

# HYDRO-DART: ENSEMBLE STREAMFLOW DATA ASSIMILATION USING WRF-HYDRO AND DART

## APPLICATION TO HURRICANE FLORENCE

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National Center for Atmospheric Research  
Data Assimilation Research Section (DAReS) - TDD - CISL



NATIONAL CENTER FOR ATMOSPHERIC RESEARCH

# MOTIVATION

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# Hurricane Florence

- Tropical wave ⇢ tropical storm ⇢ **Category 4 Hurricane**
- Landfall on Sep. 14 (Carolinas) with winds up to 150 mph
- Catastrophic damages to coastal communities [\$25 billion]
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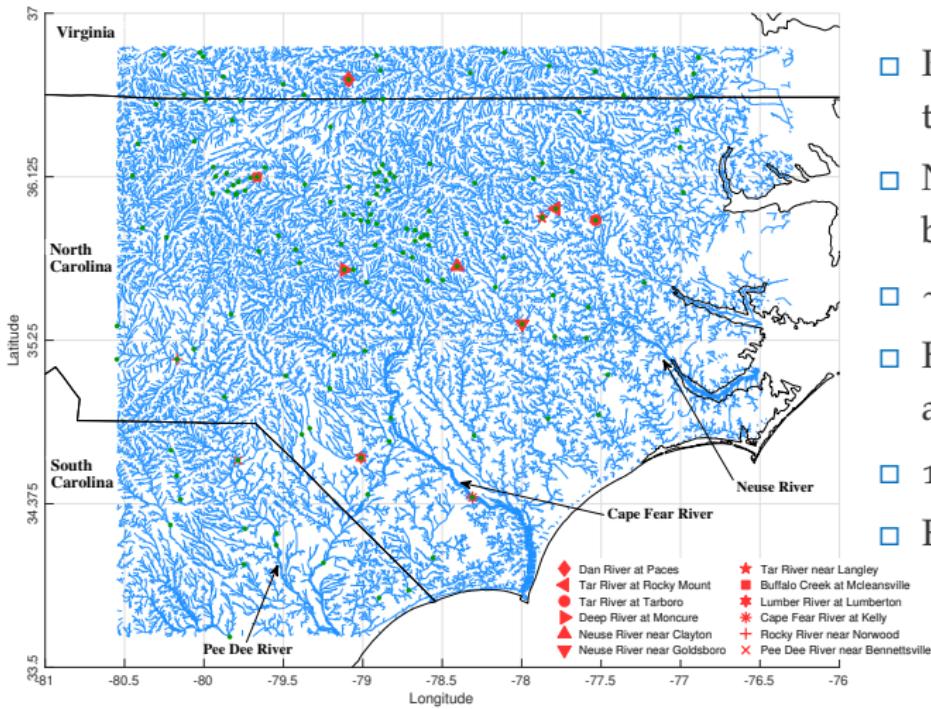


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- The **goal** is to interface the Data Assimilation Research Testbed (DART; [Anderson, 2003](#)) with WRF-Hydro (NOAA's NWM; [Gochis, 2020](#)) to enhance flood prediction during Hurricane Florence

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- Regional subdomain of the NWM CONUS
- NWM channel network based on NHDPlus v.2
- ~ 67K reaches
- Hourly streamflow assimilation
- 107 USGS gauges
- EAKF: 80 members

