FALSE, AVW_TRUE).resize(400,400).dither(64);
                       // 2 other A_Image's called otherImage and newImage are constructed.
                // the following adds two images if they are not the same
                 if (currImage != otherImage)
                                                                      //!= operator is overloaded
                   newImage = currImage + otherImage;
                                                                      // + operator is overloaded
                       // an AVW_Volume* called anAVWVolume is created
                 A_Volume someVolume(anAVWVolume);
                                                              // constructor: directly from an AVW_Volume*
                // the following puts currImage into someVolume oriented coronally at slice 4
                 someVolume.putOrthogonal(currImage, AVW_CORONAL, 4);
               }
                               // Note: at this point the destructor for each object constructed
                               // within the scope of these brackets is called, freeing allocated
                               // memory automatically, thus simplifying memory management.
```

<b>ADDITIONAL</b>
<b>PROGRAM</b>
EXAMPLES

Additional AVW example programs and tcl scripts may be found in the directory: AVW/extras

AVW\_AHEImage - performs 2D Adaptive Histogram Equalization

#### **SYNOPSIS**

#include "AVW Filter.h"

AVW\_Image \*AVW\_AHEImage(in\_image, num\_x\_regions, num\_y\_regions, clip\_maximum, clip\_minimum, clip\_fraction, out\_image)

AVW\_Image \*in\_image;

unsigned int num\_x\_regions, num\_y\_regions;

double clip\_maximum, clip\_minimum, clip\_fraction;

AVW\_Image \*out\_image;

# DESCRIPTION

AVW\_AHEImage() performs Adaptive Histogram Equalization on *in\_image*. Adaptive Histogram Equalization is a process of adjusting the gray scale values of an image based on the histogram or count of pixel values in a localized region of the image. The purpose of this equalization is to enhance the viewable contrast in all areas of the image without regard to maintaining any strict mathematical relationship between gray scale value. This method creates a histogram of gray scale values for each set of predefined regions within the image, and adjusts the gray scale values within each region to increase the contrast locally.

NOTE: Value-based measurements should be avoided on Histogram Equalized images. The resulting gray scale values are no longer related between regions.

*In\_image* specifies the image to be enhanced.

*Num\_x\_regions* and *num\_y\_regions* specify the number of regions along each axis.

Clip\_maximum and clip\_minimum specify a range of voxel values. All voxels with values greater than clip\_maximum are set equal to clip\_maximum before the gathering of the histogram information. Likewise, all voxels with values less than clip\_minimum are set to clip\_minimum.

Clip\_fraction limits the contribution of any given gray scale value, and thereby reduces the enhancement of noise in the resulting image. This method is particularly effective for images which have subtle detail in both very bright (high-valued) and very dim (low-valued) regions of the image. It may also be used to expand the dynamic range of gray scale values in a region which has subtle but significant changes.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_AHEImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **SEE ALSO**

AVW\_AHEVolume(), AVW\_AnisotropicAffineImage(), AVW\_AnisotropicDiffusionImage(), AVW\_LowpassFilterImage(), AVW\_MedianFilterImage(), AVW\_OrthoGradFilterImage(), AVW\_RankFilterImage(), AVW\_SobelFilterImage(), AVW\_SobelFilterImage(), AVW\_UnsharpFilterImage(), AVW\_UnsharpFilterImage(), AVW\_Image

AVW\_AHEVolume - performs 3D Adaptive Histogram Equalization

#### **SYNOPSIS**

#include "AVW Filter.h"

AVW\_Volume \*AVW\_AHEVolume(in\_volume, num\_x\_regions, num\_y\_regions, num\_z\_regions, clip\_maximum, clip\_minimum, clip\_fraction, out\_volume)

AVW Volume \*in volume:

 $unsigned\ int\ num\_x\_regions,\ num\_y\_regions,\ num\_z\_regions;$ 

double clip\_maximum, clip\_minimum, clip\_fraction;

AVW\_Volume \*out\_volume;

#### **DESCRIPTION**

AVW\_AHEVolume() performs Adaptive Histogram Equalization on *in\_volume*. Adaptive Histogram Equalization is a process of adjusting the gray scale values of a volume based on the histogram or count of voxel values in a localized region of the volume. The purpose of this equalization is to enhance the viewable contrast in all areas of the volume without regard to maintaining any strict mathematical relationship between gray scale values. This method creates a histogram of gray scale values for each set of predefined regions within the volume, and adjusts the gray scale values within each region to increase the contrast locally.

NOTE: Value-based measurements should be avoided on Histogram Equalized volumes. The resulting gray scale values are no longer related between regions.

*In\_volume* specifies the volume to be enhanced.

*Num\_x\_regions, Num\_y\_regions* and *num\_z\_regions* specify the number of regions along each axis.

Clip\_maximum and clip\_minimum specify a range of voxel values. All voxels with values greater than clip\_maximum are set equal to clip\_maximum before the gathering of the histogram information. Likewise, all voxels with values less than clip\_minimum are set to clip\_minimum.

Clip\_fraction limits the contribution of any given gray scale value, and thereby reduces the enhancement of noise in the resulting volume. This method is particularly effective for volumes which have subtle detail in both very bright (high-valued) and very dim (low-valued) regions of the volume. It may also be used to expand the dynamic range of gray scale values in a region which has subtle but significant changes.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful *AVW\_AHEVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **SEE ALSO**

AVW\_AHEImage(), AVW\_LowpassFilterVolume(), AVW\_MedianFilterVolume(), AVW\_OrthoGradFilterVolume(), AVW\_RankFilterVolume(), AVW\_SigmanFilterVolume(), AVW\_SobelFilterEnhanceVolume(), AVW\_UnsharpFilterVolume(), AVW\_UnsharpFilterEnhanceVolume(), AVW\_VSFMeanFilterVolume(), AVW\_Volume

**NAME** AVW\_AddFPoint2 – adds a point to a list structure

SYNOPSIS #include "AVW.h"

int AVW\_AddFPoint2(trace, point)

AVW\_FPointList2 \*trace; AVW\_FPoint2 \*point;

**DESCRIPTION** | AVW\_AddFPoint2() adds an AVW\_FPoint2, point, to an AVW\_FPointList2, trace.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** If successful *AVW\_AddFPoint2()* returns *AVW\_SUCCESS*. On failure it returns

AVW\_FAIL and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values correspond-

ing to the cause of the failure.

**ERRORS** *AVW\_AddFPoint2()* will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

SEE ALSO | AVW\_AddFPoint3(), AVW\_AddIPoint2(), AVW\_AddIPoint3(), AVW\_AddPoint2(),

AVW\_AddPoint3(), AVW\_AddPointValue(), AVW\_CopyPointList2()

 $AVW\_CreateFPointList2(),\ AVW\_DestroyFPointList2(),\ AVW\_RemoveFPoint2(),$ 

AVW\_FPointList2, AVW\_FPoint2

**NAME** AVW\_AddFPoint3 – adds a point to a list structure

SYNOPSIS #include "AVW.h"

int AVW\_AddFPoint3(trace, point)

AVW\_FPointList3 \*trace; AVW\_FPoint3 \*point;

**DESCRIPTION** AVW\_AddFPoint3() adds an AVW\_FPoint3, point, to an AVW\_FPointList3, trace.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** If successful *AVW\_AddFPoint3()* returns *AVW\_SUCCESS*. On failure it returns

AVW\_FAIL and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values correspond-

ing to the cause of the failure.

**ERRORS** | *AVW\_AddFPoint3()* will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

SEE ALSO | AVW\_AddFPoint2(), AVW\_AddIPoint2(), AVW\_AddIPoint3(), AVW\_AddIPoint2(),

AVW\_AddPoint3(), AVW\_AddPointValue(), AVW\_CopyFPointList3(),

AVW\_CreateFPointList3(), AVW\_DestroyFPointList3(), AVW\_GetFPoint3(),

AVW\_RemoveFPoint3(), AVW\_FPointList3, AVW\_FPoint3

**NAME** AVW\_AddIPoint2 – adds a point to a list structure

SYNOPSIS #include "AVW.h"

int AVW\_AddIPoint2(trace, point)

AVW\_IPointList2 \*trace; AVW\_IPoint2 \*point;

**DESCRIPTION** AVW\_AddIPoint2() adds an AVW\_IPoint2, point to an AVW\_IPointList2, trace.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** If successful AVW\_AddIPoint2() returns AVW\_SUCCESS. On failure it returns AVW\_FAIL

and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the

cause of the failure.

**ERRORS** | *AVW\_AddIPoint2()* will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

SEE ALSO | AVW AddIPoint3(), AVW AddFPoint2(), AVW AddFPoint3(), AVW AddPoint2(),

AVW\_AddPoint3(), AVW\_AddPointValue(), AVW\_CopyIPointList2(),

AVW\_CreateIPointList2(), AVW\_DestroyIPointList2(), AVW\_GetIPoint2(),

AVW\_RemoveIpoint2(), AVW\_IPointList2, AVW\_IPoint2

**NAME** AVW\_AddIPoint3 – adds a point to a list structure

SYNOPSIS #include "AVW.h"

int AVW\_AddIPoint3(trace, point)

AVW\_IPointList3 \*trace; AVW\_IPoint3 \*point;

**DESCRIPTION** AVW\_AddIPoint3() adds an AVW\_IPoint3, point, to an AVW\_IPointList3, trace.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** If successful *AVW\_AddIPoint3()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* 

and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the

cause of the failure.

**ERRORS** | *AVW\_AddIPoint3()* will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

SEE ALSO | AVW\_AddIPoint2(), AVW\_AddFPoint2(), AVW\_AddFPoint3(), AVW\_AddPoint2(),

AVW\_AddPoint3(), AVW\_AddPointValue(), AVW\_CopyIPointList3(),

AVW\_CreateIPointList3(), AVW\_DestroyIPointList3(), AVW\_GetIPoint3(),

AVW\_RemoveIPoint3(), AVW\_IPointList3, AVW\_IPoint3

**NAME** AVW\_AddObject – adds an object to an object map

SYNOPSIS #include "AVW\_ObjectMap.h"

int AVW\_AddObject(object\_map)
AVW\_ObjectMap \*object\_map;

**DESCRIPTION** | AVW\_AddObject() increases the object\_map->NumberOfObjects by one and initializes

object\_map->Object[object\_map->NumberOfObjects - 1].

**RETURN VALUES** If successful *AVW\_AddObject()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* 

and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause

of the failure.

**ERRORS** | *AVW\_AddObject()* will fail if:

**ILLPAR** 

Illegal parameter(s).

SEE ALSO | AVW\_CopyObjectMap(), AVW\_CreateObjectMap(), AVW\_DeleteObject(),

AVW\_DestroyObjectMap(), AVW\_GetObject(), AVW\_LoadObjectMap(), AVW\_PutObject(),

AVW\_SaveObjectMap(), AVW\_RemoveUnusedObjects(), AVW\_RenderVolume(),

AVW\_ObjectMap

**NAME** AVW\_AddPoint2 – adds a point to a list structure

SYNOPSIS #include "AVW.h"

int AVW\_AddPoint2(trace, point)

AVW\_PointList2 \*trace; AVW\_Point2 \*point;

**DESCRIPTION** AVW\_AddPoint2() adds an AVW\_Point2, point, to an AVW\_PointList2, trace.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** If successful *AVW\_AddPoint2()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* 

and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the

cause of the failure.

**ERRORS** | *AVW\_AddPoint2()* will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

SEE ALSO | AVW\_AddFPoint2(), AVW\_AddFPoint3(), AVW\_AddIPoint2(), AVW\_AddIPoint3(),

AVW\_AddPoint3(), AVW\_AddPointValue(), AVW\_CopyPointList2(),

AVW\_CreatePointList2(), AVW\_DestroyPointList2(), AVW\_EditPointList2(),

AVW\_FillPointList2(), AVW\_GetPoint2(), AVW\_RemovePoint2(), AVW\_PointList2,

AVW\_Point2

**NAME** AVW\_AddPoint3 – adds a point to a list structure

SYNOPSIS #include "AVW.h"

int AVW\_AddPoint3(trace, point)

AVW\_PointList3 \*trace; AVW\_Point3 \*point;

**DESCRIPTION** | AVW\_AddPoint3() adds an AVW\_Point3, point, to an AVW\_PointList3, trace.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** If successful *AVW\_AddPoint3()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* 

and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the

cause of the failure.

**ERRORS** *AVW\_AddPoint3()* will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

SEE ALSO | AVW\_AddFPoint2(), AVW\_AddFPoint3(), AVW\_AddIPoint2(), AVW\_AddIPoint3(),

AVW\_AddPoint2(), AVW\_AddPointValue(), AVW\_CopyPointList3(),

AVW\_CreatePointList3(), AVW\_DestroyPointList3(), AVW\_FillPointList3(), AVW\_GetPoint3(), AVW\_RemovePoint3(), AVW\_PointList3, AVW\_Point3

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AVW\_AddPointValue - adds a point and a value to a list structure

**SYNOPSIS** 

#include "AVW.h"

int AVW\_AddPointValue(trace, point, value)

AVW\_PointValueList \*trace;

AVW\_Point2 \*point;

double value;

**DESCRIPTION** 

AVW\_AddPointValue() adds an AVW\_Point2, point, and a value to an AVW\_PointValueList,

trace

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** 

If successful AVW\_AddPointValue() returns AVW\_SUCCESS. On failure it returns

AVW\_FAIL and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values correspond-

ing to the cause of the failure.

**ERRORS** 

AVW\_AddPointValue() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**SEE ALSO** 

AVW\_AddFPoint2(), AVW\_AddFPoint3(), AVW\_AddIPoint2(), AVW\_AddIPoint3(),

AVW\_AddPoint2(), AVW\_AddPoint3(), AVW\_CopyPointValueList(),

 $AVW\_CreatePointValueList(),\ AVW\_DestroyPointValueList(),\ AVW\_GetPointValue(),$ 

AVW\_RemovePointValue(), AVW\_PointValueList, AVW\_Point2

AVW\_AddTreeChild - adds a point to a tree structure

**SYNOPSIS** 

#include "AVW\_Tree.h"

int AVW\_AddTreeChild(tree, parent, child)

AVW\_Tree \*tree;

AVW\_Point3 \*parent, \*child;

**DESCRIPTION** 

AVW\_AddTreeChild() adds an AVW\_Point3, child, to an AVW\_Tree, tree. The parent immediately preceds the *child* in the *tree*. The *parent* point is used to search the *tree* and determine where the *child* is inserted.

These structures are defined in *AVW\_Tree.h* and are used for skeletal tree information.

**RETURN VALUES** 

If successful *AVW\_AddTreeChild()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_AddTreeChild() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**SEE ALSO** 

AVW\_CreateTree(), AVW\_DestroyTree(), AVW\_FindTreeIndex(), AVW\_FindTreeStart(), AVW\_LoadTree(), AVW\_MakeTree(), AVW\_PruneVolume(), AVW\_SaveTree(), AVW\_TreeAnalysis(), AVW\_Point3, AVW\_Tree

AVW\_AnisotropicAffineImage - performs a 2D anisotropic affine transformation

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Image \*AVW\_AnisotropicAffineImage(in\_image, dt, iterations, out\_image)

AVW\_Image \*in\_image;

double dt;

int iterations;

AVW\_Image \*out\_image;

# **DESCRIPTION**

AVW\_AnisotropicAffineImage() performs 2D affine anisotropic diffusion on the in\_image, as specified in reference (1) below, using the implementation scheme described therein. Dt is a time step parameter which specifies how long the diffusion is allowed to run per iteration. A value of 0.25 is recommended for general use and will be used as the default if the supplied value is zero or negative. However, a value of 0.10 or less is required to guarantee stable behavior in all circumstances. The lower value will require more iterations (and hence will yield lower performance) but should be used if absolutely correct results are essential. Iterations specifies how many iterations to run the filter.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **REFERENCES**

(1) Sapiro and Tannenbaum, "Affine Invariant Scale Space", Intl. Journal of Comp. Vision 11:1, pp25-44, 1993.

# **RETURN VALUES**

If successful *AVW\_AnisotropicAffineImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **SEE ALSO**

AVW\_AHEImage(), AVW\_AnisotropicDiffusionImage(), AVW\_InhomogeneityCorrectVolume(), AVW\_LowpassFilterImage(), AVW\_MedianFilterImage(), AVW\_OrthoGradFilterImage(), AVW\_RankFilterImage(), AVW\_SobelFilterImage(), AVW\_SobelFilterImage(), AVW\_UnsharpFilterImage(), AVW\_Inage(), AVW\_In

AVW\_AnisotropicDiffusionImage - performs a 2D anisotropic diffusion transformation

#### **SYNOPSIS**

#include "AVW Filter.h"

AVW\_Image \*AVW\_AnisotropicDiffusionImage(in\_image, iterations, kappa, bias\_flag, out\_image)

**AVW 3.0** 

AVW\_Image \*in\_image;

int iterations;

double kappa;

int bias\_flag;

AVW\_Image \*out\_image;

# **DESCRIPTION**

AVW\_AnisotropicDiffusionImage() performs 2D Anisotropic Diffusion on the in\_image, as specified in references (1) and (2) below, using the exponential diffusion function described therein. Iterations specifies how many iterations to run the filter. Kappa specifies the gray level value difference above which the diffusion between two adjacent pixels becomes significantly suppressed (corresponding to the kappa in the equations in the references). Bias\_flag specifies whether or not to perform biased anisotropic diffusion, as described in (2) and (3). A value of 1 specifies that biased anisotropic diffusion will be performed and 0 specifies that the biased option will not be performed.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### REFERENCES

- (1) Perona and Malik, "Scale-Space and Edge Detection Using Anisotropic Diffusion", IEEE PAMI 12, pp 629-639, 1990.
- (2) Gerig, Kubler, Kikinis, and Jolesz, "Nonlinear Anisotropic Filtering of MRI Data", IEEE Trans Med Img 11, pp 221-232, 1992.
- (3) Nordstrom, "Biased anisotropic diffusion A unified regularization and diffusion approach to edge detection", Image Vision Comput., vol. 8, no. 4, pp 318-327, 1990.

# **RETURN VALUES**

If successful *AVW\_AnisotropicDiffusionImage()* returns an *AVW\_Image.* On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **SEE ALSO**

AVW\_AHEImage(), AVW\_AnisotropicAffineImage(), AVW\_InhomogeneityCorrectVolume(), AVW\_LowpassFilterImage(), AVW\_MedianFilterImage(), AVW\_OrthoGradFilterImage(), AVW\_RankFilterImage(), AVW\_SigmaFilterImage(), AVW\_SobelFilterImage(), AVW\_SobelFilterImage(), AVW\_UnsharpFilterImage(), AVW\_UnsharpFilterImage(), AVW\_UnsharpFilterImage(), AVW\_Image

AVW\_AnisotropicDiffusionImages - performs a 2D anisotropic diffusion transformation

#### **SYNOPSIS**

#include "AVW Filter.h"

int AVW\_AnisotropicDiffusionImages(in\_images, num\_images, iterations, kappa, bias\_flag)

AVW\_Image \*\*in\_image; int num\_images; int iterations; double kappa; int bias\_flag;

#### **DESCRIPTION**

AVW\_AnisotropicDiffusionImages() performs 2D Anisotropic Diffusion on the a group of spatially correlated *in\_images*, as specified in references (1) and (2) below, using the exponential diffusion function described therein. *num\_images* is number of spatially correlated images.

Iterations specifies how many iterations to run the filter. Kappa specifies the gray level value difference above which the diffusion between two adjacent pixels becomes significantly suppressed (corresponding to the kappa in the equations in the references). Bias\_flag specifies whether or not to perform biased anisotropic diffusion, as described in (2) and (3). A value of 1 specifies that biased anisotropic diffusion will be performed and 0 specifies that the biased option will not be performed.

# REFERENCES

- (1) Perona and Malik, "Scale-Space and Edge Detection Using Anisotropic Diffusion", IEEE PAMI 12, pp 629-639, 1990.
- (2) Gerig, Kubler, Kikinis, and Jolesz, "Nonlinear Anisotropic Filtering of MRI Data", IEEE Trans Med Img 11, pp 221-232, 1992.
- (3) Nordstrom, "Biased anisotropic diffusion A unified regularization and diffusion approach to edge detection", Image Vision Comput., vol. 8, no. 4, pp 318-327, 1990.

# **RETURN VALUES**

If successful  $AVW\_AnisotropicDiffusionImages()$  returns  $AVW\_SUCCESS$ . On failure it returns  $AVW\_FAIL$  and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

#### **SEE ALSO**

AVW\_AnnisotropicDiffusionImage(), AVW\_Image

 $AVW\_An isotropic Diffusion Volumes-performs~a~2D~an isotropic~diffusion~transformation$ 

# **SYNOPSIS**

#include "AVW\_Filter.h"

int AVW\_AnisotropicDiffusionVolumes(in\_volumes, num\_volumes, iterations, kappa, bias\_flag)

AVW\_Volume \*\*in\_volumes;

int num\_volumes;

int iterations:

double kappa;

int bias\_flag;

#### **DESCRIPTION**

AVW\_Anisotropic Diffusion Volumes() performs 2D (slice by slice) Anisotropic Diffusion on the a group of spatially correlated *in\_volumes*, as specified in references (1) and (2) below, using the exponential diffusion function described therein. *num\_volumes* is number of spatially correlated volumes.

Iterations specifies how many iterations to run the filter. *Kappa* specifies the gray level value difference above which the diffusion between two adjacent pixels becomes significantly suppressed (corresponding to the *kappa* in the equations in the references). *Bias\_flag* specifies whether or not to perform biased anisotropic diffusion, as described in (2) and (3). A value of 1 specifies that biased anisotropic diffusion will be performed and 0 specifies that the biased option will not be performed.

#### **REFERENCES**

- (1) Perona and Malik, "Scale-Space and Edge Detection Using Anisotropic Diffusion", IEEE PAMI 12, pp 629-639, 1990.
- (2) Gerig, Kubler, Kikinis, and Jolesz, "Nonlinear Anisotropic Filtering of MRI Data", IEEE Trans Med Img 11, pp 221-232, 1992.
- (3) Nordstrom, "Biased anisotropic diffusion A unified regularization and diffusion approach to edge detection", Image Vision Comput., vol. 8, no. 4, pp 318-327, 1990.

#### **RETURN VALUES**

If successful *AVW\_AnisotropicDiffusionVolumes()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **SEE ALSO**

AVW\_AnnisotropicDiffusionImages(), AVW\_AnnisotropicDiffusionImage(), AVW\_Image

AVW\_AutoTrace - returns a mask for a connected thresholded region

#### **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_AutoTrace(image, thresh\_max, thresh\_min, seed, type, exterior\_only, gap\_size, mask)

AVW\_Image \*image;

double thresh\_max, thresh\_min;

AVW\_Point2 \*seed;

int type, exterior\_only, gap\_size;

AVW\_Image \*mask;

# **DESCRIPTION**

AVW\_AutoTrace() finds and returns a mask in the AVW\_Image, mask. The mask identifies the region defined by the seed, thresh\_max, and thresh\_min. The region is grown from the seed and includes all pixels which are connected via four neighbors to it and within the threshold values.

*Type* specifies the type of borders to return in the mask.

*AVW\_AUTO\_OFF\_EDGE* - sets the pixels which are just off the actual edge of the connected object.

*AVW\_AUTO\_ON\_EDGE* - indicates that the pixels exactly on the edge should be set.

 $AVW\_AUTO\_FILLED$  - returns the entire connected object, and not just the edge pixels.

Exterior\_only causes interior holes to be filled and not shown.

*Gap\_size* specified the minimum allowable gap. A value of *zero* (0) specifies an unrestricted gap.

Mask is provided as a method of reusing an existing AVW\_Image.

#### **RETURN VALUES**

If successful *AVW\_AutoTrace()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **SEE ALSO**

AVW\_GetThresholdedBoundary(), AVW\_GetBoundaryAndDelete(), AVW\_GetMaskBoundary(), AVW\_ThresholdImage(), AVW\_Point2, AVW\_Image

NAME AV

 $AVW\_BestOpDataType-returns\ best\ output\ datatype\ for\ an\ operation$ 

**SYNOPSIS** 

#include "AVW.h"

int AVW\_BestOpDataType(dt1, max1, min1, op, dt2, max2, min2)

int dt1;

double max1, min1;

int op,

int dt2,

double max2, min2;

**DESCRIPTION** 

AVW\_BestOpDataType() returns the best output datatype.

AVW\_BlendImage - merges two images

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_BlendImages(image1, factor, image2, blend\_type, out\_image)

AVW\_Image \*image1; register double factor;

AVW Image \*image2;

int blend\_type;

AVW\_Image \*out\_image;

## **DESCRIPTION**

AVW\_BlendImages() returns a blended image.

*Image1* and *image2* specify the two images to merge. They must have a data type of *AVW\_UNSIGNED\_CHAR* or *AVW\_COLOR*.

Factor is a number from 0.0 to 1.0, specifying a *image1* to *image2* weighting factor. Factor is only used for the

*Blend\_type* is one of the folling.

 $AVW\_BLEND\_AVERAGE \text{ - use weighted average of th two input images.} \\ AVW\_BLEND\_AVG\_IGNORE\_ZEROS \text{ - zero in one image, causes } 100\% \text{ of the otehr image to be used } AVW\_BLEND\_CHECKBOARD \text{ - everyother pixel is used from everyother image.} \\$ 

*AVW\_BLEND\_DIFF* - returns a normaized difference *AVW\_BLEND\_REDGREEN* - Red channel is determined by image1, green channel from image2.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_BlendImages()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_BlendImages() will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

**SEE ALSO** 

AVW\_Image()

 $AVW\_BoundedStepSearchExtreme-Searches \ for \ best \ registration \ of \ two \ volume \ images.$ 

#### **SYNOPSIS**

#include "AVW\_MatchVoxels.h"

 $AVW\_Matrix *AVW\_BoundedStepSearchExtreme (dirflag, base, match, points, steps, func, interpolation, interpolation) and dirflag, interpolation;$ 

AVW\_Volume \*base,\*match;

AVW\_FPointList3 \*points;

AVW\_Matrix \*matrix;

AVW\_StepSearchSpec \*steps;

int func;

## **DESCRIPTION**

AVW\_BoundedStepSearchExtreme() Performs a bounded stepwise search of 6-DOF physical registration space to find the nearest extreme of a voxel statistic function relating two AVW\_Volumes. AVW\_BoundedStepSearchExtreme returns the AVW\_Matrix which transforms the match volume into the space of the base volume at the extreme.

*dirflag* determines whether maxima or minima are searched for. Defined values are *AVW\_MAXIMUM* and *AVW\_MINIMUM*.

base and match are the AVW\_Volume s to be registered.

points is an  $AVW\_FPointList3$  containing a list of coordinate points in the match image to be used as the sample voxels for the registration. points is usually created by a call to  $AVW\_SetupVolumeSample$ 

*steps* contains the specification of the step search, primarily specific step sizes for each of the 6 degrees of freedom and the maximum number of steps which may be taken in searching for the extreme.

func specifies the statistical measure to be used. Defined values are AVW\_NMI.

*interpolation* specifies the intepolation type to be used in the search, and may be any of the defined AVW interpolation types.

*matrix* is taken as the starting orientation for the search. If *Matrix* is NULL, a new identity matrix is created, and used as the starting orientation.

## **RETURN VALUES**

If successful returns an *AVW\_Matrix* which transforms the match volume into the space of the base volume at the extreme.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_BoundedStepSearchExtreme() will fail if the following is true:

**BADMAL** 

Could not allocate memory for internal structures.

# **ILLPAR**

Sample or interpolation type is not recognized.

SEE ALSO AVW\_SetupVolumeSample() AVW\_StepSearchExtreme() AVW\_SampleSpec AVW\_StepSearchSpec

 $AVW\_BoundedStepSearchExtreme2D-Searches \ for \ best \ registration \ of \ two \ volume \ images.$ 

#### **SYNOPSIS**

#include "AVW\_MatchVoxels.h"

 $AVW\_Matrix *AVW\_BoundedStepSearchExtreme2D (dirflag, base, match, points, steps, func, interpolation;) and the property of t$ 

AVW\_Image \*base,\*match;

AVW\_FPointList2 \*points;

AVW\_Matrix \*matrix;

AVW\_StepSearchSpec \*steps;

int func;

## **DESCRIPTION**

AVW\_BoundedStepSearchExtreme2D() Performs a bounded stepwise search of 3-DOF physical registration space to find the nearest extreme of a voxel statistic function relating two AVW\_Images. AVW\_BoundedStepSearchExtreme2D returns the AVW\_Matrix which transforms the match image into the space of the base image at the extreme.

*dirflag* determines whether maxima or minima are searched for. Defined values are *AVW\_MAXIMUM* and *AVW\_MINIMUM*.

base and match are the AVW\_Image s to be registered.

points is an  $AVW\_FPointList2$  containing a list of coordinate points in the match image to be used as the sample voxels for the registration. points is usually created by a call to  $AVW\_SetupImageSample$ 

steps contains the specification of the step search, primarily specific step sizes for each of the 3 degrees of freedom and the maximum number of steps which may be taken in searching for the extreme. Elements of steps relating to 6-DOF volume registration are ignored by AVW\_BoundedStepSearchExtreme2D.

func specifies the statistical measure to be used. Defined values are AVW\_NMI.

*interpolation* specifies the intepolation type to be used in the search, and may be any of the defined AVW interpolation types.

*matrix* is taken as the starting orientation for the search. If *Matrix* is NULL, a new identity matrix is created, and used as the starting orientation.

## **RETURN VALUES**

If successful returns an  $AVW\_Matrix$  which transforms the match image into the space of the base image at the extreme.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

*AVW\_BoundedStepSearchExtreme2D()* will fail if the following is true:

**BADMAL** 

Could not allocate memory for internal structures.

# **ILLPAR**

Sample or interpolation type is not recognized.

AVW\_CalculateObjectRegions - calculated minimum enclosing region for objects

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW\_ObjectMap.h"

 $int\ AVW\_CalculateObjectRegions (object\_map,\ flag)$ 

AVW\_ObjectMap \*object\_map;

int flag;

**DESCRIPTION** 

AVW\_CalculateObjectRegions() calculates the minimum enclosing regions for AVW\_Objects within a AVW\_ObjectMap.

If *flag* is set to *AVW\_TRUE* (1), then the regions are calculated for all objects. A value of *AVW\_FALSE* (2), indicates that only regions for enabled objects (DisplayFlag = AVW\_TRUE) will be calculated.

**RETURN VALUES** 

If successful *AVW\_CalculateObjectRegions()* returns AVW\_SUCCESS.. On failure it returns AVW\_FAIL and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_CalculateObjectRegions() will fail if the following is true:

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_AddObject(), AVW\_DeleteObject(), AVW\_DestroyObjectMap(), AVW\_CreateObjectMap(), AVW\_GetObject(), AVW\_PutObject() AVW\_LoadObjectMap(), AVW\_SaveObjectMap(), AVW\_RenderVolume(), AVW\_ObjectMap, AVW\_Object

AVW\_Malloc – allocates system memory

## **SYNOPSIS**

#include "AVW.h"

void \*AVW\_Malloc(size)
unsigned int size;

void \*AVW\_Calloc(num, size)
unsigned int num;
unsigned int size;

void \*AVW\_Realloc(size, ptr)
unsigned int size;
void \*ptr;

void AVW\_Free(ptr)
void \*ptr;

## **DESCRIPTION**

These procedures provide a platform and compiler independent interface for memory allocation. Programs that need to transfer ownership of memory blocks between *AVW* and other modules should use these routines rather than the native *malloc()* and *free()* routines provided by the *C* run-time library.

AVW\_Malloc returns a pointer to a size bytes suitably aligned for any use.

*AVW\_Calloc allocates space for an array nelem* elements of *size* elsize. The space is initialized to zeros.

*Tcl\_Realloc* changes the size of the block pointed to by *ptr* to *size* bytes and returns a pointer to the new block. The contents will be unchanged up to the lesser of the new and old sizes. The returned location may be different from *ptr*.

*Tcl\_Free* makes the space referred to by *ptr* available for further allocation.

## **SEE ALSO**

malloc(), free()

AVW\_ChamferDistanceImage - calculates chamfer distances

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_ChamferDistanceImage(in\_image, out\_image)

AVW\_Image \*in\_image; AVW\_Image \*out\_image;

## **DESCRIPTION**

AVW\_ChamferDistanceImage() calculates the chamfer distance between all pixels in *in\_image* to the nearest nonzero pixel within the image. The integer distances, which are scaled by a factor of 3, are returned in the pixels of *out\_image*.

*In\_image* must be of data type *AVW\_UNSIGNED\_CHAR*. *Out\_image* may be of data type *AVW\_UNSIGNED\_CHAR* or *AVW\_UNSIGNED\_SHORT* depending on the maximum distance computed within the image.

The input image may be preprocessed using AVW\_ThresholdImage() and/or AVW\_FindImageEdges().

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## REFERENCE

Borgefors, G. "Distance Transformations in Arbitrary Dimensions." Computer Vision, Graphics, and Image Processing, vol27, pp.321-345, 1984.

## **RETURN VALUES**

If successful *AVW\_ChamferDistanceImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ChamferDistanceImage() will fail if:

**ILLDT** 

Data type of input image must be AVW\_UNSIGNED\_CHAR.

#### **SEE ALSO**

AVW\_ThresholdImage(), AVW\_FindImageEdges()

AVW ChamferDistanceVolume – calculates chamfer distances

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_ChamferDistanceVolume(in\_image, out\_image)

AVW\_Volume \*in\_volume; AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_ChamferDistanceVolume() calculates the chamfer distance between all voxels in *in\_volume* to the nearest nonzero pixel within the volume. The integer distances, which are scaled by a factor of 3, are returned in the voxels of *out\_volume*.

*In\_volume* must be of data type *AVW\_UNSIGNED\_CHAR*. *Out\_volume* may be of data type *AVW\_UNSIGNED\_CHAR* or *AVW\_UNSIGNED\_SHORT* depending on the maximum distance computed within the volume.

The input volume may be preprocessed using AVW\_ThresholdVolume() and/or AVW\_FindVolumeEdges().

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

REFERENCE

Borgefors, G. "Distance Transformations in Arbitrary Dimensions." Computer Vision, Graphics, and Volume Processing, vol27, pp.321-345, 1984.

**RETURN VALUES** 

If successful *AVW\_ChamferDistanceVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ChamferDistanceVolume() will fail if:

**ILLDT** 

Data type of input volume must be AVW\_UNSIGNED\_CHAR.

**SEE ALSO** 

AVW ThresholdVolume(), AVW FindVolumeEdges()

AVW\_ChangeIsolatedPixels – changes the values of isolated pixels to that of their neighbors

**SYNOPSIS** 

#include "AVW.h"

 $AVW\_Image *AVW\_ChangeIsolatedPixels (in\_image, changedPixels, out\_image) \\ AVW\_Image *in\_image;$ 

**AVW 3.0** 

int \*changedPixels;

AVW\_Image \*out\_image;

**DESCRIPTION** 

*AVW\_ChangeIsolatedPixels()* uses a mode filter to change the values of isolated pixels to that of their surrounding neighbors. This function can be used as a post processing step for the images returned from multi-spectral classification.

in\_image must be of DataType AVW\_UNSIGNED\_CHAR.

changedPixels is a pointer to an integer which returns the number of pixels changed.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_ChangeIsolatedPixels()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ChangeIsolatedPixels() will fail if one or more of the following are true:

**ILLDT** 

Input image is not AVW\_UNSIGNED\_CHAR.

**SEE ALSO** 

AVW\_ClassifyImage, AVW\_Image

AVW\_ClassifiedImageToCentroidFile - creates a multi-spectral sample file from a mask

## **SYNOPSIS**

#include "AVW.h"

int AVW\_ClassifiedImageToCentroidFile(imgs, numimgs, classImage, CentroidFile) AVW\_Image \*\*imgs;

int numimgs;

AVW Image \*classImage;

char \*CentroidFile;

#### **DESCRIPTION**

AVW\_ClassifiedImageToCentroidFile() generates an AVW multi-spectral centroid file from a mask image and a list of corresponding spatially correlated images. This file can be used to perform image classification with AVW\_UnsuperClassifyImage() and AVW\_UnsuperClassifyVolume().

An arithmetic average is computed for all the classified pixels for each class and for each input image; producing a text file where each row contains the average pixel values for that class in each volume.

Imgs is a list of spatially correlated images.

Numimgs is the number of images in Imgs

ClassImage is an AVW\_Image of DataType AVW\_UNSIGNED\_CHAR and the same size as the images in *Imgs* in which pixels to be used as training samples have non-zero values. This should be a classified image in which pixels with non-zero values are treated as belonging to a class.

*CentroidFile* is the name of the text file which is created by the function.

## Sample File Contents

9.326923 0.717949 159.322922 131.093750 186.909088 159.636368 222.125000 223.620529

The first line of the file contains a signature identifying the contents of the file. The second line indicates how many classes are described in the file. The third row indicates the number of samples in a row.

## **RETURN VALUES**

AVW\_ClassifiedImageToCentroidFile() returns an AVW\_SUCCESS. On failure it returns AVW\_FAIL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ClassifiedImageToCentroidFile() will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. A memory allocation failed.

**ILLIMG** 

Illegal Image. The images are not all the same dimension.

**ILLDT** 

Illegal Datatype. At least one of the images is not AVW\_UNSIGNED\_CHAR.

**INSPEC** 

Insufficient Specifications. Fewer than two input images were supplied.

**SEE ALSO** 

 $AVW\_ClassifiedVolumeToSampleFile(),\ AVW\_UnsuperClassifyImage, \\ AVW\_UnsuperClassifyVolume,\ AVW\_Image$ 

AVW\_ClassifiedVolumeToCentroidFile - creates a multi-spectral centroid file

## **SYNOPSIS**

#include "AVW.h"

int AVW\_ClassifiedVolumeToCentroidFile(vols, numvols, classVolume, CentroidFile) AVW\_Volume \*\*vols;

int numvols:

AVW Volume \*classVolume;

char \*CentroidFile:

#### **DESCRIPTION**

AVW\_ClassifiedVolumeToCentroidFile() generates an AVW multi-spectral centroid file from a classified volume and a list of corresponding spatially correlated volumes. This file can be used to perform image or volume classification with the Unsupervised Classification functions; AVW\_UnsuperClassifyImage() and AVW\_UnsuperClassifyVolume().

An arithmetic average is computed for all the classified voxels for each class and for each input volume; producing a text file where each row contains the average voxel values for that class in each volume.

Vols is a list of spatially correlated volumes.

Numvols is the number of vols in vols

ClassVolume is an AVW\_Volume of DataType AVW\_UNSIGNED\_CHAR and the same size as the volumes in *vols* in which voxels to be counted in the centroid calculations for each clas have non-zero values. This should be a classified volume in which voxels with non-zero values are treated as belonging to a class.

CentroidFile is the name of the text file which is created by the function.

# Sample File Contents

9.326923 0.717949 159.322922 131.093750 186.909088 159.636368 222.125000 223.620529

#### **RETURN VALUES**

AVW\_ClassifiedVolumeToCentroidFile() returns an AVW\_SUCCESS. On failure it returns AVW\_FAIL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ClassifiedVolumeToCentroidFile() will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. A memory allocation failed.

**ILLVOL** 

Illegal Volume. The volumes are not all the same dimension.

ILLDT

Illegal Datatype. At least one of the volumes is not AVW\_UNSIGNED\_CHAR.

**INSPEC** 

Insufficient Specifications. Fewer than two input images were supplied.

**SEE ALSO** 

 $AVW\_Classified Image To Centroid File (), \ AVW\_Mask Image To Sample File (), \\ AVW\_Unsuper Classify Image, \ AVW\_Unsuper Classify Volume, \ AVW\_Volume$ 

AVW\_ClassifyFromScattergram - classifies pixels from a scattergram

## **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_ClassifyFromScattergram(image1, image2, scattergram, out\_image)

AVW\_Image \*image1;

AVW\_Image \*image2;

AVW Image \*scattergram;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_ClassifyFromScattergram() uses a classified scattergram image, scattergram, and two input images, image1 and image2, to very rapidly classify the pixels in the out\_image. Classified pixels in the scattergram image map to pairs of values in the input images and specific pixels in the out\_image. The pixel values of the scattergram image are taken to be class numbers. Pixels with a value of zero are taken to be unclassified.

*Image1* and *image2* must be the same size and of data type *AVW\_UNSIGNED\_CHAR*. *Scattergram* must be created by using *AVW\_Scattergram()*.

## **RETURN VALUES**

If successful AVW\_ClassifyFromScattergram() returns an AVW\_Image. On failure NULL is returned and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_ClassifyFromScattergram() will fail if one or more of the following are true:

**ICPIMG** 

Incompatible input images. Images are not the same size or not AVW\_UNSIGNED\_CHAR data type.

**BDSCGR** 

Bad scattergram.

**SEE ALSO** 

AVW\_ClassifyImage(), AVW\_ClassifyVolume(), AVW\_Scattergram(), AVW\_Image

AVW\_ClassifyImage - classifies pixels from multi-spectral data sets

## **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_ClassifyImage(imgs, numimgs, train\_img, autotype, maxdist, sigma, kvalue, epochs, hiddenepochs, out image)

AVW\_Image \*\*imgs; int numimgs; AVW\_Image \*train\_img; int autotype; double maxdist; double sigma; double kvalue; int epochs; int hiddenepochs; AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_ClassifyImage() classifies pixels given multi-spectral data consisting of several input images under the supervision of *train\_img* training samples in which some pixels are marked as belonging to various classes.

Several different algorithms can be used to classify unclassified pixels from the input mask image.

\*\*Imgs is a list of spatially correlated images, each of which represents one spectra of the multi-spectral data set. These input images must be of the same dimension and of data type AVW\_UNSIGNED\_CHAR. This input data is unchanged by the classification process.

Numimgs is the number of images in the input image list imgs.

Train\_img is a set of training samples for the various automatic classification algorithms. It must be of the same dimensions as the images from the input image list *imgs*. Its data type must be  $AVW\_UNSIGNED\_CHAR$ . The values of pixels in *train\_img* are taken to be known class numbers of pixels in the input images. Pixels with the value of 0 are taken as unknown and are targets for the classification process. Pixels with the value of 1 are taken as belonging to class number 1, pixels with value of 2 are taken belonging to class number 2, etc. *Train\_img* must be prepared prior to invoking  $AVW\_ClassifyImage()$ .

Autotype specificies the automatic classification algorithm used to classify the image. Acceptable values are AVW\_GAUSSIAN\_CLUSTER, AVW\_NEURAL\_NETWORK, AVW\_NEAREST\_NEIGHBOR, AVW\_K\_NEAREST\_NEIGHBOR, and AVW\_PARZEN\_WINDOWS which are defined in AVW.h.

The AVW\_GAUSSIAN\_CLUSTER technique calculates means and standard deviations for each class along each feature, and then models the class' probability distribution as a Gaussian function with the specified parameters. An unknown pixel is then classified by calculating the probability that it belongs to each class and choosing the best result. A pixel is left unclassified if it lies farther than a certain number of standard deviations from all the class centers (controlled by the *maxdist* parameter).

The AVW\_NEURAL\_NETWORK classifier builds a standard 3-layer feed forward neural network, of the kind commonly trained by backpropagation, and trains it on the class

samples with a more advanced technique known as conjugate gradient optimization [1].

The AVW\_NEAREST\_NEIGHBOR technique simply takes each unclassified pixel, looks for its closest neighbor in feature space among the class samples, and assigns it to that same class. If two samples from different classes are equally close, the pixel is left unclassified

AVW\_K\_NEAREST\_NEIGHBOR extends the previous method to the kvalue nearest neighbors among the class samples, giving each of these an equal vote. In both cases, pixels are left unclassified whose best match samples are farther than the distance given by the maxdist parameter.

The AVW PARZEN WINDOWS technique is similar to AVW GAUSSIAN CLUSTER but makes a more sophisticated estimate of each class' underlying probability distribution function from the samples. It uses these estimates to draw near-optimal decision boundaries, but is much slower than AVW\_GAUSSIAN\_CLUSTER classification. This latter technique is implemented in the manner described in [2].

In each of the classification types, a pixel is assigned to the most likely class (as estimated by the classifier), and this is done for each pixel independently. This can result in a "noisy" classification if the data is noisy or if classes actually overlap in feature space.

Maxdist specifies the maximum distance in feature space that an unknown pixel can be from a sample of a known class to be considered as a possible member of that class. When autotype is AVW\_GAUSSIAN\_CLUSTERING it is in units of standard deviations. This parameter is meaningful and used only when autotype is AVW\_GAUSSIAN\_CLUSTERING, AVW\_NEAREST\_NEIGHBOR, or AVW\_K\_NEAREST\_NEIGHBOR.

Sigma is only used for the AVW\_PARZEN\_WINDOW technique, and is ignored for all others. It specifies the standard deviation of the Gaussian window which is used to smooth the input samples to estimate the probability distribution. A default value of 5.0 is suggested.

Kvalue specifies the number of nearest neighbors in feature space to be considered when using AVW\_K\_NEAREST\_NEIGHBOR classification. This parameter is ignored for all other values of autotype.

*Epochs* specifies the maximum number of passes through the class samples while training the neural network. This parameter is used only when using AVW\_NEURAL\_NETWORK, it is ignored for all other values of autotype.

Hiddenepochs specifies the number of hidden units in the (single hidden layer) neural network. This parameter is used only when using AVW\_NEURAL\_NETWORK, it is ignored for all other values of autotype.

Out\_image is the returned classified image. Pixels which have been successfully classified are set to values of pixels from the training sample mask image which they are most similar to. Pixels with a value of 0 were not classified by the function.

Out image is provided as a method of reusing an existing AVW Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to *out\_image* is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_ClassifyImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_ClassifyImage will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. A memory allocation failed.

ILLIMO

Illegal Image. The images are not all the same dimension.

**ILLDT** 

Illegal Datatype. At least one of the images is not AVW\_UNSIGNED\_CHAR.

**BDTRSM** 

Bad Training Sample. The supplied training samples were unusable.

**INSPEC** 

Insufficient Specifications. Fewer than two input images were supplied.

**SEE ALSO** 

AVW\_ClassifyVolume() AVW\_ClassifyFromScattergram(), AVW\_Scattergram(), AVW\_Image

#### REFERENCES

- [1] A. Kramer and A. Sangiovanni-Vincentelli, "Efficient Parallel Learning Algorithms for Neural Networks", in Advanced in Neural Information Processing Systems 1, pp 40-48, Morgan-Kauffman, San Mateo, CA 1989
- [2] D. F. Specht, "Probabilistic Neural Networks, Neural Networks, Vol 3, pp 109-118, 1990.
- [3] M. Morrison and Y. Attikiouzel, "A Probabilistic Network Based Image Segmentation Network for Magnetic Resonance Images", Proc. Intl. Joint Conference on Neural Networks, Baltimore, MD, June 7-11, 1992, pp III-60 III-65, IEEE Press, 1992

AVW\_ClassifyImageFromSampleFile - classifies pixels from multi-spectral data sets

## **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_ClassifyImageFromSampleFile(imgs, numimgs, SampleFile, autotype, maxdist, sigma,

kvalue, epochs, hiddenepochs,

out\_image)

AVW\_Image \*\*imgs;

int numimgs;

char \*SampleFile;

int autotype;

double maxdist;

double sigma;

double kvalue;

int epochs;

int hiddenepochs;

AVW\_Image \*out\_image;

## **DESCRIPTION**

AVW\_ClassifyImageFromSampleFile() classifies pixels given multi-spectral data consisting of several input images under the supervision of SampleFile, a text file which contains a list of class numbers and corresponding multi-spectral values.

Several different algorithms can be used to classify unclassified pixels from the input mask image.

\*\*Imgs is a list of spatially correlated images, each of which represents one spectra of the multi-spectral data set. These input images must be of the same dimension. This input data is unchanged by the classification process.

Numimgs is the number of images in the input image list imgs.

SampleFile is a set of training samples for the various automatic classification algorithms. This is a text file created by AVW\_MaskVolumeToSampleFile() or AVW\_MaskImageToSampleFile().

Autotype specificies the automatic classification algorithm used to classify the image. Acceptable values are AVW\_GAUSSIAN\_CLUSTER, AVW\_NEURAL\_NETWORK, AVW\_NEAREST\_NEIGHBOR, AVW\_K\_NEAREST\_NEIGHBOR, AVW\_PARZEN\_WINDOWS AVW\_NEAREST\_MEAN and AVW\_NEAREST\_MEDIAN which are defined in AVW.h.

The AVW\_GAUSSIAN\_CLUSTER technique calculates means and standard deviations for each class along each feature, and then models the class' probability distribution as a Gaussian function with the specified parameters. An unknown pixel is then classified by calculating the probability that it belongs to each class and choosing the best result. A pixel is left unclassified if it lies farther than a certain number of standard deviations from all the class centers (controlled by the *maxdist* parameter).

The *AVW\_NEURAL\_NETWORK* classifier builds a standard 3-layer feed forward neural network, of the kind commonly trained by backpropagation, and trains it on the class samples with a more advanced technique known as conjugate gradient optimization [1].

The AVW\_NEAREST\_NEIGHBOR technique simply takes each unclassified pixel, looks

for its closest neighbor in feature space among the class samples, and assigns it to that same class. If two samples from different classes are equally close, the pixel is left unclassified

AVW\_K\_NEAREST\_NEIGHBOR extends the previous method to the *kvalue* nearest neighbors among the class samples, giving each of these an equal vote. In both cases, pixels are left unclassified whose best match samples are farther than the distance given by the *max-dist* parameter.

The AVW\_PARZEN\_WINDOWS technique is similar to AVW\_GAUSSIAN\_CLUSTER but makes a more sophisticated estimate of each class' underlying probability distribution function from the samples. It uses these estimates to draw near-optimal decision boundaries, but is much slower than AVW\_GAUSSIAN\_CLUSTER classification. This latter technique is implemented in the manner described in [2].

The AVW\_NEAREST\_MEAN technique calculates the mean vector for each training class. Each voxel to be classified is assigned to the class with the closest mean vector within the value specified by Maxdist.

The *AVW\_NEAREST\_MEDIAN* technique works in the same way as the *AVW\_NEAREST\_MEAN* except that the median vector for each class is used.

In each of the classification types, a pixel is assigned to the most likely class (as estimated by the classifier), and this is done for each pixel independently. This can result in a "noisy" classification if the data is noisy or if classes actually overlap in feature space.

Maxdist specifies the maximum distance in feature space that an unknown pixel can be from a sample of a known class to be considered as a possible member of that class. When autotype is AVW\_GAUSSIAN\_CLUSTERING it is in units of standard deviations. This parameter is meaningful and used only when autotype is AVW\_GAUSSIAN\_CLUSTERING, AVW\_NEAREST\_NEIGHBOR, AVW\_NEAREST\_NEIGHBOR, AVW\_NEAREST\_MEAN or AVW\_NEAREST\_MEDIAN are used.

*Sigma* is only used for the *AVW\_PARZEN\_WINDOW* technique, and is ignored for all others. It specifies the standard deviation of the Gaussian window which is used to smooth the input samples to estimate the probability distribution. A default value of 5.0 is suggested.

*Kvalue* specifies the number of nearest neighbors in feature space to be considered when using *AVW\_K\_NEAREST\_NEIGHBOR* classification. This parameter is ignored for all other values of *autotype*.

*Epochs* specifies the maximum number of passes through the class samples while training the neural network. This parameter is used only when using *AVW\_NEURAL\_NETWORK*, it is ignored for all other values of *autotype*.

*Hiddenepochs* specifies the number of hidden units in the (single hidden layer) neural network. This parameter is used only when using *AVW\_NEURAL\_NETWORK*, it is ignored for all other values of *autotype*.

*Out\_image* is the returned classified image. Pixels which have been successfully classified are set to values of pixels from the training sample mask image which they are most similar to. Pixels with a value of 0 were not classified by the function.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible

only if the size and data type of the provided <code>out\_image</code> meet the requirements of the function. In this case the pointer to <code>out\_image</code> is returned by the function. If not reusable <code>out\_image</code> will be reallocated. (See <code>Memory Usage</code> in the <code>AVW Programmer</code>'s <code>Guide.</code>)

## **RETURN VALUES**

If successful *AVW\_ClassifyImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_ClassifyImage will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. A memory allocation failed.

ILLIMG

Illegal Image. The images are not all the same dimension.

**BDTRSM** 

Bad Training Sample. The supplied training samples were unusable.

INSPEC

Insufficient Specifications. Fewer than two input images were supplied.

## **SEE ALSO**

 $AVW\_ClassifyVolumeFromSampleFile(),\ AVW\_MaskVolumeToSampleFile(),\ AVW\_ClassifyVolume(),\ AVW\_ClassifyImage(),\ AVW\_Image$ 

## **REFERENCES**

[1] A. Kramer and A. Sangiovanni-Vincentelli, "Efficient Parallel Learning Algorithms for Neural Networks", in Advanced in Neural Information Processing Systems 1, pp 40-48, Morgan-Kauffman, San Mateo, CA 1989

[2] D. F. Specht, "Probabilistic Neural Networks, Neural Networks, Vol 3, pp 109-118, 1990.

AVW\_ClassifyScattergram - classifies a scattergram

**SYNOPSIS** 

#include "AVW.h"

 $AVW\_Image *AVW\_ClassifyScattergram(mask, autotype,$ 

maxdist, sigma, kvalue, epochs, hiddenunits, out image)

AVW\_Image \*mask;

int autotype;

double maxdist;

double sigma;

double kvalue;

int epochs;

int hiddenunits;

AVW\_Image \*out\_image;

## **DESCRIPTION**

AVW\_ClassifyScattergram() classifies additional pixels in a scattergram produced by AVW\_Scattergram(). Several different algorithms can be used to classify unclassified pixels from the input *mask*.

Mask is a scattergram produced with training samples with AVW\_Scattergram(). Its data type must be AVW\_UNSIGNED\_CHAR. The values of pixels in mask are taken to be known class numbers of pixels in the input images. Pixels with the value of 0 are taken as unknown and are targets for the classification process. Pixels with the value of 1 are taken as belonging to class number 1, pixels with value of 2 are taken belonging to class number 2, etc. Mask must be prepared prior to invoking AVW\_ClassifyScattergram().

Autotype specificies the automatic classification algorithm used to classify the image. Acceptable values are AVW\_GAUSSIAN\_CLUSTER, AVW\_NEURAL\_NETWORK, AVW\_NEAREST\_NEIGHBOR, AVW\_K\_NEAREST\_NEIGHBOR, and AVW\_PARZEN\_WINDOWS which are defined in AVW.h.

The AVW\_GAUSSIAN\_CLUSTER technique calculates means and standard deviations for each class along each feature, and then models the class' probability distribution as a Gaussian function with the specified parameters. An unknown pixel is then classified by calculating the probability that it belongs to each class and choosing the best result. A pixel is left unclassified if it lies farther than a certain number of standard deviations from all the class centers (controlled by the *maxdist* parameter).

The AVW\_NEURAL\_NETWORK classifier builds a standard 3-layer feed forward neural network, of the kind commonly trained by backpropagation, and trains it on the class samples with a more advanced technique known as conjugate gradient optimization [1].

The AVW\_NEAREST\_NEIGHBOR technique simply takes each unclassified pixel, looks for its closest neighbor in feature space among the class samples, and assigns it to that same class. If two samples from different classes are equally close, the pixel is left unclassified

AVW\_K\_NEAREST\_NEIGHBOR extends the previous method to the *kvalue* nearest neighbors among the class samples, giving each of these an equal vote. In both cases, pixels are left unclassified whose best match samples are farther than the distance given by the *max-dist* parameter.

The AVW\_PARZEN\_WINDOWS technique is similar to AVW\_GAUSSIAN\_CLUSTER but makes a more sophisticated estimate of each class' underlying probability distribution

function from the samples. It uses these estimates to draw near-optimal decision boundaries, but is much slower than *AVW\_GAUSSIAN\_CLUSTER* classification. This latter technique is implemented in the matter described in [2].

In each of the classification types, a pixel is assigned to the most likely class (as estimated by the classifier), and this is done for each pixel independently. This can result in a "noisy" classification if the data is noisy or if classes actually overlap in feature space.

Maxdist specifies the maximum distance in feature space that an unknown pixel can be from a sample of a known class to be considered as a possible member of that class. When autotype is AVW\_GAUSSIAN\_CLUSTERING it is in units of standard deviations. This parameter is meaningful and used only when autotype is AVW\_GAUSSIAN\_CLUSTERING, AVW\_NEAREST\_NEIGHBOR, or AVW\_K\_NEAREST\_NEIGHBOR.

*Sigma* is only used for the *AVW\_PARZEN\_WINDOW* technique, and is ignored for all others. It specifies the standard deviation of the Gaussian window which is used to smooth the input samples to estimate the probability distribution. A default value of 5.0 is suggested.

*Kvalue* specifies the number of nearest neighbors in feature space to be considered when using *AVW\_K\_NEAREST\_NEIGHBOR* classification. This parameter is ignored for all other values of *autotype*.

*Epochs* specifies the maximum number of passes through the class samples while training the neural network. This parameter is used only when using *AVW\_NEURAL\_NETWORK*, it is ignored for all other values of *autotype*.

*Hiddenepochs* specifies the number of hidden units in the (single hidden layer) neural network. This parameter is used only when using *AVW\_NEURAL\_NETWORK*, it is ignored for all other values of *autotype*.

*Out\_image* is the returned classified image. Pixels which have been successfully classified are set to values of pixels from the training sample mask image which they are most similar to. Pixels with a value of 0 were not classified by the function.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_ClassifyScattergram()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ClassifyScattergram will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. A memory allocation failed.

ILLIMO

Illegal Image. The images are not all the same dimension.

II.I.DT

Illegal Datatype. At least one of the images is not AVW\_UNSIGNED\_CHAR.

**BDTRSM** 

Bad Training Sample. The supplied training samples were unusable.

**INSPEC** 

Insufficient Specifications. Fewer than two input images were supplied.

**SEE ALSO** 

AVW\_ClassifyFromScattergram(), AVW\_Scattergram(), AVW\_Image

## **REFERENCES**

[1] A. Kramer and A. Sangiovanni-Vincentelli, "Efficient Parallel Learning Algorithms for Neural Networks", in Advanced in Neural Information Processing Systems 1, pp 40-48, Morgan-Kauffman, San Mateo, CA 1989

[2] D. F. Specht, "Probabilistic Neural Networks, Neural Networks, Vol 3, pp 109-118, 1990.

[3] M. Morrison and Y. Attikiouzel, "A Probabilistic Network Based Image Segmentation Network for Magnetic Resonance Images", Proc. Intl. Joint Conference on Neural Networks, Baltimore, MD, June 7-11, 1992, pp III-60 - III-65, IEEE Press, 1992

AVW\_ClassifyVolume - classifies voxels from multi-spectral data sets

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_ClassifyVolume(vols, numvols, train\_vol, autotype, maxdist, sigma,

kvalue, epochs, hiddenepochs,

out\_volume)

AVW\_Volume \*\*vols;

int numvols;

AVW\_Volume \*train\_vol;

int autotype;

double maxdist;

double sigma;

double kvalue;

int epochs;

int hiddenepochs;

AVW\_Volume \*out\_volume;

## **DESCRIPTION**

AVW\_ClassifyVolume() classifies voxels given multi-spectral data consisting of several input volumes under the supervision of *train\_volume* training samples in which some voxels are marked as belonging to various classes.

Several different algorithms can be used to classify unclassified voxels from the input mask volume.

\*\*Vols is a list of spatially correlated volumes, each of which represents one spectra of the multi-spectral data set. These input volumes must be of the same dimension and of data type AVW\_UNSIGNED\_CHAR. This input data is unchanged by the classification process

*Numvols* is the number of volumes in the input volume list *vols*.

*Train\_vol* is a set of training samples for the various automatic classification algorithms. It must be of the same dimensions as the volumes from the input volume list *vols*. Its data type must be *AVW\_UNSIGNED\_CHAR*. The values of voxels in *train\_vol* are taken to be known class numbers of voxels in the input volumes. Voxels with the value of 0 are taken as unknown and are targets for the classification process. Voxels with the value of 1 are taken as belonging to class number 1, voxels with value of 2 are taken belonging to class number 2, etc. *Train\_vol* must be prepared prior to invoking *AVW\_ClassifyVolume()*.

Autotype specificies the automatic classification algorithm used to classify the volume. Acceptable values are AVW\_GAUSSIAN\_CLUSTER, AVW\_NEURAL\_NETWORK, AVW\_NEAREST\_NEIGHBOR, AVW\_K\_NEAREST\_NEIGHBOR, and AVW\_PARZEN\_WINDOWS.

The AVW\_GAUSSIAN\_CLUSTER technique calculates means and standard deviations for each class along each feature, and then models the class' probabilty distribution as a Gaussian function with the specified parameters. An unknown voxel is then classified by calculating the probability that it belongs to each class and choosing the best result. A voxel is left unclassified if it lies farther than a certain number of standard deviations from all the class centers (controlled by the *maxdist* parameter).

The *AVW\_NEURAL\_NETWORK* classifier builds a standard 3-layer feed forward neural network, of the kind commonly trained by backpropagation, and trains it on the class samples with a more advanced technique known as conjugate gradient optimization [1].

The *AVW\_NEAREST\_NEIGHBOR* technique simply takes each unclassified voxel, looks for its closest neighbor in feature space among the class samples, and assigns it to that same class. If two samples from different classes are equally close, the voxel is left unclassified

AVW\_K\_NEAREST\_NEIGHBOR extends the previous method to the *kvalue* nearest neighbors among the class samples, giving each of these an equal vote. In both cases, voxels are left unclassified whose best match samples are farther than the distance given by the *max-dist* parameter.

The AVW\_PARZEN\_WINDOWS technique is similar to AVW\_GAUSSIAN\_CLUSTER but makes a more sophisticated estimate of each class' underlying probability distribution function from the samples. It uses these estimates to draw near-optimal decision boundaries, but is much slower than AVW\_GAUSSIAN\_CLUSTER classification. This latter technique is implemented in the matter described in [2].

In each of the classification types, a voxel is assigned to the most likely class (as estimated by the classifier), and this is done for each voxel independently. This can result in a "noisy" classification if the data is noisy or if classes actually overlap in feature space.

Maxdist specifies the maximum distance in feature space that an unknown voxel can be from a sample of a known class to be considered as a possible member of that class. When autotype is AVW\_GAUSSIAN\_CLUSTER it is in units of standard deviations. This parameter is meaningful and used only when autotype is AVW\_GAUSSIAN\_CLUSTER, AVW\_NEAREST\_NEIGHBOR, or AVW\_K\_NEAREST\_NEIGHBOR.

*Sigma* is only used for the *AVW\_PARZEN\_WINDOW* technique, and is ignored for all others. It specifies the standard deviation of the Gaussian window which is used to smooth the input samples to estimate the probability distribution. A default value of 5.0 is suggested.

*Kvalue* specifies the number of nearest neighbors in feature space to be considered when using *AVW\_K\_NEAREST\_NEIGHBOR* classification. This parameter is ignored for all other values of *autotype*.

*Epochs* specifies the maximum number of passes through the class samples while training the neural network. This parameter is used only when using *AVW\_NEURAL\_NETWORK*, it is ignored for all other values of *autotype*.

*Hiddenepochs* specifies the number of hidden units in the (single hidden layer) neural network. This parameter is used only when using *AVW\_NEURAL\_NETWORK*, it is ignored for all other values of *autotype*.

Out\_volume is the returned classified volume. Voxels which have been successfully classified are set to values of voxels from the training sample mask volume which they are most similar to. Voxels with a value of 0 were not classified by the function.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful AVW\_ClassifyVolume() returns an AVW\_Volume. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

## **ERRORS**

*AVW\_ClassifyVolume* will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. A memory allocation failed.

**ILLVOL** 

Illegal Volume. The volumes are not all the same dimension.

**ILLDT** 

Illegal Datatype. At least one of the volumes is not AVW\_UNSIGNED\_CHAR.

**BDTRSM** 

Bad Training Sample. The supplied training samples were unusable.

**INSPEC** 

Insufficient Specifications. Fewer than two input volumes were supplied.

**SEE ALSO** 

AVW\_ClassifyImage(), AVW\_ClassifyFromScattergram(), AVW\_Scattergram(), AVW\_Volume

#### REFERENCES

[1] A. Kramer and A. Sangiovanni-Vincentelli, "Efficient Parallel Learning Algorithms for Neural Networks", in Advanced in Neural Information Processing Systems 1, pp 40-48, Morgan-Kauffman, San Mateo, CA 1989

[2] D. F. Specht, "Probabilistic Neural Networks, Neural Networks, Vol 3, pp 109-118, 1990.

[3] M. Morrison and Y. Attikiouzel, "A Probabilistic Network Based Image Segmentation Network for Magnetic Resonance Images", Proc. Intl. Joint Conference on Neural Networks, Baltimore, MD, June 7-11, 1992, pp III-60 - III-65, IEEE Press, 1992

AVW\_ClassifyVolumeFromSampleFile - classifies voxels from multi-spectral data sets

## **SYNOPSIS**

"AVW.h" #include

AVW\_Image \*AVW\_ClassifyVolumeFromSampleFile(vols, numvols, SampleFile, autotype, maxdist, sigma, kvalue, epochs, hiddenepochs,

out vol)

AVW\_Volume \*\*vols;

int numvols;

char \*SampleFile;

int autotype;

double maxdist;

double sigma;

double kvalue;

int epochs;

int hiddenepochs;

AVW Image \*out vol;

## **DESCRIPTION**

AVW ClassifyVolumeFromSampleFile() classifies voxels given multi-spectral data consisting of several input volumes under the supervision of SampleFile which is a text file which contains a list of class numbers and corresponding multi-spectral values. Each training sample is a row in the file which consists of the class number and then tab separated values which correspond to the values for volume1, volume2, ...

Several different algorithms can be used to classify unclassified pixels from the input mask image.

\*\* Vols is a list of spatially correlated volumes, each of which represents one spectra of the multi-spectral data set. These input images must be of the same dimension. This input data is unchanged by the classification process.

*Numvols* is the number of volumess in the input image list *imgs*.

SampleFile is a set of training samples for the various automatic classification algorithms. This is a text file created by AVW\_MaskVolumeToSampleFile() or AVW\_MaskImageToSampleFile().

Autotype specificies the automatic classification algorithm used to classify the image. Acceptable values are AVW\_GAUSSIAN\_CLUSTER, AVW\_NEURAL\_NETWORK, AVW NEAREST NEIGHBOR, AVW K NEAREST NEIGHBOR, AVW\_PARZEN\_WINDOWS, AVW\_NEAREST\_MEAN, and AVW\_NEAREST\_MEDIAN which are defined in AVW.h.

The AVW GAUSSIAN CLUSTER technique calculates means and standard deviations for each class along each feature, and then models the class' probabilty distribution as a Gaussian function with the specified parameters. An unknown pixel is then classified by calculating the probability that it belongs to each class and choosing the best result. A pixel is left unclassified if it lies farther than a certain number of standard deviations from all the class centers (controlled by the *maxdist* parameter).

The AVW NEURAL NETWORK classifier builds a standard 3-layer feed forward neural network, of the kind commonly trained by backpropagation, and trains it on the class samples with a more advanced technique known as conjugate gradient optimization [1].

The AVW\_NEAREST\_NEIGHBOR technique simply takes each unclassified pixel, looks for its closest neighbor in feature space among the class samples, and assigns it to that same class. If two samples from different classes are equally close, the pixel is left unclassified

AVW\_K\_NEAREST\_NEIGHBOR extends the previous method to the *kvalue* nearest neighbors among the class samples, giving each of these an equal vote. In both cases, pixels are left unclassified whose best match samples are farther than the distance given by the *max-dist* parameter.

The AVW\_PARZEN\_WINDOWS technique is similar to AVW\_GAUSSIAN\_CLUSTER but makes a more sophisticated estimate of each class' underlying probability distribution function from the samples. It uses these estimates to draw near-optimal decision boundaries, but is much slower than AVW\_GAUSSIAN\_CLUSTER classification. This latter technique is implemented in the matter described in [2].

The AVW\_NEAREST\_MEAN technique calculates the mean vector for each training class. Each voxel to be classified is assigned to the class with the closest mean vector within the value specified by Maxdist.

The *AVW\_NEAREST\_MEDIAN* technique works in the same way as the *AVW\_NEAREST\_MEAN* except that the median vector for each class is used.

In each of the classification types, a pixel is assigned to the most likely class (as estimated by the classifier), and this is done for each pixel independently. This can result in a "noisy" classification if the data is noisy or if classes actually overlap in feature space.

Maxdist specifies the maximum distance in feature space that an unknown pixel can be from a sample of a known class to be considered as a possible member of that class. When autotype is AVW\_GAUSSIAN\_CLUSTERING it is in units of standard deviations. This parameter is meaningful and used only when autotype is AVW\_GAUSSIAN\_CLUSTERING, AVW\_NEAREST\_NEIGHBOR, AVW\_K\_NEAREST\_NEIGHBOR, AVW\_NEAREST\_MEDIAN, and AVW\_NEAREST\_MEAN.

*Sigma* is only used for the *AVW\_PARZEN\_WINDOW* technique, and is ignored for all others. It specifies the standard deviation of the Gaussian window which is used to smooth the input samples to estimate the probability distribution. A default value of 5.0 is suggested.

*Kvalue* specifies the number of nearest neighbors in feature space to be considered when using *AVW\_K\_NEAREST\_NEIGHBOR* classification. This parameter is ignored for all other values of *autotype*.

*Epochs* specifies the maximum number of passes through the class samples while training the neural network. This parameter is used only when using *AVW\_NEURAL\_NETWORK*, it is ignored for all other values of *autotype*.

*Hiddenepochs* specifies the number of hidden units in the (single hidden layer) neural network. This parameter is used only when using *AVW\_NEURAL\_NETWORK*, it is ignored for all other values of *autotype*.

Out\_image is the returned classified image. Pixels which have been successfully classified are set to values of pixels from the training sample mask image which they are most similar to. Pixels with a value of 0 were not classified by the function.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful AVW\_ClassifyImage() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ClassifyImage will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. A memory allocation failed.

**ILLIMG** 

Illegal Image. The images are not all the same dimension.

**BDTRSM** 

Bad Training Sample. The supplied Sample File was unusable.

**INSPEC** 

Insufficient Specifications. Fewer than two input images were supplied.

#### **SEE ALSO**

AVW\_ClassifyImageFromSampleFile(), AVW\_MaskVolumeToSampleFile(), AVW\_MaskImageToSampleFile(), AVW\_ClassifyVolume(), AVW\_ClassifyImage(), AVW\_Image

## **REFERENCES**

- [1] A. Kramer and A. Sangiovanni-Vincentelli, "Efficient Parallel Learning Algorithms for Neural Networks", in Advanced in Neural Information Processing Systems 1, pp 40-48, Morgan-Kauffman, San Mateo, CA 1989
- [2] D. F. Specht, "Probabilistic Neural Networks, Neural Networks, Vol 3, pp 109-118, 1990.
- [3] M. Morrison and Y. Attikiouzel, "A Probabilistic Network Based Image Segmentation Network for Magnetic Resonance Images", Proc. Intl. Joint Conference on Neural Networks, Baltimore, MD, June 7-11, 1992, pp III-60 III-65, IEEE Press, 1992

**NAME** AVW\_ClearHistogram – zeros out a histogram

**SYNOPSIS** #include "AVW\_Histogram.h"

int AVW\_ClearHistogram(histo)

AVW\_Histogram \*histo;

**DESCRIPTION** AVW\_ClearHistogram() assigns zeros to each bin of the AVW\_Histogram histo.

**RETURN VALUES** If successful *AVW\_ClearHistogram()* returns *AVW\_SUCCESS*. On failure it returns

AVW\_FAIL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding

to the cause of the failure.

**ERRORS** | *AVW\_ClearHistogram()* fails if the following is true:

**ILLHIS** 

Illegal Histogram. Nonvalid histogram was passed to this function.

**SEE ALSO** | AVW\_CreateHistogram(), AVW\_DestroyHistogram(), AVW\_FlattenImageHistogram(),

AVW\_FlattenVolumeHistogram(), AVW\_GetImageHistogram(), AVW\_GetVolumeHistogram(),

 $AVW\_MatchImageHistogram(),\ AVW\_MatchVolumeHistogram(),$ 

AVW\_NormalizeHistogram(), AVW\_PreserveImageHistogram(),

AVW\_PreserveVolumeHistogram(), AVW\_VerifyHistogram(), AVW\_Histogram

AVW\_ClipPointList2 - clips a point list at image bounds

**SYNOPSIS** 

#include "AVW.h"

AVW\_PointList2 \*AVW\_ClipPointList2(list, lowx, lowy, highx, highy, out\_list)

AVW\_PointList2 \*list;

int lowx, lowy;

int highx, highy;

AVW\_PointList2 \*out\_list;

#### **DESCRIPTION**

*AVW\_ClipPointList2()* clips the the x and y coordinates of the points in *list* so that all coodinates meet the following criteria:

 $lowx \le x \le highx$ 

lowy <= y <= highy

Out\_list

is provided as a method of reusing an existing

AVW\_PointList2.

If not reuseable

out\_list

will be reallocated. (See

Memory Usage

in the

AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_ClipPointList2()* returns an *AVW\_PointList2*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ClipPointList2() will fail if:

**BADMAL** 

Could not allocate enough memory for results.

**SEE ALSO** 

AVW\_CreatePointList2(), AVW\_DestroyPointList2(), AVW\_DrawPointList2(), AVW\_ShiftPointList2(), AVW\_TransformPoint2(), AVW\_PointList2

**NAME** AVW\_CloseImageFile – closes an image file

**SYNOPSIS** #include "AVW\_ImageFile.h"

int AVW\_CloseImageFile (imgfile)

AVW\_ImageFile \*imgfile;

**DESCRIPTION** | AVW\_CloseImageFile() closes an AVW\_ImageFile. All open files associated with the

AVW\_ImageFile are closed. All structures and memory buffers associated with the

AVW\_ImageFile are freed.

**RETURN VALUES** If successful AVW\_CloseImageFile() returns AVW\_SUCCESS. On failure AVW\_FAIL is

returned and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to

the cause of failure.

**ERRORS** | *AVW\_CloseImageFile()* will fail for the following reason:

**BDCLS** 

Bad Close.

SEE ALSO | AVW\_CreateImageFile(), AVW\_ExtendImageFile(), AVW\_OpenImageFile(),

AVW\_ReadImageFile(), AVW\_ReadVolume(), AVW\_SeekImageFile(), AVW\_WriteImageFile(),

AVW\_WriteVolume(), AVW\_ImageFile

NAME | AVW\_ClosestInPointList2 – finds the closest point in an AVW\_PointList2

**AVW 3.0** 

SYNOPSIS #include "AVW.h"

int AVW\_ClosestInPointList2(point2, plist)

AVW\_Point2 \*point2; AVW\_PointList2 \*plist;

**DESCRIPTION** AVW\_ClosestInPointList2() searches plist for the closest point to point2. When found the

index of that point is returned.

**RETURN VALUES** If successful, *AVW\_ClosestInPointList2()* returns the index of the closest point. On failure,

it returns -1 and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding

to the cause of the failure.

**ERRORS** | *AVW\_ClosestInPointList2()* will fail if one or more of the following are true:

**PTNFND** 

Pointlist didn't contain any points.

SEE ALSO | AVW\_ClosestInImage(), AVW\_Point2, AVW\_Point2List2

NAME | AVW\_ClosestPointInImage – finds the closest nonzero point in an image

SYNOPSIS #include "AVW.h"

int AVW\_ClosestPointInImage(image, point, value)

AVW\_Image \*image; AVW\_Point2 \*point;

double value

**DESCRIPTION** *AVW\_ClosestPointInImage()* resets the the coordinates of *point* to the closest pixel with an

intensity of value in image to point.

**RETURN VALUES** If successful, AVW\_ClosestPointInImage() returns AVW\_SUCCESS. On failure, it returns

AVW\_FAIL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding

to the cause of the failure.

**ERRORS** | *AVW\_ClosestPointInImage()* will fail if one or more of the following are true:

**ILLPAR** 

Point specified is outside of the image.

**ILLDT** 

Illegal datatype.

**EMPTYI** 

All pixels inthe image are zero.

**PTNFND** 

Closest point not found.

SEE ALSO | AVW\_ClosestInPointList2(), AVW\_Image, AVW\_Point2

```
NAME
                      AVW_Compute2DShapeStats - performs shape analysis
       SYNOPSIS
                      #include
                                  "AVW Measure.h"
                      int AVW_Compute2DShapeStats(mask_image, mask_value, stats)
                      AVW_Image *mask_image;
                      int mask_value:
                      AVW 2DShapeStats *stats;
   DESCRIPTION
                      AVW_Compute2DShapeStats() performs shape analysis on mask_image. All pixels of value
                      mask value are taken as belonging to the object to be analyzed. Mask image is an
                      AVW_Image of data type AVW_UNSIGNED_CHAR. The shape statistics are returned in
                      stats, which is an AVW_2DShapeStats structure, defined in AVW_Measure.h.
                      typedef struct
                       float Area,
                                                    /* pixel count of mask
                           Perimeter,
                                            /* distance around the shape */
                                                    /* in degrees
                           MERAngle
                                                    /* of minimum enclosing rectangle
                           MERArea,
                                                    /* aspect ratio of the
                           MERAspect,
                                                      minimum enclosing rectangle */
                           RFF,
                                                    /* rectangle fit factor
                                                                           */
                           Circularity;
                                                    /* ratio of region perimeter
                                                      squared to its area
                           AVW FPoint2 Centroid:
                                                   /* x & y coords of centroid */
                           AVW_FPoint2 MER1;
                           AVW FPoint2 MER2:
                           AVW_FPoint2 MER3;
                           AVW_FPoint2 MER4;
                       } AVW_2DShapeStats;
RETURN VALUES
                      If successful AVW_Compute2DShapeStats() returns AVW_SUCCESS. On failure it returns
                      AVW_FAIL and sets AVW_ErrorNumber and AVW_ErrorMessage to values corresponding
                      to the cause of the failure.
         ERRORS
                      AVW_Compute2DShapeStats() will fail for the following reasons:
                           ILLMSK
                              Illegal Mask.
                           ILLPAR
                              Illegal Parameter.
       SEE ALSO
                      AVW ComputeCircularity(), AVW ComputeImageCentroid(),
```

AVW\_ComputeImageFractalSig(), AVW\_ComputeImageIntensityStats(), AVW\_ComputeMER(), AVW\_ComputePerimeter(), AVW\_ComputeRFF(),

AVW\_2DShapeStats

**NAME** AVW\_ComputeCircularity – calculates the circularity of a 2D region

**SYNOPSIS** #include "AVW\_Measure.h"

double AVW\_ComputeCircularity(mask\_image, mask\_value)

AVW\_Image \*mask\_image;

int mask value:

**DESCRIPTION** AVW Compute

AVW\_ComputeCircularity() calculates the circularity of an two-dimensional region in an

image.

Mask\_image is an AVW\_Image whose voxels are of data type AVW\_UNSIGNED\_CHAR.

Mask\_value is the value of the pixels which define the region.

The circularity of a region is the ratio of the region's perimeter squared to its area. It takes on a minimum value of 4\*pi for a disk, and takes on higher values for more com-

plex shapes.

**RETURN VALUES** AVW\_ComputeCircularity() returns a double value equal to the region's perimeter squared

divided by its area.

**ERRORS** *AVW\_ComputeCircularity()* will fail for the following reasons:

**ILLIMG** 

Illegal Image.

ILLDT

Illegal Data Type.

**ILLPAR** 

Illegal Parameter.

**SEE ALSO** | AVW\_Compute2DShapeStats(), AVW\_ComputeImageCentroid(),

AVW ComputeImageFractalSig(), AVW ComputeImageIntensityStats().

AVW\_ComputeMER(), AVW\_ComputePerimeter(), AVW\_ComputeRFF(), AVW\_Image

AVW\_ComputeDividedTrace - computes a new trace between two traces

**SYNOPSIS** 

#include "AVW.h"

AVW\_PointList2 \*AVW\_ComputeDividedTrace(outside, inside, distance, middle) AVW\_PointList2 \*outside, \*inside, \*middle; double distance;

DESCRIPTION

AVW\_ComputeDividedTrace() creates a trace, which is stored in an AVW\_PointList2, between two other traces, *outside* and *inside*. The points of the computed trace are stored in *middle*.

The points of the computed trace are calculated by first determining the center of the inside trace. Rays are then cast in a full circle from this center point. The intersection of each ray with the *inside* trace and *outside* trace are computed, along with the distance between these two points. The new points of the divided trace are positioned on these rays a fractional *distance* from the inside trace. *Distance* should be between 0.0 and 1.0.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

Middle is provided as a method of reusing an existing AVW\_PointList2.

**RETURN VALUES** 

If successful *AVW\_ComputeDividedTrace()* returns an *AVW\_PointList2*. On failure it returns *AVW\_NULL* and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ComputeDividedTrace() will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate memory.

**SEE ALSO** 

AVW\_AddPoint2(), AVW\_CreatePointList2(), AVW\_DestroyPointList2(), AVW\_FillPointList2(), AVW\_PointList2, AVW\_Point2

AVW\_ComputeFullWidthHalfMax - calculates full width half max measurements

**SYNOPSIS** 

#include "AVW Measure.h"

int AVW\_ComputeFullWidthHalfMax(list, base, search, voxel\_width,

voxel\_height, fwhm)

AVW\_PointValueList \*list;

double base; int search;

double voxel\_width, voxel\_height; AVW\_FullWidthHalfMax \*fwhm;

**DESCRIPTION** 

AVW\_ComputeFullWidthHalfMax() calculates full width half max measurements from the line profile provided in *list. Base* specifies the base value used in the calculations. Search specifies whether the half maximums are searched for from the ends of the line profile, AVW\_SEARCHFROMOUTSIDE, or from where the maximum value of the line profile occurs, AVW\_SEARCHFROMMAXIMUM. Voxel\_width and voxel\_height are the calibrated sizes of the voxel from which the line profile was computed. Fwhm is the AVW\_FullWidthHalfMax structure in which all of measurements are stored.

**RETURN VALUES** 

If successful *AVW\_ComputeFullWidthHalfMax()* returns an *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ComputeFullWidthHalfMax() will fail if the following is true:

**HMXERR** 

Valid half maximum value could not be computed for the line profile.

**SEE ALSO** 

 $AVW\_ComputeLineProfile(),\ AVW\_ComputeThickLineProfile(),\ AVW\_FullWidthHalfMax(),\ AVW\_PointValueList,\ AVW\_Image$ 

AVW\_ComputeImageCentroid - calculates the centroid of a 2D object

**SYNOPSIS** 

#include "AVW Measure.h"

int AVW\_ComputeImageCentroid(mask\_image, mask\_value, centroid, count)

AVW\_Image \*mask\_image;

int mask\_value,

AVW\_FPoint2 \*centroid;

int \*count;

### **DESCRIPTION**

AVW\_ComputeImageCentroid() computes the centroid of a 2D object. All pixels of value mask\_value in mask\_image are taken as belonging to the object to be analyzed. Mask\_image is an AVW\_Image where the pixels are of data type AVW\_UNSIGNED\_CHAR.

*Centroid* is set to the computed object center which is the average of the x, y, and z coordinates of the pixels equal to *mask\_value*.

Count is set to the number of pixels in the object.

## **RETURN VALUES**

If successful *AVW\_ComputeImageCentroid()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **SEE ALSO**

AVW\_Compute2DShapeStats(), AVW\_ComputeCircularity(),

AVW\_ComputeImageFractalSig(), AVW\_ComputeImageIntensityStats(),

 $AVW\_Compute MER(),\ AVW\_Compute Perimeter(),\ AVW\_Compute RFF(),\ AVW\_FPoint 2,$ 

AVW\_Image

AVW\_ComputeImageFractalSig - calculates fractal signature

**SYNOPSIS** 

#include "AVW\_Measure.h"

int AVW\_ComputeImageFractalSig(in\_image, mask\_image, mask\_val, scalemax, scalemin, slope, coeff, reg\_pts,

bfloat, areas)

AVW\_Image \*in\_image;

AVW\_Image \*mask\_image;

int mask\_value:

int scalemax;

int scalemin;

double \*slope:

double \*coeff;

float reg\_pts[30], bfloat[30], areas[30];

**DESCRIPTION** 

AVW\_ComputeImageFractalSig() computes the fractal signature of in\_image in the region defined by mask\_image. The fractal signature is calculated using pixels in mask\_image equal to mask\_val over the range of scales specified by scalemin and scalemax. The return value *slope* is the best fit approximation of the fractal dimension, and the value of *coef* is the correlation coefficient of the fit.

*Reg\_pts* is the set of regression points over the range of scales.

Areas is the log(area) measurements over range of scales.

Bfloat is the area measurements over

**RETURN VALUES** 

AVW\_ComputeImageFractalSig() returns AVW\_SUCCESS or AVW\_FAIL.

**SEE ALSO** 

AVW\_ComputeImageIntensityStats(), AVW\_Compute2DShapeStats(), AVW\_Image

AVW\_ComputeImageIntensityStats - calculates image density statistics

### **SYNOPSIS**

#include "AVW Measure.h"

int AVW\_ComputeImageIntensityStats(in\_image, mask\_image, mask\_val, sample\_max, sample\_min, stats)

AVW\_Image \*in\_image;

AVW\_Image \*mask\_image;

int mask\_val;

double sample\_max, sample\_min;

AVW\_IntensityStats \*stats;

# **DESCRIPTION**

AVW\_ComputeImageIntensityStats() computes intensity statistics on in\_image.

The measured statistics include Mean, Standard Deviation, Variance, Sum, Sum of Squares, Number of Voxels, Area, Volume, Highest Intensity, Highest Intensity Location, Lowest Intensity, Lowest Intensity Location, Number Below Range, Number In Range, Number Above Range, and Brightness Area Product.

The <code>mask\_image</code> allows the user to only sample a masked part of an image. If <code>mask\_image</code> is not equal to <code>NULL</code> only pixel locations equal to the <code>mask\_val</code> will be sampled from the image. If the mask is <code>NULL</code> the entire image is sampled. If a mask is specified it must have the same dimensions as the input image and have <code>AVW\_UNSIGNED\_CHAR</code> data type.

*Sample\_max* and *sample\_min* parameters specify a grey scale subrange of the masked region in which a separate set of statistics will be computed (See the *Range* statistics below).

The intensity statistics are returned in *stats*, which is an *AVW\_IntensityStats* structure defined in *AVW\_Measure.h*.

```
typedef struct
```

{

double Mean;

double StandardDeviation;

double Variance:

double Sum;

double SumOfSquares;

unsigned long NumberOfVoxels;

double Area;

double Volume:

double HighestIntensity;

AVW\_Point3 HighestPoint;

double LowestIntensity;

AVW\_Point3 LowestPoint;

double RangeMaximum;

double RangeMinimum;

double MeanInRange;

double StandardDeviationInRange;

double VarianceInRange;

double SumInRange;

double SumOfSquaresInRange;

unsigned long NumberBelowRange;

unsigned long NumberInRange;

unsigned long NumberAboveRange;

double AreaInRange;
double VolumeInRange;
double BrightnessAreaProduct;
} AVW\_IntensityStats;

# **RETURN VALUES**

If successful *AVW\_ComputeImageIntensityStats()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_ComputeImageIntensityStats() will fail if one of the following is true:

**ILLIMG** 

Specified image was not valid.

**ILLMSK** 

Specified mask was not valid.

# **SEE ALSO**

AVW\_ComputeVolumeIntensityStats() AVW\_ComputeImageFractalSig(), AVW\_ComputeLineProfile(), AVW\_Compute2DShapeStats(), AVW\_ResetIntensityStats(), AVW\_IntensityStats, AVW\_Image

AVW\_ComputeLineProfile - calculates the intensities along a line or trace

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW\_Measure.h"

AVW\_PointValueList \*AVW\_ComputeLineProfile(image, trace, length)

AVW\_Image \*image; AVW\_PointList2 \*trace;

double \*length;

**DESCRIPTION** 

AVW\_ComputeLineProfile() finds the intensities in *image* corresponding to the coordinates specified in *trace*. The *trace* is interpolated in this function thus allowing the user to pass in endpoints of a line. The *length* of the trace is calculated and returned. The length is calibrated to the size of the voxel in *image*.

**RETURN VALUES** 

If successful *AVW\_ComputeLineProfile()* returns an *AVW\_PointValueList* containing the intensities and image coordinates of the profile. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ComputeLineProfile() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**ILLIMG** 

Image provided was not valid.

**SEE ALSO** 

AVW\_ComputeThickLineProfile(), AVW\_ComputeFullWidthHalfMax(), AVW\_ComputeImageIntensityStats(), AVW\_ComputeVolumeIntensityStats(), AVW\_PointList2, AVW\_PointValueList, AVW\_Image

AVW\_ComputeMEB - calculates the minimum enclosing brick of an object

### **SYNOPSIS**

#include "AVW\_Measure.h"

int AVW\_ComputeMEB(mask\_volume, mask\_value, resoultion, volume, angle, boxext) AVW\_Volume \*mask\_volume;

int mask value:

double resolution:

double \*volume:

double angle[3];

double boxext[3];

# **DESCRIPTION**

AVW\_ComputeMEB() calculates the minimum enclosing brick for an object defined as all voxels in mask\_vol of value mask\_value, where mask\_volume is of data type AVW\_UNSIGNED\_CHAR.

*Resolution* specifies step size in degrees of rotation to search for the minimum enclosing brick.

*Volume* is used to return the volume (number of voxels) contained by the minimum enclosing brick.

Angle[0], angle[1], and angle[2] are set to the degrees of rotation on the x, y, and z axes respectively of the minimum enclosing brick.

Boxext[0], boxext[1], and boxext[2] are set to the x, y, and z size of the minimum enclosing brick.

### **RETURN VALUES**

If successful *AVW\_ComputeMEB()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

### **ERRORS**

AVW\_ComputeMEB() will fail for the following reasons:

**ILLMSK** 

Illegal Mask.

**ILLPAR** 

Illegal Parameter.

## **SEE ALSO**

 $AVW\_ComputeCircularity(),\ AVW\_ComputeImageCentroid(),\ AVW\_ComputeMER(),\ AVW\_ComputePerimeter(),\ AVW\_ComputeRFF(),\ AVW\_ComputeVolume(),\ AVW\_ComputeVolumeCentroid(),\ AVW\_GetMaskBoundary(),\ AVW\_Volume$ 

AVW\_ComputeMER - calculates the minimum enclosing rectangle of an area

**SYNOPSIS** 

#include "AVW Measure.h"

int AVW\_ComputeMER(boundary, resolution, area, angle, aspect, merpts)

AVW\_PointList2 \*boundary;

double resolution;

double \*area:

double \*angle;

double \*aspect;

AVW\_FPointList2 \*merpts;

# **DESCRIPTION**

*AVW\_ComputeMER()* computes information about the minimum enclosing rectangle for the boundary of an arbitrary two dimensional region expressed as an *AVW\_PointList2*.

*Resolution* is the number of degrees per step to increment in finding the minimum enclosing rectangle.

Area is the pixel count of the minimum enclosing rectangle.

*Angle* is the rotational angle of the long axis of the minimum enclosing rectangle.

Aspect is the aspect ratio of the minimum enclosing rectangle.

*Merpts* is an *AVW\_FPointList2* containing the coordinates of the four corners of the minimum enclosing rectangle.

### **RETURN VALUES**

If successful *AVW\_ComputeMER()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

### **ERRORS**

AVW\_ComputeMER() will fail for the following reasons:

**ILLPAR** 

Illegal Parameter.

**SEE ALSO** 

AVW\_ComputeCircularity(), AVW\_ComputeImageCentroid(), AVW\_ComputeMEB(), AVW\_ComputePerimeter(), AVW\_ComputeRFF(), AVW\_ComputeVolume(), AVW\_ComputeVolumeCentroid(), AVW\_GetMaskBoundary(), AVW\_PointList2

AVW\_ComputeObjectsStats - returns statistics about a connected object.

**SYNOPSIS** 

#include "AVW.h"

#include "AVW\_ObjectMap.h"

int AVW\_ComputeObjectStats(in\_volume, om, seed, min, max, bound\_box, centroid, count)

AVW\_Volume \*in\_volume;

AVW\_ObjetcMap \*om;

AVW\_Point3 \*seed;

double min, max;

AVW\_Rect3 \*bound\_box;

AVW\_Point3 \*centroid;

int \*count;

# **DESCRIPTION**

AVW\_ComputeObjectsStats() returns bounding box, centroid, and volume statistics for a connected object.

*In\_volume* specifies the input *AVW\_Volume* which contains the region to be deleted or extracted.

*Object\_map* may be specified to constrain the connect to objects which have the Display component enabled. If *NULL* is specified only the threshold limits and the *connectivity* will constrain the 3D region grow.

*Seed* is a pointer to an *AVW\_Point3* structure. This structure contains the starting point for the 3D region grow.

*Min* and *max* specify the threshold limits used to constrain the 6 neighbor region growing process.

*Bound\_box* is a pointer to an *AVW\_Rect3* structure. This structure is used to return the coordinates of the minimum bounding box required to contain the object.

*centroid* is a pointer to an *AVW\_Point3* structure. This structure is used to return the coordinate of the centroid of the object. The centroid is calculated by averaging each coordinate in the 3D region grow.

### **RETURN VALUES**

If successful *AVW\_ComputeObjectsStats()* returns *AVW\_TRUE*. On failure it returns *AVW\_FALSE* and sets the *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

### **ERRORS**

AVW\_ComputeObjectsStats() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**ILLPAR** 

Illegal parameter(s).

## **SEE ALSO**

 $AVW\_ConnectAnd Nelete Volume() \ AVW\_ConnectAnd Keep Volume(), \\ AVW\_Define Connected(), \ AVW\_Find Volume Conponents(), \ AVW\_Object Map, \ AVW\_Point3, \\ AVW\_Rect3, \ AVW\_Volume$ 

AVW\_ComputePerimeter - calculates the perimeter of a region

**SYNOPSIS** 

#include "AVW\_Measure.h"

double AVW\_ComputePerimeter(boundary)
AVW\_PointList2 \*boundary;

**DESCRIPTION** 

AVW\_ComputePerimeter() calculates the length in voxels of a boundary stored in an AVW PointList2.

The algorithm measures the distance around a piecewise linear closed curve constructed between the centers of the outermost pixels of a region. The path always consists of N pixel-dimension steps plus M square-root-of-two pixel dimension steps. The perimeter value will change with orientation and will continue to increase in error for larger analytical regions because all of the "wandering" of the digital line about the "true" curve is known to be error.

**RETURN VALUES** 

If successful *AVW\_ComputePerimeter()* returns a floating point value equal to the perimeter of the *boundary*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

 $AVW\_GetMaskBoundary(),\ AVW\_ComputeImageCentroid(), \\ AVW\_ComputeVolumeCentroid(),\ AVW\_ComputeRFF(),\ AVW\_ComputeCircularity(), \\ AVW\_ComputeVolume(),\ AVW\_ComputeMEB(),\ AVW\_ComputeMER().\ AVW\_PointList2$ 

AVW\_ComputeRFF - calculates the rectangular fit factor of a 2D region

**SYNOPSIS** 

#include "AVW\_Measure.h"

double AVW\_ComputeRFF(mask\_image, mask\_value)

AVW\_Image \*mask\_image;

int mask\_value;

**DESCRIPTION** 

AVW\_ComputeRFF() calculates the rectangular fit of a two-dimensional region in an image. Mask\_image is an AVW\_Image whose voxels are of data type

AVW\_UNSIGNED\_CHAR. Mask\_value is the value of the pixels which define the region. The rectangular fit value of a region is the ratio of the region's area to the area of its

minimum enclosing rectangle.

**RETURN VALUES** 

AVW\_ComputeRFF() returns a double value equal to the region's area divided by the area of its minimum enclosing rectangle.

**ERRORS** 

*AVW\_ComputeRFF()* will fail for the following reasons:

**ILLIMG** 

Illegal Image.

**ILLDT** 

Illegal Data Type.

**ILLPAR** 

Illegal Parameter.

**SEE ALSO** 

AVW\_ComputeCircularity(), AVW\_ComputeImageCentroid(), AVW\_ComputeMEB(), AVW\_ComputeMER(), AVW\_Image

AVW\_ComputeThickLineProfile - calculates the intensities along a thick line

**SYNOPSIS** 

#include "AVW Measure.h"

AVW\_PointValueList \*AVW\_ComputeThickLineProfile(image, line, thickness, length)

AVW\_Image \*image; AVW\_Line2 \*line;

int thickness;
double \*length;

**DESCRIPTION** 

AVW\_ComputeThickLineProfile() computes the intensities of a thick line in *image* corresponding to the coordinates specified in *line*. The *line* is interpolated in this function. Perpendicular pixels above and below the line within one half of the *thickness* of the line are averaged into the profile values. The *length* of the line is calculated and returned. The length is calibrated to the size of the voxel in *image*.

**RETURN VALUES** 

If successful *AVW\_ComputeThickLineProfile()* returns an *AVW\_PointValueList* containing the averaged intensities and image coordinates of the profile. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_ComputeThickLineProfile()* will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**ILLIMG** 

Image provided was not valid.

**SEE ALSO** 

AVW\_ComputeLineProfile(), AVW\_ComputeFullWidthHalfMax(), AVW\_ComputeImageIntensityStats(), AVW\_ComputeVolumeIntensityStats(),

AVW\_PointList2, AVW\_PointValueList, AVW\_Image

**NAME** AVW\_ComputeVolume – calculates the volume of an object

SYNOPSIS #include "AVW\_Measure.h"

int AVW\_ComputeVolume(mask\_volume, mask\_value)

AVW\_Volume \*mask\_volume;

int mask\_value;

**DESCRIPTION** | *AVW\_ComputeVolume()* calculates the volume of a mask in a volume.

Mask\_volume is an AVW\_Volume of data type AVW\_UNSIGNED\_CHAR.

Mask\_value is the value of the voxels which define the object. The volume is an integer

count of the number of voxels in the object.

**RETURN VALUES** | *AVW\_ComputeVolume()* returns an integer value equal to the volume of the object.

SEE ALSO AVW\_ComputeImageCentroid(), AVW\_ComputeImageIntensityStats(), AVW\_ComputeMEB(), AVW\_ComputeVolumeCentroid(), AVW\_ComputeVolumeIntensityStats(), AVW\_Volume

AVW\_ComputeVolumeCentroid - calculates the centroid of a 3D object

**SYNOPSIS** 

#include "AVW Measure.h"

int AVW\_ComputeVolumeCentroid(mask\_volume, mask\_value, centroid, count)

AVW\_Volume \*mask\_volume;

int mask\_value,

AVW\_FPoint3 \*centroid;

int \*count;

**DESCRIPTION** 

*AVW\_ComputeVolumeCentroid()* computes the centroid of a 3D object. All voxels of value *mask\_value* in *mask\_volume* are taken as belonging to the object to be analyzed.

 ${\it Mask\_volume}$  is an  ${\it AVW\_Volume}$  where the voxels are of data type

AVW\_UNSIGNED\_CHAR.

Centroid is set to the computed object center which is the average of the x, y, and z coordi-

nates of voxels equal to mask\_value.

*Count* is set to the number of pixels or voxels in the object.

**RETURN VALUES** 

If successful AVW\_ComputeVolumeCentroid() returns AVW\_SUCCESS. On failure it

returns  $AVW\_FAIL$  and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values

corresponding to the cause of the failure.

**SEE ALSO** | AVW\_ComputeImageCentroid(), AVW\_ComputeCircularity(), AVW\_ComputeMEB(),

AVW\_ComputeMEB(), AVW\_ComputeRFF(), AVW\_ComputeVolume(), AVW\_FPoint3,

AVW\_Volume

AVW\_ComputeVolumeIntensityStats - calculates volume density statistics

### **SYNOPSIS**

#include "AVW Measure.h"

int AVW\_ComputeVolumeIntensityStats(in\_vol, mask\_vol, mask\_val, sample\_max, sample\_min, stats)

AVW\_Volume \*in\_vol;

AVW Volume \*mask vol;

int mask\_val;

double sample\_max, sample\_min;

AVW\_IntensityStats \*stats;

# **DESCRIPTION**

AVW\_ComputeVolumeIntensityStats() computes intensity statistics on in\_vol.

The measured statistics include Mean, Standard Deviation, Variance, Sum, Sum of Squares, Number of Voxels, Area, Volume, Highest Intensity, Highest Intensity Location, Lowest Intensity, Lowest Intensity Location, Number Below Range, Number In Range, Number Above Range, and Brightness Area Product.

The <code>mask\_vol</code> allows the user to only sample a masked part of a volume. If <code>mask\_vol</code> is not equal to <code>NULL</code> only voxel locations equal to the <code>mask\_val</code> will be sampled from the volume. If the mask is <code>NULL</code> the entire volume is sampled. If a mask is specified it must have the same dimensions as the input volume and have <code>AVW\_UNSIGNED\_CHAR</code> data type.

*Sample\_max* and *sample\_min* parameters specify a grey scale subrange of the masked region in which a separate set of statistics will be computed (See the *Range* statistics below).

The intensity statistics are returned in stats, which is an AVW\_IntensityStats structure.

```
typedef struct
```

{

double Mean;

double StandardDeviation;

double Variance:

double Sum;

double SumOfSquares;

unsigned long NumberOfVoxels;

double Area;

double Volume:

double HighestIntensity;

AVW\_Point3 HighestPoint;

double LowestIntensity;

AVW\_Point3 LowestPoint;

double RangeMaximum;

double RangeMinimum;

double MeanInRange;

double StandardDeviationInRange;

double VarianceInRange;

double SumInRange;

double SumOfSquaresInRange;

unsigned long NumberBelowRange;

unsigned long NumberInRange;

unsigned long NumberAboveRange;

double AreaInRange;
double VolumeInRange;
double BrightnessAreaProduct;
} AVW\_IntensityStats;

# **RETURN VALUES**

If successful *AVW\_ComputeVolumeIntensityStats()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

### **ERRORS**

AVW\_ComputeVolumeIntensityStats() will fail if one of the following is true:

**ILLVOL** 

Specified volume was not valid.

**ILLMSK** 

Specified mask was not valid.

### **SEE ALSO**

 $AVW\_ComputeImageIntensityStats(),\ AVW\_Compute2DShapeStats(),\\ AVW\_ComputeLineProfile(),\ AVW\_ComputeMEB(),\ AVW\_ComputeVolume(),\\ AVW\_ComputeVolumeCentroid(),\ AVW\_ResetIntenstyStats(),\ AVW\_SumIntensityStats(),\\ AVW\_IntensityStats,\ AVW\_Volume$ 

AVW\_ConditionalDilateGreyVolume - conditionally dilates a volume

### **SYNOPSIS**

#include "AVW.h"

AVW\_Volume \*AVW\_ConditionalDilateGreyVolume(in\_volume, cond\_volume, thresh\_max, thresh\_min, element, out\_volume)

AVW Volume \*in volume;

AVW\_Volume \*cond\_volume;

double thresh max, thresh min;

AVW\_Volume \*element;

AVW\_Volume \*out\_volume;

# **DESCRIPTION**

AVW\_ConditionalDilateGreyVolume() performs binary morphological dilation on in\_volume using element as the structuring element and cond\_volume as a conditional volume. Cond\_volume may be of any data type and thresh\_max and thresh\_min are used to determine which voxels form the conditional volume. This function performs conditional dilation without requiring the existence of a thresholded conditional volume.

In\_volume does not have to be a binary valued but all nonzero voxels are treated as ones. In\_volume, out\_volume, and element must be of the data type AVW\_UNSIGNED\_CHAR. AVW\_ConditionalDilateGreyVolume() will allocate temporary storage space for results if in\_volume and out\_volume are the same.

The conditional dilation can be thought of as an enlargement of the binary objects contained in the input data limited by the *cond\_volume*. In simplest terms the conditional dilation process takes place by translating the structuring element so that its centerpoint lies on every point of the input data. At each point, if a nonzero voxel in the structuring element corresponds to a nonzero voxel in the input data and the corresponding point in the conditional data is nonzero, the point in the output data is set to one. Otherwise the voxel is unchanged. The output data will only contain ones and zeros.

AVW\_CreateStructuringVolume() or AVW\_CreateVolume(), AVW\_SetVolume(), and AVW\_PutVoxel() may be used to create a structuring element. The structuring element is flipped on the X, Y, and Z axes prior to dilation within the routine.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_ConditionalDilateGreyVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_ConditionalDilateGreyVolume() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

**ILLDT** 

Data type is not defined or supported.

**ILLVOL** 

An illegal volume was passed to the function.

**SEE ALSO** 

 $AVW\_Conditional Dilate Image(), AVW\_Conditional Dilate Volume Image(), \\ AVW\_Create Structuring Volume(), AVW\_Create Volume(), AVW\_Erode Volume(), \\ AVW\_Dilate Volume(), AVW\_Morph Open Volume(), AVW\_Morph Close Volume(), \\ AVW\_Morph Max Volume(), AVW\_Morph Min Volume(), AVW\_Put Voxel(), \\ AVW\_Set Volume(), AVW\_ULtimate Erosion Volume(), AVW\_Volume$ 

AVW\_ConditionalDilateImage - conditionally dilates an image

### **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_ConditionalDilateImage(in\_image, cond\_image, element, out\_image)

AVW\_Image \*in\_image;

AVW\_Image \*cond\_Image;

AVW\_Image \*element;

AVW\_Image \*out\_image;

## **DESCRIPTION**

AVW\_ConditionalDilateImage() performs binary morphological dilation on in\_image using element as the structuring element and cond\_image as a conditional image.

In\_image does not have to be a binary valued but all nonzero pixels are treated as ones. In\_image, cond\_image, out\_image, and element must be of the data type AVW\_UNSIGNED\_CHAR. AVW\_ConditionalDilateImage() will allocate temporary storage space for the result if in\_image and out\_image are the same.

The conditional dilation can be thought of as an enlargement of the binary objects contained in the input data limited by the *cond\_image*. In simplest terms the conditional dilation process takes place by translating the structuring element so that its centerpoint lies on every point of the input data. At each point, if a nonzero pixel in the structuring element corresponds to a nonzero pixel in the input data and the corresponding point in the conditional data is nonzero, the point in the output data is set to one. Otherwise the pixel is unchanged. The output data will only contain ones and zeros.

AVW\_CreateStructuringImage() or AVW\_CreateImage(), AVW\_SetImage(), and AVW\_PutPixel() may be used to create a structuring element. The structuring element is flipped on the X and Y axes prior to dilation within the routine.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

### **RETURN VALUES**

If successful AVW\_ConditionalDilateImage() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_ConditionalDilateImage() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

ILLDT

Data type is not defined or supported.

**ILLIMG** 

An illegal image was passed to the function.

## **SEE ALSO**

AVW\_ConditionalDilateVolume(), AVW\_CreateStructuringImage(), AVW\_CreateImage(), AVW\_DilateImage(), AVW\_ErodeImage(), AVW\_MorphCloseImage(), AVW\_MorphMorphMorphMinImage(), AVW\_MorphMinImage(), AVW\_SetImage(), AVW\_PutPixel(), AVW\_UltimateErosionImage(), AVW\_Image

AVW\_ConditionalDilateVolume - conditionally dilates a volume

### **SYNOPSIS**

#include "AVW.h"

AVW\_Volume \*AVW\_ConditionalDilateVolume(in\_volume, cond\_volume, element, out\_volume)

AVW Volume \*in volume;

AVW Volume \*cond volume;

AVW Volume \*element:

AVW\_Volume \*out\_volume;

## **DESCRIPTION**

AVW\_ConditionalDilateVolume() performs binary morphological dilation on in\_volume using element as the structuring element and cond\_volume as a conditional volume.

In\_volume does not have to be a binary valued but all nonzero voxels are treated as ones.
In\_volume, cond\_volume, out\_volume, and element must be of the data type
AVW\_UNSIGNED\_CHAR. AVW\_ConditionalDilateVolume() will allocate temporary
storage space for results if in\_volume and out\_volume are the same.

The conditional dilation can be thought of as an enlargement of the binary objects contained in the input data limited by the *cond\_volume*. In simplest terms the conditional dilation process takes place by translating the structuring element so that its centerpoint lies on every point of the input data. At each point, if a nonzero voxel in the structuring element corresponds to a nonzero voxel in the input data and the corresponding point in the conditional data is nonzero, the point in the output data is set to one. Otherwise the voxel is unchanged. The output data will only contain ones and zeros.

AVW\_CreateStructuringVolume() or AVW\_CreateVolume(), AVW\_SetVolume(), and AVW\_PutVoxel() may be used to create a structuring element. The structuring element is flipped on the X, Y, and Z axes prior to dilation within the routine.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

### **RETURN VALUES**

If successful *AVW\_ConditionalDilateVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_ConditionalDilateVolume() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

ILLDT

Data type is not defined or supported.

**ILLVOL** 

An illegal volume was passed to the function.

## **SEE ALSO**

 $AVW\_Conditional DilateImage(), AVW\_CreateStructuringVolume(), AVW\_CreateVolume(), AVW\_ErodeVolume(), AVW\_DilateVolume(), AVW\_MorphOpenVolume(), AVW\_MorphCloseVolume(), AVW\_MorphMaxVolume(), AVW\_MorphMinVolume(), AVW\_PutVoxel(), AVW\_SetVolume(), AVW\_ULtimateErosionVolume(), AVW\_Volume(), AVW\_Vo$ 

AVW\_ConnectAndDeleteImage - deletes 2D regions based on connectivity

## **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_ConnectAndDeleteImage(in\_image, seeds, connectivity, min, max, deleted\_value, count, out\_image)

AVW\_Image \*in\_image;

AVW\_PointList2 \*seeds;

int connectivity;

double min, max, deleted\_value;

int \*count;

AVW\_Image \*out\_image;

# **DESCRIPTION**

AVW\_ConnectAndDeleteImage() is used to set a connected region from an AVW\_Image to a specified value.

In *AVW\_ConnectAndDeleteImage()* threshold limits, *max* and *min*, are used to constrain the 4 or 8 neighbor region growing process which is started at every seed point in the *seeds* structure.

*Connectivity* may be either *AVW\_4\_CONNECTED* or *AVW\_8\_CONNECTED* and specifies the neighbors to be used to determine the connected components.

*In\_image* specifies the input *AVW\_Image* which contains the region to be deleted or extracted.

*Seeds* is a pointer to an *AVW\_PointList2* structure. This structure must contain at least one point which will be used as the starting point(s) for the region growing process.

Deleted\_value specifies the value to which each deleted pixel is set.

*Count* contains the number of pixels deleted if the function returns successfully. If the function fails *count* will contain the number at the time of failure.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

### **RETURN VALUES**

If successful AVW\_ConnectAndDeleteImage() returns an AVW\_Image. On failure it returns NULL and sets the AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

### **ERRORS**

AVW\_ConnectAndDeleteImage() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**ILLPAR** 

Illegal parameter(s).

## **SEE ALSO**

 $AVW\_ConnectAnd DeleteVolume()\ AVW\_ConnectAnd Keep Image(), \\ AVW\_Find ImageComponents(),\ AVW\_Find ImageEdges(),\ AVW\_Image,\ AVW\_PointList2$ 

AVW\_ConnectAndDeleteVolume - deletes 3D regions based on connectivity

**SYNOPSIS** 

#include "AVW.h"

#include "AVW\_ObjectMap.h"

AVW\_Volume \*AVW\_ConnectAndDeleteVolume(in\_volume, object\_map, seeds, connectivity, min, max, deleted\_value, count, out\_volume)

AVW\_Volume \*in\_volume;

AVW\_ObjectMap \*object\_map;

AVW\_PointList3 \*seeds;

int connectivity;

double min, max, deleted\_value;

int \*count;

AVW\_Volume \*out\_volume;

### **DESCRIPTION**

AVW\_ConnectAndDeleteVolume() is used to set a connected region from an AVW\_Volume to a specified value.

In  $AVW\_ConnectAndDeleteVolume()$  the  $AVW\_ObjectMap$ , if specified, further constrains the connect.

*In\_volume* specifies the input *AVW\_Volume* which contains the region to be deleted or extracted.

*Object\_map* may be specified to constrain to connect to objects which have the Display component enabled. If *NULL* is specified only the threshold limits and the *connectivity* will constrain the 3D region grow.

*Seeds* is a pointer to an *AVW\_PointList3* structure. This structure must contain at least one point which will be used as the starting point(s) for the 3D region grow.

Connectivity may be either  $AVW\_6\_CONNECTED$  or  $AVW\_26\_CONNECTED$  and specifies the neighbors to be used to determine the connected components.

*Min* and *max* specify the threshold limits used to constrain the 6 or 26 neighbor region growing process.

Deleted\_value specifies the value that each deleted is changed to.

*Count* contains the number of voxels deleted if the function returns successfully. If the function fails count will contain the number at the time of failure.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful AVW\_ConnectAndDeleteVolume() returns an AVW\_Volume. On failure it returns NULL and sets the AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_ConnectAndDeleteVolume() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

ILLPAR

Illegal parameter(s).

**SEE ALSO** 

 $AVW\_ConnectAndDeleteImage()\ AVW\_ConnectAndKeepVolume(),\ AVW\_DefineConnected(),\ AVW\_FindVolumeConponents(),\ AVW\_FindVolumeEdges(),\ AVW\_ObjectMap,\ AVW\_PointList3,\ AVW\_Volume$ 

AVW\_ConnectAndKeepImage - extracts 2D regions based on connectivity

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_ConnectAndKeepImage(in\_image, seeds, connectivity, min, max, deleted\_value, count, out\_image)

AVW\_Image \*in\_image;

AVW\_PointList2 \*seeds;

int connectivity;

double min, max, deleted\_value;

int \*count;

AVW\_Image \*out\_image;

## **DESCRIPTION**

AVW\_ConnectAndKeepImage() is used to extract a connected region from an AVW\_Image. The non-connected pixels are set to a specified value. A count of connected pixels is returned and can be used for area calculations.

*In\_image* specifies the input *AVW\_Image* which contains the region to be extracted.

*Seeds* is a pointer to an *AVW\_PointList2* structure. This structure must contain at least one point which will be used as the starting point(s) for the region growing process.

*Connectivity* may be either *AVW\_4\_CONNECTED* or *AVW\_8\_CONNECTED* and specifies the neighbors to be used to determine the connected components.

*Min* and *max* specify the threshold limits used to constrain the region growing process. Voxels outside the threshold range are left unchanged.

*Deleted\_value* specifies the value to which each non-extracted pixel is set.

*Count* contains the number of pixels extracted if the function returns successfully. If the function fails, count will contain the number at the time of failure.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful AVW\_ConnectAndKeepImage() returns an AVW\_Image. On failure it returns NULL and sets the AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

### **ERRORS**

AVW\_ConnectAndKeepImage() will fail if one or more of the following is true:

BADMAL

Unable to allocate sufficient memory.

**ILLPAR** 

Illegal parameter(s).

# **SEE ALSO**

AVW\_ConnectAndKeepVolume(), AVW\_ConnectAndDeleteImage(), AVW\_FindImageComponents(), AVW\_PointList2, AVW\_Image

AVW\_ConnectAndKeepVolume - extracts 3D regions based on connectivity

## **SYNOPSIS**

#include "AVW.h"

#include "AVW\_ObjectMap.h"

AVW\_Volume \*AVW\_ConnectAndKeepVolume(in\_volume, object\_map, seeds, connectivity, min, max, deleted\_value, count, out\_volume)

AVW Volume \*in volume:

AVW\_ObjectMap \*object\_map;

AVW\_PointList3 \*seeds;

int connectivity;

double min, max, deleted\_value;

int \*count;

AVW\_Volume \*out\_volume;

### **DESCRIPTION**

AVW\_ConnectAndKeepVolume() is used to extract a connected region from an AVW\_Volume. The non-connected voxels are set to a specified value. A count of connected voxels is returned and can be used for volume calculations.

*In\_volume* specifies the input *AVW\_Volume* which contains the region to be extracted.

*Seeds* is a pointer to an *AVW\_PointList3* structure. This structure must contain at least one point which will be used as the starting point(s) for the region growing process.

may be either  $AVW\_6\_CONNECTED$  or  $AVW\_26\_CONNECTED$  and specifies the neighbors to be used to determine the connected components.

*Min* and *max* specify the threshold limits used to constrain the region growing process. Voxels outside the threshold range are left unchanged.

Deleted\_value specifies the value to which each non-extracted pixel is set.

*Count* contains the number of voxels extracted if the function returns successfully. If the function fails, count will contain the number at the time of failure.

If <code>Object\_map</code> in not <code>NULL</code> the connect will be constrained to objects defined in the <code>object\_map</code> which have the <code>DisplayFlag</code> component of the <code>AVW\_Object</code> structure enabled. If <code>NULL</code> is specified only the threshold limits and the <code>connectivity</code> will constrain the 3D region growing process.

*Seeds* is a pointer to an *AVW\_PointList3* structure. This structure must contain at least one point which will be used as the starting point(s) for the 3D, 6 neighbor region grow.

Min and max specify the threshold limits used to constrain the 3D region growing process.

Deleted\_value specifies the value to which each non-extracted voxel is set.

*Count* contains the number of voxels deleted or extracted if the function returns successfully. If the function fails count will contain the number at the time of failure.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful  $AVW\_ConnectAndKeepVolume()$  returns an  $AVW\_Volume$ . On failure it returns NULL and sets the  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ConnectAndKeepVolume() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

 $AVW\_ConnectAnd Neep Image()\ AVW\_ConnectAnd Delete Volume(),\ AVW\_Define Connected(),\ AVW\_Find Volume Components(),\ AVW\_Object,\ AVW\_ObjectMap,\ AVW\_Point List 3,\ AVW\_Volume$ 

AVW\_ConstantOpImage - transforms an image mathematically

**SYNOPSIS** 

#include "AVW Parse.h"

 $AVW\_Image *AVW\_ConstantOpImage (value, operation, in\_image, out\_image)$ 

double value; int operation;

AVW\_Image \*in\_image;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_ConstantOpImage() applies the operation and in\_image to value and returns the resulting image:

out\_image = value operation in\_image

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

The following operations are defined in AVW\_Parse.h:

 $AVW\_OP\_ADD$ 

AVW\_OP\_SUB

AVW\_OP\_MUL

 $AVW\_OP\_DIV$ 

 $AVW\_OP\_LT$ 

 $AVW_OP_GT$ 

 $AVW\_OP\_LE$ 

 $AVW\_OP\_GE$ 

 $AVW\_OP\_EQ$ 

 $AVW\_OP\_NE$ 

AVW\_OP\_AND

 $AVW_OP_OR$ 

 $AVW\_OP\_MOD$ 

# **RETURN VALUES**

If successful AVW\_ConstantOpImage() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ConstantOpImage() will fail if one or more of the following are true:

**NOTSUP** 

Operation is not supported.

**DIVZER** 

Division by zero.

**BADMAL** 

Memory could not be allocated for results.

**ILLDT** 

Data type is not defined or supported.

**SEE ALSO** 

 $AVW\_ConstantOpVolume(),\ AVW\_ImageOpConstant(),\ AVW\_ImageOpImage(),\ AVW\_FunctionImage(),\ AVW\_Image,$ 

AVW\_ConstantOpVolume - transforms a volume mathematically

**SYNOPSIS** 

#include "AVW Parse.h"

AVW\_Volume \*AVW\_ConstantOpVolume(value, operation, in\_volume, out\_volume) double value;

int operation;

AVW\_Volume \*in\_volume;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_ConstantOpVolume() applies the operation and in\_volume to value and returns the resulting volume:

out\_volume = value operation in\_volume

AVW\_ContantOpVolume() calls AVW\_ConstantOpImage() with each slice in the input volume to produce the output volume.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

The following operations are defined in AVW\_Parse.h:

 $AVW\_OP\_ADD$ 

AVW\_OP\_SUB

AVW\_OP\_MUL

AVW\_OP\_DIV

 $AVW_OP_LT$ 

 $AVW_OP_GT$ 

 $AVW\_OP\_LE$ 

 $AVW_OP_GE$ 

 $AVW_OP_EQ$ 

AVW\_OP\_NE

AVW\_OP\_AND

 $AVW_OP_OR$ 

AVW\_OP\_MOD

### **RETURN VALUES**

If successful *AVW\_ConstantOpVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ConstantOpVolume() will fail if one or more of the following are true:

**AVW 3.0** 

**NOTSUP** 

Operation is not supported.

**DIVZER** 

Division by zero.

**BADMAL** 

Memory could not be allocated for results.

**ILLDT** 

Data type is not defined or supported.

**SEE ALSO** 

 $AVW\_ConstantOpImage(),\ AVW\_VolumeOpConstant(),\ AVW\_VolumeOpVolume(),\ AVW\_FunctionVolume(),\ AVW\_Volume$ 

AVW\_ConvertImage – converts a volume to a new data type

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_ConvertImage(in\_image, datatype, out\_image)

AVW\_Image \*in\_image;

int datatype;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_ConvertImage() converts in\_image to the specified datatype. Acceptable values for datatype, as defined in AVW.h, are: AVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_INT, AVW\_SIGNED\_INT, AVW\_FLOAT, AVW\_COMPLEX, AVW\_COLOR.

If the volume is converted to a data type which can hold less information, or information in a different range, the data is clipped at the maximum and minimum values possible for the new data type. No intensity scaling is attempted during the conversion process.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful AVW\_ConvertImage() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_ConvertImage()* will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for output volume.

**ILLDT** 

Unknown or unsupported input or output datatype.

**SEE ALSO** 

AVW\_ConvertVolume(), AVW\_DitherImage(), AVW\_IntensityScaleImage(), AVW\_MakeGrayImage() AVW\_Image

AVW\_ConvertSurfaceToVolume - draws a wiregrid surface into a volume

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW\_Model.h"

 $AVW\_Volume * AVW\_ConvertSurface ToVolume (surface, faces, truncated, fill)$ 

AVW\_TiledSurface \*surface;

int\* faces;
int\* truncated;

int fill;

**DESCRIPTION** 

AVW\_ConvertSurfaceToVolume() creates a volume where all voxels along the polygonal edges defined in *surface* are set to 1. The remaining voxels are set to 0. *faces* returns the number of polygons drawn into the volume. *truncated* returns the number of polygons

that were truncated by the volume's edges.

**RETURN VALUES** 

If successful AVW\_DrawTiledSurface() returns a volume. NULL is returned in the event

of an error.

**SEE ALSO** 

AVW\_DrawVolumeLine(), AVW\_DrawImageLine(), AVW\_PutPixel(), AVW\_PutVoxel(),

AVW\_Volume, AVW\_Point3

AVW\_ConvertVolume – converts a volume to a new data type

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_ConvertVolume(in\_volume, datatype, out\_volume)

AVW\_Volume \*in\_volume;

int datatype;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_ConvertVolume() converts in\_volume to the specified datatype. Acceptable values for datatype, as defined in AVW.h, are: AVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_INT, AVW\_SIGNED\_INT, AVW\_FLOAT, AVW\_COMPLEX, AVW\_COLOR.

If the volume is convert to a data type which can hold less information, or information in a different range, the data is clipped at the maximum and minimum values possible for the new data type. No intensity scaling is attempted during the conversion process.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_ConvertVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ConvertVolume() will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for output volume.

**ILLDT** 

Unknown or unsupported input or output datatype.

**SEE ALSO** 

 $AVW\_ConvertImage(),\ AVW\_DitherVolume(),\ AVW\_IntensityScaleVolume(),\ AVW\_MakeGrayVolume()\ AVW\_Volume$ 

AVW\_ConvolveImage - performs spatial convolution of an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_ConvolveImage(in\_image, psf, out\_image)

AVW\_Image \*in\_image;

AVW\_Image \*psf;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

*AVW\_ConvolveImage()* performs spatial convolution of an *AVW\_Image. Psf* is the point spread function, and must have odd extents in all dimensions.

Since this convolution is performed in the spatial domain, the processing time will increase with the extent of the Psf. If the Psf is a significant fraction of the extent of *in\_image*, it is more efficient to perform the convolution in the Fourier domain (see *AVW\_FFT2D()*).

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful AVW\_ConvolveImage() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

### **ERRORS**

*AVW\_ConvolveImage()* will fail if the following is true:

**BADMAL** 

Malloc Failed. Could not allocate memory for the results.

**ILLVOL** 

Psf has even extent.

**ILLDT** 

Psf or in\_image is of data type AVW\_COMPLEX or AVW\_COLOR.

**SEE ALSO** 

 $AVW\_ConvolveVolume(),\ AVW\_CorrelateImage(),\ AVW\_CorrelateVolume(),\ AVW\_FFT2D(),\ AVW\_Image$ 

AVW\_ConvolveVolume – performs spatial convolution of a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_ConvolveVolume(in\_volume, psf, out\_volume)

AVW\_Volume \*in\_volume;

AVW\_Volume \*psf;

AVW Volume \*out volume;

## **DESCRIPTION**

*AVW\_ConvolveVolume()* performs spatial convolution of an *AVW\_Volume*. *Psf* is the point spread function, and must have odd extents in all dimensions.

Since this convolution is performed in the spatial domain, the processing time will increase with the extent of the Psf. If the Psf is a significant fraction of the extent of *in\_volume*, it is more efficient to perform the convolution in the Fourier domain (see *AVW\_FFT3D()*).

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_ConvolveVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ConvolveVolume() will fail if the following is true:

**BADMAL** 

Malloc Failed. Could not allocate memory for the results.

**ILLVOL** 

Psf has even extent.

**ILLDT** 

Psf or in\_volume is of data type AVW\_COMPLEX or AVW\_COLOR.

**SEE ALSO** 

AVW\_ConvolveImage(), AVW\_CorrelateVolume(), AVW\_CorrelateImage, AVW\_Volume()

**NAME** AVW\_CopyColormap – creates a copy of a colormap

SYNOPSIS #include "AVW.h"

AVW\_Colormap \*AVW\_CopyColormap(in\_colormap, out\_colormap)

AVW\_Colormap \*in\_colormap, \*out\_colormap;

**DESCRIPTION** | *AVW\_CopyColormap()* returns a copy of *in\_colormap*.

Out\_colormap is provided as a method of reusing an existing AVW\_Colormap. Reuse is possible only if the size of the provided out\_colormap meet the requirements of the function. In this case the pointer to out\_colormap is returned by the function. If not reuseable out\_colormap will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_CopyColormap()* returns an *AVW\_Colormap*. On failure it returns *NULL* 

and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause

of the failure.

**ERRORS** *AVW\_CopyColormap()* will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

SEE ALSO | AVW\_CreateColormap(), AVW\_DestroyColormap(). AVW\_Colormap

**NAME** AVW\_CopyFPointList2 – creates a copy of a point list

SYNOPSIS #include "AVW.h"

AVW\_FPointList2 \*AVW\_CopyFPointList2(in\_pl, out\_pl)

AVW\_FPointList2 \*in\_pl, \*out\_pl;

**DESCRIPTION** | *AVW\_CopyFPointList2()* returns a copy of *in\_pl.* 

Out\_pl is provided as a method of reusing an existing AVW\_FPointList2. Reuse is possible only if the size and data type of the provided out\_pl meet the requirements of the function. In this case the pointer to out\_pl is returned by the function. If not reuseable out\_pl

will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_CopyFPointList2()* returns an *AVW\_FPointList2*. On failure it returns

NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to

the cause of the failure.

**ERRORS** *AVW\_CopyFPointList2()* will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

SEE ALSO | AVW\_CopyIPointList2(), AVW\_CopyPointList2(), AVW\_CreateFPointList2(),

 $AVW\_DestroyFPointList2()\ AVW\_FPointList2()$ 

**NAME** | AVW\_CopyFPointList3 – creates a copy of a point list

SYNOPSIS #include "AVW.h"

AVW\_FPointList3 \*AVW\_CopyFPointList3(in\_pl, out\_pl)

**AVW 3.0** 

AVW\_FPointList3 \*in\_pl, \*out\_pl;

**DESCRIPTION** AVW\_CopyFPointList3() returns a copy of in\_pl.

 $Out\_pl$  is provided as a method of reusing an existing  $AVW\_FPointList3$ . Reuse is possible only if the size and data type of the provided  $out\_pl$  meet the requirements of the function. In this case the pointer to  $out\_pl$  is returned by the function. If not reuseable  $out\_pl$ 

will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_CopyFPointList3()* returns an *AVW\_FPointList3*. On failure it returns

NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to

the cause of the failure.

**ERRORS** | *AVW\_CopyFPointList3()* will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

SEE ALSO | AVW\_CopyIPointList3(), AVW\_CopyPointList3(), AVW\_CreateFPointList3(),

AVW\_DestroyFPointList3() AVW\_FPointList3()

**NAME** AVW\_CopyIPointList2 – creates a copy of a point list

SYNOPSIS #include "AVW.h"

AVW\_IPointList2 \*AVW\_CopyIPointList2(in\_pl, out\_pl)

AVW\_IPointList2 \*in\_pl, \*out\_pl;

**DESCRIPTION** | *AVW\_CopyIPointList2()* returns a copy of *in\_pl.* 

 $Out\_pl$  is provided as a method of reusing an existing  $AVW\_IPointList2$ . Reuse is possible only if the size and data type of the provided  $out\_pl$  meet the requirements of the function. In this case the pointer to  $out\_pl$  is returned by the function. If not reuseable  $out\_pl$ 

will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful AVW\_CopyIPointList2() returns an AVW\_IPointList2. On failure it returns

NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to

the cause of the failure.

**ERRORS** | *AVW\_CopyIPointList2()* will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

**SEE ALSO** AVW\_CopyFPointList2(), AVW\_CopyPointList2(), AVW\_CreateIPointList2(),

AVW\_DestroyIPointList2() AVW\_IPointList2()

**NAME** AVW\_CopyIPointList3 – creates a copy of a point list

SYNOPSIS #include "AVW.h"

AVW\_IPointList3 \*AVW\_CopyIPointList3(in\_pl, out\_pl)

 $AVW\_IPointList3*in\_pl,*out\_pl;$ 

**DESCRIPTION** | *AVW\_CopyIPointList3()* returns a copy of *in\_pl.* 

 $Out\_pl$  is provided as a method of reusing an existing  $AVW\_IPointList3$ . Reuse is possible only if the size and data type of the provided  $out\_pl$  meet the requirements of the function. In this case the pointer to  $out\_pl$  is returned by the function. If not reuseable  $out\_pl$ 

will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_CopyIPointList3()* returns an *AVW\_IPointList3*. On failure it returns

NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to

the cause of the failure.

**ERRORS** | *AVW\_CopyIPointList3()* will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

SEE ALSO | AVW\_CopyFPointList3(), AVW\_CopyPointList3(), AVW\_CreateIPointList3(),

AVW\_DestroyIPointList3() AVW\_IPointList3()

**NAME** AVW\_CopyImage – creates a copy of an image

SYNOPSIS #include "AVW.h"

AVW\_Image \*AVW\_CopyImage(in\_image, out\_image)

AVW\_Image \*in\_image, \*out\_image;

**DESCRIPTION** AVW\_CopyImage() returns a copy of in\_image.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_CopyImage()* returns an *AVW\_Image*. On failure it returns *NULL* and

sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of

the failure.

**ERRORS** | *AVW\_CopyImage()* will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

SEE ALSO | AVW\_CopyVolume(), AVW\_CreateImage(), AVW\_DestroyImage() AVW\_Image()

**NAME** AVW\_CopyMatrix – copies a transformation matrix

SYNOPSIS #include "AVW.h"

AVW\_Matrix \*AVW\_CopyMatrix(in\_matrix, out\_matrix)

AVW\_Matrix \*in\_matrix, \*out\_matrix;

**DESCRIPTION** *AVW\_CopyMatrix()* returns a copy of *in\_matrix*.

Out\_matrix is provided as a method of reusing an existing AVW\_Matrix. (See Memory

Usage in the AVW Programmer's Guide.)

**SEE ALSO** AVW\_CreateMatrix(), AVW\_InvertMatrix(), AVW\_MakeMatrixFrom3Points(),

AVW\_MakeMatrixFromAxis(), AVW\_MirrorMatrix(), AVW\_MultiplyMatrix(),

AVW\_RotateMatrix(), AVW\_SetIdentityMatrix(), AVW\_ScaleMatrix(),

AVW\_TranslateMatrix(), AVW\_Matrix

**NAME** AVW\_CopyObjectMap – creates a copy of an object map

SYNOPSIS #include "AVW.h"

#include "AVW\_ObjectMap.h"

AVW\_ObjectMap \*AVW\_CopyObjectMap(in\_map, out\_map)

AVW\_ObjectMap \*in\_map, \*out\_map;

**DESCRIPTION** *AVW\_CopyObjectMap()* returns a copy of *in\_map*.

Out\_map is provided as a method of reusing an existing AVW\_ObjectMap. Reuse is possible only if the size of the provided out\_map meet the requirements of the function. In this case the pointer to out\_map is returned by the function. If not reuseable out\_map will be

reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_CopyObjectMap()* returns an *AVW\_ObjectMap.* On failure it returns

NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to

the cause of the failure.

**ERRORS** | *AVW\_CopyObjectMap()* will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

**SEE ALSO** | AVW\_CreateObjectMap(), AVW\_DestroyObjectMap() AVW\_ObjectMap()

**NAME** AVW\_CopyPointList2 – creates a copy of a point list

SYNOPSIS #include "AVW.h"

AVW\_PointList2 \*AVW\_CopyPointList2(in\_pl, out\_pl)

AVW\_PointList2 \*in\_pl, \*out\_pl;

**DESCRIPTION** | *AVW\_CopyPointList2()* returns a copy of *in\_pl.* 

Out\_pl is provided as a method of reusing an existing AVW\_PointList2. Reuse is possible only if the size of the provided out\_pl meet the requirements of the function. In this case the pointer to out\_pl is returned by the function. If not reuseable out\_pl will be reallocated.

(See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_CopyPointList2()* returns an *AVW\_PointList2*. On failure it returns

NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to

the cause of the failure.

**ERRORS** | *AVW\_CopyPointList2()* will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

 $\textbf{SEE ALSO} \qquad AVW\_CopyFPointList2(), \ AVW\_CopyIPointList2(), \ AVW\_CreatePointList2(), \ AVW\_CopyFPointList2(), \ AVW\_$ 

AVW\_DestroyPointList2() AVW\_PointList2()

**NAME** AVW\_CopyPointList3 – creates a copy of a point list

SYNOPSIS #include "AVW.h"

AVW\_PointList3 \*AVW\_CopyPointList3(in\_pl, out\_pl)

AVW\_PointList3 \*in\_pl, \*out\_pl;

**DESCRIPTION** | *AVW\_CopyPointList3()* returns a copy of *in\_pl.* 

Out\_pl is provided as a method of reusing an existing AVW\_PointList3. Reuse is possible only if the size of the provided out\_pl meet the requirements of the function. In this case the pointer to out\_pl is returned by the function. If not reuseable out\_pl will be reallocated.

(See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_CopyPointList3()* returns an *AVW\_PointList3*. On failure it returns

NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to

the cause of the failure.

**ERRORS** *AVW\_CopyPointList3()* will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

SEE ALSO | AVW\_CopyFPointList3(), AVW\_CopyIPointList3(), AVW\_CreatePointList3(),

AVW\_DestroyPointList3() AVW\_PointList3()

**NAME** AVW\_CopyPointValueList – creates a copy of a point list

SYNOPSIS #include "AVW.h"

AVW\_PointValueList \*AVW\_CopyPointValueList(in\_pl, out\_pl)

AVW\_PointValueList \*in\_pl, \*out\_pl;

**DESCRIPTION** | *AVW\_CopyPointValueList()* returns a copy of *in\_pl.* 

 $Out\_pl$  is provided as a method of reusing an existing  $AVW\_PointValueList$ . Reuse is possible only if the size of the provided  $out\_pl$  meet the requirements of the function. In this case the pointer to  $out\_pl$  is returned by the function. If not reuseable  $out\_pl$  will be reallo-

cated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful AVW\_CopyPointValueList() returns an AVW\_PointValueList. On failure it

returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values correspond-

ing to the cause of the failure.

**ERRORS** *AVW\_CopyPointValueList()* will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

SEE ALSO | AVW CopyFPointList(), AVW CopyIPointList(), AVW CopyPointList(),

AVW\_CreatePointValueList(), AVW\_DestroyPointValueList() AVW\_PointValueList()

**NAME** AVW\_CopyRenderedImage – creates a copy of an rendered image structure

SYNOPSIS #include "AVW.h"

AVW\_RenderedImage \*AVW\_CopyRenderedImage(in\_rendered, out\_rendered) AVW\_RenderedImage \*in\_rendered, \*out\_rendered;

**DESCRIPTION** | AVW\_CopyRenderedImage() returns a copy of in\_rendered.

Out\_rendered is provided as a method of reusing an existing AVW\_RenderedImage. Reuse is possible only if the size and data type of the provided out\_rendered meet the requirements of the function. In this case the pointer to out\_rendered is returned by the function. If not reuseable out\_rendered will be reallocated. (See Memory Usage in the AVW

Programmer's Guide.)

**RETURN VALUES** If successful AVW\_CopyRenderedImage() returns an AVW\_RenderedImage. On failure it

returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values correspond-

ing to the cause of the failure.

**ERRORS** | *AVW\_CopyRenderedImage()* will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

SEE ALSO | AVW\_RenderVolume(), AVW\_RenderOblique(), AVW\_CubeSections(),

 $AVW\_Intersecting Sections (), AVW\_Destroy Rendered Image () \ AVW\_Rendered Image ()$ 

**NAME** AVW\_CopyVolume – creates a copy of a volume

SYNOPSIS #include "AVW.h"

AVW\_Volume \*AVW\_CopyVolume(in\_volume, out\_volume)

AVW\_Volume \*in\_volume, \*out\_volume;

**DESCRIPTION** | *AVW\_CopyVolume()* returns a copy of *in\_volume*.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_CopyVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* 

and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause

of the failure.

**ERRORS** | *AVW\_CopyVolume()* will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

SEE ALSO | AVW\_CopyImage(), AVW\_DestroyVolume(), AVW\_CreateVolume(), AVW\_Volume

AVW\_CorrelateImage - performs spatial correlation on two images

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_CorrelateImage(in\_image, psf, out\_image)

AVW\_Image \*in\_image;

AVW\_Image \*psf;

AVW\_Image \*out\_image;

## **DESCRIPTION**

*AVW\_CorrelateImage()* performs spatial cross-correlation of two images. *Psf* is the point spread function, and must have odd extent in all dimensions.

Since this correlation is performed in the spatial domain, the processing time will increase with the extent of the Psf. If the Psf is a significant fraction of the extent of *in\_image*, it is more efficient to perform the correlation in the Fourier domain (see *AVW\_FFT2D()*).

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful AVW\_CorrelateImage() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

## **ERRORS**

*AVW\_CorrelateImage()* will fail if the following is true:

**BADMAL** 

Malloc Failed. Could not allocate memory for the results.

**ILLIMG** 

Psf has even extent.

**ILLDT** 

Psf or in\_image is AVW\_COMPLEX or AVW\_COLOR data type.

**SEE ALSO** 

AVW\_CorrelateVolume(), AVW\_ConvolveImage(), AVW\_ConvolveVolume(), AVW\_Image

AVW\_CorrelateVolume - performs spatial correlation on two volumes

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_CorrelateVolume(in\_volume, psf, out\_volume)

AVW\_Volume \*in\_volume;

AVW\_Volume \*psf;

AVW Volume \*out volume;

## **DESCRIPTION**

*AVW\_CorrelateVolume()* performs spatial cross-correlation of two volumes. *Psf* is the point spread function, and must have odd extent in all dimensions.

Since this correlation is performed in the spatial domain, the processing time will increase with the extent of the Psf. If the Psf is a significant fraction of the extent of *in\_volume*, it is more efficient to perform the correlation in the Fourier domain (see *AVW\_FFT3D()*).

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful AVW\_CorrelateVolume() returns an AVW\_Volume. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_CorrelateVolume() will fail if the following is true:

**BADMAL** 

Malloc Failed. Could not allocate memory for the results.

**ILLVOL** 

Psf has even extent.

**ILLDT** 

Psf or in\_volume is AVW\_COMPLEX or AVW\_COLOR data type.

**SEE ALSO** 

AVW\_CorrelateImage(), AVW\_ConvolveImage(), AVW\_ConvolveVolume(), AVW\_Volume

AVW\_Counter - indicates current progress

**SYNOPSIS** 

#include "AVW.h"

int AVW\_Counter(count)

int count;

**DESCRIPTION** 

AVW\_Counter() is called by many AVW functions to indicate their current progress. Count is a positive value indicating the current status of the calling procedure. This function will not normally be called unless AVW has been extended, and the programmer wishes to report the progress of the extended routine. Use of this function should be limited to functions which would normally require many seconds to execute. Functions which report progress, should not call other functions which report progress. Nested progresses are not supported.

When *AVW\_Counter()* is called, the *count* value is passed to a user defined function. This function is indicated to *AVW* by the *AVW\_CounterFunction()* call.

The return value is used to indicate a interrupt status. If non-zero value (1) is returned, the progress function indicates the process should continue. If zero (0) is returned, the progress function is requesting that the function be terminated.

**RETURN VALUES** 

If a call to *AVW\_Counter()* returns zero, the function should be terminated. A non-zero return value indicates that processing should continue.

**SEE ALSO** 

AVW\_CounterFunction(), AVW\_Progress(), AVW\_ConnectAndDeleteVolume(), AVW\_ConnectAndKeepVolume(), AVW\_DefineConnected(), AVW\_ExtendExternalLibs(), AVW\_FindVolumeComponents(), AVW\_LabelVolumeFromEdges()

AVW\_CounterFunction – indicates the function which reports progress

**SYNOPSIS** 

#include "AVW.h"

void AVW\_CounterFunction(int (\*function)())

**DESCRIPTION** 

Many *AVW* routines require many seconds to execute. The status of these routines is generally not reported until the function completes. To allow such things as progress graphs to be generated while the function executes, many *AVW* functions call the *AVW\_Counter()* function to indicate their status. When the *AVW\_Counter()* function is called, the count value is passed on to a user specified function. The *AVW\_CounterFunction()* is used to indicate which user supplied function is to be called.

By returning zero (0), the user supplied routine can indicate a desire to interrupt the function. A non-zero value indicates the processing should continue.

**SEE ALSO** 

 $AVW\_Counter(),\ AVW\_ProgressFunction(),\ AVW\_ConnectAndDeleteVolume(),\\ AVW\_ConnectAndKeepVolume(),\ AVW\_DefineConnected(),\ AVW\_FindVolumeComponents(),\\ AVW\_LabelVolumeFromEdges()$ 

AVW\_CreateButterworthCoeffs - creates a list of coefficients for a Butterworth filter

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_FilterCoeffs \*AVW\_CreateButterworthCoeffs(type, f1, f2, order, numsamples, coeffs)

int type;

int f1;

int f2;

int order:

int numsamples;

AVW\_FilterCoeffs \*coeffs;

## **DESCRIPTION**

AVW\_CreateButterworthCoeffs() creates a list of coefficients for a Butterworth filter. These coefficients may be used to create a 2-D or 3-D transfer function for Fourier-domain image processing. If coeffs is NULL or coeffs->number is not equal to numsamples, the function allocates new memory for the returned coeffs. Type may be AVW\_LOWPASS, AVW\_HIGHPASS, AVW\_BANDPASS, or AVW\_NOTCH.

The parameters *f1* and *f2* are corner-frequency indices. Only *f1* is used for AVW\_HIGHPASS or AVW\_LOWPASS filters.

*Order* determines how rapidly the filter response falls from 1. Butterworth filters fall off at the rate of one order of magnitude per decade of frequency per order, so a filter of order 2 drops two orders of magnitude per decade while a third order filter drops three orders of magnitude per decade.

## **RETURN VALUES**

If successful  $AVW\_CreateButterworthCoeffs()$  returns a  $AVW\_FilterCoeffs$  filled with real frequency space coefficients for the specified Butterworth filter. The coefficients are designed to be used to create a 2D or 3D transfer function, and numsamples should equal (X/2+1) for an image of dimension X. On failure it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_CreateButterworthCoeffs() will fail if the following is true:

**BADMAL** 

Malloc Failed. Could not allocate memory for the results.

## **SEE ALSO**

AVW\_CalculateSphericalMTF(), AVW\_CreateCoeffs(), AVW\_CreateCircularMTF(), AVW\_CalculateGaussianCoeffs(), AVW\_CreateCoeffs(), AVW\_DestroyCoeffs(), AVW\_FilterCoeffs

AVW\_CreateCircularMTF - converts filter coefficients to circular frequency filter

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Image \*AVW\_CreateCircularMTF(coeffs, out\_image)

AVW\_FilterCoeffs \*coeffs; AVW\_Image \*out\_image;

**DESCRIPTION** 

*AVW\_CreateCircularMTF()* converts filter coefficients *coeff* into a circularly symmetrical modulation transfer function.

An *AVW\_FilterCoeffs* structure is a list of floating point coefficients describing a one-dimensional frequency domain filter. *AVW\_CreateCircularMTF()* replicates the coefficients in a circular pattern within a 2-D image formatted to match the results of *AVW\_FFT2D()*.

The *out\_image* will be *coeffs->numsamples* pixels wide and 2\*( *coeffs->numsamples* -1) pixels high.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_CreateCircularMTF()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_CreateCircularMTF()* will fail if the following is true:

**BADMAL** 

Malloc Failed. Could not allocate memory for the results.

**SEE ALSO** 

AVW\_CreateButterWorthCoeffs(), AVW\_CreateCoeffs(), AVW\_CreateGaussianCoeffs(), AVW\_DestroyCoeffs(), AVW\_CreateSphericalMTF(), AVW\_FilterCoeffs, AVW\_Image

AVW\_CreateCoeffs - creates a list of filter coefficients

**SYNOPSIS** 

#include "AVW\_Filter.h"

AVW\_FilterCoeffs \*AVW\_CreateCoeffs(numsamples, coeffs)

int numsamples;

AVW\_FilterCoeffs \*coeffs;

**DESCRIPTION** 

AVW\_CreateCoeffs() creates a list of coefficients, *coeffs*, for a frequency domain filter. An AVW\_FilterCoeffs structure is a list of floating point coefficients describing a one-dimensional frequency domain filter. These coefficients may be used to create a 2-D or 3-D transfer function for Fourier-domain image processing.

Numsamples is the number of samples in the AVW\_FilterCoeff. Coeffs is provided as a method of reusing an existing AVW\_FilterCoeffs. Reuse is possible only if the size and data type of the provided coeffs meet the requirements of the function. In this case the pointer to coeffs is returned by the function. If not reusable coeffs will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful AVW\_CreateCoeffs() returns an AVW\_FilterCoeffs. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_CreateCoeffs() will fail if the following is true:

**BADMAL** 

Malloc Failed. Could not allocate memory for the results.

**SEE ALSO** 

AVW\_CreateSphericalMTF(), AVW\_CreateCircularMTF(), AVW\_CreateCoeffs(), AVW\_CreateGaussianCoeffs(), AVW\_DestroyCoeffs(), AVW\_CreateButterworthCoeffs(), AVW FilterCoeffs

**NAME** AVW\_CreateColormap – creates a colormap

SYNOPSIS #include "AVW.h"

AVW\_Colormap \*AVW\_CreateColormap(size)

int size;

**DESCRIPTION** | *AVW\_CreateColormap()* is used to create an *AVW\_Colormap*.

*Size* indicates the number of colors to be allocated. The value must be greater than or equal to 2. The returned colormap is initialized to a linear gray scale from 0 to 255.

**RETURN VALUES** | AVW\_CreateColormap() returns an AVW\_Colormap. On failure NULL is returned and

**AVW 3.0** 

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** | *AVW\_CreateColormap()* will fail if one or more of the following are true:

**ILLPAR** 

Illegal Parameter. The passed sized parameter was out of range.

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

SEE ALSO | AVW\_DestroyColormap(), AVW\_CopyColormap(), AVW\_Colormap

**NAME** AVW\_CreateCompositeInfo – initializes a composite info structure.

SYNOPSIS #include "AVW\_CompositeInfo.h"

AVW\_CompositeInfo \*AVW\_CreateCompositeInfo()

**DESCRIPTION**AVW\_CreateCompositeInfo() creates, initializes, and returns an AVW\_CompositeInfo structure.

The Ar AVW CompositeInfo is a structure which identifies tissues in a volume.

ture. The An AVW\_CompositeInfo is a structure which identifies tissues in a volume.

**RETURN VALUES** If successful AVW\_CreateCompositeInfo() returns a pointer to an AVW\_CompositeInfo struc-

ture. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure. The initial composite info structure con-

tains a greyscale volor and opacities for the intensities between 0 and 255.

**ERRORS** | *AVW\_CreateCompositeInfo()* will fail if one or more of the following is true:

BADMAL

Unable to allocate sufficient memory.

**SEE ALSO** | AVW\_DestroyCompositeInfo(), AVW\_LoadCompositeInfo(), AVW\_SaveCompositeInfo(),

AVW\_CompositeInfo

**NAME** AVW\_CreateFPointList2 – initializes an AVW list structure

SYNOPSIS #include "AVW.h"

AVW\_FPointList2 \*AVW\_CreateFPointList2(block\_size)

int block\_size;

**DESCRIPTION** The *AVW* point list structures, defined in *AVW.h*, can be used for a variety of things

**AVW 3.0** 

including traces and stacks. They are initially allocated to store block\_size points and are

increased by *block\_size* points as needed.

AVW\_CreateFPointList2() allocates memory for and initializes an AVW\_FPointList2.

**RETURN VALUES** If successful *AVW\_CreateFPointList2()* returns an *AVW\_FPointList2.* 

On failure  $\mathit{NULL}$  is returned and  $\mathit{AVW\_ErrorNumber}$  and  $\mathit{AVW\_ErrorMessage}$  are set to

values corresponding to the cause of the failure.

**ERRORS** | *AVW\_CreateFPointList2()*, will fail if the following is true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure.

SEE ALSO AVW\_CreateFPointList3(), AVW\_CreateIPointList2(), AVW\_CreateIPointList3(), AVW\_CreatePointList3(), AVW\_CreatePointList3(), AVW\_CreatePointValueList(),

AVW\_AddFPoint2(), AVW\_DestroyFPointList2(), AVW\_FPointList2, AVW\_FPoint2

**NAME** AVW\_CreateFPointList3 – initializes an AVW list structure

SYNOPSIS #include "AVW.h"

 $AVW\_FPointList3*AVW\_CreateFPointList3(block\_size)$ 

int block\_size;

**DESCRIPTION** The *AVW* point list structures, defined in *AVW.h*, can be used for a variety of things

including traces and stacks. They are initially allocated to store block\_size points and are

increased by *block\_size* points as needed.

AVW\_CreateFPointList3() allocates memory for and initializes an AVW\_FPointList3.

**RETURN VALUES** If successful *AVW\_CreateFPointList3()* returns an *AVW\_FPointList3*.

On failure NULL is returned and AVW\_ErrorNumber and AVW\_ErrorMessage are set to

values corresponding to the cause of the failure.

**ERRORS** AVW\_CreateFPointList3() will fail if the following is true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure.

SEE ALSO AVW\_CreateFPointList2(), AVW\_CreateIPointList2(), AVW\_CreateIPointList3(), AVW\_CreatePointList2(), AVW\_CreatePointList3(), AVW\_CreatePointValueList(),

AVW\_AddFPoint3(), AVW\_DestroyFPointList3(), AVW\_FPointList3, AVW\_FPoint3

AVW\_CreateGaussianCoeffs - creates a list of coefficients for a Gaussian filter

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW Filter.h"

 $AVW\_Filter Coeffs *AVW\_Create Gaussian Coeffs (dev, numsamples, coeffs)$ 

double dev; int numsamples;

AVW FilterCoeffs \*coeffs;

**DESCRIPTION** 

AVW\_CreateGaussianCoeffs() creates a list of coefficients for a frequency domain Gaussian Filter. Dev determines the standard deviation of the of the frequency-space Gaussian. Numsamples determines the number of samples in the AVW\_FilterCoeffs structure. These coefficients may be used to create a 2-D or 3-D transfer function for Fourier-domain image processing. The Gaussian function is zero-mean with a standard deviation (in samples) as specified by the input variable. This will effect a Gaussian low-pass filter when used with AVW\_CreateSphericalMTF() or AVW\_CreateCircularMTF().

Note: in order to create a filter for a NxN image, a N/2 + 1 sample  $AVW\_FilterCoeffs$  structure is required.

Coeffs is provided as a method of reusing an existing AVW\_FilterCoeffs. Reuse is possible only if the size of the provided coeffs meet the requirements of the function. In this case the pointer to coeffs is returned by the function. If not reusable coeffs will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful  $AVW\_CreateGaussianCoeffs()$  returns an  $AVW\_FilterCoeffs$ . On failure it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the failure.

**ERRORS** 

AVW\_CreateGaussianCoeffs() will fail if the following is true:

**BADMAL** 

Malloc Failed. Could not allocate memory for the results.

**SEE ALSO** 

AVW\_CreateSphericalMTF(), AVW\_CreateCircularMTF(), AVW\_CreateCoeffs(), AVW\_DestroyCoeffs(), AVW\_CreateButterworthCoeffs(), AVW\_FilterCoeffs

AVW\_CreateHistogram - creates an AVW\_Histogram

**SYNOPSIS** 

#include "AVW\_Histogram.h"

AVW\_Histogram \*AVW\_CreateHistogram(mem, max, min, step)

double \*mem; double max;

double min;

double step;

## **DESCRIPTION**

AVW\_CreateHistogram() creates an AVW\_Histogram of the requested size. Memory for the histogram may be specified in the call or allocated by the function but must be of type double.

Max, min and step specify the size of the histogram.

*Mem* is the actual memory used to store the histogram. The *Mem* element of the *AVW\_Histogram* is set to this address. The memory pointed at by *mem* must be large enough to accommodate the size of the specified *AVW\_Histogram*.

If *NULL* is provided for *mem* then *AVW\_CreateHistogram* will allocate memory for the histogram.

# **RETURN VALUES**

If successful *AVW\_CreateHistogram()* returns an *AVW\_Histogram*. On failure *NULL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_CreateHistogram() will fail if one or more of the following are true:

## **BADMAL**

Malloc Failed. Unable to allocate memory for structure and/or histogram.

## **SEE ALSO**

 $AVW\_Clear Histogram (),\ AVW\_Destroy Histogram (),\ AVW\_Flatten Image Histogram (),$ 

 $AVW\_FlattenVolume Histogram (),\ AVW\_GetImage Histogram (),\ AVW\_GetVolume Histogram (),\ AVW\_GetVolu$ 

AVW\_MatchImageHistogram(), AVW\_MatchVolumeHistogram(),

AVW\_NormalizeHistogram(), AVW\_PreserveImageHistogram(),

AVW\_PreserveVolumeHistogram(), AVW\_VerifyHistogram(), AVW\_Histogram

**NAME** AVW\_CreateIPointList2 – initializes an AVW list structure

SYNOPSIS #include "AVW.h"

AVW\_IPointList2 \*AVW\_CreateIPointList2(block\_size) int block\_size;

**DESCRIPTION** The *AVW* point list structures, defined in *AVW.h*, can be used for a variety of things

**AVW 3.0** 

including traces and stacks. They are initially allocated to store block\_size points and are

increased by block\_size points as needed.

AVW\_CreateIPointList2() allocates memory for and initializes an AVW\_IPointList2.

**RETURN VALUES** If successful *AVW\_CreateIPointList2()* returns an *AVW\_IPointList2.* 

On failure NULL is returned and AVW\_ErrorNumber and AVW\_ErrorMessage are set to

values corresponding to the cause of the failure.

**ERRORS** AVW\_CreateIPointList2(), will fail if the following is true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure.

SEE ALSO AVW\_CreateIPointList3(), AVW\_CreateFPointList2(), AVW\_CreateFPointList3(), AVW\_CreatePointList3(), AVW\_CreatePointList3(), AVW\_CreatePointValueList(),

AVW\_AddIPoint2(), AVW\_DestroyIPointList2(), AVW\_IPointList2, AVW\_IPoint2

NAME | AVW\_CreateIPointList3 – initializes an AVW list structure

SYNOPSIS #include "AVW.h"

 $AVW\_IPointList3*AVW\_CreateIPointList3(block\_size)$ 

int block\_size;

**DESCRIPTION** The AVW point list structures, defined in AVW.h, can be used for a variety of things

including traces and stacks. They are initially allocated to store *block\_size* points and are

increased by *block\_size* points as needed.

AVW\_CreateIPointList3() allocates memory for and initializes an AVW\_IPointList3.

**RETURN VALUES** If successful *AVW\_CreateIPointList3()* returns an *AVW\_IPointList3*.

On failure NULL is returned and AVW\_ErrorNumber and AVW\_ErrorMessage are set to

values corresponding to the cause of the failure.

**ERRORS** AVW\_CreateIPointList3() will fail if the following is true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure.

 $\textbf{SEE ALSO} \qquad AVW\_CreateIPointList2(), \ AVW\_CreateFPointList2(), \ AVW\_CreateFPointList3(), \ AVW\_C$ 

AVW\_CreatePointList2(), AVW\_CreatePointList3(), AVW\_CreatePointValueList(), AVW\_AddIPoint3(), AVW\_DestroyIPointList3(), AVW\_IPointList3, AVW\_IPoint3

AVW\_CreateImage - creates an AVW\_Image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_CreateImage(mem, width, height, type)

void \*mem;

int width, height, type;

**DESCRIPTION** 

*AVW\_CreateImage()* creates *AVW\_Image* of the specified size and data type. Memory for the pixel data may be specified in the call or allocated by the function.

*Width* and *height* specify the x and y dimensions of the image in pixels.

Type specifies the AVW data type of the pixels. Acceptable values are: AVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_INT, AVW\_SIGNED\_INT, AVW\_FLOAT, AVW\_COMPLEX, AVW\_COLOR.

*Mem* is the actual memory used to store the pixel data for this image. The *Mem* element of the *AVW\_Image* is set to this address. The memory pointed at by *mem* must be large enough to accommodate the size and data type of the specified *AVW\_Image*.

If *NULL* is provided for *mem* then *AVW\_CreateImage* will allocate memory for the pixel data.

The memory that is allocated by *AVW\_CreateImage* is contiguous. Pixels in the memory are referenced from *image->Mem*.

Additionally *YTable* is an allocated offset array in the structure which enables efficient addressing of individual pixels within the space. This offset array is indexed as any other 'c' array. This means that the offset to the first line of the image is *YTable[0]*. These values can be added to the Mem element of the image structure to reference any line from an *AVW\_Image*.

**RETURN VALUES** 

If successful AVW\_CreateImage() returns an AVW\_Image. On failure NULL is returned and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_CreateImage() will fail if one or more of the following are true:

**ILLDT** 

Illegal data type given in type.

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

**SEE ALSO** 

AVW\_CreateVolume(), AVW\_DestroyImage(), AVW\_Image

AVW\_CreateImageFile - creates a new AVW\_ImageFile

## **SYNOPSIS**

#include "AVW\_ImageFile.h"

AVW\_ImageFile \*AVW\_CreateImageFile (filename, format, width, height, depth, datatype) char \*filename;

char \*format;

int width:

int height;

int depth;

int datatype;

## **DESCRIPTION**

AVW\_CreateImageFile() allocates an AVW\_ImageFile structure, initializes its attributes to the call parameters and then calls the appropriate create function for the specified format.

A list of acceptable formats which *AVW* supports for writing data is obtained from *AVW\_ListFormats(AVW\_SUPPORT\_WRITE);*. Built-in supported file formats for writing data are:

AnalyzeAVW

AVW\_VolumeFile

These writable formats are available through dynamically

loaded libraries

AnalyzeImage(7.5)

AnalyzeScreen

SunRaster

**PPM** 

**PGM** 

**BMP** 

RGB

**SGIrgb** 

PIC

The *filename* parameter is the name of the file which is being created.

*Width* and *height* are the dimensions of the images in the file. *Depth* is the number of images in a volume. This value is 1 for data formats which do not support 3D. *Datatype* is the *AVW\_DataType* of the images which will be written to the file.

This function should be used instead of AVW\_OpenImageFile() to create a new file.

# **RETURN VALUES**

If successful *AVW\_CreateImageFile()* returns an *AVW\_ImageFile*. On failure *NULL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values indicating the cause of failure.

# **ERRORS**

AVW\_CreateImageFile() will fail for these reasons:

**BADMAL** 

Bad Malloc. Unable to allocate sufficient memory.

**RDCRT** 

Bad Create. Unable to create file.

ILLEGAL\_DATATYPE

Illegal Datatype. The file format does not support the indicated datatype.

# INCOMPATIBLE\_VOLUME

Incompatible Volume. The file format does not support 3D.

# NOPERMISSION

File Permission. Cannot be written by user.

# **NOSPACE**

No Space On Device. Disk is full.

# **RDONLFS**

Read Only File System.

# UNKNOWN\_FORMAT

Unknown Format.

# **SEE ALSO**

AVW\_CloseImageFile(), AVW\_ExtendImageFile(), AVW\_ListFormats(), AVW\_OpenImageFile(), AVW\_ReadImageFile(), AVW\_ReadVolume(), AVW\_SeekImageFile(), AVW\_WriteImageFile(), AVW\_ImageFile(), AVW\_Image

**NAME** AVW\_CreateList – creates an AVW\_List

SYNOPSIS #include "AVW.h"

AVW\_List \*AVW\_CreateList(NumberOfEntries)

int NumberOfEntries;

**DESCRIPTION** | *AVW\_CreateList()* creates *AVW\_List* of the specified number of entries.

The AVW\_List structure provides an easy way to pass and return lists.

NumberOfEntries

is the number of entries in the list.

Entry is an array of (char

For example ...

list = AVW\_CreateList(3);

list->Entry[0] = "List Element 1"

list->Entry[1] = "List Element 2"

list->Entry[2] = "List Element 3"

**RETURN VALUES** If successful *AVW\_CreateList()* returns an *AVW\_List*. On failure *NULL* is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** *AVW\_CreateImage()* will fail if the following is true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

**SEE ALSO** | AVW\_DestroyList(), AVW\_ListFormats(), AVW\_List

AVW\_CreateMatrix - creates an AVW\_Matrix

**SYNOPSIS** 

#include "AVW.h"

AVW\_Matrix \*AVW\_CreateMatrix(rows, columns)

int rows, columns;

**DESCRIPTION** 

AVW\_CreateMatrix() creates an AVW\_Matrix of the specified dimensions. All values in the matrix are set to 0's expect the locations where the row and column indexs are the same those are set to 1's, thus creating a Identity Matrix by default

same, these are set to 1's, thus creating a Identity Matrix by default.

Rows and Columns can be any positive value, but most AVW function currently require 4

X 4.

**RETURN VALUES** 

If successful AVW\_CreateMatrix() returns an AVW\_Matrix. On failure NULL is returned

and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the

cause of the failure.

**ERRORS** 

AVW\_CreateMatrix() will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

**SEE ALSO** 

AVW\_DestroyMatrix(), AVW\_Matrix

AVW\_CreateObjectMap - initializes an object map

**SYNOPSIS** 

#include "AVW\_ObjectMap.h"

AVW\_ObjectMap \*AVW\_CreateObjectMap(width, height, depth) int width, height, depth;

**DESCRIPTION** 

AVW\_CreateObjectMap() creates, initializes, and returns an AVW\_ObjectMap structure. The AVW\_ObjectMap returned has one object called Original. Width, height, and depth specify the dimension of the object\_map->Volume. This size must match the size of the AVW\_Volume which will be rendered. An AVW\_ObjectMap is a structure which identifies voxels in a volume as belonging to various structures and can be used by the AVW\_RenderVolume() routine.

**RETURN VALUES** 

If successful *AVW\_CreateObjectMap()* returns a pointer to an *AVW\_ObjectMap* structure. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_CreateObjectMap() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_AddObject(), AVW\_CopyObjectMap(), AVW\_DeleteObject(), AVW\_DestroyObjectMap(), AVW\_GetObject(), AVW\_LoadObjectMap(), AVW\_PutObject(), AVW\_SaveObjectMap(), AVW\_RenderVolume(), AVW\_ObjectMap

NAME | AVW\_CreatePointList2 – initializes an AVW list structure

SYNOPSIS #include "AVW.h"

 $AVW\_PointList2*AVW\_CreatePointList2(block\_size)$ 

int block\_size;

**DESCRIPTION** The *AVW* point list structures can be used for a variety of things including traces and

stacks. They are initially allocated to store block\_size points and are increased by block\_size

points as needed. See AVW.h for a definition of the structures.

AVW\_CreatePointList2() allocates memory for and initializes an AVW\_PointList2.

**RETURN VALUES** If successful *AVW\_CreatePointList2()* returns an *AVW\_PointList2*.

On failure  $\mathit{NULL}$  is returned and  $\mathit{AVW\_ErrorNumber}$  and  $\mathit{AVW\_ErrorMessage}$  are set to

values corresponding to the cause of the failure.

**ERRORS** AVW\_CreatePointList2() will fail if the following is true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure.

 $\textbf{SEE ALSO} \qquad AVW\_CreateFPointList2(), \ AVW\_CreateFPointList3(), \ AVW\_CreateIPointList2(), \ AVW\_CreateFPointList2(), \ AVW\_C$ 

AVW\_CreateIPointList3(), AVW\_CreatePointList3(), AVW\_CreatePointValueList(),

AVW\_AddPoint2(), AVW\_DestroyPointList2(), AVW\_PointList2

NAME | AVW\_CreatePointList3 – initializes an AVW list structure

SYNOPSIS #include "AVW.h"

 $AVW\_PointList3*AVW\_CreatePointList3(block\_size)$ 

int block\_size;

**DESCRIPTION** The *AVW* point list structures can be used for a variety of things including traces and

stacks. They are initially allocated to store block\_size points and are increased by block\_size

points as needed. See AVW.h for a definition of the structures.

AVW\_CreatePointList3() allocates memory for and initializes an AVW\_PointList3.

**RETURN VALUES** If successful *AVW\_CreatePointList3()* returns an *AVW\_PointList3*.

On failure  $\mathit{NULL}$  is returned and  $\mathit{AVW\_ErrorNumber}$  and  $\mathit{AVW\_ErrorMessage}$  are set to

values corresponding to the cause of the failure.

**ERRORS** | *AVW\_CreatePointList3()* will fail if the following is true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure.

**SEE ALSO** AVW\_CreateFPointList2(), AVW\_CreateFPointList3(), AVW\_CreateIPointList2(),

AVW\_CreateIPointList3(), AVW\_CreatePointList2(), AVW\_CreatePointValueList(),

AVW\_AddPoint3(), AVW\_DestroyPointList3(), AVW\_PointList3

AVW\_CreatePointValueList - initializes an AVW list structure

**SYNOPSIS** 

#include "AVW.h"

AVW\_PointValueList \*AVW\_CreatePointValueList(block\_size) int block\_size;

**DESCRIPTION** 

The *AVW* point list structures can be used for a variety of things including traces and stacks. They are initially allocated to store *block\_size* points and are increased by *block\_size* points as needed. See *AVW.h* for a definition of the structures.

AVW\_CreatePointValueList() allocates memory for and initializes an AVW\_PointValueList.

**RETURN VALUES** 

If successful AVW\_CreatePointValueList() returns an AVW\_PointValueList.

On failure *NULL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_CreatePointValueList()*, will fail if the following is true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure.

**SEE ALSO** 

AVW\_CreateFPointList2(), AVW\_CreateFPointList3(), AVW\_CreateIPointList2(), AVW\_CreateIPointList3(), AVW\_CreatePointList2(), AVW\_CreatePointList3(), AVW\_AddPointValue(), AVW\_DestroyPointValueList() AVW\_PointValueList

AVW\_CreateSphericalMTF - converts filter coefficients to spherical frequency filter

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Volume \*AVW\_CreateSphericalMTF(coeffs, out\_vol)

AVW\_FilterCoeffs \*coeffs;

AVW\_Volume \*out\_vol;

**DESCRIPTION** 

AVW\_CreateSphericalMTF() converts filter coefficients coeff into a spherically symmetrical modulation transfer function.

An *AVW\_FilterCoeffs* structure is a list of floating point coefficients describing a one-dimensional frequency domain filter. *AVW\_CreateSphericalMTF()* replicates the coefficients in a spherical pattern within a 3-D volume formatted to match the results of *AVW\_FFT3D()*.

The *out\_vol* will be coeffs->numsamples voxels wide and 2\*(coeffs->numsamples-1) voxels high, and 2\*(coeffs->numsamples-1) voxels deep.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_CreateSphericalMTF()* returns an *AW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_CreateSphericalMTF()* will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**SEE ALSO** 

AVW\_CreateCircularMTF(), AVW\_CreateCoeffs(), AVW\_CreateButterworthCoeffs(), AVW\_CreateGaussianCoeffs() AVW\_CreateStoksethMTF() AVW\_DestroyCoeffs(), AVW\_FilterCoeffs, AVW\_Volume

AVW\_CreateStoksethMTF - creates a Stokseth 2D frequency-space filter

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Image \*AVW\_CreateStoksethMTF(xnum, slice\_no, slice\_thick, numap, pixel\_width, wavelength, refr\_index, focal\_dist, out\_image)

int xnum, slice no:

double slice\_thick, numap, pixel\_width;
double wavelength, refr\_index, focal\_dist;

AVW\_Image \*out\_image;

## **DESCRIPTION**

 $AVW\_CreateStoksethMTF()$  creates a 2D frequency-space filter which corresponds to the modulation transfer function of an optical microscope (see reference below). The filter will be of data type  $AVW\_COMPLEX$  and of dimensions xnum / 2 + 1, xnum.

The input parameter *xnum* refers to the corresponding image dimensions and must be a power of 2.

*Slice\_no* is zero if the filter is to be calculated for the in-focus slice and a positive number if the filter is to be calculated for an out-of-focus slice that many slices above or below the in-focus slice.

The distance between slices is given by *slice\_thick*, measured in microns.

*Numap* is the numerical aperture of the objective lens.

*Pixel\_width* is the distance between adjacent pixels in x and y.

Wavelength is the wavelength of the light being used (in microns).

*Refr* index is the index of refraction of the immersion medium.

*Focal\_dist* is the distance between the objective and the focal plane (in microns).

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_CreateStoksethMTF()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

*AVW\_CreateStoksethMTF()* will fail if the following is true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for return volume or image.

**ILLPAR** 

Illegal Parameter. An invalid value was given for an input parameter.

# REFERENCES

Agard, David A., *Optical Sectioning Microscopy: Cellular Architecture in Three Dimensions* 1984, Annual Review of Biophysics and Bioengineering 13: 191-219.

SEE ALSO | AVW\_DeconvDivideImage(), AVW\_DeconvWienerImage(), AVW\_IterDeconvImage(), AVW\_NearestNeighborDeconv(), AVW\_DestroyCoeffs(), AVW\_FilterCoeffs, AVW\_Volume

 $AVW\_CreateStructuringImage-creates\ a\ structuring\ element\ for\ morphology\ operations$ 

**SYNOPSIS** 

#include "AVW.h"

 $AVW\_Image *AVW\_CreateStructuringImage (type, width, height, out\_image)$ 

int type; int width; int height;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_CreateStructuringImage() creates an AVW\_Image of the specified type, width and height. The generated image can be used as the stucturing element in calls to morphology routines.

Type may be either AVW\_4\_CONNECTED or AVW\_8\_CONNECTED. AVW\_4\_CONNECTED specifies that a 2D cross, i.e. ones on the center row and column of the image, will be generated. AVW\_8\_CONNECTED specifies that a solid rectangle, i.e., ones in the entire image, will be generated.

Width and height specify the x and y dimensions of the structuring element.

The returned image will be of datatype AVW\_UNSIGNED\_CHAR.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_CreateStructuringImage()* returns an *AVW\_Image*. On failure *NULL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

#### **SEE ALSO**

AVW\_CreateStructuringVolume(), AVW\_CreateImage(), AVW\_DestroyImage(), AVW\_ErodeImage(), AVW\_DilateImage(), AVW\_ConditionalDilateImage(), AVW\_MorphCloseImage(), AVW\_MorphOpenImage(), AVW\_MorphMaxImage(), AVW\_MorphMinImage(), AVW\_Image(), AVW\_UltimateErosionImage(), AVW\_Image(), AVW\_Image(),

AVW\_CreateStructuringVolume – creates a structuring element for morphology operastions

## **SYNOPSIS**

#include "AVW.h"

AVW\_Volume \*AVW\_CreateStructuringVolume(type, width, height, depth, out\_volume)

int type;

int width;

int height;

int depth;

AVW\_Volume \*out\_volume;

# **DESCRIPTION**

*AVW\_CreateStructuringVolume()* creates an *AVW\_Volume* of the specified *type, width, height* and *depth.* The generated volume can be used as the stucturing element in calls to morphology routines.

Type may be either AVW\_6\_CONNECTED or AVW\_26\_CONNECTED. AVW\_6\_CONNECTED specifies that a 3D "jack shaped" structuring element will be generated. The structuring element will have ones on the center row and column of the center image of the volume, and ones on the center voxel of every image in the volume. AVW\_26\_CONNECTED specifies that a solid box, i.e.,ones in the entire volume, will be generated.

Width, height and depth specify the x, y, and z dimensions of the structuring element.

The returned volume will be of data type AVW\_UNSIGNED\_CHAR.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful AVW\_CreateStructuringVolume() returns an AVW\_Volume. On failure NULL is returned and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause of the failure.

#### **SEE ALSO**

 $AVW\_CreateStructuringImage(), AVW\_CreateVolume(), AVW\_DestroyVolume(), AVW\_ErodeVolume(), AVW\_DilateVolume(), AVW\_ConditionalDilateVolume(), AVW\_MorphCloseVolume(), AVW\_MorphopenVolume(), AVW\_MorphMaxVolume(), AVW\_MorphMinVolume() AVW\_NonMaxVolume(), AVW\_UltimateErosionVolume(), AVW\_Volume(), AVW\_Volume(),$ 

**NAME** AVW\_CreateTree - initializes an AVW tree structure

**SYNOPSIS** #include "AVW.h"

AVW\_Tree \*AVW\_CreateTree(block\_size)

int block\_size;

**DESCRIPTION** The AVW tree structure is used to store points and related information of skeletal trees.

They are initially allocated to store *block\_size* points and are increased by *block\_size* points

as needed. See AVW\_Tree.h for a definition of the structures.

AVW\_CreateTree() allocates memory for and initializes an AVW\_Tree.

**RETURN VALUES** If successful AVW\_CreateTree() returns an AVW\_Tree.

On failure NULL is returned and AVW\_ErrorNumber and AVW\_ErrorMessage are set to

values corresponding to the cause of the failure.

**ERRORS** *AVW\_CreateTree()* will fail if the following is true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure.

**SEE ALSO** AVW\_AddTreeChild(), AVW\_DestroyTree(), AVW\_FindTreeIndex(), AVW\_LoadTree(),

AVW\_CreateVolume - creates an AVW\_Volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_CreateVolume(mem, width, height, depth, type) void \*mem;

int width, height, depth, type;

**DESCRIPTION** 

AVW\_CreateVolume() creates an AVW\_Volume of the specified size and data type. The Mem element of the AVW\_Volume is set to the address mem.

*Width, height,* and *depth* specify the x, y, and z dimensions in voxels of the requested volume.

Type specifies the AVW data type of the voxels. Acceptable values are: AVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_INT, AVW\_SIGNED\_INT, AVW\_FLOAT, AVW\_COMPLEX, AVW\_COLOR.

*Mem* is the actual memory used to store the voxel data. The *Mem* element of the *AVW\_Volume* is set to this address. The memory pointed at by *mem* must be large enough to accomodate the size and data type of *AVW\_Volume* specified by *width*, *height*, *depth*, and *type*. If *NULL* is provided for *mem* then *AVW\_CreateVolume* allocates memory for the voxel data.

The memory that is allocated by *AVW\_CreateVolume* is contiguous. Voxels in the memory are referenced from *vol->Mem*, *where vol* is the returned *AVE\_Volume*.

Additionally *ZTable* and *YTable* are allocated offset arrays in the structure which enable efficient addressing of individual voxels within the space. These offset arrays are indexed the same as any other C language arrays. This means that the offset to the first image in a volume is *ZTable[0]*. The offset of the last image in a volume is at *ZTable[depth-1]*.

ZTable[] is a table of offset in voxels to each image slice. For example, to reference the start of the 10th image in a floating point AVW\_Volume:

```
address = (float *)vol->Mem + vol->ZTable[9];
```

*YTable[]* is a table of offsets in voxels to each line in the first image of *Mem.* These values can be added to any image start to reference any line from any image in an *AVW\_Volume*.

For example, to reference the first voxel in 10th image and 25th line in an integer *AVW\_Volume*:

```
address = (int *)vol->Mem + vol->ZTable[9] + vol->YTable[24];
```

ZTable and YTable are created even if mem was preallocated and supplied by the user.

**RETURN VALUES** 

If successful *AVW\_CreateVolume()* returns an *AVW\_Volume*. On failure *AVW\_FAIL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_CreateVolume() will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or voxels.

SEE ALSO | AVW\_CreateImage(), AVW\_DestroyVolume(), AVW\_Volume

AVW\_CropImage - automatically crops a border from an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_CropImage(in\_image, out\_image) AVW\_Image \*in\_image, \*out\_image;

**DESCRIPTION** 

AVW\_CropImage() returns a smaller cropped version of in\_image.

The value of the first pixel in the image is used to crop the left and bottom sides of the image. The value of the last pixel in the image is used to crop the top amd right sides of the image. All rows and columns of the image in which each pixel is equal to the test value is removed in the returned. *out\_image*.

If AVW\_CropImage was able to remove bordering pixels and entry in the Info string for the returned <code>out\_image</code> is made with the tag "AVW\_CropImage" followed by a string containing four integers defining the cropped sub region: left column, bottom row, right column, top row. If AVW\_CropImage is unable to remove bordering pixels a copy of <code>in\_image</code> is returned and entry is

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_CropImage()* returns an *AVW\_Image.* On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_CropImage() will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

**SEE ALSO** 

AVW\_GetSubImage(), AVW\_Image()

AVW\_CubeSections - renders intersecting sections

**SYNOPSIS** 

#include "AVW Render.h"

AVW\_RenderedImage \*AVW\_CubeSections(volume, lowx, lowy, lowz, highx, highy, highz, matrix, interpolate\_flag, shading\_fraction,

last\_rendered)

AVW Volume \*volume;

int lowx, lowy, lowz, highx, highy, highz

AVW\_Matrix \*matrix;

int interpolate\_flag;

double shading\_fraction;

AVW\_RenderedImage \*last\_rendered;

## **DESCRIPTION**

*AVW\_CubeSections()* returns an *AVW\_RenderedImage* showing all sides of a cube representing a specified sub-volume.

*Volume* specifies the *AVW\_Volume* the edge sections are extracted from.

Lowx, lowy, lowz, highx, highy, and highz specify the sub-volume to show.

Matrix is used to specify any rotation or scale factors.

The <code>interpolate\_flag</code> specifies if tri-linear interpolations should be used when generating the <code>image</code>. Setting the <code>interpolate\_flag</code> to <code>AVW\_FALSE</code> causes <code>Nearest Neighbor</code> to be used, which is much faster, but lacks some of the quality.

Last\_rendered is provided as a method of reusing an existing AVW\_RenderedImage. Reuse is possible only if the size and data type of the provided last\_rendered meet the requirements of the function. In this case the pointer to last\_rendered is returned by the function. If not reusable last\_rendered will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_CubeSections()* returns an *AVW\_RenderedImage*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_CubeSections() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**ILLPAR** 

Illegal parameter(s).

#### **SEE ALSO**

 $AVW\_Intersecting Sections(), AVW\_Destroy Rendered Image(), AVW\_Rendered Image$ 

NAME | AVW\_CubicSplineInterpolatedPixel – returns pixel value at a floating point location

SYNOPSIS #include "AVW.h"

double AVW\_CubicSplineInterpolatedPixel(image, point)

AVW\_Image \*image; AVW\_FPoint2 \*point;

**DESCRIPTION** Given a floating point location *point* within *image*, *AVW\_CubicSplineInterpolatedPixel()* 

returns the calculated pixel value at the floating point location.

Uses a Cubic Spline algorithm to estimate the pixel value at the floating point location.

Points outside the image will return a value of 0.0.

**SEE ALSO** *AVW\_GetPixel(), AVW\_GetErrorNumner(), AVW\_InterpolatedVoxel(),* 

AVW\_NearestNeighborPixel(), AVW\_InterpolatedPixel(), AVW\_SincInterpolatedPixel(),

AVW\_Image, AVW\_FPoint2

**NAME** AVW\_CubicSplineInterpolatedVoxel – returns voxel value at a floating point location

SYNOPSIS #include "AVW.h"

 $double\ AVW\_Cubic Spline Interpolated Voxel (volume, point)$ 

AVW\_Volume \*volume; AVW\_FPoint3 \*point;

**DESCRIPTION** Given a floating point location *point* within *volume*, *AVW\_CubicSplineInterpolatedVoxel()* 

returns the calculated voxel value at the floating point location.

A Cubic Spline algorithm is used to estimate the voxel value at the floating point location.

Points outside the volume will return a value of 0.0.

**SEE ALSO** *AVW\_GetVoxel(), AVW\_GetErrorNumner(), AVW\_InterpolatedPixel(),* 

 $AVW\_NearestNeighborVoxel(),\ AVW\_InterpolatedVoxel(),\ AVW\_SincInterpolatedVoxel(),$ 

AVW\_FPoint3, AVW\_Volume

**NAME** AVW\_DataTypeToBands – returns number of bands in the specified data type

**SYNOPSIS** #include "AVW.h"

int AVW\_DataTypeToBands(type)

int type;

**DESCRIPTION** | *AVW\_DataTypeToBands()* returns the number of bands in the specified data type.

*Type* is used to specify the AVW data type, acceptable values are:

ÄVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_SHORT, AVW\_UNSIGNED\_INT, AVW\_SIGNED\_INT, AVW\_FLOAT,

AVW\_COMPLEX, AVW\_COLOR.

**RETURN VALUES** If successful AVW\_DataTypeToBands() returns 1 for all data types except AVW\_COLOR,

for which it returns 3. AVW\_FAIL is returned to indicate a illegal input data type.

**SEE ALSO** AVW\_DataTypeToBytes()

AVW\_DataTypeToBytes – computes the number of bytes for a voxel

**SYNOPSIS** 

#include "AVW.h"

int AVW\_DataTypeToBytes(type)

int type;

**DESCRIPTION** 

AVW\_DataTypeToBytes() returns the number of bytes needed for one voxel of any AVW data type. Type is used to specify the AVW data type, acceptable values are: AVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_INT, AVW\_SIGNED\_INT, AVW\_FLOAT, AVW\_COMPLEX, AVW\_COLOR.

**RETURN VALUES** 

If successful *AVW\_DataTypeToBytes()* returns the number of bytes required for one voxel. On failure *AVW\_FAIL (0)* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

The return from this function should be checked, as the meaning of the return value for an unrecognized *type* is not that it requires zero bytes storage.

**ERRORS** 

AVW\_DataTypeToBytes() will fail if:

**ILLDT** 

Illegal data type.

**SEE ALSO** 

AVW\_DataTypeToBands()

AVW\_DecompressWaveletBuffer – returns an AVW\_Image from a wavelet compressed data buffer.

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_DecompressWaveletBuffer(buff) unsigned char \*buff;

**DESCRIPTION** 

*AVW\_DecompressWaveletBuffer()* decompresses buffer produced by *AVW\_WaveletCompressImage*. All the required information concerning the images data type and dimensions are contained in the buffer.

Buff is a memory buffer returned by the function AVW\_WaveletCompressImage().

**RETURN VALUES** 

If successful *AVW\_DecompressWaveletBuffer()* returns a pointer to an *AVW\_Image*. On failure it returns *AVW\_NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_DecompressWaveletBuffer will fail if the buffer is not from AVW\_WaveletCompressImage.

**BADMAL** 

Malloc Failed. A memory allocation failed.

**ILLPAR** 

Illegal parameter. Buffer is not from AVW\_WaveletCompressImage().

**SEE ALSO** 

AVW\_WaveletCompressImage() AVW\_WaveletCompressImageFile() AVW\_WaveletCompressAndDecompressImage(),

REFERENCE

Manduca, A. (1997) "Compressing Images with Wavelet/Subband Coding", IEEE Engineering in Medicine and Biology, 14(5), 639-646.

AVW\_DeconvDivideImage - divides a spectrum by a transfer function

## **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_DeconvDivideImage(spectrum, transfer\_func, fmin, out\_image)

AVW\_Image \*spectrum;

AVW\_Image \*transfer\_func;

double fmin;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_DeconvDivideImage() divides spectrum, which must be of data type AVW\_COMPLEX, by transfer\_func, which must be of data type AVW\_FLOAT or AVW\_COMPLEX. This routine can be used to carry out a simple deconvolution, where spectrum is the Fourier transform of an image and transfer\_func is the Fourier transform of a point spread function. The result, returned in out\_image, will be of data type AVW\_COMPLEX and will be the Fourier transfom of the deconvolved image.

The width of the *spectrum* must be a power of 2 plus 1 and the height must be a power of 2 (since it is the spectrum of an image whose dimensions are all a power of 2 - See  $AVW\_FFT2D()$ ).

If *transfer\_func* is of data type *AVW\_FLOAT*, each item in *transfer\_func* is checked and, if its absolute value is less than *fmin*, the corresponding item in *spectrum* is divided by *fmin* rather than by the item in *transfer\_func*.

If *transfer\_func* is of data type *AVW\_COMPLEX*, each item in *transfer\_func* is checked and, if its magnitude is less than *fmin*, it is scaled to a magnitude of *fmin* before the division. If the item is (0,0), the division is performed by ( *fmin*, 0). The values in *transfer\_func* are not actually altered by this checking.

*Fmin* must be a positive float number and will be ignored and the value .0001 used in its place if it is less than or equal to zero.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_DeconvDivideImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_DeconvDivideImage() will fail if the following is true:

## **ILLDT**

Illegal data type. Spectrum is not AVW\_COMPLEX or transfer\_func is not AVW\_COMPLEX or AVW\_FLOAT.

## **CFLSZ**

Spectrum and transfer\_func are not the same size.

#### **BDSPCT**

Width of spectrum is not a power of 2 plus 1 or height is not a power of two.

**SEE ALSO** 

 $AVW\_DeconvDivideVolume(),\ AVW\_DeconvWienerImage(),\ AVW\_CreateStoksethMTF(),\ AVW\_FFT2D(),\ AVW\_ImageOpImage(),\ AVW\_IterDeconvImage(),\ AVW\_NearestNeighborDeconv(),\ AVW\_Image$ 

AVW\_DeconvDivideVolume - divides a spectrum by a transfer function

## **SYNOPSIS**

#include "AVW.h"

AVW\_Volume \*AVW\_DeconvDivideVolume(spectrum, transfer\_func, fmin, out\_volume)

AVW\_Volume \*spectrum;

AVW\_Volume \*transfer\_func;

double fmin;

AVW\_Volume \*out\_volume;

#### **DESCRIPTION**

AVW\_DeconvDivideVolume() divides spectrum, which must be of data type AVW\_COMPLEX, by transfer\_func, which must be of data type AVW\_FLOAT or AVW\_COMPLEX. This routine can be used to carry out a simple deconvolution, where spectrum is the Fourier transform of a volume and transfer\_func is the Fourier transform of a point spread function. The result, returned in out\_volume, will be of data type AVW\_COMPLEX and will be the Fourier transform of the deconvolved volume.

The width of the *spectrum* must be a power of 2 plus 1 and the height and depth must be a power of 2 (since it is the spectrum of a volume whose dimensions are all a power of 2 - See  $AVW\_FFT3D()$ ).

If *transfer\_func* is of data type *AVW\_FLOAT*, each item in *transfer\_func* is checked and, if its absolute value is less than *fmin*, the corresponding item in *spectrum* is divided by *fmin* rather than by the item in *transfer\_func*.

If *transfer\_func* is of data type *AVW\_COMPLEX*, each item in *transfer\_func* is checked and, if its magnitude is less than *fmin*, it is scaled to a magnitude of *fmin* before the division. If the item is (0,0), the division is performed by ( *fmin*, 0). The values in *transfer\_func* are not actually altered by this checking.

*Fmin* must be a positive float number and will be ignored and the value .0001 used in its place if it is less than or equal to zero.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful *AVW\_DeconvDivideVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_DeconvDivideVolume() will fail if the following is true:

# ILLDT

Illegal data type. Spectrum is not AVW\_COMPLEX or transfer\_func is not AVW\_COMPLEX or AVW\_FLOAT.

## **CFLSZ**

Spectrum and transfer\_func are not the same size.

#### BDSPCT

Width of spectrum is not a power of 2 plus 1 or, height or width is not a power of two.

SEE ALSO | AVW\_DeconvDivideImage(), AVW\_DeconvWienerVolume(), AVW\_FFT3D(), AVW\_IterDeconvVolume(), AVW\_VolumeOpVolume(), AVW\_Volume

AVW\_DeconvWienerImage - performs a Wiener-filtering operation

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_DeconvWienerImage(spectrum, transfer\_func, alpha, out\_image)

AVW\_Image \*spectrum;

AVW\_Image \*transfer\_func;

double alpha;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_DeconvWienerImage() performs a Wiener-filtering operation on *spectrum*, which must be of data type AVW\_COMPLEX, with the filter *transfer\_func*, which must be of data type AVW\_FLOAT or AVW\_COMPLEX.

This routine can be used to carry out Wiener deconvolution, where *spectrum* is the Fourier transform of an image and *transfer\_func* is the Fourier transform of a point spread function. The result, returned in *out\_image*, will be of data type *AVW\_COMPLEX* and will be the Fourier transform of the deconvolved image.

The width of the *spectrum* must be a power of 2 plus 1 and the height must be a power of 2 (since it is the spectrum of an image whose dimensions are all a power of 2 - See *AVW\_FFT2D()*).

If *transfer\_func* is of data type *AVW\_Float*, each item in *spectrum* is multiplied by the quantity:

f / (f\*\*2 + alpha),

where f is the value of the corresponding item in transfer\_func.

If *transfer\_func* is of data type *AVW\_Complex*, each item in *spectrum* is multiplied by the quantity

f' / (|f| \*\*2 + alpha)

where f is the value of the corresponding item in  $transfer\_func$ , f' is the complex conjugate of that item, and |f|\*\*2 is its magnitude squared.

Alpha must be a positive float number and will be ignored and the value .0001 used in its place if it is less than or equal to zero.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_DeconvWienerImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_DeconvWienerImage()* will fail if the following is true:

ILLDT

Illegal data type. Spectrum is not AVW\_COMPLEX or transfer\_func is not AVW\_COMPLEX or AVW\_FLOAT.

**CFLSZ** 

Spectrum and transfer\_func are not the same size.

**BDSPCT** 

Width of spectrum is not a power of 2 plus 1 or height is not a power of two.

**SEE ALSO** 

AVW\_DeconvWienerVolume(), AVW\_DeconvDivideImage(), AVW\_CreateStoksethMTF(), AVW\_FFT2D(), AVW\_ImageOpImage(), AVW\_IterDeconvImage(), AVW\_NearestNeighborDeconv(), AVW\_Image

AVW\_DeconvWienerVolume - performs a Wiener-filtering operation

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_DeconvWienerVolume(spectrum, transfer\_func, alpha, out\_volume)

AVW\_Volume \*spectrum;

AVW\_Volume \*transfer\_func;

double alpha;

AVW\_Volume \*out\_volume;

#### **DESCRIPTION**

*AVW\_DeconvWienerVolume()* performs a Wiener-filtering operation on *spectrum,* which must be of data type *AVW\_COMPLEX,* with the filter *transfer\_func,* which must be of data type *AVW\_FLOAT* or *AVW\_COMPLEX.* 

This routine can be used to carry out Wiener deconvolution, where *spectrum* is the Fourier transform of a volume and *transfer\_func* is the Fourier transform of a point spread function. The result, returned in *out\_volume*, will be of data type *AVW\_COMPLEX* and will be the Fourier transform of the deconvolved volume.

The width of the *spectrum* must be a power of 2 plus 1 and the height and depth must be a power of 2 (since it is the spectrum of a volume whose dimensions are all a power of 2 - See *AVW\_FFT3D()* ).

If *transfer\_func* is of data type *AVW\_Float*, each item in *spectrum* is multiplied by the quantity:

f / (f\*\*2 + alpha),

where f is the value of the corresponding item in transfer\_func.

If *transfer\_func* is of data type *AVW\_Complex*, each item in *spectrum* is multiplied by the quantity

f' / (|f| \*\*2 + alpha)

where f is the value of the corresponding item in *transfer\_func*, f' is the complex conjugate of that item, and |f|\*\*2 is its magnitude squared.

*Alpha* must be a positive float number and will be ignored and the value .0001 used in its place if it is less than or equal to zero.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_DeconvWienerVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_DeconvWienerVolume() will fail if the following is true:

**ILLDT** 

Illegal data type. Spectrum is not AVW\_COMPLEX or transfer\_func is not AVW\_COMPLEX or AVW\_FLOAT.

# **CFLSZ**

Spectrum and transfer\_func are not the same size.

# **BDSPCT**

Width of spectrum is not a power of 2 plus 1 or, height or depth is not a power

**SEE ALSO** 

AVW\_DeconvWienerImage(), AVW\_DeconvDivideVolume(), AVW\_FFT3D(), AVW\_IterDeconvVolume(), AVW\_VolumeOpVolume(), AVW\_Volume()

AVW\_DefineConnected - defines 3D connected regions

**SYNOPSIS** 

#include "AVW\_ObjectMap.h"

int AVW\_DefineConnected(in\_volume, object\_map, seeds, connectivity,

min, max, defined\_object, count)

AVW\_Volume \*in\_volume;

AVW\_ObjectMap \*object\_map;

AVW\_PointList3 \*seeds;

int connectivity;

double min, max;

int defined\_object;

int \*count;

## **DESCRIPTION**

AVW\_DefineConnected() is used to define a 3D connected region from an AVW\_Volume and AVW\_ObjectMap. An AVW\_ObjectMap and threshold limits are used to constrain the 3D region grow. A *count* of defined voxels is returned. Only voxels contained in objects which are turned "on" in the object map will be connected. (See AVW\_Object)

*In\_volume* and *object\_map* specify the *AVW\_Volume* and *AVW\_ObjectMap* which contain the region to be defined.

*Seeds* is a pointer to an *AVW\_PointList3* structure. This structure must contain at least one point which will be used as the starting point(s) for the 3D region grow.

Min and max specifies the threshold limits used to constrain the 3D region grow.

*Defined\_object* specifies the object to which the connected voxels will be assigned.

*Count* contains the number of voxels defined if the function returns successfully. If the function fails count will contain the number at the time of failure.

## **RETURN VALUES**

If successful  $AVW\_DefineConnected()$  returns  $AVW\_SUCCESS$ . On failure it returns  $AVW\_FAIL$  and set the  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

## **ERRORS**

*AVW\_DefineConnected()* will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**ILLPAR** 

Illegal parameter(s).

## **SEE ALSO**

 $AVW\_ConnectAndDeleteVolume(),\ AVW\_ConnectAndKeepVolume(),\ AVW\_FindVolumeComponents(),\ AVW\_ObjectMap,\ AVW\_Object,\ AVW\_Volume,\ AVW\_PointList3$ 

AVW\_DefineUnconnected - defines 3D connected regions

## **SYNOPSIS**

#include "AVW\_ObjectMap.h"

 $int\ AVW\_Define Unconnected (in\_volume,\ object\_map,\ seeds,\ connectivity,$ 

min, max, defined\_object, count)

AVW\_Volume \*in\_volume;

AVW\_ObjectMap \*object\_map;

AVW\_PointList3 \*seeds;

int connectivity;

double min, max;

int defined\_object;

int \*count;

## **DESCRIPTION**

AVW\_DefineUnconnected() is used to define a 3D connected region from an AVW\_Volume and AVW\_ObjectMap.

All voxels which within the threhold range and are turned "on" in the object map, and are NOT connected to the seeds, are defined.

An *AVW\_ObjectMap* and threshold limits are used to constrain the 3D region grow. A *count* of defined voxels is returned. Only voxels contained in objects which are turned "on" in the object map will be connected. (See *AVW\_Object*)

*In\_volume* and *object\_map* specify the *AVW\_Volume* and *AVW\_ObjectMap* which contain the region to be defined.

*Seeds* is a pointer to an *AVW\_PointList3* structure. This structure must contain at least one point which will be used as the starting point(s) for the 3D region grow.

Min and max specifies the threshold limits used to constrain the 3D region grow.

*Defined\_object* specifies the object to which the connected voxels will be assigned.

*Count* contains the number of voxels defined if the function returns successfully. If the function fails count will contain the number at the time of failure.

#### **RETURN VALUES**

If successful *AVW\_DefineUnconnected()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and set the *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_DefineUnconnected() will fail if one or more of the following is true:

BADMAL

Unable to allocate sufficient memory.

**ILLPAR** 

Illegal parameter(s).

# **SEE ALSO**

 $AVW\_DefineConnected(),\ AVW\_ConnectAndDeleteVolume(),\\ AVW\_ConnectAndKeepVolume(),\ AVW\_FindVolumeComponents(),\ AVW\_ObjectMap,\\ AVW\_Object,\ AVW\_Volume,\ AVW\_PointList3$ 

AVW\_DeleteObject - deletes an object from an object map

**SYNOPSIS** 

#include "AVW\_ObjectMap.h"

int AVW\_DeleteObject(object\_map, object)

AVW\_ObjectMap \*object\_map;

int object;

**DESCRIPTION** 

AVW\_DeleteObject() removes the AVW\_Object specified by object from object\_map. Each

 $AVW\_Object$  with a value greater than object will be reduced by 1.

**RETURN VALUES** 

If successful *AVW\_DeleteObject()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_DeleteObject() will fail if the following is true:

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_AddObject(), AVW\_DestroyObjectMap(), AVW\_CreateObjectMap(), AVW\_GetObject(), AVW\_PutObject() AVW\_LoadObjectMap(), AVW\_SaveObjectMap(),

AVW\_RemoveUnusedObjects(), AVW\_RenderVolume(), AVW\_ObjectMap, AVW\_Object

**NAME** AVW\_DestroyCoeffs – frees filter coefficient structure memory

**SYNOPSIS** #include "AVW\_Filter.h"

void AVW\_DestroyCoeffs(coeffs)
AVW\_FilterCoeffs \*coeffs;

# **DESCRIPTION**

*AVW\_DestroyCoeffs()* destroys a list of filter coefficients and frees the memory associated with it.

Note that *AVW\_DestroyCoeffs()* does not set the passed pointer to *NULL*. It is important that this pointer be set to *NULL* before it is used again. For example:

AVW\_DestroyCoeffs(coeffs); coeffs = NULL;

Alternatively, the macro *AVW\_DESTROYCOEFFS()* defined in *AVW\_Filter.h* which automatically sets the pointer to *NULL* after freeing the memory may be used.

# **SEE ALSO**

AVW\_CreateCoeffs(), AVW\_CreateButterworthCoeffs(), AVW\_CreateGaussianCoeffs(), AVW\_DESTROYCOEFFS(), AVW\_FilterCoeffs,

AVW\_DestroyColormap - frees colormap structure memory

**SYNOPSIS** 

#include "AVW.h"

 $void\ AVW\_DestroyColormap(colormap)$ 

AVW\_Colormap \*colormap;

**DESCRIPTION** 

AVW\_DestroyColormap() deallocates the memory associated with an AVW\_Colormap.

An *AVW\_Colormap* is a member of the *AVW\_Image*, *AVW\_Volume* and *AVW\_ImageFile* structures and defines how intensity values are mapped to colors.

Note that  $AVW\_DestroyColormap()$  does not set the passed pointer to NULL. Since the  $AVW\_Colormap$  will usually be part of another AVW structure it is important to set this pointer to NULL after destroying it. For example:

AVW\_DestroyColormap(img->Colormap); img->Colormap = NULL;

Alternatively, the macro *AVW\_DESTROYCOLORMAP()* defined in *AVW.h* which automatically sets the pointer to *NULL* after freeing the memory may be used.

**SEE ALSO** 

 $AVW\_CreateColormap(),\ AVW\_CopyColormap(),\ AVW\_DESTROYCOLORMAP(),\ AVW\_Colormap$ 

**NAME** AVW\_DestroyCompositeInfo – frees composite info structure memory

SYNOPSIS #include "AVW\_CompositeInfo.h"

void AVW\_DestroyCompositeInfo(cinfo)

AVW\_CompositeInfo \*cinfo;

**DESCRIPTION** *AVW\_DestroyCompositeInfo()* frees all memory associated with *cinfo*.

Cinfo must be set to NULL after calling this function before it is used again.

**SEE ALSO** | AVW\_CreateCompositeInfo(), AVW\_LoadCompositeInfo(), AVW\_SaveCompositeInfo(),

**NAME** AVW\_DestroyContourSurface – frees ContourSurface structure memory

SYNOPSIS #include "AVW\_Model.h"

 $int\ AVW\_DestroyContourSurface (contourSurface)$ 

 $AVW\_ContourSurface *contourSurface;$ 

**DESCRIPTION** *AVW\_ContourSurface()* destroys the memory allocated to the elements in *contourSurface*.

**RETURN VALUES** AVW\_ContourSurface() returns AVW\_SUCCESS if successful. On failure, AVW\_FAIL will

be returned and I AVW\_ErrorNumber and AVW\_ErrorMessage will be set to values

corresponding to the cause of the failure.

**SEE ALSO** | AVW\_SliceVolume(), AVW\_SaveContourSurface(), AVW\_ContourSurface

NAME | AVW\_DestroyFPointList2 – frees list structure memory

SYNOPSIS #include "AVW.h"

void AVW\_DestroyFPointList2(trace)
AVW\_FPointList2 \*trace;

DESCRIPTION

 $AVW\_DestroyFPointList2()$  frees memory associated with an  $AVW\_FPointList2$  structure and the structure itself.

The list structures are managed i.e., memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

*Trace* must be set to *NULL* after calling this function before it is used again. Alternatively, the macro *AVW\_DESTROYFPOINTLIST2(trace)*, defined in *AVW.h* may be used to free the memory and set the pointer to *NULL*.

**SEE ALSO** 

AVW\_DestroyFPointList3(), AVW\_DestroyIPointList2(), AVW\_DestroyIPointList3(), AVW\_DestroyPointList2(), AVW\_DestroyPointList3(), AVW\_DestroyPointValueList(), AVW\_CreateFPointList2(), AVW\_AddFPoint2(), AVW\_AddFPoint3(), AVW\_AddPoint2(), AVW\_AddPointValue(), AVW\_DESTROYFPOINTLIST2(), AVW\_FPointList2

AVW\_DestroyFPointList3 – frees list structure memory

**SYNOPSIS** 

#include "AVW.h"

void AVW\_DestroyFPointList3(trace)
AVW\_FPointList3 \*trace;

**DESCRIPTION** 

*AVW\_DestroyFPointList3()* frees memory associated with an *AVW\_FPointList3* structure and the structure itself.

The list structures are managed i.e., memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

*Trace* must be set to *NULL* after calling this function before it is used again. Alternatively, the macro *AVW\_DESTROYFPOINTLIST3(trace)*, defined in *AVW.h* may be used to free the memory and set the pointer to *NULL*.

**SEE ALSO** 

 $AVW\_DestroyFPointList2(),\ AVW\_DestroyIPointList2(),\ AVW\_DestroyIPointList3(),\ AVW\_DestroyPointList2(),\ AVW\_DestroyPointList3(),\ AVW\_DestroyPointValueList(),\ AVW\_CreateFPointList3(),\ AVW\_AddFPoint3(),\ AVW\_DESTROYFPOINTLIST3(),\ AVW\_FPointList3$ 

NAME AVW\_DestroyGradients – frees gradient structure memory

SYNOPSIS #include "AVW\_Render.h"

 $void\ AVW\_DestroyGradients(surface)$ 

AVW\_Gradients \*surface;

**DESCRIPTION** | *AVW\_DestroyGradients()* is called to free *surface* and all its associated memory.

surface must be set to NULL after calling this function before it is used again.

**SEE ALSO** *AVW\_ExtractGradients(), AVW\_RenderGradients(), AVW\_Gradients* 

AVW\_DestroyHistogram - frees histogram structure memory

**SYNOPSIS** 

#include "AVW\_Histogram.h"

void AVW\_DestroyHistogram(histo)
AVW\_Histogram \*histo;

## **DESCRIPTION**

AVW\_DestroyHistogram() is called to free histo and all its associated memory.

*Histo* must be set to *NULL* after calling this function before it is used again. Alternatively, the macro *AVW\_DESTROYHISTOGRAM(histo)*, defined in *AVW\_Histogram.h* may be used to free the memory and set the pointer to *NULL*.

This function will also free the *Mem* element of the *AVW\_Histogram*. If you do not wish to free the memory set the *Mem* element to *NULL* before calling the function:

... pointer = histo->Mem; histo->Mem = NULL; AVW\_DestroyHistogram(histo); ...

Note that *AVW\_DestroyHistogram()* does not set the passed pointer to *NULL*. It is important to set this pointer to *NULL* after destroying it before using it again. For example:

AVW\_DestroyHistogram(histo); histo = NULL;

Alternatively, the macro *AVW\_DESTROYHISTOGRAM()* defined in *AVW\_Histogram.h* which automatically sets the pointer to *NULL* after freeing the memory and structure may be used.

# **SEE ALSO**

AVW\_ClearHistogram(), AVW\_CreateHistogram(), AVW\_FlattenVolumeHistogram(), AVW\_GetImageHistogram(), AVW\_GetVolumeHistogram(), AVW\_MatchImageHistogram(), AVW\_MatchVolumeHistogram(), AVW\_NormalizeHistogram(), AVW\_PreserveImageHistogram(), AVW\_PreserveVolumeHistogram(), AVW\_VerifyHistogram(), AVW\_DESTROYHISTOGRAM(), AVW\_Histogram

**NAME** AVW\_DestroyIPointList2 – frees list structure memory

SYNOPSIS #include "AVW.h"

void AVW\_DestroyIPointList2(trace)
AVW\_IPointList2 \*trace;

DESCRIPTION

 $AVW\_DestroyIPointList2() \ frees \ memory \ associated \ with \ an \ AVW\_IPointList2 \ structure \ and \ the \ structure \ itself.$ 

The list structures are managed i.e., memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

*Trace* must be set to *NULL* after calling this function before it is used again. Alternatively, the macro *AVW\_DESTROYIPOINTLIST2(trace)*, defined in *AVW.h* may be used to free the memory and set the pointer to *NULL*.

**SEE ALSO** 

 $AVW\_DestroyIPointList3(),\ AVW\_DestroyFPointList2(),\ AVW\_DestroyFPointList3(),\ AVW\_DestroyPointList2(),\ AVW\_DestroyPointList3(),\ AVW\_DestroyPointValueList(),\ AVW\_CreateIPointList2(),\ AVW\_AddIPoint2(),\ AVW\_DESTROYIPOINTLIST2(),\ AVW\_IPointList2$ 

AVW\_DestroyIPointList3 - frees list structure memory

**SYNOPSIS** 

#include "AVW.h"

void AVW\_DestroyIPointList3(trace)
AVW\_IPointList3 \*trace;

**DESCRIPTION** 

 $AVW\_DestroyIPointList3() \ frees \ memory \ associated \ with an \ AVW\_IPointList3 \ structure \ and \ the \ structure \ itself.$ 

The list structures are managed i.e., memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

*Trace* must be set to *NULL* after calling this function before it is used again. Alternatively, the macro *AVW\_DESTROYIPOINTLIST3(trace)*, defined in *AVW.h* may be used to free the memory and set the pointer to *NULL*.

**SEE ALSO** 

 $AVW\_DestroyIPointList2(),\ AVW\_DestroyFPointList2(),\ AVW\_DestroyFPointList3(),\ AVW\_DestroyPointList2(),\ AVW\_DestroyPointList3(),\ AVW\_DestroyPointValueList(),\ AVW\_CreateIPointList3(),\ AVW\_AddIPoint3(),\ AVW\_DESTROYIPOINTLIST3(),\ AVW\_IPointList3$ 

**NAME** AVW\_DestroyImage – frees image structure memory

SYNOPSIS #include "AVW.h"

void AVW\_DestroyImage(image)
AVW\_Image \*image;

# **DESCRIPTION**

AVW\_DestroyImage() is called to free image and all its associated memory.

*Image* must be set to *NULL* after calling this function before it is used again. Alternatively, the macro *AVW\_DESTROYIMAGE(image)*, defined in *AVW.h* may be used to free the memory and set the pointer to *NULL*.

These function will also free the *Mem* element of the *AVW\_Image*. If you do not wish to free *Mem*, set the *Mem* element to *NULL* before calling the functions.

pointer = image->Mem; image->Mem = NULL; AVW\_DestroyImage(image);

### **SEE ALSO**

AVW\_DestroyVolume(), AVW\_CreateImage(), AVW\_CreateVolume(), AVW\_DESTROYIMAGE(), AVW\_Image

**NAME** AVW\_DestroyInstructions – frees instructions structure memory

**SYNOPSIS** #include "AVW\_Parse.h"

 $void\ AVW\_DestroyInstructions (instructions)$ 

AVW\_Instructions \*instructions;

**DESCRIPTION** *AVW\_DestroyInstructions()* frees all memory associated with *instructions*.

*Instructions* must be set to *NULL* after calling this function before it is used again.

**SEE ALSO** | AVW\_Parse(), AVW\_DoInstructions(), AVW\_Instructions

**NAME** AVW\_DestroyList –frees list structure memory

SYNOPSIS #include "AVW.h"

void AVW\_DestroyList(list)

AVW\_List \*list;

**DESCRIPTION** | *AVW\_DestroyList()* frees memory used for an *AVW\_List*.

*List* must be set to *NULL* after calling this function before it is used again. Alternatively, the macro *AVW\_DESTROYLIST(list)*, defined in *AVW.h* may be used to free the memory

and set the pointer to NULL.

SEE ALSO AVW\_ListFormats(), AVW\_ListInfo(), AVW\_DESTROYLIST(), AVW\_List

**NAME** AVW\_DestroyMatchVoxelParams – frees the AVW\_MatchVoxelParams structure memory

SYNOPSIS #include "AVW\_MatchVoxels.h"

void AVW\_DestroyMatchVoxelParams(param)

AVW\_MatchVoxelParams \*param;

**DESCRIPTION** AVW\_DestroyMatchVoxelParams() destroys the memory allocated to the match voxel

parameters given in param.

**SEE ALSO** *AVW\_MatchVoxels(), AVW\_MatchVoxelsParams, AVW\_InitializeMatchVoxelParams().* 

**NAME** AVW\_DestroyMatrix – frees matrix structure memory

**SYNOPSIS** #include "AVW.h"

void AVW\_DestroyMatrix(matrix)

AVW\_Matrix \*matrix;

**DESCRIPTION** AVW\_DestroyMatrix() is called to free matrix and all its associated memory.

Matrix must be set to NULL after calling this function before it is used again.

**SEE ALSO** AVW\_CreateMatrix(), AVW\_Matrix **NAME** AVW\_DestroyMergedMap - frees merged info structure memory

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**SYNOPSIS** #include "AVW\_MergedMap.h"

void AVW\_DestroyMergedMap(merged\_map)

AVW\_MergedMap \*merged\_map;

**DESCRIPTION** AVW\_DestroyMergedMap() frees all memory associated with merged\_map.

*Merged\_info* must be set to *NULL* after calling this function before it is used again.

 $AVW\_MergeRendered(),\ AVW\_MergedMap$ **SEE ALSO** 

**NAME** AVW\_DestroyMultiList2 – frees multilist structure memory

SYNOPSIS #include "AVW.h"

void AVW\_DestroyMultiList2(mlst)

AVW\_MultiList2 \*mlst;

**DESCRIPTION** AVW\_DestroyMultiList2() frees memory associated with an AVW\_MultiList2 structure and the structure itself.

The list structures are managed i.e., memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

*Mlst* must be set to *NULL* after calling this function before it is used again. *AVW\_DestroyPointList2()*, *AVW\_MultiList2*, *AVW\_PointList2* 

**NAME** AVW\_DestroyObjectMap – frees object map structure memory

**SYNOPSIS** #include "AVW\_ObjectMap.h"

 $void\ AVW\_DestroyObjectMap(object\_map)$ 

AVW\_ObjectMap \*object\_map;

**DESCRIPTION** *AVW\_DestroyObjectMap()* frees all memory associated with *object\_map*.

Object\_map must be set to NULL after calling this function before it is used again.

SEE ALSO | AVW\_AddObject(), AVW\_DeleteObject(), AVW\_CreateObjectMap(), AVW\_LoadObjectMap(),

AVW\_SaveObjectMap(), AVW\_RemoveUnusedObjects(), AVW\_RenderVolume(),

AVW\_ObjectMap

NAME | AVW\_DestroyPointList2 – frees list structure memory

SYNOPSIS #include "AVW.h"

 $void\ AVW\_DestroyPointList2(trace)$ 

AVW\_PointList2 \*trace;

**DESCRIPTION** AVW\_DestroyPointList2() frees memory associated with an AVW\_PointList2 structure and the structure itself.

The list structures are managed i.e., memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

*Trace* must be set to *NULL* after calling this function before it is used again. Alternatively, the macro *AVW\_DESTROYPOINTLIST2(trace)*, defined in *AVW.h* may be used to free the memory and set the pointer to *NULL*.

SEE ALSO AVW\_DestroyFPointList2(), AVW\_DestroyFPointList3(), AVW\_DestroyIPointList2(), AVW\_DestroyIPointList3(), AVW\_DestroyPointList3(), AVW\_DestroyPointValueList(),

AVW\_CreatePointList2(), AVW\_AddPoint2(), AVW\_DESTROYPOINTLIST2(),

AVW\_PointList3, AVW\_Point3

**NAME** AVW\_DestroyPointList3 – frees list structure memory

SYNOPSIS #include "AVW.h"

void AVW\_DestroyPointList3(trace)

AVW\_PointList3 \*trace;

**DESCRIPTION** AVW\_DestroyPointList3() frees memory associated with an AVW\_PointList3 structure and the structure itself.

The list structures are managed i.e., memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

*Trace* must be set to *NULL* after calling this function before it is used again. Alternatively, the macro *AVW\_DESTROYPOINTLIST3(trace)*, defined in *AVW.h* may be used to free the memory and set the pointer to *NULL*.

**SEE ALSO** | *AVW\_DestroyFPointList2(), AVW\_DestroyFPointList3(), AVW\_DestroyIPointList2(),* 

 $AVW\_Destroy IPointList 3 (), \ AVW\_Destroy PointList 2 (), \ AVW\_Destroy Point Value List (), \ AVW\_Destroy IPoint Value List (), \ AVW\_$ 

AVW\_CreatePointList3(), AVW\_AddPoint3(), AVW\_DESTROYPOINTLIST3(),

AVW\_PointList3, AVW\_Point3

**NAME** AVW\_DestroyPointValueList – frees list structure memory

SYNOPSIS #include "AVW.h"

void AVW\_DestroyPointValueList(trace)

AVW\_PointValueList \*trace;

**DESCRIPTION** AVW\_DestroyPointValueList() frees memory associated with an AVW\_PointValueList structure and the structure itself.

The list structures are managed i.e., memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

*Trace* must be set to *NULL* after calling this function before it is used again. Alternatively, the macro *AVW\_DESTROYPOINTVALUELIST(trace)*, defined in *AVW.h* may be used to free the memory and set the pointer to *NULL*.

SEE ALSO AVW\_DestroyFPointList2(), AVW\_DestroyFPointList3(), AVW\_DestroyIPointList2(), AVW\_DestroyIPointList3(), AVW\_DestroyPointList2(), AVW\_DestroyPointList3(), AVW\_CreatePointValueList(), AVW\_AddPointValue(), AVW\_DESTROYPOINTVALUELIST(), AVW\_PointValueList, AVW\_Point

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**NAME** AVW\_DestroyRPParam – frees tile parameter structure memory

SYNOPSIS #include "AVW\_Model.h"

int AVW\_DestroyRPParam(rp\_param)

AVW\_RPParam \*rp\_param;

**DESCRIPTION** | AVW\_DestroyRPParam() destroys the memory allocated to the tiling parameters given in

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tile\_param.

**RETURN VALUES** | AVW\_DestroyRPParam() returns AVW\_SUCCESS if successful. On failure, AVW\_FAIL

will be returned and I AVW\_ErrorNumber and AVW\_ErrorMessage will be set to values

corresponding to the cause of the failure.

**SEE ALSO** | AVW\_SliceVolume(), AVW\_InitializeRPParam(), AVW\_RPParam

NAME | AVW\_DestroyRenderParameters – frees rendering structure memory

SYNOPSIS #include "AVW\_Render.h"

 $void\ AVW\_DestroyRenderParameters (render\_param)$ 

 $AVW\_Render Parameters * render\_param;$ 

**DESCRIPTION** AVW\_DestroyRenderParameters() is called to free render\_param and all its associated

memory.

Render\_param must be set to NULL after calling this function before it is used again. Alternatively, the macro AVW\_DESTROYRENDERPARAMETERS(render\_param), defined in

AVW.h may be used to free the memory and set the pointer to NULL.

**SEE ALSO** AVW\_DestroyRenderedImage(), AVW\_InitializeRenderParameters(), AVW\_RenderVolume(),

AVW\_DESTROYRENDERPARAMETERS(), AVW\_RenderParameters

**NAME** AVW\_DestroyRenderedImage – frees rendered image structure memory

SYNOPSIS #include "AVW\_Render.h"

void AVW\_DestroyRenderedImage(image) AVW\_RenderedImage \*rendered\_image;

**DESCRIPTION** AVW\_DestroyRenderedImage() is called to free rendered\_image and all its associated

memory.

Rendered\_image must be set to *NULL* after calling this function before it is used again. Alternatively, the macro *AVW\_DESTROYRENDEREDIMAGE*(rendered\_image), defined in *AVW\_Render.h* may be used to free the memory and set the pointer to *NULL*.

SEE ALSO AVW\_DestroyRenderParameters(), AVW\_InitializeRenderParameters(),

AVW\_RenderVolume(), AVW\_DESTROYRENDEREDIMAGE(), AVW\_RenderedImage

**NAME** AVW\_DestroyTileParameters – frees tile parameter structure memory

SYNOPSIS #include "AVW\_Model.h"

int AVW\_DestroyTileParameters(tile\_param)

AVW\_TileParameters \*tile\_param;

**DESCRIPTION** AVW\_DestroyTileParameters() destroys the memory allocated to the tiling parameters

given in tile\_param.

**RETURN VALUES** | *AVW\_DestroyTileParameters()* returns *AVW\_SUCCESS* if successful. On failure,

AVW\_FAIL will be returned and I AVW\_ErrorNumber and AVW\_ErrorMessage will be

set to values corresponding to the cause of the failure.

**SEE ALSO** AVW\_LoadTiledSurface(), AVW\_SaveTiledSurface(), AVW\_DrawTiledSurface(),

AVW\_TileVolume(), AVW\_TiledSurface

NAME | AVW\_DestroyTiledSurface – frees ordered surface structure memory

SYNOPSIS #include "AVW\_Model.h"

int AVW\_DestroyTiledSurface(srfc)

AVW\_TiledSurface \*srfc;

**DESCRIPTION** AVW\_DestroyTiledSurface() destroys the memory allocated to the ordered surface given in

srfc.

**RETURN VALUES** AVW\_DestroyTiledSurface() returns AVW\_SUCCESS if successful. On failure, AVW\_FAIL

will be returned and I AVW\_ErrorNumber and AVW\_ErrorMessage will be set to values

corresponding to the cause of the failure.

**SEE ALSO** AVW\_LoadTiledSurface(), AVW\_SaveTiledSurface(), AVW\_DrawTiledSurface(),

AVW\_TileVolume(), AVW\_TiledSurface

**NAME** AVW\_DestroyTree – frees tree structure memory

SYNOPSIS #include "AVW\_Tree.h"

 $void\ AVW\_DestroyTree(tree)$ 

AVW\_Tree \*trace;

**DESCRIPTION** AVW\_DestroyTree() frees memory associated with an AVW\_Tree structure and the structure a

ture itself.

The list structures are managed i.e., memory for the structures is reallocated as needed. These structures are defined in  $AVW\_Tree.h$  and are used to store skeletal tree informa-

tion.

Tree must be set to NULL after calling this function before it is used again.

SEE ALSO | AVW\_AddTreeChild(), AVW\_CreateTree(), AVW\_FindTreeIndex(), AVW\_LoadTree(),

AVW\_SaveTree(), AVW\_TreePoint, AVW\_Tree

**NAME** AVW\_DestroyVisibleSurface – frees visible surface structure memory

**SYNOPSIS** #include "AVW\_Render.h"

void AVW\_DestroyVisibleSurface(surface)

AVW\_VisibleSurface \*surface;

**DESCRIPTION** | *AVW\_DestroyVisibleSurface()* is called to free *surface* and all its associated memory.

surface must be set to NULL after calling this function before it is used again.

**SEE ALSO** AVW\_ExtractVisibleSurface(), AVW\_RenderVisibleSurface(), AVW\_ExtractSurface(),

AVW\_VisibleSurface

**NAME** AVW\_DestroyVolume – frees volume structure memory

SYNOPSIS #include "AVW.h"

void AVW\_DestroyVolume(volume)
AVW\_Volume \*volume;

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**DESCRIPTION** | *AVW\_DestroyVolume()* is called to free *volume* and all its associated memory.

*Volume* must be set to *NULL* after calling this function before it is used again. Alternatively, the macro *AVW\_DESTROYVOLUME(volume)*, defined in *AVW.h* may be used to free the memory and set the pointer to *NULL*.

These function will also free the *Mem* element of the *AVW\_Image* or *AVW\_Volume*. If you do not wish to free *Mem*, set the *Mem* element to *NULL* before calling the functions.

pointer = volume->Mem; volume->Mem = NULL; AVW\_DestroyVolume(volume);

SEE ALSO | AVW\_DestroyImage(), AVW\_CreateVolume(), AVW\_DESTROYVOLUME(), AVW\_Volume

AVW\_DilateImage- morphologically dilates an image

# **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_DilateImage(in\_image, element, out\_image)

AVW\_Image \*in\_image;

AVW\_Image \*element;

AVW\_Image \*out\_image;

### **DESCRIPTION**

*AVW\_DilateImage()* performs binary morphological dilation on *in\_image* using *element* as the structuring element.

In\_image does not have to be a binary valued but all nonzero voxels are treated as ones. In\_image, out\_image, and element must be of the data type AVW\_UNSIGNED\_CHAR. This function will allocate temporary storage space for results if in\_image and out\_image are the same.

The dilation can be thought of as an enlargement of the binary objects contained in the data. In simplest terms the dilation process takes place by translating the structuring element so that its centerpoint lies on every point of the data. At each point in the data, if a nonzero pixel in the structuring element corresponds to a nonzero pixel in the data the point in the result data is set to one. Otherwise the data is unchanged. The result data will only contain ones and zeros.

AVW\_CreateStructuringImage(), AVW\_CreateImage(), AVW\_SetImage(), and AVW\_PutPixel() may be used to create a structuring element. The structuring element is flipped on the X and Y axes prior to dilation.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful *AVW\_DilateImage()* returns an *AVW\_Image.* On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_DilateImage() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

**ILLDT** 

Data type is not defined or supported.

**ILLIMG** 

An illegal image was passed to the function.

#### **SEE ALSO**

AVW\_DilateVolume(), AVW\_CreateImage(), AVW\_MorphCloseImage(), AVW\_ErodeImage(), AVW\_MorphOpenImage(), AVW\_ConditionalDilateImage(), AVW\_MorphMaxImage(), AVW\_PutPixel(), AVW\_CreateStructuringImage(), AVW\_Image

AVW\_DilateVolume - morphologically dilates a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_DilateVolume(in\_volume, element, out\_volume)

 $AVW\_Volume * in\_volume;$ 

AVW\_Volume \*element;

AVW Volume \*out volume:

# **DESCRIPTION**

AVW\_DilateVolume() performs binary morphological dilation on in\_volume using element as the structuring element.

In\_volume does not have to be a binary valued but all nonzero voxels are treated as ones.
In\_volume, out\_volume, and element must be of the data type AVW\_UNSIGNED\_CHAR.
This function will allocate temporary storage space for results if in\_volume and out\_volume are the same.

The dilation can be thought of as an enlargement of the binary objects contained in the data. In simplest terms the dilation process takes place by translating the structuring element so that its centerpoint lies on every point of the data. At each point in the data, if a nonzero voxel in the structuring element corresponds to a nonzero voxel in the data the point in the result data is set to one. Otherwise the data is unchanged. The result data will only contain ones and zeros.

AVW\_CreateStructuringVolume(), AVW\_CreateVolume(), AVW\_SetVolume(), and AVW\_PutVoxel() may be used to create a structuring element. The structuring element is flipped on the X, Y and Z axes prior to dilation and unflipped afterwards within the routine.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_DilateVolume()* returns an *AVW\_Volume.* On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_DilateVolume() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

**ILLDT** 

Data type is not defined or supported.

**ILLVOL** 

An illegal volume was passed to the function.

#### **SEE ALSO**

AVW\_CreateStructuringVolume(), AVW\_DilateImage(), AVW\_CreateVolume(), AVW\_MorphCloseVolume(), AVW\_ErodeVolume(), AVW\_MorphOpenVolume(), AVW\_ConditionalDilateVolume(), AVW\_MorphMaxVolume(), AVW\_MorphMinVolume(), AVW\_SetVolume(), AVW\_PutVoxel(), AVW\_Volume

AVW\_DisableImageFileFormat – disables I/O support for an image file format

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW.h"

#include "AVW\_ImageFile.h"

 $int\ AVW\_Disable Image File Format (file format)$ 

char \*fileformat;

**DESCRIPTION** 

AVW\_DisableImageFileFormat() disables support of a named image file format.

*Fileformat* is the name by which the file format is identified in AVW and is the Description element of the AVW\_ExtendIO structure with which the format was extend.

The Properties element of the AVW\_ExtendIO structure for this format is set to 0, indicating that no data types or operations are supported. The *AVW\_ExtendIO* entry for this format remains in the list of extended file formats but is marked as disabled. This *fileformat* string identifier may not be used to identify another format with a user extended call to *AVW\_ExtendImageFile()*.

**RETURN VALUES** 

*AVW\_DisableImageFileFormat()* returns the value of the Properties element of the AVW\_EntendIO structure which indicates the properties supported in the format.

This value can be used as an argument with *AVW\_EnableImageFileFormat()* at a later time to re-enable the image file format.

**SEE ALSO** 

AVW\_ExtendExternalLibs(), AVW\_EnableImageFileFormat(), AVW\_CreateImageFile(), AVW\_CloseImageFile(), AVW\_FormatSupports(), AVW\_ListFormats(), AVW\_OpenImageFile(), AVW\_ReadImageFile(), AVW\_ReadVolume(), AVW\_SeekImageFile(), AVW\_WriteImageFile(), AVW\_WriteVolume() AVW\_ExtendIO

NAME AVW\_DisableProgress – temporarily disables progress

SYNOPSIS #include "AVW.h"

void AVW\_DisableProgress()

**DESCRIPTION** | AVW\_DisableProgress() is called to temporarily disable all calls made using

*AVW\_Progress()* to the function specified by *AVW\_ProgressFunction()*. This is normally done within functions which report progress, but call other *AVW* functions which report

progress.

SEE ALSO AVW\_Progress(), AVW\_ProgressFunction(), AVW\_EnableProgress()

AVW\_DitherImage - dithers an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_DitherImage(in\_image, ncolors, out\_image)

AVW\_Image \*in\_image;

int ncolors;

AVW\_Image \*out\_image;

**DESCRIPTION** 

*AVW\_DitherImage()* converts a 24-bit *AVW\_Image*, *in\_image*, to an 8-bit *AVW\_Image* with an associated colormap. The Colormap is an element of the returned AVW\_Image.

*Ncolors* is the number of colors to which *out\_image* will be reduced.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_DitherImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_DitherImage()* will fail if:

**ILLDT** 

Illegal Datatype. In\_image must be of type AVW\_COLOR.

**SEE ALSO** 

AVW\_DitherVolume(), AVW\_ConvertImage(), AVW\_MakeGrayImage(), AVW\_MakeMonoImage(), AVW\_Image, AVW\_Colormap

**NAME** AVW\_DitherVolume – dithers a volume

SYNOPSIS #include "AVW.h"

AVW\_Volume \*AVW\_DitherVolume(in\_volume, ncolors, out\_volume)

AVW\_Volume \*in\_volume;

int ncolors;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

 $AVW\_DitherVolume()$  converts a 24-bit  $AVW\_Volume$ , in\_volume, to an 8-bit  $AVW\_Volume$  with an associated colormap. The conversion is done in 2D. The Colormap is and element of the return  $AVW\_Volume$ .

*Ncolors* is the number of colors to which *out\_volume* will be reduced.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_DitherVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_DitherVolume() will fail if:

**ILLDT** 

Illegal Datatype. In\_volume must be of type AVW\_COLOR.

**SEE ALSO** 

AVW\_ConvertVolume(), AVW\_MakeGrayVolume(), AVW\_Colormap

**NAME** AVW\_DoInstructions – evaluates an algebraic-style formula

**SYNOPSIS** | #include "AVW\_Parse.h"

int AVW\_DoInstructions(instructions) AVW\_Instructions \*instructions;

**DESCRIPTION** | *AVW\_DoInstructions()* executes the information stored in *instructions*.

RETURN VALUES

If successful, AVW\_DoInstructions() returns AVW\_SUCCESS. On failure, it returns

AVW\_FAIL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding

to the cause of the failure.

**ERRORS** | *AVW\_DoInstructions()* will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**BADOP** 

Unknown Instruction.

**SYNTAX** 

Syntax Error In Formula.

**TCMPLX** 

Formula Too Complex To Be Parsed.

**SEE ALSO** | AVW\_Parse(), AVW\_DestroyInstructions(), AVW\_Instructions

**NAME** AVW\_DrawFilledPointList2 – draws a filled trace into an image

SYNOPSIS #include "AVW.h"

int AVW\_DrawFilledPointList2(image, list, value)

AVW\_Image \*image; AVW\_PointList2 \*list;

double value:

**DESCRIPTION** AVW\_DrawFilledPointList2() sets the locations in image specified by list to value. If list

specifies a simple or complex closed trace, the interior of the trace is also set to value.

For AVW\_COLOR images the red, green, and blue components need to be packed into

 $value. \ See \ AVW\_MAKERGB().$ 

**RETURN VALUES** If successful AVW\_DrawFilledPointList2() returns AVW\_SUCCESS. On failure AVW\_FAIL

is returned.

**ERRORS** | *AVW\_DrawFilledPointList2()* will fail if one or more of the following are true:

**ILLPAR** 

A NULL image or list was specified.

**ILLDT** 

Data type is not defined or supported.

SEE ALSO AVW\_DrawPointList2(), AVW\_DrawPointList3(), AVW\_PutVoxel(), AVW\_GetPixel(),

AVW\_GetVoxel(), AVW\_Image, AVW\_Point2, AVW\_MAKERGB()

AVW\_DrawImageLine - draws a line into an image

**SYNOPSIS** 

#include "AVW.h"

int AVW\_DrawImageLine(image, pt1, pt2, value)

AVW\_Image \*image; AVW\_Point2 \*pt1, \*pt2;

double value;

**DESCRIPTION** 

AVW\_DrawImageLine() sets all pixels in image along a line from pt1 to pt2 to value.

**RETURN VALUES** 

If successful  $AVW\_DrawImageLine()$  returns  $AVW\_SUCCESS$ .  $AVW\_FAIL$  is returned if

all points were outside the image.

**SEE ALSO** 

AVW\_DrawVolumeLine(), AVW\_PutPixel(), AVW\_PutVoxel(), AVW\_Image, AVW\_Point2

AVW\_DrawImageText - draws a text string into an image

**SYNOPSIS** 

#include "AVW.h"

int AVW\_DrawImageText(image, string, pt, value)

AVW\_Image \*image;

char \*string; AVW\_Point2 \*pt;

double value;

**DESCRIPTION** 

*AVW\_DrawImageText()* draws the text specified by *string* into an *image* at the location *pt. Image* is an *AVW\_Image*.

String is a zero terminated ascii string.

Pt specifies where the drawing begins. Text can only be drawn from left to right.

Value indicates the value that each pixel is set to.

A small crude font is all that is available.

**RETURN VALUES** 

If successful *AVW\_DrawImageText()* returns *AVW\_SUCCESS*. *AVW\_FAIL* is returned if starting position was outside the image.

**SEE ALSO** 

AVW\_DrawImageLine(), AVW\_PutPixel(), AVW\_PutVoxel(), AVW\_Image, AVW\_Point2

NAME | AVW\_DrawPointList2 – puts a value at the locations in an image sepcified by a point list

SYNOPSIS #include "AVW.h"

int AVW\_DrawPointList2(image, list, value)

AVW\_Image \*image; AVW\_PointList2 \*list;

double value:

**DESCRIPTION** AVW\_DrawPointList2() sets the locations in *image* specified by *list* to value.

For AVW\_COLOR images the red, green, and blue components need to be packed into

value. See AVW\_MAKERGB().

**RETURN VALUES** If successful *AVW\_DrawPointList2()* returns *AVW\_SUCCESS*. On failure *AVW\_FAIL* is

returned.

**ERRORS** AVW\_DrawPointList2() will fail if one or more of the following are true:

**ILLPAR** 

A NULL image or list was specified.

**ILLDT** 

Data type is not defined or supported.

SEE ALSO | AVW\_DrawPointList3(), AVW\_PutVoxel(), AVW\_GetPixel(), AVW\_GetVoxel(),

AVW\_Image, AVW\_Point2, AVW\_MAKERGB()

NAME | AVW\_DrawPointList3 – puts a value at the locations in a volume specified by a point list

SYNOPSIS #include "AVW.h"

int AVW\_DrawPointList3(volume, list, value)

AVW\_Volume \*volume;

AVW\_Point3 \*list;

double value;

**DESCRIPTION** AVW\_DrawPointList3() sets the locations in volume specified by list to value.

For  $AVW\_COLOR$  volumes the red, green, and blue components need to be packed into

value. See AVW\_MAKERGB().

**RETURN VALUES** If successful *AVW\_DrawPointList3()* returns *AVW\_SUCCESS*. On failure *AVW\_FAIL* is

returned.

**ERRORS** AVW\_DrawPointList3() will fail if

**ILLPAR** 

A NULL list or volume was specified.

**ILLDT** 

Data type is not defined or supported.

SEE ALSO | AVW\_DrawPointList2(), AVW\_PutPixel(), AVW\_GetVoxel(), AVW\_Point3, AVW\_Volume,

AVW\_MAKERGB()

AVW\_DrawRenderedbackDrop - draws a line into rendered space

**SYNOPSIS** 

#include "AVW\_Render.h"

 $int\ AVW\_DrawRenderedBackDrop(rendered,\ value)$ 

AVW\_RenderedImage \*rendered;

double value;

**DESCRIPTION** 

*AVW\_DrawRenderedbackDrop()* draws a shaded backdrop at each pixel of the rendering where *render->Depth* is contained in the *rendered->PBuffer* value for that pixel.

In other words where no output value was put into the rendering.

 $AVW\_DrawRenderedPoint(),\ AVW\_DrawRenderedLine(),\ AVW\_RenderVolume(),\ AVW\_RenderedImage,$ 

**NAME** AVW\_DrawRenderedLine – draws a line into rendered space

**SYNOPSIS** #include "AVW\_Render.h"

int AVW\_DrawRenderedLine(rendered, start, end, value)

AVW\_RenderedImage \*rendered;

AVW\_FPoint3 \*start, \*end;

double value:

**DESCRIPTION** | AVW\_DrawRenderedLine() transforms the line, specified by end points start and end, to the

rendered space and changes all pixels along the transformed line to value.

**RETURN VALUES** | *AVW\_DrawRenderedLine()* returns *AVW\_SUCCESS* if the entire line can be successfully

transformed and draw into the rendered space. AVW\_FAIL is returned if any point along

the line could not be transformed.

 $\textbf{SEE ALSO} \qquad AVW\_DrawRenderedPoint(), \ AVW\_FindRenderedPoint(), \ AVW\_RenderVolume(), \\$ 

AVW\_RenderedImage, AVW\_FPoint3

**NAME** AVW\_DrawRenderedPoint – draws a point into rendered space

**AVW 3.0** 

SYNOPSIS #include "AVW\_Render.h"

int AVW\_DrawRenderedPoint(rendered, in, value)

AVW\_RenderedImage \*rendered;

AVW\_FPoint3 \*in; double value;

**DESCRIPTION** | AVW\_DrawRenderedPoint() transforms the point in to the rendered space and changes the

pixel at that location within the rendered image to value.

**RETURN VALUES** | *AVW\_DrawRenderedPoint()* returns *AVW\_SUCCESS* if *in* can be successfully transformed

to a location within the rendered space. It returns AVW\_FAIL if the point transforms to a

location outside the rendered space.

**SEE ALSO** | *AVW\_DrawRenderedLine()*, *AVW\_FindRenderedPoint()*, *AVW\_RenderVolume()*,

AVW\_RenderedImage, AVW\_FPoint3

**NAME** AVW\_DrawVolumeLine – draws a line into a volume

**SYNOPSIS** #include "AVW.h"

int AVW\_DrawVolumeLine(volume, pt1, pt2, value)

AVW\_Volume \*volume; AVW\_Point3 \*pt1, \*pt2;

double value;

**DESCRIPTION** | *AVW\_DrawVolumeLine()* sets all voxels in *volume* along a line from *pt1* to *pt2* to *value*.

**RETURN VALUES** If successful AVW\_DrawVolumeLine() returns AVW\_SUCCESS. AVW\_FAIL is returned if

all points were outside the volume.

SEE ALSO | AVW\_DrawImageLine(), AVW\_PutPixel(), AVW\_PutVoxel(), AVW\_Volume, AVW\_Point3

AVW\_EditPointList2 - replaces a segment of a point list

**SYNOPSIS** 

#include "AVW.h"

AVW\_PointList2 \*AVW\_EditPointList2(orig\_trace, new\_segment, new\_trace)

AVW\_PointList2 \*orig\_trace, \*new\_segment, new\_trace;

**DESCRIPTION** 

AVW\_EditPointList2() is used to edit an AVW\_PointList2 with another point list. Orig\_trace contains a trace. New\_segment contains another trace which is meant to replace a portion of orig\_trace. The edited trace is returned in new\_trace. The function determines the points in orig\_trace which are closest to the first and last points of new\_segment. The trace segment of orig\_trace between these points is replaced with with the points of new\_segment.

New\_trace is provided as a method of reusing an existing AVW\_PointList2.

**RETURN VALUES** 

If successful *AVW\_EditPointList2()* returns an *AVW\_PointList2*. On failure it returns *AVW\_NULL* and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_EditPointList2() will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate memory.

**SEE ALSO** 

AVW\_AddPoint2(), AVW\_CreatePointList2(), AVW\_DestroyPointList2(), AVW\_FillPointList2(), AVW\_PointList2, AVW\_Point2

 $AVW\_Enable Image File Format-re-enables~I/O~support~for~a~previously~disabled~image~file~format$ 

**SYNOPSIS** 

#include "AVW.h"

#include "AVW\_ImageFile.h"

int AVW\_EnableImageFileFormat(fileformat, properties)

char \*fileformat;
int properties;

**DESCRIPTION** 

AVW\_EnableImageFileFormat() re-enables I/O support of a named image file format which was previously disabled by AVW\_DisableImageFileFormat()

*fileformat* is the name by which the file format is identified in AVW and is the *Description* element of the *AVW\_ExtendIO* structure with which the format was extend.

properties is the *Properties* element of the AVW\_ExtendIO structure for this format. This is the value with which this format was originally extended by *AVW\_ExtendImageIO()* and was returned by *AVW\_DisableImageFileFormat()* when the format was disabled.

**RETURN VALUES** 

AVW\_EnableImageFileFormat() returns the value of the Properties element of the AVW\_EntendIO structure for the format prior to the call.

**SEE ALSO** 

AVW\_ExtendExternalLibs(), AVW\_DisableImageFileFormat(), AVW\_CreateImageFile(), AVW\_CloseImageFile(), AVW\_FormatSupports(), AVW\_ListFormats(), AVW\_OpenImageFile(), AVW\_ReadImageFile(), AVW\_ReadVolume(), AVW\_SeekImageFile(), AVW\_WriteImageFile(), AVW\_ExtendIO

**NAME** AVW\_EnableProgress – reinstates progress

SYNOPSIS #include "AVW.h"

void AVW\_EnableProgress()

**DESCRIPTION** | AVW\_EnableProgress() is called to re-enable calls to the AVW\_ProgressFunction(). It

undoes the effect of AVW\_DisableProgress().

**SEE ALSO** AVW\_Progress(), AVW\_ProgressFunction(), AVW\_DisableProgress()

AVW\_ErodeImage - morphologically erodes an image

## **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_ErodeImage(in\_image, element, out\_image)

AVW\_Image \*in\_image;

AVW\_Image \*element;

AVW\_Image \*out\_image;

## **DESCRIPTION**

*AVW\_ErodeImage()* performs binary morphological erosion on *in\_image* using *element* as the structuring element.

In\_image does not have to be a binary valued but all nonzero pixels are treated as ones. In\_image, out\_image, and element must be of the data type AVW\_UNSIGNED\_CHAR. This function will allocate temporary storage space for results if in\_image and out\_image are the same.

The erosion can be thought of as a shrinking of the binary objects contained in the data. In simplest terms the erosion process takes place by translating the structuring element so that its centerpoint lies on every point of the data. At each point in the data, if a nonzero pixel in the structuring element corresponds to a zero pixel in the data the point in the result data is set to zero. Otherwise the pixel is unchanged. The result data will only contain ones and zeros.

The structuring element, *element*, should always have odd dimensions, be symmetric, and be smaller than *in\_image*. *AVW\_CreateImage()*, *AVW\_SetImage()*, and *AVW\_PutPixel()* may be used to create a structuring element.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_ErodeImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ErodeImage() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

**ILLDT** 

Data type is not defined or supported.

**ILLIMG** 

An illegal image was passed to the function.

#### **SEE ALSO**

AVW\_ErodeVolume(), AVW\_CreateImage(), AVW\_MorphCloseImage(), AVW\_DilateImage(), AVW\_MorphOpenImage(), AVW\_ConditionalDilateImage(), AVW\_MorphMaxImage(), AVW\_MorphMinImage(), AVW\_UltimateErosionImage(), AVW\_CreateStructuringImage(), AVW\_Image

AVW\_ErodeVolume - morphologically erodes a volume

## **SYNOPSIS**

#include "AVW.h"

AVW\_Volume \*AVW\_ErodeVolume(in\_volume, element, out\_volume)

AVW\_Volume \*in\_volume;

AVW\_Volume \*element;

AVW Volume \*out volume;

## **DESCRIPTION**

*AVW\_ErodeVolume()* performs binary morphological erosion on *in\_volume* using *element* as the structuring element.

In\_volume does not have to be a binary valued but all nonzero pixels are treated as ones. In\_volume, out\_volume, and element must be of the data type AVW\_UNSIGNED\_CHAR. This function will allocate temporary storage space for results if in\_volume and out\_volume are the same.

The erosion can be thought of as a shrinking of the binary objects contained in the data. In simplest terms the erosion process takes place by translating the structuring element so that its centerpoint lies on every point of the data. At each point in the data, if a nonzero voxel in the structuring element corresponds to a zero voxel in the data the point in the result data is set to zero. Otherwise the voxel is unchanged. The result data will only contain ones and zeros.

The structuring element, *element*, should always have odd dimensions, be symmetric, and be smaller than *in\_volume*. *AVW\_CreateVolume()*, *AVW\_SetVolume()*, and *AVW\_PutVoxel()* may be used to create a structuring element.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_ErodeVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ErodeVolume() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

**ILLDT** 

Data type is not defined or supported.

ILLVOL

An illegal volume was passed to the function.

#### **SEE ALSO**

AVW\_ErodeImage(), AVW\_MorphCloseVolume(), AVW\_DilateVolume(),

AVW\_MorphOpenVolume(), AVW\_ConditionalDilateVolume(), AVW\_MorphMaxVolume(),

AVW\_MorphMinVolume(), AVW\_UltimateErosionVolume(),

AVW\_CreateStructuringVolume(), AVW\_Volume

**NAME** AVW\_Error – writes the current AVW\_ErrorMessage to stderr

SYNOPSIS #include "AVW.h"

void AVW\_Error(string)

char \*string;

**DESCRIPTION** | AVW\_Error() writes a formatted error message to stderr consisting of your own message

(string) and the current AVW\_ErrorMessage.

For example: if the current value of AVW\_ErrorMessage is Malloc Failed, then

"AVW\_Error("Message");" will write Message: Malloc Failed to stderr.

**SEE ALSO** | AVW\_GetErrorMessage(), AVW\_GetErrorNumber(), AVW\_SetError()

AVW\_ExtendExternalLibs - loads and initializes shared libraries

**AVW 3.0** 

**SYNOPSIS** 

AVW ExtendExternalLibs()

**DESCRIPTION** 

AVW\_ExtendExternalLibs() reads the contents of a configuration file called EXTEND.conf which lists the names of external shared libraries and their initialization routines. Standard locations are searched for these libraries, and if found, the libraries are loaded into the running program. The initialization routines are then called.

This function is designed to implement loading of image file extensions to AVW, to avoid the need to recompile each application if a new file format is added to the library. If the extensions are loaded into shared libraries and referenced in the the configuration file, this function will load and install them in a running program.

The configuration file EXTEND.conf is searched for in the user's app-defaults directory. If it is not found there \$AVW/app-default is searched.

A file path specified by the environment variable AVW\_EXTEND over rides over the previous files if they exist. If no configuration file is found, the function returns.

**NOTE** 

AVW\_ExtendExternalLibs() requires linking with the avwEXTEND library.

**RETURN VALUES** 

None

**ERRORS** 

If the requested libraries cannot be found, or if the initialization routine cannot be located in the library, the requested library will be skipped. If the configuration file is not found, the function returns silently.

**SEE ALSO** 

AVW\_ExtendImageFile(), EXTEND.conf

AVW\_ExtendImageFile – extends IO routines to support additional formats

#### **SYNOPSIS**

#include "AVW.h"

#include "AVW\_ImageFile.h"

int AVW\_ExtendImageFile(fl)

AVW\_ExtendIO \*fl;

## **DESCRIPTION**

AVW\_ExtendImageFile() extends the AVW\_ImageFile library to support other data formats. In this way applications can be written using the AVW calls without concern for the data format of image files which are being processed. Applications needn't be rewritten to support additional data formats, merely extend the AVW library to support the data format. Each time AVW\_ExtendImageFile() is invoked the external integer avw\_NumberOfSupportedFormats is incremented. The argument passed to the AVW\_ExtendImageFile() is an AVW\_ImageFileFunction. The elements of this structure describe the attributes of this format, and format specific functions which correspond to and are called by AVW\_CreateImageFile(), AVW\_OpenImageFile(), AVW\_CloseImageFile(), AVW\_ReadImageFile(), AVW\_WriteImageFile(), and AVW\_SeekImageFile().

To extend the AVW\_ImageFile routines you must set the following elements of an *AVW\_ExtendIO* structure and pass the initialized structure to *AVW\_ExtendImageFile*.

## fl->Extension

is the ending (if any) by which the file type may be identified.

## fl->Description

is the text name by which this data format is identified. This is the string which will appear for this format when AVW\_ListFormats() is invoked. This is also the string used to identify what format of file is being created by AVW\_CreateImageFile()

## fl->MagicNumber

is the magic number (if any) by which the file type may be identified. NO\_MAGIC\_NUMBER is used to indicate that this file type is not identified via a magic number.

## fl->Open()

is the function that AVW\_OpenImageFile() will pass its arguments to and return its return value from. This function should do error checking and return a AVW\_ImageFile structure. AVW\_OpenImageFile() will return whatever this function returns.

# fl->Seek()

is the function that AVW\_SeekImageFile will pass its arguments to and return a value from. This function should do error checking and return AVW\_SUCESS or AVW\_FAIL. For 2D formats (various raster formats) this should

be a routine that simply checks if the volume and slice arguments are both 0.

## fl->Read()

is the function AVW\_ReadImageFile() will pass its arguments to and return a value from. The value returned should be an AVW\_Image or NULL.

# fl->Write()

is the function AVW\_WriteImageFile() will pass its arguments to and return a value from. The values returned should be AVW\_SUCCESS or AVW\_FAIL.

# fl->Close()

is the function AVW\_CloseImageFile() will pass its arguments to and return a value from. The values returned should be AVW\_SUCCESS or AVW\_FAIL.

## fl->Create()

is the function that AVW\_CreateImageFile will pass its arguments to and return a value from. The return value should be a pointer to an AVW\_ImageFile allocated and initialized by the function.

## fl->Query()

determines whether the named file is of this format. Returns TRUE or FALSE to indicate whether the name of the file passed to it is of this data format. AVW\_OpenImageFile() will call this routine to see if the named file is of this data format.

# fl->Properties

is a mask of attributes of this format which describes and controls which attributes are supported by the interface routines.

# C Datatypes supported by this format:

AVW\_SUPPORT\_UNSIGNED\_CHAR AVW\_SUPPORT\_SIGNED\_CHAR AVW\_SUPPORT\_UNSIGNED\_SHORT AVW\_SUPPORT\_SIGNED\_SHORT AVW\_SUPPORT\_UNSIGNED\_INT AVW\_SUPPORT\_SIGNED\_INT AVW\_SUPPORT\_FLOAT AVW\_SUPPORT\_COMPLEX AVW\_SUPPORT\_COLOR

Other attributes supported by this format:

AVW\_SUPPORT\_2D

AVW\_SUPPORT\_3D AVW\_SUPPORT\_READ AVW\_SUPPORT\_WRITE

For example an attribute mask for a raster file type which supported only 8 bit images might look like:

(AVW\_SUPPORT\_UNSIGNED\_CHAR| AVW\_SUPPORT\_2D| AVW\_SUPPORT\_READ| AVW\_SUPPORT\_WRITE)

The following file formats are directly supported by AVW Image File IO routines:

AnalyzeAVW AVW\_VolumeFile AVW\_Objectmap

Additional file formats are extended under the control of the configuration file EXTEND.conf. The first time an application makes a call to AVW\_OpenImageFile(), the function AVW\_ExtendExternalLibs() is invoked to dynamically load libraries for additional iage fil formats. Libraries are provided for these formats:

AnalyzeImage(7.5) AnalyzeScreen SunRaster GE9800 (Read Only) (Read Only) **GESigna** GE Advantage (Read Only) GESTARCAM (Read Only) **Imatron** (Read Only) SiemensCT (Read Only) INTERFILE (Read Only) ACRNEMA (Read Only) **PAPYRUS** (Read Only) **SGIrgb SGIbw PPM PGM** YUV **BMP** PIC JPG PICKERMRI (Read Only) (Read Only) **SMIS** CTI (Read Only) **TARGA** CTIECAT7

PostScript (Write Only)

Support for some of the formats is limited to Read Only. Files cannot be created or written in these formats.

# **RETURN VALUES**

AVW\_ExtendImageFile() returns the current number of supported formats. This is the value to which the DataFormat element within the AVW\_ImageFile is set upon a successful AVW\_OpenImageFile(). It is also the argument which is used to direct AVW\_CreateImageFile() the data format of the new file.

## **SEE ALSO**

EXTEND.conf AVW\_ExtendExternalLibs(), AVW\_DisableImageFileFormat(), AVW\_EnableImageFileFormat(), AVW\_CreateImageFile(), AVW\_CloseImageFile(), AVW\_FormatSupports(), AVW\_ListFormats(), AVW\_OpenImageFile(), AVW\_BeadImageFile(), AVW\_ReadImageFile(), AVW\_W\_IteImageFile(), AVW\_W\_IteImageFile(), AVW\_W\_IteImageFile(), AVW\_ExtendIO

AVW\_ExtractControlPoints - extracts control points from a trace

**SYNOPSIS** 

#include "AVW.h"

AVW\_PointList2 \*AVW\_ExtractControlPoints(trace, step, close\_flag, distance, control)

AVW\_PointList2 \*trace;

double step; int close flag;

int distance;

AVW\_PointList2 \*control;

## **DESCRIPTION**

AVW\_ExtractControlPoints() extracts a set of control points from a trace.

Points are removed from *trace* and *AVW\_MakeSpline()* is called using the *step* and *close\_flag* parameters. If the output does not vary by more than *distance* pixels, from the input *trace*, the point is removed. This continues until the minimum number of control points have been generated.

Control contains the resultant list of control points.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

Control is provided as a method of reusing an existing AVW\_PointList2.

## **RETURN VALUES**

If successful AVW\_ExtractControlPoints() returns an AVW\_PointList2. On failure it returns AVW\_NULL and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ExtractControlPoints() will fail if:

**ILLPAR** 

An illegal parameter, NULL trace, was passed to the routine.

**SEE ALSO** 

AVW\_AddFPoint2(), AVW\_CreatePointList2(), AVW\_DestroyPointList2(), AVW\_FillPointList2(), AVW\_MakeSpline(), AVW\_PointList2, AVW\_Point2

AVW\_ExtractGradients - extracts a surface

**SYNOPSIS** 

"AVW Render.h" #include

AVW\_Gradients \*AVW\_ExtractGradients(param, last\_gradients)

**AVW 3.0** 

AVW\_RenderParameters \*param; AVW\_Gradients \*last\_gradients;

**DESCRIPTION** 

AVW\_ExtractGradients() uses the param->ThresholdMinimum and param->ThresholdMaximum members of the AVW\_RenderParameters structure to extract all the surface points from the AVW\_Volume specified within the structure. Normals are also precomputed, so that when the AVW\_Gradients structure is used as input to AVW\_RenderGradients(), very fast interactive renderings can be generated.

Last\_gradients is provided as a method of reusing an existing AVW\_Gradients. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful AVW\_ExtractGradients() returns an AVW\_Gradients. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ExtractGradients() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**SEE ALSO** 

AVW\_DestroyGradients(), AVW\_RenderGradients(), AVW\_Gradients, AVW\_RenderParameters

AVW\_ExtractObject - extracts an object from a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_ExtractObject(in\_volume, orient, slice, seedlist, thresh\_max, thresh\_min, mask\_image, out\_volume)

AVW\_Volume \*in\_volume;

int orient, slice:

AVW PointList2 \*seedlist2;

double threshold\_max, threshold\_min;

AVW\_Image \*mask\_image;

AVW\_Volume \*out\_volume;

## **DESCRIPTION**

*AVW\_ExtractObject()* extracts an object from a volume using thresholding, region growing and morphological operations.

In\_volume specifies the input greyscale volume which contains the object. Orient and slice specify a slice of the volume on which the object can be defined by a threshold range and one or more seed points. Seedlist specifies one or more seed points from which the object can be grown. Thresh\_max and thresh\_min specify the threshold range of the object. Mask\_image contains a 2D mask of the object for the specified slice. Mask\_image may be set to NULL if the seed points and threshold range are sufficient to define the object on the specified slice. It is only necessary to provide a mask\_image if manual interaction (limits) are required for definition of the object.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_ExtractObject()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

*AVW\_ExtractObject()* will fail if the following is true:

**ILLDT** 

Illegal data type.

**SEE ALSO** 

AVW\_ConditionalDilateGreyVolume(), AVW\_ConnectAndKeepVolume(), AVW\_ErodeVolume(), AVW\_GetThresholdedBoundary(), AVW\_ThresholdVolume(), AVW\_Image

AVW\_ExtractVisibleSurface – extracts surface from rendered image

**SYNOPSIS** 

#include "AVW Render.h"

AVW\_VisibleSurface \*AVW\_ExtractVisibleSurface(rendered, last\_surface)

AVW\_RenderedImage \*rendered; AVW\_VisibleSurface \*last\_surface;

**DESCRIPTION** 

AVW\_ExtractVisibleSurface() creates an AVW\_VisibleSurface which contains only the points in the rendered->Volume which were part of the visible surface displayed in rendered->Image. Pixel values are also stored, so that when the AVW\_VisibleSurface structure is used as input to AVW\_VisibleSurfaceRender(), very fast interactive renderings can be generated.

Last\_surface is provided as a method of reusing an existing AVW\_Surface. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_ExtractVisibleSurface()* returns an *AVW\_VisibleSurface*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the failure.

**ERRORS** 

AVW\_ExtractVisibleSurface() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**SEE ALSO** 

AVW\_DestroySurface(), AVW\_RenderVisibleSurface(), AVW\_ExtractSurface(), AVW\_VisibleSurface, AVW\_RenderedImage

AVW\_FFT2D - performs 2D Fast Fourier Transformations

## **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_FFT2D(input\_image, direction, output\_image)

AVW\_Image \*input\_image;

int direction;

AVW\_Image \*output image;

#### **DESCRIPTION**

 $AVW\_FFT2D()$  returns the forward or inverse 2D FFT of the <code>input\_image</code>, depending on whether <code>direction</code> is  $AVW\_FORWARD$  or  $AVW\_BACKWARD$ . For a forward FFT, image dimensions are automatically padded to the next larger power of 2 before the transform is applied. If these (possibly padded) dimensions are X2, Y2, the returned image will be an image of data type  $AVW\_COMPLEX$  with dimensions X2/2 + 1, Y2. For an inverse FFT, the input image must be of data type  $AVW\_COMPLEX$  and of dimensions X2/2 + 1, Y2 where X2 and Y2 are powers of 2. The returned image will be of data type  $AVW\_FLOAT$  and of dimensions X2, Y2.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful AVW\_FFT2D() returns an AVW\_Image. On failure it returns NULL, and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

#### **ERRORS**

*AVW\_FFT2D()* will fail if one or more of the following are true:

BDSPCT

Bad Input Spectrum. An invalid image was entered for an inverse FFT.

**ILLPAR** 

Illegal Parameter. An invalid value was given for direction.

**BADMAL** 

Malloc Failed. Unable to allocate memory for return image.

**SEE ALSO** 

AVW\_FFT3D(), AVW\_CreateButterworthCoeffs(), AVW\_CreateCircularMTF(), AVW\_CreateCoeffs(), AVW\_CreateGaussianCoeffs(), AVW\_CreateStoksethMTF(), AVW\_DeconvDivideImage(), AVW\_DeconvWienerImage(), AVW\_ImageOpImage(), AVW\_IterDeconvImage(), AVW\_NearestNeighborDeconv(), AVW\_Image

AVW FFT3D – performs 3D Fast Fourier Transformations

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_FFT3D(input\_volume, direction, output\_volume)

AVW\_Volume \*input\_volume;

int direction;

AVW\_Volume \*output\_volume

## **DESCRIPTION**

 $AVW\_FFT3D()$  returns the forward or inverse 3D FFT of the <code>input\_volume</code>, depending on whether <code>direction</code> is  $AVW\_FORWARD$  or  $AVW\_BACKWARD$ . For a forward FFT, volume dimensions are automatically padded to the next larger power of 2 before the transform is applied. If these (possibly padded) dimensions are X2, Y2, Z2, the returned image will be an image of data type  $AVW\_COMPLEX$  with dimensions X2/2 + 1, Y2, Z2. For an inverse FFT, the input volume must be of data type  $AVW\_COMPLEX$  and of dimensions X2/2 + 1, Y2, Z2 where X2, Y2, and Z2 are powers of 2. The returned volume will be of data type  $AVW\_FLOAT$  and of dimensions X2, Y2, Z2.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful *AVW\_FFT3D()* returns an *AVW\_Volume*. On failure it returns *NULL*, and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_FFT3D() will fail if one or more of the following are true:

**BDSPCT** 

Bad Input Spectrum. An invalid image was entered for an inverse FFT.

II.I.PAR

Illegal Parameter. An invalid value was given for direction.

**BADMAL** 

Malloc Failed. Unable to allocate memory for return volume.

# **SEE ALSO**

 $AVW\_FFT2D(),\ AVW\_CreateButterworthCoeffs(),\ AVW\_CreateCoeffs(),\\ AVW\_CreateGaussianCoeffs(),\ AVW\_CreateSphericalMTF(),\ AVW\_DeconvDivideVolume(),\\ AVW\_DeconvWienerVolume(),\ AVW\_VolumeOpVolume(),\ AVW\_IterDeconvVolume(),\\ AVW\_Volume$ 

AVW\_FillHolesImage - fills holes in an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_FillHolesImage(in\_image, connectivity, out\_image)

AVW\_Image \*in\_image;

int connectivity;

AVW\_Image \*out\_image;

**DESCRIPTION** 

*AVW\_FillHolesImage()* fills in holes in an image. Holes are defined as 0 valued pixels which are entirely surrounded by pixels with a value of 1.

*Connectivity* may be either *AVW\_4\_CONNECTED* or *AVW\_8\_CONNECTED* and specifies the neighbors to be used to determine the connected components.

*In\_image* has to be a binary valued, i.e. ones and zeroes. *In\_image*, and *out\_image* must be of the data type *AVW\_UNSIGNED\_CHAR*. This function will allocate temporary storage space for results if *in\_image* and *out\_image* are the same.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_FillHolesImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_FillHolesImage() will fail if:

ILLDT

Data type is not defined or supported.

**SEE ALSO** 

AVW\_FillHolesVolume(), AVW\_FindImageComponents(), AVW\_Image

AVW\_FillHolesVolume - fills holes in a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_FillHolesVolume(in\_volume, connectivity, out\_volume)

AVW\_Volume \*in\_volume;

int connectivity;

AVW Volume \*out volume:

**DESCRIPTION** 

*AVW\_FillHolesVolume()* fills in holes in a volume. Holes are defined as 0 valued voxels which are entirely surrounded by voxels with a value of 1.

*Connectivity* may be either *AVW\_6\_CONNECTED* or *AVW\_26\_CONNECTED* and specifies the neighbors to be used to determine the connected components.

*In\_volume* has to be a binary valued, i.e. ones and zeroes. *In\_volume*, and *out\_volume* must be of the data type *AVW\_UNSIGNED\_CHAR*. This function will allocate temporary storage space for results if *in\_volume* and *out\_volume* are the same.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful AVW\_FillHolesVolume() returns an AVW\_Volume. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_FillHolesVolume() will fail if:

**ILLDT** 

Data type is not defined or supported.

**SEE ALSO** 

AVW\_FillHolesImage(), AVW\_FindVolumeComponents(), AVW\_Volume

AVW\_FillPointList2 - fills in gaps in an AVW\_PointList2 structure

**SYNOPSIS** 

#include "AVW.h"

AVW\_PointList2 \*AVW\_FillPointList2(plist, out\_plist)

AVW\_PointList2 \*plist;

AVW\_PointList2 \*out\_plist;

**DESCRIPTION** 

*AVW\_FillPointList2()* creates an 8-connected *AVW\_PointList2* by filling in any gaps in *plist* with linearly interpolated points.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks. The last point in the point list is not automatically connected to the first point.

Out\_plist is provided as a method of reusing an existing AVW\_PointList2.

**RETURN VALUES** 

If successful *AVW\_FillPointList2()* returns an *AVW\_PointList2*. On failure it returns *AVW\_NULL* and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_FillPointList2() will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate memory.

**SEE ALSO** 

AVW\_AddFPoint2(), AVW\_CreatePointList2(), AVW\_DestroyPointList2(), AVW\_MakeMaskFromTrace(), AVW\_PointList2, AVW\_Point2

AVW\_FillPointList3 - fills in gaps in an AVW\_PointList3 structure

**SYNOPSIS** 

#include "AVW.h"

AVW\_PointList3 \*AVW\_FillPointList3(plist, out\_plist)

AVW\_PointList3 \*plist;

AVW\_PointList3 \*out\_plist;

**DESCRIPTION** 

AVW\_FillPointList3() creates an 26-connected AVW\_PointList3 by filling in any gaps in plist with linearly interpolated points.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks. The last point in the point list is not automatically connected to the first point.

Out\_plist is provided as a method of reusing an existing AVW\_PointList3.

**RETURN VALUES** 

If successful *AVW\_FillPointList3()* returns an *AVW\_PointList3*. On failure it returns *AVW\_NULL* and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_FillPointList3() will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate memory.

**SEE ALSO** 

AVW\_AddPoint3(), AVW\_CreatePointList3(), AVW\_DestroyPointList3(), AVW\_PointList3, AVW\_Point3

AVW\_FindImageComponents - finds the connected regions in an image

## **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_FindImageComponents(in\_image, label\_flag, connectivity, max\_size, min\_size, out\_image)

AVW\_Image \*in\_image;

int label\_flag, connectivity, max\_size, min\_size;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_FindImageComponents() finds all of the unique four or eight connected regions in in\_image.

*In\_image* must be of the data type *AVW\_UNSIGNED\_CHAR*. It does not have to be binary valued, but all nonzero values are treated as ones.

The *label\_flag* parameter can be set to *AVW\_NO\_LABEL*, *AVW\_LABEL*, *AVW\_SORT\_AND\_LABEL*, and *AVW\_INVERSE\_SORT\_AND\_LABEL*.

When set to *AVW\_NO\_LABEL*, the returned image contains all 1's and 0's (NOTE: This option is slightly slower than AVW\_LABEL, as the labeling is actually done anyway and then removed in a post-processing step.)

When set to *AVW\_LABEL*, each seperately connected object contains a unique label. The objects are labeled 1 thru N.

When set to *AVW\_SORT\_AND\_LABEL*, the objects are labeled as above but sorted largest to smallest.

When set to *AVW\_INVERSE\_SORT\_AND\_LABEL*, the objects are labeled as above but sorted smallest to largest.

*Connectivity* may be either *AVW\_4\_CONNECTED* or *AVW\_8\_CONNECTED* and specifies the neighbors to be used to determine the connected components.

*Max\_size* specifies the largest allowable component size. Components larger than this size will be deleted, or in other words set to zero.

*Min\_size* specifies the minimum allowable component size. Components smaller than this size will be deleted, or in other words set to zero.

The returned image will be of data type *AVW\_UNSIGNED\_CHAR* unless the number of components found is greater than 255, in which case the data type will be *AVW\_UNSIGNED\_SHORT*.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_FindImageComponents()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

 $AVW\_FindVolumeComponents(), AVW\_FindImageEdges(), AVW\_LabelImageFromEdges(), AVW\_DefineConnected(), AVW\_ConnectAndDeleteImage(), AVW\_ConnectAndKeepImage(), AVW\_Image$ 

AVW\_FindImageEdges - finds the edges in an image

**SYNOPSIS** 

#include "AVW.h"

 $AVW\_Image *AVW\_FindImage Edges (in\_image, edge\_flag, connectivity, out\_image)$ 

AVW\_Image \*in\_image;

int edge\_flag;
int connectivity;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_FindImageEdges() finds all of the nonzero pixels in in\_image that have a zero as a four or eight connected neighbor. These edges are labeled as ones in out\_image.

In\_image must be of the data type AVW\_UNSIGNED\_CHAR.

If *edge\_flag* is set to one, the the edges appear on top of the nonzero pixels that have a zero neighbor. If *edge\_flag* is set to zero, the edges appear on top of zero pixels that have a nonzero neighbor.

*Connectivity* may be either *AVW\_4\_CONNECTED* or *AVW\_8\_CONNECTED* and specifies the neighbors to be used to determine the edges.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful AVW\_FindImageEdges() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**SEE ALSO** 

 $AVW\_FindVolumeEdges(),\ AVW\_FindImageComponents(),\ AVW\_LabelImageFromEdges()\\ AVW\_Image$ 

AVW\_FindImageMaxMin - finds the maximum and minimum values of an image

**SYNOPSIS** 

#include "AVW.h"

int AVW\_FindImageMaxMin(image, max\_val, min\_val)

**AVW 3.0** 

AVW\_Image \*image;

double \*max\_val, \*min\_val;

**DESCRIPTION** 

AVW\_FindImageMaxMin() finds the maximum and minimum data values in *image* and returns them in *max\_val* and *min\_val*.

After calculation, the values are stored in the information string of the input image to allow quicker future max/min queries with the *AVW\_QuickImageMaxMin* function.

**RETURN VALUES** 

If successful,  $AVW\_FindImageMaxMin()$  returns  $AVW\_SUCCESS$ . On failure, it returns  $AVW\_FAIL$  and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_FindImageMaxMin() will fail if:

**NOTSUP** 

Image data type not supported.

**SEE ALSO** 

 $AVW\_FindVolumeMaxMin(),\ AVW\_QuickImageMaxMin(),\ AVW\_QuickVolumeMaxMin(),\ AVW\_Image$ 

NAME | AVW\_FindRenderedPoint – returns volume coordinates from a rendered image

SYNOPSIS #include "AVW\_Render.h"

int AVW\_FindRenderedPoint(rendered, in, out)

AVW\_RenderedImage \*rendered;

AVW\_FPoint2 \*in; AVW\_FPoint3 \*out;

**DESCRIPTION** | AVW\_FindRenderedPoint() transforms a point from rendered space back into the input

volumes space. The point in, is specified as an AVW\_Point2 location within the rendered-

>Image. The transformed point is returned in the out AVW\_Point3 structure.

**RETURN VALUES** | AVW\_FindRenderedPoint() returns AVW\_SUCCESS if in can be successfully transformed

to a location within the input volume. It returns  $AVW\_FAIL$  if the point transforms to a

location outside the volume.

 $\textbf{SEE ALSO} \qquad AVW\_DrawRenderedLine(), \ AVW\_DrawRenderedPoint(), \ AVW\_RenderVolume(), \\$ 

AVW\_RenderedImage AVW\_FPoint2, AVW\_FPoint3

AVW\_FindRotation - adjusts render matrix to move point interactively

**SYNOPSIS** 

#include "AVW Render.h"

int AVW\_FindRotation(pt3, pt2, r\_param)

AVW\_Point3 \*out;

AVW\_Point2 \*in;

AVW\_RenderParameters \*r\_param;

**DESCRIPTION** 

*AVW\_FindRotation()* applies single degree X, Y, and Z screen relative rotations recursively to the rendering rotation matrix, *r\_param->Matrix*, *until the 3-D point*, *pt3*, is rotated into the position which is closest to the 2-point, *pt2*.

This function is used to to implement interactive "Change View", where the user selects a point on a rendered image and "drags" that point to a new location, thuse rotating the rendering.

**RETURN VALUES** 

*AVW\_FindRotation()* returns *AVW\_SUCCESS* if *in* can be successfully transformed to a location within the input volume. It returns *AVW\_FAIL* if the point transforms to a location outside the volume.

**SEE ALSO** 

 $AVW\_FindRenderedPoint(),\ AVW\_ExtractVisibleSurface(),\ AVW\_RenderVisibleSurface(),\ AVW\_RenderVisibleSurface(),\ AVW\_Point2,$ 

AVW\_FindSurfaceArea - measures surface area

**SYNOPSIS** 

#include "AVW.h"

 $int\ AVW\_FindSurface Area (rendered,\ mask,\ mask\_depth,\ surface\_voxels,$ 

surface\_faces, planar\_area, surface\_area)

AVW\_RenderedImage \*rendered;

AVW\_Image \*mask;

int mask\_depth;

int \*surface\_voxels;

int \*surface\_faces;

int \*planar\_area;

double \*surface\_area;

# **DESCRIPTION**

*AVW\_FindSurfaceArea()* returns a surface voxels, surface faces, planar area, and a estimated surface area.

*Rendered* specifies the surface to measure.

Mask is an AVW\_Image in which all non-zero pixels indicate an area on the surface to measure. Mask->Width and mask->Height must be the same as rendered->Width and rendered->Height. Mask must have a datatype of AVW\_UNSIGNED\_CHAR.

*Mask\_depth* is a flag, which when set to *AVW\_TRUE*, constrains the surface grow to the actual minimum and maximum depths found in the *mask*.

If successful, *surface\_voxels* will contain a count of each connected surface voxel which was within the *mask*. *Surface\_faces* is a count of the exposed faces from these voxels. *Planar\_area* is a count of the pixels in the *mask* which were over a surface point in the *rendered* image. Knowing the exposed surface faces for each surface voxel, triangles, rectangles and squares can be measured to estimate the value returned in *surface\_area*.

## **RETURN VALUES**

If successful *AVW\_FindSurfaceArea()* returns *AVW\_TRUE*. On failure it returns *AVW\_FALSE* and sets the *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_FindSurfaceArea() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**ILLPAR** 

Illegal parameter(s).

#### **SEE ALSO**

AVW\_FindSurfaceDistance(), AVW\_FindRenderedPoint(), AVW\_RenderedImage, AVW\_Image

AVW\_FindSurfaceDistance - returns distance along a surface

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW.h"

int AVW\_FindSurfaceDistance(rendered, pt1, pt2, curved)

AVW\_RenderedImage \*rendered;

AVW\_Point2 \*pt1, \*pt2;

double \*curved:

**DESCRIPTION** 

AVW\_FindSurfaceDistance() returns distance between two point on a surface.

*Rendered* specifies the surface to measure.

*Pt1* and *pt2* specify the two end points of the curved line to measure. Both points must be on the surface and all pixels in a straight line between then in the rendered image must be surface points.

*Curved* will contain the measured distance if *AVW\_FindSurfaceDistance()* returns successfully. The surface distance is calculated by summing the distances between each point on the surface.

**RETURN VALUES** 

If successful *AVW\_FindSurfaceDistance()* returns *AVW\_TRUE*. On failure it returns *AVW\_FALSE* and sets the *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_FindSurfaceDistance() will fail if one or more of the following is true:

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_FindSurfaceArea(), AVW\_FindRenderedPoint(), AVW\_RenderedImage, AVW\_Point2

AVW\_FindSurfacePoints - locates all surface points

**SYNOPSIS** 

#include "AVW\_ObjectMap.h"

AVW\_PointList3 \*AVW\_FindSurfacePoints(volume, object\_map, thresh\_max, thresh\_min, connect\_flag)

AVW\_Volume \*volume;

AVW\_ObjectMap \*object\_map; double thresh\_max, thresh\_min;

int connect\_flag;

**DESCRIPTION** 

AVW\_FindSurfacePoints() locates all points in the input volume which have an intensity value greater than or equal to thresh\_min and less than or equal to thresh\_max and have at least one connected neighbor which is not that within this range. If the object\_map parameter is not NULL, in addition to checking thresholds the voxels found must belong to an object which has it's DisplayFlag set to AVW\_TRUE, and at least one neighbor outside the threshold range or having it's set to AVW\_FALSE.

*Connect\_flag* may be either *AVW\_6\_CONNECTED* or *AVW\_26\_CONNECTED* and specifies the neighbors to be used to determine the connected components.

**RETURN VALUES** 

If successful *AVW\_FindSurfacePoints()* returns an *AVW\_PointList3*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_FindSurfacePoints() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**SEE ALSO** 

AVW\_DestroyPointList3(), AVW\_ExtractSurface(), AVW\_ObjectMap

**NAME** AVW\_FindTraceCenter – finds the the center point of a trace

SYNOPSIS #include "AVW.h"

int AVW\_FindTraceCenter(trace, point)

AVW\_PointList2 \*trace; AVW\_Point2 \*point;

**DESCRIPTION** AVW\_FindTraceCenter() finds the center point of a traced region defined by trace. The

center point coordinates are returned in point.

**RETURN VALUES** If successful, AVW\_FindTraceCenter() returns AVW\_SUCCESS. On failure, it returns

AVW\_FAIL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding

to the cause of the failure.

SEE ALSO | AVW\_FillPointList2(), AVW\_Image, AVW\_Point2, AVW\_PointList2

**NAME** AVW\_FindTreeIndex – get a point from a list

**SYNOPSIS** #include "AVW\_Tree.h"

int AVW\_FindTreeIndex(tree, point)

AVW\_Tree \*tree; AVW\_Point3 \*point;

**DESCRIPTION** AVW\_FindTreeIndex() gets finds the index of a specified point from a tree structure.

Tree is an AVW\_Tree.

**RETURN VALUES** If successful the index into the tree structure is returned, otherwise *AVW\_FAIL* is returned

and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the

cause of the failure.

 $\textbf{SEE ALSO} \qquad AVW\_AddTreeChild(), AVW\_CreateTree(), AVW\_DestroyTree(), AVW\_LoadTree(), AVW\_L$ 

AVW\_SaveTree(), AVW\_Point3, AVW\_Tree

AVW\_FindTreeStart - finds a tree starting point

**SYNOPSIS** 

#include "AVW\_Tree.h"

int AVW\_FindTreeStart(in\_volume, startpos)

AVW\_Volume \*in\_volume; AVW\_Point3 \*startpos;

**DESCRIPTION** 

*AVW\_FindTreeStart()* finds the closest endpoint of a thinned skeleton to the approximate root location contained in *startpos*. The coordinates of *startpos* are then set to the location of the endpoint.

**RETURN VALUES** 

If successful, *AVW\_FindTreeStart()* returns *AVW\_SUCCESS*. On failure, it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_FindTreeStart() will fail if one or more of the following are true:

**ILLPAR** 

Point specified is outside of the image.

**ILLDT** 

Illegal datatype.

**EMPTYI** 

All pixels in the image are zero.

**SEE ALSO** 

AVW\_MakeTree(), AVW\_Tree, AVW\_Point3

AVW\_FindVolumeComponents - finds the connected regions in a volume

## **SYNOPSIS**

#include "AVW.h"

AVW\_Volume \*AVW\_FindVolumeComponents(in\_volume, label\_flag, connectivity, max\_size, min\_size, out\_volume)

AVW\_Volume \*in\_volume;

int label\_flag, connectivity, max\_size, min\_size;

AVW\_Volume \*out\_volume;

#### **DESCRIPTION**

AVW\_FindVolumeComponents() finds all of the unique six or twenty six connected regions in in\_volume.

*In\_volume* must be of the data type *AVW\_UNSIGNED\_CHAR*. It does not have to be binary valued, but all nonzero values are treated as ones.

The *label\_flag* parameter can be set to *AVW\_NO\_LABEL*, *AVW\_LABEL*, *AVW\_SORT\_AND\_LABEL*, and *AVW\_INVERSE\_SORT\_AND\_LABEL*.

When set to *AVW\_NO\_LABEL*, the returned volume contains all 1's and 0's (NOTE: This option is slightly slower than AVW\_LABEL, as the labeling is actually done anyway and then removed in a post-processing step.)

When set to *AVW\_LABEL*, each seperately connected object contains a unique label. The objects are labeled 1 thru N.

When set to *AVW\_SORT\_AND\_LABEL*, the objects are labeled as above but sorted largest to smallest.

When set to *AVW\_INVERSE\_SORT\_AND\_LABEL*, the objects are labeled as above but sorted smallest to largest.

Connectivity may be either  $AVW\_6\_CONNECTED$  or  $AVW\_26\_CONNECTED$  and specifies the neighbors to be used to determine the connected components.

*Max\_size* specifies the largest allowable component size. Components larger than this size will be deleted, or in other words set to zero.

*Min\_size* specifies the minimum allowable component size. Components smaller than this size will be deleted, or in other words set to zero.

The returned volume will be of data type  $AVW\_UNSIGNED\_CHAR$  unless the number of components found is greater than 255, in which case the data type will be  $AVW\_UNSIGNED\_SHORT$ .

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_FindVolumeComponents()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

 $AVW\_ConnectAndDeleteVolume(),\ AVW\_ConnectAndKeepVolume(),\\ AVW\_DefinedConnected(),\ AVW\_FindImageComponents(),\ AVW\_FindVolumeEdges(),\\ AVW\_LabelVolumeFromEdges(),\ AVW\_Volume$ 

**AVW 3.0** 

AVW\_FindVolumeEdges - finds the edges in a volume

**SYNOPSIS** 

#include "AVW.h"

 $AVW\_Volume *AVW\_FindVolumeEdges (in\_volume, edge\_flag, connectivity, out\_volume) \\ AVW\_Volume *in\_volume;$ 

int edge\_flag;
int connectivity;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_FindVolumeEdges() finds all of the nonzero pixels in in\_volume that have a zero as a 6 or 26 connected neighbor. These edges are labeled as ones in out\_volume.

*In\_volume* must be of the data type *AVW\_UNSIGNED\_CHAR*.

If *edge\_flag* is set to one, the the edges appear on top of the nonzero voxels that have a zero neighbor. If *edge\_flag* is set to zero, the edges appear on top of zero voxels that have a nonzero neighbor.

*Connectivity* may be either *AVW\_6\_CONNECTED* or *AVW\_26\_CONNECTED* and specifies the neighbors to be used to determine the edges.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_FindVolumeEdges()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

 $AVW\_FindImageEdges(), AVW\_FindVolumeComponents(), AVW\_LabelVolumeFromEdges(), AVW\_Volume$ 

AVW\_FindVolumeMaxMin - finds the maximum and minimum values of a volume

**SYNOPSIS** 

#include "AVW.h"

int AVW\_FindVolumeMaxMin(volume, max\_val, min\_val)

**AVW 3.0** 

AVW\_Volume \*volume; double \*max\_val, \*min\_val;

**DESCRIPTION** 

AVW\_FindVolumeMaxMin() finds the maximum and minimum data values in *volume* and returns them in *max\_val* and *min\_val*.

After calculation, the values are stored in the information string of the input volume to allow quicker future max/min queries when the  $AVW\_QuickVolumeMaxMin$  function is used.

**RETURN VALUES** 

If successful,  $AVW\_FindVolumeMaxMin()$  returns  $AVW\_SUCCESS$ . On failure, it returns  $AVW\_FAIL$  and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_FindVolumeMaxMin() will fail if:

**NOTSUP** 

Data type not supported.

**SEE ALSO** 

 $AVW\_FindImageMaxMin(),\ AVW\_QuickImageMaxMin(),\ AVW\_QuickVolumeMaxMin(),\ AVW\_Volume$ 

NAME | AVW\_FindVolumePoint - returns a volume coordinates position within a rendered

image

**SYNOPSIS** #include "AVW\_Render.h"

int AVW\_FindVolumePoint(rendered, in, out)

AVW\_RenderedImage \*rendered;

AVW\_FPoint3 \*in; AVW\_FPoint3 \*out;

**DESCRIPTION** | Provided with a position within the originating volume,

The point *in*, is specified as an *AVW\_FPoint3* location within the *rendered->Volume*. The

transformed point is returned in an  $AVW\_FPoint3$ .

**RETURN VALUES** | *AVW\_FindVolumePoint()* returns *AVW\_SUCCESS* if *in* can be successfully transformed to

a location within the input volume. It returns AVW\_FAIL if the point transforms to a

location outside the volume.

**SEE ALSO** | *AVW\_DrawRenderedLine()*, *AVW\_DrawRenderedPoint()*, *AVW\_FindRenderedPoint()*,

 $AVW\_Render Volume (),\ AVW\_Render ed Image\ AVW\_FPoint 2,\ AVW\_FPoint 3$ 

AVW\_FlattenImageHistogram - distributes pixel intensities evenly

**SYNOPSIS** 

#include "AVW\_Histogram.h"

AVW\_Image \*AVW\_FlattenImageHistogram(in\_image, max, min, out\_image)

AVW\_Image \*in\_image;

double max, min;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_FlattenImageHistogram() attempts to produce an even distribution of pixels across the grey scale range specified by max and min.

An image which has roughly equal numbers of pixels at every greyscale value will tend to exhibit maximal contrast across the entire greyscale range. Original greyscale values may be brightened, darkened, and or binned together to effect the flattening procedure.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

### **RETURN VALUES**

If successful *AVW\_FlattenImageHistogram()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_FlattenImageHistogram() will fail if the following is true:

**BADMAL** 

Malloc Failed. Could not allocate memory for the results.

**ILLPAR** 

Range of max and min must be less than or equal to the range of in\_image.

**SEE ALSO** 

AVW\_FlattenVolumeHistogram(), AVW\_PreserveImageHistogram(), AVW\_ImageHistogram(), AVW\_Image

AVW\_FlattenVolumeHistogram - distributes voxel intensities evenly

**SYNOPSIS** 

#include "AVW\_Histogram.h"

AVW\_Volume \*AVW\_FlattenVolumeHistogram(in\_vol, max, min, out\_vol)

AVW\_Volume \*in\_vol;

double max, min;

AVW Volume \*out vol;

**DESCRIPTION** 

*AVW\_FlattenVolumeHistogram()* attempts to produce an even distribution of voxels across the grey scale range specified by *max* and *min*.

A volume which has roughly equal numbers of voxels at every greyscale value will tend to exhibit maximal contrast across the entire greyscale range. Original greyscale values may be brightened, darkened, and or binned together to effect the flattening procedure.

Out\_vol is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_vol meet the requirements of the function. In this case the pointer to out\_vol is returned by the function. If not reusable out\_vol will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_FlattenVolumeHistogram()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_FlattenVolumeHistogram() will fail if the following is true:

**BADMAL** 

Malloc Failed. Could not allocate memory for the results.

**ILLPAR** 

Range of max and min must be less than or equal to the range of in\_vol.

**SEE ALSO** 

AVW\_FlattenImageHistogram(), AVW\_PreserveVolumeHistogram(), AVW\_MatchVolumeHistogram(), AVW\_Volume

AVW\_FlipImage - flips an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_FlipImage(in\_image, axes, out\_image)

AVW\_Image \*in\_image;

int axes;

AVW\_Image \*out\_image;

**DESCRIPTION** 

*AVW\_FlipImage()* flips *in\_image* in the specified direction. If *axes* is set to *AVW\_FLIPX* the image will be flipped horizontally. If *axes* is set to *AVW\_FLIPY* the image will be flipped vertically. If *axes* is set to *AVW\_FLIPX* | *AVW\_FLIPY* the image will be flipped in both directions.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_FlipImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_FlipVolume(), AVW\_Image

AVW\_FlipVolume - flips a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_FlipVolume(in\_volume, axes, out\_volume)

AVW\_Volume \*in\_volume;

int axes;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_FlipVolume() flips in\_volume in the specified direction. If axes is set to AVW\_FLIPX the volume will be flipped horizontally. If axes is set to AVW\_FLIPY the volume will be flipped vertically. If axes is set to AVW\_FLIPZ the order of the slices in the volume will be flipped. Any combination of these directions is also valid.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_FlipVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_FlipImage(), AVW\_Volume

AVW\_FormatSupports - determines if image file format supports a property

**SYNOPSIS** 

#include "AVW\_ImageFile.h"

 $int\ AVW\_FormatSupports (format,\ property)$ 

char \*format;
int property;

**DESCRIPTION** 

AVW\_FormatSupports() is used to determine if an image file format supports a property.

format is a character string which identifies the format. property is a property or mask Property values are defined in AVW\_ImageFile.h and include:

AVW\_SUPPORT\_UNSIGNED\_CHAR AVW\_SUPPORT\_SIGNED\_CHAR
AVW\_SUPPORT\_UNSIGNED\_SHORT AVW\_SUPPORT\_SIGNED\_SHORT
AVW\_SUPPORT\_UNSIGNED\_INT AVW\_SUPPORT\_SIGNED\_INT
AVW\_SUPPORT\_FLOAT AVW\_SUPPORT\_COMPLEX AVW\_SUPPORT\_COLOR
AVW\_SUPPORT\_2D AVW\_SUPPORT\_3D AVW\_SUPPORT\_4D AVW\_SUPPORT\_READ
AVW\_SUPPORT\_WRITE

For example to determine if "GE9800" files can be written from AVW,

int ret:

ret = AVW\_FormatSupports("GE9800",AVW\_SUPPORT\_WRITE);
if(ret == AVW\_SUCCESS)

printf("Write Supported0);

else

printf("Write not supporte0);

**RETURN VALUES** 

*AVW\_TRUE* is returned if the image file format does support the property, otherwise *AVW\_FALSE* is returned.

**SEE ALSO** 

AVW\_CreateImageFile(), AVW\_ListFormats(), AVW\_ImageFile

AVW\_Malloc - allocates system memory

### **SYNOPSIS**

#include "AVW.h"

void \*AVW\_Malloc(size)
unsigned int size;

void \*AVW\_Calloc(num, size)
unsigned int num;
unsigned int size;

void \*AVW\_Realloc(size, ptr)
unsigned int size;
void \*ptr;

void AVW\_Free(ptr)
void \*ptr;

## **DESCRIPTION**

These procedures provide a platform and compiler independent interface for memory allocation. Programs that need to transfer ownership of memory blocks between AVW and other modules should use these routines rather than the native malloc() and free() routines provided by the C run-time library.

AVW\_Malloc returns a pointer to a size bytes suitably aligned for any use.

AVW\_Calloc allocates space for an array nelem elements of size elsize. The space is initialized to zeros.

*Tcl\_Realloc* changes the size of the block pointed to by *ptr* to *size* bytes and returns a pointer to the new block. The contents will be unchanged up to the lesser of the new and old sizes. The returned location may be different from *ptr*.

*Tcl\_Free* makes the space referred to by *ptr* available for further allocation.

# **SEE ALSO**

malloc(), free()

AVW\_FunctionImage - applies a function to an image

### **SYNOPSIS**

#include "AVW Parse.h"

AVW\_Image \*AVW\_FunctionImage(function\_code, in\_image, out\_image) int function\_code;

AVW\_Image \*in\_image;

AVW\_Image \*out\_image;

### **DESCRIPTION**

AVW\_FunctionImage() returns an AVW\_Image which is the result of applying a specified function to in\_image.

The following function codes are defined in AVW\_Parse.h:

AVW\_F\_ABS returns the absolute value of each *in\_image* pixel in the corresponding *out\_image* pixel.

AVW\_F\_SQRT returns the square root of each *in\_image* pixel in the corresponding *out\_image* pixel.

*AVW\_F\_LOG* returns the natural log of each *in\_image* pixel in the corresponding *out\_image* pixel.

AVW\_F\_EXP returns the exponential value of each *in\_image* pixel in the corresponding *out\_image* pixel.

AVW\_F\_COUNT returns a counter value in each pixel of out\_image. In\_image is used to determine size only. The counter starts at 1 and increases each time AVW\_FunctionImage() is called.

*AVW\_F\_XPOS* returns the column number in each *out\_image* pixel value. In\_image is used to determine size only. The first column is assigned #1 and the last column is assigned *in\_image->Width*;

AVW\_F\_YPOS returns the row number in each *out\_image* pixel value. In\_image is used to determine size only. The first row is assigned #1 and the last row is assigned *in\_image->Height*;

AVW\_F\_MAX returns an *out\_image* which contains the maximum value within *in\_image* in each of *out\_image* pixels.

*AVW\_F\_MIN* returns an *out\_image* which contains the minimum value within *in\_image* in each of *out\_image* pixels.

*AVW\_F\_AVG* returns an *out\_image* which contains the average value within *in\_image* in each of *out\_image* pixels.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful AVW\_FunctionImage() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** *AVW\_FunctionImage()* will fail if one or more of the following are true:

**NOTSUP** 

Unknown function type, or unsupported input data type.

SEE ALSO | AVW\_FunctionVolume(), AVW\_ConstantOpImage(), AVW\_ImageOpConstant(), AVW\_ImageOpImage(), AVW\_Image

AVW\_FunctionVolume – applies a function to a volume

**SYNOPSIS** 

#include "AVW Parse.h"

 $AVW\_Volume *AVW\_FunctionVolume (function\_code, in\_volume, out\_volume) int function\_code;$ 

AVW\_Volume \*in\_volume;

AVW\_Volume \*out\_volume;

#### DESCRIPTION

AVW\_FunctionVolume() returns an AVW\_Volume which is the result of applying a specified function to *in volume*.

AVW\_FunctionVolume() calls AVW\_FunctionImage() with each slice in the input volume(s) to produce the output volume.

The following function codes are defined in AVW\_Parse.h:

*AVW\_F\_ABS* returns the absolute value of each *in\_volume* voxel in the corresponding *out\_volume* voxel.

*AVW\_F\_SQRT* returns the square root of each *in\_volume* voxel in the corresponding *out\_volume* voxel.

*AVW\_F\_LOG* returns the natural log of each *in\_volume* voxel in the corresponding *out\_volume* voxel.

*AVW\_F\_EXP* returns the exponential value of each *in\_volume* voxel in the corresponding *out\_volume* voxel.

AVW\_F\_COUNT returns a counter value in each voxel of *out\_volume*. In\_volume is used to determine size only. The counter starts at 1 and increases each time AVW\_Functionzvolume() is called.

AVW\_F\_XPOS returns the column number in each *out\_volume* voxel value. In\_volume is used to determine size only. The firdt column is assigned #1 and the last column is assigned *in\_volume->Width*;

*AVW\_F\_YPOS* returns the row number in each *out\_volume* voxel value. In\_volume is used to determine size only. The first row is assigned #1 and the last row is assigned *in\_volume->Height*;

AVW\_F\_MAX returns an *out\_volume* which contains the maximum value within *in\_volume* in each of *out\_volume* voxels.

AVW\_F\_MIN returns an *out\_volume* which contains the minimum value within *in\_volume* in each of *out\_volume* voxels.

*AVW\_F\_AVG* returns an *out\_volume* which contains the average value within *in\_volume* in each of *out\_volume* voxels.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_FunctionVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_FunctionVolume() will fail if one or more of the following are true:

# **NOTSUP**

Unknown function type, or unsupported input data type.

# **SEE ALSO**

 $AVW\_ConstantOpVolume(),\ AVW\_FunctionImage(),\ AVW\_VolumeOpConstant(),\ AVW\_VolumeOpVolume(),\ AVW\_Volume$ 

AVW\_GetBoundaryAndDelete - finds the boundary of a thresholded region

**SYNOPSIS** 

#include "AVW.h"

AVW\_PointList2 \*AVW\_GetBoundaryAndDelete(image, thresh\_max, thresh\_min, seed\_point, del\_value, trace)

AVW\_Image \*image;

double thresh\_max, thresh\_min;

AVW\_Point2 \*seed\_point;

double del\_value;

AVW\_PointList2 \*trace;

## **DESCRIPTION**

AVW\_GetBoundaryAndDelete() finds and returns an AVW\_PointList2, trace, which contains the boundary of the region defined by the <code>seed\_point</code>, <code>threshold\_max</code>, and <code>threshold\_min</code>. The region is grown from the <code>seed\_point</code> and includes all pixels which are connected via four neighbors to it and within the threshold values. The defined region is set to <code>del\_value</code> after the boundary is found.

*Trace* is provided as a method of reusing an existing AVW\_PointList2.

## **RETURN VALUES**

If successful *AVW\_GetBoundaryAndDelete()* returns an *AVW\_PointList2*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_GetBoundaryAndDelete() will fail if:

**ILLDT** 

Data type is not defined or supported.

**ILLIMG** 

An illegal image was passed to the function.

**SEE ALSO** 

AVW\_GetThresholdedBoundary(), AVW\_GetMaskBoundary(), AVW\_ThresholdImage(), AVW\_PointList2, AVW\_Point2, AVW\_Image

AVW\_GetClippedBoundary - returns a boundary for a connected thresholded region

### **SYNOPSIS**

#include "AVW.h"

AVW\_PointList2\* AVW\_GetClippedBoundary ( image, thresh\_max, thresh\_min, seed\_point, type, gap\_size, trace)

AVW\_Image \*inImage; double thresh\_max; double thresh\_min; AVW\_Point2 \*seed\_point; int type; int gap\_size; AVW\_PointList2\* theList;

### **DESCRIPTION**

AVW\_GetClippedBoundary() finds and returns an AVW\_PointList2, trace, which contains the boundary of the region defined by the <code>seed\_point</code>, <code>threshold\_max</code>, and <code>threshold\_min</code>. The region is grown from the <code>seed\_point</code> and includes all pixels which are connected via four neighbors to it and within the threshold values.

*Type specifies whether the returned border* threshold range or off the edge. Valid values are *AVW\_AUTO\_ON\_EDGE* (1) and *AVW\_AUTO\_OFF\_EDGE* (0).

*Gap\_size* specifies the number of layers to be peeled away from and then added back to the thresholded region during the border detection process. Larger values will close the border across thin areas of the object.

Trace is provided as a method of reusing an existing AVW\_PointList2.

### **RETURN VALUES**

If successful AVW\_GetClippedBoundary() returns an AVW\_PointList2. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

## **SEE ALSO**

AVW\_GetThresholdedBoundary(), AVW\_GetBoundaryAndDelete(), AVW\_GetMaskBoundary(), AVW\_ThresholdImage(), AVW\_Point2, AVW\_Image

AVW\_GetCurved - extracts a curved image from a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_GetCurved(volume, orientation, trace)

AVW\_Volume \*volume;

int orientation;

AVW\_PointList2 \*trace;

**DESCRIPTION** 

When supplied with an *AVW\_Volume*, *orientation*, and *trace*, *AVW\_GetCurved()* returns an *AVW\_Image* representing the curved section described. The curved section is constructed by taking the lines perpendicular to each point of the *trace* and putting them into the rows of an image. *Orientation* must be *AVW\_TRANSVERSE*, *AVW\_CORONAL*, or

AVW\_SAGITTAL which are defined in AVW.h.

**RETURN VALUES** 

If successful *AVW\_GetCurved()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_GetCurved()* will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. Couldn't allocate memory.

**ILLPAR** 

Illegal trace or orientation.

**SEE ALSO** 

 $AVW\_AddPoint2(),\ AVW\_CreatePointList2(),\ AVW\_GetOblique(),\ AVW\_GetOrthogonal(),\ AVW\_PointList2,\ AVW\_Volume$ 

NAME	AVW_GetErrorMessage – returns the current error number
SYNOPSIS	#include "AVW.h"
DESCRIPTION	$char *AVW\_GetErrorMessage()$ $AVW\_GetErrorMessage() \ returns \ a \ pointer \ to \ the \ current \ error \ message. \ This \ pointer \ should \ not \ be \ freed \ or \ written \ to.$
SEE ALSO	AVW_Error(), AVW_GetErrorNumber(), AVW_SetError()

.

**NAME** AVW\_GetErrorNumber – returns the current error number

**SYNOPSIS** #include "AVW.h"

#include "AVW\_Error.h"

 $int\ AVW\_GetErrorNumber()$ 

**DESCRIPTION** | *AVW\_GetErrorNumber()* returns the current error number.

A value of zero (NOERR) indicates that no error has occured. See the AVW\_Error.h

include file for specific error values.

SEE ALSO | AVW\_Error(), AVW\_GetErrorMessage(), AVW\_SetError()

**NAME** AVW\_GetFPoint2 – get a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_GetFPoint2(trace, which\_point, point)

AVW\_FPointList2 \*trace;

int which\_point; AVW\_FPoint2 \*point;

**DESCRIPTION** | *AVW\_GetFPoint2()* gets a specific point from a point list.

Trace is an AVW\_FPointList2.

Which\_point specifies the point to get from the list. Acceptable values range from 0 (the

 $first\ point\ in\ the\ list)\ to\ trace-> Number Of Points-1\ (the\ last\ point).$ 

**RETURN VALUES** If successful *AVW\_SUCCESS* is returned, otherwise *AVW\_FAIL* is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** | *AVW\_GetFPoint2* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

**SEE ALSO** | AVW\_GetFPoint3(), AVW\_GetPoint2(), AVW\_GetPoint3(), AVW\_GetIPoint2(),

AVW\_GetPoint3(), AVW\_GetPointValue(), AVW\_AddFPoint2(), AVW\_CreateFPointList2(),

AVW\_RemoveFPoint2(), AVW\_FPoint2, AVW\_FPointList2

**NAME** AVW\_GetFPoint3 – get a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_GetFPoint3(trace, which\_point, point)

AVW\_FPointList3 \*trace;

int which\_point; AVW\_FPoint3 \*point;

**DESCRIPTION** | *AVW\_GetFPoint3()* gets a specific point from a point list.

Trace is an AVW\_FPointList3.

Which\_point specifies the point to get from the list. Acceptable values range from 0 (the

 $first\ point\ in\ the\ list)\ to\ trace-> Number Of Points-1\ (the\ last\ point).$ 

**RETURN VALUES** If successful *AVW\_SUCCESS* is returned, otherwise *AVW\_FAIL* is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** | *AVW\_GetFPoint3* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

SEE ALSO | AVW\_GetFPoint2(), AVW\_GetIPoint2(), AVW\_GetIPoint3(), AVW\_GetPoint2(),

AVW\_GetPoint3(), AVW\_GetPointValue(), AVW\_AddFPoint3(), AVW\_CreateFPointList3(),

AVW\_RemoveFPoint3(), AVW\_FPoint3, AVW\_FPointList3

NAME | AVW\_GetHistogramMedianValue - returns the mode value of a histogram

SYNOPSIS #include "AVW.h"

 $double\ AVW\_GetHistogram Median Value (histogram)$ 

AVW\_Histogram \*histogram;

**DESCRIPTION** | AVW\_GetHistogramMedianValue() returns the value of the histogram bin where half of the

counts in the entire histogram occurs. Two passes through the histogram are made. The first pass calculates the total number of counts in the histogram. The second pass deter-

mines which bin contains the half of total count.

**RETURN VALUES** If successful, AVW\_GetHistogramMedianValue() returns the median value of the histo-

gram. On failure, it returns AVW\_FAIL and sets AVW\_ErrorNumber and

AVW\_ErrorMessage to values corresponding to the cause of the failure. To insure valid

results AVW\_ErrorNumber should be checked after calling this function.

**ERRORS** | *AVW\_GetHistogramMedianValue()* will fail if one or more of the following are true:

**ILLHIS** 

Illegal histogram, histogram is NULL.

 $\textbf{SEE ALSO} \qquad AVW\_CreateHistogram(), \ AVW\_GetHistogramModeValue(), \ AVW\_GetImageHistogram(), \ AVW$ 

AVW\_GetVolumeHistogram(), AVW\_Histogram

**NAME** AVW\_GetHistogramModeValue – returns the mode value of a histogram

SYNOPSIS #include "AVW.h"

double AVW\_GetHistogramModeValue(histogram)

AVW\_Histogram \*histogram;

**DESCRIPTION** | AVW\_GetHistogramModeValue() returns the value of the histogram bin that has the highest

number of counts.

**RETURN VALUES** If successful, *AVW\_GetHistogramModeValue()* returns the mode value of the histogram.

On failure, it returns AVW\_FAIL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to

values corresponding to the cause of the failure. To insure valid results

AVW\_ErrorNumber should be checked after calling this function.

**ERRORS** | *AVW\_GetHistogramModeValue()* will fail if one or more of the following are true:

**ILLHIS** 

Illegal histogram, histogram is NULL.

SEE ALSO | AVW\_CreateHistogram(), AVW\_GetHistogramMedianValue(), AVW\_GetImageHistogram(),

 $AVW\_GetVolumeHistogram(),\ AVW\_Histogram$ 

**NAME** AVW\_GetIPoint2 – get a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_GetIPoint2(trace, which\_point, point)

AVW\_IPointList2 \*trace;

int which\_point; AVW\_IPoint2 \*point;

**DESCRIPTION** | *AVW\_GetIPoint2()* gets a specific point from a point list.

Trace is an AVW\_IPointList2.

Which\_point specifies the point to get from the list. Acceptable values range from 0 (the

first point in the list) to trace->NumberOfPoints-1 (the last point).

**RETURN VALUES** If successful *AVW\_SUCCESS* is returned, otherwise *AVW\_FAIL* is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** *AVW\_GetIPoint2* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

SEE ALSO | AVW\_GetIPoint3(), AVW\_GetFPoint2(), AVW\_GetFPoint3(), AVW\_GetPoint2(),

AVW\_GetPoint3(), AVW\_GetPointValue(), AVW\_AddIPoint2(), AVW\_CreateIPointList2(),

AVW\_RemoveIPoint2(), AVW\_IPoint2, AVW\_IPointList2

**NAME** AVW\_GetIPoint3 – get a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_GetIPoint3(trace, which\_point, point)

AVW\_IPointList3 \*trace;

int which\_point; AVW\_IPoint3 \*point;

**DESCRIPTION** | *AVW\_GetIPoint3()* gets a specific point from a point list.

Trace is an AVW\_IPointList3.

Which\_point specifies the point to get from the list. Acceptable values range from 0 (the

first point in the list) to trace->NumberOfPoints-1 (the last point).

**RETURN VALUES** If successful *AVW\_SUCCESS* is returned, otherwise *AVW\_FAIL* is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** *AVW\_GetIPoint3* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

SEE ALSO | AVW\_GetIPoint2(), AVW\_GetFPoint2(), AVW\_GetFPoint3(), AVW\_GetPoint2(),

AVW\_GetPoint3(), AVW\_GetPointValue(), AVW\_AddIPoint3(), AVW\_CreateIPointList3(),

AVW\_RemoveIPoint3(), AVW\_IPoint3, AVW\_IPointList3

AVW\_GetImageChannel - extracts a specific channel from an AVW\_Color image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_GetImageChannel(in\_image, channel, out\_image)

AVW\_Image \*in\_image;

int channel;

AVW\_Image \*out\_image;

**DESCRIPTION** 

*AVW\_GetImageChannel()* returns the contents of a specified *channel* within the *AVW\_COLOR* image, *in\_image*.

Channel can be specified as any of the following:

AVW\_RED\_CHANNEL - specifies the red channel.

AVW\_GREEN\_CHANNEL - specifies the green channel.

AVW\_BLUE\_CHANNEL - specifies the blue channel.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful AVW\_GetImageChannel() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_GetImageChannel() will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

**ILLPAR** 

Illegal Parameter. in\_image is not AVW\_COLOR or channel specification is invalid.

**SEE ALSO** 

AVW\_GetVolumeChannel(), AVW\_PutImageChannel(), AVW\_MakeColorImage(), AVW\_DestroyImage() AVW\_Image()

AVW\_GetImageHistogram - computes an image histogram

**AVW 3.0** 

**SYNOPSIS** 

#include

"AVW\_Histogram.h"

AVW\_Histogram \*AVW\_GetImageHistogram(in\_image, mask\_image, mask\_value, sumflag, histo)

AVW\_Image \*in\_image;

AVW\_Image \*mask\_image;

int sumflag, mask\_value;

AVW\_Histogram \*histo;

## **DESCRIPTION**

AVW\_GetImageHistogram() computes the histogram, histo, of in\_image. The mask\_image can be used to specify a region of the image for which the histogram is to be computed. Only pixels from the in\_image corresponding to pixels of the mask\_image equal to the mask\_value will be used in the histogram computation. If the mask\_image is equal to NULL the entire in\_image is used to compute the histogram.

*Sumflag,* if set to *AVW\_TRUE,* specifies that the occurrences are summed into *histo. AVW\_FALSE* specifies that the entire histogram is set to zero before the occurrences are counted.

Histo will contain a count of all of the pixels of each intensity within in\_image.

Histo is provided as a method of reusing an existing AVW\_Histogram. Reuse is possible only if the size of the provided histo meets the requirements of the function. In this case the pointer to histo is returned by the function. If not reusable histo will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

### **RETURN VALUES**

If successful *AVW\_GetImageHistogram()* returns an *AVW\_Histogram*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_GetImageHistogram() will fail if the following is true:

**BADMAL** 

Malloc Failed. Could not allocate memory for the results.

**ILLIMG** 

Specified image was not valid.

**NOTSUP** 

Data type not supported.

#### **SEE ALSO**

 $AVW\_Clear Histogram(),\ AVW\_Create Histogram(),\ AVW\_Get Volume Histogram(),\ AVW\_Interval AVW$ 

**NAME** AVW\_GetImageIntensities – returns pixel intensities in a masked image

SYNOPSIS #include "AVW.h"

AVW\_PointValueList \*AVW\_GetImageIntensities(image, mask, mask\_val, pvlist)

AVW\_Image \*image; AVW\_Image \*mask;

int mask\_val;

AVW\_PointValueList \*pvlist;

**DESCRIPTION** | AVW\_GetImageIntensities() returns the X and Y coordinates and pixel value of the pixels

in a  $\,$  masked region. If the mask is  $\it NULL$  the values are returned for every pixel in the

image. The values are returned in an  $AVW\_PointValueList.$ 

**RETURN VALUES** If successful, AVW\_GetImageIntensities() returns an AVW\_PointValueList. On failure, it

returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values correspond-

ing to the cause of the failure.

**SEE ALSO** AVW\_GetPixel(), AVW\_GetVoxel(), AVW\_InterpolatedPixel(), AVW\_NearestNeighborPixel(),

AVW\_PutVoxel(), AVW\_GETBLUE(), AVW\_GETGREEN(), AVW\_GETRED(), AVW\_Image,

AVW\_PointValueList

AVW\_GetLiklihoods – retrieves liklihood data from most recent statistics based multispectral classification

#### **SYNOPSIS**

#include "AVW.h"

AVW\_Volume \*AVW\_GetLiklihoods(interleaved) int interleaved;

### **DESCRIPTION**

AVW\_GetLiklihoods() retrieves the probability and liklihood data from the last multispectral classification performed with AVW\_ClassifyImage() or AVW\_ClassifyVolume() when the autotype parameter is set to one of the statistics based classification algorithms. AVW\_GAUSSIAN\_CLUSTER, AVW\_NEURAL\_NETWORK, or AVW\_PARZEN\_WINDOWS

Once an initial multispectral classification has been performed, the data in the returned liklihood volume can be used in a process of iterative relaxation with the additional AVW functions AVW\_UpdateConfidenceClasses() and AVW\_UpdateImageClassification()

to re-evaluate the classification of individual pixels based on the class assignments of neighboring pixels and the relative probabilities that a pixel belongs to each class.

When *Interleaved* is 1 the returned liklihood volume is interleaved; when 0 the the returned volume is not interleaved.

### **RETURN VALUES**

If successful *AVW\_GetVolume()* returns an *AVW\_Volume*. On failure *NULL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

### **ERRORS**

AVW\_GetLiklihoods() will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

### **SEE ALSO**

 $AVW\_ClassifyImage(),\ AVW\_ClassifyVolume(),\ AVW\_GetScatLiklihoods(), \\ AVW\_UpdateConfidenceClasses(),\ AVW\_UpdateImageClassification()$ 

AVW\_GetMaskBoundary - builds a boundary from a mask

**SYNOPSIS** 

#include "AVW.h"

AVW\_PointList2 \*AVW\_GetMaskBoundary(in\_mask, mask\_value, out\_boundary)

AVW\_Image \*in\_mask;

int mask\_value;

AVW\_PointList2 \*out\_boundary;

**DESCRIPTION** 

AVW\_GetMaskBoundary() builds an AVW\_PointList2 which contains boundary points extracted from an AVW\_Image.

All pixels of value *mask\_value* in the *in\_mask* are taken as belonging to a region. *AVW\_GetMaskBoundary* constructs and returns a connected boundary circumscribing this region. *in\_mask must be of data type* 

Out\_boundary is provided as a method of reusing an existing AVW\_PointList2. Reuse is possible only if the size and data type of the provided out\_boundary meet the requirements of the function. In this case the pointer to out\_boundary is returned by the function. If not reusable out\_boundary will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful AVW\_GetMaskBoundary() returns an AVW\_PointList2. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_AddPoint2(), AVW\_DestroyPointList2(), AVW\_FindImageEdges(), AVW\_CreatePointList2(), AVW\_MakeFPointList2()

AVW\_GetMaskedImage - extracts an irregular area from an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_GetMaskedImage( in\_image, mask, out\_image)

AVW\_Image \*in\_image;

AVW\_Image \*mask;

AVW\_Image \*out\_image;

### **DESCRIPTION**

For each non-zero pixel in *mask*, a the corresponding value is copied from *in\_image* to *out\_image*. Each zero pixel in *mask*, results in a background pixel in the corresponding location in The background value is determined by a call to *AVW\_MinimumDataValue()*.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful,  $AVW\_GetMaskedImage()$  returns an  $AVW\_Image$ . On failure, it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_GetMaskedImage() will fail if one or more of the following are true:

**ILLVOL** 

Not a legal input volume.

**BADMAL** 

Couldn't allocate enough memory.

**SEE ALSO** 

AVW\_PutMaskedImage(), AVW\_DestroyImage(), AVW\_Image

AVW\_GetMaskedVolume – extracts an irregular region from a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_GetMaskedVolume(in\_volume, mask, out\_volume)

AVW\_Volume \*in\_volume;

AVW\_Volume \*mask;

AVW Volume \*out volume;

**DESCRIPTION** 

For each non-zero voxel in *mask*, a the corresponding value is copied from *in\_volume* to *out\_volume*. Each zero voxel in *mask*, results in a background voxel in the corresponding location in The background value is determined by a call to *AVW\_MinimumDataValue()*.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful,  $AVW\_GetMaskedVolume()$  returns an  $AVW\_Volume$ . On failure, it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_GetMaskedVolume() will fail if one or more of the following are true:

**ILLVOL** 

Not a legal input volume.

**BADMAL** 

Couldn't allocate enough memory.

**SEE ALSO** 

AVW\_PutMaskedVolume(), AVW\_DestroyVolume(), AVW\_Volume

AVW\_GetNumericInfo - gets a numeric value from an AVW information string

**SYNOPSIS** 

#include "AVW.h"

double AVW\_GetNumericInfo(match\_string, info\_string)
char \*match\_string, \*info\_string;

## **DESCRIPTION**

 $AVW\_GetNumericInfo()$  is used to retrieve a numeric value and from an AVW information string.

*Match\_string* is a zero terminated string which must match an entry in an information string exactly in order to get, update, or remove information.

*Info\_string* can be any zero terminated string. Each entry within the information string begins with a tag followed by an equal sign (=) and then the value. A space character is used as a seperator between entries. String information is enclosed in double quotes (") to allow for spaces within strings.

Info strings are used in AVW structures to carry optional additional information about the data that may not always be present and to allow the user to extend AVW structures to carry application dependant data.

The numeric value is returned as a double if the *match\_string* entry is found within *info\_string*. If the *match\_string* is not found in the *info\_string* 0.0 is returned. To verify whether a match was actually found in the *info\_string* check if the the value of *AVW ErrorNumber* is *NOMTCH*.