# THE COUPLED HYDROLOGIC- ASSIMILATION FRAMEWORK

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# The Hydrologic Model

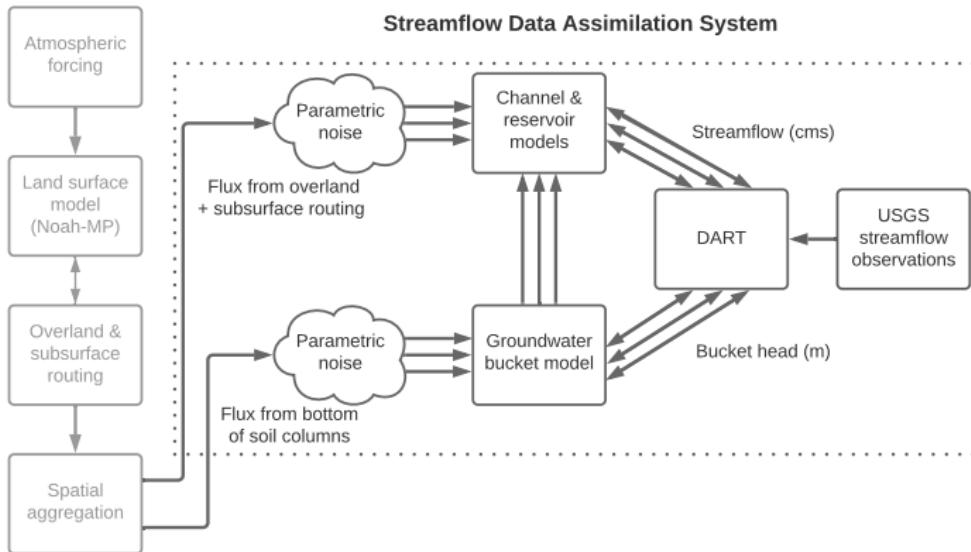
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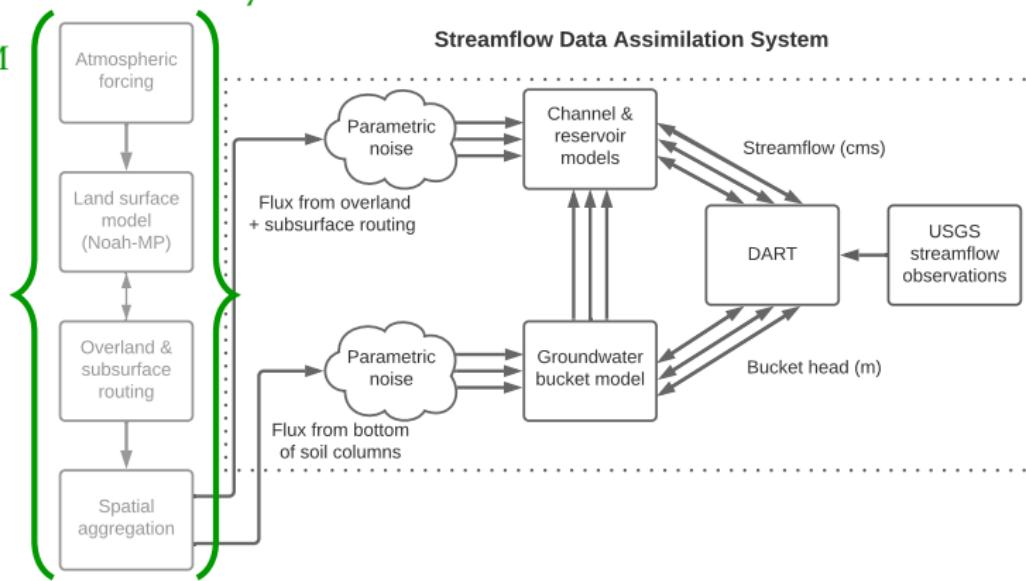
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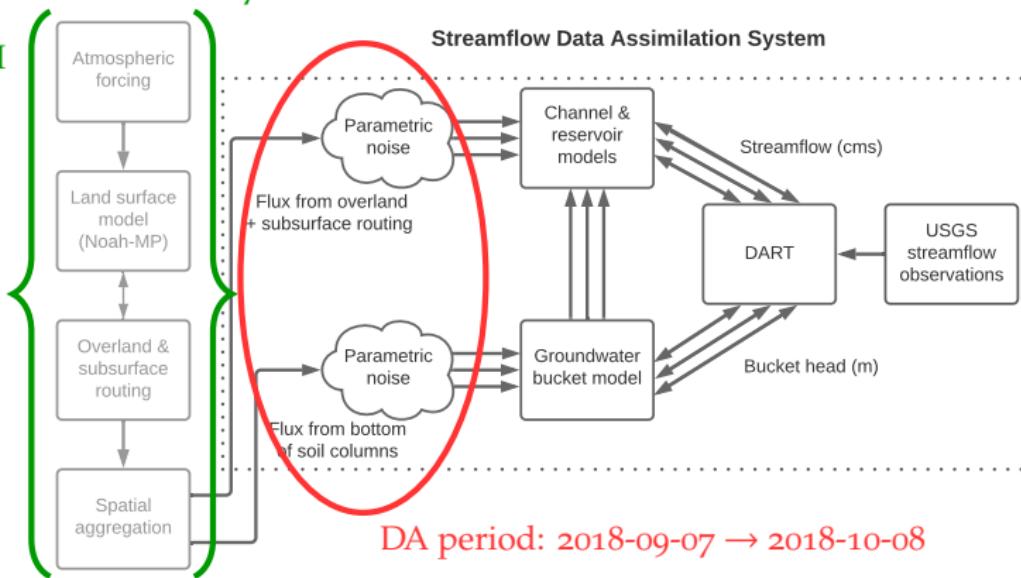
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One-way runoff  
fluxes used as input  
forcing to the  
channel+bucket  
sub-model



# Forcing and Ensemble Uncertainty

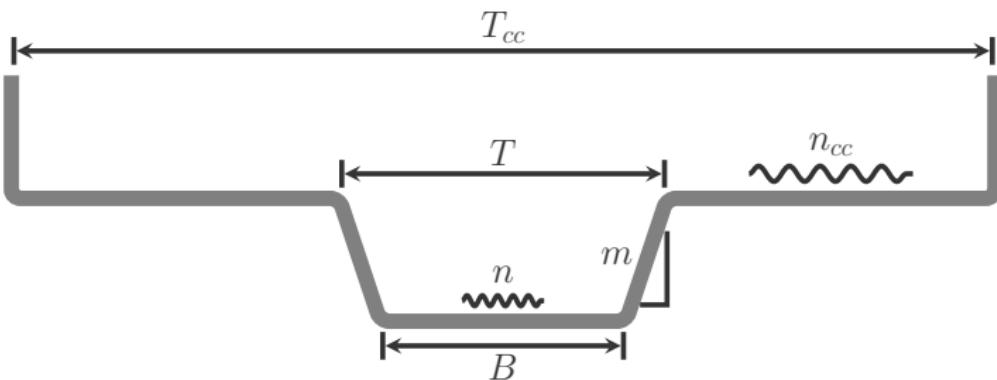
- Apply Gaussian perturbations to the boundary fluxes to the streamflow and bucket models every hourly forecast step
- To create realistic model variability, we follow a "multi-physics" approach ([Berner et al., 2011](#)) and perturb the channel parameters:
  1. top width,  $T$
  2. bottom width,  $B$
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Sampling uniformly under some physical constraints!

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# DART: The Data Assimilation Research Testbed

- Serial DA scheme: process observations one after the other
- State: [1] Streamflow & [2] groundwater bucket at every reach

## How to mitigate typical filtering issues?

- i. **Sampling Errors:** due to limited ensemble size

$$\mathbf{x}_{j,k}^{a(i)} = \mathbf{x}_{j,k}^{f(i)} + \alpha \Delta \mathbf{x}_j^{(i)}; \quad j, k, i : \{\text{space, time, ensemble}\}$$

→ Along-The-Stream (ATS) Localization       $[0 < \alpha < 1]$

- ii. **Model Biases:** e.g., physical parameters, boundary conditions, ...

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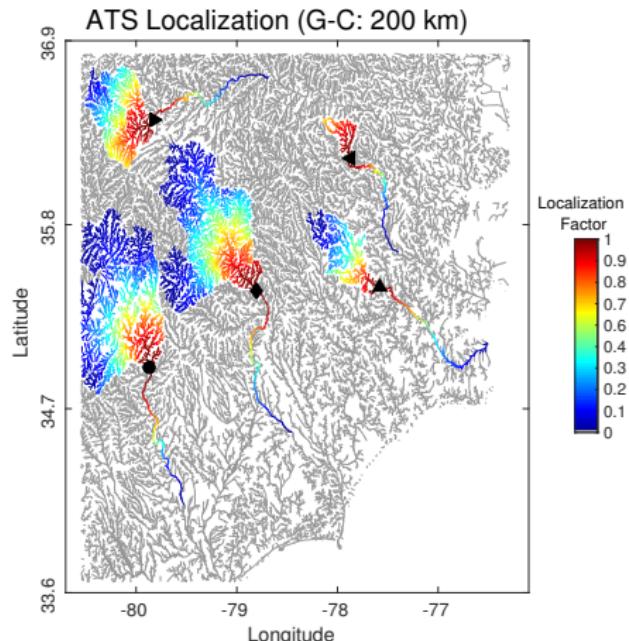
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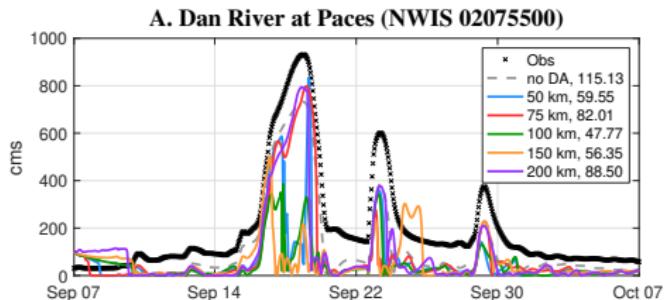
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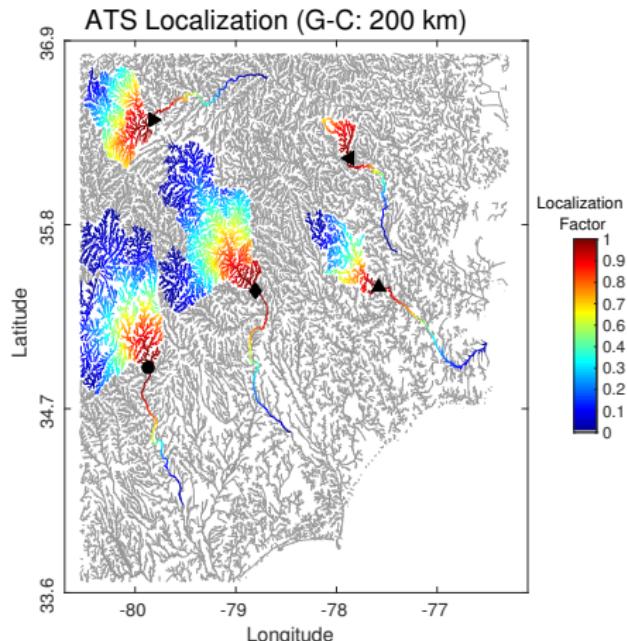


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- best performance using 100 km
- larger radii give rise to spurious correlations and smaller ones limit the amount of useful information
- G-C outperforms other correlation functions



# ATS vs Regular Localization

	ATS	Reg 20	Reg 10	Reg 5	Reg 2	Reg 1
Tar River at Tarboro (NWIS 02083500)	Prior RMSE	5.58	18.54	8.86	33.46	41.61
	Posterior RMSE	4.93	17.82	6.75	25.11	33.66
	Prior Bias	-1.13	-11.65	-1.71	-20.24	-18.09
	Posterior Bias	-0.85	-11.41	-0.74	-20.37	-17.16
	Prior Spread	1.20	3.29	2.80	10.90	10.84
	Posterior Spread	1.55	3.00	2.27	6.28	6.43

- Performance using ATS localization is significantly better (~ 40%)
- Using ATS, one can increase the effective localization radius
- Regular localization with large radii fails (correlating physically unrelated variables)

# Adaptive Covariance Inflation

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The algorithm is adaptive in time, based on Bayes' theorem, and results in spatially varying fields ([El Gharabti, 2018](#)):