```
ysize = AVW_GetNumericInfo("VoxelHeight", img->Info);
if(AVW_ErrorNumber == NOMTCH)
  fprintf(stderr, "VoxelHeight not found in info_string");
else
  printf("Y Size=%f\n", ysize);
```

### **RETURN VALUES**

If successful *AVW\_GetNumericInfo()* returns a double numeric value. On failure it returns 0.0 and sets *AVW\_ErrorNumber* to a value corresponding to the cause of the failure.

#### **ERRORS**

AVW\_GetNumericInfo() will fail if one or more of the following are true:

#### **NOMTCH**

No match string was found in the info\_string.

### **BDMTCH**

Something is wrong with the info\_string.

## **SEE ALSO**

 $AVW\_GetStringInfo(),\ AVW\_PutHistoryInfo(),\ AVW\_PutNumericInfo(),\ AVW\_Image,\ AVW\_ImageFile,\ AVW\_Volume$ 

AVW\_GetObject – extracts an object from an object map

**SYNOPSIS** 

#include "AVW\_ObjectMap.h"

AVW\_Volume \*AVW\_GetObject(object\_map, object, out\_volume)

AVW\_ObjectMap \*object\_map;

int object;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

When supplied with a *AVW\_ObjectMap* and object number, *AVW\_GetObject()* extracts and returns the desired object in an *AVW\_Volume*.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful,  $AVW\_GetObject()$  returns an  $AVW\_Volume$ . On failure, it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_GetObject() will fail if one or more of the following are true:

**ILLPAR** 

Specified *object* not in the *object\_map*.

**BADMAL** 

Couldn't allocate enough memory.

**SEE ALSO** 

AVW\_AddObject(), AVW\_CreateObjectMap(), AVW\_DeleteObject(), AVW\_DestroyObjectMap(), AVW\_PutObject(), AVW\_LoadObjectMap(), AVW\_SaveObjectMap(), AVW\_ObjectMap, AVW\_Volume

AVW\_GetOblique - extracts an oblique image from a volume

### **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_GetOblique(volume, matrix, interpolate, out\_image)

AVW\_Volume \*volume;

AVW\_Matrix \*matrix;

int interpolate:

AVW\_Image \*out\_image;

#### **DESCRIPTION**

*AVW\_GetOblique()* is used to extract an oblique plane from an *AVW\_Volume*. The identity matrix yields the middle slice from the XY volume plane.

The orientation of the plane may be specified by: directly manipulating the *matrix* with  $AVW\_TranslateMatrix()$ ,  $AVW\_RotateMatrix()$ ,  $AVW\_ScaleMatrix()$ , or  $AVW\_MirrorMatrix()$ ; or setting the *matrix* with  $AVW\_MakeMatrixFrom3Points()$  or  $AVW\_MakeMatrixFromAxis()$ .

The common oblique manuevers may be accomplished using *AVW\_RotateMatrix()* and *AVW\_TranslateMatrix()* as follows:

### **ROLL**

tmat=AVW\_RotateMatrix(tmat,angle,0.,0.,tmat);

## **PITCH**

tmat=AVW\_RotateMatrix(tmat,0.,angle.,0.,tmat);

### YAW

tmat=AVW\_RotateMatrix(tmat,0.,0.,angle,tmat);

#### **ELEVATE**

tmat=AVW\_TranslateMatrix(tmat,0.,0.,voxels,tmat);

## **SLIDE**

tmat=AVW\_TranslateMatrix(tmat,0.,voxels,0.,tmat);

## **SLIP**

tmat=AVW\_TranslateMatrix(tmat,voxels,0.,0.,tmat);

# Example: Pitch 45 degrees

/\* This example shows how two matrices are used to get an oblique image relative to the last one generated \*/

/\* matrix represents the current orientation of the oblique image \*/

/\* tmat represents the desired relative manuever \*/

tmat = AVW\_CreateMatrix(4,4);

tmat = AVW\_RotateMatrix(tmat, 45.0, 0., 0., tmat);

/\* Applies relative manuever to the current orientation \*/

matrix = AVW\_MultiplyMatrix(matrix, tmat, matrix);
AVW\_Destroymatrix(tmat);

oblq\_img = AVW\_GetOblique(vol, matrix, iflag, oblq\_img);

*Interpolate* determines the method of interpolation to use. Choose from: *AVW\_NEAREST\_NEIGHBOR\_INTERPOLATE* 

AVW\_LINEAR\_INTERPOLATE

AVW\_CUBIC\_SPLINE\_INTERPOLATE

AVW\_WINDOWED\_SINC\_INTERPOLATE

Out\_image is provided as a method of reusing an existing AVW\_Image. If out\_image is NULL and image will be created using the Width and Height of the volume. Otherwise the returned image determines is determined by the size of out\_image. In this way it is possible to generate small oblique images centered on a specific are of interest or large enough to include all voxels from the volume in the plane.

Reuse is possible only if data type of the provided <code>out\_image</code> are the same as the volume. In this case the pointer to <code>out\_image</code> is returned by the function. If not reuseable <code>out\_image</code> will be reallocated. (See <code>Memory Usage</code> in the <code>AVW Programmer</code>'s <code>Guide.</code>)

### **RETURN VALUES**

If successful *AVW\_GetOblique()* returns an *AVW\_Image* containing the specified oblique image. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

### **ERRORS**

AVW\_GetOblique() will fail if:

**ILLVOL** 

Not a legal input volume.

#### **SEE ALSO**

AVW\_GetCurved(), AVW\_GetOrthogonal(), AVW\_MakeMatrixFrom3Points(), AVW\_MakeMatrixFromAxis(), AVW\_RotateMatrix(), AVW\_MirrorMatrix(), AVW\_ScaleMatrix(), AVW\_SetIdentityMatrix(), AVW\_TranslateMatrix() AVW\_PutOblique(), AVW\_Image, AVW\_Matrix, AVW\_Volume

AVW\_GetOrthogonal - extracts an orthogonal image from a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_GetOrthogonal(vol, orient, slice, out\_image)

AVW\_Volume \*vol;

int orient;

int slice:

AVW\_Image \*out\_image;

#### **DESCRIPTION**

When supplied with a *AVW\_Volume*, *orient*, and *slice* number, *AVW\_GetOrthogonal()* extracts and returns the desired orthogonal *AVW\_Image*.

AVW numbers volume slices from 0 to (n-1). This means that acceptable slice values for Transverse slices are 0 to (vol->Depth-1). Coronal slices number from 0 to (vol->Width-1) and Sagittal slices number from 0 to (vol->Height-1).

AVW\_TRANSVERSE 0 - (vol->Depth-1) vol->Width X vol->Height

AVW\_CORONAL 0 - (vol->Height-1) vol->Width X vol->Depth

AVW\_SAGITTAL 0 - (vol->Width-1) vol->Height X vol->Depth

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

### **RETURN VALUES**

If successful,  $AVW\_GetOrthogonal()$  returns an  $AVW\_Image$ . On failure, it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_GetOrthogonal() will fail if one or more of the following are true:

**ILLVOL** 

Not a legal input volume.

**BADMAL** 

Couldn't allocate enough memory.

# **SEE ALSO**

AVW\_GetCurved(), AVW\_GetOblique(), AVW\_PutOrthogonal(), AVW\_Image, AVW\_Volume

AVW\_GetOutsideEdges - builds a set of edges from a mask

**SYNOPSIS** 

#include "AVW.h"

AVW\_MultiList2 \*AVW\_GetOutsideEdges(in\_mask, mask\_value, connectivity, Out\_boundaries)

AVW\_Image \*in\_mask;

int mask\_value;

int connectivity;

AVW\_MultiList2 \*Out\_boundaries;

# **DESCRIPTION**

AVW\_GetOutsideEdges() builds an AVW\_MultiList2 which contains a set of all edges with an AVW\_Image at a given mask\_value.

All pixels of value *mask\_value* in the *in\_mask* are taken as belonging to a region. *AVW\_GetOutsideEdges* constructs and returns a set of connected boundaries circumscribing this region. *in\_mask must be of data type* 

Out\_boundaries is provided as a method of reusing an existing AVW\_MultiList2. Reuse is possible only if the size and data type of the provided Out\_boundaries meet the requirements of the function. In this case the pointer to Out\_boundaries is returned by the function. If not reusable Out\_boundaries will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_GetOutsideEdges()* returns an *AVW\_MultiList2*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **SEE ALSO**

AVW\_DestroyMultiList2(), AVW\_CreateMultiList2(), AVW\_MultiList2,

AVW\_GetPixel - returns pixel intensity at a location in an image

## **SYNOPSIS**

#include "AVW.h"

double AVW\_GetPixel(image, point) AVW\_Image \*image; AVW\_Point2 \*point;

# **DESCRIPTION**

AVW\_GetPixel() returns the value found at the location in image specified by point.

Note that fast access to the pixel value is available by referencing the image memory directly. In large loops, direct manipulation of a pointer to the data memory will yield the fastest results.

# Example 1:

```
register unsigned char *rmem;
rmem = image->Mem;
value = *(rmem + image->YTable[point->Y] + point->X);

Example 2:
register unsigned char *rmem;
rmem = image->Mem;
num = image->PixelsPerImage;
while(num--)
{
    value = *rmem;
    rmem++;
}
```

For an *AVW\_COLOR* image, the red, green and blue components of the pixel are packed into the returned value.

```
value = red << 16 | green << 8 | blue
```

#### **RETURN VALUES**

If successful,  $AVW\_GetPixel()$  returns the pixel value at *point* in the  $AVW\_Image$ . On failure, it returns 0.0 and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_GetPixel() will fail if one or more of the following are true:

**ILLPAR** 

Point specified is outside of the image.

ILLDT

Illegal datatype.

## **SEE ALSO**

 $AVW\_GetVoxel(),\ AVW\_PutPixel(),\ AVW\_InterpolatedPixel(),\ AVW\_NearestNeighborPixel(),\ AVW\_PutVoxel(),\ AVW\_GETBLUE(),\ AVW\_GETGREEN(),\ AVW\_GETRED(),\ AVW\_Image,\ AVW\_Point2$ 

**NAME** AVW\_GetPoint2 – get a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_GetPoint2(trace, which\_point, point)

AVW\_PointList2 \*trace;

int which\_point; AVW\_Point2 \*point;

**DESCRIPTION** | AVW\_GetPoint2() gets a specific point from a point list.

Trace is an AVW\_PointList2.

Which\_point specifies the point to get from the list. Acceptable values range from 0 (the

first point in the list) to trace->NumberOfPoints-1 (the last point).

**RETURN VALUES** If successful *AVW\_SUCCESS* is returned, otherwise *AVW\_FAIL* is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** | *AVW\_GetPoint2* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

SEE ALSO | AVW\_GetPoint3(), AVW\_GetFPoint2(), AVW\_GetFPoint3(), AVW\_GetIPoint2(),

AVW\_GetIPoint3(), AVW\_GetPointValue(), AVW\_AddPoint2(), AVW\_CreatePointList2(),

AVW\_RemovePoint2(), AVW\_Point2, AVW\_PointList2

**NAME** AVW\_GetPoint3 – get a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_GetPoint3(trace, which\_point, point)

AVW\_FPointList3 \*trace;

int which\_point; AVW\_Point3 \*point;

**DESCRIPTION** | *AVW\_GetPoint3()* gets a specific point from a point list.

Trace is an AVW\_PointList3.

*Which\_point* specifies the point to get from the list. Acceptable values range from 0 (the first point in the list) to trace->NumberOfPoints-1 (the last point).

**RETURN VALUES** If successful *AVW\_SUCCESS* is returned, otherwise *AVW\_FAIL* is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** | *AVW\_GetPoint3* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

SEE ALSO | AVW\_GetPoint2(), AVW\_GetFPoint2(), AVW\_GetFPoint3(), AVW\_GetIPoint2(),

AVW\_GetIPoint3(), AVW\_GetPointValue(), AVW\_AddPoint3(), AVW\_CreatePointList3(),

AVW\_RemovePoint3(), AVW\_Point3, AVW\_FPointList3

**NAME** AVW\_GetPointValue - get a point from a list

**SYNOPSIS** #include "AVW.h"

int AVW\_GetPointValue(trace, which\_point, point, value)

AVW\_PointValueList \*trace;

int which\_point; AVW\_Point2 \*point;

double \*value;

**DESCRIPTION** AVW\_GetPointValue() gets a specific point and value from a point list.

Trace is an AVW\_PointValueList.

Which\_point specifies the point and value to get from the list. Acceptable values range from 0 (the first point in the list) to trace->NumberOfPoints-1 (the last point).

**RETURN VALUES** If successful AVW\_SUCCESS is returned, otherwise AVW\_FAIL is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** *AVW\_GetPointValue* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

**SEE ALSO** AVW\_GetFPoint2(), AVW\_GetFPoint3(), AVW\_GetIPoint2(), AVW\_GetIPoint3(),

AVW\_GetPoint2(), AVW\_GetPoint3(), AVW\_AddPointValue(), AVW\_CreatePointValueList(),

AVW\_RemovePointValue(), AVW\_PointValue, AVW\_PointValueList

AVW\_GetScatLiklihoods – retrieves liklihood data from most recent scattergram classification

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_GetScatLiklihoods(in\_img1, in\_img2, climg, interleaved)

AVW\_Image \*in\_img1; AVW\_Image \*in\_img2; AVW\_Image \*climg;

int interleaved;

**DESCRIPTION** 

AVW\_GetScatLiklihoods() retrieves the probability and liklihood data from the last scatter-gram classification performed with AVW\_ClassifyScattergram() when the autotype parameter is set to one of the statistics based classification algorithms:

AVW\_GAUSSIAN\_CLUSTER, AVW\_NEURAL\_NETWORK, or

AVW\_PARZEN\_WINDOWS

When *Interleaved* is 1 the returned liklihood volume is interleaved; when 0 the the returned volume is not interleaved.

**RETURN VALUES** 

If successful *AVW\_GetVolume()* returns an *AVW\_Volume*. On failure *NULL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_GetLiklihoods() will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

**SEE ALSO** 

AVW\_ClassifyImage(), AVW\_ClassifyVolume(), AVW\_GetLiklihoods(), AVW\_UpdateConfidenceClasses(), AVW\_UpdateImageClassification()

AVW\_GetStringInfo – gets a string from an AVW information string

#### **SYNOPSIS**

#include "AVW.h"

char \*AVW\_GetStringInfo(match\_string, info\_string)
char \*match\_string, \*info\_string;

## **DESCRIPTION**

AVW\_GetStringInfo() is used to retrieve a text string from an AVW information string.

*Match\_string* is a zero terminated string which must match an entry in an information string exactly in order to get information.

*Info\_string* can be any zero terminated string. Each entry within the information string begins with a tag followed by an equal sign (=) and then the value. A space character is used as a seperator between entries. String information is enclosed in double quotes (") to allow for spaces within strings.

Info strings are used in AVW structures to carry optional additional information about the data that may not always be present and to allow the user to extend *AVW* structures to carry application dependant data.

The string is returned if the *match\_string* entry is found within *info\_string*. If the *match\_string* is not found in the *info\_string NULL* is returned.

# Example:

```
\begin{split} & img\text{--}Info = AVW\_PutStringInfo("Name", "John Doe", img\text{--}Info); \\ & printf("\%s\n", img\text{--}Info); \\ & if((name = AVW\_GetStringInfo("Name", img\text{--}Info)) == NULL) \\ & fprintf(stderr, "Name not found in info\_string"); \\ & else \\ & \{ & printf("Name=\%s\n", name); \\ & AVW\_Free(name); \\ & \} \end{split}
```

#### **Results:**

Name="John Doe" Name=John Doe

# **RETURN VALUES**

If successful *AVW\_GetStringInfo()* returns a pointer to a character string. AVW\_Free() must be called to free this string when it is no longer needed. On failure it returns *NULL* and sets *AVW\_ErrorNumber* to a value corresponding to the cause of the failure.

# **ERRORS**

AVW\_GetStringInfo() will fail if one or more of the following are true:

## **NOMTCH**

No match string was found in the info\_string.

## **SEE ALSO**

AVW\_GetNumericInfo(), AVW\_PutHistoryInfo(), AVW\_PutNumericInfo(), AVW\_PutStringInfo(), AVW\_RemoveInfo(), AVW\_Image, AVW\_ImageFile, AVW\_Volume

AVW\_GetSubImage – extracts a sub-region from an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_GetSubImage(input\_image, region, out\_image)

 $AVW\_Image * input\_image;$ 

AVW\_Rect2 \*region;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_GetSubImage() extracts a subregion defined by region from an input\_image.

With (0, 0) as the first pixel in <code>input\_image</code>, <code>region->PointA.X</code>, <code>region->PointA.Y</code>, <code>region->PointB.Y</code> and <code>region->PointB.Y</code> specify the rectangular region to be extracted.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful, *AVW\_GetSubImage()* returns an *AVW\_Image*. On failure, it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_GetSubImage() will fail if one or more of the following are true:

**ILLPAR** 

Illegal subregion.

**BADMAL** 

Couldn't allocate enough memory.

**SEE ALSO** 

AVW\_GetSubImageWithIncrements(), AVW\_GetSubVolume(), AVW\_PadImage(), AVW\_PutSubImage(), AVW\_Rect2, AVW\_Image

AVW\_GetSubImageWithIncrements – extracts a sub-region from an image (with increments)

**SYNOPSIS** 

#include "AVW.h"

 $AVW\_Image *AVW\_GetSubImageWithIncrements (input\_image, region, xinc, yinc, out\_image)$ 

AVW\_Image \*input\_image;

AVW\_Rect2 \*region

int xinc, yinc;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_GetSubImageWithIncrements() extracts a subregion defined by region from an input\_image.

With (0, 0) as the first pixel in <code>input\_image</code>, <code>region->PointA.X</code>, <code>region->PointA.Y</code>, <code>region->PointB.Y</code>, and <code>region->PointB.Y</code> specify the rectangular region to be extracted.

*Xinc* and *yinc* specify that only every *xinc* th and *yinc* th pixel is extracted.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful,  $AVW\_GetSubImageWithIncrements()$  returns an  $AVW\_Image$ . On failure, it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the failure.

**ERRORS** 

AVW\_GetSubImageWithIncrements() will fail if one or more of the following are true:

**ILLPAR** 

Illegal subregion.

**BADMAL** 

Couldn't allocate enough memory.

**SEE ALSO** 

AVW\_GetSubImage(), AVW\_Rect2, AVW\_Image

AVW\_GetSubVolume - extracts a sub-volume from a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_GetSubVolume(input\_volume, region, out\_volume)

AVW\_Volume \*input\_volume;

AVW\_Rect3 \*region;

AVW Volume \*out volume;

DESCRIPTION

AVW\_GetSubVolume() extracts a subregion defined by region from an input\_volume.

With (0, 0, 0) as the first voxel of *input\_volume*, *region->PointA.X*, *region->PointA.Y*, *region->PointB.X*, *region->PointB.X*, *region->PointB.Z* specifies the region to be extracted.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful,  $AVW\_GetSubVolume()$  returns an  $AVW\_Volume$ . On failure, it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_GetSubVolume()* will fail if one or more of the following are true:

**ILLPAR** 

Illegal subregion.

**BADMAL** 

Couldn't allocate enough memory.

**SEE ALSO** 

 $AVW\_GetSubImage(),\ AVW\_PadVolume(),\ AVW\_PutSubVolume(),\ AVW\_Volume,\ AVW\_Rect3$ 

AVW\_GetThresholdedBoundary – finds the boundary of a thresholded region

**SYNOPSIS** 

#include "AVW.h"

 $AVW\_PointList2*AVW\_GetThresholdedBoundary(image, thresh\_max, thresh\_min, seed\_point, trace)$ 

AVW\_Image \*image;

double thresh\_max, thresh\_min;

AVW\_Point2 \*seed\_point;

AVW\_PointList2 \*trace;

**DESCRIPTION** 

AVW\_GetThresholdedBoundary() finds and returns an AVW\_PointList2, trace, which contains the boundary of the region defined by the <code>seed\_point</code>, <code>threshold\_max</code>, and <code>threshold\_min</code>. The region is grown from the <code>seed\_point</code> and includes all pixels which are connected via four neighbors to it and within the threshold values.

*Trace* is provided as a method of reusing an existing AVW\_PointList2.

**RETURN VALUES** 

If successful *AVW\_GetThresholdedBoundary()* returns an *AVW\_PointList2*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_GetThresholdedBoundary() will fail if:

ILLDT

Data type is not defined or supported.

**ILLIMG** 

An illegal image was passed to the function.

**SEE ALSO** 

AVW\_GetBoundaryAndDelete(), AVW\_GetMaskBoundary(), AVW\_ThresholdImage(), AVW\_PointList2, AVW\_Point2, AVW\_Image

AVW\_GetVolumeChannel - extracts a specific channel from an AVW\_Color volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_GetVolumeChannel(in\_volume, channel, out\_volume)

**AVW 3.0** 

AVW\_Volume \*in\_volume;

int channel;

AVW Volume \*out volume:

**DESCRIPTION** 

*AVW\_GetVolumeChannel()* returns the contents of a specified *channel* within the *AVW\_COLOR* volume, *in\_volume*.

Channel can be specified as any of the following:

AVW\_RED\_CHANNEL - specifies the red channel.

AVW\_GREEN\_CHANNEL - specifies the green channel.

AVW\_BLUE\_CHANNEL - specifies the blue channel.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_GetVolumeChannel()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_GetVolumeChannel() will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

**SEE ALSO** 

AVW\_GetImageChannel(), AVW\_MakeColorVolume(), AVW\_DestroyVolume()
AVW\_Volume()

AVW\_GetVolumeHistogram - computes a volume histogram

**SYNOPSIS** 

#include

"AVW\_Histogram.h"

AVW\_Histogram \*AVW\_GetVolumeHistogram(in\_volume, mask\_volume, mask\_value, histo)

AVW\_Volume \*in\_volume;

AVW\_Volume \*mask\_volume;

int mask value:

AVW\_Histogram \*histo;

## **DESCRIPTION**

AVW\_GetVolumeHistogram() computes the histogram, histo, of in\_volume. The mask\_volume may be used to specify a region of the volume for which the histogram is to be computed. Only voxels from the in\_volume corresponding to voxels of the mask\_volume equal to the mask\_value will be used in the histogram computation. If the mask\_volume is equal to NULL, mask\_volume and mask\_value are ignored and the entire in\_volume is used to compute the histogram.

Histo will contain a count of all of the pixels of each intensity within in\_volume.

*Histo* is provided as a method of reusing an existing *AVW\_Histogram*. Reuse is possible only if the size of the provided *histo* meets the requirements of the function. In this case the pointer to *histo* is returned by the function. If not reusable *histo* will be reallocated. (See *Memory Usage* in the *AVW Programmer's Guide.*)

## **RETURN VALUES**

If successful *AVW\_GetVolumeHistogram()* returns an *AVW\_Histogram*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

*AVW\_GetVolumeHistogram()* will fail if the following is true:

**BADMAL** 

Malloc Failed. Could not allocate memory for the results.

**ILLVOL** 

Specified volume was not valid.

**NOTSUP** 

Data type not supported.

### **SEE ALSO**

AVW\_GetImageHistogram(), AVW\_ClearHistogram(), AVW\_CreateHistogram(), AVW\_NormalizeHistogram(), AVW\_VerifyHistogram(), AVW\_Volume, AVW\_Histogram

AVW\_GetVoxel - returns the voxel intensity at a location in a volume

## **SYNOPSIS**

#include "AVW.h"

double AVW\_GetVoxel(volume, point) AVW\_Volume \*volume; AVW\_Point3 \*point;

# **DESCRIPTION**

*AVW\_GetVoxel()* returns the value found at the location in *volume* specified by *point*. Note that fast access to the voxel value is available by referencing the volume memory directly. In large loops, direct manipulation of a pointer to the data memory will yield the fastest results.

# Example 1:

For an *AVW\_COLOR* image, the red, green and blue components of the voxel are packed into the returned value.

```
value = red << 16 | green << 8 | blue
```

#### **RETURN VALUES**

If successful,  $AVW\_GetVoxel()$  returns the voxel value at *point* in the  $AVW\_Volume$ . On failure, it returns 0.0 and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure. To insure valid results  $AVW\_ErrorNumber$  should be checked after calling this function.

## **ERRORS**

*AVW\_GetVoxel()* will fail if one or more of the following are true:

**ILLPAR** 

value = \*rmem; rmem++;

Point specified is outside of the volume.

**ILLDT** 

Illegal datatype.

## **SEE ALSO**

AVW\_GetPixel(), AVW\_PutPixel(), AVW\_InterpolatedVoxel(), AVW\_NearestNeighborVoxel(), AVW\_PutVoxel(), AVW\_GETBLUE(), AVW\_GETGREEN(), AVW\_GETRED(), AVW\_Point3, AVW\_Volume

AVW\_HomotopicThickenImage - performs homtopic thickening on an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_HomotopicThickenImage(in\_image, cond\_image, iterations, out\_image)

AVW\_Image \*in\_image;

AVW\_Image \*cond\_image;

int iterations:

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_HomotopicThickenImage() performs 2D homotopic thickening on in\_image. Cond\_image is used as a conditioning image which limits the areas into which the image may be thickened. If cond\_image is equal to NULL the thickening will not be constrained. The image is thickened iterations times or until no more changes can be made. If iterations is less than or equal to zero the image will be thickened until only a single pixel border seperates distinct objects or the thickened image matches cond\_image. The thickened image is returned in out\_image.

*In\_image* has to be a binary valued, i.e. ones and zeroes. *In\_image*, and *out\_image* must be of the data type *AVW\_UNSIGNED\_CHAR*. This function will allocate temporary storage space for results if *in\_image* and *out\_image* are the same.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_HomotopicThickenImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_HomotopicThickenImage() will fail if:

**ILLDT** 

Data type is not AVW\_UNSIGNED\_CHAR.

**SEE ALSO** 

AVW\_Thin2D(), AVW\_HomotopicThickenVolume(), AVW\_Image

AVW\_HomotopicThickenVolume - performs homtopic thickening on an volume

**SYNOPSIS** 

#include "AVW.h"

 $AVW\_Volume *AVW\_HomotopicThickenVolume (in\_volume, cond\_volume, iterations, out\_volume)$ 

AVW\_Volume \*in\_volume;

AVW\_Volume \*cond\_volume;

int iterations:

AVW\_Volume \*out\_volume;

#### **DESCRIPTION**

AVW\_HomotopicThickenVolume() performs 2D homotopic thickening on in\_volume. Cond\_volume is used as a conditioning volume which limits the areas into which the volume may be thickened. If cond\_volume is equal to NULL, the thickening will not be constrained. The volume is thickened iterations times or until no more changes can be made. If iterations is less than or equal to zero the volume will be thickened until only a single pixel border seperates distinct objects or the thickened volume matches cond\_volume. The thickened volume is returned in out\_volume.

*In\_volume* has to be a binary valued, i.e. ones and zeroes. *In\_volume*, and *out\_volume* must be of the data type *AVW\_UNSIGNED\_CHAR*. This function will allocate temporary storage space for results if *in\_volume* and *out\_volume* are the same.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful  $AVW\_HomotopicThickenVolume()$  returns an  $AVW\_Volume$ . On failure it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_HomotopicThickenVolume() will fail if:

**ILLDT** 

Data type is not AVW\_UNSIGNED\_CHAR.

**SEE ALSO** 

AVW\_Thin3D(), AVW\_HomotopicThickenImage(), AVW\_Volume

AVW\_ImageOpConstant - transforms an image mathematically

**SYNOPSIS** 

#include "AVW Parse.h"

AVW\_Image \*AVW\_ImageOpConstant(in\_image, operation, value, out\_image)

AVW\_Image \*in\_image;

int operation;

double value;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_ImageOpConstant() applies the operation and value to in\_image and returns the resulting image:

output = in\_image operation value

The following operations are defined in *AVW\_Parse.h*:

 $AVW\_OP\_ADD\ AVW\_OP\_SUB\ AVW\_OP\_MUL\ AVW\_OP\_DIV\ AVW\_OP\_LT$   $AVW\_OP\_GT\ AVW\_OP\_LE\ AVW\_OP\_GE\ AVW\_OP\_EQ\ AVW\_OP\_NE$   $AVW\_OP\_AND\ AVW\_OP\_OR\ AVW\_OP\_MOD$ 

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful AVW\_ImageOpConstant(), returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ImageOpConstant() will fail if one or more of the following are true:

**NOTSUP** 

Operation is not supported.

**DIVZER** 

Division by zero.

**BADMAL** 

Memory could not be allocated for results.

**ILLDT** 

Data type is not defined or supported.

# **SEE ALSO**

 $AVW\_ConstantOpImage(),\ AVW\_ImageOpImage(),\ AVW\_VolumeOpConstant(),\ AVW\_FunctionImage(),\ AVW\_Image$ 

AVW\_ImageOpImage - transforms an image mathematically

**SYNOPSIS** 

#include "AVW Parse.h"

AVW\_Image \*AVW\_ImageOpImage(in\_image1, operation, in\_image2, out\_image)

AVW\_Image \*in\_image1;

int operation;

AVW\_Image \*in\_image2;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_ImageOpImage() applies the operation and in\_image2 to in\_image1 and returns the resulting image:

output = in\_image1 operation in\_image2

The following operations are defined in AVW\_Parse.h:

 $AVW\_OP\_ADD$ 

AVW\_OP\_SUB

AVW\_OP\_MUL

AVW\_OP\_DIV

 $AVW_OP_LT$ 

 $AVW_OP_GT$ 

 $AVW\_OP\_LE$ 

 $AVW_OP_GE$ 

 $AVW\_OP\_EQ$ 

 $AVW\_OP\_NE$ 

 $AVW\_OP\_AND$ 

AVW\_OP\_OR

 $AVW\_OP\_MOD$ 

Out\_image is provided as a method of reusing an existing AVW\_Image or AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_ImageOpImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_ImageOpImage() will fail if one or more of the following are true:

**NOTSUP** 

Operation is not supported.

**DIVZER** 

Division by zero.

**BADMAL** 

Memory could not be allocated for results.

**ILLDT** 

Data type is not defined or supported.

**CFLSZ** 

Input images conflict in size.

# **SEE ALSO**

AVW\_ConstantOpImage(), AVW\_ImageOpConstant(), AVW\_VolumeOpVolume(), AVW\_FunctionImage(), AVW\_DestroyImage(), AVW\_Image

AVW\_ImageSampleEntropy - Calculate the entropy of a sample of voxels

**SYNOPSIS** 

#include "AVW MatchVoxels.h"

double AVW\_ImageSampleEntropy(image,points,interpolate)

AVW\_Image \*image;

AVW\_FPointList2 \*points;

int interpolate;

## **DESCRIPTION**

*AVW\_ImageSampleEntropy()* calculates the entropy of a sample of pixels defined by a list of floating-point 2-D coordinates.

Interpolate determines the method of interpolation to use. Choose from:

AVW\_NEAREST\_NEIGHBOR\_INTERPOLATE

AVW\_LINEAR\_INTERPOLATE

AVW\_CUBIC\_SPLINE\_INTERPOLATE

 $AVW\_WINDOWED\_SINC\_INTERPOLATE$ 

## **RETURN VALUES**

If successful returns the entropy.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ImageSampleEntropy() will fail if the following is true:

**ILLIMG** 

Illegal Image.

**ILLPAR** 

Interpolation type is not recognized.

## **SEE ALSO**

AVW\_ImageSampleJointEntropy(), AVW\_ImageSampleNMI(), AVW\_VolumeSampleEntropy().

 $AVW\_ImageSampleJointEntropy-Calculate \ the \ joint \ entropy \ of \ a \ sample \ of \ pixels \ from \ two \ images$ 

## **SYNOPSIS**

#include "AVW\_MatchVoxels.h"

 $double\ AVW\_ImageSampleJointEntropy(base, match, points, matrix, interpolate)$ 

AVW\_Image \*base,\*match; AVW\_FPointList2 \*points; AVW\_Matrix \*matrix; int interpolate;

## **DESCRIPTION**

AVW\_ImageSampleJointEntropy() calculates the joint entropy of a sample of pixels defined by a list of floating-point 2-D coordinates. *points* defines a set of 2-D coordinates in the *match* image to be sampled. Those pixel values are paired with those from the same coordinates transformed by *matrix* in the *base* image. The joint entropy of the samples is returned

Interpolate determines the method of interpolation to use. Choose from:

AVW\_NEAREST\_NEIGHBOR\_INTERPOLATE

AVW\_LINEAR\_INTERPOLATE

AVW\_CUBIC\_SPLINE\_INTERPOLATE

AVW\_WINDOWED\_SINC\_INTERPOLATE

## **RETURN VALUES**

If successful returns the joint entropy.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

### **ERRORS**

AVW\_ImageSampleJointEntropy() will fail if the following is true:

**ILLIMG** 

Illegal Image. Floating point, Complex, and color images are not supported

**BADMAL** 

Unable to allocate memory for internal calculations.

**ILLPAR** 

Interpolation type is not recognized.

## **SEE ALSO**

AVW\_VolumeSampleJointEntropy(), AVW\_ImageSampleNMI(), AVW\_ImageSampleEntropy().

AVW\_ImageSampleNMI - Calculate the Normalized Mutual Information of a sample of pixels from two images

**SYNOPSIS** 

#include "AVW\_MatchVoxels.h"

double AVW\_ImageSampleNMI(base,match,points,matrix,interpolate)

AVW\_Image \*base,\*match; AVW\_FPointList2 \*points; AVW\_Matrix \*matrix; int interpolate;

# **DESCRIPTION**

AVW\_ImageSampleNMI() calculates the normalized mutual information of a sample of pixels defined by a list of floating-point 2-D coordinates. *points* defines a set of 2-D coordinates in the *match* image to be sampled. Those pixel values are paired with those from the same coordinates transformed by *matrix* in the *base* image. The normalized mutual information (sum of individual image entropies divided by joint entropy) of the samples is returned

Interpolate determines the method of interpolation to use. Choose from:

AVW\_NEAREST\_NEIGHBOR\_INTERPOLATE

AVW\_LINEAR\_INTERPOLATE

AVW\_CUBIC\_SPLINE\_INTERPOLATE

AVW\_WINDOWED\_SINC\_INTERPOLATE

## **RETURN VALUES**

If successful returns the normalized mutual information.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ImageSampleNMI() will fail if the following is true:

**ILLIMG** 

Illegal Image. Floating point, Complex, and color images are not supported

**BADMAL** 

Unable to allocate memory for internal calculations.

**ILLPAR** 

Interpolation type is not recognized.

## **SEE ALSO**

 $AVW\_ImageSampleEntropy(),\ AVW\_ImageSampleJointEntropy(),\ AVW\_VolumeSampleNMI().$ 

AVW\_InhomogeneityCorrectVolume - performs an inhomogeneity correction filter

# **SYNOPSIS**

#include "AVW Filter.h"

AVW\_Volume \*AVW\_InhomogeneityCorrectVolume(in\_volume, mask\_volume, mask\_volume, mask\_volume, window\_size, out\_volume)

AVW\_Volume \*in\_volume, \*mask\_volume; int mask\_value, window\_size;

AVW\_Volume \*out\_volume;

#### **DESCRIPTION**

AVW\_InhomogeneityCorrectVolume() applies mean-based homomorphic filtering to the specified *in\_volume* and returns the filtered volume in This routine scans through the volume in a slice by slice fashion and adjusts voxel intensity values by the following formula:

Io = Ii \* global\_mean/local\_mean

Io is the intensity of the filtered voxel and Ii is the intensity of the input voxel. The global mean is calculated as the average voxel intensity value for all voxels corresponding to voxels equal to *mask\_value* in *mask\_value*.

The <code>mask\_volume</code> is used to exclude noise voxels. It must be the same size as <code>in volume</code> and be of data type <code>AVW\_UNSIGNED\_CHAR</code>. The <code>mask\_volume</code> can be a thresholded version of <code>in\_volume</code> or another spatially registered volume. <code>Mask\_value</code> specifies the value of the voxels in <code>mask\_volume</code> whose corresponding voxels in <code>in\_volume</code> will be used in the mean calculations and eventually corrected in <code>out\_volume</code>.

The algorithm uses a roving square window with length and width equal to the <code>window\_size</code>. The algorithm centers the window around each voxel and calculates the mean value of all voxels in the window corresponding to voxels equal to <code>mask\_value</code> in <code>mask\_volume</code>. This value serves as the local mean for the intensity correction. Voxels which do not correspond to voxels equal to <code>mask\_value</code> in <code>mask\_volume</code> are not included in the filter calculations, nor are these voxels corrected.

This algorithm is useful for removing low-frequency grayscale gradients from images of all types. Examples of these grayscale gradients include uneven illumination in microscope images and uneven coil coverage (for example, as is seen with surface coil images) in magnetic resonance imaging.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# RECCOMMENDED PARAMETERS

For magnetic resonance images:

Mask\_volume: The *mask\_volume* is created by thresholding an MRI volume to exclude background noise. It is recommended that this value be chosen by interactively thresholding the volume and choosing the threshold value that best separates the object of interest from the background. *Mask\_value* can be set to 1 when using a thresholded volume.

Window Dimensions: The optimal *window\_size* depends upon the strength and spatial frequency of the unwanted intensity variations in the image. For a strong but smoothly-varying gradient a 65x65 window is recommended. For a more subtle gradient a larger window (95x95) should be used. For more complex inhomogeneities,

such as are found in surface coil images, smaller windows (45x45) are recommended.

For further information on this algorithm, see the following article:

**AVW 3.0** 

Brinkmann, Manduca, Robb. "Optimized Homomorphic Unsharp Masking for MR Grayscale Inhomogeneity Correction" IEEE Trans Med Img, April, 1998. vol. 17(2): 161-171.

# **RETURN VALUES**

If successful AVW\_InhomogeneityCorrectVolume() returns an AVW\_Volume. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_AHEVolume(), AVW\_LowpassFilterVolume(), AVW\_OrthoGradFilterVolume(), AVW\_RankFilterImage(), AVW\_RankFilterVolume(), AVW\_SigmaFilterVolume(), AVW\_SobelFilterEnhanceVolume(), AVW\_SobelFilterVolume(), AVW\_ThresholdVolume(), AVW\_UnsharpFilterEnhanceVolume(), AVW\_UnsharpFilterVolume(), AVW\_VSFMeanFilterVolume(), AVW\_Volume

AVW\_InitializeMatchVoxelParams – initializes match voxel parameters

**SYNOPSIS** 

#include "AVW\_MatchVoxels.h"

AVW\_MatchVoxelParams \*AVW\_InitializeMatchVoxelParams(param) AVW\_MatchVoxelParams \*param;

## **DESCRIPTION**

*AVW\_InitializeMatchVoxelParams()* creates and returns a structure required to match two specified *AVW\_Volume*. This structure is passed to *AVW\_MatchVoxels()* to obtain the matching transformation between the two specified volumes.

Parameters of AVW\_InitializeMatchVoxelParams():

*param* specifies the *AVW\_MatchVoxelParams* to be created or resets. If *param* is not NULL the function resets all of the *AVW\_MatchVoxelParams* values to their defaults.

The following elements of the *AVW\_MatchVoxelParams* structure are set by *AVW\_InitializeMatchVoxelParams()* when the structure is created or resets.

*param->Ftol* determines the convergence tolerance for the search strategy. If the change in the cost-function is smaller than this value, the search will stop assuming this is the minimum.

*param->Ptol* specifies the transformation parameters convergence tolerance. That is, if the total change in all of the 6 transformation parameters (X,Y,Z rotations and translations) is less than Ptol for a number of successive iterations the subroutine will terminate the search.

*param->Interpolate* specifies whether the transformed image will be computed with bilinear (AVW\_TRUE) or nearest neighbor (AVW\_FALSE) interpolation.

*param->Smpl1to1*, *param->Smpl2to1*, *param->Smpl4to1* and *param->Smpl8to1* Specifies sampling in the X, Y and Z directions. (i.e., if X and Y are set to 3, and Z is 1, than the calculation of the cost function will use every third voxel in the X and Y directions, and all of the slices in the Z direction.

The search is done in stages, first on a volume scaled to a size of 8:1, than 4:1, 2:1 and finally 1:1. The sampling values can be specified for each one of these scaling stages (Smpl8to1, Smpl4to1, Smpl2to1 and Smpl1to1 respectively) . If scaling to a certain size would cause a the volume to become to small the stage will be skipped. It is the users responsibility to assign reasonable values for sampling. Values which cause the use of only a very small number of voxels, will lead to non-accurate results. To determine a good experimental value, define the sample in such a way that there is 30 to 50 points in each direction. This will usually lead to good results with the best possible computation time.

*param->InitGuess* specifies the initial position (X,Y,Z rotation and translations) of the match volume.

*param->SearchLength* defines the problem characteristic scale in X, Y, Z rotation and translation. Theses parameters limit the distance of the search algorithm.

**RETURN VALUES** 

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_InitializeMatchVoxelParams() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**SEE ALSO** 

 $AVW\_MatchVoxelsParams,\ AVW\_DestroyMatchVoxelParams(),\ AVW\_MatchVoxels(),\ AVW\_Volume.$ 

AVW\_InitializeRPParam - initializes surface tiling parameters

**SYNOPSIS** 

#include "AVW Model.h"

AVW\_RPParam \*AVW\_InitializeRPParam(volume, last\_rp\_param)

AVW\_Volume \*volume;

AVW\_RPParam \*last\_rp\_param;

# **DESCRIPTION**

AVW\_InitializeRPParam() creates and returns a structure required to extract a set of ribbon contours from the specified AVW\_Volume. This structure is passed to AVW\_SliceVolume() to obtain the contours from the volume and to write them to disk. The last\_rp\_param structure may be specified as a starting point and only required changes will be made for the returned structure.

Parameters of AVW\_InitializeRPParam():

*volume* specifies the *AVW\_Volume* to use during contour extraction.

<code>last\_rp\_param</code> specifies a starting set of paramaters. This structure is most likely the results of a previous call to <code>AVW\_InitializeRPParam()</code>. Only parameters which require modification as the results of an <code>AVW\_Volume</code> change will be modified in the structure returned. If <code>last\_rp\_param</code> is equal to <code>NULL</code> a <code>AVW\_RPParam</code> structure will be created.

The following elements of the *AVW\_RPParam* structure are set by *AVW\_InitializeRPParam()* when the structure is created.

param->Format specifies the output format. Supported values include:

AVW\_HPGL\_SURFACE – A modified form of HPGL plotter commands designed to support rapid prototyping or stereolithography machines AVW\_POGO\_SURFACE() – A compressed version of the binary SLC format. This format does not differentiate between internal and external boundaries. AVW\_SLC\_SURFACE() – The standard binary SLC format. AVW\_SSD\_ASCII\_SURFACE() – The ASCII version of the standard Analyze SSD format.

*param->SubvolumeFlag* If set, will subvolume the dataset so that the object of interest is contained within a minimum enclosing volume. This may cause the data to be reoriented prior to contour extraction.

*param->MaskValue* specify the mask value of the object within the *AVW\_Volume* whose contours are to be extracted.

*param->InterpolateFlag* if set, will subvolume the dataset using trilinear interpolation.

*param->Orientation* specifies which orthogonal axis will be used during contour extraction This parameter may be one of:

AVW\_TRANSVERSE [default], AVW\_CORONAL, or AVW\_SAGITTAL

*param->AngleResolution* specifies the angle resolution used while determining the minimum enclosing box.

**RETURN VALUES** 

If successful *AVW\_InitializeRPParam()* returns a pointer to a *AVW\_RPParam* structure. This structure contains the parameters which may be modified to produce the desired contour file. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_InitializeRPParam() will fail if one or more of the following is true:

**AVW 3.0** 

**BADMAL** 

Unable to allocate sufficient memory.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_SliceVolume(), AVW\_DestroyRPParam() AVW\_Volume AVW\_RPParam

AVW\_InitializeRenderParameters - initializes volume rendering parameters

## **SYNOPSIS**

#include "AVW Render.h"

 $AVW\_Render Parameters *AVW\_Initialize Render Parameters (volume, and all the parameters) and the parameters are all the parameters the parameters a$ 

object\_map, last\_param)

AVW\_Volume \*volume;

AVW\_ObjectMap \*object\_map;

AVW\_RenderParameters \*last\_param;

#### **DESCRIPTION**

AVW\_InitializeRenderParameters() creates and returns a structure required to render the specified AVW\_Volume. This structure is passed to AVW\_RenderVolume() to obtain 3D renderings of the volume. If an AVW\_ObjectMap is specified it will be used in the rendering process also. The last\_param structure may be specified as a starting point and only required changes will be made for the returned structure.

Parameters of AVW\_InitializeRenderParameters():

Volume specifies the AVW\_Volume to be rendered.

Object\_map specifies a map of objects defined within the AVW\_Volume. This map must be exactly the same dimensions as the AVW\_Volume to be rendered. This map is commonly the result of a call to AVW\_LoadObjectMap() or AVW\_CreateObjectMap(). An AVW\_ObjectMap is not required, NULL may be specified to indicate that no object map is to be used.

Last\_param specifies a starting set of paramaters. This structure is most likely the results of a previous call to AVW\_InitializeRenderParameters(). Only parameters which require modification as the results of an AVW\_Volume or AVW\_ObjectMap change will be modified in the structure returned. If last\_parm is equal to NULL a AVW\_RenderParameters structure will be created.

The following elements of the *AVW\_RenderParameters* structure are set by *AVW\_InitializeRenderParameters()* when the structure is created.

param->Type specifies the type of ray casting preformed. Supported values include:

AVW\_DEPTH\_SHADING – The value of each output pixel is a function of depth only. The depth of the first voxel found along the ray path is used to determine the brightness of that pixel. Closer voxels will appear brighter than distant voxels. This output image may be further enhanced by AVW\_ProcessZGradients().

AVW\_GRADIENT\_SHADING – The gray scale gradient vector is computed using a 3D neighborhood about the surface voxel. The value projected at each output location is the dot product of the gradient vector and an independently specified light source vector. This simulates the appearance of a reflective surface under uniform-field illumination. [default]

*AVW\_VOLUME\_COMPOSITING* – The volumetric compositing algorithm integrates the gradient-shaded value of all voxels along the ray path. The contribution of each gradient-shaded voxel value is weighted by an opacity function described in the *AVW\_CompositeInfo* structure. Voxel intensity is used to determined the voxels color and opacity contribution during the ray casting.

AVW\_MAX\_INTENSITY\_PROJECTION - The maximum voxel intensity

along the ray path is used.

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*AVW\_SUMMED\_VOXEL\_PROJECTION* – The average of all voxels along the ray path is used.

*AVW\_SURFACE\_PROJECTION* – Once a voxel within the threshold limits is detected, the average of the next N voxels is computed.

AVW\_TRANSPARENCY\_SHADING – Available only when an AVW\_ObjectMap has been specified, this type produces a 24-bit true color projections of all the surface gradients along the ray path. Opacity parameters may be specified for each object controlling the transparency.

AVW\_DELETE\_VOXELS — Not really a rendering type, but causes the ray casting algorithm to delete (or convert to a specified value) voxels along the ray path. See the param->DeleteDepth and param->DeleteValue parameters for more information.

*param->ThresholdMinimum* and *param->ThresholdMaximum* specify the range of acceptable voxel values. Voxels outside the specified range are ignored. [Defaults are the minimum and maximum of the volume.]

param->ClipLowX, param->ClipLowY, param->ClipLowZ, param->ClipHighX, param->ClipHighY, and param->ClipHighZ specify the sub volume of the AVW\_Volume to render. [Default = is the entire volume]

*param->ClipPlaneMinimum* and *param->ClipPlaneMaximum* specify the starting and ending depths for the ray casting process.

param->ClipShading specifies the type of shading that is used when the ray casting process begins at a voxel which is within the threshold range (and object enabled). The value is only used when the render *Type* is set to *AVW\_GRADIENT\_SHADING*. Possible values are: *AVW\_CLIP\_SHADED*, *AVW\_CLIP\_ACTUAL*, *AVW\_CLIP\_REMOVE\_AND\_RENDER*, and *AVW\_CLIP\_RENDER\_AS\_IS*. [Default = *AVW\_CLIP\_SHADED*]

*param->RenderWidth, param->RenderHeight,* and *param->RenderDepth* specify the size of the rendered space. By default these values are set to the maximum of the X, Y, or Z input dimension.

param->MaximumPixelValue and param->MinimumPixelValue specify the range of possible output values for the reflectance renderings. Transmission renderings use the maximum and minimum values from the  $AVW_Volume$  as the output range. [Default = 250 and 0]

*param->SurfaceThickness* specifies the maximum thickness for the *AVW\_SURFACE\_PROJECTION* rendering type. [Default = 5]

*param->SurfaceSkip* specify the number of voxels to skip before summing begins for the *AVW\_SURFACE\_PROJECTION* rendering type. [Default = 0]

param->MIP\_Weight specify the weighting options used during a AVW\_SURFACE\_PROJECTION. Options include: AVW\_NO\_WEIGHTING, AVW\_WEIGHT\_BEFORE, and AVW\_WEIGHT\_AFTER. AVW\_WEIGHT\_BEFORE indicates that before a voxel is checked to see if it is the maximum value, a weighting factor is applied. The weighting factor is determined by dividing the length of the ray left to cast, by it's total length. AVW\_WEIGHT\_AFTER determines the

maximum voxel along the entire ray casting path and then applies the weightinh factor described above.

*param->Matrix* is an *AVW\_Matrix* which specifies the rotation and translation transformation applied to the *AVW\_Volume* during the rendering process. Scale could also be specified as part of the matrix, but it's recommended that the *ScaleX*, *ScaleY*, and *ScaleZ* parameters be used for Scale. [Default = identity matrix]

param->LightMatrix specifies the vector of the light source used in reflective renderings. [Default = identity matrix]

param->RenderMask is an AVW\_Image which specifies a specific area to be rerendered. If NULL is specified the entire rendering space is rendered each time AVW\_RenderVolume is called. Only AVW\_Images with a data type of AVW\_UNSIGNED\_CHAR are supported. This AVW\_Image should always have dimensions equal to param->RenderWidth and param->RenderedHeight. [Default = NULL]

*param->MaskValue* specifies the pixel value within the *param->RenderMask* which indicates rendering should occur for this output pixel. [Default = 255]

param->DeleteDepth specifies the number of voxels along the ray path which are deleted (changed to param->DeleteValue). When param->Type is set to AVW\_DeleteVoxels the following settings are valid:

AVW\_DELETE\_ALL\_THE\_WAY – All voxels along the ray path are changed to the value to specified by param->DeleteValue. [default]

AVW\_DELETE\_SINGLE\_LAYER – Once a value within the theshold limits is detected, all voxels with values within the threshold range are reddifined as the object specified by param->DeleteValue until a voxel outside the threshold range is detected, at which time object definition stops.

*AVW\_DELETE\_SINGLE\_VOXEL* – The first voxel along the ray path which is within the threshold range is deleted.

AVW\_DEFINE\_ALL\_THE\_WAY – All object map locations along the ray path are changed to the value to specified by param->DeleteValue.

*AVW\_DEFINE\_SINGLE\_LAYER* – Once a value within the theshold range is detected, all voxels with values within the threshold limits are redfined until a voxel outside the threshold range is detected, at which time deleting stops.

AVW\_DEFINE\_SINGLE\_VOXEL – The first object map location along the ray path which is within the threshold limits is redefined.

*NOTE:* A 3x3x3 region surrounding a voxel is deleted/defined instead of just a single voxel, this compensates for spaces which may occur between the ray paths.

*param->DeleteValue* specifies the value each voxel or object map location is changed to, when the *AVW\_DELETE\_VOXELS* rendering type is specified. [Default = 0]

param->ScaleX, ScaleY and param->ScaleZ specify the scaling factors. param->ScaleX specifies the width of each rendered voxel. param->ScaleY the height and param->ScaleZ the depth. A value of .5 indicates the voxel width ,height, or depth is half it's normal size. A value of 2.0 indicates the voxel is twice it's normal width, height,

or depth. When specifying scale factors larger than 1.0, changes to the *param-*>*RenderWidth*, *param-*>*RenderHeight* and *param-*>*RenderDepth* are required to prevent segmentation violations. [Default = 1.0]

param->PerspectiveType specifies the type of rendering to be performed. AVW\_PERSPECTIVE\_INT renders the image using the voxels without interpolation, possibly resulting in "blocky" renderings. If param->PerspectiveType is set to AVW\_PERSPECTIVE\_FLOAT, the rendered image is generated using an on the fly intepolation rendering algorithm. If param->PerspectiveType is set to AVW\_PERSPECTIVE\_OFF, parallel rendering is performed. For perspective rendering, the render matrix is interperted as a viewing direction for the camera model, however the parallel rendering conventions are followed, i.e. the matrix is left handed, and the identity matrix provides a view along the positive Z axis with X increasing to the right and Y increasing in the vertical direction. Perspective rendering does not support scaling at this time. For anisotropic data, rescaling during loading is the best option.

*param->EyePosition* specifies the location of the camera model used to generate the rendering. This parameter is only used when *param->PerspectiveType* is set to  $AVW\_PERSPECTIVE\_FLOAT$  or  $AVW\_PERSPECTIVE\_INT$ . The X, Y, and Z coordinates of the  $AVW\_FPoint3$  structure refer to the position of the camera relative to the center of the volume, thus a position of (0,0,0) in a particular volume is located at voxel (Width / 2, Height / 2, Depth / 2).

param->XFieldOfViewAngle and param->YFieldOfViewAngle specify the field of view (FOV) angle of the camera model used to generate the image. Increasing the FOV results in a zoom out effect, if the position remains the same. Decreasing the FOV results in a zoom in effect.

param->SpecularFactor specifies the ratio of gradient shading to specular shading. If param->SpecularFactor is set to 0, the rendering will be shaded entirely using gradient shading with no performance penalty. If param->SpecularFactor is set to .1, the rendering is shaded entirely using the specular shading model.

param->SpecularExponent specifies the degree of fall-off for specular shading. High values (about 10) result in very small specular highlights, while small values (about 1 or 2) result in diffuse highlights.

*param->CompositeInfo* specifies a pointer to a structure which contains compositing information. This must contain a valid pointer when the *param->Type is set to AVW\_VOLUME\_COMPOSITING*. See *AVW\_CompositeInfo* for more information.

BackgroundColor and BackgroundValue are used to specify the background color or value. The rendering type, input volumes datatype, and whether an object map is loaded determines which value is used. If the output is a grayscale image, BackgroundValue is used. If the output is a color image, then BackgroundColor will be used. Background Color is a packed RGB value which can be produced with the AVW\_RGB macro.

RenderMode is normally set to AVW\_RENDER\_NORMAL, but when set to AVW\_PREPARE\_FOR\_MOVE, the AVW\_RenderVolume() function will process the object specified in the InteractiveObject seperately and return the "visible surface" in the AVW\_RenderedImage member called InteractiveSurface. This results in the input to AVW\_RenderVisibleSurface() which produces output which can be combined using AVW\_MergeRendered() with the rendering returned at the time the InteractiveSurface was produced. This entire process allows an interface to be build to interactively move and rotate objects. RenderMode can be set to

*AVW\_RERENDER\_MOVED*, at the completion of the object transformation to rerender any missing data.

*param->Internal* contains parameter which are used internally within the rendering functions. *CHANGING OF INTERNAL PARAMETERS IS DISCOURAGED!* 

## **RETURN VALUES**

If successful *AVW\_InitializeRenderParameters()* returns a pointer to a *AVW\_RenderParameters* structure. This structure contains the parameters which may be modified to produce the desired rendered image. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_InitializeRenderParameters() will fail if one or more of the following is true:

BADMAL

Unable to allocate sufficient memory.

**CFLSZ** 

The AVW\_Volume and AVW\_ObjectMap have conflicting dimensions.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_AddObject(), AVW\_CreateObjectMap(), AVW\_DeleteObject(),
AVW\_DestroyObjectMap(), AVW\_DrawRenderedPoint(), AVW\_DrawRenderedLine(),
AVW\_FindRenderedPoint(), AVW\_LoadObjectMap(), AVW\_MirrorRendered(),
AVW\_ProcessZGradients(), AVW\_SaveObjectMap() AVW\_RenderVolume(), AVW\_Image
AVW\_ObjectMap AVW\_RenderParameters,

AVW\_InitializeTileParameters – initializes surface tiling parameters

**SYNOPSIS** 

#include "AVW Model.h"

 $AVW\_Tile Parameters *AVW\_Initialize Tile Parameters (volume,$ 

object\_map, last\_tile\_param)

AVW\_Volume \*volume;

AVW\_ObjectMap \*object\_map;

AVW\_TileParameters \*last\_tile\_param;

#### **DESCRIPTION**

AVW\_InitializeTileParameters() creates and returns a structure required to tile the specified AVW\_Volume. This structure is passed to AVW\_TileVolume() to obtain a tiled surface from the volume. If an AVW\_ObjectMap is specified it will be used in the tiling process instead of the volume. The last\_tile\_param structure may be specified as a starting point and only required changes will be made for the returned structure.

Parameters of AVW\_InitializeTileParameters():

*Volume* specifies the *AVW\_Volume* to be rendered.

Object\_map specifies a map of objects defined within the AVW\_Volume. This map must be exactly the same dimensions as the AVW\_Volume to be rendered. This map is commonly the result of a call to AVW\_LoadObjectMap() or AVW\_CreateObjectMap(). An AVW\_ObjectMap is not required, NULL may be specified to indicate that no object map is to be used.

Last\_tile\_param specifies a starting set of paramaters. This structure is most likely the results of a previous call to AVW\_InitializeTileParameters(). Only parameters which require modification as the results of an AVW\_Volume or AVW\_ObjectMap change will be modified in the structure returned. If last\_tile\_parm is equal to NULL a AVW\_TileParameters structure will be created.

The following elements of the *AVW\_TileParameters* structure are set by *AVW\_InitializeTileParameters()* when the structure is created.

param->Type specifies the type of tiling preformed. Supported values include:

*AVW\_TILE\_KOHONEN* – The tiled surface will be created using a Kohonen Net to map a mesh to the object's surface. *AVW\_TILE\_GROW()* – The tiled surface will be created using a polygon growing algorithm.

*AVW\_MARCHING\_CUBES()* – The tiled surface will be created using the marching cubes algorithm.

param->Checkpoint Ignored at present.

param->Mask specify the mask value of the object within the AVW\_Volume to tile.

*param->CurveOpRadius* specifies the spacing between elements in the curvature detection operator [default is 1].

*param->CloseSrfcFlag* toggles the production of a closed (if set) or open (if unset) ended surface [default is unset].

*param->KohonenMajorAxis* specifies which axis is to be used as the major axis when tiling. This parameter may be one of:

AVW\_XAXIS, AVW\_YAXIS, or AVW\_ZAXIS [default]

*param->KohonenShapeOrient* specifies the orientation of the initial network. This parameter may be one of:

AVW\_TRANSVERSE [default], AVW\_CORONAL, or AVW\_SAGITTAL

param->KohonenShapeOffset specifies the initial distance between the object's surface and the network. A value less than 1 will place the initial network inside the object, while a value greater than 1 will place the network outside the object. The actual distance is determined by multipling the radii of the 2-D bounding oval by param->KohonenShapeOffset

*param->KohonenFlag* is set by oring together:

*AVW\_TRAIN\_IN\_MAJOR\_AXIS* and *AVW\_TRAIN\_WITH\_WEIGHT* These parameters will cause the network to train along the major axis in addition to the minor axis and/or to use a weighted training algorithm.

*param->PolygonBudget* specifies the maximum number of polygons that may be used to form the model.

*param->KohonenRepetitions* specifies the number of times the data is presented to the network during adaptation.

param->KohonenNeighborhood specifies how a "neighborhood" of cells within the Kohonen Network will move during adaptation. This parameter is one of:

AVW\_BUBBLE\_NEIGHBORHOOD, AVW\_GAUSS\_NEIGHBORHOOD, or
AVW\_TRIANGLE\_NEIGHBORHOOD

*param->KohonenTopology* specifies the topology of the network. Currently the only accepted topology is *AVW\_RECTANGULAR\_TOPOLOGY* 

*param->KohonenNeighborRadius* specifies initial radius of a network neighborhood. If this parameter is less than 1, the initial radius will be set to be one third of the distance around a 2-D bounding oval orthogonal to the major axis

param->KohonenAlpha specifies the initial learning rate during adaptation.

*param->AddNodeFreq* specifies the number of adaptation steps envoked by the growing net algorithm before a new node is added.

*param->MaximumAge* specifies the maximal age number allowed for the growing net edges (connections). Edges with age greater than *param->MaximumAge* are removing from the growing net.

*param->Eb, param->En* specifies the adaptation factors for the best matching unit (bmu) node and its direct neighbors, respectively.

*param->GrowingAlpha* specifies the factor for decreasing the error counters of the 1st and 2nd bmus after the insertion of a new node to the growing net, respectively.

*param->GrowingD* specifies the factor for decreasing the error counters of all nodes after the insertion of a new node to the growing net.

#### **RETURN VALUES**

If successful *AVW\_InitializeTileParameters()* returns a pointer to a *AVW\_TileParameters* structure. This structure contains the parameters which may be modified to produce the desired rendered image. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_InitializeTileParameters() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

 $AVW\_CreateObjectMap(),\ AVW\_DeleteObject(),\ AVW\_DestroyObjectMap(),\ AVW\_LoadObjectMap(),\ AVW\_SaveObjectMap()\ AVW\_TileVolume(),\ AVW\_Image\ AVW\_ObjectMap\ AVW\_TileParameters$ 

AVW\_InsertFPoint2 - inserts a point in a list structure

**SYNOPSIS** 

#include "AVW.h"

int AVW\_InsertFPoint2(trace, index, point)

AVW\_FPointList2 \*trace;

int index;

AVW\_FPoint2 \*point;

**DESCRIPTION** 

AVW\_InsertFPoint2() inserts an AVW\_FPoint2, point, to an AVW\_FPointList2, trace before the point specified by index.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** 

If successful *AVW\_InsertFPoint2()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_InsertFPoint2() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**SEE ALSO** 

AVW\_AddFPoint2(), AVW\_InsertFPoint3(), AVW\_InsertIPoint2(), AVW\_InsertIPoint3(), AVW\_InsertPoint2(), AVW\_InsertPoint3(), AVW\_InsertPointValue(), AVW\_CopyPointList2() AVW\_CreateFPointList2(), AVW\_DestroyFPointList2(), AVW\_RemoveFPoint2(), AVW\_FPoint2(), AVW\_FPOI

AVW\_InsertFPoint3 - adds a point to a list structure

**SYNOPSIS** 

#include "AVW.h"

int AVW\_InsertFPoint3(trace, index, point)

AVW\_FPointList3 \*trace;

int index;

AVW\_FPoint3 \*point;

**DESCREPTION** 

*AVW\_InsertFPoint3()* adds an *AVW\_FPoint3, point* to an *AVW\_FPointList3, trace* before the point specified by *index*.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** 

If successful *AVW\_InsertFPoint2()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_InsertFPoint3() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**SEE ALSO** 

AVW\_AddFPoint3(), AVW\_InsertFPoint2(), AVW\_InsertIPoint2(), AVW\_InsertIPoint3(), AVW\_InsertPoint2(), AVW\_InsertPoint3(), AVW\_InsertPointValue(), AVW\_CopyFPointList3(), AVW\_CreateFPointList3(), AVW\_DestroyFPointList3(), AVW\_GetFPoint3(), AVW\_RemoveIpoint3(), AVW\_FPointList3, AVW\_FPoint3

NAME AVW

AVW\_InsertIPoint2 - inserts a point to a list structure

**SYNOPSIS** 

#include "AVW.h"

int AVW\_InsertIPoint2(trace, index, point)

AVW\_IPointList2 \*trace;

int index;

AVW\_IPoint2 \*point;

**DESCRIPTION** 

AVW\_InsertIPoint2() inserts an AVW\_IPoint2, point to an AVW\_IPointList2, trace before the point specified by index.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** 

If successful *AVW\_InsertIPoint2()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_InsertIPoint2() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**SEE ALSO** 

AVW\_AddIPoint2(), AVW\_InsertIPoint3(), AVW\_InsertFPoint2(), AVW\_InsertFPoint3(), AVW\_InsertPoint2(), AVW\_InsertPoint3(), AVW\_InsertPointValue(), AVW\_CopyIPointList2(), AVW\_CreateIPointList2(), AVW\_DestroyIPointList2(), AVW\_GetIPoint2(), AVW\_RemoveIpoint2(), AVW\_IPointList2, AVW\_IPoint2

AVW\_InsertIPoint3 - inserts a point to a list structure

**SYNOPSIS** 

#include "AVW.h"

int AVW\_InsertIPoint3(trace, index, point)

AVW\_IPointList3 \*trace;

int index;

AVW\_IPoint3 \*point;

**DESCRIPTION** 

AVW\_InsertIPoint3() inserts an AVW\_IPoint3, point, to an AVW\_IPointList3, trace before

the point specified by index.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** 

If successful AVW\_InsertIPoint3() returns AVW\_SUCCESS. On failure it returns

AVW\_FAIL and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values correspond-

ing to the cause of the failure.

**ERRORS** 

AVW\_InsertIPoint3() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**SEE ALSO** 

AVW\_AddIPoint3(), AVW\_InsertIPoint2(), AVW\_InsertFPoint2(), AVW\_InsertFPoint3(),

AVW\_InsertPoint2(), AVW\_InsertPoint3(), AVW\_InsertPointValue(),

 $AVW\_CopyIPointList 3 (),\ AVW\_CreateIPointList 3 (),\ AVW\_DestroyIPointList 3 (),$ 

AVW\_GetIPoint3(), AVW\_RemoveIPoint3(), AVW\_IPointList3, AVW\_IPoint3

AVW\_InsertPoint2 - inserts a point in a list structure

**SYNOPSIS** 

#include "AVW.h"

int AVW\_InsertPoint2(trace, index, point)

AVW\_PointList2 \*trace;

int index;

AVW\_Point2 \*point;

**DESCRIPTION** 

AVW\_InsertPoint2() adds an AVW\_Point2, point, to an AVW\_PointList2, trace before the point specified by index.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** 

If successful *AVW\_InsertPoint2()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_InsertPoint2() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**SEE ALSO** 

AVW\_AddPointList2(), AVW\_InsertFPoint2(), AVW\_InsertFPoint3(), AVW\_InsertIPoint2(), AVW\_InsertIPoint3(), AVW\_InsertPoint3(), AVW\_InsertPointValue(), AVW\_AddPointList2(), AVW\_CreatePointList2(), AVW\_CopyPointList2(),

AVW\_DestroyPointList2(), AVW\_EditPointList2(), AVW\_FillPointList2(), AVW\_GetPoint2(),

AVW\_RemovePoint2(), AVW\_PointList2, AVW\_Point2

AVW\_InsertPoint3 – inserts a point to a list structure

**SYNOPSIS** 

#include "AVW.h"

int AVW\_InsertPoint3(trace, index, point)

AVW\_PointList3 \*trace;

int index;

AVW\_Point3 \*point;

**DESCRIPTION** 

AVW\_InsertPoint3() inserts an AVW\_Point3, point, to an AVW\_PointList3, trace before the point specified by index.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** 

If successful *AVW\_InsertPoint3()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_InsertPoint3() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**SEE ALSO** 

 $AVW\_AddPoint3(),\ AVW\_InsertFPoint2(),\ AVW\_InsertFPoint3(),\ AVW\_InsertIPoint2(),\ AVW\_InsertIPoint3(),\ AVW\_InsertPoint2(),\ AVW\_InsertPointValue(),\ AVW\_CopyPointList3(),\ AVW\_CreatePointList3(),\ AVW\_DestroyPointList3(),\ AVW\_FillPointList3(),\ AVW\_RemovePoint3(),\ AVW\_PointList3,\ AVW\_Point3$ 

AVW\_InsertPointValue – inserts a point and a value to a list structure

**SYNOPSIS** 

#include "AVW.h"

int AVW\_InsertPointValue(trace, index, point, value)

AVW\_PointValueList \*trace;

index

AVW\_Point2 \*point;

double value;

**DESCRIPTION** 

 $AVW\_InsertPointValue()$  inserts an  $AVW\_Point2$ , point, and a value to an

AVW\_PointValueList, trace before the point specified by index.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

**RETURN VALUES** 

If successful AVW\_InsertPointValue() returns AVW\_SUCCESS. On failure it returns

AVW\_FAIL and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values correspond-

ing to the cause of the failure.

**ERRORS** 

AVW\_InsertPointValue() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**SEE ALSO** 

 $AVW\_AddPointValue(),\ AVW\_InsertFPoint2(),\ AVW\_InsertFPoint3(),\ AVW\_InsertIPoint2(),\ AVW\_INSERTIPOINT2(),$ 

AVW\_InsertIPoint3(), AVW\_InsertPoint2(), AVW\_InsertPoint3(),

AVW\_CopyPointValueList(), AVW\_CreatePointValueList(), AVW\_DestroyPointValueList(),

AVW\_GetPointValue(), AVW\_RemovePointValue(), AVW\_PointValueList, AVW\_Point2

AVW\_IntensityClipImage - sets values outside range

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_IntensityClipImage(in\_image, clip\_max, clip\_min, clip\_maxval, clip\_minval, out\_image)

AVW\_Image \*in\_image;

double clip\_max, clip\_min, clip\_maxval, clip\_minval;

AVW\_Image \*out\_image;

### **DESCRIPTION**

AVW\_IntensityClipImage() sets all pixels greater than clip\_max to clip\_maxval. All pixels less than clip\_min are set to clip\_minval. All pixels within the clip\_max and clip\_min range are copied unchanged.

The *DataType* of the returned image will always be the same as the input *DataType*. The *clip\_maxval* and *clip\_minval* need not be within the *clipmax* and *clipmin* range, but can be. They can also be set to the same value, thus setting all pixels outside the range to a specific value.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_IntensityClipImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_IntensityClipImage() will fail if the following is true:

**BADMAL** 

Couldn't allocate memory.

### **SEE ALSO**

AVW\_ConvertImage(), AVW\_IntensityClipVolume(), AVW\_IntensityScaleImage(), AVW\_TableImage(), AVW\_Image

AVW\_IntensityClipVolume - sets values outside range

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_IntensityClipVolume(in\_volume, clip\_max, clip\_min, clip\_maxval, clip\_minval, out\_volume)

AVW\_Volume \*in\_volume;

double clip\_max, clip\_min, clip\_maxval, clip\_minval;

AVW\_Volume \*out\_volume;

### **DESCRIPTION**

AVW\_IntensityClipVolume() sets all voxels greater than clip\_max to clip\_maxval. All voxels less than clip\_min are set to clip\_minval. All voxels within the clip\_max and clip\_min range are copied unchanged.

The *DataType* of the returned volume will always be the same as the input *DataType*. The *clip\_maxval* and *clip\_minval* need not be within the *clipmax* and *clipmin* range, but can be. They can also be set to the same value, thus setting all voxels outside the range to a specific value.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

### **RETURN VALUES**

If successful *AVW\_IntensityClipVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_IntensityClipVolume() will fail if the following is true:

**BADMAL** 

Couldn't allocate memory.

### **SEE ALSO**

AVW\_ConvertVolume(), AVW\_IntensityClipImage(), AVW\_IntensityScaleVolume(), AVW\_TableVolume(), AVW\_ThresholdVolume(), AVW\_Volume

AVW\_IntensityScaleImage - scales image intensity values

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_IntensityScaleImage(in\_image, in\_max, in\_min, out\_max, out\_min, out\_dt, out\_image)

AVW\_Image \*in\_image;

double in\_max, in\_min, out\_max, out\_min;

int out dt:

AVW\_Image \*out\_image;

## DESCRIPTION

AVW\_IntensityScaleImage() takes an AVW\_Image, in\_image, and maximum and minimum intensity values, in\_max and in\_min, and linearly scale the pixel values of the image to create the resulting image with the maximum and minmum values of out\_max and out\_min and of the data type out\_dt. The scaled intensity values are calculated by the following equation:

```
out_val = (in_val - in_min) *(out_max - out_min)/(in_max - in_min) + out_min
```

Where in\_val is the original intensity value of the *in\_image* and out\_val is the returned intensity in *out\_image*.

out\_dt may be one of the AVW image data types.

AVW\_UNSIGNED\_CHAR AVW\_SIGNED\_CHAR AVW\_UNSIGNED\_SHORT AVW\_SIGNED\_SHORT AVW\_UNSIGNED\_INT AVW\_SIGNED\_INT AVW\_FLOAT

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

AVW\_IntensityScaleImage() can also be used to perform image conversion.

**ERRORS** 

AVW\_ItensityScaleImage() will fail if:

**NOTSUP** 

Input or output image data type not supported.

### **RETURN VALUES**

If successful *AVW\_IntensityScaleImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_IntensityScaleVolume(), AVW\_ObjectScaleImage(), AVW\_ConstantOpImage(), AVW\_ConvertImage(), AVW\_ImageOpConstant(), AVW\_DestroyImage(), AVW\_Image

AVW\_IntensityScaleVolume - scales volume intensity values

### **SYNOPSIS**

#include "AVW.h"

 $AVW\_Volume *AVW\_IntensityScaleVolume (in\_volume, in\_max,$ 

in\_min, out\_max, out\_min, out\_dt, out\_volume)

AVW\_Volume \*in\_volume;

double in max, in min, out max, out min;

int out\_dt;

AVW\_Volume \*out\_volume;

#### **DESCRIPTION**

AVW\_IntensityScaleVolume() takes an AVW\_Volume, in\_volume, and maximum and minimum intensity values, in\_max and in\_min, and linearly scale the voxel values of the volume to create the resulting volume with the maximum and minmum values of out\_max and out\_min and of the datatype out\_dt. The scaled intensity values are calculated by the following equation:

```
out_val = (in_val - in_min) *(out_max - out_min)/(in_max - in_min) + out_min
```

Where out\_val (returned) and in\_val (original) are the intensity values of the returned volume and *in\_volume*.

out\_dt may be one of the AVW image data types.

AVW\_UNSIGNED\_CHAR AVW\_SIGNED\_CHAR AVW\_UNSIGNED\_SHORT AVW\_SIGNED\_SHORT AVW\_UNSIGNED\_INT AVW\_SIGNED\_INT AVW\_FLOAT

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

AVW\_IntensityScaleVolume() can also be used to do volume conversion.

#### **ERRORS**

AVW\_IntensityScaleVolume() will fail if:

**NOTSUP** 

Input or output volume data type not supported.

### **RETURN VALUES**

If successful *AVW\_IntensityScaleVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **SEE ALSO**

 $AVW\_IntensityScaleImage(),\ AVW\_ImageOpConstant(),\ AVW\_DestroyVolume(),\ AVW\_Volume$ 

**NAME** AVW\_InterpolatedPixel – returns pixel value at a floating point location

**AVW 3.0** 

SYNOPSIS #include "AVW.h"

double AVW\_InterpolatedPixel(image, point)

AVW\_Image \*image; AVW\_FPoint2 \*point;

**DESCRIPTION** Given a floating point location *point* within *image*, *AVW\_InterpolatedPixel()* returns the cal-

culated pixel value at the floating point location.

Bi-linear calculation is used to estimate the pixel value at the floating point location.

Points outside the image will return a value of 0.0.

 $\textbf{SEE ALSO} \qquad AVW\_GetPixel(), \ AVW\_GetErrorNumner(), \ AVW\_InterpolatedVoxel(), \\$ 

AVW\_NearestNeighborPixel(), AVW\_CubicSplineInterpolatedPixel(),

AVW\_SincInterpolatedPixel(), AVW\_Image, AVW\_FPoint2

**NAME** AVW\_InterpolatedVoxel – returns voxel value at a floating point location

SYNOPSIS #include "AVW.h"

double AVW\_InterpolatedVoxel(volume, point)

AVW\_Volume \*volume; AVW\_FPoint3 \*point;

**DESCRIPTION** Given a floating point location *point* within *volume*, *AVW\_InterpolatedVoxel()* returns the

calculated voxel value at the floating point location.

Tri-linear calculation is used to estimate the voxel value at the floating point location.

Points outside the volume will return a value of 0.0.

**SEE ALSO** | *AVW\_GetVoxel()*, *AVW\_GetErrorNumner()*, *AVW\_InterpolatedPixel()*,

AVW\_NearestNeighborVoxel(), AVW\_CubicSplineInterpolatedVoxel(),

AVW\_SincInterpolatedVoxel(), AVW\_FPoint3, AVW\_Volume

AVW\_IntersectingSections – renders intersecting sections

**SYNOPSIS** 

#include "AVW Render.h"

AVW\_RenderedImage \*AVW\_IntersectingSections(volume, x, y, z, matrix, interpolate\_flag, shading\_fraction, last\_rendered)

AVW\_Volume \*volume;

int x, y, z;

AVW\_Matrix \*matrix;

int interpolate\_flag;

double shading\_fraction;

AVW\_RenderedImage \*last\_rendered;

### **DESCRIPTION**

*AVW\_IntersectingSections()* returns an *AVW\_RenderedImage* showing the intersection of a transverse, coronal and sagittal section.

*Volume* specifies the *AVW\_Volume* the sections are extracted from.

*X*, *y*, and *z* specify the 3 space coordiate where the sections intersect. *X* specifies the which sagittal slice, *Y* specifies the coronal slice, and *Z* specifies the transverse slice.

Matrix is used to specify any rotation or scale factors.

The *interpolate\_flag* specifies if tri-linear interpolations should be used when generating the image. Setting the *interpolate\_flag* to *AVW\_FALSE* causes *Nearest Neighbor* to be used, which is much faster, but lacks some of the quality.

Last\_rendered is provided as a method of reusing an existing AVW\_RenderedImage. Reuse is possible only if the size and data type of the provided last\_rendered meet the requirements of the function. In this case the pointer to last\_rendered is returned by the function. If not reusable last\_rendered will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

### **RETURN VALUES**

If successful *AVW\_IntersectingSections()* returns an *AVW\_RenderedImage*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_IntersectingSections() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**ILLPAR** 

Illegal parameter(s).

#### **SEE ALSO**

 $AVW\_Cube Sections (), \ AVW\_Render Oblique (), \ AVW\_Destroy Rendered Image (), \ AVW\_Rendered Image$ 

AVW\_InvertImage - inverts pixel intensities

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_InvertImage(in\_image, maximum, minimum, out\_image)

AVW\_Image \*in\_image;

double maximum, minimum;

AVW\_Image \*out\_image;

### **DESCRIPTION**

*AVW\_InvertImage()* inverts the pixel intensities in *in\_image* according to the following formula:

(maximum-minimum) - (pixel\_value - minimum) + minimum

where *pixel\_value* is the value of each pixel in the image and *maximum* and *minimum* are user supplied values.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful *AVW\_InvertImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure. ERRORS *AVW\_InvertImage()* will fail if the following is true:

**NOTSUP** 

Data type not supported. AVW\_COMPLEX and AVW\_COLOR images are not supported.

**SEE ALSO** 

AVW\_InvertVolume(), AVW\_Image

**NAME** AVW\_InvertMatrix – inverts a transformation matrix

**SYNOPSIS** #include "AVW.h"

AVW\_Matrix \*AVW\_InvertMatrix(in\_matrix, out\_matrix)

AVW\_Matrix \*in\_matrix, \*out\_matrix;

**DESCRIPTION** | AVW\_InvertMatrix() returns the inverse of the AVW\_Matrix, in\_matrix.

Out\_matrix is provided as a method of reusing an existing AVW\_Matrix. (See Memory

Usage in the AVW Programmer's Guide.)

**SEE ALSO** AVW\_CopyMatrix(), AVW\_CreateMatrix(), AVW\_MakeMatrixFrom3Points(),

AVW\_MakeMatrixFromAxis(), AVW\_MirrorMatrix(), AVW\_MultiplyMatrix(),

AVW\_RotateMatrix(), AVW\_SetIdentityMatrix(), AVW\_ScaleMatrix(),

AVW\_TranslateMatrix(), AVW\_Matrix

AVW\_InvertVolume - inverts voxel intensities

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_InvertVolume(in\_volume, maximum, minimum, out\_volume)

AVW\_Volume \*in\_volume; double maximum, minimum;

AVW Volume \*out volume;

**DESCRIPTION** 

*AVW\_InvertVolume()* inverts the voxel intensities in *in\_volume* according to the following formula:

(maximum-minimum) - (voxel\_value - minimum) + minimum

where *voxel\_value* is the value of each voxel in the volume and *maximum* and *minimum* are user supplied values.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_InvertVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure. ERRORS *AVW\_InvertVolume()* will fail if the following is true:

**NOTSUP** 

Data type not supported. AVW\_COMPLEX and AVW\_COLOR volumes are not supported.

**SEE ALSO** 

AVW\_InvertImage(), AVW\_Volume

**NAME** AVW\_IsASubsetImage – determines if one image is a subset of another

SYNOPSIS #include "AVW.h"

int AVW\_IsASubsetImage(image1, image2)

AVW\_Image \*image1, image2;

**DESCRIPTION** | *AVW\_IsASubsetImage()* is used to determine if the non-zero pixels in *image1* are a subset

of the non-zero pixels in *image2*. *Image1* and *image2* must be of the same data type.

**RETURN VALUES** AVW\_TRUE is returned if *image1* is a subset of *image2*. AVW\_FALSE is returned if it is

not.

**ERRORS** *AVW\_IsASubsetImage()* will fail if:

**ILLDT** 

Data type is not defined or supported.

SEE ALSO | AVW\_Image

**NAME** AVW\_IsGrayColormap – determines if a colormap is gray scale

SYNOPSIS #include "AVW.h"

int AVW\_IsGrayColormap(map)

AVW\_Colormap \*map;

**DESCRIPTION** | *AVW\_IsGrayColormap()* is used to determine if an *AVW\_Colormap* is a gray scale map.

**RETURN VALUES** AVW\_TRUE is returned if all corresponding Red, Green, and Blue values are equal and if

successive cells have greater values. Otherwise AVW\_FALSE is returned.

**SEE ALSO** AVW\_Colormap

**NAME** AVW\_IsImageZero – determines if an entire image is zero

SYNOPSIS #include "AVW.h"

int AVW\_IsImageZero(in\_image)

AVW\_Image \*in\_image;

**DESCRIPTION** | *AVW\_IsImageZero()* is used to determine if every pixel in an *AVW\_Image* is equal to zero.

**RETURN VALUES** Upon encountering the first nonzero pixel in *in\_image AVW\_FALSE* is returned. If the

entire image is set to zero, AVW\_TRUE is returned.

**SEE ALSO** | AVW\_IsVolumeZero(), AVW\_Image

**NAME** AVW\_IsVolumeZero – determines if an entire volume is zero

SYNOPSIS #include "AVW.h"

 $int\ AVW\_IsVolumeZero (in\_volume)$ 

AVW\_Image \*in\_volume;

**DESCRIPTION** | *AVW\_IsVolumeZero()* is used to determine if every voxel in an *AVW\_Volume* is equal to

zero.

**RETURN VALUES** Upon encountering the first nonzero voxel in *in\_volume AVW\_FALSE* is returned. If the

entire volume is set to zero, *AVW\_TRUE* is returned.

**SEE ALSO** | AVW\_IsImageZero(), AVW\_Volume

AVW\_IterDeconvImage - performs constrained iterative image deconvolution

**SYNOPSIS** 

#include "AVW.h"

 $AVW\_Image *AVW\_IterDeconvImage (obs\_image, transfer\_func, transf$ 

update\_rule, no\_iter, guess\_image)

AVW\_Image \*obs\_image, \*transfer\_func;

int update\_rule, no\_iter;

AVW\_Image \*guess\_image;

#### **DESCRIPTION**

AVW\_IterDeconvImage() performs constrained iterative deconvolution on an image (see reference below). The actual observed image is <code>obs\_image</code>, and its dimensions are expected to be powers of 2. The modulation transfer function to use in the deconvolution is given by <code>transfer\_func</code>, and it must be of data type <code>AVW\_FLOAT</code> or <code>AVW\_COMPLEX</code> and of dimensions <code>xnum/2 + 1</code>, <code>ynum</code>, where <code>xnum</code> and <code>ynum</code> are the dimensions of the <code>obs\_image</code>. The initial (or current) guess is supplied in <code>guess\_image</code>, and it must be of data type <code>AVW\_FLOAT</code> and the same dimensions as the <code>obs\_image</code>. If it is not, or it is <code>NULL</code>, the function allocates new memory for the returned <code>guess\_image</code> and takes the observed image to be the initial guess.

This function can be called repeatedly with the output from the last call being the <code>guess\_image</code> supplied to the next call in order to perform some iterations, examine the result, and then perform more iterations. The <code>update\_rule</code> parameter has the acceptable values <code>AVW\_UPDATE\_VC</code> and <code>AVW\_UPDATE\_GOLD</code>, and controls which updating scheme to use (see reference). The <code>no\_iter</code> parameter controls how many iterations to perform.

More detailed information about constrained iterative deconvolution may be found in the reference:

Agard, David A., *Fluorescence Microscopy in Three Dimensions* 1989, in Methods in Cell Biology, Vol. 30, Chap. 13, Academic Press.

### **RETURN VALUES**

If successful *AVW\_IterDeconvImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

*AVW\_IterDeconvImage()* will fail if the following is true:

RADMAI.

Malloc Failed. Unable to allocate memory for return image.

**ILLPAR** 

Illegal Parameter. An invalid value was given for an input parameter.

**ILLIMG** 

Illegal Image. Input image was not a power of 2 in each dimension.

**BDSPCT** 

Bad Input Spectrum. An invalid spectrum was entered for the transfer function.

## **SEE ALSO**

AVW\_IterDeconvVolume() AVW\_CreateStoksethMTF(), AVW\_DeconvDivideImage(), AVW\_DeconvWienerImage(), AVW\_NearestNeighborDeconv(), AVW\_Image

AVW\_IterDeconvVolume - performs constrained iterative volume deconvolution

## **SYNOPSIS**

#include "AVW.h"

AVW\_Volume \*AVW\_IterDeconvVolume(obs\_volume, transfer\_func, update\_rule, no\_iter, guess\_volume)

**AVW 3.0** 

AVW\_Volume \*obs\_volume, \*transfer\_func;

int update rule, no iter;

AVW\_Volume \*guess\_volume;

#### **DESCRIPTION**

AVW\_IterDeconvVolume() performs constrained iterative deconvolution on a volume (see reference below). The actual observed volume is <code>obs\_volume</code>, and its dimensions are expected to be powers of 2. The modulation transfer function to use in the deconvolution is given by <code>transfer\_func</code>, and it must be of data type <code>AVW\_FLOAT</code> or <code>AVW\_COMPLEX</code> and of dimensions <code>xnum/2 + 1</code>, <code>ynum</code>, and <code>znum</code> where <code>xnum</code>, <code>ynum</code>, and <code>znum</code> are the dimensions of the <code>obs\_volume</code>. The initial (or current) guess is supplied in <code>guess\_volume</code>, and it must be of data type <code>AVW\_FLOAT</code> and the same dimensions as the <code>obs\_volume</code>. If it is not, or it is <code>NULL</code>, the function allocates new memory for the returned <code>guess\_volume</code> and takes the observed volume to be the initial guess.

AVW\_IterDeconvVolume() can be called repeatedly with the output from the last call being the <code>guess\_volume</code> supplied to the next call in order to perform some iterations, examine the result, and then perform more iterations. The <code>update\_rule</code> parameter has the acceptable values <code>AVW\_UPDATE\_VC</code> and <code>AVW\_UPDATE\_GOLD</code>, and controls which updating scheme to use (see reference). The <code>no\_iter</code> parameter controls how many iterations to perform.

More detailed information about constrained iterative deconvolution may be found in the reference:

Agard, David A., *Fluorescence Microscopy in Three Dimensions* 1989, in Methods in Cell Biology, Vol. 30, Chap. 13, Academic Press.

### **RETURN VALUES**

If successful *AVW\_IterDeconvVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

Both *AVW\_IterDeconvVolume()* will fail if the following is true:

RADMAI.

Malloc Failed. Unable to allocate memory for return volume or image.

**ILLPAR** 

Illegal Parameter. An invalid value was given for an input parameter.

**ILLVOL** 

Illegal Volume. Input image was not a power of 2 in each dimension.

**BDSPCT** 

Bad Input Spectrum. An invalid spectrum was entered for the transfer function.

# **SEE ALSO**

 $AVW\_IterDeconvImage(),\ AVW\_DeconvDivideVolume(),\ AVW\_DeconvWienerVolume(),\ AVW\_Volume(),\ A$ 

AVW\_LabelImageFromEdges - finds connected regions in an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_LabelImageFromEdges(in\_image, connectivity, out\_image)

AVW\_Image \*in\_image;

int connectivity;

AVW\_Image \*out\_image;

DESCRIPTION

AVW\_LabelImageFromEdges() finds all of the unique connected regions in in\_image seperated by edges. All nonzero pixels in in\_image are interpreted as edge points. See AVW\_FindImageEdges(). Each unique connected region is given a different value in out\_image.

*Connectivity* may be either *AVW\_4\_CONNECTED* or *AVW\_8\_CONNECTED* and specifies the neighbors to be used to determine the connected components.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_LabelImageFromEdges()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

 $AVW\_Label Volume From Edges (), \ AVW\_Find Image Components (), \ AVW\_Find Image Edges (), \ AVW\_Image$ 

AVW\_LabelVolumeFromEdges - finds connected regions in a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_LabelVolumeFromEdges(in\_volume, connectivity, out\_volume)

 $AVW\_Volume * in\_volume;$ 

int connectivity;

AVW\_Volume \*out\_volume;

DESCRIPTION

AVW\_LabelVolumeFromEdges() finds all of the unique connected regions in in\_volume seperated by edges. All nonzero voxels in in\_volume are interpreted as edge points. See AVW\_FindVolumeEdges(). Each unique connected region is given a different value in out\_volume.

*Connectivity* may be either *AVW\_6\_CONNECTED* or *AVW\_26\_CONNECTED* and specifies the neighbors to be used to determine the connected components.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_LabelVolumeFromEdges()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_LabelImageFromEdges(), AVW\_FindVolumeComponents(), AVW\_FindVolumeEdges(), AVW\_Volume

AVW\_ListFormats – returns a list of supported image file formats

**SYNOPSIS** 

#include "AVW\_ImageFile.h"

AVW\_List \*AVW\_ListFormats (properties)

int properties;

## **DESCRIPTION**

*AVW\_ListFormats()* returns an *AVW\_List* of image file formats that are currently extended to support the passed property. *Properties* is a value made by combining the following values from *AVW\_ImageFile.h* with the logical OR "|" operator:

AVW\_SUPPORT\_UNSIGNED\_CHAR AVW\_SUPPORT\_SIGNED\_CHAR
AVW\_SUPPORT\_UNSIGNED\_SHORT AVW\_SUPPORT\_SIGNED\_SHORT
AVW\_SUPPORT\_UNSIGNED\_INT AVW\_SUPPORT\_SIGNED\_INT
AVW\_SUPPORT\_FLOAT AVW\_SUPPORT\_COMPLEX AVW\_SUPPORT\_COLOR
AVW\_SUPPORT\_2D AVW\_SUPPORT\_3D AVW\_SUPPORT\_4D AVW\_SUPPORT\_READ
AVW\_SUPPORT\_WRITE

For example:

list = AVW\_ListFormats(AVW\_SUPPORT\_READ);

gets a list of all formats supported for reading;

and

list = AVW\_ListFormats(AVW\_SUPPORT\_WRITE);

gets a list of all formats supported for writing.

### **RETURN VALUES**

Upon success AVW\_ListFormats() returns an AVW\_List in which the entries strings used to identify the image file format. For use with AVW\_CreateImageFile(). AVW\_SUCCESS. On failure NULL is returned and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause of failure.

**ERRORS** 

*AVW\_ListFormats()* will fail if one or more of the following are true:

**BDMAL** 

Malloc Failed

**SEE ALSO** 

AVW\_CreateImageFile(), AVW\_DestroyList(), AVW\_ExtendImageFile(), AVW\_FormatSupports(), AVW\_DisableImageFileFormat(), AVW\_EnableImageFileFormat(), AVW\_ExtendIO

**NAME** AVW\_ListInfo –lists entries in an information string

SYNOPSIS #include "AVW.h"

AVW\_List \*AVW\_ListInfo(info\_string)

char \*info\_string;

**DESCRIPTION** | *AVW\_ListInfo()* creates a list of strings which correspond to each information element in

an information string. Each information element is a string of the form Label=Value. Info strings are used in AVW structures to store additional information about the data and to

allow the user to extend the structures to carry application dependant data.

**RETURN VALUES** If successful *AVW\_ListInfo()* returns an *AVW\_List*. On failure, *NULL* is returned.

**SEE ALSO** | AVW\_DestroyList(), AVW\_GetNumericInfo(), AVW\_MergeInfo(), AVW\_PutHistoryInfo(),

AVW\_PutNumericInfo(), AVW\_PutStringInfo(), AVW\_RemoveInfo(), AVW\_Image,

AVW\_ImageFile, AVW\_List, AVW\_Volume

AVW\_LoadColormap - loads a color map

**SYNOPSIS** 

#include "AVW.h"

AVW\_Colormap \*AVW\_LoadColormap(file)

char \*file;

**DESCRIPTION** 

AVW\_LoadColormap() reads an AVW\_Colormap from the disk file called file. AVW colormap files usually end in .lkup. Colormap values are stored as ASCII strings representing values from 0 to 255. The red value for the first cell, if followed by the green value for the first cell, followed by the blue value for the first cell. This order is followed for each colorcell defined by the file.

**RETURN VALUES** 

If successful *AVW\_LoadColormap()* returns a pointer to an *AVW\_Colormap* structure. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_LoadColormap() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**BADOPEN** 

Could open file for reading or writing.

**BADREAD** 

Error occurred while reading file.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_CreateColormap(), AVW\_DestroyColormap(), AVW\_SaveColormap(), AVW\_Colormap

AVW\_LoadCompositeInfo - loads compositing information

**SYNOPSIS** 

#include "AVW\_CompositeInfo.h"

AVW\_CompositeInfo \*AVW\_LoadCompositeInfo(file)

char \*file;

**DESCRIPTION** 

AVW\_LoadCompositeInfo() reads an AVW\_CompositeInfo from the disk file called file. The color and opacity at each intensity is determined by the information within the file. The composite information is used by AVW\_RenderVolume() to assign colors and opacities to voxels the rendering type is set to AVW\_VOLUME\_COMPOSITING.

**RETURN VALUES** 

If successful AVW\_LoadCompositeInfo() returns a pointer to an AVW\_CompositeInfo structure. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_LoadCompositeInfo() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**BADOPEN** 

Could open file for reading or writing.

**BADREAD** 

Error occurred while reading file.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_CreateCompositeInfo(), AVW\_DestroyCompositeInfo(), AVW\_SaveCompositeInfo(), AVW\_CompositeInfo

AVW\_LoadContourSurface - writes a contour surface to a file

**SYNOPSIS** 

#include "AVW\_Model.h"

AVW\_ContourSurface\* AVW\_LoadContourSurface(filename, format, srfc)

char\* filename;

int format;

AVW\_ContourSurface \*srfc;

**DESCRIPTION** 

AVW\_LoadContourSurface() reads a contour surface, from the file given by *filename. format* is used to determine which input format to use. Supported output formats are:

AVW\_POGO\_SURFACE, AVW\_SLC\_SURFACE, and AVW\_SSD\_ASCII\_SURFACE. srfc is

provided as a means of reusing an existing AVW\_ContourSurface.

**RETURN VALUES** 

 $AVW\_Load Contour Surface () \ returns \ a \ AVW\_Contour Surface \ if \ successful. \ On \ failure, \ NULL$ 

will be returned and AVW\_ErrorNumber and AVW\_ErrorMessage will be set to values

corresponding to the cause of the failure.

**ERRORS** 

AVW\_SaveContourSurface() will fail if one of the following is true:

**BDREAD** 

File read failed.

**BDOPEN** 

Unable to open file.

**SEE ALSO** 

AVW\_DestroyContourSurface(), AVW\_SliceVolume(), AVW\_ContourSurface, AVW\_RPParam

NAME | AVW\_LoadObjectMap – loads an object map

SYNOPSIS #include "AVW\_ObjectMap.h"

AVW\_ObjectMap \*AVW\_LoadObjectMap(file)

char \*file;

**DESCRIPTION** | AVW\_LoadObjectMap() reads an AVW\_ObjectMap from the disk file called file. The

number of objects and contents of each object is determined by information within the

file. The object map is used by AVW\_RenderVolume() to distinguish seperate objects.

**RETURN VALUES** If successful *AVW\_LoadObjectMap()* returns a pointer to an *AVW\_ObjectMap* structure.

On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values

corresponding to the cause of the failure.

**ERRORS** | *AVW\_LoadObjectMap()* will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**BADOPEN** 

Could open file for reading or writing.

**BADREAD** 

Error occurred while reading file.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** | AVW\_AddObject(), AVW\_CreateObjectMap(), AVW\_DeleteObject(),

AVW\_DestroyObjectMap(), AVW\_RenderVolume(), AVW\_SaveObjectMap(),

AVW\_ObjectMap

AVW\_LoadTiledSurface - reads an ordered surface from a file

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW\_Model.h"

AVW\_TiledSurface \*AVW\_LoadTiledSurface(path, format, outSrfc)

char \*path;
int format;

cated.

AVW\_TiledSurface \*outSrfc;

**DESCRIPTION** 

AVW\_LoadTiledSurface() reads an ordered surface from the file given by path. Format specifies which geometric file format is to be read. Supported formats are: AVW\_VRIO\_SURFACE, AVW\_DXF\_SURFACE, AVW\_OBJ\_SURFACE, AVW\_STL\_SURFACE, and AVW\_POLY\_SURFACE. OutSrfc is provided as a means of reusing an existing Kohonen Network. If outSrfc is NULL, a new vector list will be allo-

**RETURN VALUES** 

AVW\_LoadTiledSurface() returns a ordered surface if successful. On failure, NULL will be returned and AVW\_ErrorNumber and AVW\_ErrorMessage will be set to values corresponding to the cause of the failure. In the event of failure, outSrfc is not guaranteed to hold meaningful data or even to exist.

**ERRORS** 

AVW\_LoadTiledSurface() will fail if one of the following is true:

**CORRUPT** 

File is corrupt or not in correct format.

**BADMAL** 

Malloc fails.

**BDREAD** 

File read failed.

**BDOPEN** 

Unable to open file.

**SEE ALSO** 

AVW\_DestroyTiledSurface(), AVW\_SaveTiledSurface(), AVW\_TileVolume(), AVW\_DrawTiledSurface(), AVW\_TiledSurface

**NAME** AVW\_LoadTree - loads a tree structure

**SYNOPSIS** #include "AVW\_Tree.h"

AVW\_Tree \*AVW\_LoadTree(file)

char \*file;

**DESCRIPTION** AVW\_LoadTree() reads an AVW\_Tree from the disk file called file.

**RETURN VALUES** If successful AVW\_LoadTree() returns a pointer to an AVW\_Tree structure. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values correspond-

ing to the cause of the failure.

**ERRORS** AVW\_LoadTree() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**BADOPEN** 

Could open file for reading or writing.

**RDERR** 

Error occurred while reading file.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** AVW\_AddTreeChild(), AVW\_CreateTree(), AVW\_DestroyTree(), AVW\_FindTreeIndex(),

AVW\_SaveTree(), AVW\_TreePoint, AVW\_Tree

AVW\_LowpassFilterImage - performs a 2D Lowpass filter

**SYNOPSIS** 

#include "AVW\_Filter.h"

AVW\_Image \*AVW\_LowpassFilterImage(in\_image, extents, out\_image)

AVW\_Image \*in\_image;

int extents[2];

AVW\_Image \*out\_image;

### **DESCRIPTION**

AVW\_LowpassFilterImage() performs a Lowpass filter transformation on in\_image. In the Lowpass filter each pixel value is replaced with an average pixel value in the rectangular neighborhood specified by extents. Extents[0] and extents[1], specify the x and y sizes respectively of the filter.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_LowpassFilterImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **SEE ALSO**

AVW\_LowpassFilterVolume(), AVW\_AHEImage(), AVW\_OrthoGradFilterImage(), AVW\_RankFilterImage(), AVW\_SigmaFilterImage(), AVW\_SobelFilterImage(), AVW\_SobelFilterEnhanceImage(), AVW\_UnsharpFilterImage(), AVW\_UnsharpFilterEnhanceVolume(), AVW\_Image(), AVW\_UnsharpFilterEnhanceVolume(), AVW\_Image(), AVW\_Image()

AVW\_LowpassFilterVolume - performs a 3D Lowpass filter

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Volume \*AVW\_LowpassFilterVolume(in\_volume, extents, out\_volume)

AVW\_Volume \*in\_volume;

int extents[3];

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_LowpassFilterVolume() performs a Lowpass filter transformation on *in\_volume*. In the Lowpass filter each voxel value is replaced with an average voxel value in the neighborhood specified by *extents*. *Extents*[0], *extents*[1], and *extents*[2] specify the x, y, and z sizes respectively of the filter.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful AVW\_LowpassFilterVolume() returns an AVW\_Volume. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_LowpassFilterImage(), AVW\_AHEVolume(), AVW\_OrthoGradFilterVolume() AVW\_RankFilterVolume(), AVW\_SigmaFilterVolume(), AVW\_SobelFilterVolume(), AVW\_SobelFilterEnhanceVolume(), AVW\_UnsharpFilterVolume(), AVW\_UnsharpFilterVolume(), AVW\_VSFmeanFilterVolume(), AVW\_Volume(), AVW\_VSFmeanFilterVolume(), AVW\_Volume(), AVW\_VSFmeanFilterVolume(), AVW\_Volume(), AVW\_VSFmeanFilterVolume(), AVW\_Volume(), AVW\_VSFmeanFilterVolume(), AVW\_Volume(), AVW\_VSFmeanFilterVolume(), AVW\_VSFmeanFilter

AVW\_MMapSelect – selects volume from multivolume mmapped file

**SYNOPSIS** 

#include "AVW\_ImageFile.h"

int AVW\_MMapSelect(vol, which)

AVW\_Volume \*vol;

int which;

**DESCRIPTION** 

*AVW\_MMapSelect()* sets the selected volume of multi-volume file which has been previously memory mapped with function *AVW\_MMapVolume*.

vol is the pointer to the memory mapped volume.

*which* is an integer indicating the volume number to select. Volumes are numbered from 0 to the number of volumes in the file less 1.

**RETURN VALUES** 

Upon success *AVW\_MMapSelect* returns *AVW\_SUCCESS*. On failure *AVW\_FAIL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values indicating the cause of the error.

**ERRORS** 

Errors may occur for the following reasons:

**MMAPER** 

vol is not a memory-mapped volume.

**ILLVOL** 

illegal volume number.

**SEE ALSO** 

AVW\_MMapVolume()

**NAME** AVW\_MMapVolume – mmaps an image file to an AVW\_Volume

**SYNOPSIS** #include "AVW\_ImageFile.h"

AVW\_Volume \*AVW\_MMapVolume(imgfile)

AVW\_ImageFile \*imgfile;

**DESCRIPTION** | AVW\_MMapVolume() uses the UNIX mmap() function to associate an image file to an

AVW\_Volume. This is equivalent to AVW\_ReadVolume() except that the reading of the

*imgfile* is delayed until the data within the AVW\_Volume is actually accessed.

**RETURN VALUES** Upon success AVW\_MMapVolume() returns an AVW\_Volume. On failure NULL is

returned and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values indicating the

cause of error.

**ERRORS** Errors may occur for the following reasons:

**BADMAL** 

Bad Malloc. Memory allocation error.

**MMAPER** 

Unmappable file.

SEE ALSO AVW\_CreateImageFile(), AVW\_ExtendImageFile(), AVW\_OpenImageFile(),

AVW\_ReadVolume(), AVW\_ReadImageFile(), AVW\_MMapSelect(), mmap()

AVW\_MakeColorImage - makes a color image out of 3 grayscale images

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_MakeColorImage(red\_image, green\_image, blue\_image, out\_image)

AVW\_Image \*red\_image;

AVW\_Image \*green\_image;

AVW\_Image \*blue\_image;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_MakeColorImage() creates a 24-bit AVW\_Image, from one or more

AVW\_UNSIGNED\_CHAR gray scale images.

NULL may be passed for up to two of the AVW\_Images.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful AVW\_MakeColorImage() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause

of the failure.

**ERRORS** 

AVW\_MakeColorImage() will fail if:

**ILLDT** 

Illegal Datatype.

**SEE ALSO** 

AVW\_MakeColorVolume, AVW\_Image

AVW\_MakeColorVolume - makes a color volume out of 3 grayscale volumes

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_MakeColorVolume(red\_volume, green\_volume, blue\_volume,

out\_volume)

AVW\_Volume \*red\_volume;

AVW\_Volume \*green\_volume;

AVW\_Volume \*blue\_volume;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_MakeColorVolume() creates a 24-bit AVW\_Volume, from one or more

AVW\_UNSIGNED\_CHAR gray scale volumes.

NULL may be passed for up to two of the AVW\_Volumes.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful AVW\_MakeColorVolume() returns an AVW\_Volume. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to

the cause of the failure.

**ERRORS** 

AVW\_MakeColorVolume() will fail if:

**ILLDT** 

Illegal Datatype.

**SEE ALSO** 

AVW\_MakeColorImage, AVW\_Volume

AVW\_MakeComplexImageViewable – converts a complex image to a viewable data type

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_MakeComplexImageViewable(in\_image, displaytype, halfflag, out\_image) AVW\_Image \*in\_image; int displaytype,halfflag; AVW Image \*out\_image;

**DESCRIPTION** 

AVW\_MakeComplexImageViewable() converts in\_image to the specified displaytype. Acceptable values for displaytype, as defined in AVW.h, are: AVW\_SPECTRUM\_LOG\_PHASE, AVW\_SPECTRUM\_PHASE\_COLOR, AVW\_SPECTRUM\_LOG\_COLOR, AVW\_SPECTRUM\_LOG\_MAGNITUDE, AVW\_SPECTRUM\_MAGNITUDE, AVW\_SPECTRUM\_REAL, AVW\_SPECTRUM\_IMAGINARY.

The most common source of complex images is  $AVW\_FFT2D$ . These images are of dimension (Width/2 +1)x(Height) relative to the original imput image. If halfflag is 1,  $AVW\_MakeComplexImageViewable$  returns a viewable image of dimension (Width)x(Height). No intensity scaling is attempted during the conversion process.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_MakeComplexImageViewable()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_MakeComplexImageViewable() will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for output volume.

**ILLDT** 

Unknown or unsupported input or output displaytype.

**SEE ALSO** 

 $AVW\_ConvertVolume(),\ AVW\_DitherImage(),\ AVW\_IntensityScaleImage(),\ AVW\_MakeGrayImage()\ AVW\_Image$ 

**NAME** AVW\_MakeFPointList2 – converts a list of points to floats

SYNOPSIS #include "AVW.h"

AVW\_FPointList2 \*AVW\_MakeFPointList2(plist, fplist)

AVW\_PointList2 \*plist; AVW\_FPointList2 \*fplist;

**DESCRIPTION** AVW\_MakeFPointList2() builds an AVW\_FPointList2 from an AVW\_PointList2.

*fplist* is provided as a method of reusing an existing *AVW\_FPointList2*. Reuse is possible only if the size and data type of the provided *fplist* meet the requirements of the function. In this case the pointer to *fplist* is returned by the function. If not reusable *fplist* will be

reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_MakeFPointList2()* returns an *AVW\_FPointList2*. On failure it returns

NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to

the cause of the failure.

**SEE ALSO** *AVW\_CreateFPointList2(), AVW\_CreatePointList2(), AVW\_AddFPoint2(),* 

 $AVW\_DestroyFPointList2(),\ AVW\_FPointList2,\ AVW\_PointList$ 

AVW\_MakeGrayImage - converts a color image to a gray scale image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_MakeGrayImage(in\_image, out\_image)

 $AVW\_Image * in\_image;$ 

AVW\_Image \*out\_image;

# **DESCRIPTION**

AVW\_MakeGrayImage() converts a 24-bit AVW\_Image, or an AVW\_UNSIGNED\_CHAR image with a colormap, to a AVW\_UNSIGNED\_CHAR gray scale image.

Conversion is done using the following formula:

out\_color = red \* .30 + green \* .59 + blue \* .11;

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful AVW\_MakeGrayImage() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_MakeGrayImage() will fail if:

**ILLDT** 

Illegal Datatype.

**SEE ALSO** 

AVW\_ConvertImage(), AVW\_ConvertVolume(), AVW\_DitherImage(), AVW\_DitherVolume(), AVW\_MakeGrayVolume(), AVW\_Image, AVW\_Colormap

AVW\_MakeGrayVolume – converts a color volume to a gray scale volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_MakeGrayVolume(in\_volume, out\_volume)

 $AVW\_Volume * in\_volume;$ 

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_MakeGrayVolume() converts a 24-bit AVW\_Volume, or an AVW\_UNSIGNED\_CHAR volume with a colormap, to a AVW\_UNSIGNED\_CHAR gray scale volume.

Conversion is done using the following formula:

out\_color = red \* .30 + green \* .59 + blue \* .11;

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_MakeGrayVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_MakeGrayVolume() will fail if:

**ILLDT** 

Illegal Datatype.

**SEE ALSO** 

 $AVW\_ConvertVolume(),\ AVW\_DitherVolume(),\ AVW\_MakeGrayImage(),\ AVW\_Colormap,\ AVW\_Volume$ 

AVW\_MakeMaskFromTrace - makes a binary mask from a trace

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_MakeMaskFromTrace(trace, point, width, height, under\_border, out\_image)

AVW\_PointList2 \*trace;

AVW\_Point2 \*point;

int width, height, under\_border;

AVW\_Image \*out\_image;

# DESCRIPTION

AVW\_MakeMaskFromTrace() creates a binary valued mask, out\_image, in which all pixels connected to point and bounded by trace are set to 1 and all other pixels are set to 0. The dimensions of out\_image are set to width and height and the datatype is AVW\_UNSIGNED\_CHAR. If under\_border is set to AVW\_TRUE, the pixels under the trace

are set to 1. Otherwise they are set to 0.

In previous versions of *AVW* the *trace* was required to be 8 or 4 connected. Gaps in the *trace* are now filled in with linearly interpolated points.

The mask can be used to restrict the pixels of an image to be processed or sampled.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meets the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_MakeMaskFromTrace()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **SEE ALSO**

 $AVW\_ComputeImageCentroid(),\ AVW\_GetMaskBoundary(),\\ AVW\_ComputeImageFractalSig(),\ AVW\_GetImageHistogram(),\ AVW\_ComputeMEB(),\\ AVW\_ComputeRFF(),\ AVW\_Compute2DShapeStats(),\ AVW\_AVW\_FillPointList2(),\\ AVW\_Image,\ AVW\_PointList2,\ AVW\_Point2$ 

AVW\_MakeMatrixFrom3Points - defines a matrix from 3 points

**SYNOPSIS** 

#include "AVW.h"

AVW\_Matrix \*AVW\_MakeMatrixFrom3Points(p1, p2, p3, xd, yd, zd, out\_matrix)

AVW\_Point3 \*p1,\*p2,\*p3;

int xd, yd, zd;

AVW\_Matrix \*out\_matrix;

#### **DESCRIPTION**

 $AVW\_MakeMatrixFrom3Points()$  returns an  $AVW\_Matrix$ . The matrix, m, defines a plane through the three given points, p1, p2, and p3. The point equidistant from all three points is taken as the translation point. The line segment from p1 to p3 is taken as the horizontal axis. This matrix, when passed to  $AVW\_GetOblique()$  allows the user to extract an oblique plane which passes through the three points: p1, p2, and p3.

xd, yd, and zd specify the volume Width, Height, and Depth.

Out\_matrix is provided as a method of reusing an existing AVW\_Matrix. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful *AVW\_MakeMatrixFrom3Points()* returns an *AVW\_Matrix*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure. If the three points are colinear, they do not define a unique plane and *AVW\_FAIL* will be returned.

# **ERRORS**

AVW\_MakeMatrixFrom3Points() will fail if:

**ILLPAR** 

Illegal parameter. The three points are colinear or not unique.

**SEE ALSO** 

AVW\_CreateMatrix(), AVW\_GetOblique(), AVW\_MakeMatrixFromAxis(), AVW\_InitializeOblique(), AVW\_RotateMatrix(), AVW\_ScaleMatrix(), AVW\_TranslateMatrix(), AVW\_Point3, AVW\_Matrix

AVW\_MakeMatrixFromAxis – defines a plane perpendicular to an axis

**SYNOPSIS** 

#include "AVW.h"

 $AVW\_Matrix *AVW\_MakeMatrixFromAxis (axis, xd, yd, zd, midpoint, out\_matrix)$ 

AVW\_Line3 \*axis;

int xd, yd, zd;

int midpoint;

AVW\_Matrix \*out\_matrix;

#### **DESCRIPTION**

AVW\_MakeMatrixFromAxis() returns an AVW\_Matrix. The matrix defines a plane perpendicular to axis. The midpoint parameter specifies whether the plane is positioned at the start, 0, end, 1, or midpoint, 2, of axis.

xd, yd, and zd specify the volume Width, Height, and Depth.

This matrix, when passed to *AVW\_GetOblique()* allows the user to extract an oblique plane perpendicular to an axis.

Out\_matrix is provided as a method of reusing an existing AVW\_Matrix. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_MakeMatrixFromAxis()* returns an *AVW\_Matrix*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_MakeMatrixFromAxis() will fail if:

**ILLPAR** 

Illegal parameter. The value for midpoint is undefined.

**SEE ALSO** 

AVW\_CreateMatrix(), AVW\_MakeMatrixFrom3Points(), AVW\_InitializeOblique(), AVW\_GetOblique(), AVW\_RotateMatrix(), AVW\_TranslateMatrix(), AVW\_ScaleMatrix(), AVW\_Matrix, AVW\_Line3

**NAME** AVW\_MakeMonoImage – Makes a monochromatic image

SYNOPSIS #include "AVW.h"

AVW\_Image \*AVW\_MakeMonoImage(in\_image, out\_image)

AVW\_Image \*in\_image; AVW\_Image \*out\_image;

**DESCRIPTION** | AVW\_MakeMonoImage() makes a monochromatic (black and white) image from any

AVW\_Image by doing two color dithering.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_MakeMonoImage()* returns an *AVW\_Image*. On failure it returns *NULL* 

and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause

of the failure.

**ERRORS** AVW\_MakeMonoImage() will fail if:

ILLDT

Illegal Datatype. In\_image may be of any type except AVW\_Complex.

SEE ALSO | AVW\_DitherVolume(), AVW\_DitherImage(), AVW\_ConvertImage(), AVW\_MakeGrayImage(), AVW\_V

AVW\_Image

AVW\_MakeSpline - fits a spline to a set of points

**SYNOPSIS** 

#include "AVW.h"

AVW\_PointList2 \*AVW\_MakeSpline(control, step, close\_flag, spline)

AVW\_PointList2 \*control;

double step;
int close\_flag;

AVW\_PointList2 \*spline;

#### **DESCRIPTION**

AVW\_MakeSpline() fits a smooth curve to a set of *control* points. The *step* parameter specifies the spacing of points on the smooth curve between which linearly interpolated points are filled. A value of .02 is a good default. The *close\_flag* specifies whether the *control* points represent a closed (1) or open (0) trace. The resultant smoothed trace is stored in *spline*.

The list structures are managed and memory for the structures is reallocated as needed. These structures are defined in *AVW.h* and are commonly used for traces and stacks.

Spline is provided as a method of reusing an existing AVW\_PointList2.

# **RETURN VALUES**

If successful AVW\_MakeSpline() returns an AVW\_PointList2. On failure it returns AVW\_NULL and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_MakeSpline() will fail if:

**ILLPAR** 

An illegal parameter, NULL control, was passed to the routine.

**SEE ALSO** 

AVW\_AddFPoint2(), AVW\_CreatePointList2(), AVW\_DestroyPointList2(), AVW\_ExtractControlPoints(), AVW\_FillPointList2(), AVW\_PointList2, AVW\_Point2

AVW\_MakeTree - builds tree files from a thinned volume

# **SYNOPSIS**

#include "AVW Tree.h"

AVW\_Tree \*AVW\_MakeTree(in\_volume, start\_pt, minlen, maxlen)

AVW\_Volume \*in\_volume; AVW\_Point3 \*start\_pt;

int minlen, maxlen;

#### **DESCRIPTION**

AVW\_MakeTree() traverses a thinned volume and and creates an AVW\_Tree structure containing the coordinates of the tree. One tree will be created based on the first connected component encountered within the volume. This voxels of <code>in\_volume</code> are set to zero as points are added to the tree. The user can check if there are any potential trees left in the <code>in\_volume</code> by using <code>AVW\_IsVolumeZero()</code>. The tree coordinates will always start at an endpoint.

*In\_volume* is the input volume must be thinned. See *AVW\_Thin3D()*.

Start\_pt specifies the starting point of the tree. *Minlen* specifies the minimum length of an entire tree. Trees with fewer *minlen* points will be ignored. *Maxlen* specifies the maximum length of an entire tree. Trees with more than *maxlen* points will be ignored. If a zero or negative *maxlen* is specified the upper limit on the tree size will be disregarded.

#### **RETURN VALUES**

If successful *AVW\_MakeTree()* returns an *AVW\_Tree*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure. *NULL* may also be returned if the tree found by the routine is not within the specified size limits.

# **ERRORS**

AVW\_MakeTree() will fail if:

**ILLDT** 

Data type is not AVW\_UNSIGNED\_CHAR.

**ILLPT** 

Illegal starting point.

**BDOPEN** 

Could not open file.

# **SEE ALSO**

AVW\_Thin3D(), AVW\_FindTreeStart(), AVW\_FillHolesImage(), AVW\_Volume

AVW\_MakeVolumeFromImage - makes a volume from an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_MakeVolumeFromImage(image, volume)

AVW\_Image \*image; AVW\_Volume \*volume;

**DESCRIPTION** 

AVW\_MakeVolumeFromImage() creates a one slice AVW\_Volume from an AVW\_Image.

*Volume* is provided as a method of reusing an existing *AVW\_Volume*. Reuse is possible only if the size and data type of the provided *volume* meets the requirements of the function. In this case the pointer to *volume* is returned by the function. If not reuseable *volume* will be reallocated. (See *Memory Usage* in the *AVW Programmer's Guide*.)

**RETURN VALUES** 

If successful AVW\_MakeVolumeFromImage() returns an AVW\_Volume. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the failure.

**SEE ALSO** 

AVW\_CreateVolume(), AVW\_Image, AVW\_Volume

AVW\_Malloc - allocates system memory

#### **SYNOPSIS**

#include "AVW.h"

void \*AVW\_Malloc(size)
unsigned int size;

void \*AVW\_Calloc(num, size)
unsigned int num;
unsigned int size;

void \*AVW\_Realloc(size, ptr)
unsigned int size;
void \*ptr;

void AVW\_Free(ptr)
void \*ptr;

# **DESCRIPTION**

These procedures provide a platform and compiler independent interface for memory allocation. Programs that need to transfer ownership of memory blocks between *AVW* and other modules should use these routines rather than the native *malloc()* and *free()* routines provided by the *C* run-time library.

AVW\_Malloc returns a pointer to a size bytes suitably aligned for any use.

AVW\_Calloc allocates space for an array nelem elements of size elsize. The space is initialized to zeros.

*Tcl\_Realloc* changes the size of the block pointed to by *ptr* to *size* bytes and returns a pointer to the new block. The contents will be unchanged up to the lesser of the new and old sizes. The returned location may be different from *ptr*.

*Tcl\_Free* makes the space referred to by *ptr* available for further allocation.

# **SEE ALSO**

malloc(), free()

AVW\_MaskImageToSampleFile - creates a multi-spectral sample file from a mask image

# **SYNOPSIS**

#include "AVW.h"

int AVW\_MaskImageToSampleFile(imgs, numimgs, maskImage, SampleFile)

AVW\_Image \*\*imgs; int numimgs; AVW\_Image \*maskImage; char \*SampleFile;

# **DESCRIPTION**

AVW\_MaskImageToSampleFile() generates an AVW multi-spectral sample file from a mask image and a list of corresponding spatially correlated images. This file can be used to perform image classification with AVW\_ClassifyImageFromSampleFile() or volumes with AVW\_ClassifyVolumeFromSampleFile().

Classification from a Sample File makes it possible to perform multi-spectral classification of images and volumes based on standardized class definitions.

Each non-zero pixel from the *maskImage* generates an row entry in the *SampleFile* which consists of the class number (the value of that maskImage pixel) and the values of the corresponding pixels from the list of images pointed at by *Imgs*.

Imgs is a list of spatially correlated images.

Numimgs is the number of images in Imgs

*MaskImage* is an and AVW\_Image of DataType AVW\_UNSIGNED\_CHAR and the same size as the images in *Imgs* in which pixels to be used as training samples have non-zero values.

SampleFile is the name of the text file which is created by the function.

# Example Sample File contents

**AVW Multispectral Classification Samples File** 

Classes=6

#### Bands=4

- 1 48.0000 27.0000 52.0000 69.0000
- 1 61.0000 31.0000 61.0000 85.0000
- 2 59.0000 44.0000 86.0000 91.0000
- 2 58.0000 40.0000 78.0000 88.0000
- 2 59.0000 42.0000 82.0000 88.0000

The first line of the file contains a signature identifying the contents of the file. The second line indicates how many classes are described in the file. The third row indicates the number of samples in a row.

AVW\_MaskImageToSampleFile() returns an AVW\_SUCCESS. On failure it returns AVW\_FAIL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ClassifyImage will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. A memory allocation failed.

**ILLIMG** 

Illegal Image. The images are not all the same dimension.

**BDTRSM** 

Bad Training Sample. The supplied training samples were unusable.

**INSPEC** 

Insufficient Specifications. Fewer than two input images were supplied.

**SEE ALSO** 

 $AVW\_MaskVolumeToSampleFile(),\ AVW\_ClassifyVolumeFromSampleFile(),\ AVW\_LassifyImageFromSampleFile(),\ AVW\_Image$ 

 $AVW\_MaskVolume To Sample File-creates~a~multi-spectral~sample~file~from~a~mask~volume$ 

#### **SYNOPSIS**

#include "AVW.h"

int AVW\_MaskVolumeToSampleFile(vols, numvols, maskVolume, SampleFile)

AVW Volume \*\*vols:

int numvols:

AVW\_Volume \*maskVolume;

char \*SampleFile;

#### **DESCRIPTION**

AVW\_MaskVolumeToSampleFile() generates an AVW multi-spectral sample file from a mask volume and a list of corresponding spatially correlated volumes. This file can be used to perform image classification with AVW\_ClassifyImageFromSampleFile() or volumes with AVW\_ClassifyVolumeFromSampleFile().

Classification from a Sample File makes it possible to perform multi-spectral classification of images and volumes based on standardized class definitions.

Each non-zero voxel from the *maskVolume* generates an row entry in the *SampleFile* which consists of the class number (the value of that maskVolume voxel) and the values of the corresponding voxels from the list of volumes pointed at by *Vols*.

Vols is a list of spatially correlated volumes.

Numvols is the number of vols in vols

*MaskVolume* is an and AVW\_Volume of DataType AVW\_UNSIGNED\_CHAR and the same size as the volumes in *vols* in which voxels to be used as training samples have non-zero values.

SampleFile is the name of the text file which is created by the function.

# Example Sample File contents

**AVW Multispectral Classification Samples File** 

Classes=6

Bands=4

- 1 48.0000 27.0000 52.0000 69.0000
- 1 61.0000 31.0000 61.0000 85.0000
- 2 59.0000 44.0000 86.0000 91.0000
- 2 58.0000 40.0000 78.0000 88.0000
- 2 59.0000 42.0000 82.0000 88.0000

The first line of the file contains a signature identifying the contents of the file. The second line indicates how many classes are described in the file. The third row indicates the number of samples in a row.

AVW\_MaskVolumeToSampleFile() returns an AVW\_SUCCESS. On failure it returns AVW\_FAIL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ClassifyImage will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. A memory allocation failed.

**ILLIMG** 

Illegal Image. The images are not all the same dimension.

**BDTRSM** 

Bad Training Sample. The supplied training samples were unusable.

INSPEC

Insufficient Specifications. Fewer than two input images were supplied.

**SEE ALSO** 

AVW\_MaskImageToSampleFile(), AVW\_ClassifyVolumeFromSampleFile(), AVW\_ClassifyImageFromSampleFile(), AVW\_Volume

AVW\_MatchImageHistogram – matches the intensity distribution of an image to a histogram

**SYNOPSIS** 

#include "AVW\_Histogram.h"

AVW\_Image \*AVW\_MatchImageHistogram(in\_image, mhisto, out\_image)

**AVW 3.0** 

AVW\_Image \*in\_image; AVW\_Histogram \*mhisto; AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_MatchImageHistogram() forces the histogram of <code>in\_image</code> to match the grey scale distribution of <code>mhisto</code>. The results are returned in <code>out\_image</code>.

Images of the same subject should have the same general distribution of grey levels, even though the parameters of a particular image (exposure, brightness, contrast) may vary widely. Histogram matching may be used to normalize the absolute greyscale values of a set of images to a selected "optimal" example.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.).

**RETURN VALUES** 

If successful *AVW\_MatchImageHistogram()* returns an *AVW\_Image* which has been matched to the provided histogram. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_MatchImageHistogram() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**ILLHIS** 

Histogram provided was not valid.

**SEE ALSO** 

AVW\_MatchVolumeHistogram(), AVW\_CreateHistogram(), AVW\_FlattenImageHistogram(), AVW\_GetImageHistogram(), AVW\_NormalizeHistogram(), AVW\_PreserveImageHistogram(), AVW\_VerifyHistogram(), AVW\_Histogram, AVW\_Image

AVW\_MatchSurfaces – generates the matrix required to register volumes

# **SYNOPSIS**

#include "AVW SurfaceMatch.h"

AVW\_MatchResult \*AVW\_MatchSurfaces(base\_volume, match\_volume, free\_flag, param) AVW\_Volume \*base\_volume, \*match\_volume; int free\_flag;

AVW\_MatchParameters \*param;

#### **DESCRIPTION**

AVW\_MatchSurfaces() determines the geometric transformation parameters required to spatially register two volumes. The transformation parameters include: 3D translation, 3D rotation, and 3D scaling. The parameters are output in *Matrix*, which is a member of the *AVW\_MatchResults* structure. Image registration can be achieved by transforming a input volume, most likely the unedited version of the *match\_volume*, by the matrix. Note that both the *base\_volume* and *match\_volume* need to have the "VoxelWidth", "VoxelHeight" and "VoxelDepth" set in the *Info* string of their structure (See *AVW\_PutNumericInfo()*).

Surfaces are extracted from both the <code>base\_volume</code> and <code>match\_volume</code>. Both volumes must be presegmented <code>AVW\_UNSIGNED\_CHAR AVW\_Volumes</code>. All surface points in the <code>match\_volume</code> should should have corresponding points on the surface of the <code>base\_volume</code>.

Free\_flag, if set to AVW\_TRUE, allows the base\_volume and match\_volume to be freed after the surface has been extracted. This will cause the function to run more efficiently, as copies are avoided and less memory is used. This option should not be enabled if an iteration will be preformed. If this option is enabled, the base\_volume and match\_volume parameters should be set to NULL when the function returns.

For the *base\_volume*: if the data is non-cubic, shape-based interpolation is performed. Surface points are defined as any non-zero valued voxel with a zero valued 6 connected neighbor.

For the *match\_volume*: surface points are defined as any non-zero valued pixel with a zero valued 4 connected neighbor.

*param->SamplePoints* indicates the number of uniformly sampled points to be used to evaluate the *MeanSquareDistance* (MSD) between the two surfaces.

The matching process will search through the parameter space to determine the parameter set which minimizes the MSD. The initial best guess and search range is supplied by the *AVW\_MatchParameters*. The search will start from grid points uniformly distributed within the search range. A *RotationInterval* is also specified in the *AVW\_MatchParameters* structure, but the translation interval is calculated during the matching process. A pyramid multi-resolutional approach is used in the searching process. The search starts from the coarsest resolution level, and a number of starting points are rejected at each resolution level. The parameter set with the smallest (MSD) error is stored in the *AVW\_MatchResults Matrix*.

Base\_volume and match\_volume specify the AVW\_Volumes to match.

*Param->SamplePoints* specifies the number of surface points from the *match\_volume* to be used in the matching process.

If param->Centroid is set to AVW\_TRUE the initial position is set by registering the centroid of the match\_volume to the centroid of the base\_volume. If set to AVW\_FALSE, the param->TranslationX (+/- width (largest of base\_volume or match\_volume)), param->TranslationY (+/- height (largest of base\_volume or

*match\_volume*)), and *param->TranslationZ* (+/- # slices (largest of *base\_volume* or *match\_volume*)), are used as the initial match position.

*Param->TranslationRange* (0.0 to 100.0) specifies the percent search range for the three translation parameters.

*Param->RotationPrecession* (0.0 to 360.0 degrees), *param->RotationNutation* (0.0 to 180.0 degrees), and *param->RotationSpin* (0.0 to 360.0 degrees) specify the initial rotation guess.

*Param->RotationRange* (0.0 to 100.0) specifies the percent search range for the three rotation parameters.

*Param->RotationInterval* (0.0 to 360.0 degrees) specifies the interval of starting points along each rotation parmater axis.

The recommended AVW\_MatchParamenters to search the entire volume space are:

```
param->SamplePoints = 100

param->Centroid = AVW_TRUE

param->TranslationRange = 100.0

param->RotationPrecession = param->RotationNutation = param->RotationSpin = 0.0

param->RotationRange = 100.0

param->RotationInterval = 30.0
```

More detailed information about the surface matching algorithm may be found in the reference:

Jiang, H., K. Holton and R. Robb: Image registration of multimodality 3-D medical images by chamfer matching. Proceedings of Vision and Visualization, SPIE, San Jose, CA, Feb. 1992, pp. 649-659.

# **RETURN VALUES**

If successful AVW\_MatchSurfaces() returns a pointer to an AVW\_MatchResult structure.

This structure contains:

*Matrix* - homogeneous 4x4 matrix used to register *match\_volume* to *base\_volume*. A programmer could use *AVW\_InvertMatrix()* to generate the inverse and match *base\_volume* to *match\_volume*.

*MeanSquareDistance* - average distance from each match point to the closest base point. A lower value indicates a better match.

*NextInput* - a pointer to an *AVW\_MatchParameters* structure which contains the suggested parameters used for an iterative match.

The programmer is responsible for freeing the memory associated with the *AVW\_MatchResult* structure when it is no longer needed.

Example:

free(match\_results->NextInput); free(match\_results);

On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_MatchSurfaces() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**SEE ALSO** AVW\_TransformVolume(), AVW\_MatchParameters, AVW\_MatchResult, AVW\_Matrix,

 $AVW_{-}Volume$ 

AVW\_MatchVolumeHistogram - matches the intensity distribution of a volume to a histogram

#### **SYNOPSIS**

#include "AVW\_Histogram.h"

AVW\_Volume \*AVW\_MatchVolumeHistogram(in\_vol, mhisto, out\_vol)

AVW\_Volume \*in\_vol; AVW\_Histogram \*mhisto; AVW\_Volume \*out\_vol;

#### **DESCRIPTION**

AVW\_MatchVolumeHistogram() forces the histogram of in\_volume to match the grey scale distribution of mhisto.

The results are returned in out\_volume.

Volumes of the same subject should have the same general distribution of grey levels, even though the parameters of a particular volume (exposure, brightness, contrast) may vary widely. Histogram matching may be used to normalize the absolute greyscale values of a set of volumes to a selected "optimal" example.

Out\_vol is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_vol meet the requirements of the function. In this case the pointer to out\_vol is returned by the function. If not reusable out\_vol will be reallocated. (See Memory Usage in the AVW Programmer's Guide.).

# **RETURN VALUES**

If successful *AVW\_MatchVolumeHistogram()* returns an *AVW\_Volume* which has been matched to the provided histogram. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_MatchVolumeHistogram() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**ILLHIS** 

Histogram provided was not valid.

#### **SEE ALSO**

AVW\_MatchImageHistogram(), AVW\_CreateHistogram(), AVW\_DestroyHistogram(), AVW\_FlattenVolumeHistogram(), AVW\_GetVolumeHistogram(), AVW\_VerifyHistogram(), AVW\_NormalizeHistogram(), AVW\_PreserveVolumeHistogram(), AVW\_VerifyHistogram(), AVW\_VerifyHistogram

AVW\_Histogram. AVW\_Volume

AVW\_MatchVoxels - generates the matrix required to register volumes

**SYNOPSIS** 

#include "AVW MatchVoxels.h"

AVW\_Matrix \*AVW\_MatchVoxels(base\_volume, match\_volume, param, matrix)

AVW\_Volume \*base\_volume, \*match\_volume;

AVW\_MatchVoxelParams \*param;

AVW Matrix \*matrix;

**DESCRIPTION** 

AVW\_MatchVoxels() determines the geometric transformation parameters required to spatially register the base\_volume and match\_volume based on the matchin parameters in param. The transformation parameters include: 3D translation, 3D rotation, and 3D scaling. The function return an AVW\_Matrix, with the matching transformation.

The *AVW\_MatchVoxels()* function will use the mathcing parameters as deinfed in the *param* structure.

*matrix* is provided as a method of re-using an existing *AVW\_Matrix*.

**RETURN VALUES** 

If successful returns a pointer to an *AVW\_Matrix* structure which contains an homogeneous 4x4 matrix used to register *match\_volume* to *base\_volume*.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_MatchVoxels() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**SEE ALSO** 

AVW\_TransformVolume(), AVW\_MatchVoxelParams, AVW\_Matrix, AVW\_Volume.

AVW\_MatrixAngles – determines rotation angles from a transformation matrix

**SYNOPSIS** 

#include "AVW.h"

void AVW\_MatrixAngles(mat, xangle, yangle, zangle)

AVW\_Matrix \*mat; double \*xangle; double \*yangle; double \*zangle;

**DESCRIPTION** 

 $AVW\_MatrixAngles()$  returns the rotation angles xangle, yangle, and zangle, from the  $AVW\_Matrix$ , mat.

**SEE ALSO** 

 $AVW\_CopyMatrix(),\ AVW\_CreateMatrix(),\ AVW\_InvertMatrix(),\\ AVW\_MakeMatrixFrom 3Points(),\ AVW\_MakeMatrixFrom Axis()\ AVW\_Mirror Matrix(),$ 

 $AVW\_MultiplyMatrix(),\ AVW\_RotateMatrix(),\ AVW\_SetIdentityMatrix(),$ 

AVW\_ScaleMatrix(), AVW\_TranslateMatrix(), AVW\_Matrix

**NAME** AVW\_MaximumDataValue – returns maximum data type value

SYNOPSIS #include "AVW.h"

double AVW\_MaximumDataValue(type)

int type;

**DESCRIPTION** *AVW\_MaximumDataValue()* returns the maximum data value for the specified data type.

Type specifies the AVW data type. Acceptable values are: AVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_SHORT, AVW\_UNSIGNED\_INT, AVW\_FLOAT, and AVW\_COLOR.

**RETURN VALUES** If successful *AVW\_MaximumDataValue()* returns the maximum value. On failure it

returns 0.0 and sets AVW\_ErrorMessage and AVW\_ErrorNumber to appropriate values.

AVW\_ErrorNumber should be checked after calling this function.

**ERRORS** *AVW\_MaximumDataValue* will fail if:

**NOTSUP** 

AVW\_COMPLEX data type not supported.

SEE ALSO | AVW\_MinimumDataValue(), AVW\_QuickImageMaxMin(), AVW\_QuickVolumeMaxMin()

AVW\_MedialAxisTransformVolume - creates a medial axis or surface

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_MedialAxisTransformVolume(in\_volume, axis\_flag, out\_volume) AVW\_Volume \*in\_volume;

int axis\_flag;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

*AVW\_MedialAxisTransformVolume()* performs the medial axis transformations to produce a medial surface or axis.

In\_volume and out\_volume must be of the data type AVW\_UNSIGNED\_CHAR. In\_volume does not have to be a binary valued but all nonzero pixels are treated as ones. Axis\_flag is set to AVW\_MEDIAL\_AXIS (1) or AVW\_MEDIAL\_SURFACE (0) to specify what type of output will be generated and returned.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_MedialAxisTransformVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_MedialAxisTransformVolume() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

**SEE ALSO** 

AVW\_ThinVolume(), AVW\_Volume

NAME | AVW\_MedianFilterImage – performs a 2D median filter

SYNOPSIS #include "AVW\_Filter.h"

AVW\_Image \*AVW\_MedianFilterImage(in\_image, xdim, ydim, out\_image)

AVW\_Image \*in\_image;

int xdim, ydim;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_MedianFilterImage() performs a median filter transformation on in\_image. Xdim and ydim, specify the x and y sizes respectively of the filter. Filter sizes should be odd.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_MedianFilterImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_MedianFilterVolume(), AVW\_AHEImage(), AVW\_LowpassFilterImage(), AVW\_OrthoGradFilterImage(), AVW\_RankFilterImage(), AVW\_SigmaFilterImage(), AVW\_SobelFilterEnhanceImage(), AVW\_SobelFilterImage(), AVW\_UnsharpFilterEnhanceImage(), AVW\_UnsharpFilterImage(), AVW\_Image

AVW\_MedianFilterVolume – performs a 3D median filter

**SYNOPSIS** 

#include "AVW Filter.h"

 $AVW\_Volume *AVW\_MedianFilterVolume (in\_volume, xdim, ydim, zdim, out\_volume)$ 

 $AVW\_Volume * in\_volume;$ 

int xdim, ydim, zdim;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_MedianFilterVolume() performs a median filter transformation on *in\_volume*. Xdim, ydim, and zdim specify the x, y, and z sizes respectively of the filter. Filter sizes should be odd.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_MedianFilterVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_MedianFilterImage(), AVW\_AHEVolume(), AVW\_LowpassFilterVolume(), AVW\_OrthoGradFilterVolume(), AVW\_RankFilterVolume(), AVW\_SigmaFilterVolume(),

AVW\_SobelFilterEnhanceVolume(), AVW\_SobelFilterVolume(),

AVW\_UnsharpFilterEnhanceVolume(), AVW\_UnsharpFilterVolume(),

AVW\_VSFMeanFilterVolume(), AVW\_Volume

AVW\_MergeInfo - merges two AVW information strings

**SYNOPSIS** 

#include "AVW.h"

char \*AVW\_MergeInfo(info1, info2)

char \*info1;

char \*info2;

# **DESCRIPTION**

*AVW\_MergeInfo()* merges the *AVW* information strings, *info1* and *info2*. If common information occurs in both strings, *info1* takes precedence. If either string is NULL, the returned string is a copy of the non-NULL string.

*Info2* is freed at completion to make this function compatible with many of the *AVW* functions which reuse memory. This suggests that the same character string should be used as the return string and *info2*.

Example:

img->Info = AVW\_MergeInfo(vol->Info, img->Info);

#### **RETURN VALUES**

If successful *AVW\_MergeInfo()* returns a char \*. This char \* will be managed automatically if part of an *AVW* structure, but must be freed by the user if used in another way. On failure, *NULL* is returned.

# **SEE ALSO**

 $AVW\_GetNumericInfo(),\ AVW\_GetStringInfo(),\ AVW\_ListInfo(),\ AVW\_PutHistoryInfo(),\ AVW\_Intge,\ AVW\_Volume,\ AVW\_ImageFile$ 

AVW\_MergeRendered - merges two rendered images

**SYNOPSIS** 

#include "AVW.h"

AVW\_RenderedImage \*AVW\_MergeRendered(in1\_rendered, factor1, in2\_rendered, factor2, merge\_type, out\_rendered)

AVW\_RenderedImage \*in1\_rendered;

double factor1;

AVW\_RenderedImage \*in2\_rendered;

double factor2;

int merge\_type;

AVW\_RenderedImage \*out\_rendered;

# **DESCRIPTION**

AVW\_MergeRendered() combines two rendered images to produce and return a third. Factor1 and factor2, specify and opacity value between 1.0 (Opaque) and 0.0 (Transparent). Factor1 is used when a voxel from in1\_rendered is in front, Factor2 is used when in rendered2 is in front.

Merge\_type should be set to one of the following: AVW\_MERGE\_DEPTH, AVW\_MERGE\_AVERAGE, or AVW\_MERGE\_BRIGHTEST. AVW\_MERGE\_DEPTH causes the rendererings to be merged according to the depth information stored in the PBuffer member of the AVW\_RenderedImage's. AVW\_MERGE\_AVERAGE is used to Add and Average the renderings. AVW\_MERGE\_BRIGHTEST causes the birghtest pixel in the either rendering to be used.

Out\_rendered is provided as a method of reusing an existing AVW\_RenderedImage. Reuse is possible only if the size and data type of the provided out\_rendered meet the requirements of the function. In this case the pointer to out\_rendered is returned by the function. If not reuseable out\_rendered will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful *AVW\_MergeRendered()* returns an *AVW\_RenderedImage*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_MergeRendered() will fail if:

BADMAL

Malloc Failed. Unable to allocate sufficient memory.

#### **SEE ALSO**

 $AVW\_RenderVolume(),\ AVW\_RenderOblique(),\ AVW\_CubeSections(),\\ AVW\_IntersectingSections(),\ AVW\_DestroyRenderedImage()\ AVW\_RenderedImage()$ 

**NAME** AVW\_MinimumDataValue – returns minimum data type value

SYNOPSIS #include "AVW.h"

double AVW\_MinimumDataValue(type)

int type;

**DESCRIPTION** | *AVW\_MinimumDataValue()* returns the minimum data value for the specified data type.

Type specifies the AVW data type. Acceptable values are: AVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_SHORT, AVW\_UNSIGNED\_INT, AVW\_FLOAT, and AVW\_COLOR

**RETURN VALUES** If successful *AVW\_MinimumDataValue()* returns the minimum value. On failure it returns

0.0 and sets AVW\_ErrorMessage and AVW\_ErrorNumber to appropriate values.

AVW\_ErrorNumber should be checked after calling this function.

**ERRORS** | *AVW\_MinimumDataValue* will fail if:

**NOTSUP** 

AVW\_COMPLEX data type not supported.

SEE ALSO | AVW\_MaximumDataValue(), AVW\_QuickImageMaxMin(), AVW\_QuickVolumeMaxMin()

AVW\_MirrorMatrix - mirrors a transformation matrix

**SYNOPSIS** 

#include "AVW.h"

AVW\_Matrix \*AVW\_MirrorMatrix(in\_matrix, axis, out\_matrix)

AVW\_Matrix \*in\_matrix;

int axis;

AVW\_Matrix \*output\_matrix;

**DESCRIPTION** 

*AVW\_MirrorMatrix()* is used to mirror the *AVW\_Matrix, mat,* on one or more axes. *Axis* should be set a sum of *AVW\_XAXIS, AVW\_YAXIS,* and *AVW\_ZAXIS* to indicate which axis the matrix is mirrored. The order of mirroring is X, then Y, then Z.

Out\_matrix is provided as a method of reusing an existing AVW\_Matrix. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_MirrorMatrix()* returns an *AVW\_Matrix*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_CopyMatrix(), AVW\_CreateMatrix(), AVW\_InvertMatrix(), AVW\_MakeMatrixFrom3Points(), AVW\_MakeMatrixFromAxis() AVW\_MultiplyMatrix(), AVW\_RotateMatrix(), AVW\_SetIdentityMatrix(), AVW\_ScaleMatrix(), AVW\_TranslateMatrix(), AVW\_Matrix

AVW\_MirrorRendered - mirrors a rendered image

**SYNOPSIS** 

#include "AVW Render.h"

AVW\_Image \*AVW\_MirrorRendered(rendered, direction, position, out\_image)

AVW\_RenderedImage \*rendered;

int direction, position; AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_MirrorRendered() mirrors a rendered image in a specified direction and at a specified position.

*Direction* must be one of the following:

AVW\_MIRROR\_RIGHT\_TO\_LEFT

AVW\_MIRROR\_LEFT\_TO\_RIGHT

 $AVW\_MIRROR\_BOTTOM\_TO\_TOP$ 

AVW\_MIRROR\_TOP\_TO\_BOTTOM

*Position* is any location from 0 to (rendered->Image->Width - 1).

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_MirrorRendered()* returns an *AVW\_Image*. On failure, it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_MirrorRendered()* will fail if one or more of the following is true:

BADMAL

Couldn't allocate enough memory.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_RenderVolume(), AVW\_RenderedImage, AVW\_Image

AVW\_MorphCloseImage - morphologically closes an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_MorphCloseImage(in\_image, element, out\_image)

AVW\_Image \*in\_image;

AVW\_Image \*element;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

*AVW\_MorphCloseImage()* performs binary morphological closing on *in\_image* using *element* as the structuring element.

In\_image does not have to be a binary valued image but all nonzero pixels are treated as ones. In\_image, out\_image, and element must be of the data type AVW\_UNSIGNED\_CHAR. This function will allocate temporary storage space for results if in\_image and out\_image are the same.

The closing operation is defined as a dilation followed by an erosion with the same structuring element.

AVW\_CreateStructuringImage() or the combination of: AVW\_CreateImage(), AVW\_SetImage(), and AVW\_PutPixel() may be used to create a structuring element.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful  $AVW\_MorphCloseImage()$  returns a processed  $AVW\_Image$ . On failure it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_MorphCloseImage() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

**ILLDT** 

Data type is not defined or supported.

**ILLIMG** 

An illegal image was passed to the function.

### **SEE ALSO**

AVW\_ConditionalDilateImage(), AVW\_CreateImage(), AVW\_CreateStructuringImage(), AVW\_CreateStructuringImage(), AVW\_DilateImage(), AVW\_ErodeImage(), AVW\_MorphCloseVolume(), AVW\_MorphOpenImage(), AVW\_MorphMaxImage(), AVW\_NorphMinImage(), AVW\_PutPixel(), AVW\_PutVoxel(), AVW\_SetImage(), AVW\_SetVolume(), AVW\_Image

AVW\_MorphCloseVolume - morphologically closes a volume

## **SYNOPSIS**

#include "AVW.h"

AVW\_Volume \*AVW\_MorphCloseVolume(in\_volume, element, out\_volume)

AVW\_Volume \*in\_volume;

AVW\_Volume \*element;

AVW Volume \*out volume:

# **DESCRIPTION**

*AVW\_MorphCloseVolume()* performs binary morphological closing on *in\_volume* using *element* as the structuring element.

In\_volume does not have to be a binary valued volume but all nonzero voxels are treated as ones. In\_volume, out\_volume, and element must be of the data type

*AVW\_UNSIGNED\_CHAR.* This function will allocate temporary storage space for results if *in\_volume* and *out\_volume* are the same.

The closing operation is defined as a dilation followed by an erosion with the same structuring element.

AVW\_CreateSTructuringVolume() or a combination of: AVW\_CreateVolume(), AVW\_SetVolume(), and AVW\_PutVoxel() may be used to create a structuring element.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_MorphCloseVolume()* returns a processed *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_MorphCloseVolume() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

ILLDT

Data type is not defined or supported.

**ILLVOL** 

An illegal volume was passed to the function.

## **SEE ALSO**

AVW\_ConditionalDilateVolume(), AVW\_CreateStructuringVolume(), AVW\_CreateVolume(), AVW\_DilateVolume(), AVW\_ErodeVolume(), AVW\_MorphCloseImage(), AVW\_MorphOpenVolume(), AVW\_MorphMaxVolume(), AVW\_MorphMinVolume(), AVW\_PutVoxel(), AVW\_SetVolume(), AVW\_Volume

AVW\_MorphMaxImage – performs a 2D local maximum operation

## **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_MorphMaxImage(in\_image, element, out\_image)

AVW\_Image \*in\_image;

AVW\_Image \*element;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_MorphMaxImage() performs a local maximum operation on in\_image using element as the structuring element.

*Element* must be of data type *AVW\_UNSIGNED\_CHAR*.

The local maximum operation is the grey scale equivalent of a binary dilation. This function will allocate temporary storage space for results if *in\_image* and *out\_image* are the same.

In simplest terms the local maximum process takes place by translating the structuring element so that its centerpoint lies on every point of the data. The maximum value of the pixels in the data corresponding to the nonzero pixels in the structuring element is set at this point in the result data.

AVW\_CreateStructuringImage() or a combination of: AVW\_CreateImage(), AVW\_SetImage(), and AVW\_PutPixel() may be used to create a structuring element.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_MorphMaxImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_MorphMaxImage() will fail if:

RADMAI.

Malloc failed. Unable to allocate memory for results.

**ILLDT** 

Data type is not defined or supported.

**ILLIMG** 

An illegal image was passed to the function.

#### **SEE ALSO**

AVW\_ConditionalDilateImage(), AVW\_CreateImage(), AVW\_CreateStructuringImage(), AVW\_DilateImage(), AVW\_ErodeImage(), AVW\_MorphCloseImage(), AVW\_MorphMaxVolume(), AVW\_MorphMinImage(), AVW\_MorphOpenImage(), AVW\_PutPixel(), AVW\_SetImage(), AVW\_Image

AVW\_MorphMaxVolume - performs a 3D local maximum operation

## **SYNOPSIS**

#include "AVW.h"

AVW\_Volume \*AVW\_MorphMaxVolume(in\_volume, element, out\_volume)

AVW\_Volume \*in\_volume;

AVW Volume \*element:

AVW\_Volume \*out\_volume;

#### **DESCRIPTION**

AVW\_MorphMaxVolume() performs a local maximum operation on in\_volume using element as the structuring element. Element must be of data type AVW\_UNSIGNED\_CHAR.

The local maximum operation is the grey scale equivalent of a binary dilation. This function will allocate temporary storage space for results if *in\_volume* and *out\_volume* are the same.

In simplest terms the local maximum process takes place by translating the structuring element so that its centerpoint lies on every point of the data. The maximum value of the voxels in the data corresponding to the nonzero voxels in the structuring element is set at this point in the result data.

AVW\_CreateStructuringVolume() or a combination of: AVW\_CreateVolume(), AVW\_SetVolume(), and AVW\_PutVoxel() may be used to create a structuring element.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_MorphMaxVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_MorphMaxVolume() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

**ILLDT** 

Data type is not defined or supported.

**ILLVOL** 

An illegal volume was passed to the function.

#### **SEE ALSO**

 $AVW\_Conditional Dilate Volume(),\ AVW\_Create Volume(),\ AVW\_Dilate Volume(),\ AVW\_Erode Volume(),\ AVW\_MorphClose Volume(),\ AVW\_MorphMaxImage(),\ AVW\_MorphOpenVolume(),\ AVW\_MorphMinVolume(),\ AVW\_PutVoxel(),\ AVW\_Set Volume(),\ AVW\_Create Structuring Image(),\ AVW\_Image$ 

AVW\_MorphMinImage - performs a 2D local minimum operation

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_MorphMinImage(in\_image, element, out\_image)

AVW\_Image \*in\_image;

AVW\_Image \*element;

AVW Image \*out\_image;

## **DESCRIPTION**

*AVW\_MorphMinImage()* performs a local minimum operation on *in\_image* using *element* as the structuring element.

*Element* must be of data type *AVW\_UNSIGNED\_CHAR*.

The local minimum operation is the grey scale equivalent of a binary erosion.

In simplest terms the local minimum process takes place by translating the structuring element so that its centerpoint lies on every point of the data. The minimum value of the pixels in the data corresponding to the nonzero pixels in the structuring element is set in the result data.

AVW\_CreateStructureingImage or a combination of: AVW\_CreateImage(), AVW\_SetImage(), and AVW\_PutPixel() may be used to create a structuring element.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_MorphMinImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_MorphMinImage() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

II.I.DT

Data type is not defined or supported.

**ILLIMG** 

An illegal image was passed to the function.

#### **SEE ALSO**

AVW\_ConditionalDilateImage(), AVW\_CreateImage(), AVW\_CreateStructuringImage(), AVW\_DilateImage(), AVW\_ErodeImage(), AVW\_MorphCloseImage(), AVW\_MorphMinVolume(), AVW\_MorphMaxImage(), AVW\_MorphOpenImage(), AVW\_PutPixel(), AVW\_SetImage(), AVWImage

AVW\_MorphMinVolume - performs a 3D local minimum operation

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_MorphMinVolume(in\_volume, element, out\_volume)

 $AVW\_Volume * in\_volume;$ 

AVW\_Volume \*element;

AVW\_Volume \*out\_volume;

## **DESCRIPTION**

AVW\_MorphMinVolume() performs a local minimum operation on *in\_volume* using *element* as the structuring element.

*Element* must be of data type *AVW\_UNSIGNED\_CHAR*.

The local minimum operation is the grey scale equivalent of a binary erosion.

In simplest terms the local minimum process takes place by translating the structuring element so that its centerpoint lies on every point of the data. The minimum value of the voxels in the data corresponding to the nonzero voxels in the structuring element is set in the result data.

AVW\_CreateStructuringVolume() or a combination of AVW\_CreateVolume(), AVW\_SetVolume(), and AVW\_PutVoxel() may be used to create a structuring element.

Out\_volume is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_MorphMinVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_MorphMinVolume() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

II.I.DT

Data type is not defined or supported.

**ILLVOL** 

An illegal volume was passed to the function.

## **SEE ALSO**

 $AVW\_MorphMinImage(),\ AVW\_Conditional DilateVolume(), \\ AVW\_CreateStructuringVolume(),\ AVW\_CreateVolume(),\ AVW\_DilateVolume(), \\ AVW\_ErodeVolume(),\ AVW\_MorphCloseVolume(),\ AVW\_MorphOpenVolume(), \\ AVW\_MorphMaxVolume(),\ AVW\_SetVolume(),\ AVW\_PutVoxel(),\ AVW\_Volume(), \\ AVW\_NorphMaxVolume(),\ AVW\_Volume(),\ AVW\_NorphMaxVolume(),\ AVW\_Volume(),\ AVW\_NorphMaxVolume(),\ AVW\_Volume(),\ AVW\_NorphMaxVolume(),\ AVW\_Volume(),\ AVW\_NorphMaxVolume(),\ AVW\_Volume(),\ AVW\_NorphMaxVolume(),\ AVW\_Volume(),\ AVW\_NorphMaxVolume(),\ AVW\_NorphMaxVolume(),\$ 

AVW\_MorphOpenImage - morphologically opens an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_MorphOpenImage(in\_image, element, out\_image)

AVW\_Image \*in\_image;

AVW\_Image \*element;

AVW\_Image \*out\_image;

## **DESCRIPTION**

AVW\_MorphOpenImage() performs binary morphological opening on in\_image using element as the structuring element.

In\_image does not have to be a binary valued but all nonzero pixels are treated as ones. In\_image, out\_image, and element must be of the data type AVW\_UNSIGNED\_CHAR. This function will allocate temporary storage space for results if in\_image and out\_image out\_volume are the same.

The opening is defined as an erosion of the data followed by a dilation of the data with the same structuring element. The result data will only contain ones and zeros.

AVW\_CreateImage() or a combination of AVW\_CreateImage(), AVW\_SetImage(), and AVW\_PutPixel() may be used to create a structuring element.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_MorphOpenImage()* returns an *AVW\_Image.* On failure it returns *NULL* and sets the *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_MorphOpenImage() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

**ILLDT** 

Data type is not defined or supported.

**ILLIMG** 

An illegal image was passed to the function.

## **SEE ALSO**

AVW\_MorphOpenVolume(), AVW\_ConditionalDilateImage(), AVW\_CreateImage(), AVW\_CreateImage(), AVW\_ErodeImage(), AVW\_ErodeImage(), AVW\_MorphCloseImage(), AVW\_MorphMaxImage(), AVW\_MorphMinImage(), AVW\_SetImage(), AVW\_PutPixel(), AVW\_Image

AVW\_MorphOpenVolume - morphologically opens a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_MorphOpenVolume(in\_volume, element, out\_volume)

 $AVW\_Volume * in\_volume;$ 

AVW\_Volume \*element;

AVW\_Volume \*out\_volume;

## **DESCRIPTION**

*AVW\_MorphOpenVolume()* performs binary morphological opening on *in\_volume* using *element* as the structuring element.

In\_volume does not have to be a binary valued but all nonzero pixels are treated as ones. In\_volume, out\_volume, and element must be of the data type AVW\_UNSIGNED\_CHAR. This function will allocate temporary storage space for results if in\_volume and out\_volume are the same.

The opening is defined as an erosion of the data followed by a dilation of the data with the same structuring element. The result data will only contain ones and zeros.

AVW\_CreateStructuringVolume() or a combination of AVW\_CreateVolume(), AVW\_SetVolume(), and AVW\_PutVoxel() may be used to create a structuring element.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_MorphOpenVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets the *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_MorphOpenVolume() will fail if:

**BADMAL** 

Malloc failed. Unable to allocate memory for results.

**ILLDT** 

Data type is not defined or supported.

**ILLVOL** 

An illegal volume was passed to the function.

## **SEE ALSO**

AVW\_MorphOpenImage(), AVW\_ConditionalDilateVolume(), AVW\_CreateStructuringVolume(), AVW\_CreateVolume(), AVW\_DilateVolume(), AVW\_ErodeVolume(), AVW\_MorphCloseVolume(), AVW\_MorphMaxVolume(), AVW\_NorphMinVolume(), AVW\_SetVolume(), AVW\_PutVoxel(), AVW\_Volume()

**NAME** AVW\_MultiplyMatrix – multiplies two transformation matrices

SYNOPSIS #include "AVW.h"

AVW\_Matrix \*AVW\_MultiplyMatrix(mat\_in1, mat\_in2, mat\_out)

AVW\_Matrix \*mat\_in1, \*mat\_in2, \*mat\_out;

**DESCRIPTION** AVW\_MultiplyMatrix() multiplies the AVW\_Matrix, mat\_in1, times the AVW\_Matrix,

mat\_in2, and return the result.

Out\_matrix is provided as a method of reusing an existing AVW\_Matrix. (See Memory

Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_MultiplyMatrix()* returns an *AVW\_Matrix*. On failure it returns *NULL* 

and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause

of the failure.

SEE ALSO | AVW\_Matrix, AVW\_CopyMatrix(), AVW\_CreateMatrix(), AVW\_InvertMatrix(),

AVW\_MirrorMatrix(), AVW\_RotateMatrix(), AVW\_SetIdentityMatrix(),

AVW\_ScaleMatrix(), AVW\_TranslateMatrix(), AVW\_MakeMatrixFrom3Points(),

 $AVW\_Make Matrix From Axis ()$ 

AVW\_NearestNeighborDeconv - performs nearest-neighbor deconvolution on an image

# **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_NearestNeighborDeconv(in\_image, slice\_above, slice\_below, in\_focus\_filt, out\_focus\_filt, cons, alpha, out\_image)

AVW\_Image \*in\_image, \*slice\_above, \*slice\_below;

AVW\_Image \*in\_focus\_filt, \*out\_focus\_filt;

double cons, alpha;

AVW\_Image \*out\_image;

## **DESCRIPTION**

 $AVW\_NearestNeighborDeconv()$  performs nearest neighbor deconvolution for deblurring optical section data in one focal plane by using data from the slices above and below (see reference below). The slice in the focal plane is  $in\_image$  and the image dimensions and are expected to be powers of 2. The slices above and below respectively are  $slice\_above$  and  $slice\_below$  and must be of the same dimensions. The in-focus transfer function  $in\_focus\_filt$  and the one slice out-of-focus transfer function  $out\_focus\_filt$  must both be of data type  $AVW\_FLOAT$  or  $AVW\_COMPLEX$  and of dimensions xnum / 2 + 1, ynum, where xnum and ynum are the dimensions of the image. Cons is a constant between 0 and 1 which weights the out-of-focus contributions and is referred to as c in the reference. Alpha must be a positive float number and will be ignored and the value .0001 used in its place if it is less than or equal to zero.

The function allocates new memory for the returned *out\_image* if the supplied *out\_image* is incompatible in size or datatype.

More detailed information about nearest neighbor deconvolution may be found in the reference:

Agard, David A., *Fluorescence Microscopy in Three Dimensions* 1989, in Methods in Cell Biology, Vol. 30, Chap. 13, Academic Press.

## **RETURN VALUES**

If successful *AVW\_NearestNeighborDeconv()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

*AVW\_NearestNeighborDeconv()* will fail if the following is true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for return volume or image.

**ILLPAR** 

Illegal Parameter. An invalid value was given for an input parameter.

**ILLIMG** 

Illegal Image. Input image was not a power of 2 in each dimension.

**CFLSZ** 

Conflicting Size. The slices above or below did not match the input image.

**BDSPCT** 

Bad Input Spectrum. An invalid spectrum was entered for a transfer function.

**SEE ALSO** 

 $AVW\_CreateStoksethMTF(),\ AVW\_DeconvDivideImage(),\ AVW\_DeconvWienerImage(),\ AVW\_IterDeconvImage(),\ AVW\_Image$ 

**NAME** AVW\_NearestNeighborPixel – finds value of nearest pixel

SYNOPSIS #include "AVW.h"

 $double\ AVW\_NearestNeighbor Pixel (image,\ point)$ 

AVW\_Image \*image; AVW\_FPoint2 \*point;

**DESCRIPTION** | AVW\_NearestNeighborPixel() returns the value of the pixel nearest the floating point loca-

tion *point* in the *image*. 0 is returned if the location is outside the *image*.

**SEE ALSO** | AVW\_NearestNeighborVoxel(), AVW\_GetPixel(), AVW\_InterpolatedPixel(),

 $AVW\_CubicSplineInterpolatedPixel(), AVW\_SincInterpolatedPixel(), AVW\_FPoint2,$ 

AVW\_Image

**NAME** AVW\_NearestNeighborVoxel – finds value of nearest voxel

**SYNOPSIS** #include "AVW.h"

 $double\ AVW\_NearestNeighborVoxel(volume, point)$ 

AVW\_Volume \*volume; AVW\_FPoint3 \*point;

**DESCRIPTION** AVW\_NearestNeighborVoxel() returns the value of the voxel nearest the floating point loca-

**AVW 3.0** 

tion *point* in the *volume*. 0 is returned if the location is outside the *volume*.

**SEE ALSO** *AVW\_NearestNeighborPixel(), AVW\_GetVoxel(), AVW\_InterpolatedVoxel(),* 

 $AVW\_CubicSplineInterpolatedVoxel(), AVW\_SincInterpolatedVoxel(), AVW\_FPoint3,$ 

AVW\_Volume

AVW\_NonMaxImage – suppresses pixels which are not a local maximum

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_NonMaxImage(in\_image, element, out\_image)

AVW\_Image \*in\_image;

AVW\_Image \*element;

AVW\_Image \*out\_image;

## **DESCRIPTION**

*AVW\_NonMaxImage()* sets all the pixels in *in\_image* which are not a maximum in the local neighborhood defined by the set pixels in *element* to zero.

*Element* is translated so that its centerpoint lies on every point of the image. At each point in the image, if the pixel is not the maximum of all the pixels that correspond to the ones in the translated structuring element it is set to zero. Otherwise it is left unchanged.

*Element* must be of the data type *AVW\_UNSIGNED\_CHAR*. This function will allocate temporary storage space for results if *in\_image* and *out\_image* are the same.

AVW\_CreateStructuringImage() or a combination of AVW\_CreateImage(), AVW\_SetImage(), and AVW\_PutPixel() may be used to create a structuring element

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful *AVW\_NonMaxImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_NonMaxImage() will fail if:

**ILLDT** 

Data type is not defined or supported or structuring element is not AVW UNSIGNED CHAR.

**SEE ALSO** 

 $AVW\_NonMaxVolume(),\ AVW\_CreateStructuringImage(),\ AVW\_CreateImage(),\ AVW\_MorphMaxImage(),\ AVW\_MorphMinImage(),\ AVW\_SetImage(),\ AVW\_PutPixel(),\ AVW\_Image$ 

AVW\_NonMaxVolume – suppresses voxels which are not a local maximum

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_NonMaxVolume(in\_volume, element, out\_volume)

 $AVW\_Volume * in\_volume;$ 

AVW\_Volume \*element;

AVW\_Volume \*out\_volume;

## **DESCRIPTION**

*AVW\_NonMaxVolume()* sets all the voxels in *in\_volume* which are not a maximum in the local neighborhood defined by the set voxels in *element* to zero.

*Element* is translated so that its centerpoint lies on every point of the volume. At each point in the volume, if the voxel is not the maximum of all the voxels that correspond to the ones in the translated structuring element it is set to zero. Otherwise it is left unchanged.

*Element* must be of the data type *AVW\_UNSIGNED\_CHAR*. This function will allocate temporary storage space for results if *in\_volume* and *out\_volume* are the same.

AVW\_CreateStructuringVolume() or a combination of AVW\_CreateVolume(), AVW\_SetVolume(), and AVW\_PutVoxel() may be used to create a structuring element

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful AVW\_NonMaxVolume() returns an AVW\_Volume. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_NonMaxVolume() will fail if:

**ILLDT** 

Data type is not defined or supported or structuring element is not AVW\_UNSIGNED\_CHAR.

**SEE ALSO** 

AVW\_NonMaxImage(), AVW\_CreateStructuringVolume(), AVW\_CreateVolume(), AVW\_MorphMaxVolume(), AVW\_MorphMinVolume(), AVW\_SetVolume(), AVW PutVoxel(), AVW Volume

AVW\_NormalizeHistogram - normalizes a histogram

**SYNOPSIS** 

#include "AVW\_Histogram.h"

AVW\_Histogram \*AVW\_NormalizeHistogram(histo, norm\_histo)

AVW\_Histogram \*histo, \*norm\_histo;

**DESCRIPTION** 

*AVW\_NormalizeHistogram()* normalizes the *AVW\_Histogram*, *histo*, and places the results in *norm\_histo*. The number of pixels in each bin of the histogram is divided by the total number of all pixels in the histogram.

Norm\_histo is provided as a method of reusing an existing AVW\_Histogram. Reuse is possible only if the size of the provided norm\_histo match the size of histo. In this case the pointer to norm\_histo is returned by the function. If not reusable norm\_histo will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_NormalizeHistogram()* returns an *AVW\_Histogram* containing the results of the function. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_NormalizeHistogram() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**ILLHIS** 

Histogram provided was not valid.

**SEE ALSO** 

AVW\_ClearHistogram(), AVW\_CreateHistogram(), AVW\_DestroyHistogram(),

AVW\_FlattenImageHistogram(), AVW\_FlattenVolumeHistogram(),

AVW\_GetImageHistogram(), AVW\_GetVolumeHistogram(), AVW\_MatchImageHistogram(),

AVW\_MatchVolumeHistogram(), AVW\_PreserveImageHistogram(),

AVW\_PreserveVolumeHistogram(), AVW\_VerifyHistogram(), AVW\_Histogram

AVW\_ObjectScaleImage - create colored image using object map

**SYNOPSIS** 

#include "AVW.h"

#include "AVW\_ObjectMap.h"

AVW\_Image \*AVW\_ObjectScaleImage(in\_image, in\_max, in\_min,

obj\_image, object\_map, enhanced flag, out image)

AVW\_Image \*in\_image;

double in\_max, in\_min;

AVW\_Image \*obj\_image;

AVW\_ObjectMap \*object\_map;

int enhance\_flag;

AVW\_Image \*out\_image;

## **DESCRIPTION**

AVW\_ObjectScaleImage() takes an AVW\_Image, in\_image, and maximum and minimum intensity values, in\_max and in\_min, along with an image derived from an object map, the object\_map itself, and produces a color version of the original image using a variety of enhancements controlled by enhance\_flag.

In\_image is generally an image which AVW\_GetOrthogonal() or AVW\_GetOblique(). Obj\_image must be the same size as in\_image, and is usually extracted from the object\_map->Volume using the same function and parameters as were used to extract in\_image.

*Enhance\_flag* specifies the method used to combine the input images to produce the desired colored image. Methods available are:

*AVW\_OBJECT\_COLOR* – The *in\_max* and *in\_min* parameters are used to "scale" the input values into the shades of colors available for each object.

*AVW\_ENHANCED\_OBJECT\_COLOR* – The max and min values for each object within the image are determined, and then each object is scaled to it's own max/min before being divided into shades of color.

*AVW\_OBJECT\_COLOR\_ONLY* – The intensity values in the *in\_image* is ignored and the color is determined using only the object information contained in *obj\_image*.

*AVW\_OBJECT\_COLOR\_EDGES* – The edges of objects are enhanced with their color value.

*AVW\_OBJECT\_EDGES\_ONLY* – The edges of objects are returned in their color value.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_ObjectScaleImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

SEE ALSO | AVW\_IntensityScaleImage(), AVW\_DestroyImage(), AVW\_Image

AVW\_ObjectSeparator - separates connected objects

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_ObjectSeparator(in\_volume, seeds, omap, max, min)

AVW\_Volume \*in\_volume;

AVW\_PointList3 \*seeds;

AVW\_ObjectMap \*omap;

double max, min;

## **DESCRIPTION**

AVW\_ObjectSeparator() is used to separate connected objects. Max and Min, along with the DisplayFlags for each object within omap, is used to segment the objects. Seeds determine which objects should not be connected, if they are connected, layers are continually peeled away and the connection rechecked until the objects have been separated. Once separated, the layers are regrown until initial values are again part of the separated objects. Each unique object is returned as a value within the returned volume. The returned volume can be used as input to AVW\_PutMultipleObjects along with omap to redfine objects within an object map.

## **RETURN VALUES**

If successful *AVW\_ObjectSeparator()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets the *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ObjectSeparator() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_PutMultipleObjects(), AVW\_PointList3, AVW\_ObjectMap, AVW\_Volume

AVW\_OpenImageFile - opens a supported image file

**SYNOPSIS** 

#include "AVW\_ImageFile.h"

AVW\_ImageFile \*AVW\_OpenImageFile(filename, modes)

**AVW 3.0** 

char \*filename;
char \*modes;

# **DESCRIPTION**

AVW\_OpenImageFile() opens the named image file, determines the data format of the file, assigns AVW image IO functions related to this data format, calls the open() function appropriate for this data format, and associates the returned pointer to an AVW\_ImageFile structure for that file. The pointer that is returned is then used as a handle for all subsequent image IO operations with this file. The modes parameter determines with what read modes the file is opened. Acceptable values are "r" for read only and "r+" for read and write update.

The AVW\_OpenImageFile() function may not be used for the creation of new image files, only for opening existing files for reading or write modification. The AVW\_CreateImageFile() function is used for the creation of new files.

## **RETURN VALUES**

If successful AVW\_OpenImageFile() returns an AVW\_ImageFile. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of failure. The returned AVW\_ImageFile contains generic information about the size and type of images in the file without particular regard to the data format of the file. Access to data format specific attributes of the file are accessible through these elements in AVW\_ImageFile:

*NativeData* is a (void \*) pointer to the raw data for this file. This pointer allows the format specific routines in the AVW\_ImageFile library to access the raw data.

*DataFormat* is an integer index into the currently supported list of *AVW* supported formats.

#### **ERRORS**

*AVW\_OpenImageFile()* will fail if one or more of the following are true:

**BDFRMT** 

Unknown data format.

**BDOPEN** 

Bad Open. Error opening the file.

**NOFILE** 

File Doesn't Exist

**NOPERMISSION** 

File Permission Error

 $AVW\_CloseImageFile(),\ AVW\_CreateImageFile(),\ AVW\_DisableImageFileFormat(),\ AVW\_EnableIMageFileFormat(),\ AVW\_ExtendImageFile(),\ AVW\_FormatSupports(),\ AVW\_ListFormats(),\ AVW\_ReadImageFile(),\ AVW\_ReadVolume(),\ AVW\_SeekImageFile(),\ AVW\_WriteImageFile(),\ AVW\_WriteImageFile(),\ AVW\_ImageFile(),\ AVW\_ImageFile($ 

AVW\_OpenImageFileList - opens a list of supported image files

**SYNOPSIS** 

#include "AVW\_ImageFile.h"

AVW\_ImageFile \*AVW\_OpenImageFileList(filelist, modes)

AVW\_List \*filelist;

char \*modes;

## **DESCRIPTION**

AVW\_OpenImageFileFile() attempts to open all the files named in *filelist*. If all the files can be successfully opened as image files and have the same width, height, and datatype the filelist functions as a virtual volume file.

The pointer that is returned is then used as a handle for all subsequent image IO operations with this file. The *modes* parameter determines with what read modes the file is opened. Acceptable values are "r" for read only and "r+" for read and write update.

The AVW\_OpenImageFileFiles() function may not be used for the creation of new image files, only for opening existing files for reading or write modification. The AVW\_CreateImageFile() function is used for the creation of new files.

## **RETURN VALUES**

If successful AVW\_OpenImageFile() returns an AVW\_ImageFile. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of failure. The returned AVW\_ImageFile contains generic information about the size and type of images in the file without particular regard to the data format of the file. Access to data format specific attributes of the file are accessible through these elements in AVW\_ImageFile:

*NativeData* is a (void \*) pointer to the raw data for this file. This pointer allows the format specific routines in the AVW\_ImageFile library to access the raw data.

*DataFormat* is an integer index into the currently supported list of *AVW* supported formats.

#### **ERRORS**

*AVW\_OpenImageFile()* will fail if one or more of the following are true:

**BDFRMT** 

Unknown data format.

**BDOPEN** 

Bad Open. Error opening the file.

**NOFILE** 

File Doesn't Exist

**NOPERMISSION** 

File Permission Error

**SEE ALSO** 

 $AVW\_CloseImageFile(),\ AVW\_CreateImageFile(),\ AVW\_DisableImageFileFormat(),\\ AVW\_EnableIMageFileFormat(),\ AVW\_ExtendImageFile(),\ AVW\_FormatSupports(),\\ AVW\_ListFormats(),\ AVW\_OpenImageFileList(),\ AVW\_ReadImageFile(),\\ AVW\_ReadVolume(),\ AVW\_SeekImageFile(),\ AVW\_WriteImageFile(),\ AVW\_WriteVolume(),\\ AVW\_ImageFile(),\ AVW\_Image$ 

NAME | AVW Or

AVW\_OrthoGradFilterImage - performs a 2D Orthogonal Gradient filter

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Image \*AVW\_OrthoGradFilterImage(in\_image, out\_image)

AVW\_Image \*in\_image; AVW\_Image \*out\_image;

**DESCRIPTION** 

*AVW\_OrthoGradFilterImage()* replaces each pixel in *in\_image* with the maximum absolute difference between the pixel's orthogonal neighbors.

 $O(x,y) = \max(abs(P(x,y-1)-P(x,y+1)), abs(P(x-1,y)-P(x+1,y)))$ 

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_OrthoGradFilterImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets the *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_OrthoGradFilterImage will fail if the following is true:

**ILLDT** 

Illegal Data Type

**SEE ALSO** 

AVW\_OrthoGradFilterVolume(), AVW\_AHEImage(), AVW\_LowpassFilterImage(), AVW\_RankFilterImage(), AVW\_SigmaFilterImage(), AVW\_SobelFilterImage(),

AVW\_SobelFilterEnhanceImage(), AVW\_UnsharpFilterImage(),

AVW\_UnsharpFilterImageEnhance(), AVW\_Image

AVW\_OrthoGradFilterVolume – performs a 3D Orthogonal Gradient filter

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Volume \*AVW\_OrthoGradFilterVolume(in\_volume, out\_volume)

AVW\_Volume \*in\_volume;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

*AVW\_OrthoGradFilterVolume()* replaces each voxel in *in\_volume* with the maximum absolute difference between the voxel's orthogonal neighbors.

O(x,y,z) = max(abs(P(x,y,z-1)-P(x,y,z+1)), abs(P(x,y-1,z)-P(x,y+1,z)), abs(P(x-1,y,z)-P(x+1,y,z)))

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_OrthoGradFilterVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_OrthoGradFilterImage* will fail if the following is true:

**ILLDT** 

Illegal Data Type

**SEE ALSO** 

AVW\_OrthoGradFilterImage(), AVW\_AHEVolume(), AVW\_LowpassFilterVolume(), AVW\_RankFilterVolume(), AVW\_SigmaFilterVolume(), AVW\_SobelFilterVolume(), AVW\_SobelFilterEnhanceVolume(), AVW\_UnsharpFilterVolume(), AVW\_UnsharpFilterVolume(), AVW\_Volume(), AVW\_Volu

AVW\_PCAImage – transforms a group of images with principal component analysis.

**SYNOPSIS** 

#include "AVW.h"

int AVW\_PCAImages(images, numImages, scaleFlag)

AVW\_Image \*\*images;

int numImages; int scaleFlag

**DESCRIPTION** 

AVW\_PCAImages() transforms a list of spatially correlated images using principal component analysis. Principal component analysis is a preprocessing step used to reduce the number of bands required for multispectral classification. Images are transformed and resorted in order of information content.

images is an array of pointers AVW\_Images.

numImages is the number of images being passed.

*scaleFlag* may have two acceptable values; AVW\_TRUE or AVW\_FALSE. When *scaleFlag* is true the dynamic range of the output images are rescaled to the range of the first image, otherwise not.

**RETURN VALUES** 

If successful *AVW\_PCAImages()* returns an *AVW\_SUCCESS*. On failure *AVW\_FAIL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_PCAImages() will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

**SEE ALSO** 

AVW\_PCAVolumes()

AVW\_PCAVolume – transforms a group of volumes using principal component analysis.

**SYNOPSIS** 

#include "AVW.h"

int AVW\_PCAVolumes(volumes, numVolumes, scaleFlag)

AVW\_Volume \*\*volumes;

int numVolumes; int scaleFlag

**DESCRIPTION** 

*AVW\_PCAVolumes()* transforms a list of spatially correlated volumes using principal component analysis. Principal component analysis is a preprocessing step used to reduce the number of bands required for multispectral classification. Volumes are transformed and resorted in order of information content.

volumes is an array of pointers AVW\_Volumes.

numVolumes is the number of images being passed.

*scaleFlag* may have two acceptable values; AVW\_TRUE or AVW\_FALSE. When *scaleFlag* is true the ynamic range of the output volumes are rescaled to the range of the first volume, otherwise not.

**RETURN VALUES** 

If successful *AVW\_PCAVolumes()* returns an *AVW\_SUCCESS*. On failure *AVW\_FAIL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_PCAVolumes()* will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

**SEE ALSO** 

AVW\_PCAImages()

AVW\_PadImage - pads an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_PadImage(in\_image, out\_width, out\_height, location,

pad\_type, out\_image)

AVW\_Image \*in\_image;

int out\_width, out\_height;

AVW\_Point2 \*location;

int pad\_type;

AVW\_Image \*out\_image;

# **DESCRIPTION**

AVW\_PadImage() pads an image, in\_image, with zeros, the values of the edge pixels, or the maximium or minimum value for the datatype. In\_image, is placed in a larger out\_image at the position specified by location.

Out\_width and out\_height specify the width and height of the returned image. Location specifies the position within the returned image where in\_image will be placed. If NULL, the location is calculated as the middle of the out\_width and out\_height. Pad\_type specifies whether the padded region in the returned image is set to zero, AVW\_PAD\_ZERO, the values of the border pixels in the in\_image, AVW\_PAD\_VALUE. the maximum value for the datatype, AVW\_PAD\_MAX, or the minimum value for the datatype.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_PadImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_PadImage() will fail if the following is true:

**ILLDT** 

Illegal data type.

**SEE ALSO** 

AVW\_PadVolume(), AVW\_PutSubImage(), AVW\_Image, AVW\_Point2

AVW\_PadVolume - pads a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_PadVolume(in\_volume, out\_width, out\_height, out\_depth, location, pad\_type, out\_volume)

AVW\_Volume \*in\_volume;

int out\_width, out\_height, out\_depth;

AVW\_Point3 \*location;

int pad\_type;

AVW\_Volume \*out\_volume;

# **DESCRIPTION**

AVW\_PadVolume() pads a volume, in\_volume, with zeros or the values of the edge pixels. In\_volume, is placed in a larger out\_volume at the position specified by location. The padded region is set to zero or the values of the border pixels in in\_volume.

Out\_width, out\_height and out\_depth specify the width, height and depth of the returned volume. Location specifies the position within the returned volume where in\_volume will be placed. Pad\_type specifies whether the padded region in the returned volume is set to zero, AVW\_PAD\_ZERO, or the values of the border pixels in the in\_volume, AVW\_PAD\_VALUE.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_PadVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_PadVolume() will fail if the following is true:

**ILLDT** 

Illegal data type.

**SEE ALSO** 

AVW\_PadImage(), AVW\_PutSubVolume(), AVW\_Point3, AVW\_Volume

AVW\_Parse - evaluates an algebraic-style formula

**SYNOPSIS** 

#include "AVW\_Parse.h"

AVW\_Instructions \*AVW\_Parse(formula)

char \*formula;

**DESCRIPTION** 

*AVW\_Parse()* parses the string *formula* into a series of instruction which are returned in the *AVW\_Instructions* structure.

A user interface will need to fill in variable information such as filename, starting slice, slice, incrment, and number to process.

The completed AVW\_Instructions is passed to the AVW\_DoInstructions() function.

**RETURN VALUES** 

If successful,  $AVW\_Parse()$  returns  $AVW\_SUCCESS$ . On failure, it returns  $AVW\_FAIL$  and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_Parse() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**BADOP** 

Unknown Instruction.

**SYNTAX** 

Syntax Error In Formula.

**TCMPLX** 

Formula Too Complex To Be Parsed.

**SEE ALSO** 

AVW\_DoInstructions(), AVW\_DestroyInstructions(), AVW\_Instructions

AVW\_PreserveImageHistogram - preserve an image intensity distribution

**SYNOPSIS** 

#include "AVW\_Histogram.h"

AVW\_Image \*AVW\_PreserveImageHistogram(in\_image, max, min, fill\_type, out\_image)

AVW\_Image \*in\_image;

double max, min;

int fill\_type;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

 $AVW\_PreserveImageHistogram()$  maps a broad grey scale range into a narrow range in a statistically optimal manner. For example, this function may be used to map 16384 gray level bins of a 16 bit image into 256 bins of an 8 bit image. The ideal distribution would place 1/256 of the total pixels in each of the 256 bins.

*In\_image* specifies the input and *max* and *min* specify the output range.

Fill\_type specifies how the bins for equalization are filled and must be:

AVW\_OVERFILL - maps multiple input levels until output bin overfills,

AVW\_UNDERFILL - maps multiple input levels until just before output bin overfills,

or

AVW\_CLOSEST - chooses closest to ideal distribution.

The results are returned in out\_image.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_PreserveImageHistogram()* returns an *AVW\_Image* which has been optimally mapped to new range. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_PreserveImageHistogram() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**ILLIMG** 

Image provided was not valid.

#### **SEE ALSO**

AVW\_PreserveVolumeHistogram(), AVW\_FlattenImageHistogram(), AVW\_MatchImageHistogram(), AVW\_GetImageHistogram(), AVW\_Image

AVW\_PreserveVolumeHistogram - preserves a volume intensity distribution

## **SYNOPSIS**

#include "AVW\_Histogram.h"

AVW\_Volume \*AVW\_PreserveVolumeHistogram(in\_vol, max, min, fill\_type, out\_volume)

AVW\_Volume \*in\_vol;

double max, min;

int fill\_type;

AVW\_Volume \*out\_volume;

## **DESCRIPTION**

*AVW\_PreserveVolumeHistogram()* maps a broad grey scale range into a narrow range in a statistically optimal manner. For example, this function may be used to map 16384 gray level bins of a 16 bit image into 256 bins of an 8 bit image. The ideal distribution would place 1/256 of the total pixels in each of the 256 bins.

*In\_vol* specifies the input volume.

max and min specify the output range.

*Fill\_type* specifies how the bins for equalization are filled and must be:

AVW\_OVERFILL - maps multiple input levels until output bin overfills,

AVW\_UNDERFILL - maps multiple input levels until just before output bin overfills,

or

AVW\_CLOSEST - chooses closest to ideal distribution.

The results are returned in out\_volume.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful *AVW\_PreserveVolumeHistogram()* returns an *AVW\_Volume* which has been optimally mapped to new range. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_PreserveVolumeHistogram() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**ILLVOL** 

Volume provided was not valid.

# **SEE ALSO**

AVW\_FlattenVolumeHistogram(), AVW\_MatchVolumeHistogram(), AVW\_CetVolumeHistogram(), AVW\_Volume

AVW\_ProcessRenderWedge - Process subregion of Volume/Objectmap

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW\_Render.h"

int AVW\_ProcessRenderWedge(param, region, flag)

AVW\_RenderParameters \*param;

AVW\_Rect3 \*region;

int flag;

**DESCRIPTION** 

*AVW\_ProcessRenderWedge()* is used to preprocess the *param->Volume* or *param->Objectmap*. Copies should be made of the preprocessed volume if your wish to restore the volume to it's preprocessed condition.

Preprocessing of the input volumes, allows wedges or slabs to be removed. Only voxels which meet the current rendering requirements are removed. In other words, only voxels which are between the current threshold maximum and minimum values and those which are of an object type that is currently enabled will be processed.

Multiple pass preprocessing, by many calls to  $AVW\_ProcessRenderWedge()$ , can further enhance renderings.

**RETURN VALUES** 

If successful *AVW\_ProcessRenderWedge()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ProcessRenderWedge() will fail if one or more of the following is true:

**BADMAL** 

Couldn't allocate enough memory.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_RenderVolume(), AVW\_CopyVolume(), AVW\_RenderParameters, AVW\_Rect3

AVW\_ProcessZGradients - enhances a depth shaded rendering

**SYNOPSIS** 

#include "AVW\_Render.h"

AVW\_Image \*AVW\_ProcessZGradients(rendered, coef, out\_image)

AVW\_RenderedImage \*rendered;

double coef;

AVW\_Image \*out\_image;

## **DESCRIPTION**

*AVW\_ProcessZGradients()* enhances the *rendered->Image* by highlighting the changes in intensity values between neighboring pixels. This function should only be called to enhance images produced using the *AVW\_DEPTH\_SHADING* renderering algorithm.

*Rendered* is a pointer to a *AVW\_RenderedImage* structure returned by a call to *AVW\_RenderVolume()*.

*Coef* is a floating point value which specifies the relationship between depth and gradient in calculating the brightness of the output pixel. The default value of .2, indicates that the calculation is weighted 20% towards the gradient calculated and 80% towards the initial voxel brightness.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_ProcessZGradients()* returns an *AVW\_Image*. On failure, it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_ProcessZGradients() will fail if one or more of the following is true:

**BADMAL** 

Couldn't allocate enough memory.

**ILLPAR** 

Illegal parameter(s).

## **SEE ALSO**

AVW\_RenderVolume(), AVW\_RenderedImage(), AVW\_Image

AVW\_Progress - indicates current progress

## **SYNOPSIS**

#include "AVW.h"

int AVW\_Progress(percent)
int percent;

## **DESCRIPTION**

*AVW\_Progress()* is called by many *AVW* functions to indicate their current progress. *Percent* is a value from zero (0) to one hundred (100), indicating the current status of the calling procedure. This function will not normally be called unless *AVW* has been extended, and the programmer wishes to report the progress of the extended routine. Use of this function should be limited to functions which would normally require many seconds to execute. Functions which report progress, should not call other functions which report progress. Nested progresses are not supported.

When *AVW\_Progress()* is called, the percent value is passed to a user defined function. This function is indicated to *AVW* by the *AVW\_ProgressFunction()* call.

The return value is used to indicate a interrupt status. If non-zero value (1) is returned, the progress function indicates the process should continue. If zero (0) is returned, the progress function is requesting that the function be terminated.

## Example:

#### **RETURN VALUES**

If a call to *AVW\_Progress()* returns zero, the function should be terminated. A non-zero return value indicates that processing should continue.

## **SEE ALSO**

AVW\_ProgressFunction(), AVW\_Counter(), AVW\_RenderVolume(), AVW\_ReadVolume(), AVW\_WriteVolume(), AVW\_LoadObjectMap(), AVW\_SaveObjectMap()

AVW\_ProgressFunction – indicates the function which reports progress

**SYNOPSIS** 

#include "AVW.h"

void AVW\_ProgressFunction(int (\*function)())

## **DESCRIPTION**

Many *AVW* routines require many seconds to execute. The status of these routines is generally not reported until the function completes. To allow such things as progress bars to be generated while the function executes, many *AVW* functions call the *AVW\_Progress()* function to indicate their status. When the *AVW\_Progress()* function is called, the percentage value is passed on to a user specified function. The *AVW\_ProgressFunction()* is used to indicate which user supplied function is to be called.

By returning zero (0), the user supplied routine can indicate a desire to interrupt the function. A non-zero value indicates the processing should continue.