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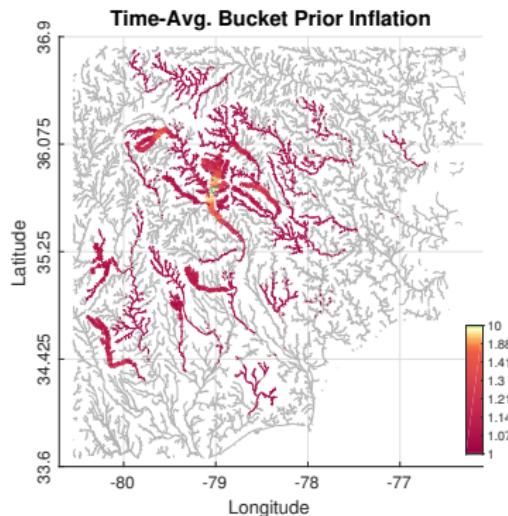
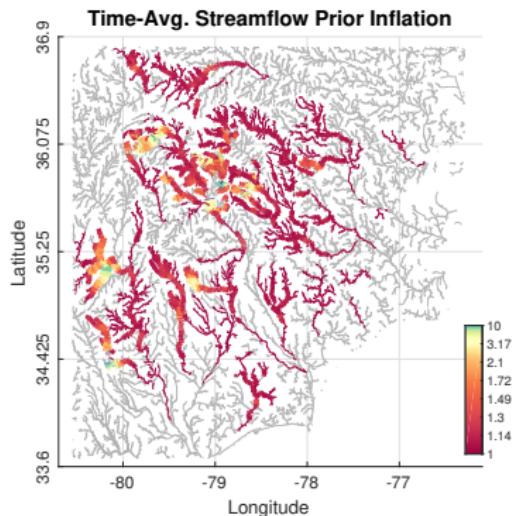
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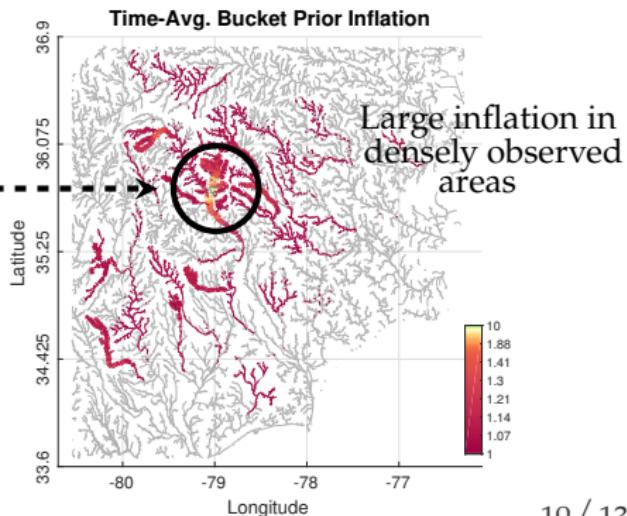
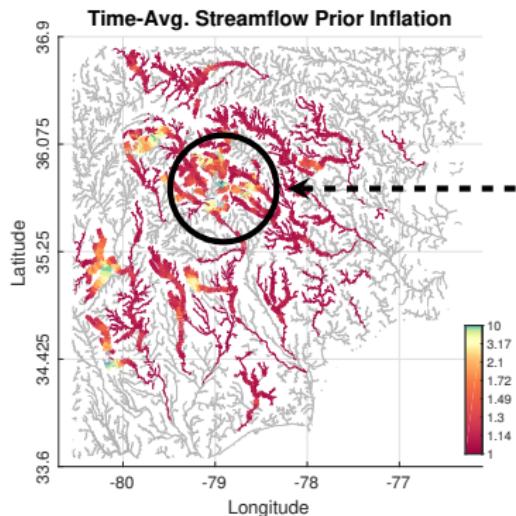


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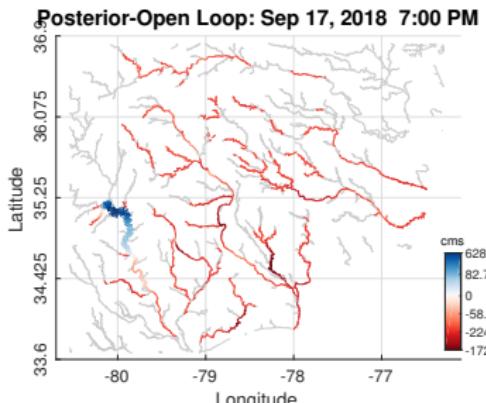
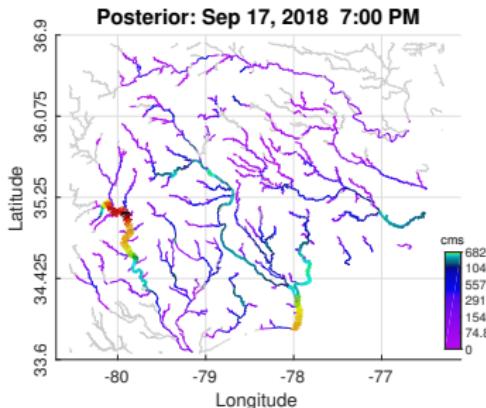
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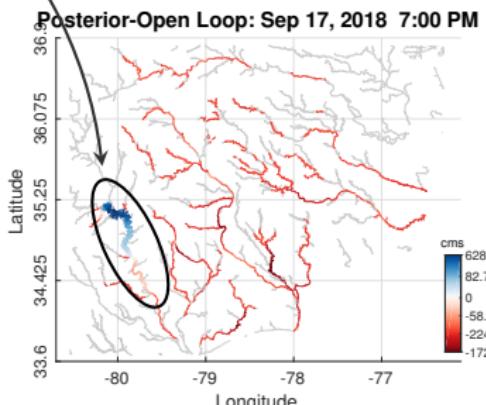
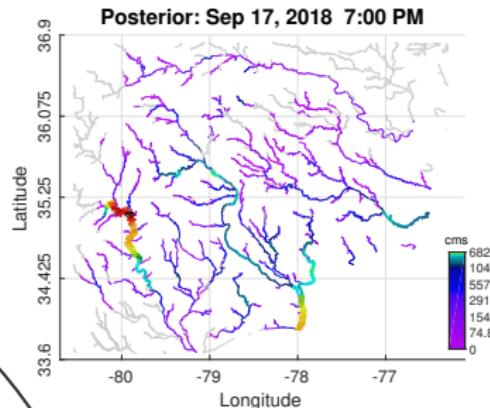
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After landfall, the model's streamflow prediction (Open Loop) is significantly smaller than the posterior along Pee-Dee River in South Carolina



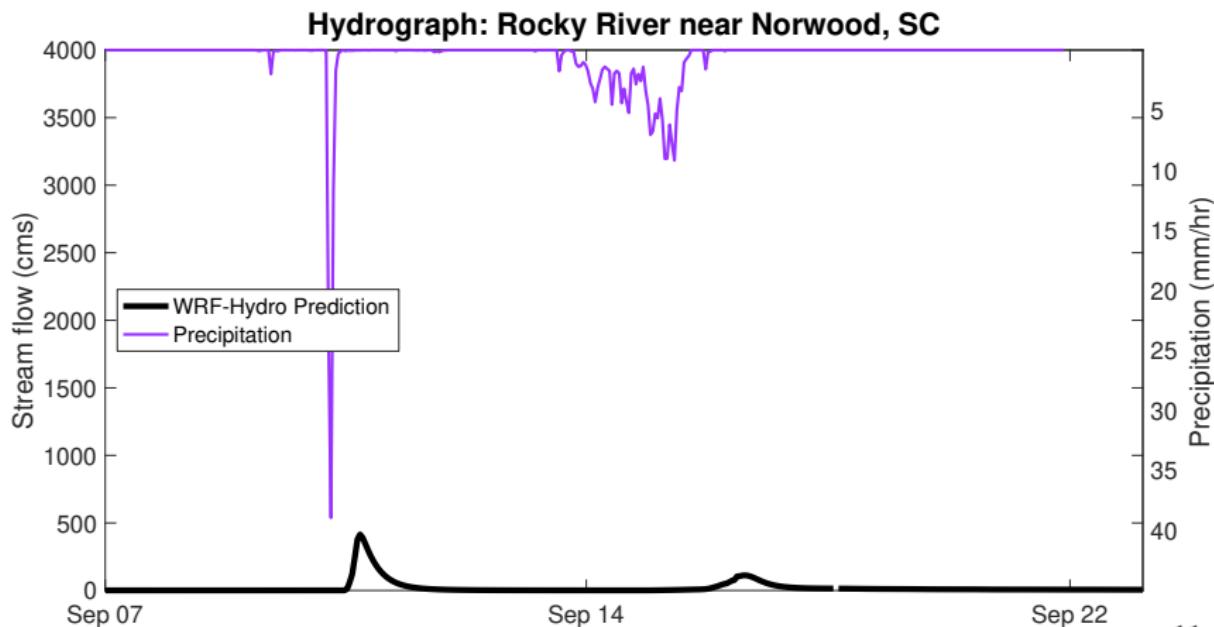
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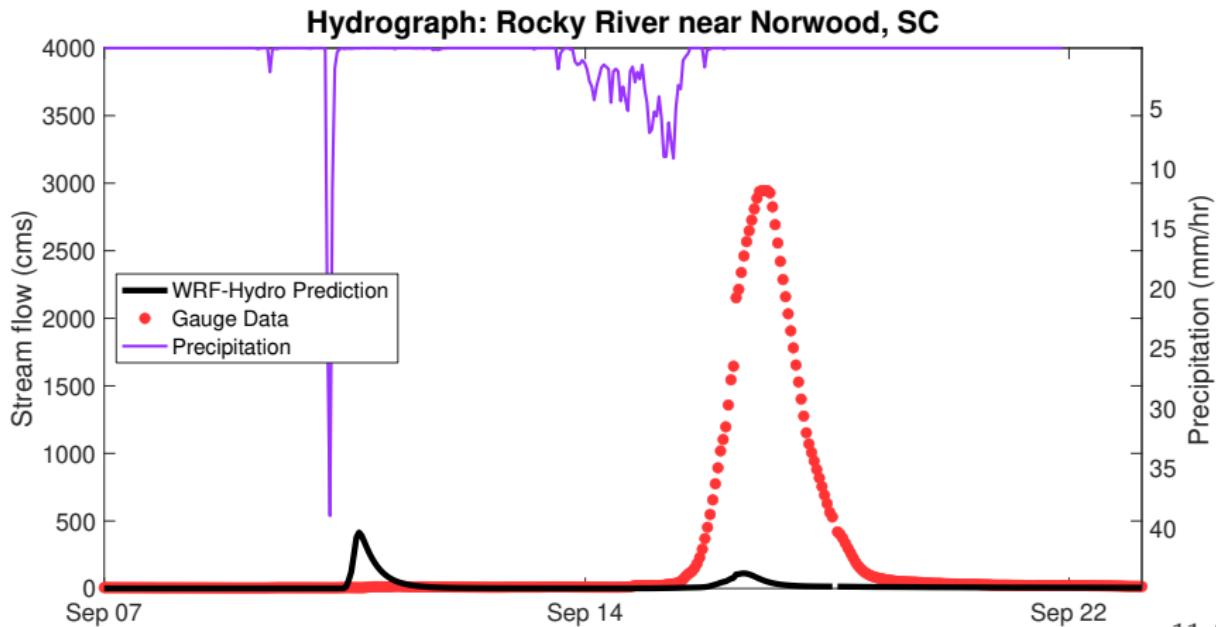
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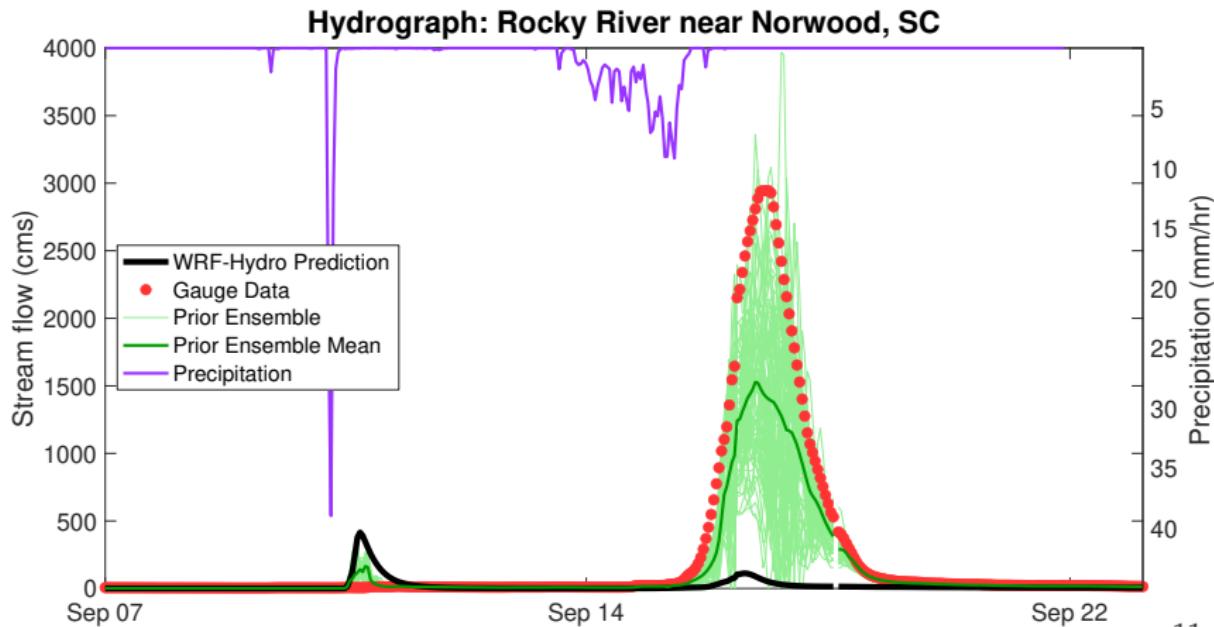