```
Example:
    {
    int my_function();
    AVW_ProgressFunction(my_function);
    db = AVW_OpenImageFile("/path/to/a/image/file", "r");
    volume = AVW_ReadVolume(db, 0, volume);
    * Etc... */
    }
int my_function(int percent)
    {
        DrawMyProgressBar(percent);
    if(CanelKeyPressed) return(0);
    return(1);
    }
```

**SEE ALSO** 

 $AVW\_Progress(),\ AVW\_RenderVolume(),\ AVW\_ReadVolume(),\ AVW\_WriteVolume(),\ AVW\_LoadObjectMap(),\ AVW\_SaveObjectMap()$ 

AVW\_PruneVolume - removes branches of a skeleton

**SYNOPSIS** 

#include "AVW.h"

int AVW\_PruneVolume(in\_volume, minlen)

AVW\_Volume \*in\_volume;

int minlen;

**DESCRIPTION** 

AVW\_PruneVolume() removes the branches of a skeleton which are shorter than minlen voxels.

*In\_volume* contains the 3D skeleton to be pruned which can be created by calling *AVW\_Thin3D()*.

*Minlen* specifies the minimum length of the branches in the skeleton. Branches with fewer than *minlen* voxels will be removed.

**RETURN VALUES** 

If successful *AVW\_PruneVolume()* returns the number of voxels removed by prunning. On failure it returns 0 and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_PruneVolume() will fail if:

**ILLDT** 

Data type is not AVW\_UNSIGNED\_CHAR.

**SEE ALSO** 

AVW\_Thin3D(), AVW\_MakeTree(), AVW\_Volume

AVW\_PutHistoryInfo - updates the History field of an AVW information string

**SYNOPSIS** 

#include "AVW.h"

char \*AVW\_PutHistoryInfo(string, info)

char \*string;
char \*info;

# **DESCRIPTION**

AVW\_PutHistoryInfo() is used to add a string value to the History field of an AVW information string. The default match\_string is History (See AVW\_PutStringInfo()) and multiple entries may be stored in this field. A string value of "On" must be passed in order to enable the logging of History for subsequent calls to this routine. "Off" disables the storing of History.

String indicates what to set the History field to within info.

*Info* can be any zero terminated string. The *History* entry within the information string begins with *History* = and then the strings, seperated by colons, which have been added with this routine.

Info strings are used in AVW structures to carry optional additional information about the data that may not always be present and to allow the user to extend AVW structures to carry application dependant data.

The logging of history information must be done by the user as AVW routines do not currently perform this internally.

# **RETURN VALUES**

If successful *AVW\_PutHistoryInfo()* returns a pointer to a character string containing the updated information.

## **SEE ALSO**

AVW\_GetNumericInfo(), AVW\_GetStringInfo(), AVW\_PutNumericInfo(), AVW\_PutStringInfo(), AVW\_RemoveInfo(), AVW\_Image, AVW\_Volume

AVW\_PutImageChannel - replaces a channel of an AVW\_Color image

**SYNOPSIS** 

#include "AVW.h"

int AVW\_PutImageChannel(image, channel, rgb\_image)

AVW\_Image \*image;

int channel;

AVW\_Image \*rgb\_image;

### **DESCRIPTION**

*AVW\_PutImageChannel()* inserts an AVW\_UNSIGNED\_CHAR image into the specified channel of an AVW\_COLOR image of the same size.

*image* must be of DataType AVW\_UNSIGNBED char and the same Width and Height as *rgb\_image*.

Channel can be specified as any of the following:

AVW\_RED\_CHANNEL - specifies the red channel.

AVW\_GREEN\_CHANNEL - specifies the green channel.

AVW\_BLUE\_CHANNEL - specifies the blue channel.

rgb\_image

must be an existing AVW\_COLOR image with the same width and height as *image*.

### **RETURN VALUES**

If successful *AVW\_PutImageChannel()* returns an *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL*. and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_PutImageChannel() will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

**ILLPAR** 

Illegal Parameter, images are wrong data type.

**CFLZ** 

Conflicting size, images not same width and height.

# **SEE ALSO**

AVW\_GetVolumeChannel(), AVW\_MakeColorImage(), AVW\_DestroyImage() AVW\_Image()

AVW\_PutMaskedImage - copies an irregular area from one image to another

**SYNOPSIS** 

#include "AVW.h"

int AVW\_PutMaskedImage(from\_image, to\_image, mask)

AVW\_Image \*from\_image; AVW\_Image \*to\_image; AVW\_Image \*mask;

**DESCRIPTION** 

For each non-zero pixel in *mask*, a the corresponding value is copied from *from\_image* to *to\_image*. Each zero pixel in *mask*, results in the corresponding pixel in *to\_image* being unchanged.

**RETURN VALUES** 

If successful *AVW\_PutMaskedImage()* returns *AVW\_SUCCESS*. On failure *AVW\_FAIL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_PutMaskedImage() will fail if one or more of the following are true:

**ILLDT** 

Illegal Datatype.

**CFLSZ** 

Conflicting size or type between the image and volume.

**SEE ALSO** 

AVW\_GetMaskedImage(), AVW\_Image

AVW\_PutMaskedVolume - copies an irregular region from one volume to another

**SYNOPSIS** 

#include "AVW.h"

int AVW\_PutMaskedVolume(from\_volume, to\_volume, mask)

AVW\_Volume \*from\_volume; AVW\_Volume \*to\_volume; AVW\_Volume \*mask;

**DESCRIPTION** 

For each non-zero voxel in *mask*, a the corresponding value is copied from *from\_volume* to *to\_volume*. Each zero voxel in *mask*, results in the corresponding voxel in *to\_volume* being unchanged.

**RETURN VALUES** 

If successful *AVW\_PutMaskedVolume()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_PutMaskedVolume() will fail if one or more of the following are true:

**ILLDT** 

Illegal Datatype.

**CFLSZ** 

Conflicting size or type between the from\_volume and to\_volume.

**SEE ALSO** 

AVW\_GetMaskedVolume(), AVW\_Volume

**NAME** AVW\_PutMultipleObjects – puts multiple objects into a object\_map

SYNOPSIS #include "AVW.h"

int AVW\_PutMultipleObjects(volume, object\_map)

AVW\_Volume \*volume;

AVW\_ObjectMap \*object\_map;

**DESCRIPTION** For each value within *volume*, a new object is created and defined in *object\_map*.

**RETURN VALUES** If successful *AVW\_PutMultipleObjects()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding

to the cause of the failure.

**ERRORS** | *AVW\_PutMultipleObjects()* will fail if one or more of the following are true:

**CFLSZ** 

*Volume* is not the same dimensions as the *object\_map*.

**ILLDT** 

*Volume* must have a *DataType* of *AVW\_UNSIGNED\_CHAR*.

**ILLPAR** 

Illegal parameter. object value outside of range for the objectmap.

SEE ALSO | AVW\_DefineConnected(), AVW\_GetObject(), AVW\_PutObject(), AVW\_RenderVolume(), AVW\_SaveObjectMap(), AVW\_ObjectMap, AVW\_Volume

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AVW\_PutNumericInfo – puts a numeric value in an AVW information string

#### **SYNOPSIS**

#include "AVW.h"

char \*AVW\_PutNumericInfo(match\_string, numeric\_value,info\_string)
char \*match\_string, \*info\_string;
double numeric\_value;

#### **DESCRIPTION**

*AVW\_PutNumericInfo()* is used to add or update numeric values in an *AVW* information string.

*Match\_string* is a zero terminated string which must match an entry in an information string exactly in order to get, update, or remove information.

*Info\_string* can be any zero terminated string. Each entry within the information string begins with a tag followed by an equal sign (=) and then the value. A space character is used as a seperator between entries. String information is enclosed in double quotes (") to allow for spaces within strings.

Numeric\_value indicates what to set match\_string to within info\_string.

Info strings are used in AVW structures to carry optional additional information about the data that may not always be present and to allow the user to extend AVW structures to carry application dependant data.

**Examples:** 

```
img->Info = AVW_PutNumericInfo("VoxelWidth", 1.285, img->Info);
img->Info = AVW_PutNumericInfo("VoxelHeight", 1.285, img->Info);
img->Info = AVW_PutNumericInfo("VoxelDepth", 1.670, img->Info);
img->Info = AVW_PutNumericInfo("Slice", 17., img->Info);
printf("%s\n", img->Info);
xsize = AVW_GetNumericInfo("VoxelWidth", img->Info);
if(AVW_ErrorNumber == NOMTCH)
  fprintf(stderr, "VoxelWidth not found in info_string");
else
  printf("X Size=%f\n", xsize);
ysize = AVW_GetNumericInfo("VoxelHeight", img->Info);
if(AVW_ErrorNumber == NOMTCH)
  fprintf(stderr, "VoxelHeight not found in info_string");
else
  printf("Y Size=%f\n", ysize);
thick = AVW_GetNumericInfo("VoxelDepth", img->Info);
if(AVW_ErrorNumber == NOMTCH)
  fprintf(stderr, "VoxelDepth not found in info_string");
  printf("Thickness=%f\n", thick);
slice = AVW_GetNumericInfo("Slice", img->Info);
if(AVW_ErrorNumber == NOMTCH)
  fprintf(stderr, "Slice not found in info_string");
  printf("Slice=%d\n", (int)slice);
```

**Results:** 

VoxelWidth=1.285 VoxelHeight=1.285 VoxelDepth=1.67 Slice=17

X Size=1.285 Y Size=1.285 Thickness=1.67 Slice=17

# **RETURN VALUES**

If successful, *AVW\_PutNumericInfo()* returns a pointer to a character string containing the updated information. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_PutNumericInfo() will fail if one or more of the following are true:

**BADMAL** 

Unable to increase information string size.

**NOMTCH** 

An illegal or NULL match\_string was passed.

**BDMTCH** 

Something is wrong with the info\_string.

**SEE ALSO** 

AVW\_GetNumericInfo(), AVW\_GetStringInfo(), AVW\_PutHistoryInfo(), AVW\_Inage, AVW\_Image, AVW\_ImageFile, AVW\_Volume

AVW\_PutObject – puts an object into a object\_map

**SYNOPSIS** 

#include "AVW.h"

int AVW\_PutObject(volume, object\_map, object)

AVW\_Volume \*volume;

AVW\_ObjectMap \*object\_map;

int object;

**DESCRIPTION** 

For each non-zero location in *volume*, the corresponding position within *object\_map* is set to the *object* value.

**RETURN VALUES** 

If successful *AVW\_PutObject()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_PutObject() will fail if one or more of the following are true:

**CFLSZ** 

*Volume* is not the same dimensions as the *object\_map*.

**ILLDT** 

*Volume* must have a *DataType* of *AVW\_UNSIGNED\_CHAR*.

**ILLPAR** 

Illegal parameter. object value outside of range for the objectmap.

**SEE ALSO** 

 $AVW\_DefineConnected(),\ AVW\_GetObject(),\ AVW\_RenderVolume(),\ AVW\_SaveObjectMap(),\ AVW\_ObjectMap,\ AVW\_Volume$ 

**NAME** AVW\_PutOblique – puts an oblique image in a volume

SYNOPSIS #include "AVW.h"

int AVW\_PutOblique(image, volume, matrix)

AVW\_Image \*image; AVW\_Volume \*volume; AVW\_Matrix \*matrix;

**DESCRIPTION** AVW\_PutOblique() writes an image into a volume.

image is the image being written into the volume.

matrix defines the oblique orientation.

volume receives the image.

This routine can be used to store edited oblique images back into a volume.

**RETURN VALUES** If successful AVW\_PutOblique() returns AVW\_SUCCESS. On failure it returns AVW\_FAIL

and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause

of the failure.

**ERRORS** *AVW\_PutOblique()* will fail if:

**ILLVOL** 

Illegal volume.

**SEE ALSO** | AVW\_GetOblique(), AVW\_MakeMatrixFrom3Points(), AVW\_MakeMatrixFromAxis(),

AVW\_MirrorMatrix(), AVW\_PutOrthogonal(), AVW\_RotateMatrix(), AVW\_ScaleMatrix(),

AVW\_SetIdentityMatrix(), AVW\_TranslateMatrix(), AVW\_Image, AVW\_Matrix,

AVW\_Volume

AVW\_PutOrthogonal – puts an image in a volume

**SYNOPSIS** 

#include "AVW.h"

int AVW\_PutOrthogonal(image, volume, orient, slice)

AVW\_Image \*image;

AVW\_Volume \*volume;

int orient; int slice;

**DESCRIPTION** 

AVW\_PutOrthogonal() writes image into volume at the position specified by orient and slice. Acceptable values for orient are AVW\_TRANSVERSE, AVW\_CORONAL, and AVW\_SAGITTAL. AVW numbers volume slices from 0 to (n-1). This means that acceptable slice values for transverse slices is 0 to (volume->Depth-1). Coronal slices number from 0 to (volume->Width-1) and sagittal slices number from 0 to (volume->Height-1).

This routine can be used to write edited or filtered images back into a volume.

**RETURN VALUES** 

If successful *AVW\_PutOrthogonal()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_PutOrthogonal() will fail if one or more of the following are true:

**ILLVOL** 

Illegal volume.

**ILLIMG** 

Illegal image.

**CFLSZ** 

Conflicting size or type between the image and volume.

**ILLPAR** 

Illegal parameter. Orient or slice is not valid.

**SEE ALSO** 

AVW\_GetOrthogonal(), AVW\_GetOblique(), AVW\_PutOblique(), AVW\_Image, AVW\_Volume

AVW\_PutPixel - puts a value at a location in an image

**SYNOPSIS** 

#include "AVW.h"

int AVW\_PutPixel(image, point, value)

AVW\_Image \*image; AVW\_Point2 \*point;

double value:

**DESCRIPTION** 

AVW\_PutPixel() sets the location in image specified by point to value.

For AVW\_COLOR images the red, green, and blue components need to be packed into

value. See AVW\_MAKERGB().

**RETURN VALUES** 

If successful AVW\_PutPixel() returns AVW\_SUCCESS.

On failure AVW\_FAIL is returned and AVW\_ErrorNumber and AVW\_ErrorMessage are set

to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_PutPixel() will fail if one or more of the following are true:

**ILLPAR** 

Point specified is outside of the image.

**ILLDT** 

Data type is not defined or supported.

**SEE ALSO** 

AVW\_PutVoxel(), AVW\_GetPixel(), AVW\_GetVoxel(), AVW\_DrawPointList2(), AVW\_DrawPointList3(), AVW\_Image, AVW\_Point2, AVW\_MAKERGB()

AVW\_PutStringInfo - puts a string in an AVW information string

## **SYNOPSIS**

#include "AVW.h"

char \*AVW\_PutStringInfo(match\_string, string\_value, info\_string)
char \*match\_string, \*string\_value, \*info\_string;

# **DESCRIPTION**

*AVW\_PutStringInfo()* is used to add or update a text string value in an *AVW* information string.

*Match\_string* is a zero terminated string which must match an entry in an information string exactly in order to get, update, or remove information.

*Info\_string* can be any zero terminated string. Each entry within the information string begins with each tag followed by an equal sign (=) and then the value. A space character is used as a seperator between entries. String information is enclosed in double quotes (") to allow for spaces within strings.

String\_value indicates what to set match\_string to within info\_string.

Info strings are used in AVW structures to carry optional additional information about the data that may not always be present and to allow the user to extend AVW structures to carry application dependant data.

# Example:

```
img->Info = AVW_PutStringInfo("Name", "John Doe", img->Info);
printf("%s\n\n", img->Info);
if((name = AVW_GetStringInfo("Name", img->Info)) == NULL)
    fprintf("Name not found in info_string");
else
    printf("Name=%s\n", name);
free(name);
Results:
Name="John Doe"
```

#### **RETURN VALUES**

If successful, *AVW\_PutStringInfo()* returns a pointer to a character string containing the updated information. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

### **ERRORS**

AVW\_PutStringInfo() will fail if one or more of the following are true:

#### **NOMTCH**

Name=John Doe

An illegal or NULL match\_string was passed.

### **BDMTCH**

Something is wrong with the info\_string.

**SEE ALSO** 

 $AVW\_GetNumericInfo(),\ AVW\_GetStringInfo(),\ AVW\_PutHistoryInfo(),\\ AVW\_PutNumericInfo(),\ AVW\_RemoveInfo(),\ AVW\_Image,\ AVW\_ImageFile,\ AVW\_Volume$ 

AVW\_PutSubImage - puts a subregion into an image

**SYNOPSIS** 

#include "AVW.h"

int AVW\_PutSubImage(from\_image, to\_image, location)

AVW\_Image \*from\_image, \*to\_image;

AVW\_Point2 \*location;

**DESCRIPTION** 

AVW\_PutSubImage() puts a smaller image, from\_image, into a larger or equal sized image, to\_image, at the position specified by location. The smaller image can be a subregion that was extracted from the larger image with AVW\_GetSubImage(), and then processed in some way.

**RETURN VALUES** 

If successful *AVW\_PutSubImage()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_PutSubImage() will fail if one or more of the following are true:

**ILLDT** 

Illegal datatype. From\_image and to\_image are not the same data type.

**ILLPAR** 

Illegal parameter. From\_image does not fit into to\_image at the specified position

**SEE ALSO** 

AVW\_PutSubVolume(), AVW\_GetOrthogonal(), AVW\_GetSubImage(), AVW\_PutOrthogonal(), AVW\_Image, AVW\_Point2

**NAME** AVW\_PutSubVolume - puts a subvolume into a volume

**SYNOPSIS** #include "AVW.h"

int AVW\_PutSubVolume(from\_volume, to\_volume, frontupperleft)

AVW\_Volume \*from\_volume, \*to\_volume;

AVW\_Point3 \*location;

**DESCRIPTION** 

AVW\_PutSubVolume() puts a smaller volume, from\_volume, into a larger volume, to\_volume, at the position specified by location. The smaller volume can be a subvolume that was extracted from the larger volume with AVW\_GetSubVolume() and then processed in some way.

**RETURN VALUES** 

If successful, AVW\_PutSubVolume() returns AVW\_SUCCESS. On failure, it returns AVW\_FAIL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_PutSubVolume() will fail if one or more of the following are true:

**ILLDT** 

Illegal datatype. From\_volume and to\_volume do not have the same data type.

**ILLPAR** 

Illegal parameter. From\_volume does not fit in to\_volume at specified position.

**SEE ALSO** 

AVW\_PutSubImage(), AVW\_GetSubVolume(), AVW\_PadVolume(), AVW\_Point3, AVW\_Volume

AVW\_PutImageChannel - replaces a channel of an AVW\_Color volume

**SYNOPSIS** 

#include "AVW.h"

int AVW\_PutVolumeChannel(volume, channel, rgb\_image)

AVW\_Volume \*volume;

int channel;

AVW\_Volume \*rgb\_volume;

### **DESCRIPTION**

*AVW\_PutVolumeChannel()* inserts an AVW\_UNSIGNED\_CHAR volume into the specified channel of an existing AVW\_COLOR volume of the same size.

*Volume* must be of DataType AVW\_UNSIGNED char and the same Width and Height as *rgb\_image*.

Channel can be specified as any of the following:

AVW\_RED\_CHANNEL - specifies the red channel.

AVW\_GREEN\_CHANNEL - specifies the green channel.

AVW\_BLUE\_CHANNEL - specifies the blue channel.

rgb\_volume

must be an existing AVW\_COLOR volume with the same width, height, and depth as *volume*.

### **RETURN VALUES**

If successful *AVW\_PutVolumeChannel()* returns an *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL*. and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_PutVolumeChannel() will fail if:

**BADMAL** 

Malloc Failed. Unable to allocate sufficient memory.

**ILLPAR** 

Illegal Parameter, volumes are wrong data type

**CFLZ** 

Conflicting size, volumes not same width, height, and depth.

# **SEE ALSO**

AVW\_GetImageChannel(), AVW\_MakeColorVolume(), AVW\_DestroyImage() AVW\_Image()

**NAME** AVW\_PutVoxel – puts a value at a location in a volume

SYNOPSIS #include "AVW.h"

int AVW\_PutVoxel(volume, point, value)

AVW\_Volume \*volume; AVW\_Point3 \*point;

double value;

**DESCRIPTION** | AVW\_PutVoxel() sets the location in volume specified by point to value.

For AVW\_COLOR volumes the red, green, and blue components need to be packed into

value. See AVW\_MAKERGB().

**RETURN VALUES** If successful *AVW\_PutVoxel()* returns *AVW\_SUCCESS*. *AVW\_FAIL* is returned. On

failure AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the

cause of the failure.

**ERRORS** | *AVW\_PutVoxel()* will fail if

**ILLPAR** 

Point specified is outside of the volume.

**ILLDT** 

Data type is not defined or supported.

SEE ALSO | AVW\_PutPixel(), AVW\_GetVoxel(), AVW\_DrawPointList2(), AVW\_DrawPointList3(),

AVW\_Point3, AVW\_Volume, AVW\_MAKERGB()

AVW\_QuadSwapImage – swaps the quadrants of an image.

**SYNOPSIS** 

#include "AVW.h"

int AVW\_QuadSwapImage(in\_image)

AVW\_Image \*in\_image;

**DESCRIPTION** 

AVW\_QuadSwapImage() swaps the quadrants of in\_image in place. The lower left quadrant becomes the upper right and vice versa, while the lower right quadrant becomes the upper left and vice versa. If an image is convolved with a point-spread function by multiplying the Fourier spectra of the image and PSF, and then performing an inverse FFT, the result will be quad-swapped. This routine undoes the swapping in place without requiring an intermediate image.

**RETURN VALUES** 

If successful *AVW\_QuadSwapImage()* returns *AVW\_SUCCESS* On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_QuadSwapImage() will fail if one or more of the following are true:

**BADTYPE** 

Function does not support AVW\_COMPLEX or AVW\_COLOR datatypes.

**ILLDT** 

Unknown or unsupported input or output displaytype.

**SEE ALSO** 

AVW\_MakeComplexImageViewable(), AVW\_Image

AVW\_QuickImageMaxMin - finds the maximum and minimum values of an image

**SYNOPSIS** 

#include "AVW.h"

int AVW\_QuickImageMaxMin(image, max\_val, min\_val)

AVW\_Image \*image;

double \*max\_val, \*min\_val;

**DESCRIPTION** 

AVW\_QuickImageMaxMin() finds the maximum and minimum data values in *image* and returns them in *max\_val* and *min\_val*.

AVW\_QuickImageMaxMin() checks the image->Info information string for MaximumData-Value and MinimumDataValue. If found, the max\_val and min\_val values are set using the information string values. If not found, the max\_val and min\_val values are calculated by calling AVW\_FindImageMaxMin().

After calculation, the values are stored in the information string to allow quicker future max/min queries.

**RETURN VALUES** 

If successful,  $AVW\_QuickImageMaxMin()$  returns  $AVW\_SUCCESS$ . On failure, it returns  $AVW\_FAIL$  and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_QuickImageMaxMin() will fail if:

**NOTSUP** 

Image data type not supported.

**SEE ALSO** 

 $AVW\_GetNumericInfo(),\ AVW\_FindImageMaxMin(),\ AVW\_QuickVolumeMaxMin(),\ AVW\_Image$ 

AVW\_QuickMatch – generates the matrix required to register volumes

**SYNOPSIS** 

#include "AVW\_MatchVoxels.h"

AVW\_Matrix \*AVW\_QuickMatch(base\_volume, match\_volume, BaseMax, BaseMin, MatchMax,MatchAVW\_Volume \*base\_volume, \*match\_volume;

double BaseMin, BaseMax, MatchMin, MatchMax;

AVW\_Matrix \*matrix;

**DESCRIPTION** 

AVW\_QuickMatch() determines the geometric transformation parameters required to spatially register the base\_volume and match\_volume

matrix is provided as a method of re-using an existing AVW\_Matrix.

**RETURN VALUES** 

If successful returns a pointer to an *AVW\_Matrix* structure which contains an homogeneous 4x4 matrix used to register *match\_volume* to *base\_volume*.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_QuickMatch() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**SEE ALSO** 

AVW\_TransformVolume(), AVW\_Matrix, AVW\_Volume.

AVW\_QuickVolumeMaxMin - finds the maximum and minimum values of an volume

**SYNOPSIS** 

#include "AVW.h"

int AVW\_QuickVolumeMaxMin(volume, max\_val, min\_val)

AVW\_Volume \*volume; double \*max\_val, \*min\_val;

**DESCRIPTION** 

AVW\_QuickVolumeMaxMin() finds the maximum and minimum data values in *volume* and returns them in *max\_val* and *min\_val*.

AVW\_QuickVolumeMaxMin() checks the volume->Info information string for MaximumDataValue and MinimumDataValue. If found, the max\_val and min\_val values are set using the information string values. If not found, the max\_val and min\_val values are calculated by calling AVW\_FindVolumeMaxMin().

After calculation, the values are stored in the information string to allow quicker future max/min queries.

**RETURN VALUES** 

If successful,  $AVW\_QuickVolumeMaxMin()$  returns  $AVW\_SUCCESS$ . On failure, it returns  $AVW\_FAIL$  and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_QuickVolumeMaxMin() will fail if:

**NOTSUP** 

Volume data type not supported.

**SEE ALSO** 

AVW\_GetNumericInfo(), AVW\_FindVolumeMaxMin(), AVW\_QuickImageMaxMin(), AVW\_Volume

AVW\_RankFilterImage - performs a 2D generic rank filter

**SYNOPSIS** 

#include "AVW\_Filter.h"

AVW\_Image \*AVW\_RankFilterImage(in\_image, extents, rank, out\_image)

AVW\_Image \*in\_image;

int extents[2];

int rank;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_RankFilterImage() performs a generic rank filter transformation on *in\_image*. Extents[0], and extents[1], specify the x and y sizes respectively of the filter. Extent values should be odd.

A rank filter orders all the values found in the filter region and returns the value of the *rank'th* pixel. For a 3X3 region, a rank of 5 would be the median value. *Rank* of value 1 is the lowest value. The maximum value for *rank* is *extents*[0]\**extents*[1]. A *rank* of value 0 effects a median filter.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful AVW\_RankFilterImage() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_RankFilterVolume(), AVW\_AHEImage(), AVW\_LowpassFilterImage(), AVW\_OrthoGradFilterImage(), AVW\_SigmaFilterImage(), AVW\_SobelFilterEnhanceImage(), AVW\_UnsharpFilterEnhanceImage(), AVW\_UnsharpFilterImage(), AVW\_Image

AVW\_RankFilterVolume - performs a 3D generic rank filter

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Volume \*AVW\_RankFilterVolume(in\_volume, extents, rank, out\_volume)

AVW\_Volume \*in\_volume;

int extents[3];

int rank;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_RankFilterVolume() performs a generic rank filter transformation on in\_volume. Extents[0], extents[1], and extents[2] specify the x, y, and z sizes respectively of the filter. Extent values should be odd.

A rank filter orders all the values found in the filter region and returns the value of the *rank'th* voxel. For a 3X3X3 region, a rank of 14 would be the median value. *Rank* of value 1 is the lowest value. The maximum value for *rank* is *extents*[0]\*extents[1]\*extents[2]. A *rank* of value 0 effects a median filter.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_RankFilterVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

 $AVW\_RankFilterImage(),\ AVW\_AHEVolume(),\ AVW\_LowpassFilterVolume(),$ 

AVW\_OrthoGradFilterVolume(), AVW\_SigmaFilterVolume(),

AVW\_SobelFilterEnhanceVolume(), AVW\_SobelFilterVolume(),

AVW\_UnsharpFilterEnhanceVolume(), AVW\_UnsharpFilterVolume(),

AVW\_VSFMeanFilterVolume(), AVW\_Volume

AVW\_ReadHistogram - reads a histogram file

**SYNOPSIS** 

#include "AVW\_Histogram.h"

AVW\_Histogram \*AVW\_ReadHistogram(filename, histo)

char \*filename;

AVW\_Histogram \*histo;

**DESCRIPTION** 

AVW\_ReadHistogram() reads a histogram from the specified file. If the passed histo parameter is NULL, AVW\_ReadHistogram() will allocate a histogram of the appropriate size as indicated in the histogram file. If the passed histo is not compatible with the requirements of the histogram file, the histo is destroyed and a new histo will be allocated.

**RETURN VALUES** 

Upon success AVW\_ReadHistogram() returns an AVW\_Histogram. On failure NULL is returned and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values indicating the cause of error.

**ERRORS** 

Errors may occur for the following reasons:

**BDOPEN** 

Bad Open. Failure opening file.

**ILLHIS** 

Illegal Histogram. Could not create histogram.

**SEE ALSO** 

AVW\_ClearHistogram(), AVW\_CreateHistogram(), AVW\_DestroyHistogram(), AVW\_GetImageHistogram(), AVW\_GetVolumeHistogram(), AVW\_NormalizeHistogram(), AVW\_VerifyHistogram(), AVW\_WriteHistogram(),

AVW\_ReadImageFile - reads an image from an image file

**SYNOPSIS** 

#include "AVW\_ImageFile.h"

AVW\_Image \*AVW\_ReadImageFile (imgfile, image)

AVW\_ImageFile \*imgfile; AVW\_Image \*image;

**DESCRIPTION** 

AVW\_ReadImageFile() reads the next image from the AVW\_ImageFile. At the conclusion of the read the file is positioned to read the following image. If the passed *image* parameter is NULL, AVW\_ReadImageFile() will allocate an image of the same size and type as indicated in the *image*. If the passed *image* is not compatible with the requirements of *image*, the *image* is destroyed and a new *image* is allocated.

**RETURN VALUES** 

Upon success *AVW\_ReadImageFile()* returns an *AVW\_Image*. On failure *NULL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values indicating the cause of error.

**ERRORS** 

Errors may occur for the following reasons:

**BADMAL** 

Bad Malloc. Memory allocation error.

**BDREAD** 

Read error.

**SEE ALSO** 

 $AVW\_Close Image File (),\ AVW\_Create Image File (),\ AVW\_Extend External Libs (),$ 

AVW\_ExtendImageFile(), AVW\_FormatSupports(), AVW\_ListFormats(),

AVW\_OpenImageFile(), AVW\_ReadVolume(), AVW\_SeekImageFile() AVW\_WriteImageFile(),

AVW\_WriteVolume(), AVW\_ImageFile, AVW\_Image

AVW\_ReadVolume - reads a volume from an image file

#### **SYNOPSIS**

#include "AVW\_ImageFile.h"

AVW\_Volume \*AVW\_ReadVolume (imgfile, volnum, vol)

AVW\_ImageFile \*imgfile;

int volnum;

AVW\_Volume \*vol;

### **DESCRIPTION**

AVW\_ReadVolume() reads the specified volume from the AVW\_ImageFile. If the passed vol parameter is NULL, AVW\_ReadVolume() will allocate a volume of the same size and type as indicated in the imgfile. If the passed vol is not compatible with the requirements of imgfile, the vol is destroyed and a new vol will be allocated.

*Volnum* is the volume number to be read. Volumes are numbered from 0 to NumVols-1. Thus if the first volume from a file is to be read, specify 0.

For image files whose data format does not support 3D or 4D the single image will be returned as a volume with Depth equal to 1.

### **RETURN VALUES**

Upon success AVW\_ReadVolume() returns an AVW\_Volume. On failure NULL is returned and AVW\_ErrorNumber and AVW\_ErrorMessage are set to values indicating the cause of error.

## **ERRORS**

Errors may occur for the following reasons:

**BADMAL** 

Bad Malloc. Memory allocation error.

**BDREAD** 

Read error.

**BDVLNM** 

Bad volume number.

### **SEE ALSO**

AVW\_CloseImageFile(), AVW\_CreateImageFile(), AVW\_ExtendExternalLibs(), AVW\_ExtendImageFile(), AVW\_FormatSupports(), AVW\_ListFormats(),

AVW\_OpenImageFile(), AVW\_ReadImageFile(), AVW\_SeekImageFile(),

AVW\_WriteImageFile(), AVW\_WriteSubVolumeDescription(), AVW\_WriteVolume(),

AVW\_ImageFile, AVW\_Volume

AVW\_Malloc - allocates system memory

### **SYNOPSIS**

#include "AVW.h"

void \*AVW\_Malloc(size)
unsigned int size;

void \*AVW\_Calloc(num, size)
unsigned int num;
unsigned int size;

void \*AVW\_Realloc(size, ptr)
unsigned int size;
void \*ptr;

void AVW\_Free(ptr)
void \*ptr;

# **DESCRIPTION**

These procedures provide a platform and compiler independent interface for memory allocation. Programs that need to transfer ownership of memory blocks between AVW and other modules should use these routines rather than the native malloc() and free() routines provided by the C run-time library.

AVW\_Malloc returns a pointer to a size bytes suitably aligned for any use.

AVW\_Calloc allocates space for an array nelem elements of size elsize. The space is initialized to zeros.

*Tcl\_Realloc* changes the size of the block pointed to by *ptr* to *size* bytes and returns a pointer to the new block. The contents will be unchanged up to the lesser of the new and old sizes. The returned location may be different from *ptr*.

*Tcl\_Free* makes the space referred to by *ptr* available for further allocation.

### **SEE ALSO**

malloc(), free()

AVW\_ReassignObject - deletes an object from an object map

**SYNOPSIS** 

#include "AVW\_ObjectMap.h"

int AVW\_ReassignObject(object\_map, from, to)

AVW\_ObjectMap \*object\_map;

int from; int to;

**DESCRIPTION** 

AVW\_ReassignObject() changes all the voxels currently assigned to the *from* object, so that they are assigned to the *to* object.

**RETURN VALUES** 

If successful *AVW\_ReassignObject()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ReassignObject() will fail if the following is true:

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_AddObject(), AVW\_DestroyObjectMap(), AVW\_CreateObjectMap(), AVW\_DeleteObject(), AVW\_GetObject(), AVW\_PutObject() AVW\_LoadObjectMap(), AVW\_SaveObjectMap(), AVW\_RemoveUnusedObjects(), AVW\_RenderVolume(), AVW\_ObjectMap, AVW\_Object

AVW\_ReduceColors - reduces colors used in an image

**SYNOPSIS** 

#include "AVW.h"

int AVW\_ReduceColors(image, method, ncolors)

AVW\_Image \*image;

int method;

int ncolors:

**DESCRIPTION** 

AVW\_ReduceColors() reduces the number of colors used in an AVW\_Image by changing the image and image->Colormap.

*Method* may be one of or a combination of *AVW\_DUPLICATE\_COLORMAP\_ENTRIES*, *AVW\_UNUSED\_COLORMAP\_ENTRIES*, and *AVW\_LEAST\_USED\_COLOR* 

When set to *AVW\_DUPLICATE\_COLORMAP\_ENTRIES*, the colormap is searched for duplicate entries and if duplicates are found they are removed.

When set to *AVW\_UNUSED\_COLORMAP\_ENTRIES*, the colormap is searched for unused entries and if found they are removed.

When set to *AVW\_LEAST\_USED\_COLOR*, the colormap is searched and the least used entry is removed, this process is repeated until the total colors is reduced to ncolors or less.

**RETURN VALUES** 

*AVW\_ReduceColors()* returns the number of colormap entries that were removed. 0 will be returned if *image* did not have an associated colormap or the data type was not *AVW\_UNSIGNED\_CHAR*.

**SEE ALSO** 

AVW\_CopyColormap(), AVW\_CreateColormap(), AVW\_DestroyColormap(), AVW\_IsGrayColormap(), AVW\_LoadColormap(), AVW\_SaveColormap(), AVW\_Colormap, AVW\_Image

AVW\_RegenerateObjectMap - loads an object map

**SYNOPSIS** 

#include "AVW\_ObjectMap.h"

AVW\_ObjectMap \*AVW\_RegenerateObjectMap(omap, vol)

AVW\_ObjectMap \*omap;

AVW\_Volume \*vol;

**DESCRIPTION** 

*AVW\_RegenerateObjectMap()* regenerates a new volume and object map by applying the transformations specified for each object.

**RETURN VALUES** 

If successful *AVW\_RegenerateObjectMap()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_RegenerateObjectMap() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

 $AVW\_AddObject(),\ AVW\_CreateObjectMap(),\ AVW\_DeleteObject(),\\ AVW\_DestroyObjectMap(),\ AVW\_LoadObjectMap(),\ AVW\_RenderVolume(),\\ AVW\_SaveObjectMap(),\ AVW\_ObjectMap$ 

NAME | AVW\_RegisterProgramName – initialize AVW

SYNOPSIS #include "AVW.h"

int AVW\_RegisterProgramName(name)

char \*name;

**DESCRIPTION** | AVW\_RegisterProgramName() should be the first AVW function called. Results can be

checked to determine if a license is available. Name specifies a unique name for program.

Name is no longer used during the validation process.

**RETURN VALUES** | *AVW\_RegisterProgramName()* returns *AVW\_SUCCESS* for valid users and systems.

AVW\_FAIL is returned for invalid systems and/or users and a descriptive message is

written to stderr and/or stdout.

**NAME** AVW\_RemoveFPoint2 – removes a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_RemoveFPoint2(trace, which\_point)

AVW\_FPointList2 \*trace;

int which\_point;

**DESCRIPTION** | *AVW\_RemoveFPoint2()* removes an AVW\_FPoint2 from an AVW\_FPointList2.

Trace is an AVW\_FPointList2.

*Which\_point* specifies the point number of the trace that is to be removed. Acceptable values range from 0 (the first point in the list) to trace->NumberOfPoints-1 (the last point).

**RETURN VALUES** If successful *AVW\_SUCCESS* is returned, otherwise *AVW\_FAIL* is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** | *AVW\_RemoveFPoint2* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

**SEE ALSO** *AVW\_AddFPoint2(), AVW\_CopyFPointList2(), AVW\_CreateFPointList2(),* 

AVW\_DestroyFPointList2(), AVW\_GetFPoint2(), AVW\_MakeFPointList2(),

AVW\_RemoveFPoint3(), AVW\_RemoveIPoint2(), AVW\_RemoveIPoint3(),

AVW\_RemovePoint2(), AVW\_RemovePoint3(), AVW\_RemovePointValue(),

AVW\_TransformFPoint2(), AVW\_FPoint2, AVW\_FPointList2

**NAME** AVW\_RemoveFPoint3 – removes a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_RemoveFPoint3(trace, which\_point)

AVW\_FPointList3 \*trace;

int which\_point;

**DESCRIPTION** | *AVW\_RemoveFPoint3()* removes an AVW\_FPoint3 from an AVW\_FPointList3.

Trace is an AVW\_FPointList3.

*Which\_point* specifies the point number of the trace that is to be removed. Acceptable values range from 0 (the first point in the list) to trace->NumberOfPoints-1 (the last point).

**RETURN VALUES** 

If successful *AVW\_SUCCESS* is returned, otherwise *AVW\_FAIL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_RemoveFPoint3 will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

**SEE ALSO** 

AVW\_AddFPoint3(), AVW\_CopyFPointList3(), AVW\_CreateFPointList3(), AVW\_DestroyFPointList3(), AVW\_GetFPoint3(), AVW\_RemoveFPoint2(), AVW\_RemoveIPoint3(), AVW\_RemovePoint3(), AVW\_RemovePoint3(), AVW\_TransformFPoint3(), AVW\_FPoint3, AVW\_FPointList3

**NAME** AVW\_RemoveIPoint2 – removes a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_RemoveIPoint2(trace, which\_point)

AVW\_IPointList2 \*trace;

int which\_point;

**DESCRIPTION** | AVW\_RemoveIPoint2() removes an AVW\_IPoint2 from an AVW\_IPointList2.

Trace is an AVW\_IPointList2.

*Which\_point* specifies the point number of the trace that is to be removed. Acceptable values range from 0 (the first point in the list) to trace->NumberOfPoints-1 (the last point).

**RETURN VALUES** If successful AVW\_SUCCESS is returned, otherwise AVW\_FAIL is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** *AVW\_RemoveIPoint2* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

SEE ALSO | AVW\_AddIPoint2(), AVW\_CopyIPointList2(), AVW\_CreateIPointList2(),

AVW\_DestroyIPointList2(), AVW\_GetIPoint2(), AVW\_RemoveFPoint2(),

AVW\_RemoveFPoint3(), AVW\_RemoveIPoint3(), AVW\_RemovePoint2(),

AVW\_RemovePoint3(), AVW\_RemovePointValue(), AVW\_TransformIPoint2(), AVW\_IPoint2,

AVW IPointList2

**NAME** AVW\_RemoveIPoint3 – removes a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_RemoveIPoint3(trace, which\_point)

AVW\_IPointList3 \*trace;

int which\_point;

**DESCRIPTION** | AVW\_RemoveIPoint3() removes an AVW\_IPoint3 from an AVW\_IPointList3.

*Trace* is an *AVW\_IPointList3*.

Which\_point specifies the point number of the trace that is to be removed. Acceptable values range from 0 (the first point in the list) to trace->NumberOfPoints-1 (the last

point).

**RETURN VALUES** | If successful AVW\_SUCCESS is returned, otherwise AVW\_FAIL is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** | *AVW\_RemoveIPoint3* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

**SEE ALSO** AVW\_AddIPoint3(), AVW\_CopyIPoint3list(), AVW\_CreateIPointList3(),

AVW\_DestroyIPointList3(), AVW\_GetIPoint3(), AVW\_RemoveFPoint2(),

AVW\_RemoveFPoint3(), AVW\_RemoveIPoint2(), AVW\_RemovePoint2(),

AVW\_RemovePoint3(), AVW\_RemovePointValue(), AVW\_TransformIpoint3(), AVW\_IPoint3,

AVW\_IPointList3

AVW\_RemoveInfo - removes a value from an information string

**SYNOPSIS** 

#include "AVW.h"

char \* AVW\_RemoveInfo(match\_string, info\_string)
char \*match\_string, \*info\_string;

**DESCRIPTION** 

AVW\_RemoveInfo() removes an entry from an information string.

*Match\_string* is a zero terminated string which must match an entry in an information string exactly in order to get, update, or remove information.

*Info\_string* can be any zero terminated string. Each entry within the information string begins with a tag followed by an equal sign (=) and then the value. A space character is used as a seperator between entries. String information is enclosed in double quotes (") to allow for spaces within strings.

Info strings are used in AVW structures to carry optional additional information about the data that may not always be present and to allow the user to extend AVW structures to carry application dependant data.

**RETURN VALUES** 

If successful,  $AVW\_RemoveInfo()$  returns a pointer to a character string with the  $match\_string$  removed. On failure it returns the unchanged  $info\_string$  and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_RemoveInfo() will fail if the following is true:

**NOMTCH** 

No match string was found in the info\_string.

**SEE ALSO** 

AVW\_GetNumericInfo(), AVW\_GetStringInfo(), AVW\_ListInfo(), AVW\_MergeInfo(), AVW\_PutHistoryInfo(), AVW\_PutNumericInfo(), AVW\_PutStringInfo(), AVW\_Image, AVW\_Volume

**NAME** AVW\_RemovePoint2 – removes a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_RemovePoint2(trace, which\_point)

AVW\_PointList2 \*trace;

int which\_point;

**DESCRIPTION** AVW\_RemovePoint2() removes an AVW\_Point2 from an AVW\_PointList2.

Trace is an AVW\_PointList2.

*Which\_point* specifies the point number of the trace that is to be removed. Acceptable values range from 0 (the first point in the list) to trace->NumberOfPoints-1 (the last point).

**RETURN VALUES** If successful AVW SUCCESS is returned, otherwise AVW FAIL is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** *AVW\_RemovePoint2* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

**SEE ALSO** AVW\_AddPoint2(), AVW\_ClipPointList2(), AVW\_ClosestInPointList2(),

AVW\_CopyPointList2(), AVW\_CreatePointList2(), AVW\_DestroyPointList2(),

AVW\_DrawPointList2(), AVW\_EditPointList2(), AVW\_FillPointList2(), AVW\_GetPoint2(),

 $AVW\_RemoveFPoint 3 (),\ AVW\_RemoveFPoint 2 (),\ AVW\_RemoveIPoint 3 (),$ 

AVW\_RemoveIPoint2(), AVW\_RemovePoint3(), AVW\_RemovePointValue(),

AVW\_ScalePointList2(), AVW\_ShiftPointList2(), AVW\_TransformPoint2(),

AVW\_TranslatePointlist2(), AVW\_Point2, AVW\_PointList2

AVW\_RemovePoint2()

**NAME** AVW\_RemovePoint3 – removes a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_RemovePoint3(trace, which\_point)

AVW\_PointList3 \*trace;

int which\_point;

**DESCRIPTION** AVW\_RemovePoint3() removes an AVW\_Point3 from an AVW\_PointList3.

Trace is an AVW\_PointList3.

*Which\_point* specifies the point number of the trace that is to be removed. Acceptable values range from 0 (the first point in the list) to trace->NumberOfPoints-1 (the last point).

**RETURN VALUES** 

If successful *AVW\_SUCCESS* is returned, otherwise *AVW\_FAIL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_RemovePoint3* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

**SEE ALSO** 

AVW\_AddPoint3(), AVW\_CopyPointList3(), AVW\_CreatePointList3(),

AVW\_DestroyPointList3(), AVW\_DrawPointList3(), AVW\_FillPointList3(),

AVW\_GetPoint3(), AVW\_RemoveFPoint2(), AVW\_RemoveFPoint3(), AVW\_RemoveIPoint2(),

AVW RemoveIPoint3(), AVW RemovePoint2(), AVW RemovePointValue(),

AVW\_TransformPoint3(), AVW\_Point3, AVW\_PointList3

**NAME** AVW\_RemovePointValue – removes a point from a list

SYNOPSIS #include "AVW.h"

int AVW\_RemovePointValue(trace, which\_point)

AVW\_PointValueList \*trace;

int which\_point;

**DESCRIPTION** | AVW\_RemovePointValue() removes an AVW\_PointValue from an AVW\_PointValueList.

Trace is an AVW\_PointValueList.

Which\_point specifies the point number of the trace that is to be removed. Acceptable values range from 0 (the first point in the list) to trace->NumberOfPoints-1 (the last

point).

**RETURN VALUES** If successful *AVW\_SUCCESS* is returned, otherwise *AVW\_FAIL* is returned and

AVW\_ErrorNumber and AVW\_ErrorMessage are set to values corresponding to the cause

of the failure.

**ERRORS** *AVW\_RemovePointValue* will fail if the following is true:

**ILLPAR** 

which\_value is less than 0 or greater or equal to trace->NumberOfPoints.

**SEE ALSO** AVW\_AddPointValue(), AVW\_CopyPointValueList(), AVW\_CreatePointValueList(),

AVW\_DestroyPointValueList(), AVW\_GetPointValue(), AVW\_RemoveFPoint2(),

AVW\_RemoveFPoint3(), AVW\_RemoveIPoint2(), AVW\_RemoveIPoint3(),

AVW\_RemovePoint2(), AVW\_RemovePoint3(), AVW\_PointValue, AVW\_PointValueList

AVW\_RemoveUnrenderable - unsets unrenderable pixels

**SYNOPSIS** 

#include "AVW.h"

int AVW\_RemoveUnrenderable(image, threshmax, threshmin, oimage, omap)

AVW\_Image \*image;

double threshmax, threshmin;

AVW\_Image \*oimage; AVW\_ObjectMap \*omap;

# **DESCRIPTION**

*AVW\_RemoveUnrenderable()* processes the *AVW\_Image image*, removing all those pixels which do not meet the current rendering requirements.

Image is an AVW\_Image extracted directly from a volume, most likely from AVW\_GetOrthogonal(), AVW\_GetOblique(), or AVW\_GetCurved.

Threshmax and threshmin indicate which range of pixels to keep.

Oimage is an optional AVW\_Image. It should have been extracted directly from the Volume member of an AVW\_Objectmap, using the same function as was used to extract image above. If this parameter is non-NULL, all voxels in image which are members of disabled objects, will be removed.

Omap is an AVW\_Objectmap which must be provided if oimage is non-NULL.

# **RETURN VALUES**

If successful *AVW\_RemoveUnrenderable()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_RemoveUnrenderable() will fail if:

**ILLPAR** 

Illegal parameter.

**ILLDT** 

Illegal data type.

**SEE ALSO** 

 $AVW\_GetOrthogonal(),\ AVW\_GetOblique(),\ AVW\_GetCurved(),\ AVW\_Image,\ AVW\_ObjectMap$ 

NAME | AVW\_RemoveUnusedObjects - deletes unused object(s) from an object map

**SYNOPSIS** #include "AVW\_ObjectMap.h"

int AVW\_RemoveUnusedObjects(object\_map)

AVW\_ObjectMap \*object\_map;

**DESCRIPTION** AVW\_RemoveUnusedObjects() removes all the unused objects within object\_map. An

unused object can be any object from 0 to object\_map->NumberOfObjects which does not

have at least one corresponding voxel in *object\_map->Volume*;

**RETURN VALUES** If successful *AVW\_RemoveUnusedObjects()* returns the number of objects removed. On

failure it returns -1 and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values

corresponding to the cause of the failure.

**ERRORS** *AVW\_RemoveUnusedObjects()* will fail if the following is true:

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** AVW AddObject(), AVW DeleteObject(), AVW DestroyObjectMap(),

AVW\_CreateObjectMap(), AVW\_GetObject(), AVW\_PutObject() AVW\_LoadObjectMap(),

AVW\_SaveObjectMap(), AVW\_RenderVolume(), AVW\_ObjectMap, AVW\_Object

AVW\_RenderGradients - quick render from gradient information

**SYNOPSIS** 

#include "AVW\_Render.h"

AVW\_RenderedImage \*AVW\_RenderGradients(gradients, param, last\_rendered)

AVW\_Gradients \*gradients;

AVW\_RenderParameters \*param;

AVW\_RenderedImage \*last\_rendered;

# **DESCRIPTION**

AVW\_RenderGradients() returns an AVW\_RenderedImage from gradients and param. Only a very limited portion of the param structure is utilitized. Param->RenderType is required to be AVW\_GRADIENT\_SHADING, and no param->RenderMask may be specified. The only parameters used from the param structure are: RenderWidth, RenderHeight, RenderDepth, and most importantly, Matrix.

This function was designed to return very interactive renderings provided that the limited parameter set used is adequate.

# **RETURN VALUES**

If successful *AVW\_RenderGradients()* returns an *AVW\_RenderedImage*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_RenderGradients() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**ILLPAR** 

Illegal parameter(s).

#### **SEE ALSO**

AVW\_DestroyGradients(), AVW\_ExtractGradients(), AVW\_ProcessZGradients(), AVW\_RenderOblique(), AVW\_RenderVisibleSurface(), AVW\_RenderVolume(), AVW\_RenderedImage, AVW\_RenderedParameters, AVW\_Gradients

AVW\_RenderOblique - renders an oblique image

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW Render.h"

AVW\_RenderedImage \*AVW\_RenderOblique(volume, ow, oh, omat, matrix, interpolate\_flag, shadin AVW\_Volume \*volume;

int ow, oh;

AVW Matrix \*omat;

AVW\_Matrix \*matrix;

int interpolate\_flag;

double shading\_fraction;

AVW\_RenderedImage \*last\_rendered;

# **DESCRIPTION**

*AVW\_RenderOblique()* returns an *AVW\_RenderedImage* showing any plane from any view point.

*Volume* specifies the *AVW\_Volume* the plane is extracted from.

Ow and oh specify the dimension of the extracted plane.

*Omat* is an *AVW\_Matrix* which describes a plane. See *AVW\_GetOblique()* for more information.

Matrix is used to specify any rotation or scale factors.

The *interpolate\_flag* specifies if tri-linear interpolations should be used when generating the image. Setting the *interpolate\_flag* to *AVW\_FALSE* causes *Nearest Neighbor* to be used, which is much faster, but lacks some of the quality.

Last\_rendered is provided as a method of reusing an existing AVW\_RenderedImage. Reuse is possible only if the size and data type of the provided last\_rendered meet the requirements of the function. In this case the pointer to last\_rendered is returned by the function. If not reusable last\_rendered will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_RenderOblique()* returns an *AVW\_RenderedImage*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_RenderOblique() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

ILLPAR

Illegal parameter(s).

#### **SEE ALSO**

AVW\_CubeSections(), AVW\_IntersectingSections(), AVW\_DestroyRenderedImage(), AVW\_MergeRendered(), AVW\_RenderedImage

AVW\_RenderSections - renders intersecting sections

**SYNOPSIS** 

#include "AVW Render.h"

AVW\_RenderedImage \*AVW\_RenderSections(volume, list, mat, interpolate, shading\_fraction, render AVW\_Volume \*volume; /\* description of volume \*/

short \*list;

AVW Matrix \*mat;

int interpolate;

double shading\_fraction;

AVW\_RenderedImage \*rendered;

# **DESCRIPTION**

*AVW\_RenderSections()* returns an *AVW\_RenderedImage* showing one or more transverse, coronal and sagittal sections.

*Volume* specifies the *AVW\_Volume* the sections are extracted from.

List is a zero terminated array of orientation and slice pairs.

Mat is used to specify any rotation or scale factors.

The *interpolate\_flag* specifies if tri-linear interpolations should be used when generating the image. Setting the *interpolate\_flag* to *AVW\_FALSE* causes *Nearest Neighbor* to be used, which is much faster, but lacks some of the quality.

Last\_rendered is provided as a method of reusing an existing AVW\_RenderedImage. Reuse is possible only if the size and data type of the provided last\_rendered meet the requirements of the function. In this case the pointer to last\_rendered is returned by the function. If not reusable last\_rendered will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_RenderSections()* returns an *AVW\_RenderedImage*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_RenderSections() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**ILLPAR** 

Illegal parameter(s).

# **SEE ALSO**

 $AVW\_IntersectingSections(),\ AVW\_CubeSections(),\ AVW\_RenderOblique(),\ AVW\_DestroyRenderedImage(),\ AVW\_RenderedImage$ 

AVW\_RenderVisibleSurface - renders a visible surface

**SYNOPSIS** 

#include "AVW\_Render.h"

int AVW\_RenderVisibleSurface(surface, param, last\_rendered)

AVW\_VisibleSurface \*surface; AVW\_RenderParameters \*param; AVW\_RenderedImage \*last\_rendered;

**DESCRIPTION** 

AVW\_RenderVisibleSurface() quickly re-renders the *surface* points at new locations as specified by *param*. The results are placed in *last\_rendered*, which is the structure which resulted in a previous call to AVW\_RenderVolume() or AVW\_RenderVisibleSurface().

Only the *Matrix* portion of the *AVW\_RenderParameters* structure will have a significant effect on the output.

This function was designed to return very interactive renderings provided that the limited parameter set used is adequate.

**RETURN VALUES** 

If successful *AVW\_RenderVisibleSurface()* returns an *AVW\_RenderedImage*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_RenderVisibleSurface() will fail if:

**BADMAL** 

Malloc Failed. Unable to increase structure size.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_DestroyVisibleSurface(), AVW\_ExtractVisibleSurface(), AVW\_FindSurfaceArea(), AVW\_FindSurfaceDistance(), AVW\_FindSurfacePoints(), AVW\_RenderGradients(), AVW\_RenderOblique(), AVW\_RenderVolume(), AVW\_RenderedImage, AVW\_RenderedParameters, AVW\_VisibleSurface

AVW\_RenderVolume - renders a volume by ray casting

**SYNOPSIS** 

#include "AVW Render.h"

AVW\_RenderedImage \*AVW\_RenderVolume(param, last\_rendered)

AVW\_RenderParameters \*param;

AVW\_RenderedImage \*last\_rendered;

# **DESCRIPTION**

AVW\_RenderVolume() renders a volume by ray casting based on the parameters set in param. Elements of the AVW\_RenderParameters structure returned by AVW\_InitializeRenderParameters() and used by AVW\_RenderVolume() are:

param->Type specifies the type of ray casting preformed. Supported values include:

AVW\_DEPTH\_SHADING – The value of each output pixel is a function of depth only. The depth of the first voxel found along the ray path is used to determine the brightness of that pixel. Closer voxels will appear brighter than distant voxels. This output image may be further enhanced by AVW\_ProcessZGradients().

AVW\_GRADIENT\_SHADING – The gray scale gradient vector is computed using a 3D neighborhood about the surface voxel. The value projected at each output location is the dot product of the gradient vector and an independently specified light source vector. This simulates the appearance of a reflective surface under uniform-field illumination.

*AVW\_VOLUME\_COMPOSITING* – The volumetric compositing algorithm integrates the gradient-shaded value of all voxels along the ray path. The contribution of each gradient-shaded voxel value is weighted by an opacity function described in the *AVW\_CompositeInfo* structure. Voxel intensity is used to determined the voxels color and opacity contribution during the ray casting.

*AVW\_MAX\_INTENSITY\_PROJECTION* – The maximum voxel intensity along the ray path is used.

*AVW\_SUMMED\_VOXEL\_PROJECTION* – The average of all voxels along the ray path is used.

*AVW\_SURFACE\_PROJECTION* – Once a voxel within the threshold limits is detected, the average of the next N voxels is computed.

AVW\_TRANSPARENCY\_SHADING — Available only when an AVW\_ObjectMap has been specified, this type produces a 24-bit true color projections of all the surface gradients along the ray path. Opacity parameters may be specified for each object controlling the transparency.

AVW\_DELETE\_VOXELS – Not really a rendering type, but causes the ray casting algorithm to delete (or convert to a specified value) voxels along the ray path. See the *param->DeleteDepth* and *param->DeleteValue* parameters for more information.

*param->ThresholdMinimum* and *param->ThresholdMaximum* specify the range of acceptable voxel values. Voxels outside the specified range are ignored.

param->ClipLowX, param->ClipLowY, param->ClipLowZ, param->ClipHighX, param->ClipHighY, and param->ClipHighZ specify the portion of the AVW\_Volume to render.

*param->ClipPlaneMinimum* and *param->ClipPlaneMaximum* specify the starting and ending depths for the ray casting process.

*param->ClipShading* specifies the type of shading that is used when the ray casting process begins at a voxel which is within the threshold range (and object enabled). The value is only used when the render *Type* is set to *AVW\_GRADIENT\_SHADING*. Possible values are:

*AVW\_CLIP\_SHADED* – A value based on only depth is used to create the shaded pixel.

AVW\_CLIP\_ACTUAL – The grayscale value of the intersected voxel is used.

*AVW\_CLIP\_REMOVE\_AND\_RENDER* – The voxel along the raypath, just before the intersected voxel, is temporarily set to the input volume minimum intensity value and the gradient shading is calculated.

*AVW\_CLIP\_RENDER\_AS\_IS* – The gradient shading is calculated for the voxel without any attempt to correct for the fact that the shading will most likely be unpredictable because no surface will be detected..

*param->RenderWidth, param->RenderHeight,* and *param->RenderDepth* specify the size of the rendered space. By default these values are set to the maximum of the X, Y, or Z input dimension.

param->MaximumPixelValue and param->MinimumPixelValue specify the range of possible output values for the reflectance renderings. Transmission renderings use the maximum and minimum values with the AVW\_Volume as the output range.

*param->SurfaceThickness* specifies the maximum thickness for the *AVW\_SURFACE\_PROJECTION* rendering type.

*param->SurfaceSkip* specify the number of voxels to skip before summing begins for the *AVW\_SURFACE\_PROJECTION* rendering type.

param->MIP\_Weight specify the weighting options used during a AVW\_SURFACE\_PROJECTION. Options include: AVW\_NO\_WEIGHTING, AVW\_WEIGHT\_BEFORE, and AVW\_WEIGHT\_AFTER. AVW\_WEIGHT\_BEFORE indicates that before a voxel is checked to see if it is the maximum value, a weighting factor is applied. The weighting factor is determined by dividing the length of the ray left to cast, by it's total length. AVW\_WEIGHT\_AFTER determines the maximum voxel along the entire ray casting path and then applies the weightinh factor described above.

param->Matrix is an AVW\_Matrix which specifies the rotation and translation transformation applied to the AVW\_Volume during the rendering process. Scale could also be specified as part of the matrix, but it's recommended that the ScaleX, ScaleY, and ScaleZ parameters be used for Scale.

*param->LightMatrix* specifies the vector of the light source used in reflective renderings.

param->RenderMask is an AVW\_Image which specifies a specific area to be rerendered. NULL is the default, specifing the entire rendering space is rendered each time AVW\_RenderVolume is called. Only AVW\_Images with a data type of AVW\_UNSIGNED\_CHAR are supported. This AVW\_Image should always have

dimensions equal to param->RenderWidth and param->RenderedHeight.

*param->MaskValue* specifies the pixel value within the *param->RenderMask* which indicates rendering should occur for this output pixel.

*param->DeleteDepth* specifies the number of voxels along the ray path which are deleted (changed to *param->DeleteValue*). The following settings are valid when the *AVW\_DELETE\_VOXELS* rendering type is specified:

*AVW\_DELETE\_ALL\_THE\_WAY* – All voxels along the ray path are changed to the value to specified by *param->DeleteValue*.

AVW\_DELETE\_SINGLE\_LAYER – Once a value within the theshold limits is detected, all voxels with values within the threshold range are deleted until a voxel outside the threshold range is detected, at which time deleting stops.

AVW\_DELETE\_SINGLE\_VOXEL – The first voxel along the ray path which is within the threshold range is deleted.

AVW\_DEFINE\_ALL\_THE\_WAY – All object map locations along the ray path are changed to the value to specified by *param->DeleteValue*.

AVW\_DEFINE\_SINGLE\_LAYER – Once a value within the theshold range is detected, all voxels with values within the threshold limits are redfined until a voxel outside the threshold range is detected, at which time deleting stops.

AVW\_DEFINE\_SINGLE\_VOXEL – The first object map location along the ray path which is within the threshold limits is redefined.

*NOTE:* A 3x3x3 region surrounding a voxel is deleted instead of just a single voxel, this compensates for spaces which may occur between the ray paths.

*param->DeleteValue* specifies the value each voxel is changed to, when the *AVW\_DELETE\_VOXELS* rendering type is specified.

*param->ScaleX*, *param->ScaleY*, and *param->ScaleZ* specify the scale factors to be applied to the inputs during the rendering process.

param->PerspectiveType specifies the type of rendering to be performed. AVW\_PERSPECTIVE\_INT renders the image using the voxels without interpolation, possibly resulting in "blocky" renderings. If param->PerspectiveType is set to AVW\_PERSPECTIVE\_FLOAT, the rendered image is generated using an on the fly intepolation rendering algorithm. If param->PerspectiveType is set to AVW\_PERSPECTIVE\_OFF, parallel rendering is performed. For perspective rendering, the render matrix is interperted as a viewing direction for the camera model, however the parallel rendering conventions are followed, i.e. the matrix is left handed, and the identity matrix provides a view along the positive Z axis with X increasing to the right and Y increasing in the vertical direction. Perspective rendering does not support scaling at this time. For anisotropic data, rescaling during loading is the best option.

*param->EyePosition* specifies the location of the camera model used to generate the rendering. This parameter is only used when *param->PerspectiveType* is set to  $AVW\_PERSPECTIVE\_FLOAT$  or  $AVW\_PERSPECTIVE\_INT$ . The X, Y, and Z coordinates of the  $AVW\_FPoint3$  structure refer to the position of the camera relative to the center of the volume, thus a position of (0,0,0) in a particular volume is located at voxel (Width / 2, Height / 2, Depth / 2).

param->XFieldOfViewAngle and param->YFieldOfViewAngle specify the field of view (FOV) angle of the camera model used to generate the image. Increasing the FOV results in a zoom out effect, if the position remains the same. Decreasing the FOV results in a zoom in effect.

param->SpecularFactor specifies the ratio of gradient shading to specular shading. If param->SpecularFactor is set to 0, the rendering will be shaded entirely using gradient shading with no performance penalty. If param->SpecularFactor is set to .1, the

param->SpecularExponent specifies the degree of fall-off for specular shading. High values (about 10) result in very small specular highlights, while small values (about 1 or 2) result in diffuse highlights.

param->CompositeInfo specifies a pointer to a structure which contains compositing information. This must contain a valid pointer when the param->Type is set to AVW\_VOLUME\_COMPOSITING. See AVW\_CompositeInfo for more information.

param->BackgroundColor and param->BackgroundValue are used to specify the background color or value. The rendering type, input volumes datatype, and whether an object map is loaded determines which value is used. If the output is a grayscale image, param->BackgroundValue is used. If the output is a color image, then param->BackgroundColor will be used. Background Color is a packed RGB value which can be produced with the *AVW\_RGB* macro.

BackgroundColor and BackgroundValue are used to specify the background color or value. The rendering type, input volumes datatype, and whether an object map is loaded determines which value is used. If the output is a grayscale image, BackgroundValue is used. If the output is a color image, then BackgroundColor will be used. Background Color is a packed RGB value which can be produced with the AVW\_RGB macro.

RenderMode is normally set to AVW\_RENDER\_NORMAL, but when set to AVW\_PREPARE\_FOR\_MOVE, the AVW\_RenderVolume() function will process the object specified in the *InteractiveObject* seperately and return the "visible surface" in the AVW\_RenderedImage member called InteractiveSurface. This results in the input to AVW\_RenderVisibleSurface() which produces output which can be combined using AVW\_MergeRendered() with the rendering returned at the time the InteractiveSurface was produced. This entire process allows an interface to be build to interactively move and rotate objects. RenderMode can be set to AVW\_RERENDER\_MOVED, at the completion of the object transformation to rerender any missing data.

param->RenderMode is normally set to AVW\_RENDER\_NORMAL, but when set to AVW\_PREPARE\_FOR\_MOVE, the AVW\_RenderVolume() function will process the object specified in the param->InteractiveObject seperately and return the "visible surface" in the AVW\_RenderedImage member called rendered->InteractiveSurface. This results in the input to AVW\_RenderVisibleSurface() which produces output which can be combined using AVW\_MergeRendered() with the rendering returned at the time the rendered->InteractiveSurface was produced. This entire process allows an interface to be build to interactively move and rotate objects. param->RenderMode can be set to AVW\_RERENDER\_MOVED, at the completion of the object transformation to rerender any missing data.

param->Internal contains parameter which are used internally within the rendering functions. CHANGING OF INTERNAL PARAMETERS IS DISCOURAGED!

Elements of the AVW\_RenderedImage structure returned by AVW\_RenderVolume() are:

*rendered->Width, rendered->Height,* and *rendered->Depth* contains the size of the output rendered space.

rendered->MaximumPixelValue and rendered->MinimumPixelValue contain the range of the values within the output data.

rendered->Image contains the output image.

*rendered->ZBuffer* contains an internal buffer indicating the position of all invisible faces.

rendered->PBuffer contains a buffer which indicates the depth of each voxel.

*rendered->Volume* contains a pointer to the *AVW\_Volume* used to generate the rendered image.

*rendered->ObjectMap* contains a pointer to the *AVW\_ObjectMap* used to generate the rendered image.

*rendered->Matrix* contains the *AVW\_Matrix* necessary to convert 3D points into the rendered space.

*rendered->InverseMatrix* contains the *AVW\_Matrix* necessary to convert points in the rendered space back into the *AVW\_Volume* space.

*rendered->PerspectiveType* indicates if one of the perspective types was used to generate this rendered image.

rendered->EyePosition indicates the eye position of the last perspective rendering.

*rendered->XFieldOfViewAngle* and rendered->YFieldOfViewAngle indicate the field of view for the last perspective rendering.

rendered->MergedMap is normally NULL, but after a call to AVW\_MergeRendered() it is filled with information about where pixels came from and how they were generated.

rendered->InteractiveSurface is normally NULL. It's filled only when AVW\_RenderVolume() is used with the param->RenderMode set to AVW\_PREPARE\_FOR\_MOVE or AVW\_RERENDER\_MOVED.

Last\_rendered is provided as a method of reusing an existing AVW\_RenderedImage. Reuse is possible only if the size and data type of the provided last\_rendered meet the requirements of the function. In this case the pointer to last\_rendered is returned by the function. If not reusable last\_rendered will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_RenderVolume()* returns a pointer to a *AVW\_RenderedImage* structure. This structure contains the output of the rendering process. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_RenderVolume() will fail if one or more of the following is true:

**BADMAL** 

Unable to allocate sufficient memory.

**CFLSZ** 

The AVW\_Volume and AVW\_ObjectMap have conflicting dimensions.

**ILLPAR** 

Illegal parameter(s).

# **SEE ALSO**

AVW\_DestroyRenderedImage(), AVW\_InitializeRenderParameters(), AVW\_RenderGradients(), AVW\_RenderOblique(), AVW\_RenderVisibleSurface(), AVW\_RenderedImage, AVW\_RenderParameters, AVW\_CompositeInfo

AVW\_RenderableVolume - thresholds a volume

**SYNOPSIS** 

#include "AVW.h"

#include "AVW\_ObjectMap.h"

AVW\_Volume \*AVW\_RenderableVolume(in\_volume, omap, tmax, tmin, out\_volume)

AVW\_Volume \*in\_volume;

AVW\_ObjectMap \*omap;

double tmax, tmin;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_RenderableVolume() processes an input volume and object map, returning a volume which contains 1s for all voxels in enabled objects and within the threshold range defined by tmax and tmin. 0s are returned for all other voxels.

The returned AVW\_Volume is of the data type AVW\_UNSIGNED\_CHAR.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_RenderableVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_RenderableVolume() will fail if the following is true:

**ILLDT** 

Illegal data type.

**SEE ALSO** 

AVW\_ThresholdVolume(), AVW\_Objectmap, AVW\_Volume

**NAME** AVW\_ResetIntensityStats – resets intensity statistics

**SYNOPSIS** #include "AVW\_Measure.h"

int AVW\_ResetIntensityStats( stats)

AVW\_IntensityStats \*stats;

**DESCRIPTION** *AVW\_ResetIntensityStats()* sets all of the members of *stats* to zero.

**RETURN VALUES** If successful AVW\_ComputeImageIntensityStats() returns AVW\_SUCCESS.

SEE ALSO AVW\_ComputeVolumeIntensityStats() AVW\_ComputeImageIntensityStats(), AVW\_IntensityStats

AVW\_ResizeImage - resizes an image

# **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_ResizeImage(in\_image, width, height, interpolate, out\_image)

AVW\_Image \*in\_image;

int width;

int height;

int interpolate;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_ResizeImage() generates an AVW\_Image, out\_image, of the size specified by the width and height parameters.

*Interpolate* determines the method of interpolation to use. Choose from:

AVW\_RESIZE\_NN\_ID - Input driven nearest neighbor

AVW\_RESIZE\_LINEAR\_ID - Input driven tri-linear

AVW\_RESIZE\_NN\_OD - Output driven nearest neighbor

AVW\_RESIZE\_LINEAR\_OD - Output driven tri-linear

AVW\_RESIZE\_CUBIC\_SPLINE\_INTERPOLATE - Cubic Spline

AVW\_RESIZE\_WINDOWED\_SINC\_INTERPOLATE - Windowed Sinc

AVW\_ResizeImage() uses highly optimized code when the specified width and height values are one of the following scale factors: 25%, 33%, 50%, 100%, 200%, 300%, and 400%. Both width and height must have the same scale factor for the optimized code to be used. The speed advantages vary depending on in\_image and out\_image sizes but 10 to 20 times faster results can be expected.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_ResizeImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

### **ERRORS**

AVW\_ResizeImage() will fail if one or more of the following are true:

**ILLDT** 

Input data type not supported by this function.

**BADMAL** 

Unable to allocate sufficient memory to complete request.

# **SEE ALSO**

 $AVW\_CropImage(),\ AVW\_GetSubImage(),\ AVW\_GetSubImageWithIncrements(),\\ AVW\_PadImage(),\ AVW\_PutSubImage(),\ AVW\_ResizeVolume(),\ AVW\_TransformImage(),\\ AVW\_Image$ 

AVW\_ResizeSubImage - resizes an image

**SYNOPSIS** 

#include "AVW.h"

int AVW\_ResizeSubImage(in\_image, in\_rect2, interpolate\_type, out\_image, out\_rect2)

AVW\_Image \*in\_image;

AVW\_Rect2 \*in\_rect2;

int interpolate\_type;

AVW\_Image \*out\_image;

AVW\_Rect2 \*out\_rect2;

# **DESCRIPTION**

AVW\_ResizeSubImage() resizes a rectanglular area specified in <code>in\_rect2</code> with <code>in\_image</code>. The output size and position within <code>out\_image</code> is specified in <code>Interpolate\_type</code> specifies the type of <code>interpolation</code>

AVW\_RESIZE\_NN\_ID specifies a nearest neighbor input driven algorithm.

AVW\_RESIZE\_LINEAR\_ID specifies a linear input driven algorithm.

AVW\_RESIZE\_NN\_OD specifies a nearest neighbor output driven algorithm.

AVW\_RESIZE\_LINEAR\_OD specifies a linear output driven algorithm.

AVW\_RESIZE\_CUBIC\_SPLINE\_INTERPOLATE specifies a cubic spline algorithm.

AVW\_RESIZE\_WINDOWED\_SINC\_INTERPOLATE specifies a windowed sinc algorithm.

# **ERRORS**

AVW\_ResizeSubImage() will fail if one or more of the following are true:

**ILLDT** 

Input data type not supported by this function.

**BADMAL** 

Unable to allocate sufficient memory to complete request.

# **SEE ALSO**

AVW\_GetSubImage(), AVW\_PutSubImage(), AVW\_ResizeImage(), AVW\_Image

AVW\_ResizeSubVolume - resizes a volume

**SYNOPSIS** 

#include "AVW.h"

int AVW\_ResizeSubVolume(in\_volume, in\_rect3, interpolate\_type, out\_volume, out \_rect3)

AVW\_Volume \*in\_volume;

AVW Rect3 \*in rect3;

int interpolate\_type;

AVW\_Volume \*out\_volume;

AVW\_Rect3 \*out\_rect3;

# **DESCRIPTION**

AVW\_ResizeSubVolume() resizes a rectanglular area specified in *in\_rect2* with *in\_image*. The output size and position within *out\_image* is specified in *Interpolate\_type specifies the type of interpolation* 

AVW\_RESIZE\_NN\_ID specifies a nearest neighbor input driven algorithm.

AVW\_RESIZE\_LINEAR\_ID specifies a linear input driven algorithm.

AVW\_RESIZE\_NN\_OD specifies a nearest neighbor output driven algorithm.

AVW\_RESIZE\_LINEAR\_OD specifies a linear output driven algorithm.

AVW\_RESIZE\_CUBIC\_SPLINE\_INTERPOLATE specifies a cubic spline algorithm.

AVW\_RESIZE\_WINDOWED\_SINC\_INTERPOLATE specifies a windowed sinc algorithm.

# **RETURN VALUES**

If successful  $AVW\_ResizeSubVolume()$  returns an  $AVW\_Volume$ . On failure it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_ResizeSubVolume() will fail if one or more of the following are true:

**ILLDT** 

Input data type not supported by this function.

**BADMAL** 

Unable to allocate sufficient memory to complete request.

#### **SEE ALSO**

AVW\_ResizeVolume(), AVW\_Volume

AVW\_ResizeVolume - resizes a volume

#### **SYNOPSIS**

#include "AVW.h"

AVW\_Volume \*AVW\_ResizeVolume(in\_volume, out\_width, out\_height, out\_slices, interpolate, out\_volume)

AVW\_Volume \*in\_volume;

int out\_width, out\_height, out\_slices;

int interpolate;

AVW\_Volume \*out\_volume;

# DESCRIPTION

*AVW\_ResizeVolume()* performs trilinear interpolation to resize a volume to a specified size.

*Interpolate* determines the method of interpolation to use. Choose from:

AVW\_RESIZE\_NN\_ID - Input driven nearest neighbor

AVW\_RESIZE\_LINEAR\_ID - Input driven tri-linear

AVW\_RESIZE\_NN\_OD - Output driven nearest neighbor

AVW\_RESIZE\_LINEAR\_OD - Output driven tri-linear

AVW\_RESIZE\_CUBIC\_SPLINE\_INTERPOLATE - Cubic Spline

AVW\_RESIZE\_WINDOWED\_SINC\_INTERPOLATE - Windowed Sinc

*In\_volume* is the input volume.

*Out\_width* indicates the desired output width.

Out\_height indicates the desired output height.

Out\_slices indicates the desired number of output slices.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful,  $AVW\_ResizeVolume()$  returns an  $AVW\_Volume$ . On failure it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_ResizeVolume() will fail if one or more of the following are true:

**ILLPAR** 

Illegal parameter.

**BADMAL** 

Unable to allocate enough memory.

**ILLDT** 

Unsupported data type.

**SEE ALSO** 

 $AVW\_GetSubVolume(),\ AVW\_PadVolume(),\ AVW\_PutSubVolume(),\ AVW\_ResizeImage(),\ AVW\_ResizeVolumeSliceBySlice(),\ AVW\_ResizeVolumeUsingShapeInt(),\ AVW\_TransformVolume(),\ AVW\_Volume$ 

AVW\_ResizeVolumeSliceBySlice - resizes a volume slice by slice

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_ResizeVolumeSliceBySlice(in\_image, in\_count, in\_slices, out\_width, out\_height, out\_slices,

out\_count, interpolate, out\_image)

AVW Image \*in image;

int in\_count, in\_slices;

int out\_width, out\_height, out\_slices;

int \*out\_count;

int interpolate;

AVW\_Image \*out\_image;

# **DESCRIPTION**

AVW\_ResizeVolumeSliceBySlice() performs a resize operation one slice at a time. This function is called one or more times with each slice in an input volume. It may or may not return an output slice, depending on whether enough input data was available to calculate the resized output slice.

*Interpolate* determines the method of interpolation to use. Choose from:

AVW\_RESIZE\_NN\_ID - Input driven nearest neighbor

AVW\_RESIZE\_LINEAR\_ID - Input driven tri-linear

AVW\_RESIZE\_NN\_OD - Output driven nearest neighbor

AVW\_RESIZE\_LINEAR\_OD - Output driven tri-linear

AVW\_RESIZE\_CUBIC\_SPLINE\_INTERPOLATE - Cubic Spline

AVW\_RESIZE\_WINDOWED\_SINC\_INTERPOLATE - Windowed Sinc

*In\_image* is the input slice.

*In\_count* indicates which slice from the input volume is being passed in. Legal values are 1 thru *in slices*.

*In\_slices* is the total number of slices in the input volume.

Out\_width indicates the desired output width.

Out\_height indicates the desired output height.

Out\_slices indicates the desired number of output slices.

Out\_count indicates the output slice position within the output volume. A value of 0 (zero) indicates no output slice was being returned. A positive value indicates a output slice was returned and AVW\_ResizeVolumeSliceBySlice should be called again with in\_count set to a value of 0 (zero) and all other parameters the same, until a 0 (zero) out\_count value is returned.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful,  $AVW\_ResizeVolumeSliceBySlice()$  returns an  $AVW\_Image$ . This returned image is only used if  $out\_count$  is a positive non-zero value. On failure, it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ResizeVolumeSliceBySlice() will fail if one or more of the following are true:

**ILLPAR** 

Illegal parameter.

**BADMAL** 

Unable to allocate enough memory.

**ILLDT** 

Unsupported data type.

**SEE ALSO** 

AVW\_GetSubVolume(), AVW\_PadVolume(), AVW\_PutSubVolume(), AVW\_ResizeImage(), AVW\_ResizeVolume(), AVW\_ResizeVolumeUsingShapeInt(), AVW\_Image, AVW\_Volume

AVW\_ResizeVolumeUsingShapeInt - performs binary shape based interpolation

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_ResizeVolumeUsingShapeInt(in\_volume, out\_volume)

 $AVW\_Volume * in\_volume;$ 

AVW\_Volume \*out\_volume;

# **DESCRIPTION**

AVW\_ResizeVolumeUsingShapeInt() creates a binary isotropic volume from in\_volume by doing shape based interpolation. The VoxelSize and SliceThickness strings and floating point values must be stored in the Info string of the AVW\_Volume structure for in\_volume. The VoxelSize must be less than the SliceThickness. AVW\_ResizeVolumeUsingShapeInt() only works on AVW\_UNSIGNED\_CHAR data type.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meets the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_ResizeVolumeUsingShapeInt()* returns a binary interpolated *AVW\_Volume*. On failure it returns *NULL* and sets the *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_ResizeVolumeUsingShapeInt() will fail if one or more of the following are true:

**CFLSZ** 

Conflicting input/output size or type.

**ILLDT** 

Illegal data type.

**NOMATCH** 

Info string is missing required values.

**SEE ALSO** 

 $AVW\_GetSubVolume(),\ AVW\_PadVolume(),\ AVW\_PutSubVolume(),\ AVW\_ResizeImage(),\ AVW\_ResizeVolume(),\ AVW\_ResizeVolumeSliceBySlice(),\ AVW\_PutNumericInfo(),\ AVW\_Volume$ 

**NAME** AVW\_ReverseBits – reverses bits

**SYNOPSIS** #include <stdio.h> #include "AVW.h"

AVW\_ReverseBits(in, out, bytes)

void \*in, \*out;
int bytes;

**DESCRIPTION** *ReverseBits()* reverses the bit order of *in* over a specified number of *bytes* and returns the

results in out.

SEE ALSO | AVW\_QuadSwapImage(), AVW\_READSWAP(), AVW\_SwapBlock(), AVW\_SwapDouble(),

AVW\_SwapFloat(), AVW\_SwapImage(), AVW\_SwapInt(), AVW\_SwapLong(),

AVW\_SwapShort(), AVW\_WRITESWAP(), fread(), fwrite(), swab()

AVW\_Rotate90Image - quick 90 degree rotation of an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_Rotate90Image(in\_image, direction, out\_image)

AVW\_Image \*in\_image;

int direction;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_Rotate90Image() rotates in\_image by 90 degrees in the direction indicated by direction

If *direction* is zero, positive, or *AVW\_COUNTERCLOCKWISE*, the image will be rotated positive 90 degrees (counterclockwise). If *direction* is less than 0 or *AVW\_CLOCKWISE*, the image will be rotated negative 90 degrees (clockwise).

The returned image will have width and height equal to *in\_image* height and width, respectively.

**RETURN VALUES** 

If successful *AVW\_Rotate90Image()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_Rotate90Image() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

ILLDT

Datatype is unsupported.

**SEE ALSO** 

AVW\_FlipImage(), AVW\_ShiftImage(), AVW\_TransformImage(), AVW\_Image

AVW\_RotateMatrix - rotates a transformation matrix

**SYNOPSIS** 

#include "AVW.h"

AVW\_Matrix \*AVW\_RotateMatrix(in\_matrix, xangle, yangle, zangle, out\_matrix)

AVW\_Matrix \*in\_matrix;

double xangle; double yangle;

double zangle;

AVW\_Matrix \*out\_matrix;

**DESCRIPTION** 

AVW\_RotateMatrix() applies the rotation specified by xangle, yangle, and zangle (specified in degress) to the AVW\_Matrix, mat. The rotation is applied to the X axis first, then the Y axis, and finally the Z axis. Out\_matrix is provided as a method of reusing an existing

AVW\_Matrix. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful AVW\_RotateMatrix() returns an AVW\_Matrix. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause

of the failure.

**SEE ALSO** 

AVW\_CopyMatrix(), AVW\_CreateMatrix(), AVW\_InvertMatrix(), AVW\_MakeMatrixFrom3Points(), AVW\_MakeMatrixFromAxis() AVW\_MatrixAngles() AVW\_MirrorMatrix(), AVW\_MultiplyMatrix(), AVW\_SetIdentityMatrix(), AVW\_ScaleMatrix(), AVW\_TranslateMatrix(), AVW\_Matrix

**NAME** AVW\_RotatePointList2 – rotates the points in a point list

SYNOPSIS #include "AVW.h"

int AVW\_RotatePointList2(ptlist, angle)

AVW\_PointList2 \*ptlist;

double angle;

**DESCRIPTION** AVW\_RotatePointList2() applies the rotation specified by angle in degrees to the

AVW\_PointList2, ptlist.

**RETURN VALUES** If successful *AVW\_RotatePointList2()* returns *AVW\_SUCCESS*. On failure *AVW\_FAIL* is

returned.

 $\textbf{SEE ALSO} \qquad AVW\_AddPoint2(), \ AVW\_CreatePointList2(), \ AVW\_DestroyPointList2(), \ AVW\_DestroyPoi$ 

AVW\_ScalePointList2(), AVW\_TranslatePointList2(), AVW\_PointList2

AVW\_RoundImage - round values in a float image to nearest integers

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_RoundImage(in\_image, datatype, out\_image)

AVW\_Image \*in\_image;

int datatype;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_RoundImage() converts in\_image, which must have a AVW\_FLOAT DataType, to the specified datatype. All values are rounded to the nearest integer. Acceptable values for datatype, as defined in AVW.h, are: AVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_INT, AVW\_SIGNED\_INT, AVW\_FLOAT, AVW\_COMPLEX, AVW\_COLOR.

AVW\_RoundImage()

If the volume is converted to a data type which can hold less information, or information in a different range, the data is clipped at the maximum and minimum values possible for the new data type. No intensity scaling is attempted during the conversion process.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_RoundImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

*AVW\_RoundImage()* will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for output volume.

**ILLDT** 

Unknown or unsupported input or output datatype.

**SEE ALSO** 

AVW\_RoundVolume(), AVW\_ConvertImage(), AVW\_Image

AVW\_RoundVolume - round values in a float volume to nearest integers

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_RoundVolume(in\_volume, datatype, out\_volume)

AVW\_Volume \*in\_volume;

int datatype;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_RoundVolume() converts in\_volume which must have a AVW\_FLOAT DataType, to the specified datatype. All values are rounded to the nearest integer. Acceptable values for datatype, as defined in AVW.h, are: AVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_INT, AVW\_SIGNED\_INT, AVW\_FLOAT, AVW\_COMPLEX, AVW\_COLOR.

If the volume is convert to a data type which can hold less information, or information in a different range, the data is clipped at the maximum and minimum values possible for the new data type. No intensity scaling is attempted during the conversion process.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_RoundVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_RoundVolume() will fail if one or more of the following are true:

BADMAL

Malloc Failed. Unable to allocate memory for output volume.

**ILLDT** 

Unknown or unsupported input or output datatype.

**SEE ALSO** 

AVW\_RoundImage(), AVW\_ConvertVolume(), AVW\_Volume

AVW\_SaveColormap - saves a color map

**SYNOPSIS** 

#include "AVW.h"

int AVW\_SaveColormap(file, colormap)

char \*filename;

AVW\_Colormap \*colormap;

**DESCRIPTION** 

AVW\_SaveColormap() saves the contents of the *colormap* to the disk file specified by *filename*.

*AVW* colormap files usually end in *.lkup.* Colormap values are stored as ASCII strings representing values from 0 to 255. The red value for the first cell, if followed by the green value for the first cell, followed by the blue value for the first cell. This order is followed for each colorcell defined in the file.

**RETURN VALUES** 

If successful *AVW\_SaveColormap()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_SaveColormap() will fail if one or more of the following is true:

**BADOPEN** 

Could open file for reading or writing.

**BADWRITE** 

Error occurred while writing file.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_LoadColormap(), AVW\_CreateColormap(), AVW\_DestroyColormap(), AVW\_Colormap

**NAME** AVW\_SaveCompositeInfo – saves compositing information

SYNOPSIS #include "AVW\_CompositeInfo.h"

int AVW\_SaveCompositeInfo(file, cinfo)

char \*filename;

AVW\_CompositeInfo \*cinfo;

**DESCRIPTION** | *AVW\_SaveCompositeInfo()* saves the contents of *cinfo* to the disk file specified by *filename*.

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**RETURN VALUES** If successful *AVW\_SaveCompositeInfo()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding

to the cause of the failure.

**ERRORS** | *AVW\_SaveCompositeInfo()* will fail if one or more of the following is true:

**BADOPEN** 

Could open file for reading or writing.

**BADWRITE** 

Error occurred while writing file.

**ILLPAR** 

Illegal parameter(s).

SEE ALSO | AVW\_CreateCompositeInfo(), AVW\_DestroyCompositeInfo(), AVW\_LoadCompositeInfo(), AVW\_CompositeInfo()

**NAME** AVW\_SaveContourSurface – writes a contour surface to a file

SYNOPSIS #include "AVW\_Model.h"

int AVW\_SaveContourSurface(srfc, path, rp\_param)

AVW\_ContourSurface \*srfc;

char \*path;

AVW\_RPParam \*rp\_param;

**DESCRIPTION** *AVW\_SaveContourSurface()* writes the contour surface, *srfc*, to the file given by *path*.

rp\_param is used to determine which output format is to be used and how blank slices are

to be managed. Supported output formats are: AVW\_HPGL\_SURFACE,

AVW\_POGO\_SURFACE, AVW\_SLC\_SURFACE, and AVW\_SSD\_ASCII\_SURFACE.

**RETURN VALUES** AVW\_SaveContourSurface() returns AVW\_SUCCESS if successful. On failure, AVW\_FAIL

will be returned and AVW\_ErrorNumber and AVW\_ErrorMessage will be set to values

corresponding to the cause of the failure.

**ERRORS** | *AVW\_SaveContourSurface()* will fail if one of the following is true:

**BDWRTE** 

File write failed.

**BDOPEN** 

Unable to open file.

SEE ALSO | AVW\_DestroyContourSurface(), AVW\_SliceVolume(), AVW\_ContourSurface, AVW\_RPParam

AVW\_SaveObjectMap - saves an object map

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW\_ObjectMap.h"

int AVW\_SaveObjectMap(file, object\_map)

char \*filename;

AVW\_ObjectMap \*object\_map;

**DESCRIPTION** 

AVW\_SaveObjectMap() saves the contents of the object\_map to the disk file specified by filename.

**RETURN VALUES** 

If successful *AVW\_SaveObjectMap()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_SaveObjectMap() will fail if one or more of the following is true:

**BADOPEN** 

Could open file for reading or writing.

**BADWRITE** 

Error occurred while writing file.

**ILLPAR** 

Illegal parameter(s).

**SEE ALSO** 

AVW\_AddObject(), AVW\_ComputeObjectStats(), AVW\_CopyObjectMap(), AVW\_CreateObjectMap(), AVW\_DeleteObject(), AVW\_DestroyObjectMap(), AVW\_GetObject(), AVW\_LoadObjectMap(), AVW\_ObjectScaleImage(), AVW\_PutObject(), AVW\_RenderVolume(), AVW\_ObjectMap

AVW\_SaveTiledSurface - writes an ordered surface to a file

**SYNOPSIS** 

#include "AVW\_Model.h"

int AVW\_SaveTiledSurface(srfc, path, format)

AVW\_TiledSurface \*srfc;

char \*path;
int format;

**DESCRIPTION** 

AVW\_SaveTiledSurface() writes the ordered surface in *srfc* to the file given by *path. Format* is used to determine which output format is to be used. Supported output formats are: AVW\_VRIO\_SURFACE, AVW\_INVENTOR\_SURFACE, AVW\_VRML\_SURFACE, AVW\_DXF\_SURFACE, AVW\_OBJ\_SURFACE, AVW\_POLY\_SURFACE, and AVW\_STL\_SURFACE.

**RETURN VALUES** 

AVW\_SaveTiledSurface() returns AVW\_SUCCESS if successful. On failure, AVW\_FAIL will be returned and AVW\_ErrorNumber and AVW\_ErrorMessage will be set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_SaveTiledSurface() will fail if one of the following is true:

**BDWRTE** 

File write failed.

**BDOPEN** 

Unable to open file.

**SEE ALSO** 

AVW\_DestroyTiledSurface(), AVW\_LoadTiledSurface(), AVW\_DrawTiledSurface(), AVW\_TileVolume(), AVW\_VolumeToSLC(), AVW\_TiledSurface

**NAME** AVW\_SaveTree – saves a tree

**SYNOPSIS** #include "AVW\_Tree.h"

int AVW\_SaveTree(tree, file)

AVW\_Tree \*tree; char \*filename;

**DESCRIPTION** *AVW\_SaveTree()* saves the contents of the *tree* to the disk file specified by *filename*.

**RETURN VALUES** If successful *AVW\_SaveTree()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause

of the failure.

**ERRORS** | *AVW\_SaveTree()* will fail if one or more of the following is true:

**BADOPEN** 

Could open file for reading or writing.

**BADWRITE** 

Error occurred while writing file.

**ILLPAR** 

Illegal parameter(s).

SEE ALSO | AVW\_AddTreeChild(), AVW\_CreateTree(), AVW\_DestroyTree(), AVW\_FindTreeIndex(),

AVW\_FindTreeStart(), AVW\_LoadTree(), AVW\_MakeTree(), AVW\_PruneTree(),

AVW\_TreeAnalysis(), AVW\_TreePoint, AVW\_Tree

**NAME** AVW\_ScaleMatrix – scales a transformation matrix

SYNOPSIS #include "AVW.h"

AVW\_Matrix \*AVW\_ScaleMatrix(in\_matrix, xfactor, yfactor, zfactor, out\_matrix)

AVW\_Matrix \*in\_matrix; double xfactor, yfactor, zfactor; AVW\_Matrix \*out\_matrix;

**DESCRIPTION**AVW\_ScaleMatrix() applies the scaling specified by xfactor, yfactor, and zfactor to the

AVW\_Matrix, in\_matrix.

 $Out\_matrix$  is provided as a method of reusing an existing  $AVW\_Matrix$ . (See Memory

Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful *AVW\_ScaleMatrix()* returns an *AVW\_Matrix*. On failure it returns *NULL* and

sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of

the failure.

**SEE ALSO** | *AVW\_CopyMatrix(), AVW\_CreateMatrix(), AVW\_InvertMatrix(),* 

AVW\_MakeMatrixFrom3Points(), AVW\_MakeMatrixFromAxis() AVW\_MirrorMatrix(),

AVW\_MultiplyMatrix(), AVW\_RotateMatrix(), AVW\_SetIdentityMatrix(),

AVW\_TranslateMatrix(), AVW\_Matrix

**NAME** AVW\_ScalePointList2 – scales the points in a point list

**SYNOPSIS** #include "AVW.h"

int AVW\_ScalePointList2(ptlist, xscale, yscale)

AVW\_PointList2 \*ptlist; double xscale, yscale;

**DESCRIPTION** AVW\_ScalePointList2() applies the scaling specified by xscale and yscale, to the

AVW\_PointList2, ptlist.

**RETURN VALUES** If successful AVW\_ScalePointList2() returns AVW\_SUCCESS. On failure AVW\_FAIL is

returned.

SEE ALSO | AVW\_AddPoint2(), AVW\_CreatePointList2(), AVW\_DestroyPointList2(),

AVW\_RotatePointList2(), AVW\_TranslatePointList2(), AVW\_PointList2

AVW\_Scattergram - creates a scattergram image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_Scattergram(img1, img2, mask, scattergram) AVW\_Image \*img1, \*img2, \*mask, \*scattergram;

## **DESCRIPTION**

AVW\_Scattergram() creates a 2 dimensional scattergram from a pair of compatible images and an optional training mask image which indicates the positions of known classes. Compatible images are those with the same width and height; they must also be of type AVW\_UNSIGNED\_CHAR.

A scattergram created with a training *mask* image can be further classified with *AVW\_ClassifyScattergram()*.

If the *mask* image is NULL the returned scattergram will be of type  $AVW\_UNSIGNED\_INT$ . If the *mask* image is the same size as the input images and has known pixel classes indicated with class numbers the returned scattergram will be of type  $AVW\_UNSIGNED\_CHAR$  with known pixels set to the class number and all others zero.

The scattergram is a representation of the frequency and occurrences of pairs of values from *img1* and *img2* The values 0 to 255 are represented on the vertical and horizontal axes of *img1* and *img2* respectively. Values at point x,y in the scattergram are a count of pixels with a value of x from *img2* and a value of y from *img1*.

A masked scattergram image is used for fast voxel classification with *AVW\_ClassifyFromScattergram()*.

If *scattergram* is an *AVW\_Image* 256 pixels square and of data type *AVW\_UNSIGNED\_INT* it will be reused. Otherwise *scattergram* will be destroyed (if necessary) and/or created.

## **RETURN VALUES**

If successful *AVW\_Scattergram()* returns an *AVW\_Image*. On failure *NULL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

### **ERRORS**

AVW\_Scattergram() will fail if one or more of the following are true:

HLLDT

Illegal data type given in type.

**ILLIMG** 

Illegal Image; img1 and img2 are incompatible.

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

#### **SEE ALSO**

 $AVW\_ClassifyFromScattergram(),\ AVW\_ClassifyScattergram(),\ AVW\_ClassifyImage(),\ AVW\_ClassifyVolume(),\ AVW\_Image$ 

AVW\_ScattergramFromImages – creates a scattergram image from images

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_ScattergramFromImages(img1, img2, mask, scattergram) AVW\_Image \*img1, \*img2, \*mask, \*scattergram;

## **DESCRIPTION**

*AVW\_ScattergramFromImages()* creates a 2 dimensional scattergram from a pair of compatible images and an optional training mask image which indicates the positions of known classes. Compatible images are those with the same width and height; they must also be of type *AVW\_UNSIGNED\_CHAR*.

A scattergram created with a training *mask* image can be further classified with *AVW\_ClassifyScattergram()*.

If the *mask* image is NULL the returned scattergram will be of type  $AVW\_UNSIGNED\_INT$ . If the *mask* image is the same size as the input images and has known pixel classes indicated with class numbers the returned scattergram will be of type  $AVW\_UNSIGNED\_CHAR$  with known pixels set to the class number and all others zero.

The scattergram is a representation of the frequency and occurrences of pairs of values from *img1* and *img2* The values 0 to 255 are represented on the vertical and horizontal axes of *img1* and *img2* respectively. Values at point x,y in the scattergram are a count of pixels with a value of x from *img2* and a value of y from *img1*.

A masked scattergram image is used for fast voxel classification with *AVW\_ClassifyFromScattergram()*.

If *scattergram* is an *AVW\_Image* 256 pixels square and of data type *AVW\_UNSIGNED\_INT* it will be reused. Otherwise *scattergram* will be destroyed (if necessary) and/or created.

## **RETURN VALUES**

If successful *AVW\_Scattergram()* returns an *AVW\_Image*. On failure *NULL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_Scattergram() will fail if one or more of the following are true:

HLLDT

Illegal data type given in type.

**ILLIMG** 

Illegal Image; img1 and img2 are incompatible.

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

#### **SEE ALSO**

AVW\_ScattergramFromVolumes(), AVW\_ClassifyFromScattergram(), AVW\_ClassifyScattergram(), AVW\_ClassifyImage(), AVW\_ClassifyVolume(), AVW\_Image

AVW\_ScattergramFromVolumes – creates a scattergram image from volumes

#### **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_ScattergramFromVolumes(vol1, vol2, mask, scattergram)

AVW\_Volume \*vol1, \*vol2, \*mask;

AVW\_Image \*scattergram;

## **DESCRIPTION**

AVW\_ScattergramFromVolumes() creates a 2 dimensional scattergram from a pair of compatible volumes and an optional training mask volume which indicates the positions of known classes. Compatible volumes are those with the same Width, Height, and Depth; they must also be of type AVW\_UNSIGNED\_CHAR.

A scattergram created with a training *mask* volume can be further classified with *AVW\_ClassifyScattergram()*.

If the *mask* volume is NULL the returned scattergram will be of type  $AVW\_UNSIGNED\_INT$ . If the *mask* volume is the same size as the input volumes and has known pixel classes indicated with class numbers the returned scattergram will be of type  $AVW\_UNSIGNED\_CHAR$  with known pixels set to the class number and all others zero.

The scattergram is a representation of the frequency and occurrences of pairs of values from *vol1* and *vol2* The values 0 to 255 are represented on the vertical and horizontal axes of *vol1* and *vol2* respectively. Values at point x,y in the scattergram are a count of pixels with a value of x from *vol2* and a value of y from *vol1*.

A masked scattergram image is used for fast voxel classification with *AVW\_ClassifyFromScattergram()*.

If *scattergram* is an *AVW\_Image* 256 pixels square and of data type *AVW\_UNSIGNED\_INT* it will be reused. Otherwise *scattergram* will be destroyed (if necessary) and/or created.

## **RETURN VALUES**

If successful *AVW\_Scattergram()* returns an *AVW\_Image*. On failure *NULL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_ScattergramFromVolumes() will fail if one or more of the following are true:

**ILLDT** 

Illegal data type given in type.

**ILLVOL** 

Illegal Volume; vol1 and vol2 are incompatible.

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

#### **SEE ALSO**

AVW\_ScattergramFromImages(), AVW\_ClassifyFromScattergram(), AVW\_ClassifyScattergram(), AVW\_ClassifyImage(), AVW\_ClassifyVolume(), AVW\_Image

AVW\_SeekImageFile - seeks to a volume and image number in a file

**SYNOPSIS** 

#include "AVW\_ImageFile.h"

int AVW\_SeekImageFile (imgfile, volume, slice)

AVW\_ImageFile \*imgfile;

int volume;
int slice;

#### **DESCRIPTION**

AVW\_SeekImageFile() positions the AVW\_ImageFile such that the subsequent call to AVW\_ReadImageFile() will return the image specified by volume in slice.

AVW\_SeekImageFile() is also used to position the AVW\_ImageFile so that the next call to AVW\_With ImageFile so that the next call to

AVW\_SeekImageFile() is also used to position the AVW\_ImageFile so that the next call to AVW\_WriteImageFile() will write its image to that position in the file. For image formats that do not support three and four dimensions this is a dummy routine provided for consistancy with formats that do.

*Volume* specifies the volume number at which the file will be positioned. *AVW* numbers volumes in an image file from 0 to (imgfile->Numvols-1).

*Slice* specifies the image number within the volume of an image file. *AVW* numbers slices in an image file from 0 to (imgfile->Depth-1).

## **RETURN VALUES**

Upon success *AVW\_SeekImageFile()* returns *AVW\_SUCCESS*. On failure *AVW\_FAIL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of failure.

## **ERRORS**

AVW\_SeekImageFile() will fail if one or more of the following are true:

**BDVLNM** 

**Bad Volume Number** 

**BDSLNM** 

**Bad Slice Number** 

## **SEE ALSO**

AVW\_CloseImageFile(), AVW\_CreateImageFile(), AVW\_ExtendImageFile(), AVW\_FormatSupports(), AVW\_ListFormats(), AVW\_ReadImageFile(), AVW\_ReadVolume(), AVW\_WriteImageFile(), AVW\_WriteSubVolumeDescription(), AVW\_WriteVolume(), AVW\_ImageFile

**NAME** AVW\_SetError – Sets the error message and number

SYNOPSIS #include "AVW.h"

void AVW\_SetError(number, string)

int number
char \*string;

**DESCRIPTION** *AVW\_SetError()* sets the error message and number.

**SEE ALSO** AVW\_Error(), AVW\_GetErrorMessage(), AVW\_GetErrorNumber(),

**NAME** AVW\_SetIdentityMatrix – sets a transformation matrix to the identity matrix

**SYNOPSIS** #include "AVW.h"

void AVW\_SetIdentityMatrix(mat)

AVW\_Matrix \*mat;

**DESCRIPTION** | *AVW\_SetIdentityMatrix()* sets the 4x4 *AVW\_Matrix, mat,* to the identity matrix.

**SEE ALSO** AVW\_CopyMatrix(), AVW\_CreateMatrix(), AVW\_InvertMatrix(), AVW\_MirrorMatrix(),

AVW\_MultiplyMatrix(), AVW\_RotateMatrix(), AVW\_ScaleMatrix(),

AVW\_TranslateMatrix(), AVW\_MakeMatrixFrom3Points(), AVW\_MakeMatrixFromAxis(),

AVW\_Matrix

AVW\_SetImage - sets every pixel of an image to a value

**SYNOPSIS** 

#include "AVW.h"

int AVW\_SetImage(image, value)

AVW\_Image \*image;

double value;

**DESCRIPTION** 

AVW\_SetImage() sets all of the pixels in image to value.

For AVW\_COMPLEX images the real component of each pixel is set to *value* and the ima-

ginary component is set to zero.

For AVW\_COLOR images the red, green, and blue components need to be packed into

value. See AVW\_MAKERGB().

**RETURN VALUES** 

If successful AVW\_SetImage() returns AVW\_SUCCESS. On failure it returns AVW\_FAIL

and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause

of the failure.

**ERRORS** 

AVW\_SetImage() will fail if:

**ILLDT** 

Illegal data type.

**SEE ALSO** 

 $AVW\_GetPixel(),\ AVW\_InterpolatedPixel(),\ AVW\_NearestNeighborPixel(),\ AVW\_PutPixel(),\ AVW\_PutPixel(),\$ 

AVW\_SetVolume(), AVW\_ThresholdImage(), AVW\_Image, AVW\_MAKERGB()

AVW\_SetVolume - sets every voxel of a volume to a value

**SYNOPSIS** 

#include "AVW.h"

int AVW\_SetVolume(volume, value)

AVW\_Volume \*volume;

double value;

**DESCRIPTION** 

AVW\_SetVolume() sets all of the voxels in volume to value.

For *AVW\_COMPLEX* Volumes the real component of each voxel is set to *value* and the imaginary component is set to zero.

For *AVW\_COLOR* volumes the red, green, and blue components need to be packed into *value*. See *AVW\_MAKERGB()*.

**RETURN VALUES** 

If successful *AVW\_SetVolume()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_SetVolume() will fail if:

**ILLDT** 

Illegal data type.

**SEE ALSO** 

 $AVW\_GetVoxel(),\ AVW\_InterpolatedVoxel(),\ AVW\_NearestNeighborVoxel(),\\ AVW\_PutVoxel(),\ AVW\_SetImage(),\ AVW\_ThresholdVolume(),\ AVW\_MAKERGB(),\\ AVW\_Volume$ 

AVW\_SetupImageSample - Creates a list of points meeting sample criteria

**SYNOPSIS** 

#include "AVW\_MatchVoxels.h"

AVW\_FPointList2 \*AVW\_SetupImageSample(spec,pointlist)

AVW\_SampleSpec spec; AVW\_FPointList2 \*pointlist;

**DESCRIPTION** 

*AVW\_SetupImageSample()* creates a list of floating-point 2-D coordinates distributed throughout a region of space as defined by the *spec*. The same structure is used to define 3-D samples. *AVW\_SetupImageSample* ignores Z extent information in the *spec* 

pointlist is provided as a method of re-using an existing AVW\_FPointList2.

**RETURN VALUES** 

If successful returns a pointer to an *AVW\_FPointList2* structure which contains the list of coordinate points.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_SetupImageSample() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**ILLPAR** 

Sample or interpolation type or in the *spec* is not recognized.

**SEE ALSO** 

AVW\_StepSearchExtreme2D(), AVW\_BoundedStepSearchExtreme2D(), AVW\_SampleSpec.

AVW\_SetupVolumeSample - Creates a list of points meeting sample criteria

**SYNOPSIS** 

#include "AVW MatchVoxels.h"

AVW\_FPointList3 \*AVW\_SetupVolumeSample(spec,pointlist)

AVW\_SampleSpec spec; AVW\_FPointList3 \*pointlist;

**DESCRIPTION** 

*AVW\_SetupVolumeSample()* creates a list of floating-point 3-D coordinates distributed throughout a region of space as defined by the *spec*.

pointlist is provided as a method of re-using an existing AVW\_FPointList3.

**RETURN VALUES** 

If successful returns a pointer to an *AVW\_FPointList3* structure which contains the list of coordinate points.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_SetupVolumeSample() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**ILLPAR** 

Sample or interpolation type or in the *spec* is not recognized.

**SEE ALSO** 

AVW\_StepSearchExtreme(), AVW\_BoundedStepSearchExtreme(), AVW\_SampleSpec.

AVW\_ShiftImage - shifts an image right/left/up/down

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_ShiftImage(input\_image, right\_shift,

up\_shift, wrap, out\_image)

AVW\_Image \*input\_image;

int right shift, up shift, wrap;

AVW\_Image \*output\_image;

**DESCRIPTION** 

AVW\_ShiftImage() shifts or translates <code>input\_image</code> in the vertical or horizontal directions and places the result in <code>out\_image</code>.

*Right\_shift* specifies the number of pixels the image is to be shifted to the right, negative values cause a shift to the left.

*Up\_shift* specifies the number of pixels the image is to be shifted up, negative values cause a downward shift.

A nonzero *wrap* value specifies that all pixels shifted off of the image are wrapped around to the opposite side of the image, otherwise the pixels are discarded and the open areas are zero filled.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_ShiftImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ShiftImage() will fail if:

**BADMAL** 

Could not allocate enough memory for results.

**SEE ALSO** 

 $AVW\_FlipImage(),\ AVW\_Rotate90Image(),\ AVW\_PadImage(),\ AVW\_TransformImage(),\ AVW\_Image(),\ AVW\_$ 

AVW\_ShiftPointList2 - shifts a point list right/left/up/down

**SYNOPSIS** 

#include "AVW.h"

AVW\_PointList2 \*AVW\_ShiftPointList2(list, right\_shift,

up\_shift, out\_list)

AVW\_PointList2 \*list;

int right shift, up shift;

AVW\_PointList2 \*out\_list;

**DESCRIPTION** 

AVW\_ShiftPointList2() shifts or translates *list* in the vertical or horizontal directions and places the result in *out\_list*.

*Right\_shift* specifies the number of pixels the point list is to be shifted to the right, negative values cause a shift to the left.

*Up\_shift* specifies the number of pixels the point list is to be shifted up, negative values cause an downward shift.

Out\_list is provided as a method of reusing an existing AVW\_PointList2. If not reuseable out\_list will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_ShiftPointList2()* returns an *AVW\_PointList2*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ShiftPointList2() will fail if:

**BADMAL** 

Could not allocate enough memory for results.

**SEE ALSO** 

AVW\_AddPoint2(), AVW\_ClipPointList2(), AVW\_CopyPointList2(), AVW\_CreatePointList2(), AVW\_DestroyPointList2(), AVW\_DrawPointList2(), AVW\_EditPointList2(), AVW\_FillPointList2(), AVW\_GetPoint2(), AVW\_RemovePoint2(), AVW\_RotatePointList2(), AVW\_ScalePointList2(), AVW\_TransformPoint2(),

AVW\_PointList2

AVW\_ShowImage - quick and dirty display

**SYNOPSIS** 

#include "AVW.h"

int AVW\_ShowImage(image)
AVW\_Image \*image;

## **DESCRIPTION**

*AVW\_ShowImage()* writes the *AVW\_Image* to a temporary *AVW\_ImageFile* in the \$TMP (/tmp by default) directory in the *AVW\_ImageFile* format. It then calls *ShowServer* to display the results on the users display.

On UNIX systems, *ShowServer* will continue to run and display any other images which are passed to *AVW\_ShowImage()*. Any keystroke or mouse click in an image display window will destroy that window. Once the program which called AVW\_ShowImage() has terminated, any keystroke or mouse click terminates all the windows.

On PC systems, a different *ShowServer* is started for image displayed. Each window will need to be dismissed seperately.

## **RETURN VALUES**

Upon success *AVW\_ShowImage()* returns *AVW\_SUCCESS*. On failure *AVW\_FAIL* is returned, and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values indicating the cause of error.

**Notes** 

The program, *ShowServer* must be in the users *path* before *AVW\_ShowImage()* is called.

Example:

set path = (\$AVW/\$TARGET/bin \${path}) (UNIX) set path=%AVW%\%TARGET%\lib;%AVW%\%TARGET%\bin;%path% (PC)

**SEE ALSO** 

AVW\_CreateImageFile(), AVW\_CloseImageFile(), AVW\_ReadImageFile(), AVW\_OpenImageFile(), AVW\_WriteImageFile(), AVW\_Image,

AVW\_SigmaFilterImage - performs a 2D Sigma filter

**SYNOPSIS** 

#include "AVW\_Filter.h"

AVW\_Image \*AVW\_SigmaFilterImage(in\_image, extents, sigma, out\_image)

AVW\_Image \*in\_image;

int extents[2];

int sigma;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_SigmaFilterImage() performs a Sigma filter transformation on in\_image. Extents[0] and extents[1] specify the x and y sizes respectively of the filter.

Sigma specifies the sigma value for the sigma filter.

The sigma filter uses a local smoothing scheme. This filter smooths noise, preserves edges and can leave thin lines untouched. For each pixel in the input image, the mean value of a set of pixels within 2\* sigma is calculated. Only pixels within the range specified by extents are considered in this calculation. If too few pixels within the extents lie with in the 2\*sigma value, then the pixel is left unchanged; otherwise, the calculated mean is assigned as a new pixel value.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful AVW\_SigmaFilterImage() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

## **SEE ALSO**

 $AVW\_AHEImage(),\ AVW\_AnisotropicAffineImage(),\ AVW\_AnisotropicDiffusionImage(),\ AVW\_LowpassFilterImage(),\ AVW\_OrthoGradFilterImage(),\ AVW\_RankFilterImage(),\ AVW\_SobelFilterImage(),\ AVW\_SobelFilterImage(),\ AVW\_SobelFilterImage(),\ AVW\_Image(),\ A$ 

AVW\_SigmaFilterVolume - performs a 3D Sigma filter

**SYNOPSIS** 

#include "AVW Filter.h"

 $AVW\_Volume *AVW\_SigmaFilterVolume (in\_volume, extents, sigma, out\_volume)$ 

AVW\_Volume \*in\_volume;

int extents[3];

int sigma;

AVW\_Volume \*out\_volume;

## **DESCRIPTION**

AVW\_SigmaFilterVolume() performs a Sigma filter transformation on in\_volume. Extents[0], extents[1], and, extents[2] specify the x, y, and z sizes respectively of the filter.

Sigma specifies the sigma value for the sigma filter.

The sigma filter uses a local smoothing scheme. This filter smooths noise, preserves edges and can leave thin lines untouched. For each voxel in the input volume, the mean value of a set of voxels within 2\* *sigma* is calculated. Only voxels within the range specified by *extents* are considered in this calculation. If too few voxels within the extents lie with in the 2\*sigma value, then the voxel is left unchanged; otherwise, the calculated mean is assigned as a new voxel value.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

## **RETURN VALUES**

If successful *AVW\_SigmaFilterVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **SEE ALSO**

AVW\_AHEVolume(), AVW\_InhomogeneityCorrectVolume(), AVW\_LowpassFilterVolume(), AVW\_OrthoGradFilterVolume(), AVW\_RankFilterVolume(), AVW\_SigmaFilterImage(), AVW\_SobelFilterEnhanceVolume(), AVW\_SobelFilterVolume(), AVW\_UnsharpFilterEnhanceVolume(), AVW\_UnsharpFilterVolume(), AVW\_VSFMeanFilterVolume(), AVW\_Volume

**NAME** AVW\_SincInterpolatedPixel – returns pixel value at a floating point location

SYNOPSIS #include "AVW.h"

double AVW\_SincInterpolatedPixel(image, point)

AVW\_Image \*image; AVW\_FPoint2 \*point;

**DESCRIPTION** Given a floating point location *point* within *image*, *AVW\_SincInterpolatedPixel()* returns the

calculated pixel value at the floating point location.

Uses a windows sinc algorithm to estimate the pixel value at the floating point location.

Points outside the image will return a value of 0.0.

**SEE ALSO** | AVW\_GetPixel(), AVW\_GetErrorNumner(), AVW\_InterpolatedVoxel(),

 $AVW\_NearestNeighborPixel(),\ AVW\_InterpolatedPixel(),$ 

AVW\_CubicSplineInterpolatedPixel(), AVW\_Image, AVW\_FPoint2

NAME | AVW\_SincInterpolatedVoxel - returns voxel value at a floating point location

SYNOPSIS #include "AVW.h"

double AVW\_SincInterpolatedVoxel(volume, point)

AVW\_Volume \*volume; AVW\_FPoint3 \*point;

**DESCRIPTION** Given a floating point location *point* within *volume*, *AVW\_SincInterpolatedVoxel()* returns

the calculated voxel value at the floating point location.

Uses a windowed sinc algorithm to estimate the voxel value at the floating point location.

Points outside the volume will return a value of 0.0.

**SEE ALSO** | *AVW\_GetVoxel()*, *AVW\_GetErrorNumner()*, *AVW\_InterpolatedPixel()*,

AVW\_NearestNeighborVoxel(), AVW\_InterpolatedVoxel(),

AVW\_CubicSplineInterpolatedVoxel(), AVW\_FPoint3, AVW\_Volume

**NAME** AVW\_SincWindowLimit – sets sinc window size

SYNOPSIS #include "AVW.h"

int AVW\_SincWindowLimit(windowsize)

int windowsize;

**DESCRIPTION**AVW\_SincWindowLimit() Changes the size of the window used during sinc interpolation

(see *AVW\_SincInterpolatedPixel* and *AVW\_SincInterpolatedVoxel*). *windowsize* is a positive value indicating the requested size of the sinc kernel. The kernel extends *windowsize* to

each side of the interpolated position.

The return value is the new window size.

**RETURN VALUES** A call to *AVW\_SincWindowLimit()* returns the new value of the window used for sinc

interpolation. The return value may be less than the requested value.

**SEE ALSO** AVW\_SincInterpolatedPixel(), AVW\_SincInterpolatedVoxel

AVW\_SliceVolume - extracts a contour surface from a volume

**SYNOPSIS** 

#include "AVW\_Model.h"

AVW\_ContourSurface \*AVW\_SliceVolume(rp\_param, oldSurface)

AVW\_RPParam \*rp\_param;

AVW\_ContourSurface \*oldSurface;

**DESCRIPTION** 

AVW\_SliceVolume() generates a set of ribbon contours based on the parameters set in rp\_param and generates a AVW\_ContourSurface structure. oldSurface is provided as a method of reusing an existing AVW\_ContourSurface. If reuse is not possible, oldSurface will be reallocated.

**RETURN VALUES** 

If successful AVW\_SliceVolume() returns an AVW\_ContourSurface. NULL is returned should AVW\_SliceVolume() fail.

**ERRORS** 

Errors may occur for the following reasons:

**ILLPAR** 

Illegal Parameter. Typically a missing or improperly set option in *rp\_param*.

**BADMAL** 

Bad Malloc. Memory allocation error.

**BDOPEN** 

Open Failed. Unable to open file for writing.

**BDWRTE** 

Write Failed. Unable to write to specified file

**ILLVOL** 

Illegal Volume. Unable to perform operation on spcified volume. Typically results from trying to extract contours from an unsupported data type.

ILLDT

Illegal Datatype. Unable to perform operation on the given data type.

**ILLMSK** 

Illegal Mask. Typically indicates a mask value that is out of range for the given volume.

**SEE ALSO** 

 $AVW\_Initialize RPP aram(), \ AVW\_Destroy Contour Surface(), \ AVW\_Destroy RPP aram(), \ AVW\_Save Contour Surface(), \ AVW\_Contour Surface, \ AVW\_RPP aram(), \ AVW\_RPP aram($ 

**NAME** AVW\_SmoothHistogram – smoothes the values of a histogram

SYNOPSIS #include "AVW.h"

int AVW\_SmoothHistogram(histogram, half\_width)

AVW\_Histogram \*histogram;

int half\_width;

**DESCRIPTION** AVW\_SmoothHistogram() smoothes each value of the histogram using a weighted average

**AVW 3.0** 

of the neighboring bins. *Half\_width* specifies how many bins to the left and right of the center bin will be used in calculating the smoothed value. The weight is inversely propo-

tional to disance from the center bin.

**RETURN VALUES** If successful, *AVW\_SmoothHistogram()* returns *AVW\_SUCCESS*. On failure, it returns

AVW\_FAIL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure. To insure valid results AVW\_ErrorNumber should be checked

after calling this function.

**ERRORS** | *AVW\_SmoothHistogram()* will fail if one or more of the following are true:

**ILLHIS** 

Illegal histogram, histogram is NULL.

**SEE ALSO** AVW\_CreateHistogram(), AVW\_GetHistogramModeValue(),

AVW\_GetHistogramMedianValue(), AVW\_GetImageHistogram(),

AVW\_GetVolumeHistogram(), AVW\_Histogram

AVW\_SobelFilterEnhanceImage - enhances an image by Sobel filtering

**SYNOPSIS** 

#include "AVW\_Filter.h"

AVW\_Image \*AVW\_SobelFilterEnhanceImage(in\_image, extents, out\_image)

AVW\_Image \*in\_image;

int extents[2];

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_SobelFilterEnhanceImage() performs a Sobel filter transformation which is used for edge detection on *in\_image*. The returned image *out\_image*, consists of the input image added to the Sobel filtered input image.

Extents[0] and extents[1], specify the x and y sizes respectively of the filter.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_SobelFilterEnhanceImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_AHEImage(), AVW\_AnisotropicAffineImage(), AVW\_AnisotropicDiffusionImage(), AVW\_LowpassFilterImage(), AVW\_OrthoGradFilterImage(), AVW\_RankFilterImage(), AVW\_SigmaFilterImage(), AVW\_SobelFilterImage(), AVW\_SobelFilterEnhanceVolume(), AVW\_UnsharpFilterEnhanceImage(), AVW\_UnsharpFilterImage(), AVW\_Image

AVW\_SobelFilterEnhanceVolume – enhances a volume by Sobel filtering

**AVW 3.0** 

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Volume \*AVW\_SobelFilterEnhanceVolume(in\_volume, extents, out\_volume)

AVW\_Volume \*in\_volume;

int extents[3];

AVW Volume \*out volume:

**DESCRIPTION** 

AVW\_SobelFilterEnhanceVolume() performs a Sobel filter transformation which is used for edge detection on *in\_volume*. The returned volume, *out\_volume*, consists of the input volume added to the Sobel filtered input volume.

Extents[0], extents[1], and extents[2] specify the x, y, and z sizes respectively of the filter.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_SobelFilterEnhanceVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_AHEVolume(), AVW\_InhomogeneityCorrectVolume(), AVW\_LowpassFilterVolume(), AVW\_OrthoGradFilterVolume(), AVW\_RankFilterVolume(), AVW\_SigmaFilterVolume(), AVW\_SobelFilterEnhanceImage(), AVW\_SobelFilterVolume(), AVW\_UnsharpFilterEnhanceVolume(), AVW\_UnsharpFilterVolume(),

AVW\_VSFMeanFilterVolume(), AVW\_Volume

NAME AVW\_SobelFilterImage – performs a 2D Sobel filter

**SYNOPSIS** #include "AVW\_Filter.h"

AVW\_Image \*AVW\_SobelFilterImage(in\_image, extents, out\_image)

AVW\_Image \*in\_image;

int extents[2];

AVW\_Image \*out\_image;

**DESCRIPTION** AVW

AVW\_SobelFilterImage() performs a Sobel filter transformation which is used for edge detection on in image.

detection on *in\_image*.

*Extents[0]* and *extents[1]*, specify the x and y sizes respectively of the filter.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful  $AVW\_SobelFilterImage()$  returns an  $AVW\_Image$ . On failure all it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to

the cause of the failure.

**SEE ALSO** 

AVW\_AHEImage(), AVW\_AnisotropicAffineImage(), AVW\_AnisoTropicDiffusionImage(), AVW\_LowpassFilterImage(), AVW\_OrthoGradFilterImage(), AVW\_RankFilterImage(), AVW\_SigmaFilterImage(), AVW\_SobelFilterEnhanceImage(), AVW\_SobelFilterEnhanceImage(), AVW\_Image(), AVW\_Image(

AVW\_SobelFilterVolume - performs a 3D Sobel filter

**SYNOPSIS** 

#include "AVW\_Filter.h"

AVW\_Volume \*AVW\_SobelFilterVolume(in\_volume, extents, out\_volume)

AVW\_Volume \*in\_volume;

int extents[3];

AVW Volume \*out volume:

**DESCRIPTION** 

AVW\_SobelFilterVolume() performs a Sobel filter transformation which is used for edge detection on *in volume*.

Extents[0], extents[1], and extents[2] specify the x, y, and z sizes respectively of the filter.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_SobelFilterVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

 $AVW\_AHEVolume(),\ AVW\_InhomogeneityCorrectVolume(),\ AVW\_LowpassFilterVolume(),\ AVW\_OrthoGradFilterVolume(),\ AVW\_RankFilterVolume(),\ AVW\_SigmaFilterVolume(),\ AVW\_SobelFilterEnhanceVolume(),\ AVW\_SobelFilterImage(),$ 

 $AVW\_UnsharpFilterEnhanceVolume(),\ AVW\_UnsharpFilterVolume(),$ 

AVW\_VSFMeanFilterVolume(), AVW\_Volume

AVW\_StepSearchExtreme - Searches for best registration of two volume images.

#### **SYNOPSIS**

#include "AVW MatchVoxels.h"

 $AVW\_Matrix *AVW\_StepSearchExtreme (dirflag, base, match, points, steps, func, interpolation, matrix) int dirflag, interpolation;$ 

AVW Volume \*base, \*match;

AVW\_FPointList3 \*points;

AVW\_Matrix \*matrix;

AVW\_StepSearchSpec \*steps;

int func:

## **DESCRIPTION**

AVW\_StepSearchExtreme() Performs a stepwise search of 6-DOF physical registration space to find the nearest extreme of a voxel statistic function relating two AVW\_Volumes. AVW\_StepSearchExtreme returns the AVW\_Matrix which transforms the match volume into the space of the base volume at the extreme.

*dirflag* determines whether maxima or minima are searched for. Defined values are *AVW\_MAXIMUM* and *AVW\_MINIMUM*.

base and match are the AVW\_Volume s to be registered.

points is an  $AVW\_FPointList3$  containing a list of coordinate points in the match image to be used as the sample voxels for the registration. points is usually created by a call to  $AVW\_SetupVolumeSample$ 

*steps* contains the specification of the step search, primarily specific step sizes for each of the 6 degrees of freedom. Bounding information in *steps* is ignored by *AVW\_StepSearchExtreme*.

func specifies the statistical measure to be used. Defined values are AVW\_NMI.

*interpolation* specifies the intepolation type to be used in the search, and may be any of the defined AVW interpolation types.

*matrix* is taken as the starting orientation for the search. If *Matrix* is NULL, a new identity matrix is created, and used as the starting orientation.

## **RETURN VALUES**

If successful returns an *AVW\_Matrix* which transforms the match volume into the space of the base volume at the extreme.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

*AVW\_StepSearchExtreme()* will fail if the following is true:

**BADMAL** 

Could not allocate memory for internal structures.

**ILLPAR** 

Sample or interpolation type is not recognized.

SEE ALSO | AVW\_SetupVolumeSample() AVW\_BoundedStepSearchExtreme() AVW\_SampleSpec | AVW\_StepSearchSpec

AVW\_StepSearchExtreme2D - Searches for best registration of two images.

#### **SYNOPSIS**

#include "AVW MatchVoxels.h"

 $AVW\_Matrix *AVW\_Step Search Extreme 2D (dirflag, base, match, points, steps, func, interpolation, matrix int dirflag, interpolation;$ 

AVW\_Image \*base,\*match;

AVW\_FPointList2 \*points;

AVW\_Matrix \*matrix;

AVW\_StepSearchSpec \*steps;

int func:

## **DESCRIPTION**

AVW\_StepSearchExtreme2D() Performs a stepwise search of 3-DOF physical registration space to find the nearest extreme of a voxel statistic function relating two AVW\_Images. AVW\_StepSearchExtreme2D returns the AVW\_Matrix which transforms the match image into the space of the base image at the extreme.

*dirflag* determines whether maxima or minima are searched for. Defined values are *AVW\_MAXIMUM* and *AVW\_MINIMUM*.

base and match are the AVW\_Image s to be registered.

points is an AVW\_FPointList2 containing a list of coordinate points in the match image to be used as the sample voxels for the registration. points is usually created by a call to AVW\_SetupImageSample

*steps* contains the specification of the step search, primarily specific step sizes for each of the 3 degrees of freedom. Bounding information in *steps* is ignored by *AVW\_StepSearchExtreme2D*.

*func* specifies the statistical measure to be used. Defined values are *AVW\_NMI*.

*interpolation* specifies the intepolation type to be used in the search, and may be any of the defined AVW interpolation types.

*matrix* is taken as the starting orientation for the search. If *Matrix* is NULL, a new identity matrix is created, and used as the starting orientation.

## **RETURN VALUES**

If successful returns an  $AVW\_Matrix$  which transforms the match image into the space of the base image at the extreme.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

## **ERRORS**

*AVW\_StepSearchExtreme2D()* will fail if the following is true:

**BADMAL** 

Could not allocate memory for internal structures.

# **ILLPAR**

Sample or interpolation type is not recognized.

SEE ALSO AVW\_SetupImageSample() AVW\_BoundedStepSearchExtreme2D() AVW\_SampleSpec AVW\_StepSearchSpec

**NAME** AVW\_SumIntensityStats – sums intensity statistics

**SYNOPSIS** #include "AVW\_Measure.h"

void AVW\_SumIntensityStats( stats, statsum)

AVW\_IntensityStats \*stats, \*statsum;

**DESCRIPTION** AVW\_SumIntensityStats() adds the statistics from stats to statsum. Elements such as Mean,

Standard Deviation, and Variance are recomputed based on the summed statistics.

**SEE ALSO** AVW\_ComputeVolumeIntensityStats() AVW\_ComputeImageIntensityStats(),

AVW\_ResetIntensityStatistics(), AVW\_IntensityStats

**NAME** AVW\_SwapBlock – swaps bytes in a block

**SYNOPSIS** #include <stdio.h> #include "AVW.h"

AVW\_SwapBlock(pntr, bytes)

void \*pntr;
int bytes;

**DESCRIPTION** | *AVW\_SwapBlock()* swaps bytes in place over a specified number of *bytes*.

SEE ALSO AVW\_QuadSwapImage(), AVW\_READSWAP(), AVW\_ReverseBits(), AVW\_SwapDouble(), AVW\_SwapInage(), AVW\_SwapInt(), AVW\_SwapInt(), AVW\_SwapLong(),

AVW\_SwapShort(), AVW\_WRITESWAP(), fread(), fwrite(), swab()

**NAME** AVW\_SwapDouble – swaps the bytes of a double

**SYNOPSIS** #include <stdio.h> #include "AVW.h"

void AVW\_SwapDouble(ptr)

double \*ptr;

**DESCRIPTION** AVW\_SwapDouble(), swaps the bytes of a double.

SEE ALSO | AVW\_QuadSwapImage(), AVW\_READSWAP(), AVW\_ReverseBits(), AVW\_SwapBlock(),

AVW\_SwapInat(), AVW\_SwapImage(), AVW\_SwapInt(), AVW\_SwapLong(),

AVW\_SwapShort(), AVW\_WRITESWAP(), fread(), fwrite(), swab()

**NAME** AVW\_SwapFloat – swaps the bytes of a float

**SYNOPSIS** #include <stdio.h> #include "AVW.h"

void AVW\_SwapFloat(ptr)

float \*ptr;

**DESCRIPTION** *AVW\_SwapFloat()* swaps the bytes of a float.

SEE ALSO | AVW\_QuadSwapImage(), AVW\_READSWAP(), AVW\_ReverseBits(), AVW\_SwapBlock(),

AVW\_SwapDouble(), AVW\_SwapImage(), AVW\_SwapInt(), AVW\_SwapLong(),

AVW\_SwapShort(), AVW\_WRITESWAP(), fread(), fwrite(), swab()

**NAME** AVW\_SwapImage – swaps the bytes of an image

**SYNOPSIS** #include <stdio.h> #include "AVW.h"

AVW\_SwapImage(image) AVW\_Image \*image;

**DESCRIPTION** AVW\_SwapImage() swap the bytes of an image.

SEE ALSO AVW\_QuadSwapImage(), AVW\_READSWAP(), AVW\_ReverseBits(), AVW\_SwapBlock(),

AVW\_SwapDouble(), AVW\_SwapFloat(), AVW\_SwapInt(), AVW\_SwapShort(),

AVW\_SwapLong(), AVW\_WRITESWAP(), fread(), fwrite(), swab()

**NAME** AVW\_SwapInt – swaps bytes of an integer

**SYNOPSIS** #include <stdio.h> #include "AVW.h"

AVW\_SwapInt(pntr)

int \*pntr;

**DESCRIPTION** AVW\_SwapInt() swaps the bytes of an integer.

SEE ALSO | AVW\_QuadSwapImage(), AVW\_READSWAP(), AVW\_ReverseBits(), AVW\_SwapBlock(),

AVW\_SwapDouble(), AVW\_SwapFloat(), AVW\_SwapImage(), AVW\_SwapLong(),

AVW\_SwapShort(), AVW\_WRITESWAP(), fread(), fwrite(), swab()

**NAME** AVW\_SwapLong – swaps bytes of a long integer

**SYNOPSIS** #include <stdio.h> #include "AVW.h"

AVW\_SwapLong(pntr)

long int \*pntr;

**DESCRIPTION** *AVW\_SwapLong* swaps the bytes of a long integer.

SEE ALSO | AVW\_QuadSwapImage(), AVW\_READSWAP(), AVW\_ReverseBits(), AVW\_SwapBlock(),

AVW\_SwapDouble(), AVW\_SwapFloat(), AVW\_SwapImage(), AVW\_SwapInt(),

AVW\_SwapShort(), AVW\_WRITESWAP(), fread(), fwrite(), swab()

**NAME** AVW\_SwapShort – swaps the bytes of a short integer

**SYNOPSIS** #include <stdio.h> #include "AVW.h"

AVW\_SwapShort(pntr)

short \*pntr;

**DESCRIPTION** *AVW\_SwapShort()* swap the bytes of a short integer.

SEE ALSO AVW\_QuadSwapImage(), AVW\_READSWAP(), AVW\_ReverseBits(), AVW\_SwapBlock(),

AVW\_SwapDouble(), AVW\_SwapFloat(), AVW\_SwapImage(), AVW\_SwapInt(),

AVW\_SwapLong(), AVW\_WRITESWAP(), fread(), fwrite(), swab()

AVW\_TableImage - applies a lookup table to an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_TableImage(in\_image, table, out\_image)

AVW\_Image \*in\_image; unsigned long \*table; AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_TableImage() uses the values of in\_image as indicies in the table array to get the values of out image.

out\_image[i] = table[in\_image[i]];

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_TableImage()* returns an *AVW\_Image*. On failure *NULL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_TableImage() will fail if the following is true:

**NOTSUP** 

Data type is not supported.

**SEE ALSO** 

AVW\_IntensityClipImage(), AVW\_IntensityScaleImage(), AVW\_InvertImage(), AVW\_MakeMonoImage(), AVW\_TableVolume(), AVW\_Image

AVW\_TableVolume – applies a lookup table to a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_TableVolume(in\_volume, table, out\_volume)

 $AVW\_Volume * in\_volume;$ 

unsigned long \*table;

AVW Volume \*out volume;

**DESCRIPTION** 

AVW\_TableVolume() uses the values of in\_volume as indicies in the table array to get the values of out volume.

out\_volume[i] = table[in\_volume[i]];

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_TableVolume()* returns an *AVW\_Volume*. On failure *NULL* is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_TableVolume() will fail if the following is true:

**NOTSUP** 

Data type is not supported.

**SEE ALSO** 

AVW\_IntensityClipVolume(), AVW\_IntensityScaleVolume(), AVW\_InvertVolume(), AVW\_TableImage(), AVW\_Volume

AVW\_Thin2D - performs 2D thinning on an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_Thin2D(in\_image, iterations, out\_image)

AVW\_Image \*in\_image;

int iterations;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_Thin2D() performs 2D thinning, using template matching, on <code>in\_image</code>. The image is thinned <code>iterations</code> times or until no more changes can be made. If <code>iterations</code> is less than or equal to zero the image will be thinned to its skeleton. The thinned image is returned in <code>out\_image</code>.

*In\_image* has to be a binary valued, i.e. ones and zeroes. *In\_image*, and *out\_image* must be of the data type *AVW\_UNSIGNED\_CHAR*. This function will allocate temporary storage space for results if *in\_image* and *out\_image* are the same.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_Thin2D()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_Thin2D() will fail if:

**ILLDT** 

Data type is not AVW\_UNSIGNED\_CHAR.

**SEE ALSO** 

AVW\_Thin3D(), AVW\_Image

AVW\_Thin3D - performs 3D thinning on a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_Thin3D(in\_volume, iterations, out\_volume)

AVW\_Volume \*in\_volume;

int iterations;

AVW Volume \*out volume;

#### DESCRIPTION

AVW\_Thin3D() performs 3D thinning, using the method described in:

S. Lobregt, P.W. Verbeek, and F.C.A. Groen, "Three-dimensional skeletonization: principle and algorithm", IEEE Trans. Pattern Anal. Mach. Intell., vol. PAMI-2, no.1, pp. 75-77, Jan, 1980.

The volume is thinned *iterations* times or until no more changes can be made. If *iterations* is less than or equal to zero, the volume will be thinned to its skeleton. The thinned volume is returned in *out\_volume*.

Basically, the connectivity of a 3X3X3 region surrounding a candidate voxel for deletion is evaluated with and without the candidate voxel. The candidate voxels are edge voxels found by scanning the volume from different directions. If the connectivity does not change, the voxel is deleted. If the connectivity changes the voxel is not deleted.

This algorithm requires solid objects, i.e. 2D holes must be filled (See *AVW\_FillHolesImage()*).

In\_Volume has to be a binary valued, i.e. ones and zeroes. In\_Volume, and out\_volume must be of the data type AVW\_UNSIGNED\_CHAR. This function will allocate temporary storage space for results if in\_volume and out\_volume are the same.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_Thin3D()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_Thin3D() will fail if:

**ILLDT** 

Data type is not AVW\_UNSIGNED\_CHAR.

**SEE ALSO** 

AVW\_Thin2D(), AVW\_Volume

AVW\_ThresholdImage - thresholds an image

**SYNOPSIS** 

#include "AVW.h"

 $AVW\_Image *AVW\_ThresholdImage (in\_image, threshold\_max, in_image) = (in\_image, threshold\_max, in_image, threshold\_max, in_image) = (in\_image, threshold\_max, in_image, threshold\_max, in_image, threshold\_max, in_image, threshold\_max, in_image, threshold\_max, i$ 

threshold\_min, out\_image)

AVW\_Image \*in\_image;

double threshold\_max, threshold\_min;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_ThresholdImage() thresholds an image, in\_image, by setting all of the pixels greater than or equal to the threshold\_min and less than or equal to threshold\_max to 1 and the rest of the pixels to 0. The returned AVW\_Image is of the data type AVW\_UNSIGNED\_CHAR.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_ThresholdImage()* returns an *AVW\_Image.* On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ThresholdImage() will fail if the following is true:

**ILLDT** 

Illegal data type.

**SEE ALSO** 

AVW\_ThresholdVolume(), AVW\_Image

AVW\_ThresholdVolume - thresholds a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_ThresholdVolume(in\_volume, threshold\_max,

**AVW 3.0** 

threshold\_min, out\_volume)

AVW\_Volume \*in\_volume;

double threshold max, threshold min;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

*AVW\_ThresholdVolume()* thresholds a volume, *in\_volume*, by setting all of the voxels greater than or equal to the *threshold\_min* and less than or equal to *threshold\_max* to 1 and the rest of the voxels to 0. The returned *AVW\_Volume* is of the data type *AVW\_UNSIGNED\_CHAR*.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_ThresholdVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_ThresholdVolume() will fail if the following is true:

**ILLDT** 

Illegal data type.

**SEE ALSO** 

AVW\_ThresholdImage(), AVW\_Volume

**NAME** AVW\_TileVolume – generates an AVW\_TiledSurface

SYNOPSIS #include "AVW\_Model.h"

AVW\_TiledSurface \*AVW\_TileVolume(tile\_param, surface)

AVW\_TileParameters \*tile\_param;

AVW\_TiledSurface \*surface;

**DESCRIPTION** | AVW\_TileVolume() generates an AVW\_TiledSurface based on the parameters set in

tile\_param.

**RETURN VALUES** If successful AVW\_TileVolume() returns AVW\_TiledSurface. NULL is returned if a

AVW\_TiledSurface cannot be created.

**ERRORS** Errors may occur for the following reasons:

**ILLPAR** 

Illegal Parameter. Typically a missing or improperly set option in *tile\_param*.

**BADMAL** 

Bad Malloc. Memory allocation error.

**SEE ALSO** *AVW\_InitializeTileParameters(), AVW\_LoadTiledSurface(), AVW\_SaveTiledSurface.3(),* 

AVW\_DrawTiledSurface(), AVW\_DestroyTiledSurface(), AVW\_DestroyTileParameters(),

AVW\_VolumeToSLC(), AVW\_TiledSurface, AVW\_TileParameters

AVW\_TransformFPoint2 - applies a matrix to a point

**SYNOPSIS** 

#include "AVW.h"

int AVW\_TransformFPoint2(point2, matrix, in\_image, out\_image)

AVW\_FPoint2 \*point2;

AVW\_Matrix \*matrix;

AVW\_Image \*in\_image;

AVW\_Image \*out\_image;

**DESCRIPTION** 

*AVW\_TransformFPoint2()* applies the 4x4 transformation *AVW\_Matrix*, *matrix*, to the *AVW\_FPoint2*, *point2*.

Point coordinates are often specified with (0,0) in the corner of the image. Matrices normally specify a rotation around the center of an image. The *in\_image* and *out\_image* parameters are optional. If specified the dimension of the images are used to locate the center of the input space and output space.

**SEE ALSO** 

 $AVW\_AddFPoint2(),\ AVW\_GetFPoint2(),\ AVW\_TransformFPoint3(),\\ AVW\_TransformFPointList2(),\ AVW\_TransformIPoint2(),\ AVW\_TransformPoint2(),\\ AVW\_FPoint2,\ AVW\_Matrix,\ AVW\_Image$ 

**NAME** AVW\_TransformFPoint3 – applies a matrix to a point

SYNOPSIS #include "AVW.h"

int AVW\_TransformFPoint3(point3, matrix, in\_volume, out\_volume)

AVW\_FPoint3 \*point3; AVW\_Matrix \*matrix;

AVW\_Volume \*in\_volume;

AVW\_Volume \*out\_volume;

**DESCRIPTION** | AVW\_TransformFPoint3() applies the 4x4 transformation AVW\_Matrix, matrix, to the

AVW\_FPoint3, point3.

Point coordinates are often specified with (0,0) in the corner of the volume. Matrices normally specify a rotation around the center of an volume. The <code>in\_volume</code> and <code>out\_volume</code> parameters are optional. If specified the dimension of the volumes are used to locate the

center of the input space and output space.

**SEE ALSO** AVW\_AddFPoint3(), AVW\_GetFPoint3(), AVW\_TransformFPoint2(),

AVW\_TransformFPointList3(), AVW\_TransformIPoint3(), AVW\_TransformPoint3(),

AVW\_FPoint3, AVW\_Matrix, AVW\_Image

AVW\_TransformFPointList2 - applies a matrix to a pointlist

**SYNOPSIS** 

#include "AVW.h"

int AVW\_TransformFPointList2(plist, matrix, in\_image, out\_image)

AVW\_FPointList2 \*plist;

AVW\_Matrix \*matrix;

AVW\_Image \*in\_image;

AVW\_Image \*out\_image;

**DESCRIPTION** 

 $AVW\_TransformFPointList2()$  applies the 4x4 transformation  $AVW\_Matrix$ , matrix, to the  $AVW\_FPointList2$ , plist.

Point coordinates are often specified with (0,0) in the corner of the image. Matrices normally specify a rotation around the center of an image. The *in\_image* and *out\_image* parameters are optional. If specified the dimension of the images are used to locate the center of the input space and output space.

**SEE ALSO** 

AVW\_AddFPointList2(), AVW\_GetFPointList2(), AVW\_TransformFPointList3(), AVW\_TransformFPoint2(), AVW\_TransformIPointList2(), AVW\_TransformPointList2(), AVW\_FPointList2, AVW\_Matrix, AVW\_Image

**NAME** AVW\_TransformFPointList3 – applies a matrix to a pointlist

SYNOPSIS #include "AVW.h"

int AVW\_TransformFPointList3(plist, matrix, in\_volume, out\_volume)

AVW\_FPointList3 \*plist; AVW\_Matrix \*matrix;

AVW\_Volume \*in\_volume; AVW\_Volume \*out\_volume;

**DESCRIPTION** 

 $AVW\_TransformFPointList3()$  applies the 4x4 transformation  $AVW\_Matrix$ , matrix, to the  $AVW\_FPointList3$ , plist.

Point coordinates are often specified with (0,0) in the corner of the volume. Matrices normally specify a rotation around the center of an volume. The *in\_volume* and *out\_volume* parameters are optional. If specified the dimension of the volumes are used to locate the center of the input space and output space.

**SEE ALSO** 

AVW\_AddFPointList3(), AVW\_GetFPointList3(), AVW\_TransformFPointList2(), AVW\_TransformFPoint3(), AVW\_TransformIPointList3(), AVW\_TransformPointList3(), AVW\_FPointList3, AVW\_Matrix, AVW\_Image

AVW\_TransformIPoint2 - applies a matrix to a point

**SYNOPSIS** 

#include "AVW.h"

int AVW\_TransformIPoint2(point2, matrix, in\_image, out\_image)

**AVW 3.0** 

AVW\_IPoint2 \*point2; AVW\_Matrix \*matrix;

AVW\_Image \*in\_image;

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_TransformIPoint2() applies the 4x4 transformation AVW\_Matrix, matrix, to the AVW\_IPoint2, point2.

Point coordinates are often specified with (0,0) in the corner of the image. Matrices normally specify a rotation around the center of an image. The *in\_image* and *out\_image* parameters are optional. If specified the dimension of the images are used to locate the center of the input space and output space.

**SEE ALSO** 

AVW\_AddIPoint2(), AVW\_GetIPoint2(), AVW\_TransformFPoint2(), AVW\_TransformIPoint3(), AVW\_TransformIPointList2(), AVW\_TransformPoint2(), AVW\_IPoint2, AVW\_Matrix, AVW\_Image

**NAME** AVW\_TransformIPoint3 – applies a matrix to a point

SYNOPSIS #include "AVW.h"

int AVW\_TransformIPoint3(point3, matrix, in\_volume, out\_volume)

AVW\_IPoint3 \*point3; AVW\_Matrix \*matrix; AVW\_Volume \*in\_volume;

AVW\_Volume \*out\_volume;

**DESCRIPTION** AVW\_TransformIPoint3() applies the 4x4 transformation AVW\_Matrix, matrix, to the

AVW\_IPoint3, point3.

Point coordinates are often specified with (0,0) in the corner of the volume. Matrices normally specify a rotation around the center of an volume. The <code>in\_volume</code> and <code>out\_volume</code> parameters are optional. If specified the dimension of the volumes are used to locate the

center of the input space and output space.

**SEE ALSO** AVW\_AddIPoint3(), AVW\_GetIPoint3(), AVW\_TransformFPoint3(),

AVW\_TransformIPoint2(), AVW\_TransformIPointlist3(), AVW\_TransformPoint3(),

AVW\_IPoint3, AVW\_Matrix, AVW\_Volume

AVW\_TransformIPointList2 - applies a matrix to a pointlist

**SYNOPSIS** 

#include "AVW.h"

int AVW\_TransformIPointList2(plist, matrix, in\_image, out\_image)

AVW\_IPointList2 \*plist; AVW\_Matrix \*matrix; AVW\_Image \*in\_image;

AVW\_Image \*out\_image;

**DESCRIPTION** 

 $AVW\_TransformIPointList2()$  applies the 4x4 transformation  $AVW\_Matrix$ , matrix, to the  $AVW\_IPointList2$ , plist.

Point coordinates are often specified with (0,0) in the corner of the image. Matrices normally specify a rotation around the center of an image. The *in\_image* and *out\_image* parameters are optional. If specified the dimension of the images are used to locate the center of the input space and output space.

**SEE ALSO** 

 $AVW\_AddIPointList2(),\ AVW\_GetIPointList2(),\ AVW\_TransformFPointList2(),\ AVW\_TransformIPointList2(),\ AVW\_TransformIPointList2(),\ AVW\_IPointList2,\ AVW\_Matrix,\ AVW\_Image$ 

**NAME** AVW\_TransformIPointList3 – applies a matrix to a pointlist

SYNOPSIS #include "AVW.h"

int AVW\_TransformIPointList3(plist, matrix, in\_volume, out\_volume)

AVW\_IPointList3 \*plist; AVW\_Matrix \*matrix; AVW\_Volume \*in\_volume;

AVW\_Volume \*out\_volume;

**DESCRIPTION** AVW\_TransformIPointList3() applies the 4x4 transformation AVW\_Matrix, matrix, to the

AVW\_IPointList3, plist.

Point coordinates are often specified with (0,0) in the corner of the volume. Matrices normally specify a rotation around the center of an volume. The *in\_volume* and *out\_volume* parameters are optional. If specified the dimension of the volumes are used to locate the center of the input space and output space.

**SEE ALSO** AVW\_AddIPointList3(), AVW\_GetIPointList3(), AVW\_TransformFPointList3(),

 $AVW\_TransformIPoint3(),\ AVW\_TransformIPointList2(),\ AVW\_TransformPointList3(),$ 

AVW\_IPointList3, AVW\_Matrix, AVW\_Volume

AVW\_TransformImage - applies a matrix to an image

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_TransformImage(in\_image, matrix, interpolate\_type, trans\_image)

AVW\_Image \*in\_image;

AVW\_Matrix \*matrix;

int interpolate\_type;

AVW\_Image \*trans\_image;

**DESCRIPTION** 

AVW\_TransformImage() applies the 4x4 transformation AVW\_Matrix, matrix, to in\_image.

*Interpolate\_type* determines the method of interpolation to use. Choose from:

AVW\_NEAREST\_NEIGHBOR\_INTERPOLATE

AVW\_LINEAR\_INTERPOLATE

AVW\_CUBIC\_SPLINE\_INTERPOLATE

AVW\_WINDOWED\_SINC\_INTERPOLATE

Trans\_image is used to return the results of the transformation. If NULL is passed trans\_image will be allocated with the same dimensions as in\_image. The results of the transformation can be placed in a larger or smaller image. In this case AVW\_CreateImage() may be called to create an image of desired dimensions. This image is then passed to the routine and the results are returned in it. Trans\_image will not be reallocated if it does not match the size of in\_image as in other functions.

**RETURN VALUES** 

If successful AVW\_TransformImage() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_TransformImage() will fail if the following is true:

**BADMAL** 

Could not allocate memory for the results.

**CFLSZ** 

Input and output data types conflict.

**SEE ALSO** 

AVW\_FlipImage(), AVW\_Rotate90Image(), AVW\_ShiftImage(), AVW\_TransformVolume(), AVW\_Image, AVW\_Matrix

**NAME** AVW\_TransformPoint2 – applies a matrix to a point

SYNOPSIS #include "AVW.h"

int AVW\_TransformPoint2(point2, matrix, in\_image, out\_image)

AVW\_Point2 \*point2; AVW\_Matrix \*matrix; AVW\_Image \*in\_image;

AVW\_Image \*out\_image;

**DESCRIPTION** | AVW\_TransformPoint2() applies the 4x4 transformation AVW\_Matrix, matrix, to the

AVW\_Point2, point2.

Point coordinates are often specified with (0,0) in the corner of the image. Matrices normally specify a rotation around the center of an image. The *in\_image* and *out\_image* parameters are optional. If specified the dimension of the images are used to locate the

center of the input space and output space.

SEE ALSO | AVW\_AddPoint2(), AVW\_GetPoint2(), AVW\_TransformFPoint2(), AVW\_TransformIPoint2(),

AVW\_TransformPoint3(), AVW\_TransformPointList2(), AVW\_Point2, AVW\_Matrix,

AVW\_Image

AVW\_TransformPoint3 - applies a matrix to a point

**SYNOPSIS** 

#include "AVW.h"

int AVW\_TransformPoint3(point3, matrix, in\_volume, out\_volume)

AVW\_Point3 \*point3; AVW\_Matrix \*matrix;

AVW\_Volume \*in\_volume;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

 $AVW\_TransformPoint3()$  applies the 4x4 transformation  $AVW\_Matrix$ , matrix, to the  $AVW\_Point3$ , point3.

Point coordinates are often specified with (0,0) in the corner of the volume. Matrices normally specify a rotation around the center of an volume. The *in\_volume* and *out\_volume* parameters are optional. If specified the dimension of the volumes are used to locate the center of the input space and output space.

**SEE ALSO** 

 $AVW\_AddPoint3(),\ AVW\_GetPoint3(),\ AVW\_TransformFPoint3(),\ AVW\_TransformIPoint3(),\ AVW\_TransformPoint2(),\ AVW\_TransformPointList3(),\ AVW\_Point3,\ AVW\_Matrix,\ AVW\_Volume$ 

NAME AVV

AVW\_TransformPointList2 - applies a matrix to a pointlist

**SYNOPSIS** 

#include "AVW.h"

int AVW\_TransformPointList2(plist, matrix, in\_image, out\_image)

AVW\_PointList2 \*plist; AVW\_Matrix \*matrix; AVW\_Image \*in\_image;

AVW\_Image \*out\_image;

**DESCRIPTION** 

*AVW\_TransformPointList2()* applies the 4x4 transformation *AVW\_Matrix, matrix,* to the *AVW\_PointList2, plist.* 

Point coordinates are often specified with (0,0) in the corner of the image. Matrices normally specify a rotation around the center of an image. The *in\_image* and *out\_image* parameters are optional. If specified the dimension of the images are used to locate the center of the input space and output space.

**SEE ALSO** 

 $AVW\_AddPointList2(),\ AVW\_GetPointList2(),\ AVW\_TransformFPointList2(),\ AVW\_TransformPointList2(),\ AVW\_TransformPointList3(),\ AVW\_TransformPoint2(),\ AVW\_PointList2,\ AVW\_Matrix,\ AVW\_Image$ 

AVW\_TransformPointList3 - applies a matrix to a pointlist

**SYNOPSIS** 

#include "AVW.h"

int AVW\_TransformPointList3(plist, matrix, in\_volume, out\_volume)

AVW\_PointList3 \*plist; AVW\_Matrix \*matrix;

AVW\_Volume \*in\_volume; AVW\_Volume \*out\_volume;

**DESCRIPTION** 

 $AVW\_TransformPointList3()$  applies the 4x4 transformation  $AVW\_Matrix$ , matrix, to the  $AVW\_PointList3$ , plist.

Point coordinates are often specified with (0,0) in the corner of the volume. Matrices normally specify a rotation around the center of an volume. The *in\_volume* and *out\_volume* parameters are optional. If specified the dimension of the volumes are used to locate the center of the input space and output space.

**SEE ALSO** 

 $AVW\_TransformFPointList3(),\ AVW\_TransformIPointList3(),\ AVW\_TransformPoint3(),\ AVW\_TransformPointList2(),\ AVW\_PointList3,\ AVW\_Matrix,\ AVW\_Volume$ 

AVW\_TransformVolume - applies a matrix to a volume

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_TransformVolume(in\_volume, matrix, interpolate\_type, trans\_volume)

AVW\_Volume \*in\_volume;

AVW\_Matrix \*matrix;

int interpolate\_type;

AVW\_Volume \*trans\_volume;

#### **DESCRIPTION**

AVW\_TransformVolume() applies the 4x4 transformation AVW\_Matrix, matrix, to in\_volume.

*Interpolate\_type* determines the method of interpolation to use. Choose from:

AVW\_NEAREST\_NEIGHBOR\_INTERPOLATE

AVW\_LINEAR\_INTERPOLATE

AVW\_CUBIC\_SPLINE\_INTERPOLATE

AVW\_WINDOWED\_SINC\_INTERPOLATE

Trans\_volume is used to return the results of the transformation. If NULL is passed trans\_volume will be allocated with the same dimensions as in\_volume. The results of the transformation can be placed in a larger or smaller volume. In this case AVW\_CreateVolume() may be called to create a volume of desired dimensions. This volume is then passed to the routine and the results are returned in it. Trans\_volume will not be reallocated if it does not match the size of in\_volume as in other functions.

#### **RETURN VALUES**

If successful *AVW\_TransformVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

*AVW\_TransformVolume()* will fail if the following is true:

BADMAL

Could not allocate memory for the results.

**CFLSZ** 

Input and output data types conflict.

# **SEE ALSO**

 $AVW\_FlipVolume(),\ AVW\_TransformImage(),\ AVW\_TransformVolumeSliceBySlice(),\ AVW\_Matrix,\ AVW\_Volume$ 

AVW\_TransformVolumeSliceBySlice - applies a matrix to a volume slice by slice

**SYNOPSIS** 

#include "AVW.h"

AVW\_Image \*AVW\_TransformVolumeSliceBySlice(in\_volume, matrix, interpolate\_type, nslices, slice, trans\_image)

AVW\_Volume \*in\_volume;

AVW Matrix \*matrix;

int interpolate\_type;

int nslices,

int slice;

AVW\_Image \*trans\_image;

#### **DESCRIPTION**

AVW\_TransformVolumeSliceBySlice() applies the 4x4 transformation AVW\_Matrix, matrix, to in\_volume.

*Interpolate\_type* determines the method of interpolation to use. Choose from:

AVW\_NEAREST\_NEIGHBOR\_INTERPOLATE

AVW\_LINEAR\_INTERPOLATE

AVW\_CUBIC\_SPLINE\_INTERPOLATE

AVW\_WINDOWED\_SINC\_INTERPOLATE

*Nslices* specifies the number of slices in the reformated volume.

*Slice* specifies which slice to reformat in the reformated volume.

*Trans\_image* is used to return the results of the transformation.

If *NULL* is passed *trans\_image* will be allocated with the same dimensions as *in\_volume* (Width & Height dimension only). The results of the transformation can be placed in a larger or smaller image. In this case *AVW\_CreateImage()* may be called to create an image of desired dimensions. This image is then passed to the routine and the results are returned in it. *Trans\_image* will not be reallocated if it does not match the *DataType* of *in volume* as in other functions.

# **RETURN VALUES**

If successful AVW\_TransformVolumeSliceBySlice() returns an AVW\_Image. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

## **ERRORS**

AVW\_TransformVolumeSliceBySlice() will fail if the following is true:

BADMAL

Could not allocate memory for the results.

**CFLSZ** 

Input and output data types conflict.

# **SEE ALSO**

AVW\_FlipVolume(), AVW\_TransformImage(), AVW\_TransformVolume(), AVW\_Image, AVW\_Matrix, AVW\_Volume

**NAME** AVW\_TranslateMatrix - translates a transformation matrix

**SYNOPSIS** #include "AVW.h"

AVW\_Matrix \*AVW\_TranslateMatrix(in\_matrix, xvoxels, yvoxels, zvoxels, out\_matrix)

AVW\_Matrix \*in\_matrix;

double xvoxels; double yvoxels; double zvoxels;

AVW\_Matrix \*out\_matrix;

**DESCRIPTION** AVW\_TranslateMatrix() applies the translation specified by xvoxels, yvoxels, and zvoxels to

the AVW\_Matrix, in\_matrix.

Out\_matrix is provided as a method of reusing an existing AVW\_Matrix. (See Memory

Usage in the AVW Programmer's Guide.)

**RETURN VALUES** If successful AVW\_TranslateMatrix() returns an AVW\_Matrix. On failure it returns NULL

and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause

of the failure.

**SEE ALSO** AVW\_CopyMatrix(), AVW\_CreateMatrix(), AVW\_DestroyMatrix(), AVW\_InvertMatrix(),

> AVW\_MakeMatrixFrom3Points(), AVW\_MakeMatrixFromAxis(), AVW\_MatrixAngles(), AVW\_MirrorMatrix(), AVW\_MultiplyMatrix(), AVW\_RotateMatrix(), AVW\_ScaleMatrix(),

AVW\_SetIdentityMatrix(), AVW\_Matrix

**NAME** AVW\_TranslatePointList2 – translates the points in a point list

SYNOPSIS #include "AVW.h"

 $int\ AVW\_TranslatePointList2(ptlist, xshift, yshift)$ 

AVW\_PointList2 \*ptlist;

int xshift;
int yshift;

**DESCRIPTION** | AVW\_TranslatePointList2() applies the translation specified by xshift and yshift to the

AVW\_PointList2, ptlist.

**RETURN VALUES** If successful *AVW\_TranslatePointList2()* returns *AVW\_SUCCESS*. On failure *AVW\_FAIL* is

returned.

**SEE ALSO** *AVW\_AddPoint2(), AVW\_ClipPointList2(), AVW\_ClosestInPointList2(),* 

AVW\_CopyPointList2(), AVW\_CreatePointList2(), AVW\_DestroyPointList2(),

AVW\_FillPointList2(), AVW\_GetPoint2(), AVW\_RemovePoint2(), AVW\_RotatePointList2(),

AVW\_ScalePointList2(), AVW\_TransformPoint2(), AVW\_PointList2

AVW\_TreeAnalysis - calculate tree statistics

#### **SYNOPSIS**

#include "AVW\_Tree.h"

int AVW\_TreeAnalysis(tree, volume, t\_max, tmin, c\_radius, filename)

AVW\_Tree \*tree;

AVW\_Volume \*volume;

double t max, tmin;

int c\_radius;

char \*filename;

### **DESCRIPTION**

AVW\_TreeAnalysis creates detailed and summary statictics files for an AVW\_Tree structure,

.I tree,

within a volume. Small oblique images are generated for each point along the tree and statistical information is written to a disk file.

*Tree* is an  $AVW\_Tree$  structure which describes a vessel structures within a volume. See  $AVW\_MakeTree()$ .

Volume contains the information to be measured.

*T\_max* and *t\_min* allow voxels outside a threshold range to excluded in calculations.

*C\_radius* defines a circle mask, which eliminates voxels outside the mask. Small vessel trees will need a smaller circle size. *C\_Radius* should be set to the expected maximum vessel radius.

*Filename* specifies the filename and path for the files. ".stats" will be appended to the file containing the detailed statistics and "\_sum.stats" is appended for the summary file. Each individual oblique image is also saved to a file, the name of this file is "filename.moblq".

**Detailed Format** 