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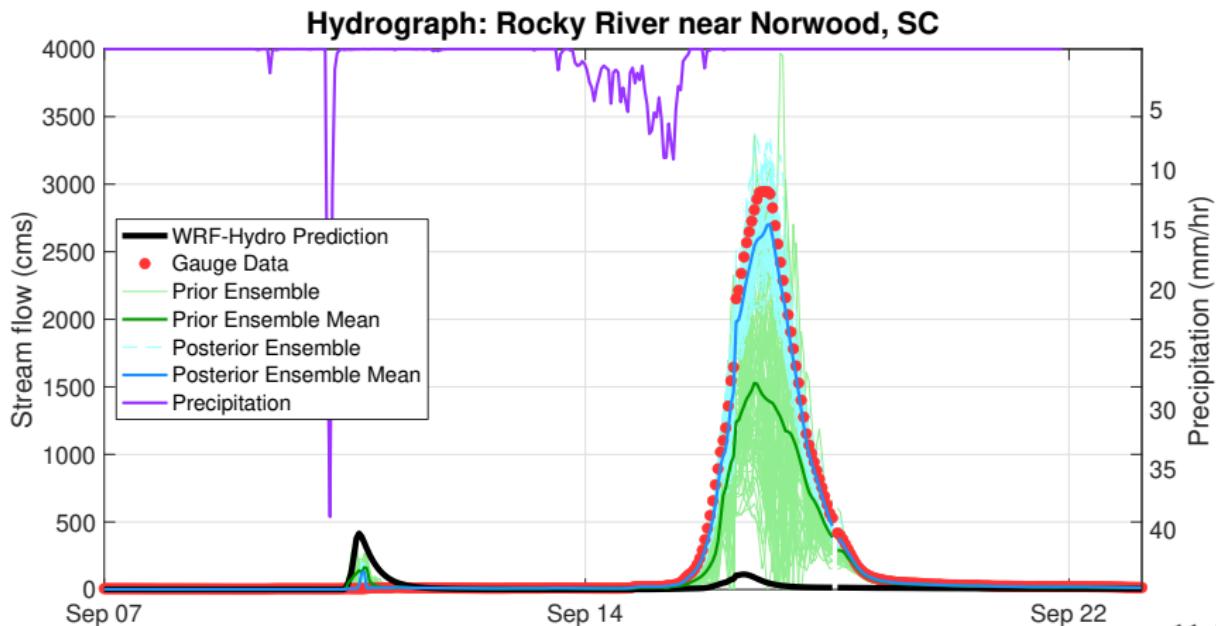
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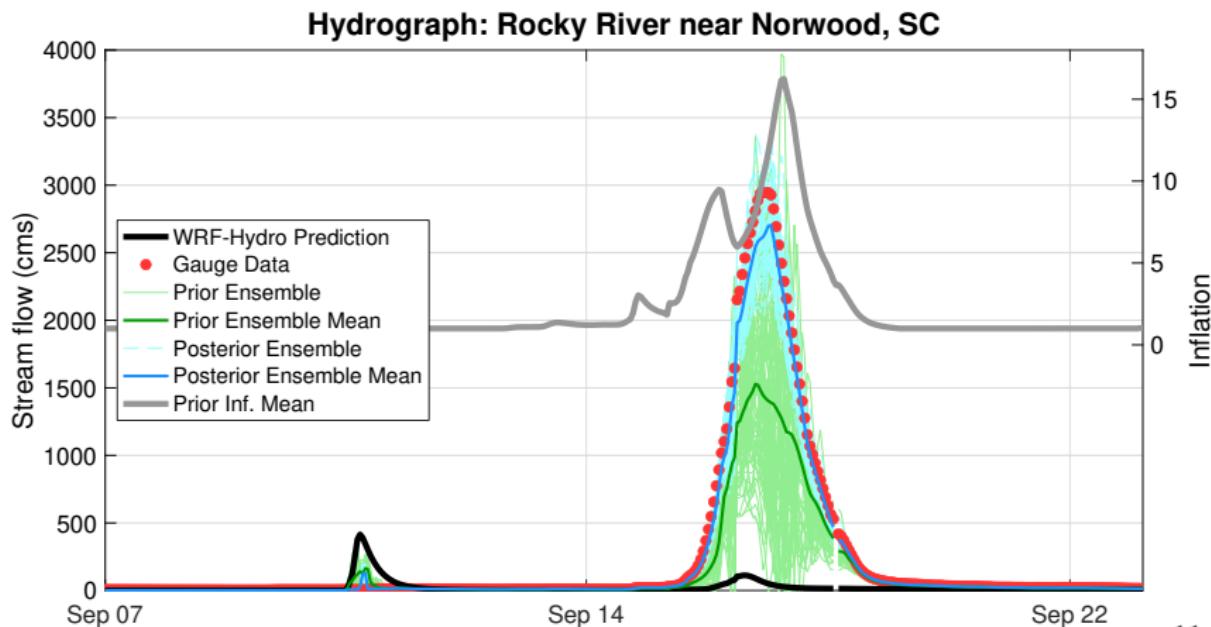
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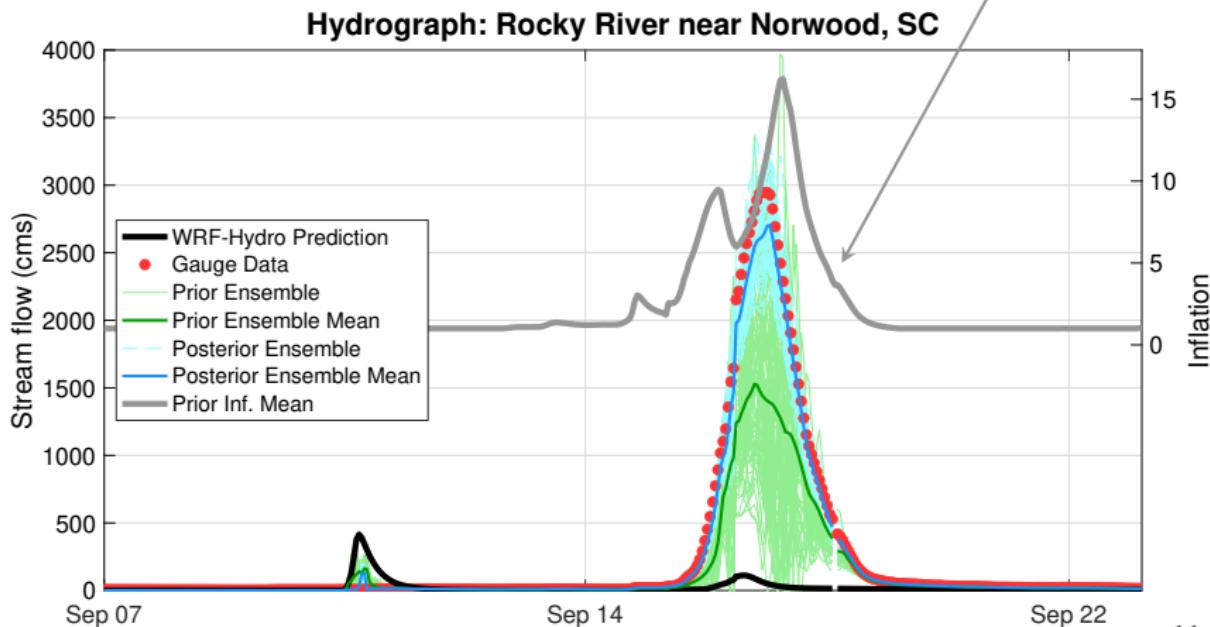
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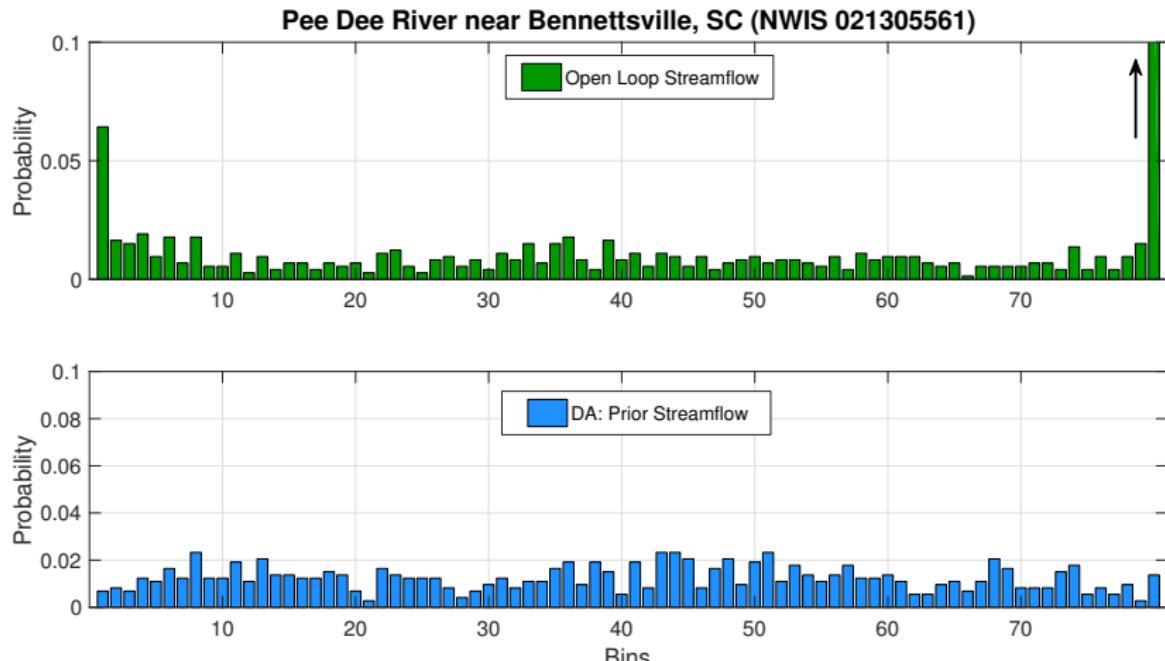
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A sizable increase in prior inflation to counter the bias in the modeled streamflow!