```
#File Name = filename.stats
#
      Brightness
       Area
# Name Segment Product Area X Y Z
#===== ===== ==== ==== ==== ====
        123.56 123 12 34 56
 Α1
   1
  Summary Format
#File Name = filename_sum.stats
#
   Average
#
   Brightness
                           Children
    Area
         BAP Average Area
# Name Product St Dev Area St Dev Length (Index, Angle)
```

12.34 123.56 1.23 123 (B1, 61.3) (B2, 123.0)

*Name* is made up of two parts, level and index. Level is represented by a single capital letter, or for complex trees, a single small letter followed by a single capitol letter. The index part, is shown as single or multiple digits. The index starts at 1 and counts up for different branchs at a given level. *Names* can be used to locate child segments.

*Segment* is a count of each individual oblique image along the tree path. It begins at 1 for each branch point.

*Brightness Area Product* is the measure of the sum of all brightness values once the *t\_min* value has been subtracted.

Area is the count of all voxels within the circle mask and the threshold range.

*X*, *Y*, and *Z* are the coordinates for the center point of each oblique image.

Average BAP is the average of all BAPs for that branch.

BAP St Dev is the standard deviation of the BAPs.

Average Area is the average of all the areas for that branch.

*Length* indicates the length of the branch.

*Children* indicates if the tree continues. If values are present they are paired, with the name of the child branch followed by it's 3D angle from it's parent branch.

#### **RETURN VALUES**

If successful *AVW\_TreeAnalysis()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

#### **ERRORS**

AVW\_TreeAnalysis() will fail if:

**SCRERR** 

Unable to create stats file.

**SEE ALSO** 

AVW\_MakeTree(), AVW\_Tree, AVW\_Volume

AVW\_UltimateErosionImage - reduces an image to its final components

**SYNOPSIS** 

#include "AVW.h"

 $AVW\_Image *AVW\_UltimateErosionImage (in\_image, element, out\_image)$ 

AVW\_Image \*in\_image;

AVW\_Image \*element;

AVW\_Image \*out\_image;

#### **DESCRIPTION**

AVW\_UltimateErosionImage() performs succesive erosions on in\_image using element. The erosion process creates disconnected components which eventually disappear. The collection of these components prior to being eliminated from the image via erosion make up the final components of the image. Out\_image will contain the final components which are labelled with the number of erosions required to create them.

*Element* is translated so that its centerpoint lies on every point of the image. At each point in the data, if a nonzero pixel in the structuring element corresponds to a zero pixel in the data the point in the result data is set to zero. Otherwise the pixel is unchanged. This process is repeated until all final components have been collected.

In\_image does not have to be a binary valued image, but all nonzero pixels are treated as ones. In\_image, out\_image, and element must be of the data type AVW\_UNSIGNED\_CHAR. This function will allocate temporary storage space for results if in\_image and out\_image are the same.

AVW\_CreateStructuringImage() or AVW\_CreateImage(), AVW\_SetImage(), and AVW\_PutPixel() may be used to create a structuring element

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful *AVW\_UltimateErosionImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_UltimateErosionImage() will fail if:

**ILLDT** 

Data type is not AVW\_UNSIGNED\_CHAR.

## **SEE ALSO**

AVW\_UltimateErosionVolume(), AVW\_CreateStructuringImage(), AVW\_ErodeImage(), AVW\_CreateImage(), AVW\_SetImage(), AVW\_PutPixel(), AVW\_Image

AVW UltimateErosionVolume – reduces a volume to its final components

**SYNOPSIS** 

#include "AVW.h"

AVW\_Volume \*AVW\_UltimateErosionVolume(in\_volume, element, out\_volume)

 $AVW\_Volume * in\_volume;$ 

AVW\_Volume \*element;

AVW\_Volume \*out\_volume;

#### DESCRIPTION

AVW\_UltimateErosionVolume() performs succesive erosions on in\_volume using element. The erosion process creates disconnected components which eventually disappear. The collection of these components prior to being eliminated from the volume via erosion make up the final components of the volume. Out\_volume will contain the final components which are labelled with the number of erosions required to create them.

*Element* is translated so that its centerpoint lies on every point of the volume. At each point in the data, if a nonzero voxel in the structuring element corresponds to a zero voxel in the data the point in the result data is set to zero. Otherwise the voxel is unchanged. This process is repeated until all final components have been collected.

In\_volume does not have to be a binary valued volume, but all nonzero voxels are treated as ones. In\_volume, out\_volume, and element must be of the data type AVW\_UNSIGNED\_CHAR. This function will allocate temporary storage space for results if in\_volume and out\_volume are the same.

AVW\_CreateStructuringVolume() or AVW\_CreateVolume(), AVW\_SetVolume(), and AVW\_PutVoxel() may be used to create a structuring element

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_UltimateErosionVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_UltimateErosionVolume() will fail if:

**ILLDT** 

Data type is not AVW\_UNSIGNED\_CHAR.

**SEE ALSO** 

 $AVW\_UltimateErosionImage(),\ AVW\_CreateStructuringVolume(),\ AVW\_ErodeVolume(),\ AVW\_Level(),\ AVW\_Volume(),\ AVW\_Volume(),\$ 

AVW\_UnsharpFilterEnhanceImage - enhances an image by Unsharp filtering

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Image \*AVW\_UnsharpFilterEnhanceImage(in\_image, extents, out\_image)

AVW\_Image \*in\_image;

int extents[2];

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_UnsharpFilterEnhanceImage() performs a Unsharp filter transformation on in\_image. The returned out\_image is created by adding in\_image to the Unsharp filter transformation of the input image.

Extents[0], and extents[1], specify the x and y sizes respectively of the filter.

The unsharp filter is a high-pass filter created by subtracting a low-pass filtered image from the original.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful  $AVW\_UnsharpFilterEnhanceImage()$  returns an  $AVW\_Image$ . On failure it returns NULL and sets  $AVW\_ErrorNumber$  and  $AVW\_ErrorMessage$  to values corresponding to the failure.

**SEE ALSO** 

AVW\_AHEImage(), AVW\_AnisotropicAffineImage(), AVW\_AnisotropicDiffusionImage(), AVW\_LowpassFilterImage(), AVW\_OrthoGradFilterImage(), AVW\_RankFilterImage(), AVW\_SigmaFilterImage(), AVW\_SobelFilterImage(), AVW\_SobelFilterEnhanceImage(), AVW\_UnsharpFilterImage(), AVW\_UnsharpFilterImage(), AVW\_Image

AVW\_UnsharpFilterEnhanceVolume - enhances a volume by Unsharp filtering

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Volume \*AVW\_UnsharpFilterEnhanceVolume(in\_volume, extents, out\_volume) AVW\_Volume \*in\_volume;

int extents[3];

AVW Volume \*out volume:

**DESCRIPTION** 

*AVW\_UnsharpFilterEnhanceVolume()* performs a Unsharp filter transformation on *in\_volume*. The returned *out\_volume* is created by adding *in\_volume* to the Unsharp filter transformation of the input volume.

*Extents*[0], extents[1], and extents[2] specify the x, y, and z sizes respectively of the filter.

The unsharp filter is a high-pass filter created by subtracting a low-pass filtered volume from the original.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_UnsharpFilterEnhanceVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_AHEVolume(), AVW\_InhomogeneityCorrectVolume(), AVW\_LowpassFilterVolume(), AVW\_OrthoGradFilterVolume(), AVW\_RankFilterVolume(), AVW\_SobelFilterVolume(), AVW\_SobelFilterEnhanceVolume(), AVW\_SigmaFilterVolume(), AVW\_UnsharpFilterEnhanceImage(), AVW\_UnsharpFilterVolume(), AVW\_VSFMeanFilterVolume(), AVW\_Volume

AVW\_UnsharpFilterImage - performs a 2D Unsharp filter

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Image \*AVW\_UnsharpFilterImage(in\_image, extents, out\_image)

AVW\_Image \*in\_image;

int extents[2];

AVW\_Image \*out\_image;

**DESCRIPTION** 

AVW\_UnsharpFilterImage() performs an Unsharp filter transformation on in\_image.

*Extents*[0] and *extents*[1] specify the x and y sizes respectively of the filter.

The unsharp filter is a high-pass filter created by subtracting a low-pass filtered image from the original.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_UnsharpFilterImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_AHEImage(), AVW\_AnisotropicAffineImage(), AVW\_AnisotropicDiffusionImage(), AVW\_LowpassFilterImage(), AVW\_OrthoGradFilterImage(), AVW\_RankFilterImage(), AVW\_SigmaFilterImage(), AVW\_SobelFilterImage(), AVW\_SobelFilterEnhanceImage(), AVW\_UnsharpFilterVolume(), AVW\_Image

AVW\_UnsharpFilterVolume - performs a 3D Unsharp filter

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Volume \*AVW\_UnsharpFilterVolume(in\_volume, extents, out\_volume)

AVW\_Volume \*in\_volume;

int extents[3];

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_UnsharpFilterVolume() performs an Unsharp filter transformation on in\_volume.

Extents[0], extents[1], and extents[2] specify the x, y, and z sizes respectively of the filter.

The unsharp filter is a high-pass filter created by subtracting a low-pass filtered volume from the original.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_UnsharpFilterVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

AVW\_AHEVolume(), AVW\_InhomogeneityCorrectVolume(), AVW\_LowpassFilterVolume(), AVW\_OrthoGradFilterVolume(), AVW\_RankFilterVolume(), AVW\_SobelFilterVolume(), AVW\_SobelFilterEnhanceVolume(), AVW\_SigmaFilterVolume(), AVW\_UnsharpFilterImage(), AVW\_UnsharpFilterEnhanceImage(), AVW\_VSFMeanFilterVolume(), AVW\_Volume

AVW\_UnsuperClassifyImage - classifies pixels from multi-spectral data sets

# **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_UnsuperClassifyImage(imgs, numimgs, type, centroidArray, threshold, pchange, classes, out\_image)

AVW\_Image \*\*imgs; int numimgs; int type; char \*centroidfile; int threshold; double pchange; int classes; AVW\_Image \*out\_image;

# **DESCRIPTION**

AVW\_UnsuperClassifyImage() without supervision or training samples classifies pixels given multi-spectral data consisting of several input images. Three different algorithms can be used to classify unclassified pixels from the input mask image.

\*\*Imgs is a list of spatially correlated images, each of which represents one spectra of the multi-spectral data set. These input images must be of the same dimension and of data type AVW\_UNSIGNED\_CHAR. This input data is unchanged by the classification process.

Numings is the number of images in the array. imgs.

*Type* specifies the unsupervised classification algorithm. Acceptable values are *AVW\_UNSUPERVISED\_CHAIN*, *AVW\_UNSUPERVISED\_ISODATA*, and *AVW\_UNSUPERVISED\_ISOMERGE* 

The AVW\_UNSUPERVISED\_CHAIN technique arbitrarily assigns the first voxel within the data set to class 1, making it the initial centroid of that class. Subsequent voxels are placed into that class or a new class depending on their Euclidean distance from the class cetroids. The centroids are updated every time a new member is added to the class.

The AVW\_UNSUPERVISED\_ISODATA classifier calculates a set of centroids to cover a broad region of the feature space. Proximity of initial centroids to their final positions determines the number of iterations it takes to meet the stopping criteria. Voxels are classified based on their distance from the initial class centroids similarly to the superised Nearest Neighbors algorithm.

The AVW\_UNSUPERVISED\_ISOMERGE technique expands on the ISODATA algorithm to include merging of clusters whose centroids are closer than a user-defined threshold distance in feature space. At that point everything starts over, each voxel being compared to the newly merged cluster centroids in order to determine class membership.

*Centroidfile* is a text file containing centroids used to pass starting centroids of starting classes to *AVW\_UnsuperClassifyImage()*.

Threshold specifies the maximum distance that a voxel can be from existing class centroids before a new class is formed when type is AVW\_UNSUPERVISED\_CHAIN. For the AVW\_UNSUPERVISED\_ISOMERGE algorithm, this distance is the

AVW\_UNSUPERVISED\_ISODATA threshold is ignored.

*Pchange* specifies the stopping criterion for all the unsupervised classifiers. When the percentage of voxels which have changed from the previous iteration falls below this number, the classification stops.

*Classes* is used to randomly determine the number of class centroids chosen in feature space as initial class centroids.

*Out\_image* is the returned classified image. Pixels which have been successfully classified are set to values of pixels from the training sample mask image which they are most similar to. Pixels with a value of 0 were not classified by the function.

Out\_image is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_image meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reusable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful *AVW\_UnsuperClassifyImage()* returns an *AVW\_Image*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

*AVW\_ClassifyImage* will fail if one or more of the following are true:

#### **BADMAL**

Malloc Failed. A memory allocation failed.

# **ILLIMG**

Illegal Image. The images are not all the same dimension.

#### **INSPEC**

Insufficient Specifications. Fewer than two input images were supplied.

# **TOMNCLS**

To Many Unsupervised Classes. More than AVW\_MAX\_UNSUPERVISED\_CLASSES developed during classification. Try a smaller value for threshold.

# **SEE ALSO**

AVW\_ClassifiedImageToCentroidFile(), AVW\_ClassifyImage()
AVW\_ClassifyImageFromSampleFile(), AVW\_MaskImageToSampleFile(),
AVW\_UnsuperClassifyVolume() AVW\_Image

# **REFERENCES**

G.H. Ball & D.J. Hall "ISODATA", an iterative method of multivariate data analysis and pattern classification. In IEEE International Communications Conference, Philadelphia, June 1966.

AVW\_UnsuperClassifyVolume - classifies pixels from multi-spectral data sets

# **SYNOPSIS**

#include "AVW.h"

AVW\_Volme \*AVW\_UnsuperClassifyVolume(vols, numvols, type, centroidfile, threshold, pchange, classes, out\_vol)

AVW\_Volume \*\*vols; int numvols; int type; char \*centroidfile; int threshold; double pchange; int classes; AVW\_Volume \*out\_volume;

# **DESCRIPTION**

*AVW\_UnsuperClassifyVolume()* without supervision or training samples classifies voxels given multi-spectral data consisting of several input volumes. Three different algorithms can be used to classify unclassified voxels from the input volumes.

\*\*Vols is a list of spatially correlated volumes, each of which represents one spectra of the multi-spectral data set. These input volumes must be of the same dimension and of data type AVW\_UNSIGNED\_CHAR. This input data is unchanged by the classification process.

Numvols is the number of vols in the array vols.

*Type* specifies the unsupervised classification algorithm. Acceptable values are *AVW\_UNSUPERVISED\_CHAIN*, *AVW\_UNSUPERVISED\_ISODATA*, and *AVW\_UNSUPERVISED\_ISOMERGE* 

The AVW\_UNSUPERVISED\_CHAIN technique arbitrarily assigns the first voxel within the data set to class 1, making it the initial centroid of that class. Subsequent voxels are placed into that class or a new class depending on their Euclidean distance from the class centroids. The centroids are updated every time a new member is added to the class.

The AVW\_UNSUPERVISED\_ISODATA classifier calculates a set of centroids to cover a broad region of the feature space. Proximity of initial centroids to their final positions determines the number of iterations it takes to meet the stopping criteria. Voxels are classified based on their distance from the initial class centroids similar to the supervised Nearest Neighbors algorithm.

The AVW\_UNSUPERVISED\_ISOMERGE technique expands on the ISODATA algorithm to include merging of clusters whose centroids are closer than a user-defined threshold distance in feature space. At that point everything starts over, each voxel being compared to the newly merged cluster centroids in order to determine class membership.

*Centroidfile* is a text file containing centroids used to pass starting centroids of starting classes to *AVW\_UnsuperClassifyImage()*.

Threshold specifies the maximum distance that a voxel can be from existing class centroids before a new class is formed when type is AVW\_UNSUPERVISED\_CHAIN. For the AVW\_UNSUPERVISED\_ISOMERGE algorithm, this distance is the minimum distance between class centroids. Classes whose centroids are closer than this distance will be

merged into that class. For AVW\_UNSUPERVISED\_ISODATA threshold is ignored.

*Pchange* specifies the stopping criterion for all the unsupervised classifiers. When the percentage of voxels which have changed from the previous iteration falls below this number, the classification stops.

*Classes* is used to randomly determine the number of class centroids chosen in feature space as initial class centroids.

*Out\_volume* is the returned classified volume. Voxels which have been successfully classified are set to values of voxels from the training sample mask image to which they are most similar. Voxels with a value of 0 were not classified by the function.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

#### **RETURN VALUES**

If successful AVW\_UnsuperClassifyVolume() returns an AVW\_Volume. On failure it returns NULL and sets AVW\_ErrorNumber and AVW\_ErrorMessage to values corresponding to the cause of the failure.

# **ERRORS**

*AVW\_ClassifyVolume* will fail if one or more of the following are true:

## **BADMAL**

Malloc Failed. A memory allocation failed.

# **ILLVOL**

Illegal Volume. The volumes are not all the same dimension.

#### **INSPEC**

Insufficient Specifications. Fewer than two input volumes were supplied.

# **TOMNCLS**

To Many Unsupervised Classes. More than AVW\_MAX\_UNSUPERVISED\_CLASSES developed during classification. Try a smaller value for threshold.

# **SEE ALSO**

 $AVW\_ClassifiedVolumeToCentroidFile(),\ AVW\_ClassifyVolume(), \\ AVW\_ClassifyVolumeFromSampleFile(),\ AVW\_MaskVolumeToSampleFile(), \\ AVW\_UnsuperClassifyImage(),\ AVW\_Volume$ 

## **REFERENCES**

G.H. Ball & D.J. Hall "ISODATA", an iterative method of multivariate data analysis and pattern classification. In IEEE International Communications Conference, Philadelphia, June 1966.

AVW\_UpdateConfidenceClasses - updates liklihood data from AVW\_GetLiklihoods()

# **SYNOPSIS**

#include "AVW.h"

int AVW\_UpdateConfidenceClasses(classifiedImage, liklihoods, alpha) AVW\_Image \*classifiedImage; AVW\_Volume \*liklihoods double alpha;

#### **DESCRIPTION**

AVW\_UpdateConfidenceClasses() updates the liklihood data from AVW\_GetLiklihoods(). and reclassifies the passed in previously classifiedImage.

*classifiedImage* is image initially classified with the *AVW\_GAUSSIAN\_CLUSTER*, *AVW\_NEURAL\_NETWORK*, or *AVW\_PARZEN\_WINDOWS* classification algorithms.

liklihoods is the liklihood data returned by AVW\_GetLiklihoods().

alpha is a confidence-weighting parameter which controls the strength of the iterative relaxation. High alpha means that voxels are influenced more strongly by classification results of their spatial neighbors, and results in a smoother overall classification; low alpha means the opposite (alpha - 0.0) turns relaxation off). High values of Alpha (~4.0) are suggested for the AVW\_GAUUSIAN\_CLUSTER and AVW\_PARZEN\_WINDOWS classifiers and low values (~0.25) for the AVW\_NEURAL\_NETWORK classifier

AVW\_UpdateConfidenceClasses is used with other AVW functions to perform iterative relaxationon

classification performed with  $AVW\_ClassifyImage()$  or  $AVW\_ClassifyVolume()$  when the autotype parameter is set to one of the statistics based classification algorithms.  $AVW\_GAUSSIAN\_CLUSTER, AVW\_NEURAL\_NETWORK,$  or  $AVW\_PARZEN\_WINDOWS$ 

Once an initial multispectral classification has been performed, the data in the returned liklihood volume can be used in a process of iterative relaxation with the additional AVW functions AVW\_UpdateConfidenceClasses() and AVW\_UpdateImageClassification()

to re-evaluate the classification of individual pixels based on the class assignments of neighboring pixels and the relative probabilities that a pixel belongs to each class.

# **RETURN VALUES**

 $AVW\_Up date Confidence Classes () \ returns \ the \ number \ of \ pixels \ which \ were \ reclassified \ in \ classified Image.$ 

AVW\_UpdateConfidenceClasses() will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

**SEE ALSO** 

AVW\_ClassifyImage(), AVW\_ClassifyVolume(), AVW\_GetScatLiklihoods(), AVW\_UpdateImageClassification()

 $AVW\_UpdateImageClassification-updates~an~image~classification~through~iterative~relaxation$ 

#### **SYNOPSIS**

#include "AVW.h"

int AVW\_UpdateImageClassification(classifiedImage, liklihoods, alpha) AVW\_Image \*classifiedImage; AVW\_Volume \*liklihoods double alpha;

# **DESCRIPTION**

AVW\_UpdateImageClassification() uses iterative relaxation and liklihood information from a previous classification to re-evaluate and change voxels based on class assignements of neighboring voxels liklihood data from the last multispectral classification.

classifiedImage is an image initially classified with the AVW\_GAUSSIAN\_CLUSTER, AVW\_NEURAL\_NETWORK, or AVW\_PARZEN\_WINDOWS classification algorithms.

liklihoods is the liklihood data returned by AVW\_GetLiklihoods().

alpha is a confidence-weighting parameter which controls the strength of the iterative relaxation. High alpha means that voxels are influenced more strongly by classification results of their spatial neighbors, and results in a smoother overall classification; low alpha means the opposite (alpha - 0.0) turns relaxation off). High values of Alpha (~4.0) are suggested for the AVW\_GAUUSIAN\_CLUSTER and AVW\_PARZEN\_WINDOWS classifiers and low values (~0.25) for the AVW\_NEURAL\_NETWORK classifier

# **RETURN VALUES**

If successful *AVW\_UpdateImageClassification()* returns an the number of changed voxels in *classifiedImage*. On failure 0 is returned and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_UpdateImageClassification() will fail ifthe following is true:

**BADMAL** 

Malloc Failed. Unable to allocate memory for structure and/or pixel memory.

## **SEE ALSO**

AVW\_ClassifyImage(), AVW\_ClassifyVolume(), AVW\_GetScatLiklihoods(), AVW\_UpdateConfidenceClasses(), AVW\_GetLiklihoods()

AVW\_UpdateImageMask - updates image pixel values

**SYNOPSIS** 

#include "AVW.h"

int AVW\_UpdateImageMask(image, mask, mode, value)

AVW\_Image \*image;

AVW\_Image \*mask;

int mode;

double value:

#### **DESCRIPTION**

AVW\_UpdateImageMask() sets the value of all of the pixels of image to a value based on the corresponding value in mask and the mode value.

The *mode* parameter determines how pixels values are determined:

A value of *AVW\_REPLACE\_MASK\_VALUE* specifies that all of the pixels values of *image* are set to *value* if the corresponding pixel in *mask* is nonzero.

A value of *AVW\_MAINTAIN\_MASK\_VALUE* means that only the zero valued pixels of *image* that correspond to nonzero pixels in *mask* are set to *value*. The nonzero pixels of *image* maintain their value regadless of the corresponding pixel value in *mask*.

AVW\_NEW\_MASK\_VALUE causes each seperate connected intersection of the two images to become a new intensity. The maximum of the *image* is determined and the intersections are assigned values above the maximum as they are encountered. Zero valued pixels of *image* that correspond to nonzero pixels in *mask* are set to *value*.

A value of *AVW\_OR\_MASK\_VALUE* causes the pixel value in *image* to be OR'd with *value* for each non-zero pixel in *mask*.

A value of *AVW\_AND\_MASK\_VALUE* causes the pixel value in *image* to be AND'd with *value* for each non-zero pixel in *mask*.

Mask must be of data type AVW\_UNSIGNED\_CHAR.

#### **RETURN VALUES**

If successful *AVW\_UpdateImageMask()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_UpdateImageMask() will fail if:

**ILLDT** 

Illegal data type.

**ILLPAR** 

A NULL image was specified.

**CFLSZ** 

The images were not the same size.

# **SEE ALSO**

AVW\_GetMaskedImage(), AVW\_MakeMaskFromTrace(), AVW\_PutMaskedImage(), AVW\_UpdateVolumeMask(), AVW\_Image

AVW\_UpdateVolumeMask - updates volume voxel values

# **SYNOPSIS**

#include "AVW.h"

int AVW\_UpdateVolumeMask(volume, mask, mode, value)

AVW\_Volume \*volume;

AVW\_Volume \*mask;

int mode, value:

# **DESCRIPTION**

AVW\_UpdateVolumeMask() sets the value of all of the voxels of volume to a value based on the corresponding value in mask and the mode value.

The *mode* parameter determines how voxels values are determined:

A value of *AVW\_REPLACE\_MASK\_VALUE* specifies that all of the voxels values of *volume* are set to *value* if the corresponding voxel in *mask* is nonzero.

A value of *AVW\_MAINTAIN\_MASK\_VALUE* means that only the zero valued voxels of *volume* that correspond to nonzero voxels in *mask* are set to *value*. The nonzero voxels of *volume* maintain their value regadless of the corresponding voxel value in *mask*.

AVW\_NEW\_MASK\_VALUE causes each seperate connected intersection of the two volumes to become a new intensity. The maximum of the *volume* is determined and the intersections are assigned values above the maximum as they are encountered. Zero valued voxels of *volume* that correspond to nonzero voxels in *mask* are set to *value*.

A value of *AVW\_OR\_MASK\_VALUE* causes the voxel value in *volume* to be OR'd with *value* for each non-zero voxel in *mask*.

A value of *AVW\_AND\_MASK\_VALUE* causes the voxel value in *volume* to be AND'd with *value* for each non-zero voxel in *mask*.

Volume and Mask must be of data type AVW\_UNSIGNED\_CHAR.

## **RETURN VALUES**

If successful *AVW\_UpdateVolumeMask()* returns *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_UpdateVolumeMask() will fail if:

ILLDT

Illegal data type.

**ILLPAR** 

A NULL volume was specified.

**CFLSZ** 

The volumes were not the same size.

# **SEE ALSO**

 $AVW\_GetMaskedVolume(),\ AVW\_MakeMaskFromTrace(),\ AVW\_PutMaskedVolume(),\ AVW\_UpdateImageMask(),\ AVW\_Volume$ 

AVW\_VSFMeanFilterVolume - performs a VSFmean filter

**SYNOPSIS** 

#include "AVW Filter.h"

AVW\_Volume \*AVW\_VSFMeanFilterVolume(in\_volume, ring, sigma, out\_volume) AVW\_Volume \*in\_volume;

int ring; int sigma;

AVW\_Volume \*out\_volume;

**DESCRIPTION** 

AVW\_VSFMeanFilterVolume() performs a VSFmean filter transformation on the input volume. Voxels are averaged in a circular neighborhood of size *ring* voxels about a seed voxel. Neighboring voxels whose values differ from the seed voxel by a value greater than *sigma* are not included in the mean calculation.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reusable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

**RETURN VALUES** 

If successful *AVW\_VSFMeanFilterVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**SEE ALSO** 

 $AVW\_AHEVolume(),\ AVW\_InhomogeneityCorrectVolume(),\ AVW\_LowpassFilterVolume(),\ AVW\_OrthoGradFilterVolume(),\ AVW\_RankFilterVolume(),\ AVW\_SigmaFilterVolume(),\ AVW\_SobelFilterEnhanceVolume(),\ AVW\_UnsharpFilterVolume(),\ AVW\_UnsharpFilterEnhanceVolume(),\ AVW\_Volume(),\ A$ 

 $AVW\_ValidationErrorFunction\ - indicates\ the\ function\ which\ handles\ validation\ error\ reporting$ 

**SYNOPSIS** 

#include "AVW.h"

void AVW\_ValidationErrorFunction(int (\*function)())

**DESCRIPTION** 

By default, *AVW* dumps all validation errors to either *stdout* or *stderr*. *AVW\_ValidationErrorFunction* allows the programmer the capability of reporting the errors to the user in a friendlier fashion. The user can also choose to attempt recovery, if the condition is recoverable.

When a validation error is detected, AVW\_VALIDATE\_UNRECOVERABLE, AVW\_VALIDATE\_RECOVERABLE or AVW\_VALIDATE\_WARNING. If the type is AVW\_VALIDATE\_RECOVERABLE the return value from the function is checked, if one (1), the function which reported the error will be retried.

AVW\_VerifyDataType - verifies valid AVW data types

**SYNOPSIS** 

#include "AVW.h"

int AVW\_VerifyDataType(type)

int type;

**DESCRIPTION** 

AVW\_VerifyDataType() verifies that type is a supported AVW data type.

Valid *AVW* data types, defined in *AVW.h*, include:

 $AVW\_UNSIGNED\_CHAR$ 

AVW\_SIGNED\_CHAR

 $AVW\_UNSIGNED\_SHORT$ 

AVW\_SIGNED\_SHORT

AVW\_UNSIGNED\_INT

 $AVW\_SIGNED\_INT$ 

 $AVW\_FLOAT$ 

AVW\_COMPLEX

AVW\_COLOR

**RETURN VALUES** 

If successful  $AVW\_VerifyDataType()$  returns  $AVW\_TRUE$ . On failure it returns

AVW\_FALSE.

**SEE ALSO** 

 $AVW\_VerifyImage(),\,AVW\_VerifyVolume()$ 

**NAME** AVW\_VerifyHistogram – verifies a valid AVW\_Histogram

**SYNOPSIS** #include "AVW\_Histogram.h"

int AVW\_VerifyHistogram(histo)

AVW\_Histogram \*histo;

**DESCRIPTION** | *AVW\_VerifyHistogram()* verifies that *histo* is a supported *AVW\_Histogram*.

**RETURN VALUES** If successful *AVW\_VerifyHistogram()* returns *AVW\_TRUE*. On failure it returns

AVW\_FALSE.

**SEE ALSO** | AVW\_ClearHistogram(), AVW\_CreateHistogram(), AVW\_DestroyHistogram(),

 $AVW\_GetImageHistogram(),\ AVW\_GetVolumeHistogram(),\ AVW\_NormalizeHistogram(),$ 

AVW\_ReadHistogram(), AVW\_WriteHistogram(), AVW\_Histogram

AVW\_VerifyImage – verifies a valid AVW\_Image structure

**SYNOPSIS** 

#include "AVW.h"

int AVW\_VerifyImage(image)

AVW\_Image \*image;

**DESCRIPTION** 

*AVW\_VerifyImage()* checks consistancy within the *AVW\_Image* structure elements to determine if the pointer is to a valid *AVW\_Image*.

An invalid *AVW\_Image* is detected if:

image->Mem is NULL,

*image->DataType* is invalid,

image->Width or image->Height are zero or negative,

image->BytesPerPixel incorrect for image->Datatype,

image->BytesPerLine does not equal image->BytesPerPixel X image->Width,

image->BytesPerImage does not equal image->BytesPerLine X image->Height,

image->PixelsPerImage does not equal image->Width X image->Height.

**RETURN VALUES** 

If successful AVW\_VerifyImage() returns AVW\_TRUE. On failure it returns AVW\_FALSE.

**SEE ALSO** 

AVW\_ClosestPointInImage(), AVW\_CopyImage(), AVW\_CreateImage(), AVW\_DestroyImage(), AVW\_VerifyDataType(), AVW\_VerifyVolume(), AVW\_Image

AVW\_VerifyVolume - verifies a valid AVW\_Volume structure

**SYNOPSIS** 

#include "AVW.h"

int AVW\_VerifyVolume(volume) AVW\_Volume \*volume;

**DESCRIPTION** 

*AVW\_VerifyVolume()* checks consistancy within the *AVW\_Volume* structure elements to determine if the pointer is to a valid *AVW\_Volume*.

An invalid AVW\_Volume is detected if:

volume->Mem is NULL,

volume->Datatype is illegal,

volume->Width, volume->Height or volume->Depth are zero or negative,

volume->BytesPerPixel incorrect for volume->DataType,

volume->BytesPerLine does not equal volume->BytesPerPixel X volume->Width,

volume->BytesPerImage does not equal volume->BytesPerLine X volume->Height,

volume->PixelsPerImage does not equal volume->Width X volume->Height,

*volume->BytesPerVolume* does not equal *volume->BytesPerImage* X *volume->Depth*,

*volume->VoxelsPerVolume* does not equal *volume->Width* X *volume->Height* times *volume->Depth*.

**RETURN VALUES** 

If successful *AVW\_VerifyVolume()* returns *AVW\_TRUE*. On failure it returns *AVW\_FALSE*.

**SEE ALSO** 

 $AVW\_CopyVolume(),\ AVW\_CreateVolume(),\ AVW\_DestroyVolume(),\\ AVW\_MakeVolumeFromImage(),\ AVW\_VerifyDataType(),\ AVW\_VerifyImage(),\\ AVW\_Volume$ 

AVW\_VolumeOpConstant – transforms a volume mathematically

**SYNOPSIS** 

#include "AVW Parse.h"

AVW\_Volume \*AVW\_VolumeOpConstant(in\_volume, operation, value, out\_volume)

AVW\_Volume \*in\_volume;

int operation;

double value;

AVW\_Volume \*out\_volume;

#### **DESCRIPTION**

AVW\_VolumeOpConstant() applies the operation and value to in\_volume and returns the resulting volume:

output = in\_volume operation value

AVW\_VolumeOpConstant(), calls AVW\_ImageOpConstant(), with each slice in the input volume to produce the output volume.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume meet the requirements of the function. In this case the pointer to out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

The following operations are defined in AVW\_Parse.h:

 $AVW\_OP\_ADD$ 

AVW\_OP\_SUB

AVW\_OP\_MUL

AVW\_OP\_DIV

 $AVW_OP_LT$ 

 $AVW\_OP\_GT$ 

 $AVW\_OP\_LE$ 

 $AVW_OP_GE$ 

 $AVW_OP_EQ$ 

AVW\_OP\_NE

 $AVW\_OP\_AND$ 

 $AVW_OP_OR$ 

AVW\_OP\_MOD

# **RETURN VALUES**

If successful *AVW\_VolumeOpConstant()*, returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_VolumeOpConstant() will fail if one or more of the following are true:

**NOTSUP** 

Operation is not supported.

**DIVZER** 

Division by zero.

**BADMAL** 

Memory could not be allocated for results.

**ILLDT** 

Data type is not defined or supported.

**CFLSZ** 

Input volumes conflict in size.

# **SEE ALSO**

 $AVW\_ConstantOpImage(),\ AVW\_ConstantOpVolume(),\ AVW\_EvalFormula(),\ AVW\_FunctionImage(),\ AVW\_FunctionVolume(),\ AVW\_ImageOpConstant(),\ AVW\_ImageOpImage(),\ AVW\_VolumeOpVolume(),\ AVW\_Volume$ 

AVW\_VolumeOpVolume - transforms a volume mathematically

**SYNOPSIS** 

#include "AVW Parse.h"

AVW\_Volume \*AVW\_VolumeOpVolume(in\_volume1, operation, in\_volume2, out\_volume)

AVW\_Volume \*in\_volume1;

int operation;

AVW\_Volume \*in\_volume2;

AVW\_Volume \*out\_volume;

#### **DESCRIPTION**

AVW\_VolumeOpVolume() applies the operation and in\_volume2 to in\_volume1 and returns the resulting image:

output = in\_volume1 operation in\_volume2

AVW\_VolumeOpVolume() calls AVW\_ImageOpImage() with each slice in the input volumes to produce the output volume.

Out\_volume is provided as a method of reusing an existing AVW\_Volume. Reuse is possible only if the size and data type of the provided out\_volume out\_volume is returned by the function. If not reuseable out\_volume will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

The following operations are defined in AVW\_Parse.h:

 $AVW\_OP\_ADD$ 

AVW\_OP\_SUB

 $AVW_OP_MUL$ 

AVW\_OP\_DIV

 $AVW_OP_LT$ 

 $AVW_OP_GT$ 

 $AVW\_OP\_LE$ 

 $AVW_OP_GE$ 

 $AVW_OP_EQ$ 

AVW\_OP\_NE

AVW\_OP\_AND

 $AVW_OP_OR$ 

AVW\_OP\_MOD

# **RETURN VALUES**

If successful *AVW\_VolumeOpVolume()* returns an *AVW\_Volume*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_VolumeOpVolume() will fail if one or more of the following are true:

**NOTSUP** 

Operation is not supported.

**DIVZER** 

Division by zero.

**BADMAL** 

Memory could not be allocated for results.

**ILLDT** 

Data type is not defined or supported.

**CFLSZ** 

Input volumes conflict in size.

# **SEE ALSO**

AVW\_ConstantOpImage(), AVW\_ConstantOpVolume(), AVW\_EvalFormula(), AVW\_FunctionImage(), AVW\_FunctionVolume(), AVW\_ImageOpConstant(), AVW\_ImageOpImage(), AVW\_VolumeOpConstant(), AVW\_Volume

AVW\_VolumeSampleEntropy - Calculate the entropy of a sample of voxels

**SYNOPSIS** 

#include "AVW MatchVoxels.h"

double AVW\_VolumeSampleEntropy(volume,points,interpolate)

AVW\_Volume \*volume; AVW\_FPointList3 \*points;

int interpolate;

# **DESCRIPTION**

AVW\_VolumeSampleEntropy() calculates the entropy of a sample of voxels defined by a list of floating-point 3-D coordinates.

Interpolate determines the method of interpolation to use. Choose from:

AVW\_NEAREST\_NEIGHBOR\_INTERPOLATE

AVW\_LINEAR\_INTERPOLATE

AVW\_CUBIC\_SPLINE\_INTERPOLATE

 $AVW\_WINDOWED\_SINC\_INTERPOLATE$ 

# **RETURN VALUES**

If successful returns the entropy.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_VolumeSampleEntropy() will fail if the following is true:

**ILLVOL** 

Illegal Volume.

**ILLPAR** 

Interpolation type is not recognized.

# **SEE ALSO**

AVW\_VolumeSampleJointEntropy(), AVW\_VolumeSampleNMI(), AVW\_ImageSampleEntropy().

AVW\_VolumeSampleJointEntropy - Calculate the joint entropy of a sample of voxels from two volumes

# **SYNOPSIS**

#include "AVW\_MatchVoxels.h"

 $double\ AVW\_Volume Sample Joint Entropy (base, match, points, matrix, interpolate)$ 

AVW\_Volume \*base,\*match; AVW\_FPointList3 \*points; AVW\_Matrix \*matrix; int interpolate;

# DESCRIPTION

AVW\_VolumeSampleJointEntropy() calculates the joint entropy of a sample of voxels defined by a list of floating-point 3-D coordinates. *points* defines a set of 3-D coordinates in the *match* volume to be sampled. Those voxel values are paired with those from the same coordinates transformed by *matrix* in the *base* volume. The joint entropy of the samples is returned

Interpolate determines the method of interpolation to use. Choose from:

AVW\_NEAREST\_NEIGHBOR\_INTERPOLATE

AVW\_LINEAR\_INTERPOLATE

AVW\_CUBIC\_SPLINE\_INTERPOLATE

AVW\_WINDOWED\_SINC\_INTERPOLATE

# **RETURN VALUES**

If successful returns the joint entropy.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_VolumeSampleJointEntropy() will fail if the following is true:

**ILLVOL** 

Illegal Volume. Floating point, Complex, and color images are not supported

**BADMAL** 

Unable to allocate memory for internal calculations.

**ILLPAR** 

Interpolation type is not recognized.

# **SEE ALSO**

AVW\_VolumeSampleEntropy(), AVW\_VolumeSampleNMI(), AVW\_ImageSampleJointEntropy().

AVW\_VolumeSampleNMI - Calculate the Normalized Mutual Information of a sample of voxels from two volumes

# **SYNOPSIS**

#include "AVW\_MatchVoxels.h"

 $double\ AVW\_VolumeSampleNMI(base, match, points, matrix, interpolate)$ 

AVW\_Volume \*base,\*match; AVW\_FPointList3 \*points; AVW\_Matrix \*matrix; int interpolate;

# **DESCRIPTION**

AVW\_VolumeSampleNMI() calculates the normalized mutual information of a sample of voxels defined by a list of floating-point 3-D coordinates. *points* defines a set of 3-D coordinates in the *match* volume to be sampled. Those voxel values are paired with those from the same coordinates transformed by *matrix* in the *base* volume. The normalized mutual information (sum of individual image entropies divided by joint entropy) of the samples is returned

Interpolate determines the method of interpolation to use. Choose from:

AVW\_NEAREST\_NEIGHBOR\_INTERPOLATE

AVW\_LINEAR\_INTERPOLATE

AVW\_CUBIC\_SPLINE\_INTERPOLATE

AVW\_WINDOWED\_SINC\_INTERPOLATE

# **RETURN VALUES**

If successful returns the normalized mutual information.

On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_VolumeSampleNMI() will fail if the following is true:

**ILLVOL** 

Illegal Volume. Floating point, Complex, and color images are not supported

**BADMAL** 

Unable to allocate memory for internal calculations.

**ILLPAR** 

Interpolation type is not recognized.

# **SEE ALSO**

 $AVW\_Volume Sample Entropy(),\ AVW\_Volume Sample Joint Entropy(),\ AVW\_Image Sample NMI().$ 

AVW\_WaveletCompressAndDecompressImage – uses wavelet transformation and runlength encoding to compress and then decompress an image.

# **SYNOPSIS**

#include "AVW.h"

AVW\_Image \*AVW\_WaveletCompressAndDecompressImage(in\_img, Levels, HVSFlag, MasterBin, compressedSize, out img)

AVW\_Image \*in\_img;

int Levels; int HSVFlag; double MasterBin; int \*compressedSize

AVW\_Image \*out\_img;

#### **DESCRIPTION**

AVW\_WaveletCompressAnddecompressImage() is a convenience function which invokes AVW\_WaveletCompressImage and AVW\_DecompressWaveletBuffer into a single call facilitating evaluation of the quality of compression.

in\_img is an AVW\_Image to be compressed.

Levels number of levels in the wavelet decomposition.

*HVS\_Flag* (Human Visual System) Flag - if set to 1, the quantization is varied in the different levels to approximate the human visual system sensitivity to different frequencies. At a given compression ratio, this should result in smoother images that technically have poorer fidelity but are more pleasing to the eye.

*MasterBin* the quantization parameter by which the wavelet coefficients are divided. A larger value means coarser approximations of the wavelet coefficients, poorer image fidelity, and higher compression ratio; a smaller value means the reverse.

returnBufferSize is the size in bytes of the returned data buffer.

out\_img is provided as a method of reusing an existing AVW\_Image. Reuse is possible only if the size and data type of the provided out\_img meet the requirements of the function. In this case the pointer to out\_image is returned by the function. If not reuseable out\_image will be reallocated. (See Memory Usage in the AVW Programmer's Guide.)

# **RETURN VALUES**

If successful *AVW\_WaveletCompressAndDecompressImage()* returns an AVW\_Image. On failure it returns *AVW\_NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_WaveletCompressImageFile will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. A memory allocation failed.

# **ILLDT**

Illegal Datatype. Does not support multi-band datatypes such as AVW\_COLOR or AVW\_COMPLEX.

**REFERENCE** Manduca, A. (1997) "Compressing Images with Wavelet/Subband Coding", IEEE Engineering in Medicine and Biology, 14(5), 639-646.

 $AVW\_Wave let Compress Image-uses\ wavelet\ transformation\ and\ run-length\ encoding\ to\ compress\ an\ image.$ 

# **SYNOPSIS**

#include "AVW.h"

unsigned char \*AVW\_WaveletCompressImage(in\_img, Levels, HVSFlag, MasterBin, returnBufferSize)

AVW\_Image \*in\_img; int Levels;

int HSVFlag;

double MasterBin;

int \*returnBufferSize;

# **DESCRIPTION**

AVW\_WaveletCompressImage() compresses an AVW\_Image wavelet transformation and runlength encoding into compressed a binary data buffer.

The compression scheme used, is based on uniformly quantizing the wavelet coefficients by dividing by a user-specified quanization value and rounding off (typically, a large majority of coefficients with very small values are quantized to zero by this step). The zeros in the resulting sequence are then run-length encoded, and the entire sequence is Huffman encoded. If the quantization value is increased, more coefficients are quantized to zero, the remaining ones are quantized more coarsely, the representation accuracy decreases, and the compression ratio increases; if the value is decreased, the reverse happens. An alternative (HVS) compression scheme uses the user-specified quantization value at the lowest scale, but adjusts this value at other scales in accordance with the frequency sensitivity of the human visual system - the idea begin to preferentially suppress information which a human observer cannot perceive. The differences may be subtle; typically the images may look better with HVS quantization but the RMS error between the original and compressed versions may be smaller with uniform quantization.

*in\_img* is an *AVW\_Image* to be compressed.

Levels number of levels in the wavelet decomposition.

*HVS\_Flag* (Human Visual System) Flag - if set to 1, the quantization is varied in the different levels to approximate the human visual system sensitivity to different frequencies. At a given compression ratio, this should result in smoother images that technically have poorer fidelity but are more pleasing to the eye.

*MasterBin* the quantization parameter by which the wavelet coefficients are divided. A larger value means coarser approximations of the wavelet coefficients, poorer image fidelity, and higher compression ratio; a smaller value means the reverse.

returnBufferSize is the size in bytes of the returned data buffer.

The resulting data buffer can decompressed with AVW\_WaveletDecompressWaveletBuffer().

# **RETURN VALUES**

If successful *AVW\_WaveletCompressImage()* returns an pointer to an unsigned char. On failure it returns *AVW\_NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_WaveletCompressImageFile will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. A memory allocation failed.

**ILLDT** 

Illegal Datatype. Does not support multi-band datatypes such as AVW\_COLOR or AVW\_COMPLEX.

**SEE ALSO** 

AVW\_WaveletCompressAndDecompressImage(), AVW\_WaveletCompressImageFile(), AVW\_DecompressWaveletBuffer(), AVW\_Image

REFERENCE

Manduca, A. (1997) "Compressing Images with Wavelet/Subband Coding", IEEE Engineering in Medicine and Biology, 14(5), 639-646.

AVW\_WaveletCompressImageFile – uses wavelet transformation and run-length encoding to compress an image file

# **SYNOPSIS**

#include "AVW.h"

int \*AVW\_WaveletCompressImageFile(in\_name, Levels, HVSFlag, MasterBin, outName)

char \*in\_name; int Levels; int HSVFlag; double MasterBin; char \*outName;

# **DESCRIPTION**

AVW\_WaveletCompressImageFile() compresses any image file recognizeable by AVW with wavelet transformation and runlength encoding into a file of format AVW\_ImageFile.

The compression scheme used, is based on uniformly quantizing the wavelet coefficients by dividing by a user-specified quanization value and rounding off (typically, a large majority of coefficients with very small values are quantized to zero by this step). The zeros in the resulting sequence are then run-length encoded, and the entire sequence is Huffman encoded. If the quantization value is increased, more coefficients are quantized to zero, the remaining ones are quantized more coarsely, the representation accuracy decreases, and the compression ratio increases; if the value is decreased, the reverse happens. An alternative (HVS) compression scheme uses the user-specified quantization value at the lowest scale, but adjusts this value at other scales in accordance with the frequency sensitivity of the human visual system - the idea begin to preferentially suppress information which a human observer cannot perceive. The differences may be subtle; typically the images may look better with HVS quantization but the RMS error between the original and compressed versions may be smaller with uniform quantization.

*in\_name* is the name of the input file.

Levels number of levels in the wavelet decomposition.

*HVS\_Flag* (Human Visual System) Flag - if set to 1, the quantization is varied in the different levels to approximate the human visual system sensitivity to different frequencies. At a given compression ratio, this should result in smoother images that technically have poorer fidelity but are more pleasing to the eye.

*MasterBin* the quantization parameter by which the wavelet coefficients are divided. A larger value means coarser approximations of the wavelet coefficients, poorer image fidelity, and higher compression ratio; a smaller value means the reverse.

out\_file is the name of the output file.

The resulting output file can be read from and written to as transparantly as any other AVW\_ImageFile format file. Each slice is individually compressed.

# **RETURN VALUES**

If successful *AVW\_WaveletCompressImageFile()* returns an *AVW\_SUCCESS*. On failure it returns *AVW\_FAIL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

**ERRORS** 

AVW\_WaveletCompressImageFile will fail if one or more of the following are true:

**BADMAL** 

Malloc Failed. A memory allocation failed.

**ILLIMG** 

Illegal Image. The images are not all the same dimension.

**ILLDT** 

Illegal Datatype. Does not support multi-band datatypes such as AVW\_COLOR or AVW\_COMPLEX.

**SEE ALSO** 

AVW\_WaveletCompressAndDecompressImage(), AVW\_WaveletCompressImage(), AVW\_Image

REFERENCE

Manduca, A. (1997) "Compressing Images with Wavelet/Subband Coding", IEEE Engineering in Medicine and Biology, 14(5), 639-646.

AVW\_WireGrid – creates a wire-mesh plot from an image

# **SYNOPSIS**

#include "AVW.h"

AVW\_PointList2 \*AVW\_WireGrid(image, matrix, xspace, yspace, out\_plist)

AVW\_Image \*image; AVW Matrix \*matrix;

int xspace, yspace;

AVW\_PointList2 \*out\_plist;

#### **DESCRIPTION**

AVW\_WireGrid() generates a wire-mesh plot in the form of an AVW\_PointList2, from an AVW\_Image, image, an AVW\_Matrix, matrix, and two integer values, xspace and yspace. The image->Width and image->Height determine the size of the wiregrid, and the intensity values at each pixel within the image, determine the amount that the grid is raised or lowered at the pixel position.

*Matrix* is used to transform the 2-D image into 3-D space. *AVW\_RotateMatrix()* is used to specify the angle at which the wire grid is viewed from. Wiregrids are best viewed at non-orthogonal angles like 30-45 degrees. *AVW\_ScaleMatrix()* can be used to enlarge or shrink the grid on one or all of the axes. A good starting point is probably 1. for X & Y and .1 for Z. *AVW\_TranslateMatrix()* is normally used to translate the points returned to the center of an output window. *AVW\_Wiregrid()* uses the center of the input *image* as point (0,0). *AVW\_TranslateMatrix(mat, win\_width/2., win\_height/2., 0.)*; could be used to translate the point list returned to be displayed at the center of a window which has dimensions of win\_width by win\_height.

*Xspace* and *yspace* determine at which points along the grid the image is sampled. Small values causes the *image* to be sampled very finely. Large values result in a very course sampling. Very large and very small values will not produce very good results. Start with values in the 5-10 range.

Out\_plist is provided as a method of reusing an existing AVW\_PointList2.

# **RETURN VALUES**

If successful *AVW\_WireGrid()* returns an *AVW\_PointList2*. On failure it returns *NULL* and sets *AVW\_ErrorNumber* and *AVW\_ErrorMessage* to values corresponding to the cause of the failure.

# **ERRORS**

AVW\_WireGrid() will fail if:

**ILLDT** 

Data type is not defined or supported.

**ILLIMG** 

An illegal image was passed to the function.

#### **SEE ALSO**

AVW\_PointList2, AVW\_Image

AVW\_WriteHistogram - writes a histogram to a file

**SYNOPSIS** 

#include "AVW\_Histogram.h"

int AVW\_WriteHistogram(histo, filename)

AVW\_Histogram \*histo;

char \*filename;

**DESCRIPTION** 

AVW\_WriteHistogram() writes the AVW\_Histogram, histo, to a file called filename.

**RETURN VALUES** 

Upon success *AVW\_WriteHistogram()* returns *AVW\_SUCCESS*. On failure *AVW\_FAIL* is returned, and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values indicating the cause of error.

**ERRORS** 

AVW\_WriteHistogram() will fail if one or more of the following is true:

**BDOPEN** 

Bad Open. Failure opening file for writing.

**ILLHIS** 

Illegal Histogram.

**SEE ALSO** 

 $AVW\_ClearHistogram(),\ AVW\_CreateHistogram(),\ AVW\_DestroyHistogram(),\ AVW\_GetImageHistogram(),\ AVW\_MatchVolumeHistogram(),\ AVW\_MatchImageHistogram(),\ AVW\_NormalizeHistogram(),\ AVW\_ReadHistogram(),\ AVW\_VerifyHistogram(),\ AVW\_Histogram(),\ AVW\_VerifyHistogram(),\ AVW\_Histogram(),\ AVW\_VerifyHistogram(),\ AVW\_$ 

AVW\_WriteImageFile - writes an image to an image file

**SYNOPSIS** 

#include "AVW\_ImageFile.h"

int AVW\_WriteImageFile (imgfile, image)

AVW\_ImageFile \*imgfile; AVW\_Image \*image;

**DESCRIPTION** 

AVW\_WriteImageFile() writes the AVW\_Image to an AVW\_ImageFile. The AVW\_ImageFile must have been opened with the write mode specified.

**RETURN VALUES** 

Upon success *AVW\_WriteImageFile()* returns *AVW\_SUCCESS*. On failure *AVW\_FAIL* is returned, and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values indicating the cause of error.

**ERRORS** 

AVW\_WriteImageFile() will fail if one or more of the following are true:

**ICPIMG** 

Incompatible Image. The image and imagile are incompatible with regard to image size and/or data type.

**BDWRTE** 

Bad Write. Error writing image.

**NOSPACE** 

No Space On Device. Disk is full.

**SEE ALSO** 

AVW\_CloseImageFile(), AVW\_CreateImageFile(), AVW\_ExtendExternalLibs(), AVW\_ExtendImageFile(), AVW\_FormatSupports(), AVW\_ListFormats(), AVW\_OpenImageFile(), AVW\_ReadImageFile(), AVW\_ReadVolume(), AVW\_SeekImageFile(), AVW\_SeekImageFile(), AVW\_WriteSubVolumeDescription(), AVW\_WriteVolume(), AVW\_Image, AVW\_ImageFile

AVW\_WriteSubVolumeDescription – writes a subvolume description file

# **SYNOPSIS**

#include "AVW\_ImageFile.h"

 $int\ AVW\_WriteSubVolumeDescription\ (outname, infile, involnum, subv, info)$ 

char \*outname;

char \*infile;

int involnum;

AVW Rect3 \*subv:

char \*info;

# **DESCRIPTION**

AVW\_WriteSubVolumeDescription() writes a subvolume description file. A subvolume description file is a type of AVW\_VolumeFile which contains a description of a subvolume of interest contained in another image file. The description file is opened as if it were an AVW\_VolumeFile.

Outname is the name of the output file to be written.

*Infile* is the name of the image file containing the described subvolume. *Infile* can be any image file format supported by *AVW*, including the *AVW\_VolumeFile* format.

*Involnum* is the volume number containing the specified subvolume. Acceptable values are from 0 to the number of volumes in *infile* less 1.

Subv specifies the position and size of the subvolume.

*Info* is an *AVW\_Info* string whose elements will be written in the file. Set *info* to NULL if no additional info is to be written to the file.

# **RETURN VALUES**

Upon success *AVW\_WriteSubVolumeDescription()* returns *AVW\_SUCCESS*. On failure *AVW\_FAIL* is returned, and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values indicating the cause of error.

#### **ERRORS**

AVW\_WriteSubVolumeDescription() will fail if one or more of the following is true:

**BDOPEN** 

Unable to open infile.

**ICPVOL** 

Subv is incompatible with infile.

**BDVLNM** 

Involnum incompatible with infile.

**BDCRT** 

Error creating outfile.

## **SEE ALSO**

AVW\_CloseImageFile(), AVW\_CreateImageFile(), AVW\_ExtendExternalLibs(), AVW\_ExtendImageFile(), AVW\_FormatSupports(), AVW\_ListFormats(), AVW\_OpenImageFile(), AVW\_ReadImageFile(), AVW\_ReadVolume(), AVW\_SeekImageFile(), AVW SeekImageFile(), AVW WriteImageFile(), AVW WriteVolume(), AVW Rect3

AVW\_WriteVolume - writes a volume to an image file

**SYNOPSIS** 

#include "AVW\_ImageFile.h"

int AVW\_WriteVolume (imgfile, volnum, volume)

AVW\_ImageFile \*imgfile;

int volnum;

AVW Volume \*volume;

**DESCRIPTION** 

AVW\_WriteVolume() writes the AVW\_Volume, volume, to an AVW\_ImageFile, imgfile. The AVW\_ImageFile must have been opened with the write mode specified.

*Volnum* is the volume number to be written. Volumes are numbered from 0 to imgfile>NumVols-1. Thus if the first volume of a file is to be written, specify 0.

**RETURN VALUES** 

Upon success *AVW\_WriteVolume()* returns *AVW\_SUCCESS*. On failure *AVW\_FAIL* is returned, and *AVW\_ErrorNumber* and *AVW\_ErrorMessage* are set to values indicating the cause of error.

**ERRORS** 

AVW\_WriteVolume() will fail if one or more of the following is true:

**ICPVOL** 

Incompatible Volume. The volume and impfile are incompatible with regard to dimensions and/or data type.

**BDWRTE** 

Bad Write. Error writing image.

**SEE ALSO** 

AVW\_CloseImageFile(), AVW\_CreateImageFile(), AVW\_ExtendExternalLibs(), AVW\_ExtendImageFile(), AVW\_FormatSupports(), AVW\_ListFormats(), AVW\_OpenImageFile(), AVW\_ReadImageFile(), AVW\_ReadVolume(), AVW\_SeekImageFile(), AVW\_WriteSubVolumeDescription(), AVW\_ImageFile, AVW\_Volume

EXTEND.conf- configuration file for loading AVW shared libraries

**SYNOPSIS** 

\$AVW/app-defaults/EXTEND.conf

#### DESCRIPTION

The file *EXTEND.conf* provides a list of shared libraries and configuration routines, and optionally other external libraries which may need to be loaded to resolve all references to the listed library. This file is opened and read by the function *AVW\_ExtendExternalFormats()* which executes the steps necessary to link the named libraries into a running AVW based program. This function is designed to implement loading of image file extensions to AVW, to avoid the need to recompile each application if a new file format is added to the library. If the extensions are loaded into shared libraries and referenced in the the *EXTEND.conf* configuration file, the *AVW\_ExtendExternalFormats()* function will load and install them in a running program.

The format of the file consists of lines containing 4 entries:

*Target-System* Is the name of AVW known system target types. Currently these are: SPARC, SGI5, ALPHA, PC\_NT, HP. If the extension applies to all versions, the keyword "ALL" can be used.

*Library-Name* Is the name of a shared library containing functions to be linked into the running AVW based program. For most systems, this library is found in the path described in the environment variable LD\_LIBRARY\_PATH and/or /usr/lib.

*Initialization-Function* If the listed library is located and loaded, the library is searched for a function of this name, and if found, this function is executed with no arguments. Any return value is discarded.

Other-Libraries In some cases, AVW extensions will rely on other libraries to resolve internal references. (For example, a image format extension for movie files may require movie libraries provided by another vendor). This field contains the single character N if no other libraries are required, else it contains a comma separated list of other libraries.

# **EXAMPLES**

To include an image file extension for AVW for Compuserve GIF image files, which has been compiled and placed in a library called avwGIF.so, and is initialized into the application by calling the function "extend\_for\_gif()" from the shared library, and no other libraries are required:

ALL avwGIF.so extend\_for\_gif N

To include a multimedia image file format implemented on SGI only into AVW applications which is compiled into a library called mmedia.so, and is initialized by a call to "init\_multimedia()" in the library, and which depends on vendor provided libraries libmovie.so, libaudio.so,

(located in /usr/lib):

SGI6 libavwSGIMOVIE.so avw\_extend\_for\_sgi\_movie libmovie.a,libaudio.a

**SEE ALSO** 

AVW\_ExtendExternalLibs(), AVW\_ExtendImageFile(), AVW\_ExtendIO

**FILES** This file is sought in the following search order:

 $AVW/app\-defaults/EXTEND.conf\ \ (default)\ /home/AVW/app\-defaults/EXTEND.conf\ a file specified by the environment variable AVW_EXTEND$ 

**NOTES** There must be 4 fields on each line.

Comments are NOT allowed in this file.

There must not be spaces in the comma separated list of other libraries.

# **NAME** AVW\_2DShapeStats - 2D Shape Stats Structure **SYNOPSIS** typedef struct float Area; float Perimeter; float MERAngle; float MERArea; float MERAspect; float RFF; float Circularity; AVW\_FPoint2 Centroid; AVW\_FPoint2 MER1; **AVW FPoint2 MER2**; AVW\_FPoint2 MER3; AVW\_FPoint2 MER4; } AVW\_2DShapeStats;

# **DESCRIPTION**

The  $AVW_2DS$  hape Stats structure provides an easy way to return shape statistics from AVW functions.

Area - count of pixels.

*Perimeter* - distance around the shape.

MERAngle - angle in degrees of Minimum Enclosing Rectangle.

MERArea - area of the Minimum Enclosing Rectangle.

MERAspect - aspect ratio of the Minimum Enclosing Rectangle.

RFF - Rectangular Fit Factor.

Circularity - ratio of region perimeter squured to its area.

*Centroid* - average of x and y coordinates in the region.

*MER1, MER2, MER3* and *MER4* are the corner coordinates of the Minimum Enclosing Rectangle.

# **LOCATION**

AVW\_Measure.h

# **SEE ALSO**

 $AVW\_FPoint2, AVW\_Compute2DShapeStats(), AVW\_ComputeCircularity(), \\ AVW\_ComputeImageCentroid(), AVW\_ComputeMER(), AVW\_ComputePerimeter(), \\ AVW\_ComputeRFF()$ 

NAME AVW\_Colormap - Colormap Structure

SYNOPSIS typedef struct

typedef struct {

int Size; unsigned char \*Red; unsigned char \*Green; unsigned char \*Blue; } AVW\_Colormap;

**DESCRIPTION** 

The *AVW\_Colormap* structure provides an easy way to pass colors to and from *AVW* functions.

Size indicates the number of colors defined by this colormap.

Red, Green and Blue are pointers to the arrays.

**LOCATION** 

AVW.h

**SEE ALSO** 

AVW\_CreateColormap(), AVW\_CopyColormap(), AVW\_DestroyColormap(), AVW\_DESTROYCOLORMAP(), AVW\_Image, AVW\_Volume

AVW\_Complex - Complex Number Structure

**SYNOPSIS** 

typedef struct

float Real, Imaginary; } AVW\_Complex;

**DESCRIPTION** 

The AVW\_Complex structure provides an easy way to pass and return Complex numbers.

*Real* contains the "real" portion of the complex numbers.

*Imaginary* contains the "imaginary" portion of the complex numbers.

**LOCATION** 

AVW.h