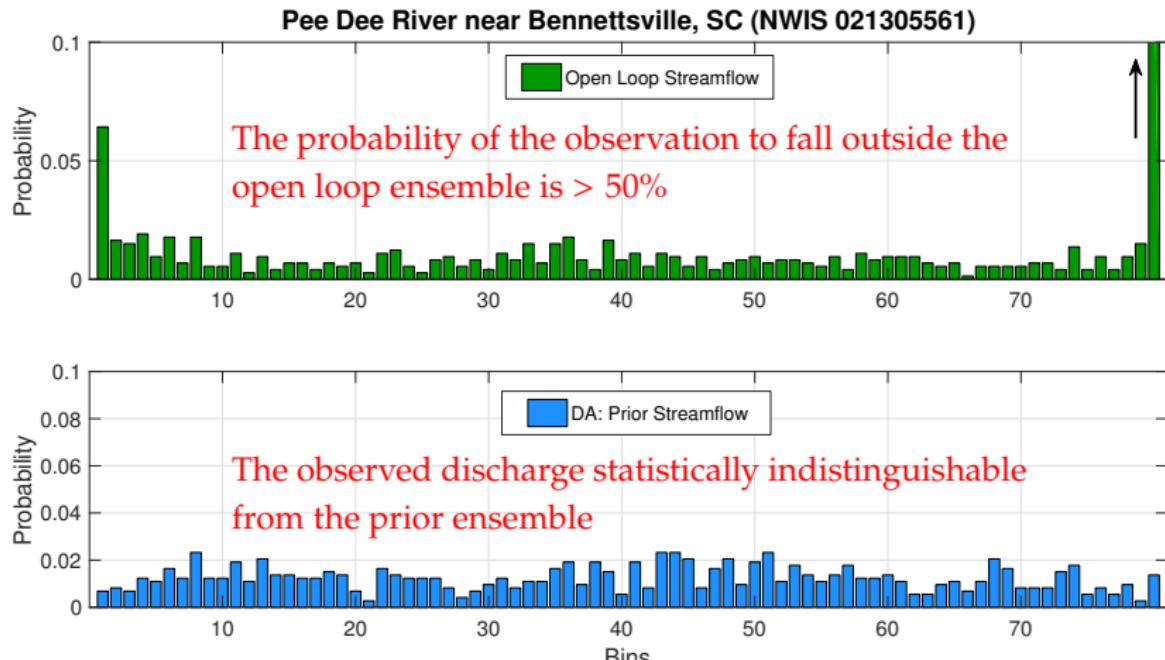
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