```
NAME AVW_CompositeInfo – Composite Information Structure

typedef struct {
    int RedType;
    int GreenType;
    int AlphaType;
    int AlphaType;
    AVW_FPointList2* Red;
    AVW_FPointList2* Blue;
    AVW_FPointList2* Blue;
    AVW_FPointList2* Alpha;
} AVW_CompositeInfo;
```

#### **DESCRIPTION**

The *AVW\_CompositeInfo* structure provides an easy way to pass composite information to the *AVW\_RenderParameters* structure.

*RedType* specifies the curve type used to interpolate the red color values. *RedType* is one of *AVW\_LINEAR* or *AVW\_SPLINE*. *Red* contains the Intensity and Red value coordinate used to generate the appropriate color during Volume Compositing. The X coordinate of each point corresponds to voxel intensity and the Y value correspondes to the value of the Red Component of the color at that intensity. The Red component must be in the range 0.0 to 1.0.

*GreenType* specifies the curve type used to interpolate the green color values. *GreenType* is one of *AVW\_LINEAR* or *AVW\_SPLINE*. *Green* contains the Intensity and Green value coordinate used to generate the appropriate color during Volume Compositing. The X coordinate of each point corresponds to voxel intensity and the Y value correspondes to the value of the Green Component of the color at that intensity. The Green component must be in the range 0.0 to 1.0.

BlueType specifies the curve type used to interpolate the blue color values. BlueType is one of AVW\_LINEAR or AVW\_SPLINE. Blue contains the Intensity and Blue value coordinate used to generate the appropriate color during Volume Compositing. The X coordinate of each point corresponds to voxel intensity and the Y value correspondes to the value of the Blue Component of the color at that intensity. The Blue component must be in the range 0.0 to 1.0.

AlphaType specifies the curve type used to interpolate the Alpha values. AlphaType is one of AVW\_LINEAR or AVW\_SPLINE. Alpha contains the opacity value coordinate used to generate the appropriate opacity during Volume Compositing. The X coordinate of each point corresponds to voxel intensity and the Y value corresponds to the value of the Alpha Component at that intensity. The Alpha component must be in the range 0.0 to 1.0.

**LOCATION** 

AVW\_CompositeInfo.h

**SEE ALSO** 

AVW FPointList2, AVW RenderParameters

AVW\_ContourSurface - Contour Surface Structure

#### **SYNOPSIS**

typedef struct

AVW\_MultiList2 \*Interior; AVW\_MultiList2 \*Exterior;

AVW\_Point3 MinExtent; AVW\_Point3 MaxExtent;

unsigned int StartSlice; unsigned int EndSlice; unsigned int TotalSlices; double LayerThickness; AVW\_ContourSurface;

# **DESCRIPTION**

The AVW\_ContourSurface structure represents the surface of an object as a series of stacked edges or contours. This two and a half dimensional representation of a surface is often used by rapid prototyping applications.

The *Interior* and *Exterior* multilist arrays contain pointers to a single *AVW\_MultiList2* structure for each data slice. The arrays are indexed from 0 to *TotalSlices - 1*. The *AVW\_MultiList2s* that comprise *Interior* contain the interior edges of the object, while those that comprise *Exterior* contain the exterior edges. Each edge is a series of X,Y points. The Z values begin with *StartSlice* and end with *EndSlice;* Thus the edges found in *Exterior[0]* would have a Z value of *StartSlice* and those found in *Exterior[TotalSlices - 1]* would have a Z value of *EndSlice.* 

*LayerThickness* gives the "thickness" of each contour. It is calculated by *AVW\_SliceVolume* and is currently limited to the resolution of the original volumetric data.

**LOCATION** 

AVW\_Model.h

**SEE ALSO** 

 $AVW\_DestroyContourSurface(),\ AVW\_SaveContourSurface(),\ AVW\_SliceVolume()\\ AVW\_MultiList2$ 

AVW\_ExtendIO - Extend I/O Structure

#### **SYNOPSIS**

```
typedef struct
  char
            *Extension;
  char
            *Description;
           MagicNumber;
  int
           Properties:
  int
  AVW_ImageFile *(*Open)();
            (*Seek)();
  AVW_Image
                  *(*Read)();
           (*Write)();
  int
            (*Close)();
  int
  AVW_ImageFile *(*Create)();
           (*Query)();
  } AVW_ExtendIO;
```

#### **DESCRIPTION**

The *AVW\_ExtendIO* structure enables the user to extend the AVW\_Image IO functions to support additional image file formats. The elements of the structure are set and the structure is then passed to AVW\_ExtendImageFile().

Extension is a pointer to the extension (if any) by which this file may be easily identified .

*Description* is the name by which AVW will recognize this format. This is the value that is used by AVW\_CreateImageFile() to specify the file format.

MagicNumber is a magic number (if any) by which this file format may be identified.

*Properties* specifies what properties are supported by this file format. These symbols may be combined with the bitwise OR "|" operator to set the supported properties flag.

```
AVW_SUPPORT_2D, AVW_SUPPORT_3D, AVW_SUPPORT_4D,
AVW_SUPPORT_READ, AVW_SUPPORT_WRITE,
AVW_SUPPORT_UNSIGNED_CHAR, AVW_SUPPORT_SIGNED_CHAR,
AVW_SUPPORT_UNSIGNED_SHORT, AVW_SUPPORT_SIGNED_SHORT,
AVW_SUPPORT_UNSIGNED_INT, AVW_SUPPORT_SIGNED_INT,
AVW_SUPPORT_FLOAT, AVW_SUPPORT_COMPLEX, AVW_SUPPORT_COLOR
```

*Open()* specifies the user supplied function which opens and returns an AVW\_ImageFile structure for this format. AVW\_OpenImageFile() passes its arguments to this function and returns what is returned by this routine.

*Seek()* specifies the user supplied function which performs image seeks for this format. AVW\_SeekImageFile() passes its arguments to this function and returns what is returned by this function.

*Read()* specifies the user supplied function which reads and returns an AVW\_ImageFile for this format. AVW\_ReadImageFile() file passes its arguments to this function and returns what is returned by this function.

*Write()* specifies the user supplied function which writes an AVW\_ImageFile for this format. AVW\_WriteImageFile() passes its arguments to this function and returns what is returned by this function.

*Close()* specifies the user supplied function which closes an AVW\_ImageFile for this format. AVW\_CloseImageFile() passes its arguments to this function and returns what is returned by this function.

*Create()* specifies the user supplied function which creates an AVW\_ImageFile for this format. AVW\_CreateImageFile() passes its arguments to this function and returns what is returned by this function.

Query() specifies the user supplied function which tests whether a file is of this format. This function is called by AVW\_OpenImageFile() to determine if a file is of this format. Given the name of the file; this function returns AVW\_TRUE is the file is of the file format and AVW\_FALSE if it is not. AVW\_OpenImageFile() uses the routine to assign the appropriate image file IO routines once a file's data format is determined.

**LOCATION** 

AVW\_ImageFile.h

**SEE ALSO** 

AVW\_CloseImageFile(), AVW\_CreateImageFile(), AVW\_ExtendExternalLibs(), AVW\_ExtendImageFile(), AVW\_FormatSupports(), AVW\_ListFormats(), AVW\_OpenImageFile(), AVW\_ReadImageFile(), AVW\_ReadVolume(), AVW\_SeekImageFile(), AVW\_WriteSubVolumeDescription(), AVW\_WriteVolume(), AVW\_Image, AVW\_ImageFile()

**NAME** AVW\_FPoint2 – 2D (Float) Point Structure

**SYNOPSIS** typedef struct

float X, Y;
} AVW\_FPoint2;

**DESCRIPTION** The *AVW\_FPoint2* structure provides an easy way to pass and return 2D floating point

coordinates.

X and Y specify coordinate values.

LOCATION | AVW.h

**SEE ALSO** AVW\_Point2, AVW\_IPoint2, AVW\_FPoint3, AVW\_FPointList2, AVW\_AddFPoint2(),

AVW\_GetFPoint2(), AVW\_Compute2DShapeStats(), AVW\_ComputeImageCentroid(),

 $AVW\_CreateFPointList2(),\ AVW\_InterpolatedPixel(),\ AVW\_NearestNeighborPixel(),$ 

AVW\_RemoveFPoint2()

AVW\_FPoint3 - 3D (float) Point Structure

**SYNOPSIS** 

typedef struct

float X, Y, Z; } AVW\_FPoint3;

**DESCRIPTION** 

The AVW\_FPoint3 structure provides an easy way to pass and return 3D float coordi-

*X*, *Y*, and *Z* specify coordinate values.

**LOCATION** 

AVW.h

**SEE ALSO** 

AVW\_FPoint2, AVW\_Point3, AVW\_IPoint3, AVW\_FPointList3, AVW\_AddFPoint3(), AVW\_ComputeVolumeCentroid(), AVW\_CreateFPointList3(), AVW\_GetFPoint3(),

AVW\_InterpolatedVoxel(), AVW\_NearestNeighborVoxel(), AVW\_RemoveFPoint3()

AVW\_FPointList2 - List of 2D (float) points

# **SYNOPSIS**

typedef struct

unsigned int NumberOfPoints; unsigned int MaximumPoints; unsigned int BlockSize; AVW\_FPoint2 \*Points; } AVW\_FPointList2;

## **DESCRIPTION**

The *AVW\_FPointList2* structure provides an easy way to pass and return a list of 2D (float) points.

*NumberOfPoints* is the current number of points in the list.

*MaximumPoints* indicates the number of points this list can hold before automatic reallocation.

*BlockSize* indicates the number added to the current size when reallocation is necessary.

*Points* is a pointer to an array of *AVW\_FPoint2s*.

#### **LOCATION**

AVW.h

## **SEE ALSO**

 $AVW\_FPoint2,\ AVW\_AddFPoint2(),\ AVW\_CreateFPointList2(),\ AVW\_DestroyFPointList2(),\ AVW\_DESTROYFPOINTLIST2(),\ AVW\_GetFPoint2(),\ AVW\_MakeFPointList2(),\ AVW\_RemoveFPoint2(),\ AVW\_RemoveFPOINT2($ 

AVW\_FPointList3 - List of 3D (float) points

## **SYNOPSIS**

typedef struct

unsigned int NumberOfPoints; unsigned int MaximumPoints; unsigned int BlockSize; AVW\_FPoint3 \*Points; AVW\_FPointList3;

## **DESCRIPTION**

The *AVW\_FPointList3* structure provides an easy way to pass and return a list of 3D (float) points.

*NumberOfPoints* is the current number of points in the list.

*MaximumPoints* indicates the number of points this list can hold before automatic reallocation.

BlockSize indicates the number added to the current size when reallocation is necessary.

*Points* is a pointer to an array of *AVW\_FPoint3s*.

#### **LOCATION**

AVW.h

## **SEE ALSO**

AVW\_FPoint3, AVW\_FPointList2, AVW\_AddFPoint3(), AVW\_CreateFPointList3(), AVW\_DestroyFPointList3(), AVW\_DESTROYFPOINTLIST3(), AVW\_GetFPoint3() AVW\_RemoveFPoint3()

AVW\_FilterCoeffs - Coefficents Structure

**SYNOPSIS** 

typedef struct

/ r }

int Number; float \*Coeffs;

} AVW\_FilterCoeffs;

**DESCRIPTION** 

The AVW\_FilterCoeffs structure provides an easy way to pass and return Coefficents.

Number indicates the total number of coefficents.

*Coeffs* is a pointer to an array of floating point coefficents.

**LOCATION** 

AVW\_Filter.h

**SEE ALSO** 

AVW\_CreateButterworthCoeffs(), AVW\_CreateCircularMTF(), AVW\_CreateCoeffs(), AVW\_CreateGaussianCoeffs(), AVW\_CreateSphericalMTF(), AVW\_CreateStoksethMTF(), AVW\_DestroyCoeffs(), AVW\_DESTROYCOEFFS()

AVW\_FullWidthHalfMax - Full width half max measurments.

# **SYNOPSIS**

```
typedef struct
{
    AVW_Point2 Start;
    AVW_Point2 End;
    double Maximum;
    AVW_Point2 MaximumPoint;
    double HalfMax;
    int StartIndex;
    AVW_FPoint2 HM_Start;
    int EndIndex;
    AVW_FPoint2 HM_End;
    double FWHM_Distance;
    double Mean;
    double StdDev;
```

} AVW\_FullWidthHalfMax;

#### **DESCRIPTION**

The AVW\_FullWidthHalfMax structure contains all of the full width half max measurements which are usually computed by AVW\_ComputeFullWidthHalfMax(). The measurements contained in this structure are computed from a line profile which is contained in an AVW\_PointValueList. Some of the measurements are related the AVW\_PointValueList.

Start is the coordinates of the first point in the line profile.

*End* is is the coordinates of the last point in the line profile.

Maximum indicates the maximum value of the line profile.

*MaximumPoint* is the coordinates of the first occurrence of the *Maximum* value in the line profile.

HalfMax indicates the half max value of the line profile.

*StartIndex* indicates index of the line profile where the first half max occurrs.

*HM\_Start* indicates the coordinates of the first half max.

EndIndex indicates index of the line profile where the second half max occurrs.

HM\_End indicates the coordinates of the second half max.

*FWHM\_Distance* specifies the distance, which is calibrated according to the voxel size, between *HM\_Start* and *HM\_End*.

*Mean* specifies the mean of all of the values in the line profile.

StdDev specifies the standard deviation of all of the values in the line profile.

## **LOCATION**

AVW\_Measure.h

SEE ALSO | AVW\_Point2, AVW\_FPoint2, AVW\_PointValueList, AVW\_ComputeFullWidthHalfMax() | AVW\_ComputeLineProfile()

AVW\_GradientPoint - Gradient Point Structure

**SYNOPSIS** 

typedef struct

AVW\_Point3 Location; AVW\_Point3 Gradient; AVW\_GradientPoint;

**DESCRIPTION** 

The *AVW\_GradientPoint* structure holds the location and precalculated gradient information for a predetermined surface voxel.

Location indicates a voxels 3-D location.

Gradient contains the pre-calculated gradient information for this voxel.

**LOCATION** 

AVW\_Render.h

**SEE ALSO** 

AVW\_Gradients, AVW\_Point3

AVW\_Gradients - Gradients Structure

**SYNOPSIS** 

typedef struct

{

int NumberOfGradients; int MaximumGradients;

AVW\_GradientPoint \*GradientPoint;

} AVW\_Gradients;

**DESCRIPTION** 

The *AVW\_Gradients* structure is used to pass pre-determined surface information to and from *AVW* functions.

NumberOfGradients is the number of points in this surface.

*MaximumGradients* is the number of points that can be held in the *GradientPoint* array, before it must be realloc'd.

GradientPoint is an array of AVW\_GradientPoint's.

**LOCATION** 

AVW\_Render.h

**SEE ALSO** 

 $AVW\_ExtractGradients(),\ AVW\_DestroyGradients(),\ AVW\_RenderGradients(),\ AVW\_GradientPoint$ 

# NAME AVW\_Histogram – Histogram Structure SYNOPSIS typedef struct { double \*Mem; double Max; double Min; double Step; unsigned int Bins;

# **DESCRIPTION**

The AVW\_Histogram structure provides an easy way to pass and return histograms.

*Mem* is a pointer to an array of doubles. Each value in the array indicates the number of points in this bin.

Max and Min indicate the values of the first and last bins.

*Step* is the increment between bins.

} AVW\_Histogram;

Bins is the total number of bins.

# **LOCATION**

AVW\_Histogram.h

#### **SEE ALSO**

AVW\_ClearHistogram(), AVW\_CreateHistogram(), AVW\_DestroyHistogram(),

AVW\_FlattenImageHistogram(), AVW\_FlattenVolumeHistogram(),

AVW\_GetImageHistogram(), AVW\_GetVolumeHistogram(), AVW\_MatchImageHistogram(),

AVW\_MatchVolumeHistogram(), AVW\_NormalizeHistogram(),

AVW\_PreserveImageHistogram(), AVW\_PreserveVolumeHistogram(),

AVW\_VerifyHistogram()

**NAME** AVW\_IPoint2 – 2D (Integer) Point Structure

**SYNOPSIS** typedef struct

int X, Y;

} AVW\_IPoint2;

**DESCRIPTION** The *AVW\_IPoint2* structure provides an easy way to pass and return 2D integer point

coordinates.

*X* and *Y* specify coordinate values.

LOCATION AVW.h

SEE ALSO | AVW\_IPoint3, AVW\_FPoint2, AVW\_Point2, AVW\_IPointList2, AVW\_AddIPoint2(),

AVW\_CreateIPointList2(), AVW\_GetIPoint2() AVW\_RemoveIPoint2()

**NAME** AVW\_IPoint3 – 3D (integer) Point Structure

**SYNOPSIS** typedef struct

{
int X, Y, Z;
} AVW\_IPoint3;

**DESCRIPTION** The *AVW\_IPoint3* structure provides an easy way to pass and return 3D integer coordi-

nates

*X*, *Y*, and *Z* specify coordinate values.

LOCATION AVW.h

SEE ALSO | AVW\_IPoint2, AVW\_FPoint2, AVW\_FPoint3, AVW\_Point2, AVW\_Point3,

 $AVW\_IPointList3,\ AVW\_AddIPoint3(),\ AVW\_GetIPoint3(),\ AVW\_RemoveIPoint3()$ 

AVW\_IPointList2 - List of 2D (integer) points

# **SYNOPSIS**

typedef struct

unsigned int NumberOfPoints; unsigned int MaximumPoints; unsigned int BlockSize; AVW\_IPoint2 \*Points; } AVW\_IPointList2;

## **DESCRIPTION**

The *AVW\_IPointList2* structure provides an easy way to pass and return a list of 2D (integer) points.

*NumberOfPoints* is the current number of points in the list.

*MaximumPoints* indicates the number of points this list can hold before automatic reallocation.

BlockSize indicates the number added to the current size when reallocation is necessary.

Points is a pointer to an array of AVW\_IPoint2s.

#### **LOCATION**

AVW.h

## **SEE ALSO**

AVW\_IPointList3, AVW\_FPointList2, AVW\_FPointList3, AVW\_PointList2, AVW\_PointList3, AVW\_PointValueList, AVW\_AddIPoint2(), AVW\_CreateIPointList2(), AVW\_DestroyIPointList2(), AVW\_GetIPoint2(), AVW\_DESTROYIPOINTLIST2(), AVW\_RemoveIPoint2(),

AVW\_IPointList3 - List of 3D (integer) points

#### **SYNOPSIS**

typedef struct

unsigned int NumberOfPoints; unsigned int MaximumPoints; unsigned int BlockSize; AVW\_IPoint3 \*Points; } AVW\_IPointList3;

## **DESCRIPTION**

The *AVW\_IPointList3* structure provides an easy way to pass and return a list of 3D (integer) points.

NumberOfPoints is the current number of points in the list.

*MaximumPoints* indicates the number of points this list can hold before automatic reallocation.

*BlockSize* indicates the number added to the current size when reallocation is necessary.

Points is a pointer to an array of AVW\_IPoint3s.

#### **LOCATION**

AVW.h

## **SEE ALSO**

AVW\_IPoint3, AVW\_IPointList2, AVW\_AddIPoint3(), AVW\_CreateIPointList3(), AVW\_DestroyIPointList3(), AVW\_GetIPoint3(), AVW\_DESTROYIPOINTLIST3(), AVW\_RemoveIPoint3()

AVW\_Image - Image Structure

#### **SYNOPSIS**

```
typedef struct
{
    void *Mem;
    int DataType;
    unsigned int Width;
    unsigned int Height;
    unsigned int BytesPerPixel;
    unsigned int BytesPerImage;
    unsigned int PixelsPerImage;
    unsigned int PixelsPerImage;
    AVW_Colormap *Colormap;
    char *Info;
    unsigned int *YTable;
} AVW_Image;
```

#### **DESCRIPTION**

The *AVW\_Image* structure provides an easy way to pass images to and from *AVW* functions.

*Mem* is a pointer to the raw data. It is often necessary to typecast this pointer when using it.

Example: ptr = (unsigned char \*) image->Mem

DataType specifies pixel data type. Types include all AVW data types: AVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_INT, AVW\_SIGNED\_INT, AVW\_FLOAT, AVW\_COMPLEX, AVW\_COLOR.

Width and Height specify the dimensions of the image.

BytesPerPixel, BytesPerLine, BytesPerImage, and PixelsPerImage contain often used precalcuated values.

Colormap is a pointer to an AVW\_Colormap.

*Info* is a pointer to an *AVW* information string which is used to store additional information about the image.

*YTable* is an array of pre-calculated offsets to the start of each line in the image. The following example shows how to get the starting address of the tenth line of the image.

ptr = (unsigned char \*) image->Mem + image->YTable[9];

#### **LOCATION**

AVW.h

# **SEE ALSO**

 $AVW\_Colormap,\ AVW\_Volume,\ AVW\_CreateImage(),\ AVW\_DestroyImage(),\ AVW\_DESTROYIMAGE()$ 

AVW\_ImageFile - Image File Structure

#### **SYNOPSIS**

```
typedef struct
{
  char *FileName;
  char *FileModes;
```

int DataFormat; int DataType;

unsigned int Width; unsigned int Height; unsigned int Depth; unsigned int NumVols;

unsigned int BitsPerPixel; unsigned int BytesPerPixel; unsigned int BytesPerLine; unsigned int BytesPerImage; unsigned int BytesPerVolume; unsigned int PixelsPerImage; unsigned int VoxelsPerVolume; unsigned int VoxelsPerFile;

int CurrentSlice;
int CurrentVolume;

AVW\_Colormap \*Colormap;

void \*NativeData;
char \*Info;
} AVW\_ImageFile;

#### **DESCRIPTION**

The *AVW\_ImageFile* structure provides a transparent way to read and write image files in a variety of supported formats.

FileName is a pointer to the name of this file.

*FileModes* is the mode string with which the file has been opened.

DataFormat is an index into a list of supported Data Formats.

DataType specifies what type of image(s) are contained in the file. Types include: AVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_INT, AVW\_SIGNED\_INT, AVW\_FLOAT, AVW\_COMPLEX, AVW\_COLOR.

*Width* and *Height* specify the dimensions of the image(s).

*Depth* specifies the number of images in a volume.

*NumVols* specifies the number of volumes in the file.

BitsPerPixel, BytesPerPixel, BytesPerLine, BytesPerImage, BytesPerVolume, PixelsPerImage,

VoxelsPerVolume, and VoxelsPerFile contain often used pre-calcuated values.

*CurrentSlice* and *CurrentVolume* indicate the volume and image at which the file is currently positioned to read or write.

Colormap is a pointer to an AVW\_Colormap.

*Info* is a pointer to an *AVW* information string.

*NativeData* is a pointer to information about the image file specific to its particular format.

# **LOCATION**

AVW\_ImageFile.h

# **SEE ALSO**

AVW\_CloseImageFile(), AVW\_CreateImageFile(), AVW\_ExtendImageFile(), AVW\_FormatSupports(), AVW\_ListFormats(), AVW\_MMapVolume(), AVW\_OpenImageFile(), AVW\_ReadImageFile(), AVW\_ReadVolume(), AVW\_SeekImageFile(), AVW\_WriteImageFile(), AVW\_WriteVolume()

```
NAME
                   AVW_Instructions - Instruction Structure
    SYNOPSIS
                   typedef struct
                          int NumberOfOperations;
                          unsigned short **Operations;
                          int NumberOfConstants;
                          char **ConstantNames;
                          int NumberOfVariables;
                          char **VariableNames;
                          char **FileName;
                          char **DataFormat;
                          int *DataType;
                          int *StartingVolume;
                          int *VolumeIncrement;
                          int *VolumesToProcess;
                          int *StartingSlice;
                          int *SliceIncrement;
                          int *SlicesToProcess;
                          int *SlicesPerVolume;
                          int *MaxMinOption;
                          int (*Communicator)();
                          } AVW_Instructions;
DESCRIPTION
                   The AVW_Instructions structure provides an easy way to pass and return instructions.
   LOCATION
                   AVW_Parse.h
```

AVW\_Parse(), AVW\_DoInstructions(), AVW\_DestroyInstructions()

**SEE ALSO** 

double Area; double Volume; double HighestIntensity; AVW\_Point3 HighestPoint;

double LowestIntensity; AVW\_Point3 LowestPoint; double RangeMaximum; double RangeMinimum; double MeanInRange;

double StandardDeviationInRange;

double VarianceInRange; double SumInRange; double SumOfSquaresInF

double SumOfSquaresInRange; unsigned long NumberBelowRange; unsigned long NumberInRange;

unsigned long NumberAboveRange;

double AreaInRange; double VolumeInRange; double BrightnessAreaProduct; } AVW\_IntensityStats;

**DESCRIPTION** 

The *AVW\_IntensityStats* structure provides an easy way to return intensity statistics from *AVW* functions.

**LOCATION** 

AVW\_Measure.h

**SEE ALSO** 

AVW\_Point3, AVW\_ComputeImageIntensityStats(), AVW\_ComputeVolumeIntensityStats()

**NAME** AVW\_Line2 – 2D Line Structure

**SYNOPSIS** typedef struct

AVW\_Point2 Start, End;

} AVW\_Line2;

**DESCRIPTION** The *AVW\_Line2* structure provides an easy way to pass and return 2D lines.

Start and End specify end points of the line.

LOCATION AVW.h

**SEE ALSO** *AVW\_Point2, AVW\_Line3* 

**NAME** AVW\_Line3 – 3D Line Structure

**SYNOPSIS** typedef struct

AVW\_Point3 Start, End;

} AVW\_Line3;

**DESCRIPTION** The *AVW\_Line3* structure provides an easy way to pass and return 3D lines.

Start and End specify end points of the line.

LOCATION AVW.h

SEE ALSO AVW\_Point3, AVW\_Line2

**NAME** AVW\_List – List Structure

**SYNOPSIS** typedef struct

int NumberOfEntries;

char \*\*Entry;
} AVW\_List;

**DESCRIPTION** The *AVW\_List* structure provides an easy way to pass and return lists.

NumberOfEntries indicates the total number of entries in the list.

*Entry* is a pointer to an array of char pointers.

LOCATION AVW.h

SEE ALSO | AVW\_DestroyList(), AVW\_ListFormats(), AVW\_ListInfo()

AVW\_MatchParameters - Surface Match Parameters Structure

# **SYNOPSIS**

typedef struct

{

int SamplePoints;

int Centroid;

float TranslationX, TranslationY, TranslationZ;

float TranslationRange;

float RotationPrecession, RotationNutation, RotationSpin;

float RotationRange;

float RotationInterval;

} AVW\_MatchParameters;

#### **DESCRIPTION**

The *AVW\_MatchParameters* structure controls the initial position of the match surface and the range of translational and rotational motion allowed during the search for the best match.

*SamplePoints* determines how many randomly-selected points on the match surface are used for the search. Larger numbers give better matches, but require more search time.

*Centroid*, if nonzero, indicates that the *TranslationX*, *TranslationY* and *TranslationZ* values are to be ignored, and the centroids of the base and match surface used for the initial search position.

*TranslationX*, *TranslationY* and *TranslationZ* specify the starting match position if *Centroid* is zero.

*TranslationRange* specifies the maximum translation (in voxels) allowed in the search.

RotationPrecession, RotationNutation, and RotationSpin indicate the initial 3D rotational search position.

*RotationRange* specifies the total allowable range of rotation (about all three axes) for the search.

*RotationInterval* specifies the number of degrees per step in the final (high-resoluton) search for the best matching position. The default is one degree.

# **LOCATION**

AVW\_SurfaceMatch.h

#### **SEE ALSO**

AVW\_MatchSurfaces(), AVW\_MatchResults

AVW\_MatchResult - Surface Match Results Structure

#### **SYNOPSIS**

typedef struct

{
 AVW\_Matrix \*Matrix;
float MeanSquareDistance;
 AVW\_MatchParameters \*NextInput;
} AVW\_MatchResult;

#### **DESCRIPTION**

The *AVW\_MatchResult* structure provides the scpecification of the best matching position found as well as a modified *AVW\_MatchParameters* structure set up for a more rigorous (i.e. finer resolution) search over a restricted search range.

*Matrix* contains the entire translational, rotational, and scaling transformation required to take the Match image into the coordinate space of the base image.

*MeanSquareDistance* is the residual error of the current match. Since this absolute number is dependent upon the specific surfaces used for matching, it is only usefull as a comparison of different matches of the same surfaces.

*NextInput* is a *AVW\_MatchParameters* structure set up for a more rigorous search over a restricted search range.

**LOCATION** 

AVW\_SurfaceMatch.h

**SEE ALSO** 

AVW\_MatchParameters, AVW\_MatchSurfaces()

AVW\_MatchVoxelParams - Voxel Match Parameters Structure

#### **SYNOPSIS**

#### **DESCRIPTION**

The AVW\_MatchVoxelParams structure controls the convergence tolerance for the searching strategy, total number of iterations, the interpolation method used to evaluate the transformed volume voxels, the sub-sampling used for histogram evaluation in each scaling level, initial position of the match surface and the range of translational and rotational motion allowed during the search for the best match.

*Ftol* determines the convergence tolerance for the search strategy. If the change in the cost-function is smaller than this value, the search will stop assuming this is the minimum.

*Ptol* specifies the transformation parameters convergence tolerance. That is, if the total change in all of the 6 transformation parameters (X,Y,Z rotations and translations) is less than Ptol for a number of successive iterations the subroutine will terminate the search.

*Interpolate* specifies whether the transformed image will be computed with bilinear (AVW\_TRUE) or nearest neighbor (AVW\_FALSE) interpolation.

*Smpl1to1*, *Smpl2to1*, *Smpl4to1* and *Smpl8to1* Specifies sampling in the X, Y and Z directions. (i.e., if X and Y are set to 3, and Z is 1, than the calculation of the cost function will use every third voxel in the X and Y directions, and all of the slices in the Z direction.

The search is done in stages, first on a volume scaled to a size of 8:1, than 4:1, 2:1 and finally 1:1. The sampling values can be specified for each one of these scaling stages (Smpl8to1, Smpl4to1, Smpl2to1 and Smpl1to1 respectively). If scaling to a certain size would cause a the volume to become to small the stage will be skipped. It is the users responsibility to assign reasonable values for sampling. Values which cause the use of only a very small number of voxels, will lead to non-accurate results. To determine a good experimental value, define the sample in such a way that there is 30 to 50 points in each direction. This will usually lead to good results with the best possible computation time.

*InitGuess* specifies the initial position (X,Y,Z rotation and translations) of the match volume.

*SearchLength* defines the problem characteristic scale in X, Y, Z rotation and translation. Theses parameters limit the distance of the search algorithm.

LOCATION AVW\_MatchVoxels.h

AVW\_Matrix - Transformation Matrix Definition

## **SYNOPSIS**

typedef struct
 {
 unsigned int Rows;
 unsigned int Columns;
 double \*\*Matrix;
 } AVW\_Matrix;

## **DESCRIPTION**

The *AVW\_Matrix* structure provides an easy way to pass and return a transformation matrix.

*Rows* and *Columns* specify the dimensions of the matrix. These values will almost always be 4 and 4.

*Matrix* is a double dimensioned array which allows access to each element within the structure. Example: mat->Matrix[1][2] returns the value in the row 1 and column 2.

# **LOCATION**

AVW.h

# **SEE ALSO**

AVW\_CreateMatrix(), AVW\_DestroyMatrix(), AVW\_RotateMatrix(), AVW\_CopyMatrix(), AVW\_InvertMatrix(), AVW\_MakeMatrixFrom3Points(), AVW\_MakeMatrixFromAxis(), AVW\_MirrorMatrix(), AVW\_MultiplyMatrix(), AVW\_RotateMatrix(), AVW\_ScaleMatrix(), AVW\_ScaleMatrix(), AVW\_TransformImage(), AVW\_TransformVolume()

AVW\_MergedMap - Merged Map Structure

#### **SYNOPSIS**

typedef struct

int NumberMerged; AVW\_Image \*Image; AVW\_Matrix \*\*Matrix; } AVW\_MergedMap;

# **DESCRIPTION**

The *AVW\_MergedMap* structure is filled in the *AVW\_MergeRendered()* function. It contains information about where each pixel in the output image came from and what *AVW\_Matrix* was used to create it.

NumberMerged is the number of images merged to produce the output.

*Image* is an *AVW\_Image* which indicates which image each pixel came from.

*Matrix* is an array of *AVW\_Matrix's* which were used in creating the original pixels before merging.

# **LOCATION**

AVW\_MergedMap.h

# **SEE ALSO**

 $AVW\_MergeRendered(),\ AVW\_DestroyMergedMap(),\ AVW\_Image,\ AVW\_Matrix,\ AVW\_RenderedImage$ 

**NAME** AVW\_MultiList2 – List of AVW\_PointList2s

**SYNOPSIS** typedef struct

unsigned int NumberOfLists; AVW\_PointList2 \*\*Lists;

} AVW\_MultiList2;

**DESCRIPTION** The AVW\_MultiList2 structure provides an easy way to pass and return a list of

AVW\_PointList2s.

*NumberOfList* is the current number of lists.

*Lists* is a pointer to an array of *AVW\_PointList2s*.

LOCATION | AVW.h

**SEE ALSO** AVW\_DestroyMultiList2(), AVW\_PointList2

AVW\_Object - Object Structure

# **SYNOPSIS**

```
typedef struct
{
```

char Name[32]; int DisplayFlag;

unsigned char TransformFlag;

unsigned char MirrorFlag; unsigned char StatusFlag;

unsigned char NeighborsUsedFlag;

int Shades;

int StartRed, StartGreen, StartBlue;

int EndRed, EndGreen, EndBlue;

int XRotation, YRotation, ZRotation;

int XTranslation, YTranslation, ZTranslation;

int XCenter, YCenter, ZCenter;

int XRotationIncrement, YRotationIncrement, ZRotationIncrement;

int XTranslationIncrement, YTranslationIncrement, ZTranslationIncrement;

 $short\ int\ Minimum XV alue,\ Minimum YV alue,\ Minimum ZV alue;$ 

short int MaximumXValue, MaximumYValue, MaximumZValue;

float Opacity;

int OpacityThickness;

int Dummy;

} AVW\_Object;

## **DESCRIPTION**

The AVW\_Object structure contains all the attributes for each object in a AVW\_ObjectMap.

Name specifies an identifier for this object.

*DisplayFlag* specifies whether this object will be visable or not. If this flag is set to *AVW\_FALSE*, all voxels of this object type will be ignored during the next render.

*TransformFlag* enables and disables the special object transformation parameters. A value of *zero* (0), *indicates that the Rotation, Translation, Mirror*, and *Region* parameters are ignored. A value of *one* (1), causes a seperate rendering pass for this object where the transformations are applied. A value of *two* (2), indicates that this objects should be rendered in both the untransformed and the transformed rendering pass.

MirrorFlag specifies an axis which this object is mirrored against. [See TransformFlag]

StatusFlag is currently unused.

Neighbors UsedFlag indicates how neighbors are processed.

*Shades* indicates the number of shades to allow for this object. A total of 256 (250 in AnalyzeAVW) total shades are available.

*StartRed, StartGreen,* and *StartBlue* specifies the starting color for this object. These values range from 0-255. Black is 0, 0, 0. Red is 255, 0, 0. etc... AnalyzeAVW normally defaults this to 10% of the ending color.

EndRed, EndGreen, and EndBlue specifies the ending color.

*XRotation, YRotation,* and *ZRotation* indicates the amount of rotation to apply specifically to this object. [See TransformFlag]

XTranslation, YTranslation, and ZTranslation indicates the amount of translation to apply specifically to this object. [See TransformFlag]

*XCenter, YCenter,* and *ZCenter* indicates the center of rotation for this object. [See TransformFlag]

*XRotationIncrement, YRotationIncrement,* and *ZRotationIncrement* specifies the amount of desired rotational change for this object during a SEQUENCE.

XTranslationIncrement, YTranslationIncrement, and ZTranslationIncrement specifies the amount of desired translational change for this object during a SEQUENCE.

MinimumXValue, MinimumYValue, MinimumZValue, MaximumXValue, MaximumYValue, and MaximumZValue specifies the minimum bounding box (Region) for this object. These values allow transformed objects to be rendered in less time. The AVW\_CalculateObjectRegions() function can be used to set these values. [See Transform-Flag]

*Opacity* specifies a value from .001 (Very Transparent) to 1.000 (Opaque) for this object. This value is used when the render *Type* is set to *AVW\_TRANSPARENCY\_SHADING*.

OpacityThickness specifies a count of voxels for which the Opacity value is calculated. Normally this is set to one and only the 1st voxel of each surface encountered is processed. Setting this to a higher value allows the rendering to show object thicknesses, because thicker regions will obscure more of a object than thinner regions.

Dummy is just a space filler and is not used.

**LOCATION** AVW\_ObjectMap.h

**SEE ALSO** | AVW\_ObjectMap

```
NAME AVW_ObjectMap - Object Map Structure

typedef struct

{
    int Version;
    int NumberOfObjects;
    AVW_Volume *Volume;
    AVW_Object *Object[256];
    unsigned char ShowObject[256];
    unsigned char MinimumPixelValue[256];
    unsigned char MaximumPixelValue[256];
    int NeedsSaving;
    int NeedsRegionsCalculated;
} AVW_ObjectMap;
```

#### **DESCRIPTION**

The *AVW\_ObjectMap* structure provides an easy way to pass an object map to and from *AVW* functions.

*Version* specifies which version of a *.obj* file this *AVW\_ObjectMap* was read from. This field is not used, but is for information purposes only.

*NumberOfObjects* indicates the current number of objects defined in this object map.

*Volume* is a pointer to an  $AVW\_Volume$ . This volume contains a zero (0) in each voxel which has been defined as being part of Object[0]. A one (1) for Object[1], and so on. This volume may be manipulated with the other routines.

Object is an array of pointer to AVW\_Object structures.

*ShowObject* is an array of flags used internally to indicate whether an object is currently being rendered. This is for internal use only.

*MinimumPixelValue* and *MaximumPixelValue* are arrays which indicate at which position in a color lookup table each objects colors start or end. This is for internal use only.

*NeedsSaving* is a flag which can be checked by an interface program to determine if the ObjectMap should be saved before exiting or unloading.

*NeedsRegionsCalculated* is a flag which indicates that the ObjectMap data has changed and that *AVW\_CalculateObjectRegions()* should be called to calculate the minimum bounding box (Region).

**LOCATION** 

AVW\_ObjectMap.h

**SEE ALSO** 

AVW\_Object, AVW\_Volume

**NAME** AVW\_Point2 – 2D Point Structure

**SYNOPSIS** typedef struct

short X, Y;
} AVW\_Point2;

**DESCRIPTION** The *AVW\_Point2* structure provides an easy way to pass and return 2D coordinates.

X and Y specify coordinate values.

LOCATION AVW.h

SEE ALSO AVW\_Point3, AVW\_IPoint2, AVW\_FPoint2, AVW\_PointList2, AVW\_AddPoint2(),

AVW\_GetPixel(), AVW\_GetPoint2() AVW\_PutPixel(), AVW\_RemovePoint2()

**NAME** AVW\_Point3 – 3D Point Structure

**SYNOPSIS** typedef struct

{
short X, Y, Z;
short padding;
} AVW\_Point3;

**DESCRIPTION** The *AVW\_Point3* structure provides an easy way to pass and return 3D coordinates.

*X*, *Y*, and *Z* specify coordinate values.

**LOCATION** | AVW.h

SEE ALSO AVW\_Point2, AVW\_IPoint3, AVW\_FPoint3, AVW\_PointList3, AVW\_AddPoint3(), AVW\_GetPoint3() AVW\_GetVoxel(), AVW\_PutVoxel(), AVW\_RemovePoint3()

AVW\_PointList2 - List of 2D points

**SYNOPSIS** 

typedef struct

unsigned int NumberOfPoints; unsigned int MaximumPoints; unsigned int BlockSize; AVW\_Point2 \*Points; AVW\_PointList2;

# **DESCRIPTION**

The *AVW\_PointList2* structure provides an easy way to pass and return a list of 2D points.

NumberOfPoints is the current number of points in the list.

*MaximumPoints* indicates the number of points this list can hold before automatic reallocation.

BlockSize indicates the number added to the current size when reallocation is necessary.

*Points* is a pointer to an array of *AVW\_Point2s*.

**LOCATION** 

AVW.h

**SEE ALSO** 

AVW\_Point2, AVW\_AddPoint2(), AVW\_CreatePointList2(), AVW\_DestroyPointList2(), AVW\_GetPoint2() AVW\_RemovePoint2()

AVW\_PointList3 - List of 3D points

# **SYNOPSIS**

typedef struct

unsigned int NumberOfPoints; unsigned int MaximumPoints; unsigned int BlockSize; AVW\_Point3 \*Points; } AVW\_PointList3;

# **DESCRIPTION**

The *AVW\_PointList3* structure provides an easy way to pass and return a list of 3D points.

*NumberOfPoints* is the current number of points in the list.

*MaximumPoints* indicates the number of points this list can hold before automatic reallocation.

*BlockSize* indicates the number added to the current size when reallocation is necessary.

Points is a pointer to an array of AVW\_Point3s.

# **LOCATION**

AVW.h

# **SEE ALSO**

AVW\_Point3, AVW\_AddPoint3(), AVW\_CreatePointList3(), AVW\_DestroyPointList3(), AVW\_GetPoint3() AVW\_RemovePoint3()

AVW\_PointValueList - List of 2D points w/values

# **SYNOPSIS**

typedef struct

unsigned int NumberOfPoints; unsigned int MaximumPoints; unsigned int BlockSize; AVW\_Point2 \*Points; double \*Values; } AVW\_PointValueList;

# **DESCRIPTION**

The *AVW\_PointValueList* structure provides an easy way to pass and return a list of 2D points.

*NumberOfPoints* is the current number of points in the list.

*MaximumPoints* indicates the number of points this list can hold before automatic reallocation.

*BlockSize* indicates the number added to the current size when reallocation is necessary.

Points is a pointer to an array of AVW\_Point2s.

Values is a pointer to an array of doubles.

# **LOCATION**

AVW.h

# **SEE ALSO**

AVW\_Point2, AVW\_AddPointValue(), AVW\_ComputeLineProfile(), AVW\_CreatePointValueList(), AVW\_DestroyPointValueList(), AVW\_GetPointValue() AVW\_RemovePointValue()

NAME AVW\_RPParam – Tile Structure

typedef struct
{
 AVW\_Volume \*MaskVolume;
 double MaskValue;
 double AngleResolution;

int InterpolateFlag;
 int SubvolumeFlag;
 int Format;

int Orientation; int HandleBlankSlices; int Connectivity;

} AVW\_RPParam;

#### **DESCRIPTION**

The *AVW\_RPParam* structure provides a method of passing parameters to and from the AVW contour extraction routines.

*Format* specifies the output format and is used by *AVW\_SaveContourSurface*. Supported values include:

AVW\_HPGL\_SURFACE – A modified form of HPGL plotter commands designed to support rapid prototyping or stereolithography machines AVW\_POGO\_SURFACE – A compressed version of the binary SLC format. This format does not differentiate between internal and external boundaries. AVW\_SLC\_SURFACE – The standard binary SLC format. AVW\_SSD\_ASCII\_SURFACE – The ASCII version of the standard Analyze SSD format.

*SubvolumeFlag* if set, *AVW\_SliceVolume* will subvolume the dataset so that the object of interest is contained within a minimum enclosing volume. This may cause the data to be reoriented prior to contour extraction.

*MaskValue* specify the mask value of the object within the *AVW\_Volume* whose contours are to be extracted.

*InterpolateFlag* if set, *AVW\_SliceVolume* will subvolume the dataset using trilinear interpolation.

*Orientation* specifies which orthogonal axis will be used during contour extraction This parameter may be one of:

AVW\_TRANSVERSE [default], AVW\_CORONAL, or AVW\_SAGITTAL

AngleResolution specifies the angle resolution used while determining the minimum enclosing box.

HandleBlankSlices if set, AVW\_SaveContourSurface will repeat the previous slice's contours if the current slice is blank and the output file format supports slice repetition. Otherwise, AVW\_SaveContourSurface will terminate on a blank slice if the output file format is unable to handle missing data. At present, this flag only effects

SLC formatted files.

Connectivity is used by  $AVW\_SliceVolume$  to determine the connectivity of the extracted edges. It may be set to:  $AVW\_4\_CONNECTED$  or  $AVW\_8\_CONNECTED$ .

LOCATION

 $AVW\_Model.h$ 

**SEE ALSO** 

AVW\_DestroyRPParam(), AVW\_InitializeRPParam(), AVW\_SliceVolume(), AVW\_Volume

**NAME** AVW\_Rect2 – 2D Rectangle Structure

**SYNOPSIS** typedef struct

AVW\_Point2 PointA, PointB;

} AVW\_Rect2;

**DESCRIPTION** The *AVW\_Rect2* structure provides an easy way to pass and return 2D rectangles.

*PointA* and *PointB* specify opposite corners.

LOCATION | AVW.h

**SEE ALSO** AVW\_Point2, AVW\_Rect3, AVW\_GetSubImage()

**NAME** AVW\_Rect3 – 3D Rectangle (Cube) Structure

**SYNOPSIS** typedef struct

AVW\_Point3 PointA, PointB;

} AVW\_Rect3;

**DESCRIPTION** The *AVW\_Rect2* structure provides an easy way to pass and return 3D rectangles (cubes).

*PointA* and *PointB* specify opposite corners.

LOCATION AVW.h

SEE ALSO | AVW\_Point3, AVW\_Rect2, AVW\_GetSubVolume()

AVW\_RenderParameters - Render Structure

#### **SYNOPSIS**

typedef struct

{

int Type;

double ThresholdMinimum, ThresholdMaximum;

int ClipLowX, ClipLowY, ClipLowZ;

int ClipHighX, ClipHighY, ClipHighZ;

int ClipPlaneMinimum, ClipPlaneMaximum;

int ClipShading;

int RenderWidth, RenderHeight, RenderDepth;

int MaximumPixelValue, MinimumPixelValue;

int SurfaceThickness;

AVW\_Matrix \*Matrix;

AVW\_Matrix \*LightMatrix;

AVW\_Image \*RenderMask;

int MaskValue;

int DeleteDepth;

double DeleteValue;

double ScaleX, ScaleY, ScaleZ;

int PerspectiveType;

AVW\_FPoint3 EyePosition;

double XFieldOfViewAngle, YFieldOfViewAngle;

double SpecularFactor;

double SpecularExponent;

int SurfaceSkip;

int MIP\_Weight;

AVW\_CompositeInfo \*CompositeInfo;

int BackgroundColor;

double BackgroundValue;

int RenderMode;

int InteractiveObject;

AVW\_InternalParameters Internal;

} AVW\_RenderParameters;

# **DESCRIPTION**

The *AVW\_RenderParameters* structure provides a method of passing the large number of render parameters to and from the AVW rendering routines.

*Type* determines the type of raycasting preformed. The default is

AVW\_GRADIENT\_SHADING. Possible values are: AVW\_USER\_DEFINED,

AVW\_DEPTH\_SHADING, AVW\_GRADIENT\_SHADING,

AVW\_VOLUME\_COMPOSITING, AVW\_MAX\_INTENSITY\_PROJECTION,

AVW\_SUMMED\_VOXEL\_PROJECTION, AVW\_SURFACE\_PROJECTION,

AVW\_TRANSPARENCY\_SHADING, and AVW\_DELETE\_VOXELS,

ThresholdMinimum and ThresholdMaximum specifies the range of voxels value to process.

*ClipLowX*, *ClipLowY*, *ClipLowZ*, *ClipHighX*, *ClipHighY*, and *ClipHighZ* specify the portion of the input volume that is processed.

*ClipPlaneMinimum* and *ClipPlaneMaximum* specify the starting and ending depths for the ray casting process.

ClipShading determines the type of shading that is used when the ray casting process

begins at a voxel which is within the threshold range (and object enabled). The value is only used when the render *Type* is set to *AVW\_GRADIENT\_SHADING*. Possible values are: *AVW\_CLIP\_SHADED*, *AVW\_CLIP\_ACTUAL*,

AVW\_CLIP\_REMOVE\_AND\_RENDER, and AVW\_CLIP\_RENDER\_AS\_IS. [Default = AVW\_CLIP\_SHADED]

RenderWidth and RenderHeight specify the dimension of the output image and buffers. RenderDepth determines the range of depths. Matrix. The ScaleX, ScaleY, and ScaleZ also need to be considered when determining the proper RenderWidth, RenderHeight and RenderDepth.

MaximumPixelValue, and MinimumPixelValue specify the output intensity range.

Surface Thickness specify the number of voxels to sum during a Surface Projection.

*SurfaceSkip* specify the number of voxels to skip before summing begins during a Surface Projection.

MIP\_Weight specify the weighting options used during a Maximum Intensity Projections. Options include: AVW\_NO\_WEIGHTING, AVW\_WEIGHT\_BEFORE, and AVW\_WEIGHT\_AFTER. AVW\_WEIGHT\_BEFORE indicates that before a voxel is checked to see if it is the maximum value, a weighting factor is applied. The weighting factor is determined by dividing the length of the ray left to cast, by it's total length. AVW\_WEIGHT\_AFTER determines the maximum voxel along the entire ray casting path and then applies the weightinh factor described above.

*Matrix* is an *AVW\_Matrix* which specifies any rotation and translation that is applied to the input volume. Scale could also be specified as part of the matrix, but it's recommended that the *ScaleX*, *ScaleY*, and *ScaleZ* parameters be used for Scale.

LightMatrix is an AVW\_Matrix which specifies the location of the light source.

*RenderMask*, if not *NULL*, restricts the rendering process to all voxels in the *RenderMask* image, which have a value of *MaskValue*. This must always be either NULL, or have a dimension of *RenderWidth* by *RenderHeight*.

*DeleteDepth* and *DeleteValue* are used in conjuction with the *AVW\_DELETE\_VOXELS* rendering *Type* and the *RenderMask* and *MaskValue* to delete voxels in the input volume.

DeleteDepth should be set to one of the following: AVW\_DELETE\_ALL\_THE\_WAY, AVW\_DELETE\_SINGLE\_LAYER, AVW\_DELETE\_SINGLE\_VOXEL, AVW\_DEFINE\_ALL\_THE\_WAY, AVW\_DEFINE\_SINGLE\_LAYER, or AVW\_DEFINE\_SINGLE\_VOXEL.

If the *DEFINE* values are used, objects within an object\_map are redefined.

*ScaleX*, *ScaleY*, and *ScaleZ* specify the scale factors to be applied to each input axis during the rendering process. A value of 1.0 indicates no scaling is applied.

PerspectiveType specifies the type of rendering to be performed. AVW\_PERSPECTIVE\_INT renders the image using the voxels without interpolation, possibly resulting in "blocky" renderings. If PerspectiveType is set to AVW\_PERSPECTIVE\_FLOAT, the rendered image is generated using an on the fly interpolation rendering algorithm. If PerspectiveType is set to AVW\_PERSPECTIVE\_OFF, parallel rendering is performed. For perspective rendering, the render matrix is interperted as a viewing direction for the camera model, however the parallel rendering conventions are followed, i.e. the matrix is left handed, and the identity matrix provides a

view along the positive Z axis with X increasing to the right and Y increasing in the vertical direction. Perspective rendering does not support scaling at this time. For anisotropic data, rescaling during loading is the best option.

*EyePosition* specifies the location of the camera model used to generate the rendering. This parameter is only used when *PerspectiveType* is set to  $AVW\_PERSPECTIVE\_FLOAT$  or  $AVW\_PERSPECTIVE\_INT$ . The X, Y, and Z coordinates of the  $AVW\_FPoint3$  structure refer to the position of the camera relative to the center of the volume, thus a position of (0,0,0) in a particular volume is located at voxel (Width / 2, Height / 2, Depth / 2).

XFieldOfViewAngle and YFieldOfViewAngle specify the field of view (FOV) angle of the camera model used to generate the image. Increasing the FOV results in a zoom out effect, if the position remains the same. Decreasing the FOV results in a zoom in effect.

SpecularFactor specifies the ratio of gradient shading to specular shading. If SpecularFactor is set to 0, the rendering will be shaded entirely using gradient shading with no performance penalty. If SpecularFactor is set to .1, the rendering is shaded entirely using the specular shading model.

*SpecularExponent* specifies the degree of fall-off for specular shading. High values (about 10) result in very small specular highlights, while small values (about 1 or 2) result in diffuse highlights.

CompositeInfo specifies a pointer to a structure which contains compositing information. This must contain a valid pointer when the *Type is set to* AVW\_VOLUME\_COMPOSITING. See AVW\_CompositeInfo for more information.

BackgroundColor and BackgroundValue are used to specify the background color or value. The rendering type, input volumes datatype, and whether an object map is loaded determines which value is used. If the output is a grayscale image, BackgroundValue is used. If the output is a color image, then BackgroundColor will be used. Background Color is a packed RGB value which can be produced with the AVW\_RGB macro.

RenderMode is normally set to AVW\_RENDER\_NORMAL, but when set to AVW\_PREPARE\_FOR\_MOVE, the AVW\_RenderVolume() function will process the object specified in the InteractiveObject seperately and return the "visible surface" in the AVW\_RenderedImage member called InteractiveSurface. This results in the input to AVW\_RenderVisibleSurface() which produces output which can be combined using AVW\_MergeRendered() with the rendering returned at the time the InteractiveSurface was produced. This entire process allows an interface to be build to interactively move and rotate objects. RenderMode can be set to AVW\_RERENDER\_MOVED, at the completion of the object transformation to rerender any missing data.

The *AVW* rendering routines also have a variety of other parameters and tables which are not available for user modification. These are stored in the *Internal* member of the AVW RenderParameters structure.

**LOCATION** 

AVW\_Render.h

**SEE ALSO** 

AVW\_DestroyRenderParameters(), AVW\_ExtractSurface(), AVW\_RenderParameters(), AVW\_RenderSurface(), AVW\_RenderVolume(), AVW\_FPoint3, AVW\_CompositeInfo, AVW\_Image, AVW\_Matrix

AVW\_RenderedImage - Rendered Image Structure

#### **SYNOPSIS**

typedef struct

int Width, Height, Depth;

double MaximumPixelValue, MinimumPixelValue;

AVW\_Image \*Image;

AVW\_Image \*ZBuffer;

AVW\_Image \*PBuffer;

AVW\_Volume \*Volume;

AVW\_ObjectMap \*ObjectMap;

AVW\_Matrix \*Matrix;

AVW\_Matrix \*InverseMatrix;

int PerspectiveType;

AVW\_FPoint3 EyePosition;

double XFieldOfViewAngle, YFieldOfViewAngle;

AVW\_MergedMap \*MergedMap;

AVW\_VisibleSurface \*InteractiveSurface;

double ReservedForFuture1:

double ReservedForFuture2:

double ReservedForFuture3:

} AVW\_RenderedImage;

#### **DESCRIPTION**

The *AVW\_RenderedImage* structure is provides an easy way for rendered images to be returned from or passed to *AVW* functions.

Width, and Height indicate the size of the rendered image.

*Depth* indicates the maximum depth value.

*MaximumPixelValue* and *MinimumPixelValue* specify the range of pixels possible in the output image.

*Image* contains the visual information that resulted from the rendering process.

ZBuffer contains depth information used in calculating ray lengths.

PBuffer contains depth information for points found.

Volume is a pointer to the input volume of the last rendering process.

*ObjectMap* is a pointer to the object map of the last rendering process.

Matrix is the matrix used during the creation of this rendered image.

*InverseMatrix* is the inverse of the matrix used to create this rendered image.

*PerspectiveType* indicates if one of the perspective types was used to generate this rendered image.

*EyePosition* indicates the eye position of the last perspective rendering.

XFieldOfViewAngle and YFieldOfViewAngle indicate the field of view for the last perspective rendering.

*MergedMap* is normally *NULL*, *but after a call to AVW\_MergeRendered* it is filled with information about where pixels came from and how they were generated.

Interactive Surface is normally NULL. It's filled only when  $AVW\_RenderVolume()$  is used with the Interactive Mode set to  $AVW\_PREPARE\_FOR\_MOVE$  or  $AVW\_RERENDER\_MOVED$ .

**LOCATION** 

AVW\_Render.h

**SEE ALSO** 

AVW\_FPoint3, AVW\_Image, AVW\_Matrix, AVW\_MergedMap, AVW\_ObjectMap, AVW\_Volume

AVW\_SampleSpec - Image or Volume Sample Specification

# **SYNOPSIS**

typedef struct {

int SampleType; int Interpolation;

int XSamples, YSamples, ZSamples;

double XStart,YStart,ZStart; double XEnd,YEnd,ZEnd; } AVW\_SampleSpec;

# **DESCRIPTION**

The *AVW\_SampleSpec* structure provides the specification for an sample of 2D or 3D coordinate points to be used for voxel statistics registration functions.

*SampleType* specifies the type of sample. Currently defined are AVW\_GRID\_SAMPLE and AVW\_RANDOM\_SAMPLE.

*Interpolation* is any of the standard AVW interpolation types. If *Interpolation* is AVW\_NEAREST\_NEIGHBOR\_INTERPOLATE, all coordinate values will be truncated to integer values, otherwise floating point (double) coordinates are calculated.

XSamples, YSamples, ZSamples indicates the sampling density in all three dimensions. The total number of coordinates calculated is XSamples\* YSamples\* ZSamples.

XStart, YStart, ZStart, XEnd, YEnd, ZEnd are starting and ending coordinates for the region to be sampled.

# **LOCATION**

AVW\_MatchVoxels.h

# **SEE ALSO**

AVW\_StepSearchSpec, AVW\_SetupVolumeSample() AVW\_SampleVolume() AVW\_SetupImageSample() AVW\_SampleImage()

AVW\_StepSearchSpec - 6-DOF Bounded Step Search Specification

**SYNOPSIS** 

typedef struct {

double XStep,YStep,ZStep;
double XRStep,YRStep,ZRStep;
int XBound,YBound,ZBound,XRBound,YRBound,ZRBound;
} AVW\_StepSearchSpec;

**DESCRIPTION** 

The *AVW\_StepSearchSpec* structure provides the specification for a bounded, stepwise extrema search of a 6-DOF physical registration parameter space.

*XStep*, *YStep*, *ZStep* specifies the translational step size in voxels, and may be non-integer.

*XRStep*, *YRStep*, *ZRStep* specifies the rotational step size in degrees, and may be non-integer.

XBound, YBound, ZBound, ZRBound, ZRBound specifies the maximum allowable number of steps in 6-DOF.

**LOCATION** 

AVW\_MatchVoxels.h

**SEE ALSO** 

AVW\_StepSearchExtreme() AVW\_StepSearchExtreme2D() AVW\_BoundedStepSearchExtreme() AVW\_BoundedStepSearchExtreme2D()

AVW\_TileParameters - Tile Structure

# **SYNOPSIS**

```
typedef struct
```

AVW\_Volume \*Vol; AVW\_ObjectMap \*Omap;

unsigned int Type; unsigned int Checkpoint;

int MaskValue;

int CurveOpRadius; int CloseSrfcFlag; int KohonenMajorAxis;

unsigned int KohonenShapeOrient; float KohonenShapeOffset; unsigned int KohonenNeighborhood; unsigned int KohonenTopology;

float KohonenNeighborRadius;

float KohonenAlpha;

unsigned int AddNodeFreq; unsigned int MaximumAge;

float Eb, En;

float GrowingAlpha; float GrowingD;

int Edge; int Iteration;

double Step; double Kd; double Kj; } AVW\_TileParameters;

#### DESCRIPTION

The *AVW\_TileParameters* structure provides a method of passing the large number of tiling parameters to and from the AVW tiling routines.

*Type* determines the type of tiling preformed. The default is *AVW\_DEFORMATION*. Possible values are:

AVW\_TILE\_KOHONEN, AVW\_TILE\_GROW, AVW\_DEFORMATION and AVW\_MARCHING\_CUBES,

*MaskValue* specifies the object to tile. The object is considered to be all voxels having the value *MaskValue* (if the data is an object map, mask is the object number).

*CurveOpRadius* specifies the spacing between the elements of the curvature operator. Increasing the spacing between the elements reduces the effects of local noise on the curvature calculation.

CloseSrfcFlag if set will cause the generation of a surface with closed ends.

KohonenMajorAxis specifies the major adaptation axis for the kohonen tiling algorithm.

*KohonenShapeOrient* specifies the initial orientation of the network for the kohonen tiling algorithm.

*KohonenShapeOffset* specifies the multiplier used to determine the initial distance from the network to the object for the kohonen tiling algorithm

*KohonenFlag* specifies modifications to the kohonen tiling algorithm. May be one of: *AVW\_TRAIN\_IN\_MAJOR\_AXIS*, and/or *AVW\_TRAIN\_WITH\_WEIGHT*,

*PolygonBudget* specifies the maximum number of polygons that may be in the surface produced by the tiling algorithm(s). If *AVW\_DEFORMATION* is set to *AVW\_DEFORMATION*, the algorithm will attempt to determine the optimal number of polygonal tiles based on the size of the deresolution element.

*KohonenRepetitions,* specifies the number of times the data is presented to the network during adaptation.

*KohonenNeighborhood* specifies how a neighborhood of cells will move during adaptation of the kohonen network. May be one of

AVW\_BUBBLE\_NEIGHBORHOOD, AVW\_GAUSS\_NEIGHBORHOOD, and/or AVW\_TRIANGLE\_NEIGHBORHOOD,

*KohonenTopology* describes the network topology for the kohonen tiling algorithm. Currently only *AVW\_RECTANGULAR\_TOPOLOGY* is supported

*KohonenNeighborRadius* specifies the initial radius of a kohonen neighborhood. If the value is less than 1, the initial radius will be set to be one third of the distance around the 2-D bounding oval orthogonal to the major axis.

Kohonen Alpha specifies the initial learning rate for the kohonen tiling algorithm.

*AddNodeFreq* specifies the number of adaptation steps envoked by the growing net algorithm before a new node is added.

*MaximumAge* specifies the maximal age number allowed for the growing net edges (connections). Edges with age greater than *MaximumAge* are removing from the growing net.

*Eb, En* specifies the adaptation factors for the best matching unit (bmu) node and its direct neighbors, respectively.

*GrowingAlpha* specifies the factor for decreasing the error counters of the 1st and 2nd bmus after the insertion of a new node to the growing net, respectively.

*GrowingD* specifies the factor for decreasing the error counters of all nodes after the insertion of a new node to the growing net.

Edge specifies the length (in voxels) of the initial deresolution cube. if *PolygonBudget* is set to 0, this parameter will be used in determining the number of polyonal tiles used in the surface. The smaller the value, the greater then number of polygonal tiles. A value of 1 will tile at the voxel level. It is possible for the algorithm to start thrashing if the *Polygon-Budget* and *Edge* are set to small values. In this case, the algorithm will be unable to build a topology that meets the error conditions.

*Iteration* specifies the number of deformation steps the algorithm will take during its

Mayo Foundation AVW\_TileParameters()

> adaptation phase. The more iterations the surface under goes, the better its fit. It is possible for the algorithm to start thrashing if the number of iterations is too high as it will be unable to meet the error conditions.

Step specifies the time step size for the adaptation phase.

Kd specifies the amount of attraction between the object's surface and the polygonal topology. The greater the attraction, the faster the polygonal topology will approach the surface. Conversely, the greater the attraction, the harder it is for the algorithm to avoid getting stuck in a local rather than global minima.

Kj specifies the stiffness of the polygonal topology. The stiffer the topology, the less effect small amounts of surface noise has on the final geometric surface. Likewise, the stiffer the surface, the more likely it will be that small surface details will be lost.

**LOCATION** 

AVW\_Model.h

**SEE ALSO** 

AVW\_DestroyTileParameters(), AVW\_InitializeTileParameters(), AVW\_TileVolume(), AVW\_ObjectMap, AVW\_Volume

AVW\_TiledSurface – 3D polygonal surface description

# **SYNOPSIS**

```
typedef struct
{
    AVW_FPointList3 *Coords;
    unsigned int NumberOfIndices;
    unsigned int MaximumIndices;
    unsigned int BlockSize;
    int *Indices
} AVW_TiledSurface
```

#### **DESCRIPTION**

The *AVW\_TiledSurface* structure describes a 3D polygonal surface. It consists of a list of 3-space coordinates given in *Coords* and a list of the interconnections between those coordinates given in *Indices*. Thus a surface consisting of a single unit quadralateral polygon would have *Coords* containing: (0,0,0) (0,1,0) (1,1,0) (1,0,0) and *Indices* containing: 0 1 2 3 SRFC\_END\_INDEX *NumberOfIndices* is the current number of indices in the list. *Maximu-mIndices* indicates the number of indices this list can hold before automatic reallocation. *BlockSize* indicates the number of indices added to the current size when reallocation is necessary.

#### **LOCATION**

AVW\_Model.h

# **SEE ALSO**

AVW\_ExtractTiledSurface(), AVW\_LoadTiledSurface(), AVW\_SaveTiledSurface(), AVW\_DestroyTiledSurface(), AVW\_FPointList3

```
NAME
SYNOPSIS

typedef struct

{
    unsigned int NumberOfPoints;
    unsigned int MaximumPoints;
    unsigned int BlockSize;
    AVW_TreePoint *Points;
    } AVW_Tree;

DESCRIPTION

The AVW_Tree structure provides way to pass and return a list of skeletal trees.
```

LOCATION | AVW\_Tree.h

SEE ALSO | AVW\_TreePoint, AVW\_CreateTree(), AVW\_AddTreeChild(), AVW\_DestroyTree(), AVW\_FindTreeIndex() AVW\_LoadTree(), AVW\_SaveTree()

AVW\_TreePoint - Point of a tree

**SYNOPSIS** 

typedef struct
{
 short X, Y, Z;
 unsigned short Level;
 int ParentIndex;

unsigned int NumberOfChildren; unsigned int \*ChildIndex;

} AVW\_TreePoint;

**DESCRIPTION** 

The *AVW\_TreePoint* structure provides way to pass points of skeletal trees.

**LOCATION** 

 $AVW\_TreePoint.h$ 

**SEE ALSO** 

 $AVW\_Tree,\ AVW\_CreateTree(),\ AVW\_AddTreeChild(),\ AVW\_DestroyTree(),\ AVW\_FindTreeIndex()\ AVW\_LoadTree(),\ AVW\_SaveTree()$ 

AVW\_VisibleSurface - Visible Surface Structure

**SYNOPSIS** 

typedef struct

int NumberOfSurfaces; int MaximumSurfaces;

AVW\_VisibleSurfacePoint \*SurfacePoint;

} AVW\_VisibleSurface;

**DESCRIPTION** 

The *AVW\_VisibleSurface* structure is used to pass pre-determined surface information to and from *AVW* functions.

*NumberOfSurfaces* is the number of points in this surface.

*MaximumSurfaces* is the number of points that can be held in the *SurfacePoint* array, before it must be realloc'd.

SurfacePoint is an array of AVW\_VisibleSurfacePoint's.

**LOCATION** 

AVW\_Render.h

**SEE ALSO** 

AVW\_VisibleSurfacePoint

AVW\_VisibleSurfacePoint - Surface Point Structure

**SYNOPSIS** 

typedef struct {
 short int X. Y

short int X, Y, Z; short int Padding; double Value; } AVW\_VisibleSurfacePoint;

**DESCRIPTION** 

The *AVW\_VisibleSurfacePoint* structure holds the location and pixel value for a predetermined surface voxel.

*X*, *Y*, and *Z* indicates a voxels 3-D location.

Padding is unused. It exists for byte alignment purposes only.

value contains the pixel value information.

**LOCATION** 

AVW\_Render.h

**SEE ALSO** 

 $AVW\_Visible Surface$ 

AVW\_Volume - Volume Structure

#### **SYNOPSIS**

```
typedef struct
  void *Mem;
  int DataType;
  unsigned int Width;
  unsigned int Height;
  unsigned int Depth;
  unsigned int BytesPerPixel;
  unsigned int BytesPerLine;
  unsigned int BytesPerImage;
  unsigned int PixelsPerImage;
  unsigned int BytesPerVolume;
  unsigned int VoxelsPerVolume;
  AVW_Colormap *Colormap;
  char *Info;
  unsigned int *ZTable;
  unsigned int *YTable;
  } AVW_Volume;
```

#### **DESCRIPTION**

The *AVW\_Volume* structure provides an easy way to pass volumes to and from *AVW* functions.

*Mem* is a pointer to the raw data. It is often necessary to typecast this pointer when using it. For example:

```
ptr = (unsigned char *) volume->Mem
```

DataType specifies the voxel data type. All AVW data types are valid: AVW\_UNSIGNED\_CHAR, AVW\_SIGNED\_CHAR, AVW\_UNSIGNED\_SHORT, AVW\_SIGNED\_INT, AVW\_SIGNED\_INT, AVW\_FLOAT, AVW\_COMPLEX, and AVW\_COLOR.

Width, Height, and Depth specify the dimensions of the volume.

BytesPerPixel, BytesPerLine, BytesPerImage, PixelsPerImage, BytesPerVolume, and VoxelsPer-Volume contain often used pre-calcuated values.

Colormap is a pointer to an AVW\_Colormap.

*Info* is a pointer to an AVW information string.

*ZTable* and *YTable* is an array of pre-calculated offsets. The following example shows how to get the address of the tenth line of the fifth image in the volume.

ptr = (unsigned char \*) volume->Mem + volume->ZTable[4] + volume->YTable[9]

#### LOCATION

AVW.h

#### **SEE ALSO**

AVW\_Colormap, AVW\_Image, AVW\_CreateVolume(), AVW\_DestroyVolume(), AVW\_DESTROYVOLUME()

**DESCRIPTION** 

The *AVW\_DESTROYCOEFFS* macro provides a convenient method of freeing an *AVW\_FilterCoeffs* structure and setting the pointer to *NULL*.

**LOCATION** 

AVW\_Filter.h

**SEE ALSO** 

 $AVW\_DestroyCoeffs(),\ AVW\_CreateButterworthCoeffs(),\ AVW\_CreateCoeffs(),\ AVW\_CreateCoeffs(),\ AVW\_CreateSphericalMTF(),\ AVW\_CreateSphericalMTF(),\ AVW\_CreateStoksethMTF(),\ AVW\_FilterCoeffs$ 

**DESCRIPTION** 

The *AVW\_DESTROYCOMPOSITEINFO* macro provides a convenient method of freeing an *AVW\_CompositeInfo* and setting the pointer to that composite info to *NULL*.

**LOCATION** 

AVW.h

**SEE ALSO** 

 $AVW\_DestroyCompositeInfo(),\ AVW\_CreateCompositeInfo(),\ AVW\_CompositeInfo(),\ AVW\_Com$ 

**DESCRIPTION** 

The *AVW\_DESTROYFPOINTLIST3* macro provides a convenient method of freeing an *AVW\_FPointList3* and setting the pointer to that point list to *NULL*.

LOCATION

AVW.h

**SEE ALSO** 

 $AVW\_CreateFPointList3(),\ AVW\_DestroyFPointList3(),\ AVW\_FPointList3$ 

NAME AVW\_DESTROYHISTOGRAM – Destroy Histogram Macro

#define AVW\_DESTROYHISTOGRAM(histo) \
{
 AVW\_DestroyHistogram(histo);
 histo = NULL;
}

DESCRIPTION The AVW\_DESTROYHISTOGRAM macro provides a convenient method of freeing an AVW\_Histogram and setting the pointer to that histogram to NULL.

LOCATION AVW\_Histogram.h

SEE ALSO AVW\_DestroyHistogram(), AVW\_CreateHistogram(), AVW\_Histogram

**DESCRIPTION** 

The *AVW\_DESTROYIMAGE* macro provides a convenient method of freeing an *AVW\_Image* and setting the pointer to that image to *NULL*.

**LOCATION** 

AVW.h

**SEE ALSO** 

AVW\_DestroyImage(), AVW\_CreateImage(), AVW\_Image

NAME AVW\_DESTROYIPOINTLIST3 – Destroy AVW\_IPointList3 Macro

SYNOPSIS #define AVW\_DESTROYIPOINTLIST3(plist) \
{
 AVW\_DestroyIPointList3(plist);
 plist = NULL;
}

**DESCRIPTION** 

The *AVW\_DESTROYIPOINTLIST3* macro provides a convenient method of freeing an *AVW\_IPointList3* and setting the pointer to that point list to *NULL*.

**LOCATION** 

AVW.h

**SEE ALSO** 

 $AVW\_Create IPointList 3 (),\ AVW\_Destroy IPointList 3 (),\ AVW\_IPointList 3$ 

**DESCRIPTION** 

The *AVW\_DESTROYLIST* macro provides a convenient method of freeing an *AVW\_List* and setting the pointer to that list to *NULL*.

**LOCATION** 

AVW.h

**SEE ALSO** 

AVW\_DestroyList(), AVW\_List

**DESCRIPTION** 

The *AVW\_DESTROYPOINTLIST2* macro provides a convenient method of freeing an *AVW\_PointList2* and setting the pointer to that point list to *NULL*.

**LOCATION** 

AVW.h

**SEE ALSO** 

AVW\_CreatePointList2(), AVW\_DestroyPointList2(), AVW\_PointList2

**DESCRIPTION** 

The *AVW\_DESTROYPOINTVALUELIST* macro provides a convenient method of freeing an *AVW\_PointValueList* and setting the pointer to that point list to *NULL*.

**LOCATION** 

AVW.h

**SEE ALSO** 

 $AVW\_CreatePointValueList(),\ AVW\_DestroyPointValueList(),\ AVW\_PointValueList(),\ AVW\_Poi$ 

NAME AVW\_GETBLUE – Get Blue Macro

**SYNOPSIS** #define AVW\_GETBLUE(v) (((int) (v) & 0xff)

**DESCRIPTION** The *AVW\_GETBLUE* macro gets the blue portion of a packed RGB value.

LOCATION AVW.h

SEE ALSO | AVW\_GETRED(), AVW\_GETGREEN(), AVW\_MAKERGB(), AVW\_GetPixel(),

AVW\_GetVoxel()

**NAME** AVW\_GETGREEN – Get Green Macro

**SYNOPSIS** #define AVW\_GETGREEN(v) ((((int) (v)) >> 8) & 0xff)

**DESCRIPTION** The *AVW\_GETGREEN* macro gets the green portion of a packed RGB value.

LOCATION AVW.h

SEE ALSO | AVW\_GETRED(), AVW\_GETBLUE(), AVW\_MAKERGB(), AVW\_GetPixel(),

AVW\_GetVoxel()

**NAME** AVW\_GETRED – Get Red Macro

**SYNOPSIS** #define AVW\_GETRED(v) ((((int) (v)) >> 16) & 0xff)

**DESCRIPTION** The *AVW\_GETRED* macro gets the red portion of a packed RGB value.

LOCATION AVW.h

SEE ALSO | AVW\_GETGREEN(), AVW\_GETBLUE(), AVW\_MAKERGB(), AVW\_GetPixel(),

AVW\_GetVoxel()

NAME AVW\_MAKERGB – Make RGB Macro

**SYNOPSIS** #define AVW\_MAKERGB(r, g, b) ((double) ((((int) (r)) << 16) | (((int) (g)) << 8)

| ((int) (b))))

**DESCRIPTION** The AVW\_MAKERGB macro provides an easy method of packing Red, Green, and Blue

values into a double. Some AVW function require the packed RGB values.

LOCATION AVW.h

SEE ALSO | AVW\_GETRED(), AVW\_GETGREEN(), AVW\_GETBLUE(), AVW\_PutPixel(),

AVW\_PutVoxel(), AVW\_SetImage(), AVW\_SetVolume()

**NAME** 

AVW\_READSWAP - swaps bytes in data as it is read

**SYNOPSIS** 

#include <stdio.h> #include "AVW.h"

AVW\_READSWAP(ptr, size, nitems, stream)

void \*ptr;
int size, nitems;
FILE \*stream;

**DESCRIPTION** 

*AVW\_READSWAP()* is a modification of the system call fread() which causes data to be byte swapped on Little Endian machines. Byte swapping data as it is read from disk allows machines of different types to share data files.

**RETURN VALUES** 

*AVW\_READSWAP()* returns the value returned from the internal call to fread(). Please refer to the fread() call for possible return values and error checking.

**SEE ALSO** 

 $AVW\_QuadSwapImage(),\ AVW\_ReverseBits(),\ AVW\_SwapBlock(),\ AVW\_SwapDouble(),\ AVW\_SwapFloat(),\ AVW\_SwapImage(),\ AVW\_SwapInt(),\ AVW\_SwapLong(),\ AVW\_SwapShort(),\ AVW\_WRITESWAP(),\ fread(),\ fwrite(),\ swab()$ 

NAME AVV

AVW\_WRITESWAP - swaps bytes on disk writes

**SYNOPSIS** 

#include <stdio.h>
#include "AVW.h"

AVW\_WRITESWAP(ptr, size, nitems, stream)

void \*ptr;
int size, nitems;
FILE \*stream;

**DESCRIPTION** 

*AVW\_WRITESWAP()* is a modification of the system call fwrite() which causes data to be byte swapped on Little Endian machines. Byte swapping data as it is written to disk allows machines of different types to share data files.

**RETURN VALUES** 

*AVW\_WRITESWAP()* returns the value returned from the internal call to fwrite(). Refer to the fwrite() call for possible return values and error checking.

**SEE ALSO** 

AVW\_DataTypeToBands(), AVW\_DataTypeToBytes(), AVW\_QuadSwapImage(), AVW\_ReverseBits(), AVW\_SwapBlock(), AVW\_SwapDouble(), AVW\_SwapFloat(), AVW\_SwapImage(), AVW\_SwapInt(), AVW\_SwapLong(), AVW\_SwapShort(), AVW\_READSWAP(), fread(), fwrite(), swab()